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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, PWM, WDT
Number of I/O	30
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.5V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/nuvoton-technology-corporation-america/mini58lde

- Two I^2C devices
- Supports Master/Slave mode
- Bidirectional data transfer between masters and slaves
- Multi-master bus (no central master)
- Arbitration between simultaneously transmitting masters without corruption of serial data on the bus
- Serial clock synchronization allowing devices with different bit rates to communicate via one serial bus
- Serial clock synchronization can be used as a handshake mechanism to suspend and resume serial transfer
- Programmable clocks allow for versatile rate control
- Supports multiple address recognition (four slave addresses with mask option)

- ADC (Analog-to-Digital Converter)
  - 10-bit SAR ADC with 250 kSPS
  - Up to 8-ch single-end input and one internal input from band-gap
  - Conversion started either by software trigger or external pin trigger
- Analog Comparator
  - Two analog comparators with programmable 16-level internal voltage reference
  - Built-in CRV (comparator reference voltage)
- ISP (In-System Programming), ICP (In-Circuit Programming), and IAP (In-Application-Programming) update
- BOD (Brown-out Detector)
  - With 4 programmable threshold levels: 4.4V/3.7V/2.7V/2.2V
  - Supports Brown-out interrupt and reset option
- 96-bit unique ID
- LVR (Low Voltage Reset)
  - Threshold voltage level: 2.0V
- Operating Temperature: -40℃~105℃
- Reliability: EFT > ± 4KV, ESD HBM pass 4KV
- Packages:
  - Green package (RoHS)
  - 48-pin LQFP (7x7), 33-pin QFN (5x5) , 33-pin QFN (4x4), 20-pin TSSOP

