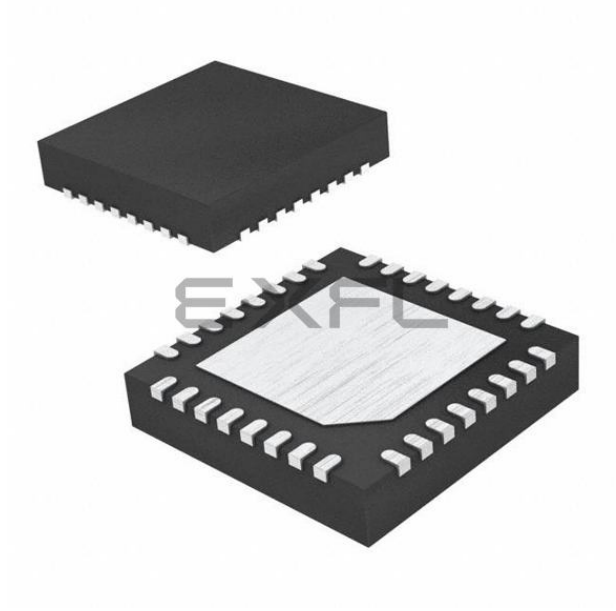
Microchip Technology - DSPIC33EP16GS502-E/2N Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPs
Connectivity	I²C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	21
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 12x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-UQFN Exposed Pad
Supplier Device Package	28-UQFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep16gs502-e-2n

TABLE 4-19: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33EPXXGS506 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	0670	—	—	RP33R5	RP33R4	RP33R3	RP33R2	RP33R1	RP33R0	—	—	RP32R5	RP32R4	RP32R3	RP32R2	RP32R1	RP32R0	0000
RPOR1	0672	—	—	RP35R5	RP35R4	RP35R3	RP35R2	RP35R1	RP35R0	—	—	RP34R5	RP34R4	RP34R3	RP34R2	RP34R1	RP34R0	0000
RPOR2	0674	—	—	RP37R5	RP37R4	RP37R3	RP37R2	RP37R1	RP37R0	—	—	RP36R5	RP36R4	RP36R3	RP36R2	RP36R1	RP36R0	0000
RPOR3	0676	—	—	RP39R5	RP39R4	RP39R3	RP39R2	RP39R1	RP39R0	—	—	RP38R5	RP38R4	RP38R3	RP38R2	RP38R1	RP38R0	0000
RPOR4	0678	—	—	RP41R5	RP41R4	RP41R3	RP41R2	RP41R1	RP41R0	—	—	RP40R5	RP40R4	RP40R3	RP40R2	RP40R1	RP40R0	0000
RPOR5	067A	—	—	RP43R5	RP43R4	RP43R3	RP43R2	RP43R1	RP43R0	—	—	RP42R5	RP42R4	RP42R3	RP42R2	RP42R1	RP42R0	0000
RPOR6	067C	—	—	RP45R5	RP45R4	RP45R3	RP45R2	RP45R1	RP45R0	—	—	RP44R5	RP44R4	RP44R3	RP44R2	RP44R1	RP44R0	0000
RPOR7	067E	—	—	RP47R5	RP47R4	RP47R3	RP47R2	RP47R1	RP47R0	—	—	RP46R5	RP46R4	RP46R3	RP46R2	RP46R1	RP46R0	0000
RPOR8	0680	—	—	RP49R5	RP49R4	RP49R3	RP49R2	RP49R1	RP49R0	—	—	RP48R5	RP48R4	RP48R3	RP48R2	RP48R1	RP48R0	0000
RPOR9	0682	—	—	RP51R5	RP51R4	RP51R3	RP51R2	RP51R1	RP51R0	—	—	RP50R5	RP50R4	RP50R3	RP50R2	RP50R1	RP50R0	0000
RPOR10	0684	—	—	RP53R5	RP53R4	RP53R3	RP53R2	RP53R1	RP53R0	—	—	RP52R5	RP52R4	RP52R3	RP52R2	RP52R1	RP52R0	0000
RPOR11	0686	—	—	RP55R5	RP55R4	RP55R3	RP55R2	RP55R1	RP55R0	—	—	RP54R5	RP54R4	RP54R3	RP54R2	RP54R1	RP54R0	0000
RPOR12	0688	—	—	RP57R5	RP57R4	RP57R3	RP57R2	RP57R1	RP57R0	—	—	RP56R5	RP56R4	RP56R3	RP56R2	RP56R1	RP56R0	0000
RPOR13	068A	—	—	RP59R5	RP59R4	RP59R3	RP59R2	RP59R1	RP59R0	—	—	RP58R5	RP58R4	RP58R3	RP58R2	RP58R1	RP58R0	0000
RPOR14	068C	—	—	RP61R5	RP61R4	RP61R3	RP61R2	RP61R1	RP61R0	—	—	RP60R5	RP60R4	RP60R3	RP60R2	RP60R1	RP60R0	0000
RPOR15	068E	—	—	RP63R5	RP63R4	RP63R3	RP63R2	RP63R1	RP63R0	—	—	RP62R5	RP62R4	RP62R3	RP62R2	RP62R1	RP62R0	0000
RPOR16	0690	—	—	RP177R5	RP177R4	RP177R3	RP177R2	RP177R1	RP177R0	—	—	RP176R5	RP176R4	RP176R3	RP176R2	RP176R1	RP176R0	0000
RPOR17	0692	—	—	RP179R5	RP179R4	RP179R3	RP179R2	RP179R1	RP179R0	—	—	RP178R5	RP178R4	RP178R3	RP178R2	RP178R1	RP178R0	0000
RPOR18	0694	—	—	RP181R5	RP181R4	RP181R3	RP181R2	RP181R1	RP181R0	—	—	RP180R5	RP180R4	RP180R3	RP180R2	RP180R1	RP180R0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-20: PERIPHERAL PIN SELECT INPUT REGISTER MAP

