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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

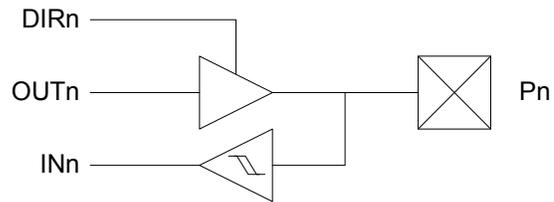
Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	50
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d3-au">https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d3-au</a>

## 14.3 Output Driver

All port pins ( $P_n$ ) have programmable output configuration.

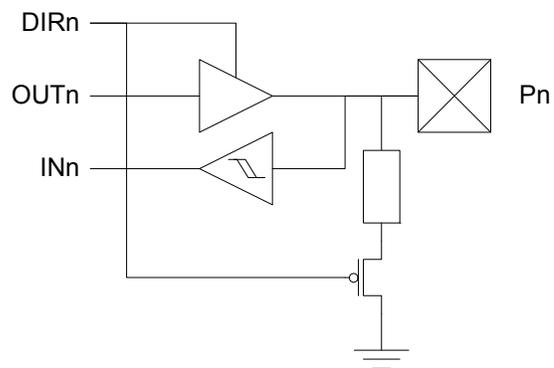
### 14.3.1 Push-pull

Figure 14-1. I/O Configuration - Totem-pole



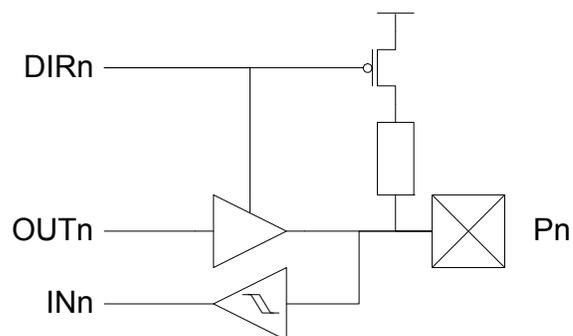
### 14.3.2 Pull-down

Figure 14-2. I/O Configuration - Totem-pole with Pull-down (on input)



### 14.3.3 Pull-up

Figure 14-3. I/O Configuration - Totem-pole with Pull-up (on input)



## 28. Pinout and Pin Functions

The device pinout is shown in “[Pinout/block Diagram](#)” on page 5. In addition to general purpose I/O functionality, each pin can have several alternate functions. This will depend on which peripheral is enabled and connected to the actual pin. Only one of the pin functions can be used at time.

### 28.1 Alternate Pin Function Description

The tables below show the notation for all pin functions available and describe its function.

#### 28.1.1 Operation/power Supply

$V_{CC}$	Digital supply voltage
$AV_{CC}$	Analog supply voltage
GND	Ground

#### 28.1.2 Port Interrupt Functions

SYNC	Port pin with full synchronous and limited asynchronous interrupt function
ASYNC	Port pin with full synchronous and full asynchronous interrupt function

#### 28.1.3 Analog Functions

ACn	Analog comparator input pin n
ACnOUT	Analog comparator n output
ADCn	Analog to digital converter input pin n
$A_{REF}$	Analog reference input pin

#### 28.1.4 Timer/counter and AWEX Functions

OCnxLS	Output compare channel x low side for Timer/Counter n
OCnxHS	Output compare channel x high side for Timer/Counter n

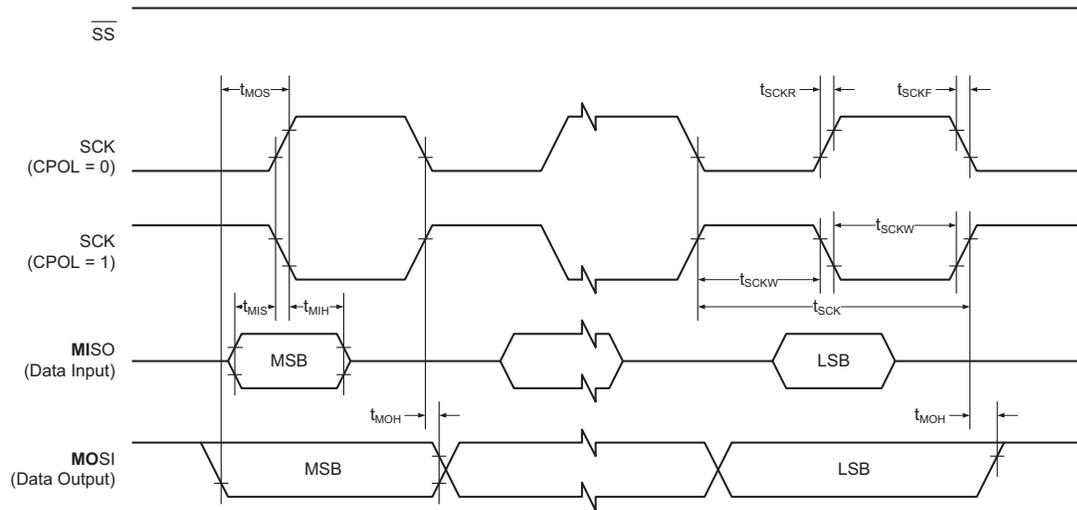
**Table 32-10. Accuracy Characteristics**

Symbol	Parameter	Condition <sup>(2)</sup>		Min.	Typ.	Max.	Units
RES	Resolution	12-bit resolution	Differential	8	12	12	Bits
			Single ended signed	7	11	11	
			Single ended unsigned	8	12	12	
INL <sup>(1)</sup>	Integral non-linearity	Differential mode	16ksps, V <sub>REF</sub> = 3V		0.5	1	lsb
			16ksps, all V <sub>REF</sub>		0.8	2	
			300ksps, V <sub>REF</sub> = 3V		0.6	1	
			300ksps, all V <sub>REF</sub>		1	2	
		Single ended unsigned mode	16ksps, V <sub>REF</sub> = 3.0V		0.5	1	
			16ksps, all V <sub>REF</sub>		1.3	2	
DNL <sup>(1)</sup>	Differential non-linearity	Differential mode	16ksps, V <sub>REF</sub> = 3V		0.3	1	lsb
			16ksps, all V <sub>REF</sub>		0.5	1	
			300ksps, V <sub>REF</sub> = 3V		0.3	1	
			300ksps, all V <sub>REF</sub>		0.5	1	
		Single ended unsigned mode	16ksps, V <sub>REF</sub> = 3V		0.6	1	
			16ksps, all V <sub>REF</sub>		0.6	1	
	Offset error	Differential mode	300ksps, V <sub>REF</sub> = 3V		-7		mV
			Temperature drift, V <sub>REF</sub> = 3V		0.01		mV/K
			Operating voltage drift		0.16		mV/V
	Gain error	Differential mode	External reference		-5		mV
			AV <sub>CC</sub> /1.6		-5		
			AV <sub>CC</sub> /2.0		-6		
			Bandgap		±10		
			Temperature drift		0.02		mV/K
			Operating voltage drift		2		mV/V
	Gain error	Single ended unsigned mode	External reference		-8		mV
			AV <sub>CC</sub> /1.6		-8		
			AV <sub>CC</sub> /2.0		-8		
			Bandgap		±10		
			Temperature drift		0.03		mV/K
			Operating voltage drift		2		mV/V

