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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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#### Details

Product Status	Active
Core Processor	PIC
Core Size	16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	33
Program Memory Size	32KB (11K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 13x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic24fj32gb004-i-pt">https://www.e-xfl.com/product-detail/microchip-technology/pic24fj32gb004-i-pt</a>

# PIC24FJ64GB004 FAMILY

**TABLE 1-2: PIC24FJ64GB004 FAMILY PINOUT DESCRIPTIONS (CONTINUED)**

Function	Pin Number			I/O	Input Buffer	Description
	28-Pin SPDIP/ SOIC/SSOP	28-Pin QFN	44-Pin QFN/TQFP			
RP0	4	1	21	I/O	ST	Remappable Peripheral (input or output).
RP1	5	2	22	I/O	ST	
RP2	6	3	23	I/O	ST	
RP3	7	4	24	I/O	ST	
RP4	11	8	33	I/O	ST	
RP5	2	27	19	I/O	ST	
RP6	3	28	20	I/O	ST	
RP7	16	13	43	I/O	ST	
RP8	17	14	44	I/O	ST	
RP9	18	15	1	I/O	ST	
RP10	21	18	8	I/O	ST	
RP11	22	19	9	I/O	ST	
RP13	24	21	11	I/O	ST	
RP14	25	22	14	I/O	ST	
RP15	26	23	15	I/O	ST	
RP16	—	—	25	I/O	ST	
RP17	—	—	26	I/O	ST	
RP18	—	—	27	I/O	ST	
RP19	—	—	36	I/O	ST	
RP20	—	—	37	I/O	ST	
RP21	—	—	38	I/O	ST	
RP22	—	—	2	I/O	ST	
RP23	—	—	3	I/O	ST	
RP24	—	—	4	I/O	ST	
RP25	—	—	5	I/O	ST	
RTCC	7	4	24	O	—	Real-Time Clock Alarm/Seconds Pulse Output.
SESEND	24	21	11	I	ST	USB Vbus Session End Status Input.
SESSVLD	3	28	20	I	ST	USB Vbus Session Valid Status Input.
SCL1	17	14	44	I/O	I <sup>2</sup> C	I2C1 Synchronous Serial Clock Input/Output.
SCL2	7	4	24	I/O	I <sup>2</sup> C	I2C2 Synchronous Serial Clock Input/Output.
SDA1	18	15	1	I/O	I <sup>2</sup> C	I2C1 Data Input/Output.
SDA2	6	3	23	I/O	I <sup>2</sup> C	I2C2 Data Input/Output.
SOSCI	11	8	33	I	ANA	Secondary Oscillator/Timer1 Clock Input.
SOSCO	12	9	34	O	ANA	Secondary Oscillator/Timer1 Clock Output.
T1CK	12	9	34	I	ST	Timer1 Clock Input.
TCK	17	14	13	I	ST	JTAG Test Clock Input.
TDI	16	13	35	I	ST	JTAG Test Data Input.
TDO	18	15	32	O	—	JTAG Test Data Output.
TMS	14	11	12	I	ST	JTAG Test Mode Select Input.
USBID	14	11	41	I	ST	USB OTG ID (OTG mode only).
USBOEN	17	14	44	O	—	USB Output Enable Control (for external transceiver).

**Legend:** TTL = TTL input buffer  
ANA = Analog level input/output

ST = Schmitt Trigger input buffer  
I<sup>2</sup>C™ = I<sup>2</sup>C/SMBus input buffer

## 10.3 Input Change Notification

The input change notification function of the I/O ports allows the PIC24FJ64GB004 family of devices to generate interrupt requests to the processor in response to a change of state on selected input pins. This feature is capable of detecting input Change-of-States (COS) even in Sleep mode, when the clocks are disabled. Depending on the device pin count, there are up to 29 external inputs that may be selected (enabled) for generating an interrupt request on a Change-of-State.

Registers, CNEN1 and CNEN2, contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin has a weak pull-up connected to it. The pull-up acts as a current source that is connected to the pin. This eliminates the need for external resistors when push button or keypad devices are connected. The pull-ups are separately enabled using the CNPU1 and CNPU2 registers (for pull-ups). Each CN pin has individual control bits for its pull-up. Setting a control bit enables the weak pull-up for the corresponding pin.

When the internal pull-up is selected, the pin pulls up to VDD-0.7V (typical). Make sure that there is no external pull-up source when the internal pull-ups are enabled, as the voltage difference can cause a current path.

**Note:** Pull-ups on change notification pins should always be disabled whenever the port pin is configured as a digital output.

## 10.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. In an application that needs to use more than one peripheral multiplexed on a single pin, inconvenient work arounds in application code or a complete redesign may be the only option.

The Peripheral Pin Select feature provides an alternative to these choices by enabling the user's peripheral set selection and their placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of any one of many digital peripherals to any one of these I/O pins. Peripheral Pin Select is performed in software and generally does not require the device to be reprogrammed. Hardware

safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

### 10.4.1 AVAILABLE PINS

The Peripheral Pin Select feature is used with a range of up to 25 pins, depending on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the designation "RPn" in their full pin designation, where "n" is the remappable pin number.

See Table 1-2 for a summary of pinout options in each package offering.

### 10.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the Peripheral Pin Select are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer related peripherals (input capture and output compare) and external interrupt inputs. Also included are the outputs of the comparator module, since these are discrete digital signals.

Peripheral Pin Select is not available for I<sup>2</sup>C™ change notification inputs, RTCC alarm outputs or peripherals with analog inputs.

A key difference between pin select and non pin select peripherals is that pin select peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non pin select peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

#### 10.4.2.1 Peripheral Pin Select Function Priority

Pin-selectable peripheral outputs (for example, OC and UART transmit) take priority over any general purpose digital functions permanently tied to that pin, such as PMP and port I/O. Specialized digital outputs, such as USB functionality, take priority over PPS outputs on the same pin. The pin diagrams at the beginning of this data sheet list peripheral outputs in order of priority. Refer to them for priority concerns on a particular pin.

