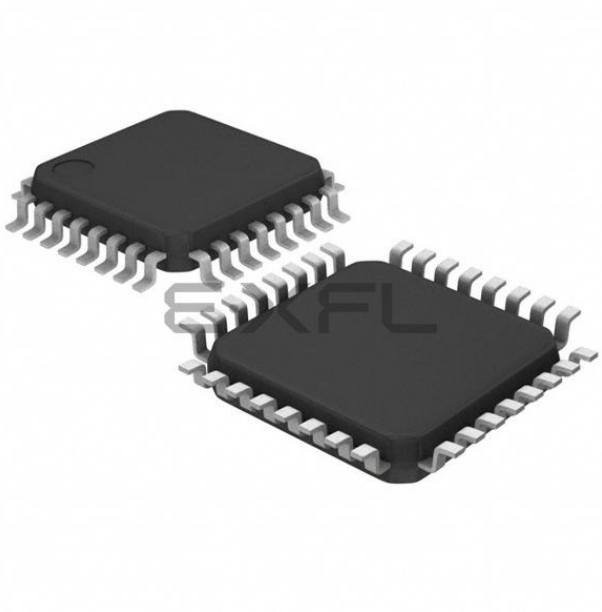

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	CIP-51 8051
Core Size	8-Bit
Speed	48MHz
Connectivity	I²C, SMBus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	25
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4.25K x 8
Voltage - Supply (Vcc/Vdd)	2.65V ~ 3.6V
Data Converters	A/D 20x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-QFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm8ub20f64g-b-qfp32

3. System Overview

3.1 Introduction

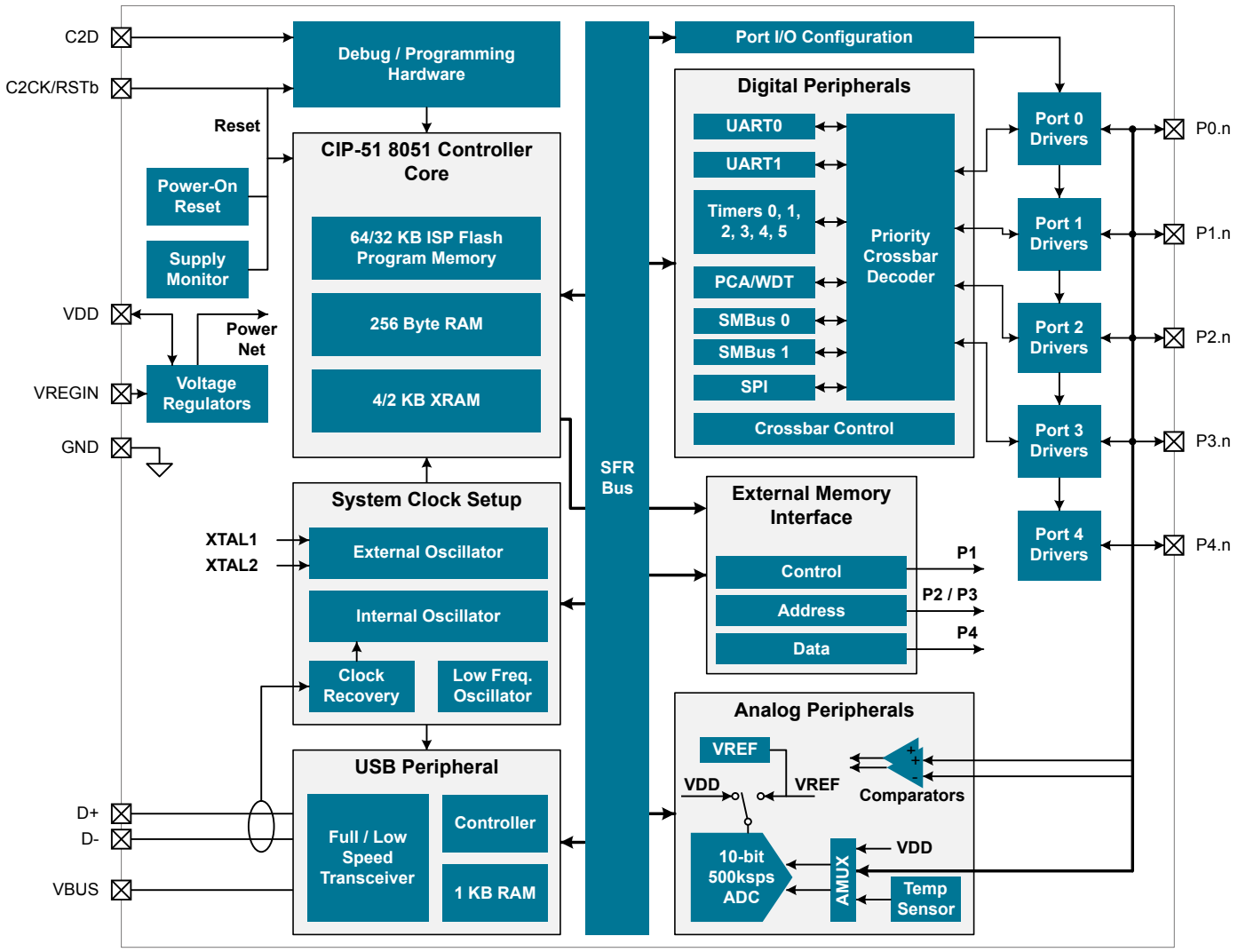


Figure 3.1. Detailed EFM8UB2 Block Diagram

This section describes the EFM8UB2 family at a high level. For more information on each module including register definitions, see the EFM8UB2 Reference Manual.

