Renesas Electronics America Inc - R5F2L388MDFA#V0 Datasheet

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SIO, SSU, UART/USART
Peripherals	LCD, POR, PWM, Voltage Detect, WDT
Number of I/O	68
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 16x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f2l388mdfa-v0

1.1.2 Differences between Groups

Table 1.1 lists the Differences between Groups, Table 1.2 lists the Programmable I/O Ports Provided for Each Group, and Table 1.3 lists the LCD Display Function Pins Provided for Each Group. Figures 1.9 to 1.13 show the Pin Assignment for Each Group, and Tables 1.7 to 1.10 list Product Information.
The explanations in the chapters which follow apply to the R8C/L3AM Group only. Note the differences shown below.

Table 1.1 Differences between Groups

Item	Function	R8C/L35M Group	R8C/L36M Group	R8C/L38M Group	R8C/L3AM Group
I/O Ports	Programmable I/O ports	41 pins	52 pins	68 pins	88 pins
	High current drive ports	5 pins	8 pins	8 pins	16 pins
Interrupts	$\overline{\text{INT}}$ interrupt pins	5 pins	8 pins	8 pins	8 pins
	Key input interrupt pins	4 pins	4 pins	8 pins	8 pins
Timer RA	Timer RA output pin	None	1 pin	1 pin	1 pin
Timer RB	Timer RB output pin	None	1 pin	1 pin	1 pin
Timer RD	Timer RD I/O pin	None	None	8 pins	8 pins
Timer RE	Timer RE output pin	None	1 pin	1 pin	1 pin
Timer RG	Timer RG I/O pin	None	None	None	2 pins
	Timer RG output pin	None	None	None	2 pins
A/D Converter	Analog input pin	12 pins	12 pins	16 pins	20 pins
LCD Drive Control Circuit	LCD power supply	3 pins (VL1, VL2, VL4)	4 pins (VL1 to VL4)	4 pins (VL1 to VL4)	4 pins (VL1 to VL4)
	Common output pins	Max. 4 pins	Max. 8 pins	Max. 8 pins	Max. 8 pins
	Segment output pins	Max. 24 pins	Max. 32 pins	Max. 48 pins	Max. 56 pins
Packages		52-pin LQFP	64-pin LQFP	80-pin LQFP	100-pin LQFP/ 100-pin QFP

Note:
1. I/O ports are shared with I/O functions, such as interrupts or timers.
Refer to **Tables 1.11 to 1.13, Pin Name Information by Pin Number**, for details.

1.1.3 Specifications

Tables 1.4 to 1.6 list the Specifications.

Table 1.4 Specifications (1)

Item	Function		Specification
CPU	Central processing unit		R8C CPU core • Number of fundamental instructions: 89 • Minimum instruction execution time: 50 ns (f(XIN) = 20 MHz, VCC = 2.7 to 5.5 V) 200 ns (f(XIN) = 5 MHz, VCC = 1.8 to 5.5 V) • Multiplier: 16 bits × 16 bits → 32 bits • Multiply-accumulate instruction: 16 bits × 16 bits + 32 bits → 32 bits • Operating mode: Single-chip mode (address space: 1 Mbyte)
Memory	ROM/RAM Data flash		Refer to **Tables 1.7 to 1.10 Product Lists**.
Power Supply Voltage Detection	Voltage detection circuit		• Power-on reset • Voltage detection 3 (detection level of voltage detection 0 and voltage detection 1 selectable)
I/O Ports	Programmable I/O ports	R8C/L35M Group	• CMOS I/O ports: 41, selectable pull-up resistor • High current drive ports: 5
		R8C/L36M Group	• CMOS I/O ports: 52, selectable pull-up resistor • High current drive ports: 8
		R8C/L38M Group	• CMOS I/O ports: 68, selectable pull-up resistor • High current drive ports: 8
		R8C/L3AM Group	• CMOS I/O ports: 88, selectable pull-up resistor • High current drive ports: 16
Clock	Clock generation circuits		4 circuits: XIN clock oscillation circuit XCIN clock oscillation circuit (32 kHz) High-speed on-chip oscillator (with frequency adjustment function) Low-speed on-chip oscillator • Oscillation stop detection: XIN clock oscillation stop detection function • Frequency divider circuit: Division ratio selectable from 1, 2, 4, 8, and 16 • Low-power-consumption modes: Standard operating mode (high-speed clock, low-speed clock, high-speed on-chip oscillator, low-speed on-chip oscillator), wait mode, stop mode, power-off mode
			Real-time clock (timer RE)
Interrupts		R8C/L35M Group	• Number of interrupt vectors: 69 • External Interrupt: 9 ($\overline{\text{INT}}$ × 5, key input × 4) • Priority levels: 7 levels
		R8C/L36M Group	• Number of interrupt vectors: 69 • External Interrupt: 12 ($\overline{\text{INT}}$ × 8, key input × 4) • Priority levels: 7 levels
		R8C/L38M Group	• Number of interrupt vectors: 69 • External Interrupt: 16 ($\overline{\text{INT}}$ × 8, key input × 8) • Priority levels: 7 levels
		R8C/L3AM Group	• Number of interrupt vectors: 69 • External Interrupt: 16 ($\overline{\text{INT}}$ × 8, key input × 8) • Priority levels: 7 levels
Watchdog Timer			• 14 bits × 1 (with prescaler) • Selectable reset start function • Selectable low-speed on-chip oscillator for watchdog timer
DTC (Data Transfer Controller)			• 1 channel • Activation sources: 38 • Transfer modes: 2 (normal mode, repeat mode)

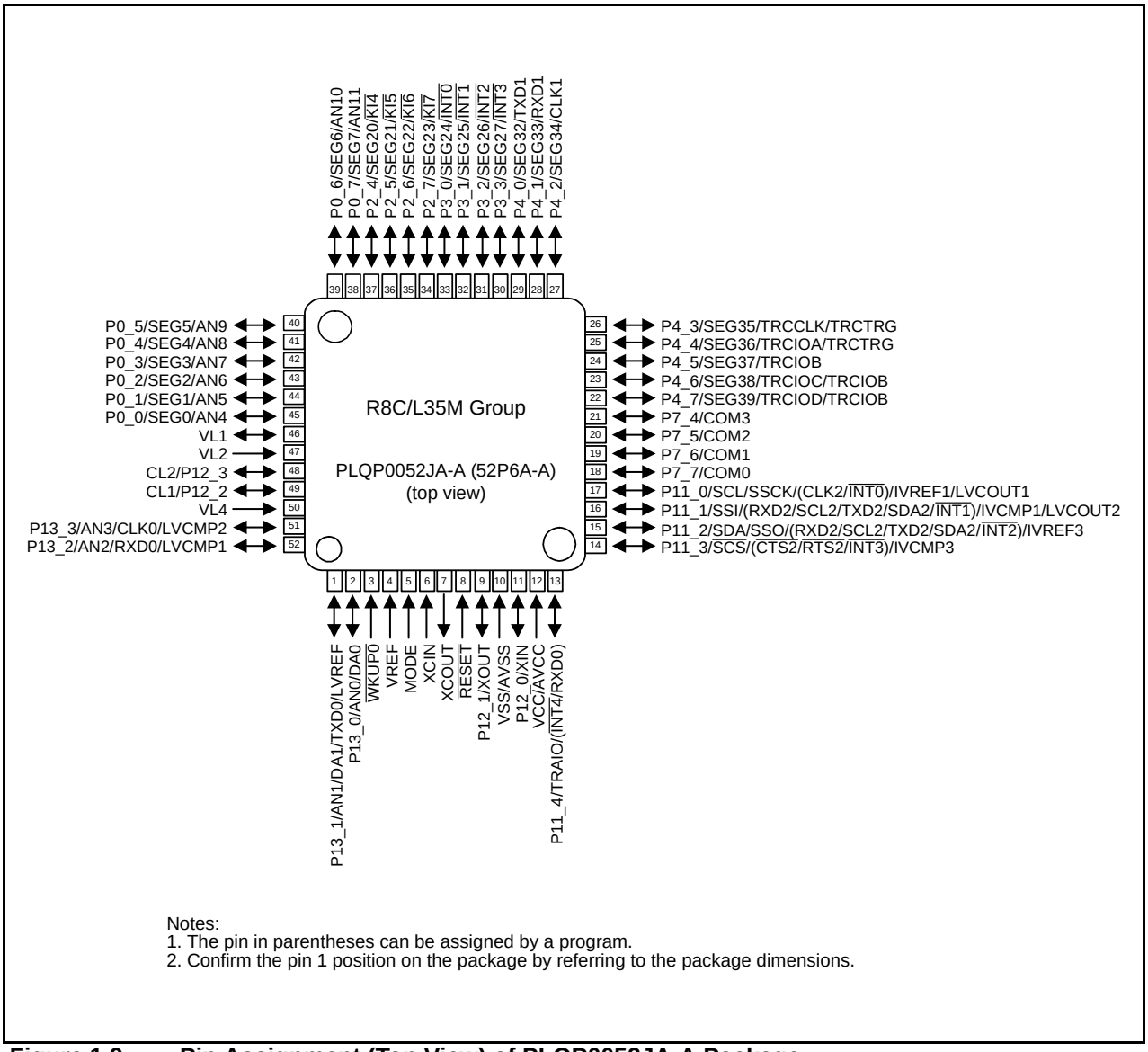
Table 1.5 Specifications (2)

