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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	60 MIPS
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	35
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 19x12b; D/A 1x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep16gs504t-e-pt

dsPIC33EPXXGS50X FAMILY

FIGURE 4-1: PROGRAM MEMORY MAP FOR dsPIC33EP16GS50X DEVICES

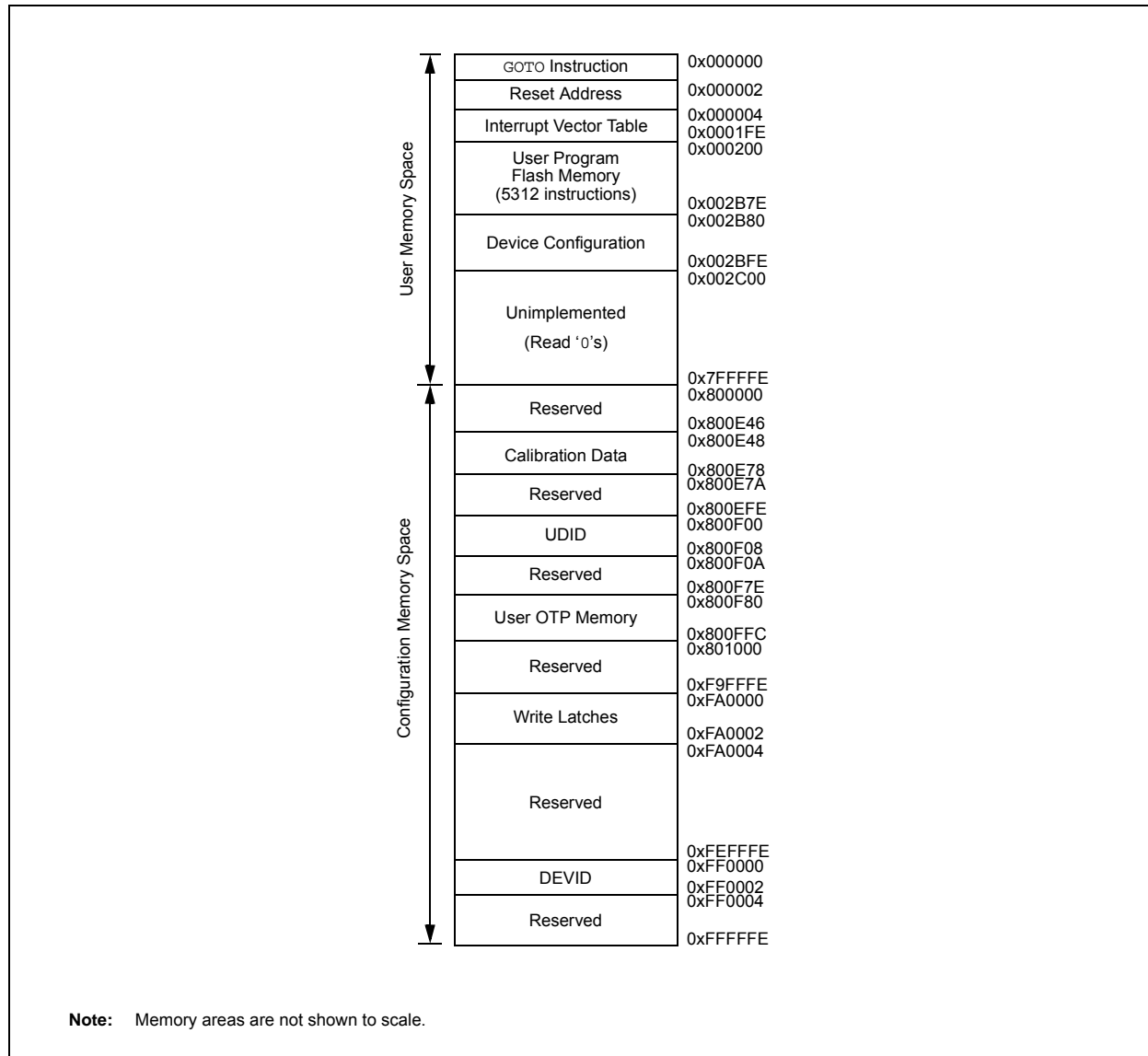


TABLE 4-30: PORTA REGISTER MAP FOR dsPIC33EPXXGS504/505 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISA	0E00	—	—	—	—	—	—	—	—	—	—	—	TRISA<4:0>					001F
PORTA	0E02	—	—	—	—	—	—	—	—	—	—	—	RA<4:0>					0000
LATA	0E04	—	—	—	—	—	—	—	—	—	—	—	LATA<4:0>					0000
ODCA	0E06	—	—	—	—	—	—	—	—	—	—	—	ODCA<4:0>					0000
CNENA	0E08	—	—	—	—	—	—	—	—	—	—	—	CNIEA<4:0>					0000
CNPUA	0E0A	—	—	—	—	—	—	—	—	—	—	—	CNPUA<4:0>					0000
CNPDA	0E0C	—	—	—	—	—	—	—	—	—	—	—	CNPDA<4:0>					0000
ANSELA	0E0E	—	—	—	—	—	—	—	—	—	—	—	—	—	ANSA<2:0>			0007

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-31: PORTB REGISTER MAP FOR dsPIC33EPXXGS504/505 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	0E10	TRISB<15:0>																FFFF
PORTB	0E12	RB<15:0>																xxxx
LATB	0E14	LATB<15:0>																xxxx
ODCB	0E16	ODCB<15:0>																0000
CNENB	0E18	CNIEB<15:0>																0000
CNPUB	0E1A	CNPUB<15:0>																0000
CNPDB	0E1C	CNPDB<15:0>																0000
ANSELB	0E1E	—	—	—	—	—	ANSB<10:9>		—	ANSB<7:5>			—	ANSB<3:0>				06EF

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-32: PORTC REGISTER MAP FOR dsPIC33EPXXGS504/505 DEVICES

SFR Name	Addr.	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
TRISC	0E20	—	—	TRISC<13:0>															3FFF
PORTC	0E22	—	—	RC<13:0>															xxxx
LATC	0E24	—	—	LATC<13:0>															xxxx