3.2 Power

All internal circuitry draws power from the VDD supply pin. External I/O pins are powered from the VIO supply voltage (or VDD on devices without a separate VIO connection), while most of the internal circuitry is supplied by an on-chip LDO regulator. Control over the device power can be achieved by enabling/disabling individual peripherals as needed. Each analog peripheral can be disabled when not in use and placed in low power mode. Digital peripherals, such as timers and serial buses, have their clocks gated off and draw little power when they are not in use.

Table 3.1. Power Modes

Power Mode	Details	Mode Entry	Wake-Up Sources
Normal	Core and all peripherals clocked and fully operational	—	—
Idle	• Core halted • All peripherals clocked and fully operational • Code resumes execution on wake event	Set IDLE bit in PCON0	Any interrupt
Suspend	• Core and peripheral clocks halted • Code resumes execution on wake event	1. Switch SYSCLK to HFOSC0 2. Set SUSPEND bit in HFO0CN	USB0 Bus Activity
Stop	• All internal power nets shut down • Pins retain state • Exit on any reset source	Set STOP bit in PCON0	Any reset source
Shutdown	• All internal power nets shut down • 5V regulator remains active (if enabled) • Pins retain state • Exit on pin or power-on reset	1. Set STOPCF bit in REG01CN 2. Set STOP bit in PCON0	• RSTb pin reset • Power-on reset

3.3 I/O

Digital and analog resources are externally available on the device's multi-purpose I/O pins. Port pins P0.0-P3.7 can be defined as general-purpose I/O (GPIO), assigned to one of the internal digital resources through the crossbar or dedicated channels, or assigned to an analog function. Port pins P4.0-P4.7 can be used as GPIO. Additionally, the C2 Interface Data signal (C2D) is shared with P3.0 on some packages.

- Up to 40 multi-functions I/O pins, supporting digital and analog functions.
- Flexible priority crossbar decoder for digital peripheral assignment.
- Two direct-pin interrupt sources with dedicated interrupt vectors (INT0 and INT1) available on P0 pins.

3.4 Clocking

The CPU core and peripheral subsystem may be clocked by both internal and external oscillator resources. By default, the system clock comes up running from the 48 MHz oscillator divided by 4, then divided by 8 (1.5 MHz).

- Provides clock to core and peripherals.
- 48 MHz internal oscillator (HFOSC0), accurate to ±1.5% over supply and temperature corners: accurate to +/- 0.25% when using USB clock recovery.
- 80 kHz low-frequency oscillator (LFOSC0).
- External RC, C, CMOS, and high-frequency crystal clock options (EXTCLK) for QFP48 packages.
- External CMOS clock option (EXTCLK) for QFP32 and QFN32 packages.
- Internal oscillator has clock divider with eight settings for flexible clock scaling: 1, 2, 4, or 8.

3.5 Counters/Timers and PWM

Programmable Counter Array (PCA0)

The programmable counter array (PCA) provides multiple channels of enhanced timer and PWM functionality while requiring less CPU intervention than standard counter/timers. The PCA consists of a dedicated 16-bit counter/timer and one 16-bit capture/compare module for each channel. The counter/timer is driven by a programmable timebase that has flexible external and internal clocking options. Each capture/compare module may be configured to operate independently in one of five modes: Edge-Triggered Capture, Software Timer, High-Speed Output, Frequency Output, or Pulse-Width Modulated (PWM) Output. Each capture/compare module has its own associated I/O line (CEXn) which is routed through the crossbar to port I/O when enabled.

- 16-bit time base.
- Programmable clock divisor and clock source selection.
- Up to five independently-configurable channels
- 8- or 16-bit PWM modes (edge-aligned operation).
- Frequency output mode.
- Capture on rising, falling or any edge.
- Compare function for arbitrary waveform generation.
- Software timer (internal compare) mode.
- Integrated watchdog timer.

Timers (Timer 0, Timer 1, Timer 2, Timer 3, Timer 4, and Timer 5)

Several counter/timers are included in the device: two are 16-bit counter/timers compatible with those found in the standard 8051, and the rest are 16-bit auto-reload timers for timing peripherals or for general purpose use. These timers can be used to measure time intervals, count external events and generate periodic interrupt requests. Timer 0 and Timer 1 are nearly identical and have four primary modes of operation. The other timers offer both 16-bit and split 8-bit timer functionality with auto-reload and capture capabilities.

Timer 0 and Timer 1 include the following features:

- Standard 8051 timers, supporting backwards-compatibility with firmware and hardware.
- Clock sources include SYSCLK, SYSCLK divided by 12, 4, or 48, the External Clock divided by 8, or an external pin.
- 8-bit auto-reload counter/timer mode
- 13-bit counter/timer mode
- 16-bit counter/timer mode
- Dual 8-bit counter/timer mode (Timer 0)

Timer 2, Timer 3, Timer 4, and Timer 5 are 16-bit timers including the following features:

- Clock sources include SYSCLK, SYSCLK divided by 12, or the External Clock divided by 8.
- 16-bit auto-reload timer mode
- Dual 8-bit auto-reload timer mode
- USB start-of-frame or falling edge of LFOSC0 capture (Timer 2 and Timer 3)

Watchdog Timer (WDT0)

The device includes a programmable watchdog timer (WDT) integrated within the PCA0 peripheral. A WDT overflow forces the MCU into the reset state. To prevent the reset, the WDT must be restarted by application software before overflow. If the system experiences a software or hardware malfunction preventing the software from restarting the WDT, the WDT overflows and causes a reset. Following a reset, the WDT is automatically enabled and running with the default maximum time interval. If needed, the WDT can be disabled by system software. The state of the RSTb pin is unaffected by this reset.

The Watchdog Timer integrated in the PCA0 peripheral has the following features:

- Programmable timeout interval
- Runs from the selected PCA clock source
- Automatically enabled after any system reset

Low Current Comparators (CMP0, CMP1)

Analog comparators are used to compare the voltage of two analog inputs, with a digital output indicating which input voltage is higher. External input connections to device I/O pins and internal connections are available through separate multiplexers on the positive and negative inputs. Hysteresis, response time, and current consumption may be programmed to suit the specific needs of the application.

