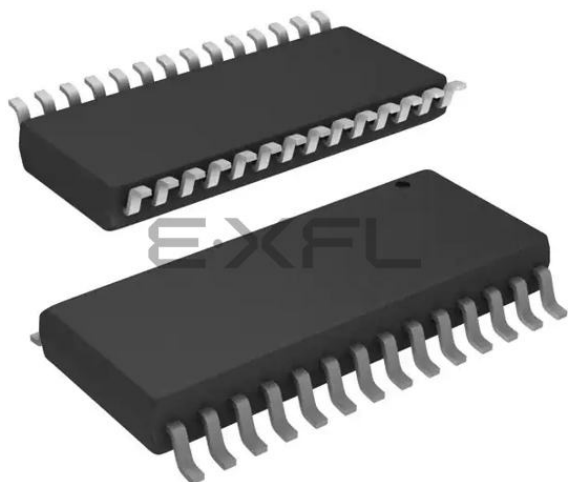




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Details

Product Status	Obsolete
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I ² C, IrDA, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	19
Program Memory Size	32KB (11K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 9x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic24fj32gb002t-i-so

PIC24FJ64GB004 FAMILY

Analog Features:

- 10-Bit, up to 13-Channel Analog-to-Digital (A/D) Converter:
 - 500 ksp/s conversion rate
 - Conversion available during Sleep and Idle
- Three Analog Comparators with Programmable Input/Output Configuration
- Charge Time Measurement Unit (CTMU):
 - Supports capacitive touch sensing for touch screens and capacitive switches
 - Provides high-resolution time measurement and simple temperature sensing

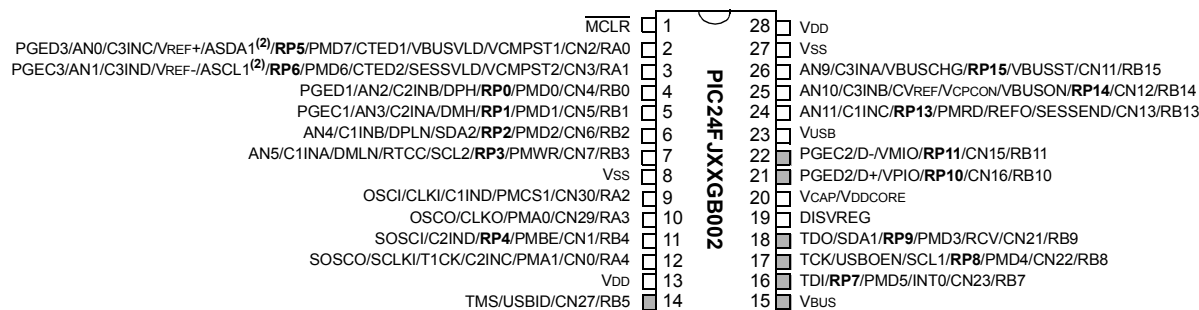
Peripheral Features:

- Peripheral Pin Select:
 - Allows independent I/O mapping of many peripherals
 - Up to 25 available pins (44-pin devices)
 - Continuous hardware integrity checking and safety interlocks prevent unintentional configuration changes
- 8-Bit Parallel Master Port (PMP/PSP):
 - Up to 16-bit multiplexed addressing, with up to 11 dedicated address pins on 44-pin devices
 - Programmable polarity on control lines
 - Supports legacy Parallel Slave Port

- Hardware Real-Time Clock/Calendar (RTCC):
 - Provides clock, calendar and alarm functions
 - Functions even in Deep Sleep mode
- Two 3-Wire/4-Wire SPI modules (support 4 Frame modes) with 8-Level FIFO Buffer
- Two I²C™ modules support Multi-Master/Slave mode and 7-Bit/10-Bit Addressing
- Two UART modules:
 - Supports RS-485, RS-232 and LIN/J2602
 - On-chip hardware encoder/decoder for IrDA®
 - Auto-wake-up on Start bit
 - Auto-Baud Detect (ABD)
 - 4-level deep FIFO buffer
- Five 16-Bit Timers/Counters with Programmable Prescaler
- Five 16-Bit Capture Inputs, each with a Dedicated Time Base
- Five 16-Bit Compare/PWM Outputs, each with a Dedicated Time Base
- Programmable, 32-Bit Cyclic Redundancy Check (CRC) Generator
- Configurable Open-Drain Outputs on Digital I/O Pins
- Up to 3 External Interrupt Sources

Pin Diagrams

28-Pin SPDIP, SOIC, SSOP⁽¹⁾



Legend: RPn represents remappable peripheral pins.

Note 1: Gray shading indicates 5.5V tolerant input pins.

2: Alternative multiplexing for SDA1 and SCL1 when the I2C1SEL bit is set.

