Renesas Electronics America Inc - R5F2L38CMNFA#V1 Datasheet

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	I²C, LINbus, SIO, SSU, UART/USART
Peripherals	LCD, POR, PWM, Voltage Detect, WDT
Number of I/O	68
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 16x10b; D/A 2x8b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	80-LQFP
Supplier Device Package	80-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f2l38cmnfa-v1

1.1.2 Differences between Groups

Table 1.1 lists the Differences between Groups, Table 1.2 lists the Programmable I/O Ports Provided for Each Group, and Table 1.3 lists the LCD Display Function Pins Provided for Each Group. Figures 1.9 to 1.13 show the Pin Assignment for Each Group, and Tables 1.7 to 1.10 list Product Information.
The explanations in the chapters which follow apply to the R8C/L3AM Group only. Note the differences shown below.

Table 1.1 Differences between Groups

Item	Function	R8C/L35M Group	R8C/L36M Group	R8C/L38M Group	R8C/L3AM Group
I/O Ports	Programmable I/O ports	41 pins	52 pins	68 pins	88 pins
	High current drive ports	5 pins	8 pins	8 pins	16 pins
Interrupts	$\overline{\text{INT}}$ interrupt pins	5 pins	8 pins	8 pins	8 pins
	Key input interrupt pins	4 pins	4 pins	8 pins	8 pins
Timer RA	Timer RA output pin	None	1 pin	1 pin	1 pin
Timer RB	Timer RB output pin	None	1 pin	1 pin	1 pin
Timer RD	Timer RD I/O pin	None	None	8 pins	8 pins
Timer RE	Timer RE output pin	None	1 pin	1 pin	1 pin
Timer RG	Timer RG I/O pin	None	None	None	2 pins
	Timer RG output pin	None	None	None	2 pins
A/D Converter	Analog input pin	12 pins	12 pins	16 pins	20 pins
LCD Drive Control Circuit	LCD power supply	3 pins (VL1, VL2, VL4)	4 pins (VL1 to VL4)	4 pins (VL1 to VL4)	4 pins (VL1 to VL4)
	Common output pins	Max. 4 pins	Max. 8 pins	Max. 8 pins	Max. 8 pins
	Segment output pins	Max. 24 pins	Max. 32 pins	Max. 48 pins	Max. 56 pins
Packages		52-pin LQFP	64-pin LQFP	80-pin LQFP	100-pin LQFP/ 100-pin QFP

Note:
1. I/O ports are shared with I/O functions, such as interrupts or timers.
Refer to **Tables 1.11 to 1.13, Pin Name Information by Pin Number**, for details.

Table 1.5 Specifications (2)

Item	Function	Specification	
Timer	Timer RA	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), pulse output mode (output level inverted every period), event counter mode, pulse width measurement mode, pulse period measurement mode	
	Timer RB	8 bits × 1 (with 8-bit prescaler) Timer mode (period timer), programmable waveform generation mode (PWM output), programmable one-shot generation mode, programmable wait one-shot generation mode	
	Timer RC	16 bits × 1 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output: 3 pins), PWM2 mode (PWM output: 1 pin)	
	Timer RD	16 bits × 2 (with 4 capture/compare registers) Timer mode (input capture function, output compare function), PWM mode (output: 6 pins), reset synchronous PWM mode (three-phase waveform output: 6 pins, sawtooth wave modulation), complementary PWM mode (three-phase waveform output: 6 pins, triangular wave modulation), PWM3 mode (PWM output with fixed period: 2 pins)	
	Timer RE	8 bits × 1 Real-time clock mode (counting of seconds, minutes, hours, days of week), output compare mode	
	Timer RG	16 bits × 1 Phase-counting mode, timer mode (output compare function, input capture function), PWM mode (output: 1 pin)	
Serial Interface	UART0, UART1	Clock synchronous serial I/O/UART × 2 channels	
	UART2	Clock synchronous serial I/O/UART, I^2C mode (I^2C-bus), multiprocessor communication function	
Synchronous Serial Communication Unit (SSU)		1 (shared with I^2C-bus)	
I^2C bus		1 (shared with SSU)	
LIN Module		Hardware LIN: 1 channel (timer RA, UART0 used)	
A/D Converter	R8C/L35M Group	10-bit resolution × 12 channels, including sample and hold function, with sweep mode	
	R8C/L36M Group	10-bit resolution × 12 channels, including sample and hold function, with sweep mode	
	R8C/L38M Group	10-bit resolution × 16 channels, including sample and hold function, with sweep mode	
	R8C/L3AM Group	10-bit resolution × 20 channels, including sample and hold function, with sweep mode	
D/A Converter		8-bit resolution × 2 circuits	
Comparator A		• 2 circuits (sheared with voltage monitor 1 and voltage monitor 2) • External reference voltage input available	
Comparator B		2 circuits	
LCD Drive Control Circuit	R8C/L35M Group	Common output: Max. 4 pins Segment output: Max. 24 pins	Bias: 1/2, 1/3 Duty: static, 1/2, 1/3, 1/4
	R8C/L36M Group	Common output: Max. 8 pins Segment output: Max. 32 pins (1)	Bias: 1/2, 1/3, 1/4 Duty: static, 1/2, 1/3, 1/4, 1/8
	R8C/L38M Group	Common output: Max. 8 pins Segment output: Max. 48 pins (1)	
	R8C/L3AM Group	Common output: Max. 8 pins Segment output: Max. 56 pins (1)	
		Voltage multiplier and dedicated regulator integrated	

Note:
1. This applies when four pins are selected for common output.

Table 1.9 Product List for R8C/L38M Group **Current of Jun 2011**

Part No.	Internal ROM Capacity		Internal RAM Capacity	Package Type	Remarks
	Program ROM	Data Flash			
R5F2L387MNFP	48 Kbytes	1 Kbyte × 4	6 Kbytes	PLQP0080KB-A	N Version
R5F2L387MNFA	48 Kbytes	1 Kbyte × 4	6 Kbytes	PLQP0080JA-A	
R5F2L388MNFP	64 Kbytes	1 Kbyte × 4	8 Kbytes	PLQP0080KB-A	
R5F2L388MNFA	64 Kbytes	1 Kbyte × 4	8 Kbytes	PLQP0080JA-A	
R5F2L38AMNFP	96 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080KB-A	
R5F2L38AMNFA	96 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080JA-A	
R5F2L38CMNFP	128 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080KB-A	
R5F2L38CMNFA	128 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080JA-A	
R5F2L387MDFP	48 Kbytes	1 Kbyte × 4	6 Kbytes	PLQP0080KB-A	D Version
R5F2L387MDFA	48 Kbytes	1 Kbyte × 4	6 Kbytes	PLQP0080JA-A	
R5F2L388MDFP	64 Kbytes	1 Kbyte × 4	8 Kbytes	PLQP0080KB-A	
R5F2L388MDFA	64 Kbytes	1 Kbyte × 4	8 Kbytes	PLQP0080JA-A	
R5F2L38AMDFP	96 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080KB-A	
R5F2L38AMDFA	96 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080JA-A	
R5F2L38CMDFP	128 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080KB-A	
R5F2L38CMDFA	128 Kbytes	1 Kbyte × 4	10 Kbytes	PLQP0080JA-A	

