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Details

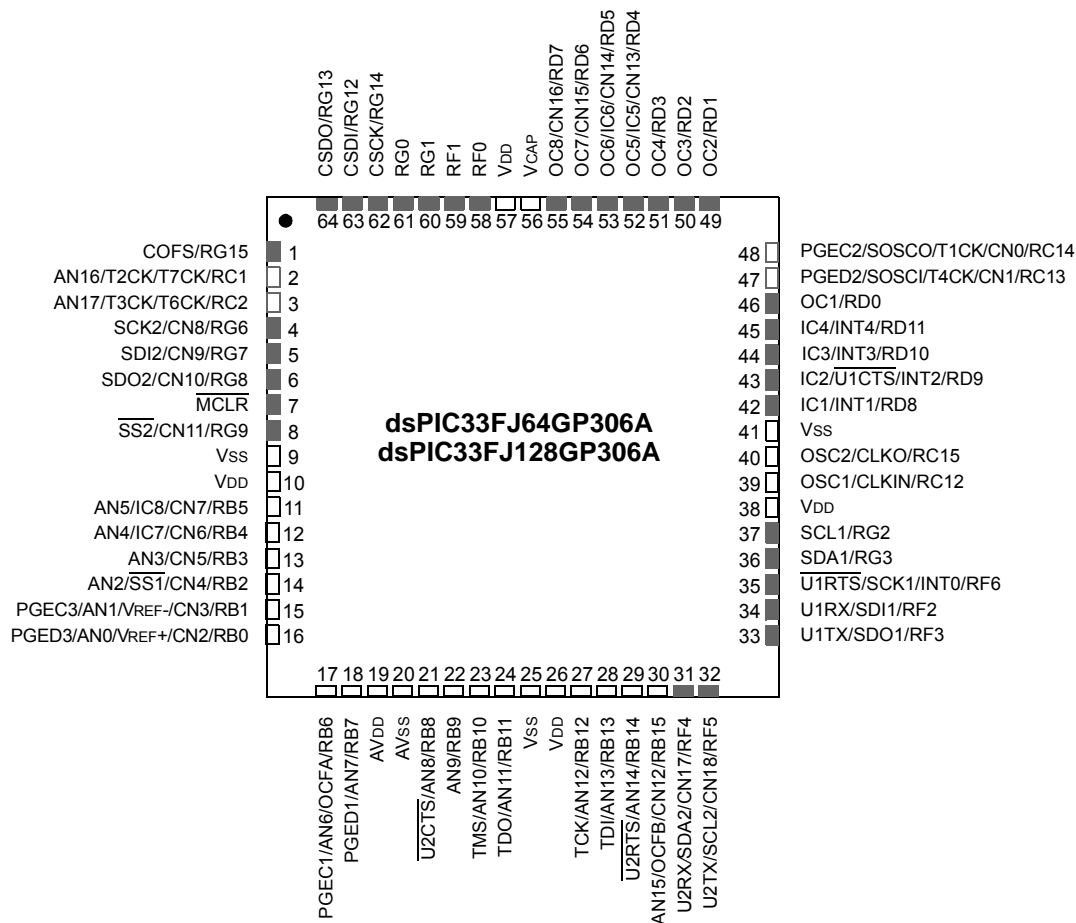
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	40 MIPS
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	AC'97, Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	85
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	16K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 32x10b/12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (12x12)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33fj64gp310a-i-pt

dsPIC33FJXXXGPX06A/X08A/X10A

Pin Diagrams (Continued)

64-Pin QFN⁽¹⁾

■ = Pins are up to 5V tolerant



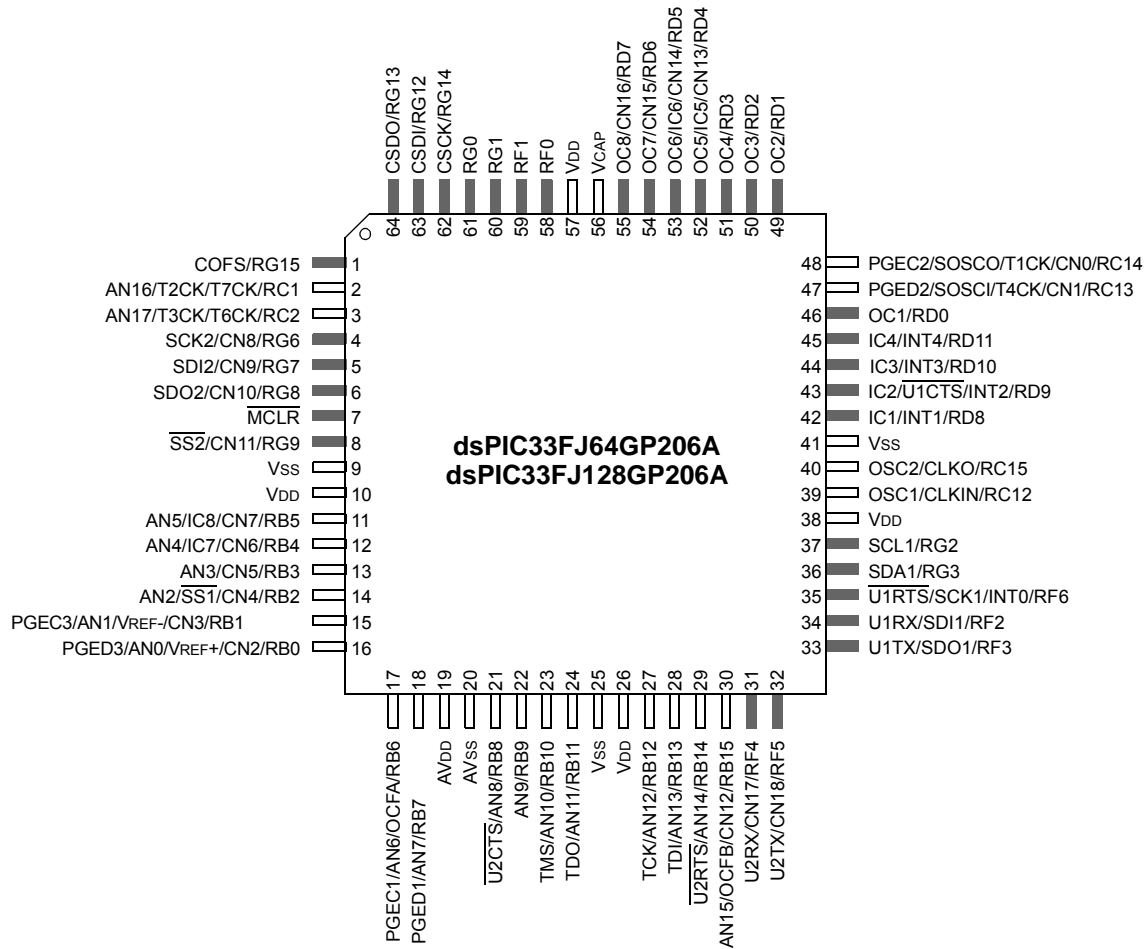
Note 1: The metal plane at the bottom of the device is not connected to any pins and should be connected to Vss externally.