TABLE 4-5: INTERRUPT CONTROLLER REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	0080	NSTDIS	—	—	—	—	—	—	—	—	—	—	MATHERR	ADDRERR	STKERR	OSCFail	—	0000
INTCON2	0082	ALTIVT	DISI	—	—	—	—	—	—	—	—	—	—	—	INT2EP	INT1EP	INT0EP	0000
IFS0	0084	—	—	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPF1IF	T3IF	T2IF	OC2IF	IC2IF	—	T1IF	OC1IF	IC1IF	INT0IF	0000
IFS1	0086	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	—	—	—	—	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF	0000
IFS2	0088	—	—	PMPIF	—	—	—	OC5IF	—	IC5IF	IC4IF	IC3IF	—	—	—	SPI2IF	SPF2IF	0000
IFS3	008A	—	RTCIF	—	—	—	—	—	—	—	—	—	—	—	MI2C2IF	SI2C2IF	—	0000
IFS4	008C	—	—	CTMUIF	—	—	—	—	LVDIF	—	—	—	—	CRCIF	U2ERIF	U1ERIF	—	0000
IFS5	008E	—	—	—	—	—	—	—	—	—	USB1IF	—	—	—	—	—	—	0000
IEC0	0094	—	—	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPF1IE	T3IE	T2IE	OC2IE	IC2IE	—	T1IE	OC1IE	IC1IE	INT0IE	0000
IEC1	0096	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	—	—	—	—	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE	0000
IEC2	0098	—	—	PMPIE	—	—	—	OC5IE	—	IC5IE	IC4IE	IC3IE	—	—	—	SPI2IE	SPF2IE	0000
IEC3	009A	—	RTCIE	—	—	—	—	—	—	—	—	—	—	—	MI2C2IE	SI2C2IE	—	0000
IEC4	009C	—	—	CTMUIE	—	—	—	—	LVDIE	—	—	—	—	CRCIE	U2ERIE	U1ERIE	—	0000
IEC5	009E	—	—	—	—	—	—	—	—	—	USB1IE	—	—	—	—	—	—	0000
IPC0	00A4	—	T1IP2	T1IP1	T1IP0	—	OC1IP2	OC1IP1	OC1IP0	—	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0	4444
IPC1	00A6	—	T2IP2	T2IP1	T2IP0	—	OC2IP2	OC2IP1	OC2IP0	—	IC2IP2	IC2IP1	IC2IP0	—	—	—	—	4440
IPC2	00A8	—	U1RXIP2	U1RXIP1	U1RXIP0	—	SPI1IP2	SPI1IP1	SPI1IP0	—	SPF1IP2	SPF1IP1	SPF1IP0	—	T3IP2	T3IP1	T3IP0	4444
IPC3	00AA	—	—	—	—	—	—	—	—	—	AD1IP2	AD1IP1	AD1IP0	—	U1TXIP2	U1TXIP1	U1TXIP0	0044
IPC4	00AC	—	CNIP2	CNIP1	CNIP0	—	CMIP2	CMIP1	CMIP0	—	MI2C1IP2	MI2C1IP1	MI2C1IP0	—	SI2C1IP2	SI2C1IP1	SI2C1IP0	4444
IPC5	00AE	—	—	—	—	—	—	—	—	—	—	—	—	—	INT1IP2	INT1IP1	INT1IP0	0004
IPC6	00B0	—	T4IP2	T4IP1	T4IP0	—	OC4IP2	OC4IP1	OC4IP0	—	OC3IP2	OC3IP1	OC3IP0	—	—	—	—	4440
IPC7	00B2	—	U2TXIP2	U2TXIP1	U2TXIP0	—	U2RXIP2	U2RXIP1	U2RXIP0	—	INT2IP2	INT2IP1	INT2IP0	—	T5IP2	T5IP1	T5IP0	4444
IPC8	00B4	—	—	—	—	—	—	—	—	—	SPI2IP2	SPI2IP1	SPI2IP0	—	SPF2IP2	SPF2IP1	SPF2IP0	0044
IPC9	00B6	—	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0	—	IC3IP2	IC3IP1	IC3IP0	—	—	—	—	4440
IPC10	00B8	—	—	—	—	—	—	—	—	—	OC5IP2	OC5IP1	OC5IP0	—	—	—	—	0040
IPC11	00BA	—	—	—	—	—	—	—	—	—	PMPIP2	PMPIP1	PMPIP0	—	—	—	—	0040
IPC12	00BC	—	—	—	—	—	MI2C2IP2	MI2C2IP1	MI2C2IP0	—	SI2C2IP2	SI2C2IP1	SI2C2IP0	—	—	—	—	0440
IPC15	00C2	—	—	—	—	—	RTCIP2	RTCIP1	RTCIP0	—	—	—	—	—	—	—	—	0400
IPC16	00C4	—	CRCIP2	CRCIP1	CRCIP0	—	U2ERIP2	U2ERIP1	U2ERIP0	—	U1ERIP2	U1ERIP1	U1ERIP0	—	—	—	—	4440
IPC18	00C8	—	—	—	—	—	—	—	—	—	—	—	—	—	LVDIP2	LVDIP1	LVDIP0	0004
IPC19	00CA	—	—	—	—	—	—	—	—	—	CTMUIP2	CTMUIP1	CTMUIP0	—	—	—	—	0040
IPC21	00CE	—	—	—	—	—	USB1IP2	USB1IP1	USB1IP0	—	—	—	—	—	—	—	—	0400
INTTREG	00E0	CPUIRQ	—	VHOLD	—	ILR3	ILR2	ILR1	ILR0	—	VECNUM6	VECNUM5	VECNUM4	VECNUM3	VECNUM2	VECNUM1	VECNUM0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

PIC24FJ64GB004 FAMILY

EXAMPLE 5-4: LOADING THE WRITE BUFFERS – ‘C’ LANGUAGE CODE

```
// C example using MPLAB C30

#define NUM_INSTRUCTION_PER_ROW 64
unsigned int offset;
unsigned int i;
unsigned long progAddr = 0XXXXXX;           // Address of row to write
unsigned int progData[2*NUM_INSTRUCTION_PER_ROW]; // Buffer of data to write

//Set up NVMCON for row programming
NVMCON = 0x4001;                           // Initialize NVMCON

//Set up pointer to the first memory location to be written
TBLPAG = progAddr>>16;                      // Initialize PM Page Boundary SFR
offset = progAddr & 0xFFFF;                 // Initialize lower word of address

//Perform TBLWT instructions to write necessary number of latches
for(i=0; i < 2*NUM_INSTRUCTION_PER_ROW; i++)
{
    __builtin_tblwtl(offset, progData[i++]); // Write to address low word
    __builtin_tblwth(offset, progData[i]);   // Write to upper byte
    offset = offset + 2;                     // Increment address
}
```

EXAMPLE 5-5: INITIATING A PROGRAMMING SEQUENCE – ASSEMBLY LANGUAGE CODE

```
DISI    #5                                ; Block all interrupts with priority <7
                                           ; for next 5 instructions

MOV     #0x55, W0
MOV     W0, NVMKEY                        ; Write the 55 key
MOV     #0xAA, W1
MOV     W1, NVMKEY                        ; Write the AA key
BSET    NVMCON, #WR                       ; Start the erase sequence
NOP
NOP
BTSC    NVMCON, #15                       ; and wait for it to be
BRA     $-2                               ; completed
```

EXAMPLE 5-6: INITIATING A PROGRAMMING SEQUENCE – ‘C’ LANGUAGE CODE

```
// C example using MPLAB C30

asm("DISI #5");                          // Block all interrupts with priority < 7
                                           // for next 5 instructions

__builtin_write_NVM();                    // Perform unlock sequence and set WR
```

PIC24FJ64GB004 FAMILY

REGISTER 7-7: IFS2: INTERRUPT FLAG STATUS REGISTER 2

U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	U-0
—	—	PMPIF	—	—	—	OC5IF	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
IC5IF	IC4IF	IC3IF	—	—	—	SPI2IF	SPF2IF
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **PMPIF:** Parallel Master Port Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 12-10 **Unimplemented:** Read as '0'
- bit 9 **OC5IF:** Output Compare Channel 5 Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 8 **Unimplemented:** Read as '0'
- bit 7 **IC5IF:** Input Capture Channel 5 Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 6 **IC4IF:** Input Capture Channel 4 Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 5 **IC3IF:** Input Capture Channel 3 Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 4-2 **Unimplemented:** Read as '0'
- bit 1 **SPI2IF:** SPI2 Event Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 0 **SPF2IF:** SPI2 Fault Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred

PIC24FJ64GB004 FAMILY

REGISTER 7-9: IFS4: INTERRUPT FLAG STATUS REGISTER 4

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0
—	—	CTMUIF	—	—	—	—	LVDIF
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0
—	—	—	—	CRCIF	U2ERIF	U1ERIF	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13 **CTMUIF:** CTMU Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 12-9 **Unimplemented:** Read as '0'
- bit 8 **LVDIF:** Low-Voltage Detect Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 7-4 **Unimplemented:** Read as '0'
- bit 3 **CRCIF:** CRC Generator Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 2 **U2ERIF:** UART2 Error Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 1 **U1ERIF:** UART1 Error Interrupt Flag Status bit
 - 1 = Interrupt request has occurred
 - 0 = Interrupt request has not occurred
- bit 0 **Unimplemented:** Read as '0'

PIC24FJ64GB004 FAMILY

REGISTER 7-23: IPC6: INTERRUPT PRIORITY CONTROL REGISTER 6

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T4IP2	T4IP1	T4IP0	—	OC4IP2	OC4IP1	OC4IP0
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	OC3IP2	OC3IP1	OC3IP0	—	—	—	—
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **T4IP<2:0>:** Timer4 Interrupt Priority bits
 111 = Interrupt is Priority 7 (highest priority interrupt)
 .
 .
 .
 001 = Interrupt is Priority 1
 000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OC4IP<2:0>:** Output Compare Channel 4 Interrupt Priority bits
 111 = Interrupt is Priority 7 (highest priority interrupt)
 .
 .
 .
 001 = Interrupt is Priority 1
 000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **OC3IP<2:0>:** Output Compare Channel 3 Interrupt Priority bits
 111 = Interrupt is Priority 7 (highest priority interrupt)
 .
 .
 .
 001 = Interrupt is Priority 1
 000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'

PIC24FJ64GB004 FAMILY

8.0 OSCILLATOR CONFIGURATION

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, Section 6. “Oscillator” (DS39700).

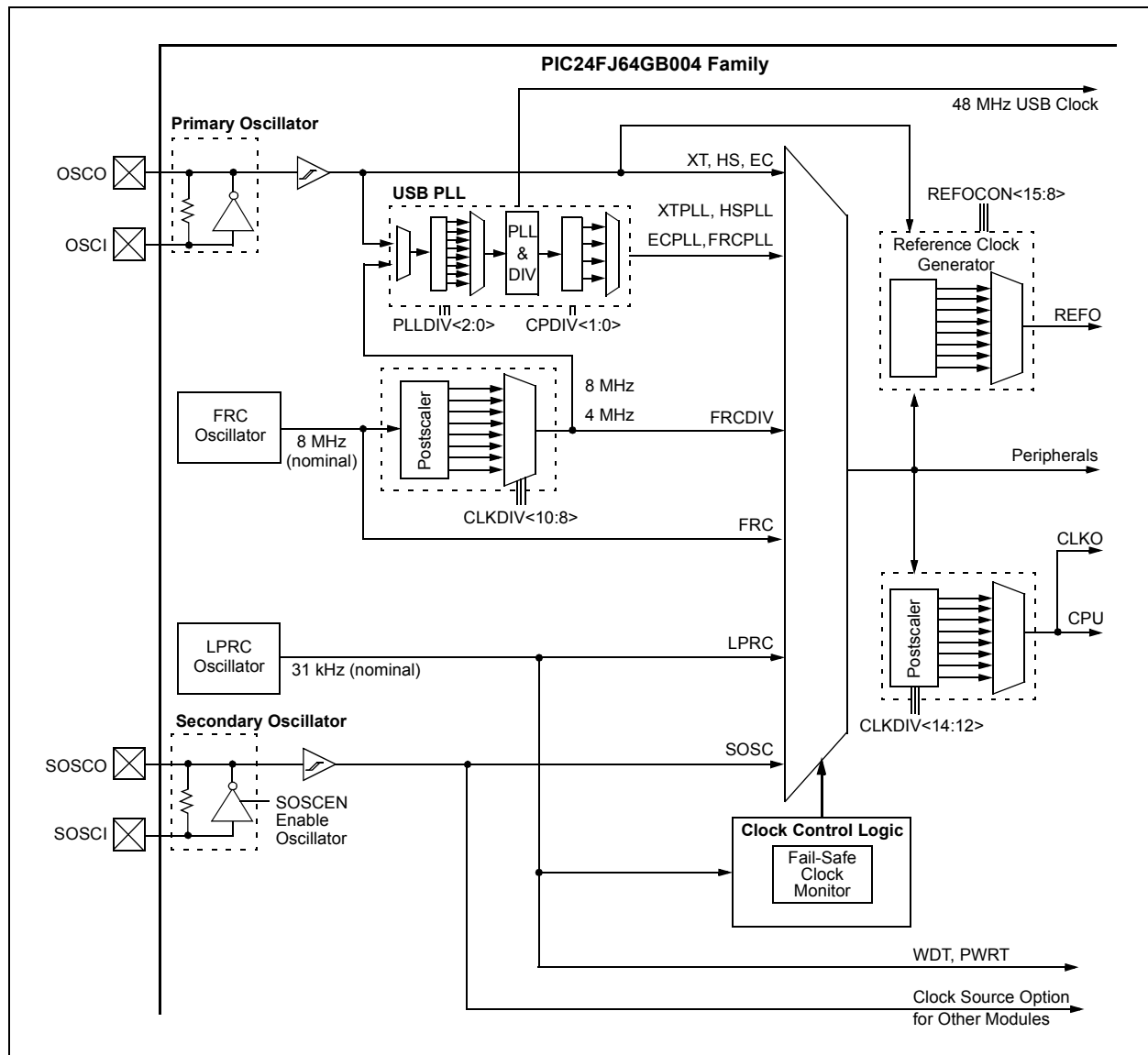
The oscillator system for PIC24FJ64GB004 family devices has the following features:

- A total of four external and internal oscillator options as clock sources, providing 11 different clock modes

- An on-chip USB PLL block to provide a stable 48 MHz clock for the USB module, as well as a range of frequency options for the system clock
- Software-controllable switching between various clock sources
- Software-controllable postscaler for selective clocking of CPU for system power savings
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and permits safe application recovery or shutdown
- A separate and independently configurable system clock output for synchronizing external hardware

A simplified diagram of the oscillator system is shown in Figure 8-1.