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPINR0	06A0	INT1R<7:0>								—	—	—	—	—	—	—	—	0000
RPINR1	06A2	—	—	—	—	—	—	—	—	INT2R<7:0>								0000
RPINR2	06A4	T1CKR<7:0>								—	—	—	—	—	—	—	—	0000
RPINR3	06A6	T3CKR7	T3CKR6	T3CKR5	T3CKR4	T3CKR3	T3CKR2	T3CKR1	T3CKR0	T2CKR7	T2CKR6	T2CKR5	T2CKR4	T2CKR3	T2CKR2	T2CKR1	T2CKR0	0000
RPINR7	06AE	IC2R7	IC2R6	IC2R5	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0	IC1R7	IC1R6	IC1R5	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0	0000
RPINR8	06B0	IC4R7	IC4R6	IC4R5	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0	IC3R7	IC3R6	IC3R5	IC3R4	IC3R3	IC3R2	IC3R1	IC3R0	0000
RPINR11	06B6	—	—	—	—	—	—	—	—	OCFAR<7:0>								0000
RPINR12	06B8	FLT2R7	FLT2R6	FLT2R5	FLT2R4	FLT2R3	FLT2R2	FLT2R1	FLT2R0	FLT1R7	FLT1R6	FLT1R5	FLT1R4	FLT1R3	FLT1R2	FLT1R1	FLT1R0	0000
RPINR13	06BA	FLT4R7	FLT4R6	FLT4R5	FLT4R4	FLT4R3	FLT4R2	FLT4R1	FLT4R0	FLT3R7	FLT3R6	FLT3R5	FLT3R4	FLT3R3	FLT3R2	FLT3R1	FLT3R0	0000
RPINR18	06C4	U1CTSR7	U1CTSR6	U1CTSR5	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTS0	U1RXR7	U1RXR6	U1RXR5	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0	0000
RPINR19	06C6	U2CTSR7	U2CTSR6	U2CTSR5	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0	U2RXR7	U2RXR6	U2RXR5	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0	0000
RPINR20	06C8	SCK1INR7	SCK1INR6	SCK1INR5	SCK1INR4	SCK1INR3	SCK1INR2	SCK1INR1	SCK1INR0	SDI1R7	SDI1R6	SDI1R5	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0	0000
RPINR21	06CA	—	—	—	—	—	—	—	—	SS1R<7:0>								0000
RPINR22	06CC	SCK2INR7	SCK2INR6	SCK2INR5	SCK2INR4	SCK2INR3	SCK2INR2	SCK2INR1	SCK2INR0	SDI2R7	SDI2R6	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0	0000
RPINR23	06CE	—	—	—	—	—	—	—	—	SS2R<7:0>								0000
RPINR37	06EA	SYNCI1R<7:0>								—	—	—	—	—	—	—	—	0000
RPINR38	06EC	—	—	—	—	—	—	—	—	SYNCI2R<7:0>								0000
RPINR42	06F4	FLT6R7	FLT6R6	FLT6R5	FLT6R4	FLT6R3	FLT6R2	FLT6R1	FLT6R0	FLT5R7	FLT5R6	FLT5R5	FLT5R4	FLT5R3	FLT5R2	FLT5R1	FLT5R0	0000
RPINR43	06F6	FLT8R7	FLT8R6	FLT8R5	FLT8R4	FLT8R3	FLT8R2	FLT8R1	FLT8R0	FLT7R7	FLT7R6	FLT7R5	FLT7R4	FLT7R3	FLT7R2	FLT7R1	FLT7R0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

7.0 INTERRUPT CONTROLLER

Note 1: This data sheet summarizes the features of the dsPIC33EPXXGS50X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **"Interrupts"** (DS70000600) in the *"dsPIC33/PIC24 Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXGS50X family interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the dsPIC33EPXXGS50X family CPU.

The interrupt controller has the following features:

- Six processor exceptions and software traps
- Seven user-selectable priority levels
- Interrupt Vector Table (IVT) with a unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Fixed interrupt entry and return latencies
- Alternate Interrupt Vector Table (AIVT) for debug support

7.1 Interrupt Vector Table

The dsPIC33EPXXGS50X family Interrupt Vector Table (IVT), shown in Figure 7-1, resides in program memory, starting at location, 000004h. The IVT contains six non-maskable trap vectors and up to 246 sources of interrupts. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority. This priority is linked to their position in the vector table. Lower addresses generally have a higher natural priority. For example, the interrupt associated with Vector 0 takes priority over interrupts at any other vector address.

7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT), shown in Figure 7-2, is available only when the Boot Segment is defined and the AIVT has been enabled. To enable the Alternate Interrupt Vector Table, the Configuration bit, AIVTDIS in the FSEC register, must be programmed and the AIVTEN bit must be set (INTCON2<8> = 1). When the AIVT is enabled, all interrupt and exception processes use the alternate vectors instead of the default vectors. The AIVT begins at the start of the last page of the Boot Segment, defined by BSLIM<12:0>. The second half of the page is no longer usable space. The Boot Segment must be at least 2 pages to enable the AIVT.

Note: Although the Boot Segment must be enabled in order to enable the AIVT, application code does not need to be present inside of the Boot Segment. The AIVT (and IVT) will inherit the Boot Segment code protection.

The AIVT supports debugging by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time.

