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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	16 MIPS
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, Motor Control PWM, POR, PWM, WDT
Number of I/O	21
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 6x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj16mc102-i-ss

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104 PRODUCT FAMILIES

The device names, pin counts, memory sizes and peripheral availability of each device are listed in Table 1. The following pages show their pinout diagrams.

TABLE 1: dsPIC33FJ16(GP/MC)101/102 DEVICE FEATURES

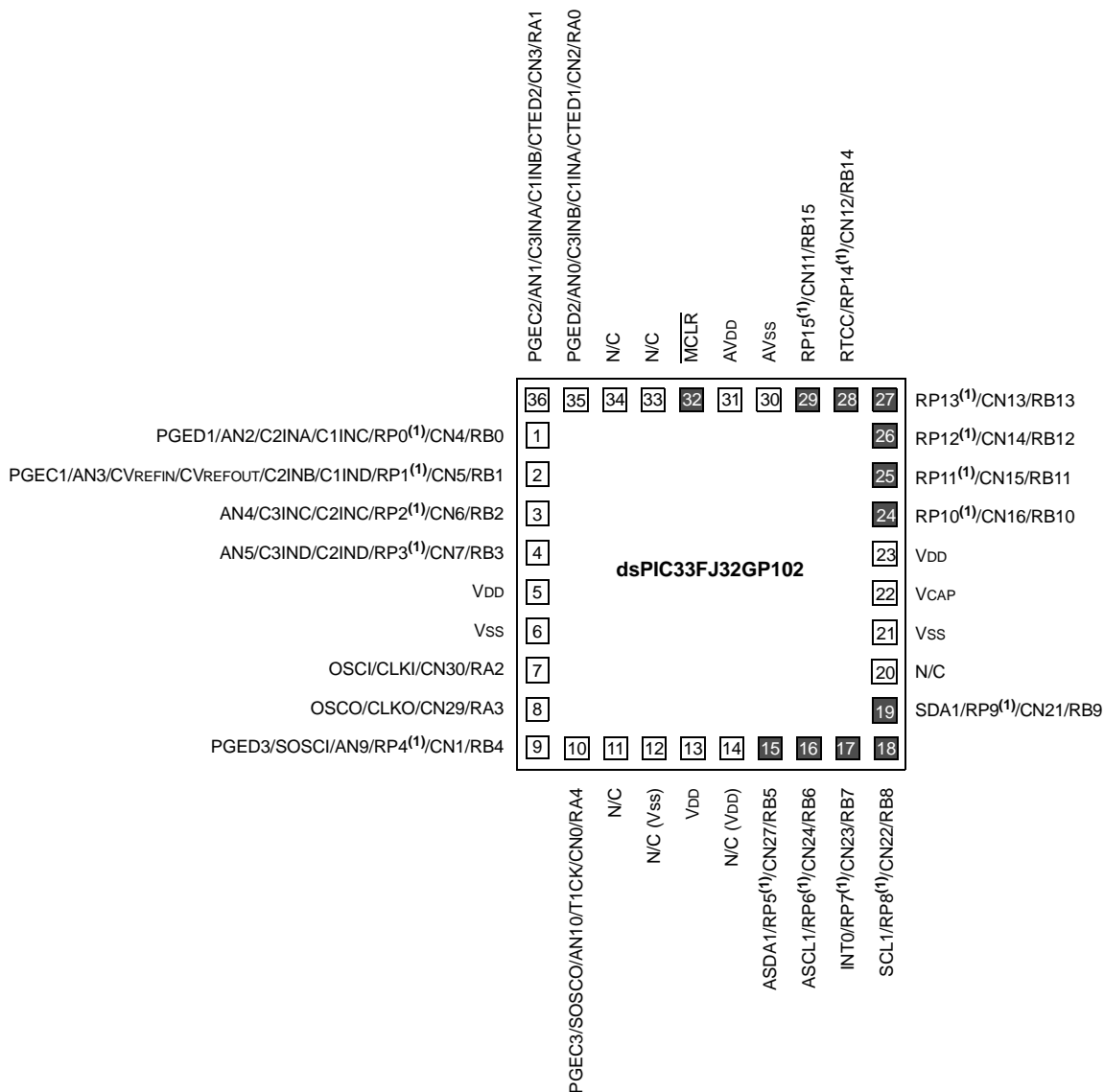
Device	Pins	Program Flash (Kbyte)	RAM (Kbytes)	Remappable Peripherals							Motor Control PWM	PWM Faults	10-Bit, 1.1 Msp/s ADC	RTCC	I ² C™	Comparators	CTMU	I/O Pins	Packages
				Remappable Pins	16-bit Timer ^(1,2)	Input Capture	Output Compare	UART	External Interrupts ⁽³⁾	SPI									
dsPIC33FJ16GP101	18	16	1	8	3	3	2	1	3	1	—	—	1 ADC, 4-ch	Y	1	3	Y	13	PDIP, SOIC
	20	16	1	8	3	3	2	1	3	1	—	—	1 ADC, 4-ch	Y	1	3	Y	15	SSOP
dsPIC33FJ16GP102	28	16	1	16	3	3	2	1	3	1	—	—	1 ADC, 6-ch	Y	1	3	Y	21	SPDIP, SOIC, SSOP, QFN
	36	16	1	16	3	3	2	1	3	1	—	—	1 ADC, 6-ch	Y	1	3	Y	21	VTLA
dsPIC33FJ16MC101	20	16	1	10	3	3	2	1	3	1	6-ch	1	1 ADC, 4-ch	Y	1	3	Y	15	PDIP, SOIC, SSOP
dsPIC33FJ16MC102	28	16	1	16	3	3	2	1	3	1	6-ch	2	1 ADC, 6-ch	Y	1	3	Y	21	SPDIP, SOIC, SSOP, QFN
	36	16	1	16	3	3	2	1	3	1	6-ch	2	1 ADC, 6-ch	Y	1	3	Y	21	VTLA

- Note** 1: Two out of three timers are remappable.
2: One pair can be combined to create one 32-bit timer.
3: Two out of three interrupts are remappable.