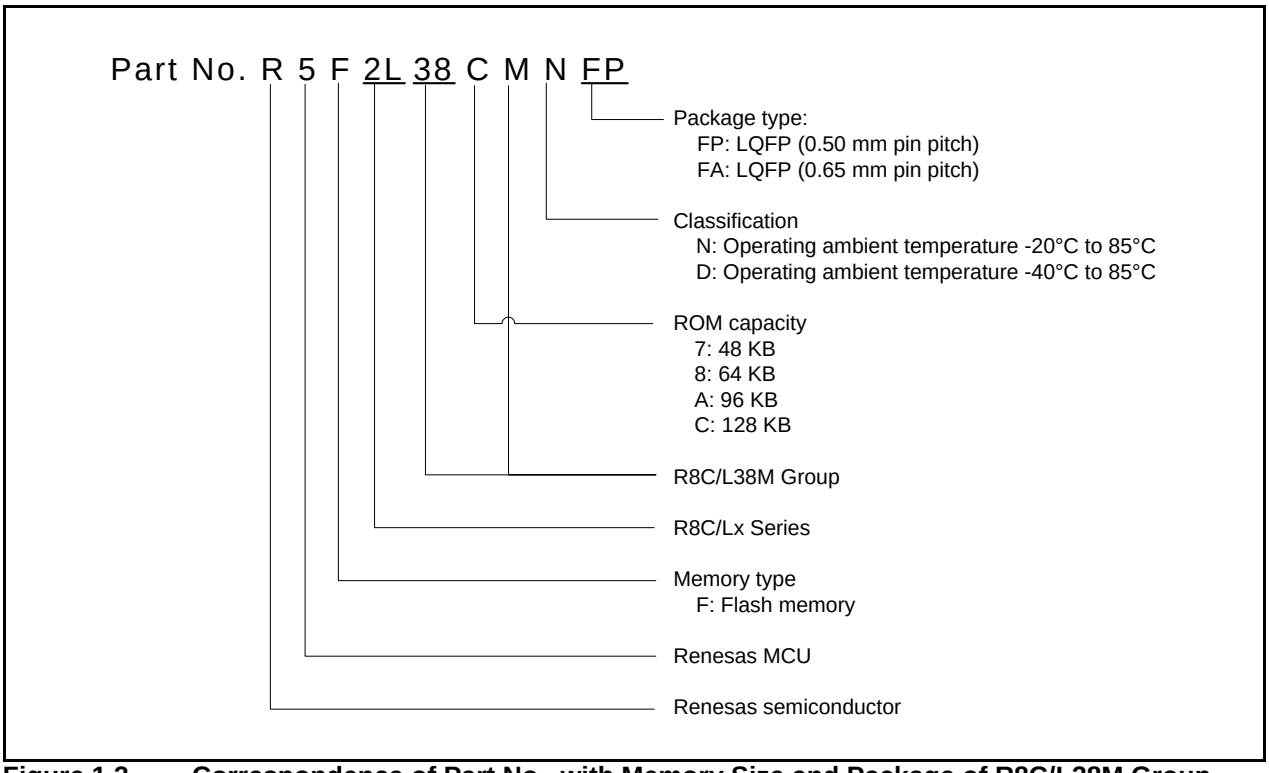


Figure 1.3 Correspondence of Part No., with Memory Size and Package of R8C/L38M Group

Table 1.13 Pin Name Information by Pin Number (3)

Pin Number				Control Pin	Port	I/O Pin Functions for Peripheral Modules						
L3AM (Note 2)	L38M	L36M	L35M			Interrupt	Timer	Serial Interface	SSU	I^2C bus	A/D Converter, D/A Converter, Comparator A, Comparator B, Voltage Detection Circuit	LCD drive control circuit
85 [87]	68	49	40		P0_5						AN9	SEG5
86 [88]	69	50	41		P0_4						AN8	SEG4
87 [89]	70	51	42		P0_3						AN7	SEG3
88 [90]	71	52	43		P0_2						AN6	SEG2
89 [91]	72	53	44		P0_1						AN5	SEG1
90 [92]	73	54	45		P0_0						AN4	SEG0
91 [93]	74	55	46									VL1
92 [94]	75	56	47									VL2
93 [95]	76	57										VL3
94 [96]	77	58	48		P12_3							CL2
95 [97]	78	59	49		P12_2							CL1
96 [98]	79	60	50									VL4
97 [99]					P13_7		TRGCLKB				AN19	
98 [100]					P13_6		TRGIOB				AN18	
99 [1]					P13_5		TRGCLKA				AN17	
100 [2]					P13_4		TRGIOA				AN16	

Notes:
1. The pin in parentheses can be assigned by a program.
2. The number in brackets indicates the pin number for the 100P6F package.

2.1 Data Registers (R0, R1, R2, and R3)

R0 is a 16-bit register for transfer, arithmetic, and logic operations. The same applies to R1 to R3. R0 can be split into high-order bits (R0H) and low-order bits (R0L) to be used separately as 8-bit data registers. R1H and R1L are analogous to R0H and R0L. R2 can be combined with R0 and used as a 32-bit data register (R2R0). R3R1 is analogous to R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. It is also used for transfer, arithmetic, and logic operations. A1 is analogous to A0. A1 can be combined with A0 and as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register that indicates the starting address of an interrupt vector table.

2.5 Program Counter (PC)

PC is 20 bits wide and indicates the address of the next instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointers (SP), USP and ISP, are each 16 bits wide. The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is an 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains carry, borrow, or shift-out bits that have been generated by the arithmetic and logic unit.

2.8.2 Debug Flag (D)

The D flag is for debugging only. Set it to 0.

2.8.3 Zero Flag (Z)

The Z flag is set to 1 when an arithmetic operation results in 0; otherwise to 0.

2.8.4 Sign Flag (S)

The S flag is set to 1 when an arithmetic operation results in a negative value; otherwise to 0.

2.8.5 Register Bank Select Flag (B)

Register bank 0 is selected when the B flag is 0. Register bank 1 is selected when this flag is set to 1.

2.8.6 Overflow Flag (O)

The O flag is set to 1 when an operation results in an overflow; otherwise to 0.

2.8.7 Interrupt Enable Flag (I)

The I flag enables maskable interrupts.
Interrupts are disabled when the I flag is set to 0, and are enabled when the I flag is set to 1. The I flag is set to 0 when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to 0; USP is selected when the U flag is set to 1.
The U flag is set to 0 when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is 3 bits wide and assigns processor interrupt priority levels from level 0 to level 7.
If a requested interrupt has higher priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

If necessary, set to 0. When read, the content is undefined.