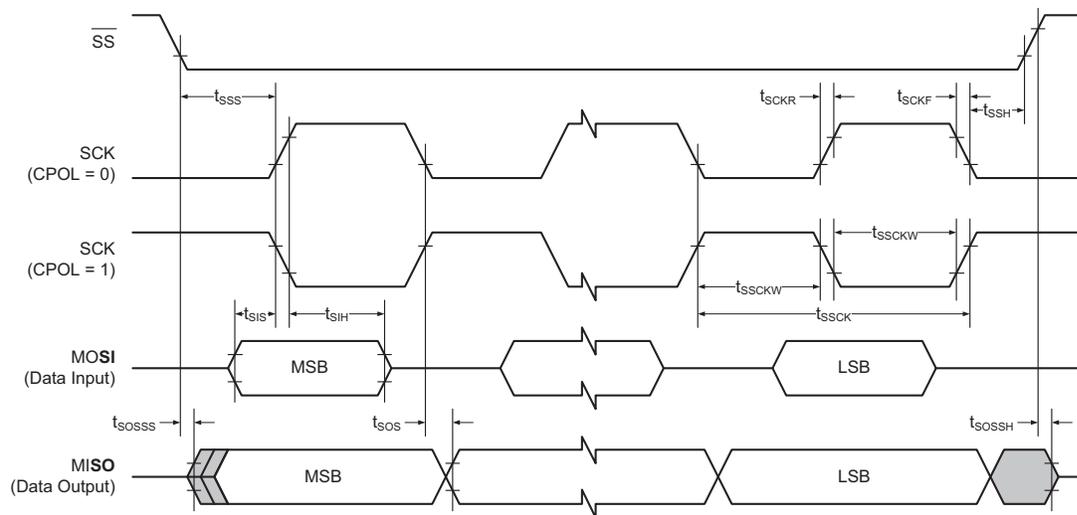
- Notes: 1. Maximum numbers are based on characterisation and not tested in production, and valid for 5% to 95% input voltage range.  
 2. Unless otherwise noted all linearity, offset and gain error numbers are valid under the condition that external VREF is used.

### 32.1.14 SPI Characteristics

**Figure 32-5. SPI Timing Requirements in Master Mode**



**Figure 32-6. SPI Timing Requirements in Slave Mode**



**Table 32-34. Current Consumption for Modules and Peripherals**

Symbol	Parameter	Condition <sup>(1)</sup>	Min.	Typ.	Max.	Units	
I <sub>CC</sub>	ULP oscillator			0.9		μA	
	32.768kHz int. oscillator			29			
	2MHz int. oscillator			82			
		DFLL enabled with 32.768kHz int. osc. as reference			114		
	32MHz int. oscillator			250			
		DFLL enabled with 32.768kHz int. osc. as reference			400		
	PLL	20× multiplication factor, 32MHz int. osc. DIV4 as reference			300		
	Watchdog timer				1.0		
	BOD	Continuous mode			140		
		Sampled mode, includes ULP oscillator			1.4		
Internal 1.0V reference				180			
Temperature sensor				175			
ADC	16ksps V <sub>REF</sub> = Ext. ref.			1.23		mA	
		CURRLIMIT = LOW		1.1			
		CURRLIMIT = MEDIUM		0.98			
		CURRLIMIT = HIGH		0.87			
	75ksps V <sub>REF</sub> = Ext. ref.	CURRLIMIT = LOW		1.7			
300ksps V <sub>REF</sub> = Ext. ref.			3.1				
USART	Rx and Tx enabled, 9600 BAUD			9.7		μA	
Flash memory and EEPROM programming				5		mA	

Note: 1. All parameters measured as the difference in current consumption between module enabled and disabled. All data at V<sub>CC</sub> = 3.0V, CLK<sub>SYS</sub> = 1MHz external clock without prescaling, T = 25°C unless other conditions are given.

**Table 32-68. Accuracy Characteristics**

Symbol	Parameter	Condition <sup>(2)</sup>		Min.	Typ.	Max.	Units
RES	Resolution	12-bit resolution	Differential	8	12	12	Bits
			Single ended signed	7	11	11	
			Single ended unsigned	8	12	12	
INL <sup>(1)</sup>	Integral non-linearity	Differential mode	16ksps, V <sub>REF</sub> = 3V		0.5	1	lsb
			16ksps, all V <sub>REF</sub>		0.8	2	
			300ksps, V <sub>REF</sub> = 3V		0.6	1	
			300ksps, all V <sub>REF</sub>		1.0	2	
		Single ended unsigned mode	16ksps, V <sub>REF</sub> = 3.0V		0.5	1	
			16ksps, all V <sub>REF</sub>		1.3	2	
DNL <sup>(1)</sup>	Differential non-linearity	Differential mode	16ksps, V <sub>REF</sub> = 3V		0.3	1	lsb
			16ksps, all V <sub>REF</sub>		0.5	1	
			300ksps, V <sub>REF</sub> = 3V		0.3	1	
			300ksps, all V <sub>REF</sub>		0.5	1	
		Single ended unsigned mode	16ksps, V <sub>REF</sub> = 3.0V		0.6	1	
			16ksps, all V <sub>REF</sub>		0.6	1	
	Offset error	Differential mode	300ksps, V <sub>REF</sub> = 3V		-7		mV
			Temperature drift, V <sub>REF</sub> = 3V		0.01		mV/K
			Operating voltage drift		0.16		mV/V
	Gain error	Differential mode	External reference		-5		mV
			AV <sub>CC</sub> /1.6		-5		
			AV <sub>CC</sub> /2.0		-6		
			Bandgap		±10		
			Temperature drift		0.02		mV/K
			Operating voltage drift		2		mV/V
	Gain error	Single ended unsigned mode	External reference		-8		mV
			AV <sub>CC</sub> /1.6		-8		
			AV <sub>CC</sub> /2.0		-8		
			Bandgap		±10		
			Temperature drift		0.03		mV/K
			Operating voltage drift		2		mV/V

Notes: 1. Maximum numbers are based on characterization and not tested in production and valid for 5% to 95% input voltage range.  
 2. Unless otherwise noted all linearity, offset and gain error numbers are valid under the condition that external V<sub>REF</sub> is used.