FIGURE 8-1: PIC24FJ64GB004 FAMILY CLOCK DIAGRAM



PIC24FJ64GB004 FAMILY

REGISTER 8-3: OSCTUN: FRC OSCILLATOR TUNE REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	TUN5 ⁽¹⁾	TUN4 ⁽¹⁾	TUN3 ⁽¹⁾	TUN2 ⁽¹⁾	TUN1 ⁽¹⁾	TUN0 ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-6

Unimplemented: Read as '0'

bit 5-0

TUN<5:0>: FRC Oscillator Tuning bits⁽¹⁾

011111 = Maximum frequency deviation

011110 =

•

•

•

000001 =

000000 = Center frequency, oscillator is running at factory calibrated frequency

111111 =

•

•

•

100001 =

100000 = Minimum frequency deviation

Note 1: Increments or decrements of TUN<5:0> may not change the FRC frequency in equal steps over the FRC tuning range and may not be monotonic.

8.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the four clock sources (POSC, SOSC, FRC and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

Note: The Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMDx Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

8.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM Configuration bits in CW2 must be programmed to '00'. (Refer to **Section 26.1 "Configuration Bits"** for further details.) If the FCKSM Configuration bits are unprogrammed ('1x'), the clock switching function and Fail-Safe Clock Monitor function are disabled; this is the default setting.

The NOSCx control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSCx bits (OSCCON<14:12>) will reflect the clock source selected by the FNOSCx Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled; it is held at '0' at all times.

PIC24FJ64GB004 FAMILY

14.3 Pulse-Width Modulation (PWM) Mode

In PWM mode, the output compare module can be configured for edge-aligned or center-aligned pulse waveform generation. All PWM operations are double-buffered (buffer registers are internal to the module and are not mapped into SFR space).

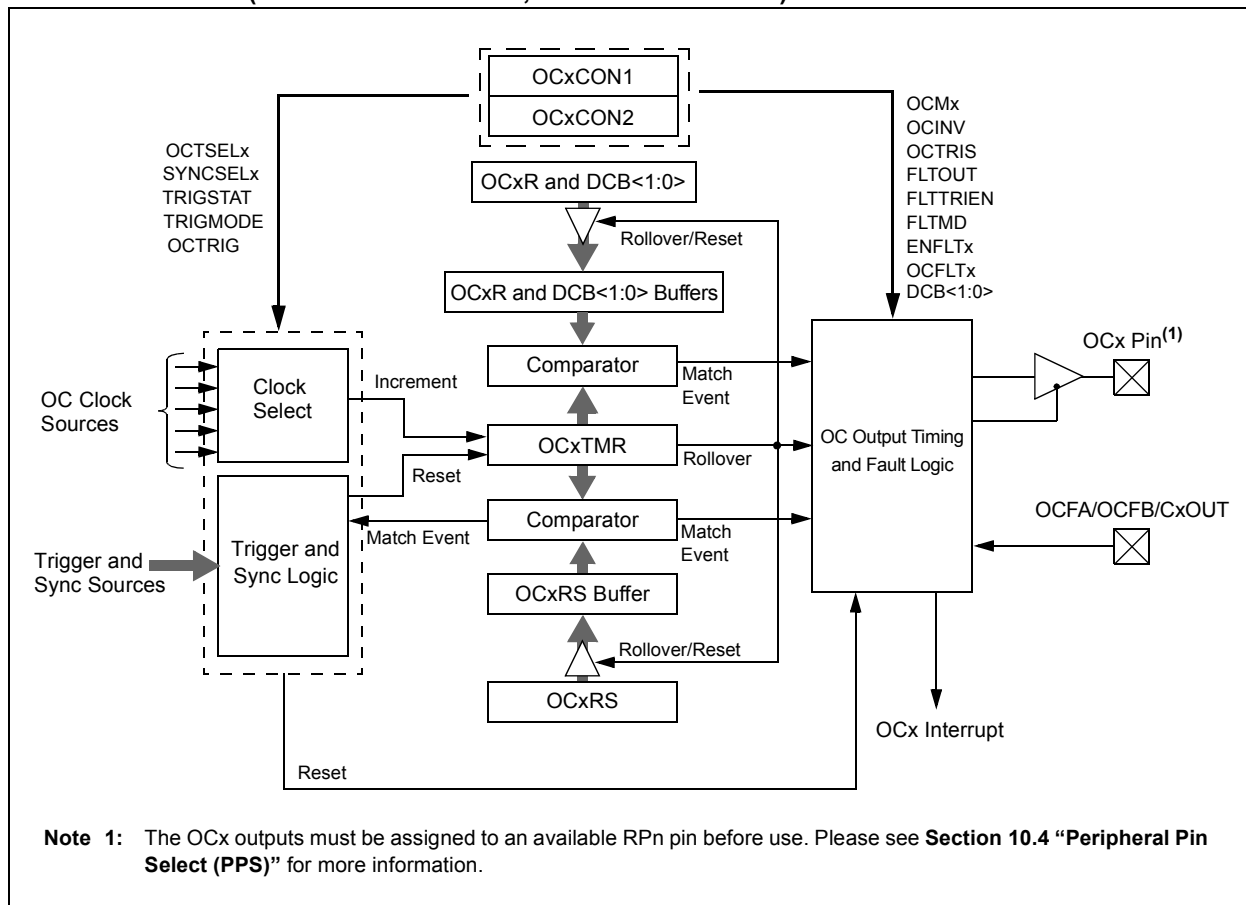
To configure the output compare module for edge-aligned PWM operation:

1. Configure the OCx output for one of the available Peripheral Pin Select pins.
2. Calculate the desired on-time and load it into the OCxR register.
3. Calculate the desired period and load it into the OCxRS register.
4. Select the current OCx as the synchronization source by writing 0x1F to SYNCSEL<4:0> (OCxCON2<4:0>) and '0' to OCTRIG (OCxCON2<7>).

5. Select a clock source by writing to the OCTSEL2<2:0> (OCxCON1<12:10>) bits.
6. Enable interrupts, if required, for the timer and output compare modules. The output compare interrupt is required for PWM Fault pin utilization.
7. Select the desired PWM mode in the OCM<2:0> (OCxCON1<2:0>) bits.
8. If a timer is selected as a clock source, set the TMRy prescale value and enable the time base by setting the TON (TxCON<15>) bit.