Table 4.2 SFR Information (2) (1)

Address	Register	Symbol	After Reset
003Ah	Voltage Monitor 2 Circuit Control Register	VW2C	10000010b
003Bh			
003Ch			
003Dh			
003Eh			
003Fh			
0040h			
0041h	Flash Memory Ready Interrupt Control Register	FMRDYIC	XXXXX000b
0042h			
0043h	INT7 Interrupt Control Register	INT7IC	XX00X000b
0044h	INT6 Interrupt Control Register	INT6IC	XX00X000b
0045h	INT5 Interrupt Control Register	INT5IC	XX00X000b
0046h	INT4 Interrupt Control Register	INT4IC	XX00X000b
0047h	Timer RC Interrupt Control Register	TRCIC	XXXXX000b
0048h	Timer RD0 Interrupt Control Register	TRD0IC	XXXXX000b
0049h	Timer RD1 Interrupt Control Register	TRD1IC	XXXXX000b
004Ah	Timer RE Interrupt Control Register	TREIC	XXXXX000b
004Bh	UART2 Transmit Interrupt Control Register	S2TIC	XXXXX000b
004Ch	UART2 Receive Interrupt Control Register	S2RIC	XXXXX000b
004Dh	Key Input Interrupt Control Register	KUPIC	XXXXX000b
004Eh	A/D Conversion Interrupt Control Register	ADIC	XXXXX000b
004Fh	SSU Interrupt Control Register / IIC bus Interrupt Control Register (2)	SSUIC/IICIC	XXXXX000b
0050h			
0051h	UART0 Transmit Interrupt Control Register	S0TIC	XXXXX000b
0052h	UART0 Receive Interrupt Control Register	S0RIC	XXXXX000b
0053h	UART1 Transmit Interrupt Control Register	S1TIC	XXXXX000b
0054h	UART1 Receive Interrupt Control Register	S1RIC	XXXXX000b
0055h	INT2 Interrupt Control Register	INT2IC	XX00X000b
0056h	Timer RA Interrupt Control Register	TRAIC	XXXXX000b
0057h			
0058h	Timer RB Interrupt Control Register	TRBIC	XXXXX000b
0059h	INT1 Interrupt Control Register	INT1IC	XX00X000b
005Ah	INT3 Interrupt Control Register	INT3IC	XX00X000b
005Bh			
005Ch			
005Dh	INT0 Interrupt Control Register	INT0IC	XX00X000b
005Eh	UART2 Bus Collision Detection Interrupt Control Register	U2BCNIC	XXXXX000b
005Fh			
0060h			
0061h			
0062h			
0063h			
0064h			
0065h			
0066h			
0067h			
0068h			
0069h			
006Ah			
006Bh	Timer RG Interrupt Control Register	TRGIC	XXXXX000b
006Ch			
006Dh			
006Eh			
006Fh			
0070h			
0071h			
0072h	Voltage monitor 1 / Comparator A1 Interrupt Control Register	VCMP1IC	XXXXX000b
0073h	Voltage monitor 2 / Comparator A2 Interrupt Control Register	VCMP2IC	XXXXX000b
0074h			
0075h			
0076h			
0077h			
0078h			
0079h			
007Ah			
007Bh			
007Ch			
007Dh			
007Eh			
007Fh			

X: Undefined

Notes:
1. Blank spaces are reserved. No access is allowed.
2. Selectable by the IICSEL bit in the SSUIICSR register.

Table 4.3 SFR Information (3) (1)

Address	Register	Symbol	After Reset
0080h	DTC Activation Control Register	DTCTL	00h
0081h			
0082h			
0083h			
0084h			
0085h			
0086h			
0087h			
0088h	DTC Activation Enable Register 0	DTCEN0	00h
0089h	DTC Activation Enable Register 1	DTCEN1	00h
008Ah	DTC Activation Enable Register 2	DTCEN2	00h
008Bh	DTC Activation Enable Register 3	DTCEN3	00h
008Ch	DTC Activation Enable Register 4	DTCEN4	00h
008Dh	DTC Activation Enable Register 5	DTCEN5	00h
008Eh	DTC Activation Enable Register 6	DTCEN6	00h
008Fh			
0090h			
0091h			
0092h			
0093h			
0094h			
0095h			
0096h			
0097h			
0098h			
0099h			
009Ah			
009Bh			
009Ch			
009Dh			
009Eh			
009Fh			
00A0h	UART0 Transmit/Receive Mode Register	U0MR	00h
00A1h	UART0 Bit Rate Register	U0BRG	XXh
00A2h	UART0 Transmit Buffer Register	U0TB	XXh
00A3h			XXh
00A4h	UART0 Transmit/Receive Control Register 0	U0C0	00001000b
00A5h	UART0 Transmit/Receive Control Register 1	U0C1	00000010b
00A6h	UART0 Receive Buffer Register	U0RB	XXh
00A7h			XXh
00A8h	UART2 Transmit/Receive Mode Register	U2MR	00h
00A9h	UART2 Bit Rate Register	U2BRG	XXh
00AAh	UART2 Transmit Buffer Register	U2TB	XXh
00ABh			XXh
00ACh	UART2 Transmit/Receive Control Register 0	U2C0	00001000b
00ADh	UART2 Transmit/Receive Control Register 1	U2C1	00000010b
00AEh	UART2 Receive Buffer Register	U2RB	XXh
00AFh			XXh
00B0h	UART2 Digital Filter Function Select Register	URXDF	00h
00B1h			
00B2h			
00B3h			
00B4h			
00B5h			
00B6h			
00B7h			
00B8h			
00B9h			
00BAh			
00BBh	UART2 Special Mode Register 5	U2SMR5	00h
00BCh	UART2 Special Mode Register 4	U2SMR4	00h
00BDh	UART2 Special Mode Register 3	U2SMR3	000X0X0Xb
00BEh	UART2 Special Mode Register 2	U2SMR2	X0000000b
00BFh	UART2 Special Mode Register	U2SMR	X0000000b

X: Undefined

Note:

1. Blank spaces are reserved. No access is allowed.

Table 4.9 SFR Information (9) (1)

