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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Active
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	80MHz
Co-Processors/DSP	Communications; CPM
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (4), 10/100Mbps (1)
SATA	-
USB	-
Voltage - I/O	3.3V
Operating Temperature	0°C ~ 95°C (TA)
Security Features	-
Package / Case	357-BBGA
Supplier Device Package	357-PBGA (25x25)
Purchase URL	https://www.e-xfl.com/pro/item?MUrl=&PartUrl=mpc860tvr80d4

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



2 Features

The following list summarizes the key MPC860 features:

- Embedded single-issue, 32-bit core (implementing the Power Architecture technology) with thirty-two 32-bit general-purpose registers (GPRs)
 - The core performs branch prediction with conditional prefetch without conditional execution.
 - 4- or 8-Kbyte data cache and 4- or 16-Kbyte instruction cache (see Table 1)
 - 16-Kbyte instruction caches are four-way, set-associative with 256 sets; 4-Kbyte instruction caches are two-way, set-associative with 128 sets.
 - 8-Kbyte data caches are two-way, set-associative with 256 sets; 4-Kbyte data caches are two-way, set-associative with 128 sets.
 - Cache coherency for both instruction and data caches is maintained on 128-bit (4-word) cache blocks.
 - Caches are physically addressed, implement a least recently used (LRU) replacement algorithm, and are lockable on a cache block basis.
 - MMUs with 32-entry TLB, fully-associative instruction, and data TLBs
 - MMUs support multiple page sizes of 4-, 16-, and 512-Kbytes, and 8-Mbytes; 16 virtual address spaces and 16 protection groups
 - Advanced on-chip-emulation debug mode
- Up to 32-bit data bus (dynamic bus sizing for 8, 16, and 32 bits)
- 32 address lines
- Operates at up to 80 MHz
- Memory controller (eight banks)
 - Contains complete dynamic RAM (DRAM) controller
 - Each bank can be a chip select or \overline{RAS} to support a DRAM bank.
 - Up to 15 wait states programmable per memory bank
 - Glueless interface to DRAM, SIMMS, SRAM, EPROM, Flash EPROM, and other memory devices
 - DRAM controller programmable to support most size and speed memory interfaces
 - Four \overline{CAS} lines, four \overline{WE} lines, and one \overline{OE} line
 - Boot chip-select available at reset (options for 8-, 16-, or 32-bit memory)
 - Variable block sizes (32 Kbytes to 256 Mbytes)
 - Selectable write protection
 - On-chip bus arbitration logic
- General-purpose timers
 - Four 16-bit timers or two 32-bit timers
 - Gate mode can enable/disable counting
 - Interrupt can be masked on reference match and event capture.



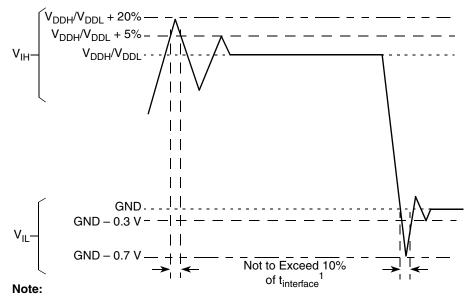
Features

- System integration unit (SIU)
 - Bus monitor
 - Software watchdog
 - Periodic interrupt timer (PIT)
 - Low-power stop mode
 - Clock synthesizer
 - Decrementer, time base, and real-time clock (RTC)
 - Reset controller
 - IEEE 1149.1TM Std. test access port (JTAG)
- Interrupts
 - Seven external interrupt request (IRQ) lines
 - 12 port pins with interrupt capability
 - 23 internal interrupt sources
 - Programmable priority between SCCs
 - Programmable highest priority request
- 10/100 Mbps Ethernet support, fully compliant with the IEEE 802.3u® Standard (not available when using ATM over UTOPIA interface)
- ATM support compliant with ATM forum UNI 4.0 specification
 - Cell processing up to 50–70 Mbps at 50-MHz system clock
 - Cell multiplexing/demultiplexing
 - Support of AAL5 and AAL0 protocols on a per-VC basis. AAL0 support enables OAM and software implementation of other protocols.
 - ATM pace control (APC) scheduler, providing direct support for constant bit rate (CBR) and unspecified bit rate (UBR) and providing control mechanisms enabling software support of available bit rate (ABR)
 - Physical interface support for UTOPIA (10/100-Mbps is not supported with this interface) and byte-aligned serial (for example, T1/E1/ADSL)
 - UTOPIA-mode ATM supports level-1 master with cell-level handshake, multi-PHY (up to four physical layer devices), connection to 25-, 51-, or 155-Mbps framers, and UTOPIA/system clock ratios of 1/2 or 1/3.
 - Serial-mode ATM connection supports transmission convergence (TC) function for T1/E1/ADSL lines, cell delineation, cell payload scrambling/descrambling, automatic idle/unassigned cell insertion/stripping, header error control (HEC) generation, checking, and statistics.
- Communications processor module (CPM)
 - RISC communications processor (CP)
 - Communication-specific commands (for example, GRACEFUL STOP TRANSMIT, ENTER HUNT MODE, and RESTART TRANSMIT)
 - Supports continuous mode transmission and reception on all serial channels