Item	Function	Specification	
Timer	Timer RA	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode	
	Timer RB	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode	
	Timer RC	16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output: 3 pins), PWM2 mode (PWM output: 1 pin)	
	Timer RD	16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output: 6 pins), reset synchronous PWM mode (three-phase waveform output: 6 pins, sawtooth wave modulation), complementary PWM mode (three-phase waveform output: 6 pins, triangular wave modulation), PWM3 mode (PWM output with fixed period: 2 pins)	
	Timer RE	8 bits × 1 Real-time clock mode (counting of seconds, minutes, hours, days of week), output compare mode	
	Timer RG	16 bits × 1 Phase-counting mode, timer mode (output compare function, input capture function), PWM mode (output: 1 pin)	
Serial Interface	UART0, UART1	Clock synchronous serial I/O/UART × 2 channels	
	UART2	Clock synchronous serial I/O/UART, I^2C mode (I^2C-bus), multiprocessor communication function	
Synchronous Serial Communication Unit (SSU)		1 (shared with I^2C-bus)	
I^2C bus		1 (shared with SSU)	
LIN Module		Hardware LIN: 1 channel (timer RA, UART0 used)	
A/D Converter	R8C/L35M Group	10-bit resolution × 12 channels, including sample and hold function, with sweep mode	
	R8C/L36M Group	10-bit resolution × 12 channels, including sample and hold function, with sweep mode	
	R8C/L38M Group	10-bit resolution × 16 channels, including sample and hold function, with sweep mode	
	R8C/L3AM Group	10-bit resolution × 20 channels, including sample and hold function, with sweep mode	
D/A Converter		8-bit resolution × 2 circuits	
Comparator A		• 2 circuits (sheared with voltage monitor 1 and voltage monitor 2) • External reference voltage input available	
Comparator B		2 circuits	
LCD Drive Control Circuit	R8C/L35M Group	Common output: Max. 4 pins Segment output: Max. 24 pins	Bias: 1/2, 1/3 Duty: static, 1/2, 1/3, 1/4
	R8C/L36M Group	Common output: Max. 8 pins Segment output: Max. 32 pins (1)	Bias: 1/2, 1/3, 1/4 Duty: static, 1/2, 1/3, 1/4, 1/8
	R8C/L38M Group	Common output: Max. 8 pins Segment output: Max. 48 pins (1)	
	R8C/L3AM Group	Common output: Max. 8 pins Segment output: Max. 56 pins (1)	
		Voltage multiplier and dedicated regulator integrated	

Note:
1. This applies when four pins are selected for common output.

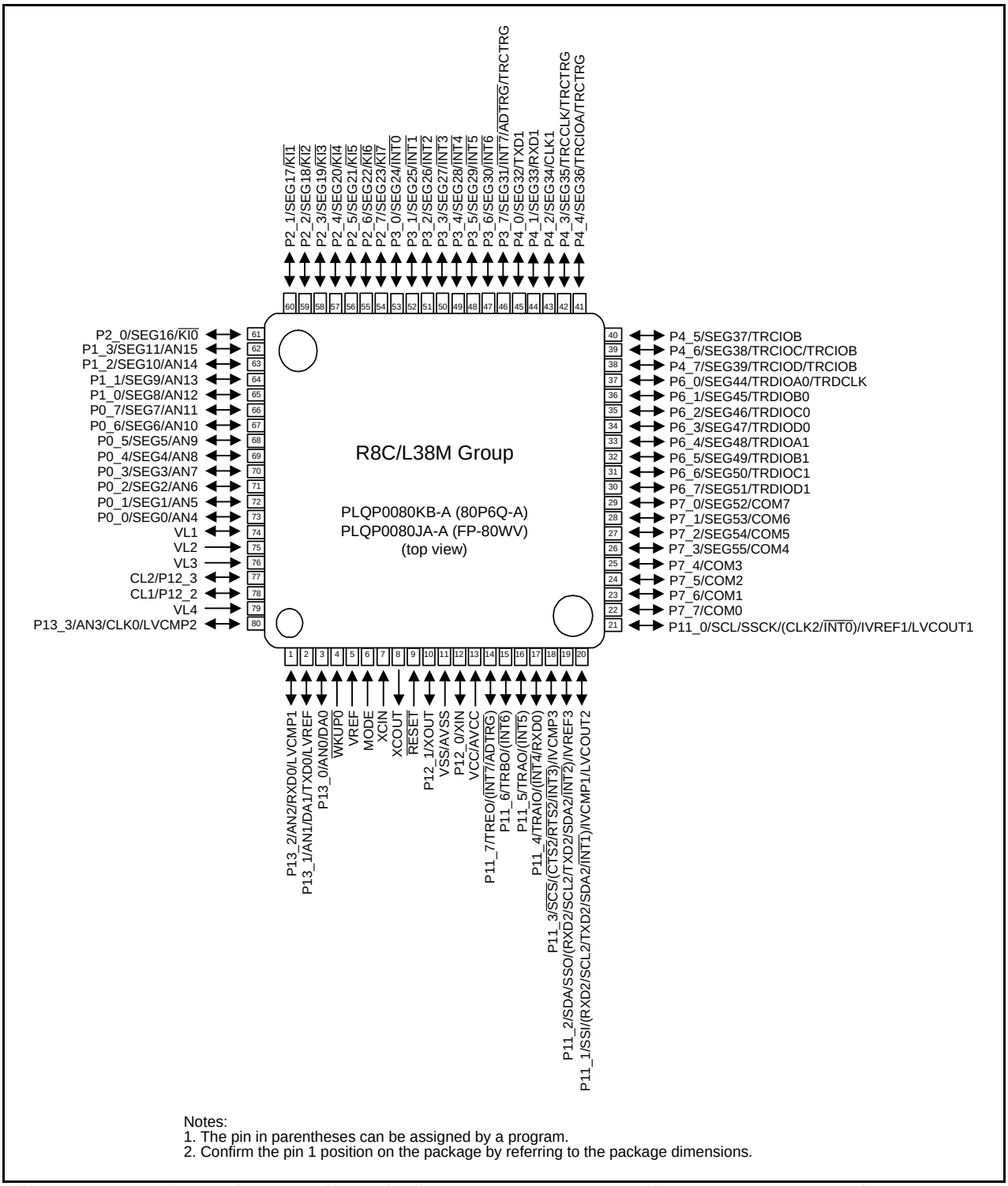
1.4 Pin Assignments

Figures 1.9 to 1.13 show Pin Assignments (Top View). Tables 1.11 to 1.13 list the Pin Name Information by Pin Number.



