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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

| Details	
Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	36864
Number of I/O	65
Number of Gates	250000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	180-WFQFN Dual Rows, Exposed Pad
Supplier Device Package	180-QFN (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/m1afs250-1qng180i
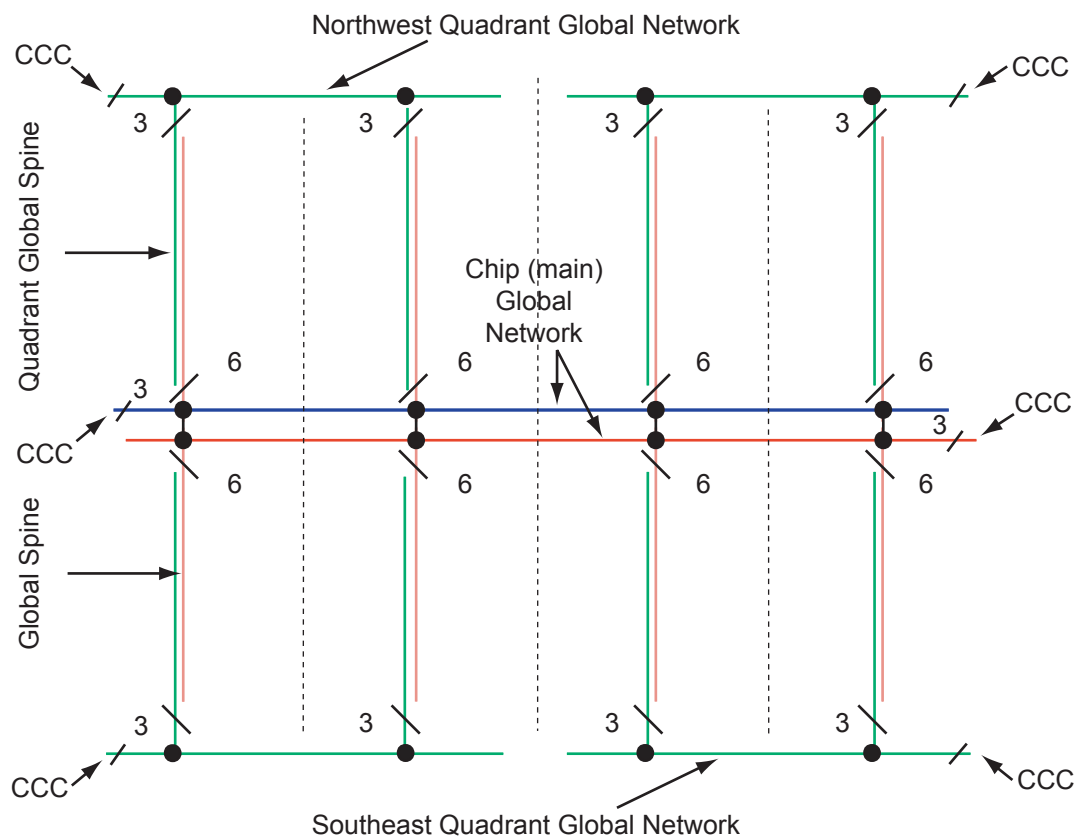
Figure 2-12 • **Global Network Architecture**

Table 2-4 • **Globals/Spines/Rows by Device**

	AFS090	AFS250	AFS600	AFS1500
Global VersaNets (trees)*	9	9	9	9
VersaNet Spines/Tree	4	8	12	20
Total Spines	36	72	108	180
VersaTiles in Each Top or Bottom Spine	384	768	1,152	1,920
Total VersaTiles	2,304	6,144	13,824	38,400

*Note: *There are six chip (main) globals and three globals per quadrant.*

Clock Aggregation

Clock aggregation allows for multi-spine clock domains. A MUX tree provides the necessary flexibility to allow long lines or I/Os to access domains of one, two, or four global spines. Signal access to the clock aggregation system is achieved through long-line resources in the central rib, and also through local resources in the north and south ribs, allowing I/Os to feed directly into the clock system. As Figure 2-14 indicates, this access system is contiguous.

There is no break in the middle of the chip for north and south I/O VersaNet access. This is different from the quadrant clocks, located in these ribs, which only reach the middle of the rib. Refer to the *Using Global Resources in Actel Fusion Devices* application note.
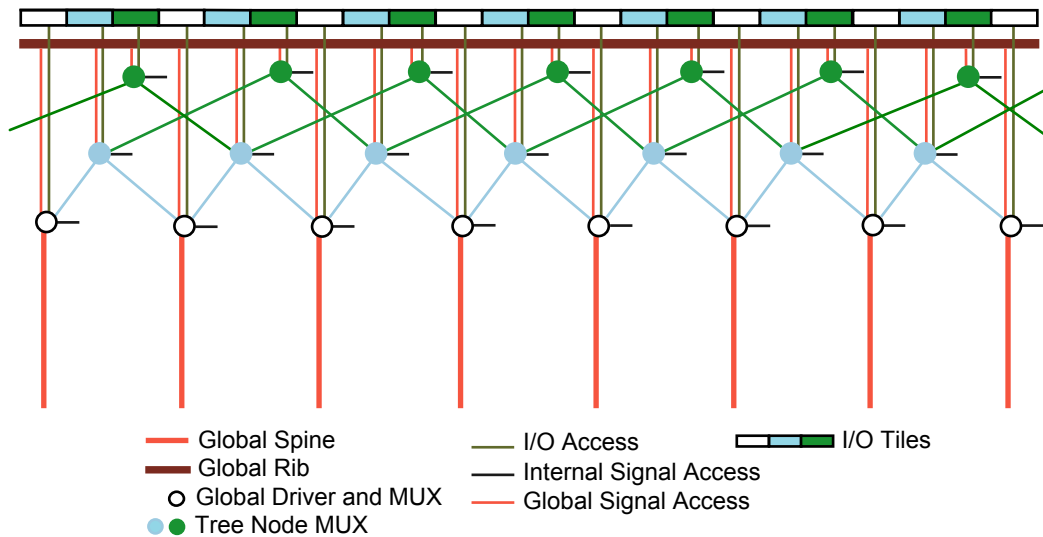

Figure 2-14 • **Clock Aggregation Tree Architecture**

Table 2-7 • **AFS250 Global Resource Timing**
Commercial Temperature Range Conditions: T$_J$ = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	−2		−1		Std.		Units
		Min.[1]	Max.[2]	Min.[1]	Max.[2]	Min.[1]	Max.[2]	
t$_{RCKL}$	Input Low Delay for Global Clock	0.89	1.12	1.02	1.27	1.20	1.50	ns
t$_{RCKH}$	Input High Delay for Global Clock	0.88	1.14	1.00	1.30	1.17	1.53	ns
t$_{RCKMPWH}$	Minimum Pulse Width High for Global Clock							ns
t$_{RCKMPWL}$	Minimum Pulse Width Low for Global Clock							ns
t$_{RCKSW}$	Maximum Skew for Global Clock		0.26		0.30		0.35	ns