Address	Register	Symbol	After Reset
0200h	LCD Control Register	LCR0	00h
0201h	LCD Bias Control Register	LCR1	00h
0202h	LCD Display Control Register	LCR2	X0000000b
0203h	LCD Clock Control Register	LCR3	00h
0204h			
0205h			
0206h	LCD Port Select Register 0	LSE0	00h
0207h	LCD Port Select Register 1	LSE1	00h
0208h	LCD Port Select Register 2	LSE2	00h
0209h	LCD Port Select Register 3	LSE3	00h
020Ah	LCD Port Select Register 4	LSE4	00h
020Bh	LCD Port Select Register 5	LSE5	00h
020Ch	LCD Port Select Register 6	LSE6	00h
020Dh	LCD Port Select Register 7	LSE7	00h
020Eh			
020Fh			
0210h	LCD Display Data Register	LRA0L	XXh
0211h		LRA1L	XXh
0212h		LRA2L	XXh
0213h		LRA3L	XXh
0214h		LRA4L	XXh
0215h		LRA5L	XXh
0216h		LRA6L	XXh
0217h		LRA7L	XXh
0218h		LRA8L	XXh
0219h		LRA9L	XXh
021Ah		LRA10L	XXh
021Bh		LRA11L	XXh
021Ch		LRA12L	XXh
021Dh		LRA13L	XXh
021Eh		LRA14L	XXh
021Fh		LRA15L	XXh
0220h		LRA16L	XXh
0221h		LRA17L	XXh
0222h		LRA18L	XXh
0223h		LRA19L	XXh
0224h		LRA20L	XXh
0225h		LRA21L	XXh
0226h		LRA22L	XXh
0227h		LRA23L	XXh
0228h		LRA24L	XXh
0229h		LRA25L	XXh
022Ah		LRA26L	XXh
022Bh		LRA27L	XXh
022Ch		LRA28L	XXh
022Dh		LRA29L	XXh
022Eh		LRA30L	XXh
022Fh		LRA31L	XXh
0230h		LRA32L	XXh
0231h		LRA33L	XXh
0232h		LRA34L	XXh
0233h		LRA35L	XXh
0234h		LRA36L	XXh
0235h		LRA37L	XXh
0236h		LRA38L	XXh
0237h		LRA39L	XXh
0238h		LRA40L	XXh
0239h		LRA41L	XXh
023Ah		LRA42L	XXh
023Bh		LRA43L	XXh
023Ch		LRA44L	XXh
023Dh		LRA45L	XXh
023Eh		LRA46L	XXh
023Fh		LRA47L	XXh

X: Undefined

Note:

1. Blank spaces are reserved. No access is allowed.

Table 4.13 SFR Information (13) (1)

Address	Register	Symbol	After Reset
2C00h	DTC Transfer Vector Area		XXh
2C01h	DTC Transfer Vector Area		XXh
2C02h	DTC Transfer Vector Area		XXh
2C03h	DTC Transfer Vector Area		XXh
2C04h	DTC Transfer Vector Area		XXh
2C05h	DTC Transfer Vector Area		XXh
2C06h	DTC Transfer Vector Area		XXh
2C07h	DTC Transfer Vector Area		XXh
2C08h	DTC Transfer Vector Area		XXh
2C09h	DTC Transfer Vector Area		XXh
2C0Ah	DTC Transfer Vector Area		XXh
:	DTC Transfer Vector Area		XXh
:	DTC Transfer Vector Area		XXh
2C3Ah	DTC Transfer Vector Area		XXh
2C3Bh	DTC Transfer Vector Area		XXh
2C3Ch	DTC Transfer Vector Area		XXh
2C3Dh	DTC Transfer Vector Area		XXh
2C3Eh	DTC Transfer Vector Area		XXh
2C3Fh	DTC Transfer Vector Area		XXh
2C40h	DTC Control Data 0	DTCD0	XXh
2C41h			XXh
2C42h			XXh
2C43h			XXh
2C44h			XXh
2C45h			XXh
2C46h			XXh
2C47h			XXh
2C48h	DTC Control Data 1	DTCD1	XXh
2C49h			XXh
2C4Ah			XXh
2C4Bh			XXh
2C4Ch			XXh
2C4Dh			XXh
2C4Eh			XXh
2C4Fh			XXh
2C50h	DTC Control Data 2	DTCD2	XXh
2C51h			XXh
2C52h			XXh
2C53h			XXh
2C54h			XXh
2C55h			XXh
2C56h			XXh
2C57h			XXh
2C58h	DTC Control Data 3	DTCD3	XXh
2C59h			XXh
2C5Ah			XXh
2C5Bh			XXh
2C5Ch			XXh
2C5Dh			XXh
2C5Eh			XXh
2C5Fh			XXh
2C60h	DTC Control Data 4	DTCD4	XXh
2C61h			XXh
2C62h			XXh
2C63h			XXh
2C64h			XXh
2C65h			XXh
2C66h			XXh
2C67h			XXh
2C68h	DTC Control Data 5	DTCD5	XXh
2C69h			XXh
2C6Ah			XXh
2C6Bh			XXh
2C6Ch			XXh
2C6Dh			XXh
2C6Eh			XXh
2C6Fh			XXh

X: Undefined
Note:
1. Blank spaces are reserved. No access is allowed.

Table 5.8 Flash Memory (Data flash Block A to Block D) Characteristics (V_{CC} = 2.7 to 5.5 V and T_{opr} = −20 to 85°C (N version) / −40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
—	Program/erase endurance (1)		10,000 (2)	—	—	times
—	Byte program time (program/erase endurance ≤ 1,000 times)		—	160	1500	µs
—	Byte program time (program/erase endurance > 1,000 times)		—	300	1500	µs
—	Block erase time (program/erase endurance ≤ 1,000 times)		—	0.2	1	s
—	Block erase time (program/erase endurance > 1,000 times)		—	0.3	1	s
$t_{d(SR-SUS)}$	Time delay from suspend request until suspend		—	—	5 + CPU clock × 3 cycles	ms
—	Interval from erase start/restart until following suspend request		0	—	—	ms
—	Time from suspend until erase restart		—	—	30+CPU clock × 1 cycle	µs
$t_{d(CMDRST-READY)}$	Time from when command is forcibly terminated until reading is enabled		—	—	30+CPU clock × 1 cycle	µs
—	Program, erase voltage		2.7	—	5.5	V
—	Read voltage		1.8	—	5.5	V
—	Program, erase temperature		−20 (6)	—	85	°C
—	Data hold time (7)	Ambient temperature = 55 °C	20	—	—	year

Notes:
1. Definition of programming/erasure endurance
   The programming and erasure endurance is defined on a per-block basis.
   If the programming and erasure endurance is n (n = 10,000), each block can be erased n times. For example, if 1,024 1-byte writes are performed to different addresses in block A, a 1 Kbyte block, and then the block is erased, the programming/erasure endurance still stands at one.
   However, the same address must not be programmed more than once per erase operation (overwriting prohibited).
2. Endurance to guarantee all electrical characteristics after program and erase. (1 to Min. value can be guaranteed).
3. In a system that executes multiple programming operations, the actual erasure count can be reduced by writing to sequential addresses in turn so that as much of the block as possible is used up before performing an erase operation. For example, when programming groups of 16 bytes, the effective number of rewrites can be minimized by programming up to 128 groups before erasing them all in one operation. In addition, averaging the erasure endurance between blocks A to D can further reduce the actual erasure endurance. It is also advisable to retain data on the erasure endurance of each block and limit the number of erase operations to a certain number.
4. If an error occurs during block erase, attempt to execute the clear status register command, then execute the block erase command at least three times until the erase error does not occur.
5. Customers desiring program/erase failure rate information should contact their Renesas technical support representative.
6. −40°C for D version.
7. The data hold time includes time that the power supply is off or the clock is not supplied.