Note: This peripheral contains input and output functions that may need to be configured by the Peripheral Pin Select. See **Section 10.4 “Peripheral Pin Select (PPS)”** for more information.

FIGURE 14-2: OUTPUT COMPARE BLOCK DIAGRAM (DOUBLE-BUFFERED, 16-BIT PWM MODE)



REGISTER 17-1: UxMODE: UARTx MODE REGISTER (CONTINUED)

bit 3	BRGH: High Baud Rate Enable bit 1 = High-Speed mode (four BRG clock cycles per bit) 0 = Standard mode (16 BRG clock cycles per bit)
bit 2-1	PDSEL<1:0>: Parity and Data Selection bits 11 = 9-bit data, no parity 10 = 8-bit data, odd parity 01 = 8-bit data, even parity 00 = 8-bit data, no parity
bit 0	STSEL: Stop Bit Selection bit 1 = Two Stop bits 0 = One Stop bit

- Note 1:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See **Section 10.4 “Peripheral Pin Select (PPS)”** for more information.
- 2:** This feature is only available for the 16x BRG mode (BRGH = 0).

PIC24FJ64GB004 FAMILY

BDs have a fixed relationship to a particular endpoint, depending on the buffering configuration. Table 18-2 provides the mapping of BDs to endpoints. This relationship also means that gaps may occur in the BDT if endpoints are not enabled contiguously. This theoretically means that the BDs for disabled endpoints could be used as buffer space. In practice, users should avoid using such spaces in the BDT unless a method of validating BD addresses is implemented.

18.2.1 BUFFER OWNERSHIP

Because the buffers and their BDs are shared between the CPU and the USB module, a simple semaphore mechanism is used to distinguish which is allowed to update the BD and associated buffers in memory. This is done by using the UOWN bit as a semaphore to distinguish which is allowed to update the BD and associated buffers in memory. UOWN is the only bit that is shared between the two configurations of BDnSTAT.

When UOWN is clear, the BD entry is “owned” by the microcontroller core. When the UOWN bit is set, the BD entry and the buffer memory are “owned” by the USB peripheral. The core should not modify the BD or its corresponding data buffer during this time. Note that the microcontroller core can still read BDnSTAT while the SIE owns the buffer and vice versa.

The buffer descriptors have a different meaning based on the source of the register update. Register 18-1 and Register 18-2 show the differences in BDnSTAT depending on its current “ownership”.

When UOWN is set, the user can no longer depend on the values that were written to the BDs. From this point, the USB module updates the BDs as necessary, overwriting the original BD values. The BDnSTAT register is updated by the SIE with the token PID and the transfer count is updated.

18.2.2 DMA INTERFACE

The USB OTG module uses a dedicated DMA to access both the BDT and the endpoint data buffers. Since part of the address space of the DMA is dedicated to the Buffer Descriptors, a portion of the memory connected to the DMA must comprise a contiguous address space properly mapped for the access by the module.

TABLE 18-2: ASSIGNMENT OF BUFFER DESCRIPTORS FOR THE DIFFERENT BUFFERING MODES

Endpoint	BDs Assigned to Endpoint							
	Mode 0 (No Ping-Pong)		Mode 1 (Ping-Pong on EP0 OUT)		Mode 2 (Ping-Pong on all EPs)		Mode 3 (Ping-Pong on all other EPs, except EP0)	
	Out	In	Out	In	Out	In	Out	In
0	0	1	0 (E), 1 (O)	2	0 (E), 1 (O)	2 (E), 3 (O)	0	1
1	2	3	3	4	4 (E), 5 (O)	6 (E), 7 (O)	2 (E), 3 (O)	4 (E), 5 (O)
2	4	5	5	6	8 (E), 9 (O)	10 (E), 11 (O)	6 (E), 7 (O)	8 (E), 9 (O)
3	6	7	7	8	12 (E), 13 (O)	14 (E), 15 (O)	10 (E), 11 (O)	12 (E), 13 (O)
4	8	9	9	10	16 (E), 17 (O)	18 (E), 19 (O)	14 (E), 15 (O)	16 (E), 17 (O)
5	10	11	11	12	20 (E), 21 (O)	22 (E), 23 (O)	18 (E), 19 (O)	20 (E), 21 (O)
6	12	13	13	14	24 (E), 25 (O)	26 (E), 27 (O)	22 (E), 23 (O)	24 (E), 25 (O)
7	14	15	15	16	28 (E), 29 (O)	30 (E), 31 (O)	26 (E), 27 (O)	28 (E), 29 (O)
8	16	17	17	18	32 (E), 33 (O)	34 (E), 35 (O)	30 (E), 31 (O)	32 (E), 33 (O)
9	18	19	19	20	36 (E), 37 (O)	38 (E), 39 (O)	34 (E), 35 (O)	36 (E), 37 (O)
10	20	21	21	22	40 (E), 41 (O)	42 (E), 43 (O)	38 (E), 39 (O)	40 (E), 41 (O)
11	22	23	23	24	44 (E), 45 (O)	46 (E), 47 (O)	42 (E), 43 (O)	44 (E), 45 (O)
12	24	25	25	26	48 (E), 49 (O)	50 (E), 51 (O)	46 (E), 47 (O)	48 (E), 49 (O)
13	26	27	27	28	52 (E), 53 (O)	54 (E), 55 (O)	50 (E), 51 (O)	52 (E), 53 (O)
14	28	29	29	30	56 (E), 57 (O)	58 (E), 59 (O)	54 (E), 55 (O)	56 (E), 57 (O)
15	30	31	31	32	60 (E), 61 (O)	62 (E), 63 (O)	58 (E), 59 (O)	60 (E), 61 (O)

Legend: (E) = Even transaction buffer, (O) = Odd transaction buffer

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18.7.3 USB ENDPOINT MANAGEMENT REGISTERS

REGISTER 18-21: U1EPn: USB ENDPOINT CONTROL REGISTERS (n = 0 TO 15)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
LSPD ⁽¹⁾	RETRYDIS ⁽¹⁾	—	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSK
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **LSPD:** Low-Speed Direct Connection Enable bit (U1EP0 only)⁽¹⁾

1 = Direct connection to a low-speed device is enabled

0 = Direct connection to a low-speed device is disabled

bit 6 **RETRYDIS:** Retry Disable bit (U1EP0 only)⁽¹⁾

1 = Retry NAK transactions are disabled

0 = Retry NAK transactions are enabled; retry done in hardware

bit 5 **Unimplemented:** Read as '0'

bit 4 **EPCONDIS:** Bidirectional Endpoint Control bit

If EPTXEN and EPRXEN = 1:

1 = Disable Endpoint n from Control transfers; only Tx and Rx transfers are allowed

0 = Enable Endpoint n for Control (SETUP) transfers; Tx and Rx transfers also are allowed.

