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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	Coldfire V1
Core Size	32-Bit Single-Core
Speed	50MHz
Connectivity	CANbus, I²C, SCI, SPI
Peripherals	LVD, PWM, WDT
Number of I/O	54
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 20x12b
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mcf51ac256acpue

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1 MCF51AC256 Family Configurations

1.1 Device Comparison

The MCF51AC256 series is summarized in Table 1.

Table 1. MCF51AC256 Series Device Comparison

Feature	MCF51AC256A		MCF51AC256B			MCF51AC128A		MCF51AC128C		
	80-pin	64-pin	80-pin	64-pin	44-pin	80-pin	64-pin	80-pin	64-pin	44-pin
Flash memory size (Kbytes)	256					128				
RAM size (Kbytes)	32					32 or 16[1]				
V1 ColdFire core with BDM (background debug module)	Yes									
ACMP1 (analog comparator)	Yes									
ACMP2 (analog comparator)	Yes		Yes		No	Yes				No
ADC (analog-to-digital converter) channels (12-bit)	24	20	24	20	9	24	20	24	20	9
CAN (controller area network)	Yes		No			Yes		No		
COP (computer operating properly)	Yes									
CRC (cyclic redundancy check)	Yes									
RTI	Yes									
DBG (debug)	Yes									
IIC1 (inter-integrated circuit)	Yes									
IRQ (interrupt request input)	Yes									
INTC (interrupt controller)	Yes									
KBI (keyboard interrupts)	Yes									
LVD (low-voltage detector)	Yes									
MCG (multipurpose clock generator)	Yes									
OSC (crystal oscillator)	Yes									
Port I/O[2]	69	54	69	54	36	69	54	69	54	36
RGPIO (rapid general-purpose I/O)	16				12	16				12
SCI1, SCI2 (serial communications interfaces)	Yes									
SPI1 (serial peripheral interface)	Yes									
SPI2 (serial peripheral interface)	Yes	No	Yes	No		Yes	No	Yes	No	
FTM1 (flexible timer module) channels	6				4	6				4
FTM2 channels	6	2	6	2	2	6	2	6	2	2

Table 1. MCF51AC256 Series Device Comparison (continued)

Feature	MCF51AC256A		MCF51AC256B			MCF51AC128A		MCF51AC128C		
	80-pin	64-pin	80-pin	64-pin	44-pin	80-pin	64-pin	80-pin	64-pin	44-pin
TPM3 (timer pulse-width modulator) channels	2									
VBUS (debug visibility bus)	Yes	No	Yes	No		Yes	No	Yes	No	

1 The members of MCF51AC128A with CAN support have 32 KB RAM. The other members have 16 KB RAM.

2 Up to 16 pins on Ports E and F are shared with the ColdFire Rapid GPIO module.

1.2 Block Diagram

Figure 1 shows the connections between the MCF51AC256 series pins and modules.

