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#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	50
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d3-mnr">https://www.e-xfl.com/product-detail/microchip-technology/atxmega32d3-mnr</a>

**Table 28-6. Port F - Alternate Functions**

<b>PORT F</b>	<b>PIN #</b>	<b>INTERRUPT</b>	<b>TCF0</b>
PF0	46	SYNC	OC0A
PF1	47	SYNC	OC0B
PF2	48	SYNC/ASYNC	OC0C
PF3	49	SYNC	OC0D
PF4	50	SYNC	
PF5	51	SYNC	
PF6	54	SYNC	
PF7	55	SYNC	
GND	52		
VCC	53		

**Table 28-7. Port R - Alternate Functions**

<b>PORT R</b>	<b>PIN #</b>	<b>INTERRUPT</b>	<b>PDI</b>	<b>XTAL</b>
PDI	56		PDI_DATA	
RESET	57		PDI_CLOCK	
PRO	58	SYNC		XTAL2
PR1	59	SYNC		XTAL1

### 32.3.11 Power-on Reset Characteristics

**Table 32-74. Power-on Reset Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$V_{POT^-}$ <sup>(1)</sup>	POR threshold voltage falling $V_{CC}$	$V_{CC}$ falls faster than 1V/ms	0.4	1.0		V
		$V_{CC}$ falls at 1V/ms or slower	0.8	1.3		
$V_{POT^+}$	POR threshold voltage rising $V_{CC}$			1.3	1.59	

Note: 1.  $V_{POT^-}$  values are only valid when BOD is disabled. When BOD is enabled  $V_{POT^-} = V_{POT^+}$ .

### 32.3.12 Flash and EEPROM Memory Characteristics

**Table 32-75. Endurance and Data Retention**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
Flash	Write/Erase cycles	25°C	10K			Cycle
		85°C	10K			
		105°C	2K			
	Data retention	25°C	100			Year
		85°C	25			
		105°C	10			
EEPROM	Write/Erase cycles	25°C	100K			Cycle
		85°C	100K			
		105°C	30K			
	Data retention	25°C	100			Year
		85°C	25			
		105°C	10			

**Table 32-76. Programming Time**

Symbol	Parameter	Condition	Min.	Typ. <sup>(1)</sup>	Max.	Units
	Chip erase <sup>(2)</sup>	128KB Flash, EEPROM		75		ms
	Application erase	Section erase		6		
	Flash	Page erase		4		
		Page write		4		
		Atomic page erase and write		8		
	EEPROM	Page erase		4		
		Page write		4		
		Atomic page erase and write		8		

Notes: 1. Programming is timed from the 2MHz internal oscillator.  
2. EEPROM is not erased if the EESAVE fuse is programmed.

### 32.4.11 Power-on Reset Characteristics

**Table 32-103. Power-on Reset Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$V_{POT^-}$ (1)	POR threshold voltage falling $V_{CC}$	$V_{CC}$ falls faster than 1V/ms	0.4	1.0		V
		$V_{CC}$ falls at 1V/ms or slower	0.8	1.3		
$V_{POT^+}$	POR threshold voltage rising $V_{CC}$			1.3	1.59	

Note: 1.  $V_{POT^-}$  values are only valid when BOD is disabled. When BOD is enabled  $V_{POT^-} = V_{POT^+}$ .

### 32.4.12 Flash and EEPROM Memory Characteristics

**Table 32-104. Endurance and Data Retention**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
Flash	Write/Erase cycles	25°C	10K			Cycle
		85°C	10K			
		105°C	2K			
	Data retention	25°C	100			Year
		85°C	25			
		105°C	10			
EEPROM	Write/Erase cycles	25°C	100K			Cycle
		85°C	100K			
		105°C	30K			
	Data retention	25°C	100			Year
		85°C	25			
		105°C	10			

**Table 32-105. Programming Time**

Symbol	Parameter	Condition	Min.	Typ. (1)	Max.	Units
	Chip erase (2)	192KB flash, EEPROM		90		ms
	Application erase	Section erase		6		
	Flash	Page erase		4		
		Page write		4		
		Atomic page erase and write		8		
	EEPROM	Page erase		4		
		Page write		4		
		Atomic page erase and write		8		

Notes: 1. Programming is timed from the 2MHz internal oscillator.  
2. EEPROM is not erased if the EESAVE fuse is programmed.