For all other combinations of EPTXEN and EPRXEN:

This bit is ignored.

bit 3 **EPRXEN:** Endpoint Receive Enable bit

1 = Endpoint n receive is enabled

0 = Endpoint n receive is disabled

bit 2 **EPTXEN:** Endpoint Transmit Enable bit

1 = Endpoint n transmit is enabled

0 = Endpoint n transmit is disabled

bit 1 **EPSTALL:** Endpoint Stall Status bit

1 = Endpoint n was stalled

0 = Endpoint n was not stalled

bit 0 **EPHSK:** Endpoint Handshake Enable bit

1 = Endpoint handshake is enabled

0 = Endpoint handshake is disabled (typically used for isochronous endpoints)

Note 1: These bits are available only for U1EP0, and only in Host mode. For all other U1EPn registers, these bits are always unimplemented and read as '0'.

19.0 PARALLEL MASTER PORT (PMP)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the “PIC24F Family Reference Manual”, **Section 13. “Parallel Master Port (PMP)”** (DS39713).

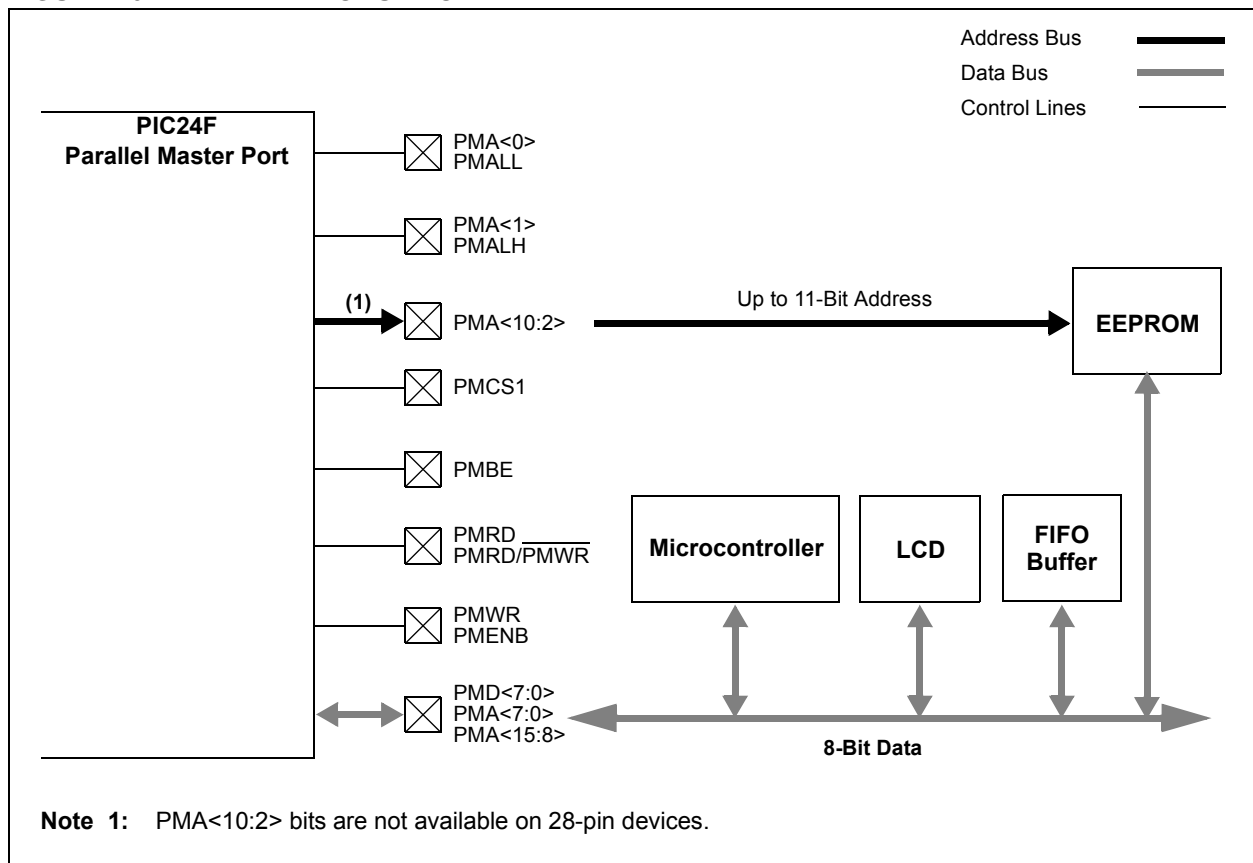
The Parallel Master Port (PMP) module is a parallel, 8-bit I/O module, specifically designed to communicate with a wide variety of parallel devices, such as communication peripherals, LCDs, external memory devices and microcontrollers. Because the interface to parallel peripherals varies significantly, the PMP is highly configurable.

Note: A number of the pins for the PMP are not present on PIC24FJ64GB0 family devices. Refer to the specific device's pinout to determine which pins are available.

Key features of the PMP module include:

- Up to 16 Programmable Address Lines
- One Chip Select Line
- Programmable Strobe Options:
 - Individual Read and Write Strobes or;
 - Read/Write Strobe with Enable Strobe
- Address Auto-Increment/Auto-Decrement
- Programmable Address/Data Multiplexing
- Programmable Polarity on Control Signals
- Legacy Parallel Slave Port Support
- Enhanced Parallel Slave Support:
 - Address Support
 - 4-Byte Deep Auto-Incrementing Buffer
- Programmable Wait States
- Selectable Input Voltage Levels

FIGURE 19-1: PMP MODULE OVERVIEW



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REGISTER 22-5: AD1PCFG: A/D PORT CONFIGURATION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0 ⁽¹⁾	R/W-0	R/W-0	R/W-0	R/W-0 ⁽¹⁾
PCFG15	PCFG14	PCFG13	PCFG12	PCFG11	PCFG10	PCFG9	PCFG8
bit 15							bit 8