Notes:
1. The pin in parentheses can be assigned by a program.
2. Confirm the pin 1 position on the package by referring to the package dimensions.

Figure 1.9 Pin Assignment (Top View) of PLQP0052JA-A Package

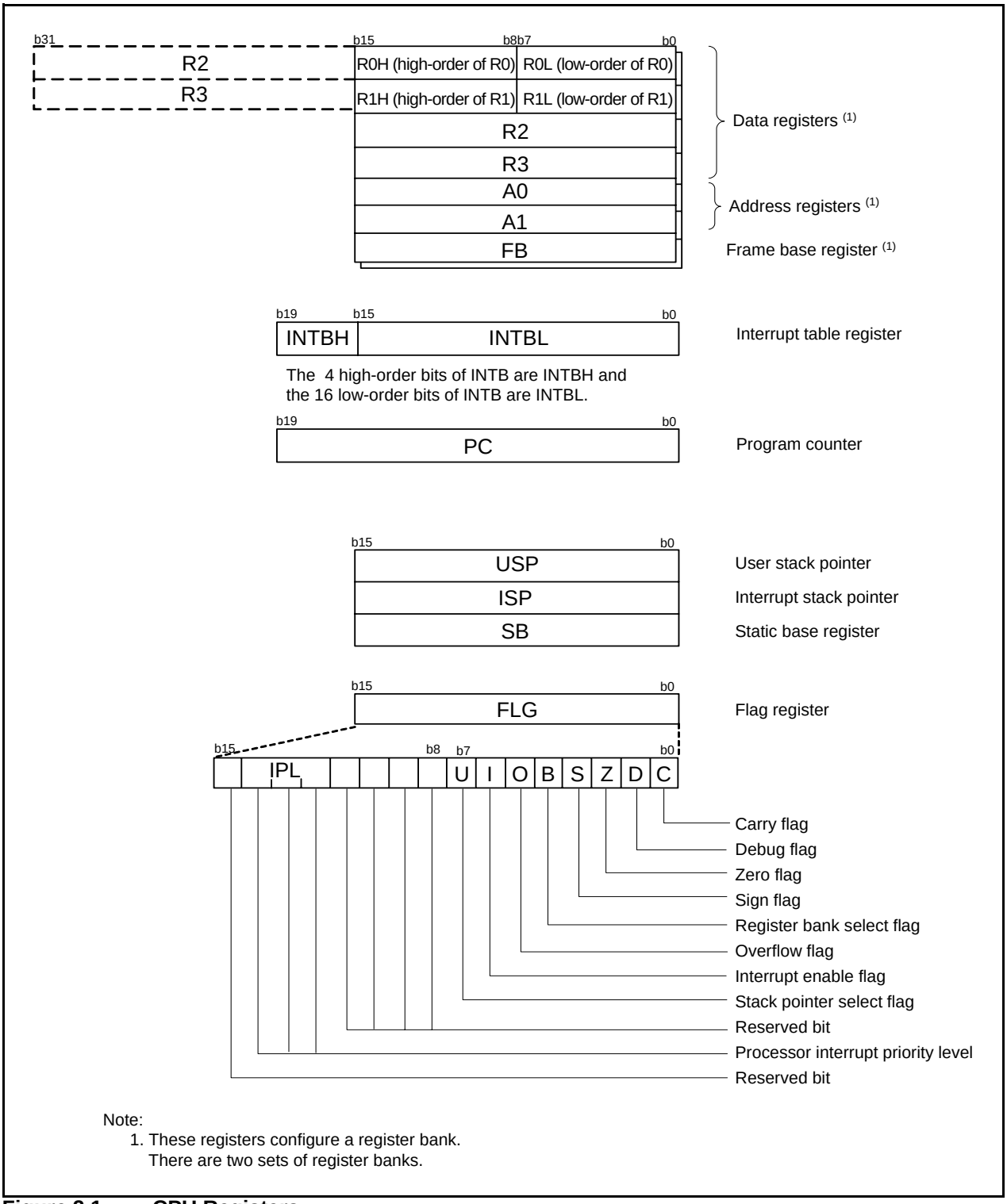


Notes:
1. The pin in parentheses can be assigned by a program.
2. Confirm the pin 1 position on the package by referring to the package dimensions.

Figure 1.11 Pin Assignment (Top View) of PLQP0080KB-A and PLQP0080JA-A Packages

2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU Registers. The CPU contains 13 registers. R0, R1, R2, R3, A0, A1, and FB configure a register bank. There are two sets of register banks.



Note:
1. These registers configure a register bank.
There are two sets of register banks.

Figure 2.1 CPU Registers

2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.
Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.
The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

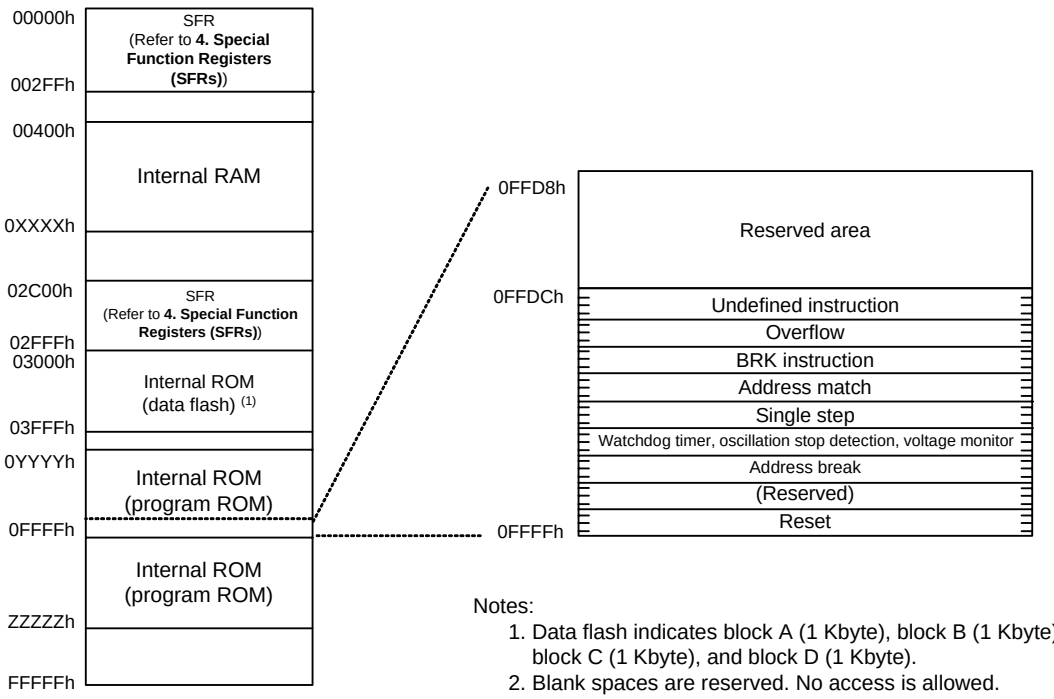
IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7.
If a requested interrupt has higher priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.

