Intel - EP4CE75F23I7 Datasheet

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Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details	
Product Status	Active
Number of LABs/CLBs	4713
Number of Logic Elements/Cells	75408
Total RAM Bits	2810880
Number of I/O	292
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	484-BGA
Supplier Device Package	484-FBGA (23x23)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep4ce75f23i7

Section I. Device Core

This section provides a complete overview of all features relating to the Cyclone® IV device family, which is the most architecturally advanced, high-performance, low-power FPGA in the marketplace. This section includes the following chapters:

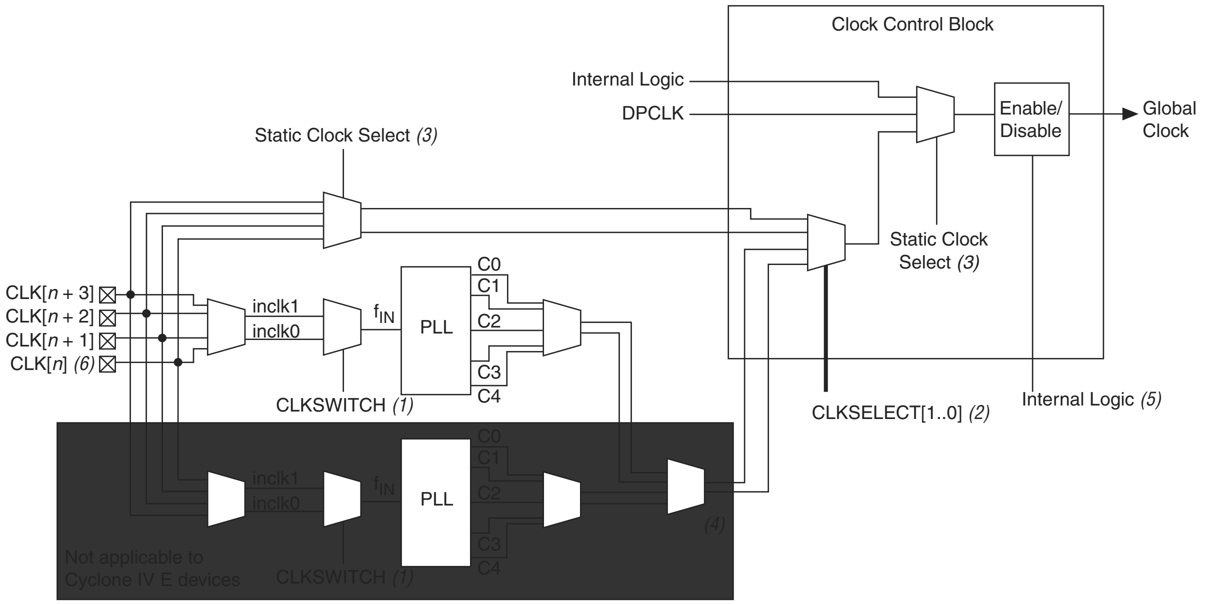
- Chapter 1, Cyclone IV FPGA Device Family Overview
- Chapter 2, Logic Elements and Logic Array Blocks in Cyclone IV Devices
- Chapter 3, Memory Blocks in Cyclone IV Devices
- Chapter 4, Embedded Multipliers in Cyclone IV Devices
- Chapter 5, Clock Networks and PLLs in Cyclone IV Devices

Revision History

Refer to each chapter for its own specific revision history. For information about when each chapter was updated, refer to the Chapter Revision Dates section, which appears in the complete handbook.

Figure 5–1 shows the clock control block.

Figure 5–1. Clock Control Block



Notes to Figure 5–1:

(1) The `clkswitch` signal can either be set through the configuration file or dynamically set when using the manual PLL switchover feature. The output of the multiplexer is the input clock (f_{IN}) for the PLL.

(2) The `clkselect[1..0]` signals are fed by internal logic and are used to dynamically select the clock source for the GCLK when the device is in user mode.

(3) The static clock select signals are set in the configuration file. Therefore, dynamic control when the device is in user mode is not feasible.

(4) Two out of four PLL clock outputs are selected from adjacent PLLs to drive into the clock control block.

(5) You can use internal logic to enable or disable the GCLK in user mode.

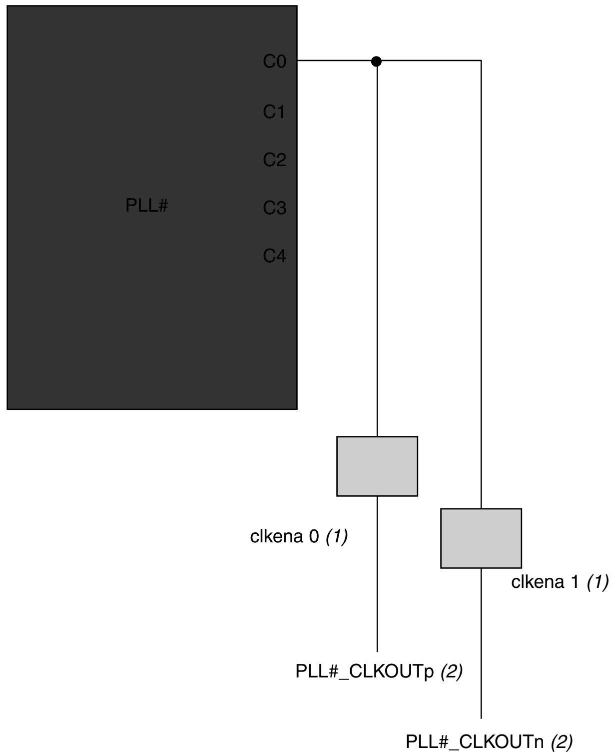
(6) `CLK[n]` is not available on the left side of Cyclone IV E devices.

Each PLL generates five clock outputs through the `c[4..0]` counters. Two of these clocks can drive the GCLK through a clock control block, as shown in Figure 5–1.

For more information about how to use the clock control block in the Quartus II software, refer to the *ALTCLKCTRL Megafunction User Guide*.

Figure 5–11 shows the external clock outputs for PLLs.

Figure 5–11. External Clock Outputs for PLLs



Notes to Figure 5–11:

(1) These external clock enable signals are available only when using the ALTCLKCTRL megafunction.

(2) PLL#_CLKOUTp and PLL#_CLKOUTn pins are dual-purpose I/O pins that you can use as one single-ended clock output or one differential clock output. When using both pins as single-ended I/Os, one of them can be the clock output while the other pin is configured as a regular user I/O.

Each pin of a differential output pair is 180° out of phase. The Quartus II software places the NOT gate in your design into the I/O element to implement 180° phase with respect to the other pin in the pair. The clock output pin pairs support the same I/O standards as standard output pins.

To determine which I/O standards are supported by the PLL clock input and output pins, refer to the *Cyclone IV Device I/O Features* chapter.

Cyclone IV PLLs can drive out to any regular I/O pin through the GCLK. You can also use the external clock output pins as GPIO pins if external PLL clocking is not required.