dsPIC33FJXXXGPX06A/X08A/X10A

Pin Diagrams (Continued)

64-Pin TQFP

■ = Pins are up to 5V tolerant



2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS

Note 1: This data sheet summarizes the features of the dsPIC33FJXXXGPX06A/X08A/X10A family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the “dsPIC33F/PIC24H Family Reference Manual”. Please see the Microchip web site (www.microchip.com) for the latest dsPIC33F/PIC24H Family Reference Manual sections.

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

2.1 Basic Connection Requirements

Getting started with the dsPIC33FJXXXGPX06A/X08A/X10A family of 16-bit Digital Signal Controllers (DSCs) requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names, which must always be connected:

- All VDD and VSS pins (see **Section 2.2 “Decoupling Capacitors”**)
- All AVDD and AVSS pins (regardless if ADC module is not used) (see **Section 2.2 “Decoupling Capacitors”**)
- VCAP (see **Section 2.3 “CPU Logic Filter Capacitor Connection (VCAP)”**)
- MCLR pin (see **Section 2.4 “Master Clear (MCLR) Pin”**)
- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes (see **Section 2.5 “ICSP Pins”**)
- OSC1 and OSC2 pins when external oscillator source is used (see **Section 2.6 “External Oscillator Pins”**)

Additionally, the following pins may be required:

- VREF+/VREF- pins used when external voltage reference for ADC module is implemented

Note: The AVDD and AVSS pins must be connected independent of the ADC voltage reference source.

2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- **Value and type of capacitor:** Recommendation of 0.1 μ F (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended that ceramic capacitors be used.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is within one-quarter inch (6 mm) in length.
- **Handling high frequency noise:** If the board is experiencing high frequency noise, upward of tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μ F to 0.001 μ F. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1 μ F in parallel with 0.001 μ F.
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum thereby reducing PCB track inductance.

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REGISTER 3-1: SR: CPU STATUS REGISTER

bit 8	DC: MCU ALU Half Carry/Borrow bit 1 = A carry-out from the 4th low-order bit (for byte sized data) or 8th low-order bit (for word sized data) of the result occurred 0 = No carry-out from the 4th low-order bit (for byte sized data) or 8th low-order bit (for word sized data) of the result occurred
bit 7-5	IPL<2:0>: CPU Interrupt Priority Level Status bits ⁽²⁾ 111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled 110 = CPU Interrupt Priority Level is 6 (14) 101 = CPU Interrupt Priority Level is 5 (13) 100 = CPU Interrupt Priority Level is 4 (12) 011 = CPU Interrupt Priority Level is 3 (11) 010 = CPU Interrupt Priority Level is 2 (10) 001 = CPU Interrupt Priority Level is 1 (9) 000 = CPU Interrupt Priority Level is 0 (8)
bit 4	RA: REPEAT Loop Active bit 1 = REPEAT loop in progress 0 = REPEAT loop not in progress
bit 3	N: MCU ALU Negative bit 1 = Result was negative 0 = Result was non-negative (zero or positive)
bit 2	OV: MCU ALU Overflow bit This bit is used for signed arithmetic (2's complement). It indicates an overflow of the magnitude which causes the sign bit to change state. 1 = Overflow occurred for signed arithmetic (in this arithmetic operation) 0 = No overflow occurred
bit 1	Z: MCU ALU Zero bit 1 = An operation which affects the Z bit has set it at some time in the past 0 = The most recent operation which affects the Z bit has cleared it (i.e., a non-zero result)
bit 0	C: MCU ALU Carry/Borrow bit 1 = A carry-out from the Most Significant bit of the result occurred 0 = No carry-out from the Most Significant bit of the result occurred

Note 1: This bit may be read or cleared (not set).

2: The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.

3: The IPL<2:0> Status bits are read only when NSTDIS = 1 (INTCON1<15>).

4.2.7 SOFTWARE STACK

In addition to its use as a working register, the W15 register in the dsPIC33FJXXGXPX06A/X08A/X10A devices is also used as a software Stack Pointer. The Stack Pointer always points to the first available free word and grows from lower to higher addresses. It pre-decrements for stack pops and post-increments for stack pushes, as shown in Figure 4-6. For a PC push during any CALL instruction, the MSb of the PC is zero-extended before the push, ensuring that the MSb is always clear.

Note: A PC push during exception processing concatenates the SRL register to the MSb of the PC prior to the push.

The Stack Pointer Limit register (SPLIM) associated with the Stack Pointer sets an upper address boundary for the stack. SPLIM is uninitialized at Reset. As is the case for the Stack Pointer, SPLIM<0> is forced to '0' because all stack operations must be word-aligned. Whenever an EA is generated using W15 as a source or destination pointer, the resulting address is compared with the value in SPLIM. If the contents of the Stack Pointer (W15) and the SPLIM register are equal and a push operation is performed, a stack error trap will not occur. The stack error trap will occur on a subsequent push operation. Thus, for example, if it is desirable to cause a stack error trap when the stack grows beyond address 0x2000 in RAM, initialize the SPLIM with the value 0x1FFE.

