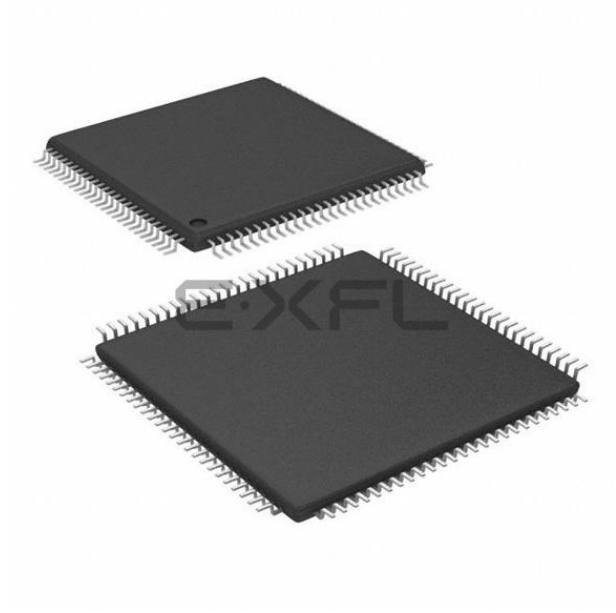
Microchip Technology - PIC32MZ2048ECM100-I/PF Datasheet



Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	MIPS32® microAptiv™
Core Size	32-Bit Single-Core
Speed	200MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, SPI, SQI, UART/USART, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I²S, POR, PWM, WDT
Number of I/O	78
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 3.6V
Data Converters	A/D 40x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic32mz2048ecm100-i-pf

The System Bus arbitration scheme implements a non-programmable, Least Recently Serviced (LRS) priority, which provides Quality Of Service (QOS) for most initiators. However, some initiators can use Fixed High Priority (HIGH) arbitration to guarantee their access to data.

The arbitration scheme for the available initiators is shown in Table 4-5.

TABLE 4-5: INITIATOR ID AND QOS

Name	ID	QOS
CPU	1	LRS(1)
CPU	2	HIGH(1,2)
DMA Read	3	LRS(1)
DMA Read	4	HIGH(1,2)
DMA Write	5	LRS(1)
DMA Write	6	HIGH(1,2)
USB	7	LRS
Ethernet Read	8	LRS
Ethernet Write	9	LRS
CAN1	10	LRS
CAN2	11	LRS
SQI1	12	LRS
Flash Controller	13	HIGH(2)
Crypto	14	LRS

Note 1: When accessing SRAM, the DMAPRI bit (CFGCON<25>) and the CPUPRI bit (CFGCON<24>) provide arbitration control for the DMA and CPU (when servicing an interrupt (i.e., EXL = 1)), respectively, by selecting the use of LRS or HIGH When using HIGH, the DMA and CPU get arbitration preference over all initiators using LRS.

2: Using HIGH arbitration can have serious negative effects on other initiators. Therefore, it is recommended to not enable this type of arbitration for an initiator that uses significant system bandwidth. HIGH arbitration is intended to be used for low bandwidth applications that require low latency, such as LCC graphics applications.

4.3 Permission Access and System Bus Registers

The System Bus on PIC32MZ EC family of microcontrollers provides access control capabilities for the transaction initiators on the System Bus.

The System Bus divides the entire memory space into fourteen target regions and permits access to each target by initiators via permission groups. Four Permission Groups (0 through 3) can be assigned to each initiator. Each permission group is independent of the others and can have exclusive or shared access to a region.

Using the CFGPG register (see Register 34-10 in **Section 34.0 “Special Features”**), Boot firmware can assign a permission group to each initiator, which can make requests on the System Bus.

The available targets and their regions, as well as the associated control registers to assign protection, are described and listed in Table 4-6.

Register 4-2 through Register 4-10 are used for setting and controlling access permission groups and regions.

To change these registers, they must be unlocked in hardware. The register lock is controlled by the PGLOCK Configuration bit (CFGCON<11>). Setting PGLOCK prevents writes to the control registers; clearing PGLOCK allows writes.

To set or clear the PGLOCK bit, an unlock sequence must be executed. Refer to **Section 42. “Oscillators with Enhanced PLL”** (DS60001250) in the *“PIC32 Family Reference Manual”* for details.

REGISTER 5-1: NVMCON: PROGRAMMING CONTROL REGISTER (CONTINUED)

bit 3-0 **NVMOP<3:0>:** NVM Operation bits

These bits are only writable when WREN = 0.

