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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Active
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	50MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (4)
SATA	-
SATA USB	-
	- - 3.3V
USB	- - 3.3V -40°C ~ 95°C (TA)
USB Voltage - I/O	
USB Voltage - I/O Operating Temperature	-40°C ~ 95°C (TA)
USB Voltage - I/O Operating Temperature Security Features	-40°C ~ 95°C (TA)
USB Voltage - I/O Operating Temperature Security Features Package / Case	-40°C ~ 95°C (TA) - 357-BBGA

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2 Features

The following list summarizes the key MPC860 features:

- Embedded single-issue, 32-bit core (implementing the Power Architecture technology) with thirty-two 32-bit general-purpose registers (GPRs)
 - The core performs branch prediction with conditional prefetch without conditional execution.
 - 4- or 8-Kbyte data cache and 4- or 16-Kbyte instruction cache (see Table 1)
 - 16-Kbyte instruction caches are four-way, set-associative with 256 sets; 4-Kbyte instruction caches are two-way, set-associative with 128 sets.
 - 8-Kbyte data caches are two-way, set-associative with 256 sets; 4-Kbyte data caches are two-way, set-associative with 128 sets.
 - Cache coherency for both instruction and data caches is maintained on 128-bit (4-word) cache blocks.
 - Caches are physically addressed, implement a least recently used (LRU) replacement algorithm, and are lockable on a cache block basis.
 - MMUs with 32-entry TLB, fully-associative instruction, and data TLBs
 - MMUs support multiple page sizes of 4-, 16-, and 512-Kbytes, and 8-Mbytes; 16 virtual address spaces and 16 protection groups
 - Advanced on-chip-emulation debug mode
- Up to 32-bit data bus (dynamic bus sizing for 8, 16, and 32 bits)
- 32 address lines
- Operates at up to 80 MHz
- Memory controller (eight banks)
 - Contains complete dynamic RAM (DRAM) controller
 - Each bank can be a chip select or RAS to support a DRAM bank.
 - Up to 15 wait states programmable per memory bank
 - Glueless interface to DRAM, SIMMS, SRAM, EPROM, Flash EPROM, and other memory devices
 - DRAM controller programmable to support most size and speed memory interfaces
 - Four \overline{CAS} lines, four \overline{WE} lines, and one \overline{OE} line
 - Boot chip-select available at reset (options for 8-, 16-, or 32-bit memory)
 - Variable block sizes (32 Kbytes to 256 Mbytes)
 - Selectable write protection
 - On-chip bus arbitration logic
- General-purpose timers
 - Four 16-bit timers or two 32-bit timers
 - Gate mode can enable/disable counting
 - Interrupt can be masked on reference match and event capture.



Features

- System integration unit (SIU)
 - Bus monitor
 - Software watchdog
 - Periodic interrupt timer (PIT)
 - Low-power stop mode
 - Clock synthesizer
 - Decrementer, time base, and real-time clock (RTC)
 - Reset controller
 - IEEE 1149.1TM Std. test access port (JTAG)
- Interrupts
 - Seven external interrupt request (IRQ) lines
 - 12 port pins with interrupt capability
 - 23 internal interrupt sources
 - Programmable priority between SCCs
 - Programmable highest priority request
- 10/100 Mbps Ethernet support, fully compliant with the IEEE 802.3u® Standard (not available when using ATM over UTOPIA interface)
- ATM support compliant with ATM forum UNI 4.0 specification
 - Cell processing up to 50–70 Mbps at 50-MHz system clock
 - Cell multiplexing/demultiplexing
 - Support of AAL5 and AAL0 protocols on a per-VC basis. AAL0 support enables OAM and software implementation of other protocols.
 - ATM pace control (APC) scheduler, providing direct support for constant bit rate (CBR) and unspecified bit rate (UBR) and providing control mechanisms enabling software support of available bit rate (ABR)
 - Physical interface support for UTOPIA (10/100-Mbps is not supported with this interface) and byte-aligned serial (for example, T1/E1/ADSL)
 - UTOPIA-mode ATM supports level-1 master with cell-level handshake, multi-PHY (up to four physical layer devices), connection to 25-, 51-, or 155-Mbps framers, and UTOPIA/system clock ratios of 1/2 or 1/3.
 - Serial-mode ATM connection supports transmission convergence (TC) function for T1/E1/ADSL lines, cell delineation, cell payload scrambling/descrambling, automatic idle/unassigned cell insertion/stripping, header error control (HEC) generation, checking, and statistics.
- Communications processor module (CPM)
 - RISC communications processor (CP)
 - Communication-specific commands (for example, GRACEFUL STOP TRANSMIT, ENTER HUNT MODE, and RESTART TRANSMIT)
 - Supports continuous mode transmission and reception on all serial channels