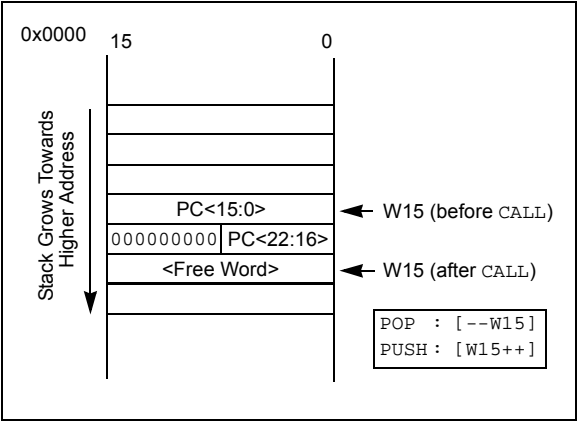
Similarly, a Stack Pointer underflow (stack error) trap is generated when the Stack Pointer address is found to be less than 0x0800. This prevents the stack from interfering with the Special Function Register (SFR) space.

A write to the SPLIM register should not be immediately followed by an indirect read operation using W15.

4.2.8 DATA RAM PROTECTION FEATURE

The dsPIC33F product family supports Data RAM protection features which enable segments of RAM to be protected when used in conjunction with Boot and Secure Code Segment Security. BSRAM (Secure RAM segment for BS) is accessible only from the Boot Segment Flash code when enabled. SSRAM (Secure RAM segment for RAM) is accessible only from the Secure Segment Flash code when enabled. See Table 4-1 for an overview of the BSRAM and SSRAM SFRs.

FIGURE 4-6: CALL STACK FRAME



4.3 Instruction Addressing Modes

The addressing modes in Table 4-35 form the basis of the addressing modes optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions are somewhat different from those in the other instruction types.

4.3.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (Near Data Space). Most file register instructions employ a working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file reg-

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REGISTER 5-2: NVMKEY: NON-VOLATILE MEMORY KEY REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
NVMKEY<7:0>							
bit 7							bit 0

Legend:	SO = Settable only bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **NVMKEY<7:0>:** Key Register (Write Only) bits

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REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	DMA21IF
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
IC8IF	IC7IF	AD2IF	INT1IF	CNIF	—	MI2C1IF	SI2C1IF
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **U2TXIF:** UART2 Transmitter Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 14 **U2RXIF:** UART2 Receiver Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 13 **INT2IF:** External Interrupt 2 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 12 **T5IF:** Timer5 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 11 **T4IF:** Timer4 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 10 **OC4IF:** Output Compare Channel 4 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 9 **OC3IF:** Output Compare Channel 3 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 8 **DMA21IF:** DMA Channel 2 Data Transfer Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 7 **IC8IF:** Input Capture Channel 8 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 6 **IC7IF:** Input Capture Channel 7 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 5 **AD2IF:** ADC2 Conversion Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred
- bit 4 **INT1IF:** External Interrupt 1 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

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REGISTER 7-23: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	C1IP<2:0>			—	C1RXIP<2:0>		
bit 15				bit 8			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI2IP<2:0>			—	SPI2EIP<2:0>		
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **C1IP<2:0>:** ECAN1 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **C1RXIP<2:0>:** ECAN1 Receive Data Ready Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SPI2IP<2:0>:** SPI2 Event Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SPI2EIP<2:0>:** SPI2 Error Interrupt Priority bits

111 = Interrupt is priority 7 (highest priority interrupt)

•

•

•

001 = Interrupt is priority 1

000 = Interrupt source is disabled

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REGISTER 9-1: OSCCON: OSCILLATOR CONTROL REGISTER^(1,3) (CONTINUED)

- bit 1 **LPOSCEN:** Secondary (LP) Oscillator Enable bit
 1 = Enable secondary oscillator
 0 = Disable secondary oscillator
- bit 0 **OSWEN:** Oscillator Switch Enable bit
 1 = Request oscillator switch to selection specified by NOSC<2:0> bits
 0 = Oscillator switch is complete

- Note 1:** Writes to this register require an unlock sequence. Refer to **Section 7. “Oscillator”** (DS70186) in the *dsPIC33F/PIC24H Family Reference Manual* for details.
- 2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.
- 3:** This register is reset only on a Power-on Reset (POR).

9.2 Clock Switching Operation

Applications are free to switch between any of the four clock sources (Primary, LP, FRC and LPRC) under software control at any time. To limit the possible side effects that could result from this flexibility, dsPIC33FJXXGPX06A/X08A/X10A devices have a safeguard lock built into the switch process.

Note: Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMD<1:0> Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

9.2.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in the Configuration register must be programmed to '0'. (Refer to **Section 22.1 "Configuration Bits"** for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSC control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC bits (OSCCON<14:12>) reflect the clock source selected by the FNOSC Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled. It is held at '0' at all times.

9.2.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

1. If desired, read the COSC bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSC control bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSC status bits with the new value of the NOSC control bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.

2. If a valid clock switch has been initiated, the status bits, LOCK (OSCCON<5>) and CF (OSCCON<3>) are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware waits until the Oscillator Start-up Timer (OST) expires. If the new source is using the PLL, the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSC bit values are transferred to the COSC status bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or LP (if LPOSCEN remains set).

Note 1: The processor continues to execute code throughout the clock switching sequence. Timing sensitive code should not be executed during this time.

- 2: Direct clock switches between any primary oscillator mode with PLL and FRC-PLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

- 3: Refer to **Section 7. "Oscillator"** (DS70186) in the *"dsPIC33F/PIC24H Family Reference Manual"* for details.

9.3 Fail-Safe Clock Monitor (FSCM)

The Fail-Safe Clock Monitor (FSCM) allows the device to continue to operate even in the event of an oscillator failure. The FSCM function is enabled by programming. If the FSCM function is enabled, the LPRC internal oscillator runs at all times (except during Sleep mode) and is not subject to control by the Watchdog Timer.

In the event of an oscillator failure, the FSCM generates a clock failure trap event and switches the system clock over to the FRC oscillator. Then the application program can either attempt to restart the oscillator or execute a controlled shutdown. The trap can be treated as a warm Reset by simply loading the Reset address into the oscillator fail trap vector.

