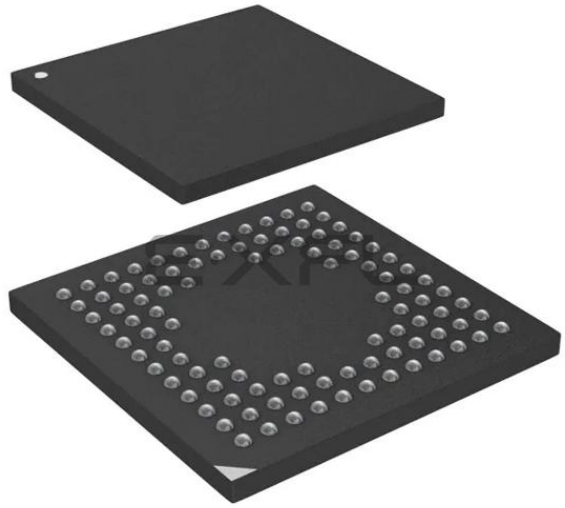

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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, Cap Sense, DMA, I²S, POR, PWM, WDT
Number of I/O	83
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 24x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-UFBGA
Supplier Device Package	100-UFBGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l151vbh6tr

Contents

3.1 Low power modes

The ultra-low-power STM32L151x6/8/B and STM32L152x6/8/B devices support dynamic voltage scaling to optimize its power consumption in run mode. The voltage from the internal low-drop regulator that supplies the logic can be adjusted according to the system's maximum operating frequency and the external voltage supply:

- In Range 1 (V_{DD} range limited to 1.71-3.6 V), the CPU runs at up to 32 MHz (refer to *Table 17* for consumption).
- In Range 2 (full V_{DD} range), the CPU runs at up to 16 MHz (refer to *Table 17* for consumption)
- In Range 3 (full V_{DD} range), the CPU runs at up to 4 MHz (generated only with the multispeed internal RC oscillator clock source). Refer to *Table 17* for consumption.

Seven low power modes are provided to achieve the best compromise between low power consumption, short startup time and available wakeup sources:

- **Sleep** mode

  In Sleep mode, only the CPU is stopped. All peripherals continue to operate and can wake up the CPU when an interrupt/event occurs.

  Sleep mode power consumption: refer to *Table 19*.

- **Low power run** mode

  This mode is achieved with the multispeed internal (MSI) RC oscillator set to the minimum clock (65 kHz), execution from SRAM or Flash memory, and internal regulator in low power mode to minimize the regulator's operating current. In the Low power run mode, the clock frequency and the number of enabled peripherals are both limited.

  Low power run mode consumption: refer to *Table 20: Current consumption in Low power run mode*.

- **Low power sleep** mode

  This mode is achieved by entering the Sleep mode with the internal voltage regulator in Low power mode to minimize the regulator's operating current. In the Low power sleep mode, both the clock frequency and the number of enabled peripherals are limited; a typical example would be to have a timer running at 32 kHz.
  When wakeup is triggered by an event or an interrupt, the system reverts to the run mode with the regulator on.

  Low power sleep mode consumption: refer to *Table 21: Current consumption in Low power sleep mode*.

- **Stop** mode with RTC

  Stop mode achieves the lowest power consumption while retaining the RAM and register contents and real time clock. All clocks in the V_{CORE} domain are stopped, the PLL, MSI RC, HSI RC and HSE crystal oscillators are disabled. The LSE or LSI is still running. The voltage regulator is in the low power mode.

  The device can be woken up from Stop mode by any of the EXTI line, in 8 µs. The EXTI line source can be one of the 16 external lines. It can be the PVD output, the Comparator 1 event or Comparator 2 event (if internal reference voltage is on), it can be the RTC alarm(s), the USB wakeup, the RTC tamper events, the RTC timestamp event or the RTC wakeup.

- **Stop** mode without RTC

  Stop mode achieves the lowest power consumption while retaining the RAM and register contents. All clocks are stopped, the PLL, MSI RC, HSI and LSI RC, LSE and

Table 3. Functionalities depending on the operating power supply range (continued)

Operating power supply range	Functionalities depending on the operating power supply range			
	DAC and ADC operation	USB	Dynamic voltage scaling range	I/O operation
V_{DD} = 2.0 to 2.4 V	Conversion time up to 500 Ksps	Functional(2)	Range 1, Range 2 or Range 3	Full speed operation
V_{DD} = 2.4 to 3.6 V	Conversion time up to 1 Msps	Functional(2)	Range 1, Range 2 or Range 3	Full speed operation

1. The CPU frequency changes from initial to final must respect "F_{CPU} initial < 4*F_{CPU} final" to limit V_{CORE} drop due to current consumption peak when frequency increases. It must also respect 5 µs delay between two changes. For example to switch from 4.2 MHz to 32 MHz, you can switch from 4.2 MHz to 16 MHz, wait 5 µs, then switch from 16 MHz to 32 MHz.
2. Should be USB compliant from I/O voltage standpoint, the minimum V_{DD} is 3.0 V.

Table 4. CPU frequency range depending on dynamic voltage scaling

CPU frequency range	Dynamic voltage scaling range
16 MHz to 32 MHz (1ws) 32 kHz to 16 MHz (0ws)	Range 1
8 MHz to 16 MHz (1ws) 32 kHz to 8 MHz (0ws)	Range 2
2.1 MHz to 4.2 MHz (1ws) 32 kHz to 2.1 MHz (0ws)	Range 3

Five BOR thresholds are available through option bytes, starting from 1.8 V to 3 V. To reduce the power consumption in Stop mode, it is possible to automatically switch off the internal reference voltage (V_{REFINT}) in Stop mode. The device remains in reset mode when V_{DD} is below a specified threshold, $V_{POR/PDR}$ or V_{BOR}, without the need for any external reset circuit.