7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The dsPIC33EPXXGS50X family devices clear their registers in response to a Reset, which forces the PC to zero. The device then begins program execution at location, 0x000000. A GOTO instruction at the Reset address can redirect program execution to the appropriate start-up routine.

Note: Any unimplemented or unused vector locations in the IVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)

bit 2 **STKERR:** Stack Error Trap Status bit
1 = Stack error trap has occurred
0 = Stack error trap has not occurred

bit 1 **OSCFAIL:** Oscillator Failure Trap Status bit
1 = Oscillator failure trap has occurred
0 = Oscillator failure trap has not occurred

bit 0 **Unimplemented:** Read as '0'

8.5 Oscillator Control Registers

REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER(1)

U-0	R-0	R-0	R-0	U-0	R/W-y	R/W-y	R/W-y
—	COSC2	COSC1	COSC0	—	NOSC2(2)	NOSC1(2)	NOSC0(2)
bit 15							bit 8

R/W-0	R/W-0	R-0	U-0	R/W-0	U-0	U-0	R/W-0
CLKLOCK	IOLOCK	LOCK	—	CF(3)	—	—	OSWEN
bit 7							bit 0

Legend:	y = Value set from Configuration bits on POR		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits (read-only)
111 = Fast RC Oscillator (FRC) with Divide-by-n
110 = Fast RC Oscillator (FRC) with Divide-by-16
101 = Low-Power RC Oscillator (LPRC)
100 = Reserved
011 = Primary Oscillator (XT, HS, EC) with PLL
010 = Primary Oscillator (XT, HS, EC)
001 = Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL)
000 = Fast RC Oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits(2)
111 = Fast RC Oscillator (FRC) with Divide-by-n
110 = Fast RC Oscillator (FRC) with Divide-by-16
101 = Low-Power RC Oscillator (LPRC)
100 = Reserved
011 = Primary Oscillator (XT, HS, EC) with PLL
010 = Primary Oscillator (XT, HS, EC)
001 = Fast RC Oscillator (FRC) with Divide-by-N and PLL (FRCPLL)
000 = Fast RC Oscillator (FRC)

bit 7 **CLKLOCK:** Clock Lock Enable bit
1 = If (FCKSM0 = 1), then clock and PLL configurations are locked; if (FCKSM0 = 0), then clock and PLL configurations may be modified
0 = Clock and PLL selections are not locked, configurations may be modified

bit 6 **IOLOCK:** I/O Lock Enable bit
1 = I/O lock is active
0 = I/O lock is not active

bit 5 **LOCK:** PLL Lock Status bit (read-only)
1 = Indicates that PLL is in lock or PLL start-up timer is satisfied
0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled

Note 1: Writes to this register require an unlock sequence.

2: Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transitional clock source between the two PLL modes.

3: This bit should only be cleared in software. Setting the bit in software (= 1) will have the same effect as an actual oscillator failure and will trigger an oscillator failure trap.

REGISTER 8-2: CLKDIV: CLOCK DIVISOR REGISTER (CONTINUED)

bit 4-0 **PLLPRE<4:0>:** PLL Phase Detector Input Divider Select bits (also denoted as 'N1', PLL prescaler)
11111 = Input divided by 33
•
•
•
00001 = Input divided by 3
00000 = Input divided by 2 (default)

Note 1: The DOZE<2:0> bits can only be written to when the DOZEN bit is clear. If DOZEN = 1, any writes to DOZE<2:0> are ignored.
2: This bit is cleared when the ROI bit is set and an interrupt occurs.
3: The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

REGISTER 8-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PLLDIV8
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
PLLDIV<7:0>							
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8-0 **PLLDIV<8:0>:** PLL Feedback Divisor bits (also denoted as 'M', PLL multiplier)
111111111 = 513
•
•
•
000110000 = 50 (default)
•
•
•
000000010 = 4
000000001 = 3
000000000 = 2

REGISTER 8-6: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ROON	—	ROSSLP	ROSEL	RODIV3(1)	RODIV2(1)	RODIV1(1)	RODIV0(1)
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **ROON:** Reference Oscillator Output Enable bit
1 = Reference oscillator output is enabled on the RPn pin(2)
0 = Reference oscillator output is disabled

bit 14 **Unimplemented:** Read as '0'

bit 13 **ROSSLP:** Reference Oscillator Run in Sleep bit
1 = Reference oscillator output continues to run in Sleep
0 = Reference oscillator output is disabled in Sleep

bit 12 **ROSEL:** Reference Oscillator Source Select bit
1 = Oscillator crystal is used as the reference clock
0 = System clock is used as the reference clock

bit 11-8 **RODIV<3:0>:** Reference Oscillator Divider bits(1)
1111 = Reference clock divided by 32,768
1110 = Reference clock divided by 16,384
1101 = Reference clock divided by 8,192
1100 = Reference clock divided by 4,096
1011 = Reference clock divided by 2,048
1010 = Reference clock divided by 1,024
1001 = Reference clock divided by 512
1000 = Reference clock divided by 256
0111 = Reference clock divided by 128
0110 = Reference clock divided by 64
0101 = Reference clock divided by 32
0100 = Reference clock divided by 16
0011 = Reference clock divided by 8
0010 = Reference clock divided by 4
0001 = Reference clock divided by 2
0000 = Reference clock

bit 7-0 **Unimplemented:** Read as '0'

Note 1: The reference oscillator output must be disabled (ROON = 0) before writing to these bits.
2: This pin is remappable. See **Section 10.4 "Peripheral Pin Select (PPS)"** for more information.

10.1.1 OPEN-DRAIN CONFIGURATION

In addition to the PORTx, LATx and TRISx registers for data control, port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control x register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs other than VDD by using external pull-up resistors. The maximum open-drain voltage allowed on any pin is the same as the maximum VIH specification for that particular pin.