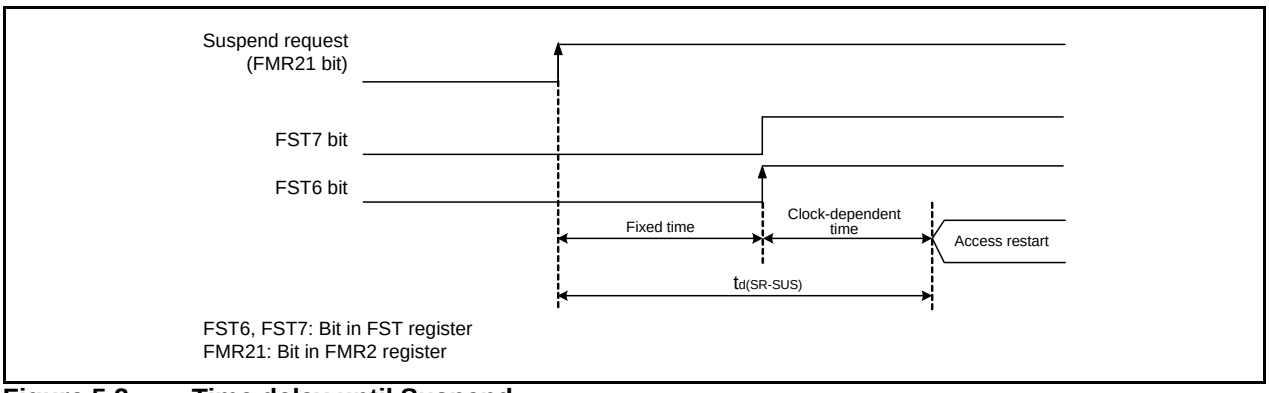


Figure 5.2 Time delay until Suspend

Table 5.9 Voltage Detection 0 Circuit Characteristics (Vcc = 1.8 to 5.5 V and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V_{det0}	Voltage detection level Vdet0_0 (1)		1.80	1.90	2.05	V
	Voltage detection level Vdet0_1 (1)		2.15	2.35	2.50	V
	Voltage detection level Vdet0_2 (1)		2.70	2.85	3.05	V
	Voltage detection level Vdet0_3 (1)		3.55	3.80	4.05	V
—	Voltage detection 0 circuit response time (3)	At the falling of Vcc from 5 V to (Vdet0_0 – 0.1) V	—	6	150	µs
—	Voltage detection circuit self power consumption	VCA25 = 1, Vcc = 5.0 V	—	1.5	—	µA
$t_{d(E-A)}$	Waiting time until voltage detection circuit operation starts (2)		—	—	100	µs

Notes:
1. Select the voltage detection level with bits VDSEL0 and VDSEL1 in the OFS register.
2. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA25 bit in the VCA2 register to 0.
3. Time until the voltage monitor 0 reset is generated after the voltage passes V_{det0}.

Table 5.10 Voltage Detection 1 Circuit Characteristics (Vcc = 1.8 to 5.5 V and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
V_{det1}	Voltage detection level Vdet1_0 (1)	At the falling of Vcc	2.00	2.20	2.40	V
	Voltage detection level Vdet1_1 (1)	At the falling of Vcc	2.15	2.35	2.55	V
	Voltage detection level Vdet1_2 (1)	At the falling of Vcc	2.30	2.50	2.70	V
	Voltage detection level Vdet1_3 (1)	At the falling of Vcc	2.45	2.65	2.85	V
	Voltage detection level Vdet1_4 (1)	At the falling of Vcc	2.60	2.80	3.00	V
	Voltage detection level Vdet1_5 (1)	At the falling of Vcc	2.75	2.95	3.15	V
	Voltage detection level Vdet1_6 (1)	At the falling of Vcc	2.85	3.10	3.40	V
	Voltage detection level Vdet1_7 (1)	At the falling of Vcc	3.00	3.25	3.55	V
	Voltage detection level Vdet1_8 (1)	At the falling of Vcc	3.15	3.40	3.70	V
	Voltage detection level Vdet1_9 (1)	At the falling of Vcc	3.30	3.55	3.85	V
	Voltage detection level Vdet1_A (1)	At the falling of Vcc	3.45	3.70	4.00	V
	Voltage detection level Vdet1_B (1)	At the falling of Vcc	3.60	3.85	4.15	V
	Voltage detection level Vdet1_C (1)	At the falling of Vcc	3.75	4.00	4.30	V
	Voltage detection level Vdet1_D (1)	At the falling of Vcc	3.90	4.15	4.45	V
	Voltage detection level Vdet1_E (1)	At the falling of Vcc	4.05	4.30	4.60	V
	Voltage detection level Vdet1_F (1)	At the falling of Vcc	4.20	4.45	4.75	V
—	Hysteresis width at the rising of Vcc in voltage detection 1 circuit	Vdet1_0 to Vdet1_5 selected	—	0.07	—	V
		Vdet1_6 to Vdet1_F selected	—	0.10	—	V
—	Voltage detection 1 circuit response time (2)	At the falling of Vcc from 5 V to (Vdet1_0 – 0.1) V	—	60	150	µs
—	Voltage detection circuit self power consumption	VCA26 = 1, Vcc = 5.0 V	—	1.7	—	µA
$t_{d(E-A)}$	Waiting time until voltage detection circuit operation starts (3)		—	—	100	µs

Notes:
1. Select the voltage detection level with bits VD1S0 to VD1S3 in the VD1LS register.
2. Time until the voltage monitor 1 interrupt request is generated after the voltage passes V_{det1}.
3. Necessary time until the voltage detection circuit operates when setting to 1 again after setting the VCA26 bit in the VCA2 register to 0.

Table 5.16 LCD Drive Control Circuit Characteristics (VCC = 1.8 to 5.5 V, VSS = 0 V, and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
VLCD	LCD power supply voltage	VLCD = VL4	2.2	—	5.5	V
VL3	VL3 voltage		VL2	—	VL4	V
VL2	VL2 voltage	R8C/L35M	VL1	—	VL4	V
		R8C/L36M, R8C/L38M, R8C/L3AM	VL1	—	VL3	V
VL1	VL1 voltage		1	—	VL2 (3)	V
—	VL1 internally-generated voltage accuracy (1)		Setting voltage –0.2	Setting voltage	Setting voltage +0.2	V
f(FR)	Frame frequency		50	—	180	Hz
ILCD	LCD drive control circuit current		—	(Note 2)	—	µA

Notes:
1. The voltage is selected with bits LVLS0 to LVLS3 in the LCR1 register.
2. Refer to **Table 5.19 DC Characteristics (2)**, **Table 5.21 DC Characteristics (4)**, and **Table 5.23 DC Characteristics (6)**.
3. The VL1 voltage should be VCC or below.