Pin Diagrams (Continued)

36-Pin VTLA⁽²⁾

■ = Pins are up to 5V tolerant



- Note 1:** The RPN pins can be used by any remappable peripheral. See Table 1 for the list of available peripherals.
- Note 2:** The metal pad at the bottom of the device is not connected to any pins and is recommended to be connected to VSS externally.

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4.6 Interfacing Program and Data Memory Spaces

The dsPIC33FJ16(GP/MC)101/102 and dsPIC33FJ32(GP/MC)101/102/104 architecture uses a 24-bit-wide program space and a 16-bit-wide data space. The architecture is also a modified Harvard scheme, meaning that data can also be present in the program space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the dsPIC33FJ16(GP/MC)101/102 and dsPIC33FJ32(GP/MC)101/102/104 architecture provides two methods by which program space can be accessed during operation:

- Using table instructions to access individual bytes, or words, anywhere in the program space
- Remapping a portion of the program space into the data space (Program Space Visibility)

Table instructions allow an application to read or write to small areas of the program memory. This capability makes the method ideal for accessing data tables that need to be updated periodically. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for lookups from a large table of static data. The application can only access the lsw of the program word.

4.6.1 ADDRESSING PROGRAM SPACE

Since the address ranges for the data and program spaces are 16 and 24 bits, respectively, a method is needed to create a 23-bit or 24-bit program address from 16-bit data registers. The solution depends on the interface method to be used.

For table operations, the 8-bit Table Page (TBLPAG) register is used to define a 32K word region within the program space. This is concatenated with a 16-bit EA to arrive at a full 24-bit program space address. In this format, the MSb of TBLPAG is used to determine if the operation occurs in the user memory (TBLPAG<7> = 0) or the configuration memory (TBLPAG<7> = 1).

For remapping operations, the 8-bit Program Space Visibility (PSVPAG) register is used to define a 16K word page in the program space. When the MSb of the EA is '1', PSVPAG is concatenated with the lower 15 bits of the EA to form a 23-bit program space address. Unlike table operations, this limits remapping operations strictly to the user memory area.

Table 4-42 and Figure 4-9 show how the program EA is created for table operations and remapping accesses from the data EA.

TABLE 4-42: PROGRAM SPACE ADDRESS CONSTRUCTION

Access Type	Access Space	Program Space Address				
		<23>	<22:16>	<15>	<14:1>	<0>
Instruction Access (Code Execution)	User	0	PC<22:1>			0
		0xx xxxx xxxx xxxx xxxx xxx0				
TBLRD/TBLWT (Byte/Word Read/Write)	User	TBLPAG<7:0>		Data EA<15:0>		
		0xxx xxxx xxxx xxxx xxxx xxxx				
	Configuration	TBLPAG<7:0>		Data EA<15:0>		
		1xxx xxxx xxxx xxxx xxxx xxxx				
Program Space Visibility (Block Remap/Read)	User	0	PSVPAG<7:0>		Data EA<14:0> ⁽¹⁾	
		0	xxxx xxxx xxx xxxx xxxx xxxx			

Note 1: Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is PSVPAG<0>.

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104

REGISTER 7-22: IPC7: INTERRUPT PRIORITY CONTROL REGISTER 7

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	INT2IP2	INT2IP1	INT2IP0	—	T5IP2 ⁽¹⁾	T5IP1 ⁽¹⁾	T5IP0 ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **INT2IP<2:0>:** External Interrupt 2 Priority bits

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **T5IP<2:0>:** Timer5 Interrupt Priority bits⁽¹⁾

111 = Interrupt is Priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is Priority 1

000 = Interrupt source is disabled

Note 1: These bits are available in dsPIC33FJ32(GP/MC)10X devices only.

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104

REGISTER 10-11: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP1R<4:0>				
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP0R<4:0>				
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP1R<4:0>:** Peripheral Output Function is Assigned to RP1 Output Pin bits
(see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP0R<4:0>:** Peripheral Output Function is Assigned to RP0 Output Pin bits
(see Table 10-2 for peripheral function numbers)

REGISTER 10-12: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP3R<4:0> ⁽¹⁾				
bit 15							bit 8

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	RP2R<4:0> ⁽¹⁾				
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

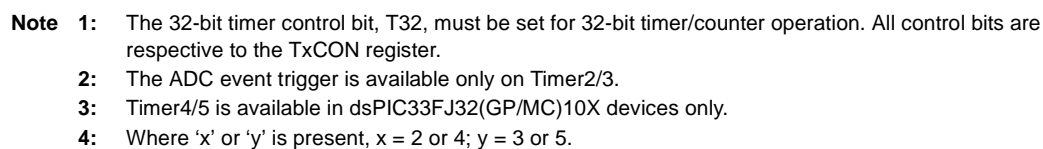
bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP3R<4:0>:** Peripheral Output Function is Assigned to RP3 Output Pin bits⁽¹⁾
(see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP2R<4:0>:** Peripheral Output Function is Assigned to RP2 Output Pin bits⁽¹⁾
(see Table 10-2 for peripheral function numbers)

Note 1: These bits are not available in dsPIC33FJXX(GP/MC)101 devices.