The comparator module includes the following features:

- Up to 5 external positive inputs.
- Up to 5 external negative inputs.
- Synchronous and asynchronous outputs can be routed to pins via crossbar.
- Programmable hysteresis between 0 and +/-20 mV.
- Programmable response time.
- Interrupts generated on rising, falling, or both edges.

3.8 Reset Sources

Reset circuitry allows the controller to be easily placed in a predefined default condition. On entry to this reset state, the following occur:

- The core halts program execution.
- Module registers are initialized to their defined reset values unless the bits reset only with a power-on reset.
- External port pins are forced to a known state.
- Interrupts and timers are disabled.

All registers are reset to the predefined values noted in the register descriptions unless the bits only reset with a power-on reset. The contents of RAM are unaffected during a reset; any previously stored data is preserved as long as power is not lost. The Port I/O latches are reset to 1 in open-drain mode. Weak pullups are enabled during and after the reset. For Supply Monitor and power-on resets, the RSTb pin is driven low until the device exits the reset state. On exit from the reset state, the program counter (PC) is reset, and the system clock defaults to an internal oscillator. The Watchdog Timer is enabled, and program execution begins at location 0x0000.

Reset sources on the device include:

- Power-on reset
- External reset pin
- Comparator reset
- Software-triggered reset
- Supply monitor reset (monitors VDD supply)
- Watchdog timer reset
- Missing clock detector reset
- Flash error reset
- USB reset

3.9 Debugging

The EFM8UB2 devices include an on-chip Silicon Labs 2-Wire (C2) debug interface to allow flash programming and in-system debugging with the production part installed in the end application. The C2 interface uses a clock signal (C2CK) and a bi-directional C2 data signal (C2D) to transfer information between the device and a host system. See the C2 Interface Specification for details on the C2 protocol.

4.1.12 Comparators

Table 4.12. Comparators

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Response Time, CPMD = 00 (Highest Speed)	t_{RESP0}	+100 mV Differential	—	100	—	ns
		-100 mV Differential	—	250	—	ns
Response Time, CPMD = 11 (Lowest Power)	t_{RESP3}	+100 mV Differential	—	1.05	—	µs
		-100 mV Differential	—	5.2	—	µs
Positive Hysteresis Mode 0 (CPMD = 00)	HYS_{CP+}	CPHYP = 00	—	0.4	—	mV
		CPHYP = 01	—	8	—	mV
		CPHYP = 10	—	16	—	mV
		CPHYP = 11	—	32	—	mV
Negative Hysteresis Mode 0 (CPMD = 00)	HYS_{CP-}	CPHYN = 00	—	-0.4	—	mV
		CPHYN = 01	—	-8	—	mV
		CPHYN = 10	—	-16	—	mV
		CPHYN = 11	—	-32	—	mV
Positive Hysteresis Mode 1 (CPMD = 01)	HYS_{CP+}	CPHYP = 00	—	0.5	—	mV
		CPHYP = 01	—	6	—	mV
		CPHYP = 10	—	12	—	mV
		CPHYP = 11	—	24	—	mV
Negative Hysteresis Mode 1 (CPMD = 01)	HYS_{CP-}	CPHYN = 00	—	-0.5	—	mV
		CPHYN = 01	—	-6	—	mV
		CPHYN = 10	—	-12	—	mV
		CPHYN = 11	—	-24	—	mV
Positive Hysteresis Mode 2 (CPMD = 10)	HYS_{CP+}	CPHYP = 00	—	0.7	—	mV
		CPHYP = 01	—	4.5	—	mV
		CPHYP = 10	—	9	—	mV
		CPHYP = 11	—	18	—	mV
Negative Hysteresis Mode 2 (CPMD = 10)	HYS_{CP-}	CPHYN = 00	—	-0.6	—	mV
		CPHYN = 01	—	-4.5	—	mV
		CPHYN = 10	—	-9	—	mV
		CPHYN = 11	—	-18	—	mV
Positive Hysteresis Mode 3 (CPMD = 11)	HYS_{CP+}	CPHYP = 00	—	1.5	—	mV
		CPHYP = 01	—	4	—	mV
		CPHYP = 10	—	8	—	mV
		CPHYP = 11	—	16	—	mV

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Negative Hysteresis Mode 3 (CPMD = 11)	HYS_{CP-}	CPHYN = 00	—	-1.5	—	mV
		CPHYN = 01	—	-4	—	mV
		CPHYN = 10	—	-8	—	mV
		CPHYN = 11	—	-16	—	mV
Input Range (CP+ or CP-)	V_{IN}		-0.25	—	V_{DD}+0.25	V
Input Pin Capacitance	C_{CP}		—	7.5	—	pF
Common-Mode Rejection Ratio	$CMRR_{CP}$		—	60	—	dB
Power Supply Rejection Ratio	$PSRR_{CP}$		—	60	—	dB
Input Offset Voltage	V_{OFF}	T_A = 25 °C	-10	0	10	mV

4.1.13 Port I/O

Table 4.13. Port I/O

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output High Voltage	V_{OH}	I_{OH} = -3 mA	V_{DD} - 0.7	—	—	V
		I_{OH} = -10 µA	V_{DD} - 0.1	—	—	V
Output Low Voltage	V_{OL}	I_{OL} = 8.5 mA	—	—	0.6	V
		I_{OL} = 10 µA	—	—	0.1	V
Input High Voltage	V_{IH}		2.0	—	—	V
Input Low Voltage	V_{IL}		—	—	0.8	V
Pin Capacitance	C_{IO}		—	7	—	pF
Weak Pull-Up Current (V_{IN} = 0 V)	I_{PU}	V_{DD} = 3.6	-50	-15	—	µA
Input Leakage (Pullups off or Analog)	I_{LK}	GND < V_{IN} < V_{DD}	-1	—	1	µA
Input Leakage Current with V_{IN} above V_{DD}	I_{LK}	V_{DD} < V_{IN} < V_{DD}+2.0 V	0	5	150	µA