Unlike devices with fixed peripherals, pin-selectable peripheral inputs never take ownership of a pin. The pin's output buffer is controlled by the pin's TRIS bit setting, or by a fixed peripheral on the pin. If the pin is configured in Digital mode, then the PPS input will operate correctly, reading the input. If an analog function is enabled on the same pin, the pin-selectable input will be disabled.

# PIC24FJ64GB004 FAMILY

## EXAMPLE 10-2: CONFIGURING UART1 INPUT AND OUTPUT FUNCTIONS IN ASSEMBLY CODE

```
;unlock      registers
push        w1;
push        w2;
push        w3;
mov         #OSCCON, w1;
mov         #0x46, w2;
mov         #0x57, w3;
mov.b       w2, [w1];
mov.b       w3, [w1];
bclr        OSCCON, #6;

; Configure Input Functions (Table10-2)
; Assign U1CTS To Pin RP1, U1RX To Pin RP0
mov         #0x0100, w1;
mov         w1,RPINR18;

; Configure Output Functions (Table 10-3)
; Assign U1RTS To Pin RP3, U1TX To Pin RP2
mov         #0x0403, w1;
mov         w1, RPOR1;

;lock        registers
mov         #OSCCON, w1;
mov         #0x46, w2;
mov         #0x57, w3;
mov.b       w2, [w1];
mov.b       w3, [w1];
bset        OSCCON, #6;
pop         w3;
pop         w2;
pop         w1;
```

## EXAMPLE 10-3: CONFIGURING UART1 INPUT AND OUTPUT FUNCTIONS IN 'C'

```
//unlock registers
__builtin_write_OSCCONL(OSCCON & 0xBF);

// Configure Input Functions (Table 9-1)
// Assign U1RX To Pin RP0
RPINR18bits.U1RXR = 0;

// Assign U1CTS To Pin RP1
RPINR18bits.U1CTSR = 1;

// Configure Output Functions (Table 9-2)
// Assign U1TX To Pin RP2
RPOR1bits.RP2R = 3;

// Assign U1RTS To Pin RP3
RPOR1bits.RP3R = 4;

//lock registers
__builtin_write_OSCCONL(OSCCON | 0x40);
```

# PIC24FJ64GB004 FAMILY

## REGISTER 10-19: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP9R<4:0>:** RP9 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP9 (see Table 10-3 for peripheral function numbers).
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP8R<4:0>:** RP8 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP8 (see Table 10-3 for peripheral function numbers).

## REGISTER 10-20: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0
bit 7							bit 0

### Legend:

R = Readable bit      W = Writable bit      U = Unimplemented bit, read as '0'  
-n = Value at POR      '1' = Bit is set      '0' = Bit is cleared      x = Bit is unknown

- bit 15-13      **Unimplemented:** Read as '0'
- bit 12-8      **RP11R<4:0>:** RP11 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP11 (see Table 10-3 for peripheral function numbers).
- bit 7-5      **Unimplemented:** Read as '0'
- bit 4-0      **RP10R<4:0>:** RP10 Output Pin Mapping bits  
Peripheral output number n is assigned to pin, RP10 (see Table 10-3 for peripheral function numbers).

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**REGISTER 12-2: TyCON: TIMER3 AND TIMER5 CONTROL REGISTER<sup>(3)</sup>**

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON <sup>(1)</sup>	—	TSIDL <sup>(1)</sup>	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
—	TGATE <sup>(1)</sup>	TCKPS1 <sup>(1)</sup>	TCKPS0 <sup>(1)</sup>	—	—	TCS <sup>(1,2)</sup>	—
bit 7							bit 0

**Legend:**

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **TON:** Timery On bit<sup>(1)</sup>  
1 = Starts 16-bit Timery  
0 = Stops 16-bit Timery
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **TSIDL:** Stop in Idle Mode bit<sup>(1)</sup>  
1 = Discontinue module operation when device enters Idle mode  
0 = Continue module operation in Idle mode
- bit 12-7 **Unimplemented:** Read as '0'
- bit 6 **TGATE:** Timery Gated Time Accumulation Enable bit<sup>(1)</sup>  
When TCS = 1:  
This bit is ignored.  
When TCS = 0:  
1 = Gated time accumulation enabled  
0 = Gated time accumulation disabled
- bit 5-4 **TCKPS<1:0>:** Timery Input Clock Prescale Select bits<sup>(1)</sup>  
11 = 1:256  
10 = 1:64  
01 = 1:8  
00 = 1:1
- bit 3-2 **Unimplemented:** Read as '0'
- bit 1 **TCS:** Timery Clock Source Select bit<sup>(1,2)</sup>  
1 = External clock from pin TyCK (on the rising edge)  
0 = Internal clock (Fosc/2)
- bit 0 **Unimplemented:** Read as '0'

**Note 1:** When 32-bit operation is enabled (T2CON<3> or T4CON<3> = 1), these bits have no effect on Timery operation; all timer functions are set through T2CON and T4CON.

**2:** If TCS = 1, RPINRx (TxCK) must be configured to an available RPn pin. See **Section 10.4 “Peripheral Pin Select (PPS)”** for more information.

**3:** Changing the value of TyCON while the timer is running (TON = 1) causes the timer prescale counter to reset and is not recommended.

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## 17.1 UART Baud Rate Generator (BRG)

The UART module includes a dedicated 16-bit Baud Rate Generator. The UxBRG register controls the period of a free-running, 16-bit timer. Equation 17-1 shows the formula for computation of the baud rate with BRGH = 0.

### EQUATION 17-1: UART BAUD RATE WITH BRGH = 0<sup>(1,2)</sup>

$$\text{Baud Rate} = \frac{\text{FCY}}{16 \cdot (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{\text{FCY}}{16 \cdot \text{Baud Rate}} - 1$$

- Note 1:** FCY denotes the instruction cycle clock frequency (FOSC/2).
- 2:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

Example 17-1 shows the calculation of the baud rate error for the following conditions:

- FCY = 4 MHz
- Desired Baud Rate = 9600

The maximum baud rate (BRGH = 0) possible is FCY/16 (for UxBRG = 0) and the minimum baud rate possible is FCY/(16 \* 65536).