14.1 Output Compare Modes

Configure the Output Compare modes by setting the appropriate Output Compare Mode bits (OCM<2:0>) in the Output Compare x Control (OCxCON<2:0>) register. Table 14-1 lists the different bit settings for the Output Compare modes. Figure 14-2 illustrates the output compare operation for various modes. The user

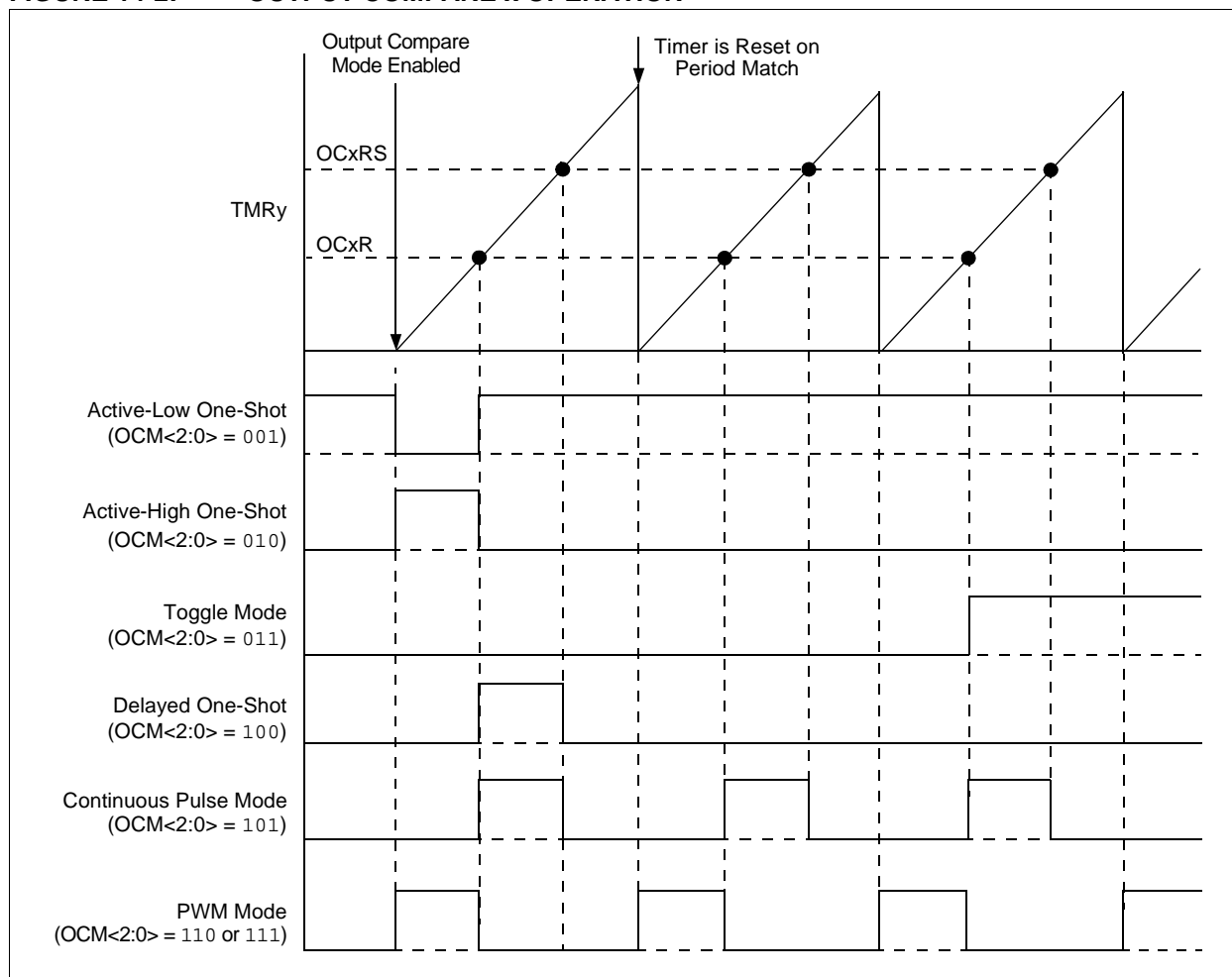
application must disable the associated timer when writing to the Output Compare Control registers to avoid malfunctions.

Note: See “Output Compare” in the “dsPIC33/PIC24 Family Reference Manual” (DS70209) for OCxR and OCxRS register restrictions.