4.1.14 USB Transceiver

Table 4.14. USB Transceiver

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
VBUS Detection Input Low Voltage	V_{BUS_L}		—	—	1.0	V
VBUS Detection Input High Voltage	V_{BUS_H}		3.0	—	—	V
Transmitter						
Output High Voltage	V_{OH}	V_{DD} ≥3.0V	2.8	—	—	V
Output Low Voltage	V_{OL}	V_{DD} ≥3.0V	—	—	0.8	V
Output Crossover Point	V_{CRS}		1.3	—	2.0	V
Output Impedance	Z_{DRV}	Driving High	—	38	—	Ω
		Driving Low	—	38	—	
Pull-up Resistance	R_{PU}	Full Speed (D+ Pull-up)	1.425	1.5	1.575	kΩ
		Low Speed (D- Pull-up)				
Output Rise Time	T_R	Low Speed	75	—	300	ns
		Full Speed	4	—	20	ns
Output Fall Time	T_F	Low Speed	75	—	300	ns
		Full Speed	4	—	20	ns
Receiver						V
Differential Input Sensitivity	V_{DI}	| (D+) - (D-) |	0.2	—	—	V
Differential Input Common Mode Range	V_{CM}		0.8	—	2.5	V
Input Leakage Current	I_L	Pullups Disabled	—	<1.0	—	µA
Refer to the USB Specification for timing diagrams and symbol definitions.						

Table 6.1. Pin Definitions for EFM8UB2x-QFP48

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
1	P0.5	Multifunction I/O	Yes	UART0_RX INT0.5 INT1.5	
2	P0.4	Multifunction I/O	Yes	UART0_TX INT0.4 INT1.4	ADC0P.18 ADC0N.18 CMP0N.4
3	P0.3	Multifunction I/O	Yes	INT0.3 INT1.3	ADC0P.17 ADC0N.17 CMP0P.4
4	P0.2	Multifunction I/O	Yes	INT0.2 INT1.2	
5	P0.1	Multifunction I/O	Yes	INT0.1 INT1.1	
6	P0.0	Multifunction I/O	Yes	INT0.0 INT1.0	
7	GND	Ground			
8	D+	USB Data Positive			
9	D-	USB Data Negative			
10	VDD	Supply Power Input / 5V Regulator Output			
11	VREGIN	5V Regulator Input			
12	VBUS	USB VBUS Sense Input		VBUS	
13	RST / C2CK	Active-low Reset / C2 Debug Clock			
14	C2D	C2 Debug Data			
15	P4.7	Multifunction I/O		EMIF_D7 EMIF_AD7m	ADC0P.34 ADC0N.34
16	P4.6	Multifunction I/O		EMIF_D6 EMIF_AD6m	ADC0P.15 ADC0N.15 CMP1N.3
17	P4.5	Multifunction I/O		EMIF_D5 EMIF_AD5m	ADC0P.14 ADC0N.14 CMP1P.3

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
18	P4.4	Multifunction I/O		EMIF_D4 EMIF_AD4m	ADC0P.13 ADC0N.13 CMP0N.3
19	P4.3	Multifunction I/O		EMIF_D3 EMIF_AD3m	ADC0P.12 ADC0N.12 CMP0P.3
20	P4.2	Multifunction I/O		EMIF_D2 EMIF_AD2m	ADC0P.33 ADC0N.33
21	P4.1	Multifunction I/O		EMIF_D1 EMIF_AD1m	ADC0P.32 ADC0N.32
22	P4.0	Multifunction I/O		EMIF_D0 EMIF_AD0m	ADC0P.11 ADC0N.11 CMP1N.2
23	P3.7	Multifunction I/O	Yes	EMIF_A7 EMIF_A15m	ADC0P.10 ADC0N.10 CMP1P.2
24	P3.6	Multifunction I/O	Yes	EMIF_A6 EMIF_A14m	ADC0P.29 ADC0N.29
25	P3.5	Multifunction I/O	Yes	EMIF_A5 EMIF_A13m	ADC0P.9 ADC0N.9 CMP0N.2
26	P3.4	Multifunction I/O	Yes	EMIF_A4 EMIF_A12m	ADC0P.8 ADC0N.8 CMP0P.2
27	P3.3	Multifunction I/O	Yes	EMIF_A3 EMIF_A11m	ADC0P.28 ADC0N.28
28	P3.2	Multifunction I/O	Yes	EMIF_A2 EMIF_A10m	ADC0P.27 ADC0N.27
29	P3.1	Multifunction I/O	Yes	EMIF_A1 EMIF_A9m	ADC0P.7 ADC0N.7 CMP1N.1
30	P3.0	Multifunction I/O	Yes	EMIF_A0 EMIF_A8m	ADC0P.6 ADC0N.6 CMP1P.1
31	P2.7	Multifunction I/O	Yes	EMIF_A15	ADC0P.26 ADC0N.26