### 32.3.14 SPI Characteristics

Figure 32-19. SPI Timing Requirements in Master Mode

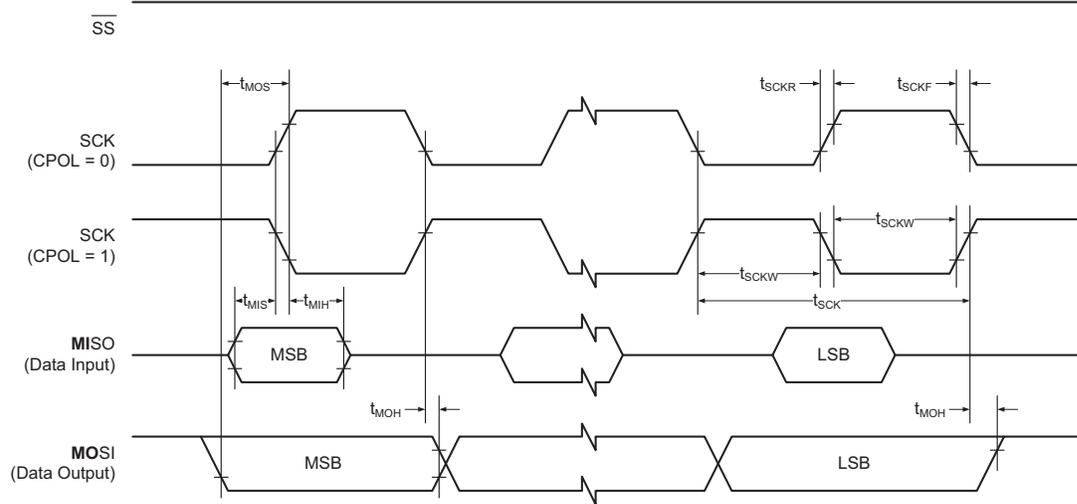
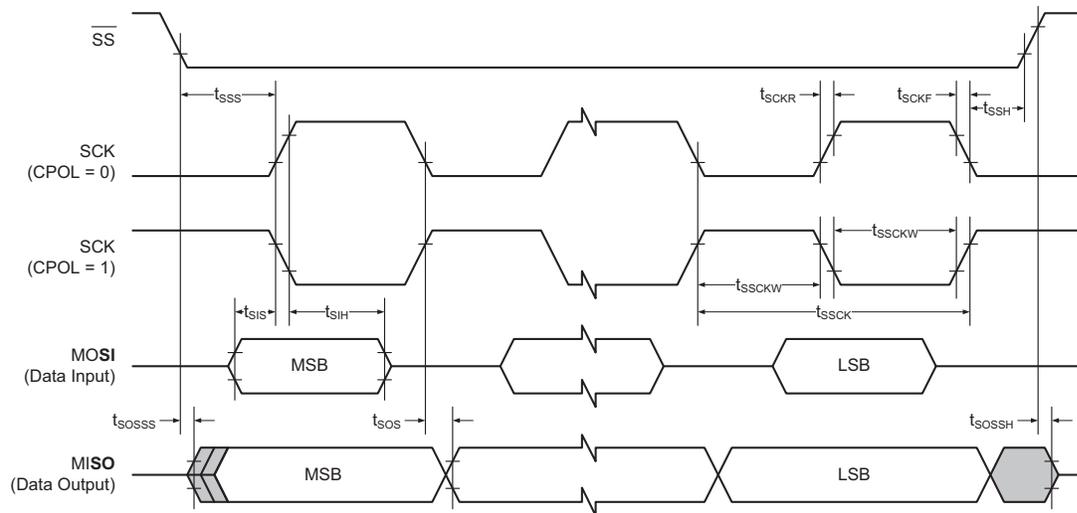


Figure 32-20. SPI Timing Requirements in Slave Mode



Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$C_{XTAL1}$	Parasitic capacitance XTAL1 pin			5.9		pF
$C_{XTAL2}$	Parasitic capacitance XTAL2 pin			8.3		
$C_{LOAD}$	Parasitic capacitance load			3.5		

Notes: 1. Numbers for negative impedance are not tested in production but guaranteed from design and characterization.

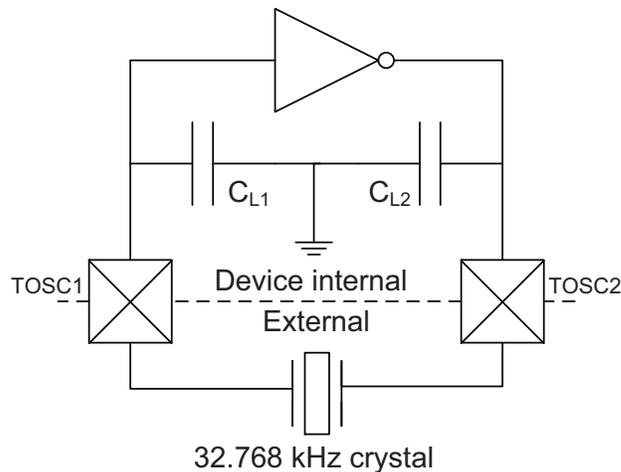
### 32.4.13.8 External 32.768kHz Crystal Oscillator and TOSC Characteristics

**Table 32-114. External 32.768kHz Crystal Oscillator and TOSC Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
ESR/R1	Recommended crystal equivalent series resistance (ESR)	Crystal load capacitance 6.5pF			60	k $\Omega$
		Crystal load capacitance 9.0pF			35	
		Crystal load capacitance 12pF			28	
$C_{TOSC1}$	Parasitic capacitance TOSC1 pin			3.5		pF
$C_{TOSC2}$	Parasitic capacitance TOSC2 pin			3.5		
	Recommended safety factor	Capacitance load matched to crystal specification	3			

Note: See [Figure 32-25](#) for definition.

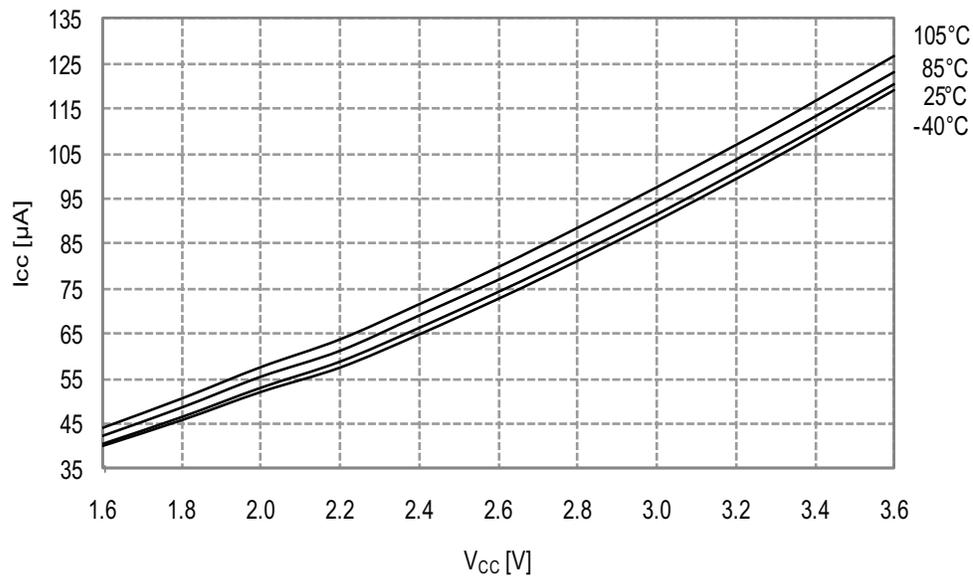
**Figure 32-25. TOSC Input Capacitance**



The parasitic capacitance between the TOSC pins is  $C_{L1} + C_{L2}$  in series as seen from the crystal when oscillating without external capacitors.

