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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	20MHz
Connectivity	-
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 11x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1903t-i-ml

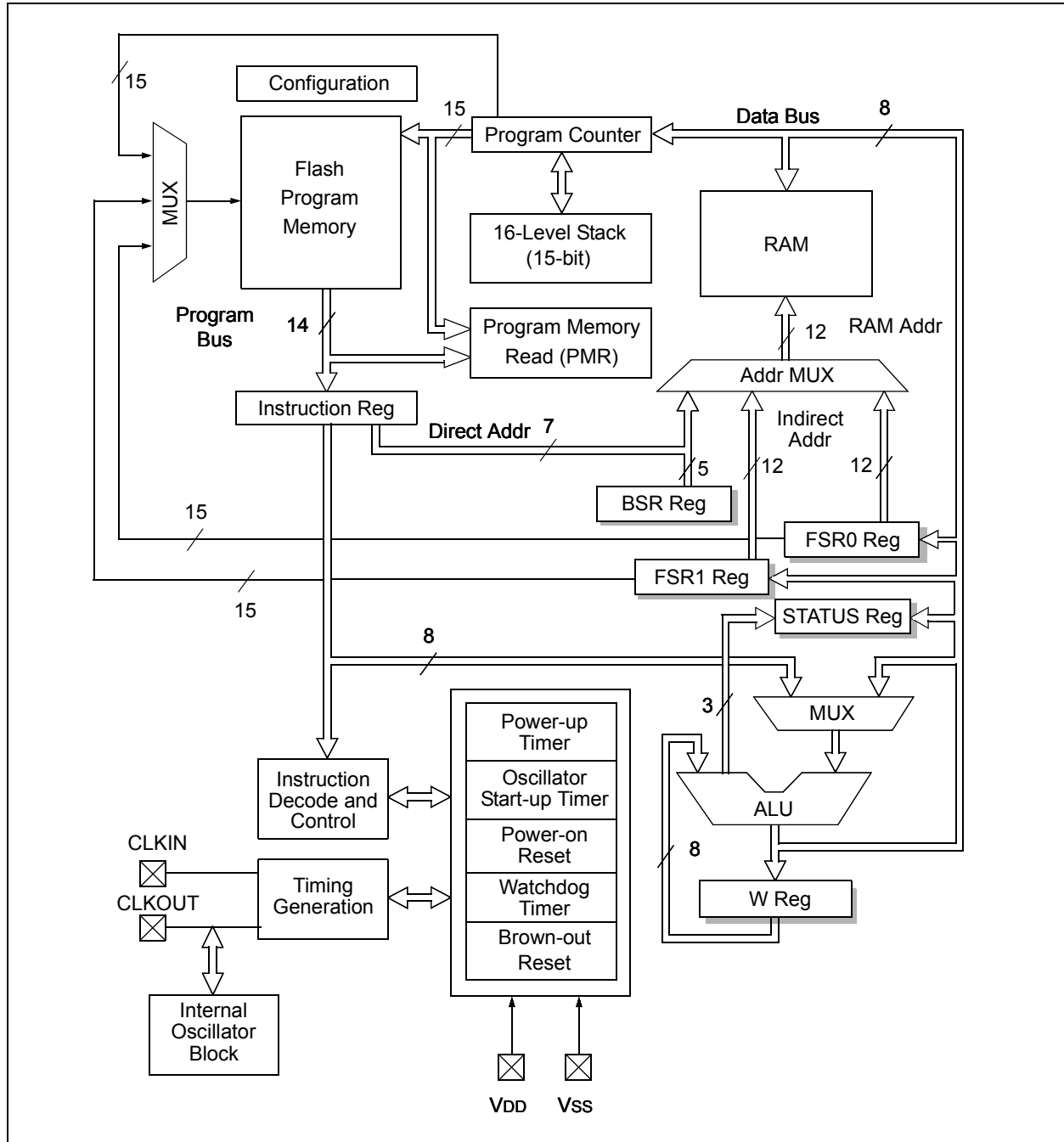
TABLE 1-2: PIC16LF1902/3 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RB4 ⁽¹⁾ /AN11/COM0	RB4	TTL	CMOS	General purpose I/O.
	AN11	AN	—	A/D Channel 11 input.
	COM0	—	AN	LCD Analog output.
RB5 ⁽¹⁾ /AN13/COM1	RB5	TTL	CMOS	General purpose I/O.
	AN13	AN	—	A/D Channel 13 input.
	COM1	—	AN	LCD Analog output.
RB6 ⁽¹⁾ /ICSPCLK/SEG14	RB6	TTL	CMOS	General purpose I/O.
	ICSPCLK	ST	—	Serial Programming Clock.
	SEG14	—	AN	LCD Analog output.
RB7 ⁽¹⁾ /ICSPDAT/SEG13	RB7	TTL	CMOS	General purpose I/O.
	ICSPDAT	ST	CMOS	ICSP™ Data I/O.
	SEG13	—	AN	LCD Analog output.
RC0/T1OSO/T1CKI	RC0	TTL	CMOS	General purpose I/O.
	T1OSO	XTAL	XTAL	Timer1 oscillator connection.
	T1CKI	ST	—	Timer1 clock input.
RC1/T1OSI	RC1	TTL	CMOS	General purpose I/O.
	T1OSI	XTAL	XTAL	Timer1 oscillator connection.
RC2/SEG3	RC2	TTL	CMOS	General purpose I/O.
	SEG3	—	AN	LCD Analog output.
RC3/SEG6	RC3	TTL	CMOS	General purpose I/O.
	SEG6	—	AN	LCD Analog output.
RC4/T1G/SEG11	RC4	TTL	CMOS	General purpose I/O.
	T1G	XTAL	XTAL	Timer1 oscillator connection.
	SEG11	—	AN	LCD Analog output.
RC5/SEG10	RC5	TTL	CMOS	General purpose I/O.
	SEG10	—	AN	LCD Analog output.
RC6/SEG9	RC6	ST	CMOS	General purpose I/O.
	SEG9	—	AN	LCD Analog output.
RC7/SEG8	RC7	ST	CMOS	General purpose I/O.
	SEG8	—	AN	LCD Analog output.
RE3/MCLR/VPP	RE3	TTL	CMOS	General purpose I/O.
	MCLR	ST	—	Master Clear with internal pull-up.
	VPP	HV	—	Programming voltage.
VDD	VDD	Power	—	Positive supply.
VSS	VSS	Power	—	Ground reference.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open-Drain
TTL = TTL compatible input ST = Schmitt Trigger input with CMOS levels I²C = Schmitt Trigger input with I²C levels
HV = High Voltage XTAL = Crystal

Note 1: These pins have interrupt-on-change functionality.