- Up to 8 Kbytes of dual-port RAM
- 16 serial DMA (SDMA) channels
- Three parallel I/O registers with open-drain capability
- Four baud-rate generators (BRGs)
 - Independent (can be tied to any SCC or SMC)
 - Allows changes during operation
 - Autobaud support option
- Four serial communications controllers (SCCs)
 - Ethernet/IEEE 802.3® standard optional on SCC1–4, supporting full 10-Mbps operation (available only on specially programmed devices)
 - HDLC/SDLC (all channels supported at 2 Mbps)
 - HDLC bus (implements an HDLC-based local area network (LAN))
 - Asynchronous HDLC to support point-to-point protocol (PPP)
 - AppleTalk
 - Universal asynchronous receiver transmitter (UART)
 - Synchronous UART
 - Serial infrared (IrDA)
 - Binary synchronous communication (BISYNC)
 - Totally transparent (bit streams)
 - Totally transparent (frame-based with optional cyclic redundancy check (CRC))
- Two SMCs (serial management channels)
 - UART
 - Transparent
 - General circuit interface (GCI) controller
 - Can be connected to the time-division multiplexed (TDM) channels
- One SPI (serial peripheral interface)
 - Supports master and slave modes
 - Supports multimaster operation on the same bus
- One I²C (inter-integrated circuit) port
 - Supports master and slave modes
 - Multiple-master environment support
- Time-slot assigner (TSA)
 - Allows SCCs and SMCs to run in multiplexed and/or non-multiplexed operation
 - Supports T1, CEPT, PCM highway, ISDN basic rate, ISDN primary rate, user defined
 - 1- or 8-bit resolution
 - Allows independent transmit and receive routing, frame synchronization, and clocking



Table 4 shows the thermal characteristics for the MPC860.

Table 4. MPC860 Thermal Resistance Data

Rating	Environment Symbo			ZP MPC860P	ZQ / VR MPC860P	Unit
Mold Compound Thickness					1.15	mm
Junction-to-ambient ¹	Natural convection	Single-layer board (1s)	$R_{\theta JA}^2$	34	34	°C/W
		Four-layer board (2s2p)	$R_{\theta JMA}^3$	22	22	
	Airflow (200 ft/min)	Single-layer board (1s)	$R_{\theta JMA}^3$	27	27	
		Four-layer board (2s2p)	$R_{\theta JMA}^3$	18	18	
Junction-to-board 4		•	$R_{\theta JB}$	14	13	
Junction-to-case ⁵			$R_{\theta JC}$	6	8	
Junction-to-package top 6	Natural convection	Ψ_{JT}	2	2		

Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, airflow, power dissipation of other components on the board, and board thermal resistance

² Per SEMI G38-87 and JEDEC JESD51-2 with the single-layer board horizontal.

³ Per JEDEC JESD51-6 with the board horizontal.

⁴ Thermal resistance between the die and the printed-circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.

Indicates the average thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1) with the cold plate temperature used for the case temperature. For exposed pad packages where the pad would be expected to be soldered, junction-to-case thermal resistance is a simulated value from the junction to the exposed pad without contact resistance.

⁶ Thermal characterization parameter indicating the temperature difference between the package top and the junction temperature per JEDEC JESD51-2.

Thermal Calculation and Measurement

7 Thermal Calculation and Measurement

For the following discussions, $P_D = (V_{DD} \times I_{DD}) + PI/O$, where PI/O is the power dissipation of the I/O drivers.