See the **"Pin Diagrams"** section for the available 5V tolerant pins and Table 26-11 for the maximum VIH specification for each pin.

10.2 Configuring Analog and Digital Port Pins

The ANSELx register controls the operation of the analog port pins. The port pins that are to function as analog inputs or outputs must have their corresponding ANSELx and TRISx bits set. In order to use port pins for I/O functionality with digital modules, such as timers, UARTs, etc., the corresponding ANSELx bit must be cleared.

The ANSELx register has a default value of 0xFFFF; therefore, all pins that share analog functions are analog (not digital) by default.

Pins with analog functions affected by the ANSELx registers are listed with a buffer type of analog in the Pinout I/O Descriptions (see Table 1-1).

If the TRISx bit is cleared (output) while the ANSELx bit is set, the digital output level (VOH or VOL) is converted by an analog peripheral, such as the ADC module or comparator module.

When the PORTx register is read, all pins configured as analog input channels are read as cleared (a low level).

Pins configured as digital inputs do not convert an analog input. Analog levels on any pin, defined as a digital input (including the ANx pins), can cause the input buffer to consume current that exceeds the device specifications.

10.2.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be a NOP, as shown in Example 10-1.

10.3 Input Change Notification (ICN)

The Input Change Notification function of the I/O ports allows devices to generate interrupt requests to the processor in response to a Change-of-State (COS) on selected input pins. This feature can detect input Change-of-States, even in Sleep mode, when the clocks are disabled. Every I/O port pin can be selected (enabled) for generating an interrupt request on a Change-of-State.

Three control registers are associated with the ICN functionality of each I/O port. The CNENx registers contain the ICN interrupt enable control bits for each of the input pins. Setting any of these bits enables an ICN interrupt for the corresponding pins.

Each I/O pin also has a weak pull-up and a weak pull-down connected to it. The pull-ups and pull-downs act as a current source, or sink source, connected to the pin, and eliminate the need for external resistors when push button or keypad devices are connected. The pull-ups and pull-downs are enabled separately, using the CNPUx and the CNPDx registers, which contain the control bits for each of the pins. Setting any of the control bits enables the weak pull-ups and/or pull-downs for the corresponding pins.

Note:	Pull-ups and pull-downs on Input Change Notification pins should always be disabled when the port pin is configured as a digital output.

EXAMPLE 10-1: PORT WRITE/READ EXAMPLE

```
MOV   0xFF00, W0   ; Configure PORTB<15:8>
                   ; as inputs
MOV   W0, TRISB    ; and PORTB<7:0>
                   ; as outputs
NOP                ; Delay 1 cycle
BTSS  PORTB, #13   ; Next Instruction
```

11.2 Timer1 Control Register

REGISTER 11-1: T1CON: TIMER1 CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON(1)	—	TSIDL	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
—	TGATE	TCKPS1	TCKPS0	—	TSYNC(1)	TCS(1)	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **TON:** Timer1 On bit(1)
1 = Starts 16-bit Timer1
0 = Stops 16-bit Timer1

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Timer1 Stop in Idle Mode bit
1 = Discontinues module operation when device enters Idle mode
0 = Continues module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timer1 Gated Time Accumulation Enable bit
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation is enabled
0 = Gated time accumulation is disabled

bit 5-4 **TCKPS<1:0>:** Timer1 Input Clock Prescale Select bits
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1

bit 3 **Unimplemented:** Read as '0'

bit 2 **TSYNC:** Timer1 External Clock Input Synchronization Select bit(1)
When TCS = 1:
1 = Synchronizes external clock input
0 = Does not synchronize external clock input
When TCS = 0:
This bit is ignored.

bit 1 **TCS:** Timer1 Clock Source Select bit(1)
1 = External clock is from pin, T1CK (on the rising edge)
0 = Internal clock (FP)

bit 0 **Unimplemented:** Read as '0'

Note 1: When Timer1 is enabled in External Synchronous Counter mode (TCS = 1, TSYNC = 1, TON = 1), any attempts by user software to write to the TMR1 register are ignored.

REGISTER 15-8: SSEVTCMP: PWMx SECONDARY SPECIAL EVENT COMPARE REGISTER(1)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SSEVTCMP<12:5>							
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
SSEVTCMP<4:0>					—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3 **SSEVTCMP<12:0>:** Special Event Compare Count Value bits

bit 2-0 **Unimplemented:** Read as '0'

Note 1: One LSB = 1.04 ns (at fastest auxiliary clock rate); therefore, the minimum SEVTCMP resolution is 8.32 ns.

REGISTER 15-9: CHOP: PWMx CHOP CLOCK GENERATOR REGISTER(1)

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
CHPCLKEN	—	—	—	—	—	CHOPCLK6	CHOPCLK5
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0
CHOPCLK4	CHOPCLK3	CHOPCLK2	CHOPCLK1	CHOPCLK0	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **CHPCLKEN:** Enable Chop Clock Generator bit
1 = Chop clock generator is enabled
0 = Chop clock generator is disabled

bit 14-10 **Unimplemented:** Read as '0'

bit 9-3 **CHOPCLK<6:0>:** Chop Clock Divider bits
Value is in 8.32 ns increments. The frequency of the chop clock signal is given by:
Chop Frequency = 1/(16.64 * (CHOP<7:3> + 1) * Primary Master PWM Input Clock Period)

bit 2-0 **Unimplemented:** Read as '0'

Note 1: The chop clock generator operates with the primary PWMx clock prescaler (PCLKDIV<2:0>) in the PTCON2 register (Register 15-2).