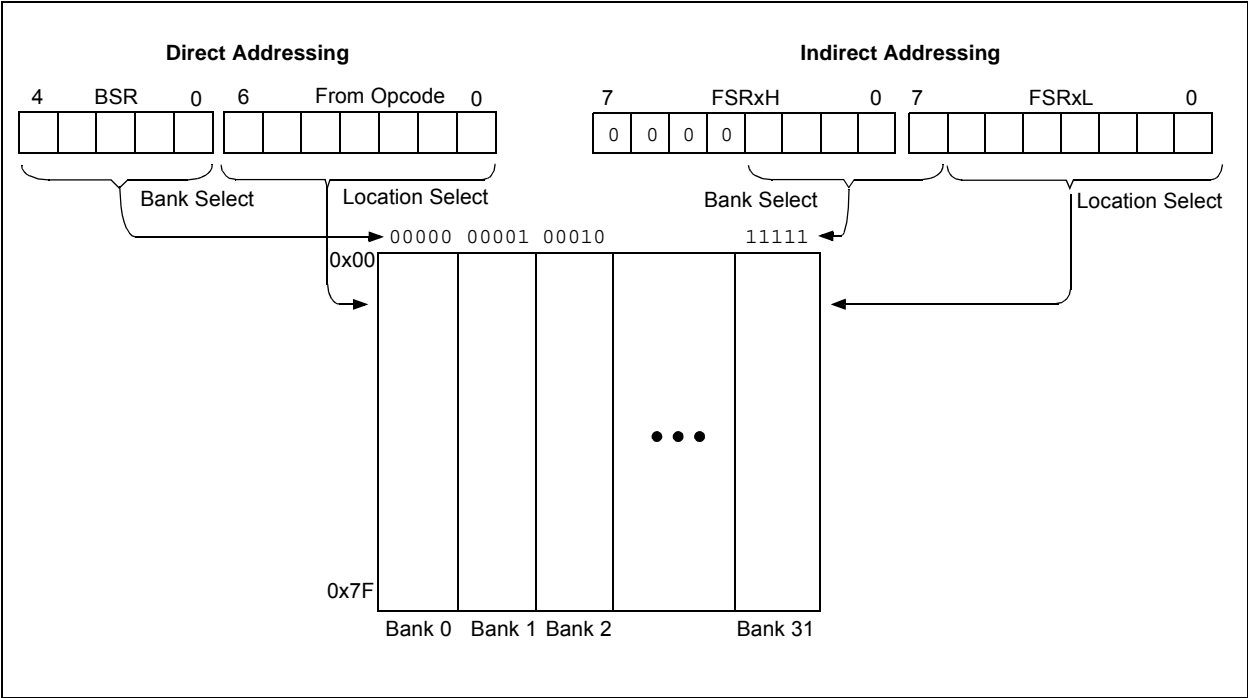
FIGURE 2-1: CORE BLOCK DIAGRAM



3.5.1 TRADITIONAL DATA MEMORY

The traditional data memory is a region from FSR address 0x000 to FSR address 0xFFF. The addresses correspond to the absolute addresses of all SFR, GPR and common registers.

FIGURE 3-10: TRADITIONAL DATA MEMORY MAP



4.0 DEVICE CONFIGURATION

Device Configuration consists of Configuration Word 1 and Configuration Word 2, Code Protection and Device ID.

4.1 Configuration Words

There are several Configuration Word bits that allow different oscillator and memory protection options. These are implemented as Configuration Word 1 at 8007h and Configuration Word 2 at 8008h.

<p>Note: The <code>DEBUG</code> bit in Configuration Words is managed automatically by device development tools including debuggers and programmers. For normal device operation, this bit should be maintained as a '1'.</p>
--

5.3 Low-Power Brown-out Reset (LPBOR)

The Low-Power Brown-Out Reset (LPBOR) is an essential part of the Reset subsystem. Refer to Figure 5-1 to see how the BOR interacts with other modules.

The LPBOR is used to monitor the external VDD pin. When too low of a voltage is detected, the device is held in Reset. When this occurs, a register bit ($\overline{\text{BOR}}$) is changed to indicate that a BOR Reset has occurred. The same bit is set for both the BOR and the LPBOR. Refer to Register 5-2.

5.3.1 ENABLING LPBOR

The LPBOR is controlled by the $\overline{\text{LPBOR}}$ bit of Configuration Word 2. When the device is erased, the LPBOR module defaults to disabled.

5.3.1.1 LPBOR Module Output

The output of the LPBOR module is a signal indicating whether or not a Reset is to be asserted. This signal is to be OR'd together with the Reset signal of the BOR module to provide the generic $\overline{\text{BOR}}$ signal which goes to the PCON register and to the power control block.

5.4 $\overline{\text{MCLR}}$

The $\overline{\text{MCLR}}$ is an optional external input that can reset the device. The MCLR function is controlled by the MCLRE bit of Configuration Word 1 and the LVP bit of Configuration Word 2 (Table 5-2).

TABLE 5-2: $\overline{\text{MCLR}}$ CONFIGURATION

MCLRE	LVP	$\overline{\text{MCLR}}$
0	0	Disabled
1	0	Enabled
x	1	Enabled

5.4.1 $\overline{\text{MCLR}}$ ENABLED

When $\overline{\text{MCLR}}$ is enabled and the pin is held low, the device is held in Reset. The $\overline{\text{MCLR}}$ pin is connected to VDD through an internal weak pull-up.

The device has a noise filter in the $\overline{\text{MCLR}}$ Reset path. The filter will detect and ignore small pulses.