Notes:

1. *Value reflects minimum load. The delay is measured from the CCC output to the clock pin of a sequential element located in a lightly loaded row (single element is connected to the global net).*
2. *Value reflects maximum load. The delay is measured on the clock pin of the farthest sequential element located in a fully loaded row (all available flip-flops are connected to the global net in the row).*
3. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.*

Table 2-8 • **AFS090 Global Resource Timing**
Commercial Temperature Range Conditions: T$_J$ = 70°C, Worst-Case VCC = 1.425 V

Parameter	Description	−2		−1		Std.		Units
		Min.[1]	Max.[2]	Min.[1]	Max.[2]	Min.[1]	Max.[2]	
t$_{RCKL}$	Input Low Delay for Global Clock	0.84	1.07	0.96	1.21	1.13	1.43	ns
t$_{RCKH}$	Input High Delay for Global Clock	0.83	1.10	0.95	1.25	1.12	1.47	ns
t$_{RCKMPWH}$	Minimum Pulse Width High for Global Clock							ns
t$_{RCKMPWL}$	Minimum Pulse Width Low for Global Clock							ns
t$_{RCKSW}$	Maximum Skew for Global Clock		0.27		0.30		0.36	ns

Notes:

1. *Value reflects minimum load. The delay is measured from the CCC output to the clock pin of a sequential element located in a lightly loaded row (single element is connected to the global net).*
2. *Value reflects maximum load. The delay is measured on the clock pin of the farthest sequential element located in a fully loaded row (all available flip-flops are connected to the global net in the row).*
3. *For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.*

Real-Time Counter System

The RTC system enables Fusion devices to support standby and sleep modes of operation to reduce power consumption in many applications.

- Sleep mode, typical 10 µA
- Standby mode (RTC running), typical 3 mA with 20 MHz

The RTC system is composed of five cores:

- RTC sub-block inside Analog Block (AB)
- Voltage Regulator and Power System Monitor (VRPSM)
- Crystal oscillator (XTLOSC); refer to the "Crystal Oscillator" section in the Fusion Clock Resources chapter of the *Fusion FPGA Fabric User Guide* for more detail.
- Crystal clock; does not require instantiation in RTL
- 1.5 V voltage regulator; does not require instantiation in RTL

All cores are powered by 3.3 V supplies, so the RTC system is operational without a 1.5 V supply during standby mode. Figure 2-27 shows their connection.
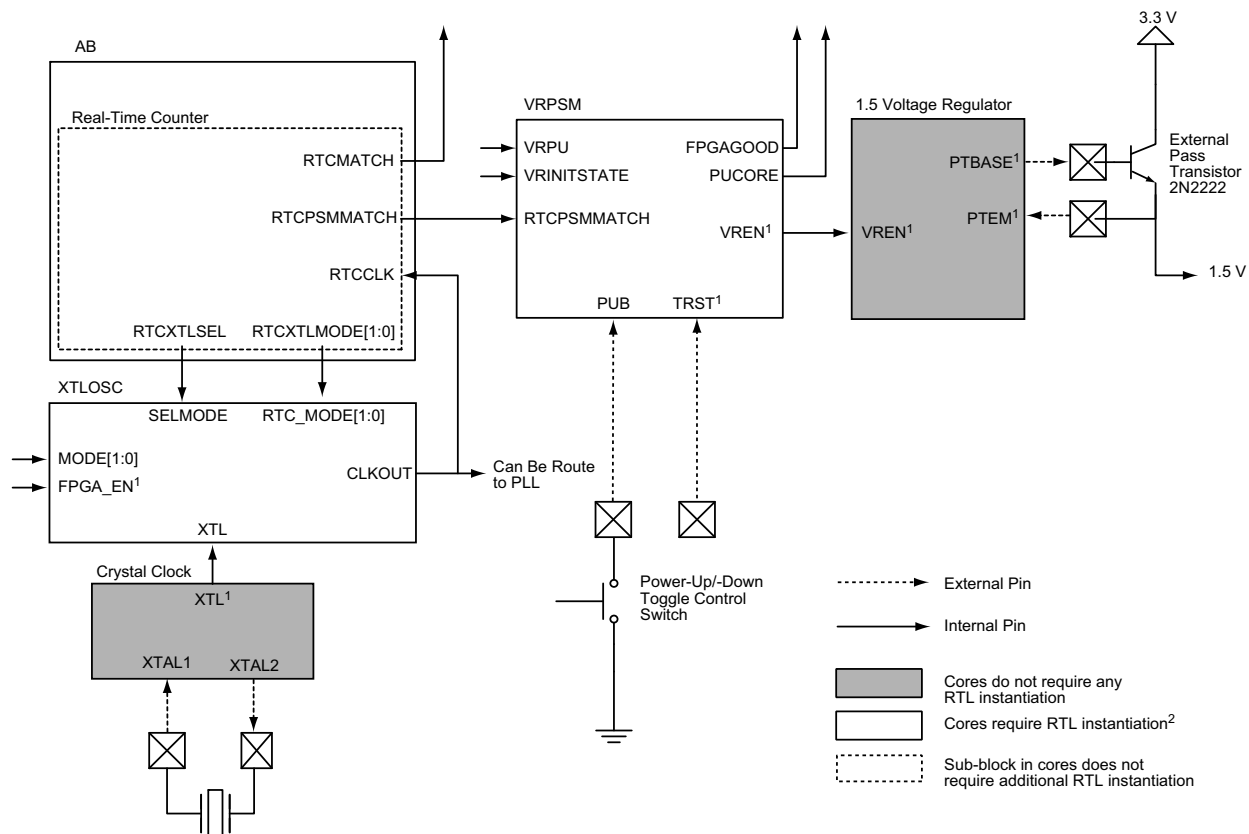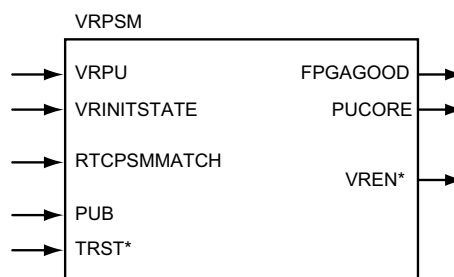

Notes:

1. *Signals are hardwired internally and do not exist in the macro core.*
2. *User is only required to instantiate the VRPSM macro if the user wishes to specify PUPO behavior of the voltage regulator to be different from the default, or employ user logic to shut the voltage regulator off.*

Figure 2-27 • Real-Time Counter System (not all the signals are shown for the AB macro)

Voltage Regulator and Power System Monitor (VRPSM)

The VRPSM macro controls the power-up state of the FPGA. The power-up bar (PUB) pin can turn on the voltage regulator when set to 0. TRST can enable the voltage regulator when deasserted, allowing the FPGA to power-up when user want access to JTAG ports. The inputs VRINITSTATE and RTCPSMMATCH come from the flash bits and RTC, and can also power up the FPGA.