ODCC	0E26	—	—	ODCC<13:0>															0000
CNENC	0E28	—	—	CNIEC<13:0>															0000
CNPUC	0E2A	—	—	CNPUC<13:0>															0000
CNPDC	0E2C	—	—	CNPDC<13:0>															0000
ANSELC	0E2E	—	—	—	ANSC<12:9>				—	—	ANSC<6:4>			—	ANSC<2:0>			1E77	

Legend: x = unknown value on Reset; — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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When a PSV page overflow or underflow occurs, EA<15> is cleared as a result of the register indirect EA calculation. An overflow or underflow of the EA in the PSV pages can occur at the page boundaries when:

- The initial address, prior to modification, addresses the PSV page
- The EA calculation uses Pre- or Post-Modified Register Indirect Addressing; however, this does not include Register Offset Addressing

In general, when an overflow is detected, the DSRPAG register is incremented and the EA<15> bit is set to keep the base address within the PSV window. When an underflow is detected, the DSRPAG register is decremented and the EA<15> bit is set to keep the base

address within the PSV window. This creates a linear PSV address space, but only when using Register Indirect Addressing modes.

Exceptions to the operation described above arise when entering and exiting the boundaries of Page 0 and PSV spaces. Table 4-37 lists the effects of overflow and underflow scenarios at different boundaries.

In the following cases, when overflow or underflow occurs, the EA<15> bit is set and the DSRPAG is not modified; therefore, the EA will wrap to the beginning of the current page:

- Register Indirect with Register Offset Addressing
- Modulo Addressing
- Bit-Reversed Addressing

TABLE 4-37: OVERFLOW AND UNDERFLOW SCENARIOS AT PAGE 0 AND PSV SPACE BOUNDARIES^(2,3,4)

