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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Not For New Designs
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, Cap Sense, DMA, I <sup>2</sup> S, LCD, POR, PWM, WDT
Number of I/O	51
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	10K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 20x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l152r8t6">https://www.e-xfl.com/product-detail/stmicroelectronics/stm32l152r8t6</a>

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HSE crystal oscillators are disabled. The voltage regulator is in the low power mode. The device can be woken up from Stop mode by any of the EXTI line, in 8  $\mu$ s. The EXTI line source can be one of the 16 external lines. It can be the PVD output, the Comparator 1 event or Comparator 2 event (if internal reference voltage is on). It can also be wakened by the USB wakeup.

Stop mode consumption: refer to [Table 22: Typical and maximum current consumptions in Stop mode](#).

- **Standby mode with RTC**

Standby mode is used to achieve the lowest power consumption and real time clock. The internal voltage regulator is switched off so that the entire  $V_{CORE}$  domain is powered off. The PLL, MSI RC, HSI RC and HSE crystal oscillators are also switched off. The LSE or LSI is still running. After entering Standby mode, the RAM and register contents are lost except for registers in the Standby circuitry (wakeup logic, IWDG, RTC, LSI, LSE Crystal 32K osc, RCC\_CSR).

The device exits Standby mode in 60  $\mu$ s when an external reset (NRST pin), an IWDG reset, a rising edge on one of the three WKUP pins, RTC alarm (Alarm A or Alarm B), RTC tamper event, RTC timestamp event or RTC Wakeup event occurs.

- **Standby mode without RTC**

Standby mode is used to achieve the lowest power consumption. The internal voltage regulator is switched off so that the entire  $V_{CORE}$  domain is powered off. The PLL, MSI, RC, HSI and LSI RC, HSE and LSE crystal oscillators are also switched off. After entering Standby mode, the RAM and register contents are lost except for registers in the Standby circuitry (wakeup logic, IWDG, RTC, LSI, LSE Crystal 32K osc, RCC\_CSR).

The device exits Standby mode in 60  $\mu$ s when an external reset (NRST pin) or a rising edge on one of the three WKUP pin occurs.

Standby mode consumption: refer to [Table 23](#).

**Note:** *The RTC, the IWDG, and the corresponding clock sources are not stopped by entering the Stop or Standby mode.*

**Table 3. Functionalities depending on the operating power supply range**

Operating power supply range	Functionalities depending on the operating power supply range			
	DAC and ADC operation	USB	Dynamic voltage scaling range	I/O operation
$V_{DD} = 1.65$ to $1.71$ V	Not functional	Not functional	Range 2 or Range 3	Degraded speed performance
$V_{DD} = 1.71$ to $1.8$ V <sup>(1)</sup>	Not functional	Not functional	Range 1, Range 2 or Range 3	Degraded speed performance
$V_{DD} = 1.8$ to $2.0$ V <sup>(1)</sup>	Conversion time up to 500 Ksps	Not functional	Range 1, Range 2 or Range 3	Degraded speed performance

Five BOR thresholds are available through option bytes, starting from 1.8 V to 3 V. To reduce the power consumption in Stop mode, it is possible to automatically switch off the internal reference voltage ( $V_{REFINT}$ ) in Stop mode. The device remains in reset mode when  $V_{DD}$  is below a specified threshold,  $V_{POR/PDR}$  or  $V_{BOR}$ , without the need for any external reset circuit.

*Note: The start-up time at power-on is typically 3.3 ms when BOR is active at power-up, the start-up time at power-on can be decreased down to 1 ms typically for devices with BOR inactive at power-up.*

The device features an embedded programmable voltage detector (PVD) that monitors the  $V_{DD}/V_{DDA}$  power supply and compares it to the  $V_{PVD}$  threshold. This PVD offers 7 different levels between 1.85 V and 3.05 V, chosen by software, with a step around 200 mV. An interrupt can be generated when  $V_{DD}/V_{DDA}$  drops below the  $V_{PVD}$  threshold and/or when  $V_{DD}/V_{DDA}$  is higher than the  $V_{PVD}$  threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

### 3.3.3 Voltage regulator

The regulator has three operation modes: main (MR), low power (LPR) and power down.

- MR is used in Run mode (nominal regulation)
- LPR is used in the Low-power run, Low-power sleep and Stop modes
- Power down is used in Standby mode. The regulator output is high impedance, the kernel circuitry is powered down, inducing zero consumption but the contents of the registers and RAM are lost except for the standby circuitry (wakeup logic, IWDG, RTC, LSI, LSE crystal 32K osc, RCC\_CSR).

### 3.3.4 Boot modes

At startup, boot pins are used to select one of three boot options:

- Boot from Flash memory
- Boot from System Memory
- Boot from embedded RAM

The boot loader is located in System Memory. It is used to reprogram the Flash memory by using USART1 or USART2. See STM32™ microcontroller system memory boot mode AN2606 for details.