1111 = Reserved

•
•
•

1000 = Reserved

0111 = Program erase operation: erase all of program Flash memory (all pages must be unprotected, PWP<23:0> = 0x000000)

0110 = Upper program Flash memory erase operation: erases only the upper mapped region of program Flash (all pages in that region must be unprotected)

0101 = Lower program Flash memory erase operation: erases only the lower mapped region of program Flash (all pages in that region must be unprotected)

0100 = Page erase operation: erases page selected by NVMADDR, if it is not write-protected

0011 = Row program operation: programs row selected by NVMADDR, if it is not write-protected

0010 = Quad Word (128-bit) program operation: programs the 128-bit Flash word selected by NVMADDR, if it is not write-protected

0001 = Word program operation: programs word selected by NVMADDR, if it is not write-protected**(2)**

0000 = No operation

Note 1: These bits are only reset by a Power-on Reset (POR) and are not affected by other reset sources.

2: This operation results in a “no operation” (NOP) when the Dynamic Flash ECC Configuration bits = 00 (FECCCON<1:0> (DVCFG0<9:8>)), which enables ECC at all times. For all other FECCCON<1:0> bit settings, this command will execute, but will not write the ECC bits for the word and can cause DED errors if dynamic Flash ECC is enabled (FECCCON<1:0> = 01). Refer to **Section 52. “Flash Program Memory with Support for Live Update”** (DS60001193) for information regarding ECC and Flash programming.

REGISTER 11-12: USBFIFOx: USB FIFO DATA REGISTER 'x' ('x' = 0-7)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATA<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATA<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATA<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	DATA<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **DATA<31:0>:** USB Transmit/Receive FIFO Data bits

Writes to this register loads data into the TxFIFO for the corresponding endpoint. Reading from this register unloads data from the RxFIFO for the corresponding endpoint.

Transfers may be 8-bit, 16-bit or 32-bit as required, and any combination of access is allowed provided the data accessed is contiguous. However, all transfers associated with one packet must be of the same width so that data is consistently byte-, word- or double-word aligned. The last transfer may contain fewer bytes than the previous transfers in order to complete an odd-byte or odd-word transfer.

REGISTER 11-29: USBLPMR2: USB LINK POWER MANAGEMENT CONTROL REGISTER 2

bit 0 **LPMSTIF:** LPM STALL Interrupt Flag bit

When in *Device mode*:

1 = A LPM transaction was received and the USB Module responded with a STALL

0 = No Stall condition

When in *Host mode*:

1 = A LPM transaction was transmitted and the device responded with a STALL

0 = No Stall condition

REGISTER 15-7: DMTPSINTV: POST STATUS CONFIGURE DMT INTERVAL STATUS REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	PSINTV<31:24>							
23:16	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	PSINTV<23:16>							
15:8	R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
	PSINTV<15:8>							
7:0	R-0	R-0	R-0	R-0	R-0	R-y	R-y	R-y
	PSINTV<7:0>							

Legend:		y = Value set from Configuration bits on POR	
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-8 **PSINTV<31:0>:** DMT Window Interval Configuration Status bits
This is always the value of the DMTINTV<2:0> bits in the DEVCFG1 Configuration register.

REGISTER 16-1: WDTCON: WATCHDOG TIMER CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<15:8>							
23:16	W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
	WDTCLRKEY<7:0>							
15:8	R/W-y	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	ON(1)	—	—	—	—	—	—	—
7:0	U-0	R-y	R-y	R-y	R-y	R-y	R/W-0	U-0
	—	SWDTPS<4:0>					WDTWINEN	—

Legend:	y = Values set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **WDTCLRKEY<15:0>:** Watchdog Timer Clear Key bits
To clear the Watchdog Timer to prevent a time-out, software must write the value 0x5743 to this location using a single 16-bit write.

bit 15 **ON:** Watchdog Timer Enable bit(1)
1 = The WDT is enabled
0 = The WDT is disabled

bit 14-7 **Unimplemented:** Read as '0'

bit 6-2 **SWDTPS<4:0>:** Shadow Copy of Watchdog Timer Postscaler Value from Device Configuration bits
On reset, these bits are set to the values of the WDTPS <4:0> Configuration bits in DEVCFG1.

bit 1 **WDTWINEN:** Watchdog Timer Window Enable bit
1 = Enable windowed Watchdog Timer
0 = Disable windowed Watchdog Timer

bit 0 **Unimplemented:** Read as '0'

Note 1: This bit only has control when FWDTEN (DEVCFG1<23>) = 0.