3. Memory

Figure 3.1 is a Memory Map of each group. Each group has a 1-Mbyte address space from addresses 00000h to FFFFFh. For example, a 48-Kbyte internal ROM area is allocated addresses 04000h to 0FFFFh.
The fixed interrupt vector table is allocated addresses 0FFDCh to 0FFFFh. The starting address of each interrupt routine is stored here.
The internal ROM (data flash) is allocated addresses 03000h to 03FFFh.
The internal RAM is allocated higher addresses, beginning with address 00400h. For example, a 6-Kbyte internal RAM area is allocated addresses 00400h to 01BFFh. The internal RAM is used not only for data storage but also as a stack area when a subroutine is called or when an interrupt request is acknowledged.
Special function registers (SFRs) are allocated addresses 00000h to 002FFh and 02C00h to 02FFFh. Peripheral function control registers are allocated here. All unallocated spaces within the SFRs are reserved and cannot be accessed by users.



Notes:
1. Data flash indicates block A (1 Kbyte), block B (1 Kbyte), block C (1 Kbyte), and block D (1 Kbyte).
2. Blank spaces are reserved. No access is allowed.

Part Number	Internal ROM			Internal RAM	
	Capacity	Address 0YYYYh	Address ZZZZZh	Capacity	Address 0XXXXh
R5F2L357M***, R5F2L367M***, R5F2L387M***, R5F2L3A7M***	48 Kbytes	04000h	–	6 Kbytes	01BFFh
R5F2L358M***, R5F2L368M***, R5F2L388M***, R5F2L3A8M***	64 Kbytes	04000h	13FFFh	8 Kbytes	023FFh
R5F2L35AM***, R5F2L36AM***, R5F2L38AM***, R5F2L3AAM***	96 Kbytes	04000h	1BFFFh	10 Kbytes	02BFFh
R5F2L35CM***, R5F2L36CM***, R5F2L38CM***, R5F2L3ACM***	128 Kbytes	04000h	23FFFh	10 Kbytes	02BFFh

Figure 3.1 Memory Map

Table 4.10 SFR Information (10) (1)

Address	Register	Symbol	After Reset
0240h	LCD Display Data Register	LRA48L	XXh
0241h		LRA49L	XXh
0242h		LRA50L	XXh
0243h		LRA51L	XXh
0244h		LRA52L	XXh
0245h		LRA53L	XXh
0246h		LRA54L	XXh
0247h		LRA55L	XXh
0248h			
0249h			
024Ah			
024Bh			
024Ch			
024Dh			
024Eh			
024Fh			
0250h			
0251h			
0252h			
0253h			
0254h			
0255h			
0256h			
0257h			
0258h			
0259h			
025Ah			
025Bh			
025Ch			
025Dh			
025Eh			
025Fh			
0260h			
0261h			
0262h			
0263h			
0264h			
0265h			
0266h			
0267h			
0268h			
0269h			
026Ah			
026Bh			
026Ch			
026Dh			
026Eh			
026Fh			
0270h	LCD Display Control Data Register	LRA0H	XXh
0271h		LRA1H	XXh
0272h		LRA2H	XXh
0273h		LRA3H	XXh
0274h		LRA4H	XXh
0275h		LRA5H	XXh
0276h		LRA6H	XXh
0277h		LRA7H	XXh
0278h		LRA8H	XXh
0279h		LRA9H	XXh
027Ah		LRA10H	XXh
027Bh		LRA11H	XXh
027Ch		LRA12H	XXh
027Dh		LRA13H	XXh
027Eh		LRA14H	XXh
027Fh		LRA15H	XXh

X: Undefined
Note:
1. Blank spaces are reserved. No access is allowed.

5. Electrical Characteristics

5.1 Absolute Maximum Ratings

Table 5.1 Absolute Maximum Ratings

Symbol	Parameter		Condition	Rated Value	Unit
V_{CC}/AV_{CC}	Supply voltage			–0.3 to 6.5	V
V_I	Input voltage	XIN	XIN-XOUT oscillation on (oscillation buffer ON) (1)	–0.3 to 1.65	V
		XIN	XIN-XOUT oscillation on (oscillation buffer OFF) (1)	–0.3 to V_{CC} + 0.3	V
		VL1		–0.3 to VL2	V
		VL2	R8C/L35M	VL1 to VL4	V
			R8C/L36M, R8C/L38M, R8C/L3AM	VL1 to VL3	V
		VL3		VL2 to VL4	V
		VL4		VL3 to 6.5	V
		Other pins		–0.3 to V_{CC} + 0.3	V
V_O	Output voltage	XOUT	XIN-XOUT oscillation on (oscillation buffer ON) (1)	–0.3 to 1.65	V
		XOUT	XIN-XOUT oscillation on (oscillation buffer OFF) (1)	–0.3 to V_{CC} + 0.3	V
		VL1		–0.3 to VL2 (2)	V
		VL2	R8C/L35M	VL1 to VL4	V
			R8C/L36M, R8C/L38M, R8C/L3AM	VL1 to VL3	V
		VL3		VL2 to VL4	V
		VL4		–0.3 to 6.5	V
		CL1, CL2		–0.3 to 6.5	V
		COM0 to COM7		–0.3 to VL4	V
		SEG0 to SEG55		–0.3 to VL4	V
		Other pins		–0.3 to V_{CC} + 0.3	V
P_d	Power dissipation		–40°C ≤ T_{opr} ≤ 85°C	500	mW
T_{opr}	Operating ambient temperature			–20 to 85 (N version) / –40 to 85 (D version)	°C
T_{stg}	Storage temperature			–65 to 150	°C

Notes:
1. For the register settings for each operation, refer to **7. I/O Ports** and **9. Clock Generation Circuit** in the User's Manual: Hardware.
2. The VL1 voltage should be VCC or below.