7.1 Estimation with Junction-to-Ambient Thermal Resistance

An estimation of the chip junction temperature, T_I , in °C can be obtained from the equation:

$$T_I = T_A + (R_{\theta IA} \times P_D)$$

where:

 T_A = ambient temperature (°C)

 $R_{\theta,IA}$ = package junction-to-ambient thermal resistance (°C/W)

 P_D = power dissipation in package

The junction-to-ambient thermal resistance is an industry standard value which provides a quick and easy estimation of thermal performance. However, the answer is only an estimate; test cases have demonstrated that errors of a factor of two (in the quantity $T_I - T_A$) are possible.

7.2 Estimation with Junction-to-Case Thermal Resistance

Historically, the thermal resistance has frequently been expressed as the sum of a junction-to-case thermal resistance and a case-to-ambient thermal resistance:

$$R_{\theta JA} = R_{\theta JC} + R_{\theta CA}$$

where:

 $R_{\theta JA}$ = junction-to-ambient thermal resistance (°C/W)

 $R_{\theta JC}$ = junction-to-case thermal resistance (°C/W)

 $R_{\theta CA}$ = case-to-ambient thermal resistance (°C/W)

 $R_{\theta JC}$ is device related and cannot be influenced by the user. The user adjusts the thermal environment to affect the case-to-ambient thermal resistance, $R_{\theta CA}$. For instance, the user can change the airflow around the device, add a heat sink, change the mounting arrangement on the printed-circuit board, or change the thermal dissipation on the printed-circuit board surrounding the device. This thermal model is most useful for ceramic packages with heat sinks where some 90% of the heat flows through the case and the heat sink to the ambient environment. For most packages, a better model is required.

7.3 Estimation with Junction-to-Board Thermal Resistance

A simple package thermal model which has demonstrated reasonable accuracy (about 20%) is a two-resistor model consisting of a junction-to-board and a junction-to-case thermal resistance. The junction-to-case thermal resistance covers the situation where a heat sink is used or where a substantial amount of heat is dissipated from the top of the package. The junction-to-board thermal resistance describes the thermal performance when most of the heat is conducted to the printed-circuit board. It has been observed that the thermal performance of most plastic packages, especially PBGA packages, is strongly dependent on the board temperature; see Figure 2.

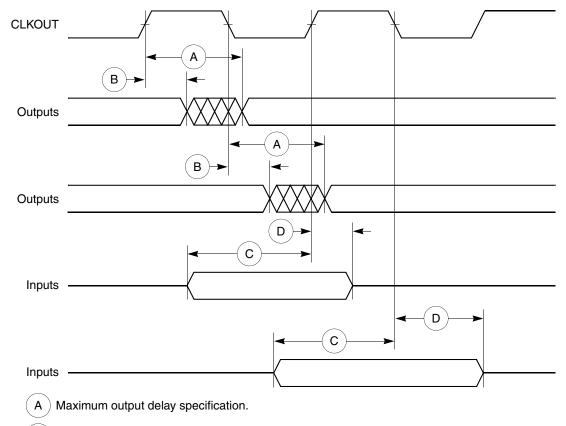


Table 7. Bus Operation Timings (continued)

N	Characteristic	33 MHz		40 MHz		50 MHz		66 MHz		Unit
Num	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
B31a	CLKOUT falling edge to CS valid—as requested by control bit CST1 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B31b	CLKOUT rising edge to CS valid—as requested by control bit CST2 in the corresponding word in UPM	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns
B31c	CLKOUT rising edge to CS valid—as requested by control bit CST3 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.04	ns
B31d	CLKOUT falling edge to $\overline{\text{CS}}$ valid—as requested by control bit CST1 in the corresponding word in UPM, EBDF = 1	13.26	17.99	11.28	16.00	9.40	14.13	7.58	12.31	ns
B32	CLKOUT falling edge to BS valid—as requested by control bit BST4 in the corresponding word in UPM	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B32a	CLKOUT falling edge to $\overline{\text{BS}}$ valid—as requested by control bit BST1 in the corresponding word in UPM, EBDF = 0	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B32b	CLKOUT rising edge to BS valid—as requested by control bit BST2 in the corresponding word in UPM	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns
B32c	CLKOUT rising edge to BS valid—as requested by control bit BST3 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B32d	CLKOUT falling edge to BS valid—as requested by control bit BST1 in the corresponding word in UPM, EBDF = 1	13.26	17.99	11.28	16.00	9.40	14.13	7.58	12.31	ns
B33	CLKOUT falling edge to GPL valid—as requested by control bit GxT4 in the corresponding word in UPM		6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B33a	CLKOUT rising edge to GPL valid—as requested by control bit GxT3 in the corresponding word in UPM		14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B34	A(0:31), BADDR(28:30), and D(0:31) to $\overline{\text{CS}}$ valid—as requested by control bit CST4 in the corresponding word in UPM		_	4.25	_	3.00	_	1.79	_	ns
B34a	A(0:31), BADDR(28:30), and D(0:31) to $\overline{\text{CS}}$ valid—as requested by control bit CST1 in the corresponding word in UPM		_	10.50	_	8.00	_	5.58	_	ns
B34b	A(0:31), BADDR(28:30), and D(0:31) to $\overline{\text{CS}}$ valid—as requested by control bit CST2 in the corresponding word in UPM		_	16.75	_	13.00	_	9.36	_	ns