R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PCFG7	PCFG6	PCFG5	PCFG4	PCFG3	PCFG2	PCFG1	PCFG0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15 **PCFG15:** A/D Input Band Gap Reference Enable bit
 1 = Internal band gap (V_{BG}) reference channel is disabled
 0 = Internal band gap reference channel is enabled
- bit 14 **PCFG14:** A/D Input Half Band Gap Reference Enable bit
 1 = Internal half band gap (V_{BG}/2) reference channel is disabled
 0 = Internal half band gap reference channel is enabled
- bit 13 **PCFG13:** A/D Input Voltage Regulator Output Reference Enable bit
 1 = Internal voltage regulator output (V_{DDCORE}) reference channel is disabled
 0 = Internal voltage regulator output reference channel is enabled
- bit 12-0 **PCFG<12:0>:** Analog Input Pin Configuration Control bits⁽¹⁾
 1 = Pin for corresponding analog channel is configured in Digital mode; I/O port read is enabled
 0 = Pin is configured in Analog mode; I/O port read is disabled, A/D samples pin voltage

Note 1: Analog channels, AN6, AN7, AN8 and AN12, are unavailable on 28-pin devices; leave these corresponding bits set.

26.6 JTAG Interface

PIC24FJ64GB004 family devices implement a JTAG interface, which supports boundary scan device testing.

26.7 In-Circuit Serial Programming

PIC24FJ64GB004 family microcontrollers can be serially programmed while in the end application circuit. This is simply done with two lines for clock (PGECx) and data (PGEDx), and three other lines for power, ground and the programming voltage. This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

26.8 In-Circuit Debugger

When MPLAB® ICD 2 is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pins.

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, VSS and the PGECx/PGEDx pin pair designated by the ICS Configuration bits. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

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TABLE 29-3: DC CHARACTERISTICS: TEMPERATURE AND VOLTAGE SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)				
			Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Conditions
Operating Voltage							
DC10	Supply Voltage						
	VDD		2.2	—	3.6	V	Regulator enabled
	VDD		VDDCORE	—	3.6	V	Regulator disabled
	VDDCORE		2.0	—	2.75	V	Regulator disabled
DC12	VDR	RAM Data Retention Voltage⁽²⁾	1.5	—	—	V	
DC16	VPOR	VDD Start Voltage to Ensure Internal Power-on Reset Signal	VSS	—	—	V	
DC17	SVDD	VDD Rise Rate to Ensure Internal Power-on Reset Signal	0.05	—	—	V/ms	0-3.3V in 0.1s 0-2.5V in 60 ms
DC18	VBOR	Brown-out Reset Voltage	—	2.05	—	V	

Note 1: Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: This is the limit to which VDD can be lowered without losing RAM data.

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**TABLE 29-7: DC CHARACTERISTICS: POWER-DOWN PERIPHERAL
MODULE Δ CURRENT (IPD) (CONTINUED)**

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)		
			Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended		
Parameter No.	Typical ⁽¹⁾	Max	Units	Conditions	
Δ Power-Down Current (IPD): PMD Bits are Set, PMSLP Bit is '0' ⁽²⁾					
DC63	1.8	2.3	μA	-40°C	32 kHz Crystal with RTCC, DSWDT or Timer1: ΔIsosc; SOSCSEL = 11 ⁽⁵⁾
DC63a	1.8	2.7	μA	+25°C	
DC63i	1.8	3.0	μA	+60°C	
DC63b	1.8	3.0	μA	+85°C	
DC63m	2.2	3.3	μA	+125C	
DC63c	2	2.7	μA	-40°C	
DC63d	2	2.9	μA	+25°C	
DC63j	2	3.2	μA	+60°C	
DC63e	2	3.5	μA	+85°C	
DC63n	2.5	3.8	μA	+125C	
DC63f	2.25	3.0	μA	-40°C	
DC63g	2.25	3.0	μA	+25°C	
DC63k	2.25	3.3	μA	+60°C	
DC63h	2.25	3.5	μA	+85°C	
DC63p	2.8	4.0	μA	+125C	
DC71c	0.001	0.25	μA	-40°C	Deep Sleep BOR: ΔIDSBOR ⁽⁵⁾
DC71d	0.03	0.25	μA	+25°C	
DC71j	0.05	0.60	μA	+60°C	
DC71e	0.08	2.0	μA	+85°C	
DC71a	3.9	10	μA	+125C	
DC71f	0.001	0.50	μA	-40°C	
DC71g	0.03	0.50	μA	+25°C	
DC71k	0.05	0.75	μA	+60°C	
DC71h	0.08	2.5	μA	+85°C	
DC71b	3.9	12.5	μA	+125C	

Note 1: Data in the Typical column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

- Peripheral IPD deltas are measured with the device in Sleep mode (all peripherals and clocks shut down). All I/Os are configured as inputs and pulled high. Only the peripheral or clock being measured is enabled. PMSLP bit is clear and the Peripheral Module Disable bits (PMD) for all unused peripherals are set.
- On-chip voltage regulator disabled (DISVREG tied to V_{DD}).
- On-chip voltage regulator enabled (DISVREG tied to V_{SS}). Low-Voltage Detect (LVD) and Brown-out Detect (BOD) are enabled.
- The Δ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.

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TABLE 29-8: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS

DC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Sym	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Conditions
DI10	V _{IL}	Input Low Voltage⁽⁴⁾ I/O Pins with ST Buffer	V _{SS}	—	0.2 V _{DD}	V	SMBus enabled
DI11		I/O Pins with TTL Buffer	V _{SS}	—	0.15 V _{DD}	V	
DI15		$\overline{\text{MCLR}}$	V _{SS}	—	0.2 V _{DD}	V	
DI16		OSC1 (XT mode)	V _{SS}	—	0.2 V _{DD}	V	
DI17		OSC1 (HS mode)	V _{SS}	—	0.2 V _{DD}	V	
DI18		I/O Pins with I ² C™ Buffer:	V _{SS}	—	0.3 V _{DD}	V	
DI19		I/O Pins with SMBus Buffer:	V _{SS}	—	0.8	V	
DI20	V _{IH}	Input High Voltage⁽⁴⁾ I/O Pins with ST Buffer: with Analog Functions, Digital Only	0.8 V _{DD} 0.8 V _{DD}	— —	V _{DD} 5.5	V V	2.5V ≤ V _{PIN} ≤ V _{DD}
DI21		I/O Pins with TTL Buffer: with Analog Functions, Digital Only	0.25 V _{DD} + 0.8 0.25 V _{DD} + 0.8	— —	V _{DD} 5.5	V V	
DI25		$\overline{\text{MCLR}}$	0.8 V _{DD}	—	V _{DD}	V	
DI26		OSC1 (XT mode)	0.7 V _{DD}	—	V _{DD}	V	
DI27		OSC1 (HS mode)	0.7 V _{DD}	—	V _{DD}	V	
DI28		I/O Pins with I ² C Buffer: with Analog Functions, Digital Only	0.7 V _{DD} 0.7 V _{DD}	— —	V _{DD} 5.5	V V	
DI29		I/O Pins with SMBus Buffer: with Analog Functions, Digital Only	2.1 2.1	—	V _{DD} 5.5	V V	
DI30	ICNPU	CN_x Pull-up Current	50	250	400	μA	V _{DD} = 3.3V, V _{PIN} = V _{SS}
DI50	I _{IL}	Input Leakage Current^(2,3) I/O Ports	—	—	±50	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance
DI51		Analog Input Pins	—	—	±50	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance
DI52		USB Differential Pins (D+, D-)	—	—	±50	nA	V _{USB} ≥ V _{DD}
DI55		$\overline{\text{MCLR}}$	—	—	±50	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD}
DI56		OSC1	—	—	±50	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , XT and HS modes