Equation 17-2 shows the formula for computation of the baud rate with BRGH = 1.

### EQUATION 17-2: UART BAUD RATE WITH BRGH = 1<sup>(1,2)</sup>

$$\text{Baud Rate} = \frac{\text{FCY}}{4 \cdot (\text{UxBRG} + 1)}$$

$$\text{UxBRG} = \frac{\text{FCY}}{4 \cdot \text{Baud Rate}} - 1$$

- Note 1:** FCY denotes the instruction cycle clock frequency.
- 2:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

The maximum baud rate (BRGH = 1) possible is FCY/4 (for UxBRG = 0) and the minimum baud rate possible is FCY/(4 \* 65536).

Writing a new value to the UxBRG register causes the BRG timer to be reset (cleared). This ensures the BRG does not wait for a timer overflow before generating the new baud rate.

### EXAMPLE 17-1: BAUD RATE ERROR CALCULATION (BRGH = 0)<sup>(1)</sup>

$$\text{Desired Baud Rate} = \text{FCY}/(16 (\text{UxBRG} + 1))$$

Solving for UxBRG Value:

$$\text{UxBRG} = ((\text{FCY}/\text{Desired Baud Rate})/16) - 1$$

$$\text{UxBRG} = ((4000000/9600)/16) - 1$$

$$\text{UxBRG} = 25$$

$$\begin{aligned}\text{Calculated Baud Rate} &= 4000000/(16 (25 + 1)) \\ &= 9615\end{aligned}$$

$$\begin{aligned}\text{Error} &= (\text{Calculated Baud Rate} - \text{Desired Baud Rate}) / \text{Desired Baud Rate} \\ &= (9615 - 9600)/9600 \\ &= 0.16\%\end{aligned}$$

- Note 1:** Based on FCY = FOSC/2, Doze mode and PLL are disabled.

# PIC24FJ64GB004 FAMILY

## REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	R/W-0, HC	R/W-0	R-0	R-1
UTXISEL1	UTXINV <sup>(1)</sup>	UTXISEL0	—	UTXBRK	UTXEN <sup>(2)</sup>	UTXBF	TRMT
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-1	R-0	R-0	R/C-0	R-0
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

<b>Legend:</b>	C = Clearable bit	HC = Hardware Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 15,13 **UTXISEL<1:0>**: Transmission Interrupt Mode Selection bits  
 11 = Reserved; do not use  
 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR), and as a result, the transmit buffer becomes empty  
 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed  
 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)
- bit 14 **UTXINV**: IrDA<sup>®</sup> Encoder Transmit Polarity Inversion bit<sup>(1)</sup>  
**IREN = 0:**  
 1 = UxTX Idle '0'  
 0 = UxTX Idle '1'  
**IREN = 1:**  
 1 = UxTX Idle '1'  
 0 = UxTX Idle '0'
- bit 12 **Unimplemented**: Read as '0'
- bit 11 **UTXBRK**: Transmit Break bit  
 1 = Send Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion  
 0 = Sync Break transmission disabled or completed
- bit 10 **UTXEN**: Transmit Enable bit<sup>(2)</sup>  
 1 = Transmit enabled, UxTX pin controlled by UARTx  
 0 = Transmit disabled, any pending transmission is aborted and the buffer is reset; UxTX pin controlled by port
- bit 9 **UTXBF**: Transmit Buffer Full Status bit (read-only)  
 1 = Transmit buffer is full  
 0 = Transmit buffer is not full; at least one more character can be written
- bit 8 **TRMT**: Transmit Shift Register Empty bit (read-only)  
 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)  
 0 = Transmit Shift Register is not empty, a transmission is in progress or queued
- bit 7-6 **URXISEL<1:0>**: Receive Interrupt Mode Selection bits  
 11 = Interrupt is set on RSR transfer, making the receive buffer full (i.e., has 4 data characters)  
 10 = Interrupt is set on RSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters)  
 0x = Interrupt is set when any character is received and transferred from the RSR to the receive buffer; receive buffer has one or more characters

**Note 1:** Value of bit only affects the transmit properties of the module when the IrDA encoder is enabled (IREN = 1).

**Note 2:** If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. See **Section 10.4 “Peripheral Pin Select (PPS)”** for more information.



# PIC24FJ64GB004 FAMILY

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NOTES:

# PIC24FJ64GB004 FAMILY

## 18.1.2 HOST AND OTG MODES

### 18.1.2.1 D+ and D- Pull-down Resistors

PIC24FJ64GB004 family devices have built-in 15 k $\Omega$  pull-down resistor on the D+ and D- lines. These are used in tandem to signal to the bus that the microcontroller is operating in Host mode. They are engaged by setting the HOSTEN bit (U1CON<3>). If the OTGEN bit (U1OTGCON<2>) is set, then these pull-downs are enabled by setting the DPPULDWN and DMPULDWN bits (U1OTGCON<5:4>).