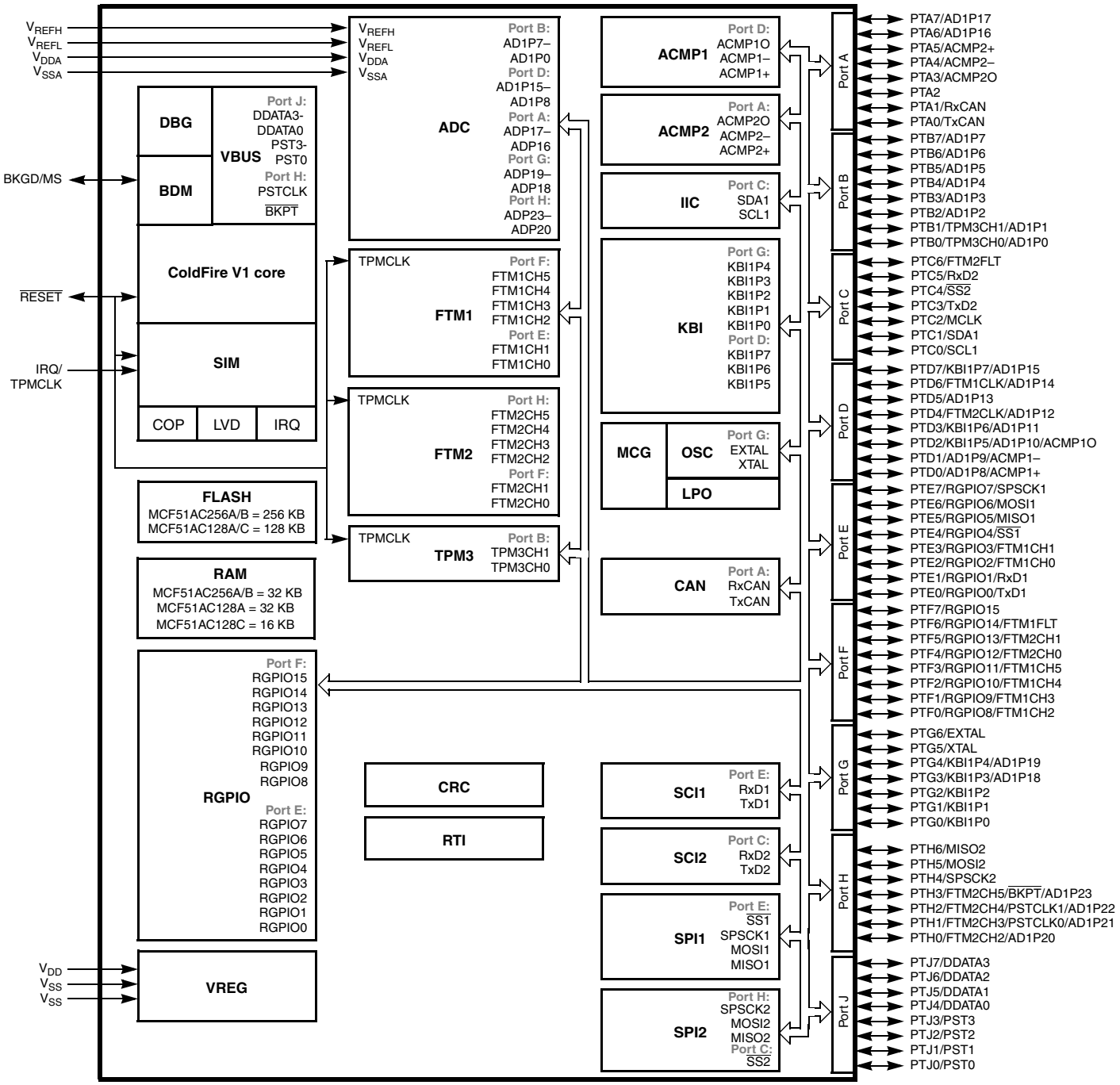

Figure 1. MCF51AC256 Series Block Diagram

1.3.1 Feature List

- 32-bit Version 1 ColdFire® central processor unit (CPU)
  - Up to 50.33 MHz at 2.7 V – 5.5 V
  - Provide 0.94 Dhrystone 2.1 DMIPS per MHz performance when running from internal RAM (0.76 DMIPS per MHz when running from flash)
  - Implements instruction set revision C (ISA_C)
- On-chip memory
  - Up to 256 KB flash memory read/program/erase over full operating voltage and temperature
  - Up to 32 KB static random access memory (SRAM)
  - Security circuitry to prevent unauthorized access to SRAM and flash contents
- Power-Saving Modes
  - Three low-power stop plus wait modes
  - Peripheral clock enable register can disable clocks to unused modules, reducing currents; allows clocks to remain enabled to specific peripherals in stop3 mode
- System protection features
  - Watchdog computer operating properly (COP) reset with options to run from independent LPO clock or bus clock
  - Low-voltage detection with reset or interrupt
  - Illegal opcode and illegal address detection with programmable reset or exception response
  - Flash block protection
- Debug support
  - Single-wire background debug interface
  - Real-time debug support, with 6 hardware breakpoints (4 PC, 1 address pair and 1 data) that can be configured into a 1- or 2-level trigger
  - On-chip trace buffer provides programmable start/stop recording conditions plus support for continuous or PC-profiling modes
  - Support for real-time program (and optional partial data) trace using the debug visibility bus
- V1 ColdFire interrupt controller (CF1_INTC)
  - Support of 40 peripheral I/O interrupt requests plus seven software (one per level) interrupt requests
  - Fixed association between interrupt request source and level plus priority, up to two requests can be remapped to the highest maskable level + priority
  - Unique vector number for each interrupt source
  - Support for service routine interrupt acknowledge (software IACK) read cycles for improved system performance
- Multipurpose clock generator (MCG)
  - Oscillator (XOSC); loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 38.4 kHz or 1 MHz to 16 MHz
  - LPO clock as an optional independent clock source for COP and RTI
  - FLL/PLL controlled by internal or external reference

  - Trimmable internal reference allows 0.2% resolution and 2% deviation
- Analog-to-digital converter (ADC)
  - 24 analog inputs with 12 bits resolution
  - Output formatted in 12-, 10- or 8-bit right-justified format
  - Single or continuous conversion (automatic return to idle after single conversion)
  - Operation in low-power modes for lower noise operation
  - Asynchronous clock source for lower noise operation
  - Automatic compare with interrupt for less-than, or greater-than or equal-to, programmable value
  - On-chip temperature sensor
- Flexible timer/pulse-width modulators (FTM)
  - 16-bit Free-running counter or a counter with initial and final value. The counting can be up and unsigned, up and signed, or up-down and unsigned
  - Up to 6 channels, and each channel can be configured for input capture, output compare or edge-aligned PWM mode, all channels can be configured for center-aligned PWM mode
    - Channels can operate as pairs with equal outputs, pairs with complimentary outputs or independent channels (with independent outputs)
    - Each pair of channels can be combined to generate a PWM signal (with independent control of both edges of PWM signal)
    - Deadtime insertion is available for each complementary pair
  - The load of the FTM registers which have write buffer can be synchronized; write protection for critical registers
  - Generation of the triggers to ADC (hardware trigger)
  - A fault input for global fault control
  - Backwards compatible with TPM
- Timer/pulse width modulator (TPM)
  - 16-bit free-running or modulo up/down count operation
  - Two channels, each channel may be input capture, output compare, or edge-aligned PWM
  - One interrupt per channel plus terminal count interrupt
- Cyclic redundancy check (CRC) generator
  - High speed hardware CRC generator circuit using 16-bit shift register
  - CRC16-CCITT compliancy with $x^{16} + x^{12} + x^5 + 1$ polynomial
  - Error detection for all single, double, odd, and most multi-bit errors
  - Programmable initial seed value
- Analog comparators (ACMP)
  - Full rail to rail supply operation
  - Selectable interrupt on rising edge, falling edge, or either rising or falling edges of comparator output
  - Option to compare to fixed internal bandgap reference voltage
  - Option to allow comparator output to be visible on a pin, ACMPxO