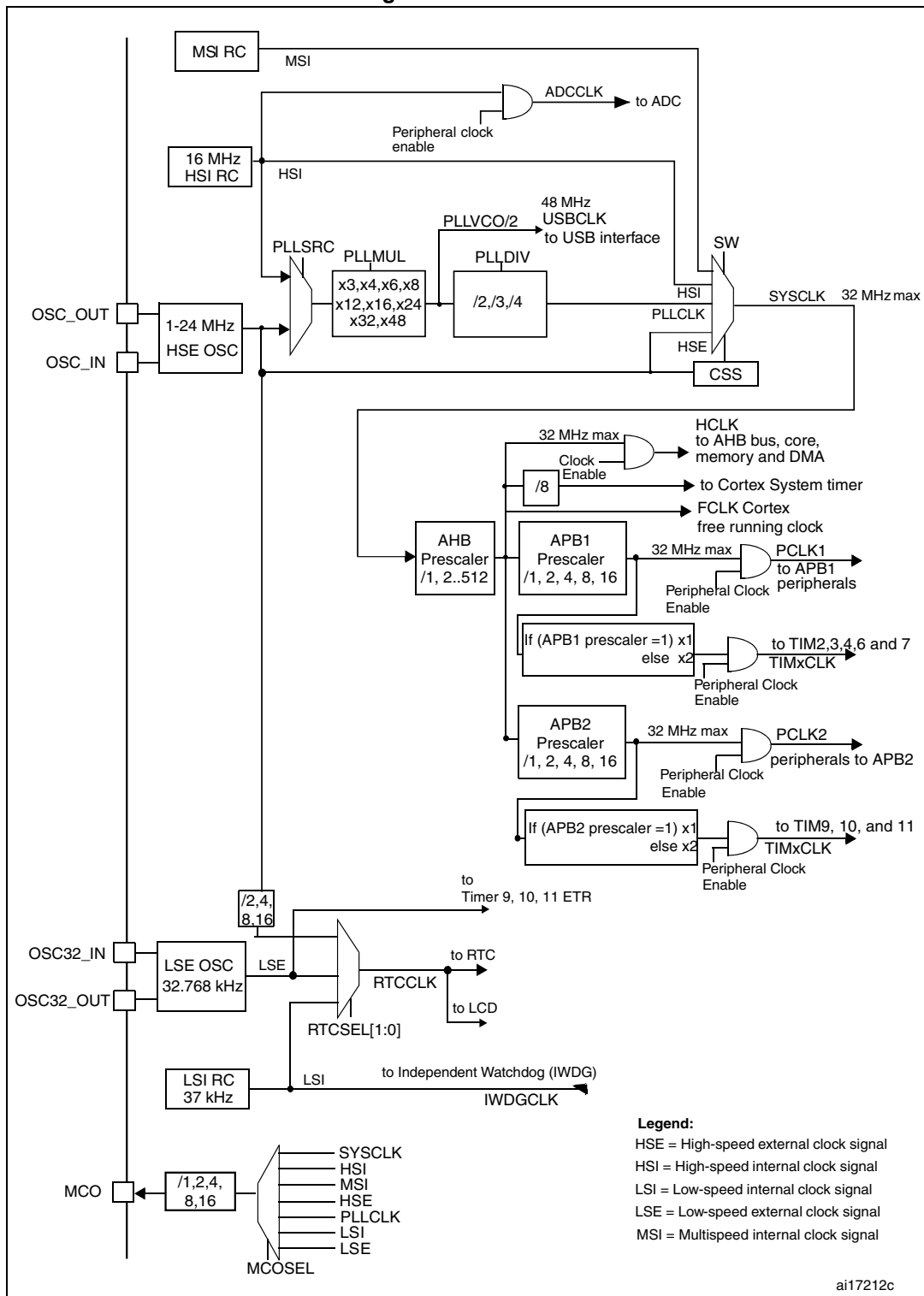
### 3.4 Clock management

The clock controller distributes the clocks coming from different oscillators to the core and the peripherals. It also manages clock gating for low power modes and ensures clock robustness. It features:

- **Clock prescaler:** to get the best trade-off between speed and current consumption, the clock frequency to the CPU and peripherals can be adjusted by a programmable prescaler
- **Safe clock switching:** clock sources can be changed safely on the fly in run mode through a configuration register.
- **Clock management:** to reduce power consumption, the clock controller can stop the clock to the core, individual peripherals or memory.
- **Master clock source:** three different clock sources can be used to drive the master clock:
  - 1-24 MHz high-speed external crystal (HSE), that can supply a PLL
  - 16 MHz high-speed internal RC oscillator (HSI), trimmable by software, that can supply a PLL
  - Multispeed internal RC oscillator (MSI), trimmable by software, able to generate 7 frequencies (65.5 kHz, 131 kHz, 262 kHz, 524 kHz, 1.05 MHz, 2.1 MHz, 4.2 MHz) with a consumption proportional to speed, down to 750 nA typical. When a 32.768 kHz clock source is available in the system (LSE), the MSI frequency can be trimmed by software down to a  $\pm 0.5\%$  accuracy.
- **Auxiliary clock source:** two ultra-low-power clock sources that can be used to drive the LCD controller and the real-time clock:
  - 32.768 kHz low-speed external crystal (LSE)
  - 37 kHz low-speed internal RC (LSI), also used to drive the independent watchdog. The LSI clock can be measured using the high-speed internal RC oscillator for greater precision.
- **RTC and LCD clock sources:** the LSI, LSE or HSE sources can be chosen to clock the RTC and the LCD, whatever the system clock.
- **USB clock source:** the embedded PLL has a dedicated 48 MHz clock output to supply the USB interface.
- **Startup clock:** after reset, the microcontroller restarts by default with an internal 2.1 MHz clock (MSI). The prescaler ratio and clock source can be changed by the application program as soon as the code execution starts.
- **Clock security system (CSS):** this feature can be enabled by software. If a HSE clock failure occurs, the master clock is automatically switched to HSI and a software interrupt is generated if enabled.
- **Clock-out capability (MCO: microcontroller clock output):** it outputs one of the internal clocks for external use by the application.

Several prescalers allow the configuration of the AHB frequency, the high-speed APB (APB2) and the low-speed APB (APB1) domains. The maximum frequency of the AHB and the APB domains is 32 MHz. See [Figure 2](#) for details on the clock tree.

Figure 2. Clock tree



### 3.10 ADC (analog-to-digital converter)

A 12-bit analog-to-digital converters is embedded into STM32L151x6/8/B and STM32L152x6/8/B devices with up to 24 external channels, performing conversions in single-shot or scan mode. In scan mode, automatic conversion is performed on a selected group of analog inputs.

The ADC can be served by the DMA controller.

An analog watchdog feature allows very precise monitoring of the converted voltage of one, some or all selected channels. An interrupt is generated when the converted voltage is outside the programmed thresholds.

The events generated by the general-purpose timers (TIMx) can be internally connected to the ADC start trigger and injection trigger, to allow the application to synchronize A/D conversions and timers. An injection mode allows high priority conversions to be done by interrupting a scan mode which runs in as a background task.

The ADC includes a specific low power mode. The converter is able to operate at maximum speed even if the CPU is operating at a very low frequency and has an auto-shutdown function. The ADC's runtime and analog front-end current consumption are thus minimized whatever the MCU operating mode.

#### 3.10.1 Temperature sensor

The temperature sensor (TS) generates a voltage  $V_{\text{SENSE}}$  that varies linearly with temperature.

The temperature sensor is internally connected to the ADC\_IN16 input channel which is used to convert the sensor output voltage into a digital value.