The timer source for each Input Capture module depends on the setting of the ICACLK bit in the CFGCON register. The available configurations are shown in Table 17-1.

TABLE 17-1: TIMER SOURCE CONFIGURATIONS

Input Capture Module	Timerx	Timery
ICACLK (CFGCON<17>) = 0		
IC1 • • • IC9	Timer2 • • • Timer 2	Timer3 • • • Timer 3
ICACLK (CFGCON<17>) = 1		
IC1	Timer4	Timer5
IC2	Timer4	Timer5
IC3	Timer4	Timer5
IC4	Timer2	Timer3
IC5	Timer2	Timer3
IC6	Timer2	Timer3
IC7	Timer6	Timer7
IC8	Timer6	Timer7
IC9	Timer6	Timer7

REGISTER 28-19: AD1CALx: ADC1 CALIBRATION REGISTER 'x' ('x' = 1-5)

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ADCAL<31:24>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ADCAL<23:16>							
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ADCAL<15:8>							
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	ADCAL<7:0>							

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-0 **ADCAL<31:0>:** Calibration Data for the ADC Module bits
This data must be copied from the corresponding DEVADCx register. Refer to **Section 34.1 "Configuration Bits"** for more information.

29.0 CONTROLLER AREA NETWORK (CAN)

Note: This data sheet summarizes the features of the PIC32MZ Embedded Connectivity (EC) Family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 34. "Controller Area Network (CAN)"** (DS60001154), which is available from the *Documentation > Reference Manual* section of the Microchip PIC32 web site (www.microchip.com/pic32).

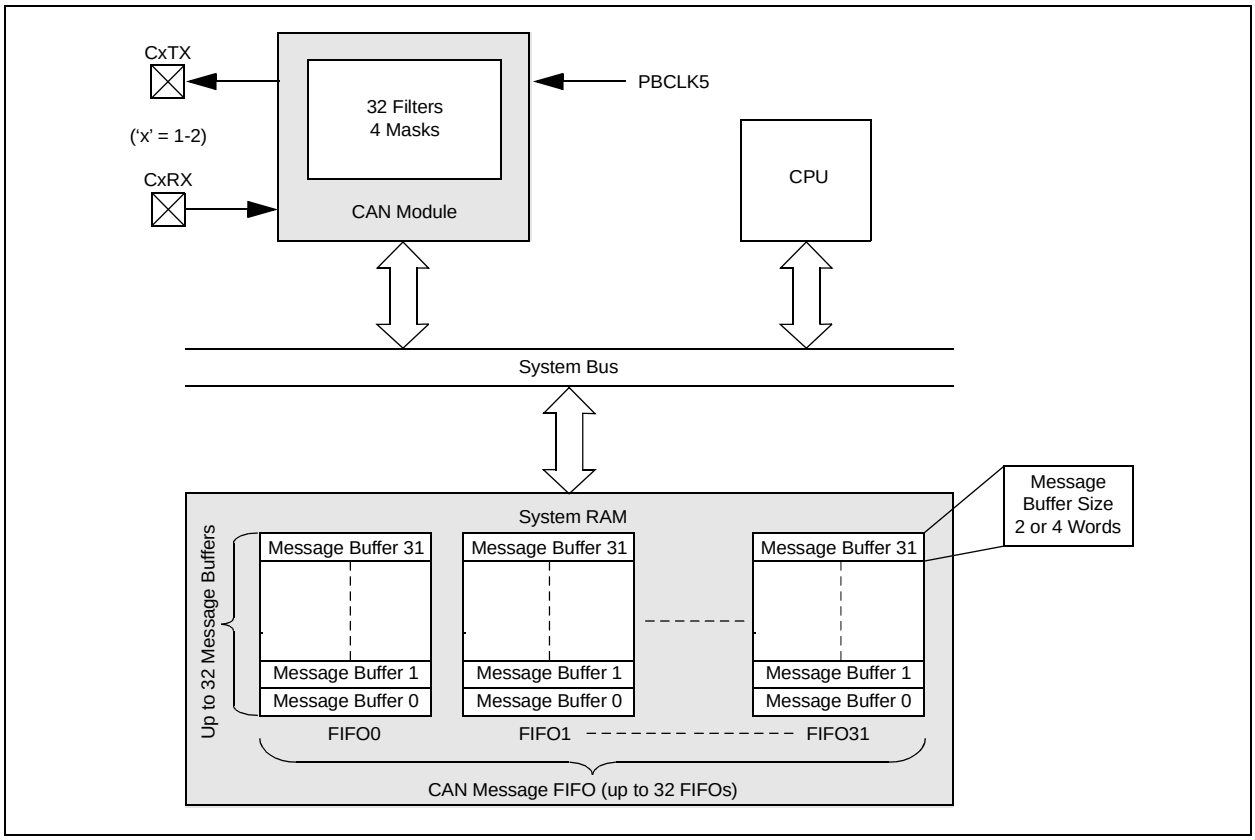
The Controller Area Network (CAN) module supports the following key features:

- Standards Compliance:
  - Full CAN 2.0B compliance
  - Programmable bit rate up to 1 Mbps
- Message Reception and Transmission:
  - 32 message FIFOs
  - Each FIFO can have up to 32 messages for a total of 1024 messages
  - FIFO can be a transmit message FIFO or a receive message FIFO
  - User-defined priority levels for message FIFOs used for transmission
  - 32 acceptance filters for message filtering
  - Four acceptance filter mask registers for message filtering
  - Automatic response to remote transmit request
  - DeviceNet™ addressing support
- Additional Features:
  - Loopback, Listen All Messages and Listen Only modes for self-test, system diagnostics and bus monitoring
  - Low-power operating modes
  - CAN module is a bus master on the PIC32 System Bus
  - Use of DMA is not required
  - Dedicated time-stamp timer
  - Dedicated DMA channels
  - Data-only Message Reception mode

Figure 29-1 illustrates the general structure of the CAN module.

Note: To avoid cache coherency problems on devices with L1 cache, CAN buffers must only be allocated or accessed from the KSEG1 segment.

FIGURE 29-1: PIC32 CAN MODULE BLOCK DIAGRAM



REGISTER 29-1: CiCON: CAN MODULE CONTROL REGISTER

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	U-0	U-0	U-0	U-0	S/HC-0	R/W-1	R/W-0	R/W-0
	—	—	—	—	ABAT	REQOP<2:0>		
23:16	R-1	R-0	R-0	R/W-0	U-0	U-0	U-0	U-0
	OPMOD<2:0>			CANCAP	—	—	—	—
15:8	R/W-0	U-0	R/W-0	U-0	R-0	U-0	U-0	U-0
	ON(1)	—	SIDLE	—	CANBUSY	—	—	—
7:0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	—	—	DNCNT<4:0>				

Legend:	HC = Hardware Clear	S = Settable bit	
R = Readable bit	W = Writable bit	P = Programmable bit	r = Reserved bit
U = Unimplemented bit	-n = Bit Value at POR: (‘0’, ‘1’, x = Unknown)		

bit 31-28 **Unimplemented:** Read as ‘0’

bit 27 **ABAT:** Abort All Pending Transmissions bit
1 = Signal all transmit buffers to abort transmission
0 = Module will clear this bit when all transmissions aborted

bit 26-24 **REQOP<2:0>:** Request Operation Mode bits
111 = Set Listen All Messages mode
110 = Reserved - Do not use
101 = Reserved - Do not use
100 = Set Configuration mode
011 = Set Listen Only mode
010 = Set Loopback mode
001 = Set Disable mode
000 = Set Normal Operation mode

bit 23-21 **OPMOD<2:0>:** Operation Mode Status bits
111 = Module is in Listen All Messages mode
110 = Reserved
101 = Reserved
100 = Module is in Configuration mode
011 = Module is in Listen Only mode
010 = Module is in Loopback mode
001 = Module is in Disable mode
000 = Module is in Normal Operation mode

bit 20 **CANCAP:** CAN Message Receive Time Stamp Timer Capture Enable bit
1 = CANTMR value is stored on valid message reception and is stored with the message
0 = Disable CAN message receive time stamp timer capture and stop CANTMR to conserve power

bit 19-16 **Unimplemented:** Read as ‘0’

bit 15 **ON:** CAN On bit(1)
1 = CAN module is enabled
0 = CAN module is disabled

bit 14 **Unimplemented:** Read as ‘0’

Note 1: If the user application clears this bit, it may take a number of cycles before the CAN module completes the current transaction and responds to this request. The user application should poll the CANBUSY bit to verify that the request has been honored.

