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### Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Betans	
Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	110592
Number of I/O	95
Number of Gates	600000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	208-BFQFP
Supplier Device Package	208-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/afs600-2pqg208

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# **Temperature Monitor**

The final pin in the Analog Quad is the Analog Temperature (AT) pin. The AT pin is used to implement an accurate temperature monitor in conjunction with an external diode-connected bipolar transistor (Figure 2-76). For improved temperature measurement accuracy, it is important to use the ATRTN pin for the return path of the current sourced by the AT pin. Each ATRTN pin is shared between two adjacent Analog Quads. Additionally, if not used for temperature monitoring, the AT pin can provide functionality similar to that of the AV pad. However, in this mode only positive voltages can be applied to the AT pin, and only two prescaler factors are available (16 V and 4 V ranges—refer to Table 2-57 on page 2-130).



Figure 2-76 • Temperature Monitor Quad

### TUE – Total Unadjusted Error

TUE is a comprehensive specification that includes linearity errors, gain error, and offset error. It is the worst-case deviation from the ideal device performance. TUE is a static specification (Figure 2-87).



Figure 2-87 • Total Unadjusted Error (TUE)

# ADC Operation

Once the ADC has powered up and been released from reset, ADCRESET, the ADC will initiate a calibration routine designed to provide optimal ADC performance. The Fusion ADC offers a robust calibration scheme to reduce integrated offset and linearity errors. The offset and linearity errors of the main capacitor array are compensated for with an 8-bit calibration capacitor array. The offset/linearity error calibration is carried out in two ways. First, a power-up calibration is carried out when the ADC comes out of reset. This is initiated by the CALIBRATE output of the Analog Block macro and is a fixed number of ADC\_CLK cycles (3,840 cycles), as shown in Figure 2-89 on page 2-111. In this mode, the linearity and offset errors of the capacitors are calibrated.

To further compensate for drift and temperature-dependent effects, every conversion is followed by postcalibration of either the offset or a bit of the main capacitor array. The post-calibration ensures that, over time and with temperature, the ADC remains consistent.

After both calibration and the setting of the appropriate configurations, as explained above, the ADC is ready for operation. Setting the ADCSTART signal high for one clock period will initiate the sample and conversion of the analog signal on the channel as configured by CHNUMBER[4:0]. The status signals SAMPLE and BUSY will show when the ADC is sampling and converting (Figure 2-91 on page 2-112). Both SAMPLE and BUSY will initially go high. After the ADC has sampled and held the analog signal, SAMPLE will go low. After the entire operation has completed and the analog signal is converted, BUSY will go low and DATAVALID will go high. This indicates that the digital result is available on the RESULT[11:0] pins.

DATAVALID will remain high until a subsequent ADCSTART is issued. The DATAVALID goes low on the rising edge of SYSCLK as shown in Figure 2-90 on page 2-112. The RESULT signals will be kept constant until the ADC finishes the subsequent sample. The next sampled RESULT will be available when DATAVALID goes high again. It is ideal to read the RESULT when DATAVALID is '1'. The RESULT is latched and remains unchanged until the next DATAVLAID rising edge.



### Table 2-54 • ACM Address Decode Table for Analog Quad (continued)

ACMADDR [7:0] in Decimal	Name	Description	Associated Peripheral						
73	MATCHREG1	Match register bits 15:8	RTC						
74	MATCHREG2	Match register bits 23:16	RTC						
75	MATCHREG3	Match register bits 31:24	RTC						
76	MATCHREG4	Match register bits 39:32	RTC						
80	MATCHBITS0	Individual match bits 7:0	RTC						
81	MATCHBITS1	Individual match bits 15:8	RTC						
82	MATCHBITS2	Individual match bits 23:16	RTC						
83	MATCHBITS3	Individual match bits 31:24	RTC						
84	MATCHBITS4	Individual match bits 39:32	RTC						
88	CTRL_STAT	Control (write) / Status (read) register bits 7:0	RTC						
Note: ACMADDR bytes 1 to 40 pertain to the Analog Quads; bytes 64 to 89 pertain to the RTC.									

# **ACM Characteristics<sup>1</sup>**



Figure 2-97 • ACM Write Waveform



Figure 2-98 • ACM Read Waveform

<sup>1.</sup> When addressing the RTC addresses (i.e., ACMADDR 64 to 89), there is no timing generator, and the rc\_osc, byte\_en, and aq\_wen signals have no impact.



# Analog Quad ACM Description

Table 2-56 maps out the ACM space associated with configuration of the Analog Quads within the Analog Block. Table 2-56 shows the byte assignment within each quad and the function of each bit within each byte. Subsequent tables will explain each bit setting and how it corresponds to a particular configuration. After 3.3 V and 1.5 V are applied to Fusion, Analog Quad configuration registers are loaded with default settings until the initialization and configuration state machine changes them to user-defined settings.