### 32.4.13.5 Internal Phase Locked Loop (PLL) Characteristics

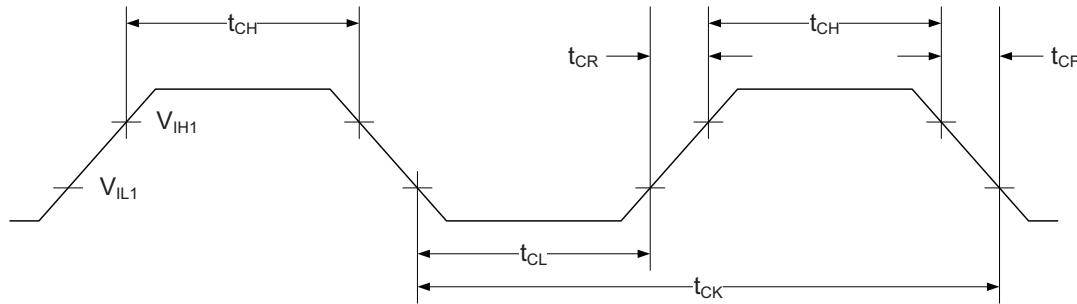
**Table 32-110. Internal PLL Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$f_{IN}$	Input frequency	Output frequency must be within $f_{OUT}$	0.4		64	
$f_{OUT}$	Output frequency <sup>(1)</sup>	$V_{CC} = 1.6 - 1.8V$	20		48	MHz
		$V_{CC} = 2.7 - 3.6V$	20		128	
	Start-up time			25		$\mu s$
	Re-lock time			25		

Note: 1. The maximum output frequency vs. supply voltage is linear between 1.8V and 2.7V, and can never be higher than four times the maximum CPU frequency.

### 32.4.13.6 External Clock Characteristics

**Figure 32-24. External Clock Drive Waveform**



**Table 32-111.External Clock used as System Clock without Prescaling**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$1/t_{CK}$	Clock Frequency <sup>(1)</sup>	$V_{CC} = 1.6 - 1.8V$	0		12	MHz
		$V_{CC} = 2.7 - 3.6V$	0		32	
$t_{CK}$	Clock Period	$V_{CC} = 1.6 - 1.8V$	83.3			
		$V_{CC} = 2.7 - 3.6V$	31.5			
$t_{CH}$	Clock High Time	$V_{CC} = 1.6 - 1.8V$	30.0			
		$V_{CC} = 2.7 - 3.6V$	12.5			
$t_{CL}$	Clock Low Time	$V_{CC} = 1.6 - 1.8V$	30.0			
		$V_{CC} = 2.7 - 3.6V$	12.5			
$t_{CR}$	Rise Time (for maximum frequency)	$V_{CC} = 1.6 - 1.8V$			10	
		$V_{CC} = 2.7 - 3.6V$			3	
$t_{CF}$	Fall Time (for maximum frequency)	$V_{CC} = 1.6 - 1.8V$			10	
		$V_{CC} = 2.7 - 3.6V$			3	
$\Delta t_{CK}$	Change in period from one clock cycle to the next				10	%

Note: 1. The maximum frequency vs. supply voltage is linear between 1.6V and 2.7V, and the same applies for all other parameters with supply voltage conditions.

### 32.5.13 Clock and Oscillator Characteristics

#### 32.5.13.1 Calibrated 32.768kHz Internal Oscillator Characteristics

**Table 32-135.** 32.768kHz Internal Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency			32.768		kHz
	Factory calibration accuracy	T = 85°C, V <sub>CC</sub> = 3.0V	-0.5		0.5	%
	User calibration accuracy		-0.5		0.5	

#### 32.5.13.2 Calibrated 2MHz RC Internal Oscillator Characteristics

**Table 32-136.** 2MHz Internal Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency range	DFLL can tune to this frequency over voltage and temperature	1.8	2.0	2.2	MHz
	Factory calibrated frequency			2.0		
	Factory calibration accuracy	T = 85°C, V <sub>CC</sub> = 3.0V	-1.5		1.5	%
	User calibration accuracy		-0.2		0.2	
	DFLL calibration stepsize			0.18		