O/U, R/W	Operation	Before			After		
		DSxPAG	DS EA<15>	Page Description	DSxPAG	DS EA<15>	Page Description
O, Read	[++Wn] or [Wn++]	DSRPAG = 0x2FF	1	PSV: Last lsw page	DSRPAG = 0x300	1	PSV: First MSB page
O, Read		DSRPAG = 0x3FF	1	PSV: Last MSB page	DSRPAG = 0x3FF	0	See Note 1
U, Read	[--Wn] or [Wn--]	DSRPAG = 0x001	1	PSV page	DSRPAG = 0x001	0	See Note 1
U, Read		DSRPAG = 0x200	1	PSV: First lsw page	DSRPAG = 0x200	0	See Note 1
U, Read		DSRPAG = 0x300	1	PSV: First MSB page	DSRPAG = 0x2FF	1	PSV: Last lsw page

Legend: O = Overflow, U = Underflow, R = Read, W = Write

Note 1: The Register Indirect Addressing now addresses a location in the base Data Space (0x0000-0x7FFF).

2: An EDS access, with DSRPAG = 0x000, will generate an address error trap.

3: Only reads from PS are supported using DSRPAG.

4: Pseudolinear Addressing is not supported for large offsets.

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REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

bit 3	SLEEP: Wake-up from Sleep Flag bit 1 = Device has been in Sleep mode 0 = Device has not been in Sleep mode
bit 2	IDLE: Wake-up from Idle Flag bit 1 = Device has been in Idle mode 0 = Device has not been in Idle mode
bit 1	BOR: Brown-out Reset Flag bit 1 = A Brown-out Reset has occurred 0 = A Brown-out Reset has not occurred
bit 0	POR: Power-on Reset Flag bit 1 = A Power-on Reset has occurred 0 = A Power-on Reset has not occurred

Note 1: All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

2: If the WDTEN<1:0> Configuration bits are '11' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

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REGISTER 7-1: SR: CPU STATUS REGISTER⁽¹⁾

R/W-0	R/W-0	R/W-0	R/W-0	R/C-0	R/C-0	R-0	R/W-0
OA	OB	SA	SB	OAB	SAB	DA	DC
bit 15							bit 8

R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R/W-0 ⁽³⁾	R-0	R/W-0	R/W-0	R/W-0	R/W-0
IPL2 ⁽²⁾	IPL1 ⁽²⁾	IPL0 ⁽²⁾	RA	N	OV	Z	C
bit 7							bit 0

Legend:	C = Clearable bit
R = Readable bit	W = Writable bit
-n = Value at POR	'1' = Bit is set
	'0' = Bit is cleared
	x = Bit is unknown

bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits^(2,3)

111 = CPU Interrupt Priority Level is 7 (15); user interrupts are disabled
110 = CPU Interrupt Priority Level is 6 (14)
101 = CPU Interrupt Priority Level is 5 (13)
100 = CPU Interrupt Priority Level is 4 (12)
011 = CPU Interrupt Priority Level is 3 (11)
010 = CPU Interrupt Priority Level is 2 (10)
001 = CPU Interrupt Priority Level is 1 (9)
000 = CPU Interrupt Priority Level is 0 (8)

- Note 1:** For complete register details, see Register 3-1.
- 2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL, if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
- 3:** The IPL<2:0> Status bits are read-only when the NSTDIS bit (INTCON1<15>) = 1.

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REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)

bit 2	STKERR: Stack Error Trap Status bit 1 = Stack error trap has occurred 0 = Stack error trap has not occurred
bit 1	OSCFAIL: Oscillator Failure Trap Status bit 1 = Oscillator failure trap has occurred 0 = Oscillator failure trap has not occurred
bit 0	Unimplemented: Read as '0'

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REGISTER 8-2: CLKDIV: CLOCK DIVISOR REGISTER (CONTINUED)

bit 4-0 **PLLPRE<4:0>**: PLL Phase Detector Input Divider Select bits (also denoted as 'N1', PLL prescaler)
11111 = Input divided by 33
•
•
•
00001 = Input divided by 3
00000 = Input divided by 2 (default)

- Note 1:** The DOZE<2:0> bits can only be written to when the DOZEN bit is clear. If DOZEN = 1, any writes to DOZE<2:0> are ignored.
- 2:** This bit is cleared when the ROI bit is set and an interrupt occurs.
- 3:** The DOZEN bit cannot be set if DOZE<2:0> = 000. If DOZE<2:0> = 000, any attempt by user software to set the DOZEN bit is ignored.