REGISTER 19-5: ADCON3L: ADC CONTROL REGISTER 3 LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R-0, HSC	R/W-0	R-0, HSC
REFSEL2	REFSEL1	REFSEL0	SUSPEND	SUSPCIE	SUSPRDY	SHRSAMP	CNVRTCH
bit 15							bit 8

R/W-0	R/W-0, HSC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SWLCTRG	SWCTRG	CNVCHSEL5	CNVCHSEL4	CNVCHSEL3	CNVCHSEL2	CNVCHSEL1	CNVCHSEL0
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'		
R = Readable bit	W = Writable bit	HSC = Hardware Settable/Clearable bit	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 **REFSEL<2:0>:** ADC Reference Voltage Selection bits

Value	VREFH	VREFL
000	AVDD	AVSS

001-111 = **Unimplemented:** Do not use

bit 12 **SUSPEND:** All ADC Cores Triggers Disable bit

1 = All new trigger events for all ADC cores are disabled
0 = All ADC cores can be triggered

bit 11 **SUSPCIE:** Suspend All ADC Cores Common Interrupt Enable bit

1 = Common interrupt will be generated when ADC core triggers are suspended (SUSPEND bit = 1) and all previous conversions are finished (SUSPRDY bit becomes set)
0 = Common interrupt is not generated for suspend ADC cores event

bit 10 **SUSPRDY:** All ADC Cores Suspended Flag bit

1 = All ADC cores are suspended (SUSPEND bit = 1) and have no conversions in progress
0 = ADC cores have previous conversions in progress

bit 9 **SHRSAMP:** Shared ADC Core Sampling Direct Control bit

This bit should be used with the individual channel conversion trigger controlled by the CNVRTCH bit. It connects an analog input, specified by the CNVCHSEL<5:0> bits, to the shared ADC core and allows extending the sampling time. This bit is not controlled by hardware and must be cleared before the conversion starts (setting CNVRTCH to '1').

1 = Shared ADC core samples an analog input specified by the CNVCHSEL<5:0> bits
0 = Sampling is controlled by the shared ADC core hardware

bit 8 **CNVRTCH:** Software Individual Channel Conversion Trigger bit

1 = Single trigger is generated for an analog input specified by the CNVCHSEL<5:0> bits; when the bit is set, it is automatically cleared by hardware on the next instruction cycle
0 = Next individual channel conversion trigger can be generated

bit 7 **SWLCTRG:** Software Level-Sensitive Common Trigger bit

1 = Triggers are continuously generated for all channels with the software, level-sensitive common trigger selected as a source in the ADTRIGxL and ADTRIGxH registers
0 = No software, level-sensitive common triggers are generated

bit 6 **SWCTRG:** Software Common Trigger bit

1 = Single trigger is generated for all channels with the software, common trigger selected as a source in the ADTRIGxL and ADTRIGxH registers; when the bit is set, it is automatically cleared by hardware on the next instruction cycle
0 = Ready to generate the next software, common trigger

bit 5-0 **CNVCHSEL <5:0>:** Channel Number Selection for Software Individual Channel Conversion Trigger bits

These bits define a channel to be converted when the CNVRTCH bit is set.

REGISTER 19-8: ADCON4H: ADC CONTROL REGISTER 4 HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
C3CHS1	C3CHS0	C2CHS1	C2CHS0	C1CHS1	C1CHS0	C0CHS1	C0CHS0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’	
-n = Value at POR	‘1’ = Bit is set	‘0’ = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-6 **C3CHS<1:0>:** Dedicated ADC Core 3 Input Channel Selection bits
1x = Reserved
01 = AN15 (differential negative input when DIFF3 (ADMOD0L<7>) = 1)
00 = AN3

bit 5-4 **C2CHS<1:0>:** Dedicated ADC Core 2 Input Channel Selection bits
11 = Reserved
10 = VREF Band Gap
01 = AN11 (differential negative input when DIFF2 (ADMOD0L<5>) = 1)
00 = AN2

bit 3-2 **C1CHS<1:0>:** Dedicated ADC Core 1 Input Channel Selection bits
11 = AN1ALT
10 = PGA2
01 = AN18 (differential negative input when DIFF1 (ADMOD0L<3>) = 1)
00 = AN1

bit 1-0 **C0CHS<1:0>:** Dedicated ADC Core 0 Input Channel Selection bits
11 = AN0ALT
10 = PGA1
01 = AN7 (differential negative input when DIFF0 (ADMOD0L<1>) = 1)
00 = AN0

21.2 PGA Resources

Many useful resources are provided on the main product page of the Microchip website for the devices listed in this data sheet. This product page contains the latest updates and additional information.

21.2.1 KEY RESOURCES

- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *"dsPIC33/PIC24 Family Reference Manual"* Sections
- Development Tools

REGISTER 21-1: PGAxCON: PGAx CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PGAEN	PGAOEN	SELPI2	SELPI1	SELPI0	SELNI2	SELNI1	SELNI0
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	GAIN2	GAIN1	GAIN0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15 **PGAEN:** PGAx Enable bit
1 = PGAx module is enabled
0 = PGAx module is disabled (reduces power consumption)

bit 14 **PGAOEN:** PGAx Output Enable bit
1 = PGAx output is connected to the DACOUTx pin
0 = PGAx output is not connected to the DACOUTx pin

bit 13-11 **SELPI<2:0>:** PGAx Positive Input Selection bits
111 = Reserved
110 = Reserved
101 = Reserved
100 = Reserved
011 = PGAxP4
010 = PGAxP3
001 = PGAxP2
000 = PGAxP1

bit 10-8 **SELNI<2:0>:** PGAx Negative Input Selection bits
111 = Reserved
110 = Reserved
101 = Reserved
100 = Reserved
011 = Ground (Single-Ended mode)
010 = PGAxN3
001 = PGAxN2
000 = Ground (Single-Ended mode)

bit 7-3 **Unimplemented:** Read as '0'