If the PLL multiplier is used to scale the system clock, the internal FRC is also multiplied by the same factor on clock failure. Essentially, the device switches to FRC with PLL on a clock failure.

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REGISTER 10-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0
T5MD	T4MD	T3MD	T2MD	T1MD	—	—	DCIMD
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	C2MD	C1MD	AD1MD ⁽¹⁾
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

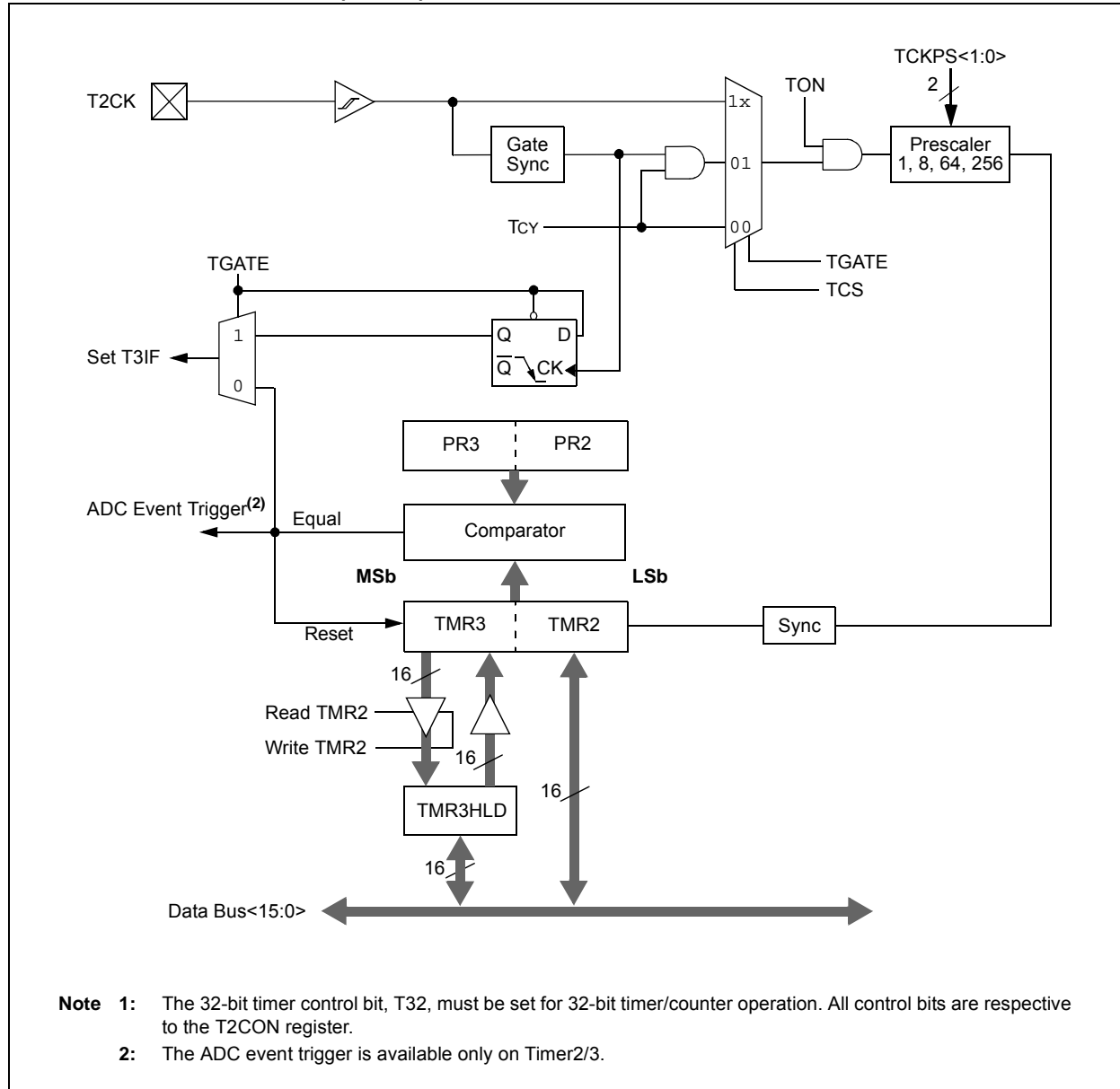
x = Bit is unknown

- bit 15 **T5MD:** Timer5 Module Disable bit
1 = Timer5 module is disabled
0 = Timer5 module is enabled
- bit 14 **T4MD:** Timer4 Module Disable bit
1 = Timer4 module is disabled
0 = Timer4 module is enabled
- bit 13 **T3MD:** Timer3 Module Disable bit
1 = Timer3 module is disabled
0 = Timer3 module is enabled
- bit 12 **T2MD:** Timer2 Module Disable bit
1 = Timer2 module is disabled
0 = Timer2 module is enabled
- bit 11 **T1MD:** Timer1 Module Disable bit
1 = Timer1 module is disabled
0 = Timer1 module is enabled
- bit 10-9 **Unimplemented:** Read as '0'
- bit 8 **DCIMD:** DCI Module Disable bit
1 = DCI module is disabled
0 = DCI module is enabled
- bit 7 **I2C1MD:** I²C1 Module Disable bit
1 = I²C1 module is disabled
0 = I²C1 module is enabled
- bit 6 **U2MD:** UART2 Module Disable bit
1 = UART2 module is disabled
0 = UART2 module is enabled
- bit 5 **U1MD:** UART1 Module Disable bit
1 = UART1 module is disabled
0 = UART1 module is enabled
- bit 4 **SPI2MD:** SPI2 Module Disable bit
1 = SPI2 module is disabled
0 = SPI2 module is enabled
- bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = SPI1 module is disabled
0 = SPI1 module is enabled

Note 1: PCFGx bits have no effect if ADC module is disabled by setting this bit. In this case all port pins multiplexed with ANx will be in Digital mode.