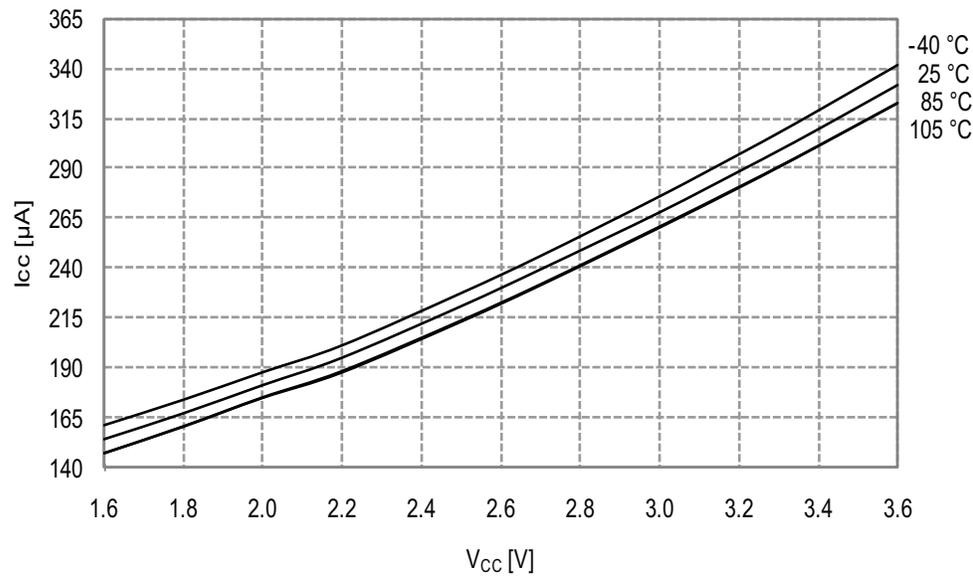
**Figure 33-82. Idle Mode Supply Current vs.  $V_{CC}$**

$f_{SYS} = 1\text{MHz external clock}$



**Figure 33-83. Idle Mode Supply Current vs.  $V_{CC}$**

$f_{SYS} = 2\text{MHz internal oscillator}$



## 33.2.2 I/O Pin Characteristics

### 33.2.2.1 Pull-up

Figure 33-90. I/O Pin Pull-up Resistor Current vs. Input Voltage

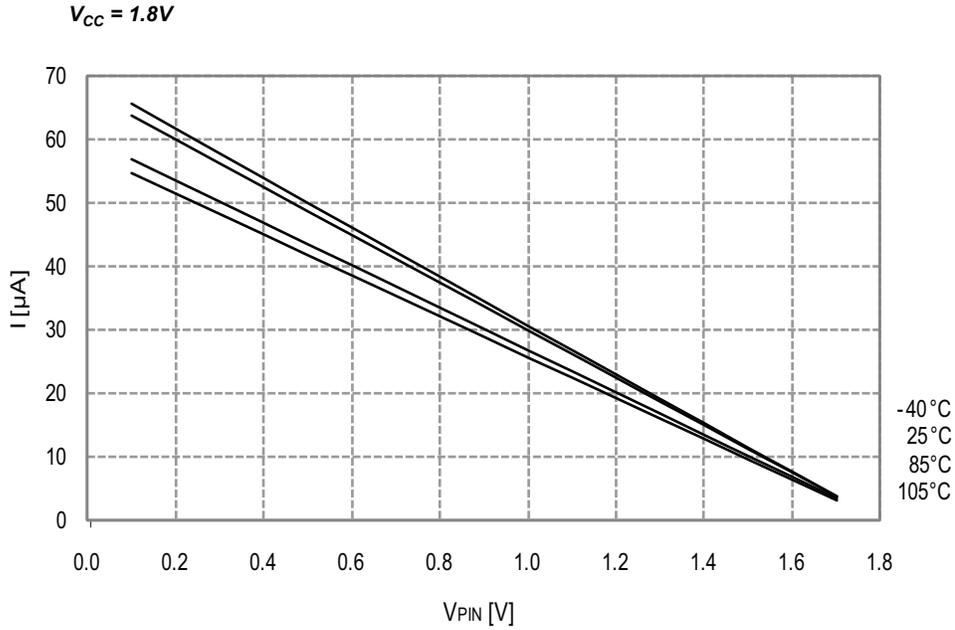
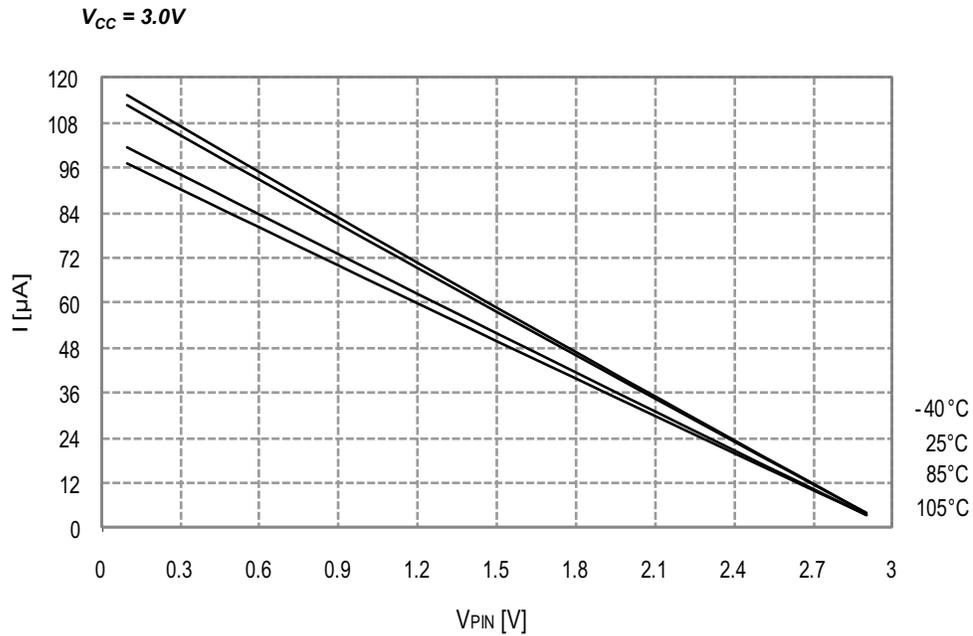
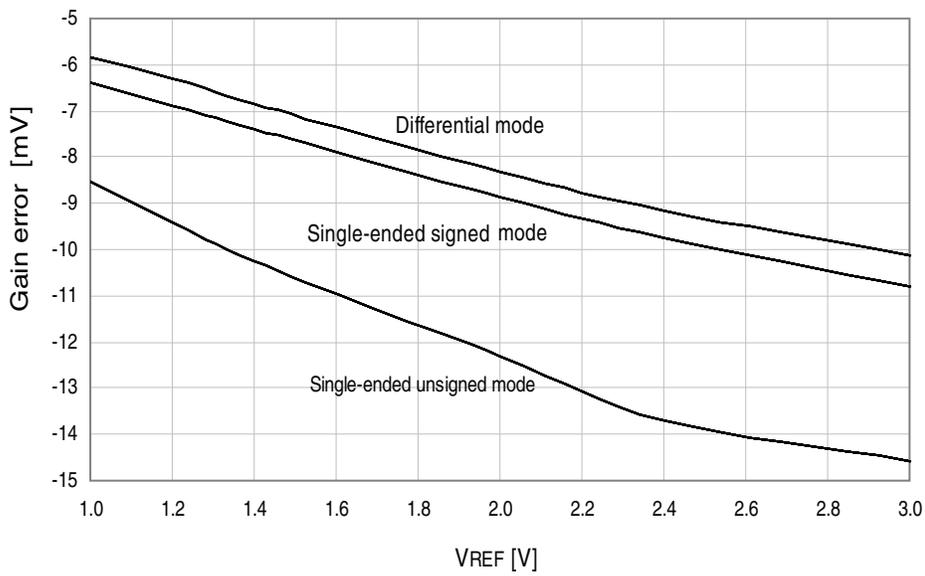