Voltage-Referenced I/O Standard Termination

Voltage-referenced I/O standards require an input reference voltage (V_{REF}) and a termination voltage (V_{TT}). The reference voltage of the receiving device tracks the termination voltage of the transmitting device, as shown in Figure 6–5 and Figure 6–6.

Figure 6–5. Cyclone IV Devices HSTL I/O Standard Termination

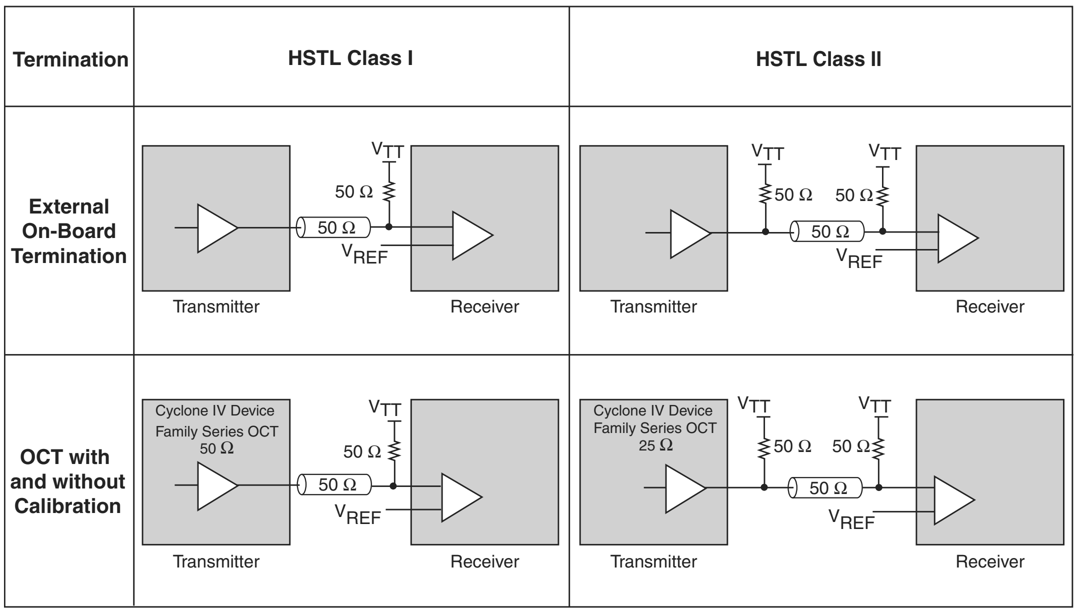
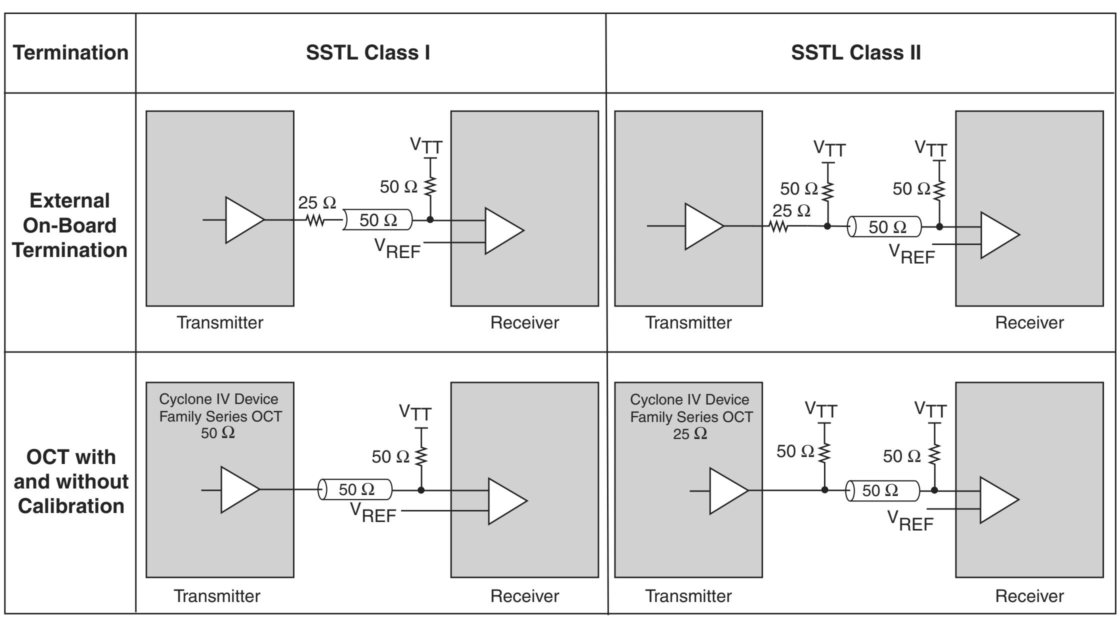


Figure 6–6. Cyclone IV Devices SSTL I/O Standard Termination



External Memory Interfacing

Cyclone IV devices support I/O standards required to interface with a broad range of external memory interfaces, such as DDR SDRAM, DDR2 SDRAM, and QDR II SRAM.

For more information about Cyclone IV devices external memory interface support, refer to the *External Memory Interfaces in Cyclone IV Devices* chapter.

Pad Placement and DC Guidelines

You can use the Quartus II software to validate your pad and pin placement.

Pad Placement

Altera recommends that you create a Quartus II design, enter your device I/O assignments and compile your design to validate your pin placement. The Quartus II software checks your pin connections with respect to the I/O assignment and placement rules to ensure proper device operation. These rules depend on device density, package, I/O assignments, voltage assignments and other factors that are not fully described in this chapter.

For more information about how the Quartus II software checks I/O restrictions, refer to the *I/O Management* chapter in volume 2 of the *Quartus II Handbook*.

DC Guidelines

For the Quartus II software to automatically check for illegally placed pads according to the DC guidelines, set the DC current sink or source value to **Electromigration Current** assignment on each of the output pins that are connected to the external resistive load.

The programmable current strength setting has an impact on the amount of DC current that an output pin can source or sink. Determine if the current strength setting is sufficient for the external resistive load condition on the output pin.

Clock Pins Functionality

Cyclone IV clock pins have multiple purposes, as per listed:

- `CLK` pins—Input support for single-ended and voltage-referenced standards. For I/O standard support, refer to Table 6–3 on page 6–11.
- `DIFFCLK` pins—Input support for differential standards. For I/O standard support, refer to Table 6–3 on page 6–11. When used as `DIFFCLK` pins, DC or AC coupling can be used depending on the interface requirements and external termination is required. For more information, refer to “High-Speed I/O Standards Support” on page 6–28.
- `REFCLK` pins—Input support for high speed differential reference clocks used by the transceivers in Cyclone IV GX devices. For I/O support, coupling, and termination requirements, refer to Table 6–10 on page 6–29.