Thermal Characteristics

Figure 1 shows the undershoot and overshoot voltages at the interface of the MPC860.



^{1.} $t_{\text{interface}}$ refers to the clock period associated with the bus clock interface.

Figure 1. Undershoot/Overshoot Voltage for V_{DDH} and V_{DDL}

4 Thermal Characteristics

Table 3. Package Description

Package Designator	Package Code (Case No.)	Package Description
ZP	5050 (1103-01)	PBGA 357 25*25*0.9P1.27
ZQ/VR	5058 (1103D-02)	PBGA 357 25*25*1.2P1.27



Power Dissipation

5 Power Dissipation

Table 5 provides power dissipation information. The modes are 1:1, where CPU and bus speeds are equal, and 2:1, where CPU frequency is twice the bus speed.

Table 5. Power Dissipation (P_D)

Die Revision	Frequency (MHz)	Typical ¹	Maximum ²	Unit
D.4	50	656	735	mW
(1:1 mode)	66	TBD	TBD	mW
0.4	66	722	762	mW
(2:1 mode)	80	851	909	mW

¹ Typical power dissipation is measured at 3.3 V.

NOTE

Values in Table 5 represent V_{DDL} -based power dissipation and do not include I/O power dissipation over V_{DDH} . I/O power dissipation varies widely by application due to buffer current, depending on external circuitry.

6 DC Characteristics

Table 6 provides the DC electrical characteristics for the MPC860.

Table 6. DC Electrical Specifications

Characteristic	Symbol	Min	Max	Unit
Operating voltage at 40 MHz or less	V _{DDH} , V _{DDL} , V _{DDSYN}	3.0	3.6	V
	KAPWR (power-down mode)	2.0	3.6	V
	KAPWR (all other operating modes)	V _{DDH} – 0.4	V _{DDH}	V
Operating voltage greater than 40 MHz	$V_{\mathrm{DDH}}, V_{\mathrm{DDL}}, \mathrm{KAPWR}, \ V_{\mathrm{DDSYN}}$	3.135	3.465	V
	KAPWR (power-down mode)	2.0	3.6	V
	KAPWR (all other operating modes)	V _{DDH} – 0.4	V _{DDH}	V
Input high voltage (all inputs except EXTAL and EXTCLK)	V _{IH}	2.0	5.5	V
Input low voltage ¹	V _{IL}	GND	0.8	V
EXTAL, EXTCLK input high voltage	V _{IHC}	0.7 × (V _{DDH})	V _{DDH} + 0.3	V
Input leakage current, V_{in} = 5.5 V (except TMS, \overline{TRST} , DSCK, and DSDI pins)	I _{in}		100	μА

² Maximum power dissipation is measured at 3.5 V.



Table 7. Bus Operation Timings (continued)