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
32	P2.6	Multifunction I/O	Yes	EMIF_A14	ADC0P.5 ADC0N.5 CMP0N.1
33	P2.5	Multifunction I/O	Yes	EMIF_A13	ADC0P.4 ADC0N.4 CMP0P.1
34	P2.4	Multifunction I/O	Yes	EMIF_A12	ADC0P.25 ADC0N.25
35	P2.3	Multifunction I/O	Yes	EMIF_A11	ADC0P.3 ADC0N.3 CMP1N.0
36	P2.2	Multifunction I/O	Yes	EMIF_A10	ADC0P.2 ADC0N.2 CMP1P.0
37	P2.1	Multifunction I/O	Yes	EMIF_A9	ADC0P.1 ADC0N.1 CMP0N.0
38	P2.0	Multifunction I/O	Yes	EMIF_A8	ADC0P.0 ADC0N.0 CMP0P.0
39	P1.7	Multifunction I/O	Yes	EMIF_WRb	ADC0P.24 ADC0N.24
40	P1.6	Multifunction I/O	Yes	EMIF_RDb	ADC0P.23 ADC0N.23
41	P1.5	Multifunction I/O	Yes		VREF
42	P1.4	Multifunction I/O	Yes	CNVSTR	
43	P1.3	Multifunction I/O	Yes	EMIF_ALEm	ADC0P.22 ADC0N.22
44	P1.2	Multifunction I/O	Yes		ADC0P.20 ADC0N.20 CMP1N.4
45	P1.1	Multifunction I/O	Yes		ADC0P.19 ADC0N.19 CMP1P.4
46	P1.0	Multifunction I/O	Yes		ADC0P.21 ADC0N.21

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
47	P0.7	Multifunction I/O	Yes	XTAL2 EXTCLK INT0.7 INT1.7	
48	P0.6	Multifunction I/O	Yes	XTAL1 INT0.6 INT1.6	

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
5	D-	USB Data Negative			
6	VDD	Supply Power Input / 5V Regulator Output			
7	VREGIN	5V Regulator Input			
8	VBUS	USB VBUS Sense Input		VBUS	
9	RST / C2CK	Active-low Reset / C2 Debug Clock			
10	P3.0 / C2D	Multifunction I/O / C2 Debug Data	Yes		ADC0P.16 ADC0N.16
11	P2.7	Multifunction I/O	Yes		ADC0P.15 ADC0N.15
12	P2.6	Multifunction I/O	Yes		ADC0P.14 ADC0N.14
13	P2.5	Multifunction I/O	Yes		ADC0P.13 ADC0N.13 CMP0N.3
14	P2.4	Multifunction I/O	Yes		ADC0P.12 ADC0N.12 CMP0P.3
15	P2.3	Multifunction I/O	Yes		ADC0P.11 ADC0N.11 CMP1N.2
16	P2.2	Multifunction I/O	Yes		ADC0P.10 ADC0N.10 CMP1P.2
17	P2.1	Multifunction I/O	Yes		ADC0P.9 ADC0N.9 CMP0N.2
18	P2.0	Multifunction I/O	Yes		ADC0P.8 ADC0N.8 CMP0P.2
19	P1.7	Multifunction I/O	Yes		ADC0P.7 ADC0N.7 CMP1N.1