The sensor provides good linearity but it has to be calibrated to obtain good overall accuracy of the temperature measurement. As the offset of the temperature sensor varies from chip to chip due to process variation, the uncalibrated internal temperature sensor is suitable for applications that detect temperature changes only.

To improve the accuracy of the temperature sensor measurement, each device is individually factory-calibrated by ST. The temperature sensor factory calibration data are stored by ST in the system memory area, accessible in read-only mode, see [Table 58: Temperature sensor calibration values](#).

#### 3.10.2 Internal voltage reference ( $V_{\text{REFINT}}$ )

The internal voltage reference ( $V_{\text{REFINT}}$ ) provides a stable (bandgap) voltage output for the ADC and Comparators.  $V_{\text{REFINT}}$  is internally connected to the ADC\_IN17 input channel. It enables accurate monitoring of the  $V_{\text{DD}}$  value (when no external voltage,  $V_{\text{REF+}}$ , is available for ADC). The precise voltage of  $V_{\text{REFINT}}$  is individually measured for each part by ST during production test and stored in the system memory area. It is accessible in read-only mode see [Table 16: Embedded internal reference voltage](#).

### 3.11 DAC (digital-to-analog converter)

The two 12-bit buffered DAC channels can be used to convert two digital signals into two analog voltage signal outputs. The chosen design structure is composed of integrated resistor strings and an amplifier in non-inverting configuration.

Table 8. STM32L151x6/8/B and STM32L152x6/8/B pin definitions (continued)

Pins					Pin name	Pin type <sup>(1)</sup>	I/O structure	Main function <sup>(2)</sup> (after reset)	Pins functions	Additional functions
LQFP100	LQFP64	TFBGA64	UFBGA100	LQFP48 or UQFPN48					Alternate functions	
35	26	F5	M5	18	PB0	I/O	TC	PB0	TIM3_CH3/LCD_SEG5	ADC_IN8/ COMP1_INP/ VREF_OUT
36	27	G5	M6	19	PB1	I/O	FT	PB1	TIM3_CH4/LCD_SEG6	ADC_IN9/ COMP1_INP/ VREF_OUT
37	28	G6	L6	20	PB2	I/O	FT	PB2/BOOT1	BOOT1	-
38	-	-	M7	-	PE7	I/O	TC	PE7	-	ADC_IN22/ COMP1_INP
39	-	-	L7	-	PE8	I/O	TC	PE8	-	ADC_IN23/ COMP1_INP
40	-	-	M8	-	PE9	I/O	TC	PE9	TIM2_CH1_ETR	ADC_IN24/ COMP1_INP
41	-	-	L8	-	PE10	I/O	TC	PE10	TIM2_CH2	ADC_IN25/ COMP1_INP
42	-	-	M9	-	PE11	I/O	FT	PE11	TIM2_CH3	-
43	-	-	L9	-	PE12	I/O	FT	PE12	TIM2_CH4/SPI1_NSS	-
44	-	-	M10	-	PE13	I/O	FT	PE13	SPI1_SCK	-
45	-	-	M11	-	PE14	I/O	FT	PE14	SPI1_MISO	-
46	-	-	M12	-	PE15	I/O	FT	PE15	SPI1_MOSI	-
47	29	G7	L10	21	PB10	I/O	FT	PB10	I2C2_SCL/USART3_TX/ TIM2_CH3/LCD_SEG10	-
48	30	H7	L11	22	PB11	I/O	FT	PB11	I2C2_SDA/USART3_RX/ TIM2_CH4/LCD_SEG11	-
49	31	D6	F12	23	V <sub>SS_1</sub>	S	-	V <sub>SS_1</sub>	-	-
50	32	E6	G12	24	V <sub>DD_1</sub>	S	-	V <sub>DD_1</sub>	-	-
51	33	H8	L12	25	PB12	I/O	FT	PB12	SPI2_NSS/I2C2_SMBA/ USART3_CK/ LCD_SEG12/TIM10_CH1	ADC_IN18/ COMP1_INP
52	34	G8	K12	26	PB13	I/O	FT	PB13	SPI2_SCK/USART3_CTS/ LCD_SEG13/ TIM9_CH1	ADC_IN19/ COMP1_INP



Table 19. Current consumption in Sleep mode (continued)

Symbol	Parameter	Conditions		f <sub>HCLK</sub>	Typ	Max <sup>(1)</sup>			Unit
						55 °C	85 °C	105 °C	
I <sub>DD</sub> (Sleep)	Supply current in Sleep mode, code executed from Flash	MSI clock, 65 kHz	Range 3, V <sub>CORE</sub> =1.2V VOS[1:0] = 11	65 kHz	40	70	70	80	μA
		MSI clock, 524 kHz		524 kHz	60	90	90	100	
		MSI clock, 4.2 MHz		4.2 MHz	210	250	250	260	

1. Guaranteed by characterization results, unless otherwise specified.
2. Oscillator bypassed (HSEBYP = 1 in RCC\_CR register)
3. Tested in production

Table 21. Current consumption in Low power sleep mode

Symbol	Parameter	Conditions			Typ	Max (1)	Unit
$I_{DD}$ (LP Sleep)	Supply current in Low power sleep mode	All peripherals OFF, $V_{DD}$ from 1.65 V to 3.6 V	MSI clock, 65 kHz $f_{HCLK} = 32$ kHz Flash OFF	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	4.4	-	$\mu\text{A}$
			MSI clock, 65 kHz $f_{HCLK} = 32$ kHz Flash ON	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	17.5	25	
				$T_A = 85\text{ }^{\circ}\text{C}$	22	27	
				$T_A = 105\text{ }^{\circ}\text{C}$	31	39	
			MSI clock, 65 kHz $f_{HCLK} = 65$ kHz, Flash ON	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	18	26	
				$T_A = 85\text{ }^{\circ}\text{C}$	23	28	
				$T_A = 105\text{ }^{\circ}\text{C}$	31	40	
			MSI clock, 131 kHz $f_{HCLK} = 131$ kHz, Flash ON	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	22	30	
				$T_A = 55\text{ }^{\circ}\text{C}$	24	32	
				$T_A = 85\text{ }^{\circ}\text{C}$	26	34	
				$T_A = 105\text{ }^{\circ}\text{C}$	34	45	
		TIM9 and USART1 enabled, Flash ON, $V_{DD}$ from 1.65 V to 3.6 V	MSI clock, 65 kHz $f_{HCLK} = 32$ kHz	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	17.5	25	
				$T_A = 85\text{ }^{\circ}\text{C}$	22	27	
				$T_A = 105\text{ }^{\circ}\text{C}$	31	39	
			MSI clock, 65 kHz $f_{HCLK} = 65$ kHz	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	18	26	
				$T_A = 85\text{ }^{\circ}\text{C}$	23	28	
				$T_A = 105\text{ }^{\circ}\text{C}$	31	40	
			MSI clock, 131 kHz $f_{HCLK} = 131$ kHz	$T_A = -40\text{ }^{\circ}\text{C}$ to $25\text{ }^{\circ}\text{C}$	22	30	
				$T_A = 55\text{ }^{\circ}\text{C}$	24	32	
				$T_A = 85\text{ }^{\circ}\text{C}$	26	34	
				$T_A = 105\text{ }^{\circ}\text{C}$	34	45	
$I_{DD}$ Max (LP Sleep)	Max allowed current in Low power Sleep mode	$V_{DD}$ from 1.65 V to 3.6 V	-	-	-	200	