5.2 Recommended Operating Conditions

Table 5.2 Recommended Operating Conditions
(Vcc = 1.8 to 5.5 V and Topr = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter				Conditions	Standard			Unit
						Min.	Typ.	Max.	
Vcc/AVcc	Supply voltage					1.8	—	5.5	V
Vss/AVss	Supply voltage					—	0	—	V
VIH	Input “H” voltage	Other than CMOS input			4.0 V ≤ Vcc ≤ 5.5 V	0.8 Vcc	—	Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0.8 Vcc	—	Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0.9 Vcc	—	Vcc	V
		CMOS input	Input level switching function (I/O port)	Input level selection : 0.35 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0.5 Vcc	—	Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0.55 Vcc	—	Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0.65 Vcc	—	Vcc	V
				Input level selection : 0.5 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0.65 Vcc	—	Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0.7 Vcc	—	Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0.8 Vcc	—	Vcc	V
				Input level selection : 0.7 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0.85 Vcc	—	Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0.85 Vcc	—	Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0.85 Vcc	—	Vcc	V
VIL	Input “L” voltage	Other than CMOS input			4.0 V ≤ Vcc ≤ 5.5 V	0	—	0.2 Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0	—	0.2 Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0	—	0.05 Vcc	V
		CMOS input	Input level switching function (I/O port)	Input level selection : 0.35 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0	—	0.2 Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0	—	0.2 Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0	—	0.2 Vcc	V
				Input level selection : 0.5 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0	—	0.4 Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0	—	0.3 Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0	—	0.2 Vcc	V
				Input level selection : 0.7 Vcc	4.0 V ≤ Vcc ≤ 5.5 V	0	—	0.55 Vcc	V
					2.7 V ≤ Vcc < 4.0 V	0	—	0.45 Vcc	V
					1.8 V ≤ Vcc < 2.7 V	0	—	0.35 Vcc	V
IOH(sum)	Peak sum output “H” current	Sum of all pins IOH(peak)				—	—	−160	mA
IOH(sum)	Average sum output “H” current	Sum of all pins IOH(avg)				—	—	−80	mA
IOH(peak)	Peak output “H” current	Port P10, P11 (2)				—	—	−40	mA
		Other pins				—	—	−10	mA
IOH(avg)	Average output “H” current (1)	Port P10, P11 (2)				—	—	−20	mA
		Other pins				—	—	−5	mA
IOL(sum)	Peak sum output “L” current	Sum of all pins IOL(peak)				—	—	160	mA
IOL(sum)	Average sum output “L” current	Sum of all pins IOL(avg)				—	—	80	mA
IOL(peak)	Peak output “L” current	Port P10, P11 (2)				—	—	40	mA
		Other pins				—	—	10	mA
IOL(avg)	Average output “L” current (1)	Port P10, P11 (2)				—	—	20	mA
		Other pins				—	—	5	mA
f(XIN)	XIN clock input oscillation frequency				2.7 V ≤ Vcc ≤ 5.5 V	—	—	20	MHz
					1.8 V ≤ Vcc < 2.7 V	—	—	5	MHz
f(XCIN)	XCIN clock input oscillation frequency				1.8 V ≤ Vcc ≤ 5.5 V	—	32.768	50	kHz
fOCO40M	When used as the count source for timer RC, timer RD, or timer RG (3)				2.7 V ≤ Vcc ≤ 5.5 V	32	—	40	MHz
fOCO-F	fOCO-F frequency				2.7 V ≤ Vcc ≤ 5.5 V	—	—	20	MHz
					1.8 V ≤ Vcc < 2.7 V	—	—	5	MHz
—	System clock frequency				2.7 V ≤ Vcc ≤ 5.5 V	—	—	20	MHz
					1.8 V ≤ Vcc < 2.7 V	—	—	5	MHz
f(BCLK)	CPU clock frequency				2.7 V ≤ Vcc ≤ 5.5 V	—	—	20	MHz
					1.8 V ≤ Vcc < 2.7 V	—	—	5	MHz

Notes:
1. The average output current indicates the average value of current measured during 100 ms.
2. This applies when the drive capacity of the output transistor is set to High by registers P10DRR and P11DRR. When the drive capacity is set to Low, the value of any other pin applies.
3. fOCO40M can be used as the count source for timer RC, timer RD, or timer RG in the range of Vcc = 2.7 V to 5.5V.

Table 5.23 DC Characteristics (6) [1.8 V ≤ Vcc < 2.7 V]
(Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter		Condition							Standard			Unit
			Oscillation Circuit		On-Chip Oscillator		CPU Clock	Low-Power-Consumption Setting	Other	Min.	Typ. (3)	Max.	
			XIN (2)	XCIN	High-Speed (fOCO-F)	Low-Speed							
Icc	Power supply current (1)	High-speed clock mode	5 MHz	Off	Off	125 kHz	No division	—		—	2.2	—	mA
			5 MHz	Off	Off	125 kHz	Divide-by-8	—		—	0.8	—	mA
		High-speed on-chip oscillator mode	Off	Off	5 MHz	125 kHz	No division	—		—	2.5	10	mA
			Off	Off	5 MHz	125 kHz	Divide-by-8	—		—	1.7	—	mA
			Off	Off	4 MHz	125 kHz	Divide-by-16	MSTIIC = 1 MSTTRD = 1 MSTTRC = 1 MSTTRG = 1		—	1	—	mA
		Low-speed on-chip oscillator mode	Off	Off	Off	125 kHz	Divide-by-8	FMR27 = 1 VCA20 = 0		—	90	300	µA
		Low-speed clock mode	Off	32 kHz	Off	Off	No division	FMR27 = 1 VCA20 = 0		—	90	400	µA
			Off	32 kHz	Off	Off	No division	FMSTP = 1 VCA20 = 0	Flash memory off Program operation on RAM	—	45	—	µA
		Wait mode	Off	Off	Off	125 kHz	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1	While a WAIT instruction is executed Peripheral clock operation	—	15	90	µA
			Off	Off	Off	125 kHz	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 1	While a WAIT instruction is executed Peripheral clock off	—	4	80	µA
			Off	32 kHz	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 0	While a WAIT instruction is executed Peripheral clock off Timer RE operation in real-time clock mode	LCD drive control circuit (4) When external division resistors are used	—	4	—	µA
										LCD drive control circuit (5) When the internal voltage multiplier is used	—	11	—	µA
			Off	32 kHz	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 1	While a WAIT instruction is executed Peripheral clock off Timer RE operation in real-time clock mode		—	3.5	—	µA
		Stop mode	Off	Off	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 CM10 = 1	Topr = 25°C Peripheral clock off		—	2.0	5.0	µA
			Off	Off	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 CM10 = 1	Topr = 85°C Peripheral clock off		—	13	—	µA
		Power-off mode	Off	Off	Off	Off	—	—	Power-off 0 Topr = 25°C		—	0.02	0.2	µA
			Off	Off	Off	Off	—	—	Power-off 0 Topr = 85°C		—	0.3	—	µA
			Off	32 kHz	Off	Off	—	—	Power-off 1 Topr = 25°C		—	1.3	2.6	µA
			Off	32 kHz	Off	Off	—	—	Power-off 1 Topr = 85°C		—	1.7	—	µA

Notes:
1. Vcc = 1.8 V to 2.7 V, single chip mode, output pins are open, and other pins are Vss.
2. XIN is set to square wave input.
3. Vcc = 2.2 V
4. VLCD = Vcc, external division resistors are used for VL4 to VL1, 1/3 bias, 1/4 duty, f(FR) = 64 Hz, SEG0 to SEG55 are selected, and segment and common output pins are open.The standard value does not include the current that flows through external division resistors.
5. The internal voltage multiplier is used, bits LVLS3 to LVLS0 in the LCR1 register = 1011b, 1/3 bias, 1/4 duty, f(FR) = 64 Hz, SEG0 to SEG55 are selected, and segment and common output pins are open.