Table	2-56 •	Analog	Quad	Bvte /	Assianme	nt
1 4010	200	Analog	auuu .		Rooiginno	

Byte	Bit	Signal (Bx)	Function	Default Setting		
Byte 0	0	B0[0]	Scaling factor control – prescaler	Highest voltage range		
(AV)	1	B0[1]				
	2	B0[2]	-			
	3	B0[3]	Analog MUX select	Prescaler		
	4	B0[4]	Current monitor switch	Off		
	5	B0[5]	Direct analog input switch	Off		
	6	B0[6]	Selects V-pad polarity	Positive		
	7	B0[7]	Prescaler op amp mode	Power-down		
Byte 1	0	B1[0]	Scaling factor control – prescaler	Highest voltage range		
(AC)	1	B1[1]				
	2	B1[2]				
	3	B1[3]	Analog MUX select	Prescaler		
	4	B1[4]				
	5	B1[5]	Direct analog input switch	Off		
	6	B1[6]	Selects C-pad polarity	Positive		
	7	B1[7]	Prescaler op amp mode	Power-down		
Byte 2	0	B2[0]	Internal chip temperature monitor *	Off		
(AG)	1	B2[1]	Spare	-		
	2	B2[2]	Current drive control	Lowest current		
	3	B2[3]				
	4	B2[4]	Spare	-		
	5	B2[5]	Spare	-		
	6	B2[6]	Selects G-pad polarity	Positive		
	7	B2[7]	Selects low/high drive	Low drive		
Byte 3	0	B3[0]	Scaling factor control – prescaler	Highest voltage range		
(AT)	1	B3[1]	-			
	2	B3[2]	-			
	3	B3[3]	Analog MUX select	Prescaler		
	4	B3[4]				
	5	B3[5]	Direct analog input switch	Off		
	6	B3[6]	_	-		
	7	B3[7]	Prescaler op amp mode	Power-down		

Note: \*For the internal temperature monitor to function, Bit 0 of Byte 2 for all 10 Quads must be set.

### Table 2-68 • I/O Bank Support by Device

I/O Bank	AFS090	AFS250	AFS600	AFS1500
Standard I/O	Ν	Ν	_	-
Advanced I/O	E, W	E, W	E, W	E, W
Pro I/O	-	_	Ν	Ν
Analog Quad	S	S	S	S

*Note: E* = *East side of the device* 

W = West side of the device

N = North side of the device

S = South side of the device

### Table 2-69 • Fusion VCCI Voltages and Compatible Standards

VCCI (typical)	Compatible Standards
3.3 V	LVTTL/LVCMOS 3.3, PCI 3.3, SSTL3 (Class I and II),* GTL+ 3.3, GTL 3.3,* LVPECL
2.5 V	LVCMOS 2.5, LVCMOS 2.5/5.0, SSTL2 (Class I and II),* GTL+ 2.5,* GTL 2.5,* LVDS, BLVDS, M-LVDS
1.8 V	LVCMOS 1.8
1.5 V	LVCMOS 1.5, HSTL (Class I),* HSTL (Class II)*

*Note:* \*I/O standard supported by Pro I/O banks.

### Table 2-70 • Fusion VREF Voltages and Compatible Standards\*

VREF (typical)	Compatible Standards
1.5 V	SSTL3 (Class I and II)
1.25 V	SSTL2 (Class I and II)
1.0 V	GTL+ 2.5, GTL+ 3.3
0.8 V	GTL 2.5, GTL 3.3
0.75 V	HSTL (Class I), HSTL (Class II)

*Note:* \*I/O standards supported by Pro I/O banks.



Figure 2-102 • DDR Output Support in Fusion Devices

# Solution 3

The board-level design must ensure that the reflected waveform at the pad does not exceed limits provided in Table 3-4 on page 3-4. This is a long-term reliability requirement.

This scheme will also work for a 3.3 V PCI/PCIX configuration, but the internal diode should not be used for clamping, and the voltage must be limited by the bus switch, as shown in Figure 2-105. Relying on the diode clamping would create an excessive pad DC voltage of 3.3 V + 0.7 V = 4 V.





# Solution 4



Figure 2-106 • Solution 4



Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	C <sub>LOAD</sub> (pF)
0	3.3	1.4	-	35

Note: \*Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

#### Timing Characteristics

### Table 2-104 • 3.3 V LVTTL / 3.3 V LVCMOS Low Slew

Commercial Temperature Range Conditions: T<sub>J</sub> = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V Applicable to Pro I/Os