1. Guaranteed by characterization results, unless otherwise specified.

Table 24. Peripheral current consumption<sup>(1)</sup> (continued)

Peripheral		Typical consumption, V <sub>DD</sub> = 3.0 V, T <sub>A</sub> = 25 °C				Unit
		Range 1, V <sub>CORE</sub> =1.8 V VOS[1:0] = 01	Range 2, V <sub>CORE</sub> =1.5 V VOS[1:0] = 10	Range 3, V <sub>CORE</sub> =1.2 V VOS[1:0] = 11	Low power sleep and run	
AHB	GPIOA	5	4.5	3.5	4	μA/MHz (f <sub>HCLK</sub> )
	GPIOB	5	4.5	3.5	4.5	
	GPIOC	5	4.5	3.5	4.5	
	GPIOD	5	4.5	3.5	4.5	
	GPIOE	5	4.5	3.5	4.5	
	GPIOH	4	4	3	3.5	
	CRC	1	0.5	0.5	0.5	
	FLASH	13	11.5	9	18.5	
	DMA1	12	10	8	10.5	
All enabled		166	138	106	130	
I <sub>DD</sub> (RTC)		0.47				μA
I <sub>DD</sub> (LCD)		3.1				
I <sub>DD</sub> (ADC) <sup>(3)</sup>		1450				
I <sub>DD</sub> (DAC) <sup>(4)</sup>		340				
I <sub>DD</sub> (COMP1)		0.16				
I <sub>DD</sub> (COMP2)	Slow mode	2				
	Fast mode	5				
I <sub>DD</sub> (PVD / BOR) <sup>(5)</sup>		2.6				
I <sub>DD</sub> (IWDG)		0.25				

1. Data based on differential I<sub>DD</sub> measurement between all peripherals OFF and one peripheral with clock enabled, in the following conditions: f<sub>HCLK</sub> = 32 MHz (Range 1), f<sub>HCLK</sub> = 16 MHz (Range 2), f<sub>HCLK</sub> = 4 MHz (Range 3), f<sub>HCLK</sub> = 64kHz (Low power run/sleep), f<sub>APB1</sub> = f<sub>HCLK</sub>, f<sub>APB2</sub> = f<sub>HCLK</sub>, default prescaler value for each peripheral. The CPU is in Sleep mode in both cases. No I/O pins toggling.
2. HSI oscillator is OFF for this measure.
3. Data based on a differential I<sub>DD</sub> measurement between ADC in reset configuration and continuous ADC conversion (HSI consumption not included).
4. Data based on a differential I<sub>DD</sub> measurement between DAC in reset configuration and continuous DAC conversion of V<sub>DD</sub>/2. DAC is in buffered mode, output is left floating.
5. Including supply current of internal reference voltage.

## Multi-speed internal (MSI) RC oscillator

Table 32. MSI oscillator characteristics

Symbol	Parameter	Condition	Typ	Max	Unit
$f_{\text{MSI}}$	Frequency after factory calibration, done at $V_{\text{DD}} = 3.3 \text{ V}$ and $T_{\text{A}} = 25 \text{ }^{\circ}\text{C}$	MSI range 0	65.5	-	kHz
		MSI range 1	131	-	
		MSI range 2	262	-	
		MSI range 3	524	-	
		MSI range 4	1.05	-	MHz
		MSI range 5	2.1	-	
		MSI range 6	4.2	-	
$\text{ACC}_{\text{MSI}}$	Frequency error after factory calibration	-	$\pm 0.5$	-	%
$D_{\text{TEMP}(\text{MSI})}^{(1)}$	MSI oscillator frequency drift $0 \text{ }^{\circ}\text{C} \leq T_{\text{A}} \leq 85 \text{ }^{\circ}\text{C}$	-	$\pm 3$	-	%
$D_{\text{VOLT}(\text{MSI})}^{(1)}$	MSI oscillator frequency drift $1.65 \text{ V} \leq V_{\text{DD}} \leq 3.6 \text{ V}$ , $T_{\text{A}} = 25 \text{ }^{\circ}\text{C}$	-	-	2.5	%/V
$I_{\text{DD}(\text{MSI})}^{(2)}$	MSI oscillator power consumption	MSI range 0	0.75	-	$\mu\text{A}$
		MSI range 1	1	-	
		MSI range 2	1.5	-	
		MSI range 3	2.5	-	
		MSI range 4	4.5	-	
		MSI range 5	8	-	
		MSI range 6	15	-	
$t_{\text{SU}(\text{MSI})}$	MSI oscillator startup time	MSI range 0	30	-	$\mu\text{s}$
		MSI range 1	20	-	
		MSI range 2	15	-	
		MSI range 3	10	-	
		MSI range 4	6	-	
		MSI range 5	5	-	
		MSI range 6, Voltage range 1 and 2	3.5	-	
		MSI range 6, Voltage range 3	5	-	

### 6.3.9 Memory characteristics

The characteristics are given at  $T_A = -40$  to  $105\text{ }^{\circ}\text{C}$  unless otherwise specified.