Figure 3 is the control timing diagram.



- (B) Minimum output hold time.
- C Minimum input setup time specification.
- (D) Minimum input hold time specification.

Figure 3. Control Timing

Figure 4 provides the timing for the external clock.

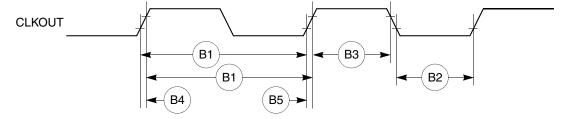


Figure 4. External Clock Timing



Bus Signal Timing

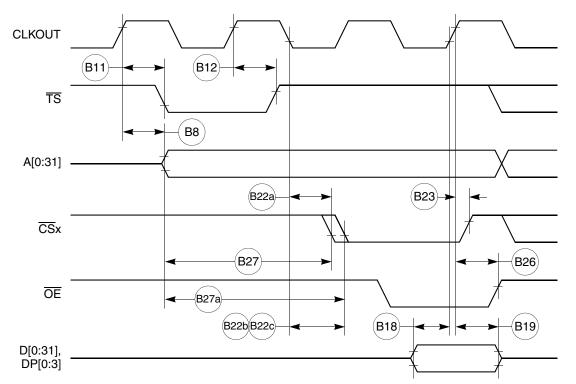


Figure 13. External Bus Read Timing (GPCM Controlled—TRLX = 0 or 1, ACS = 10, ACS = 11)



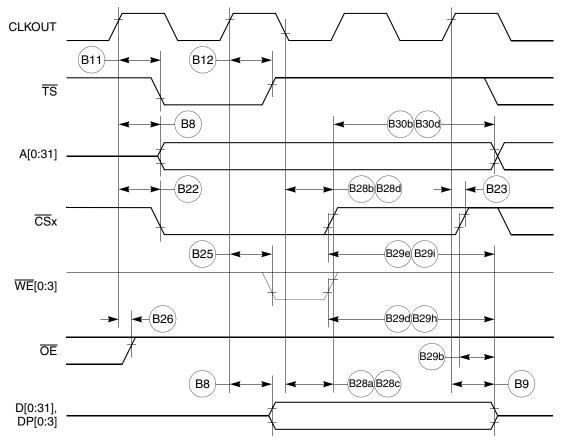


Figure 16. External Bus Write Timing (GPCM Controlled—TRLX = 0 or 1, CSNT = 1)



Bus Signal Timing

Figure 20 provides the timing for the synchronous external master access controlled by the GPCM.

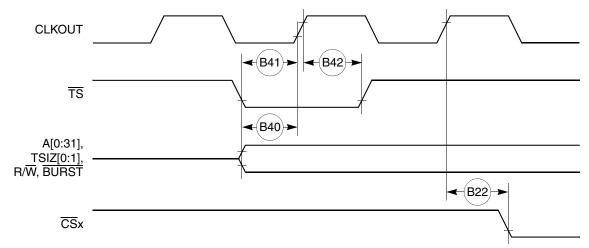


Figure 20. Synchronous External Master Access Timing (GPCM Handled ACS = 00)

Figure 21 provides the timing for the asynchronous external master memory access controlled by the GPCM.