REGISTER 8-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0
—	—	—	—	—	—	—	PLLDIV8
bit 15							bit 8

R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	R/W-0	R/W-0
PLLDIV<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown

bit 15-9 **Unimplemented:** Read as '0'

bit 8-0 **PLLDIV<8:0>**: PLL Feedback Divisor bits (also denoted as 'M', PLL multiplier)
111111111 = 513
•
•
•
000110000 = 50 (default)
•
•
•
000000010 = 4
000000001 = 3
000000000 = 2

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REGISTER 9-3: PMD3: PERIPHERAL MODULE DISABLE CONTROL REGISTER 3

U-0	U-0	U-0	U-0	U-0	R/W-0	U-0	U-0
—	—	—	—	—	CMPMD	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	U-0
—	—	—	—	—	—	I2C2MD	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-11 **Unimplemented:** Read as '0'
- bit 10 **CMPMD:** Comparator Module Disable bit
1 = Comparator module is disabled
0 = Comparator module is enabled
- bit 9-2 **Unimplemented:** Read as '0'
- bit 1 **I2C2MD:** I2C2 Module Disable bit
1 = I2C2 module is disabled
0 = I2C2 module is enabled
- bit 0 **Unimplemented:** Read as '0'

REGISTER 9-4: PMD4: PERIPHERAL MODULE DISABLE CONTROL REGISTER 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/W-0	U-0	U-0	U-0
—	—	—	—	REFOMD	—	—	—
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-4 **Unimplemented:** Read as '0'
- bit 3 **REFOMD:** Reference Clock Module Disable bit
1 = Reference clock module is disabled
0 = Reference clock module is enabled
- bit 2-0 **Unimplemented:** Read as '0'

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10.4.5 OUTPUT MAPPING

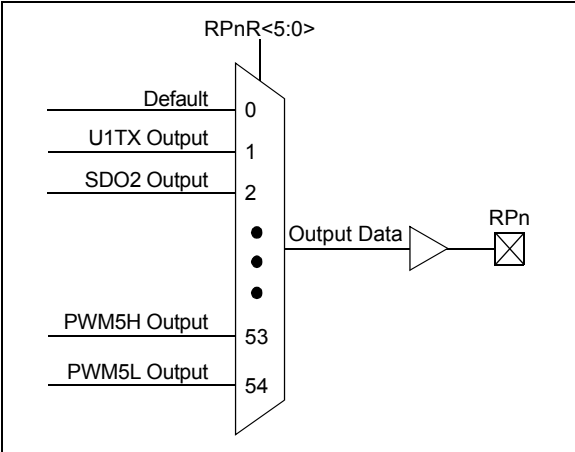
In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Each register contains sets of 6-bit fields, with each set associated with one RPn pin (see Register 10-20 through Register 10-38). The value of the bit field corresponds to one of the peripherals and that peripheral's output is mapped to the pin (see Table 10-2 and Figure 10-3).

A null output is associated with the output register Reset value of '0'. This is done to ensure that remappable outputs remain disconnected from all output pins by default.

10.4.5.1 Mapping Limitations

The control schema of the peripheral select pins is not limited to a small range of fixed peripheral configurations. There are no mutual or hardware-enforced lockouts between any of the peripheral mapping SFRs. Literally any combination of peripheral mappings, across any or all of the RPn pins, is possible. This includes both many-to-one and one-to-many mappings of peripheral inputs, and outputs to pins. While such mappings may be technically possible from a configuration point of view, they may not be supportable from an electrical point of view.