REGISTER 29-14: CiFLTCON4: CAN FILTER CONTROL REGISTER 4 (CONTINUED)

bit 15 **FLTEN17:** Filter 13 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 14-13 **MSEL17<1:0>:** Filter 17 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 12-8 **FSEL17<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 7 **FLTEN16:** Filter 16 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 6-5 **MSEL16<1:0>:** Filter 16 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 4-0 **FSEL16<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 29-15: CiFLTCON5: CAN FILTER CONTROL REGISTER 5

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN23	MSEL23<1:0>		FSEL23<4:0>				
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN22	MSEL22<1:0>		FSEL22<4:0>				
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN21	MSEL21<1:0>		FSEL21<4:0>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN20	MSEL20<1:0>		FSEL20<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **FLTEN23:** Filter 23 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 30-29 **MSEL23<1:0>:** Filter 23 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 28-24 **FSEL23<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN22:** Filter 22 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 22-21 **MSEL22<1:0>:** Filter 22 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 20-16 **FSEL22<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 29-16: CiFLTCON6: CAN FILTER CONTROL REGISTER 6

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN27	MSEL27<1:0>		FSEL27<4:0>				
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN26	MSEL26<1:0>		FSEL26<4:0>				
15:8	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN25	MSEL25<1:0>		FSEL25<4:0>				
7:0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	FLTEN24	MSEL24<1:0>		FSEL24<4:0>				

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31 **FLTEN27:** Filter 27 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 30-29 **MSEL27<1:0>:** Filter 27 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 28-24 **FSEL27<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

bit 23 **FLTEN26:** Filter 26 Enable bit
1 = Filter is enabled
0 = Filter is disabled

bit 22-21 **MSEL26<1:0>:** Filter 26 Mask Select bits
11 = Acceptance Mask 3 selected
10 = Acceptance Mask 2 selected
01 = Acceptance Mask 1 selected
00 = Acceptance Mask 0 selected

bit 20-16 **FSEL26<4:0>:** FIFO Selection bits
11111 = Message matching filter is stored in FIFO buffer 31
11110 = Message matching filter is stored in FIFO buffer 30
•
•
•
00001 = Message matching filter is stored in FIFO buffer 1
00000 = Message matching filter is stored in FIFO buffer 0

Note: The bits in this register can only be modified if the corresponding filter enable (FLTENn) bit is '0'.

REGISTER 30-1: ETHCON1: ETHERNET CONTROLLER CONTROL REGISTER 1

Bit Range	Bit 31/23/15/7	Bit 30/22/14/6	Bit 29/21/13/5	Bit 28/20/12/4	Bit 27/19/11/3	Bit 26/18/10/2	Bit 25/17/9/1	Bit 24/16/8/0
31:24	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PTV<15:8>							
23:16	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	PTV<7:0>							
15:8	R/W-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0
	ON	—	SIDL	—	—	—	TXRTS	RXEN(1)
7:0	R/W-0	U-0	U-0	R/W-0	U-0	U-0	U-0	R/W-0
	AUTOFC	—	—	MANFC	—	—	—	BUFCDEC

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 31-16 **PTV<15:0>:** PAUSE Timer Value bits

PAUSE Timer Value used for Flow Control.
This register should only be written when RXEN (ETHCON1<8>) is not set.

These bits are only used for Flow Control operations.

bit 15 **ON:** Ethernet ON bit

1 = Ethernet module is enabled
0 = Ethernet module is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **SIDL:** Ethernet Stop in Idle Mode bit

1 = Ethernet module transfers are paused during Idle mode
0 = Ethernet module transfers continue during Idle mode

bit 12-10 **Unimplemented:** Read as '0'

bit 9 **TXRTS:** Transmit Request to Send bit

1 = Activate the TX logic and send the packet(s) defined in the TX EDT
0 = Stop transmit (when cleared by software) or transmit done (when cleared by hardware)

After the bit is written with a '1', it will clear to a '0' whenever the transmit logic has finished transmitting the requested packets in the Ethernet Descriptor Table (EDT). If a '0' is written by the CPU, the transmit logic finishes the current packet's transmission and then stops any further.

This bit only affects TX operations.

bit 8 **RXEN:** Receive Enable bit(1)

1 = Enable RX logic, packets are received and stored in the RX buffer as controlled by the filter configuration
0 = Disable RX logic, no packets are received in the RX buffer

This bit only affects RX operations.

Note 1: It is not recommended to clear the RXEN bit and then make changes to any RX related field/register. The Ethernet Controller must be reinitialized (ON cleared to '0'), and then the RX changes applied.

36.6 MPLAB X SIM Software Simulator

The MPLAB X SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB X SIM Software Simulator fully supports symbolic debugging using the MPLAB XC Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

36.7 MPLAB REAL ICE In-Circuit Emulator System

The MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs all 8, 16 and 32-bit MCU, and DSC devices with the easy-to-use, powerful graphical user interface of the MPLAB X IDE.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ-11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB X IDE. MPLAB REAL ICE offers significant advantages over competitive emulators including full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, logic probes, a ruggedized probe interface and long (up to three meters) interconnection cables.