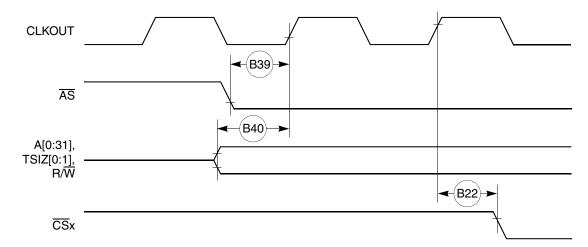


Figure 21. Asynchronous External Master Memory Access Timing (GPCM Controlled—ACS = 00)

Figure 22 provides the timing for the asynchronous external master control signals negation.

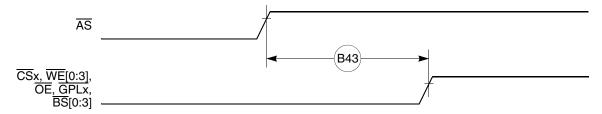


Figure 22. Asynchronous External Master—Control Signals Negation Timing



Figure 25 provides the PCMCIA access cycle timing for the external bus read.

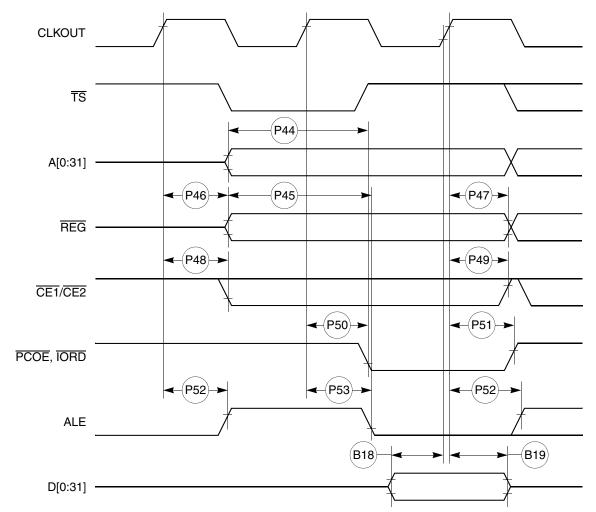


Figure 25. PCMCIA Access Cycle Timing External Bus Read



Bus Signal Timing

Figure 32 shows the reset timing for the data bus configuration.

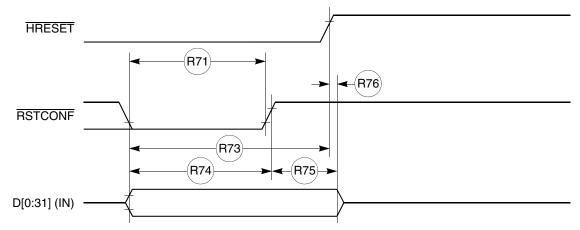


Figure 32. Reset Timing—Configuration from Data Bus

Figure 33 provides the reset timing for the data bus weak drive during configuration.

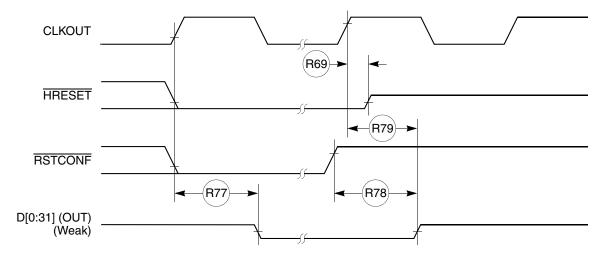


Figure 33. Reset Timing—Data Bus Weak Drive During Configuration

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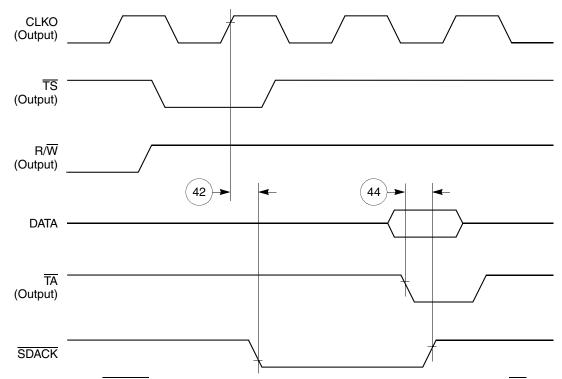