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FIGURE 13-1: TIMER2/3 (32-BIT) BLOCK DIAGRAM⁽¹⁾



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REGISTER 13-1: TxCON (T2CON, T4CON, T6CON OR T8CON) CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
—	TGATE	TCKPS<1:0>		T32	—	TCS ⁽¹⁾	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **TON:** Timerx On bit
When T32 = 1:
1 = Starts 32-bit Timerx/y
0 = Stops 32-bit Timerx/y
When T32 = 0:
1 = Starts 16-bit Timerx
0 = Stops 16-bit Timerx
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **TSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode
- bit 12-7 **Unimplemented:** Read as '0'
- bit 6 **TGATE:** Timerx Gated Time Accumulation Enable bit
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation enabled
0 = Gated time accumulation disabled
- bit 5-4 **TCKPS<1:0>:** Timerx Input Clock Prescale Select bits
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1
- bit 3 **T32:** 32-bit Timer Mode Select bit
1 = Timerx and Timery form a single 32-bit timer
0 = Timerx and Timery act as two 16-bit timers
- bit 2 **Unimplemented:** Read as '0'
- bit 1 **TCS:** Timerx Clock Source Select bit⁽¹⁾
1 = External clock from pin TxCK (on the rising edge)
0 = Internal clock (FCY)
- bit 0 **Unimplemented:** Read as '0'

Note 1: The TxCK pin is not available on all timers. Refer to the “Pin Diagrams” section for the available pins.

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14.1 Input Capture Registers

REGISTER 14-1: ICxCON: INPUT CAPTURE x CONTROL REGISTER

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
—	—	ICSIDL	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-0, HC	R-0, HC	R/W-0	R/W-0	R/W-0
ICTMR ⁽¹⁾	ICI<1:0>	ICOV	ICBNE	ICM<2:0>			
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **ICSIDL:** Input Capture Module Stop in Idle Control bit
 1 = Input capture module will halt in CPU Idle mode
 0 = Input capture module will continue to operate in CPU Idle mode

bit 12-8 **Unimplemented:** Read as '0'

bit 7 **ICTMR:** Input Capture Timer Select bits⁽¹⁾
 1 = TMR2 contents are captured on capture event
 0 = TMR3 contents are captured on capture event

bit 6-5 **ICI<1:0>:** Select Number of Captures per Interrupt bits
 11 = Interrupt on every fourth capture event
 10 = Interrupt on every third capture event
 01 = Interrupt on every second capture event
 00 = Interrupt on every capture event

bit 4 **ICOV:** Input Capture Overflow Status Flag bit (read-only)
 1 = Input capture overflow occurred
 0 = No input capture overflow occurred

bit 3 **ICBNE:** Input Capture Buffer Empty Status bit (read-only)
 1 = Input capture buffer is not empty, at least one more capture value can be read
 0 = Input capture buffer is empty

bit 2-0 **ICM<2:0>:** Input Capture Mode Select bits
 111 = Input capture functions as interrupt pin only when device is in Sleep or Idle mode
 (Rising edge detect only, all other control bits are not applicable.)
 110 = Unused (module disabled)
 101 = Capture mode, every 16th rising edge
 100 = Capture mode, every 4th rising edge
 011 = Capture mode, every rising edge
 010 = Capture mode, every falling edge
 001 = Capture mode, every edge (rising and falling)
 (ICI<1:0> bits do not control interrupt generation for this mode.)
 000 = Input capture module turned off

18.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

Note 1: This data sheet summarizes the features of the dsPIC33FJXXGPX06A/X08A/X10A family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 17. "UART"** (DS70188) in the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33FJXXGPX06A/X08A/X10A device family. The UART is a full-duplex asynchronous system that can communicate with peripheral devices, such as personal computers, LIN, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins and also includes an IrDA® encoder and decoder.

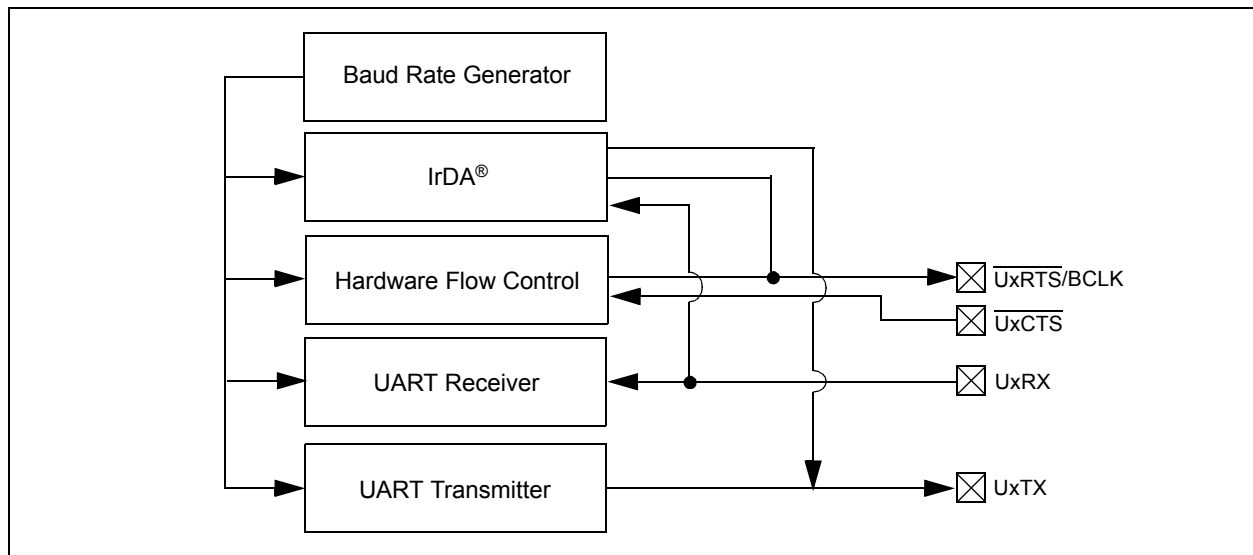
The primary features of the UART module are:

- Full-Duplex, 8 or 9-bit Data Transmission through the UxTX and UxRX pins
- Even, Odd or No Parity Options (for 8-bit data)
- One or Two Stop bits
- Hardware Flow Control Option with $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins
- Fully Integrated Baud Rate Generator with 16-bit Prescaler
- Baud rates ranging from 10 Mbps to 38 bps at 40 MIPS
- 4-deep First-In-First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- Transmit and Receive Interrupts
- A Separate Interrupt for all UART Error Conditions
- Loopback mode for Diagnostic Support
- Support for Sync and Break Characters
- Supports Automatic Baud Rate Detection
- IrDA® Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA® Support

A simplified block diagram of the UART is shown in Figure 18-1. The UART module consists of the key important hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

FIGURE 18-1: UART SIMPLIFIED BLOCK DIAGRAM



Note 1: Both UART1 and UART2 can trigger a DMA data transfer. If U1TX, U1RX, U2TX or U2RX is selected as a DMA IRQ source, a DMA transfer occurs when the U1TXIF, U1RXIF, U2TXIF or U2RXIF bit gets set as a result of a UART1 or UART2 transmission or reception.