6.3 EFM8UB2x-QFN32 Pin Definitions

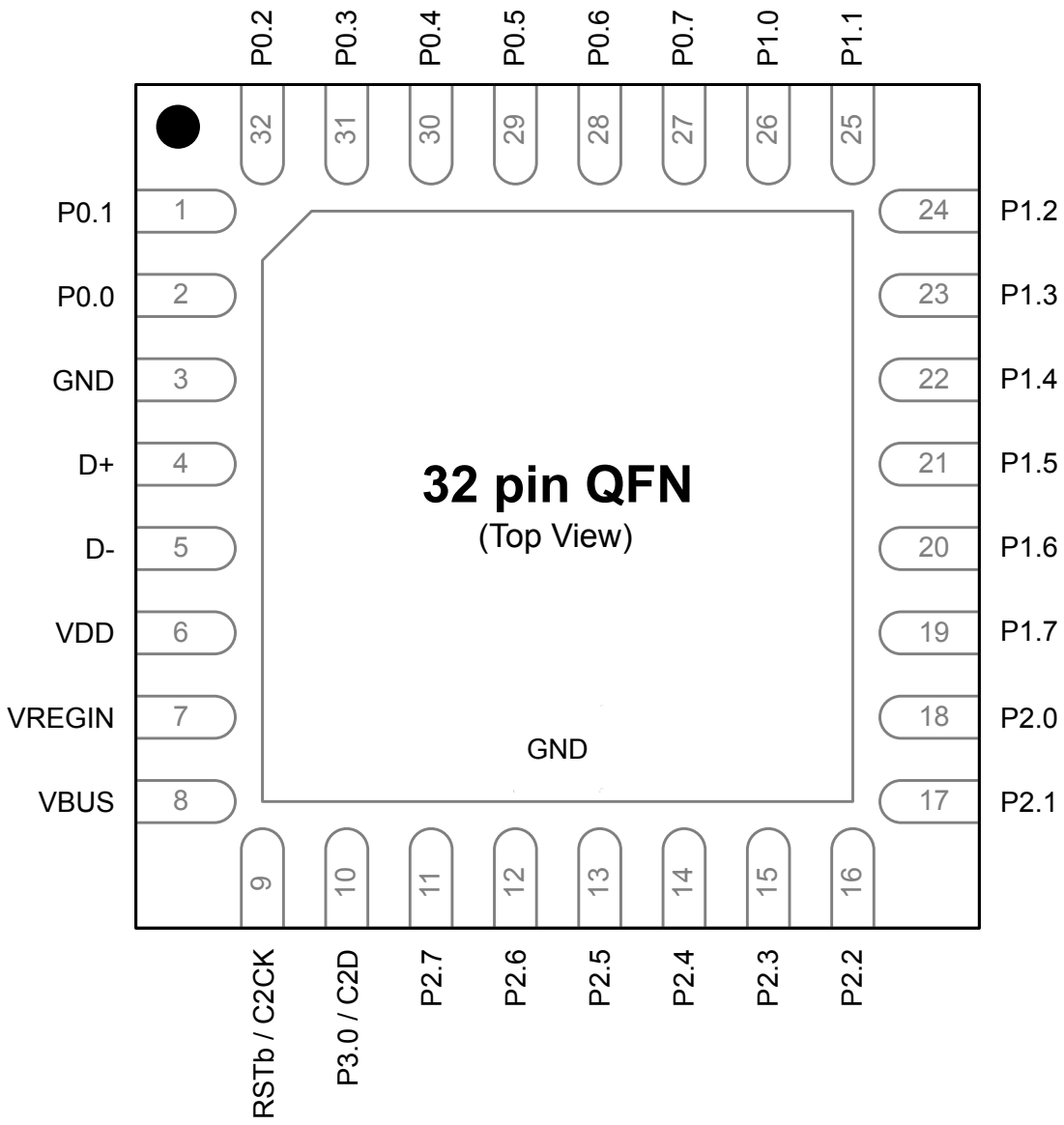


Figure 6.3. EFM8UB2x-QFN32 Pinout

Table 6.3. Pin Definitions for EFM8UB2x-QFN32

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
1	P0.1	Multifunction I/O	Yes	INT0.1 INT1.1	ADC0P.18 ADC0N.18 CMP0N.4

Pin Number	Pin Name	Description	Crossbar Capability	Additional Digital Functions	Analog Functions
18	P2.0	Multifunction I/O	Yes		ADC0P.8 ADC0N.8 CMP0P.2
19	P1.7	Multifunction I/O	Yes		ADC0P.7 ADC0N.7 CMP1N.1
20	P1.6	Multifunction I/O	Yes		ADC0P.6 ADC0N.6 CMP1P.1
21	P1.5	Multifunction I/O	Yes		ADC0P.5 ADC0N.5 CMP0N.1
22	P1.4	Multifunction I/O	Yes		ADC0P.4 ADC0N.4 CMP0P.1
23	P1.3	Multifunction I/O	Yes		ADC0P.3 ADC0N.3 CMP1N.0
24	P1.2	Multifunction I/O	Yes		ADC0P.2 ADC0N.2 CMP1P.0
25	P1.1	Multifunction I/O	Yes		ADC0P.1 ADC0N.1 CMP0N.0
26	P1.0	Multifunction I/O	Yes		ADC0P.0 ADC0N.0 CMP0P.0
27	P0.7	Multifunction I/O	Yes	INT0.7 INT1.7	VREF
28	P0.6	Multifunction I/O	Yes	CNVSTR INT0.6 INT1.6	
29	P0.5	Multifunction I/O	Yes	INT0.5 INT1.5 UART0_RX	ADC0P.20 ADC0N.20 CMP1N.4

7. QFP48 Package Specifications

7.1 QFP48 Package Dimensions

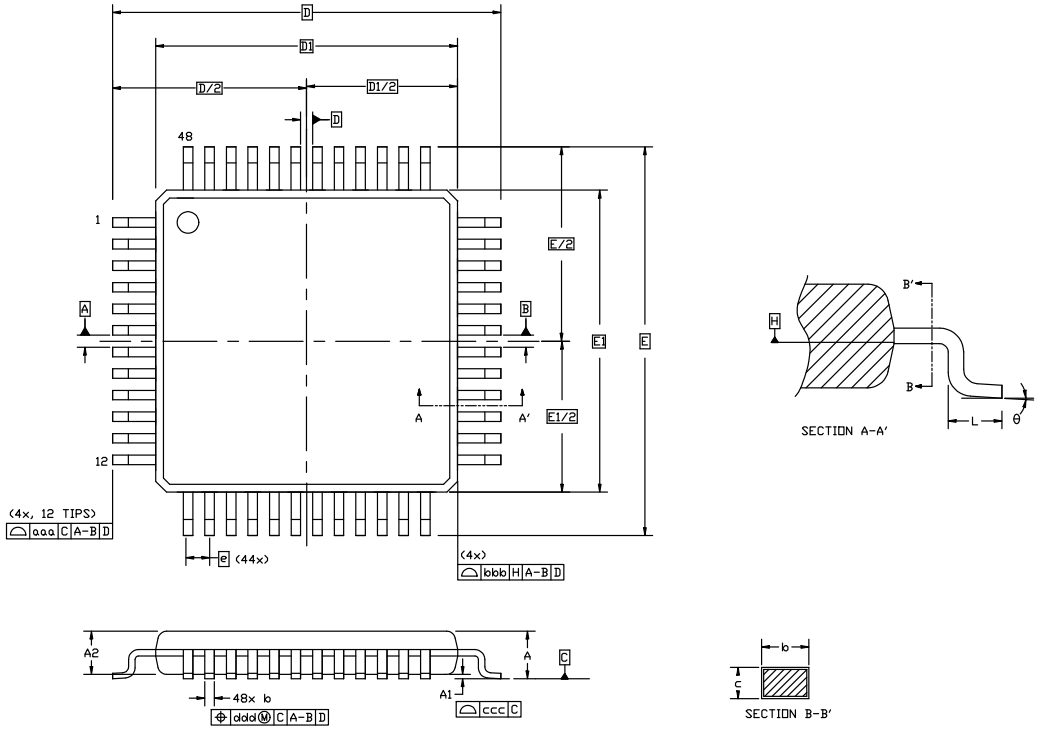


Figure 7.1. QFP48 Package Drawing

Table 7.1. QFP48 Package Dimensions

Dimension	Min	Typ	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.17	0.22	0.27
D		9.00 BSC	
D1		7.00 BSC	
e		0.50 BSC	
E		9.00 BSC	
E1		7.00 BSC	
L	0.45	0.60	0.75
aaa		0.20	
bbb		0.20	

Dimension	Min	Max

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This Land Pattern Design is based on the IPC-7351 guidelines.
3. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.
4. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
5. The stencil thickness should be 0.125 mm (5 mils).
6. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pads.
7. A No-Clean, Type-3 solder paste is recommended.
8. The recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.