Figure 47. SDACK Timing Diagram—Peripheral Write, Internally-Generated TA

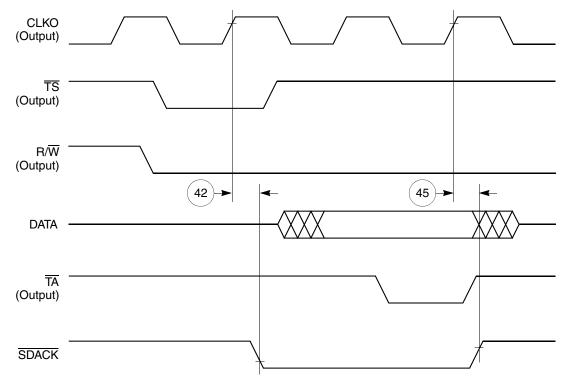


Figure 48. SDACK Timing Diagram—Peripheral Read, Internally-Generated TA



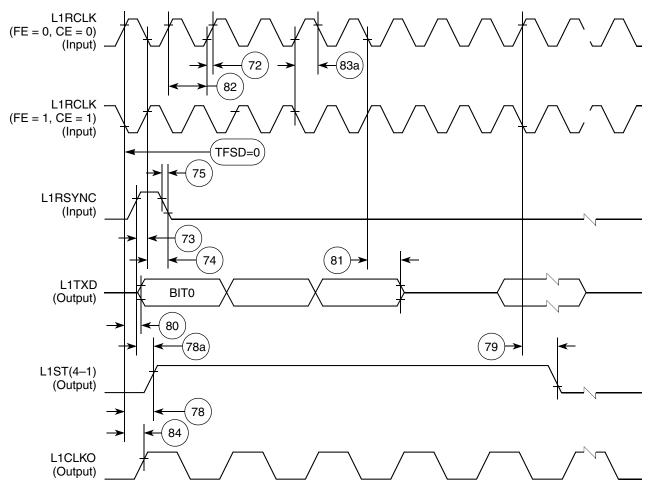


Figure 54. SI Transmit Timing with Double Speed Clocking (DSC = 1)



CPM Electrical Characteristics

Table 22. Ethernet Timing (continued)

Num	Chavastaviatia	All Frequencies		Unit
Num	Characteristic	Min Max Unit		
135	RSTRT active delay (from TCLK1 falling edge)	10	50	ns
136	RSTRT inactive delay (from TCLK1 falling edge)	10	50	ns
137	REJECT width low	1	_	CLK
138	CLKO1 low to SDACK asserted ²	_	20	ns
139	CLKO1 low to SDACK negated ²	_	20	ns

¹ The ratios SYNCCLK/RCLK1 and SYNCCLK/TCLK1 must be greater than or equal to 2/1.

² SDACK is asserted whenever the SDMA writes the incoming frame DA into memory.

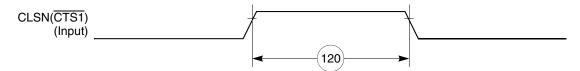


Figure 59. Ethernet Collision Timing Diagram

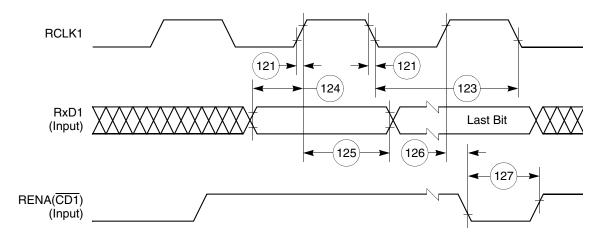
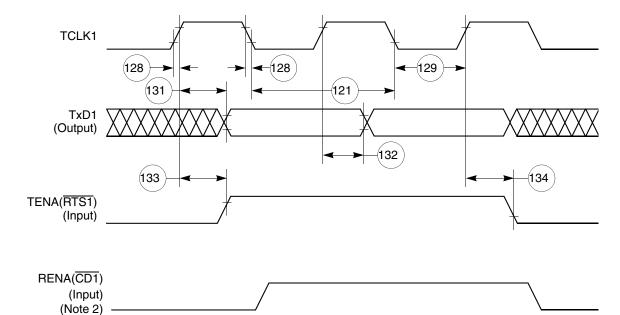


Figure 60. Ethernet Receive Timing Diagram





Notes:

- 1. Transmit clock invert (TCI) bit in GSMR is set.
- 2. If RENA is deasserted before TENA, or RENA is not asserted at all during transmit, then the CSL bit is set in the buffer descriptor at the end of the frame transmission.