*Note: *Signals are hardwired internally and do not exist in the macro core.*

Figure 2-30 • VRPSM Macro

Table 2-17 • VRPSM Signal Descriptions

Signal Name	Width	Direction	Function
VRPU	1	In	Voltage Regulator Power-Up 0 – Voltage regulator disabled. PUB must be floated or pulled up, and the TRST pin must be grounded to disable the voltage regulator. 1 – Voltage regulator enabled
VRINITSTATE	1	In	Voltage Regulator Initial State Defines the voltage Regulator status upon power-up of the 3.3 V. The signal is configured by Libero SoC when the VRPSM macro is generated. Tie off to 1 – Voltage regulator enables when 3.3 V is powered. Tie off to 0 – Voltage regulator disables when 3.3 V is powered.
RTCPSMMATCH	1	In	RTC Power System Management Match Connect from RTCPSMATCH signal from RTC in AB 0 transition to 1 turns on the voltage regulator
PUB	1	In	External pin, built-in weak pull-up Power-Up Bar 0 – Enables voltage regulator at all times
TRST*	1	In	External pin, JTAG Test Reset 1 – Enables voltage regulator at all times
FPGAGOOD	1	Out	Indicator that the FPGA is powered and functional No need to connect if it is not used. 1 – Indicates that the FPGA is powered up and functional. 0 – Not possible to read by FPGA since it has already powered off.
PUCORE	1	Out	Power-Up Core Inverted signal of PUB. No need to connect if it is not used.
VREN*	1	Out	Voltage Regulator Enable Connected to 1.5 V voltage regulator in Fusion device internally. 0 – Voltage regulator disables 1 – Voltage regulator enables

*Note: *Signals are hardwired internally and do not exist in the macro core.*

1.5 V Voltage Regulator

The 1.5 V voltage regulator uses an external pass transistor to generate 1.5 V from a 3.3 V supply. The base of the pass transistor is tied to PTBASE, the collector is tied to 3.3 V, and an emitter is tied to PTBASE and the 1.5 V supplies of the Fusion device. Figure 2-27 on page 2-31 shows the hook-up of the 1.5 V voltage regulator to an external pass transistor.

Microsemi recommends using a PN2222A or 2N2222A transistor. The gain of such a transistor is approximately 25, with a maximum base current of 20 mA. The maximum current that can be supported is 0.5 A. Transistors with different gain can also be used for different current requirements.

Table 2-18 • **Electrical Characteristics**
VCC33A = 3.3 V

Symbol	Parameter	Condition		Min	Typical	Max	Units
VOUT	Output Voltage	Tj = 25ºC		1.425	1.5	1.575	V
ICC33A	Operation Current	Tj = 25ºC	ILOAD = 1 mA		11		mA
			ILOAD = 100 mA		11		mA
			ILOAD = 0.5 A		30		mA
ΔVOUT	Load Regulation	Tj = 25ºC	ILOAD = 1 mA to 0.5 A		90		mV
ΔVOUT	Line Regulation	Tj = 25ºC	VCC33A = 2.97 V to 3.63 V ILOAD = 1 mA		10.6		mV/V
			VCC33A = 2.97 V to 3.63 V ILOAD = 100 mA		12.1		mV/V
			VCC33A = 2.97 V to 3.63 V ILOAD = 500 mA		10.6		mV/V
	Dropout Voltage*	Tj = 25ºC	ILOAD = 1 mA		0.63		V
			ILOAD = 100 mA		0.84		V
			ILOAD = 0.5 A		1.35		V
IPTBASE	PTBase Current	Tj = 25ºC	ILOAD = 1 mA		48		µA
			ILOAD = 100 mA		736		µA
			ILOAD = 0.5 A		12	20	mA

Note: *Data collected with 2N2222A.*

RAM512X18 exhibits slightly different behavior from RAM4K9, as it has dedicated read and write ports.

WW and RW

These signals enable the RAM to be configured in one of the two allowable aspect ratios (Table 2-30).

Table 2-30 • **Aspect Ratio Settings for WW[1:0]**

WW[1:0]	RW[1:0]	D×W
01	01	512×9
10	10	256×18
00, 11	00, 11	Reserved

WD and RD

These are the input and output data signals, and they are 18 bits wide. When a 512×9 aspect ratio is used for write, WD[17:9] are unused and must be grounded. If this aspect ratio is used for read, then RD[17:9] are undefined.

WADDR and RADDR

These are read and write addresses, and they are nine bits wide. When the 256×18 aspect ratio is used for write or read, WADDR[8] or RADDR[8] are unused and must be grounded.

WCLK and RCLK

These signals are the write and read clocks, respectively. They are both active high.

WEN and REN

These signals are the write and read enables, respectively. They are both active low by default. These signals can be configured as active high.

RESET

This active low signal resets the output to zero, disables reads and/or writes from the SRAM block, and clears the data hold registers when asserted. It does not reset the contents of the memory.

PIPE

This signal is used to specify pipelined read on the output. A Low on PIPE indicates a nonpipelined read, and the data appears on the output in the same clock cycle. A High indicates a pipelined read, and data appears on the output in the next clock cycle.

Clocking

The dual-port SRAM blocks are only clocked on the rising edge. SmartGen allows falling-edge-triggered clocks by adding inverters to the netlist, hence achieving dual-port SRAM blocks that are clocked on either edge (rising or falling). For dual-port SRAM, each port can be clocked on either edge or by separate clocks, by port.

Fusion devices support inversion (bubble pushing) throughout the FPGA architecture, including the clock input to the SRAM modules. Inversions added to the SRAM clock pin on the design schematic or in the HDL code will be automatically accounted for during design compile without incurring additional delay in the clock path.

The two-port SRAM can be clocked on the rising edge or falling edge of WCLK and RCLK.

