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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Obsolete
Number of LABs/CLBs	-
Number of Logic Elements/Cells	-
Total RAM Bits	110592
Number of I/O	95
Number of Gates	600000
Voltage - Supply	1.425V ~ 1.575V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	208-BFQFP
Supplier Device Package	208-PQFP (28x28)
Purchase URL	https://www.e-xfl.com/product-detail/microsemi/m1afs600-2pq208

Temperature Grade Offerings

Fusion Devices	AFS090	AFS250	AFS600	AFS1500
ARM Cortex-M1 Devices		M1AFS250	M1AFS600	M1AFS1500
Pigeon Point Devices			P1AFS600 [3]	P1AFS1500 [3]
MicroBlade Devices		U1AFS250 [4]	U1AFS600 [4]	U1AFS1500 [4]
QN108 [5]	C, I	–	–	–
QN180 [5]	C, I	C, I	–	–
PQ208	–	C, I	C, I	–
FG256	C, I	C, I	C, I	C, I
FG484	–	–	C, I	C, I
FG676	–	–	–	C, I

Notes:
1. *C = Commercial Temperature Range: 0°C to 85°C Junction*
2. *I = Industrial Temperature Range: –40°C to 100°C Junction*
3. *Pigeon Point devices are only offered in FG484 and FG256.*
4. *MicroBlade devices are only offered in FG256.*
5. *Package not available.*

Speed Grade and Temperature Grade Matrix

	Std.[1]	–1	–2[2]
C[3]	✓	✓	✓
I[4]	✓	✓	✓

Notes:
1. *MicroBlade devices are only offered in standard speed grade.*
2. *Pigeon Point devices are only offered in –2 speed grade.*
3. *C = Commercial Temperature Range: 0°C to 85°C Junction*
4. *I = Industrial Temperature Range: –40°C to 100°C Junction*

Contact your local Microsemi SoC Products Group representative for device availability:

http://www.microsemi.com/index.php?option=com_content&id=137&lang=en&view=article.

Cortex-M1, Pigeon Point, and MicroBlade Fusion Device Information

This datasheet provides information for all Fusion (AFS), Cortex-M1 (M1), Pigeon Point (P1), and MicroBlade (U1) devices. The remainder of the document will only list the Fusion (AFS) devices. Please apply relevant information to M1, P1, and U1 devices when appropriate. Please note the following:

- Cortex-M1 devices are offered in the same speed grades and packages as basic Fusion devices.
- Pigeon Point devices are only offered in –2 speed grade and FG484 and FG256 packages.
- MicroBlade devices are only offered in standard speed grade and the FG256 package.

Instant On

Flash-based Fusion devices are Level 0 Instant On. Instant On Fusion devices greatly simplify total system design and reduce total system cost by eliminating the need for CPLDs. The Fusion Instant On clocking (PLLs) replaces off-chip clocking resources. The Fusion mix of Instant On clocking and analog resources makes these devices an excellent choice for both system supervisor and system management functions. Instant On from a single 3.3 V source enables Fusion devices to initiate, control, and monitor multiple voltage supplies while also providing system clocks. In addition, glitches and brownouts in system power will not corrupt the Fusion device flash configuration. Unlike SRAM-based FPGAs, the device will not have to be reloaded when system power is restored. This enables reduction or complete removal of expensive voltage monitor and brownout detection devices from the PCB design.
Flash-based Fusion devices simplify total system design and reduce cost and design risk, while increasing system reliability.

Firm Errors

Firm errors occur most commonly when high-energy neutrons, generated in the upper atmosphere, strike a configuration cell of an SRAM FPGA. The energy of the collision can change the state of the configuration cell and thus change the logic, routing, or I/O behavior in an unpredictable way. Another source of radiation-induced firm errors is alpha particles. For an alpha to cause a soft or firm error, its source must be in very close proximity to the affected circuit. The alpha source must be in the package molding compound or in the die itself. While low-alpha molding compounds are being used increasingly, this helps reduce but does not entirely eliminate alpha-induced firm errors.

Firm errors are impossible to prevent in SRAM FPGAs. The consequence of this type of error can be a complete system failure. Firm errors do not occur in Fusion flash-based FPGAs. Once it is programmed, the flash cell configuration element of Fusion FPGAs cannot be altered by high-energy neutrons and is therefore immune to errors from them.

Recoverable (or soft) errors occur in the user data SRAMs of all FPGA devices. These can easily be mitigated by using error detection and correction (EDAC) circuitry built into the FPGA fabric.

Low Power

Flash-based Fusion devices exhibit power characteristics similar to those of an ASIC, making them an ideal choice for power-sensitive applications. With Fusion devices, there is no power-on current surge and no high current transition, both of which occur on many FPGAs.

Fusion devices also have low dynamic power consumption and support both low power standby mode and very low power sleep mode, offering further power savings.

Advanced Flash Technology

The Fusion family offers many benefits, including nonvolatility and reprogrammability through an advanced flash-based, 130-nm LVCMOS process with seven layers of metal. Standard CMOS design techniques are used to implement logic and control functions. The combination of fine granularity, enhanced flexible routing resources, and abundant flash switches allows very high logic utilization (much higher than competing SRAM technologies) without compromising device routability or performance. Logic functions within the device are interconnected through a four-level routing hierarchy.