Figure 61. Ethernet Transmit Timing Diagram

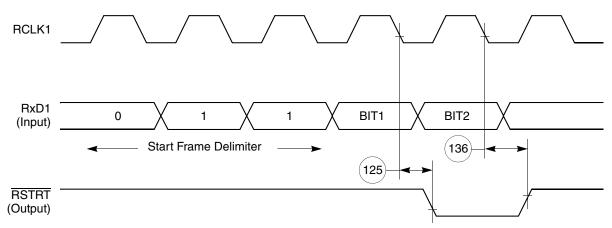


Figure 62. CAM Interface Receive Start Timing Diagram

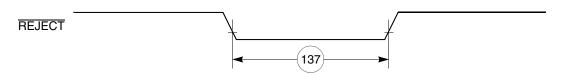


Figure 63. CAM Interface REJECT Timing Diagram

CPM Electrical Characteristics

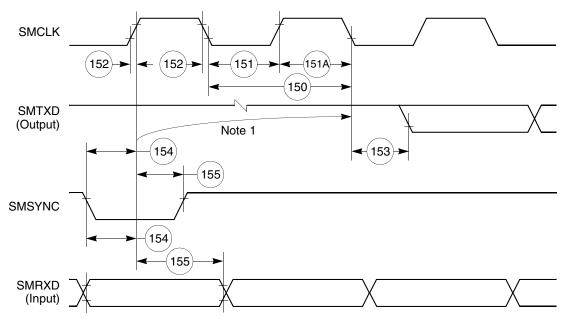
SMC Transparent AC Electrical Specifications 11.9

Table 23 provides the SMC transparent timings as shown in Figure 64.

Table 23. SMC Transparent Timing

Neven	Characteristic	All Freq	Unit	
Num	Characteristic	Min Max Unit		
150	SMCLK clock period ¹	100	_	ns
151	SMCLK width low	50	_	ns
151A	SMCLK width high	50	_	ns
152	SMCLK rise/fall time	_	15	ns
153	SMTXD active delay (from SMCLK falling edge)	10	50	ns
154	SMRXD/SMSYNC setup time	20	_	ns
155	RXD1/SMSYNC hold time	5	_	ns

¹ SYNCCLK must be at least twice as fast as SMCLK.



Note:
1. This delay is equal to an integer number of character-length clocks.