#### RAM memory

**Table 34. RAM and hardware registers**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
VRM	Data retention mode <sup>(1)</sup>	STOP mode (or RESET)	1.65	-	-	V

1. Minimum supply voltage without losing data stored in RAM (in Stop mode or under Reset) or in hardware registers (only in Stop mode).

#### Flash memory and data EEPROM

**Table 35. Flash memory and data EEPROM characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max <sup>(1)</sup>	Unit
$V_{DD}$	Operating voltage Read / Write / Erase	-	1.65	-	3.6	V
$t_{prog}$	Programming / erasing time for byte / word / double word / half- page	Erasing	-	3.28	3.94	ms
		Programming	-	3.28	3.94	
$I_{DD}$	Average current during whole program/erase operation	$T_A = 25\text{ }^{\circ}\text{C}$ , $V_{DD} = 3.6\text{ V}$	-	300	-	$\mu\text{A}$
	Maximum current (peak) during program/erase operation		-	1.5	2.5	mA

1. Guaranteed by design.

**Table 36. Flash memory, data EEPROM endurance and data retention**

Symbol	Parameter	Conditions	Value			Unit
			Min <sup>(1)</sup>	Typ	Max	
NCYC <sup>(2)</sup>	Cycling (erase / write) Program memory	$T_A = -40\text{ }^{\circ}\text{C}$ to $105\text{ }^{\circ}\text{C}$	10	-	-	kcycles
	Cycling (erase / write) EEPROM data memory		300	-	-	
$t_{RET}$ <sup>(2)</sup>	Data retention (program memory) after 10 kcycles at $T_A = 85\text{ }^{\circ}\text{C}$	TRET = $+85\text{ }^{\circ}\text{C}$	30	-	-	years
	Data retention (EEPROM data memory) after 300 kcycles at $T_A = 85\text{ }^{\circ}\text{C}$		30	-	-	
	Data retention (program memory) after 10 kcycles at $T_A = 105\text{ }^{\circ}\text{C}$	TRET = $+105\text{ }^{\circ}\text{C}$	10	-	-	
	Data retention (EEPROM data memory) after 300 kcycles at $T_A = 105\text{ }^{\circ}\text{C}$		10	-	-	

1. Guaranteed by characterization results.  
2. Characterization is done according to JEDEC JESD22-A117.

**SPI characteristics**

Unless otherwise specified, the parameters given in the following table are derived from tests performed under ambient temperature,  $f_{PCLKx}$  frequency and  $V_{DD}$  supply voltage conditions summarized in [Table 13](#).

Refer to [Section 6.3.12: I/O current injection characteristics](#) for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO).

**Table 49. SPI characteristics<sup>(1)</sup>**

Symbol	Parameter	Conditions	Min	Max <sup>(2)</sup>	Unit
$f_{SCK}$ $1/t_{c(SCK)}$	SPI clock frequency	Master mode	-	16	MHz
		Slave mode	-	16	
		Slave transmitter	-	12 <sup>(3)</sup>	
$t_{r(SCK)}^{(2)}$ $t_{f(SCK)}^{(2)}$	SPI clock rise and fall time	Capacitive load: C = 30 pF	-	6	ns
DuCy(SCK)	SPI slave input clock duty cycle	Slave mode	30	70	%
$t_{su(NSS)}$	NSS setup time	Slave mode	$4t_{HCLK}$	-	ns
$t_h(NSS)$	NSS hold time	Slave mode	$2t_{HCLK}$	-	
$t_{w(SCKH)}^{(2)}$ $t_{w(SCKL)}^{(2)}$	SCK high and low time	Master mode	$t_{SCK}/2 - 5$	$t_{SCK}/2 + 3$	
$t_{su(MI)}^{(2)}$	Data input setup time	Master mode	5	-	
$t_{su(SI)}^{(2)}$		Slave mode	6	-	
$t_{h(MI)}^{(2)}$	Data input hold time	Master mode	5	-	
$t_{h(SI)}^{(2)}$		Slave mode	5	-	
$t_{a(SO)}^{(4)}$	Data output access time	Slave mode	0	$3t_{HCLK}$	
$t_{v(SO)}^{(2)}$	Data output valid time	Slave mode	-	33	
$t_{v(MO)}^{(2)}$	Data output valid time	Master mode	-	6.5	
$t_{h(SO)}^{(2)}$	Data output hold time	Slave mode	17	-	
$t_{h(MO)}^{(2)}$		Master mode	0.5	-	

1. The characteristics above are given for voltage Range 1.
2. Guaranteed by characterization results.
3. The maximum SPI clock frequency in slave transmitter mode is given for an SPI slave input clock duty cycle (DuCy(SCK)) ranging between 40 to 60%.
4. Min time is for the minimum time to drive the output and max time is for the maximum time to validate the data.

Table 51. USB DC electrical characteristics

Symbol	Parameter	Conditions	Min. <sup>(1)</sup>	Max. <sup>(1)</sup>	Unit
Input levels					
V <sub>DD</sub>	USB operating voltage <sup>(2)</sup>	-	3.0	3.6	V
V <sub>DI</sub> <sup>(3)</sup>	Differential input sensitivity	I(USB_DP, USB_DM)	0.2	-	V
V <sub>CM</sub> <sup>(3)</sup>	Differential common mode range	Includes V <sub>DI</sub> range	0.8	2.5	
V <sub>SE</sub> <sup>(3)</sup>	Single ended receiver threshold	-	1.3	2.0	
Output levels					
V <sub>OL</sub> <sup>(4)</sup>	Static output level low	R <sub>L</sub> of 1.5 kΩ to 3.6 V <sup>(5)</sup>	-	0.3	V
V <sub>OH</sub> <sup>(4)</sup>	Static output level high	R <sub>L</sub> of 15 kΩ to V <sub>SS</sub> <sup>(5)</sup>	2.8	3.6	

1. All the voltages are measured from the local ground potential.
2. To be compliant with the USB 2.0 full speed electrical specification, the USB\_DP (D+) pin should be pulled up with a 1.5 k $\Omega$  resistor to a 3.0-to-3.6 V voltage range.
3. Guaranteed by characterization results.
4. Tested in production.
5.  $R_L$  is the load connected on the USB drivers.