Note: The start-up time at power-on is typically 3.3 ms when BOR is active at power-up, the start-up time at power-on can be decreased down to 1 ms typically for devices with BOR inactive at power-up.

The device features an embedded programmable voltage detector (PVD) that monitors the V_{DD}/V_{DDA} power supply and compares it to the V_{PVD} threshold. This PVD offers 7 different levels between 1.85 V and 3.05 V, chosen by software, with a step around 200 mV. An interrupt can be generated when V_{DD}/V_{DDA} drops below the V_{PVD} threshold and/or when V_{DD}/V_{DDA} is higher than the V_{PVD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

3.3.3 Voltage regulator

The regulator has three operation modes: main (MR), low power (LPR) and power down.

- MR is used in Run mode (nominal regulation)
- LPR is used in the Low-power run, Low-power sleep and Stop modes
- Power down is used in Standby mode. The regulator output is high impedance, the kernel circuitry is powered down, inducing zero consumption but the contents of the registers and RAM are lost are lost except for the standby circuitry (wakeup logic, IWDG, RTC, LSI, LSE crystal 32K osc, RCC_CSR).

3.3.4 Boot modes

At startup, boot pins are used to select one of three boot options:

- Boot from Flash memory
- Boot from System Memory
- Boot from embedded RAM

The boot loader is located in System Memory. It is used to reprogram the Flash memory by using USART1 or USART2. See STM32™ microcontroller system memory boot mode AN2606 for details.

This dual digital Interface supports the following features:

- two DAC converters: one for each output channel
- left or right data alignment in 12-bit mode
- synchronized update capability
- noise-wave generation
- triangular-wave generation
- dual DAC channels' independent or simultaneous conversions
- DMA capability for each channel (including the underrun interrupt)
- external triggers for conversion
- input reference voltage V_{REF+}

Eight DAC trigger inputs are used in the STM32L151x6/8/B and STM32L152x6/8/B devices. The DAC channels are triggered through the timer update outputs that are also connected to different DMA channels.

3.12 Ultra-low-power comparators and reference voltage

The STM32L151x6/8/B and STM32L152x6/8/B devices embed two comparators sharing the same current bias and reference voltage. The reference voltage can be internal or external (coming from an I/O).

- one comparator with fixed threshold
- one comparator with rail-to-rail inputs, fast or slow mode. The threshold can be one of the following:
  - DAC output
  - External I/O
  - Internal reference voltage (V_{REFINT}) or V_{REFINT} submultiple (1/4, 1/2, 3/4)

Both comparators can wake up from Stop mode, and be combined into a window comparator.

The internal reference voltage is available externally via a low power / low current output buffer (driving current capability of 1 µA typical).

3.13 Routing interface

This interface controls the internal routing of I/Os to TIM2, TIM3, TIM4 and to the comparator and reference voltage output.

3.14 Touch sensing

The STM32L151x6/8/B and STM32L152x6/8/B devices provide a simple solution for adding capacitive sensing functionality to any application. These devices offer up to 20 capacitive sensing channels distributed over 10 analog I/O groups. Only software capacitive sensing acquisition mode is supported.

Capacitive sensing technology is able to detect the presence of a finger near a sensor which is protected from direct touch by a dielectric (glass, plastic, ...). The capacitive variation introduced by the finger (or any conductive object) is measured using a proven

Table 8. STM32L151x6/8/B and STM32L152x6/8/B pin definitions

Pins					Pin name	Pin type[1]	I/O structure	Main function[2] (after reset)	Pins functions	
LQFP100	LQFP64	TFBGA64	UFBGA100	LQFP48 or UFQFPN48					Alternate functions	Additional functions
1	-	-	B2	-	PE2	I/O	FT	PE2	TRACECLK/LCD_SEG38/ TIM3_ETR	-
2	-	-	A1	-	PE3	I/O	FT	PE3	TRACED0/LCD_SEG39/ TIM3_CH1	-
3	-	-	B1	-	PE4	I/O	FT	PE4	TRACED1/TIM3_CH2	-
4	-	-	C2	-	PE5	I/O	FT	PE5	TRACED2/TIM9_CH1	-
5	-	-	D2	-	PE6-WKUP3	I/O	FT	PE6	TRACED3/TIM9_CH2	WKUP3
6	1	B2	E2	1	V_{LCD}[3]	S		V_{LCD}	-	-
7	2	A2	C1	2	PC13-WKUP2	I/O	FT	PC13	-	RTC_TAMP1/ RTC_TS/ RTC_OUT/ WKUP2
8	3	A1	D1	3	PC14-OSC32_IN[4]	I/O	TC	PC14	-	OSC32_IN
9	4	B1	E1	4	PC15-OSC32_OUT[4]	I/O	TC	PC15	-	OSC32_OUT
10	-	-	F2	-	V_{SS_5}	S	-	V_{SS_5}	-	-
11	-	-	G2	-	V_{DD_5}	S	-	V_{DD_5}	-	-
12	5	C1	F1	5	PH0-OSC_IN[5]	I/O	TC	PH0	-	OSC_IN
13	6	D1	G1	6	PH1-OSC_OUT	I/O	TC	PH1	-	OSC_OUT
14	7	E1	H2	7	NRST	I/O	RST	NRST	-	-
15	8	E3	H1	-	PC0	I/O	FT	PC0	LCD_SEG18	ADC_IN10/ /COMP1_INP
16	9	E2	J2	-	PC1	I/O	FT	PC1	LCD_SEG19	ADC_IN11/ COMP1_INP
17	10	F2	J3	-	PC2	I/O	FT	PC2	LCD_SEG20	ADC_IN12/ COMP1_INP
18	11	-[6]	K2	-	PC3	I/O	TC	PC3	LCD_SEG21	ADC_IN13/ COMP1_INP