LVPECL I/O Support in Cyclone IV Devices

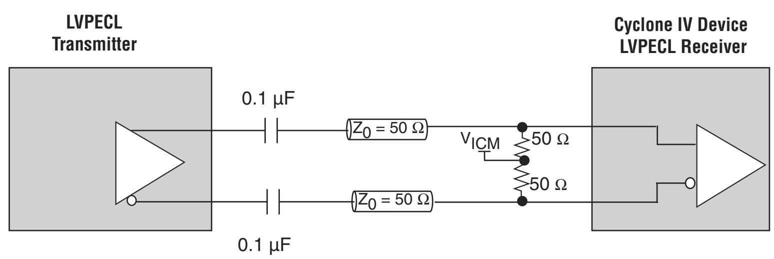
The LVPECL I/O standard is a differential interface standard that requires a 2.5-V V_{CCIO}. This standard is used in applications involving video graphics, telecommunications, data communications, and clock distribution. Cyclone IV devices support the LVPECL input standard at the dedicated clock input pins only. The LVPECL receiver requires an external 100-Ω termination resistor between the two signals at the input buffer.

For the LVPECL I/O standard electrical specification, refer to the *Cyclone IV Device Datasheet* chapter.

AC coupling is required when the LVPECL common mode voltage of the output buffer is higher than the Cyclone IV devices LVPECL input common mode voltage.

Figure 6–18 shows the AC-coupled termination scheme. The 50-Ω resistors used at the receiver are external to the device. DC-coupled LVPECL is supported if the LVPECL output common mode voltage is in the Cyclone IV devices LVPECL input buffer specification (refer to Figure 6–19).

Figure 6–18. LVPECL AC-Coupled Termination *(1)*

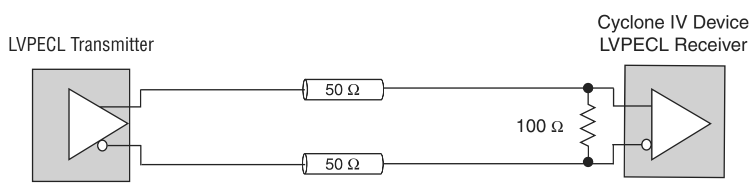


Note to Figure 6–18:

(1) The LVPECL AC-coupled termination is applicable only when an Altera FPGA transmitter is used.

Figure 6–19 shows the LVPECL DC-coupled termination.

Figure 6–19. LVPECL DC-Coupled Termination *(1)*



Note to Figure 6–19:

(1) The LVPECL DC-coupled termination is applicable only when an Altera FPGA transmitter is used.

JTAG instructions have precedence over any other configuration modes. Therefore, JTAG configuration can take place without waiting for other configuration modes to complete. For example, if you attempt JTAG configuration in Cyclone IV devices during PS configuration, PS configuration terminates and JTAG configuration begins. If the MSEL pins are set to AS mode, the Cyclone IV device does not output a DCLK signal when JTAG configuration takes place.

The four required pins for a device operating in JTAG mode are TDI, TDO, TMS, and TCK. All the JTAG input pins are powered by the V_{CCIO} pin and support the LVTTL I/O standard only. All user I/O pins are tri-stated during JTAG configuration. Table 8–14 explains the function of each JTAG pin.

Table 8–14. Dedicated JTAG Pins

Pin Name	Pin Type	Description
TDI	Test data input	Serial input pin for instructions as well as test and programming data. Data shifts in on the rising edge of TCK. If the JTAG interface is not required on the board, the JTAG circuitry is disabled by connecting this pin to V_{CC}. TDI pin has weak internal pull-up resistors (typically 25 kΩ).
TDO	Test data output	Serial data output pin for instructions as well as test and programming data. Data shifts out on the falling edge of TCK. The pin is tri-stated if data is not being shifted out of the device. If the JTAG interface is not required on the board, the JTAG circuitry is disabled by leaving this pin unconnected.
TMS	Test mode select	Input pin that provides the control signal to determine the transitions of the TAP controller state machine. Transitions in the state machine occur on the rising edge of TCK. Therefore, TMS must be set up before the rising edge of TCK. TMS is evaluated on the rising edge of TCK. If the JTAG interface is not required on the board, the JTAG circuitry is disabled by connecting this pin to V_{CC}. TMS pin has weak internal pull-up resistors (typically 25 kΩ).
TCK	Test clock input	The clock input to the BST circuitry. Some operations occur at the rising edge, while others occur at the falling edge. If the JTAG interface is not required on the board, the JTAG circuitry is disabled by connecting this pin to GND. The TCK pin has an internal weak pull-down resistor.

You can download data to the device through the USB-Blaster, MasterBlaster, ByteBlaster II, or ByteBlasterMV download cable, or the EthernetBlaster communications cable during JTAG configuration. Configuring devices with a cable is similar to programming devices in-system. Figure 8–23 and Figure 8–24 show the JTAG configuration of a single Cyclone IV device.

ACTIVE_DISENGAGE

The ACTIVE_DISENGAGE instruction places the active configuration controller (AS and AP) into an idle state prior to JTAG programming. The two purposes of placing the active controller in an idle state are:

- To ensure that it is not trying to configure the device during JTAG programming
- To allow the controllers to properly recognize a successful JTAG programming that results in the device reaching user mode

The ACTIVE_DISENGAGE instruction is required before JTAG programming regardless of the current state of the Cyclone IV device if the MSEL pins are set to an AS or AP configuration scheme. If the ACTIVE_DISENGAGE instruction is issued during a passive configuration scheme (PS or FPP), it has no effect on the Cyclone IV device. Similarly, the CONFIG_IO instruction is issued after an ACTIVE_DISENGAGE instruction, but is no longer required to properly halt configuration. Table 8–17 lists the required, recommended, and optional instructions for each configuration mode. The ordering of the required instructions is a hard requirement and must be met to ensure functionality.

Table 8–17. JTAG Programming Instruction Flows *(1)*

JTAG Instruction	Configuration Scheme and Current State of the Cyclone IV Device											
	Prior to User Mode (Interrupting Configuration)				User Mode				Power Up			
	PS	FPP	AS	AP	PS	FPP	AS	AP	PS	FPP	AS	AP
ACTIVE_DISENGAGE	O	O	R	R	O	O	O	R	O	O	R	R
CONFIG_IO	Rc	Rc	O	O	O	O	O	O	NA	NA	NA	NA
Other JTAG instructions	O	O	O	O	O	O	O	O	O	O	O	O
JTAG_PROGRAM	R	R	R	R	R	R	R	R	R	R	R	R
CHECK_STATUS	Rc	Rc	Rc	Rc	Rc	Rc	Rc	Rc	Rc	Rc	Rc	Rc
JTAG_STARTUP	R	R	R	R	R	R	R	R	R	R	R	R
JTAG TAP Reset/other instruction	R	R	R	R	R	R	R	R	R	R	R	R

Note to Table 8–17:

(1) "R" indicates that the instruction must be executed before the next instruction, "O" indicates the optional instruction, "Rc" indicates the recommended instruction, and "NA" indicates that the instruction is not allowed in this mode.