Num	Chavastavistis	33 I	MHz	40 I	MHz	50 I	ИНz	66 I	ИНz	Heit
Num	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
В9	CLKOUT to A(0:31), BADDR(28:30), RD/WR, BURST, D(0:31), DP(0:3), TSIZ(0:1), REG, RSV, AT(0:3), PTR High-Z	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.04	ns
B11	CLKOUT to TS, BB assertion	7.58	13.58	6.25	12.25	5.00	11.00	3.80	11.29	ns
B11a	CLKOUT to TA, BI assertion (when driven by the memory controller or PCMCIA interface)	2.50	9.25	2.50	9.25	2.50	9.25	2.50	9.75	ns
B12	CLKOUT to TS, BB negation	7.58	14.33	6.25	13.00	5.00	11.75	3.80	8.54	ns
B12a	CLKOUT to TA, BI negation (when driven by the memory controller or PCMCIA interface)	2.50	11.00	2.50	11.00	2.50	11.00	2.50	9.00	ns
B13	CLKOUT to TS, BB High-Z	7.58	21.58	6.25	20.25	5.00	19.00	3.80	14.04	ns
B13a	CLKOUT to TA, BI High-Z (when driven by the memory controller or PCMCIA interface)	2.50	15.00	2.50	15.00	2.50	15.00	2.50	15.00	ns
B14	CLKOUT to TEA assertion	2.50	10.00	2.50	10.00	2.50	10.00	2.50	9.00	ns
B15	CLKOUT to TEA High-Z	2.50	15.00	2.50	15.00	2.50	15.00	2.50	15.00	ns
B16	TA, BI valid to CLKOUT (setup time)	9.75	_	9.75	_	9.75	_	6.00	_	ns
B16a	TEA, KR, RETRY, CR valid to CLKOUT (setup time)	10.00	_	10.00	_	10.00	_	4.50	_	ns
B16b	$\overline{BB}, \overline{BG}, \overline{BR},$ valid to CLKOUT (setup time) 5	8.50	_	8.50	_	8.50	_	4.00	_	ns
B17	CLKOUT to \overline{TA} , \overline{TEA} , \overline{BI} , \overline{BB} , \overline{BG} , \overline{BR} valid (hold time)	1.00	_	1.00	_	1.00	_	2.00	_	ns
B17a	CLKOUT to KR, RETRY, CR valid (hold time)	2.00	_	2.00	_	2.00	_	2.00	_	ns
B18	D(0:31), DP(0:3) valid to CLKOUT rising edge (setup time) ⁶	6.00	_	6.00	_	6.00	_	6.00	_	ns
B19	CLKOUT rising edge to D(0:31), DP(0:3) valid (hold time) ⁶	1.00	_	1.00	_	1.00	_	2.00	_	ns
B20	D(0:31), DP(0:3) valid to CLKOUT falling edge (setup time) ⁷	4.00	_	4.00	_	4.00	_	4.00	_	ns
B21	CLKOUT falling edge to D(0:31), DP(0:3) valid (hold time) ⁷	2.00	_	2.00	_	2.00	_	2.00	_	ns
B22	CLKOUT rising edge to $\overline{\text{CS}}$ asserted GPCM ACS = 00	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.04	ns
B22a	CLKOUT falling edge to $\overline{\text{CS}}$ asserted GPCM ACS = 10, TRLX = 0	_	8.00	_	8.00	_	8.00	_	8.00	ns
B22b	CLKOUT falling edge to \overline{CS} asserted GPCM ACS = 11, TRLX = 0, EBDF = 0	7.58	14.33	6.25	13.00	5.00	11.75	3.80	10.54	ns
B22c	CLKOUT falling edge to $\overline{\text{CS}}$ asserted GPCM ACS = 11, TRLX = 0, EBDF = 1	10.86	17.99	8.88	16.00	7.00	14.13	5.18	12.31	ns

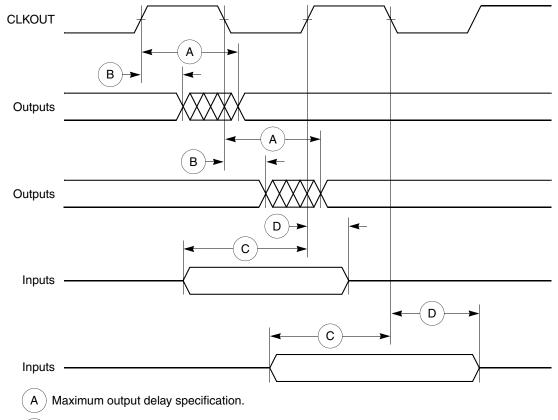


Table 7. Bus Operation Timings (continued)