Table 8. STM32L151x6/8/B and STM32L152x6/8/B pin definitions (continued)

Pins					Pin name	Pin type[1]	I/O structure	Main function[2] (after reset)	Pins functions	
LQFP100	LQFP64	TFBGA64	UFBGA100	LQFP48 or UFQFPN48					Alternate functions	Additional functions
19	12	F1	J1	8	V_{SSA}	S	-	V_{SSA}	-	-
20	-	-	K1	-	V_{REF-}	S	-	V_{REF-}	-	-
21	-	G1 (6)	L1	-	V_{REF+}	S	-	V_{REF+}	-	-
22	13	H1	M1	9	V_{DDA}	S	-	V_{DDA}	-	-
23	14	G2	L2	10	PA0-WKUP1	I/O	FT	PA0	USART2_CTS/ TIM2_CH1_ETR	WKUP1/ ADC_IN0/ COMP1_INP
24	15	H2	M2	11	PA1	I/O	FT	PA1	USART2_RTS/ TIM2_CH2/LCD_SEG0	ADC_IN1/ COMP1_INP
25	16	F3	K3	12	PA2	I/O	FT	PA2	USART2_TX/TIM2_CH3/ TIM9_CH1/LCD_SEG1	ADC_IN2/ COMP1_INP
26	17	G3	L3	13	PA3	I/O	TC	PA3	USART2_RX/TIM2_CH4/ TIM9_CH2/LCD_SEG2	ADC_IN3/ COMP1_INP
27	18	C2	E3	-	V_{SS_4}	S	-	V_{SS_4}	-	-
28	19	D2	H3	-	V_{DD_4}	S	-	V_{DD_4}	-	-
29	20	H3	M3	14	PA4	I/O	TC	PA4	SPI1_NSS/USART2_CK	ADC_IN4/ DAC_OUT1/ COMP1_INP
30	21	F4	K4	15	PA5	I/O	TC	PA5	SPI1_SCK/ TIM2_CH1_ETR	ADC_IN5/ DAC_OUT2/ COMP1_INP
31	22	G4	L4	16	PA6	I/O	FT	PA6	SPI1_MISO/TIM3_CH1/ LCD_SEG3/TIM10_CH1	ADC_IN6 /COMP1_INP
32	23	H4	M4	17	PA7	I/O	FT	PA7	SPI1_MOSI//TIM3_CH2/ LCD_SEG4/TIM11_CH1	ADC_IN7/ COMP1_INP
33	24	H5	K5	-	PC4	I/O	FT	PC4	LCD_SEG22	ADC_IN14/ COMP1_INP
34	25	H6	L5	-	PC5	I/O	FT	PC5	LCD_SEG23	ADC_IN15/ COMP1_INP

Table 8. STM32L151x6/8/B and STM32L152x6/8/B pin definitions (continued)

Pins					Pin name	Pin type(1)	I/O structure	Main function(2) (after reset)	Pins functions	
LQFP100	LQFP64	TFBGA64	UFBGA100	LQFP48 or UFQFPN48					Alternate functions	Additional functions
71	45	B8	A12	33	PA12	I/O	FT	PA12	USART1_RTS/ SPI1_MOSI	USB_DP
72	46	A8	A11	34	PA13	I/O	FT	JTMS-SWDIO	JTMS-SWDIO	-
73	-	-	C11	-	PH2	I/O	FT	PH2	-	-
74	47	D5	F11	35	V_{SS_2}	S	-	V_{SS_2}	-	-
75	48	E5	G11	36	V_{DD_2}	S	-	V_{DD_2}	-	-
76	49	A7	A10	37	PA14	I/O	FT	JTCK -SWCLK	JTCK-SWCLK	-
77	50	A6	A9	38	PA15	I/O	FT	JTDI	TIM2_CH1_ETR/PA15/ SPI1_NSS/ LCD_SEG17	-
78	51	B7	B11	-	PC10	I/O	FT	PC10	USART3_TX/LCD_SEG28 /LCD_SEG40/LCD_COM4	-
79	52	B6	C10	-	PC11	I/O	FT	PC11	USART3_RX/LCD_SEG29 /LCD_SEG41/LCD_COM5	-
80	53	C5	B10	-	PC12	I/O	FT	PC12	USART3_CK/LCD_SEG30 /LCD_SEG42/LCD_COM6	-
81	-	-	C9	-	PD0	I/O	FT	PD0	SPI2_NSS/TIM9_CH1	-
82	-	-	B9	-	PD1	I/O	FT	PD1	SPI2_SCK	-
83	54	B5	C8	-	PD2	I/O	FT	PD2	TIM3_ETR/LCD_SEG31/ LCD_SEG43/LCD_COM7	-
84	-	-	B8	-	PD3	I/O	FT	PD3	USART2_CTS/ SPI2_MISO	-
85	-	-	B7	-	PD4	I/O	FT	PD4	USART2_RTS/ SPI2_MOSI	-
86	-	-	A6	-	PD5	I/O	FT	PD5	USART2_TX	-
87	-	-	B6	-	PD6	I/O	FT	PD6	USART2_RX	-
88	-	-	A5	-	PD7	I/O	FT	PD7	USART2_CK/TIM9_CH2	-
89	55	A5	A8	39	PB3	I/O	FT	JTDO	TIM2_CH2/PB3/ SPI1_SCK/LCD_SEG7/ JTDO	COMP2_INM