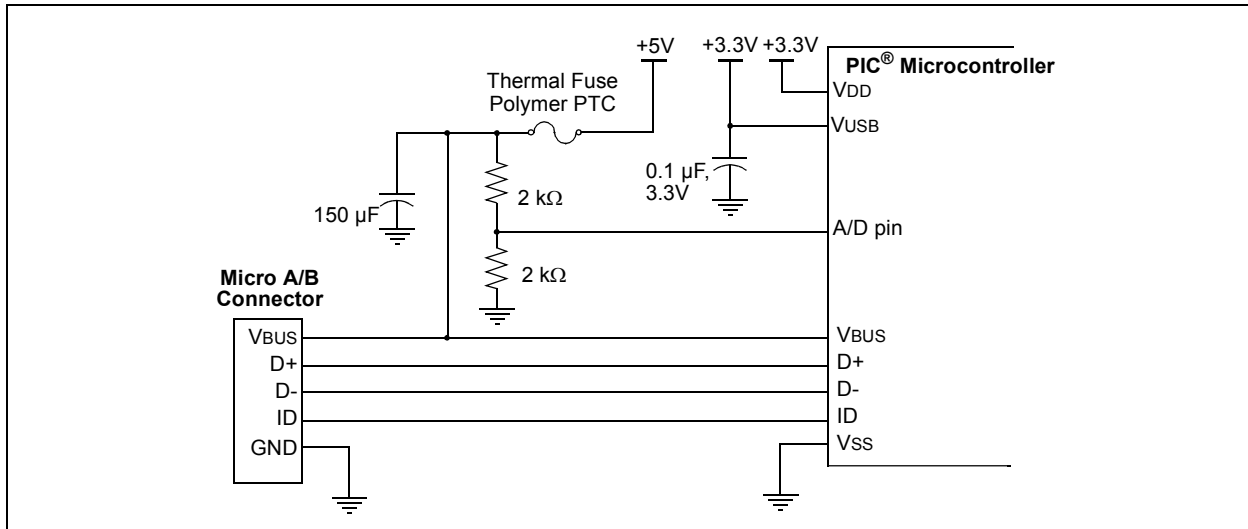
### 18.1.2.2 Power Configurations

In Host mode, as well as Host mode in On-the-Go operation, the USB 2.0 specification requires that the Host application supply power on VBUS. Since the

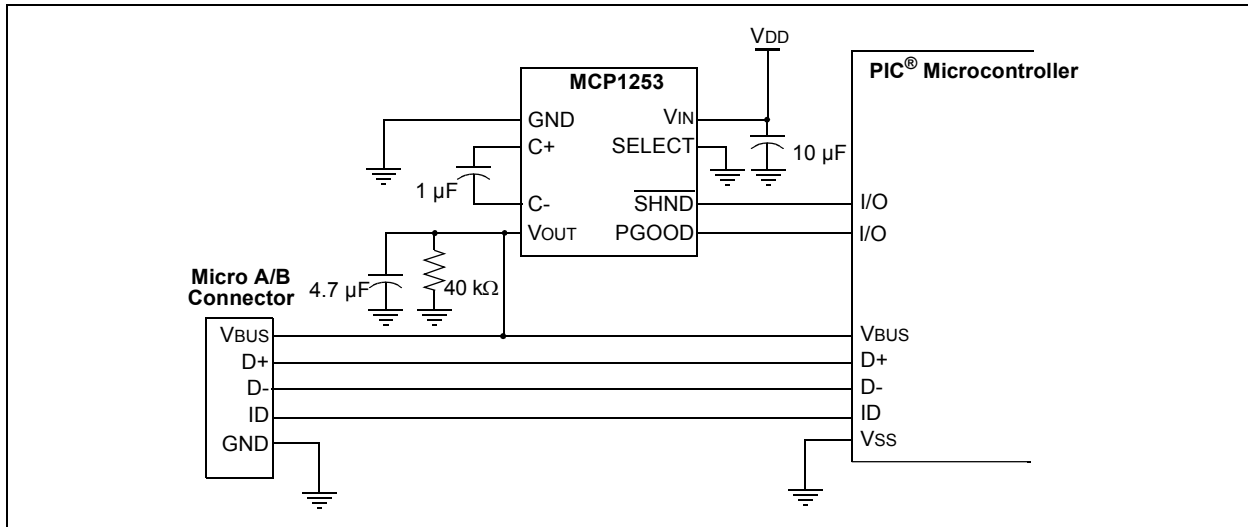
microcontroller is running below VBUS and is not able to source sufficient current, a separate power supply must be provided.

When the application is always operating in Host mode, a simple circuit can be used to supply VBUS and regulate current on the bus (Figure 18-6). For OTG operation, it is necessary to be able to turn VBUS on or off as needed, as the microcontroller switches between Device and Host modes. A typical example using an external charge pump is shown in Figure 18-7.

**FIGURE 18-6: HOST INTERFACE EXAMPLE**



**FIGURE 18-7: OTG INTERFACE EXAMPLE**



# PIC24FJ64GB004 FAMILY

## REGISTER 18-11: U1SOF: USB OTG START-OF-TOKEN THRESHOLD REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNT7	CNT6	CNT5	CNT4	CNT3	CNT2	CNT1	CNT0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **CNT<7:0>:** Start-of-Frame Size bits;  
Value represents 10 + (packet size of n bytes). For example:

0100 1010 = 64-byte packet

0010 1010 = 32-byte packet

0001 0010 = 8-byte packet

## REGISTER 18-12: U1CNFG1: USB CONFIGURATION REGISTER 1

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0
UTEYE	UOEMON <sup>(1)</sup>	—	USBSIDL	—	—	PPB1	PPB0
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7 **UTEYE:** USB Eye Pattern Test Enable bit

1 = Eye pattern test is enabled

0 = Eye pattern test is disabled

bit 6 **UOEMON:** USB  $\overline{OE}$  Monitor Enable bit<sup>(1)</sup>

1 =  $\overline{OE}$  signal is active; it indicates the intervals during which the D+/D- lines are driving

0 =  $\overline{OE}$  signal is inactive

bit 5 **Unimplemented:** Read as '0'

bit 4 **USBSIDL:** USB OTG Stop in Idle Mode bit

1 = Discontinue module operation when device enters Idle mode

0 = Continue module operation in Idle mode

bit 3-2 **Unimplemented:** Read as '0'

**Note 1:** This bit is only active when the UTRDIS bit (U1CNFG2<0>) is set.

# PIC24FJ64GB004 FAMILY

## 18.7.2 USB INTERRUPT REGISTERS

### REGISTER 18-14: U1OTGIR: USB OTG INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	U-0	R/K-0, HS
IDIF	T1MSECIF	LSTATEIF	ACTVIF	SESVDIF	SESENDIF	—	VBUSVDIF
bit 7							bit 0