TABLE 14-1: OUTPUT COMPARE x MODES

OCM<2:0>	Mode	OCx Pin Initial State	OCx Interrupt Generation
000	Module Disabled	Controlled by GPIO register	—
001	Active-Low One-Shot	0	OCx Rising Edge
010	Active-High One-Shot	1	OCx Falling Edge
011	Toggle	Current output is maintained	OCx Rising and Falling Edge
100	Delayed One-Shot	0	OCx Falling Edge
101	Continuous Pulse	0	OCx Falling Edge
110	PWM without Fault Protection	0, if OCxR is zero 1, if OCxR is non-zero	No Interrupt
111	PWM with Fault Protection	0, if OCxR is zero 1, if OCxR is non-zero	OCFA Falling Edge for OC1 to OC4

FIGURE 14-2: OUTPUT COMPARE x OPERATION



15.2 PWM Faults

The Motor Control PWM module incorporates up to two Fault inputs, FLTA1 and FLTB1. These Fault inputs are implemented with Class B safety features. These features ensure that the PWM outputs enter a safe state when either of the Fault inputs is asserted.

The FLTA1 and FLTB1 pins, when enabled and having ownership of a pin, also enable a soft internal pull-down resistor. The soft pull-down provides a safety feature by automatically asserting the Fault should a break occur in the Fault signal connection.

The implementation of internal pull-down resistors is dependent on the device variant. Table 15-1 describes which devices and pins implement the internal pull-down resistors.

TABLE 15-1: INTERNAL PULL-DOWN RESISTORS ON PWM FAULT PINS

Device	Fault Pin	Internal Pull-Down Implemented?
dsPIC33FJXXMC101	FLTA1	No
dsPIC33FJXXMC102	FLTA1	Yes
	FLTB1	Yes
dsPIC33FJ32MC104	FLTA1	Yes
	FLTB1	Yes

On devices without internal pull-downs on the Fault pin, it is recommended to connect an external pull-down resistor for Class B safety features.

15.2.1 PWM FAULTS AT RESET

During any Reset event, the PWM module maintains ownership of both PWM Fault pins. At Reset, both Faults are enabled in latched mode to guarantee the fail-safe power-up of the application. The application software must clear both of the PWM Faults before enabling the Motor Control PWM module.

The Fault condition must be cleared by the external circuitry driving the Fault input pin high and clearing the Fault interrupt flag. After the Fault pin condition has been cleared, the PWM module restores the PWM output signals on the next PWM period or half-period boundary.

Refer to “**Motor Control PWM**” (DS70187) in the “*dsPIC33/PIC24 Family Reference Manual*” for more information on the PWM Faults.

Note: The number of PWM Faults mapped to the device pins depend on the specific variant. Regardless of the variant, both Faults will be enabled during any Reset event. The application must clear both FLTA1 and FLTB1 before enabling the Motor Control PWM module. Refer to the specific device pin diagrams to see which Fault pins are mapped to the device pins.

15.3 Write-Protected Registers

On dsPIC33FJ(16/32)MC10X devices, write protection is implemented for the PWMxCON1, PxFLTACON and PxFLTBCON registers. The write protection feature prevents any inadvertent writes to these registers. The write protection feature can be controlled by the PWMLOCK Configuration bit in the FOSCSEL Configuration register. The default state of the write protection feature is enabled (PWMLOCK = 1). The write protection feature can be disabled by configuring PWMLOCK (FOSCSEL<6>) = 0.

The user application can gain access to these locked registers either by configuring the PWMLOCK bit (FOSCSEL<6>) = 0 or by performing the unlock sequence. To perform the unlock sequence, the user application must write two consecutive values (0xABCD and 0x4321) to the PWMxKEY register to perform the unlock operation. The write access to the PWMxCON1, PxFLTACON or PxFLTBCON registers must be the next SFR access following the unlock process. There can be no other SFR accesses during the unlock process and subsequent write access.

To write to all registers, the PWMxCON1, PxFLTACON and PxFLTBCON registers require three unlock operations.

The correct unlocking sequence is described in Example 15-1 and Example 15-2.

REGISTER 15-4: PxSECMP: PWMx SPECIAL EVENT COMPARE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTDIR ⁽¹⁾	SEVTCMP<14:8> ⁽²⁾						
bit 15	bit 8						

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SEVTCMP<7:0> ⁽²⁾							
bit 7	bit 0						

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 15 **SEVTDIR:** Special Event Trigger Time Base Direction bit⁽¹⁾
 1 = A Special Event Trigger will occur when the PWMx time base is counting down
 0 = A Special Event Trigger will occur when the PWMx time base is counting up

bit 14-0 **SEVTCMP<14:0>:** Special Event Compare Value bits⁽²⁾

- Note 1:** SEVTDIR is compared with PTDIR (PxTMR<15>) to generate the Special Event Trigger.
2: PxSECMP<14:0> is compared with PxTMR<14:0> to generate the Special Event Trigger.

REGISTER 20-2: CMxCON: COMPARATOR x CONTROL REGISTER (CONTINUED)

- bit 4 **CREF:** Comparator x Reference Select bit (VIN+ input)
 1 = VIN+ input connects to internal CVREFIN voltage
 0 = VIN+ input connects to CxINA pin
- bit 3-2 **Unimplemented:** Read as '0'
- bit 1-0 **CCH<1:0>:** Comparator x Channel Select bits
 11 = VIN- input of comparator connects to INTREF
 10 = VIN- input of comparator connects to CxIND pin
 01 = VIN- input of comparator connects to CxINC pin
 00 = VIN- input of comparator connects to CxINB pin

The Configuration Shadow register map is shown in Table 23-1.