5.5 AC Characteristics

Table 5.24 Timing Requirements of Synchronous Serial Communication Unit (SSU) (V_{CC} = 1.8 to 5.5 V, V_{SS} = 0 V, and T_{opr} = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter		Conditions	Standard			Unit
				Min.	Typ.	Max.	
t_{SUCYC}	SSCK clock cycle time			4	—	—	t_{CYC} (1)
t_{HI}	SSCK clock “H” width			0.4	—	0.6	t_{SUCYC}
t_{LO}	SSCK clock “L” width			0.4	—	0.6	t_{SUCYC}
t_{RISE}	SSCK clock rising time	Master		—	—	1	t_{CYC} (1)
		Slave		—	—	1	µs
t_{FALL}	SSCK clock falling time	Master		—	—	1	t_{CYC} (1)
		Slave		—	—	1	µs
t_{SU}	SSO, SSI data input setup time			100	—	—	ns
t_H	SSO, SSI data input hold time			1	—	—	t_{CYC} (1)
t_{LEAD}	$\overline{SCS}$ setup time	Slave		1t_{CYC} + 50	—	—	ns
t_{LAG}	$\overline{SCS}$ hold time	Slave		1t_{CYC} + 50	—	—	ns
t_{OD}	SSO, SSI data output delay time			—	—	1	t_{CYC} (1)
t_{SA}	SSI slave access time		2.7 V ≤ V_{CC} ≤ 5.5 V	—	—	1.5t_{CYC} + 100	ns
			1.8 V ≤ V_{CC} < 2.7 V	—	—	1.5t_{CYC} + 200	ns
t_{OR}	SSI slave out open time		2.7 V ≤ V_{CC} ≤ 5.5 V	—	—	1.5t_{CYC} + 100	ns
			1.8 V ≤ V_{CC} < 2.7 V	—	—	1.5t_{CYC} + 200	ns

Note:
1. 1t_{CYC} = 1/f1(s)

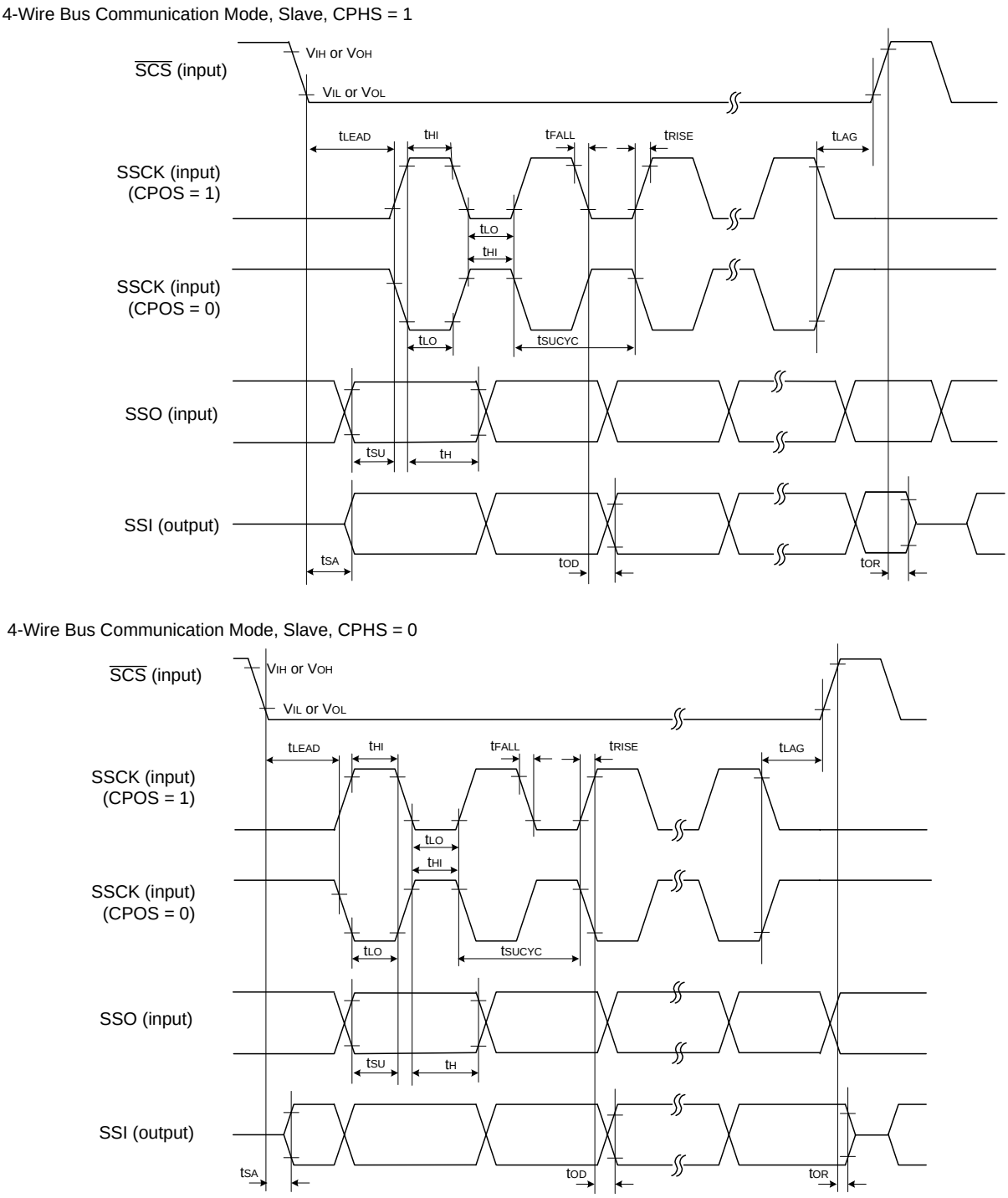
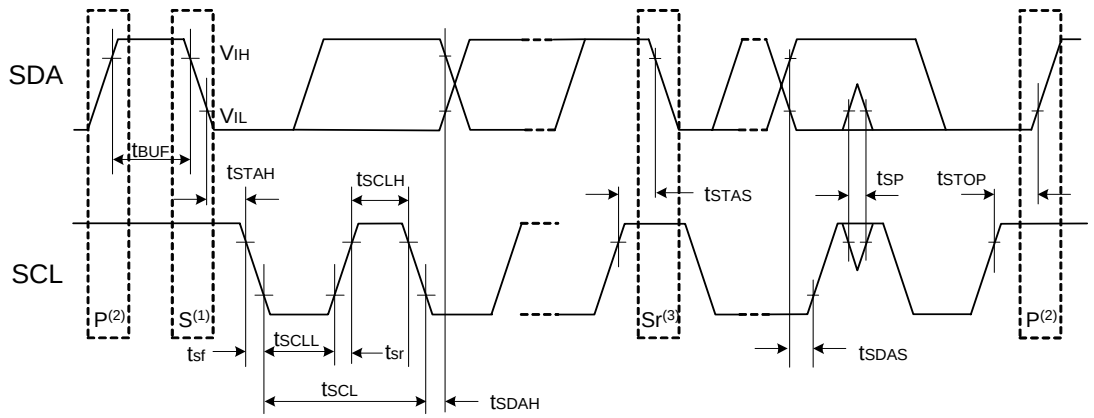


Figure 5.5 I/O Timing of Synchronous Serial Communication Unit (SSU) (Slave)

Table 5.25 Timing Requirements of I²C bus Interface (1)
(Vcc = 1.8 to 5.5 V, Vss = 0 V, and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
tSCL	SCL input cycle time		12tCYC + 600 (1)	—	—	ns
tSCLH	SCL input “H” width		3tCYC + 300 (1)	—	—	ns
tSCLL	SCL input “L” width		5tCYC + 500 (1)	—	—	ns
tsf	SCL, SDA input fall time		—	—	300	ns
tSP	SCL, SDA input spike pulse rejection time		—	—	1tCYC (1)	ns
tBUF	SDA input bus-free time		5tCYC (1)	—	—	ns
tSTAH	Start condition input hold time		3tCYC (1)	—	—	ns
tSTAS	Retransmit start condition input setup time		3tCYC (1)	—	—	ns
tSTOP	Stop condition input setup time		3tCYC (1)	—	—	ns
tSDAS	Data input setup time		1tCYC + 40 (1)	—	—	ns
tSDAH	Data input hold time		10	—	—	ns

Note:
1. 1tCYC = 1/f1(s)