Drive Strength	Speed Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>PYS</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>zLS</sub>	t <sub>zHS</sub>	Units
4 mA	Std.	0.66	11.01	0.04	1.20	1.57	0.43	11.21	9.05	2.69	2.44	13.45	11.29	ns
	-1	0.56	9.36	0.04	1.02	1.33	0.36	9.54	7.70	2.29	2.08	11.44	9.60	ns
	-2	0.49	8.22	0.03	0.90	1.17	0.32	8.37	6.76	2.01	1.82	10.04	8.43	ns
8 mA	Std.	0.66	7.86	0.04	1.20	1.57	0.43	8.01	6.44	3.04	3.06	10.24	8.68	ns
	-1	0.56	6.69	0.04	1.02	1.33	0.36	6.81	5.48	2.58	2.61	8.71	7.38	ns
	-2	0.49	5.87	0.03	0.90	1.17	0.32	5.98	4.81	2.27	2.29	7.65	6.48	ns
12 mA	Std.	0.66	6.03	0.04	1.20	1.57	0.43	6.14	5.02	3.28	3.47	8.37	7.26	ns
	-1	0.56	5.13	0.04	1.02	1.33	0.36	5.22	4.27	2.79	2.95	7.12	6.17	ns
	-2	0.49	4.50	0.03	0.90	1.17	0.32	4.58	3.75	2.45	2.59	6.25	5.42	ns
16 mA	Std.	0.66	5.62	0.04	1.20	1.57	0.43	5.72	4.72	3.32	3.58	7.96	6.96	ns
	-1	0.56	4.78	0.04	1.02	1.33	0.36	4.87	4.02	2.83	3.04	6.77	5.92	ns
	-2	0.49	4.20	0.03	0.90	1.17	0.32	4.27	3.53	2.48	2.67	5.94	5.20	ns
24 mA	Std.	0.66	5.24	0.04	1.20	1.57	0.43	5.34	4.69	3.39	3.96	7.58	6.93	ns
	-1	0.56	4.46	0.04	1.02	1.33	0.36	4.54	3.99	2.88	3.37	6.44	5.89	ns
	-2	0.49	3.92	0.03	0.90	1.17	0.32	3.99	3.50	2.53	2.96	5.66	5.17	ns



### Table 2-107 • 3.3 V LVTTL / 3.3 V LVCMOS High Slew

Commercial Temperature Range Conditions:  $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V Applicable to Advanced I/Os

Drive	Speed												l
Strength	Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
4 mA	Std.	0.66	7.66	0.04	1.20	0.43	7.80	6.59	2.65	2.61	10.03	8.82	ns
	-1	0.56	6.51	0.04	1.02	0.36	6.63	5.60	2.25	2.22	8.54	7.51	ns
	-2	0.49	5.72	0.03	0.90	0.32	5.82	4.92	1.98	1.95	7.49	6.59	ns
8 mA	Std.	0.66	4.91	0.04	1.20	0.43	5.00	4.07	2.99	3.20	7.23	6.31	ns
	-1	0.56	4.17	0.04	1.02	0.36	4.25	3.46	2.54	2.73	6.15	5.36	ns
	-2	0.49	3.66	0.03	0.90	0.32	3.73	3.04	2.23	2.39	5.40	4.71	ns
12 mA	Std.	0.66	3.53	0.04	1.20	0.43	3.60	2.82	3.21	3.58	5.83	5.06	ns
	-1	0.56	3.00	0.04	1.02	0.36	3.06	2.40	2.73	3.05	4.96	4.30	ns
	-2	0.49	2.64	0.03	0.90	0.32	2.69	2.11	2.40	2.68	4.36	3.78	ns
16 mA	Std.	0.66	3.33	0.04	1.20	0.43	3.39	2.56	3.26	3.68	5.63	4.80	ns
	-1	0.56	2.83	0.04	1.02	0.36	2.89	2.18	2.77	3.13	4.79	4.08	ns
	-2	0.49	2.49	0.03	0.90	0.32	2.53	1.91	2.44	2.75	4.20	3.58	ns
24 mA	Std.	0.66	3.08	0.04	1.20	0.43	3.13	2.12	3.32	4.06	5.37	4.35	ns
	-1	0.56	2.62	0.04	1.02	0.36	2.66	1.80	2.83	3.45	4.57	3.70	ns
	-2	0.49	2.30	0.03	0.90	0.32	2.34	1.58	2.48	3.03	4.01	3.25	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

### Table 2-108 • 3.3 V LVTTL / 3.3 V LVCMOS Low Slew

Commercial Temperature Range Conditions:  $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V Applicable to Standard I/Os

Drive	Speed										
Strength	Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	Units
2 mA	Std.	0.66	9.46	0.04	1.00	0.43	9.64	8.54	2.07	2.04	ns
	-1	0.56	8.05	0.04	0.85	0.36	8.20	7.27	1.76	1.73	ns
	-2	0.49	7.07	0.03	0.75	0.32	7.20	6.38	1.55	1.52	ns
4 mA	Std.	0.66	9.46	0.04	1.00	0.43	9.64	8.54	2.07	2.04	ns
	-1	0.56	8.05	0.04	0.85	0.36	8.20	7.27	1.76	1.73	ns
	-2	0.49	7.07	0.03	0.75	0.32	7.20	6.38	1.55	1.52	ns
6 mA	Std.	0.66	6.57	0.04	1.00	0.43	6.69	5.98	2.40	2.57	ns
	-1	0.56	5.59	0.04	0.85	0.36	5.69	5.09	2.04	2.19	ns
	-2	0.49	4.91	0.03	0.75	0.32	5.00	4.47	1.79	1.92	ns
8 mA	Std.	0.66	6.57	0.04	1.00	0.43	6.69	5.98	2.40	2.57	ns
	-1	0.56	5.59	0.04	0.85	0.36	5.69	5.09	2.04	2.19	ns
	-2	0.49	4.91	0.03	0.75	0.32	5.00	4.47	1.79	1.92	ns