If negative-edge RAM and FIFO clocking is selected for memory macros, clock edge inversion management (bubble pushing) is automatically used within the Fusion development tools, without performance penalty.
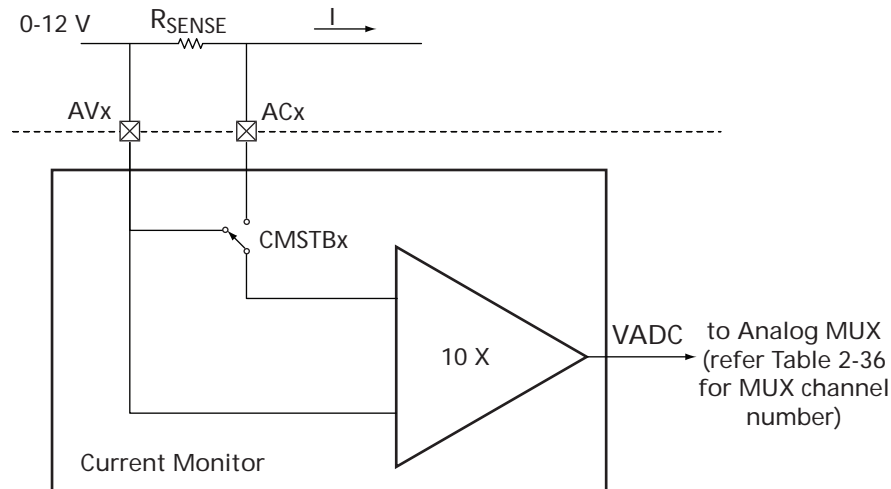
Figure 2-72 • Positive Current Monitor

Care must be taken when choosing the right resistor for current measurement application. Note that because of the 10× amplification, the maximum measurable difference between the AV and AC pads is V_{AREF} / 10. A larger AV-to-AC voltage drop will result in ADC saturation; that is, the digital code put out by the ADC will stay fixed at the full scale value. Therefore, the user must select the external sense resistor appropriately. Table 2-38 shows recommended resistor values for different current measurement ranges. When choosing resistor values for a system, there is a trade-off between measurement accuracy and power consumption. Choosing a large resistor will increase the voltage drop and hence increase accuracy of the measurement; however the larger voltage drop dissipates more power ($P = I^2 \times R$).

The Current Monitor is a unipolar system, meaning that the differential voltage swing must be from 0 V to V_{AREF}/10. Therefore, the Current Monitor only supports differential voltage where $|V_{AV}\text{-}V_{AC}|$ is greater than 0 V. This results in the requirement that the potential of the AV pad must be larger than the potential of the AC pad. This is straightforward for positive voltage systems. For a negative voltage system, it means that the AV pad must be "more negative" than the AC pad. This is shown in Figure 2-73.

In this case, both the AV pad and the AC pad are configured for negative operations and the output of the differential amplifier still falls between 0 V and V_{AREF} as required.

Table 2-37 • Recommended Resistor for Different Current Range Measurement

Current Range	Recommended Minimum Resistor Value (Ohms)
> 5 mA – 10 mA	10 – 20
> 10 mA – 20 mA	5 – 10
> 20 mA – 50 mA	2.5 – 5
> 50 mA – 100 mA	1 – 2
> 100 mA – 200 mA	0.5 – 1
> 200 mA – 500 mA	0.3 – 0.5
> 500 mA – 1 A	0.1 – 0.2
> 1 A – 2 A	0.05 – 0.1
> 2 A – 4 A	0.025 – 0.05
> 4 A – 8 A	0.0125 – 0.025
> 8 A – 12 A	0.00625 – 0.02
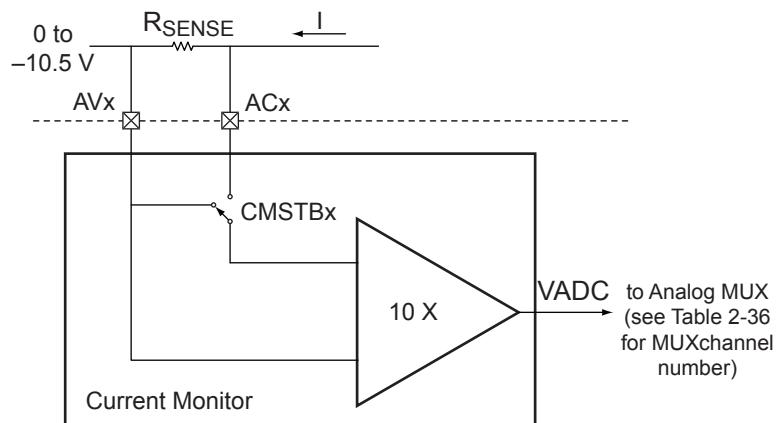
Figure 2-73 • Negative Current Monitor

Terminology

Accuracy

The accuracy of Fusion Current Monitor is ±2 mV minimum plus 5% of the differential voltage at the input. The input accuracy can be translated to error at the ADC output by using EQ 4. The 10 V/V gain is the gain of the Current Monitor Circuit, as described in the "Current Monitor" section on page 2-86. For 8-bit mode, $N = 8$, V_{AREF} = 2.56 V, zero differential voltage between AV and AC, the Error (E_{ADC}) is equal to 2 LSBs.

$$E_{ADC} = (2mV + 0.05|V_{AV} - V_{AC}|) \times (10V)/V \times \frac{2^N}{V_{AREF}}$$

EQ 4

where

N is the number of bits

V_{AREF} is the Reference voltage

V_{AV} is the voltage at AV pad

V_{AC} is the voltage at AC pad

Gate Driver

The Fusion Analog Quad includes a Gate Driver connected to the Quad's AG pin (Figure 2-74). Designed to work with external p- or n-channel MOSFETs, the Gate driver is a configurable current sink or source and requires an external pull-up or pull-down resistor. The AG supports 4 selectable gate drive levels: 1 µA, 3 µA, 10 µA, and 30 µA (Figure 2-75 on page 2-91). The AG also supports a High Current Drive mode in which it can sink 20 mA; in this mode the switching rate is approximately 1.3 MHz with 100 ns turn-on time and 600 ns turn-off time. Modeled on an open-drain-style output, it does not output a voltage level without an appropriate pull-up or pull-down resistor. If 1 V is forced on the drain, the current sinking/sourcing will exceed the ability of the transistor, and the device could be damaged.