— Double-buffered transmit and receive
— Serial clock phase and polarity options
— Slave select output
— Selectable MSB-first or LSB-first shifting
— 16-bit and FIFO operations in SPI2

- Input/Output
  — 69 GPIOs
  — 8 keyboard interrupt pins with selectable polarity
  — Hysteresis and configurable pull-up device on all input pins; Configurable slew rate and drive strength on all output pins
  — 16-bits Rapid GPIO pins connected to the processor's local 32-bit platform bus with set, clear, and faster toggle functionality

1.4 Part Numbers

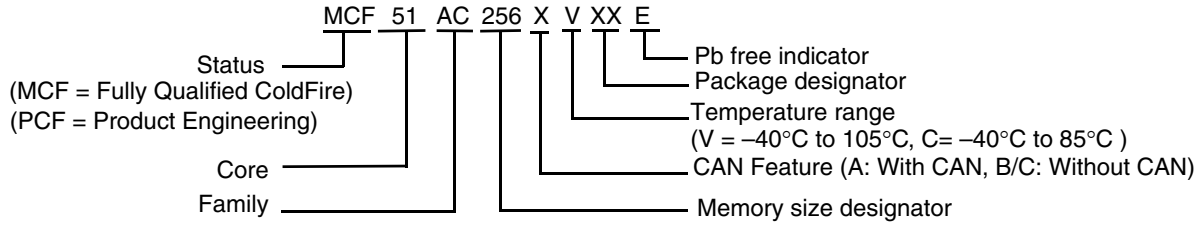

Table 3. Orderable Part Number Summary

Freescale Part Number	Description	Flash / SRAM (Kbytes)	Package	Temperature
MCF51AC256AVFUE	MCF51AC256 ColdFire Microcontroller with CAN	256 / 32	64 QFP	–40°C to 105°C
MCF51AC256BVFUE	MCF51AC256 ColdFire Microcontroller without CAN	256 / 32	64 QFP	–40°C to 105°C
MCF51AC256AVLKE	MCF51AC256 ColdFire Microcontroller with CAN	256 / 32	80 LQFP	–40°C to 105°C
MCF51AC256BVLKE	MCF51AC256 ColdFire Microcontroller without CAN	256 / 32	80 LQFP	–40°C to 105°C
MCF51AC256AVPUE	MCF51AC256 ColdFire Microcontroller with CAN	256 / 32	64 LQFP	–40°C to 105°C
MCF51AC256BVPUE	MCF51AC256 ColdFire Microcontroller without CAN	256 / 32	64 LQFP	–40°C to 105°C
MCF51AC128AVFUE	MCF51AC128 ColdFire Microcontroller with CAN	128 / 32	64 QFP	–40°C to 105°C
MCF51AC128CVFUE	MCF51AC128 ColdFire Microcontroller without CAN	128 / 16	64 QFP	–40°C to 105°C
MCF51AC128AVLKE	MCF51AC128 ColdFire Microcontroller with CAN	128 / 32	80 LQFP	–40°C to 105°C
MCF51AC128CVLKE	MCF51AC128 ColdFire Microcontroller without CAN	128 / 16	80 LQFP	–40°C to 105°C
MCF51AC128AVPUE	MCF51AC128 ColdFire Microcontroller with CAN	128 / 32	64 LQFP	–40°C to 105°C
MCF51AC128CVPUE	MCF51AC128 ColdFire Microcontroller without CAN	128 / 16	64 LQFP	–40°C to 105°C
MCF51AC256ACFUE	MCF51AC256 ColdFire Microcontroller with CAN	256 / 32	64 QFP	–40°C to 85°C
MCF51AC256BCFUE	MCF51AC256 ColdFire Microcontroller without CAN	256 / 32	64 QFP	–40°C to 85°C
MCF51AC256ACLKE	MCF51AC256 ColdFire Microcontroller with CAN	256 / 32	80 LQFP	–40°C to 85°C
MCF51AC256BCLKE	MCF51AC256 ColdFire Microcontroller without CAN	256 / 32	80 LQFP	–40°C to 85°C