<b>Legend:</b>	U = Unimplemented bit, read as '0'		
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15-8 **Unimplemented:** Read as '0'
- bit 7 **IDIF:** ID State Change Indicator bit  
 1 = Change in ID state is detected  
 0 = No ID state change
- bit 6 **T1MSECIF:** 1 Millisecond Timer bit  
 1 = The 1 millisecond timer has expired  
 0 = The 1 millisecond timer has not expired
- bit 5 **LSTATEIF:** Line State Stable Indicator bit  
 1 = USB line state (as defined by the SE0 and JSTATE bits) has been stable for 1 ms, but different from last time  
 0 = USB line state has not been stable for 1 ms
- bit 4 **ACTVIF:** Bus Activity Indicator bit  
 1 = Activity on the D+/D- lines or VBUS is detected  
 0 = No activity on the D+/D- lines or VBUS is detected
- bit 3 **SESVDIF:** Session Valid Change Indicator bit  
 1 = VBUS has crossed VA\_SESS\_END (as defined in the USB OTG Specification)<sup>(1)</sup>  
 0 = VBUS has not crossed VA\_SESS\_END
- bit 2 **SESENDIF:** B-Device VBUS Change Indicator bit  
 1 = VBUS change on B-device is detected; VBUS has crossed VB\_SESS\_END (as defined in the USB OTG Specification)<sup>(1)</sup>  
 0 = VBUS has not crossed VA\_SESS\_END
- bit 1 **Unimplemented:** Read as '0'
- bit 0 **VBUSVDIF:** A-Device VBUS Change Indicator bit  
 1 = VBUS change on A-device is detected; VBUS has crossed VA\_VBUS\_VLD (as defined in the USB OTG Specification)<sup>(1)</sup>  
 0 = No VBUS change on A-device is detected

**Note 1:** VBUS threshold crossings may be either rising or falling.

**Note:** Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

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## REGISTER 19-1: PMCON: PARALLEL PORT CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PMPEN	—	PSIDL	ADMUX1 <sup>(1)</sup>	ADMUX0 <sup>(1)</sup>	PTBEEN	PTWREN	PTRDEN
bit 15							bit 8

R/W-0	R/W-0	R/W-0 <sup>(2)</sup>	U-0	R/W-0 <sup>(2)</sup>	R/W-0	R/W-0	R/W-0
CSF1	CSF0	ALP	—	CS1P	BEP	WRSP	RDSP
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **PMPEN:** Parallel Master Port Enable bit  
 1 = PMP is enabled  
 0 = PMP is disabled, no off-chip access performed
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **PSIDL:** Stop in Idle Mode bit  
 1 = Discontinue module operation when device enters Idle mode  
 0 = Continue module operation in Idle mode
- bit 12-11 **ADMUX<1:0>:** Address/Data Multiplexing Selection bits<sup>(1)</sup>  
 11 = Reserved  
 10 = All 16 bits of address are multiplexed on PMD<7:0> pins  
 01 = Lower 8 bits of address are multiplexed on PMD<7:0> pins; upper 3 bits are multiplexed on PMA<10:8>  
 00 = Address and data appear on separate pins
- bit 10 **PTBEEN:** Byte Enable Port Enable bit (16-Bit Master mode)  
 1 = PMBE port is enabled  
 0 = PMBE port is disabled
- bit 9 **PTWREN:** Write Enable Strobe Port Enable bit  
 1 = PMWR/PMENB port is enabled  
 0 = PMWR/PMENB port is disabled
- bit 8 **PTRDEN:** Read/Write Strobe Port Enable bit  
 1 = PMRD/PMWR port is enabled  
 0 = PMRD/PMWR port is disabled
- bit 7-6 **CSF<1:0>:** Chip Select Function bits  
 11 = Reserved  
 10 = PMCS1 functions as chip set  
 01 = Reserved  
 00 = Reserved
- bit 5 **ALP:** Address Latch Polarity bit<sup>(2)</sup>  
 1 = Active-high (PMALL and PMALH)  
 0 = Active-low (PMALL and PMALH)
- bit 4 **Unimplemented:** Read as '0'
- bit 3 **CS1P:** Chip Select 1 Polarity bit<sup>(2)</sup>  
 1 = Active-high (PMCS1/PMCS1)  
 0 = Active-low (PMCS1/PMCS1)

**Note 1:** PMA<10:2> bits are not available on 28-pin devices.

**2:** These bits have no effect when their corresponding pins are used as address lines.

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## REGISTER 19-6: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	RTSECSEL1 <sup>(1)</sup>	RTSECSEL0 <sup>(1)</sup>	PMPTTL
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-3 **Unimplemented:** Read as '0'

bit 2-1 **RTSECSEL<1:0>:** RTCC Seconds Clock Output Select bits<sup>(1)</sup>

11 = Reserved; do not use

10 = RTCC source clock is selected for the RTCC pin (clock can be LPRC or SOSC, depending on the setting of the Flash Configuration bit, RTCOSC (CW4<5>))

01 = RTCC seconds clock is selected for the RTCC pin

00 = RTCC alarm pulse is selected for the RTCC pin

bit 0 **PMPTTL:** PMP Module TTL Input Buffer Select bit

1 = PMP module uses TTL input buffers

0 = PMP module uses Schmitt Trigger input buffers

**Note 1:** To enable the actual RTCC output, the RTCOE (RCFGCAL<10>) bit needs to be set.

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## REGISTER 21-1: CRCCON1: CRC CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R-0	R-0	R-0	R-0	R-0
CRCEN	—	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0
bit 15							bit 8