Note: A Reset does not drive the $\overline{\text{MCLR}}$ pin low.

5.4.2 $\overline{\text{MCLR}}$ DISABLED

When $\overline{\text{MCLR}}$ is disabled, the pin functions as a general purpose input and the internal weak pull-up is under software control. See Section 11.4 “PORTE Registers” for more information.

5.5 Watchdog Timer (WDT) Reset

The Watchdog Timer generates a Reset if the firmware does not issue a CLRWDT instruction within the time-out period. The $\overline{\text{TO}}$ and $\overline{\text{PD}}$ bits in the STATUS register are changed to indicate the WDT Reset. See Section 9.0 “Watchdog Timer” for more information.

5.6 RESET Instruction

A RESET instruction will cause a device Reset. The $\overline{\text{RI}}$ bit in the PCON register will be set to '0'. See Table 5-4 for default conditions after a RESET instruction has occurred.

5.7 Stack Overflow/Underflow Reset

The device can reset when the Stack Overflows or Underflows. The STKOVF or STKUNF bits of the PCON register indicate the Reset condition. These Resets are enabled by setting the STVREN bit in Configuration Word 2. See Section 5.7 “Stack Overflow/Underflow Reset” for more information.

5.8 Programming Mode Exit

Upon exit of Programming mode, the device will behave as if a POR had just occurred.

5.9 Power-Up Timer

The Power-up Timer optionally delays device execution after a BOR or POR event. This timer is typically used to allow VDD to stabilize before allowing the device to start running.

The Power-up Timer is controlled by the $\overline{\text{PWRT}}$ bit of Configuration Word 1.

5.10 Start-up Sequence

Upon the release of a POR or BOR, the following must occur before the device will begin executing:

1. Power-up Timer runs to completion (if enabled).
2. Oscillator start-up timer runs to completion (if required for oscillator source).
3. $\overline{\text{MCLR}}$ must be released (if enabled).

The total time-out will vary based on oscillator configuration and Power-up Timer configuration. See Section 6.0 “Oscillator Module” for more information.

The Power-up Timer and oscillator start-up timer run independently of $\overline{\text{MCLR}}$ Reset. If $\overline{\text{MCLR}}$ is kept low long enough, the Power-up Timer and oscillator start-up timer will expire. Upon bringing $\overline{\text{MCLR}}$ high, the device will begin execution immediately (see Figure 5-3). This is useful for testing purposes or to synchronize more than one device operating in parallel.

TABLE 5-5: SUMMARY OF REGISTERS ASSOCIATED WITH RESETS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BORCON	SBOREN	BORFS	—	—	—	—	—	BORRDY	40
PCON	STKOVF	STKUNF	—	$\overline{\text{RWD\overline{T}}}$	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	44
STATUS	—	—	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	Z	DC	C	16
WDTCON	—	—	WDTPS<4:0>					SWDTEN	70

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Resets.

7.6.2 PIE1 REGISTER

The PIE1 register contains the interrupt enable bits, as shown in Register 7-2.

Note: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt.

REGISTER 7-2: PIE1: PERIPHERAL INTERRUPT ENABLE REGISTER 1

R/W-0/0	R/W-0/0	U-0	U-0	U-0	U-0	U-0	R/W-0/0
TMR1GIE	ADIE	—	—	—	—	—	TMR1IE
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

- bit 7 **TMR1GIE:** Timer1 Gate Interrupt Enable bit
 1 = Enables the Timer1 Gate Acquisition interrupt
 0 = Disables the Timer1 Gate Acquisition interrupt
- bit 6 **ADIE:** A/D Converter (ADC) Interrupt Enable bit
 1 = Enables the ADC interrupt
 0 = Disables the ADC interrupt
- bit 5-1 **Unimplemented:** Read as '0'
- bit 0 **TMR1IE:** Timer1 Overflow Interrupt Enable bit
 1 = Enables the Timer1 overflow interrupt
 0 = Disables the Timer1 overflow interrupt

8.0 POWER-DOWN MODE (SLEEP)

The Power-Down mode is entered by executing a `SLEEP` instruction.

Upon entering Sleep mode, the following conditions exist:

1. WDT will be cleared but keeps running, if enabled for operation during Sleep.
2. $\overline{\text{PD}}$ bit of the STATUS register is cleared.
3. $\overline{\text{TO}}$ bit of the STATUS register is set.
4. CPU clock is disabled.
5. 31 kHz LFINTOSC is unaffected and peripherals that operate from it may continue operation in Sleep.
6. Secondary oscillator is unaffected and peripherals that operate from it may continue operation in Sleep.
7. ADC is unaffected, if the dedicated FRC clock is selected.
8. Capacitive Sensing oscillator is unaffected.
9. I/O ports maintain the status they had before `SLEEP` was executed (driving high, low or high-impedance).
10. Resets other than WDT are not affected by Sleep mode.

Refer to individual chapters for more details on peripheral operation during Sleep.

To minimize current consumption, the following conditions should be considered:

- I/O pins should not be floating
- External circuitry sinking current from I/O pins
- Internal circuitry sourcing current from I/O pins
- Current draw from pins with internal weak pull-ups
- Modules using 31 kHz LFINTOSC
- Modules using Secondary oscillator

I/O pins that are high-impedance inputs should be pulled to VDD or VSS externally to avoid switching currents caused by floating inputs.

Examples of internal circuitry that might be sourcing current include the FVR module. See **13.0 “Fixed Voltage Reference (FVR)”** for more information.

8.1 Wake-up from Sleep

The device can wake-up from Sleep through one of the following events:

1. External Reset input on $\overline{\text{MCLR}}$ pin, if enabled
2. BOR Reset, if enabled
3. POR Reset
4. Watchdog Timer, if enabled
5. Any external interrupt
6. Interrupts by peripherals capable of running during Sleep (see individual peripheral for more information)

The first three events will cause a device Reset. The last three events are considered a continuation of program execution. To determine whether a device Reset or wake-up event occurred, refer to **Section 5.11, Determining the Cause of a Reset**.