4.3 PIN CONFIGURATION

4.3.1 LQFP 48-pin

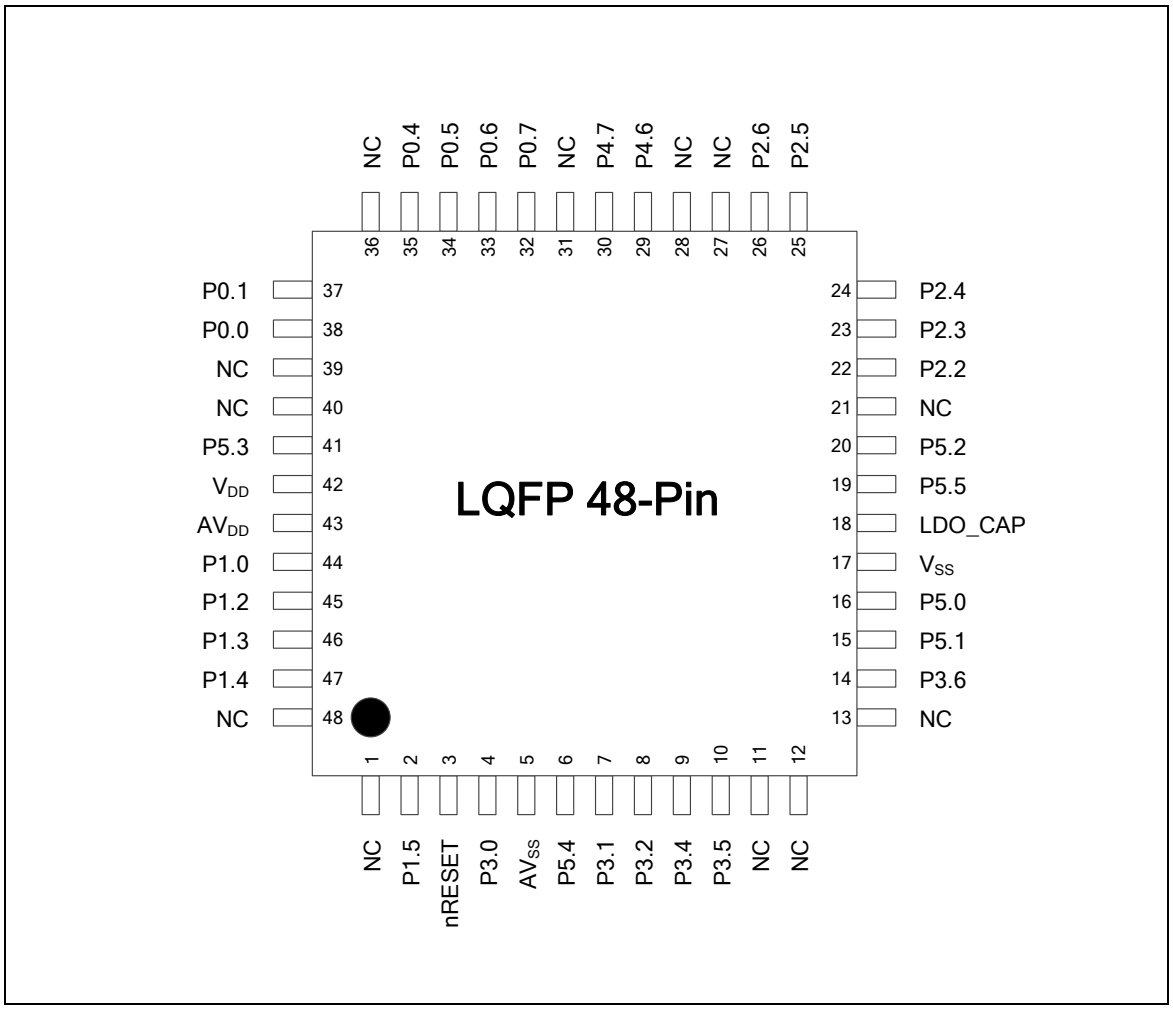

Figure 4.3-1 NuMicro® Mini58 Series LQFP 48-pin Diagram

4.4 Pin Description

Pin Number			Pin Name	Pin Type	Description
LQFP 48-pin	QFN 33-pin	TSSOP 20-pin			
1	---	---	NC	**---**	Not connected
2	1	4	P1.5	**I/O**	General purpose digital I/O pin
			ADC_CH5	**AI**	ADC analog input pin
			UART1_TXD	**O**	UART1 transmitter output pin
			ACMP0_P0	**AI**	Analog comparator positive input pin
3	2	5	nRESET	**I(ST)**	The Schmitt trigger input pin for hardware device reset. A "**Low**" on this pin for 768 clock counter of Internal RC 22.1184 MHz while the system clock is running will reset the device. nRESET pin has an internal pull-up resistor allowing power-on reset by simply connecting an external capacitor to GND.
4	3	---	P3.0	**I/O**	General purpose digital I/O pin
			ADC_CH6	**AI**	ADC analog input pin
			ACMP1_N	**AI**	Analog comparator negative input pin
5	---	---	AV_{SS}	**AP**	Ground pin for analog circuit
6	4	---	P5.4	**I/O**	General purpose digital I/O pin
7	5	---	P3.1	**I/O**	General purpose digital I/O pin
			ADC_CH7	**AI**	ADC analog input pin
			ACMP1_P0	**AI**	Analog comparator positive input pin
8	6	6	P3.2	**I/O**	General purpose digital I/O pin
			INT0	**I**	External interrupt 0 input pin
			STADC	**I**	ADC external trigger input pin
			TM0_EXT	**I/O**	Timer 0 external capture / reset trigger input pin / toggle output pin
			ACMP1_P1	**AI**	Analog comparator positive input pin (not support in TSSOP20 package)
9	7	7	P3.4	**I/O**	General purpose digital I/O pin
			TM0_CNT_OUT	**I/O**	Timer 0 external event counter input pin / toggle output pin
			I2C0_SDA	**I/O**	I^2C0 data I/O pin
			ACMP1_P2	**AI**	Analog comparator positive input pin
10	8	8	P3.5	**I/O**	General purpose digital I/O pin
			TM1_CNT_OUT	**I/O**	Timer 1 external event counter input pin / toggle output pin
			I2C0_SCL	**I/O**	I^2C0 clock I/O pin
			ACMP1_P3	**AI**	Analog comparator positive input pin
11	---	---	NC	**---**	Not connected

Pin Number			Pin Name	Pin Type	Description
LQFP 48-pin	QFN 33-pin	TSSOP 20-pin			
25	17	13	P2.5	**I/O**	General purpose digital I/O pin
			UART1_TXD	**O**	UART1 transmitter output pin
			PWM0_CH3	**O**	PWM3 output of PWM unit
26	18	---	P2.6	**I/O**	General purpose digital I/O pin
			PWM0_CH4	**O**	PWM4 output of PWM unit
			ACMP1_O	**O**	Analog comparator output pin
27	---	---	NC	**---**	Not connected
28	---	---	NC	**---**	Not connected
29	19	14	P4.6	**I/O**	General purpose digital I/O pin
			ICE_CLK	**I**	Serial wired debugger clock pin
			UART1_RXD	**I**	UART1 data receiver input pin
30	20	15	P4.7	**I/O**	General purpose digital I/O pin
			ICE_DAT	**I/O**	Serial wired debugger data pin
			UART1_TXD	**O**	UART1 transmitter output pin
31	---	---	NC	**---**	Not connected
32	21	16	P0.7	**I/O**	General purpose digital I/O pin
			SPI0_CLK	**I/O**	SPI serial clock pin
			PWM0_CH0	**O**	PWM0 output of PWM unit
33	22	17	P0.6	**I/O**	General purpose digital I/O pin
			SPI0_MISO	**I/O**	SPI MISO (master in/slave out) pin
			PWM0_CH1	**O**	PWM1 output of PWM unit
34	23	18	P0.5	**I/O**	General purpose digital I/O pin
			SPI0_MOSI	**O**	SPI MOSI (master out/slave in) pin
			PWM0_CH4	**O**	PWM4 output of PWM unit
35	24	19	P0.4	**I/O**	General purpose digital I/O pin
			SPI0_SS	**I/O**	SPI slave select pin
			PWM0_CH5	**O**	PWM5 output of PWM unit
36	---	---	NC	**---**	Not connected
37	25	---	P0.1	**I/O**	General purpose digital I/O pin
			UART0_nRTS	**O**	UART0 RTS pin
			UART0_RXD	**I**	UART0 data receiver input pin
			SPI0_SS	**I/O**	SPI slave select pin
38	26	---	P0.0	**I/O**	General purpose digital I/O pin

6 FUNCTIONAL DESCRIPTION

6.1 ARM® Cortex®-M0 Core

6.1.1 Overview

The Cortex®-M0 processor, a configurable, multistage, 32-bit RISC processor, has an AMBA AHB-Lite interface and includes an NVIC component. It also has optional hardware debug functionality. The processor can execute Thumb code and is compatible with other Cortex®-M profile processors. The profile supports two modes - Thread mode and Handler mode. Handler mode is entered as a result of an exception. An exception return can only be issued in Handler mode. Thread mode is entered on Reset and can be entered as a result of an exception return. Figure 6.1-1 shows the functional controller of the processor.