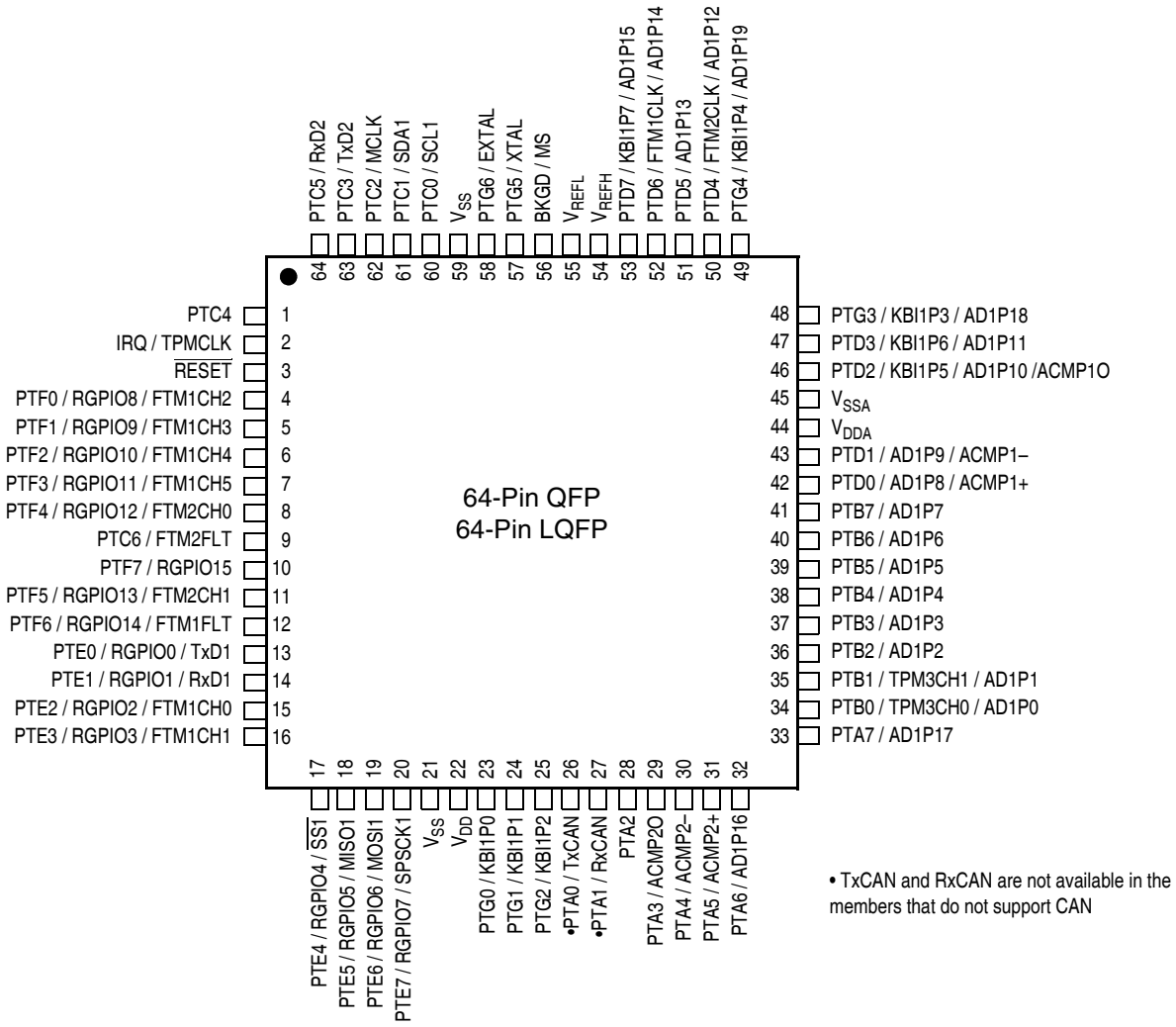

Figure 3. MCF51AC256 Series ColdFire Microcontroller 64-Pin QFP/LQFP

Figure 4 shows the pinout of the 44-pin LQFP.

Table 6. Absolute Maximum Ratings

Rating	Symbol	Value	Unit
Supply voltage	V_{DD}	–0.3 to 5.8	V
Input voltage	V_{In}	–0.3 to V_{DD} + 0.3	V
Instantaneous maximum current Single pin limit (applies to all port pins)[1, 2, 3]	I_D	±25	mA
Maximum current into V_{DD}	I_{DD}	120	mA
Storage temperature	T_{stg}	–55 to 150	°C

1 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.

2 All functional non-supply pins are internally clamped to V_{SS} and V_{DD}.

3 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD}, the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low which would reduce overall power consumption.

2.3 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and it is user-determined rather than being controlled by the MCU design. In order to take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 7. Thermal Characteristics

Rating		Symbol	Value	Unit
Operating temperature range (packaged)		T_A	–40 to 105	°C
Maximum junction temperature		T_J	150	°C
Thermal resistance [1,2,3,4]				
80-pin LQFP				
	1s		51	
	2s2p		38	
64-pin LQFP				
	1s		59	
	2s2p	θ_{JA}	41	°C/W
64-pin QFP				
			50	
	1s		36	
	2s2p			
44-pin LQFP				
	1s		67	
	2s2p		45	

applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 8. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human body	Series resistance	R1	1500	Ω
	Storage capacitance	C	100	pF
	Number of pulse per pin	—	3	
Charge device model	Series resistance	R1	0	Ω
	Storage capacitance	C	0	pF
	Number of pulse per pin	—	3	—
Latch-up	Minimum input voltage limit	—	–2.5	V
	Maximum input voltage limit	—	7.5	V

Table 9. ESD and Latch-Up Protection Characteristics

Num	Rating	Symbol	Min	Max	Unit
1	Human body model (HBM)	V_{HBM}	±2000	—	V
2	Charge device model (CDM)	V_{CDM}	±500	—	V
3	Latch-up current at T_A = 85 °C	I_{LAT}	±100	—	mA

2.5 DC Characteristics

This section includes information about power supply requirements, I/O pin characteristics, and power supply current in various operating modes.

Table 10. DC Characteristics

Num	C	Parameter	Symbol	Min	Typical[1]	Max	Unit
1	—	Operating voltage		2.7	—	5.5	V
2	P	Output high voltage — Low drive (PTxDSn = 0) 5 V, I_{Load} = –4 mA 3 V, I_{Load} = –2 mA 5 V, I_{Load} = –2 mA 3 V, I_{Load} = –1 mA	V_{OH}	 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	V
		Output high voltage — High drive (PTxDSn = 1) 5 V, I_{Load} = –15 mA 3 V, I_{Load} = –8 mA 5 V, I_{Load} = –8 mA 3 V, I_{Load} = –4 mA		 V_{DD} – 1.5 V_{DD} – 1.5 V_{DD} – 0.8 V_{DD} – 0.8	 — — — —	 — — — —	

Table 10. DC Characteristics (continued)