Figure 33-91. I/O Pin Pull-up Resistor Current vs. Input Voltage



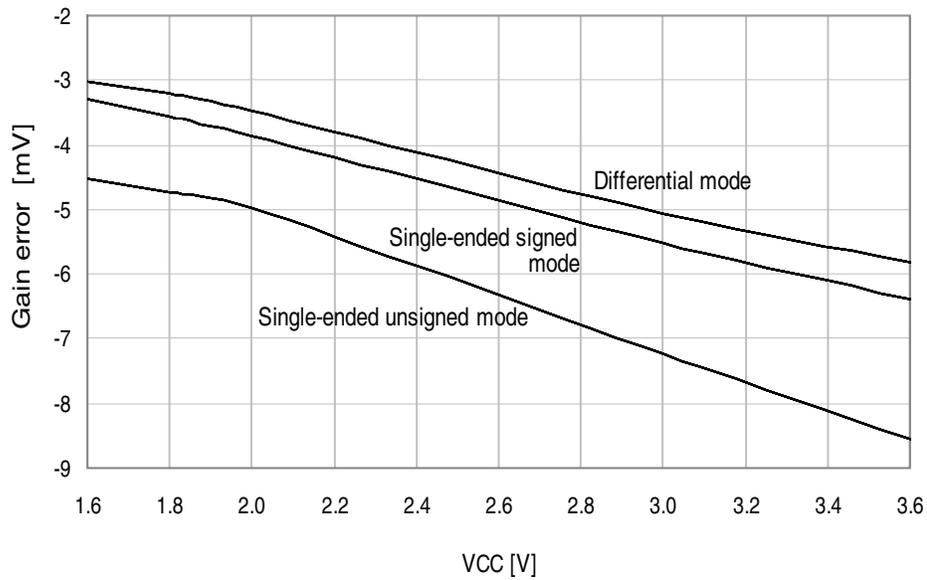
**Figure 33-108. Gain Error vs.  $V_{REF}$**

$T = 25^{\circ}\text{C}$ ,  $V_{CC} = 3.6\text{V}$ ,  $\text{ADC sample rate} = 300\text{kpsps}$



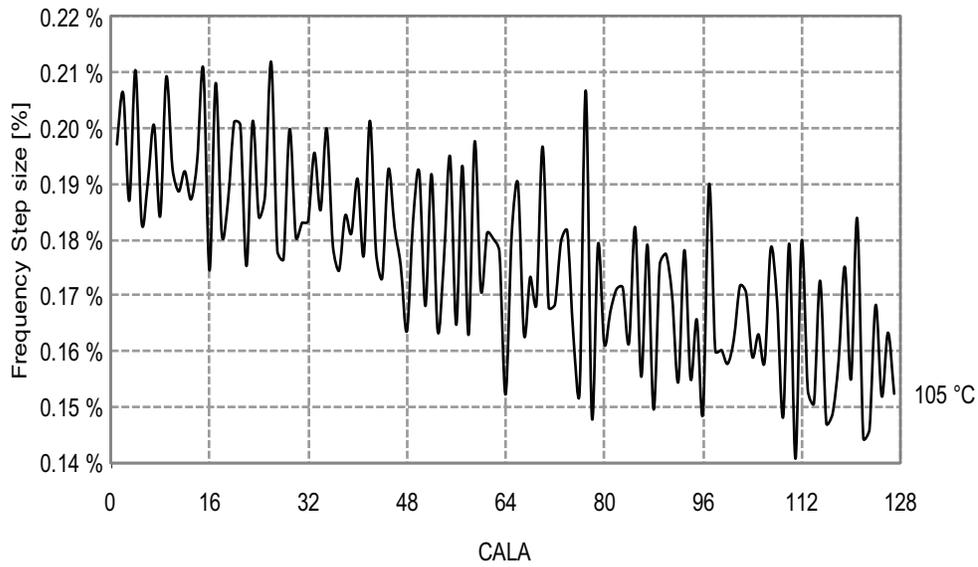
**Figure 33-109. Gain Error vs.  $V_{CC}$**

$T = 25^{\circ}\text{C}$ ,  $V_{REF} = \text{external } 1.0\text{V}$ ,  $\text{ADC sample rate} = 300\text{kpsps}$



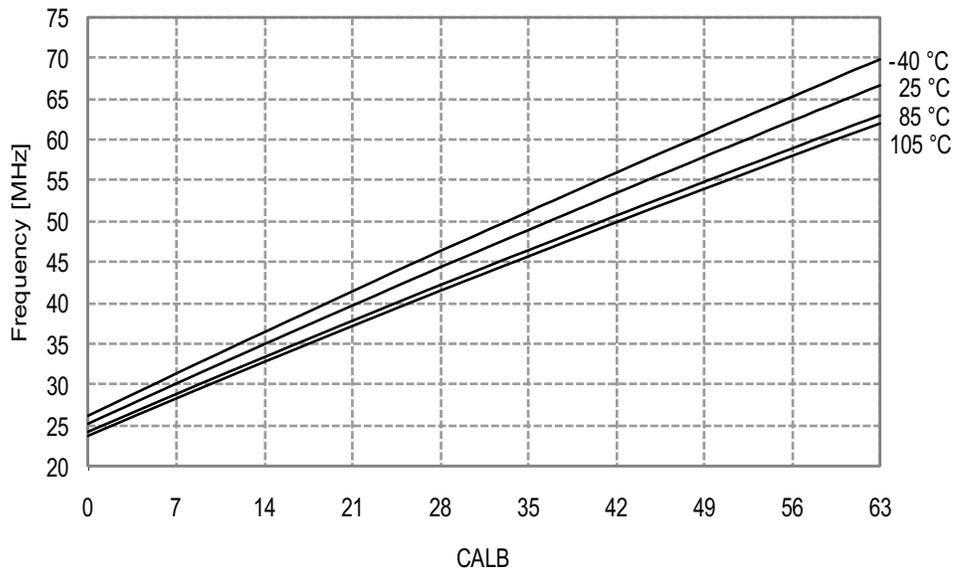
**Figure 33-136. 32MHz Internal Oscillator CALA Calibration Step Size**