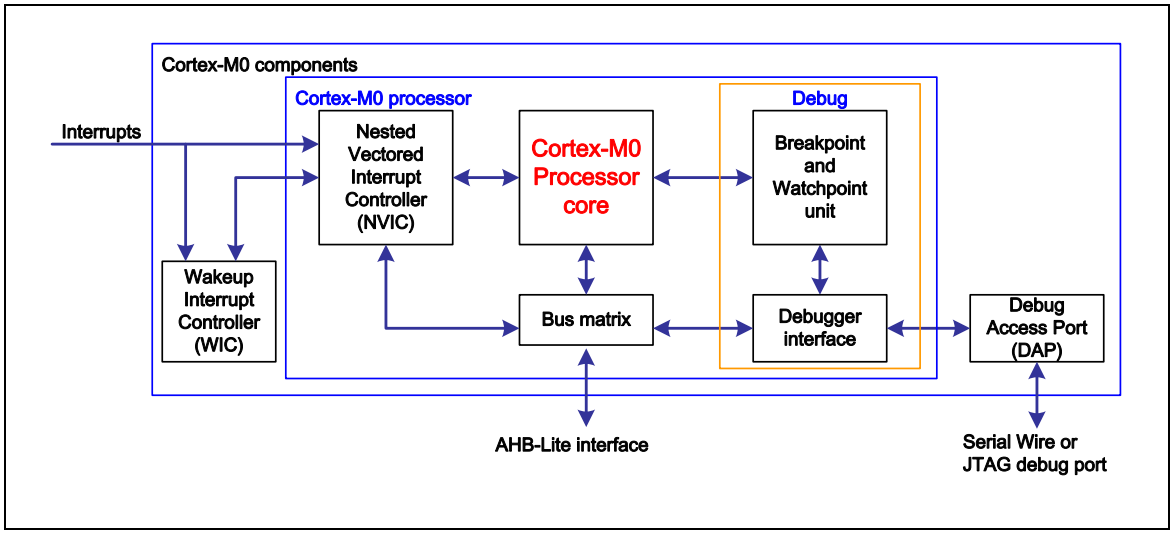

Figure 6.1-1 Functional Block Diagram

6.1.2 Features

- A low gate count processor
  - ARMv6-M Thumb® instruction set
  - Thumb-2 technology
  - ARMv6-M compliant 24-bit SysTick timer
  - A 32-bit hardware multiplier
  - System interface supported with little-endian data accesses
  - Ability to have deterministic, fixed-latency, interrupt handling
  - Load/store-multiples and multicycle-multiplies that can be abandoned and restarted to facilitate rapid interrupt handling
  - C Application Binary Interface compliant exception model:

    This is the ARMv6-M, C Application Binary Interface (C-ABI) compliant exception model that enables the use of pure C functions as interrupt handlers
  - Low power Idle mode entry using the Wait For Interrupt (WFI), Wait For Event (WFE) instructions, or return from interrupt sleep-on-exit feature

6.2 System Manager

6.2.1 Overview

System management includes the following sections:

- System Reset
- System Power Architecture
- System Memory Map
- System management registers for Part Number ID, chip reset and on-chip controllers reset, and multi-functional pin control
- System Timer (SysTick)
- Nested Vectored Interrupt Controller (NVIC)
- System Control registers

6.2.2 System Reset

The system reset can be issued by one of the events listed below. These reset event flags can be read from SYS_RSTSTS register to determine the reset source. Hardware reset can reset chip through peripheral reset signals. Software reset can trigger reset through control registers.

- Hardware Reset Sources
  - Power-on Reset (POR)
  - Low level on the nRESET pin
  - Watchdog Time-out Reset and Window Watchdog Reset (WDT/WWDT Reset)
  - Low Voltage Reset (LVR)
  - Brown-out Detector Reset (BOD Reset)
  - CPU Lockup Reset
- Software Reset Sources
  - CHIP Reset will reset whole chip by writing 1 to CHIPRST (SYS_IPRST0[0])
  - MCU Reset to reboot but keeping the booting setting from APROM or LDROM by writing 1 to SYSRESETREQ (SCS_AIRCR[2])
  - CPU Reset for Cortex®-M0 core Only by writing 1 to CPURST (SYS_IPRST0[1])