To initiate a current measurement, the appropriate Current Monitor Strobe (CMSTB) signal on the AB macro must be asserted low for at least t_{CMSLO} in order to discharge the previous measurement. Then CMSTB must be asserted high for at least t_{CMSET} prior to asserting the ADCSTART signal. The CMSTB must remain high until after the SAMPLE signal is de-asserted by the AB macro. Note that the minimum sample time cannot be less than t_{CMSHI}. Figure 2-71 shows the timing diagram of CMSTB in relationship with the ADC control signals.

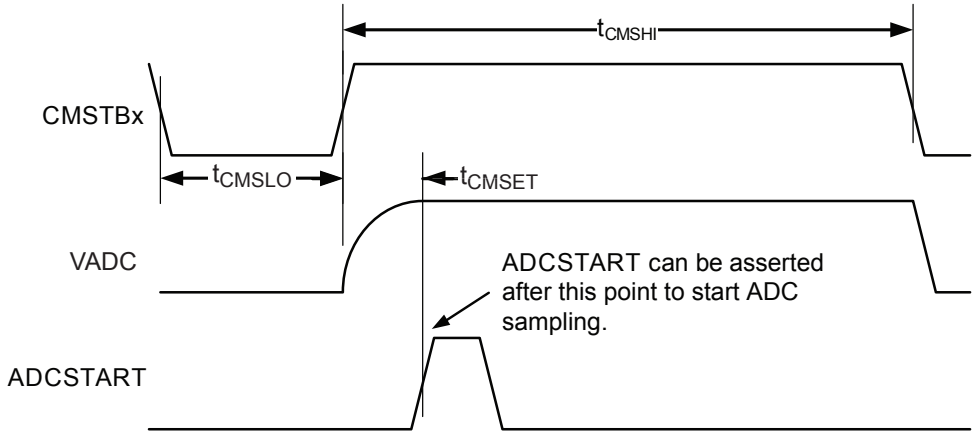


Figure 2-71 • **Timing Diagram for Current Monitor Strobe**

Figure 2-72 illustrates positive current monitor operation. The differential voltage between AV and AC goes into the 10× amplifier and is then converted by the ADC. For example, a current of 1.5 A is drawn from a 10 V supply and is measured by the voltage drop across a 0.050 Ω sense resistor, The voltage drop is amplified by ten times by the amplifier and then measured by the ADC. The 1.5 A current creates a differential voltage across the sense resistor of 75 mV. This becomes 750 mV after amplification. Thus, the ADC measures a current of 1.5 A as 750 mV. Using an ADC with 8-bit resolution and VAREF of 2.56 V, the ADC result is decimal 75. EQ 3 shows how to compute the current from the ADC result.

$$|I| = (ADC \times V_{AREF}) / (10 \times 2^{N} \times R_{sense})$$

EQ 3

where

I is the current flowing through the sense resistor

ADC is the result from the ADC

VAREF is the Reference voltage

N is the number of bits

Rsense is the resistance of the sense resistor

Gate Driver

The Fusion Analog Quad includes a Gate Driver connected to the Quad's AG pin (Figure 2-74). Designed to work with external p- or n-channel MOSFETs, the Gate driver is a configurable current sink or source and requires an external pull-up or pull-down resistor. The AG supports 4 selectable gate drive levels: 1 µA, 3 µA, 10 µA, and 30 µA (Figure 2-75 on page 2-91). The AG also supports a High Current Drive mode in which it can sink 20 mA; in this mode the switching rate is approximately 1.3 MHz with 100 ns turn-on time and 600 ns turn-off time. Modeled on an open-drain-style output, it does not output a voltage level without an appropriate pull-up or pull-down resistor. If 1 V is forced on the drain, the current sinking/sourcing will exceed the ability of the transistor, and the device could be damaged.

The AG pad is turned on via the corresponding GDON*x* pin in the Analog Block macro, where *x* is the number of the corresponding Analog Quad for the AG pad to be enabled (GDON0 to GDON9).