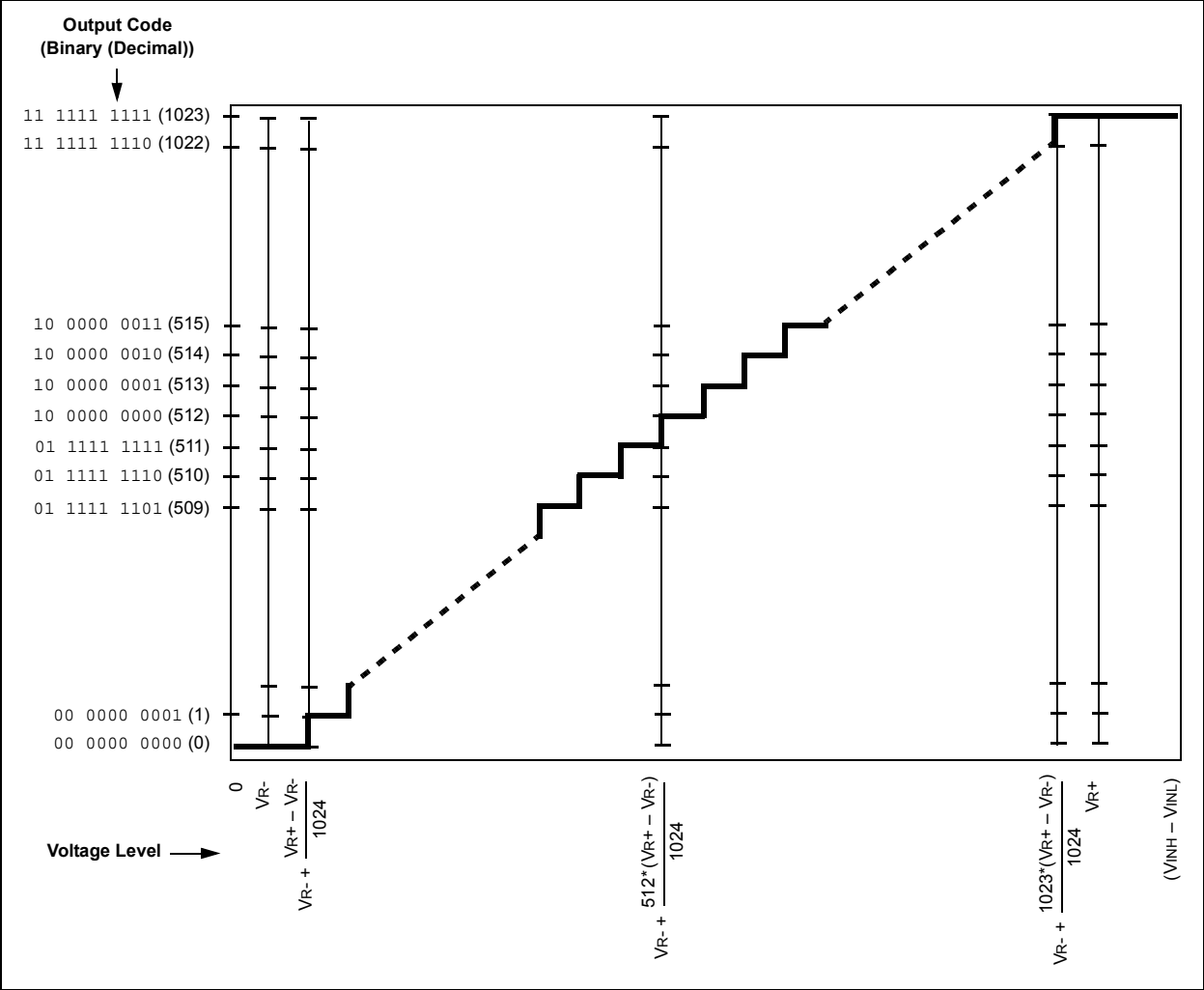
R-0, HCS	R-1, HCS	R/W-0	R/W-0, HC	R/W-0	U-0	U-0	U-0
CRCFUL	CRCMPT	CRCISEL	CRCGO	LENDIAN	—	—	—
bit 7							bit 0

<b>Legend:</b>	HC = Hardware Clearable bit	HCS = Hardware Clearable/Settable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 15      **CRCEN:** CRC Enable bit  
1 = Module is enabled  
0 = Module is enabled. All state machines, pointers and CRCWDAT/CRCDAT are reset; other SFRs are NOT reset
- bit 14      **Unimplemented:** Read as '0'
- bit 13      **CSIDL:** CRC Stop in Idle Mode bit  
1 = Discontinue module operation when device enters Idle mode  
0 = Continue module operation in Idle mode
- bit 12-8    **VWORD<4:0>:** Pointer Value bits  
Indicates the number of valid words in the FIFO. Has a maximum value of 8 when PLEN<3:0> > 7 or 16 when PLEN<3:0> ≤ 7.
- bit 7      **CRCFUL:** FIFO Full bit  
1 = FIFO is full  
0 = FIFO is not full
- bit 6      **CRCMPT:** FIFO Empty Bit  
1 = FIFO is empty  
0 = FIFO is not empty
- bit 5      **CRCISEL:** CRC interrupt Selection bit  
1 = Interrupt on FIFO is empty; CRC calculation is not complete  
0 = Interrupt on shift is complete and CRCWDAT result is ready
- bit 4      **CRCGO:** Start CRC bit  
1 = Start CRC serial shifter  
0 = CRC serial shifter is turned off
- bit 3      **LENDIAN:** Data Shift Direction Select bit  
1 = Data word is shifted into the CRC starting with the LSb (little endian)  
0 = Data word is shifted into the CRC starting with the MSb (big endian)
- bit 2-0    **Unimplemented:** Read as '0'

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FIGURE 22-3: A/D TRANSFER FUNCTION





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## 25.2 Measuring Time

Time measurements on the pulse width can be similarly performed using the A/D module's internal capacitor (CAD) and a precision resistor for current calibration. Figure 25-2 shows the external connections used for time measurements, and how the CTMU and A/D modules are related in this application. This example also shows both edge events coming from the external CTEDG pins, but other configurations using internal edge sources are possible. For the smallest time measurements, select the internal A/D Channel 31, CH0S<4:0> = 11111. This minimizes any stray capacitance that may otherwise be associated with using an input pin, thus keeping the total capacitance to that of the A/D Converter itself (4-5 pF). A detailed discussion on measuring capacitance and time with the CTMU module is provided in the "PIC24F Family Reference Manual".

