NXP USA Inc. - MPC860PCZQ66D4 Datasheet



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Applications of **Embedded - Microprocessors**

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Obsolete
MPC8xx
1 Core, 32-Bit
66MHz
Communications; CPM
DRAM
No
-
10Mbps (4), 10/100Mbps (1)
-
-
3.3V
-40°C ~ 95°C (TA)
-
357-BBGA
357-PBGA (25x25)
https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc860pczq66d4

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Overview

1 Overview

The MPC860 power quad integrated communications controller (PowerQUICCTM) is a versatile one-chip integrated microprocessor and peripheral combination designed for a variety of controller applications. It particularly excels in communications and networking systems. The PowerQUICC unit is referred to as the MPC860 in this hardware specification.

The MPC860 implements Power ArchitectureTM technology and contains a superset of Freescale's MC68360 quad integrated communications controller (QUICC), referred to here as the QUICC, RISC communications proceessor module (CPM). The CPU on the MPC860 is a 32-bit core built on Power Architecture technology that incorporates memory management units (MMUs) and instruction and data caches.. The CPM from the MC68360 QUICC has been enhanced by the addition of the inter-integrated controller (I²C) channel. The memory controller has been enhanced, enabling the MPC860 to support any type of memory, including high-performance memories and new types of DRAMs. A PCMCIA socket controller supports up to two sockets. A real-time clock has also been integrated.

Table 1 shows the functionality supported by the MPC860 family.

	Cache (Kbytes)		Ethe	ernet				
Part	Instruction Cache	Data Cache	10T	10/100	ΑΤΜ	SCC	Reference ¹	
MPC860DE	4	4	Up to 2	_	_	2	1	
MPC860DT	4	4	Up to 2	1	Yes	2	1	
MPC860DP	16	8	Up to 2	1	Yes	2	1	
MPC860EN	4	4	Up to 4	—	—	4	1	
MPC860SR	4	4	Up to 4	—	Yes	4	1	
MPC860T	4	4	Up to 4	1	Yes	4	1	
MPC860P	16	8	Up to 4	1	Yes	4	1	
MPC855T	4	4	1	1	Yes	1	2	

Table 1. MPC860 Family Functionality

Supporting documentation for these devices refers to the following:

1. MPC860 PowerQUICC Family User's Manual (MPC860UM, Rev. 3)

2. MPC855T User's Manual (MPC855TUM, Rev. 1)



2 Features

The following list summarizes the key MPC860 features:

- Embedded single-issue, 32-bit core (implementing the Power Architecture technology) with thirty-two 32-bit general-purpose registers (GPRs)
 - The core performs branch prediction with conditional prefetch without conditional execution.
 - 4- or 8-Kbyte data cache and 4- or 16-Kbyte instruction cache (see Table 1)
 - 16-Kbyte instruction caches are four-way, set-associative with 256 sets; 4-Kbyte instruction caches are two-way, set-associative with 128 sets.
 - 8-Kbyte data caches are two-way, set-associative with 256 sets; 4-Kbyte data caches are two-way, set-associative with 128 sets.
 - Cache coherency for both instruction and data caches is maintained on 128-bit (4-word) cache blocks.
 - Caches are physically addressed, implement a least recently used (LRU) replacement algorithm, and are lockable on a cache block basis.
 - MMUs with 32-entry TLB, fully-associative instruction, and data TLBs
 - MMUs support multiple page sizes of 4-, 16-, and 512-Kbytes, and 8-Mbytes; 16 virtual address spaces and 16 protection groups
 - Advanced on-chip-emulation debug mode
- Up to 32-bit data bus (dynamic bus sizing for 8, 16, and 32 bits)
- 32 address lines
- Operates at up to 80 MHz
- Memory controller (eight banks)
 - Contains complete dynamic RAM (DRAM) controller
 - Each bank can be a chip select or \overline{RAS} to support a DRAM bank.
 - Up to 15 wait states programmable per memory bank
 - Glueless interface to DRAM, SIMMS, SRAM, EPROM, Flash EPROM, and other memory devices
 - DRAM controller programmable to support most size and speed memory interfaces
 - Four $\overline{\text{CAS}}$ lines, four $\overline{\text{WE}}$ lines, and one $\overline{\text{OE}}$ line
 - Boot chip-select available at reset (options for 8-, 16-, or 32-bit memory)
 - Variable block sizes (32 Kbytes to 256 Mbytes)
 - Selectable write protection
 - On-chip bus arbitration logic
- General-purpose timers
 - Four 16-bit timers or two 32-bit timers
 - Gate mode can enable/disable counting
 - Interrupt can be masked on reference match and event capture.