Table 19. Current consumption in Sleep mode

Symbol	Parameter	Conditions		f_{HCLK}	Typ	Max(1)			Unit
						55 °C	85 °C	105 °C	
I_{DD} (Sleep)	Supply current in Sleep mode, code executed from RAM, Flash switched OFF	f_{HSE} = f_{HCLK} up to 16 MHz included, f_{HSE} = f_{HCLK}/2 above 16 MHz (PLL ON)(2)	Range 3, V_{CORE}=1.2 V VOS[1:0] = 11	1 MHz	80	140	140	140	µA
				2 MHz	150	210	210	210	
				4 MHz	280	330	330	330(3)	
			Range 2, V_{CORE}=1.5 V VOS[1:0] = 10	4 MHz	280	400	400	400	
				8 MHz	450	550	550	550	
				16 MHz	900	1050	1050	1050	
			Range 1, V_{CORE}=1.8 V VOS[1:0] = 01	8 MHz	550	650	650	650	
				16 MHz	1050	1200	1200	1200	
				32 MHz	2300	2500	2500	2500	
		HSI clock source (16 MHz)	Range 2, V_{CORE}=1.5 V VOS[1:0] = 10	16 MHz	1000	1100	1100	1100	
			Range 1, V_{CORE}=1.8 V VOS[1:0] = 01	32 MHz	2300	2500	2500	2500	
		MSI clock, 65 kHz	Range 3, V_{CORE}=1.2 V VOS[1:0] = 11	65 kHz	30	50	50	60	
		MSI clock, 524 kHz		524 kHz	50	70	70	80	
		MSI clock, 4.2 MHz		4.2 MHz	200	240	240	250	
	Supply current in Sleep mode, code executed from Flash	f_{HSE} = f_{HCLK} up to 16 MHz included, f_{HSE} = f_{HCLK}/2 above 16 MHz (PLL ON)(2)	Range 3, V_{CORE}=1.2 V VOS[1:0] = 11	1 MHz	80	140	140	140	µA
				2 MHz	150	210	210	210	
				4 MHz	290	350	350	350	
			Range 2, V_{CORE}=1.5 V VOS[1:0] = 10	4 MHz	300	400	400	400	
				8 MHz	500	600	600	600	
				16 MHz	1000	1100	1100	1100	
			Range 1, V_{CORE}=1.8 V VOS[1:0] = 01	8 MHz	550	650	650	650	
				16 MHz	1050	1200	1200	1200	
				32 MHz	2300	2500	2500	2500	
		HSI clock source (16 MHz)	Range 2, V_{CORE}=1.5 V VOS[1:0] = 10	16 MHz	1000	1100	1100	1100	
			Range 1, V_{CORE}=1.8 V VOS[1:0] = 01	32 MHz	2300	2500	2500	2500	

6.3.5 Wakeup time from Low power mode

The wakeup times given in the following table are measured with the MSI RC oscillator. The clock source used to wake up the device depends on the current operating mode:

- Sleep mode: the clock source is the clock that was set before entering Sleep mode
- Stop mode: the clock source is the MSI oscillator in the range configured before entering Stop mode
- Standby mode: the clock source is the MSI oscillator running at 2.1 MHz

All timings are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in *Table 13*.

Table 25. Low-power mode wakeup timings

Symbol	Parameter	Conditions	Typ	Max(1)	Unit
$t_{WUSLEEP}$	Wakeup from Sleep mode	f_{HCLK} = 32 MHz	0.36	-	µs
$t_{WUSLEEP\_LP}$	Wakeup from Low power sleep mode f_{HCLK} = 262 kHz	f_{HCLK} = 262 kHz Flash enabled	32	-	
		f_{HCLK} = 262 kHz Flash switched OFF	34	-	
t_{WUSTOP}	Wakeup from Stop mode, regulator in Run mode	$f_{HCLK} = f_{MSI}$ = 4.2 MHz	8.2	-	
	Wakeup from Stop mode, regulator in low power mode	$f_{HCLK} = f_{MSI}$ = 4.2 MHz Voltage Range 1 and 2	8.2	9.3	
		$f_{HCLK} = f_{MSI}$ = 4.2 MHz Voltage Range 3	7.8	11.2	
		$f_{HCLK} = f_{MSI}$ = 2.1 MHz	10	12	
		$f_{HCLK} = f_{MSI}$ = 1.05 MHz	15.5	20	
		$f_{HCLK} = f_{MSI}$ = 524 kHz	29	35	
		$f_{HCLK} = f_{MSI}$ = 262 kHz	53	63	
		$f_{HCLK} = f_{MSI}$ = 131 kHz	105	118	
		f_{HCLK} = MSI = 65 kHz	210	237	
$t_{WUSTDBY}$	Wakeup from Standby mode FWU bit = 1	f_{HCLK} = MSI = 2.1 MHz	50	103	
	Wakeup from Standby mode FWU bit = 0	f_{HCLK} = MSI = 2.1 MHz	2.5	3.2	ms

1. Guaranteed by characterization results, unless otherwise specified

6.3.9 Memory characteristics

The characteristics are given at T_A = -40 to 105 °C unless otherwise specified.