#### 32.5.13.3 Calibrated 32MHz Internal Oscillator Characteristics

**Table 32-137.** 32MHz Internal Oscillator Characteristics

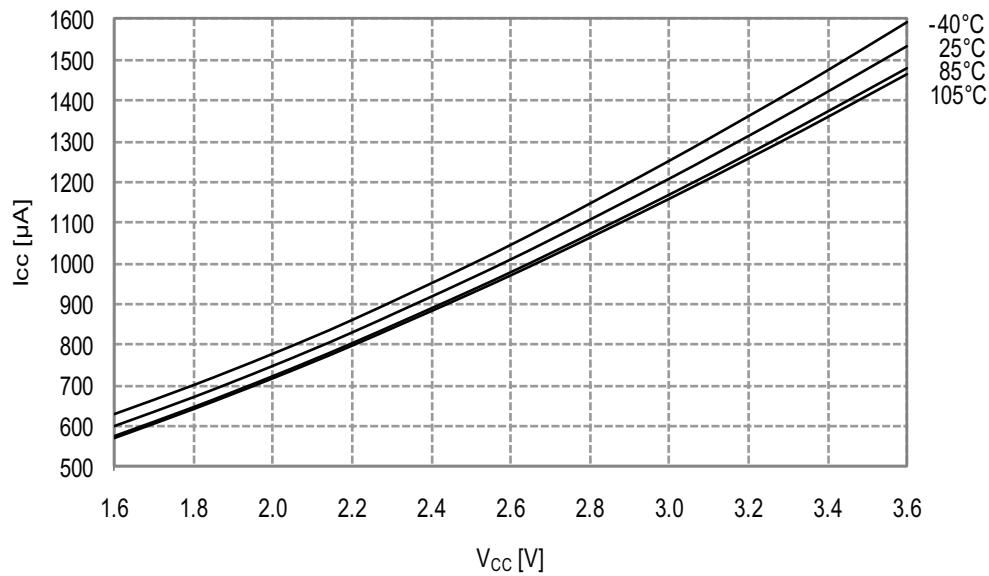
Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Frequency range	DFLL can tune to this frequency over voltage and temperature	30	32	55	MHz
	Factory calibrated frequency			32		
	Factory calibration accuracy	T = 85°C, V <sub>CC</sub> = 3.0V	-1.5		1.5	%
	User calibration accuracy		-0.2		0.2	
	DFLL calibration step size			0.19		

#### 32.5.13.4 32kHz Internal ULP Oscillator Characteristics

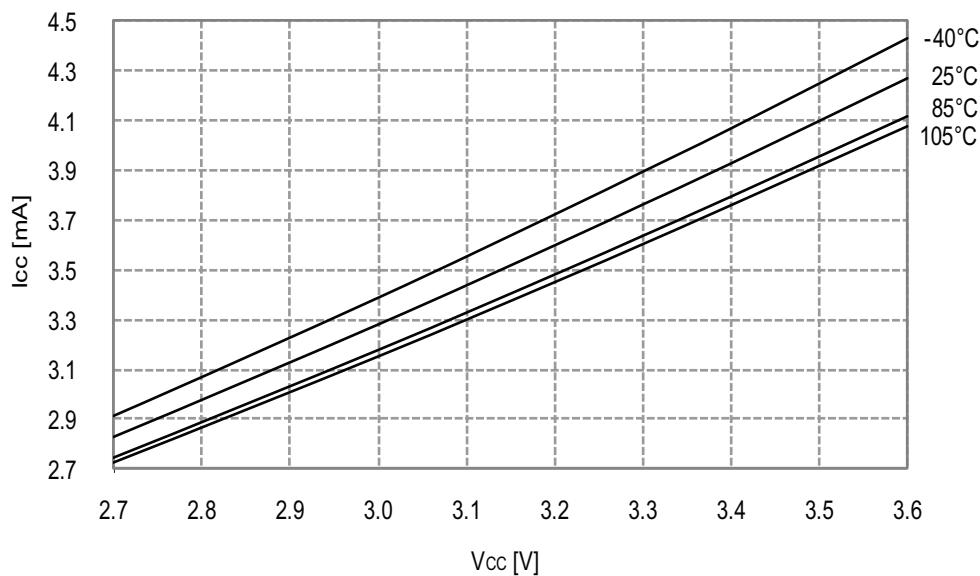
**Table 32-138.** 32kHz Internal ULP Oscillator Characteristics

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Factory calibrated frequency			32		kHz
	Factory calibration accuracy	T = 85°C, V <sub>CC</sub> = 3.0V	-12		12	%

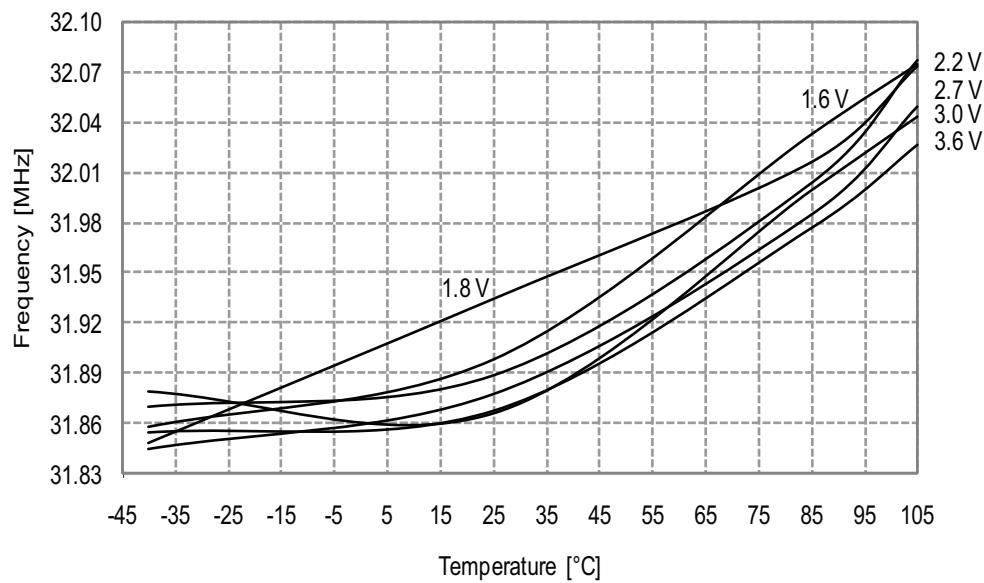
**Figure 33-13. Idle Mode Supply Current vs.  $V_{CC}$**   
 $f_{SYS} = 32\text{MHz}$  internal oscillator prescaled to 8MHz