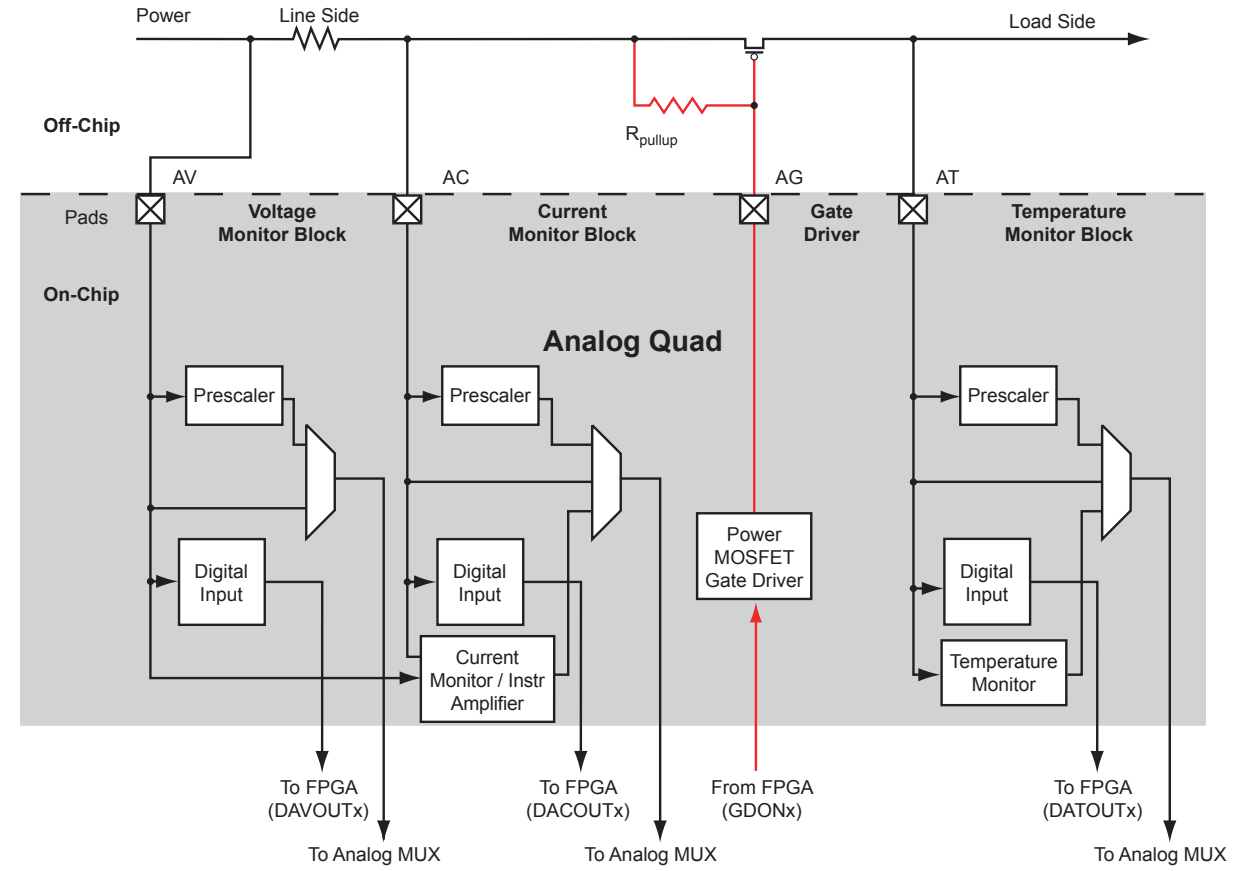


Figure 2-74 • **Gate Driver**

The gate-to-source voltage (V_{gs}) of the external MOSFET is limited to the programmable drive current times the external pull-up or pull-down resistor value (EQ 5).

$$V_{gs} \le I_g \times (R_{pullup} \text{ or } R_{pulldown})$$

EQ 5

Integrated Voltage Reference

The Fusion device has an integrated on-chip 2.56 V reference voltage for the ADC. The value of this reference voltage was chosen to make the prescaling and postscaling factors for the prescaler blocks change in a binary fashion. However, if desired, an external reference voltage of up to 3.3 V can be connected between the VAREF and ADCGNDREF pins. The VAREFSEL control pin is used to select the reference voltage.

Table 2-42 • VAREF Bit Function

Name	Bit	Function
VAREF	0	Reference voltage selection 0 – Internal voltage reference selected. VAREF pin outputs 2.56 V. 1 – Input external voltage reference from VAREF and ADCGNDREF

ADC Clock

The speed of the ADC depends on its internal clock, ADCCLK, which is not accessible to users. The ADCCLK is derived from SYSCLK. Input signal TVC[7:0], Time Divider Control, determines the speed of the ADCCLK in relationship to SYSCLK, based on EQ 15.

$$t_{ADCCLK} = 4 \times (1 + TVC) \times t_{SYSCLK}$$

EQ 15

TVC: Time Divider Control (0–255)

t_{ADCCLK} is the period of ADCCLK, and must be between 0.5 MHz and 10 MHz

t_{SYSCLK} is the period of SYSCLK

Table 2-43 • TVC Bits Function

Name	Bits	Function
TVC	[7:0]	SYSCLK divider control

The frequency of ADCCLK, f_{ADCCLK}, must be within 0.5 Hz to 10 MHz.

The inputs to the ADC are synchronized to SYSCLK. A conversion is initiated by asserting the ADCSTART signal on a rising edge of SYSCLK. Figure 2-90 on page 2-112 and Figure 2-91 on page 2-112 show the timing diagram for the ADC.

Acquisition Time or Sample Time Control

Acquisition time (t_{SAMPLE}) specifies how long an analog input signal has to charge the internal capacitor array. Figure 2-88 shows a simplified internal input sampling mechanism of a SAR ADC.