TABLE 23-1: CONFIGURATION SHADOW REGISTER MAP

File Name	Addr.	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FGS	F80004	—	—	—	—	—	—	GCP	GWRP
FOSCSEL	F80006	IESO	PWMLOCK ⁽¹⁾	—	WDTWIN1	WDTWIN0	FNOSC2	FNOSC1	FNOSC0
FOSC	F80008	FCKSM1	FCKSM0	IOL1WAY	—	—	OSCIOFNC	POSCMD1	POSCMD0
FWDT	F8000A	FWDTEN	WINDIS	PLLKEN	WDTPRE	WDTPOST3	WDTPOST2	WDTPOST1	WDTPOST0
FPOR	F8000C	PWMPIN ⁽¹⁾	HPOL ⁽¹⁾	LPOL ⁽¹⁾	ALT12C1	—	—	—	—
FICD	F8000E	Reserved ⁽²⁾	—	Reserved ⁽³⁾	Reserved ⁽³⁾	—	—	ICS1	ICS0

Legend: — = unimplemented, read as '1'.

- Note** 1: These bits are available in dsPIC33FJ16(32)MC10X devices only.
 2: This bit is reserved for use by development tools.
 3: These bits are reserved, program as '0'.

The Configuration Flash Word maps are shown in Table 23-2 and Table 23-3.

TABLE 23-2: CONFIGURATION FLASH WORDS FOR dsPIC33FJ16(GP/MC)10X DEVICES⁽¹⁾

File Name	Addr.	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CONFIG2	002BFC	—	IESO	PWMLOCK ⁽²⁾	PWMPIN ⁽²⁾	WDTWIN1	WDTWIN0	FNOSC2	FNOSC1	FNOSC0	FCKSM1	FCKSM0	OSCIOFNC ⁽⁵⁾	IOL1WAY	LPOL ⁽²⁾	ALT12C1	POSCMD1	POSCMD0
CONFIG1	002BFE	—	Reserved ⁽³⁾	Reserved ⁽³⁾	GCP	GWRP	Reserved ⁽⁴⁾	HPOL ⁽²⁾	ICS1	ICS0	FWDTEN	WINDIS	PLLKEN	WDTPRE	WDTPOST3	WDTPOST2	WDTPOST1	WDTPOST0

Legend: — = unimplemented, read as '1'.

- Note** 1: During a Power-on Reset (POR), the contents of these Flash locations are transferred to the Configuration Shadow registers.
 2: These bits are reserved in dsPIC33FJ16GP10X devices and read as '1'.
 3: These bits are reserved, program as '0'.
 4: This bit is reserved for use by development tools and must be programmed as '1'.
 5: This bit is programmed to '0' during final tests in the factory.

TABLE 23-3: CONFIGURATION FLASH WORDS FOR dsPIC33FJ32(GP/MC)10X DEVICES⁽¹⁾

File Name	Addr.	Bits 23-16	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CONFIG2	0057FC	—	IESO	PWMLOCK ⁽²⁾	PWMPIN ⁽²⁾	WDTWIN1	WDTWIN0	FNOSC2	FNOSC1	FNOSC0	FCKSM1	FCKSM0	OSCIOFNC ⁽⁵⁾	IOL1WAY	LPOL ⁽²⁾	ALT12C1	POSCMD1	POSCMD0
CONFIG1	0057FE	—	Reserved ⁽³⁾	Reserved ⁽³⁾	GCP	GWRP	Reserved ⁽⁴⁾	HPOL ⁽²⁾	ICS1	ICS0	FWDTEN	WINDIS	PLLKEN	WDTPRE	WDTPOST3	WDTPOST2	WDTPOST1	WDTPOST0

Legend: — = unimplemented, read as '1'.

- Note** 1: During a Power-on Reset (POR), the contents of these Flash locations are transferred to the Configuration Shadow registers.
 2: These bits are reserved in dsPIC33FJ32GP10X devices and read as '1'.
 3: These bits are reserved, program as '0'.
 4: This bit is reserved for use by development tools and must be programmed as '1'.
 5: This bit is programmed to '0' during final tests in the factory.

FIGURE 26-6: INPUT CAPTURE x (ICx) TIMING CHARACTERISTICS

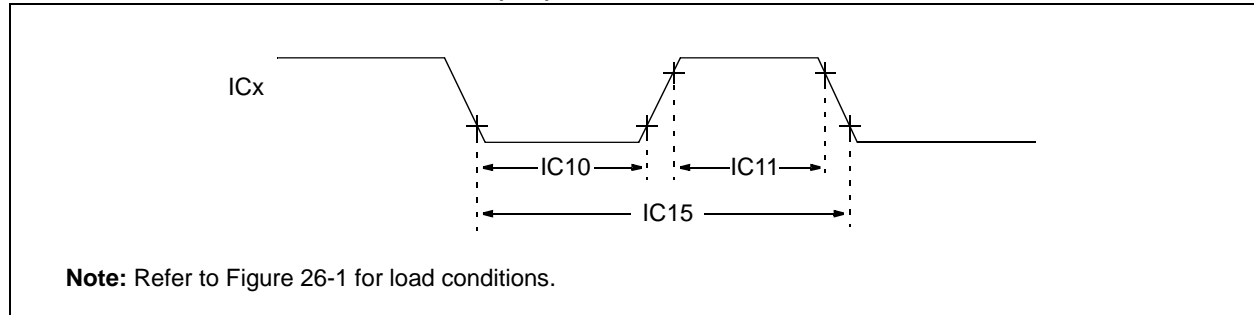


TABLE 26-25: INPUT CAPTURE x (ICx) TIMING REQUIREMENTS

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Symbol	Characteristic ⁽¹⁾		Min	Max	Units	Conditions
IC10	TccL	ICx Input Low Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	
			With Prescaler	10	—	ns	
IC11	TccH	ICx Input High Time	No Prescaler	$0.5 T_{CY} + 20$	—	ns	
			With Prescaler	10	—	ns	
IC15	TccP	ICx Input Period		$(T_{CY} + 40)/N$	—	ns	N = prescale value (1, 4, 16)

Note 1: These parameters are characterized by similarity, but are not tested in manufacturing.