The AG pad is turned on via the corresponding GDONx pin in the Analog Block macro, where x is the number of the corresponding Analog Quad for the AG pad to be enabled (GDON0 to GDON9).
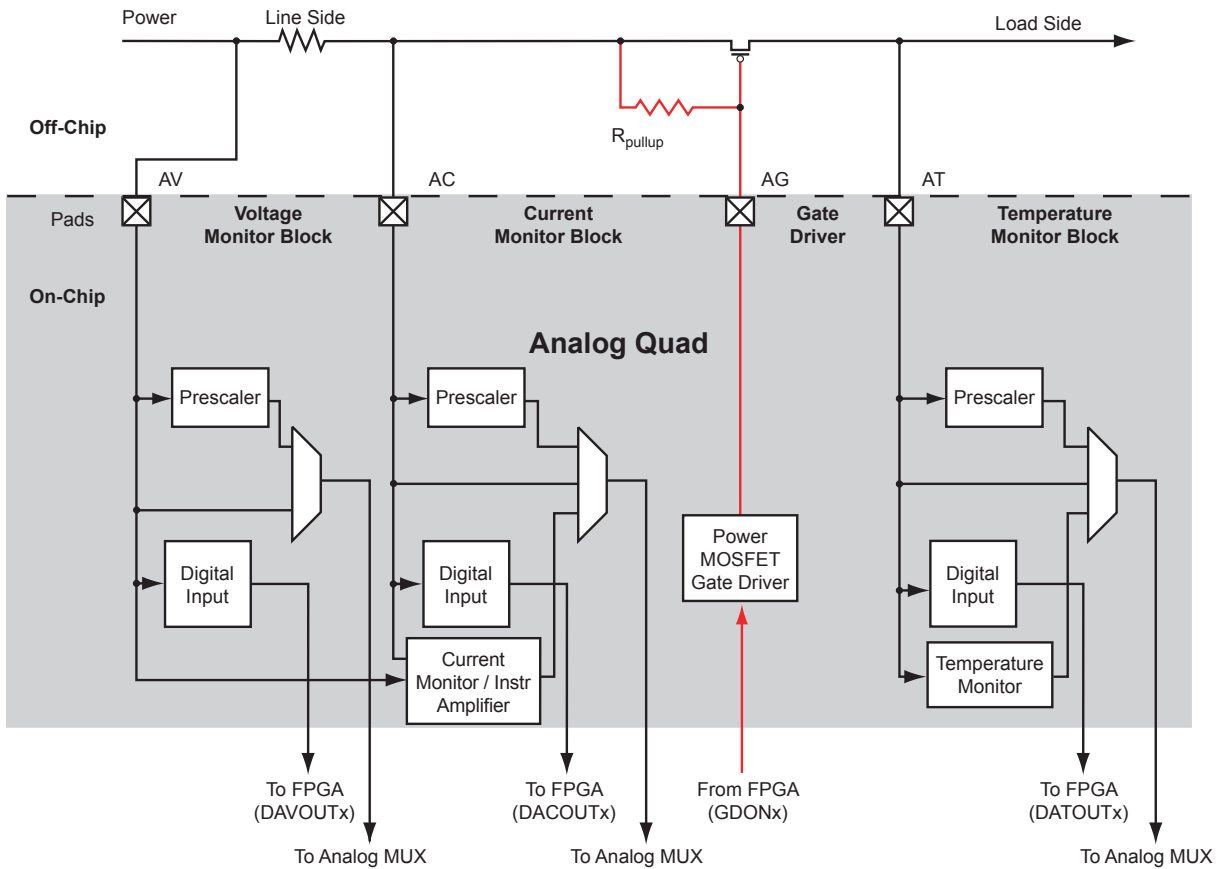

Figure 2-74 • **Gate Driver**

The gate-to-source voltage (V_{gs}) of the external MOSFET is limited to the programmable drive current times the external pull-up or pull-down resistor value (EQ 5).

$$V_{gs} \leq I_g \times (R_{pullup} \text{ or } R_{pulldown})$$

EQ 5

Hot-Swap Support

Hot-swapping (also called hot plugging) is the operation of hot insertion or hot removal of a card in (or from) a powered-up system. The levels of hot-swap support and examples of related applications are described in Table 2-74. The I/Os also need to be configured in hot insertion mode if hot plugging compliance is required.

Table 2-74 • **Levels of Hot-Swap Support**

Hot Swapping Level	Description	Power Applied to Device	Bus State	Card Ground Connection	Device Circuitry Connected to Bus Pins	Example of Application with Cards that Contain Fusion Devices	Compliance of Fusion Devices
1	Cold-swap	No	–	–	–	System and card with Microsemi FPGA chip are powered down, then card gets plugged into system, then power supplies are turned on for system but not for FPGA on card.	Compliant I/Os can but do not have to be set to hot insertion mode.
2	Hot-swap while reset	Yes	Held in reset state	Must be made and maintained for 1 ms before, during, and after insertion/removal	–	In PCI hot plug specification, reset control circuitry isolates the card busses until the card supplies are at their nominal operating levels and stable.	Compliant I/Os can but do not have to be set to hot insertion mode.
3	Hot-swap while bus idle	Yes	Held idle (no ongoing I/O processes during insertion/removal)	Same as Level 2	Must remain glitch-free during power-up or power-down	Board bus shared with card bus is "frozen," and there is no toggling activity on bus. It is critical that the logic states set on the bus signal do not get disturbed during card insertion/removal.	Compliant with cards with two levels of staging. I/Os have to be set to hot insertion mode.
4	Hot-swap on an active bus	Yes	Bus may have active I/O processes ongoing, but device being inserted or removed must be idle.	Same as Level 2	Same as Level 3	There is activity on the system bus, and it is critical that the logic states set on the bus signal do not get disturbed during card insertion/removal.	Compliant with cards with two levels of staging. I/Os have to be set to hot insertion mode.

Electrostatic Discharge (ESD) Protection

Fusion devices are tested per JEDEC Standard JESD22-A114-B.

Fusion devices contain clamp diodes at every I/O, global, and power pad. Clamp diodes protect all device pads against damage from ESD as well as from excessive voltage transients.

Each I/O has two clamp diodes. One diode has its positive (P) side connected to the pad and its negative (N) side connected to VCCI. The second diode has its P side connected to GND and its N side connected to the pad. During operation, these diodes are normally biased in the Off state, except when transient voltage is significantly above VCCI or below GND levels.

By selecting the appropriate I/O configuration, the diode is turned on or off. Refer to Table 2-75 and Table 2-76 on page 2-143 for more information about I/O standards and the clamp diode.

The second diode is always connected to the pad, regardless of the I/O configuration selected.