$T = 105^{\circ}\text{C}$ ,  $V_{CC} = 3.0\text{V}$

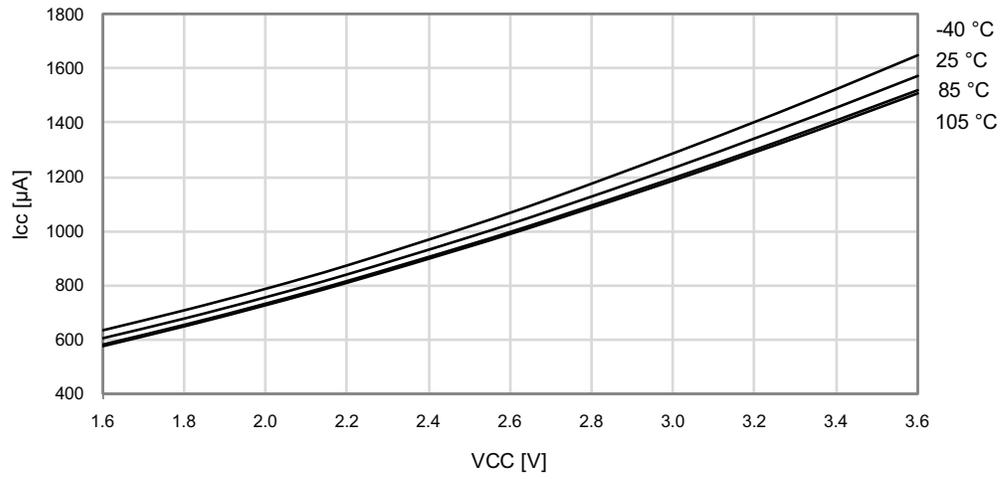


**Figure 33-137. 32MHz Internal Oscillator Frequency vs. CALB Calibration Value**

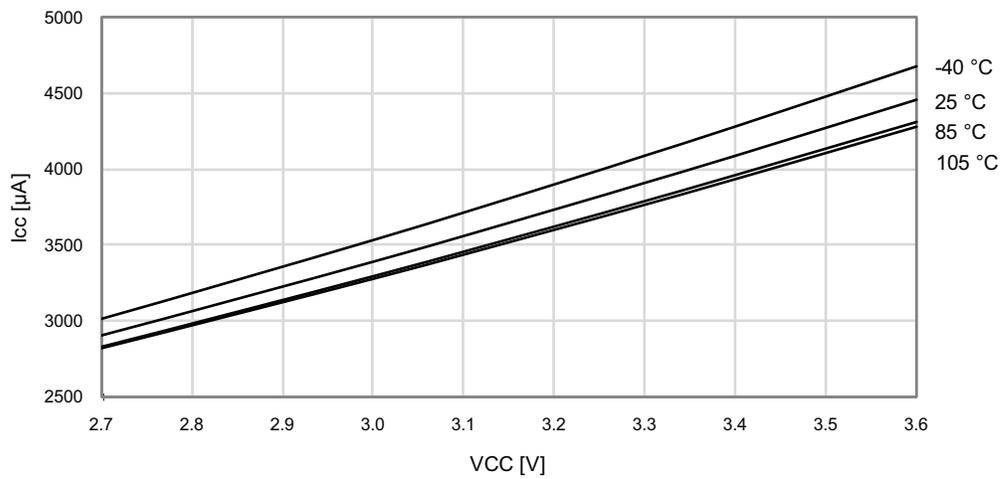
$V_{CC} = 3.0\text{V}$



**Figure 33-155. Idle Mode Supply Current vs.  $V_{CC}$**   
 $f_{SYS} = 32\text{MHz}$  internal oscillator prescaled to 8MHz



**Figure 33-156. Idle Mode Current vs.  $V_{CC}$**   
 $f_{SYS} = 32\text{MHz}$  internal oscillator



## 33.4 Atmel ATxmega192D3

### 33.4.1 Current Consumption

#### 33.4.1.1 Active Mode Supply Current

Figure 33-213. Active Supply Current vs. Frequency

$f_{SYS} = 0 - 1\text{MHz}$  external clock,  $T = 25^\circ\text{C}$

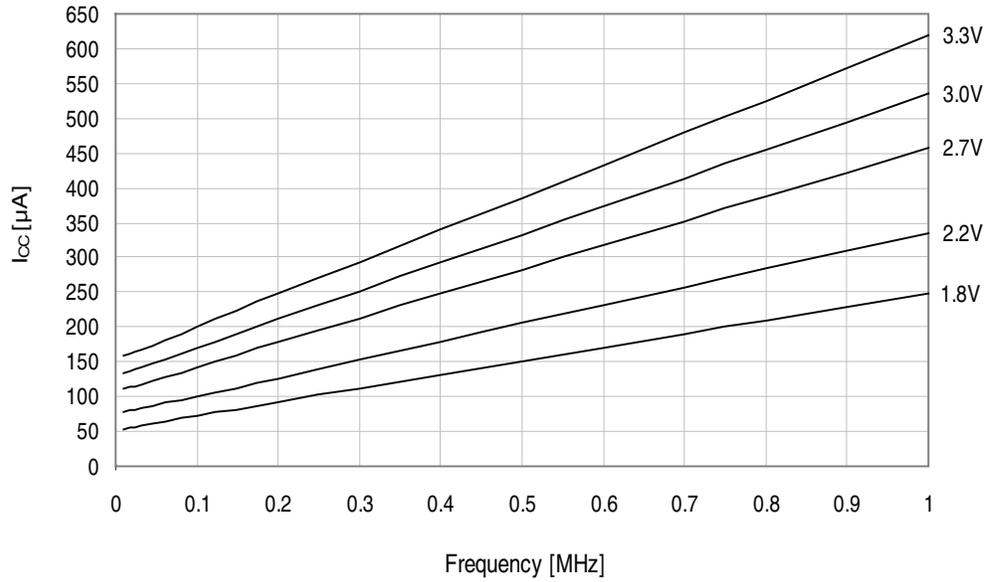
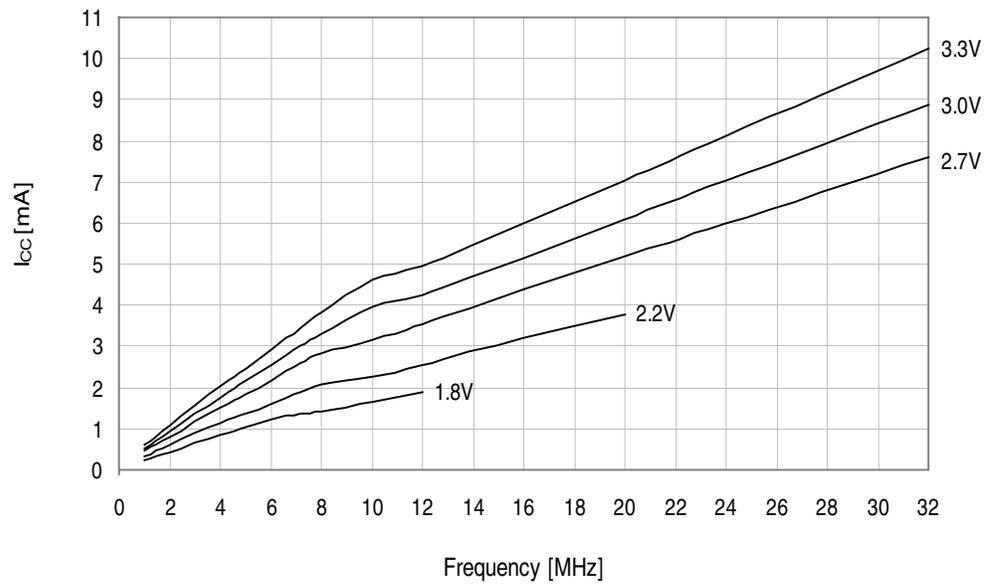