Table 5.17 Power-Off Mode Characteristics (VCC = 2.2 to 5.5 V, VSS = 0 V, and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition	Standard			Unit
			Min.	Typ.	Max.	
—	Power-off mode operating supply voltage		2.2	—	5.5	V

5.4 DC Characteristics

Table 5.18 DC Characteristics (1) [4.0 V ≤ Vcc ≤ 5.5 V]
(Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter		Condition		Standard			Unit
					Min.	Typ.	Max.	
V_{OH}	Output “H” voltage	Port P10, P11 (1)	V_{CC} = 5V	I_{OH} = –20 mA	V_{CC} – 2.0	—	V_{CC}	V
		Other pins	V_{CC} = 5V	I_{OH} = –5 mA	V_{CC} – 2.0	—	V_{CC}	V
		XOUT	V_{CC} = 5V	I_{OH} = –200 μA	1.0	—	—	V
V_{OL}	Output “L” voltage	Port P10, P11 (1)	V_{CC} = 5V	I_{OL} = 20 mA	—	—	2.0	V
		Other pins	V_{CC} = 5V	I_{OL} = 5 mA	—	—	2.0	V
		XOUT	V_{CC} = 5V	I_{OL} = 200 μA	—	—	0.5	V
V_{T+}-V_{T-}	Hysteresis	$\overline{INT0}$, $\overline{INT1}$, $\overline{INT2}$, $\overline{INT3}$, $\overline{INT4}$, $\overline{INT5}$, $\overline{INT6}$, $\overline{INT7}$, $\overline{KI0}$, $\overline{KI1}$, $\overline{KI2}$, $\overline{KI3}$, KI4, KI5, KI6, KI7, TRAIO, TRCIOA, TRCIOB, TRCIOC, TRCIOD, TRDIOA0, TRDIOB0, TRDIOC0, TRDIOD0, TRDIOA1, TRDIOB1, TRDIOC1, TRDIOD1, TRCTRG, TRCCLK, TRGCLKA, TRGCLKB, TRGIOA, TRGIOB, $\overline{ADTRG}$, RXD0, RXD1, RXD2, CLK0, CLK1, CLK2, SSI, SCL, SDA, SSO			0.05	0.5	—	V
		$\overline{RESET}$, $\overline{WKUP0}$			0.1	1.0	—	V
I_{IH}	Input “H” current		VI = 5.0 V, V_{CC} = 5.0 V		—	—	5.0	μA
I_{IL}	Input “L” current		VI = 0 V, V_{CC} = 5.0 V		—	—	–5.0	μA
R_{PULLUP}	Pull-up resistance		VI = 0 V, V_{CC} = 5.0 V		25	50	100	kΩ
R_{fXIN}	Feedback resistance	XIN			—	0.3	—	MΩ
R_{fXCIN}	Feedback resistance	XCIN			—	14	—	MΩ
V_{RAM}	RAM hold voltage		During stop mode		1.8	—	—	V

Note:
1. This applies when the drive capacity of the output transistor is set to High by registers P10DRR and P11DRR. When the drive capacity is set to Low, the value of any other pin applies.

Table 5.19 DC Characteristics (2) [4.0 V ≤ Vcc ≤ 5.5 V]
(Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Condition								Standard			Unit
			Oscillation Circuit		On-Chip Oscillator		CPU Clock	Low-Power-Consumption Setting	Other	Min.	Typ. (3)	Max.	
			XIN (2)	XCIN	High-Speed (fOCO-F)	Low-Speed							
Icc	Power supply current (1)	High-speed clock mode	20 MHz	Off	Off	125 kHz	No division	—		—	7.0	15	mA
			16 MHz	Off	Off	125 kHz	No division	—		—	5.6	12.5	mA
			10 MHz	Off	Off	125 kHz	No division	—		—	3.6	—	mA
			20 MHz	Off	Off	125 kHz	Divide-by-8	—		—	3.0	—	mA
			16 MHz	Off	Off	125 kHz	Divide-by-8	—		—	2.2	—	mA
			10 MHz	Off	Off	125 kHz	Divide-by-8	—		—	1.5	—	mA
		High-speed on-chip oscillator mode	Off	Off	20 MHz	125 kHz	No division	—		—	7.0	15	mA
			Off	Off	20 MHz	125 kHz	Divide-by-8	—		—	3.0	—	mA
			Off	Off	4 MHz	125 kHz	Divide-by-16	MSTIIC = 1 MSTTRD = 1 MSTTRC = 1 MSTTRG = 1		—	1	—	mA
		Low-speed on-chip oscillator mode	Off	Off	Off	125 kHz	Divide-by-8	FMR27 = 1 VCA20 = 0		—	90	400	µA
		Low-speed clock mode	Off	32 kHz	Off	Off	No division	FMR27 = 1 VCA20 = 0		—	100	400	µA
			Off	32 kHz	Off	Off	No division	FMSTP = 1 VCA20 = 0	Flash memory off Program operation on RAM	—	55	—	µA
		Wait mode	Off	Off	Off	125 kHz	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1	While a WAIT instruction is executed Peripheral clock operation	—	15	100	µA
			Off	Off	Off	125 kHz	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 1	While a WAIT instruction is executed Peripheral clock off	—	4	90	µA
			Off	32 kHz	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 0	While a WAIT instruction is executed Peripheral clock off Timer RE operation in real-time clock mode	LCD drive control circuit (4) When external division resistors are used	—	7	—	µA
										LCD drive control circuit (5) When the internal voltage multiplier is used	—	12	—	µA
			Off	32 kHz	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 VCA20 = 1 CM02 = 1 CM01 = 1	While a WAIT instruction is executed Peripheral clock off Timer RE operation in real-time clock mode		—	3.5	—	µA
		Stop mode	Off	Off	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 CM10 = 1	Topr = 25°C Peripheral clock off		—	2.0	5.0	µA
			Off	Off	Off	Off	—	VCA27 = 0 VCA26 = 0 VCA25 = 0 CM10 = 1	Topr = 85°C Peripheral clock off		—	15	—	µA
		Power-off mode	Off	Off	Off	Off	—	—	Power-off 0 Topr = 25°C		—	0.02	0.2	µA
			Off	Off	Off	Off	—	—	Power-off 0 Topr = 85°C		—	0.4	—	µA
			Off	32 kHz	Off	Off	—	—	Power-off 1 Topr = 25°C		—	1.6	3.2	µA
			Off	32 kHz	Off	Off	—	—	Power-off 1 Topr = 85°C		—	2.0	—	µA

Notes:
1. Vcc = 4.0 V to 5.5 V, single chip mode, output pins are open, and other pins are Vss.
2. XIN is set to square wave input.
3. Vcc = 5.0 V
4. VLCD = Vcc, external division resistors are used for VL4 to VL1, 1/3 bias, 1/4 duty, f(FR) = 64 Hz, SEG0 to SEG55 are selected, and segment and common output pins are open. The standard value does not include the current that flows through external division resistors.
5. The internal voltage multiplier is used, bits LVLS3 to LVLS0 in the LCR1 register = 1011b, 1/3 bias, 1/4 duty, f(FR) = 64 Hz, SEG0 to SEG55 are selected, and segment and common output pins are open.