FIGURE 26-12: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 1) TIMING CHARACTERISTICS FOR dsPIC33FJ16(GP/MC)10X

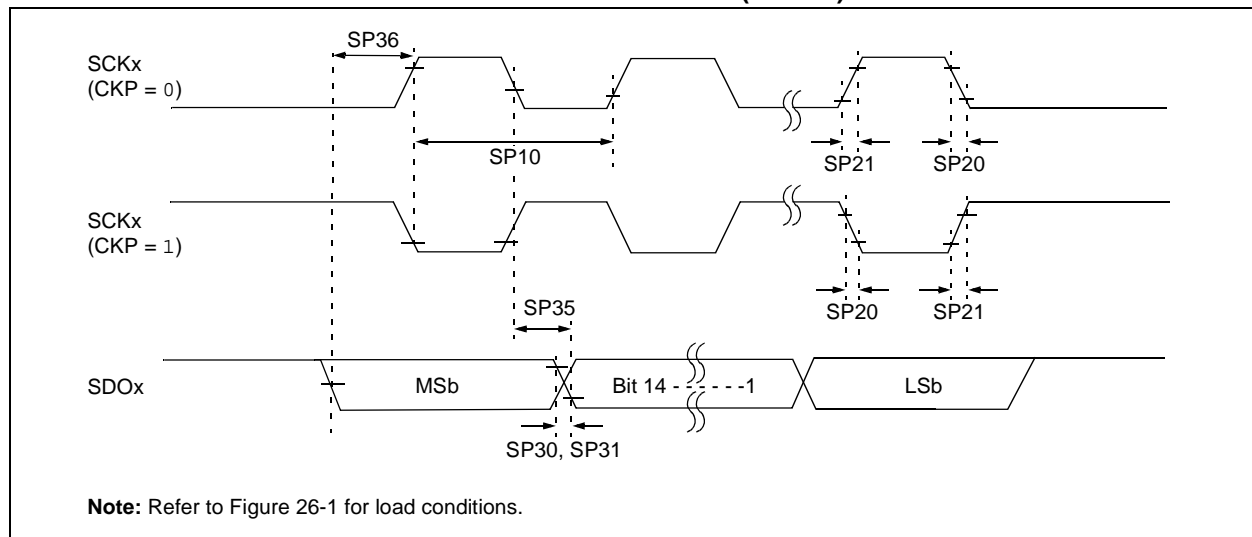


TABLE 26-30: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS FOR dsPIC33FJ16(GP/MC)10X

AC CHARACTERISTICS			Standard Operating Conditions: 2.4V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ Ta ≤ +85°C for Industrial -40°C ≤ Ta ≤ +125°C for Extended				
Param No.	Symbol	Characteristic ⁽¹⁾	Min	Typ ⁽²⁾	Max	Units	Conditions
SP10	TscP	Maximum SCKx Frequency	—	—	15	MHz	See Note 3
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP21	TscR	SCKx Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See Parameter DO32 and Note 4
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See Parameter DO31 and Note 4
SP35	TscH2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	
SP36	TdiV2sch, TdiV2scL	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	

Note 1: These parameters are characterized, but are not tested in manufacturing.

2: Data in “Typ” column is at 3.3V, +25°C unless otherwise stated.

3: The minimum clock period for SCKx is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

4: Assumes 50 pF load on all SPIx pins.