Nivers	Chayantayintin	33	ИНz	40 I	ИНz	50 1	MHz	66 1	ИHz	11:4
Num	Characteristic	Min	Max	Min	Max	Min	Max	Min	Max	Unit
B29d	WE(0:3) negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 1, CSNT = 1, EBDF = 0	43.45	_	35.5	_	28.00	_	20.73		ns
B29e	CS negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 0	43.45	_	35.5	_	28.00	_	29.73		ns
B29f	WE(0:3) negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, EBDF = 1	8.86	_	6.88	_	5.00	_	3.18		ns
B29g	CS negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 0, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 1	8.86	_	6.88	_	5.00	_	3.18		ns
B29h	WE(0:3) negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 1, CSNT = 1, EBDF = 1	38.67		31.38		24.50	_	17.83	1	ns
B29i	CS negated to D(0:31), DP(0:3) High-Z GPCM write access, TRLX = 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 1	38.67	_	31.38	_	24.50	_	17.83		ns
B30	CS, WE(0:3) negated to A(0:31), BADDR(28:30) invalid GPCM write access ⁸	5.58	_	4.25	_	3.00	_	1.79	_	ns
B30a	WE(0:3) negated to A(0:31), BADDR(28:30) invalid GPCM, write access, TRLX = 0, CSNT = 1, \overline{CS} negated to A(0:31) invalid GPCM write access, TRLX = 0, CSNT = 1 ACS = 10, or ACS = 11, EBDF = 0	13.15	_	10.50	_	8.00	_	5.58	_	ns
B30b	WE(0:3) negated to A(0:31), invalid GPCM BADDR(28:30) invalid GPCM write access, TRLX = 1, CSNT = 1. CS negated to A(0:31), Invalid GPCM, write access, TRLX = 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 0	43.45	_	35.50	_	28.00	_	20.73	_	ns
B30c	WE(0:3) negated to A(0:31), BADDR(28:30) invalid GPCM write access, TRLX = 0, CSNT = 1. $\overline{\text{CS}}$ negated to A(0:31) invalid GPCM write access, TRLX = 0, CSNT = 1, ACS = 10, ACS = 11, EBDF = 1	8.36	_	6.38	_	4.50	_	2.68	_	ns
B30d	WE(0:3) negated to A(0:31), BADDR(28:30) invalid GPCM write access, TRLX = 1, CSNT = 1. CS negated to A(0:31) invalid GPCM write access TRLX = 1, CSNT = 1, ACS = 10, or ACS = 11, EBDF = 1	38.67	_	31.38	_	24.50	_	17.83	_	ns
B31	CLKOUT falling edge to CS valid—as requested by control bit CST4 in the corresponding word in UPM	1.50	6.00	1.50	6.00	1.50	6.00	1.50	6.00	ns



Figure 3 is the control timing diagram.



- (B) Minimum output hold time.
- C Minimum input setup time specification.
- (D) Minimum input hold time specification.

Figure 3. Control Timing

Figure 4 provides the timing for the external clock.

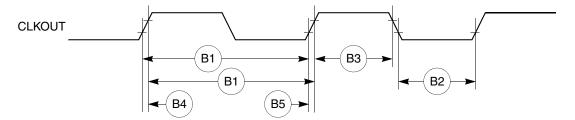


Figure 4. External Clock Timing



Figure 9 provides the timing for the input data controlled by the UPM for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.)

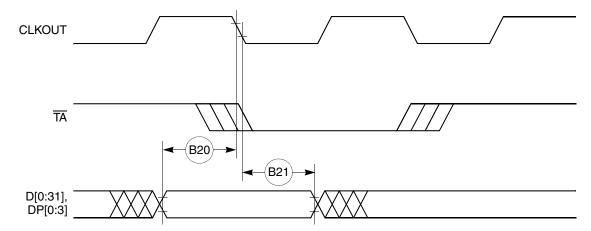


Figure 9. Input Data Timing when Controlled by UPM in the Memory Controller and DLT3 = 1

Figure 10 through Figure 13 provide the timing for the external bus read controlled by various GPCM factors.

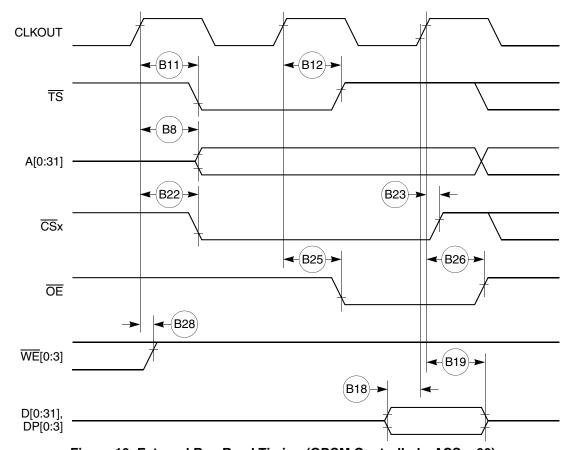


Figure 10. External Bus Read Timing (GPCM Controlled—ACS = 00)



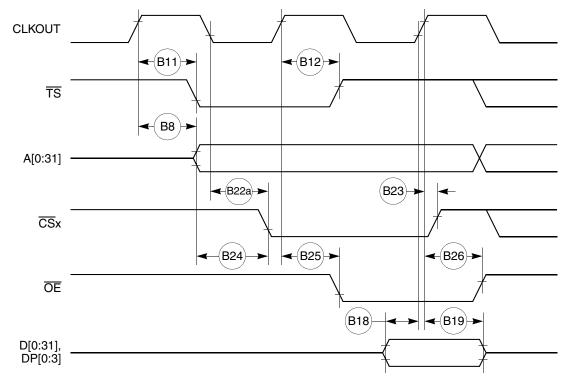


Figure 11. External Bus Read Timing (GPCM Controlled—TRLX = 0, ACS = 10)