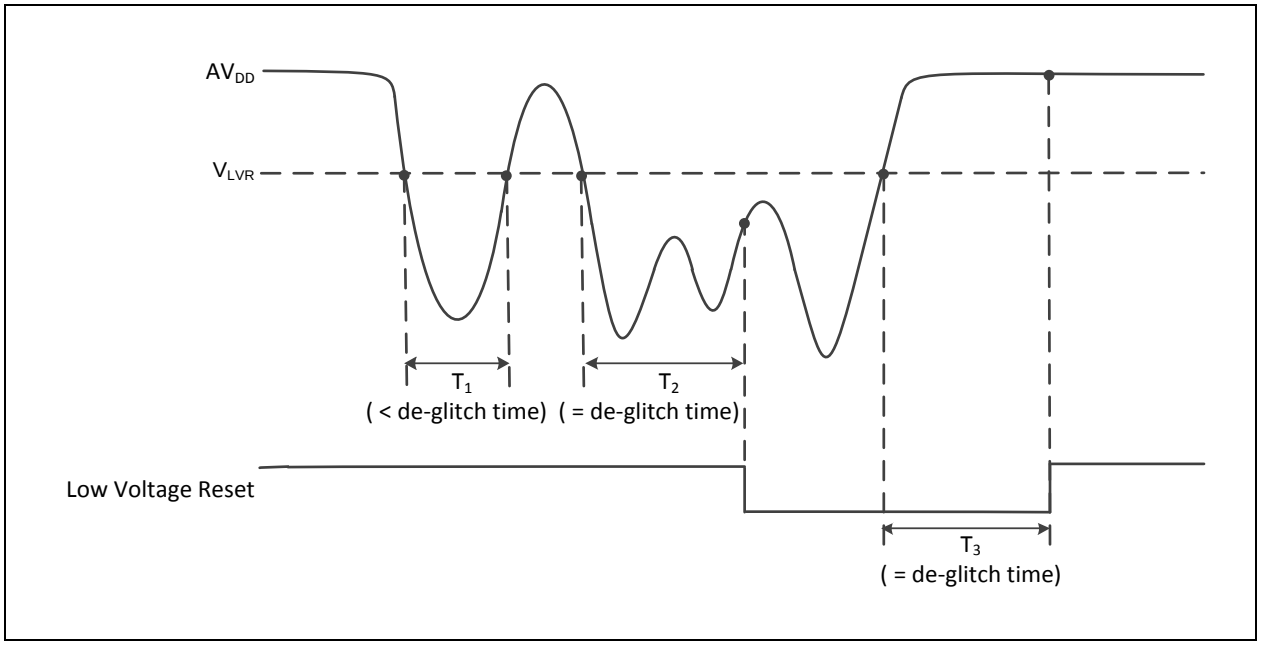

Figure 6.2-4 Low Voltage Reset (LVR) Waveform

6.2.2.4 Brown-out Detector Reset (BOD Reset)

If the Brown-out Detector (BOD) function is enabled by setting the Brown-out Detector Enable Bit BODEN (SYS_BODCTL[0]), Brown-Out Detector function will detect AV_{DD} during system operation. When the AV_{DD} voltage is lower than V_{BOD} which is decided by BODEN (SYS_BODCTL[0]) and BODVL (SYS_BODCTL[2:1]) and the state keeps longer than De-glitch time (Max(20*HCLK cycles, 1*LIRC cycle)), chip will be reset. The BOD reset will control the chip in reset state until the AV_{DD} voltage rises above V_{BOD} and the state keeps longer than De-glitch time. The default value of BODEN, BODVL and BODRSTEN is set by flash controller user configuration register CBOVEXT (CONFIG0[23]), CBOV (CONFIG0[22:21]) and CBORST (CONFIG0[20]) respectively. User can determine the initial BOD setting by setting the CONFIG0 register. Figure 6.2-5 shows the Brown-Out Detector waveform.

(FMC_ISPCTL[1]) bit is automatically reloaded from CONFIG setting. User can set the CHIPRST (SYS_IPRST0[0]) to 1 to assert the CHIP Reset signal.

The MCU Reset is similar with CHIP Reset. The difference is that BS (FMC_ISPCTL[1]) will not be reloaded from CONFIG setting and keep its original software setting for booting from APROM or LDROM. User can set the SYSRESETREQ (SCS_AIRCR[2]) to 1 to assert the MCU Reset.

6.2.3 Power Modes and Wake-up Sources

There are several wake-up sources in Idle mode and Power-down mode. Table 6.2-2 lists the available clocks for each power mode.

Power Mode	Normal Mode	Idle Mode	Power-down Mode
Definition	CPU is in active state	CPU is in sleep state	CPU is in sleep state and all clocks stop except LXT and LIRC. SRAM content retended.
Entry Condition	Chip is in normal mode after system reset released	CPU executes WFI instruction.	CPU sets sleep mode enable and power down enable and executes WFI instruction.
Wake-up Sources	N/A	All interrupts	WDT, I²C, Timer, UART, BOD and GPIO
Available Clocks	All	All except CPU clock	LXT and LIRC
After Wake-up	N/A	CPU back to normal mode	CPU back to normal mode