26.1 DC Characteristics

TABLE 26-1: OPERATING MIPS vs. VOLTAGE

Characteristic	VDD Range (in Volts)	Temperature Range (in °C)	Maximum MIPS
			dsPIC33EPXXGS50X Family
—	3.0V to 3.6V(1)	-40°C to +85°C	70
—	3.0V to 3.6V(1)	-40°C to +125°C	60

Note 1: Device is functional at VBORMIN < VDD < VDDMIN. Analog modules (ADC, PGAs and comparators) may have degraded performance. Device functionality is tested but not characterized. Refer to Parameter BO10 in Table 26-13 for the minimum and maximum BOR values.

TABLE 26-2: THERMAL OPERATING CONDITIONS

Rating	Symbol	Min.	Typ.	Max.	Unit
Industrial Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+125	°C
Operating Ambient Temperature Range	TA	-40	—	+85	°C
Extended Temperature Devices					
Operating Junction Temperature Range	TJ	-40	—	+140	°C
Operating Ambient Temperature Range	TA	-40	—	+125	°C
Power Dissipation: Internal Chip Power Dissipation: PINT = VDD x (IDD – Σ IOH) I/O Pin Power Dissipation: I/O = Σ ({VDD – VOH} x IOH) + Σ (VOL x IOL)	PD	PINT + PI/O			W
Maximum Allowed Power Dissipation	PDMAX	(TJ – TA)/θJA			W

TABLE 26-3: THERMAL PACKAGING CHARACTERISTICS

Characteristic	Symbol	Typ.	Max.	Unit	Notes
Package Thermal Resistance, 64-Pin TQFP 10x10x1 mm	θJA	49.0	—	°C/W	1
Package Thermal Resistance, 48-Pin TQFP 7x7x1.0 mm	θJA	63.0	—	°C/W	1
Package Thermal Resistance, 44-Pin QFN 8x8 mm	θJA	29.0	—	°C/W	1
Package Thermal Resistance, 44-Pin TQFP 10x10x1 mm	θJA	50.0	—	°C/W	1
Package Thermal Resistance, 28-Pin QFN-S 6x6x0.9 mm	θJA	30.0	—	°C/W	1
Package Thermal Resistance, 28-Pin UQFN 6x6x0.5 mm	θJA	26.0	—	°C/W	1
Package Thermal Resistance, 28-Pin SOIC 7.50 mm	θJA	70.0	—	°C/W	1

Note 1: Junction to ambient thermal resistance, Theta-JA (θJA) numbers are achieved by package simulations.

TABLE 26-18: PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic**	**Min.**	**Typ.(1)**	**Max.**	**Units**	**Conditions**
OS50	FPLLI	PLL Voltage Controlled Oscillator (VCO) Input Frequency Range	0.8	—	8.0	MHz	ECPLL, XTPLL modes
OS51	FVCO	On-Chip VCO System Frequency	120	—	340	MHz	
OS52	TLOCK	PLL Start-up Time (Lock Time)	0.9	1.5	3.1	ms	
OS53	DCLK	CLKO Stability (Jitter)(2)	-3	0.5	3	%	

Note 1: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: This jitter specification is based on clock cycle-by-clock cycle measurements. To get the effective jitter for individual time bases, or communication clocks used by the application, use the following formula:

$$\text{Effective Jitter} = \frac{DCLK}{\sqrt{\frac{FOSC}{\text{Time Base or Communication Clock}}}}$$

For example, if FOSC = 120 MHz and the SPIx bit rate = 10 MHz, the effective jitter is as follows:

$$\text{Effective Jitter} = \frac{DCLK}{\sqrt{\frac{120}{10}}} = \frac{DCLK}{\sqrt{12}} = \frac{DCLK}{3.464}$$

TABLE 26-19: AUXILIARY PLL CLOCK TIMING SPECIFICATIONS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic**	**Min**	**Typ(1)**	**Max**	**Units**	**Conditions**
OS56	FHPOUT	On-Chip 16x PLL CCO Frequency	112	118	120	MHz	
OS57	FHPIN	On-Chip 16x PLL Phase Detector Input Frequency	7.0	7.37	7.5	MHz	
OS58	TSU	Frequency Generator Lock Time	—	—	10	µs	

Note 1: Data in "Typ" column is at 3.3V, +25°C unless otherwise stated. Parameters are for design guidance only and are not tested in manufacturing.

TABLE 26-23: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	**Symbol**	**Characteristic(1)**	**Min.**	**Typ.(2)**	**Max.**	**Units**	**Conditions**
SY00	TPU	Power-up Period	—	400	600	μs	
SY10	TOST	Oscillator Start-up Time	—	1024 TOSC	—	—	TOSC = OSC1 period
SY12	TWDT	Watchdog Timer Time-out Period	0.81	—	1.22	ms	WDTPRE = 0, WDTPOST<3:0> = 0000, using LPRC tolerances indicated in F21 (see Table 26-21) at +85°C
			3.25	—	4.88	ms	WDTPRE = 1, WDTPOST<3:0> = 0000, using LPRC tolerances indicated in F21 (see Table 26-21) at +85°C
SY13	TIOZ	I/O High-Impedance from $\overline{\text{MCLR}}$ Low or Watchdog Timer Reset	0.68	0.72	1.2	μs	
SY20	TMCLR	$\overline{\text{MCLR}}$ Pulse Width (low)	2	—	—	μs	
SY30	TBOR	BOR Pulse Width (low)	1	—	—	μs	
SY35	TFSCM	Fail-Safe Clock Monitor Delay	—	500	900	μs	-40°C to +85°C
SY36	TVREG	Voltage Regulator Standby-to-Active mode Transition Time	—	—	30	μs	
SY37	TOSCDFRC	FRC Oscillator Start-up Delay	—	48	—	μs	
SY38	TOSCDLPRC	LPRC Oscillator Start-up Delay	—	—	70	μs	