Table 2-75 • **Fusion Standard and Advanced I/O – Hot-Swap and 5 V Input Tolerance Capabilities**

I/O Assignment	Clamp Diode		Hot Insertion		5 V Input Tolerance [1]		Input Buffer	Output Buffer
	Standard I/O	Advanced I/O	Standard I/O	Advanced I/O	Standard I/O	Advanced I/O		
3.3 V LVTTL/LVCMOS	No	Yes	Yes	No	Yes[1]	Yes[1]	Enabled/Disabled	
3.3 V PCI, 3.3 V PCI-X	N/A	Yes	N/A	No	N/A	Yes[1]	Enabled/Disabled	
LVCMOS 2.5 V	No	Yes	Yes	No	No	No	Enabled/Disabled	
LVCMOS 2.5 V / 5.0 V	N/A	Yes	N/A	No	N/A	Yes[2]	Enabled/Disabled	
LVCMOS 1.8 V	No	Yes	Yes	No	No	No	Enabled/Disabled	
LVCMOS 1.5 V	No	Yes	Yes	No	No	No	Enabled/Disabled	
Differential, LVDS/BLVDS/M-LVDS/ LVPECL [3]	N/A	Yes	N/A	No	N/A	No	Enabled/Disabled	

Notes:

1. *Can be implemented with an external IDT bus switch, resistor divider, or Zener with resistor.*
2. *Can be implemented with an external resistor and an internal clamp diode.*
3. *Bidirectional LVPECL buffers are not supported. I/Os can be configured as either input buffers or output buffers.*

Table 2-76 • **Fusion Pro I/O – Hot-Swap and 5 V Input Tolerance Capabilities**

I/O Assignment	Clamp Diode	Hot Insertion	5 V Input Tolerance	Input Buffer	Output Buffer
3.3 V LVTTL/LVCMOS	No	Yes	Yes[1]	Enabled/Disabled	
3.3 V PCI, 3.3 V PCI-X	Yes	No	Yes[1]	Enabled/Disabled	
LVCMOS 2.5 V [3]	No	Yes	No	Enabled/Disabled	
LVCMOS 2.5 V / 5.0 V [3]	Yes	No	Yes[2]	Enabled/Disabled	
LVCMOS 1.8 V	No	Yes	No	Enabled/Disabled	
LVCMOS 1.5 V	No	Yes	No	Enabled/Disabled	
Voltage-Referenced Input Buffer	No	Yes	No	Enabled/Disabled	
Differential, LVDS/BLVDS/M-LVDS/LVPECL[4]	No	Yes	No	Enabled/Disabled	

Notes:

1. *Can be implemented with an external IDT bus switch, resistor divider, or Zener with resistor.*
2. *Can be implemented with an external resistor and an internal clamp diode.*
3. *In the SmartGen, FlashROM, Flash Memory System Builder, and Analog System Builder User Guide, select the LVCMOS5 macro for the LVCMOS 2.5 V / 5.0 V I/O standard or the LVCMOS25 macro for the LVCMOS 2.5 V I/O standard.*
4. *Bidirectional LVPECL buffers are not supported. I/Os can be configured as either input buffers or output buffers.*

Table 2-96 • I/O Output Buffer Maximum Resistances [1] (continued)

Standard	Drive Strength	R$_{PULL-DOWN}$ (ohms) [2]	R$_{PULL-UP}$ (ohms) [3]
Applicable to Standard I/O Banks			
3.3 V LVTTL / 3.3 V LVCMOS	2 mA	100	300
	4 mA	100	300
	6 mA	50	150
	8 mA	50	150
2.5 V LVCMOS	2 mA	100	200
	4 mA	100	200
	6 mA	50	100
	8 mA	50	100
1.8 V LVCMOS	2 mA	200	225
	4 mA	100	112
1.5 V LVCMOS	2 mA	200	224

Notes:

1. *These maximum values are provided for informational reasons only. Minimum output buffer resistance values depend on VCC, drive strength selection, temperature, and process. For board design considerations and detailed output buffer resistances, use the corresponding IBIS models located on the Microsemi SoC Products Group website: http://www.microsemi.com/soc/techdocs/models/ibis.html.*

2. $R_{(PULL-DOWN-MAX)} = VOLspec / I_{OLspec}$

3. $R_{(PULL-UP-MAX)} = (VCCImax – VOHspec) / IOHspec$

Table 2-97 • I/O Weak Pull-Up/Pull-Down Resistances
Minimum and Maximum Weak Pull-Up/Pull-Down Resistance Values

VCCI	R$_{(WEAK PULL-UP)}$[1] (ohms)		R$_{(WEAK PULL-DOWN)}$[2] (ohms)	
	Min.	**Max.**	**Min.**	**Max.**
3.3 V	10 k	45 k	10 k	45 k
2.5 V	11 k	55 k	12 k	74 k
1.8 V	18 k	70 k	17 k	110 k
1.5 V	19 k	90 k	19 k	140 k

Notes:

1. $R_{(WEAK\ PULL-UP-MAX)} = (VCCImax – VOHspec) / I_{WEAK\ PULL-UP-MIN}$

2. $R_{(WEAK\ PULL-DOWN-MAX)} = VOLspec / I_{WEAK\ PULL-DOWN-MIN}$

Table 2-99 • **Short Current Event Duration before Failure**

Temperature	Time Before Failure
–40°C	>20 years
0°C	>20 years
25°C	>20 years
70°C	5 years
85°C	2 years
100°C	6 months

Table 2-100 • **Schmitt Trigger Input Hysteresis**
Hysteresis Voltage Value (typ.) for Schmitt Mode Input Buffers

Input Buffer Configuration	Hysteresis Value (typ.)
3.3 V LVTTL/LVCMOS/PCI/PCI-X (Schmitt trigger mode)	240 mV
2.5 V LVCMOS (Schmitt trigger mode)	140 mV
1.8 V LVCMOS (Schmitt trigger mode)	80 mV
1.5 V LVCMOS (Schmitt trigger mode)	60 mV

Table 2-101 • **I/O Input Rise Time, Fall Time, and Related I/O Reliability**

Input Buffer	Input Rise/Fall Time (min.)	Input Rise/Fall Time (max.)	Reliability
LVTTL/LVCMOS (Schmitt trigger disabled)	No requirement	10 ns*	20 years (100°C)
LVTTL/LVCMOS (Schmitt trigger enabled)	No requirement	No requirement, but input noise voltage cannot exceed Schmitt hysteresis	20 years (100°C)
HSTL/SSTL/GTL	No requirement	10 ns*	10 years (100°C)
LVDS/BLVDS/M-LVDS/LVPECL	No requirement	10 ns*	10 years (100°C)

Note: ** The maximum input rise/fall time is related only to the noise induced into the input buffer trace. If the noise is low, the rise time and fall time of input buffers, when Schmitt trigger is disabled, can be increased beyond the maximum value. The longer the rise/fall times, the more susceptible the input signal is to the board noise. Microsemi recommends signal integrity evaluation/characterization of the system to ensure there is no excessive noise coupling into input signals.*

Table 2-106 • 3.3 V LVTTL / 3.3 V LVCMOS Low Slew
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V,
Worst-Case VCCI = 3.0 V
Applicable to Advanced I/Os