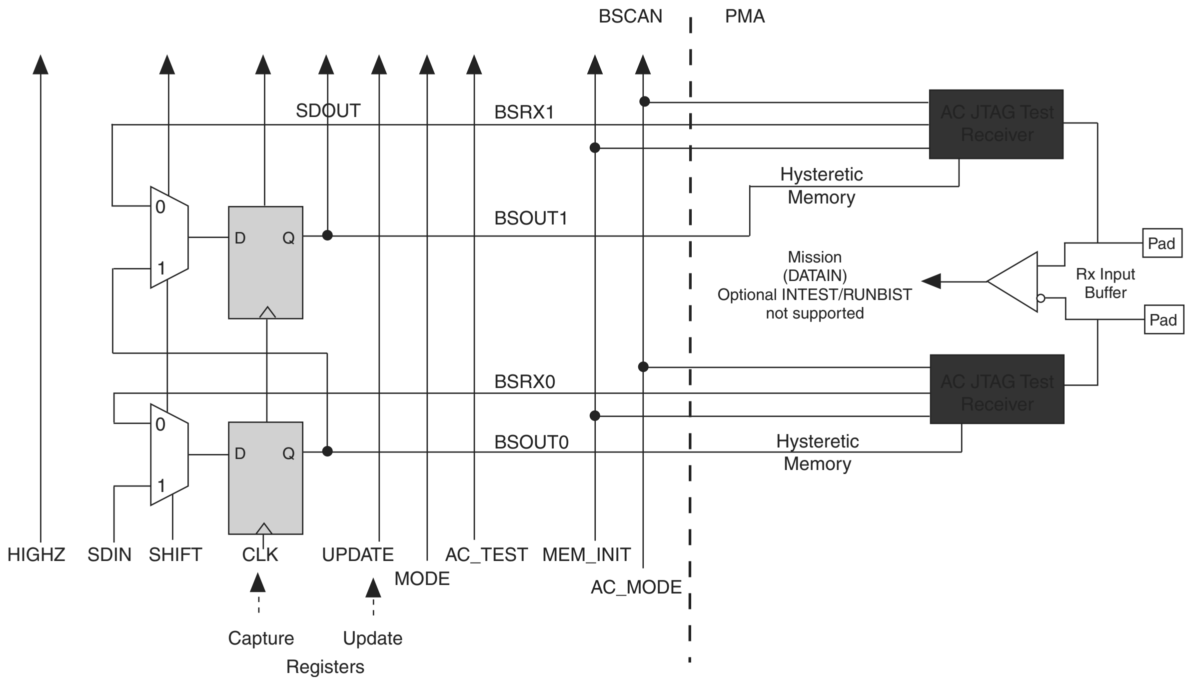
In the AS or AP configuration scheme, the ACTIVE_DISENGAGE instruction puts the active configuration controller into idle state. If a successful JTAG programming is executed, the active controller is automatically re-engaged after user mode is reached through JTAG programming. This causes the active controller to transition to their respective user mode states.

If JTAG programming fails to get the Cyclone IV device to enter user mode and re-engage active programming, there are available methods to achieve this:

- In AS configuration scheme, you can re-engage the AS controller by moving the JTAG TAP controller to the reset state or by issuing the ACTIVE_ENGAGE instruction.

Figure 10–2 shows the Cyclone IV GX HSSI receiver BSC.

Figure 10–2. HSSI Receiver BSC with IEEE Std. 1149.6 BST Circuitry for the Cyclone IV GX Devices



For more information about Cyclone IV devices user I/O boundary-scan cells, refer to the *IEEE 1149.1 (JTAG) Boundary-Scan Testing for Cyclone III Devices* chapter.

BST Operation Control

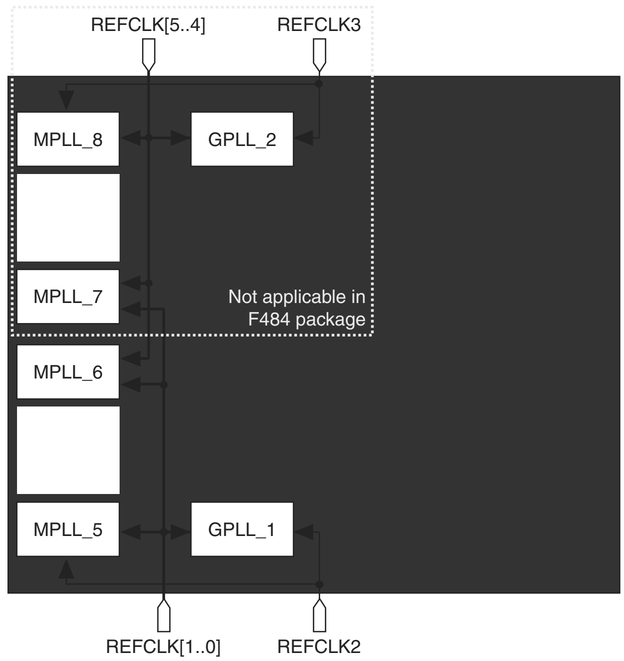
Table 10–1 lists the boundary-scan register length for Cyclone IV devices.

Table 10–1. Boundary-Scan Register Length for Cyclone IV Devices (Part 1 of 2)

Device	Boundary-Scan Register Length
EP4CE6	603
EP4CE10	603
EP4CE15	1080
EP4CE22	732
EP4CE30	1632
EP4CE40	1632
EP4CE55	1164
EP4CE75	1314
EP4CE115	1620
EP4CGX15	260
EP4CGX22	494
EP4CGX30 *(1)*	494
EP4CGX50	1006

Visual Cue	Meaning
`Courier type`	Indicates signal, port, register, bit, block, and primitive names. For example, `data1`, `tdi`, and `input`. The suffix `n` denotes an active-low signal. For example, `resetn`. Indicates command line commands and anything that must be typed exactly as it appears. For example, `c:\qdesigns\tutorial\chiptrip.gdf`. Also indicates sections of an actual file, such as a Report File, references to parts of files (for example, the AHDL keyword `SUBDESIGN`), and logic function names (for example, `TRI`).
↵	An angled arrow instructs you to press the Enter key.
1., 2., 3., and a., b., c., and so on	Numbered steps indicate a list of items when the sequence of the items is important, such as the steps listed in a procedure.
■ ■ ■	Bullets indicate a list of items when the sequence of the items is not important.
☞	The hand points to information that requires special attention.
?	The question mark directs you to a software help system with related information.
	The feet direct you to another document or website with related information.
	The multimedia icon directs you to a related multimedia presentation.
CAUTION	A caution calls attention to a condition or possible situation that can damage or destroy the product or your work.
WARNING	A warning calls attention to a condition or possible situation that can cause you injury.
	The envelope links to the Email Subscription Management Center page of the Altera website, where you can sign up to receive update notifications for Altera documents.