Num	C	Parameter	Symbol	Min	Typical[1]	Max	Unit
3	P	Output low voltage — Low Drive (PTxDSn = 0) 5 V, I_{Load} = 4 mA 3 V, I_{Load} = 2 mA 5 V, I_{Load} = 2 mA 3 V, I_{Load} = 1 mA	V_{OL}	—	—	1.5 1.5 0.8 0.8	V
		Output low voltage — High Drive (PTxDSn = 1) 5 V, I_{Load} = 15 mA 3 V, I_{Load} = 8 mA 5 V, I_{Load} = 8 mA 3 V, I_{Load} = 4 mA		—	—	1.5 1.5 0.8 0.8	
4	C	Output high current — Max total I_{OH} for all ports 5V 3V	I_{OHT}	—	—	100 60	mA
5	C	Output low current — Max total I_{OL} for all ports 5 V 3 V	I_{OLT}	—	—	100 60	mA
6	P	Input high voltage; all digital inputs	V_{IH}	0.65 × V_{DD}	—	—	V
7	P	Input low voltage; all digital inputs	V_{IL}	—	—	0.35 × V_{DD}	V
8	D	Input hysteresis; all digital inputs	V_{hys}	0.06 × V_{DD}	—	—	mV
9	P	Input leakage current; input only pins[2]	$\|I_{In}\|$	—	0.1	1	µA
10	P	High impedance (off-state) leakage current[2]	$\|I_{OZ}\|$	—	0.1	1	µA
11	P	Internal pullup resistors[3]	R_{PU}	20	45	65	kΩ
12	P	Internal pulldown resistors[4]	R_{PD}	20	45	65	kΩ
13	C	Input capacitance; all non-supply pins	C_{In}	—	—	8	pF
14	P	POR rearm voltage	V_{POR}	0.9	1.4	2.0	V
15	D	POR rearm time	t_{POR}	10	—	—	µs
16	P	Low-voltage detection threshold — high range V_{DD} falling V_{DD} rising	V_{LVDH}	4.2 4.27	4.35 4.4	4.5 4.6	V
17	P	Low-voltage detection threshold — low range V_{DD} falling V_{DD} rising	V_{LVDL}	2.48 2.5	2.68 2.7	2.7 2.72	V
18	P	Low-voltage warning threshold — high range V_{DD} falling V_{DD} rising	V_{LVWH}	4.2 4.27	4.4 4.45	4.5 4.6	V
19	P	Low-voltage warning threshold low range V_{DD} falling V_{DD} rising	V_{LVWL}	2.48 2.5	2.68 2.7	2.7 2.72	V
20	T	Low-voltage inhibit reset/recover hysteresis 5 V 3 V	V_{hys}	—	100 60	—	mV
21	D	RAM retention voltage	V_{RAM}	—	0.6	1.0	V

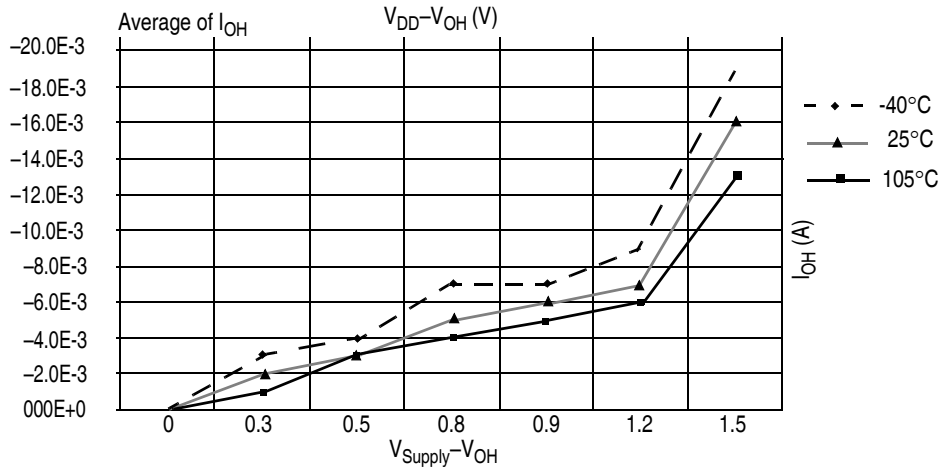

Figure 6. Typical I_{OH} vs. $V_{DD}–V_{OH}$ at V_{DD} = 3 V (High Drive, PTxDSn = 1)

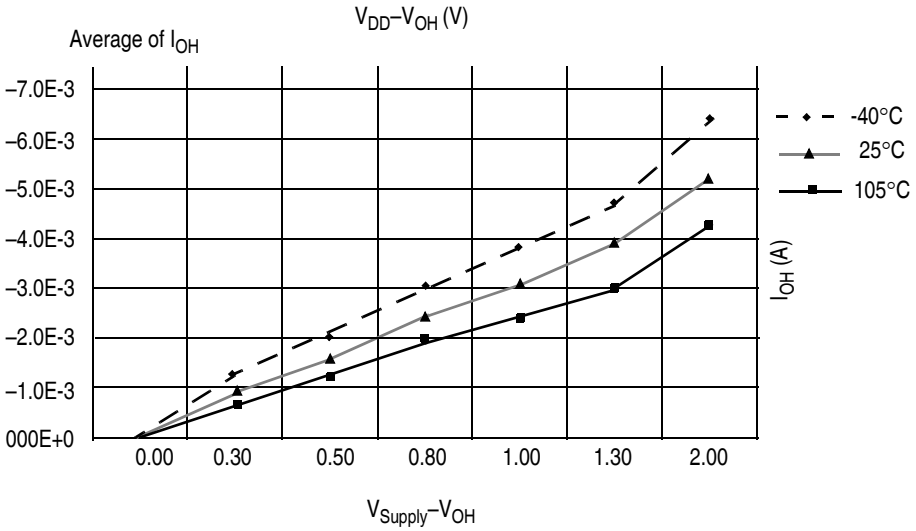

Figure 7. Typical I_{OH} vs. $V_{DD}–V_{OH}$ at V_{DD} = 5 V (Low Drive, PTxDSn = 0)