When the `SLEEP` instruction is being executed, the next instruction (`PC + 1`) is prefetched. For the device to wake-up through an interrupt event, the corresponding interrupt enable bit must be enabled. Wake-up will occur regardless of the state of the GIE bit. If the GIE bit is disabled, the device continues execution at the instruction after the `SLEEP` instruction. If the GIE bit is enabled, the device executes the instruction after the `SLEEP` instruction, the device will then call the Interrupt Service Routine. In cases where the execution of the instruction following `SLEEP` is not desirable, the user should have a `NOP` after the `SLEEP` instruction.

The WDT is cleared when the device wakes up from Sleep, regardless of the source of wake-up.

10.2.2 FLASH MEMORY UNLOCK SEQUENCE

The unlock sequence is a mechanism that protects the Flash Program Memory from unintended self-write programming or erasing. The sequence must be executed and completed without interruption to successfully complete any of the following operations:

- Row Erase
- Load program memory write latches
- Write of program memory write latches to program memory
- Write of program memory write latches to User IDs

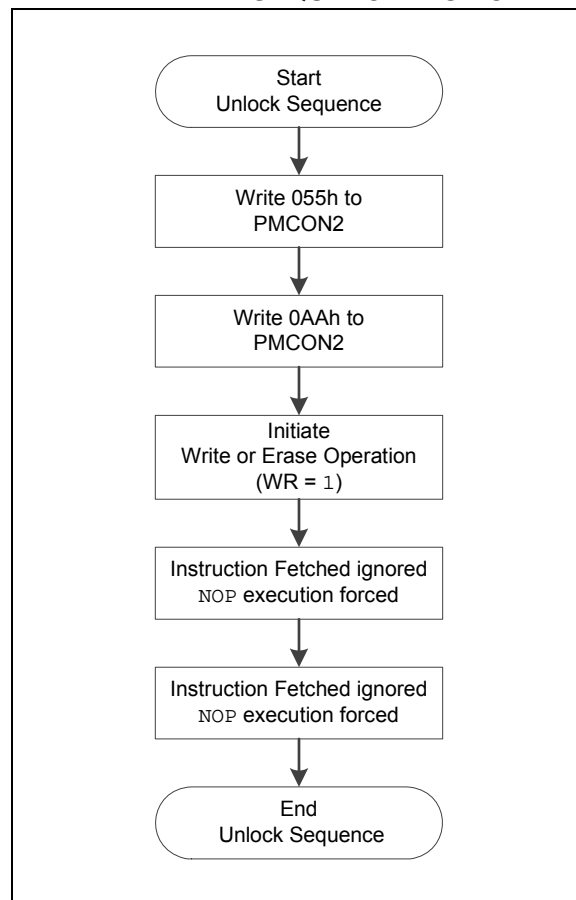
The unlock sequence consists of the following steps:

1. Write 55h to PMCON2
2. Write AAh to PMCON2
3. Set the WR bit in PMCON1
4. NOP instruction
5. NOP instruction

Once the WR bit is set, the processor will always force two NOP instructions. When an Erase Row or Program Row operation is being performed, the processor will stall internal operations (typical 2 ms), until the operation is complete and then resume with the next instruction. When the operation is loading the program memory write latches, the processor will always force the two NOP instructions and continue uninterrupted with the next instruction.

Since the unlock sequence must not be interrupted, global interrupts should be disabled prior to the unlock sequence and re-enabled after the unlock sequence is completed.

FIGURE 10-3: FLASH PROGRAM MEMORY UNLOCK SEQUENCE FLOWCHART



REGISTER 11-5: PORTB: PORTB REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
 '1' = Bit is set '0' = Bit is cleared

bit 7-0 **RB<7:0>**: PORTB General Purpose I/O Pin bits⁽¹⁾

1 = Port pin is $\geq V_{IH}$

0 = Port pin is $\leq V_{IL}$

Note 1: Writes to PORTB are actually written to corresponding LATB register. Reads from PORTB register is return of actual I/O pin values.

REGISTER 11-6: TRISB: PORTB TRI-STATE REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
 '1' = Bit is set '0' = Bit is cleared

bit 7-0 **TRISB<7:0>**: PORTB Tri-State Control bits

1 = PORTB pin configured as an input (tri-stated)

0 = PORTB pin configured as an output

REGISTER 11-7: LATB: PORTB DATA LATCH REGISTER

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets
 '1' = Bit is set '0' = Bit is cleared

bit 7-0 **LATB<7:0>**: PORTB Output Latch Value bits⁽¹⁾

Note 1: Writes to PORTB are actually written to corresponding LATB register. Reads from PORTB register is return of actual I/O pin values.

15.0 ANALOG-TO-DIGITAL CONVERTER (ADC) MODULE

The Analog-to-Digital Converter (ADC) allows conversion of an analog input signal to a 10-bit binary representation of that signal. This device uses analog inputs, which are multiplexed into a single sample and hold circuit. The output of the sample and hold is connected to the input of the converter. The converter generates a 10-bit binary result via successive approximation and stores the conversion result into the ADC result registers (ADRESH:ADRESL register pair). Figure 15-1 shows the block diagram of the ADC.

The ADC voltage reference is software selectable to be either internally generated or externally supplied.

The ADC can generate an interrupt upon completion of a conversion. This interrupt can be used to wake-up the device from Sleep.