FIGURE 26-33: FORWARD VOLTAGE VERSUS TEMPERATURE

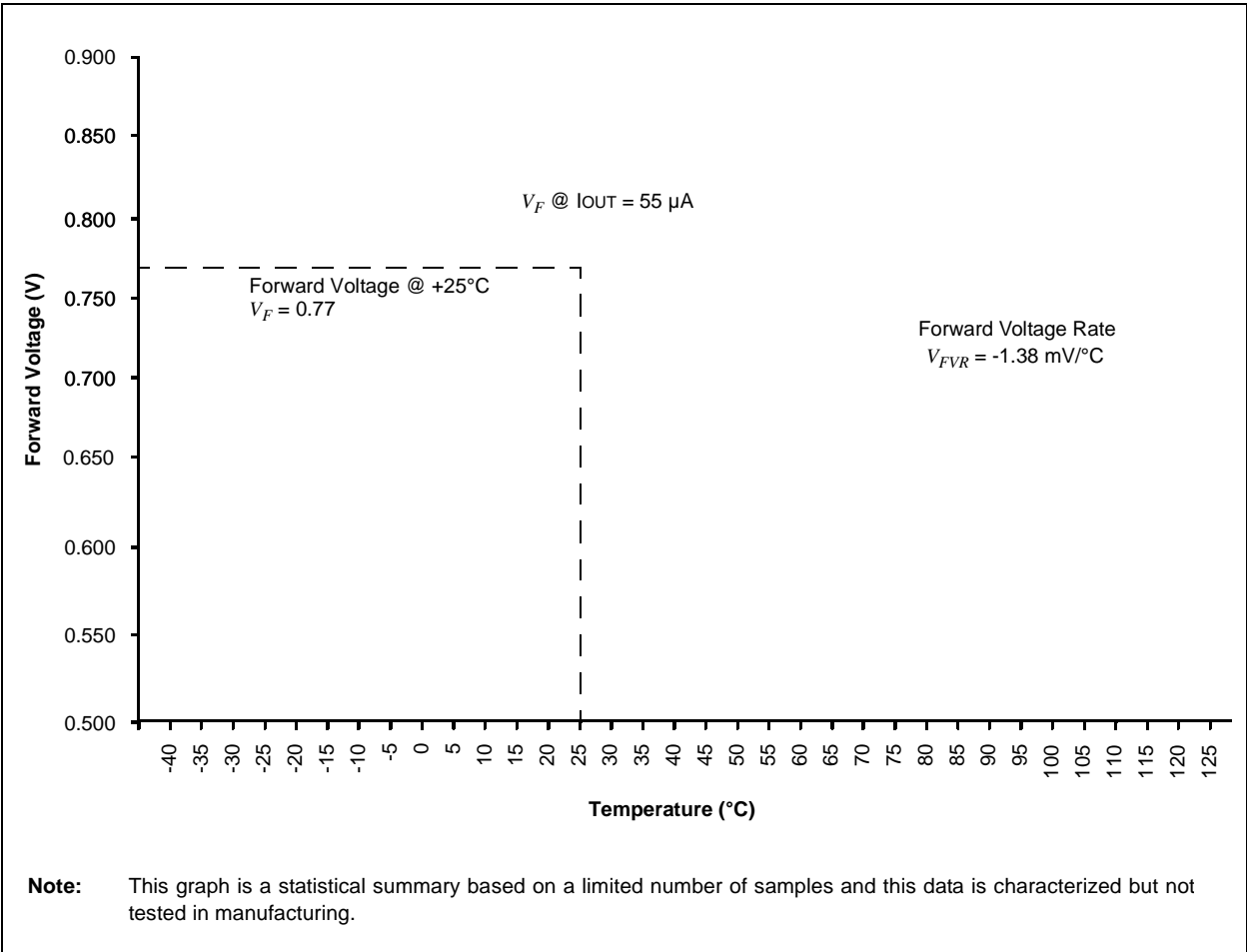


TABLE 27-4: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature		
Parameter No.	Typical	Max	Units	Conditions	
Operating Current (IDD) – dsPIC33FJ32(GP/MC)10X Devices					
DC20e	1.3	2.0	mA	3.3V	LPRC (32.768 kHz)
DC22e	7.25	8.5	mA	3.3V	5 MIPS

TABLE 27-5: DC CHARACTERISTICS: IDLE CURRENT (IDLE)

DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature		
Parameter No.	Typical	Max	Units	Conditions	
Idle Current (IDLE) – dsPIC33FJ16(GP/MC)10X Devices					
DC40e	0.5	1.0	mA	3.3V	LPRC (32.768 kHz)
DC22e	1.2	1.6	mA	3.3V	5 MIPS
Idle Current (IDLE) – dsPIC33FJ32(GP/MC)10X Devices					
DC40e	0.5	1.0	mA	3.3V	LPRC (32.768 kHz)
DC22e	1.4	1.8	mA	3.3V	5 MIPS

TABLE 27-6: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

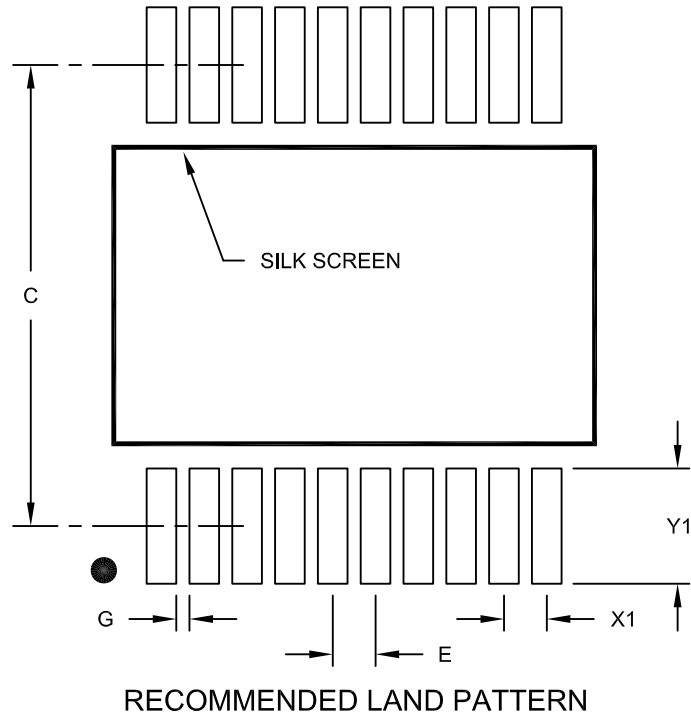
DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +150°C for High Temperature		
Parameter No.	Typical ⁽¹⁾	Max	Units	Conditions	
Power-Down Current (IPD) – dsPIC33FJXX(GP/MC)10X					
DC60e	500	1000	μA	3.3V	Base Power-Down Current
DC61e	650	1000	μA	3.3V	Watchdog Timer Current: ΔIWDT

Note 1: Data in the Typical column is 3.3V unless otherwise stated.