FIGURE 10-3: MULTIPLEXING REMAPPABLE OUTPUTS FOR RPn



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REGISTER 10-14: RPNR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SCK2INR7	SCK2INR6	SCK2INR5	SCK2INR4	SCK2INR3	SCK2INR2	SCK2INR1	SCK2INR0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
SDI2R7	SDI2R6	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **SCK2INR<7:0>**: Assign SPI2 Clock Input (SCK2) to the Corresponding RPn Pin bits

10110101 = Input tied to RP181

10110100 = Input tied to RP180

•

•

•

00000001 = Input tied to RP1

00000000 = Input tied to Vss

bit 7-0 **SDI2R<7:0>**: Assign SPI2 Data Input (SDI2) to the Corresponding RPn Pin bits

10110101 = Input tied to RP181

10110100 = Input tied to RP180

•

•

•

00000001 = Input tied to RP1

00000000 = Input tied to Vss

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REGISTER 10-20: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP33R5	RP33R4	RP33R3	RP33R2	RP33R1	RP33R0
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP32R5	RP32R4	RP32R3	RP32R2	RP32R1	RP32R0
bit 7						bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP33R<5:0>:** Peripheral Output Function is Assigned to RP33 Output Pin bits
 (see Table 10-2 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP32R<5:0>:** Peripheral Output Function is Assigned to RP32 Output Pin bits
 (see Table 10-2 for peripheral function numbers)

REGISTER 10-21: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP35R5	RP35R4	RP35R3	RP35R2	RP35R1	RP35R0
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP34R5	RP34R4	RP34R3	RP34R2	RP34R1	RP34R0
bit 7						bit 0	

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'
 -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

- bit 15-14 **Unimplemented:** Read as '0'
- bit 13-8 **RP35R<5:0>:** Peripheral Output Function is Assigned to RP35 Output Pin bits
 (see Table 10-2 for peripheral function numbers)
- bit 7-6 **Unimplemented:** Read as '0'
- bit 5-0 **RP34R<5:0>:** Peripheral Output Function is Assigned to RP34 Output Pin bits
 (see Table 10-2 for peripheral function numbers)

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NOTES:

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REGISTER 15-12: PWMCONx: PWMx CONTROL REGISTER (x = 1 to 5) (CONTINUED)

bit 7-6	DTC<1:0> : Dead-Time Control bits 11 = Reserved 10 = Dead-time function is disabled 01 = Negative dead time is actively applied for Complementary Output mode 00 = Positive dead time is actively applied for all Output modes
bit 5-4	Unimplemented : Read as '0'
bit 3	MTBS : Master Time Base Select bit 1 = PWMx generator uses the secondary master time base for synchronization and the clock source for the PWMx generation logic (if secondary time base is available) 0 = PWMx generator uses the primary master time base for synchronization and the clock source for the PWMx generation logic
bit 2	CAM : Center-Aligned Mode Enable bit ^(2,3,4) 1 = Center-Aligned mode is enabled 0 = Edge-Aligned mode is enabled
bit 1	XPRES : External PWMx Reset Control bit ⁽⁵⁾ 1 = Current-limit source resets the time base for this PWMx generator if it is in Independent Time Base mode 0 = External pins do not affect the PWMx time base
bit 0	IUE : Immediate Update Enable bit 1 = Updates to the active Duty Cycle, Phase Offset, Dead-Time and local Time Base Period registers are immediate 0 = Updates to the active Duty Cycle, Phase Offset, Dead-Time and local Time Base Period registers are synchronized to the local PWMx time base

- Note 1:** Software must clear the interrupt status here and in the corresponding IFSx bit in the interrupt controller.
- 2:** The Independent Time Base mode (ITB = 1) must be enabled to use Center-Aligned mode. If ITB = 0, the CAM bit is ignored.
- 3:** These bits should not be changed after the PWMx is enabled by setting PTEN = 1 (PTCON<15>).
- 4:** Center-Aligned mode ignores the Least Significant 3 bits of the Duty Cycle, Phase and Dead-Time registers. The highest Center-Aligned mode resolution available is 8.32 ns with the clock prescaler set to the fastest clock.
- 5:** Configure CLMOD = 0 (FCLCONx<8>) and ITB = 1 (PWMCONx<9>) to operate in External Period Reset mode.