Drive Strength	Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
4 mA	Std.	0.66	10.26	0.04	1.20	0.43	10.45	8.90	2.64	2.46	12.68	11.13	ns
	−1	0.56	8.72	0.04	1.02	0.36	8.89	7.57	2.25	2.09	10.79	9.47	ns
	−2	0.49	7.66	0.03	0.90	0.32	7.80	6.64	1.98	1.83	9.47	8.31	ns
8 mA	Std.	0.66	7.27	0.04	1.20	0.43	7.41	6.28	2.98	3.04	9.65	8.52	ns
	−1	0.56	6.19	0.04	1.02	0.36	6.30	5.35	2.54	2.59	8.20	7.25	ns
	−2	0.49	5.43	0.03	0.90	0.32	5.53	4.69	2.23	2.27	7.20	6.36	ns
12 mA	Std.	0.66	5.58	0.04	1.20	0.43	5.68	4.87	3.21	3.42	7.92	7.11	ns
	−1	0.56	4.75	0.04	1.02	0.36	4.84	4.14	2.73	2.91	6.74	6.05	ns
	−2	0.49	4.17	0.03	0.90	0.32	4.24	3.64	2.39	2.55	5.91	5.31	ns
16 mA	Std.	0.66	5.21	0.04	1.20	0.43	5.30	4.56	3.26	3.51	7.54	6.80	ns
	−1	0.56	4.43	0.04	1.02	0.36	4.51	3.88	2.77	2.99	6.41	5.79	ns
	−2	0.49	3.89	0.03	0.90	0.32	3.96	3.41	2.43	2.62	5.63	5.08	ns
24 mA	Std.	0.66	4.85	0.04	1.20	0.43	4.94	4.54	3.32	3.88	7.18	6.78	ns
	−1	0.56	4.13	0.04	1.02	0.36	4.20	3.87	2.82	3.30	6.10	5.77	ns
	−2	0.49	3.62	0.03	0.90	0.32	3.69	3.39	2.48	2.90	5.36	5.06	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

SSTL3 Class II

Stub-Speed Terminated Logic for 3.3 V memory bus standard (JESD8-8). Fusion devices support Class II. This provides a differential amplifier input buffer and a push-pull output buffer.

Table 2-165 • **Minimum and Maximum DC Input and Output Levels**

SSTL3 Class II	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL[1]	IIH[2]
	Min.	Max.	Min.	Max.	Max.	Min.			Max.	Max.		
Drive Strength	V	V	V	V	V	V	mA	mA	mA[3]	mA[3]	μA[4]	μA[4]
21 mA	–0.3	VREF – 0.2	VREF + 0.2	3.6	0.5	VCCI – 0.9	21	21	109	103	10	10

Notes:

1. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*

2. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*

3. *Currents are measured at high temperature (100°C junction temperature) and maximum voltage.*
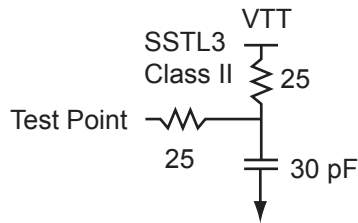
4. *Currents are measured at 85°C junction temperature.*

Figure 2-133 • **AC Loading**

Table 2-166 • **AC Waveforms, Measuring Points, and Capacitive Loads**

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C_{LOAD} (pF)
VREF – 0.2	VREF + 0.2	1.5	1.5	1.485	30

Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.

Timing Characteristics

Table 2-167 • **SSTL3- Class II**
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V, VREF = 1.5 V

Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
Std.	0.66	2.07	0.04	1.25	0.43	2.10	1.67			4.34	3.91	ns
–1	0.56	1.76	0.04	1.06	0.36	1.79	1.42			3.69	3.32	ns
–2	0.49	1.54	0.03	0.93	0.32	1.57	1.25			3.24	2.92	ns

Note: *For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.*

XTAL2   **Crystal Oscillator Circuit Input**

Input to crystal oscillator circuit. Pin for connecting external crystal, ceramic resonator, RC network, or external clock input. When using an external crystal or ceramic oscillator, external capacitors are also recommended (Please refer to the crystal oscillator manufacturer for proper capacitor value).

If using external RC network or clock input, XTAL1 should be used and XTAL2 left unconnected. In the case where the Crystal Oscillator block is not used, the XTAL1 pin should be connected to GND and the XTAL2 pin should be left floating.

Security

Fusion devices have a built-in 128-bit AES decryption core. The decryption core facilitates highly secure, in-system programming of the FPGA core array fabric and the FlashROM. The FlashROM and the FPGA core fabric can be programmed independently from each other, allowing the FlashROM to be updated without the need for change to the FPGA core fabric. The AES master key is stored in on-chip nonvolatile memory (flash). The AES master key can be preloaded into parts in a security-protected programming environment (such as the Microsemi in-house programming center), and then "blank" parts can be shipped to an untrusted programming or manufacturing center for final personalization with an AES-encrypted bitstream. Late stage product changes or personalization can be implemented easily and with high level security by simply sending a STAPL file with AES-encrypted data. Highly secure remote field updates over public networks (such as the Internet) are possible by sending and programming a STAPL file with AES-encrypted data. For more information, refer to the *Fusion Security* application note.

128-Bit AES Decryption

The 128-bit AES standard (FIPS-197) block cipher is the National Institute of Standards and Technology (NIST) replacement for DES (Data Encryption Standard FIPS46-2). AES has been designed to protect sensitive government information well into the 21st century. It replaces the aging DES, which NIST adopted in 1977 as a Federal Information Processing Standard used by federal agencies to protect sensitive, unclassified information. The 128-bit AES standard has 3.4×10^{38} possible 128-bit key variants, and it has been estimated that it would take 1,000 trillion years to crack 128-bit AES cipher text using exhaustive techniques. Keys are stored (protected with security) in Fusion devices in nonvolatile flash memory. All programming files sent to the device can be authenticated by the part prior to programming to ensure that bad programming data is not loaded into the part that may possibly damage it. All programming verification is performed on-chip, ensuring that the contents of Fusion devices remain as secure as possible.

AES decryption can also be used on the 1,024-bit FlashROM to allow for remote updates of the FlashROM contents. This allows for easy support of subscription model products and protects them with measures designed to provide the highest level of security available. See the application note *Fusion Security* for more details.

AES for Flash Memory

AES decryption can also be used on the flash memory blocks. This provides the best available security during update of the flash memory blocks. During runtime, the encrypted data can be clocked in via the JTAG interface. The data can be passed through the internal AES decryption engine, and the decrypted data can then be stored in the flash memory block.

Programming

Programming can be performed using various programming tools, such as Silicon Sculptor II (BP Micro Systems) or FlashPro3 (Microsemi).

The user can generate STP programming files from the Designer software and can use these files to program a device.

Fusion devices can be programmed in-system. During programming, VCCOSC is needed in order to power the internal 100 MHz oscillator. This oscillator is used as a source for the 20 MHz oscillator that is used to drive the charge pump for programming.