Table 6.2-2 Power Mode Difference Table

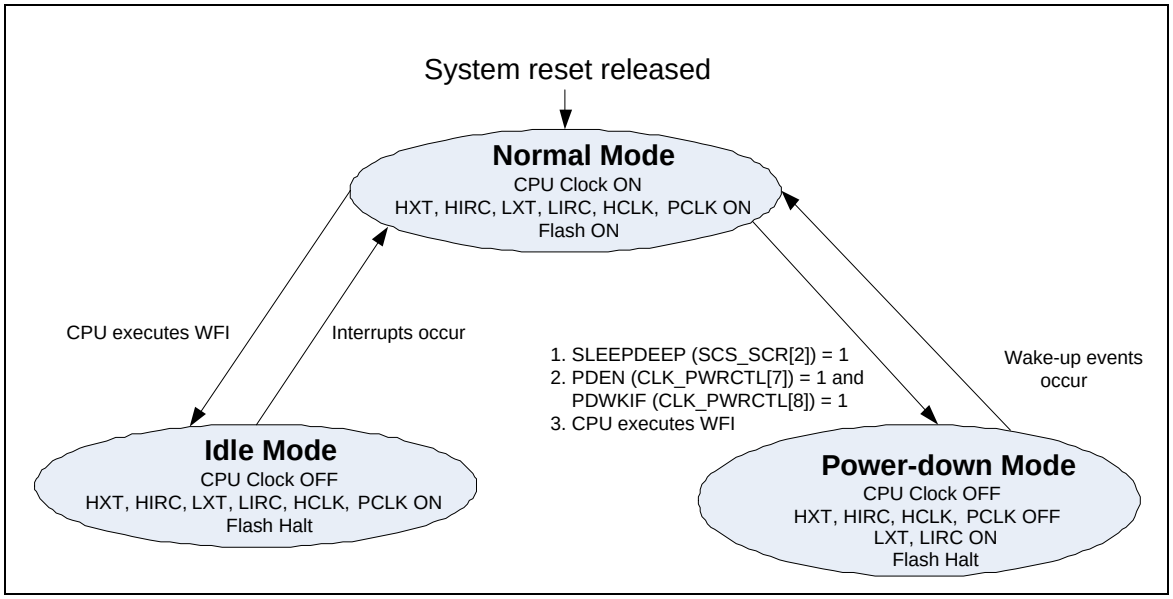

Figure 6.2-6 Power Mode State Machine

BOD	Brown-Out Detector Interrupt	After software writes 1 to clear SYS_BODCTL[BODIF].
GPIO	GPIO Interrupt	After software write 1 to clear the Px_INTSRC[n] bit.
TIMER	Timer Interrupt	After software writes 1 to clear TWKF (TIMERx_INTSTS[1]) and TIF (TIMERx_INTSTS[0]).
WDT	WDT Interrupt	After software writes 1 to clear WKF (WDT_CTL[5]) (Write Protect).
UART	nCTS wake-up	After software writes 1 to clear CTSWKIF (UARTx_INTSTS[16]).
I^2C	Falling edge in the I2C_SDA or I2C_CLK	After software writes 1 to clear WKIF (I2C_STATUS1[0]).

Table 6.2-4 Condition of Entering Power-down Mode Again

6.2.4 System Power Architecture

In this chip, the power distribution is divided into three segments.

- Analog power from AV_{DD} and AV_{SS} provides the power for analog components operation. AV_{DD} must be equal to V_{DD} to avoid leakage current.
- Digital power from V_{DD} and V_{SS} supplies power to the I/O pins and internal regulator which provides a fixed 1.8V power for digital operation.
- Built-in a capacitor for internal voltage regulator

The output of internal voltage regulator, LDO_CAP, requires an external capacitor which should be located close to the corresponding pin. Analog power (AV_{DD}) should be the same voltage level as the digital power (V_{DD}). Figure 6.2-7 shows the power distribution of the Mini58 series.

6.2.6.2 System Memory Map

The memory locations assigned to each on-chip controllers are shown in the following table.

Addressing Space	Token	Modules
Flash and SRAM Memory Space		
0x0000_0000 – 0x0000_7FFF	FLASH_BA	Flash Memory Space (32 KB)
0x2000_0000 – 0x2000_0FFF	SRAM_BA	SRAM Memory Space (4 KB)
AHB Modules Space (0x5000_0000 – 0x501F_FFFF)		
0x5000_0000 – 0x5000_01FF	SYS_BA	System Global Control Registers
0x5000_0200 – 0x5000_02FF	CLK_BA	Clock Control Registers
0x5000_0300 – 0x5000_03FF	INT_BA	Interrupt Multiplexer Control Registers
0x5000_4000 – 0x5000_7FFF	GP_BA	GPIO (P0~P5) Control Registers
0x5000_C000 – 0x5000_FFFF	FMC_BA	Flash Memory Control Registers
APB Modules Space (0x4000_0000 – 0x401F_FFFF)		
0x4000_4000 – 0x4000_00FF	WDT_BA	Watchdog Timer Control Registers
0x4000_4100 – 0x4000_47FF	WWDT_BA	Window Watchdog Timer Control Registers
0x4001_0000 – 0x4001_3FFF	TMR_BA	Timer0/Timer1 Control Registers
0x4002_0000 – 0x4002_3FFF	I2C0_BA	I^2C0 Interface Control Registers
0x4003_0000 – 0x4003_3FFF	SPI_BA	SPI with Master/slave Function Control Registers
0x4004_0000 – 0x4004_3FFF	PWM_BA	PWM Control Registers
0x4005_0000 – 0x4005_3FFF	UART0_BA	UART0 Control Registers
0x400D_0000 – 0x400D_3FFF	ACMP_BA	Analog Comparator Control Registers
0x400E_0000 – 0x400E_3FFF	ADC_BA	Analog-Digital-Converter (ADC) Control Registers
0x4012_0000 – 0x4012_3FFF	I2C1_BA	I^2C1 Interface Control Registers
0x4015_0000 – 0x4015_3FFF	UART1_BA	UART1 Control Registers
System Control Space (0xE000_E000 – 0xE000_EFFF)		
0xE000_E010 – 0xE000_E0FF	SCS_BA	System Timer Control Registers
0xE000_E100 – 0xE000_ECFF	SCS_BA	Nested Vectored Interrupt Control Registers
0xE000_ED00 – 0xE000_ED8F	SCS_BA	System Control Block Registers