FIGURE 15-1: ADC BLOCK DIAGRAM

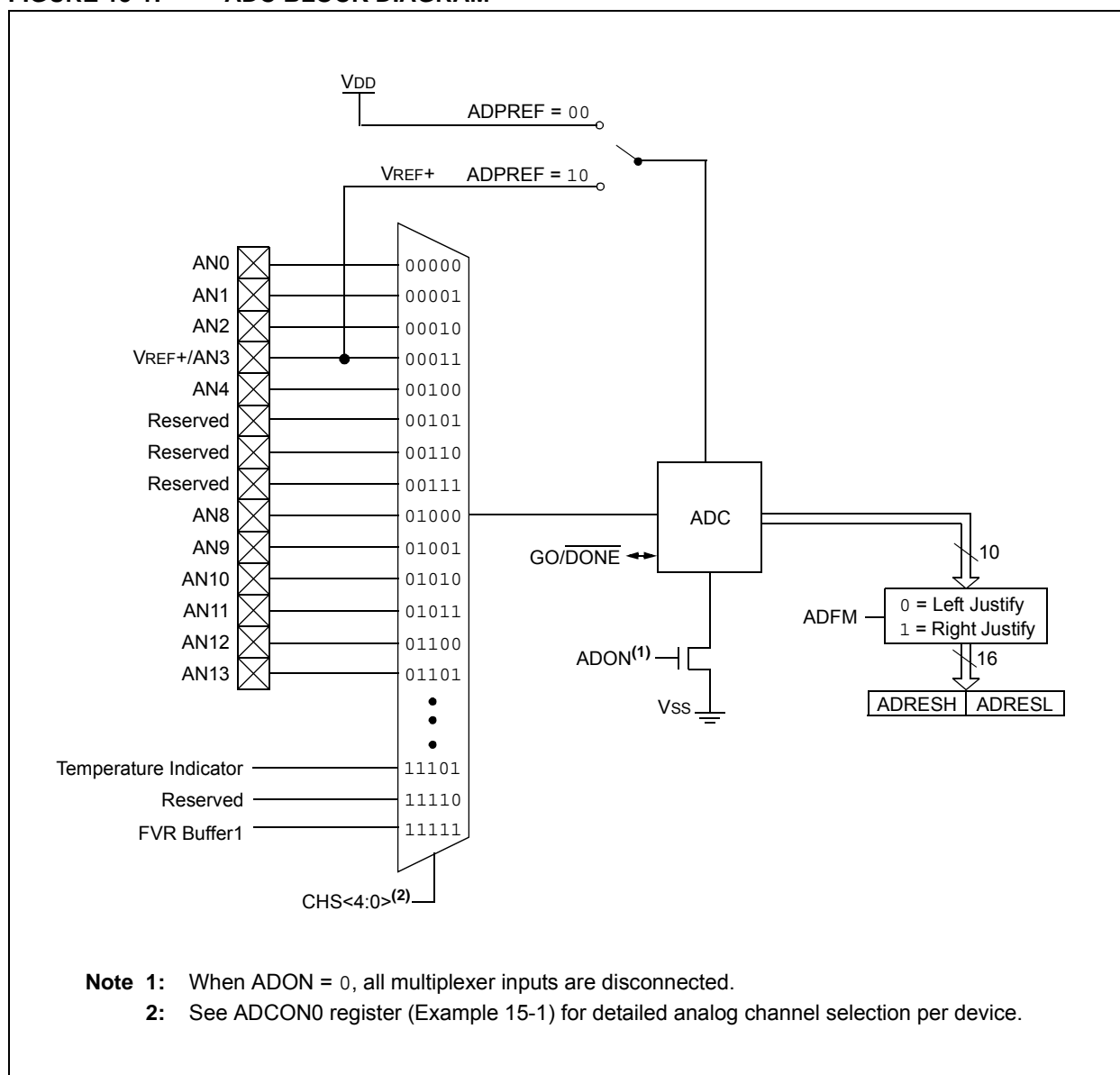
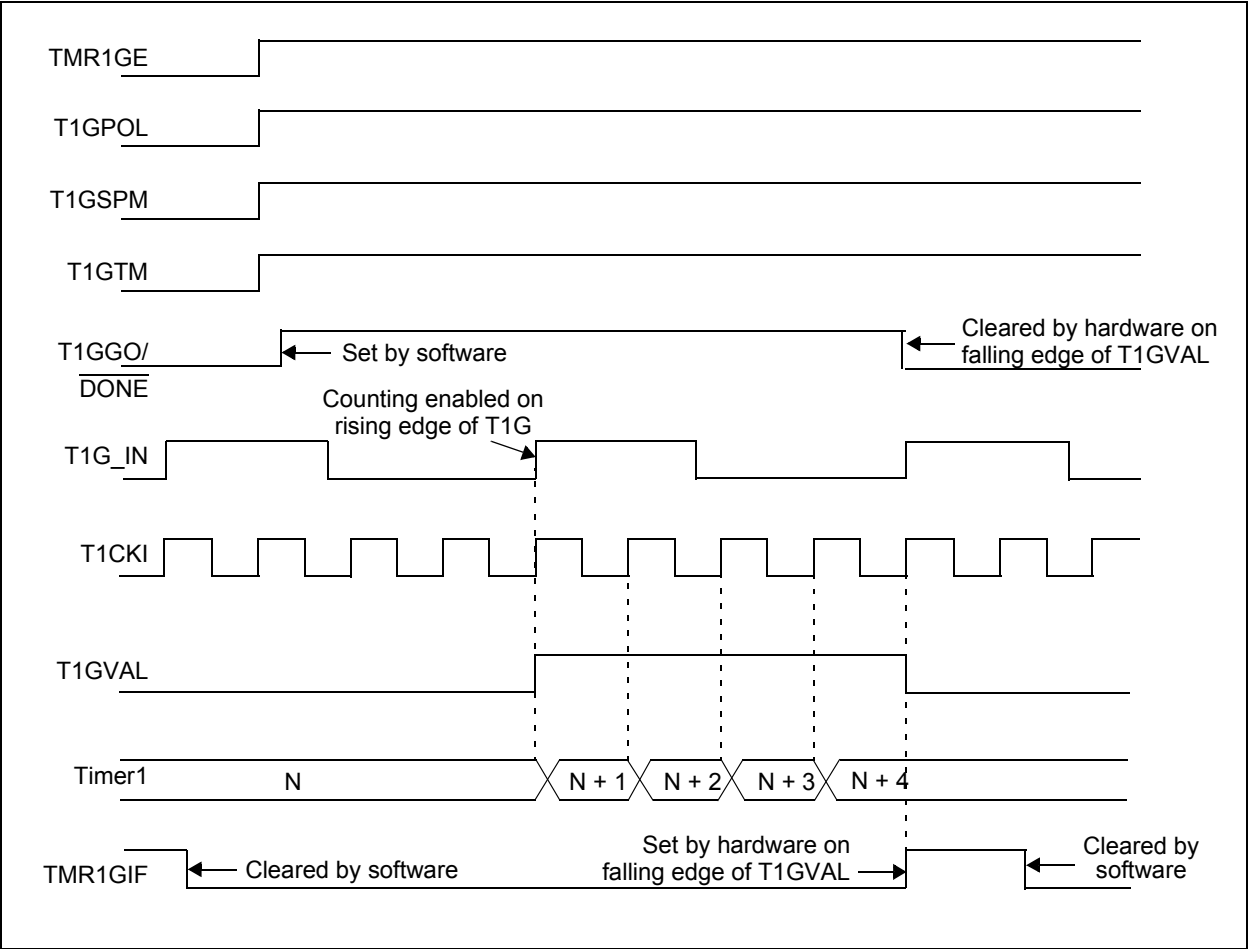