2: If DMA transfers are required, the UART TX/RX FIFO buffer must be set to a size of 1 byte/word (i.e., UTXISEL<1:0> = 00 and URXISEL<1:0> = 00).

dsPIC33FJXXGPX06A/X08A/X10A

18.3 UART Control Registers

REGISTER 18-1: UxMODE: UARTx MODE REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾	—	USIDL	IREN ⁽²⁾	RTSMD	—	UEN<1:0>	
bit 15							bit 8

R/W-0 HC	R/W-0	R/W-0 HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	URXINV	BRGH	PDSEL<1:0>		STSEL
bit 7							bit 0

Legend:	HC = Hardware cleared		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 15 **UARTEN:** UARTx Enable bit⁽¹⁾
1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
0 = UARTx is disabled; all UARTx pins are controlled by port latches; UARTx power consumption minimal
- bit 14 **Unimplemented:** Read as '0'
- bit 13 **USIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode
- bit 12 **IREN:** IrDA[®] Encoder and Decoder Enable bit⁽²⁾
1 = IrDA[®] encoder and decoder enabled
0 = IrDA[®] encoder and decoder disabled
- bit 11 **RTSMD:** Mode Selection for UxRTS Pin bit
1 = UxRTS pin in Simplex mode
0 = UxRTS pin in Flow Control mode
- bit 10 **Unimplemented:** Read as '0'
- bit 9-8 **UEN<1:0>:** UARTx Pin Enable bits
11 = UxTX, UxRX and BCLK pins are enabled and used; UxCTS pin controlled by port latches
10 = UxTX, UxRX, UxCTS and UxRTS pins are enabled and used
01 = UxTX, UxRX and UxRTS pins are enabled and used; UxCTS pin controlled by port latches
00 = UxTX and UxRX pins are enabled and used; UxCTS and UxRTS/BCLK pins controlled by port latches
- bit 7 **WAKE:** Wake-up on Start bit Detect During Sleep Mode Enable bit
1 = UARTx will continue to sample the UxRX pin; interrupt generated on falling edge; bit cleared in hardware on following rising edge
0 = No wake-up enabled
- bit 6 **LPBACK:** UARTx Loopback Mode Select bit
1 = Enable Loopback mode
0 = Loopback mode is disabled
- bit 5 **ABAUD:** Auto-Baud Enable bit
1 = Enable baud rate measurement on the next character - requires reception of a Sync field (55h) before other data; cleared in hardware upon completion
0 = Baud rate measurement disabled or completed

Note 1: Refer to **Section 17. “UART”** (DS70188) in the “dsPIC33F/PIC24H Family Reference Manual” for information on enabling the UART module for receive or transmit operation.

2: This feature is only available for the 16x BRG mode (BRGH = 0).

20.0 DATA CONVERTER INTERFACE (DCI) MODULE

Note 1: This data sheet summarizes the features of the dsPIC33FJXXXGPX06A/X08A/X10A family of devices. However, it is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 20. "Data Converter Interface (DCI)"** (DS70288) in the "dsPIC33F/PIC24H Family Reference Manual", which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

20.1 Module Introduction

The dsPIC33FJXXXGPX06A/X08A/X10A Data Converter Interface (DCI) module allows simple interfacing of devices, such as audio coder/decoders (Codecs), ADC and D/A converters. The following interfaces are supported:

- Framed Synchronous Serial Transfer (Single or Multi-Channel)
- Inter-IC Sound (I²S) Interface
- AC-Link Compliant mode

The DCI module provides the following general features:

- Programmable word size up to 16 bits
- Supports up to 16 time slots, for a maximum frame size of 256 bits
- Data buffering for up to 4 samples without CPU overhead

20.2 Module I/O Pins

There are four I/O pins associated with the module. When enabled, the module controls the data direction of each of the four pins.

20.2.1 CCLK PIN

The CCLK pin provides the serial clock for the DCI module. The CCLK pin may be configured as an input or output using the CCLKD control bit in the DCICON1 SFR. When configured as an output, the serial clock is provided by the dsPIC33FJXXXGPX06A/X08A/X10A. When configured as an input, the serial clock must be provided by an external device.

20.2.2 CSDO PIN

The Serial Data Output (CSDO) pin is configured as an output only pin when the module is enabled. The CSDO pin drives the serial bus whenever data is to be

transmitted. The CSDO pin is tri-stated, or driven to '0', during CCLK periods when data is not transmitted depending on the state of the CSDOM control bit. This allows other devices to place data on the serial bus during transmission periods not used by the DCI module.

20.2.3 CSDI PIN

The Serial Data Input (CSDI) pin is configured as an input only pin when the module is enabled.

20.2.3.1 COFS Pin

The Codec Frame Synchronization (COFS) pin is used to synchronize data transfers that occur on the CSDO and CSDI pins. The COFS pin may be configured as an input or an output. The data direction for the COFS pin is determined by the COFSD control bit in the DCICON1 register.

The DCI module accesses the shadow registers while the CPU is in the process of accessing the memory mapped buffer registers.

20.2.4 BUFFER DATA ALIGNMENT

Data values are always stored left justified in the buffers since most Codec data is represented as a signed 2's complement fractional number. If the received word length is less than 16 bits, the unused Least Significant bits in the Receive Buffer registers are set to '0' by the module. If the transmitted word length is less than 16 bits, the unused LSbs in the Transmit Buffer register are ignored by the module. The word length setup is described in subsequent sections of this document.