Features

- Allows dynamic changes
- Can be internally connected to six serial channels (four SCCs and two SMCs)
- Parallel interface port (PIP)
 - Centronics interface support
 - Supports fast connection between compatible ports on the MPC860 or the MC68360
- PCMCIA interface
 - Master (socket) interface, release 2.1 compliant
 - Supports two independent PCMCIA sockets
 - Supports eight memory or I/O windows
- Low power support
 - Full on-all units fully powered
 - Doze—core functional units disabled except time base decrementer, PLL, memory controller, RTC, and CPM in low-power standby
 - Sleep-all units disabled except RTC and PIT, PLL active for fast wake up
 - Deep sleep—all units disabled including PLL except RTC and PIT
 - Power down mode—all units powered down except PLL, RTC, PIT, time base, and decrementer
- Debug interface
 - Eight comparators: four operate on instruction address, two operate on data address, and two
 operate on data
 - Supports conditions: = $\neq < >$
 - Each watchpoint can generate a break-point internally.
- 3.3-V operation with 5-V TTL compatibility except EXTAL and EXTCLK
- 357-pin ball grid array (BGA) package



3 Maximum Tolerated Ratings

This section provides the maximum tolerated voltage and temperature ranges for the MPC860. Table 2 provides the maximum ratings.

This device contains circuitry protecting against damage due to high-static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for example, either GND or V_{DD}).

(GND = 0 V)

Table 2. Maximum Tolerated Ratings

Rating	Symbol	Value	Unit
Supply voltage ¹	V _{DDH}	-0.3 to 4.0	V
	V _{DDL}	-0.3 to 4.0	V
	KAPWR	-0.3 to 4.0	V
	V _{DDSYN}	-0.3 to 4.0	V
Input voltage ²	V _{in}	GND – 0.3 to V _{DDH}	V
Temperature ³ (standard)	T _{A(min)}	0	°C
	T _{j(max)}	95	°C
Temperature ³ (extended)	T _{A(min)}	-40	°C
	T _{j(max)}	95	°C
Storage temperature range	T _{stg}	-55 to 150	°C

¹ The power supply of the device must start its ramp from 0.0 V.

² Functional operating conditions are provided with the DC electrical specifications in Table 6. Absolute maximum ratings are stress ratings only; functional operation at the maxima is not guaranteed. Stress beyond those listed may affect device reliability or cause permanent damage to the device.

Caution: All inputs that tolerate 5 V cannot be more than 2.5 V greater than the supply voltage. This restriction applies to power-up and normal operation (that is, if the MPC860 is unpowered, voltage greater than 2.5 V must not be applied to its inputs).

³ Minimum temperatures are guaranteed as ambient temperature, T_A. Maximum temperatures are guaranteed as junction temperature, T_j.



Thermal Calculation and Measurement

7 Thermal Calculation and Measurement

For the following discussions, $P_D = (V_{DD} \times I_{DD}) + PI/O$, where PI/O is the power dissipation of the I/O drivers.

7.1 Estimation with Junction-to-Ambient Thermal Resistance

An estimation of the chip junction temperature, T_J, in °C can be obtained from the equation:

$$T_J = T_A + (R_{\theta JA} \times P_D)$$

where:

 T_A = ambient temperature (°C)

 $R_{\theta JA}$ = package junction-to-ambient thermal resistance (°C/W)

 P_D = power dissipation in package

The junction-to-ambient thermal resistance is an industry standard value which provides a quick and easy estimation of thermal performance. However, the answer is only an estimate; test cases have demonstrated that errors of a factor of two (in the quantity $T_J - T_A$) are possible.

7.2 Estimation with Junction-to-Case Thermal Resistance

Historically, the thermal resistance has frequently been expressed as the sum of a junction-to-case thermal resistance and a case-to-ambient thermal resistance:

 $R_{\theta JA} = R_{\theta JC} + R_{\theta CA}$

where:

 $R_{\theta JA}$ = junction-to-ambient thermal resistance (°C/W)

 $R_{\theta IC}$ = junction-to-case thermal resistance (°C/W)

 $R_{\theta CA}$ = case-to-ambient thermal resistance (°C/W)

 $R_{\theta JC}$ is device related and cannot be influenced by the user. The user adjusts the thermal environment to affect the case-to-ambient thermal resistance, $R_{\theta CA}$. For instance, the user can change the airflow around the device, add a heat sink, change the mounting arrangement on the printed-circuit board, or change the thermal dissipation on the printed-circuit board surrounding the device. This thermal model is most useful for ceramic packages with heat sinks where some 90% of the heat flows through the case and the heat sink to the ambient environment. For most packages, a better model is required.