Figure 25. USB timings: definition of data signal rise and fall time

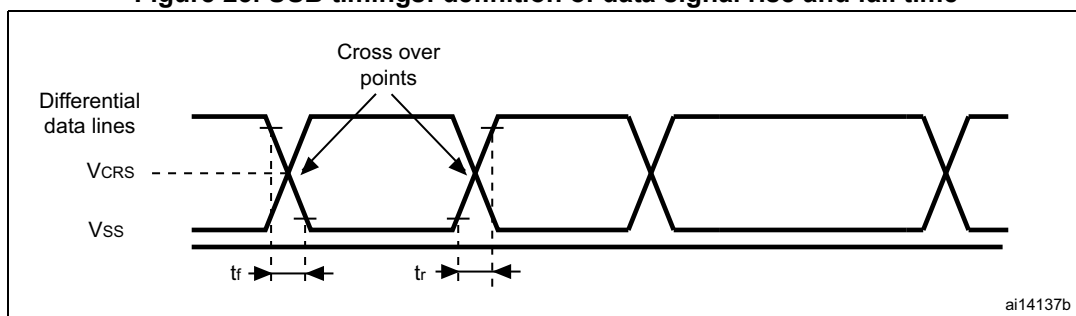
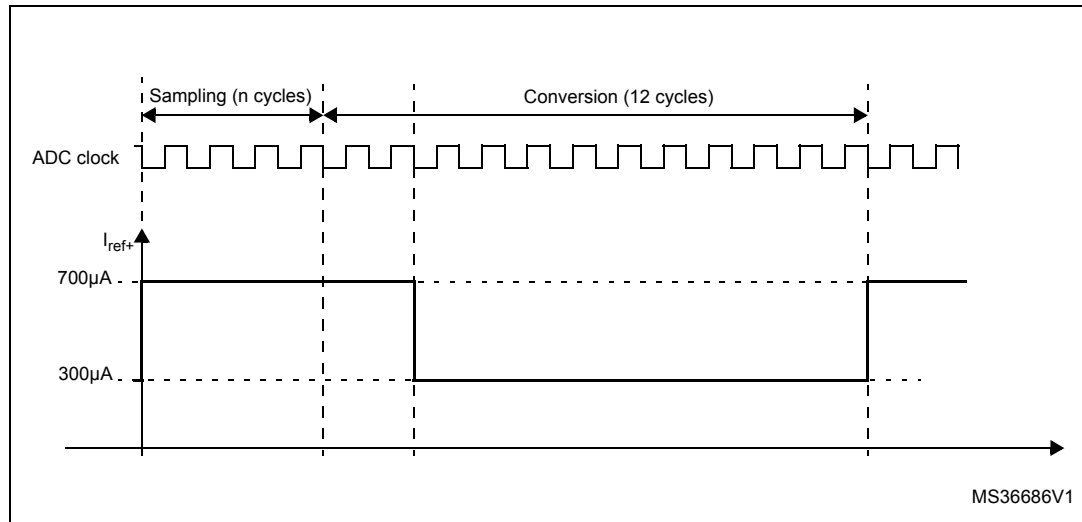


Table 52. USB: full speed electrical characteristics

Driver characteristics <sup>(1)</sup>					
Symbol	Parameter	Conditions	Min	Max	Unit
$t_r$	Rise time <sup>(2)</sup>	$C_L = 50$ pF	4	20	ns
$t_f$	Fall Time <sup>(2)</sup>	$C_L = 50$ pF	4	20	ns
$t_{rfm}$	Rise/ fall time matching	$t_r/t_f$	90	110	%
$V_{CRS}$	Output signal crossover voltage		1.3	2.0	V

1. Guaranteed by design.
2. Measured from 10% to 90% of the data signal. For more detailed informations, please refer to USB Specification - Chapter 7 (version 2.0).

**Figure 28. Maximum dynamic current consumption on  $V_{REF+}$  supply pin during ADC conversion****Table 56. Maximum source impedance  $R_{AIN\ max}^{(1)}$** 

Ts ( $\mu$ s)	R <sub>AIN</sub> max (kOhm)				Ts (cycles) f <sub>ADC</sub> = 16 MHz <sup>(2)</sup>
	Multiplexed channels		Direct channels		
	2.4 V < V <sub>DDA</sub> < 3.6 V	1.8 V < V <sub>DDA</sub> < 2.4 V	2.4 V < V <sub>DDA</sub> < 3.3 V	1.8 V < V <sub>DDA</sub> < 2.4 V	
0.25	Not allowed	Not allowed	0.7	Not allowed	4
0.5625	0.8	Not allowed	2.0	1.0	9
1	2.0	0.8	4.0	3.0	16
1.5	3.0	1.8	6.0	4.5	24
3	6.8	4.0	15.0	10.0	48
6	15.0	10.0	30.0	20.0	96
12	32.0	25.0	50.0	40.0	192
24	50.0	50.0	50.0	50.0	384

1. Guaranteed by design.

2. Number of samples calculated for  $f_{ADC} = 16\ MHz$ . For  $f_{ADC} = 8$  and  $4\ MHz$  the number of sampling cycles can be reduced with respect to the minimum sampling time Ts ( $\mu s$ ).

### General PCB design guidelines

Power supply decoupling should be performed as shown in The 10 nF capacitors should be ceramic (good quality). They should be placed as close as possible to the chip.