Notes:
1. Start condition
2. Stop condition
3. Retransmit start condition

Figure 5.7 I/O Timing of I²C bus Interface

Table 5.26 External Clock Input (XIN, XCIN)
(Vcc = 1.8 to 5.5 V, Vss = 0 V, and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		Vcc = 2.2V, Topr = 25°C		Vcc = 3V, Topr = 25°C		Vcc = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(XIN)}$	XIN input cycle time	200	—	50	—	50	—	ns
$t_{WH(XIN)}$	XIN input “H” width	90	—	24	—	24	—	ns
$t_{WL(XIN)}$	XIN input “L” width	90	—	24	—	24	—	ns
$t_{c(XCIN)}$	XCIN input cycle time	14	—	14	—	14	—	µs
$t_{WH(XCIN)}$	XCIN input “H” width	7	—	7	—	7	—	µs
$t_{WL(XCIN)}$	XCIN input “L” width	7	—	7	—	7	—	µs

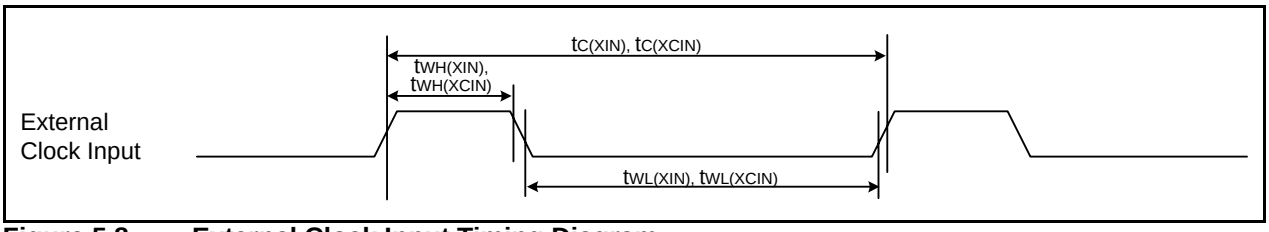


Figure 5.8 External Clock Input Timing Diagram

Table 5.27 Timing Requirements of TRAIO
(Vcc = 1.8 to 5.5 V, Vss = 0 V and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		Vcc = 2.2V, Topr = 25°C		Vcc = 3V, Topr = 25°C		Vcc = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(TRAIO)}$	TRAIO input cycle time	500	—	300	—	100	—	ns
$t_{WH(TRAIO)}$	TRAIO input “H” width	200	—	120	—	40	—	ns
$t_{WL(TRAIO)}$	TRAIO input “L” width	200	—	120	—	40	—	ns

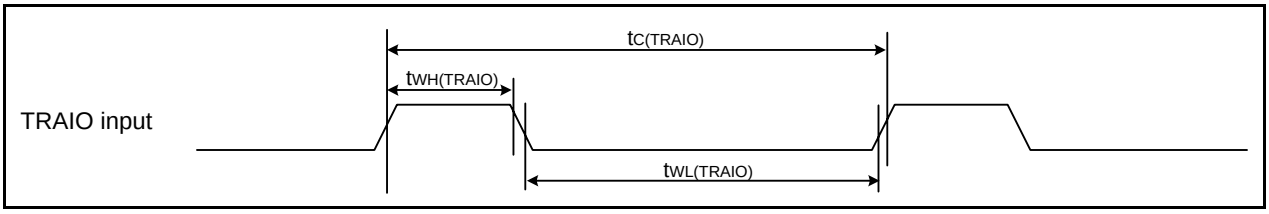


Figure 5.9 Input Timing of TRAIO

Table 5.28 Timing Requirements of Serial Interface
(V_{CC} = 1.8 to 5.5 V, V_{SS} = 0 V, and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		V_{CC} = 2.2V, Topr = 25°C		V_{CC} = 3V, Topr = 25°C		V_{CC} = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	800	—	300	—	200	—	ns
$t_{W(CKH)}$	CLKi input “H” width	400	—	150	—	100	—	ns
$t_{W(CKL)}$	CLKi input “L” width	400	—	150	—	100	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	200	—	80	—	50	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	0	—	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	150	—	70	—	50	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	90	—	90	—	ns

i = 0 to 2

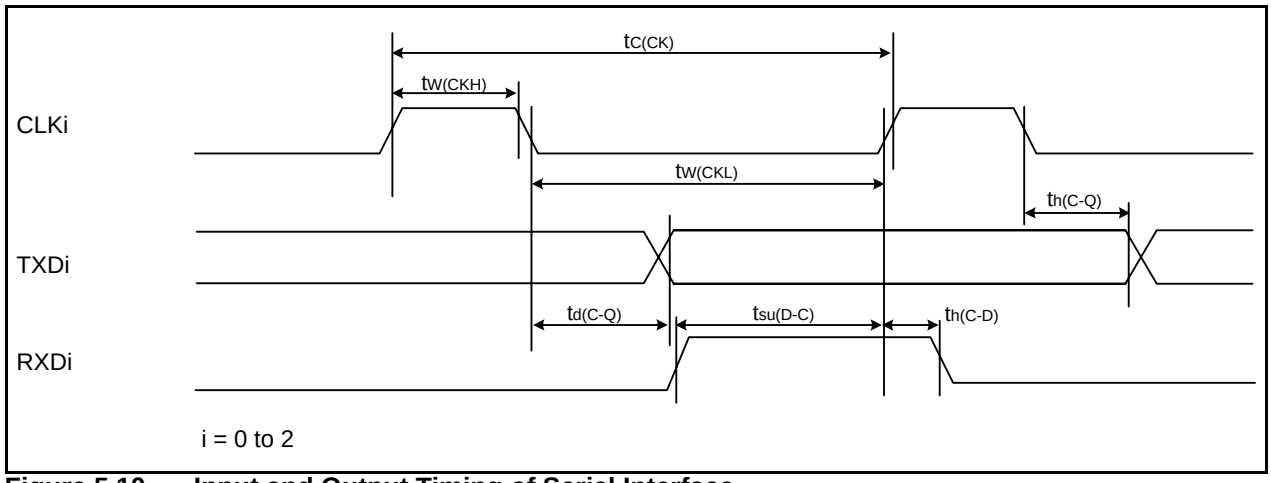


Figure 5.10 Input and Output Timing of Serial Interface

Table 5.29 Timing Requirements of External Interrupt $\overline{INTi}$ (i = 0 to 7) and Key Input Interrupt $\overline{KIi}$ (i = 0 to 7)
(V_{CC} = 1.8 to 5.5 V, V_{SS} = 0 V, and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		V_{CC} = 2.2V, Topr = 25°C		V_{CC} = 3V, Topr = 25°C		V_{CC} = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{W(INH)}$	$\overline{INTi}$ input “H” width, $\overline{KIi}$ input “H” width	1000 (1)	—	380 (1)	—	250 (1)	—	ns
$t_{W(INL)}$	$\overline{INTi}$ input “L” width, $\overline{KIi}$ input “L” width	1000 (2)	—	380 (2)	—	250 (2)	—	ns

Notes:
1. When selecting the digital filter by the $\overline{INTi}$ input filter select bit, use an $\overline{INTi}$ input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the $\overline{INTi}$ input filter select bit, use an $\overline{INTi}$ input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