7.3 Estimation with Junction-to-Board Thermal Resistance

A simple package thermal model which has demonstrated reasonable accuracy (about 20%) is a two-resistor model consisting of a junction-to-board and a junction-to-case thermal resistance. The junction-to-case thermal resistance covers the situation where a heat sink is used or where a substantial amount of heat is dissipated from the top of the package. The junction-to-board thermal resistance describes the thermal performance when most of the heat is conducted to the printed-circuit board. It has been observed that the thermal performance of most plastic packages, especially PBGA packages, is strongly dependent on the board temperature; see Figure 2.



		33	MHz	40	MHz	50 I	MHz	66 I	MHz	
Num	Characteristic	Min	Мах	Min	Max	Min	Мах	Min	Max	Unit
B23	CLKOUT rising edge to \overline{CS} negated GPCM read access, GPCM write access ACS = 00, TRLX = 0, and CSNT = 0	2.00	8.00	2.00	8.00	2.00	8.00	2.00	8.00	ns
B24	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 10, TRLX = 0	5.58	—	4.25	_	3.00	_	1.79	—	ns
B24a	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 11, TRLX = 0	13.15	—	10.50	—	8.00	—	5.58	—	ns
B25	CLKOUT rising edge to \overline{OE} , \overline{WE} (0:3) asserted	—	9.00	—	9.00	—	9.00	—	9.00	ns
B26	CLKOUT rising edge to OE negated	2.00	9.00	2.00	9.00	2.00	9.00	2.00	9.00	ns
B27	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 10, TRLX = 1	35.88	_	29.25	_	23.00	_	16.94	_	ns
B27a	A(0:31) and BADDR(28:30) to \overline{CS} asserted GPCM ACS = 11, TRLX = 1	43.45	—	35.50	—	28.00	—	20.73	—	ns
B28	CLKOUT rising edge to $\overline{WE}(0:3)$ negated GPCM write access CSNT = 0	—	9.00	—	9.00	—	9.00	—	9.00	ns
B28a	CLKOUT falling edge to $\overline{WE}(0:3)$ negated GPCM write access TRLX = 0, 1, CSNT = 1, EBDF = 0	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B28b	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0, 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 0	—	14.33	—	13.00		11.75		10.54	ns
B28c	CLKOUT falling edge to \overline{WE} (0:3) negated GPCM write access TRLX = 0, 1, CSNT = 1 write access TRLX = 0, CSNT = 1, EBDF = 1	10.86	17.99	8.88	16.00	7.00	14.13	5.18	12.31	ns
B28d	CLKOUT falling edge to \overline{CS} negated GPCM write access TRLX = 0, 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 1	_	17.99	_	16.00		14.13		12.31	ns
B29	$\overline{WE}(0:3)$ negated to D(0:31), DP(0:3) High-Z GPCM write access CSNT = 0, EBDF = 0	5.58	_	4.25	—	3.00	—	1.79	—	ns
B29a	$\overline{WE}(0:3)$ negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, EBDF = 0	13.15	—	10.5	—	8.00		5.58	—	ns
B29b	$\overline{\text{CS}}$ negated to D(0:31), DP(0:3), High-Z GPCM write access, ACS = 00, TRLX = 0, 1, and CSNT = 0	5.58		4.25		3.00		1.79		ns
B29c	$\overline{\text{CS}}$ negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 0	13.15		10.5		8.00		5.58		ns

Table 7. Bus Operation Timings (continued)