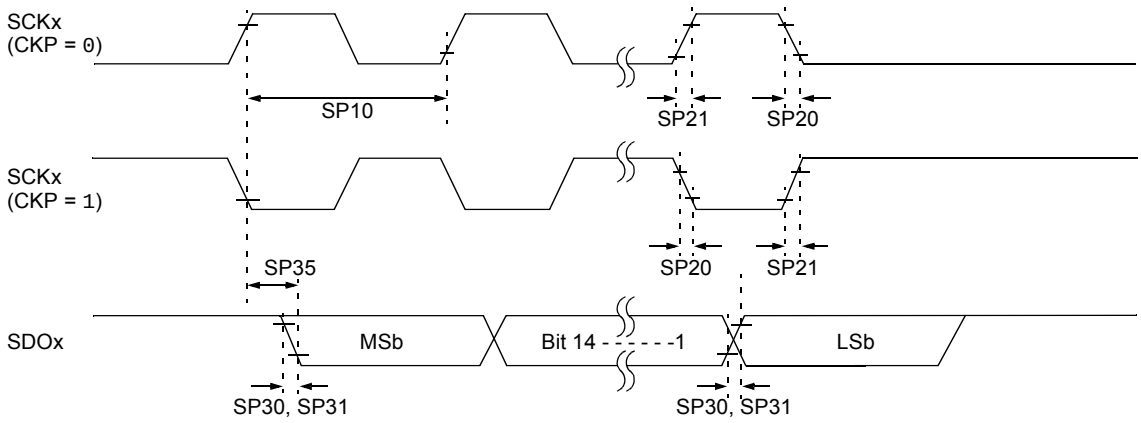
Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ." column is at 3.3V, +25°C unless otherwise stated.

TABLE 26-31: SPIx MAXIMUM DATA/CLOCK RATE SUMMARY

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended			
Maximum Data Rate	**Master Transmit Only (Half-Duplex)**	**Master Transmit/Receive (Full-Duplex)**	**Slave Transmit/Receive (Full-Duplex)**	**CKE**	**CKP**	**SMP**
15 MHz	Table 26-31	—	—	0,1	0,1	0,1
9 MHz	—	Table 26-32	—	1	0,1	1
9 MHz	—	Table 26-33	—	0	0,1	1
15 MHz	—	—	Table 26-34	1	0	0
11 MHz	—	—	Table 26-35	1	1	0
15 MHz	—	—	Table 26-36	0	1	0
11 MHz	—	—	Table 26-37	0	0	0

FIGURE 26-11: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY, CKE = 0) TIMING CHARACTERISTICS



Note: Refer to Figure 26-1 for load conditions.