Table 6.2-6 Address Space Assignments for On-Chip Modules

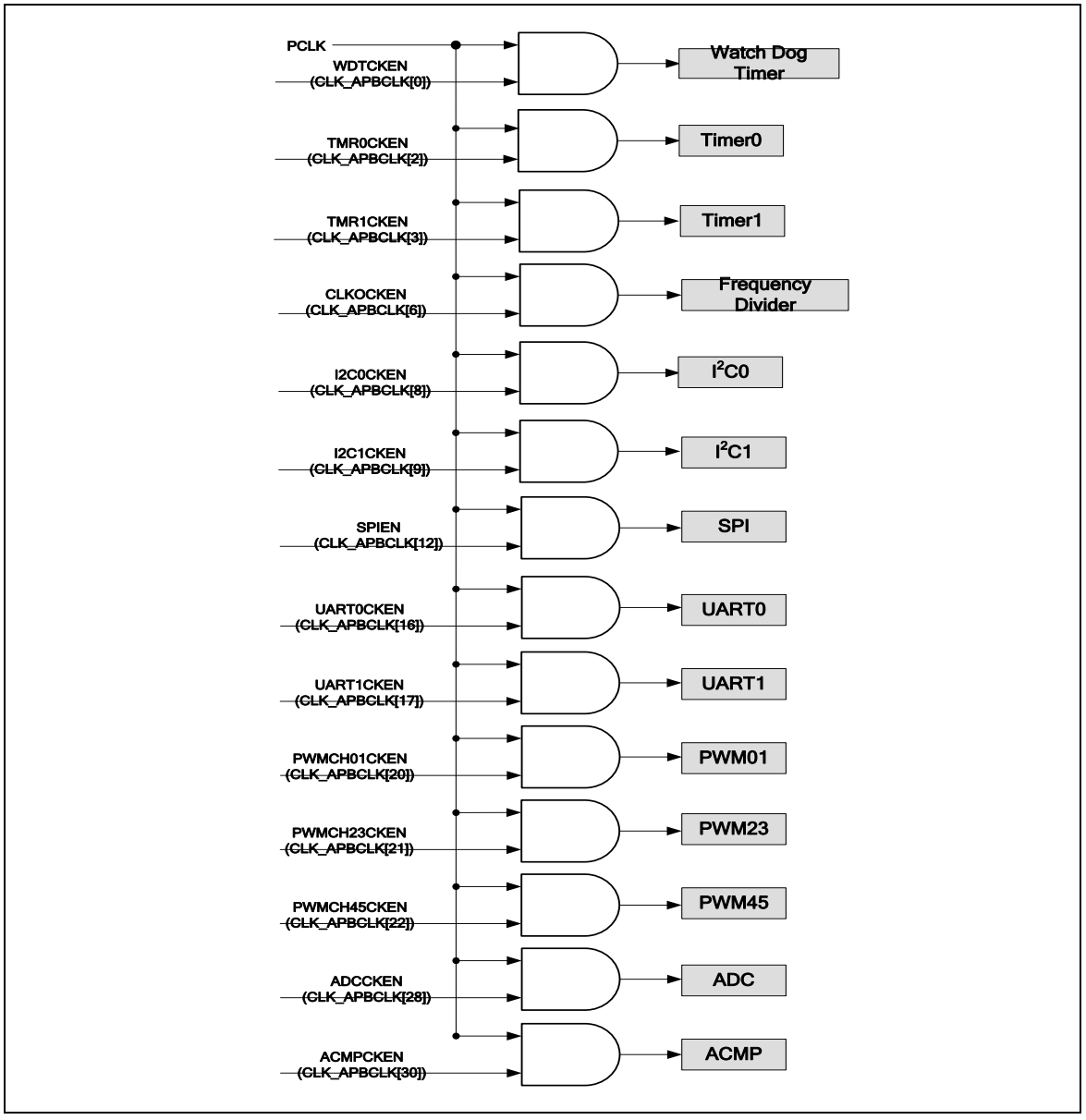

Figure 6.3-5 Peripherals Bus Clock Source Selection for PCLK

6.4 Flash Memory Controller (FMC)

6.4.1 Overview

The NuMicro® Mini58 series is equipped with 32 Kbytes on-chip embedded flash for application and Data Flash to store some application dependent data. A User Configuration block provides for system initialization. A 2.5 Kbytes loader ROM (LDROM) is used for In-System-Programming (ISP) function. A 512 bytes security protection ROM (SPROM) can conceal user program. This chip also supports In-Application-Programming (IAP) function, user switches the code executing without the chip reset after the embedded flash updated.

6.4.2 Features

- Supports 32 Kbytes application ROM (APROM).
- Supports 2.5 Kbytes loader ROM (LDROM).
- Supports configurable Data Flash size to share with APROM.
- Supports 512 bytes security protection ROM (SPROM) to conceal user program.
- Supports 12 bytes User Configuration block to control system initialization.
- Supports 512 bytes page erase for all embedded flash.
- Supports CRC-32 checksum calculation function.
- Supports In-System-Programming (ISP) / In-Application-Programming (IAP) to update embedded flash memory.

- Each pin of PWM0_CH0 to PWM0_CH5 has independent polarity setting control
- Hardware fault brake protections
  - Supports software trigger
  - Two Interrupt source types:
    - Synchronously requested at PWM frequency when down counter comparison matched (edge- and center-aligned type) or underflow (edge-aligned type)
    - Requested when external fault brake asserted
      - BKP0: EINT0 or CPO1
      - BKP1: EINT1 or CPO0
- The PWM signals before polarity control stage are defined in the view of positive logic. The PWM ports is active high or active low are controlled by polarity control register
- Supports mask aligned function
- Supports independently rising CMP matching, PERIOD matching, falling CMP matching (in Center-aligned type), period matching to trigger ADC conversion
- Timer comparing matching event trigger PWM to do phase change in BLDC application
- Supports ACMP output event trigger PWM to force PWM output at most one period low, this feature is usually for step motor control
- Provides interrupt accumulation function