FIGURE 17-6: TIMER1 GATE SINGLE-PULSE AND TOGGLE COMBINED MODE



PIC16LF1902/3

REGISTER 18-2: LCDPS: LCD PHASE REGISTER

R/W-0/0	R/W-0/0	R-0/0	R-0/0	R/W-0/0	R/W-0/0	R/W-1/1	R/W-1/1
WFT	BIASMD	LCDA	WA	LP<3:0>			
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	C = Only clearable bit

- bit 7 **WFT:** Waveform Type bit
1 = Type-B phase changes on each frame boundary
0 = Type-A phase changes within each common type
- bit 6 **BIASMD:** Bias Mode Select bit
When LMUX<1:0> = 00:
0 = Static Bias mode (do not set this bit to '1')
When LMUX<1:0> = 01:
1 = 1/2 Bias mode
0 = 1/3 Bias mode
When LMUX<1:0> = 10:
1 = 1/2 Bias mode
0 = 1/3 Bias mode
When LMUX<1:0> = 11:
0 = 1/3 Bias mode (do not set this bit to '1')
- bit 5 **LCDA:** LCD Active Status bit
1 = LCD Driver module is active
0 = LCD Driver module is inactive
- bit 4 **WA:** LCD Write Allow Status bit
1 = Writing to the LCDDATAN registers is allowed
0 = Writing to the LCDDATAN registers is not allowed
- bit 3-0 **LP<3:0>:** LCD Prescaler Selection bits
1111 = 1:16
1110 = 1:15
1101 = 1:14
1100 = 1:13
1011 = 1:12
1010 = 1:11
1001 = 1:10
1000 = 1:9
0111 = 1:8
0110 = 1:7
0101 = 1:6
0100 = 1:5
0011 = 1:4
0010 = 1:3
0001 = 1:2
0000 = 1:1

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REGISTER 18-7: LCDRL: LCD REFERENCE LADDER CONTROL REGISTERS

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0
LRLAP<1:0>		LRLBP<1:0>		—	LRLAT<2:0>		
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-6 **LRLAP<1:0>**: LCD Reference Ladder A Time Power Control bits

During Time interval A (Refer to Figure 18-4):

- 00 = Internal LCD Reference Ladder is powered down and unconnected
- 01 = Internal LCD Reference Ladder is powered in Low-Power mode
- 10 = Internal LCD Reference Ladder is powered in Medium-Power mode
- 11 = Internal LCD Reference Ladder is powered in High-Power mode

bit 5-4 **LRLBP<1:0>**: LCD Reference Ladder B Time Power Control bits

During Time interval B (Refer to Figure 18-4):

- 00 = Internal LCD Reference Ladder is powered down and unconnected
- 01 = Internal LCD Reference Ladder is powered in Low-Power mode
- 10 = Internal LCD Reference Ladder is powered in Medium-Power mode
- 11 = Internal LCD Reference Ladder is powered in High-Power mode

bit 3 **Unimplemented**: Read as '0'

bit 2-0 **LRLAT<2:0>**: LCD Reference Ladder A Time Interval Control bits

Sets the number of 32 kHz clocks that the A Time Interval Power mode is active

For type A waveforms (WFT = 0):