RAM memory

Table 34. RAM and hardware registers

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
VRM	Data retention mode(1)	STOP mode (or RESET)	1.65	-	-	V

1. Minimum supply voltage without losing data stored in RAM (in Stop mode or under Reset) or in hardware registers (only in Stop mode).

Flash memory and data EEPROM

Table 35. Flash memory and data EEPROM characteristics

Symbol	Parameter	Conditions	Min	Typ	Max(1)	Unit
V_{DD}	Operating voltage Read / Write / Erase	-	1.65	-	3.6	V
t_{prog}	Programming / erasing time for byte / word / double word / half-page	Erasing	-	3.28	3.94	ms
		Programming	-	3.28	3.94	
I_{DD}	Average current during whole program/erase operation	T_A = 25 °C, V_{DD} = 3.6 V	-	300	-	µA
	Maximum current (peak) during program/erase operation		-	1.5	2.5	mA

1. Guaranteed by design.

Table 36. Flash memory, data EEPROM endurance and data retention

Symbol	Parameter	Conditions	Value			Unit
			Min(1)	Typ	Max	
NCYC(2)	Cycling (erase / write) Program memory	T_A = -40°C to 105 °C	10	-	-	kcycles
	Cycling (erase / write) EEPROM data memory		300	-	-	
t_{RET}(2)	Data retention (program memory) after 10 kcycles at T_A = 85 °C	TRET = +85 °C	30	-	-	years
	Data retention (EEPROM data memory) after 300 kcycles at T_A = 85 °C		30	-	-	
	Data retention (program memory) after 10 kcycles at T_A = 105 °C	TRET = +105 °C	10	-	-	
	Data retention (EEPROM data memory) after 300 kcycles at T_A = 105 °C		10	-	-	

1. Guaranteed by characterization results.
2. Characterization is done according to JEDEC JESD22-A117.

6.3.10 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports). the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- **Electrostatic discharge (ESD)** (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- **FTB**: A Burst of Fast Transient voltage (positive and negative) is applied to V_{DD} and V_{SS} through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in *Table 37*. They are based on the EMS levels and classes defined in application note AN1709.

Table 37. EMS characteristics

Symbol	Parameter	Conditions	Level/ Class
V_{FESD}	Voltage limits to be applied on any I/O pin to induce a functional disturbance	V_{DD} = 3.3 V, LQFP100, T_A = +25 °C, f_{HCLK} = 32 MHz conforms to IEC 61000-4-2	2B
V_{EFTB}	Fast transient voltage burst limits to be applied through 100 pF on V_{DD} and V_{SS} pins to induce a functional disturbance	V_{DD} = 3.3 V, LQFP100, T_A = +25 °C, f_{HCLK} = 32 MHz conforms to IEC 61000-4-4	4A

Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user applies EMC software optimization and prequalification tests in relation with the EMC level requested for his application.

Software recommendations

The software flowchart must include the management of runaway conditions such as:

- Corrupted program counter
- Unexpected reset
- Critical data corruption (control registers...)

Prequalification trials

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the oscillator pins for 1 second.

Table 55. ADC accuracy(1)(2)

Symbol	Parameter	Test conditions	Min(3)	Typ	Max(3)	Unit
ET	Total unadjusted error	$2.4\ V \le V_{DDA} \le 3.6\ V$ $2.4\ V \le V_{REF+} \le 3.6\ V$ $f_{ADC} = 8\ MHz$, $R_{AIN} = 50\ \Omega$ $T_A = -40$ to $105\ °C$	-	2	4	LSB
EO	Offset error		-	1	2	
EG	Gain error		-	1.5	3.5	
ED	Differential linearity error		-	1	2	
EL	Integral linearity error		-	1.7	3	
ENOB	Effective number of bits	$2.4\ V \le V_{DDA} \le 3.6\ V$ $V_{DDA} = V_{REF+}$ $f_{ADC} = 16\ MHz$, $R_{AIN} = 50\ \Omega$ $T_A = -40$ to $105\ °C$ $1\ kHz \le F_{input} \le 100\ kHz$	9.2	10	-	bits
SINAD	Signal-to-noise and distortion ratio		57.5	62	-	dB
SNR	Signal-to-noise ratio		57.5	62	-	
THD	Total harmonic distortion		-74	-75	-	
ET	Total unadjusted error	$2.4\ V \le V_{DDA} \le 3.6\ V$ $1.8\ V \le V_{REF+} \le 2.4\ V$ $f_{ADC} = 4\ MHz$, $R_{AIN} = 50\ \Omega$ $T_A = -40$ to $105\ °C$	-	4	6.5	LSB
EO	Offset error		-	2	4	
EG	Gain error		-	4	6	
ED	Differential linearity error		-	1	2	
EL	Integral linearity error		-	1.5	3	
ET	Total unadjusted error	$1.8\ V \le V_{DDA} \le 2.4\ V$ $1.8\ V \le V_{REF+} \le 2.4\ V$ $f_{ADC} = 4\ MHz$, $R_{AIN} = 50\ \Omega$ $T_A = -40$ to $105\ °C$	-	2	3	LSB
EO	Offset error		-	1	1.5	
EG	Gain error		-	1.5	2	
ED	Differential linearity error		-	1	2	
EL	Integral linearity error		-	1	1.5	

1. ADC DC accuracy values are measured after internal calibration.
2. ADC accuracy vs. negative injection current: Injecting a negative current on any analog input pins should be avoided as this significantly reduces the accuracy of the conversion being performed on another analog input. It is recommended to add a Schottky diode (pin to ground) to analog pins which may potentially inject negative currents.
   Any positive injection current within the limits specified for $I_{INJ(PIN)}$ and $\Sigma I_{INJ(PIN)}$ in *Section 6.3.12* does not affect the ADC accuracy.
3. Guaranteed by characterization results.