2.6 Supply Current Characteristics

Table 11. Supply Current Characteristics

Num	C	Parameter		Symbol	V_{DD} (V)	Typical[1]	Max[2]	Unit
1	T	Run supply current measured at FEI mode, all modules off, system clock at:	2 MHz	RI_{DD}	5	2.27	—	mA
					3.3	2.24	—	
			4 MHz		5	3.67	—	
					3.3	3.64	—	
			8 MHz		5	6.55	—	
					3.3	6.54	—	
			16 MHz		5	11.90	—	
					3.3	11.85	—	
2	T	Run supply current measured at FEI mode, all modules on, system clock at:	2 MHz		5	3.28	—	
					3.3	3.26	—	
			4 MHz		5	4.33	—	
					3.3	4.32	—	
			8 MHz		5	8.17	—	
					3.3	8.05	—	
			16 MHz		5	14.8	—	
					3.3	14.74	—	
3	T	Run supply current measured at FBE mode, all modules off (RANGE = 1, HGO = 0), system clock at:	2 MHz		5	3.28	—	
					3.3	3.26	—	
			4 MHz		5	4.69	—	
					3.3	4.67	—	
			8 MHz		5	7.48	—	
					3.3	7.46	—	
			16 MHz		5	13.10	—	
					3.3	13.07	—	
4	T	Run supply current measured at FBE mode, all modules on (RANGE = 1, HGO = 0), system clock at:	2 MHz		5	3.64	—	
					3.3	3.63	—	
			4 MHz		5	5.38	—	
					3.3	5.35	—	
			8 MHz		5	8.65	—	
					3.3	8.64	—	
			16 MHz		5	15.55	—	
					3.3	15.40	—	

Table 11. Supply Current Characteristics (continued)

Num	C	Parameter	Symbol	V_{DD} (V)	Typical[1]	Max[2]	Unit
5	C	Wait mode supply[3] current measured at (CPU clock = 2 MHz, f_{Bus} = 1 MHz)	WI_{DD}	5	1.3	2	mA
				3	1.29	2	
6	C	Wait mode supply[3] current measured at (CPU clock = 16 MHz, f_{Bus} = 8 MHz)		5	5.11	8	mA
				3	5.1	8	
7	C	Wait mode supply[3] current measured at (CPU clock = 50 MHz, f_{Bus} = 25 MHz)		5	15.24	25	mA
				3	15.2	25	
8	C	Stop2 mode supply current –40 °C 25 °C 120 °C	$S2I_{DD}$	5	1.40	2.5 2.5 200	µA
		–40 °C 25 °C 120 °C		3	1.16	2.5 2.5 200	µA
9	C	Stop3 mode supply current –40 °C 25 °C 120 °C	$S3I_{DD}$	5	1.60	2.5 2.5 220	µA
		–40 °C 25 °C 120 °C		3	1.35	2.5 2.5 220	µA
10	C	RTI adder to stop2 or stop3[3], 25 °C	$S23I_{DDRTI}$	5	300		nA
				3	300		nA
11	C	Adder to stop3 for oscillator enabled[4] (ERCLKEN =1 and EREFSTEN = 1)	$S3I_{DDOSC}$	5, 3	5		µA

1 Typicals are measured at 25 °C.

2 Values given here are preliminary estimates prior to completing characterization.

3 Most customers are expected to find that auto-wakeup from stop2 or stop3 can be used instead of the higher current wait mode.

4 Values given under the following conditions: low range operation (RANGE = 0), low power mode (HGO = 0).

2.8 ADC Characteristics

Table 13. 5 Volt 12-bit ADC Operating Conditions

Num	C	Characteristic	Conditions	Symb	Min	Typical[1]	Max	Unit	Comment
1	D	Supply voltage	Absolute	V_{DDA}	2.7	—	5.5	V	
	D		Delta to V_{DD} ($V_{DD} - V_{DDA}$)[2]	ΔV_{DDA}	–100	0	100	mV	
2	D	Ground voltage	Delta to V_{SS} ($V_{SS} - V_{SSA}$)[2]	ΔV_{SSA}	–100	0	100	mV	
3	D	Reference voltage high		V_{REFH}	2.7	V_{DDA}	V_{DDA}	V	
4	D	Reference voltage low		V_{REFL}	V_{SSA}	V_{SSA}	V_{SSA}	V	
5	D	Input voltage		V_{ADIN}	V_{REFL}	—	V_{REFH}	V	
6	C	Input capacitance		C_{ADIN}	—	4.5	5.5	pF	
7	C	Input resistance		R_{ADIN}	—	3	5	kΩ	
8	C	Analog source resistance	12-bit mode f_{ADCK} > 4MHz f_{ADCK} < 4MHz	R_{AS}	 — —	 — —	 2 5	kΩ	External to MCU
	C		10-bit mode f_{ADCK} > 4MHz f_{ADCK} < 4MHz		 — —	 — —	 5 10		
	C		8-bit mode (all valid f_{ADCK})		—	—	10		
9	D	ADC conversion clock frequency	High speed (ADLPC = 0)	f_{ADCK}	0.4	—	8.0	MHz	
	D		Low power (ADLPC = 1)		0.4	—	4.0		