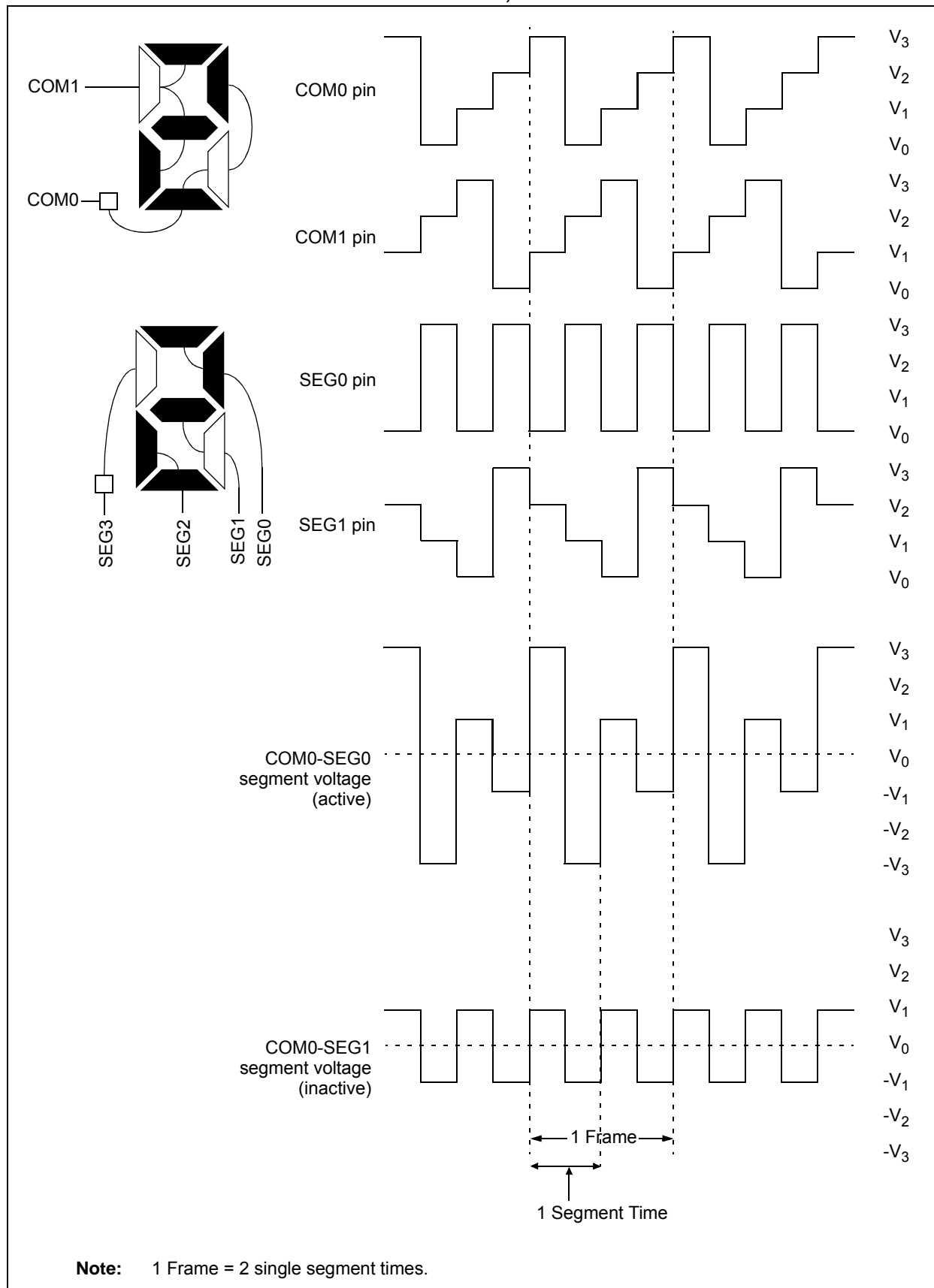
- 000 = Internal LCD Reference Ladder is always in 'B' Power mode
- 001 = Internal LCD Reference Ladder is in 'A' Power mode for 1 clock and 'B' Power mode for 15 clocks
- 010 = Internal LCD Reference Ladder is in 'A' Power mode for 2 clocks and 'B' Power mode for 14 clocks
- 011 = Internal LCD Reference Ladder is in 'A' Power mode for 3 clocks and 'B' Power mode for 13 clocks
- 100 = Internal LCD Reference Ladder is in 'A' Power mode for 4 clocks and 'B' Power mode for 12 clocks
- 101 = Internal LCD Reference Ladder is in 'A' Power mode for 5 clocks and 'B' Power mode for 11 clocks
- 110 = Internal LCD Reference Ladder is in 'A' Power mode for 6 clocks and 'B' Power mode for 10 clocks
- 111 = Internal LCD Reference Ladder is in 'A' Power mode for 7 clocks and 'B' Power mode for 9 clocks

For type B waveforms (WFT = 1):

- 000 = Internal LCD Reference Ladder is always in 'B' Power mode.
- 001 = Internal LCD Reference Ladder is in 'A' Power mode for 1 clock and 'B' Power mode for 31 clocks
- 010 = Internal LCD Reference Ladder is in 'A' Power mode for 2 clocks and 'B' Power mode for 30 clocks
- 011 = Internal LCD Reference Ladder is in 'A' Power mode for 3 clocks and 'B' Power mode for 29 clocks
- 100 = Internal LCD Reference Ladder is in 'A' Power mode for 4 clocks and 'B' Power mode for 28 clocks
- 101 = Internal LCD Reference Ladder is in 'A' Power mode for 5 clocks and 'B' Power mode for 27 clocks
- 110 = Internal LCD Reference Ladder is in 'A' Power mode for 6 clocks and 'B' Power mode for 26 clocks
- 111 = Internal LCD Reference Ladder is in 'A' Power mode for 7 clocks and 'B' Power mode for 25 clocks

PIC16LF1902/3

FIGURE 18-11: TYPE-A WAVEFORMS IN 1/2 MUX, 1/3 BIAS DRIVE



PIC16LF1902/3

TABLE 20-3: PIC16LF1902/3 ENHANCED INSTRUCTION SET (CONTINUED)

Mnemonic, Operands		Description	Cycles	14-Bit Opcode				Status Affected	Notes
				MSb		LSb			
CONTROL OPERATIONS									
BRA	k	Relative Branch	2	11	001k	kkkk	kkkk		
BRW	—	Relative Branch with W	2	00	0000	0000	1011		
CALL	k	Call Subroutine	2	10	0kkk	kkkk	kkkk		
CALLW	—	Call Subroutine with W	2	00	0000	0000	1010		
GOTO	k	Go to address	2	10	1kkk	kkkk	kkkk		
RETFIE	k	Return from interrupt	2	00	0000	0000	1001		
RETLW	k	Return with literal in W	2	11	0100	kkkk	kkkk		
RETURN	—	Return from Subroutine	2	00	0000	0000	1000		
INHERENT OPERATIONS									
CLRWDT	—	Clear Watchdog Timer	1	00	0000	0110	0100	\overline{TO} , \overline{PD}	
NOP	—	No Operation	1	00	0000	0000	0000		
OPTION	—	Load OPTION_REG register with W	1	00	0000	0110	0010		
RESET	—	Software device Reset	1	00	0000	0000	0001	\overline{TO} , \overline{PD}	
SLEEP	—	Go into Standby mode	1	00	0000	0110	0011		
TRIS	f	Load TRIS register with W	1	00	0000	0110	0fff		
C-COMPILER OPTIMIZED									
ADDFSR	n, k	Add Literal k to FSRn	1	11	0001	0nkk	kkkk		
MOVIW	n mm	Move Indirect FSRn to W with pre/post inc/dec modifier, mm	1	00	0000	0001	0nmm	Z	2, 3
MOVWI	k[n]	Move INDFn to W, Indexed Indirect.	1	11	1111	0nkk	kkkk	Z	2
	n mm	Move W to Indirect FSRn with pre/post inc/dec modifier, mm	1	00	0000	0001	1nmm		2, 3
	k[n]	Move W to INDFn, Indexed Indirect.	1	11	1111	1nkk	kkkk		2

Note 1: If the Program Counter (PC) is modified, or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

2: If this instruction addresses an INDF register and the MSb of the corresponding FSR is set, this instruction will require one additional instruction cycle.