20.2.5 TRANSMIT/RECEIVE SHIFT REGISTER

The DCI module has a 16-bit shift register for shifting serial data in and out of the module. Data is shifted in/out of the shift register, MSb first, since audio PCM data is transmitted in signed 2's complement format.

20.2.6 DCI BUFFER CONTROL

The DCI module contains a buffer control unit for transferring data between the shadow buffer memory and the Serial Shift register. The buffer control unit is a simple 2-bit address counter that points to word locations in the shadow buffer memory. For the receive memory space (high address portion of DCI buffer memory), the address counter is concatenated with a '0' in the MSb location to form a 3-bit address. For the transmit memory space (high portion of DCI buffer memory), the address counter is concatenated with a '1' in the MSb location.

Note: The DCI buffer control unit always accesses the same relative location in the transmit and receive buffers, so only one address counter is provided.

dsPIC33FJXXXGPX06A/X08A/X10A

TABLE 23-2: INSTRUCTION SET OVERVIEW

Base Instr #	Assembly Mnemonic	Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
1	ADD	ADD <i>Acc</i>	Add Accumulators	1	1	OA,OB,SA,SB
		ADD <i>f</i>	$f = f + \text{WREG}$	1	1	C,DC,N,OV,Z
		ADD <i>f, WREG</i>	$\text{WREG} = f + \text{WREG}$	1	1	C,DC,N,OV,Z
		ADD <i>#lit10, Wn</i>	$\text{Wd} = \text{lit10} + \text{Wd}$	1	1	C,DC,N,OV,Z
		ADD <i>Wb, Ws, Wd</i>	$\text{Wd} = \text{Wb} + \text{Ws}$	1	1	C,DC,N,OV,Z
		ADD <i>Wb, #lit5, Wd</i>	$\text{Wd} = \text{Wb} + \text{lit5}$	1	1	C,DC,N,OV,Z
		ADD <i>Wso, #Slit4, Acc</i>	16-bit Signed Add to Accumulator	1	1	OA,OB,SA,SB
2	ADDC	ADDC <i>f</i>	$f = f + \text{WREG} + (\text{C})$	1	1	C,DC,N,OV,Z
		ADDC <i>f, WREG</i>	$\text{WREG} = f + \text{WREG} + (\text{C})$	1	1	C,DC,N,OV,Z
		ADDC <i>#lit10, Wn</i>	$\text{Wd} = \text{lit10} + \text{Wd} + (\text{C})$	1	1	C,DC,N,OV,Z
		ADDC <i>Wb, Ws, Wd</i>	$\text{Wd} = \text{Wb} + \text{Ws} + (\text{C})$	1	1	C,DC,N,OV,Z
		ADDC <i>Wb, #lit5, Wd</i>	$\text{Wd} = \text{Wb} + \text{lit5} + (\text{C})$	1	1	C,DC,N,OV,Z
3	AND	AND <i>f</i>	$f = f \text{ .AND. } \text{WREG}$	1	1	N,Z
		AND <i>f, WREG</i>	$\text{WREG} = f \text{ .AND. } \text{WREG}$	1	1	N,Z
		AND <i>#lit10, Wn</i>	$\text{Wd} = \text{lit10} \text{ .AND. } \text{Wd}$	1	1	N,Z
		AND <i>Wb, Ws, Wd</i>	$\text{Wd} = \text{Wb} \text{ .AND. } \text{Ws}$	1	1	N,Z
		AND <i>Wb, #lit5, Wd</i>	$\text{Wd} = \text{Wb} \text{ .AND. } \text{lit5}$	1	1	N,Z
4	ASR	ASR <i>f</i>	$f = \text{Arithmetic Right Shift } f$	1	1	C,N,OV,Z
		ASR <i>f, WREG</i>	$\text{WREG} = \text{Arithmetic Right Shift } f$	1	1	C,N,OV,Z
		ASR <i>Ws, Wd</i>	$\text{Wd} = \text{Arithmetic Right Shift } \text{Ws}$	1	1	C,N,OV,Z
		ASR <i>Wb, Wns, Wnd</i>	$\text{Wnd} = \text{Arithmetic Right Shift } \text{Wb} \text{ by } \text{Wns}$	1	1	N,Z
		ASR <i>Wb, #lit5, Wnd</i>	$\text{Wnd} = \text{Arithmetic Right Shift } \text{Wb} \text{ by } \text{lit5}$	1	1	N,Z
5	BCLR	BCLR <i>f, #bit4</i>	Bit Clear <i>f</i>	1	1	None
		BCLR <i>Ws, #bit4</i>	Bit Clear <i>Ws</i>	1	1	None
6	BRA	BRA <i>C, Expr</i>	Branch if Carry	1	1 (2)	None
		BRA <i>GE, Expr</i>	Branch if greater than or equal	1	1 (2)	None
		BRA <i>GEU, Expr</i>	Branch if unsigned greater than or equal	1	1 (2)	None
		BRA <i>GT, Expr</i>	Branch if greater than	1	1 (2)	None
		BRA <i>GTU, Expr</i>	Branch if unsigned greater than	1	1 (2)	None
		BRA <i>LE, Expr</i>	Branch if less than or equal	1	1 (2)	None
		BRA <i>LEU, Expr</i>	Branch if unsigned less than or equal	1	1 (2)	None
		BRA <i>LT, Expr</i>	Branch if less than	1	1 (2)	None
		BRA <i>LTU, Expr</i>	Branch if unsigned less than	1	1 (2)	None
		BRA <i>N, Expr</i>	Branch if Negative	1	1 (2)	None
		BRA <i>NC, Expr</i>	Branch if Not Carry	1	1 (2)	None
		BRA <i>NN, Expr</i>	Branch if Not Negative	1	1 (2)	None
		BRA <i>NOV, Expr</i>	Branch if Not Overflow	1	1 (2)	None
		BRA <i>NZ, Expr</i>	Branch if Not Zero	1	1 (2)	None
		BRA <i>OA, Expr</i>	Branch if Accumulator A overflow	1	1 (2)	None
		BRA <i>OB, Expr</i>	Branch if Accumulator B overflow	1	1 (2)	None
		BRA <i>OV, Expr</i>	Branch if Overflow	1	1 (2)	None
		BRA <i>SA, Expr</i>	Branch if Accumulator A saturated	1	1 (2)	None
		BRA <i>SB, Expr</i>	Branch if Accumulator B saturated	1	1 (2)	None
		BRA <i>Expr</i>	Branch Unconditionally	1	2	None
		BRA <i>Z, Expr</i>	Branch if Zero	1	1 (2)	None
		BRA <i>Wn</i>	Computed Branch	1	2	None
7	BSET	BSET <i>f, #bit4</i>	Bit Set <i>f</i>	1	1	None
		BSET <i>Ws, #bit4</i>	Bit Set <i>Ws</i>	1	1	None
8	BSW	BSW.C <i>Ws, Wb</i>	Write C bit to <i>Ws</i> < <i>Wb</i> >	1	1	None
		BSW.Z <i>Ws, Wb</i>	Write Z bit to <i>Ws</i> < <i>Wb</i> >	1	1	None
9	BTG	BTG <i>f, #bit4</i>	Bit Toggle <i>f</i>	1	1	None
		BTG <i>Ws, #bit4</i>	Bit Toggle <i>Ws</i>	1	1	None