Figure 26. ADC accuracy characteristics

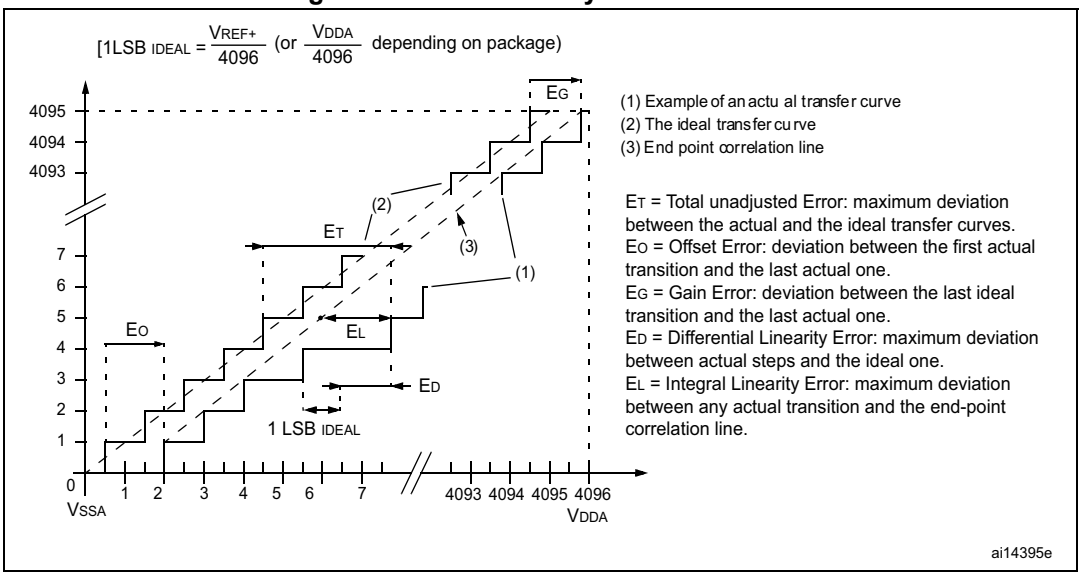
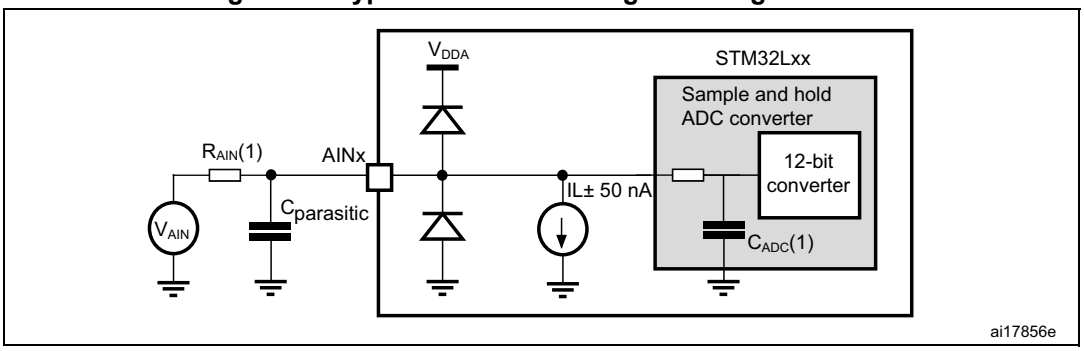


Figure 27. Typical connection diagram using the ADC



1. Refer to *Table 56: Maximum source impedance RAIN max* for the value of R_{AIN} and *Table 54: ADC characteristics* for the value of CADC
2. $C_{parasitic}$ represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (roughly 7 pF). A high $C_{parasitic}$ value will downgrade conversion accuracy. To remedy this, f_{ADC} should be reduced.

6.3.18 DAC electrical specifications

Data guaranteed by design, unless otherwise specified.