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REGISTER 15-24: LEBCONx: PWMx LEADING-EDGE BLANKING (LEB) CONTROL REGISTER (x = 1 to 5)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
PHR	PHF	PLR	PLF	FLTLEBEN	CLLEBEN	—	—
bit 15						bit 8	

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	BCH ⁽¹⁾	BCL ⁽¹⁾	BPHH	BPHL	BPLH	BPLL
bit 7						bit 0	

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15 **PHR:** PWMxH Rising Edge Trigger Enable bit
1 = Rising edge of PWMxH will trigger the Leading-Edge Blanking counter
0 = Leading-Edge Blanking ignores the rising edge of PWMxH
- bit 14 **PHF:** PWMxH Falling Edge Trigger Enable bit
1 = Falling edge of PWMxH will trigger the Leading-Edge Blanking counter
0 = Leading-Edge Blanking ignores the falling edge of PWMxH
- bit 13 **PLR:** PWMxL Rising Edge Trigger Enable bit
1 = Rising edge of PWMxL will trigger the Leading-Edge Blanking counter
0 = Leading-Edge Blanking ignores the rising edge of PWMxL
- bit 12 **PLF:** PWMxL Falling Edge Trigger Enable bit
1 = Falling edge of PWMxL will trigger the Leading-Edge Blanking counter
0 = Leading-Edge Blanking ignores the falling edge of PWMxL
- bit 11 **FLTLEBEN:** Fault Input Leading-Edge Blanking Enable bit
1 = Leading-Edge Blanking is applied to the selected Fault input
0 = Leading-Edge Blanking is not applied to the selected Fault input
- bit 10 **CLLEBEN:** Current-Limit Leading-Edge Blanking Enable bit
1 = Leading-Edge Blanking is applied to the selected current-limit input
0 = Leading-Edge Blanking is not applied to the selected current-limit input
- bit 9-6 **Unimplemented:** Read as '0'
- bit 5 **BCH:** Blanking in Selected Blanking Signal High Enable bit⁽¹⁾
1 = State blanking (of current-limit and/or Fault input signals) when the selected blanking signal is high
0 = No blanking when the selected blanking signal is high
- bit 4 **BCL:** Blanking in Selected Blanking Signal Low Enable bit⁽¹⁾
1 = State blanking (of current-limit and/or Fault input signals) when the selected blanking signal is low
0 = No blanking when the selected blanking signal is low
- bit 3 **BPHH:** Blanking in PWMxH High Enable bit
1 = State blanking (of current-limit and/or Fault input signals) when the PWMxH output is high
0 = No blanking when the PWMxH output is high
- bit 2 **BPHL:** Blanking in PWMxH Low Enable bit
1 = State blanking (of current-limit and/or Fault input signals) when the PWMxH output is low
0 = No blanking when the PWMxH output is low

Note 1: The blanking signal is selected via the BLANKSEL<3:0> bits in the AUXCONx register.

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22.3 Current Source Control Register

REGISTER 22-1: ISRCCON: CONSTANT-CURRENT SOURCE CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
ISRCEN	—	—	—	—	OUTSEL2	OUTSEL1	OUTSEL0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	ISRCCAL5	ISRCCAL4	ISRCCAL3	ISRCCAL2	ISRCCAL1	ISRCCAL0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15 **ISRCEN:** Constant-Current Source Enable bit

1 = Current source is enabled

0 = Current source is disabled

bit 14-11 **Unimplemented:** Read as '0'

bit 10-8 **OUTSEL<2:0>:** Output Constant-Current Select bits

111 = Reserved

110 = Reserved

101 = Reserved

100 = Input pin, ISRC4 (AN4)

011 = Input pin, ISRC3 (AN5)

010 = Input pin, ISRC2 (AN6)

001 = Input pin, ISRC1 (AN12)

000 = No output is selected

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **ISRCCAL<5:0>:** Constant-Current Source Calibration bits

The calibration value must be copied from Flash address, 0x800E78, into these bits before the module is enabled. Refer to the calibration data address table (Table 23-3) in **Section 23.0 “Special Features”** for more information.