dsPIC33FJXXGPX06A/X08A/X10A

FIGURE 25-10: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY CKE = 1) TIMING CHARACTERISTICS

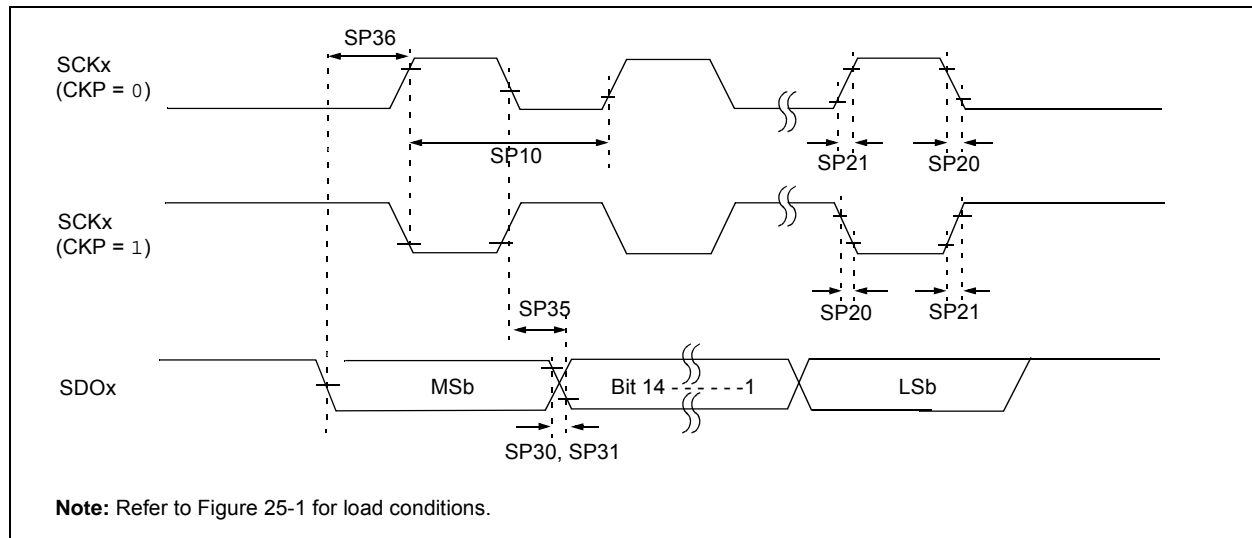


TABLE 25-29: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic ⁽¹⁾	Min	Typ ⁽²⁾	Max	Units	Conditions
SP10	TscP	Maximum SCK Frequency	—	—	15	MHz	See Note 3
SP20	TscF	SCKx Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP21	TscR	SCKx Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP30	TdoF	SDOx Data Output Fall Time	—	—	—	ns	See parameter DO32 and Note 4
SP31	TdoR	SDOx Data Output Rise Time	—	—	—	ns	See parameter DO31 and Note 4
SP35	Tsch2doV, TscL2doV	SDOx Data Output Valid after SCKx Edge	—	6	20	ns	—
SP36	TdiV2sch, TdiV2scl	SDOx Data Output Setup to First SCKx Edge	30	—	—	ns	—

- Note 1:** These parameters are characterized, but are not tested in manufacturing.
- Note 2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.
- Note 3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.
- Note 4:** Assumes 50 pF load on all SPIx pins.

dsPIC33FJXXXGPX06A/X08A/X10A

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

		dsPIC 33 FJ 256 GP7 10 A T I / PT - XXX									
Microchip Trademark	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Architecture	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Flash Memory Family	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Program Memory Size (KB)	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Product Group	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Pin Count	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Revision Level	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Tape and Reel Flag (if applicable)	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Temperature Range	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Package	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____
Pattern	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____	_____

Architecture:	33	=	16-bit Digital Signal Controller
Flash Memory Family:	FJ	=	Flash program memory, 3.3V
Product Group:	GP2	=	General purpose family
	GP3	=	General purpose family
	GP5	=	General purpose family
	GP7	=	General purpose family
Pin Count:	06	=	64-pin
	08	=	80-pin
	10	=	100-pin
Temperature Range:	I	=	-40°C to+85°C(Industrial)
	E	=	-40°C to+125°C(Extended)
	H	=	-40°C to+150°C(High)
Package:	PT	=	10x10 or 12x12 mm TQFP (Thin Quad Flatpack)
	PF	=	14x14 mm TQFP (Thin Quad Flatpack)
	MR	=	9x9mm QFN (Plastic Quad Flatpack)
Pattern	Three-digit QTP, SQTP, Code or Special Requirements		
	(blank otherwise)		
	ES	=	Engineering Sample

Examples:

- a) dsPIC33FJ256GP710AI/PT:
General-purpose dsPIC33, 64 KB program memory, 100-pin, Industrial temp., TQFP package.