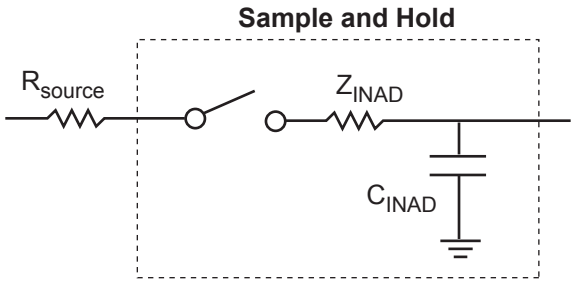


Figure 2-88 • Simplified Sample and Hold Circuitry

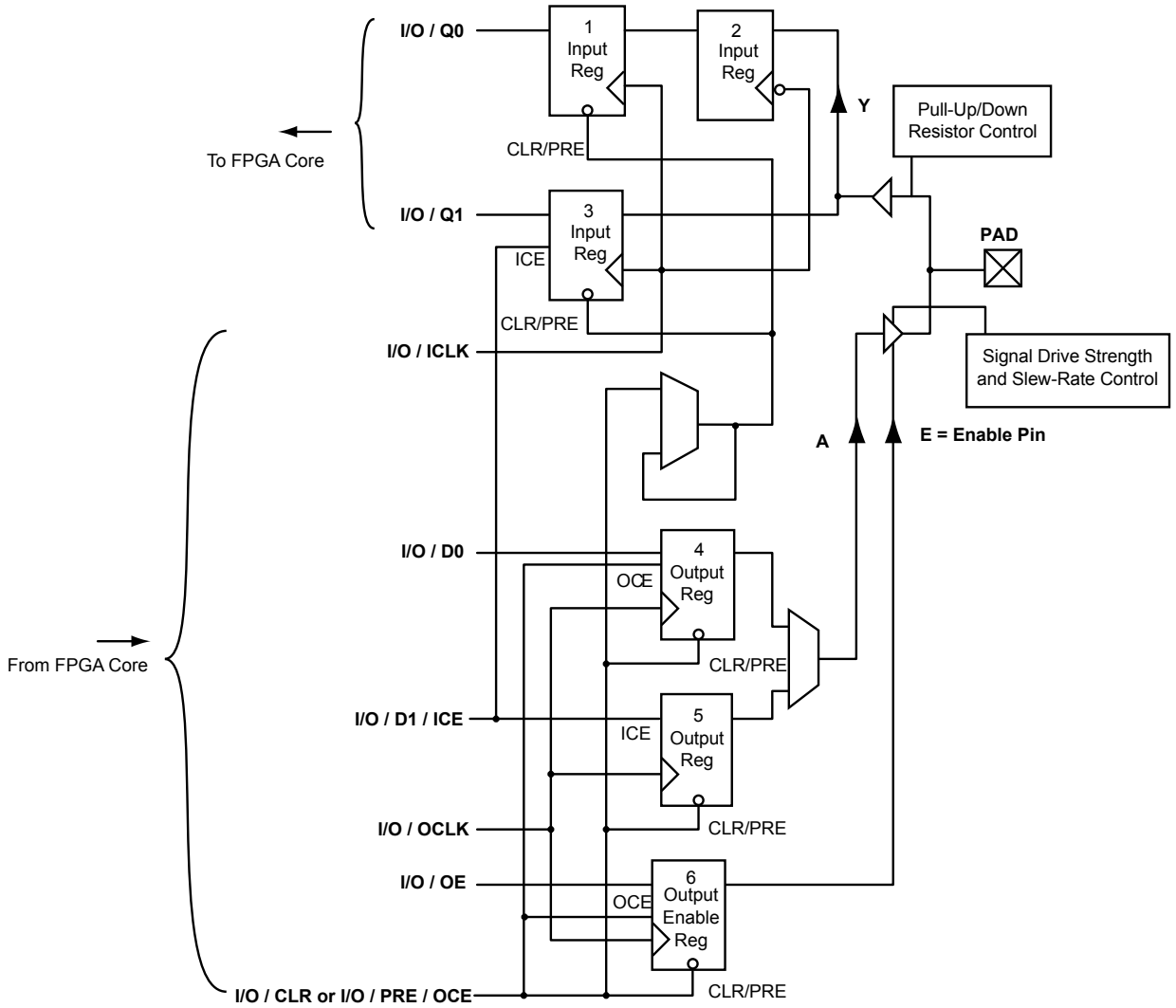
The internal impedance (Z_{INAD}), external source resistance (R_{SOURCE}), and sample capacitor (C_{INAD}) form a simple RC network. As a result, the accuracy of the ADC can be affected if the ADC is given insufficient time to charge the capacitor. To resolve this problem, you can either reduce the source resistance or increase the sampling time by changing the acquisition time using the STC signal.

I/O Registers

Each I/O module contains several input, output, and enable registers. Refer to Figure 2-100 for a simplified representation of the I/O block.

The number of input registers is selected by a set of switches (not shown in Figure 2-100) between registers to implement single or differential data transmission to and from the FPGA core. The Designer software sets these switches for the user.

A common CLR/PRE signal is employed by all I/O registers when I/O register combining is used. Input register 2 does not have a CLR/PRE pin, as this register is used for DDR implementation. The I/O register combining must satisfy some rules.



Note: Fusion I/Os have registers to support DDR functionality (see the "Double Data Rate (DDR) Support" section on page 2-139 for more information).

Figure 2-100 • **I/O Block Logical Representation**

Timing Characteristics

Table 2-120 • 1.8 V LVCMOS Low Slew
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.7 V
Applicable to Pro I/Os