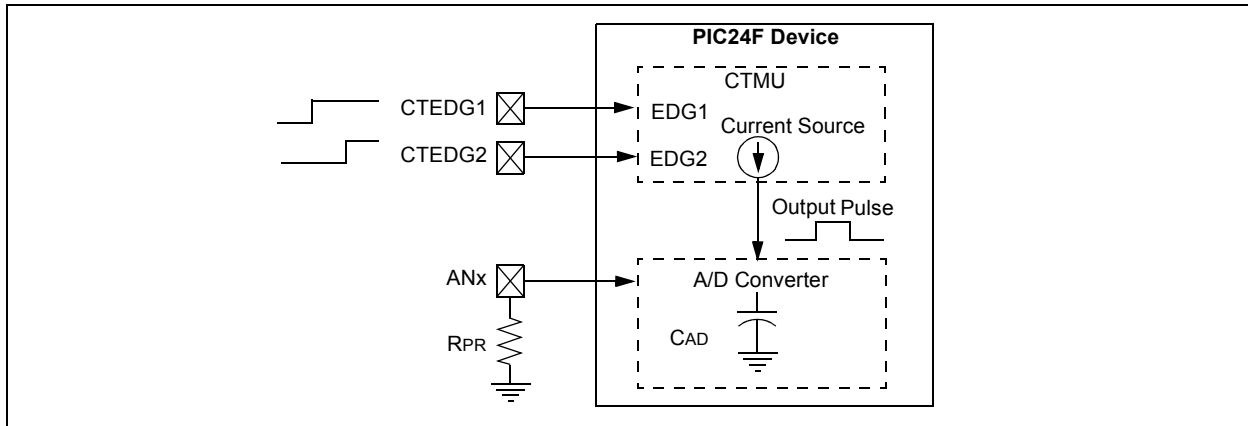
## 25.3 Pulse Generation and Delay

The CTMU module can also generate an output pulse with edges that are not synchronous with the device's system clock. More specifically, it can generate a pulse with a programmable delay from an edge event input to the module.

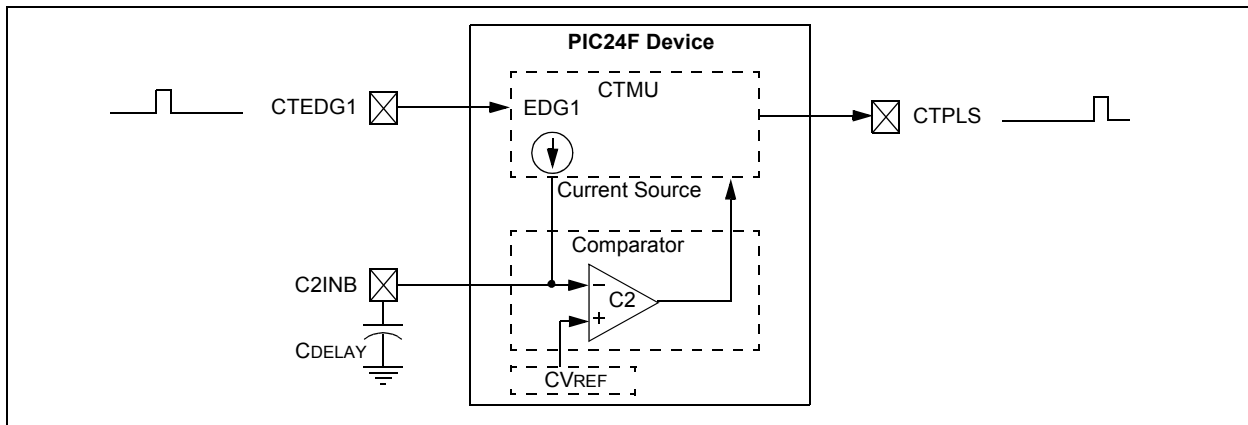
When the module is configured for pulse generation delay by setting the TGEN bit (CTMUCON<12>), the internal current source is connected to the B input of Comparator 2. A capacitor (CDELAY) is connected to the Comparator 2 pin, C2INB, and the comparator voltage reference, CVREF, is connected to C2INA. CVREF is then configured for a specific trip point. The module begins to charge CDELAY when an edge event is detected. When CDELAY charges above the CVREF trip point, a pulse is output on CTPLS. The length of the pulse delay is determined by the value of CDELAY and the CVREF trip point.

Figure 25-3 shows the external connections for pulse generation, as well as the relationship of the different analog modules required. While CTEDG1 is shown as the input pulse source, other options are available. A detailed discussion on pulse generation with the CTMU module is provided in the "PIC24F Family Reference Manual".

**FIGURE 25-2: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR TIME MEASUREMENT**



**FIGURE 25-3: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR PULSE DELAY GENERATION**



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## REGISTER 25-1: CTMUCON: CTMU CONTROL REGISTER (CONTINUED)

bit 3-2 **EDG1SEL<1:0>**: Edge 1 Source Select bits

11 = CTED1 pin  
10 = CTED2 pin  
01 = OC1 module  
00 = Timer1 module

bit 1 **EDG2STAT**: Edge 2 Status bit

1 = Edge 2 event has occurred  
0 = Edge 2 event has not occurred

bit 0 **EDG1STAT**: Edge 1 Status bit

1 = Edge 1 event has occurred  
0 = Edge 1 event has not occurred

**Note 1:** If TGEN = 1, the peripheral inputs and outputs must be configured to an available RPN pin. For more information, see **Section 10.4 “Peripheral Pin Select (PPS)”**.

## REGISTER 25-2: CTMUICON: CTMU CURRENT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15						bit 8	

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7						bit 0	

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-10 **ITRIM<5:0>**: Current Source Trim bits

011111 = Maximum positive change from nominal current  
011110

.....

000001 = Minimum positive change from nominal current

000000 = Nominal current output specified by IRNG<1:0>

111111 = Minimum negative change from nominal current

.....