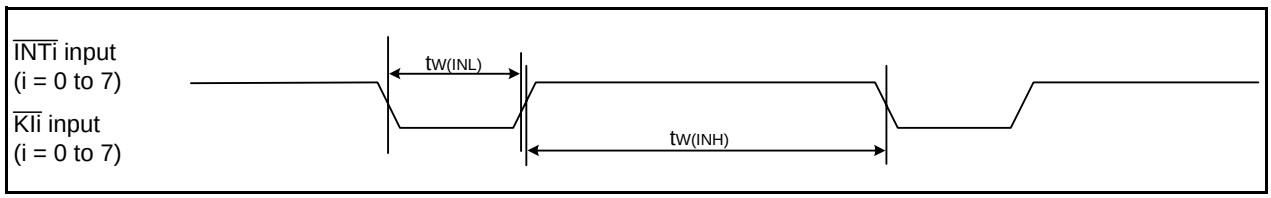
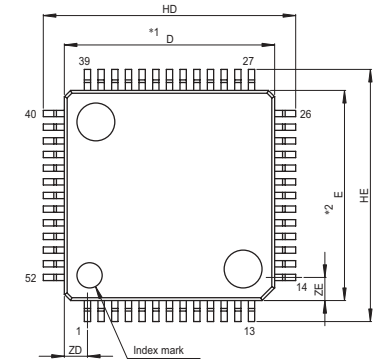


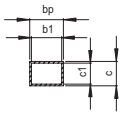
Figure 5.11 Input Timing of External Interrupt $\overline{INTi}$ and Key Input Interrupt $\overline{KIi}$

Package Dimensions

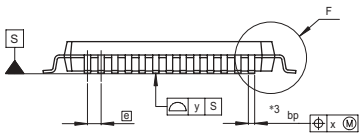
Diagrams showing the latest package dimensions and mounting information are available in the “Packages” section of the Renesas Electronics web site.

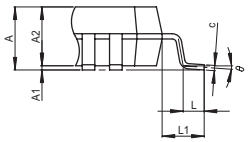
JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-LQFP52-10x10-0.65	PLQP0052JA-A	52P6A-A	0.3g





Terminal cross section



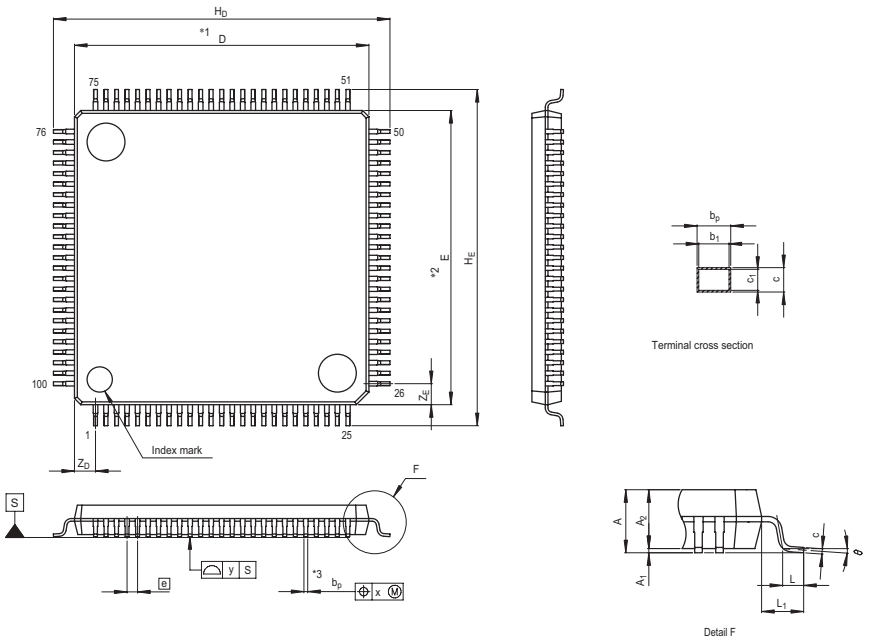


Detail F

NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	9.9	10.0	10.1
E	9.9	10.0	10.1
A_2	—	1.4	—
H_D	11.8	12.0	12.2
H_E	11.8	12.0	12.2
A	—	—	1.7
A_1	0.05	0.1	0.15
b_p	0.27	0.32	0.37
b_1	—	0.30	—
c	0.09	0.145	0.20
c_1	—	0.125	—
θ	0°	—	8°
e	—	0.65	—
x	—	—	0.13
y	—	—	0.10
Z_D	—	1.1	—
Z_E	—	1.1	—
L	0.35	0.5	0.65
L_1	—	1.0	—

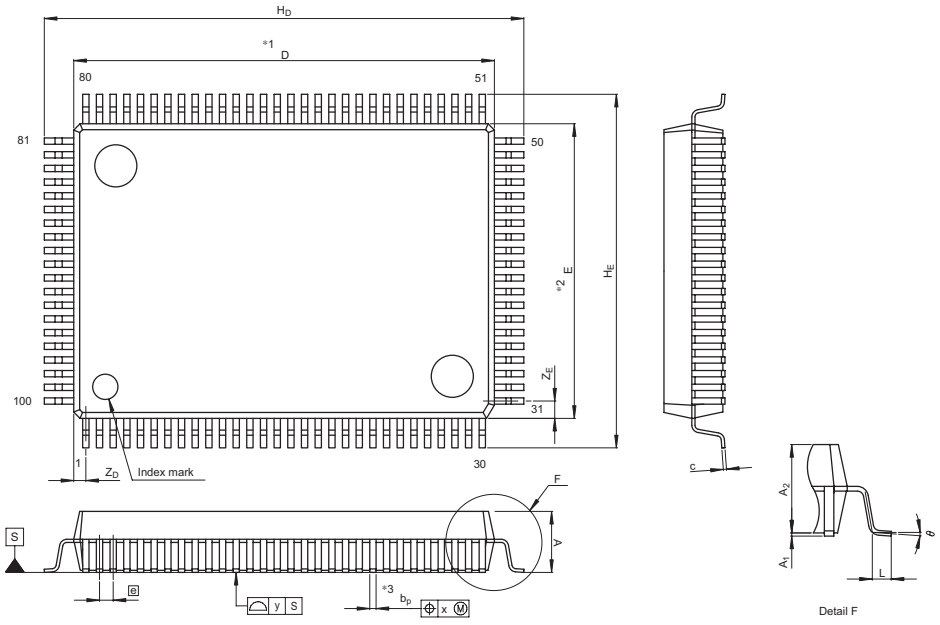
JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-LQFP100-14x14-0.50	PLQP0100KB-A	100P6Q-A / FP-100U / FP-100UV	0.6g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	13.9	14.0	14.1
E	13.9	14.0	14.1
A_2	—	1.4	—
H_D	15.8	16.0	16.2
H_E	15.8	16.0	16.2
A	—	—	1.7
A_1	0.05	0.1	0.15
b_p	0.15	0.20	0.25
b_1	—	0.18	—
c	0.09	0.145	0.20
c_1	—	0.125	—
θ	0°	—	8°
e	—	0.5	—
x	—	—	0.08
y	—	—	0.08
Z_D	—	1.0	—
Z_E	—	1.0	—
L	0.35	0.5	0.65
L_1	—	1.0	—

JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-QFP100-14x20-0.65	PRQP0100JD-B	100P6F-A	1.8g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	19.8	20.0	20.2
E	13.8	14.0	14.2
A_2	—	2.8	—
H_D	22.5	22.8	23.1
H_E	16.5	16.8	17.1
A	—	—	3.05
A_1	0	0.1	0.2
b_p	0.25	0.3	0.4
c	0.13	0.15	0.2
θ	0°	—	10°
e	—	0.65	—
x	—	—	0.13
y	—	—	0.10
Z_D	—	0.575	—
Z_E	—	0.825	—
L	0.4	0.6	0.8

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