7.3 QFP48 Package Marking

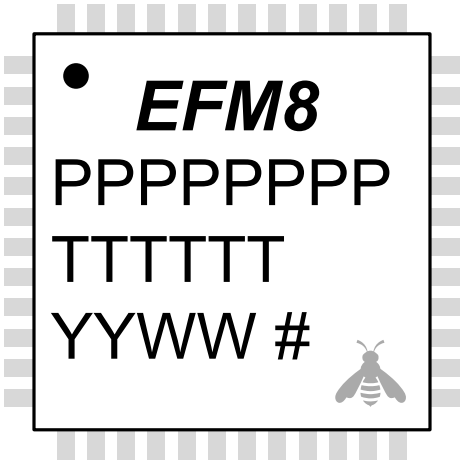


Figure 7.3. QFP48 Package Marking

The package marking consists of:

- PPPPPPPP – The part number designation.
- TTTTTT – A trace or manufacturing code.
- YY – The last 2 digits of the assembly year.
- WW – The 2-digit workweek when the device was assembled.
- # – The device revision (A, B, etc.).

8. QFP32 Package Specifications

8.1 QFP32 Package Dimensions

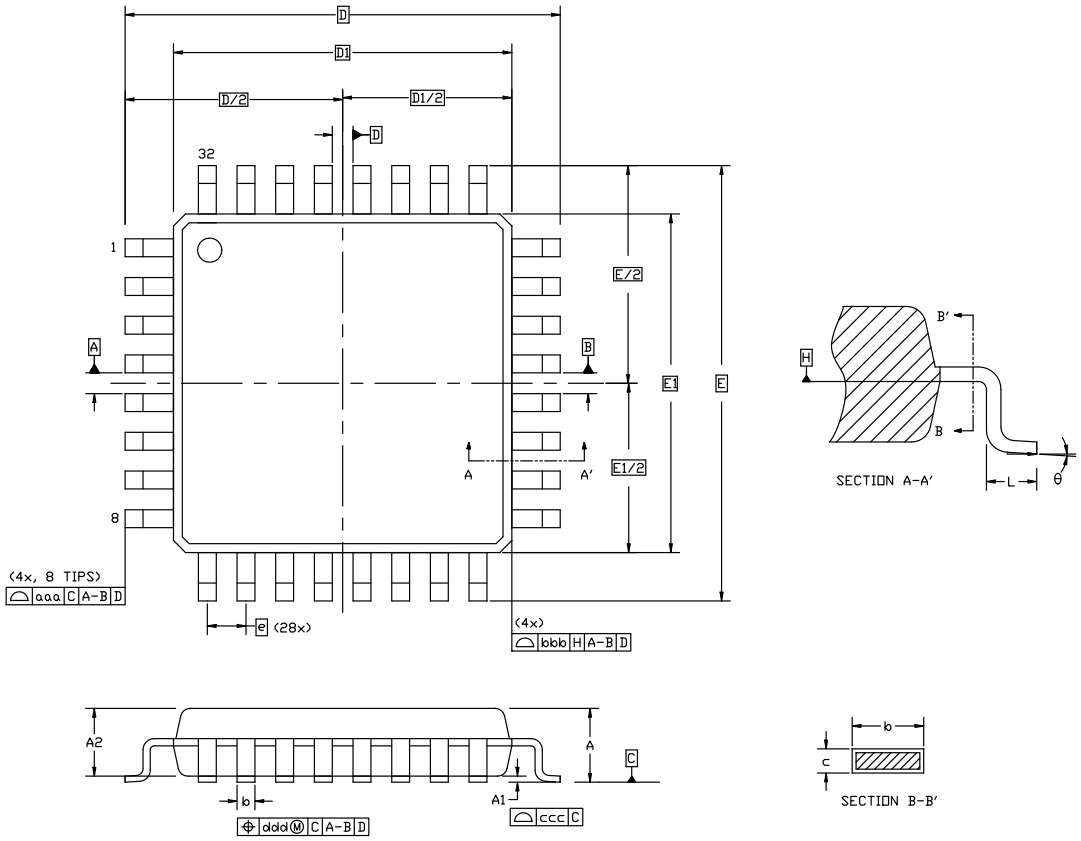


Figure 8.1. QFP32 Package Drawing

Table 8.1. QFP32 Package Dimensions

Dimension	Min	Typ	Max
A	—	—	1.60
A1	0.05	—	0.15
A2	1.35	1.40	1.45
b	0.30	0.37	0.45
D		9.00 BSC	
D1		7.00 BSC	
e		0.80 BSC	
E		9.00 BSC	
E1		7.00 BSC	
L	0.45	0.60	0.75
aaa		0.20	