36.8 MPLAB ICD 3 In-Circuit Debugger System

The MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost-effective, high-speed hardware debugger/programmer for Microchip Flash DSC and MCU devices. It debugs and programs PIC Flash microcontrollers and dsPIC DSCs with the powerful, yet easy-to-use graphical user interface of the MPLAB IDE.

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

36.9 PICkit 3 In-Circuit Debugger/ Programmer

The MPLAB PICkit 3 allows debugging and programming of PIC and dsPIC Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB IDE. The MPLAB PICkit 3 is connected to the design engineer's PC using a full-speed USB interface and can be connected to the target via a Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the Reset line to implement in-circuit debugging and In-Circuit Serial Programming™ (ICSP™).

36.10 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at V_{DDMIN} and V_{DDMAX} for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages, and a modular, detachable socket assembly to support various package types. The ICSP cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices, and incorporates an MMC card for file storage and data applications.

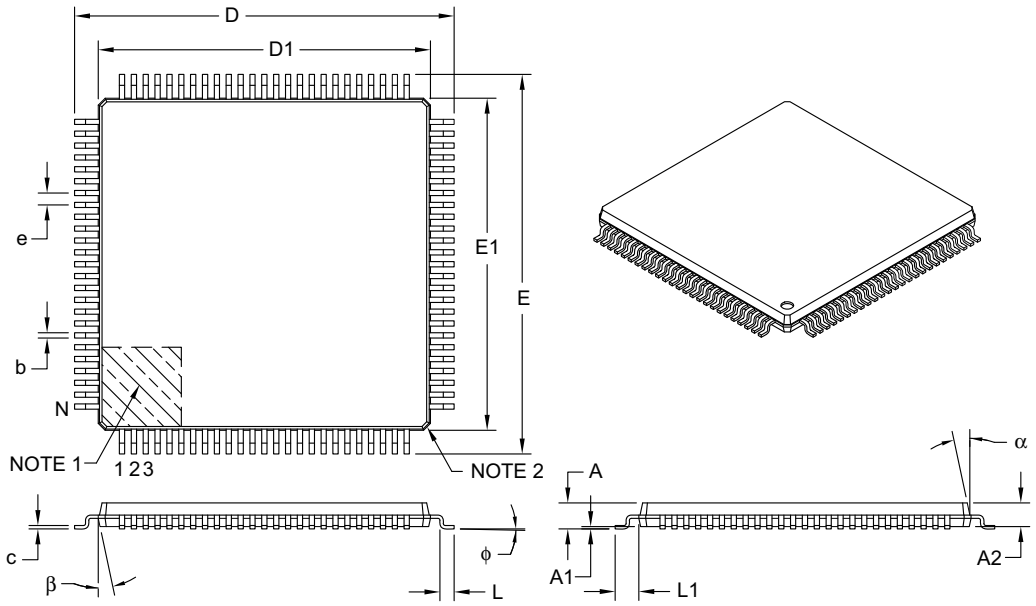
TABLE 37-11: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS (CONTINUED)

DC CHARACTERISTICS			Standard Operating Conditions: 2.3V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial				
Param.	**Sym.**	**Characteristic**	**Min.**	**Typ.**	**Max.**	**Units**	**Conditions(1)**
DO20a	VOH1	**Output High Voltage** I/O Pins: 4x Source Driver Pins - RA3, RA9, RA10, RA14, RA15 RB0-7, RB11, RB13 RC12-RC15 RD0, RD6-RD7, RD11, RD14 RE8, RE9 RF2, RF3, RF8 RG15 RH0, RH1, RH4-RH6, RH8-RH13 RJ0-RJ2, RJ8, RJ9, RJ11	1.5	—	—	V	IOH ≥ -14 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -12 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -7 mA, VDD = 3.3V
		Output High Voltage I/O Pins: 8x Source Driver Pins - RA0-RA2, RA4, RA5 RB8-RB10, RB12, RB14, RB15 RC1-RC4 RD1-RD5, RD9, RD10, RD12, RD13, RD15 RE4-RE7 RF0, RF4, RF5, RF12, RF13 RG0, RG1, RG6-RG9 RH2, RH3, RH7, RH14, RH15 RJ3-RJ7, RJ10, RJ12-RJ15 RK0-RK7	1.5	—	—	V	IOH ≥ -22 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -18 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -10 mA, VDD = 3.3V
		Output High Voltage I/O Pins: 12x Source Driver Pins - RA6, RA7 RE0-RE3 RF1 RG12-RG14	1.5	—	—	V	IOH ≥ -32 mA, VDD = 3.3V
			2.0	—	—	V	IOH ≥ -25 mA, VDD = 3.3V
			3.0	—	—	V	IOH ≥ -14 mA, VDD = 3.3V

Note 1: Parameters are characterized, but not tested.