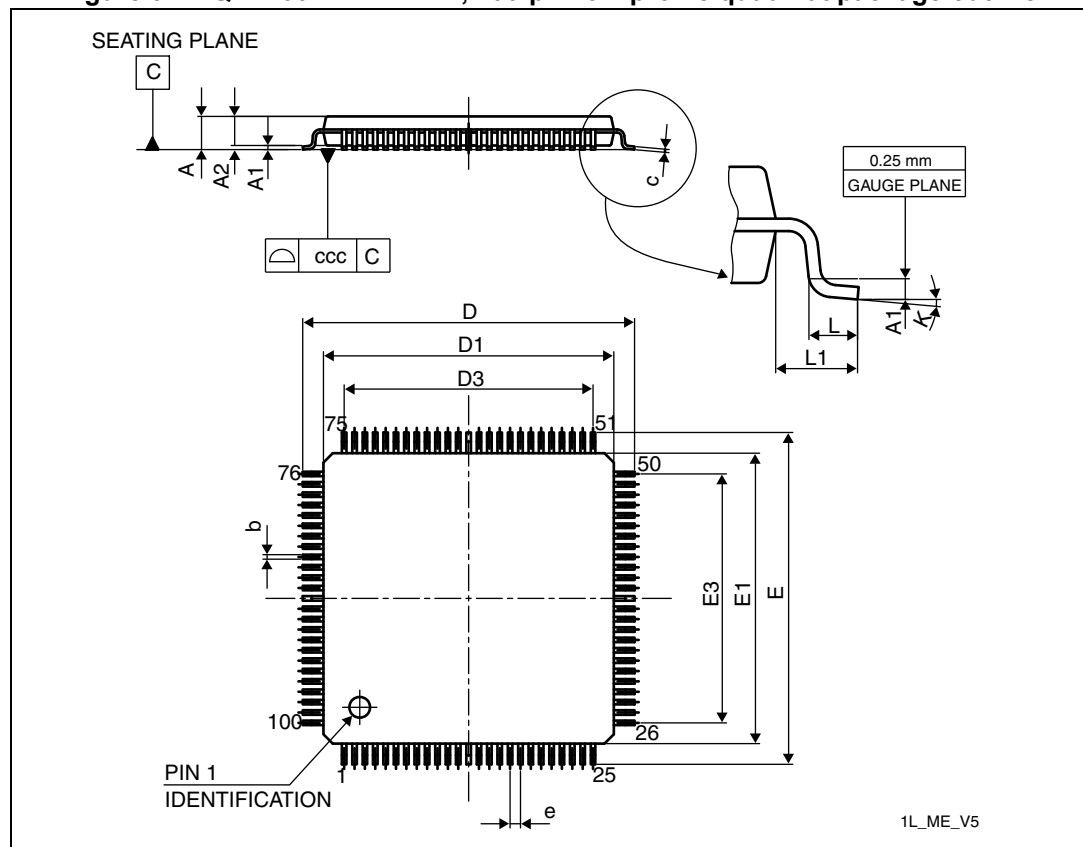


## 7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com). ECOPACK® is an ST trademark.

### 7.1 LQFP100 14 x 14 mm, 100-pin low-profile quad flat package information

Figure 32. LQFP100 14 x 14 mm, 100-pin low-profile quad flat package outline

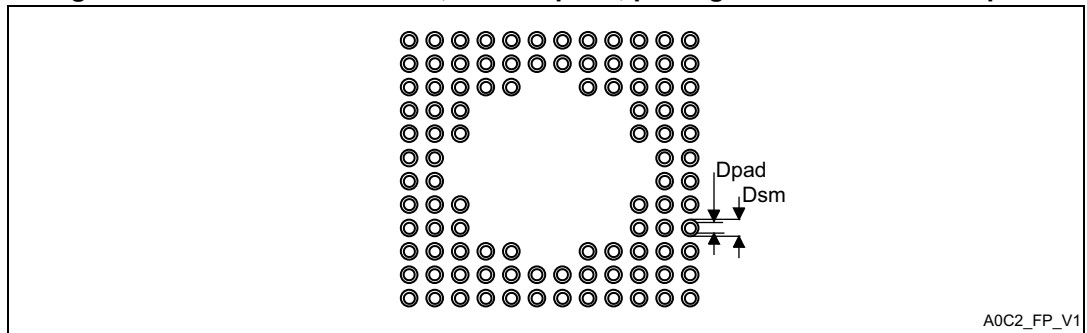


1. Drawing is not to scale.

**Table 67. UFBGA100 7 x 7 mm, 0.5 mm pitch, package mechanical data (continued)**

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
eee	-	-	0.15	-	-	0.0059
fff	-	-	0.05	-	-	0.002

1. Values in inches are converted from mm and rounded to 4 decimal digits.

**Figure 45. UFBGA100 7 x 7 mm, 0.5 mm pitch, package recommended footprint****Table 68. UFBGA100 7 x 7 mm, 0.5 mm pitch, recommended PCB design rules**

Dimension	Recommended values
Pitch	0.5
Dpad	0.280 mm
Dsm	0.370 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.280 mm
Stencil thickness	Between 0.100 mm and 0.125 mm