### Timing Characteristics

### Table 2-112 • 2.5 V LVCMOS Low Slew

Commercial Temperature Range Conditions: T<sub>J</sub> = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 2.3 V Applicable to Pro I/Os

Drive	Speed													
Strength	Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>PYS</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
4 mA	Std.	0.60	12.00	0.04	1.51	1.66	0.43	12.23	11.61	2.72	2.20	14.46	13.85	ns
	-1	0.51	10.21	0.04	1.29	1.41	0.36	10.40	9.88	2.31	1.87	12.30	11.78	ns
	-2	0.45	8.96	0.03	1.13	1.24	0.32	9.13	8.67	2.03	1.64	10.80	10.34	ns
8 mA	Std.	0.60	8.73	0.04	1.51	1.66	0.43	8.89	8.01	3.10	2.93	11.13	10.25	ns
	-1	0.51	7.43	0.04	1.29	1.41	0.36	7.57	6.82	2.64	2.49	9.47	8.72	ns
	-2	0.45	6.52	0.03	1.13	1.24	0.32	6.64	5.98	2.32	2.19	8.31	7.65	ns
12 mA	Std.	0.66	6.77	0.04	1.51	1.66	0.43	6.90	6.11	3.37	3.39	9.14	8.34	ns
	-1	0.56	5.76	0.04	1.29	1.41	0.36	5.87	5.20	2.86	2.89	7.77	7.10	ns
	-2	0.49	5.06	0.03	1.13	1.24	0.32	5.15	4.56	2.51	2.53	6.82	6.23	ns
16 mA	Std.	0.66	6.31	0.04	1.51	1.66	0.43	6.42	5.73	3.42	3.52	8.66	7.96	ns
	-1	0.56	5.37	0.04	1.29	1.41	0.36	5.46	4.87	2.91	3.00	7.37	6.77	ns
	-2	0.49	4.71	0.03	1.13	1.24	0.32	4.80	4.28	2.56	2.63	6.47	5.95	ns
24 mA	Std.	0.66	5.93	0.04	1.51	1.66	0.43	6.04	5.70	3.49	4.00	8.28	7.94	ns
	-1	0.56	5.05	0.04	1.29	1.41	0.36	5.14	4.85	2.97	3.40	7.04	6.75	ns
	-2	0.49	4.43	0.03	1.13	1.24	0.32	4.51	4.26	2.61	2.99	6.18	5.93	ns

### Timing Characteristics

Table 2-128 • 1.5 V LVCMOS Low Slew

Commercial Temperature Range Conditions:  $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V Applicable to Pro I/Os

Drive Strength	Speed Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>PYS</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
2 mA	Std.	0.66	14.11	0.04	1.70	2.14	0.43	14.37	13.14	3.40	2.68	16.61	15.37	ns
	-1	0.56	12.00	0.04	1.44	1.82	0.36	12.22	11.17	2.90	2.28	14.13	13.08	ns
	-2	0.49	10.54	0.03	1.27	1.60	0.32	10.73	9.81	2.54	2.00	12.40	11.48	ns
4 mA	Std.	0.66	11.23	0.04	1.70	2.14	0.43	11.44	9.87	3.77	3.36	13.68	12.10	ns
	-1	0.56	9.55	0.04	1.44	1.82	0.36	9.73	8.39	3.21	2.86	11.63	10.29	ns
	-2	0.49	8.39	0.03	1.27	1.60	0.32	8.54	7.37	2.81	2.51	10.21	9.04	ns
8 mA	Std.	0.66	10.45	0.04	1.70	2.14	0.43	10.65	9.24	3.84	3.55	12.88	11.48	ns
	-1	0.56	8.89	0.04	1.44	1.82	0.36	9.06	7.86	3.27	3.02	10.96	9.76	ns
	-2	0.49	7.81	0.03	1.27	1.60	0.32	7.95	6.90	2.87	2.65	9.62	8.57	ns
12 mA	Std.	0.66	10.02	0.04	1.70	2.14	0.43	10.20	9.23	3.97	4.22	12.44	11.47	ns
	-1	0.56	8.52	0.04	1.44	1.82	0.36	8.68	7.85	3.38	3.59	10.58	9.75	ns
	-2	0.49	7.48	0.03	1.27	1.60	0.32	7.62	6.89	2.97	3.15	9.29	8.56	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

### Table 2-129 • 1.5 V LVCMOS High Slew

Commercial Temperature Range Conditions:  $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V Applicable to Pro I/Os