100-Lead Plastic Thin Quad Flatpack (PF) – 14x14x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Leads	N		100	
Lead Pitch	e		0.50 BSC	
Overall Height	A	–	–	1.20
Molded Package Thickness	A2	0.95	1.00	1.05
Standoff	A1	0.05	–	0.15
Foot Length	L	0.45	0.60	0.75
Footprint	L1		1.00 REF	
Foot Angle	ϕ	0°	3.5°	7°
Overall Width	E		16.00 BSC	
Overall Length	D		16.00 BSC	
Molded Package Width	E1		14.00 BSC	
Molded Package Length	D1		14.00 BSC	
Lead Thickness	c	0.09	–	0.20
Lead Width	b	0.17	0.22	0.27
Mold Draft Angle Top	α	11°	12°	13°
Mold Draft Angle Bottom	β	11°	12°	13°

Notes:

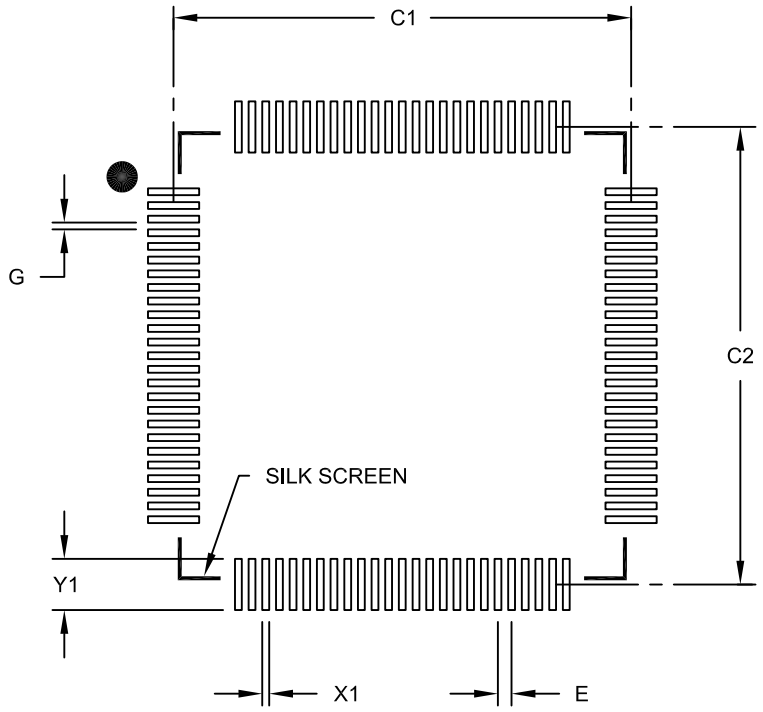
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Chamfers at corners are optional; size may vary.
3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-110B

100-Lead Plastic Thin Quad Flatpack (PT)-12x12x1mm Body, 2.00 mm Footprint [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E		0.40 BSC	
Contact Pad Spacing	C1		13.40	
Contact Pad Spacing	C2		13.40	
Contact Pad Width (X100)	X1			0.20
Contact Pad Length (X100)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

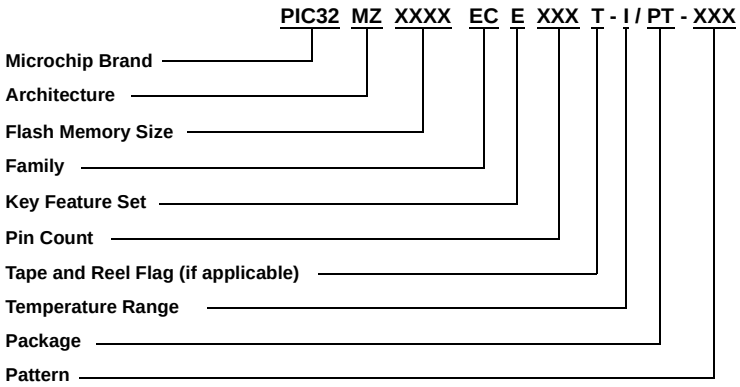
Microchip Technology Drawing No. C04-2100B