100010

100001 = Maximum negative change from nominal current

bit 9-8 **IRNG<1:0>**: Current Source Range Select bits

11 = 100 × Base Current

10 = 10 × Base Current

01 = Base current level (0.55 μA nominal)

00 = Current source disabled

bit 7-0 **Unimplemented**: Read as '0'

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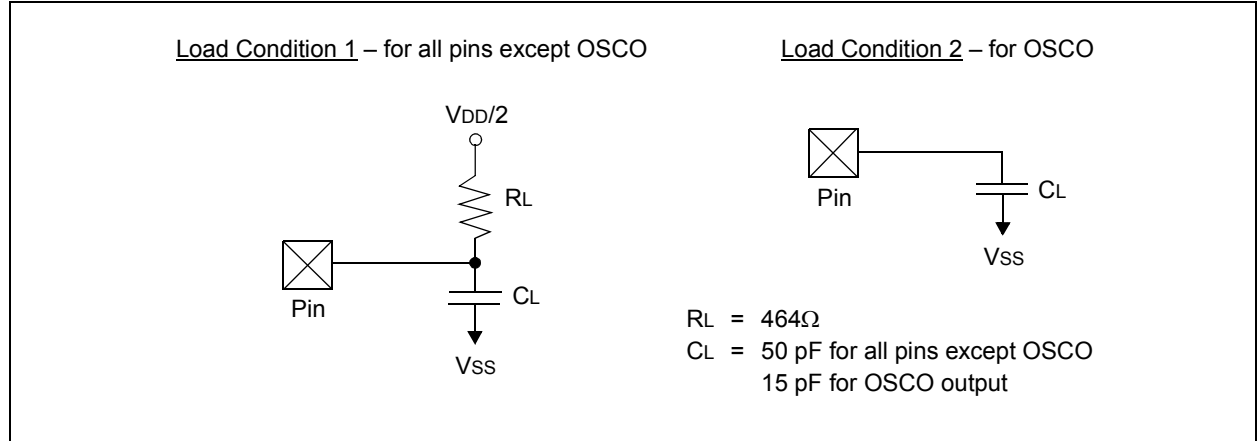
## 29.2 AC Characteristics and Timing Parameters

The information contained in this section defines the PIC24FJ64GB004 family AC characteristics and timing parameters.

**TABLE 29-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

<b>AC CHARACTERISTICS</b>	<b>Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated)</b>
	Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial and
	$-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended
	Operating voltage $V_{DD}$ range as described in <b>Section 29.1 “DC Characteristics”</b> .

**FIGURE 29-3: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**



**TABLE 29-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

Param No.	Symbol	Characteristic	Min	Typ <sup>(1)</sup>	Max	Units	Conditions
DO50	Cosc2	OSCO/CLKO Pin	—	—	15	pF	In XT and HS modes when external clock is used to drive OSCI.
DO56	Cio	All I/O Pins and OSCO	—	—	50	pF	EC mode.
DO58	Cb	SCLx, SDAx	—	—	400	pF	In I <sup>2</sup> C™ mode.

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

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**TABLE 29-23: ADC CONVERSION TIMING REQUIREMENTS<sup>(1)</sup>**

AC CHARACTERISTICS			Standard Operating Conditions: 2.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ	Max.	Units	Conditions
<b>Clock Parameters</b>							
AD50	TAD	ADC Clock Period	75	—	—	ns	Tcy = 75 ns, AD1CON3 in default state
AD51	tRC	ADC Internal RC Oscillator Period	—	250	—	ns	
<b>Conversion Rate</b>							
AD55	tCONV	Conversion Time	—	12	—	TAD	
AD56	FCNV	Throughput Rate	—	—	500	ksps	AVDD > 2.7V
AD57	tSAMP	Sample Time	—	1	—	TAD	
<b>Clock Parameters</b>							
AD61	tPSS	Sample Start Delay from setting Sample bit (SAMP)	2	—	3	TAD	

**Note 1:** Because the sample capacitors will eventually lose charge, clock rates below 10 kHz can affect linearity performance, especially at elevated temperatures.

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RTCC		Universal Asynchronous Receiver Transmitter. See UART.	
Alarm Configuration .....	250	Universal Serial Bus	
Alarm Mask Settings (figure).....	251	Buffer Descriptors	
Calibration .....	250	Assignment in Different Buffering Modes .....	203
Register Mapping .....	242	Interrupts	
Selecting Clock Source .....	242	and USB Transactions.....	207
Source Clock.....	241	Universal Serial Bus. See USB OTG.	
Write Lock .....	242	USB On-The-Go (OTG).....	10
<b>S</b>		USB OTG	
Selective Peripheral Power Control .....	125	Buffer Descriptors and BDT.....	202
Serial Peripheral Interface. See SPI.		Device Mode Operation .....	207
SFR Space.....	34	DMA Interface.....	203
Software Simulator (MPLAB SIM).....	295	Hardware Configuration	
Software Stack.....	50	Device Mode.....	199
Special Features .....	10	External Interface .....	201
SPI		Host and OTG Modes.....	200
<b>T</b>		Transceiver Power Requirements .....	201
Timer1 .....	149	VBUS Voltage Generation .....	201
Timer2/3 and Timer4/5.....	151	Host Mode Operation .....	208
Timing Diagrams		Interrupts .....	206
CLKO and I/O Timing.....	322	OTG Operation .....	210
External Clock .....	320	Registers .....	212–230
Trap Service Routine (TSR).....	106	VBUS Voltage Generation .....	201
Triple Comparator .....	269	<b>V</b>	
<b>U</b>		VDDCORE/VCAP Pin .....	287
UART .....	189	<b>W</b>	
Baud Rate Generator (BRG).....	190	Watchdog Timer (WDT).....	288
IrDA Support .....	191	Control Register.....	289
Operation of $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ Pins .....	191	Windowed Operation .....	289
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8-Bit or 9-Bit Data Mode .....	191	WWW, On-Line Support .....	8
Transmitting			
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9-Bit Data Mode .....	191		
Break and Sync Sequence .....	191		