		33	MHz	40	40 MHz		MHz	66 MHz		
Num	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
B31a	CLKOUT falling edge to CS valid—as requested by control bit CST1 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B31b	CLKOUT rising edge to \overline{CS} valid—as requested by control bit CST2 in the corresponding word in UPM	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns
B31c	CLKOUT rising edge to $\overline{\text{CS}}$ valid—as requested by control bit CST3 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.04	ns
B31d	CLKOUT falling edge to \overline{CS} valid—as requested by control bit CST1 in the corresponding word in UPM, EBDF = 1	13.26	17.99	11.28	16.00	9.40	14.13	7.58	12.31	ns
B32	CLKOUT falling edge to BS valid—as requested by control bit BST4 in the corresponding word in UPM	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B32a	CLKOUT falling edge to \overline{BS} valid—as requested by control bit BST1 in the corresponding word in UPM, EBDF = 0	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B32b	CLKOUT rising edge to $\overline{\text{BS}}$ valid—as requested by control bit BST2 in the corresponding word in UPM	1.50	8.00	1.50	8.00	1.50	8.00	1.50	8.00	ns
B32c	CLKOUT rising edge to $\overline{\text{BS}}$ valid—as requested by control bit BST3 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B32d	CLKOUT falling edge to \overline{BS} valid—as requested by control bit BST1 in the corresponding word in UPM, EBDF = 1	13.26	17.99	11.28	16.00	9.40	14.13	7.58	12.31	ns
B33	CLKOUT falling edge to GPL valid—as requested by control bit GxT4 in the corresponding word in UPM	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns
B33a	CLKOUT rising edge to GPL valid—as requested by control bit GxT3 in the corresponding word in UPM	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B34	A(0:31), BADDR(28:30), and D(0:31) to \overline{CS} valid—as requested by control bit CST4 in the corresponding word in UPM	5.58	—	4.25	—	3.00	—	1.79	—	ns
B34a	A(0:31), BADDR(28:30), and D(0:31) to \overline{CS} valid—as requested by control bit CST1 in the corresponding word in UPM	13.15		10.50		8.00		5.58	_	ns
B34b	A(0:31), BADDR(28:30), and D(0:31) to \overline{CS} valid—as requested by control bit CST2 in the corresponding word in UPM	20.73	_	16.75		13.00		9.36	_	ns

Table 7. Bus Operation Timings (continued)



Bus Signal Timing

Figure 9 provides the timing for the input data controlled by the UPM for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.)



Figure 9. Input Data Timing when Controlled by UPM in the Memory Controller and DLT3 = 1

Figure 10 through Figure 13 provide the timing for the external bus read controlled by various GPCM factors.





Figure 14 through Figure 16 provide the timing for the external bus write controlled by various GPCM factors.



Figure 14. External Bus Write Timing (GPCM Controlled—TRLX = 0 or 1, CSNT = 0)



Table 12 shows the reset timing for the MPC860.

Table 12. Reset Timing

Num	Characteristic	33 N	/IHz	40 MHz		50 N	ЛНz	66 N	ΛHz	llmit
Num	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
R69	CLKOUT to HRESET high impedance	—	20.00	—	20.00	—	20.00	—	20.00	ns
R70	CLKOUT to SRESET high impedance	—	20.00	—	20.00	—	20.00	—	20.00	ns
R71	RSTCONF pulse width	515.15	_	425.00		340.00	_	257.58	_	ns
R72	_		_	_	_	_	_		_	
R73	Configuration data to HRESET rising edge setup time	504.55	_	425.00		350.00	_	277.27	_	ns
R74	Configuration data to RSTCONF rising edge setup time	350.00	—	350.00	—	350.00	—	350.00	—	ns
R75	Configuration data hold time after RSTCONF negation	0.00	—	0.00	—	0.00	—	0.00	—	ns
R76	Configuration data hold time after HRESET negation	0.00	—	0.00	—	0.00	—	0.00	—	ns
R77	HRESET and RSTCONF asserted to data out drive	-	25.00		25.00	—	25.00	—	25.00	ns
R78	RSTCONF negated to data out high impedance	—	25.00	_	25.00	_	25.00	_	25.00	ns
R79	CLKOUT of last rising edge before chip three-state HRESET to data out high impedance	_	25.00	—	25.00	_	25.00	_	25.00	ns
R80	DSDI, DSCK setup	90.91	—	75.00	—	60.00	—	45.45	—	ns
R81	DSDI, DSCK hold time	0.00	—	0.00	_	0.00	_	0.00	—	ns
R82	SRESET negated to CLKOUT rising edge for DSDI and DSCK sample	242.42	_	200.00		160.00		121.21	_	ns





Figure 34 provides the reset timing for the debug port configuration.

Figure 34. Reset Timing—Debug Port Configuration

10 IEEE 1149.1 Electrical Specifications

Table 13 provides the JTAG timings for the MPC860 shown in Figure 35 through Figure 38.