3: See Table in the MOVIW and MOVWI instruction descriptions.

21.3 AC Characteristics

The timing parameter symbols have been created with one of the following formats:

- 1. TppS2ppS
- 2. TppS

T			
F	Frequency	T	Time

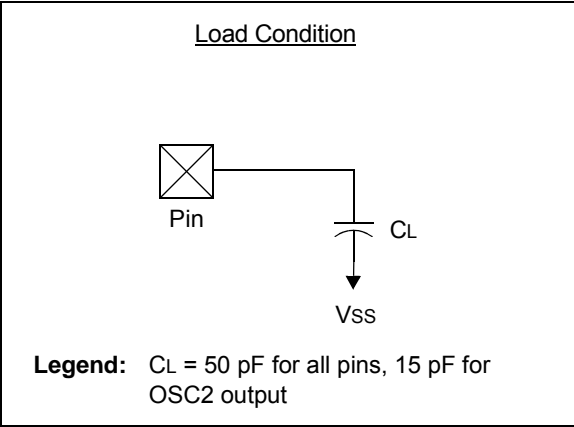
Lowercase letters (pp) and their meanings:

pp			
cc	CCP1	osc	OSC1
ck	CLKOUT	rd	\overline{RD}
cs	\overline{CS}	rw	\overline{RD} or \overline{WR}
di	SDI	sc	SCK
do	SDO	ss	\overline{SS}
dt	Data in	t0	T0CKI
io	I/O PORT	t1	T1CKI
mc	\overline{MCLR}	wr	\overline{WR}

Uppercase letters and their meanings:

S			
F	Fall	P	Period
H	High	R	Rise
I	Invalid (High-Impedance)	V	Valid
L	Low	Z	High-Impedance

FIGURE 21-4: LOAD CONDITIONS



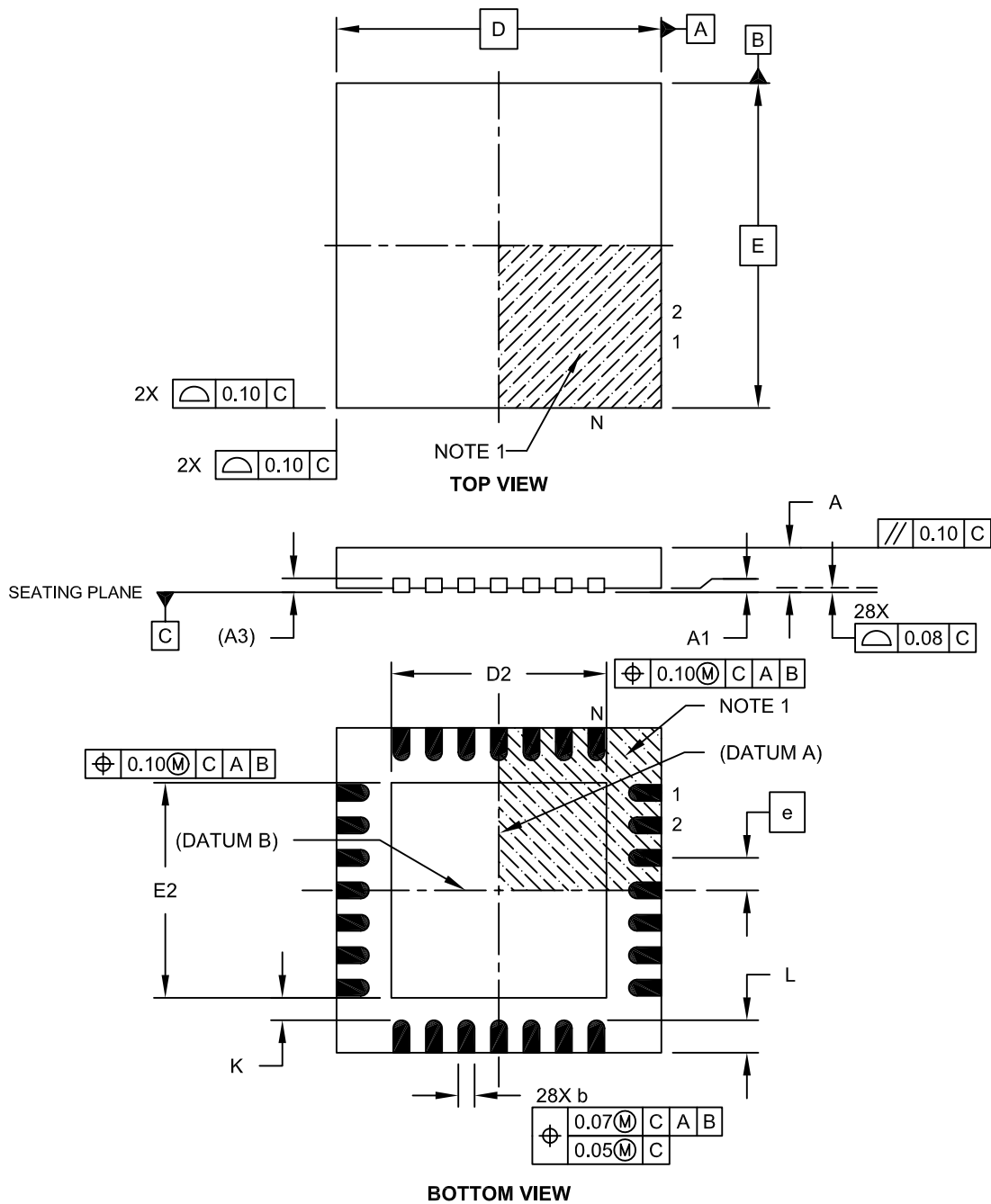
22.0 DC AND AC CHARACTERISTICS GRAPHS AND CHARTS

Graphs and charts are not available at this time.

PIC16LF1902/3

28-Lead Plastic Ultra Thin Quad Flat, No Lead Package (MV) – 4x4x0.5 mm Body [UQFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-152A Sheet 1 of 2

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