Figure 1–26. PLL Input Reference Clocks in Transceiver Operation for F484 and Larger Packages (1), (2), (3)



Notes to Figure 1–26:

(1) The `REFCLK2` and `REFCLK3` pins are dual-purpose `CLKIO`, `REFCLK`, or `DIFFCLK` pins that reside in banks 3A and 8A respectively.

(2) The `REFCLK[1..0]` and `REFCLK[5..4]` pins are dual-purpose differential `REFCLK` or `DIFFCLK` pins that reside in banks 3B and 8B respectively. These clock input pins do not have access to the clock control blocks and GCLK networks. For more details, refer to the *Clock Networks and PLLs in Cyclone IV Devices* chapter.

(3) Using any clock input pins other than the designated `REFCLK` pins as shown here to drive the MPLLs and GPLLs may have reduced jitter performance.

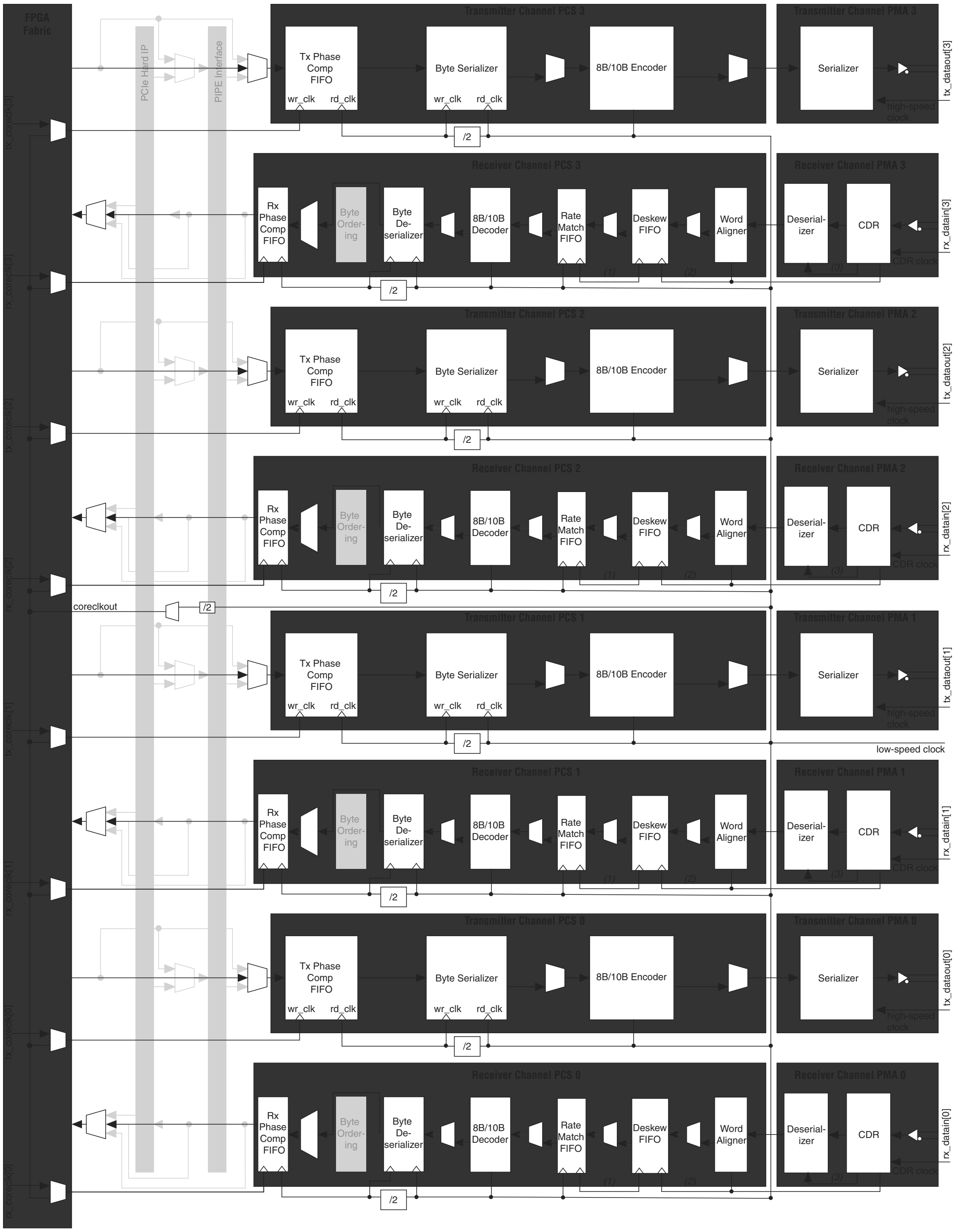
The input reference clocks reside in banks 3A, 3B, 8A, and 8B have dedicated $V_{CC\_CLKIN3A}$, $V_{CC\_CLKIN3B}$, $V_{CC\_CLKIN8A}$, and $V_{CC\_CLKIN8B}$ power supplies separately in their respective I/O banks to avoid the different power level requirements in the same bank for general purpose I/Os (GPIOs). Table 1–6 lists the supported I/O standard for the `REFCLK` pins.

Table 1–6. REFCLK I/O Standard Support

I/O Standard	HSSI Protocol	Coupling	Termination	VCC_CLKIN Level		I/O Pin Type		
				Input	Output	Column I/O	Row I/O	Supported Banks
LVDS	ALL	Differential AC (Needs off-chip resistor to restore V_{CM})	Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B
LVPECL	ALL		Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B
1.2 V, 1.5 V, 3.3 V PCML	ALL		Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B
	ALL		Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B
	ALL		Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B
HCSL	PCIe	Differential DC	Off-chip	2.5 V	Not Supported	Yes	No	3A, 3B, 8A, 8B

Figure 1–63 shows the transceiver channel datapath and clocking when configured in XAUI mode.

Figure 1–63. Transceiver Channel Datapath and Clocking when Configured in XAUI Mode



Notes to Figure 1–63:

(1) Channel 1 low-speed recovered clock.

(2) Low-speed recovered clock.

(3) High-speed recovered clock.

Table 1–28. PIPE Interface Ports in ALTGX Megafunction for Cyclone IV GX (1) (Part 2 of 2)

Port Name	Input/ Output	Clock Domain	Description
pipestatus	Output	N/A	PIPE receiver status port. ■ Signal is 3 bits wide and is encoded as follows: ■ 3'b000: Received data OK ■ 3'b001: one SKP symbol added ■ 3'b010: one SKP symbol removed ■ 3'b011: Receiver detected ■ 3'b100: 8B/10B decoder error ■ 3'b101: Elastic buffer overflow ■ 3'b110: Elastic buffer underflow ■ 3'b111: Received disparity error
rx_elecidleinfersel	Input	N/A	Controls the electrical idle inference mechanism as specified in Table 1–17 on page 1–57

Note to Table 1–28:

(1) For equivalent signals defined in PIPE 2.00 specification, refer to Table 1–15 on page 1–54.