Drive Strength	Speed Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>PYS</sub>	t <sub>EOU</sub> T	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
2 mA	Std.	0.66	8.53	0.04	1.70	2.14	0.43	7.26	8.53	3.39	2.79	9.50	10.77	ns
	-1	0.56	7.26	0.04	1.44	1.82	0.36	6.18	7.26	2.89	2.37	8.08	9.16	ns
	-2	0.49	6.37	0.03	1.27	1.60	0.32	5.42	6.37	2.53	2.08	7.09	8.04	ns
4 mA	Std.	0.66	5.41	0.04	1.70	2.14	0.43	5.22	5.41	3.75	3.48	7.45	7.65	ns
	-1	0.56	4.60	0.04	1.44	1.82	0.36	4.44	4.60	3.19	2.96	6.34	6.50	ns
	-2	0.49	4.04	0.03	1.27	1.60	0.32	3.89	4.04	2.80	2.60	5.56	5.71	ns
8 mA	Std.	0.66	4.80	0.04	1.70	2.14	0.43	4.89	4.75	3.83	3.67	7.13	6.98	ns
	-1	0.56	4.09	0.04	1.44	1.82	0.36	4.16	4.04	3.26	3.12	6.06	5.94	ns
	-2	0.49	3.59	0.03	1.27	1.60	0.32	3.65	3.54	2.86	2.74	5.32	5.21	ns
12 mA	Std.	0.66	4.42	0.04	1.70	2.14	0.43	4.50	3.62	3.96	4.37	6.74	5.86	ns
	-1	0.56	3.76	0.04	1.44	1.82	0.36	3.83	3.08	3.37	3.72	5.73	4.98	ns
	-2	0.49	3.30	0.03	1.27	1.60	0.32	3.36	2.70	2.96	3.27	5.03	4.37	ns

### SSTL2 Class II

Stub-Speed Terminated Logic for 2.5 V memory bus standard (JESD8-9). Fusion devices support Class II. This provides a differential amplifier input buffer and a push-pull output buffer.

SSTL2 Class II		VIL	VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL¹	IIH <sup>2</sup>
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA <sup>3</sup>	Max. mA <sup>3</sup>	μA <sup>4</sup>	μA <sup>4</sup>
18 mA	-0.3	VREF – 0.2	VREF + 0.2	3.6	0.35	VCCI – 0.43	18	18	124	169	10	10

Table 2-159 • Minimum and Maximum DC Input and Output Levels

Notes:

1. IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.

2. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

3. Currents are measured at high temperature (100°C junction temperature) and maximum voltage.

4. Currents are measured at 85°C junction temperature.



### Figure 2-131 • AC Loading

#### Table 2-160 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C <sub>LOAD</sub> (pF)
VREF – 0.2	VREF + 0.2	1.25	1.25	1.25	30

Note: \*Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

#### Timing Characteristics

### Table 2-161 • SSTL 2 Class II Commercial Temperature Range Conditions: T<sub>J</sub> = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 2.3 V, VREF = 1.25 V

Speed Grade	t <sub>DOUT</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
Std.	0.66	2.17	0.04	1.33	0.43	2.21	1.77			4.44	4.01	ns
-1	0.56	1.84	0.04	1.14	0.36	1.88	1.51			3.78	3.41	ns
-2	0.49	1.62	0.03	1.00	0.32	1.65	1.32			3.32	2.99	ns



### SSTL3 Class I

Stub-Speed Terminated Logic for 3.3 V memory bus standard (JESD8-8). Fusion devices support Class I. This provides a differential amplifier input buffer and a push-pull output buffer.

Table 2-162 • Minimum and Maximum DC Input and Output Levels

SSTL3 Class I		VIL	VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL¹	IIH <sup>2</sup>
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA <sup>3</sup>	Max. mA <sup>3</sup>	μA <sup>4</sup>	μA <sup>4</sup>
14 mA	-0.3	VREF – 0.2	VREF + 0.2	3.6	0.7	VCCI - 1.1	14	14	54	51	10	10

Notes:

1. IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.

2. IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.

3. Currents are measured at high temperature (100°C junction temperature) and maximum voltage.

4. Currents are measured at 85°C junction temperature.



### Figure 2-132 • AC Loading

#### Table 2-163 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C <sub>LOAD</sub> (pF)
VREF – 0.2	VREF + 0.2	1.5	1.5	1.485	30

Note: \*Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

#### Timing Characteristics

Table 2-164 • SSTL3 Class I

Commercial Temperature Range Conditions:  $T_J = 70^{\circ}$ C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V, VREF = 1.5 V

Speed Grade	t <sub>dout</sub>	t <sub>DP</sub>	t <sub>DIN</sub>	t <sub>PY</sub>	t <sub>EOUT</sub>	t <sub>ZL</sub>	t <sub>zH</sub>	t <sub>LZ</sub>	t <sub>HZ</sub>	t <sub>ZLS</sub>	t <sub>zHS</sub>	Units
Std.	0.66	2.31	0.04	1.25	0.43	2.35	1.84			4.59	4.07	ns
-1	0.56	1.96	0.04	1.06	0.36	2.00	1.56			3.90	3.46	ns
-2	0.49	1.72	0.03	0.93	0.32	1.75	1.37			3.42	3.04	ns

### XTAL2 Crystal Oscillator Circuit Input

Input to crystal oscillator circuit. Pin for connecting external crystal, ceramic resonator, RC network, or external clock input. When using an external crystal or ceramic oscillator, external capacitors are also recommended (Please refer to the crystal oscillator manufacturer for proper capacitor value).