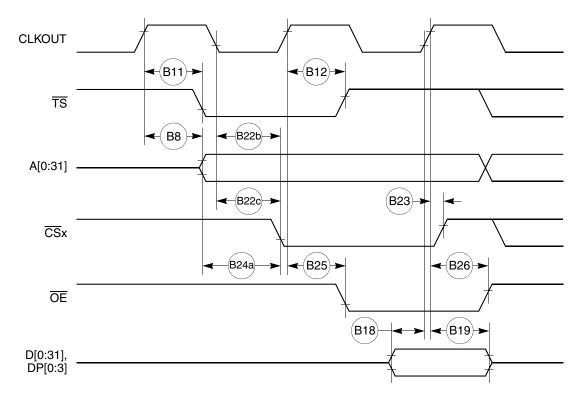


Figure 12. External Bus Read Timing (GPCM Controlled—TRLX = 0, ACS = 11)



Figure 14 through Figure 16 provide the timing for the external bus write controlled by various GPCM factors.

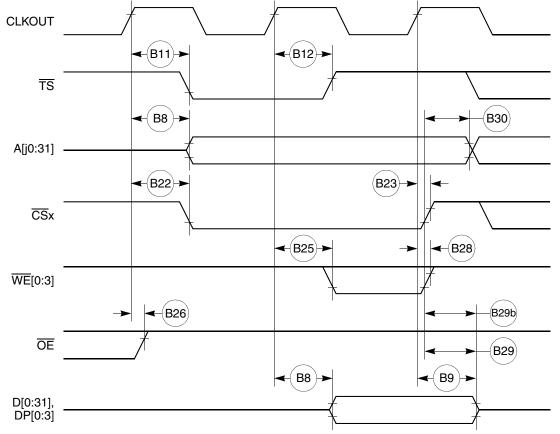


Figure 14. External Bus Write Timing (GPCM Controlled—TRLX = 0 or 1, CSNT = 0)



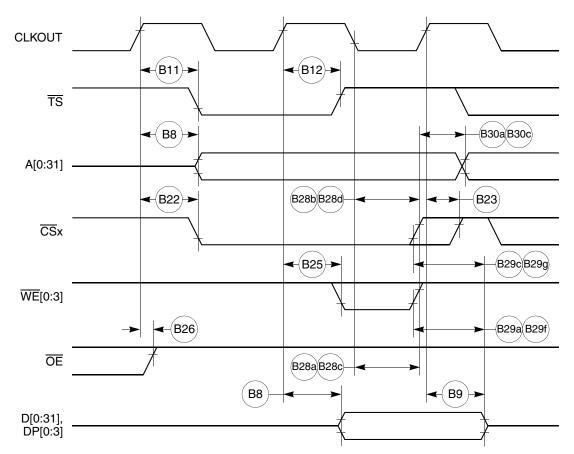


Figure 15. External Bus Write Timing (GPCM Controlled—TRLX = 0 or 1, CSNT = 1)



Figure 17 provides the timing for the external bus controlled by the UPM.

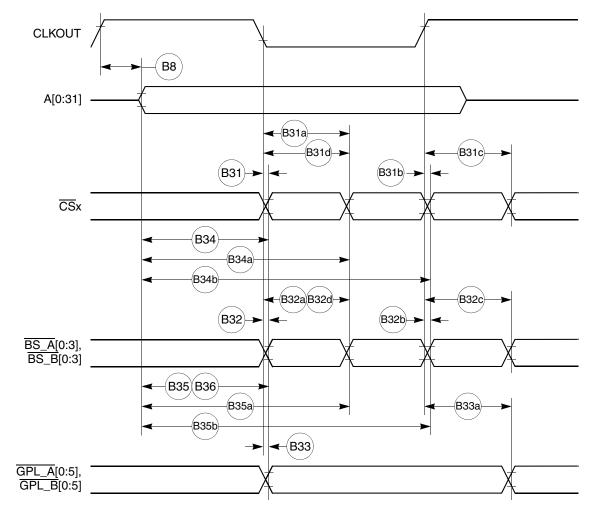


Figure 17. External Bus Timing (UPM Controlled Signals)



Figure 18 provides the timing for the asynchronous asserted UPWAIT signal controlled by the UPM.