Table 1–29. Multipurpose PLL, General Purpose PLL and Miscellaneous Ports in ALTGX Megafunction for Cyclone IV GX (Part 1 of 2)

Block	Port Name	Input/ Output	Clock Domain	Description
PLL	pll_inclk	Input	Clock signal	Input reference clock for the PLL (multipurpose PLL or general purpose PLL) used by the transceiver instance. When configured with the transmitter and receiver channel configuration in Deterministic Latency mode, multiple `pll_inclk` ports are available as follows. Configured with PLL PFD feedback—x is the number of channels selected: ■ `pll_inclk[x-1..0]` are input reference clocks for each transmitter in the transceiver instance ■ `pll_inclk[x+1..x]` are input reference clocks for receivers in the transceiver instance Configured without PLL PFD feedback: ■ `pll_inclk[0]` is input reference clock for transmitters in the transceiver instance ■ `pll_inclk[1]` is input reference clock for receivers in the transceiver instance
	pll_locked	Output	Asynchronous signal	PLL (used by the transceiver instance) lock indicator.
	pll_areset	Input	Asynchronous signal	PLL (used by the transceiver instance) reset. ■ When asserted, the PLL is kept in reset state. ■ When deasserted, the PLL is active and locks to the input reference clock.
	coreclkout	Output	Clock signal	FPGA fabric-transceiver interface clock in bonded modes.

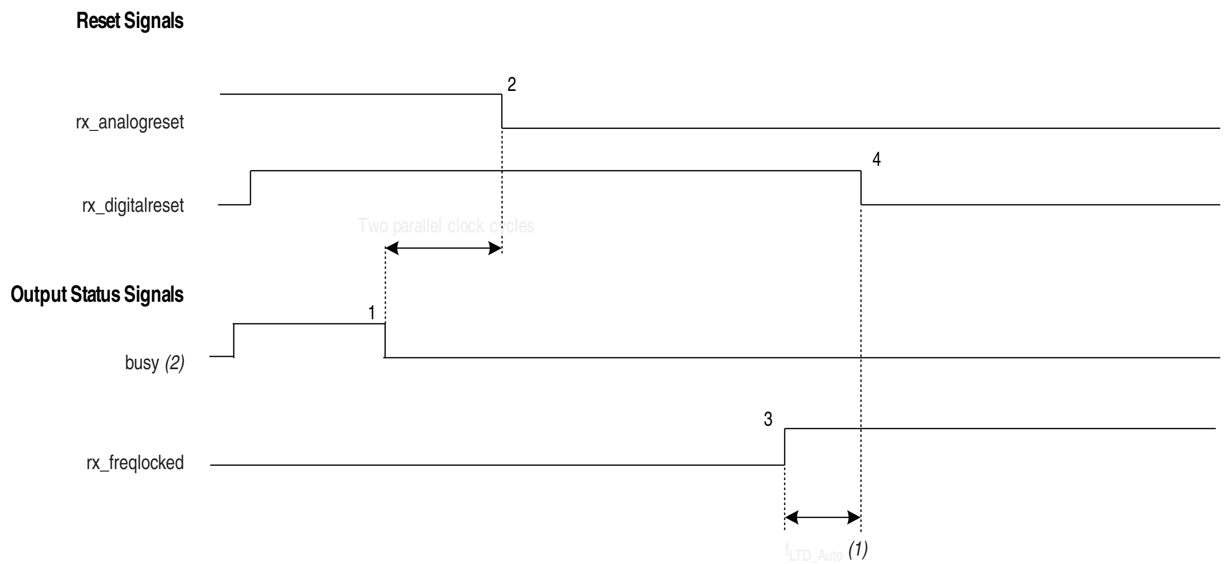
Transmitter Only Channel

This configuration contains only a transmitter channel. If you create a **Transmitter Only** instance in the ALTGX MegaWizard Plug-In Manager, use the same reset sequence shown in Figure 2–3 on page 2–7.

Receiver Only Channel—Receiver CDR in Automatic Lock Mode

This configuration contains only a receiver channel. If you create a **Receiver Only** instance in the ALTGX MegaWizard Plug-In Manager with the receiver CDR in automatic lock mode, use the reset sequence shown in Figure 2–6.

Figure 2–6. Sample Reset Sequence of Receiver Only Channel—Receiver CDR in Automatic Lock Mode



Notes to Figure 2–6:

(1) For t_{LTD_Auto} duration, refer to the *Cyclone IV Device Datasheet* chapter.

(2) The `busy` signal is asserted and deasserted only during initial power up when offset cancellation occurs. In subsequent reset sequences, the `busy` signal is asserted and deasserted only if there is a read or write operation to the ALTGX_RECONFIG megafunction.

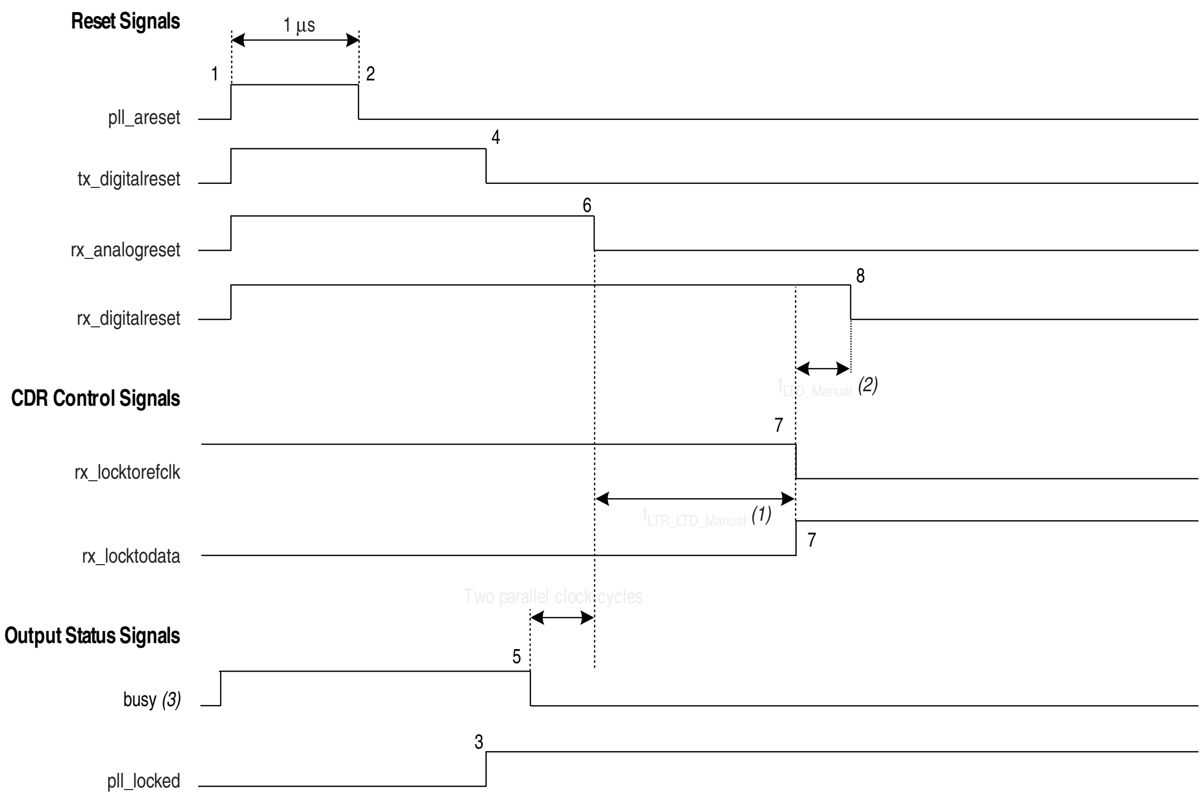
As shown in Figure 2–6, perform the following reset procedure for the receiver in CDR automatic lock mode:

1. After power up, wait for the `busy` signal to be deasserted.
2. Keep the `rx_digitalreset` and `rx_analogreset` signals asserted during this time period.
3. After the busy signal is deasserted, wait for another two parallel clock cycles, then deassert the `rx_analogreset` signal.
4. Wait for the `rx_freqlocked` signal to go high.
5. When `rx_freqlocked` goes high (marker 3), from that point onwards, wait for at least t_{LTD_Auto}, then de-assert the `rx_digitalreset` signal (marker 4). At this point, the receiver is ready to receive data.

Receiver and Transmitter Channel—Receiver CDR in Manual Lock Mode

This configuration contains both a transmitter and receiver channel. If you create a **Receiver and Transmitter** instance in the ALTGX MegaWizard Plug-In Manager with the receiver CDR in manual lock mode, use the reset sequence shown in Figure 2–9.

Figure 2–9. Sample Reset Sequence of Receiver and Transmitter Channel—Receiver CDR in Manual Lock Mode



Notes to Figure 2–9:

(1) For $t_{LTR\_LTD\_Manual}$ duration, refer to the *Cyclone IV Device Datasheet* chapter.

(2) For t_{LTD_Manual} duration, refer to the *Cyclone IV Device Datasheet* chapter.

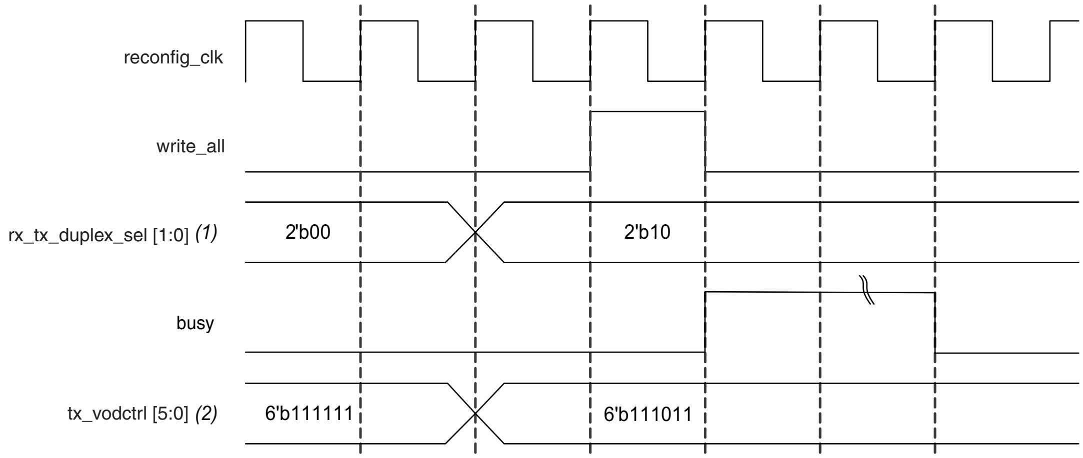
(3) The `busy` signal is asserted and deasserted only during initial power up when offset cancellation occurs. In subsequent reset sequences, the `busy` signal is asserted and deasserted only if there is a read or write operation to the ALTGX_RECONFIG megafunction.

As shown in Figure 2–9, perform the following reset procedure for the receiver in manual lock mode:

1. After power up, assert `pll_areset` for a minimum period of 1 µs (the time between markers 1 and 2).
2. Keep the `tx_digitalreset`, `rx_analogreset`, `rx_digitalreset`, and `rx_locktorefclk` signals asserted and the `rx_locktodata` signal deasserted during this time period. After you deassert the `pll_areset` signal, the multipurpose PLL starts locking to the transmitter input reference clock.
3. After the multipurpose PLL locks, as indicated by the `pll_locked` signal going high (marker 3), deassert `tx_digitalreset` (marker 4). For receiver operation, after deassertion of busy signal (marker 5), wait for two parallel clock cycles to deassert the `rx_analogreset` signal (marker 6). After `rx_analogreset` deassert, `rx_pll_locked` will assert.

Figure 3–8 shows a write transaction waveform with the **Use the same control signal for all the channels** option disabled.

Figure 3–8. Write Transaction Waveform—Use the same control signal for all the channels Option Disabled



Notes to Figure 3–8:

(1) In this waveform example, you want to write to only the transmitter portion of the channel.

(2) In this waveform example, the number of channels controlled by the dynamic reconfiguration controller (the ALTGX_RECONFIG instance) is two and that the `tx_vodctrl` control port is enabled.

☞ Simultaneous write and read transactions are not allowed.

Read Transaction

The read transaction in Method 3 is identical to that in Method 2. Refer to "Read Transaction" on page 3–18.

☞ This is the slowest method. You have to write all the PMA settings for all channels even if you may only be changing one parameter on the channel. Altera recommends using the `logical_channel_address` method for time-critical applications.

For each method, you can additionally reconfigure the PMA setting of both transmitter and receiver portion, transmitter portion only, or receiver portion only of the transceiver channel. For more information, refer to "Dynamic Reconfiguration Controller Port List" on page 3–4. You can enable the `rx_tx_duplex_sel` port by selecting the **Use 'rx_tx_duplex_sel' port to enable RX only, TX only or duplex reconfiguration** option on the **Error checks** tab of the ALTGX_RECONFIG MegaWizard Plug-In Manager.

Figure 3–9 shows the ALTGX_RECONFIG connection to the ALTGX instances when set in analog reconfiguration mode. For the port information, refer to the "Dynamic Reconfiguration Controller Port List" on page 3–4.

1. Cyclone IV Device Datasheet

CYIV-53001-2.1

This chapter describes the electrical and switching characteristics for Cyclone® IV devices. Electrical characteristics include operating conditions and power consumption. Switching characteristics include transceiver specifications, core, and periphery performance. This chapter also describes I/O timing, including programmable I/O element (IOE) delay and programmable output buffer delay.