If using external RC network or clock input, XTAL1 should be used and XTAL2 left unconnected. In the case where the Crystal Oscillator block is not used, the XTAL1 pin should be connected to GND and the XTAL2 pin should be left floating.

# Security

Fusion devices have a built-in 128-bit AES decryption core. The decryption core facilitates highly secure, in-system programming of the FPGA core array fabric and the FlashROM. The FlashROM and the FPGA core fabric can be programmed independently from each other, allowing the FlashROM to be updated without the need for change to the FPGA core fabric. The AES master key is stored in on-chip nonvolatile memory (flash). The AES master key can be preloaded into parts in a security-protected programming environment (such as the Microsemi in-house programming center), and then "blank" parts can be shipped to an untrusted programming or manufacturing center for final personalization with an AES-encrypted bitstream. Late stage product changes or personalization can be implemented easily and with high level security by simply sending a STAPL file with AES-encrypted data. Highly secure remote field updates over public networks (such as the Internet) are possible by sending and programming a STAPL file with AES-encrypted data. For more information, refer to the *Fusion Security* application note.

### 128-Bit AES Decryption

The 128-bit AES standard (FIPS-197) block cipher is the National Institute of Standards and Technology (NIST) replacement for DES (Data Encryption Standard FIPS46-2). AES has been designed to protect sensitive government information well into the 21st century. It replaces the aging DES, which NIST adopted in 1977 as a Federal Information Processing Standard used by federal agencies to protect sensitive, unclassified information. The 128-bit AES standard has 3.4 × 10<sup>38</sup> possible 128-bit key variants, and it has been estimated that it would take 1,000 trillion years to crack 128-bit AES cipher text using exhaustive techniques. Keys are stored (protected with security) in Fusion devices in nonvolatile flash memory. All programming files sent to the device can be authenticated by the part prior to programming to ensure that bad programming data is not loaded into the part that may possibly damage it. All programming verification is performed on-chip, ensuring that the contents of Fusion devices remain as secure as possible.

AES decryption can also be used on the 1,024-bit FlashROM to allow for remote updates of the FlashROM contents. This allows for easy support of subscription model products and protects them with measures designed to provide the highest level of security available. See the application note *Fusion Security* for more details.

# AES for Flash Memory

AES decryption can also be used on the flash memory blocks. This provides the best available security during update of the flash memory blocks. During runtime, the encrypted data can be clocked in via the JTAG interface. The data can be passed through the internal AES decryption engine, and the decrypted data can then be stored in the flash memory block.

# Programming

Programming can be performed using various programming tools, such as Silicon Sculptor II (BP Micro Systems) or FlashPro3 (Microsemi).

The user can generate STP programming files from the Designer software and can use these files to program a device.

Fusion devices can be programmed in-system. During programming, VCCOSC is needed in order to power the internal 100 MHz oscillator. This oscillator is used as a source for the 20 MHz oscillator that is used to drive the charge pump for programming.



# *Table 3-13* • Summary of I/O Output Buffer Power (per pin)—Default I/O Software Settings<sup>1</sup> (continued)

	C <sub>LOAD</sub> (pF)	VCCI (V)	Static Power PDC8 (mW) <sup>2</sup>	Dynamic Power PAC10 (µW/MHz) <sup>3</sup>
Differential				
LVDS	-	2.5	7.74	88.92
LVPECL	_	3.3	19.54	166.52
Applicable to Standard I/O Bank	s			
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	35	3.3	-	431.08
2.5 V LVCMOS	35	2.5	-	247.36
1.8 V LVCMOS	35	1.8	-	128.46
1.5 V LVCMOS (JESD8-11)	35	1.5	-	89.46

Notes:

1. Dynamic power consumption is given for standard load and software-default drive strength and output slew.

2. PDC8 is the static power (where applicable) measured on VCCI.

3. PAC10 is the total dynamic power measured on VCC and VCCI.

# Example of Power Calculation

This example considers a shift register with 5,000 storage tiles, including a counter and memory that stores analog information. The shift register is clocked at 50 MHz and stores and reads information from a RAM.

The device used is a commercial AFS600 device operating in typical conditions.

The calculation below uses the power calculation methodology previously presented and shows how to determine the dynamic and static power consumption of resources used in the application.

Also included in the example is the calculation of power consumption in operating, standby, and sleep modes to illustrate the benefit of power-saving modes.