Num	Charactariatia	All Freq	Unit	
Nulli	Characteristic	Min	Мах	Onit
J82	TCK cycle time	100.00	—	ns
J83	TCK clock pulse width measured at 1.5 V	40.00	_	ns
J84	TCK rise and fall times	0.00	10.00	ns
J85	TMS, TDI data setup time	5.00	—	ns
J86	TMS, TDI data hold time	25.00	_	ns
J87	TCK low to TDO data valid	—	27.00	ns
J88	TCK low to TDO data invalid	0.00	—	ns
J89	TCK low to TDO high impedance	—	20.00	ns
J90	TRST assert time	100.00	_	ns
J91	TRST setup time to TCK low	40.00	—	ns
J92	TCK falling edge to output valid	—	50.00	ns
J93	TCK falling edge to output valid out of high impedance	—	50.00	ns
J94	TCK falling edge to output high impedance	—	50.00	ns
J95	Boundary scan input valid to TCK rising edge	50.00	—	ns
J96	TCK rising edge to boundary scan input invalid	50.00		ns

Table 13. JTAG Timing



IEEE 1149.1 Electrical Specifications



Figure 35. JTAG Test Clock Input Timing



Figure 36. JTAG Test Access Port Timing Diagram



Figure 37. JTAG TRST Timing Diagram





CPM Electrical Characteristics

11.4 Baud Rate Generator AC Electrical Specifications

Table 17 provides the baud rate generator timings as shown in Figure 49.

Table 17. Baud Rate Generator Timing

Num	Charactariatia	All Freq	Unit	
Nulli	Characteristic	Min	Мах	Unit
50	BRGO rise and fall time	—	10	ns
51	BRGO duty cycle	40	60	%
52	BRGO cycle	40	—	ns



Figure 49. Baud Rate Generator Timing Diagram

11.5 Timer AC Electrical Specifications

Table 18 provides the general-purpose timer timings as shown in Figure 50.

Table 18. Timer Timing

Num	Characteristic	All Freq	Unit		
Num	Characteristic	Min Max			
61	TIN/TGATE rise and fall time	10	—	ns	
62	TIN/TGATE low time	1	—	CLK	
63	TIN/TGATE high time	2	—	CLK	
64	TIN/TGATE cycle time	3	—	CLK	
65	CLKO low to TOUT valid	3	25	ns	





Figure 50. CPM General-Purpose Timers Timing Diagram

11.6 Serial Interface AC Electrical Specifications

Table 19 provides the serial interface timings as shown in Figure 51 through Figure 55.

Num	Obarrastaviatia	All Frec	11	
NUM	Characteristic	Min	Max	Unit
70	L1RCLK, L1TCLK frequency (DSC = 0) ^{1, 2}	—	SYNCCLK/2.5	MHz
71	L1RCLK, L1TCLK width low $(DSC = 0)^2$	P + 10	—	ns
71a	L1RCLK, L1TCLK width high $(DSC = 0)^3$	P + 10	—	ns
72	L1TXD, L1ST(1–4), L1RQ, L1CLKO rise/fall time	—	15.00	ns
73	L1RSYNC, L1TSYNC valid to L1CLK edge (SYNC setup time)	20.00	—	ns
74	L1CLK edge to L1RSYNC, L1TSYNC, invalid (SYNC hold time)	35.00	—	ns
75	L1RSYNC, L1TSYNC rise/fall time	—	15.00	ns
76	L1RXD valid to L1CLK edge (L1RXD setup time)	17.00	—	ns
77	L1CLK edge to L1RXD invalid (L1RXD hold time)	13.00	—	ns
78	L1CLK edge to L1ST(1-4) valid ⁴	10.00	45.00	ns
78A	L1SYNC valid to L1ST(1-4) valid	10.00	45.00	ns
79	L1CLK edge to L1ST(1-4) invalid	10.00	45.00	ns
80	L1CLK edge to L1TXD valid	10.00	55.00	ns
80A	L1TSYNC valid to L1TXD valid ⁴	10.00	55.00	ns
81	L1CLK edge to L1TXD high impedance	0.00	42.00	ns
82	L1RCLK, L1TCLK frequency (DSC =1)	—	16.00 or SYNCCLK/2	MHz
83	L1RCLK, L1TCLK width low (DSC = 1)	P + 10	_	ns
83a	L1RCLK, L1TCLK width high $(DSC = 1)^3$	P + 10	—	ns

Table 19. SI Timing



CPM Electrical Characteristics

Figure 56 through Figure 58 show the NMSI timings.





CPM Electrical Characteristics



11.11 SPI Slave AC Electrical Specifications

Table 25 provides the SPI slave timings as shown in Figure 67 and Figure 68.