Table 57. DAC characteristics

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage	-		1.8	-	3.6	V
V_{REF+}	Reference supply voltage	V_{REF+} must always be below V_{DDA}		1.8	-	3.6	V
V_{REF-}	Lower reference voltage	-			V_{SSA}		V
$I_{DDVREF+}$(1)	Current consumption on V_{REF+} supply V_{REF+} = 3.3 V	No load, middle code (0x800)		-	130	220	µA
		No load, worst code (0x000)		-	220	350	µA
I_{DDA}(1)	Current consumption on V_{DDA} supply V_{DDA} = 3.3 V	No load, middle code (0x800)		-	210	320	µA
		No load, worst code (0xF1C)		-	320	520	µA
R_L	Resistive load	DAC output buffer ON	Connected to V_{SSA}	5	-	-	kΩ
			Connected to V_{DDA}	25	-	-	
C_L	Capacitive load	DAC output buffer ON		-	-	50	pF
R_O	Output impedance	DAC output buffer OFF		12	16	20	kΩ
V_{DAC_OUT}	Voltage on DAC_OUT output	DAC output buffer ON		0.2	-	V_{DDA} – 0.2	V
		DAC output buffer OFF		0.5	-	V_{REF+} – 1LSB	mV
DNL(1)	Differential non linearity(2)	$C_L \leq 50$ pF, $R_L \geq 5$ kΩ DAC output buffer ON		-	1.5	3	LSB
		No R_{LOAD}, $C_L \leq 50$ pF DAC output buffer OFF		-	1.5	3	
INL(1)	Integral non linearity(3)	$C_L \leq 50$ pF, $R_L \geq 5$ kΩ DAC output buffer ON		-	2	4	
		No R_{LOAD}, $C_L \leq 50$ pF DAC output buffer OFF		-	2	4	
Offset(1)	Offset error at code 0x800 (4)	$C_L \leq 50$ pF, $R_L \geq 5$ kΩ DAC output buffer ON		-	±10	±25	
		No R_{LOAD}, $C_L \leq 50$ pF DAC output buffer OFF		-	±5	±8	
Offset1(1)	Offset error at code 0x001(5)	No R_{LOAD}, $C_L \leq 50$ pF DAC output buffer OFF		-	±1.5	±5	

Table 61. Comparator 2 characteristics

Symbol	Parameter	Conditions	Min	Typ	Max(1)	Unit
V_{DDA}	Analog supply voltage	-	1.	-	3.6	V
V_{IN}	Comparator 2 input voltage range	-	0	-	V_{DDA}	V
t_{START}	Comparator startup time	Fast mode	-	15	20	µs
		Slow mode	-	20	25	
$t_{d\ slow}$	Propagation delay(2) in slow mode	1. V ≤V_{DDA} ≤2.7 V	-	1.8	3.5	
		2.7 V ≤V_{DDA} ≤3.6 V	-	2.5	6	
$t_{d\ fast}$	Propagation delay(2) in fast mode	1. V ≤V_{DDA} ≤2.7 V	-	0.8	2	
		2.7 V ≤V_{DDA} ≤3.6 V	-	1.2	4	
V_{offset}	Comparator offset error	-	-	±4	±20	mV
dThreshold/ dt	Threshold voltage temperature coefficient	V_{DDA} = 3.3V T_A = 0 to 50 °C V- = V_{REFINT}, 3/4 V_{REFINT}, 1/2 V_{REFINT}, 1/4 V_{REFINT}	-	15	100	ppm /°C
I_{COMP2}	Current consumption(3)	Fast mode	-	3.5	5	µA
		Slow mode	-	0.5	2	

1. Guaranteed by characterization results.
2. The delay is characterized for 100 mV input step with 10 mV overdrive on the inverting input, the non-inverting input set to the reference.
3. Comparator consumption only. Internal reference voltage (necessary for comparator operation) is not included.

6.3.21 LCD controller (STM32L152xx only)

The STM32L152xx embeds a built-in step-up converter to provide a constant LCD reference voltage independently from the V_{DD} voltage. An external capacitor C_{ext} must be connected to the V_{LCD} pin to decouple this converter.

Table 62. LCD controller characteristics

Symbol	Parameter	Min	Typ	Max	Unit
V_{LCD}	LCD external voltage	-	-	3.6	V
V_{LCD0}	LCD internal reference voltage 0	-	2.6	-	
V_{LCD1}	LCD internal reference voltage 1	-	2.73	-	
V_{LCD2}	LCD internal reference voltage 2	-	2.86	-	
V_{LCD3}	LCD internal reference voltage 3	-	2.98	-	
V_{LCD4}	LCD internal reference voltage 4	-	3.12	-	
V_{LCD5}	LCD internal reference voltage 5	-	3.26	-	
V_{LCD6}	LCD internal reference voltage 6	-	3.4	-	
V_{LCD7}	LCD internal reference voltage 7	-	3.55	-	
C_{ext}	V_{LCD} external capacitance	0.1	-	2	µF
I_{LCD}(1)	Supply current at V_{DD} = 2.2 V	-	3.3	-	µA
	Supply current at V_{DD} = 3.0 V	-	3.1	-	
R_{Htot}(2)	Low drive resistive network overall value	5.28	6.6	7.92	MΩ
R_L(2)	High drive resistive network total value	192	240	288	kΩ
V_{44}	Segment/Common highest level voltage	-	-	V_{LCD}	V
V_{34}	Segment/Common 3/4 level voltage	-	3/4 V_{LCD}	-	V
V_{23}	Segment/Common 2/3 level voltage	-	2/3 V_{LCD}	-	
V_{12}	Segment/Common 1/2 level voltage	-	1/2 V_{LCD}	-	
V_{13}	Segment/Common 1/3 level voltage	-	1/3 V_{LCD}	-	
V_{14}	Segment/Common 1/4 level voltage	-	1/4 V_{LCD}	-	
V_0	Segment/Common lowest level voltage	0	-	-	
ΔVxx(3)	Segment/Common level voltage error T_A = -40 to 85 °C	-	-	±50	mV

1. LCD enabled with 3 V internal step-up active, 1/8 duty, 1/4 bias, division ratio= 64, all pixels active, no LCD connected
2. Guaranteed by design.
3. Guaranteed by characterization results.