Drive Strength	Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{PYS}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
2 mA	Std.	0.66	15.84	0.04	1.45	1.91	0.43	15.65	15.84	2.78	1.58	17.89	18.07	ns
	–1	0.56	13.47	0.04	1.23	1.62	0.36	13.31	13.47	2.37	1.35	15.22	15.37	ns
	–2	0.49	11.83	0.03	1.08	1.42	0.32	11.69	11.83	2.08	1.18	13.36	13.50	ns
4 mA	Std.	0.66	11.39	0.04	1.45	1.91	0.43	11.60	10.76	3.26	2.77	13.84	12.99	ns
	–1	0.56	9.69	0.04	1.23	1.62	0.36	9.87	9.15	2.77	2.36	11.77	11.05	ns
	–2	0.49	8.51	0.03	1.08	1.42	0.32	8.66	8.03	2.43	2.07	10.33	9.70	ns
8 mA	Std.	0.66	8.97	0.04	1.45	1.91	0.43	9.14	8.10	3.57	3.36	11.37	10.33	ns
	–1	0.56	7.63	0.04	1.23	1.62	0.36	7.77	6.89	3.04	2.86	9.67	8.79	ns
	–2	0.49	6.70	0.03	1.08	1.42	0.32	6.82	6.05	2.66	2.51	8.49	7.72	ns
12 mA	Std.	0.66	8.35	0.04	1.45	1.91	0.43	8.50	7.59	3.64	3.52	10.74	9.82	ns
	–1	0.56	7.10	0.04	1.23	1.62	0.36	7.23	6.45	3.10	3.00	9.14	8.35	ns
	–2	0.49	6.24	0.03	1.08	1.42	0.32	6.35	5.66	2.72	2.63	8.02	7.33	ns
16 mA	Std.	0.66	7.94	0.04	1.45	1.91	0.43	8.09	7.56	3.74	4.11	10.32	9.80	ns
	–1	0.56	6.75	0.04	1.23	1.62	0.36	6.88	6.43	3.18	3.49	8.78	8.33	ns
	–2	0.49	5.93	0.03	1.08	1.42	0.32	6.04	5.65	2.79	3.07	7.71	7.32	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

2.5 V GTL

Gunning Transceiver Logic is a high-speed bus standard (JESD8-3). It provides a differential amplifier input buffer and an open-drain output buffer. The VCCI pin should be connected to 2.5 V.

Table 2-141 • Minimum and Maximum DC Input and Output Levels

2.5 GTL	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL[1]	IIH[2]
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA[3]	Max. mA[3]	µA[4]	µA[4]
20 mA[3]	–0.3	VREF – 0.05	VREF + 0.05	3.6	0.4	–	20	20	124	169	10	10

Notes:

1. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*
2. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*
3. *Currents are measured at high temperature (100°C junction temperature) and maximum voltage.*
4. *Currents are measured at 85°C junction temperature.*

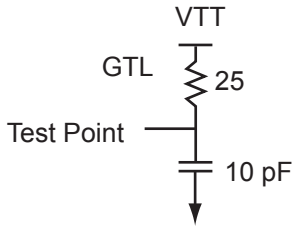


Figure 2-125 • AC Loading

Table 2-142 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C_{LOAD} (pF)
VREF – 0.05	VREF + 0.05	0.8	0.8	1.2	10

*Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.*

Timing Characteristics

Table 2-143 • 2.5 V GTL
Commercial Temperature Range Conditions: TJ = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 3.0 V, VREF = 0.8 V

Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
Std.	0.66	2.13	0.04	2.46	0.43	2.16	2.13			4.40	4.36	ns
–1	0.56	1.81	0.04	2.09	0.36	1.84	1.81			3.74	3.71	ns
–2	0.49	1.59	0.03	1.83	0.32	1.61	1.59			3.28	3.26	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

HSTL Class I

High-Speed Transceiver Logic is a general-purpose high-speed 1.5 V bus standard (EIA/JESD8-6). Fusion devices support Class I. This provides a differential amplifier input buffer and a push-pull output buffer.

Table 2-150 • Minimum and Maximum DC Input and Output Levels

HSTL Class I	VIL		VIH		VOL	VOH	IOL	IOH	IOSL	IOSH	IIL[1]	IIH[2]
Drive Strength	Min. V	Max. V	Min. V	Max. V	Max. V	Min. V	mA	mA	Max. mA[3]	Max. mA[3]	µA[4]	µA[4]
8 mA	–0.3	VREF – 0.1	VREF + 0.1	3.6	0.4	VCCI – 0.4	8	8	39	32	10	10

Notes:

1. *IIL is the input leakage current per I/O pin over recommended operation conditions where –0.3 V < VIN < VIL.*
2. *IIH is the input leakage current per I/O pin over recommended operating conditions VIH < VIN < VCCI. Input current is larger when operating outside recommended ranges.*
3. *Currents are measured at high temperature (100°C junction temperature) and maximum voltage.*
4. *Currents are measured at 85°C junction temperature.*

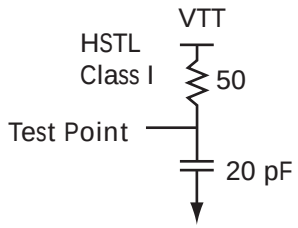


Figure 2-128 • AC Loading

Table 2-151 • AC Waveforms, Measuring Points, and Capacitive Loads

Input Low (V)	Input High (V)	Measuring Point* (V)	VREF (typ.) (V)	VTT (typ.) (V)	C_{LOAD} (pF)
VREF – 0.1	VREF + 0.1	0.75	0.75	0.75	20

*Note: *Measuring point = Vtrip. See Table 2-90 on page 2-166 for a complete table of trip points.*

Timing Characteristics

Table 2-152 • HSTL Class I
Commercial Temperature Range Conditions: T_J = 70°C, Worst-Case VCC = 1.425 V, Worst-Case VCCI = 1.4 V, VREF = 0.75 V

Speed Grade	t_{DOUT}	t_{DP}	t_{DIN}	t_{PY}	t_{EOUT}	t_{ZL}	t_{ZH}	t_{LZ}	t_{HZ}	t_{ZLS}	t_{ZHS}	Units
Std.	0.66	3.18	0.04	2.12	0.43	3.24	3.14			5.47	5.38	ns
–1	0.56	2.70	0.04	1.81	0.36	2.75	2.67			4.66	4.58	ns
–2	0.49	2.37	0.03	1.59	0.32	2.42	2.35			4.09	4.02	ns

Note: For the derating values at specific junction temperature and voltage supply levels, refer to Table 3-7 on page 3-9.