Table 25. SPI Slave Timing

Num	Characteristic	All Freq	Unit	
Nulli		Min	Мах	Unit
170	Slave cycle time	2	_	t _{cyc}
171	Slave enable lead time	15	—	ns
172	Slave enable lag time	15	—	ns
173	Slave clock (SPICLK) high or low time	1	—	t _{cyc}
174	Slave sequential transfer delay (does not require deselect)	1	_	t _{cyc}
175	Slave data setup time (inputs)	20	—	ns
176	Slave data hold time (inputs)	20	—	ns
177	Slave access time	_	50	ns



FEC Electrical Characteristics

13.3 MII Async Inputs Signal Timing (MII_CRS, MII_COL)

Table 31 provides information on the MII async inputs signal timing.

Table 31. MII Async Inputs Signal Timing

Num	Characteristic	Min	Мах	Unit
M9	MII_CRS, MII_COL minimum pulse width	1.5		MII_TX_CLK period

Figure 74 shows the MII asynchronous inputs signal timing diagram.



13.4 MII Serial Management Channel Timing (MII_MDIO, MII_MDC)

Table 32 provides information on the MII serial management channel signal timing. The FEC functions correctly with a maximum MDC frequency in excess of 2.5 MHz. The exact upper bound is under investigation.

Num	Characteristic	Min	Мах	Unit
M10	MII_MDC falling edge to MII_MDIO output invalid (minimum propagation delay)	0	_	ns
M11	MII_MDC falling edge to MII_MDIO output valid (max prop delay)	_	25	ns
M12	MII_MDIO (input) to MII_MDC rising edge setup	10	—	ns
M13	MII_MDIO (input) to MII_MDC rising edge hold	0	—	ns
M14	MII_MDC pulse width high	40%	60%	MII_MDC period
M15	MII_MDC pulse width low	40%	60%	MII_MDC period

Table 32. MII Serial Management Channel Timing



Figure 78 shows the mechanical dimensions of the ZQ PBGA package.



- 1. All Dimensions in millimeters.
- 2. Dimensions and tolerance per ASME Y14.5M, 1994.
- 3. Maximum Solder Ball Diameter measured parallel to Datum A.
- 4. Datum A, the seating plane, is defined by the spherical crowns of the solder balls.

Figure 78. Mechanical Dimensions and Bottom Surface Nomenclature of the ZQ PBGA Package



Document Revision History

15 Document Revision History

Table 35 lists significant changes between revisions of this hardware specification.

Revision	Date	Changes
10	09/2015	In Table 34, moved MPC855TCVR50D4 and MPC855TCVR66D4 under the extended temperature (–40° to 95°C) and removed MC860ENCVR50D4R2 from the normal temperature Tape and Reel.
9	10/2011	Updated orderable part numbers in Table 34, "MPC860 Family Package/Frequency Availability."
8	08/2007	 Updated template. On page 1, added a second paragraph. After Table 2, inserted a new figure showing the undershoot/overshoot voltage (Figure 1) and renumbered the rest of the figures. In Figure 3, changed all reference voltage measurement points from 0.2 and 0.8 V to 50% level. In Table 16, changed num 46 description to read, "TA assertion to rising edge" In Figure 46, changed TA to reflect the rising edge of the clock.
7.0	9/2004	 Added a tablefootnote to Table 6 DC Electrical Specifications about meeting the VIL Max of the I2C Standard Replaced the thermal characteristics in Table 4 by the ZQ package Add the new parts to the Ordering and Availablity Chart in Table 34 Added the mechanical spec of the ZQ package in Figure 78 Removed all of the old revisions from Table 5
6.3	9/2003	 Added Section 11.2 on the Port C interrupt pins Nontechnical reformatting
6.2	8/2003	 Changed B28a through B28d and B29d to show that TRLX can be 0 or 1 Changed reference documentation to reflect the Rev 2 MPC860 PowerQUICC Family Users Manual Nontechnical reformatting
6.1	11/2002	 Corrected UTOPIA RXenb* and TXenb* timing values Changed incorrect usage of Vcc to Vdd Corrected dual port RAM to 8 Kbytes
6	10/2002	Added the MPC855T. Corrected Figure 26 on page -36.
5.1	11/2001	Revised template format, removed references to MAC functionality, changed Table 7 B23 max value @ 66 MHz from 2ns to 8ns, added this revision history table

Table 35. Document Revision History



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