Table 67. UFBGA100 7 x 7 mm, 0.5 mm pitch, package mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
eee	-	-	0.15	-	-	0.0059
fff	-	-	0.05	-	-	0.002

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 45. UFBGA100 7 x 7 mm, 0.5 mm pitch, package recommended footprint

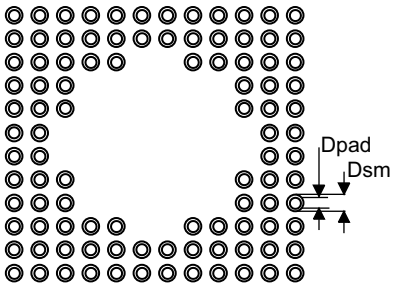


Table 68. UFBGA100 7 x 7 mm, 0.5 mm pitch, recommended PCB design rules

Dimension	Recommended values
Pitch	0.5
Dpad	0.280 mm
Dsm	0.370 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.280 mm
Stencil thickness	Between 0.100 mm and 0.125 mm

7.7 Thermal characteristics

The maximum chip-junction temperature, T_J max, in degrees Celsius, may be calculated using the following equation:

T_J max = T_A max + (P_D max × Θ_{JA})

Where:

- T_A max is the maximum ambient temperature in °C,
- Θ_{JA} is the package junction-to-ambient thermal resistance, in °C/W,
- P_D max is the sum of P_{INT} max and $P_{I/O}$ max (P_D max = P_{INT} max + $P_{I/O}$max),
- P_{INT} max is the product of I_{DD} and V_{DD}, expressed in Watts. This is the maximum chip internal power.

$P_{I/O}$ max represents the maximum power dissipation on output pins where:

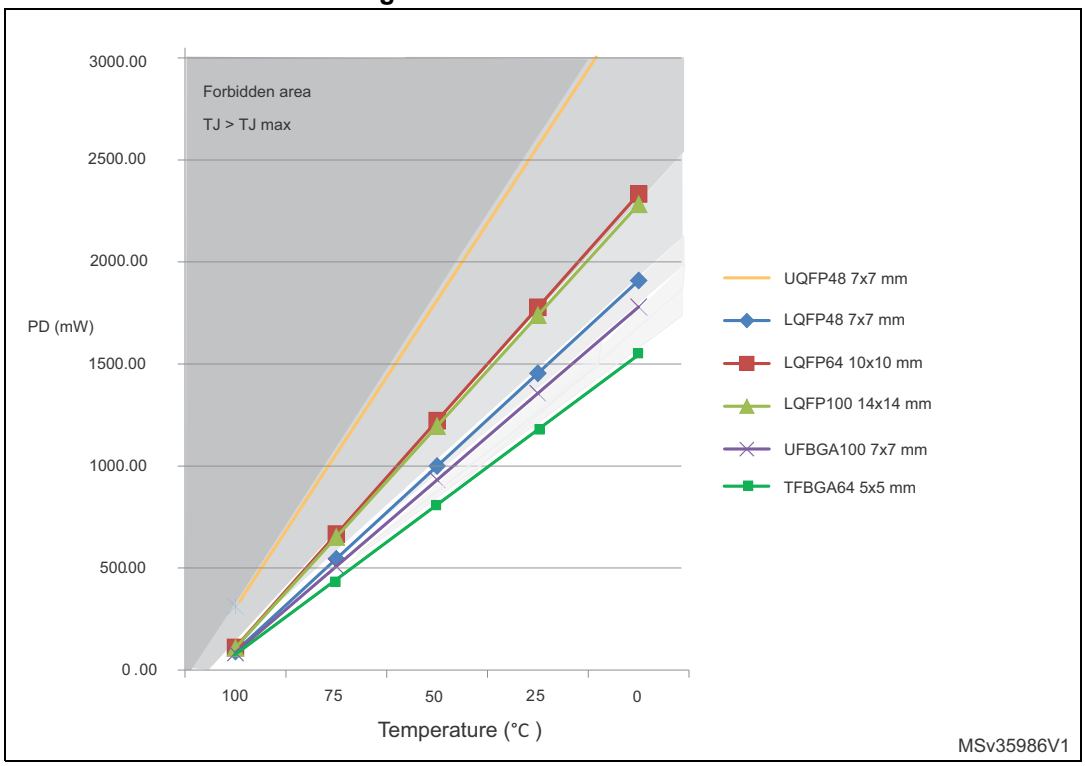
$P_{I/O}$ max = Σ (V_{OL} × I_{OL}) + Σ((V_{DD} – V_{OH}) × I_{OH}),

taking into account the actual V_{OL} / I_{OL} and V_{OH} / I_{OH} of the I/Os at low and high level in the application.

Table 71. Thermal characteristics

Symbol	Parameter	Value	Unit
Θ_{JA}	**Thermal resistance junction-ambient** BGA100 - 7 x 7 mm	59	°C/W
	Thermal resistance junction-ambient LQFP100 - 14 x 14 mm / 0.5 mm pitch	46	
	Thermal resistance junction-ambient TFBGA64 - 5 x 5 mm	65	
	Thermal resistance junction-ambient LQFP64 - 10 x 10 mm / 0.5 mm pitch	45	
	Thermal resistance junction-ambient LQFP48 - 7 x 7 mm / 0.5 mm pitch	55	
	Thermal resistance junction-ambient UFQFPN48 - 7 x 7 mm / 0.5 mm pitch	16	

Figure 50. Thermal resistance



7.7.1 Reference document

JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air). Available from www.jedec.org.