## 7.6 TFBGA64 5 x 5 mm, 0.5 mm pitch, thin fine-pitch ball grid array package information

Figure 47. TFBGA64 5 x 5 mm, 0.5 mm pitch, package outline

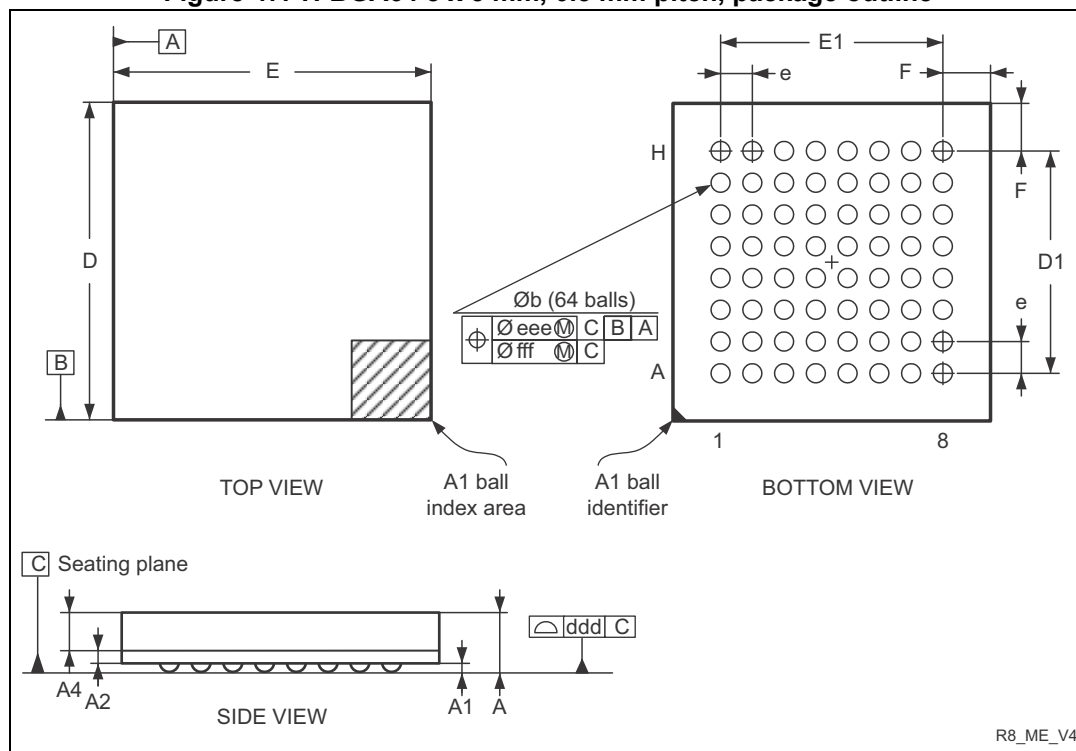


Table 69. TFBGA64 5 x 5 mm, 0.5 mm pitch, package mechanical data

Symbol	millimeters			inches <sup>(1)</sup>		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.200	-	-	0.0472
A1	0.150	-	-	0.0059	-	-
A2	-	0.200	-	-	0.0079	-
A4	-	-	0.600	-	-	0.0236
b	0.250	0.300	0.350	0.0098	0.0118	0.0138
D	4.850	5.000	5.150	0.1909	0.1969	0.2028
D1	-	3.500	-	-	0.1378	-
E	4.850	5.000	5.150	0.1909	0.1969	0.2028
E1	-	3.500	-	-	0.1378	-
e	-	0.500	-	-	0.0197	-
F	-	0.750	-	-	0.0295	-
ddd	-	-	0.080	-	-	0.0031

## 8 Ordering information

**Table 72. Ordering information scheme**

Example:	STM32	L	151	C	8	T	6	T	TR
<b>Device family</b>									
STM32 = ARM-based 32-bit microcontroller									
<b>Product type</b>									
L = Low power									
<b>Device subfamily</b>									
151: Devices without LCD									
152: Devices with LCD									
<b>Pin count</b>									
C = 48 pins									
R = 64 pins									
V = 100 pins									
<b>Flash memory size</b>									
6 = 32 Kbytes of Flash memory									
8 = 64 Kbytes of Flash memory									
B = 128 Kbytes of Flash memory									
<b>Package</b>									
H = BGA									
T = LQFP									
U = UFQFPN									
<b>Temperature range</b>									
6 = Industrial temperature range, -40 to 85 °C									
<b>Options</b>									
No character = V <sub>DD</sub> range: 1.8 to 3.6 V and BOR enabled									
T = V <sub>DD</sub> range: 1.65 to 3.6 V and BOR disabled									
<b>Packing</b>									
TR = tape and reel									
No character = tray or tube									

For a list of available options (speed, package, etc.) or for further information on any aspect of this device, please contact your nearest ST sales office.

Table 73. Document revision history (continued)

Date	Revision	Changes
17-June-2011	5	<p>Modified 1st page (low power features)</p> <p>Added STM32L15xC6 and STM32L15xR6 devices (32 Kbytes of Flash memory).</p> <p>Modified <a href="#">Section 3.6: GPIOs (general-purpose inputs/outputs) on page 22</a></p> <p>Modified <a href="#">Section 6.3: Operating conditions on page 53</a></p> <p>Modified <a href="#">Table 55: ADC accuracy on page 95</a>, <a href="#">Table 57: DAC characteristics on page 99</a> and <a href="#">Table 60: Comparator 1 characteristics on page 102</a></p>
25-Jan-2012	6	<p><a href="#">Features</a>: updated internal multispeed low power RC.</p> <p><a href="#">Table 2: Ultralow power STM32L15xx6/8/B device features and peripheral counts</a>: LCD 4x44 and 8x40 available for both 64- and 128-Kbyte devices; two comparators available for all devices.</p> <p><a href="#">Table 3: Functionalities depending on the operating power supply range</a>: added footnote 1.</p> <p><a href="#">Figure 8: STM32L15xCx UFQFPN48 pinout</a>: replaced VFQPN48 by UFQFPN48 as name of package.</p> <p><a href="#">Table 8: STM32L15xx6/8/B pin definitions</a>: replaced PH0/PH1 by PC14/PC15.</p> <p><a href="#">Table 9: Alternate function input/output</a>: removed EVENT OUT from PH2 port, AFIO15 column.</p> <p><a href="#">Table 19: Current consumption in Sleep mode</a>: updated MSI conditions and <math>f_{HCLK}</math>.</p> <p><a href="#">Table 20: Current consumption in Low power run mode</a>: updated some temperature conditions; added footnote 2.</p> <p><a href="#">Table 21: Current consumption in Low power sleep mode</a>: updated some temperature conditions and one of the MSI clock conditions.</p> <p><a href="#">Table 22: Typical and maximum current consumptions in Stop mode</a>: updated <math>I_{DD}</math> (WU from Stop) parameter.</p> <p><a href="#">Table 23: Typical and maximum current consumptions in Standby mode</a>: updated <math>I_{DD}</math> (WU from Standby) parameter.</p> <p><a href="#">Table 25: Low-power mode wakeup timings</a>: updated <math>f_{HCLK}</math> value for <math>t_{WUSLEEP\_LP}</math>; updated typical value of parameter "Wakeup from Stop mode, regulator in Run mode".</p> <p><a href="#">Table 24: Peripheral current consumption</a>: replaced GPIOF by GPIOH.</p> <p><a href="#">Table 33: PLL characteristics</a>: updated "PLL output clock"</p> <p><a href="#">Table 35: Flash memory and data EEPROM characteristics</a>: updated all information for <math>I_{DD}</math>.</p> <p><a href="#">Figure 19: I/O AC characteristics definition</a>: replaced the falling edge "<math>t_{f(I/O)out}</math>" by "<math>t_{f(I/O)out}</math>".</p> <p><a href="#">Table 47: I2C characteristics</a>: amended footnote 2.</p> <p><a href="#">Table 54: ADC characteristics</a>: updated <math>f_S</math> max value for direct channels, 6-bit sampling rate.</p> <p><a href="#">Table 55: ADC accuracy</a>: Updated the first, third and fourth <math>f_{ADC}</math> test condition.</p> <p><a href="#">Table 59: Temperature sensor characteristics</a>: updated typ, min, and max values of the <math>T_{S\_temp}</math> parameter.</p>