1 Typical values assume V_{DDA} = 5.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 DC potential difference.

Table 14. 5 Volt 12-bit ADC Characteristics (V_{REFH} = V_{DDA}, V_{REFL} = V_{SSA}) (continued)

Num	C	Characteristic	Conditions	Symb	Min	Typical[1]	Max	Unit	Comment
7	P	Conversion time (including sample time)	Short sample (ADLSMP = 0)	t_{ADC}	—	20	—	ADCK cycles	See Table 10 for conversion time variances
			Long sample (ADLSMP = 1)		—	40	—		
8	T	Sample time	Short sample (ADLSMP = 0)	t_{ADS}	—	3.5	—	ADCK cycles	
			Long sample (ADLSMP = 1)		—	23.5	—		
9	T	Total unadjusted error	12-bit mode	E_{TUE}	—	±3.0	—	LSB[2]	Includes quantization
	P		10-bit mode		—	±1	±2.5		
	T		8-bit mode		—	±0.5	±1.0		
10	T	Differential non-linearity	12-bit mode	DNL	—	±1.75	—	LSB[2]	
	P		10-bit mode[3]		—	±0.5	±1.0		
	T		8-bit mode[3]		—	±0.3	±0.5		
11	T	Integral non-linearity	12-bit mode	INL	—	±1.5	—	LSB[2]	
	T		10-bit mode		—	±0.5	±1.0		
	T		8-bit mode		—	±0.3	±0.5		
12	T	Zero-scale error	12-bit mode	E_{ZS}	—	±1.5	—	LSB[2]	V_{ADIN} = V_{SSA}
	P		10-bit mode		—	±0.5	±1.5		
	T		8-bit mode		—	±0.5	±0.5		
13	T	Full-scale error	12-bit mode	E_{FS}	—	±1	—	LSB[2]	V_{ADIN} = V_{DDA}
	P		10-bit mode		—	±0.5	±1		
	T		8-bit mode		—	±0.5	±0.5		
14	D	Quantization error	12-bit mode	E_Q	—	–1 to 0	—	LSB[2]	
			10-bit mode		—	—	±0.5		
			8-bit mode		—	—	±0.5		
15	D	Input leakage error	12-bit mode	E_{IL}	—	±1	—	LSB[2]	Pad leakage[4] * R_{AS}
			10-bit mode		—	±0.2	±2.5		
			8-bit mode		—	±0.1	±1		
16	D	Temp sensor voltage	25°C	V_{TEMP25}	—	1.396	—	V	
17	D	Temp sensor slope	–40 °C–25 °C	m	—	3.266	—	mV/°C	
			25 °C–85 °C		—	3.638	—		

1 Typical values assume V_{DDA} = 5.0 V, Temp = 25 °C, f_{ADCK} = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

2 1 LSB = $(V_{REFH} - V_{REFL})/2^N$.

3 Monotonicity and No-Missing-Codes guaranteed in 10-bit and 8-bit modes

4 Based on input pad leakage current. Refer to pad electricals.

2.9 External Oscillator (XOSC) Characteristics

Table 15. Oscillator Electrical Specifications (Temperature Range = –40 to 105 °C Ambient)

Num	C	Rating	Symbol	Min	Typical[1]	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0) High range (RANGE = 1) FEE or FBE mode[2] High range (RANGE = 1) PEE or PBE mode[3] High range (RANGE = 1, HGO = 1) BLPE mode High range (RANGE = 1, HGO = 0) BLPE mode	 f_{lo} f_{hi-fll} f_{hi-pll} f_{hi-hgo} f_{hi-lp}	 32 1 1 1 1	 — — — — —	 38.4 5 16 16 8	 kHz MHz MHz MHz MHz
2	—	Load capacitors	C_1 C_2	See crystal or resonator manufacturer's recommendation.			
3	—	Feedback resistor Low range (32 kHz to 38.4 kHz) High range (1 MHz to 16 MHz)	R_F		 10 1		MΩ
4	—	Series resistor Low range, low gain (RANGE = 0, HGO = 0) Low range, high gain (RANGE = 0, HGO = 1) High range, low gain (RANGE = 1, HGO = 0) High range, high gain (RANGE = 1, HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	R_S	 — — — — — —	 0 100 0 0 0 0	 — — — 0 10 20	kΩ
5	T	Crystal start-up time [4] Low range, low gain (RANGE = 0, HGO = 0) Low range, high gain (RANGE = 0, HGO = 1) High range, low gain (RANGE = 1, HGO = 0)[5] High range, high gain (RANGE = 1, HGO = 1)[5]	 $t_{CSTL-LP}$ $t_{CSTL-HGO}$ $t_{CSTH-LP}$ $t_{CSTH-HGO}$	 — — — —	 200 400 5 15	 — — — —	ms
6	T	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE or FBE mode [2] PEE or PBE mode [3] BLPE mode	f_{extal}	0.03125 1 0	—	5 16 40	MHz

1 Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.

2 When MCG is configured for FEE or FBE mode, input clock source must be divisible using RDIV to within the range of 31.25 kHz to 39.0625 kHz.

3 When MCG is configured for PEE or PBE mode, input clock source must be divisible using RDIV to within the range of 1 MHz to 2 MHz.

4 This parameter is characterized and not tested on each device. Proper PC board layout procedures must be followed to achieve specifications.