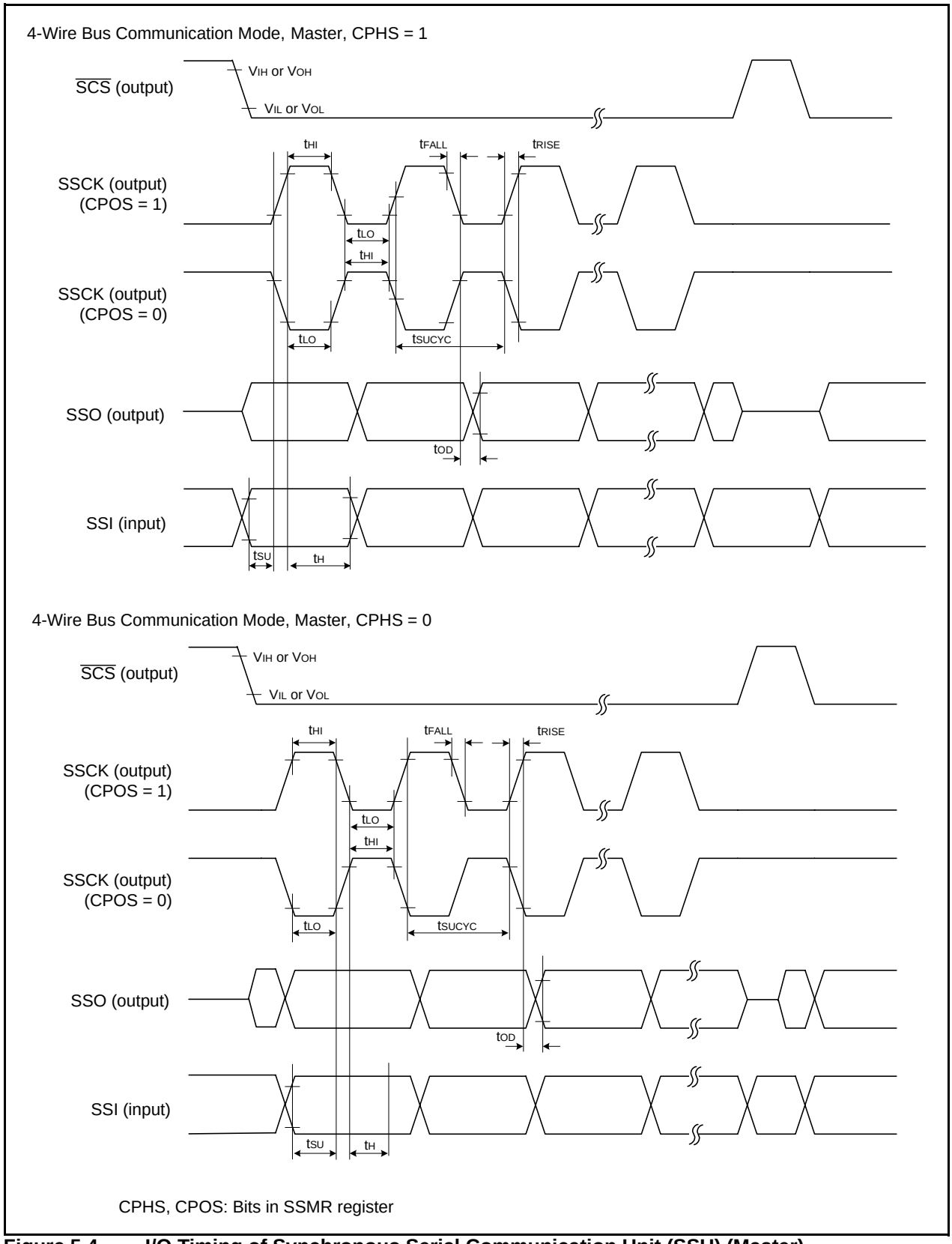


Figure 5.4 I/O Timing of Synchronous Serial Communication Unit (SSU) (Master)

Table 5.26 External Clock Input (XIN, XCIN)
(Vcc = 1.8 to 5.5 V, Vss = 0 V, and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		Vcc = 2.2V, Topr = 25°C		Vcc = 3V, Topr = 25°C		Vcc = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(XIN)}$	XIN input cycle time	200	—	50	—	50	—	ns
$t_{WH(XIN)}$	XIN input “H” width	90	—	24	—	24	—	ns
$t_{WL(XIN)}$	XIN input “L” width	90	—	24	—	24	—	ns
$t_{c(XCIN)}$	XCIN input cycle time	14	—	14	—	14	—	µs
$t_{WH(XCIN)}$	XCIN input “H” width	7	—	7	—	7	—	µs
$t_{WL(XCIN)}$	XCIN input “L” width	7	—	7	—	7	—	µs

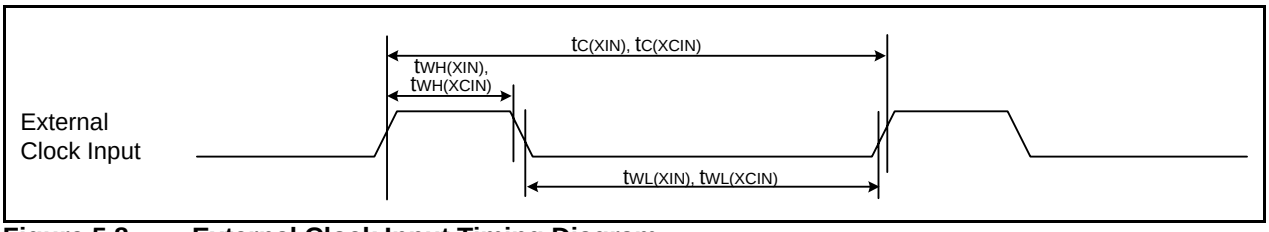


Figure 5.8 External Clock Input Timing Diagram

Table 5.27 Timing Requirements of TRAIO
(Vcc = 1.8 to 5.5 V, Vss = 0 V and Topr = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		Vcc = 2.2V, Topr = 25°C		Vcc = 3V, Topr = 25°C		Vcc = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(TRAIO)}$	TRAIO input cycle time	500	—	300	—	100	—	ns
$t_{WH(TRAIO)}$	TRAIO input “H” width	200	—	120	—	40	—	ns
$t_{WL(TRAIO)}$	TRAIO input “L” width	200	—	120	—	40	—	ns

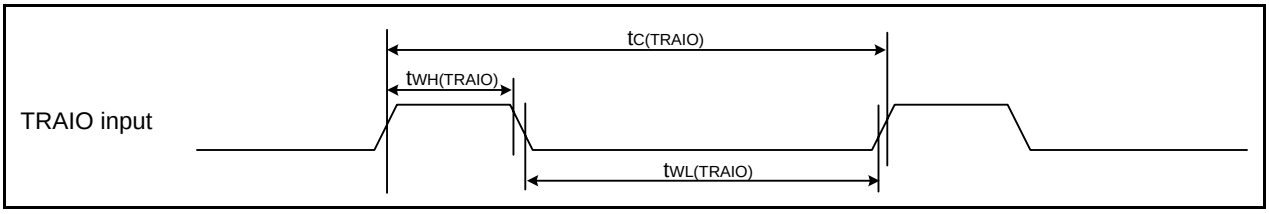


Figure 5.9 Input Timing of TRAIO

Table 5.28 Timing Requirements of Serial Interface
(V_{CC} = 1.8 to 5.5 V, V_{SS} = 0 V, and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		V_{CC} = 2.2V, Topr = 25°C		V_{CC} = 3V, Topr = 25°C		V_{CC} = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	800	—	300	—	200	—	ns
$t_{W(CKH)}$	CLKi input “H” width	400	—	150	—	100	—	ns
$t_{W(CKL)}$	CLKi input “L” width	400	—	150	—	100	—	ns
$t_{d(C-Q)}$	TXDi output delay time	—	200	—	80	—	50	ns
$t_{h(C-Q)}$	TXDi hold time	0	—	0	—	0	—	ns
$t_{su(D-C)}$	RXDi input setup time	150	—	70	—	50	—	ns
$t_{h(C-D)}$	RXDi input hold time	90	—	90	—	90	—	ns