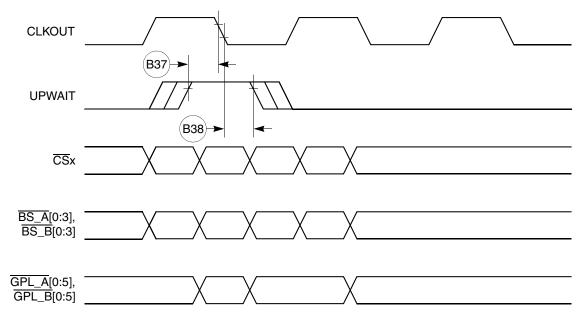


Figure 18. Asynchronous UPWAIT Asserted Detection in UPM Handled Cycles Timing

Figure 19 provides the timing for the asynchronous negated UPWAIT signal controlled by the UPM.

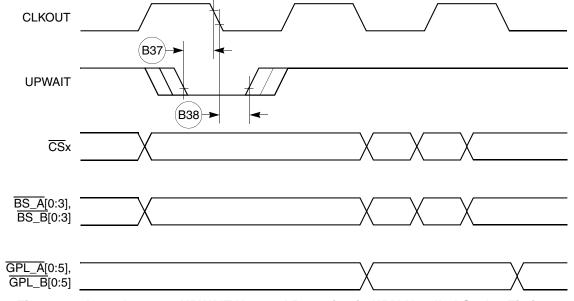


Figure 19. Asynchronous UPWAIT Negated Detection in UPM Handled Cycles Timing



IEEE 1149.1 Electrical Specifications

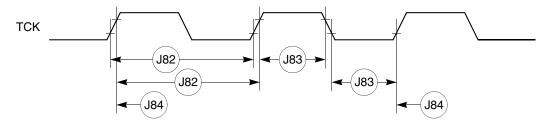


Figure 35. JTAG Test Clock Input Timing

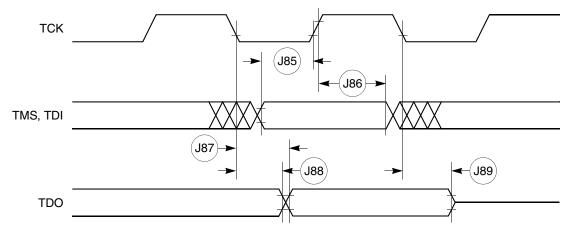


Figure 36. JTAG Test Access Port Timing Diagram

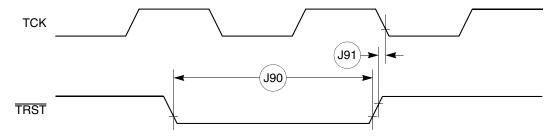


Figure 37. JTAG TRST Timing Diagram

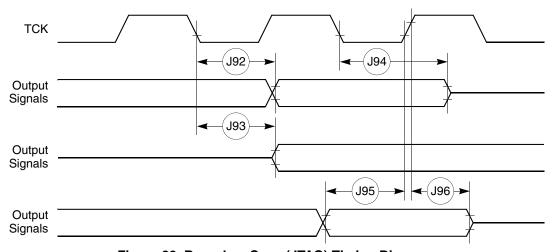


Figure 38. Boundary Scan (JTAG) Timing Diagram

MPC860 PowerQUICC Family Hardware Specifications, Rev. 10



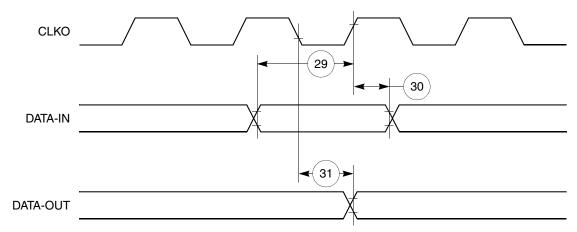


Figure 43. Parallel I/O Data-In/Data-Out Timing Diagram

11.2 Port C Interrupt AC Electrical Specifications

Table 15 provides the timings for port C interrupts.

Table 15. Port C Interrupt Timing

Num	Characteristic	\geq 33.34 MHz ¹		Unit
Num	Onaracteristic	Min	Max	Oille
35	Port C interrupt pulse width low (edge-triggered mode)		_	ns
36	Port C interrupt minimum time between active edges	55	_	ns

¹ External bus frequency of greater than or equal to 33.34 MHz.

Figure 44 shows the port C interrupt detection timing.

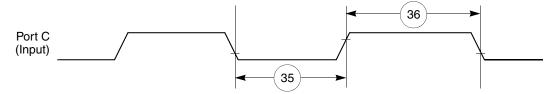


Figure 44. Port C Interrupt Detection Timing

11.3 IDMA Controller AC Electrical Specifications

Table 16 provides the IDMA controller timings as shown in Figure 45 through Figure 48.