Table 3-2 • **Recommended Operating Conditions**[1]

Symbol	Parameter[2]		Commercial	Industrial	Units
T_J	Junction temperature		0 to +85	–40 to +100	°C
VCC	1.5 V DC core supply voltage		1.425 to 1.575	1.425 to 1.575	V
VJTAG	JTAG DC voltage		1.4 to 3.6	1.4 to 3.6	V
VPUMP	Programming voltage	Programming mode[3]	3.15 to 3.45	3.15 to 3.45	V
		Operation[4]	0 to 3.6	0 to 3.6	V
VCCPLL	Analog power supply (PLL)		1.425 to 1.575	1.425 to 1.575	V
VCCI	1.5 V DC supply voltage		1.425 to 1.575	1.425 to 1.575	V
	1.8 V DC supply voltage		1.7 to 1.9	1.7 to 1.9	V
	2.5 V DC supply voltage		2.3 to 2.7	2.3 to 2.7	V
	3.3 V DC supply voltage		3.0 to 3.6	3.0 to 3.6	V
	LVDS differential I/O		2.375 to 2.625	2.375 to 2.625	V
	LVPECL differential I/O		3.0 to 3.6	3.0 to 3.6	V
VCC33A	+3.3 V power supply		2.97 to 3.63	2.97 to 3.63	V
VCC33PMP	+3.3 V power supply		2.97 to 3.63	2.97 to 3.63	V
VAREF	Voltage reference for ADC		2.527 to 2.593	2.527 to 2.593	V
VCC15A [5]	Digital power supply for the analog system		1.425 to 1.575	1.425 to 1.575	V
VCCNVM	Embedded flash power supply		1.425 to 1.575	1.425 to 1.575	V
VCCOSC	Oscillator power supply		2.97 to 3.63	2.97 to 3.63	V
AV, AC [6]	Unpowered, ADC reset asserted or unconfigured		–10.5 to 12.0	–10.5 to 11.6	V
	Analog input (+16 V to +2 V prescaler range)		–0.3 to 12.0	–0.3 to 11.6	V
	Analog input (+1 V to + 0.125 V prescaler range)		–0.3 to 3.6	–0.3 to 3.6	V
	Analog input (–16 V to –2 V prescaler range)		–10.5 to 0.3	–10.5 to 0.3	V
	Analog input (–1 V to –0.125 V prescaler range)		–3.6 to 0.3	–3.6 to 0.3	V
	Analog input (direct input to ADC)		–0.3 to 3.6	–0.3 to 3.6	V
	Digital input		–0.3 to 12.0	–0.3 to 11.6	V
AG [6]	Unpowered, ADC reset asserted or unconfigured		–10.5 to 12.0	–10.5 to 11.6	V
	Low Current Mode (1 µA, 3 µA, 10 µA, 30 µA)		–0.3 to 12.0	–0.3 to 11.6	V
	Low Current Mode (–1 µA, –3 µA, –10 µA, –30 µA)		–10.5 to 0.3	–10.5 to 0.3	V
	High Current Mode [7]		–10.5 to 12.0	–10.5 to 11.6	V
AT [6]	Unpowered, ADC reset asserted or unconfigured		–0.3 to 15.5	–0.3 to 14.5	V
	Analog input (+16 V, +4 V prescaler range)		–0.3 to 15.5	–0.3 to 14.5	V
	Analog input (direct input to ADC)		–0.3 to 3.6	–0.3 to 3.6	V
	Digital input		–0.3 to 15.5	–0.3 to 14.5	V

Notes:

1. *The ranges given here are for power supplies only. The recommended input voltage ranges specific to each I/O standard are given in Table 2-85 on page 2-157.*
2. *All parameters representing voltages are measured with respect to GND unless otherwise specified.*
3. *The programming temperature range supported is $T_{ambient}$ = 0°C to 85°C.*
4. *VPUMP can be left floating during normal operation (not programming mode).*
5. *Violating the V_{CC15A} recommended voltage supply during an embedded flash program cycle can corrupt the page being programmed.*
6. *The input voltage may overshoot by up to 500 mV above the Recommended Maximum (150 mV in Direct mode), provided the duration of the overshoot is less than 50% of the operating lifetime of the device.*
7. *The AG pad should also conform to the limits as specified in Table 2-48 on page 2-114.*

Table 3-13 • **Summary of I/O Output Buffer Power (per pin)—Default I/O Software Settings[1]**