This chapter includes the following sections:

Operating Conditions

When Cyclone IV devices are implemented in a system, they are rated according to a set of defined parameters. To maintain the highest possible performance and reliability of Cyclone IV devices, you must consider the operating requirements described in this chapter.

Cyclone IV devices are offered in commercial, industrial, extended industrial and, automotive grades. Cyclone IV E devices offer –6 (fastest), –7, –8, –8L, and –9L speed grades for commercial devices, –8L speed grades for industrial devices, and –7 speed grade for extended industrial and automotive devices. Cyclone IV GX devices offer –6 (fastest), –7, and –8 speed grades for commercial devices and –7 speed grade for industrial devices.

For more information about the supported speed grades for respective Cyclone IV devices, refer to the *Cyclone IV FPGA Device Family Overview* chapter.

Cyclone IV E devices are offered in core voltages of 1.0 and 1.2 V. Cyclone IV E devices with a core voltage of 1.0 V have an 'L' prefix attached to the speed grade.

In this chapter, a prefix associated with the operating temperature range is attached to the speed grades; commercial with a "C" prefix, industrial with an "I" prefix, and automotive with an "A" prefix. Therefore, commercial devices are indicated as C6, C7, C8, C8L, or C9L per respective speed grade. Industrial devices are indicated as I7, I8, or I8L. Automotive devices are indicated as A7.

Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1–12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

Table 1–12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices *(1)*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$R_{\_PU}$	Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you enable the programmable pull-up resistor option	V_{CCIO} = 3.3 V ± 5% *(2), (3)*	7	25	41	kΩ
		V_{CCIO} = 3.0 V ± 5% *(2), (3)*	7	28	47	kΩ
		V_{CCIO} = 2.5 V ± 5% *(2), (3)*	8	35	61	kΩ
		V_{CCIO} = 1.8 V ± 5% *(2), (3)*	10	57	108	kΩ
		V_{CCIO} = 1.5 V ± 5% *(2), (3)*	13	82	163	kΩ
		V_{CCIO} = 1.2 V ± 5% *(2), (3)*	19	143	351	kΩ
$R_{\_PD}$	Value of the I/O pin pull-down resistor before and during configuration	V_{CCIO} = 3.3 V ± 5% *(4)*	6	19	30	kΩ
		V_{CCIO} = 3.0 V ± 5% *(4)*	6	22	36	kΩ
		V_{CCIO} = 2.5 V ± 5% *(4)*	6	25	43	kΩ
		V_{CCIO} = 1.8 V ± 5% *(4)*	7	35	71	kΩ
		V_{CCIO} = 1.5 V ± 5% *(4)*	8	50	112	kΩ

Notes to Table 1–12:

(1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG `TCK`.

(2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO}.

(3) $R_{\_PU} = (V_{CCIO} - V_I)/I_{R\_PU}$
Minimum condition: –40°C; $V_{CCIO} = V_{CC} + 5\%$, $V_I = V_{CC} + 5\% - 50$ mV;
Typical condition: 25°C; $V_{CCIO} = V_{CC}$, $V_I = 0$ V;
Maximum condition: 100°C; $V_{CCIO} = V_{CC} - 5\%$, $V_I = 0$ V; in which V_I refers to the input voltage at the I/O pin.

(4) $R_{\_PD} = V_I/I_{R\_PD}$
Minimum condition: –40°C; $V_{CCIO} = V_{CC} + 5\%$, $V_I = 50$ mV;
Typical condition: 25°C; $V_{CCIO} = V_{CC}$, $V_I = V_{CC} - 5\%$;
Maximum condition: 100°C; $V_{CCIO} = V_{CC} - 5\%$, $V_I = V_{CC} - 5\%$; in which V_I refers to the input voltage at the I/O pin.

Hot-Socketing

Table 1–13 lists the hot-socketing specifications for Cyclone IV devices.

Table 1–13. Hot-Socketing Specifications for Cyclone IV Devices

Symbol	Parameter	Maximum
$I_{IOPIN(DC)}$	DC current per I/O pin	300 μA
$I_{IOPIN(AC)}$	AC current per I/O pin	8 mA *(1)*
$I_{XCVRTX(DC)}$	DC current per transceiver `TX` pin	100 mA
$I_{XCVRRX(DC)}$	DC current per transceiver `RX` pin	50 mA

Note to Table 1–13:

(1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |IIOPIN| = C dv/dt, in which C is the I/O pin capacitance and dv/dt is the slew rate.

☞ During hot-socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF.

Embedded Multiplier Specifications

Table 1–26 lists the embedded multiplier specifications for Cyclone IV devices.

Table 1–26. Embedded Multiplier Specifications for Cyclone IV Devices

Mode	Resources Used	Performance					Unit
	Number of Multipliers	C6	C7, I7, A7	C8	C8L, I8L	C9L	
9 × 9-bit multiplier	1	340	300	260	240	175	MHz
18 × 18-bit multiplier	1	287	250	200	185	135	MHz

Memory Block Specifications

Table 1–27 lists the M9K memory block specifications for Cyclone IV devices.

Table 1–27. Memory Block Performance Specifications for Cyclone IV Devices

Memory	Mode	Resources Used		Performance					Unit
		LEs	M9K Memory	C6	C7, I7, A7	C8	C8L, I8L	C9L	
M9K Block	FIFO 256 × 36	47	1	315	274	238	200	157	MHz
	Single-port 256 × 36	0	1	315	274	238	200	157	MHz
	Simple dual-port 256 × 36 CLK	0	1	315	274	238	200	157	MHz
	True dual port 512 × 18 single CLK	0	1	315	274	238	200	157	MHz

Configuration and JTAG Specifications

Table 1–28 lists the configuration mode specifications for Cyclone IV devices.

Table 1–28. Passive Configuration Mode Specifications for Cyclone IV Devices *(1)*

Programming Mode	V_{CCINT} Voltage Level (V)	DCLK f_{MAX}	Unit
Passive Serial (PS)	1.0 *(3)*	66	MHz
	1.2	133	MHz
Fast Passive Parallel (FPP) *(2)*	1.0 *(3)*	66	MHz
	1.2 *(4)*	100	MHz

Notes to Table 1–28:

(1) For more information about PS and FPP configuration timing parameters, refer to the *Configuration and Remote System Upgrades in Cyclone IV Devices* chapter.

(2) FPP configuration mode supports all Cyclone IV E devices (except for E144 package devices) and EP4CGX50, EP4CGX75, EP4CGX110, and EP4CGX150 only.

(3) V_{CCINT} = 1.0 V is only supported for Cyclone IV E 1.0 V core voltage devices.

(4) Cyclone IV E devices support 1.2 V V_{CCINT}. Cyclone IV E 1.2 V core voltage devices support 133 MHz DCLK f_{MAX} for EP4CE6, EP4CE10, EP4CE15, EP4CE22, EP4CE30, and EP4CE40 only.