Table 16. IDMA Controller Timing

Num	Characteristic	All Freq	Unit	
Num	Characteristic	Min	Max	Oilit
40	DREQ setup time to clock high	7	_	ns
41	DREQ hold time from clock high	3		ns

MPC860 PowerQUICC Family Hardware Specifications, Rev. 10



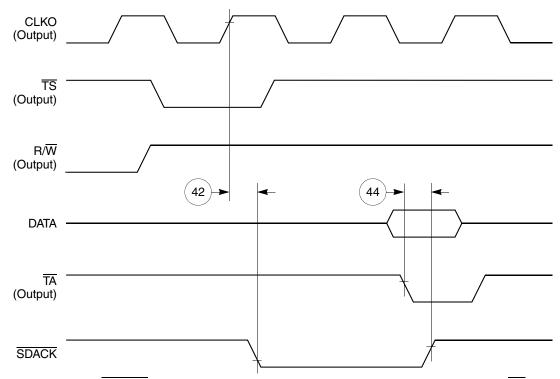


Figure 47. SDACK Timing Diagram—Peripheral Write, Internally-Generated TA

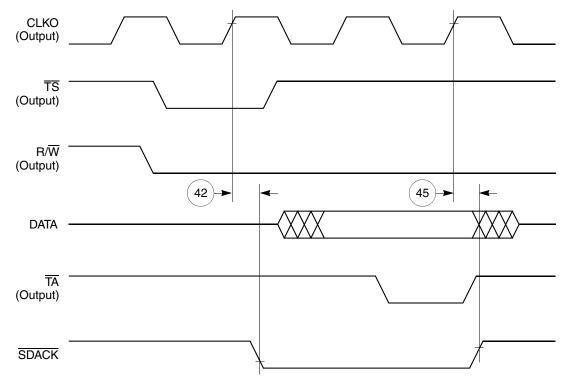


Figure 48. SDACK Timing Diagram—Peripheral Read, Internally-Generated TA



CPM Electrical Characteristics

Table 22. Ethernet Timing (continued)

Nivers	Characteristic	All Freq	uencies	I I m i t
Num	Characteristic	Min	Max	Unit
135	RSTRT active delay (from TCLK1 falling edge)	10	50	ns
136	RSTRT inactive delay (from TCLK1 falling edge)	10	50	ns
137	REJECT width low	1	_	CLK
138	CLKO1 low to SDACK asserted ²	_	20	ns
139	CLKO1 low to SDACK negated ²	_	20	ns

¹ The ratios SYNCCLK/RCLK1 and SYNCCLK/TCLK1 must be greater than or equal to 2/1.

² SDACK is asserted whenever the SDMA writes the incoming frame DA into memory.

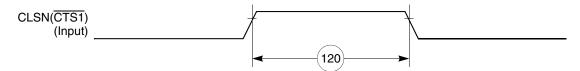


Figure 59. Ethernet Collision Timing Diagram

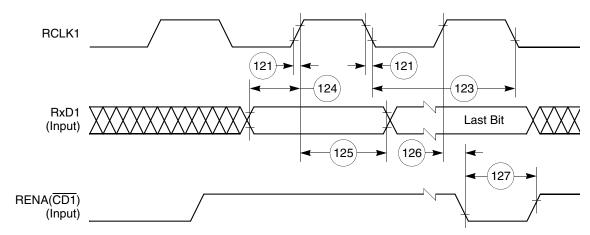
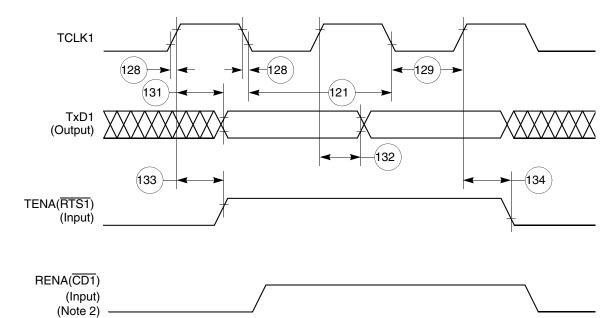


Figure 60. Ethernet Receive Timing Diagram





Notes:

- 1. Transmit clock invert (TCI) bit in GSMR is set.
- 2. If RENA is deasserted before TENA, or RENA is not asserted at all during transmit, then the CSL bit is set in the buffer descriptor at the end of the frame transmission.