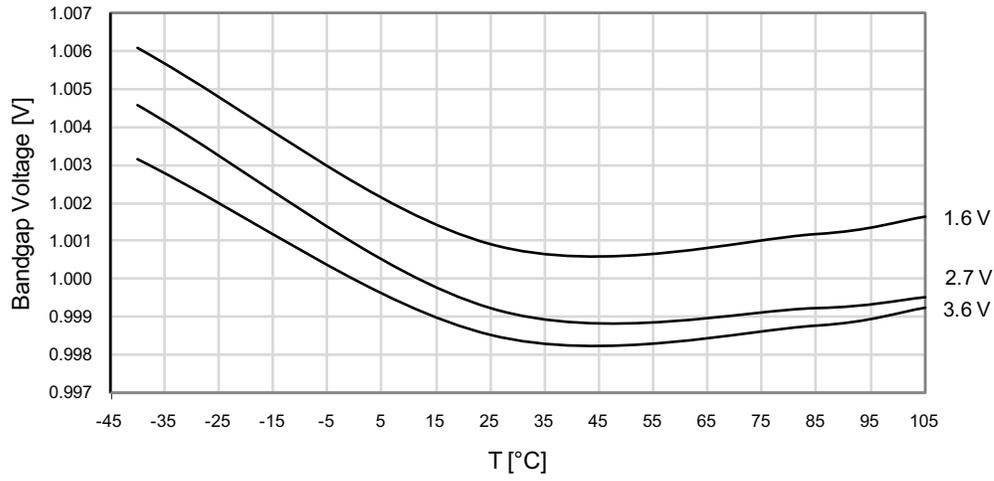
Figure 33-214. Active Supply Current vs. Frequency

$f_{SYS} = 1 - 32\text{MHz}$  external clock,  $T = 25^\circ\text{C}$



### 33.4.5 Internal 1.0V Reference Characteristics

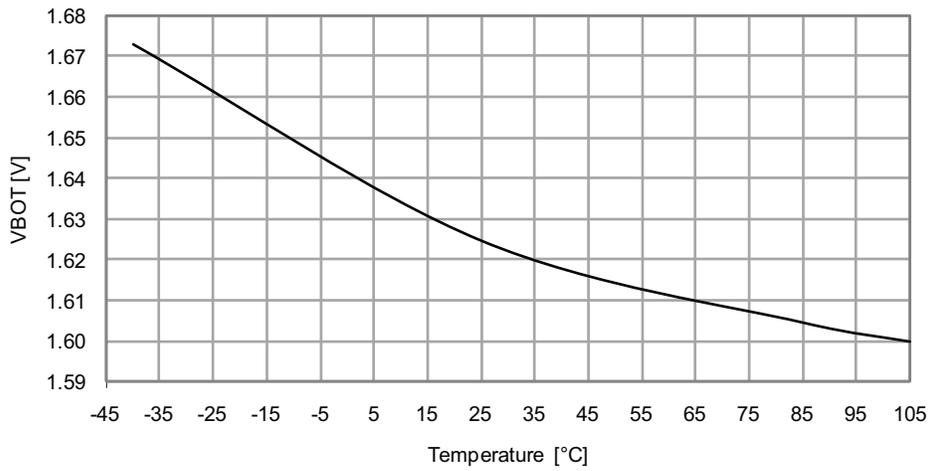
Figure 33-257.ADC Internal 1.0V Reference vs. Temperature



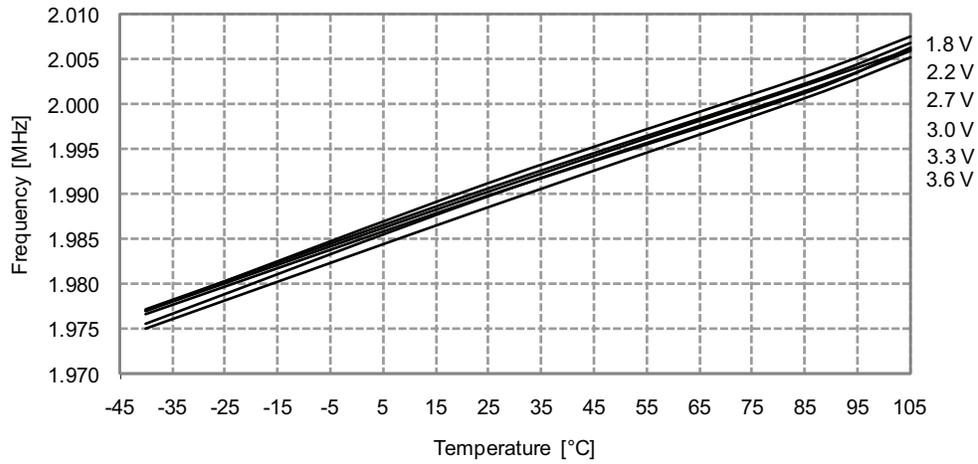
### 33.4.6 BOD Characteristics

Figure 33-258.BOD Thresholds vs. Temperature

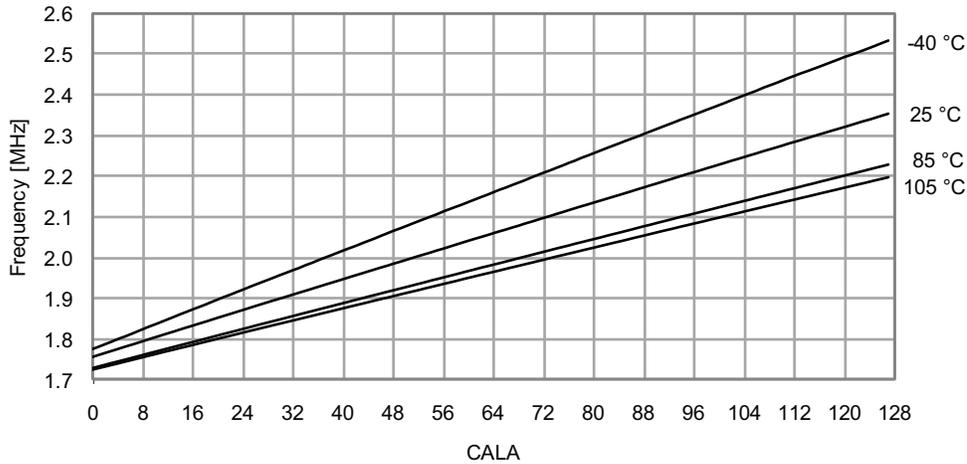
*BOD level = 1.6V*



**Figure 33-339. 2MHz Internal Oscillator Frequency vs. Temperature**  
*DPLL enabled, from the 32.768kHz internal oscillator*