Figure 64. SMC Transparent Timing Diagram



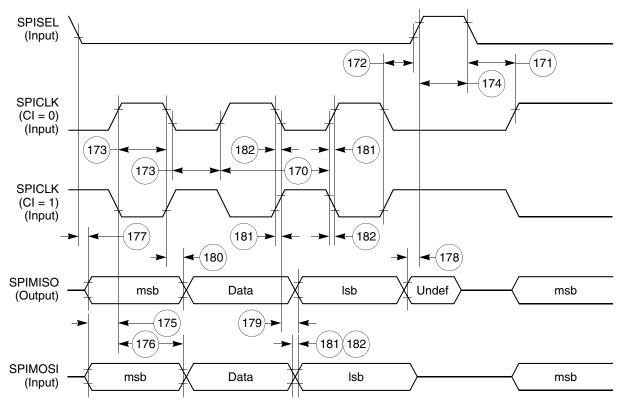


Figure 67. SPI Slave (CP = 0) Timing Diagram

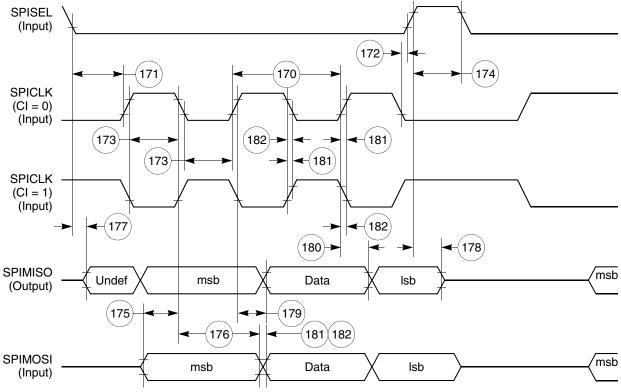


Figure 68. SPI Slave (CP = 1) Timing Diagram



UTOPIA AC Electrical Specifications

Figure 70 shows signal timings during UTOPIA receive operations.

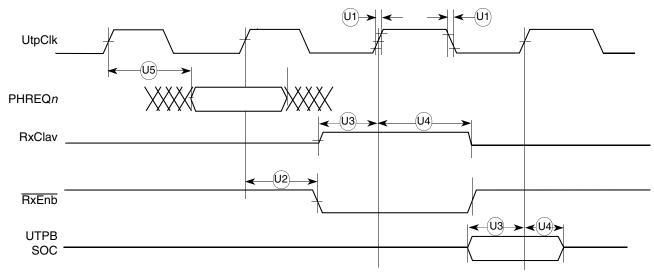


Figure 70. UTOPIA Receive Timing

Figure 71 shows signal timings during UTOPIA transmit operations.

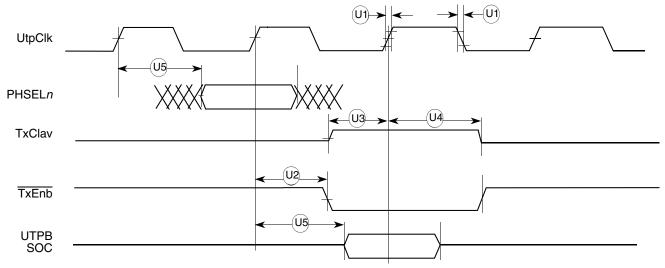


Figure 71. UTOPIA Transmit Timing

MPC860 PowerQUICC Family Hardware Specifications, Rev. 10



Document Revision History

15 Document Revision History

Table 35 lists significant changes between revisions of this hardware specification.

Table 35. Document Revision History

Revision	Date	Changes
10	09/2015	In Table 34, moved MPC855TCVR50D4 and MPC855TCVR66D4 under the extended temperature (–40° to 95°C) and removed MC860ENCVR50D4R2 from the normal temperature Tape and Reel.
9	10/2011	Updated orderable part numbers in Table 34, "MPC860 Family Package/Frequency Availability."
8	08/2007	 Updated template. On page 1, added a second paragraph. After Table 2, inserted a new figure showing the undershoot/overshoot voltage (Figure 1) and renumbered the rest of the figures. In Figure 3, changed all reference voltage measurement points from 0.2 and 0.8 V to 50% level. In Table 16, changed num 46 description to read, "TA assertion to rising edge" In Figure 46, changed TA to reflect the rising edge of the clock.
7.0	9/2004	 Added a tablefootnote to Table 6 DC Electrical Specifications about meeting the VIL Max of the I2C Standard Replaced the thermal characteristics in Table 4 by the ZQ package Add the new parts to the Ordering and Availablity Chart in Table 34 Added the mechanical spec of the ZQ package in Figure 78 Removed all of the old revisions from Table 5
6.3	9/2003	Added Section 11.2 on the Port C interrupt pins Nontechnical reformatting
6.2	8/2003	Changed B28a through B28d and B29d to show that TRLX can be 0 or 1 Changed reference documentation to reflect the Rev 2 MPC860 PowerQUICC Family Users Manual Nontechnical reformatting
6.1	11/2002	 Corrected UTOPIA RXenb* and TXenb* timing values Changed incorrect usage of Vcc to Vdd Corrected dual port RAM to 8 Kbytes
6	10/2002	Added the MPC855T. Corrected Figure 26 on page -36.
5.1	11/2001	Revised template format, removed references to MAC functionality, changed Table 7 B23 max value @ 66 MHz from 2ns to 8ns, added this revision history table