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104

20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C		7.20	
Contact Pad Width (X20)	X1			0.45
Contact Pad Length (X20)	Y1			1.75
Distance Between Pads	G	0.20		

Notes:

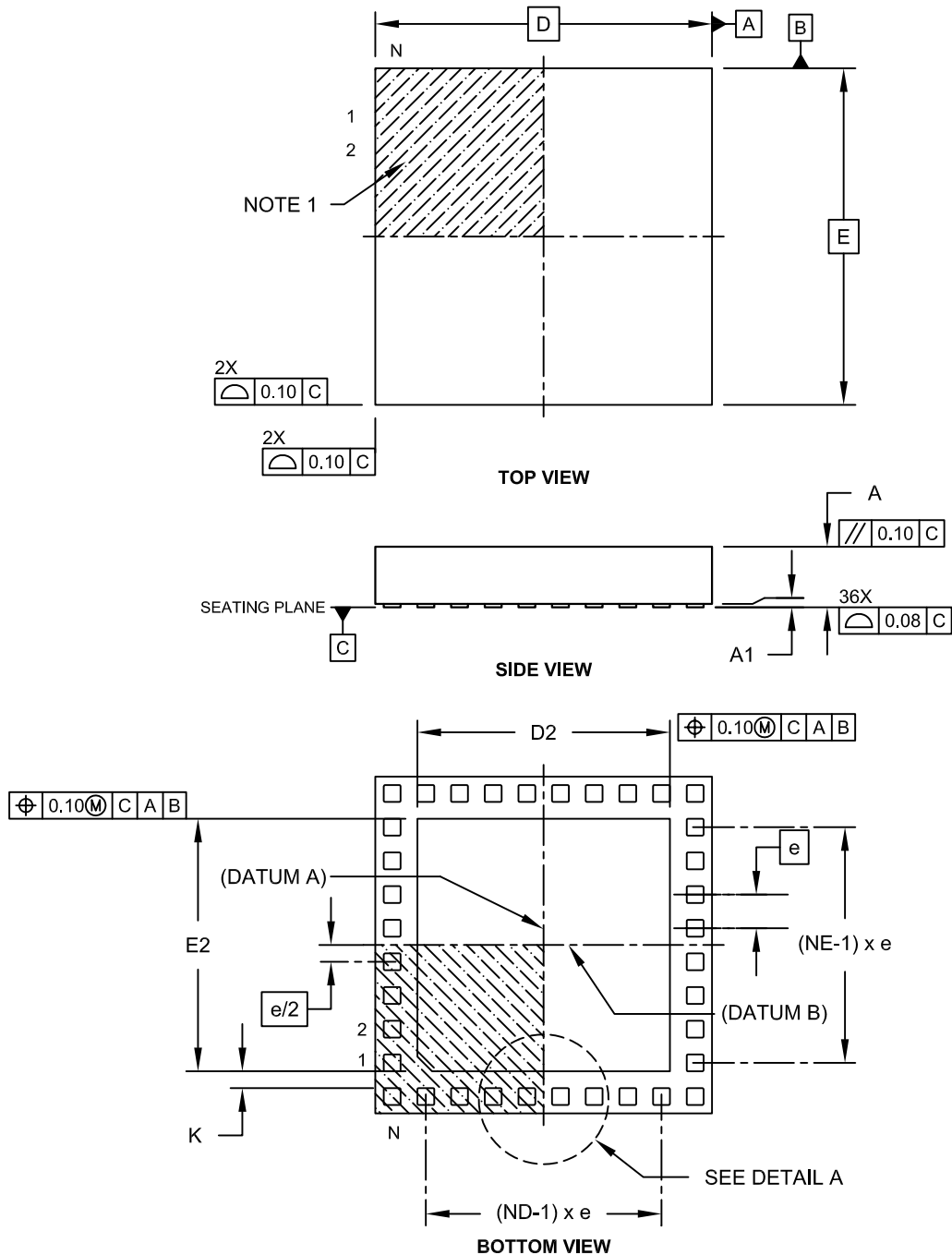
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2072A

36-Terminal Very Thin Thermal Leadless Array Package (TL) – 5x5x0.9 mm Body with Exposed Pad [VTLA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Microchip Technology Drawing C04-187C Sheet 1 of 2

dsPIC33FJ16(GP/MC)101/102 AND dsPIC33FJ32(GP/MC)101/102/104

ALCFGRPT (Alarm Configuration).....	248	PMD3 (Peripheral Module Disable Control 3).....	137
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ALRMVAL (Alarm Month and Day Value, ALRMPTR Bits = 10)	252	PWMxCON1 (PWMx Control 1).....	188
ALRMVAL (Alarm Weekday and Hours Value, ALRMPTR Bits = 01)	253	PWMxCON2 (PWMx Control 2).....	189
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CMxCON (Comparator x Control)	235	PxDC2 (PWMx Duty Cycle 2)	195
CMxFLTR (Comparator x Filter Control)	241	PxDC3 (PWMx Duty Cycle 3)	195
CMxMSKCON (Comparator x Mask Gating Control).....	239	PxDTCN1 (PWMx Dead-Time Control 1)	190
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IPC2 (Interrupt Priority Control 2)	114	RPOR8 (Peripheral Pin Select Output 8).....	161
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