### Global Clock Contribution—P<sub>CLOCK</sub>

 $F_{CLK}$  = 50 MHz Number of sequential VersaTiles: N<sub>S-CELL</sub> = 5,000 Estimated number of Spines: N<sub>SPINES</sub> = 5 Estimated number of Rows: N<sub>ROW</sub> = 313

### **Operating Mode**

$$\begin{split} & \mathsf{P}_{\mathsf{CLOCK}} = (\mathsf{PAC1} + \mathsf{N}_{\mathsf{SPINE}} * \mathsf{PAC2} + \mathsf{N}_{\mathsf{ROW}} * \mathsf{PAC3} + \mathsf{N}_{\mathsf{S}\text{-}\mathsf{CELL}} * \mathsf{PAC4}) * \mathsf{F}_{\mathsf{CLK}} \\ & \mathsf{P}_{\mathsf{CLOCK}} = (0.0128 + 5 * 0.0019 + 313 * 0.00081 + 5,000 * 0.00011) * 50 \\ & \mathsf{P}_{\mathsf{CLOCK}} = 41.28 \ \mathsf{mW} \end{split}$$

### Standby Mode and Sleep Mode

 $P_{CLOCK} = 0 W$ 

Logic—Sequential Cells, Combinational Cells, and Routing Net Contributions— $P_{S-CELL}$ ,  $P_{C-CELL}$ , and  $P_{NET}$ 

 $\label{eq:F_CLK} \ensuremath{\mathsf{F_{CLK}}}\xspace = 50 \ensuremath{\,\mathsf{MHz}}\xspace \\ \ensuremath{\mathsf{Number}}\xspace of sequential VersaTiles: \ensuremath{\mathsf{N}_{S-CELL}}\xspace = 5,000 \\ \ensuremath{\mathsf{Number}}\xspace of versaTiles: \ensuremath{\mathsf{N}_{C-CELL}}\xspace = 6,000 \\ \ensuremath{\mathsf{Estimated}}\xspace toggle rate of VersaTile outputs: \ensuremath{\alpha_1}\xspace = 0.1 \ensuremath{\,(10\%)}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{}\xspace \ensuremath{\mathsf{R}}\xspace \ensuremath{}\xspace \ensuremath{$ 

### **Operating Mode**

$$\begin{split} \mathsf{P}_{S\text{-}CELL} &= \mathsf{N}_{S\text{-}CELL} * (\mathsf{P}_{\mathsf{AC5}}\text{+} (\alpha_1 \, / \, 2) * \mathsf{PAC6}) * \mathsf{F}_{\mathsf{CLK}} \\ \mathsf{P}_{S\text{-}CELL} &= 5,000 * (0.00007 + (0.1 \, / \, 2) * 0.00029) * 50 \\ \mathsf{P}_{S\text{-}CELL} &= 21.13 \text{ mW} \end{split}$$

 $P_{C-CELL} = N_{C-CELL}^* (\alpha_1 / 2) * PAC7 * F_{CLK}$  $P_{C-CELL} = 6,000 * (0.1 / 2) * 0.00029 * 50$  $P_{C-CELL} = 4.35 \text{ mW}$ 

$$\begin{split} \mathsf{P}_{\mathsf{NET}} &= (\mathsf{N}_{\mathsf{S}\text{-}\mathsf{CELL}} + \mathsf{N}_{\mathsf{C}\text{-}\mathsf{CELL}}) * (\alpha_1 \,/\, 2) * \mathsf{PAC8} * \mathsf{F}_{\mathsf{CLK}} \\ \mathsf{P}_{\mathsf{NET}} &= (5,000 + 6,000) * (0.1 \,/\, 2) * 0.0007 * 50 \\ \mathsf{P}_{\mathsf{NET}} &= 19.25 \text{ mW} \end{split}$$

 $P_{LOGIC} = P_{S-CELL} + P_{C-CELL} + P_{NET}$  $P_{LOGIC} = 21.13 \text{ mW} + 4.35 \text{ mW} + 19.25 \text{ mW}$  $P_{LOGIC} = 44.73 \text{ mW}$ 

Standby Mode and Sleep Mode



### Total Static Power Consumption—PSTAT

Number of Quads used:  $N_{QUADS} = 4$ Number of NVM blocks available (AFS600):  $N_{NVM-BLOCKS} = 2$ Number of input pins used:  $N_{INPUTS} = 30$ Number of output pins used:  $N_{OUTPUTS} = 40$ 

### **Operating Mode**

 $\mathsf{P}_{\mathsf{STAT}} = \mathsf{PDC1} + (\mathsf{N}_{\mathsf{NVM-BLOCKS}} * \mathsf{PDC4}) + \mathsf{PDC5} + (\mathsf{N}_{\mathsf{QUADS}} * \mathsf{PDC6}) + (\mathsf{N}_{\mathsf{INPUTS}} * \mathsf{PDC7}) + (\mathsf{N}_{\mathsf{OUTPUTS}} * \mathsf{PDC8})$ 

P<sub>STAT</sub> = 7.50 mW + (2 \* 1.19 mW) + 8.25 mW + (4 \* 3.30 mW) + (30 \* 0.00) + (40 \* 0.00)

P<sub>STAT</sub> = 31.33 mW

### Standby Mode

P<sub>STAT</sub> = PDC2

 $P_{STAT}$  = 0.03 mW

### Sleep Mode

 $P_{STAT} = PDC3$ 

 $P_{STAT} = 0.03 \text{ mW}$ 

### Total Power Consumption—PTOTAL

In operating mode, the total power consumption of the device is 174.39 mW:

 $P_{TOTAL} = P_{STAT} + P_{DYN}$ 

P<sub>TOTAL</sub> = 143.06 mW + 31.33 mW

P<sub>TOTAL</sub> = 174.39 mW

In standby mode, the total power consumption of the device is limited to 0.66 mW:

 $P_{TOTAL} = P_{STAT} + P_{DYN}$ 

 $P_{TOTAL} = 0.03 \text{ mW} + 0.63 \text{ mW}$ 

 $P_{TOTAL} = 0.66 \text{ mW}$ 

In sleep mode, the total power consumption of the device drops as low as 0.03 mW:

 $P_{TOTAL} = P_{STAT} + P_{DYN}$  $P_{TOTAL} = 0.03 \text{ mW}$ 



# 4 – Package Pin Assignments

# QN108



Note: The die attach paddle center of the package is tied to ground (GND).

# Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/default.aspx.

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Package Pin Assignments

	FG676		FG676		FG676
Pin Number	AFS1500 Function	Pin Number	AFS1500 Function	Pin Number	AFS1500 Function
C9	IO07PDB0V1	D19	GBC1/IO40PDB1V2	F3	IO121NDB4V0
C10	IO09PDB0V1	D20	GBA1/IO42PDB1V2	F4	GND
C11	IO13NDB0V2	D21	GND	F5	IO123NDB4V0
C12	IO13PDB0V2	D22	VCCPLB	F6	GAC2/IO123PDB4V0
C13	IO24PDB1V0	D23	GND	F7	GAA2/IO125PDB4V0
C14	IO26PDB1V0	D24	NC	F8	GAC0/IO03NDB0V0
C15	IO27NDB1V1	D25	NC	F9	GAC1/IO03PDB0V0
C16	IO27PDB1V1	D26	NC	F10	IO10NDB0V1
C17	IO35NDB1V2	E1	GND	F11	IO10PDB0V1
C18	IO35PDB1V2	E2	IO122NPB4V0	F12	IO14NDB0V2
C19	GBC0/IO40NDB1V2	E3	IO121PDB4V0	F13	IO23NDB1V0
C20	GBA0/IO42NDB1V2	E4	IO122PPB4V0	F14	IO23PDB1V0
C21	IO43NDB1V2	E5	IO00NDB0V0	F15	IO32NPB1V1
C22	IO43PDB1V2	E6	IO00PDB0V0	F16	IO34NDB1V1
C23	NC	E7	VCCIB0	F17	IO34PDB1V1
C24	GND	E8	IO05NDB0V1	F18	IO37PDB1V2
C25	NC	E9	IO05PDB0V1	F19	GBB1/IO41PDB1V2
C26	NC	E10	VCCIB0	F20	VCCIB2
D1	NC	E11	IO11NDB0V1	F21	IO47PPB2V0
D2	NC	E12	IO14PDB0V2	F22	IO44NDB2V0
D3	NC	E13	VCCIB0	F23	GND
D4	GND	E14	VCCIB1	F24	IO45NDB2V0
D5	GAA0/IO01NDB0V0	E15	IO29NDB1V1	F25	VCCIB2
D6	GND	E16	IO29PDB1V1	F26	NC
D7	IO04NDB0V0	E17	VCCIB1	G1	NC
D8	IO04PDB0V0	E18	IO37NDB1V2	G2	IO119PPB4V0
D9	GND	E19	GBB0/IO41NDB1V2	G3	IO120NDB4V0
D10	IO09NDB0V1	E20	VCCIB1	G4	IO120PDB4V0
D11	IO11PDB0V1	E21	VCOMPLB	G5	VCCIB4
D12	GND	E22	GBA2/IO44PDB2V0	G6	GAB2/IO124PDB4V0
D13	IO24NDB1V0	E23	IO48PPB2V0	G7	IO125NDB4V0
D14	IO26NDB1V0	E24	GBB2/IO45PDB2V0	G8	GND
D15	GND	E25	NC	G9	VCCIB0
D16	IO31NDB1V1	E26	GND	G10	IO08NDB0V1
D17	IO31PDB1V1	F1	NC	G11	IO08PDB0V1
D18	GND	F2	VCCIB4	G12	GND



# **Datasheet Categories**

### Categories

In order to provide the latest information to designers, some datasheet parameters are published before data has been fully characterized from silicon devices. The data provided for a given device, as highlighted in the "Fusion Device Status" table, is designated as either "Product Brief," "Advance," "Preliminary," or "Production." The definitions of these categories are as follows:

# **Product Brief**

The product brief is a summarized version of a datasheet (advance or production) and contains general product information. This document gives an overview of specific device and family information.

### Advance

This version contains initial estimated information based on simulation, other products, devices, or speed grades. This information can be used as estimates, but not for production. This label only applies to the DC and Switching Characteristics chapter of the datasheet and will only be used when the data has not been fully characterized.

### Preliminary

The datasheet contains information based on simulation and/or initial characterization. The information is believed to be correct, but changes are possible.

### Production

This version contains information that is considered to be final.

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