Figure 61. Ethernet Transmit Timing Diagram

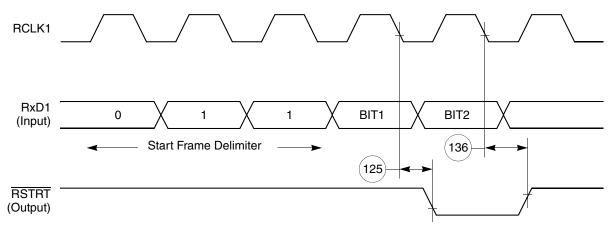


Figure 62. CAM Interface Receive Start Timing Diagram

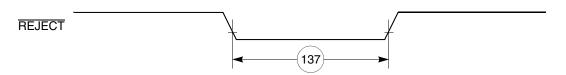


Figure 63. CAM Interface REJECT Timing Diagram



UTOPIA AC Electrical Specifications

Figure 70 shows signal timings during UTOPIA receive operations.

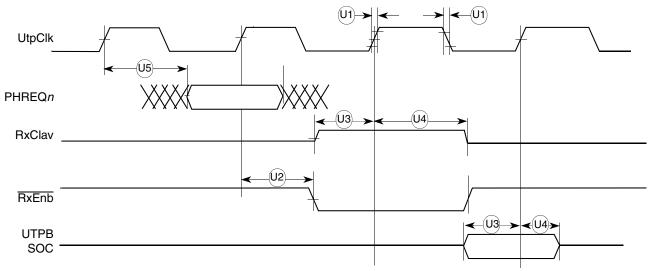


Figure 70. UTOPIA Receive Timing

Figure 71 shows signal timings during UTOPIA transmit operations.

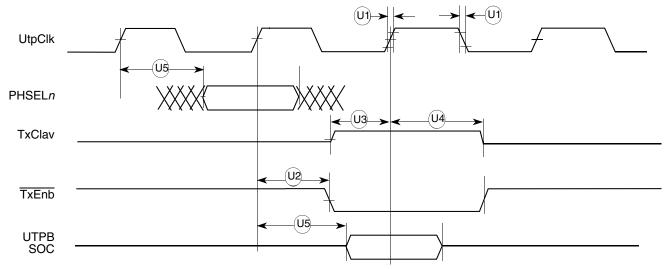


Figure 71. UTOPIA Transmit Timing

Freescale Semiconductor

MPC860 PowerQUICC Family Hardware Specifications, Rev. 10



Mechanical Data and Ordering Information

Table 34. MPC860 Family Package/Frequency Availability (continued)

Package Type	Freq. (MHz) / Temp. (Tj)	Package	Order Number
Ball grid array (continued) ZP suffix—leaded ZQ suffix—leaded VR suffix—lead-free	suffix—leaded 0° to 95°C suffix—leaded		MPC855TZQ80D4 MPC860DEZQ80D4 MPC860DTZQ80D4 MPC860ENZQ80D4 MPC860SRZQ80D4 MPC860TZQ80D4 MPC860DPZQ80D4 MPC860PZQ80D4
		Tape and Reel	MPC860PZQ80D4R2 MPC860PVR80D4R2
		VR	MPC855TVR80D4 MPC860DEVR80D4 MPC860DPVR80D4 MPC860ENVR80D4 MPC860PVR80D4 MPC860SRVR80D4 MPC860TVR80D4
Ball grid array (CZP suffix) CZP suffix—leaded CZQ suffix—leaded CVR suffix—lead-free	50 ZP/ZQ ¹ -40° to 95°C	MPC855TCZQ50D4 MPC855TCVR50D4 MPC860DECZQ50D4 MPC860DTCZQ50D4 MPC860ENCZQ50D4 MPC860SRCZQ50D4 MPC860TCZQ50D4 MPC860DPCZQ50D4 MPC860PCZQ50D4	
		Tape and Reel	MPC855TCZQ50D4R2 MC860ENCVR50D4R2
		CVR	MPC860DECVR50D4 MPC860DTCVR50D4 MPC860ENCVR50D4 MPC860PCVR50D4 MPC860SRCVR50D4 MPC860TCVR50D4
	66 -40° to 95°C	ZP/ZQ ¹	MPC855TCZQ66D4 MPC855TCVR66D4 MPC860ENCZQ66D4 MPC860SRCZQ66D4 MPC860TCZQ66D4 MPC860DPCZQ66D4 MPC860PCZQ66D4
		CVR	MPC860DTCVR66D4 MPC860ENCVR66D4 MPC860PCVR66D4 MPC860SRCVR66D4 MPC860TCVR66D4

¹ The ZP package is no longer recommended for use. The ZQ package replaces the ZP package.

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