25.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
 - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB XC Compiler
 - MPASM™ Assembler
 - MPLINK™ Object Linker/
MPLIB™ Object Librarian
 - MPLAB Assembler/Linker/Librarian for
Various Device Families
- Simulators
 - MPLAB X SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
 - MPLAB ICD 3
 - PICKit™ 3
- Device Programmers
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards,
Evaluation Kits and Starter Kits
- Third-party development tools

25.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

- Local file history feature
- Built-in support for Bugzilla issue tracker

dsPIC33EPXXGS50X FAMILY

TABLE 26-44: ANALOG-TO-DIGITAL CONVERSION TIMING REQUIREMENTS

AC CHARACTERISTICS ⁽²⁾			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristics	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions
Clock Parameters							
AD50	TAD	ADC Clock Period	14.28	—	—	ns	
Throughput Rate							
AD51	FTP	SH0-SH3	—	—	3.25	Msp/s	70 MHz ADC clock, 12 bits, no pending conversion at time of trigger
		SH4	—	—	3.25	Msp/s	

Note 1: These parameters are characterized but not tested in manufacturing.

2: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is ensured, but not characterized.

TABLE 26-45: HIGH-SPEED ANALOG COMPARATOR MODULE SPECIFICATIONS

AC/DC CHARACTERISTICS ⁽²⁾			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Comments
CM10	VIOFF	Input Offset Voltage	-35	±5	+35	mV	
CM11	VICM	Input Common-Mode Voltage Range ⁽¹⁾	0	—	AVDD	V	
CM13	CMRR	Common-Mode Rejection Ratio	60	—	—	dB	
CM14	TRESP	Large Signal Response	—	15	—	ns	V+ input step of 100 mV while V- input is held at AVDD/2. Delay measured from analog input pin to PWMx output pin.
CM15	VHYST	Input Hysteresis	5	10	20	mV	Depends on HYSSEL<1:0>
CM16	TON	Comparator Enabled to Valid Output	—	—	1	μs	

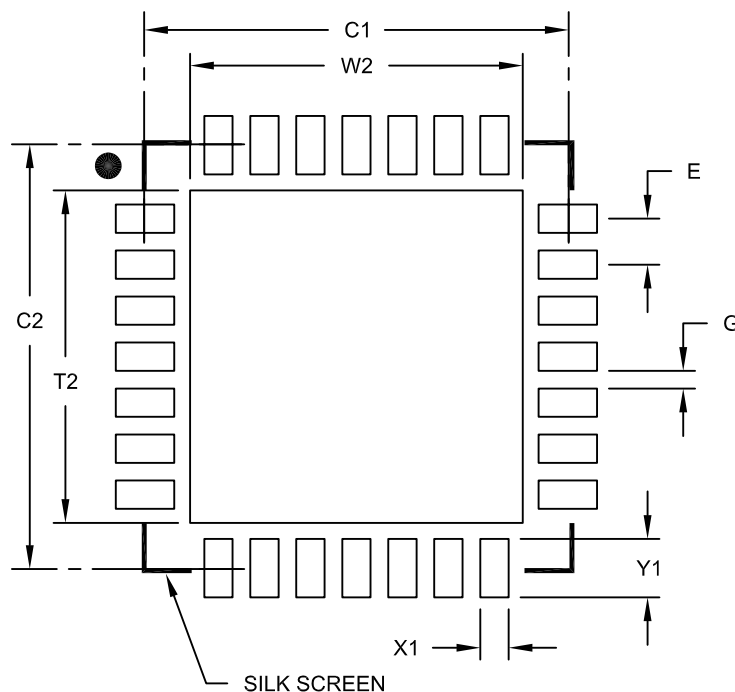
Note 1: These parameters are for design guidance only and are not tested in manufacturing.

2: The comparator module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

dsPIC33EPXXGS50X FAMILY

28-Lead Plastic Quad Flat, No Lead Package (MM) – 6x6x0.9 mm Body [QFN-S] with 0.40 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Optional Center Pad Width	W2			4.70
Optional Center Pad Length	T2			4.70
Contact Pad Spacing	C1		6.00	
Contact Pad Spacing	C2		6.00	
Contact Pad Width (X28)	X1			0.40
Contact Pad Length (X28)	Y1			0.85
Distance Between Pads	G	0.25		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2124A

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