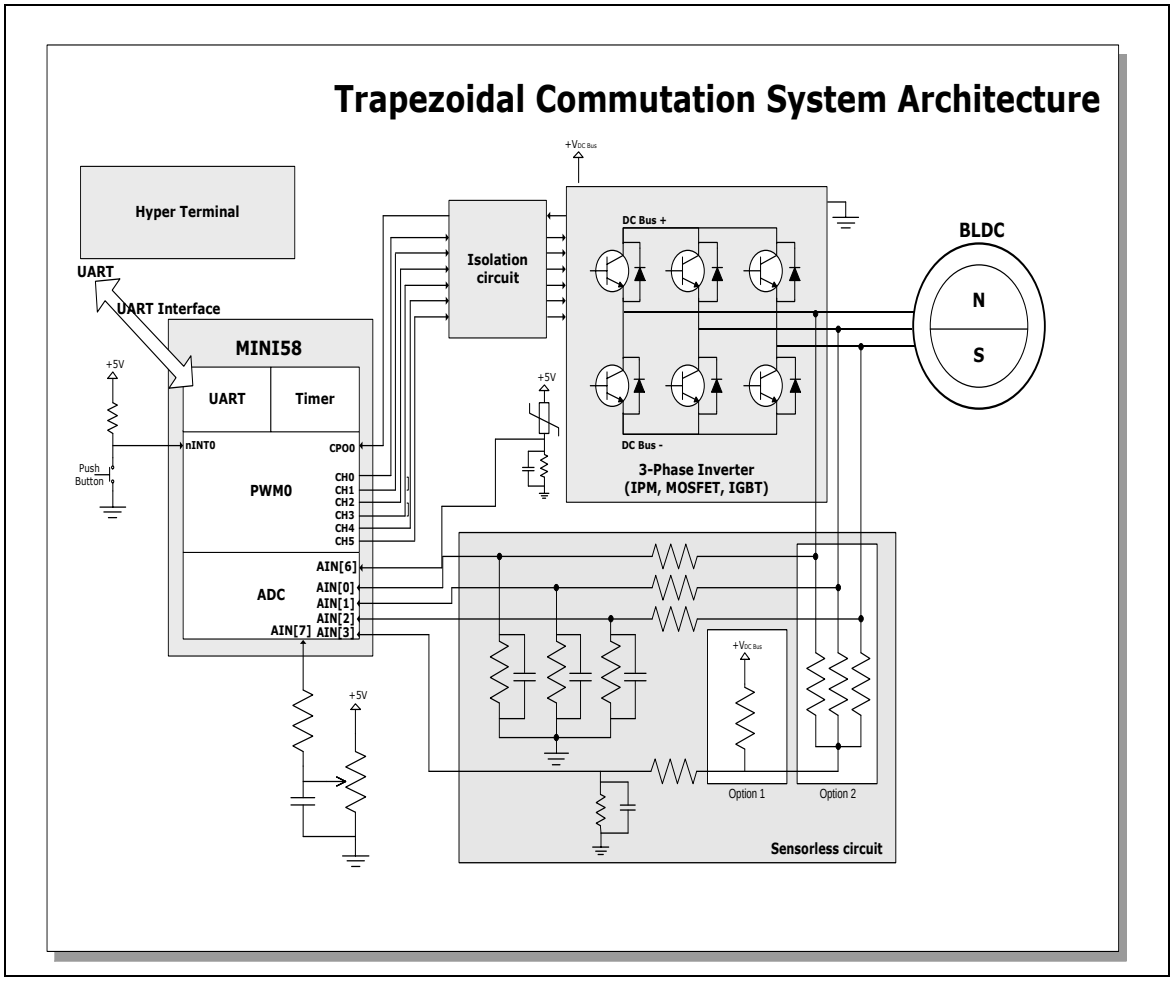

Figure 6.7-1 Application Circuit Diagram

6.11 I²C Serial Interface Controller (I²C)

6.11.1 Overview

I²C is a two-wire, bi-directional serial bus that provides a simple and efficient method for data exchange between devices. The I²C standard is a true multi-master bus including collision detection and arbitration that prevents data corruption if two or more masters attempt to control the bus simultaneously. There are two sets of I²C controller and only I²C0 supports Power-down wake-up function.

6.11.2 Features

The I²C bus uses two wires (SDA and SCL) to transfer information between devices connected to the bus. The main features of the bus include:

- Supports up to two I²C ports
- Master/Slave mode
- Bi-directional data transfer between masters and slaves
- Multi-master bus
- Arbitration between simultaneously transmitting masters without corruption of serial data on the bus
- Serial clock synchronization allowing devices with different bit rates to communicate via one serial bus
- Serial clock synchronization can be used as a handshake mechanism to suspend and resume serial transfer
- Built-in 14-bit time-out counter that requests the I²C interrupt if the I²C bus hangs up and timer-out counter overflows
- Programmable clocks allowing for versatile rate control
- Supports 7-bit addressing mode
- Supports multiple address recognition (four slave address registers with mask option)
- Supports Power-down wake-up function (Only I²C0 channel support this function)
- Supports two-level buffer function

6.12 Serial Peripheral Interface (SPI)

6.12.1 Overview

The Serial Peripheral Interface (SPI) applies to synchronous serial data communication and allows full duplex transfer. Devices communicate in Master/Slave mode with 4-wire bi-direction interface. The SPI controller performing a serial-to-parallel conversion on data received from a peripheral device, and a parallel-to-serial conversion on data transmitted to a peripheral device. SPI controller can be configured as a master or a slave device.