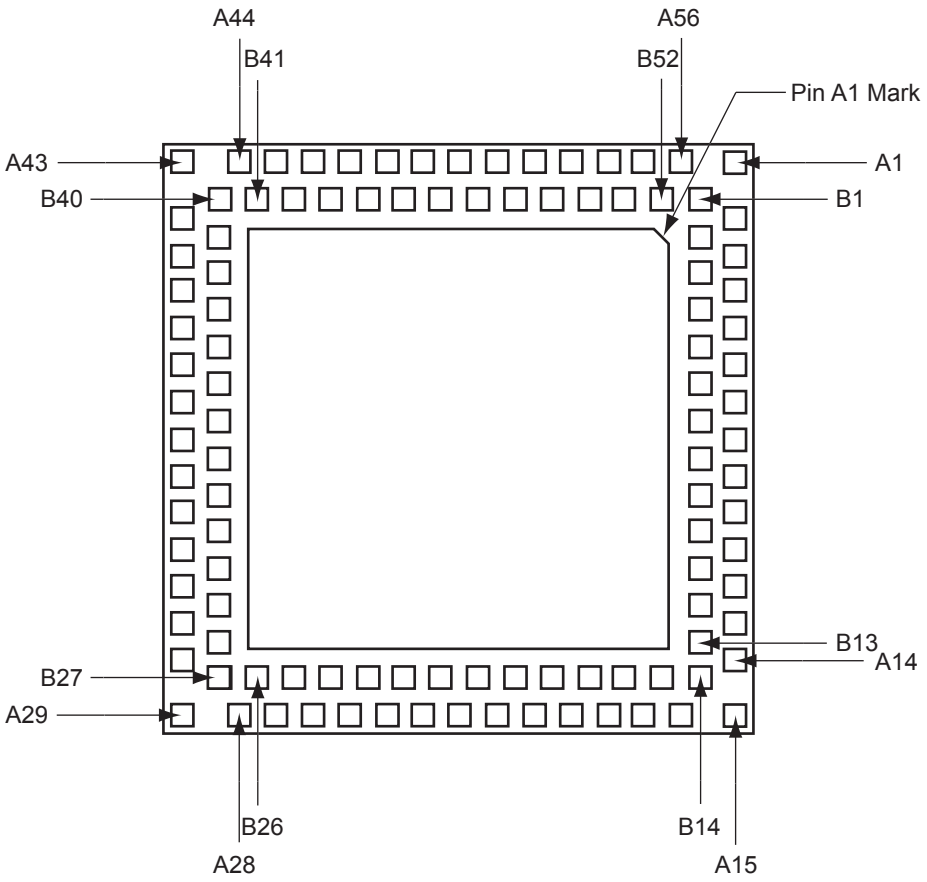
	C_{LOAD} (pF)	VCCI (V)	Static Power PDC8 (mW)[2]	Dynamic Power PAC10 (µW/MHz)[3]
Applicable to Pro I/O Banks				
Single-Ended				
3.3 V LVTTL/LVCMOS	35	3.3	–	474.70
2.5 V LVCMOS	35	2.5	–	270.73
1.8 V LVCMOS	35	1.8	–	151.78
1.5 V LVCMOS (JESD8-11)	35	1.5	–	104.55
3.3 V PCI	10	3.3	–	204.61
3.3 V PCI-X	10	3.3	–	204.61
Voltage-Referenced				
3.3 V GTL	10	3.3	–	24.08
2.5 V GTL	10	2.5	–	13.52
3.3 V GTL+	10	3.3	–	24.10
2.5 V GTL+	10	2.5	–	13.54
HSTL (I)	20	1.5	7.08	26.22
HSTL (II)	20	1.5	13.88	27.22
SSTL2 (I)	30	2.5	16.69	105.56
SSTL2 (II)	30	2.5	25.91	116.60
SSTL3 (I)	30	3.3	26.02	114.87
SSTL3 (II)	30	3.3	42.21	131.76
Differential				
LVDS	–	2.5	7.70	89.62
LVPECL	–	3.3	19.42	168.02
Applicable to Advanced I/O Banks				
Single-Ended				
3.3 V LVTTL / 3.3 V LVCMOS	35	3.3	–	468.67
2.5 V LVCMOS	35	2.5	–	267.48
1.8 V LVCMOS	35	1.8	–	149.46
1.5 V LVCMOS (JESD8-11)	35	1.5	–	103.12
3.3 V PCI	10	3.3	–	201.02
3.3 V PCI-X	10	3.3	–	201.02

Notes:

1. *Dynamic power consumption is given for standard load and software-default drive strength and output slew.*
2. *PDC8 is the static power (where applicable) measured on VCCI.*
3. *PAC10 is the total dynamic power measured on VCC and VCCI.*

4 – Package Pin Assignments

QN108



Note: The die attach paddle center of the package is tied to ground (GND).

Note

For Package Manufacturing and Environmental information, visit the Resource Center at http://www.microsemi.com/soc/products/solutions/package/default.aspx.