i = 0 to 2

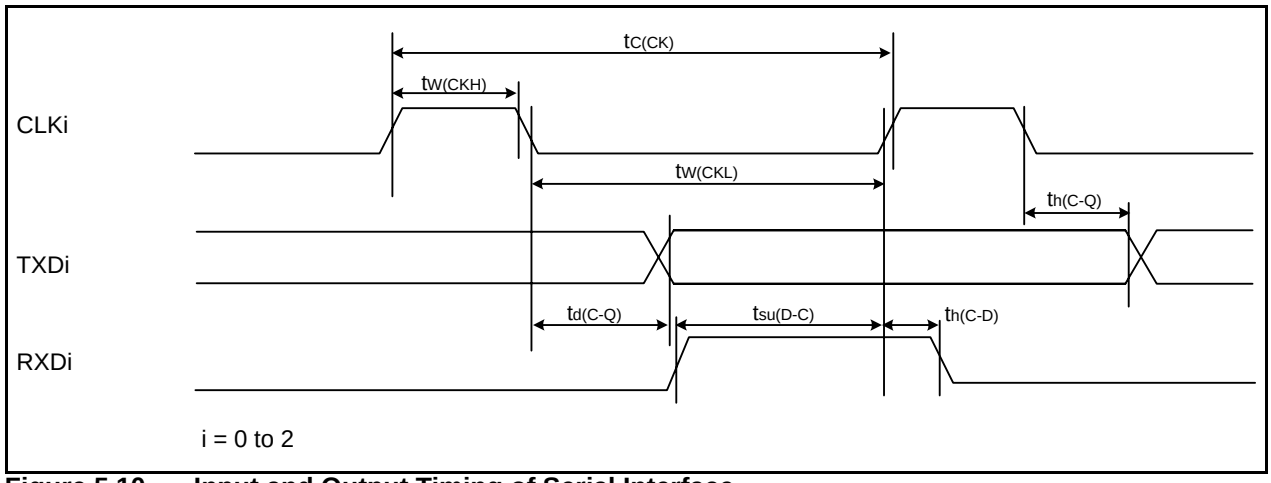


Figure 5.10 Input and Output Timing of Serial Interface

Table 5.29 Timing Requirements of External Interrupt $\overline{INTi}$ (i = 0 to 7) and Key Input Interrupt $\overline{KIi}$ (i = 0 to 7)
(V_{CC} = 1.8 to 5.5 V, V_{SS} = 0 V, and T_{opr} = –20 to 85°C (N version) / –40 to 85°C (D version), unless otherwise specified.)

Symbol	Parameter	Standard						Unit
		V_{CC} = 2.2V, Topr = 25°C		V_{CC} = 3V, Topr = 25°C		V_{CC} = 5V, Topr = 25°C		
		Min.	Max.	Min.	Max.	Min.	Max.	
$t_{W(INH)}$	$\overline{INTi}$ input “H” width, $\overline{KIi}$ input “H” width	1000 (1)	—	380 (1)	—	250 (1)	—	ns
$t_{W(INL)}$	$\overline{INTi}$ input “L” width, $\overline{KIi}$ input “L” width	1000 (2)	—	380 (2)	—	250 (2)	—	ns

Notes:
1. When selecting the digital filter by the $\overline{INTi}$ input filter select bit, use an $\overline{INTi}$ input HIGH width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.
2. When selecting the digital filter by the $\overline{INTi}$ input filter select bit, use an $\overline{INTi}$ input LOW width of either (1/digital filter clock frequency × 3) or the minimum value of standard, whichever is greater.

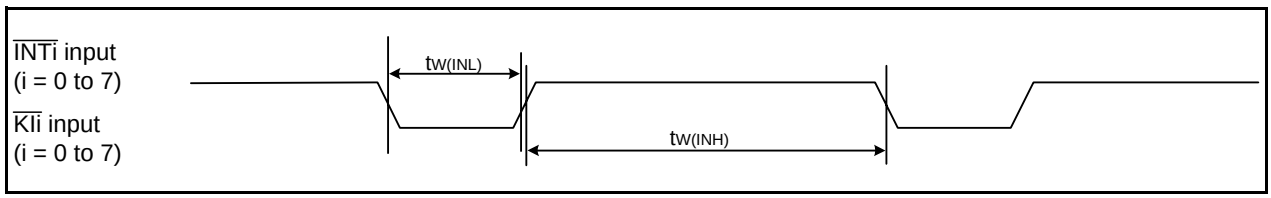
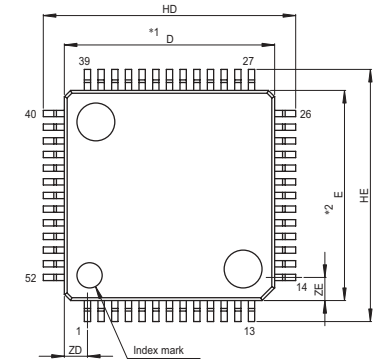


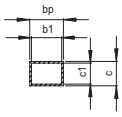
Figure 5.11 Input Timing of External Interrupt $\overline{INTi}$ and Key Input Interrupt $\overline{KIi}$

Package Dimensions

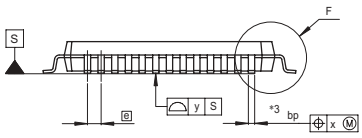
Diagrams showing the latest package dimensions and mounting information are available in the “Packages” section of the Renesas Electronics web site.

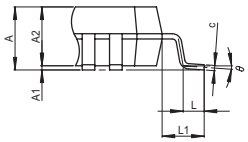
JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-LQFP52-10x10-0.65	PLQP0052JA-A	52P6A-A	0.3g





Terminal cross section





Detail F

NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	9.9	10.0	10.1
E	9.9	10.0	10.1
A_2	—	1.4	—
H_D	11.8	12.0	12.2
H_E	11.8	12.0	12.2
A	—	—	1.7
A_1	0.05	0.1	0.15
b_p	0.27	0.32	0.37
b_1	—	0.30	—
c	0.09	0.145	0.20
c_1	—	0.125	—
θ	0°	—	8°
e	—	0.65	—
x	—	—	0.13
y	—	—	0.10
Z_D	—	1.1	—
Z_E	—	1.1	—
L	0.35	0.5	0.65
L_1	—	1.0	—

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

   Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

   — The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

   The state of the product is undefined at the moment when power is supplied.

   — The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

   In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

   In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

   Access to reserved addresses is prohibited.

   — The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

   After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

   — When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

   Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

   — The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.