FIGURE 26-15: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS

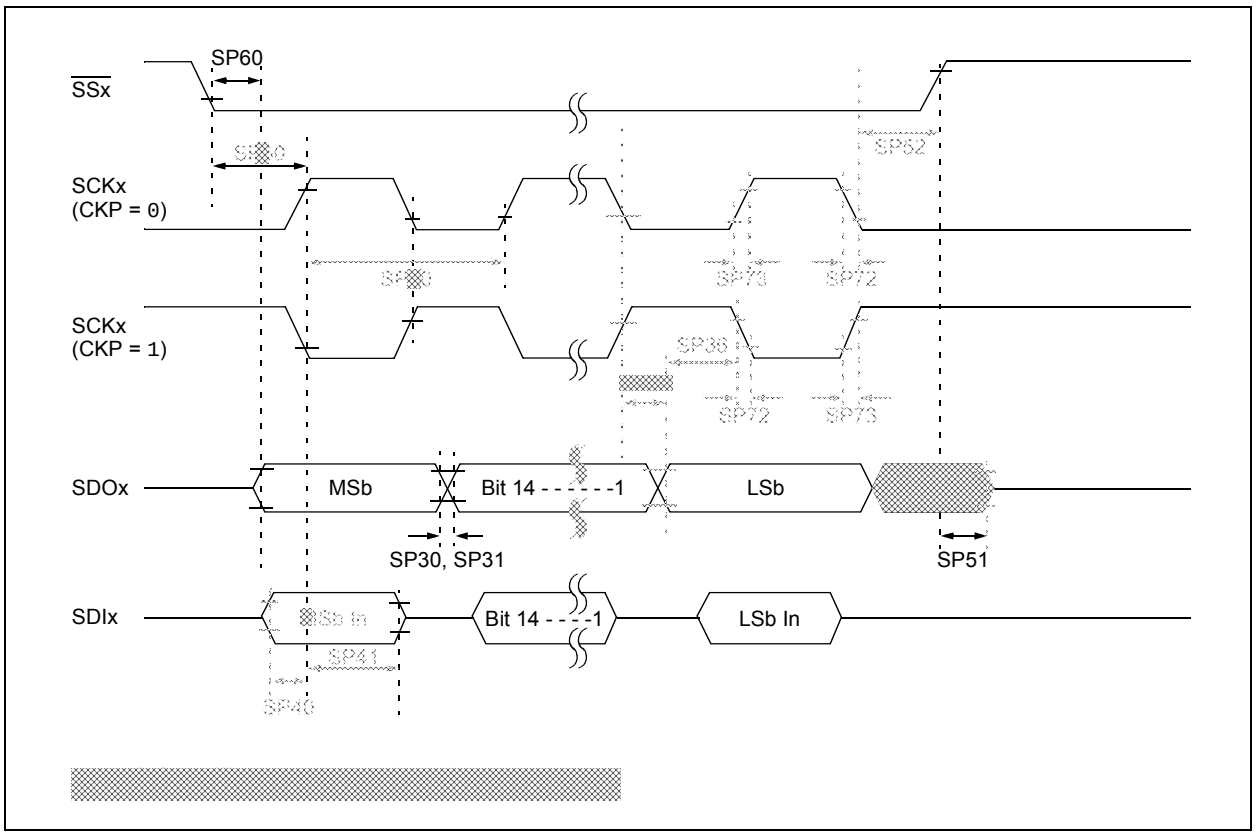
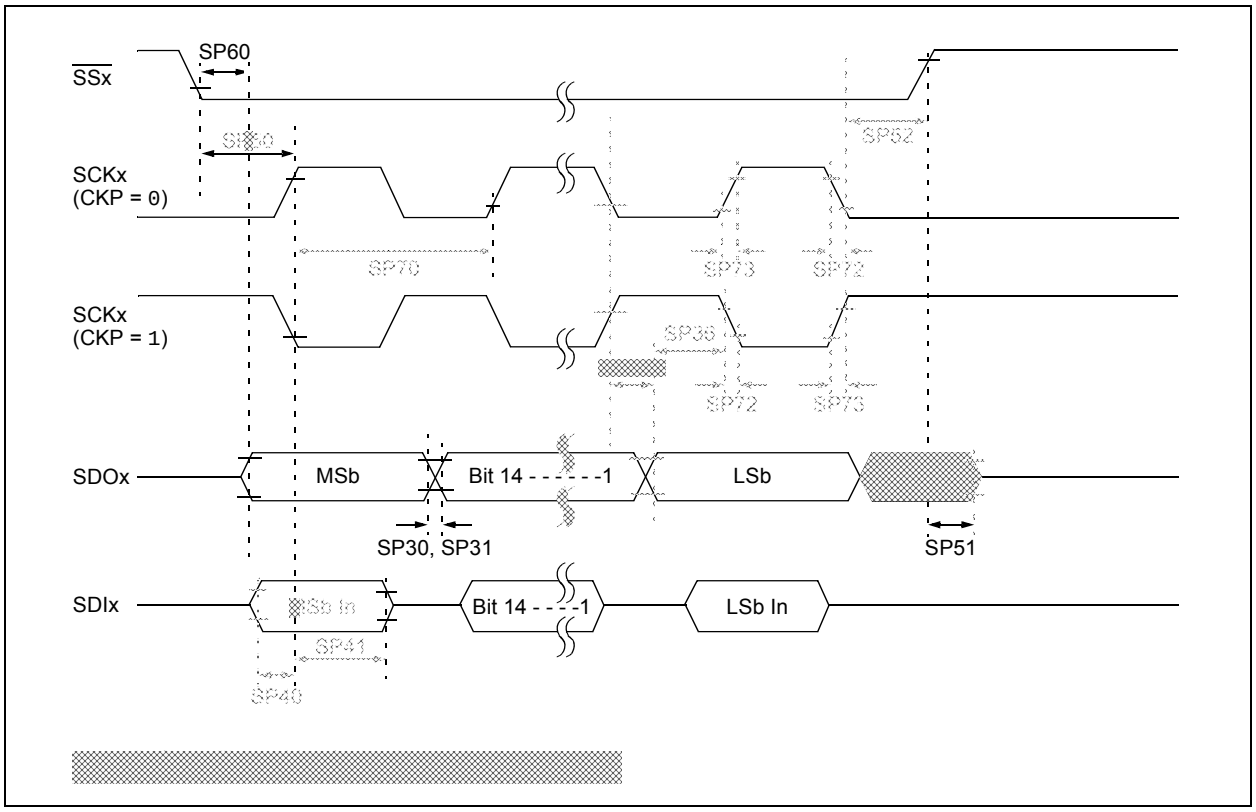
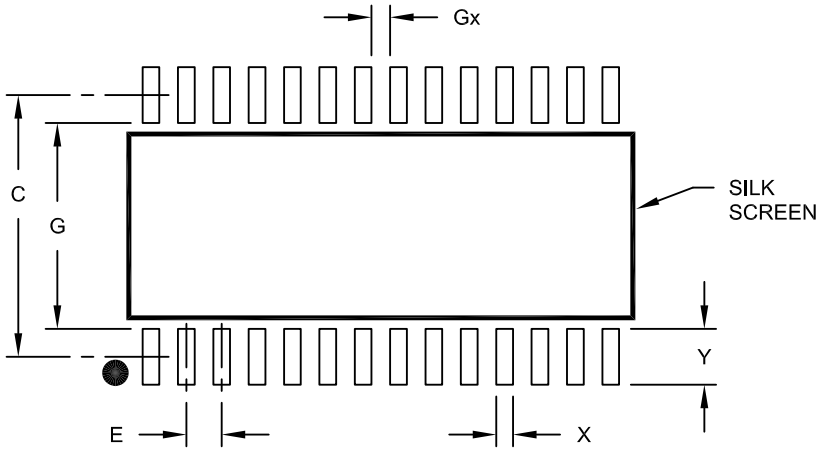


FIGURE 26-16: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS



28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	1.27 BSC		
Contact Pad Spacing	C		9.40	
Contact Pad Width (X28)	X			0.60
Contact Pad Length (X28)	Y			2.00
Distance Between Pads	Gx	0.67		
Distance Between Pads	G	7.40		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A