FG256				
Pin Number	**AFS090 Function**	**AFS250 Function**	**AFS600 Function**	**AFS1500 Function**
H3	XTAL2	XTAL2	XTAL2	XTAL2
H4	XTAL1	XTAL1	XTAL1	XTAL1
H5	GNDOSC	GNDOSC	GNDOSC	GNDOSC
H6	VCCOSC	VCCOSC	VCCOSC	VCCOSC
H7	VCC	VCC	VCC	VCC
H8	GND	GND	GND	GND
H9	VCC	VCC	VCC	VCC
H10	GND	GND	GND	GND
H11	GDC0/IO38NDB1V0	IO51NDB1V0	IO47NDB2V0	IO69NDB2V0
H12	GDC1/IO38PDB1V0	IO51PDB1V0	IO47PDB2V0	IO69PDB2V0
H13	GDB1/IO39PDB1V0	GCA1/IO49PDB1V0	GCA1/IO45PDB2V0	GCA1/IO64PDB2V0
H14	GDB0/IO39NDB1V0	GCA0/IO49NDB1V0	GCA0/IO45NDB2V0	GCA0/IO64NDB2V0
H15	GCA0/IO36NDB1V0	GCB0/IO48NDB1V0	GCB0/IO44NDB2V0	GCB0/IO63NDB2V0
H16	GCA1/IO36PDB1V0	GCB1/IO48PDB1V0	GCB1/IO44PDB2V0	GCB1/IO63PDB2V0
J1	GEA0/IO44NDB3V0	GFA0/IO66NDB3V0	GFA0/IO70NDB4V0	GFA0/IO105NDB4V0
J2	GEA1/IO44PDB3V0	GFA1/IO66PDB3V0	GFA1/IO70PDB4V0	GFA1/IO105PDB4V0
J3	IO43NDB3V0	GFB0/IO67NDB3V0	GFB0/IO71NDB4V0	GFB0/IO106NDB4V0
J4	GEC2/IO43PDB3V0	GFB1/IO67PDB3V0	GFB1/IO71PDB4V0	GFB1/IO106PDB4V0
J5	NC	GFC0/IO68NDB3V0	GFC0/IO72NDB4V0	GFC0/IO107NDB4V0
J6	NC	GFC1/IO68PDB3V0	GFC1/IO72PDB4V0	GFC1/IO107PDB4V0
J7	GND	GND	GND	GND
J8	VCC	VCC	VCC	VCC
J9	GND	GND	GND	GND
J10	VCC	VCC	VCC	VCC
J11	GDC2/IO41NPB1V0	IO56NPB1V0	IO56NPB2V0	IO83NPB2V0
J12	NC	GDB0/IO53NPB1V0	GDB0/IO53NPB2V0	GDB0/IO80NPB2V0
J13	NC	GDA1/IO54PDB1V0	GDA1/IO54PDB2V0	GDA1/IO81PDB2V0
J14	GDA0/IO40PDB1V0	GDC1/IO52PPB1V0	GDC1/IO52PPB2V0	GDC1/IO79PPB2V0
J15	NC	IO50NPB1V0	IO51NSB2V0	IO77NSB2V0
J16	GDA2/IO40NDB1V0	GDC0/IO52NPB1V0	GDC0/IO52NPB2V0	GDC0/IO79NPB2V0
K1	NC	IO65NPB3V0	IO67NPB4V0	IO92NPB4V0
K2	VCCIB3	VCCIB3	VCCIB4	VCCIB4
K3	NC	IO65PPB3V0	IO67PPB4V0	IO92PPB4V0
K4	NC	IO64PDB3V0	IO65PDB4V0	IO96PDB4V0
K5	GND	GND	GND	GND
K6	NC	IO64NDB3V0	IO65NDB4V0	IO96NDB4V0
K7	VCC	VCC	VCC	VCC
K8	GND	GND	GND	GND

Revision	Changes	Page
Advance 1.0 (continued)	In Table 2-47 • ADC Characteristics in Direct Input Mode, the commercial conditions were updated and note 2 is new.	2-121
	The $V_{CC33ACAP}$ signal name was changed to "XTAL1 Crystal Oscillator Circuit Input".	2-228
	Table 2-48 • Uncalibrated Analog Channel Accuracy* is new.	2-123
	Table 2-49 • Calibrated Analog Channel Accuracy [1,2,3] is new.	2-124
	Table 2-50 • Analog Channel Accuracy: Monitoring Standard Positive Voltages is new.	2-125
	In Table 2-57 • Voltage Polarity Control Truth Table—AV (x = 0), AC (x = 1), and AT (x = 3)*, the following I/O Bank names were changed: Hot-Swap changed to Standard LVDS changed to Advanced	2-131
	In Table 2-58 • Prescaler Op Amp Power-Down Truth Table—AV (x = 0), AC (x = 1), and AT (x = 3), the following I/O Bank names were changed: Hot-Swap changed to Standard LVDS changed to Advanced	2-132
	In the title of Table 2-64 • I/O Standards Supported by Bank Type, LVDS I/O was changed to Advanced I/O.	2-134
	The title was changed from "Fusion Standard, LVDS, and Standard plus Hot-Swap I/O" to Table 2-68 • Fusion Standard and Advanced I/O Features. In addition, the table headings were all updated. The heading used to be Standard and LVDS I/O and was changed to Advanced I/O. Standard Hot-Swap was changed to just Standard.	2-136
	This sentence was deleted from the "Slew Rate Control and Drive Strength" section: The Standard hot-swap I/Os do not support slew rate control. In addition, these references were changed: • From: Fusion hot-swap I/O (Table 2-69 on page 2-122) To: Fusion Standard I/O • From: Fusion LVDS I/O (Table 2-70 on page 2-122) To: Fusion Advanced I/O	2-152
	The "Cold-Sparing Support" section was significantly updated.	2-143
	In the title of Table 2-75 • Fusion Standard I/O Standards—OUT_DRIVE Settings, Hot-Swap was changed to Standard.	2-153
	In the title of Table 2-76 • Fusion Advanced I/O Standards—SLEW and OUT_DRIVE Settings, LVDS was changed to Advanced.	2-153
	In the title of Table 2-81 • Fusion Standard and Advanced I/O Attributes vs. I/O Standard Applications, LVDS was changed to Advanced.	2-157
	In Figure 2-111 • Naming Conventions of Fusion Devices with Three Digital I/O Banks and Figure 2-112 • Naming Conventions of Fusion Devices with Four I/O Banks the following names were changed: Hot-Swap changed to Standard LVDS changed to Advanced	2-160
	The Figure 2-113 • Timing Model was updated.	2-161
	In the notes for Table 2-86 • Summary of Maximum and Minimum DC Input Levels Applicable to Commercial and Industrial Conditions, T_J was changed to T_A.	2-166