5 4 MHz crystal

Table 16. MCG Frequency Specifications (continued)(Temperature Range = –40 to 105 °C Ambient)

Num	C	Rating	Symbol	Min	Typical[1]	Max	Unit
18	D	Lock exit frequency tolerance [8]	D_{unl}	±4.47	—	±5.97	%
19	D	Lock time — FLL	t_{fll_lock}	—	—	$t_{fll\_acquire}$+ 1075(1/f_{int_t})	s
20	D	Lock time — PLL	t_{pll_lock}	—	—	$t_{pll\_acquire}$+ 1075(1/f_{pll_ref})	s
21	D	Loss of external clock minimum frequency — RANGE = 0	f_{loc_low}	(3/5) × f_{int}	—	—	kHz

1 Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.

2 The resulting bus clock frequency must not exceed the maximum specified bus clock frequency of the device.

3 This specification applies when the FLL reference source or reference divider is changed, trim value changed or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

4 This specification applies when the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

5 Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{BUS}. Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

6 625 ns represents 5 time quanta for CAN applications, under worst case conditions of 8 MHz CAN bus clock, 1 Mbps CAN bus speed, and 8 time quanta per bit for bit time settings. 5 time quanta is the minimum time between a synchronization edge and the sample point of a bit using 8 time quanta per bit.

7 Below D_{lock} minimum, the MCG enters lock. Above D_{lock} maximum, the MCG will not enter lock. But if the MCG is already in lock, then the MCG may stay in lock.

8 Below D_{unl} minimum, the MCG will not exit lock if already in lock. Above D_{unl} maximum, the MCG is guaranteed to exit lock.

2.11 AC Characteristics

This section describes ac timing characteristics for each peripheral system.

2.11.2 Timer (TPM/FTM) Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 18. TPM/FTM Input Timing

NUM	C	Function	Symbol	Min	Max	Unit
1	—	External clock frequency	f_{TPMext}	DC	$f_{Bus}/4$	MHz
2	—	External clock period	t_{TPMext}	4	—	t_{cyc}
3	D	External clock high time	t_{clkh}	1.5	—	t_{cyc}
4	D	External clock low time	t_{clkl}	1.5	—	t_{cyc}
5	D	Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

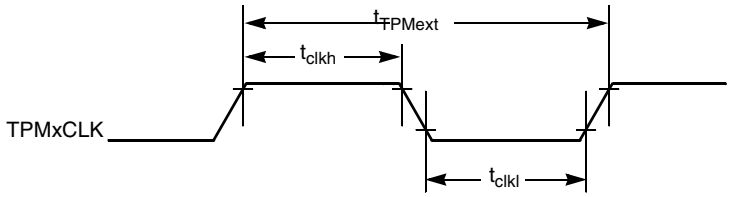

Figure 13. Timer External Clock

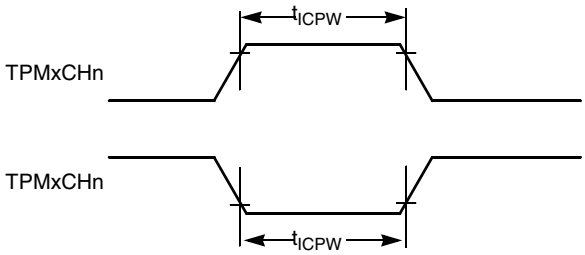

Figure 14. Timer Input Capture Pulse

2.11.3 MSCAN

Table 19. MSCAN Wake-Up Pulse Characteristics

Num	C	Parameter	Symbol	Min	Typical[1]	Max	Unit
1	D	MSCAN wake-up dominant pulse filtered	t_{WUP}	—	—	2	µs
2	D	MSCAN wake-up dominant pulse pass	t_{WUP}	5	—	5	µs

1 Typical values are based on characterization data at V_{DD} = 5.0 V, 25 °C unless otherwise stated.

2.12 SPI Characteristics

Table 20 and Figure 15 through Figure 18 describe the timing requirements for the SPI system.

Table 20. SPI Timing

No.	C	Function	Symbol	Min	Max	Unit
—	D	Operating frequency Master Slave	f_{op}	$f_{Bus}/2048$ 0	$f_{Bus}/2$ $f_{Bus}/4$	Hz
1	D	SPSCK period Master Slave	t_{SPSCK}	2 4	2048 —	t_{cyc} t_{cyc}
2	D	Enable lead time Master Slave	t_{Lead}	1/2 1	— —	t_{SPSCK} t_{cyc}
3	D	Enable lag time Master Slave	t_{Lag}	1/2 1	— —	t_{SPSCK} t_{cyc}
4	D	Clock (SPSCK) high or low time Master Slave	t_{WSPSCK}	$t_{cyc} - 30$ $t_{cyc} - 30$	1024 t_{cyc} —	ns ns
5	D	Data setup time (inputs) Master Slave	t_{SU}	15 15	— —	ns ns
6	D	Data hold time (inputs) Master Slave	t_{HI}	0 25	— —	ns ns
7	D	Slave access time	t_a	—	1	t_{cyc}
8	D	Slave MISO disable time	t_{dis}	—	1	t_{cyc}
9	D	Data valid (after SPSCK edge) Master Slave	t_v	— —	25 25	ns ns
10	D	Data hold time (outputs) Master Slave	t_{HO}	0 0	— —	ns ns
11	D	Rise time Input Output	t_{RI} t_{RO}	— —	$t_{cyc} - 25$ 25	ns ns
12	D	Fall time Input Output	t_{FI} t_{FO}	— —	$t_{cyc} - 25$ 25	ns ns