6.12.2 Features

- Supports Master or Slave mode operation
- Configurable transfer bit length
- Provides four 32-bit FIFO buffers
- Supports MSB first or LSB first transfer
- Supports byte reorder function
- Supports byte or word suspend mode
- Supports Slave 3-wire mode

6.14 Analog Comparator (ACMP)

6.14.1 Overview

The NuMicro® Mini58 series contains two comparators which can be used in a number of different configurations. The comparator output is logic 1 when positive input is greater than negative input, otherwise the output is 0. Each comparator can be configured to generate interrupt when the comparator output value changes.

6.14.2 Features

- Analog input voltage range: 0 ~ AV_{DD}
- Supports Hysteresis function
- Optional internal reference voltage source for each comparator negative input
- ACMP0 supports:
  - Four positive sources
    - P1.5, P1.0, P1.2, or P1.3
  - Three negative sources
    - P1.4
    - Internal Comparator Reference Voltage (CRV)
    - Internal band-gap voltage (V_{BG})
- ACMP1 supports:
  - Four positive sources
    - P3.1, P3.2, P3.4, or P3.5
  - Three negative sources
    - P3.0
    - Internal Comparator Reference Voltage (CRV)
    - Internal band-gap voltage (V_{BG})

8 ELECTRICAL CHARACTERISTICS

8.1 Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
V_{DD}– V_{SS}	DC Power Supply	-0.3	+7.0	V
V_{IN}	Input Voltage	V_{SS} -0.3	V_{DD} +0.3	V
$1/t_{CLCL}$	Oscillator Frequency	4	24	MHz
T_A	Operating Temperature	-40	+105	℃
T_{ST}	Storage Temperature	-55	+150	℃
I_{DD}	Maximum Current into V_{DD}	-	120	mA
I_{SS}	Maximum Current out of V_{SS}	-	120	mA
I_{IO}	Maximum Current sunk by an I/O pin	-	35	mA
	Maximum Current sourced by an I/O pin	-	35	mA
	Maximum Current sunk by total I/O pins	-	100	mA
	Maximum Current sourced by total I/O pins	-	100	mA

Note: Exposure to conditions beyond those listed under absolute maximum ratings may adversely affects the life and reliability of the device.

2. XTAL1 is a CMOS input.

3. Pins of P0, P1, P2, P3, P4 and P5 can source a transition current when they are being externally driven from 1 to 0. In the condition of V_{DD}=5.5V, the transition current reaches its maximum value when V_{IN} approximates to 2V.

4. Only enable modules which support 10 kHz LIRC clock source

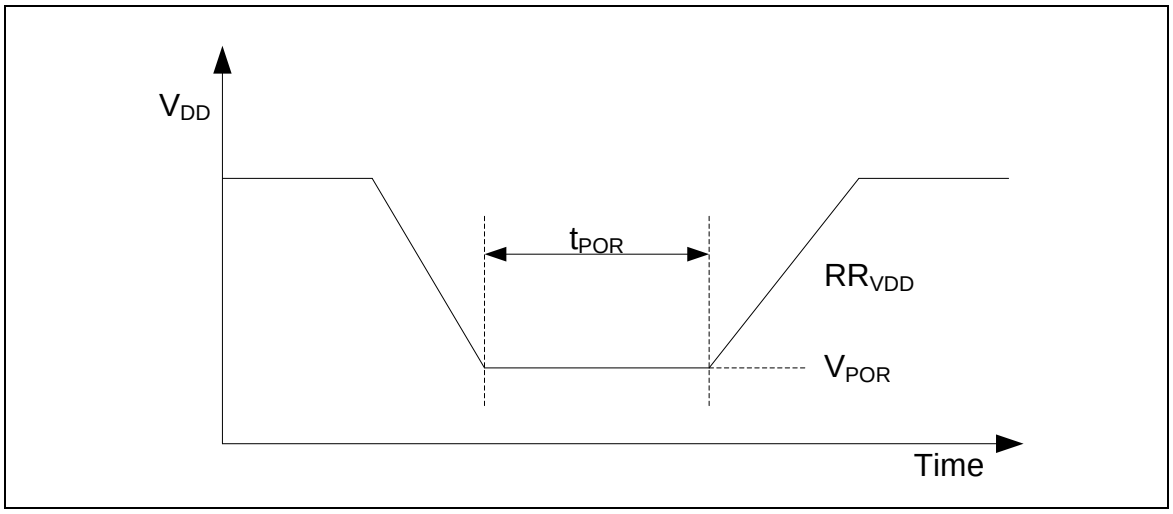

Figure 8.4-1 Power-up Ramp Condition

8.4.6 Comparator

Symbol	Parameter	Min	Typ	Max	Unit	Test Condition
V_{CMP}	Supply Voltage	2.5	-	5.5	V	
T_A	Temperature	-40	25	105	℃	-
I_{CMP}	Operation Current	-	40	80	μA	AV_{DD}=5V
V_{OFF}	Input Offset Voltage		10	20	mV	-
V_{SW}	Output Swing	0.1	-	AV_{DD} – 0.1	V	-
V_{COM}	Input Common Mode Range	0.1	-	AV_{DD} – 0.1	V	-
-	DC Gain	40	70	-	dB	-
T_{PGD}	Propagation Delay	-	200	-	ns	V_{COM}=1.2 V, V_{DIFF}=0.1 V
V_{HYS}	Hysteresis	-	±30	±60	mV	V_{COM}=1.2 V
T_{STB}	Stable time	-	-	1	μs	