Note 1: Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: The leakage current on the $\overline{\text{MCLR}}$ pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

3: Negative current is defined as current sourced by the pin.

4: Refer to Table 1-2 for I/O pins buffer types.

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TABLE 29-22: ADC MODULE SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended				
Param No.	Symbol	Characteristic	Min.	Typ	Max.	Units	Conditions
Device Supply							
AD01	AVDD	Module VDD Supply	Greater of $V_{DD} - 0.3$ or 2.0	—	Lesser of $V_{DD} + 0.3$ or 3.6	V	
AD02	AVSS	Module VSS Supply	$V_{SS} - 0.3$	—	$V_{SS} + 0.3$	V	
Reference Inputs							
AD05	VREFH	Reference Voltage High	$AV_{SS} + 1.7$	—	AVDD	V	
AD06	VREFL	Reference Voltage Low	AVSS	—	$AV_{DD} - 1.7$	V	
AD07	VREF	Absolute Reference Voltage	$AV_{SS} - 0.3$	—	$AV_{DD} + 0.3$	V	
AD08	IVREF	Reference voltage input current	—	—	1.25	mA	(Note 3)
AD09	ZVREF	Reference input impedance	—	10k	—	Ω	(Note 4)
Analog Input							
AD10	VINH-VINL	Full-Scale Input Span	VREFL	—	VREFH	V	(Note 2)
AD11	VIN	Absolute Input Voltage	$AV_{SS} - 0.3$	—	$AV_{DD} + 0.3$	V	
AD12	VINL	Absolute VINL Input Voltage	$AV_{SS} - 0.3$	—	$AV_{DD}/2$	V	
AD13	—	Leakage Current	—	± 0.001	± 0.610	μA	$V_{INL} = AV_{SS} = V_{REFL} = 0\text{V}$, $AV_{DD} = V_{REFH} = 3\text{V}$, Source Impedance = 2.5 k Ω
AD17	RIN	Recommended Impedance of Analog Voltage Source	—	—	2.5K	Ω	10-bit
ADC Accuracy							
AD20b	NR	Resolution	—	10	—	bits	
AD21b	INL	Integral Nonlinearity	—	± 1	$< \pm 2$	LSb	$V_{INL} = AV_{SS} = V_{REFL} = 0\text{V}$, $AV_{DD} = V_{REFH} = 3\text{V}$
AD22b	DNL	Differential Nonlinearity	—	± 0.5	$< \pm 1.25$	LSb	$V_{INL} = AV_{SS} = V_{REFL} = 0\text{V}$, $AV_{DD} = V_{REFH} = 3\text{V}$
AD23b	GERR	Gain Error	—	± 1	± 3	LSb	$V_{INL} = AV_{SS} = V_{REFL} = 0\text{V}$, $AV_{DD} = V_{REFH} = 3\text{V}$
AD24b	E _{OFF}	Offset Error	—	± 1	± 2	LSb	$V_{INL} = AV_{SS} = V_{REFL} = 0\text{V}$, $AV_{DD} = V_{REFH} = 3\text{V}$
AD25b	—	Monotonicity ⁽¹⁾	—	—	—	—	Guaranteed

Note 1: The ADC conversion result never decreases with an increase in the input voltage and has no missing codes.

2: Measurements taken with external VREF+ and VREF- are used as the ADC voltage reference.

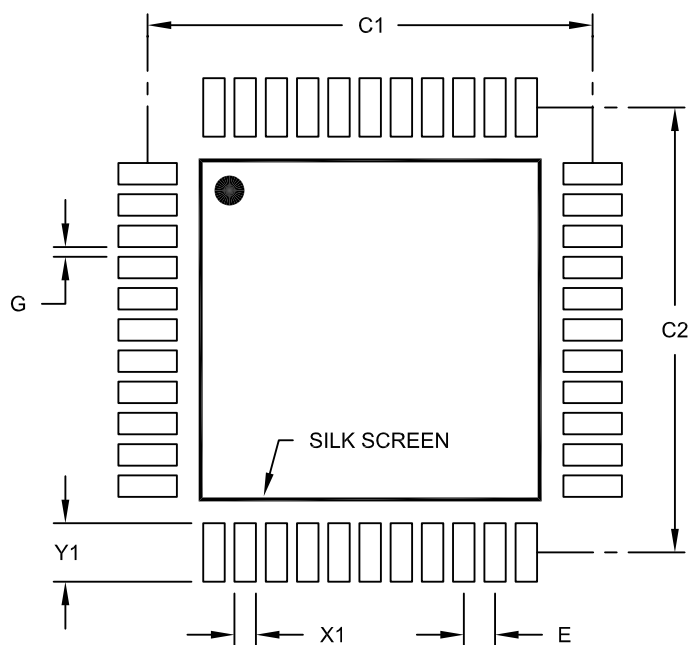
3: External reference voltage applied to VREF+/- pins. IVREF is current during conversion at 3.3v, 25C. Parameter is for design guidance only and is not tested.

4: Impedance during sampling at 3.3, 25C. Parameter is for design guidance only and is not tested.

PIC24FJ64GB004 FAMILY

44-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packages>



RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.80 BSC		
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X44)	X1			0.55
Contact Pad Length (X44)	Y1			1.50
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2076A