9. QFN32 Package Specifications

9.1 QFN32 Package Dimensions

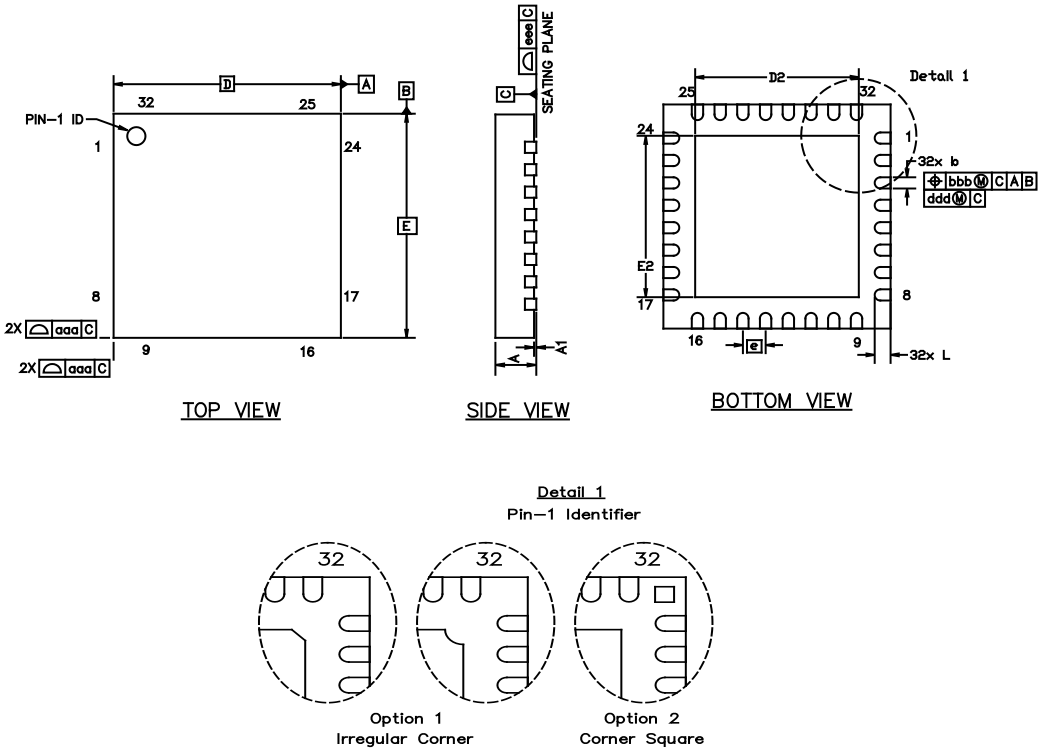
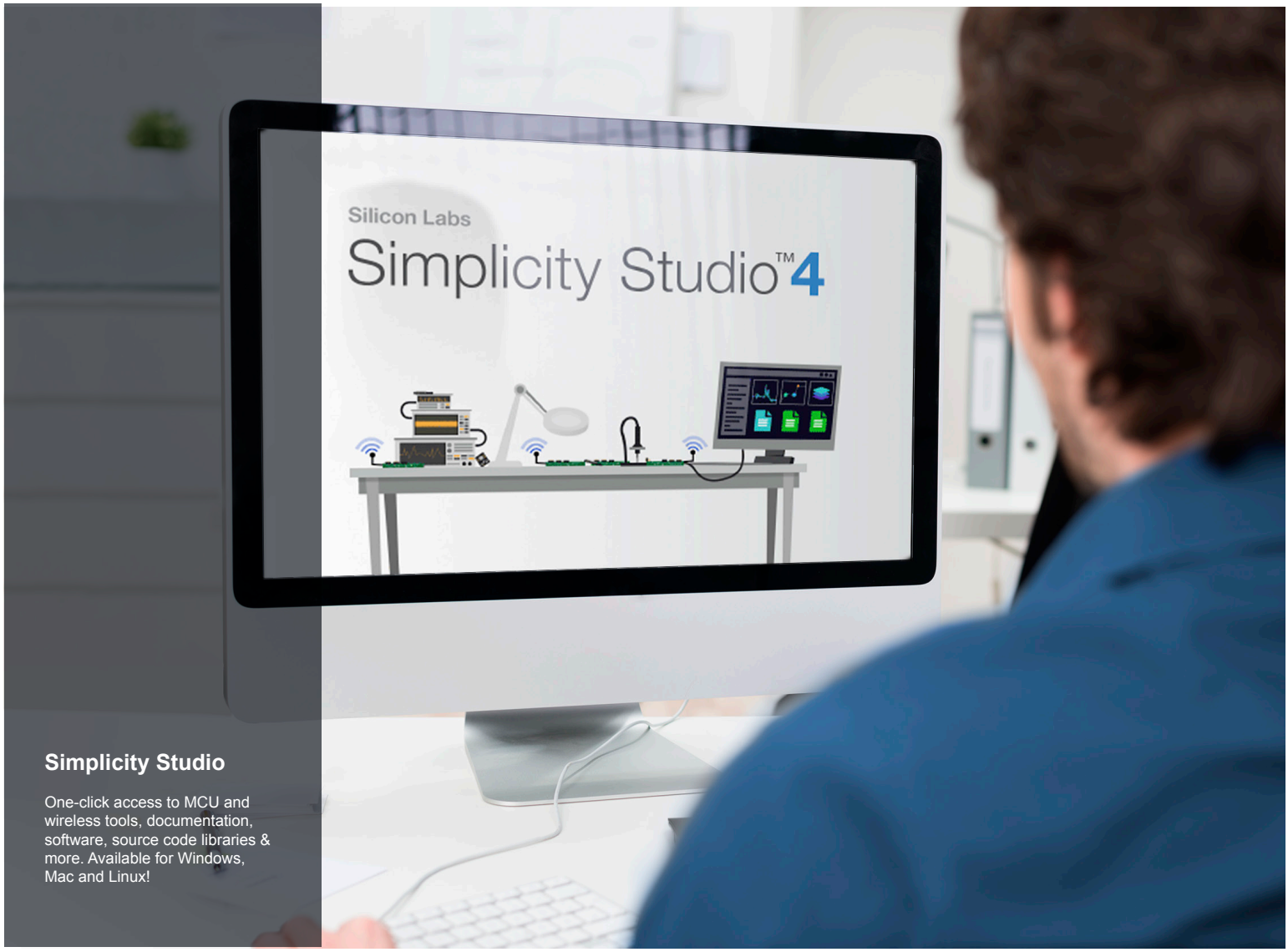


Figure 9.1. QFN32 Package Drawing

Table 9.1. QFN32 Package Dimensions

Dimension	Min	Typ	Max
A	0.80	0.85	0.90
A1	0.00	0.02	0.05
b	0.18	0.25	0.30
D		5.00 BSC	
D2	3.20	3.30	3.40
e		0.50 BSC	
E		5.00 BSC	
E2	3.20	3.30	3.40
L	0.35	0.40	0.45
aaa	—	—	0.10
bbb	—	—	0.10



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