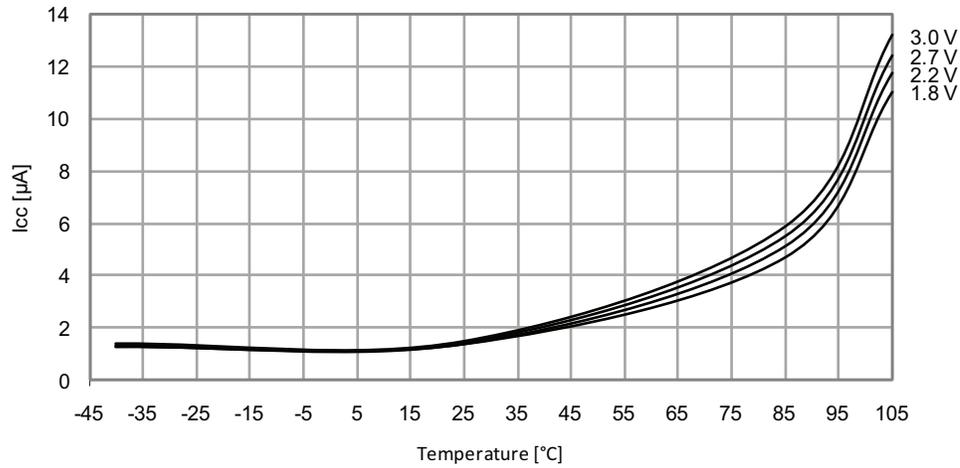


**Figure 33-340. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value**  
 $V_{CC} = 3V$



**Figure 33-369. Power-down Mode Supply Current vs. Temperature**

*Watchdog and sampled BOD enabled and running from internal ULP oscillator*

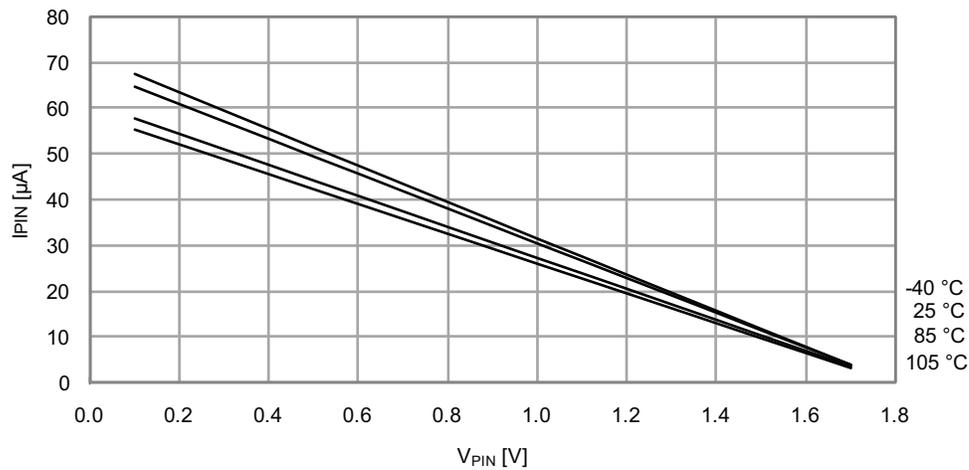


### 33.6.2 I/O Pin Characteristics

#### 33.6.2.1 Pull-up

**Figure 33-370. I/O Pin Pull-up Resistor Current vs. Input Voltage**

$V_{CC} = 1.8V$



## 34. Errata

### 34.1 Atmel ATxmega32D3

#### 34.1.1 Rev. I

- AC system status flags are only valid if AC-system is enabled
- Sampled BOD in Active mode will cause noise when bandgap is used as reference
- Temperature sensor not calibrated

#### 1. AC system status flags are only valid if AC-system is enabled

The status flags for the ac-output are updated even though the AC is not enabled which is invalid. Also, it is not possible to clear the AC interrupt flags without enabling either of the Analog comparators.

##### **Problem fix/workaround**

Software should clear the AC system flags once, after enabling the AC system before using the AC system status flags.

#### 2. Sampled BOD in Active mode will cause noise when bandgap is used as reference

Using the BOD in sampled mode when the device is running in Active or Idle mode will add noise on the bandgap reference for ADC, DAC, and Analog Comparator.

##### **Problem fix/workaround**

If the bandgap is used as reference for either the ADC, DAC and Analog Comparator, the BOD must not be set in sampled mode.

#### 3. Temperature sensor not calibrated

Temperature sensor factory calibration not implemented.

##### **Problem fix/workaround**

None.

#### 34.1.2 Rev A - H

Not sampled.

## 34.2 Atmel ATxmega64D3

### 34.2.1 Rev. I

- AC system status flags are only valid if AC-system is enabled
- Sampled BOD in Active mode will cause noise when bandgap is used as reference
- Temperature sensor not calibrated

#### 1. AC system status flags are only valid if AC-system is enabled

The status flags for the ac-output are updated even though the AC is not enabled which is invalid. Also, it is not possible to clear the AC interrupt flags without enabling either of the Analog comparators.

##### **Problem fix/workaround**

Software should clear the AC system flags once, after enabling the AC system before using the AC system status flags.

#### 2. Sampled BOD in Active mode will cause noise when bandgap is used as reference

Using the BOD in sampled mode when the device is running in Active or Idle mode will add noise on the bandgap reference for ADC, DAC, and Analog Comparator.

##### **Problem fix/workaround**

If the bandgap is used as reference for either the ADC, DAC and Analog Comparator, the BOD must not be set in sampled mode.

#### 3. Temperature sensor not calibrated

Temperature sensor factory calibration not implemented.

##### **Problem fix/workaround**

None.

### 34.2.2 Rev. H

Not sampled.

### 34.2.3 Rev. G

Not sampled.

### 34.2.4 Rev. F

Not sampled.

- CRC generator module
- ADC 1/2× gain option, and this configuration option in the GAIN bits in the ADC Channel CTRL register
- ADC VCC/2 reference option and this configuration option in the REFSEL bits on the ADC REFCTRL register
- ADC option to use internal Gnd as negative input in differential measurements and this configuration option in the MUXNEG bits in the ADC Channel MUXCTRL register
- ADC channel scan and the ADC SCAN register
- ADC current limitation option, and the CURRLIMIT bits in the ADC CTRLB register
- ADC impedance mode selection for the gain stage, and the IMPMODE bit in the ADC CTRLB register
- Timer/Counter 2 and the SPLITMODE configuration option in the BYTEM bits in the Timer/Counter 0 CTRL register
- Analog Comparator (AC) current output option, and the AC CURRCTRL and CURRCALIB registers
- PORT remap functions with alternate pin locations for Timer/Counter output compare channels, USART0 and SPI, and the PORT REMAP register
- PORT RTC clock output option and the RTCOUT bit in the PORT CLKEVOUT register
- PORT remap functions with alternate pin locations for the clock and event output, and the CLKEVPIN bit in the PORT CLKEVOUT register
- TOSC alternate pin locations, and TOSSEL bit in FUSEBYTE2
- Real Time Counter clock source options of external clock from TOSC1, and 32.768kHz from TOSC, and 32.768kHz from the 32.768kHz internal oscillator, and these configuration options in the RTCSRC bits in the Clock RTCTRL register
- PLL divide by two option, and the PLLDIV bit in the Clock PLLCTRL register
- PLL lock detection failure function and the PLLDIF and PLLFDEN bits in the Clock XOSCFAIL register
- The high drive option for external crystal and the XOSCPWR bit on the Oscillator XOSCCTRL register
- The option to enable sequential startup of the analog modules and the ANAINIT register in MCU Control memory

**Problem fix/workaround**

None.

**26. Sampled BOD in Active mode will cause noise when bandgap is used as reference**

Using the BOD in sampled mode when the device is running in Active or Idle mode will add noise on the bandgap reference for ADC, DAC and Analog Comparator.

**Problem fix/workaround**

If the bandgap is used as reference for either the ADC, DAC and Analog Comparator, the BOD must not be set in sampled mode.

**27. Temperature sensor not calibrated**

Temperature sensor factory calibration not implemented.

**Problem fix/workaround**

None.

**28. Disabling of USART transmitter does not automatically set the TxD pin direction to input**

If the USART transmitter is idle with no frames to transmit, setting TXEN to zero will not automatically set the TxD pin direction to input.