TABLE B-1: MAJOR SECTION UPDATES (CONTINUED)

Section Name	Update Description
28.0 "12-bit Pipelined Analog-to-Digital Converter (ADC)"	Figure 28-1, Figure 28-2, and Figure 28-3 were updated. Register names were updated in the ADC Register Map (see Table 28-1). The OVRSAM<2:0> bit values were updated (see Register 28-14).
34.0 "Special Features"	The DEVCFG3/ADEVCFG3 register was updated (see Register 34-6).
37.0 "Electrical Characteristics"	Various electrical specifications were updated, including: • The minimum value for parameter DC10 (V_{DD}) in the DC Temperature and Voltage Specifications was updated (see Table 37-4). • The minimum and maximum values for parameter BO10 (V_{BOR}) were updated in the BOR Electrical Characteristics (see Table 37-4). • Updated the third and fourth bullet list items in Note 2 in DC Characteristics: Operating Current (I_{DD}) (see Table 37-6). • Updated the third and fourth bullet list items in Note 1 in DC Characteristics: Idle Current (I_{IDLE}) (see Table 37-7). • Updated the third and fourth bullet list items in Note 1in DC Characteristics: Power-Down Current (I_{PD}) (see Table 37-8). • Added Note 6 and updated parameters DI20, DI28a, DI28b, DI30, and DI31 in DC Characteristics: I/O Pin Input Specifications (see Table 37-9). • Added DC Characteristics: I/O Pin Input Injection Current Specifications (see Table 37-10). • Added parameter DO50 to Capacitive Loading Requirements on Output Pins (see Table 37-15). • Note 3 was added and the Conditions were updated for parameter OS42 in the External Clock Timing Requirements (see Table 37-16). • Updated the Minimum value for parameter OS51 (F_{SYS}) in the System Timing Requirements (see Table 37-17). • Added parameter OS54a and updated the Maximum value for parameter OS50 in the PLL Clock Timing Specifications (see Table 37-18). • The Internal Backup FRC (BFRC) Accuracy specification was added (see Table 37-21). • The SQI Input and Output Timing Characteristics diagram were updated (see Figure 37-14 and Figure 37-15). • The SQI Timing Requirements were updated (see Table 37-33). • Parameter AD13 was removed (see Table 37-37). • The Min. and Max. values for parameter TS12 and the Conditions for parameter TS13 and TS14 in the Temperature Sensor Specifications were updated (see Table 36-39).
38.0 "AC and DC Characteristics Graphs"	Updated Typical Temperature Sensor Voltage (see Figure 38-7).
Appendix A: "Migrating from PIC32MX5XX/6XX/7XX to PIC32MZ"	New appendix for migrating to PIC32MZ devices was added.

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



Example:

PIC32MZ2048ECH144-I/PT: Embedded Connectivity PIC32, MIPS32® microAptiv™ MPU core, 2048 KB program memory, 144-pin, Industrial temperature, TQFP package.

Flash Memory Family

Architecture	MZ	= MIPS32® microAptiv™ MPU Core
Flash Memory Size	0512	= 512 KB
	1024	= 1024 KB
	2048	= 2048 KB
Family	EC	= Embedded Connectivity Microcontroller Family
Key Feature	E	= PIC32 EC Family Features (no CAN, no Crypto)
	F	= PIC32 EC Family Features (CAN, no Crypto)
	G	= PIC32 EC Family Features (no CAN, no Crypto)
	H	= PIC32 EC Family Features (CAN, no Crypto)
	K	= PIC32 EC Family Features (Crypto and CAN)
	M	= PIC32 EC Family Features (Crypto and CAN)
Pin Count	064	= 64-pin
	100	= 100-pin
	124	= 124-pin
	144	= 144-pin
Temperature Range	I	= -40°C to +85°C (Industrial)
Package	MR	= 64-Lead (9x9x0.9 mm) QFN (Plastic Quad Flatpack)
	PT	= 64-Lead (10x10x1 mm) TQFP (Thin Quad Flatpack)
	PT	= 100-Lead (12x12x1 mm) TQFP (Thin Quad Flatpack)
	PF	= 100-Lead (14x14x1 mm) TQFP (Thin Quad Flatpack)
	TL	= 124-Lead (9x9x0.9 mm) VTLA (Very Thin Leadless Array)
	PH	= 144-Lead (16x16x1 mm) TQFP (Thin Quad Flatpack)
	PL	= 144-Lead (20x20x1.40 mm) LQFP (Low Profile Quad Flatpack)
Pattern		Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise)
	ES	= Engineering Sample