Power per I/O Pin

Table 3-12 • **Summary of I/O Input Buffer Power (per pin)—Default I/O Software Settings**

	VCCI (V)	Static Power PDC7 (mW)[1]	Dynamic Power PAC9 (µW/MHz)[2]
Applicable to Pro I/O Banks			
Single-Ended			
3.3 V LVTTL/LVCMOS	3.3	–	17.39
3.3 V LVTTL/LVCMOS – Schmitt trigger	3.3	–	25.51
2.5 V LVCMOS	2.5	–	5.76
2.5 V LVCMOS – Schmitt trigger	2.5	–	7.16
1.8 V LVCMOS	1.8	–	2.72
1.8 V LVCMOS – Schmitt trigger	1.8	–	2.80
1.5 V LVCMOS (JESD8-11)	1.5	–	2.08
1.5 V LVCMOS (JESD8-11) – Schmitt trigger	1.5	–	2.00
3.3 V PCI	3.3	–	18.82
3.3 V PCI – Schmitt trigger	3.3	–	20.12
3.3 V PCI-X	3.3	–	18.82
3.3 V PCI-X – Schmitt trigger	3.3	–	20.12
Voltage-Referenced			
3.3 V GTL	3.3	2.90	8.23
2.5 V GTL	2.5	2.13	4.78
3.3 V GTL+	3.3	2.81	4.14
2.5 V GTL+	2.5	2.57	3.71
HSTL (I)	1.5	0.17	2.03
HSTL (II)	1.5	0.17	2.03
SSTL2 (I)	2.5	1.38	4.48
SSTL2 (II)	2.5	1.38	4.48
SSTL3 (I)	3.3	3.21	9.26
SSTL3 (II)	3.3	3.21	9.26
Differential			
LVDS	2.5	2.26	1.50
LVPECL	3.3	5.71	2.17

Notes:

1. PDC7 is the static power (where applicable) measured on VCCI.

2. PAC9 is the total dynamic power measured on VCC and VCCI.

Table 3-13 • **Summary of I/O Output Buffer Power (per pin)—Default I/O Software Settings[1] (continued)**

	C$_{LOAD}$ (pF)	VCCI (V)	Static Power PDC8 (mW)[2]	Dynamic Power PAC10 (µW/MHz)[3]
Differential				
LVDS	–	2.5	7.74	88.92
LVPECL	–	3.3	19.54	166.52
Applicable to Standard I/O Banks				
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	35	3.3	–	431.08
2.5 V LVCMOS	35	2.5	–	247.36
1.8 V LVCMOS	35	1.8	–	128.46
1.5 V LVCMOS (JESD8-11)	35	1.5	–	89.46

Notes:

1. *Dynamic power consumption is given for standard load and software-default drive strength and output slew.*
2. *PDC8 is the static power (where applicable) measured on VCCI.*
3. *PAC10 is the total dynamic power measured on VCC and VCCI.*

FG256			
Pin Number	AFS090 Function	AFS250 Function	AFS600 Function	AFS1500 Function
C7	IO09RSB0V0	IO12RSB0V0	IO06NDB0V0	IO09NDB0V1
C8	IO14RSB0V0	IO22RSB0V0	IO16PDB1V0	IO23PDB1V0
C9	IO15RSB0V0	IO23RSB0V0	IO16NDB1V0	IO23NDB1V0
C10	IO22RSB0V0	IO30RSB0V0	IO25NDB1V1	IO31NDB1V1
C11	IO20RSB0V0	IO31RSB0V0	IO25PDB1V1	IO31PDB1V1
C12	VCCIB0	VCCIB0	VCCIB1	VCCIB1
C13	GBB1/IO28RSB0V0	GBC1/IO35RSB0V0	GBC1/IO26PPB1V1	GBC1/IO40PPB1V2
C14	VCCIB1	VCCIB1	VCCIB2	VCCIB2
C15	GND	GND	GND	GND
C16	VCCIB1	VCCIB1	VCCIB2	VCCIB2
D1	GFC2/IO50NPB3V0	IO75NDB3V0	IO84NDB4V0	IO124NDB4V0
D2	GFA2/IO51NDB3V0	GAB2/IO75PDB3V0	GAB2/IO84PDB4V0	GAB2/IO124PDB4V0
D3	GAC2/IO51PDB3V0	IO76NDB3V0	IO85NDB4V0	IO125NDB4V0
D4	GAA2/IO52PDB3V0	GAA2/IO76PDB3V0	GAA2/IO85PDB4V0	GAA2/IO125PDB4V0
D5	GAB2/IO52NDB3V0	GAB0/IO02RSB0V0	GAB0/IO02NPB0V0	GAB0/IO02NPB0V0
D6	GAC0/IO04RSB0V0	GAC0/IO04RSB0V0	GAC0/IO03NDB0V0	GAC0/IO03NDB0V0
D7	IO08RSB0V0	IO13RSB0V0	IO06PDB0V0	IO09PDB0V1
D8	NC	IO20RSB0V0	IO14NDB0V1	IO15NDB0V2
D9	NC	IO21RSB0V0	IO14PDB0V1	IO15PDB0V2
D10	IO21RSB0V0	IO28RSB0V0	IO23PDB1V1	IO37PDB1V2
D11	IO23RSB0V0	GBB0/IO36RSB0V0	GBB0/IO27NDB1V1	GBB0/IO41NDB1V2
D12	NC	NC	VCCIB1	VCCIB1
D13	GBA2/IO31PDB1V0	GBA2/IO40PDB1V0	GBA2/IO30PDB2V0	GBA2/IO44PDB2V0
D14	GBB2/IO31NDB1V0	IO40NDB1V0	IO30NDB2V0	IO44NDB2V0
D15	GBC2/IO32PDB1V0	GBB2/IO41PDB1V0	GBB2/IO31PDB2V0	GBB2/IO45PDB2V0
D16	GCA2/IO32NDB1V0	IO41NDB1V0	IO31NDB2V0	IO45NDB2V0
E1	GND	GND	GND	GND
E2	GFB0/IO48NPB3V0	IO73NDB3V0	IO81NDB4V0	IO118NDB4V0
E3	GFB2/IO50PPB3V0	IO73PDB3V0	IO81PDB4V0	IO118PDB4V0
E4	VCCIB3	VCCIB3	VCCIB4	VCCIB4
E5	NC	IO74NPB3V0	IO83NPB4V0	IO123NPB4V0
E6	NC	IO08RSB0V0	IO04NPB0V0	IO05NPB0V1
E7	GND	GND	GND	GND
E8	NC	IO18RSB0V0	IO08PDB0V1	IO11PDB0V1
E9	NC	NC	IO20NDB1V0	IO27NDB1V1
E10	GND	GND	GND	GND
E11	IO24RSB0V0	GBB1/IO37RSB0V0	GBB1/IO27PDB1V1	GBB1/IO41PDB1V2
E12	NC	IO50PPB1V0	IO33PSB2V0	IO48PSB2V0