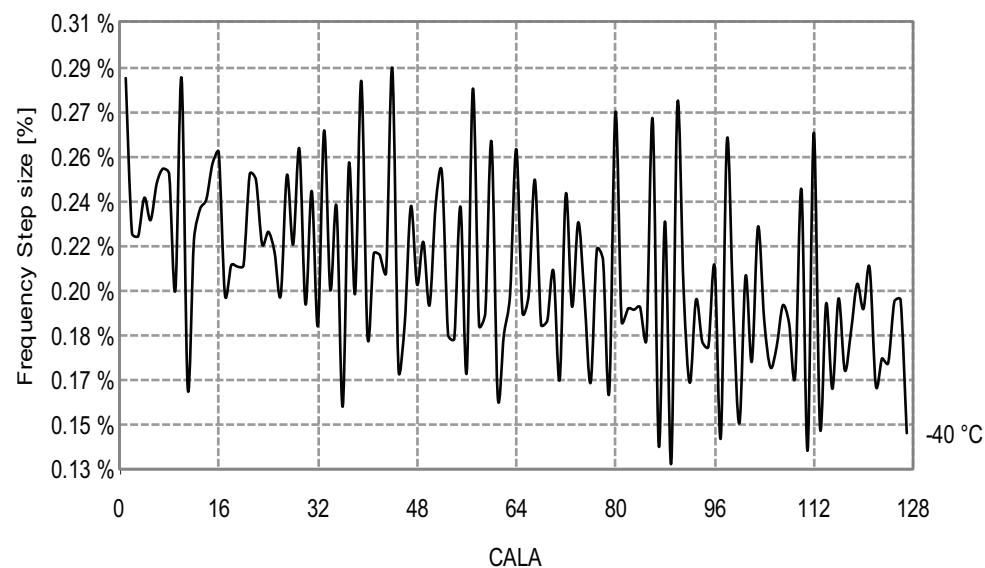
**Figure 33-14. Idle Mode Current vs.  $V_{CC}$**   
 $f_{SYS} = 32\text{MHz}$  internal oscillator



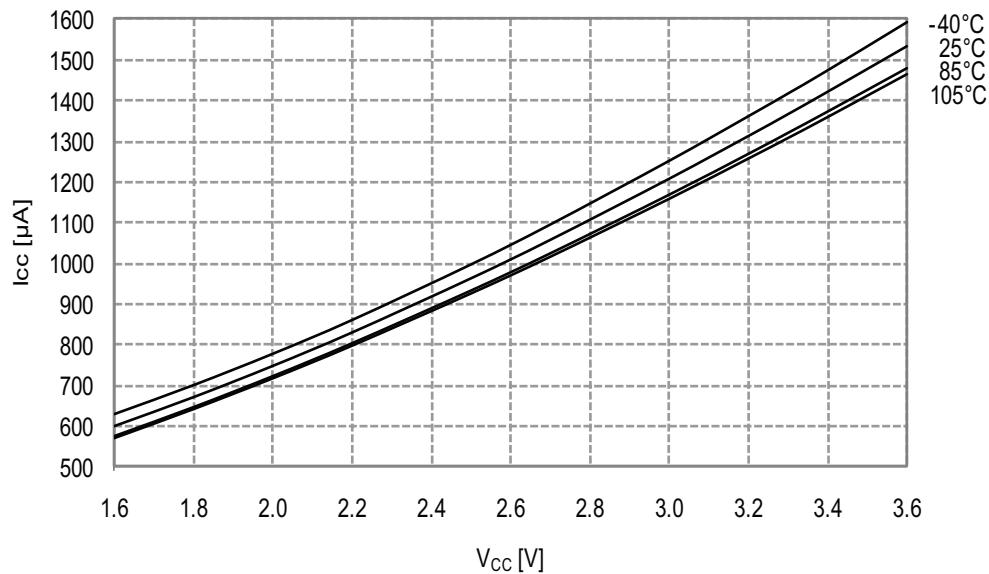
**Figure 33-61. 32MHz Internal Oscillator Frequency vs. Temperature**  
**DFLL enabled, from the 32.768kHz internal oscillator**



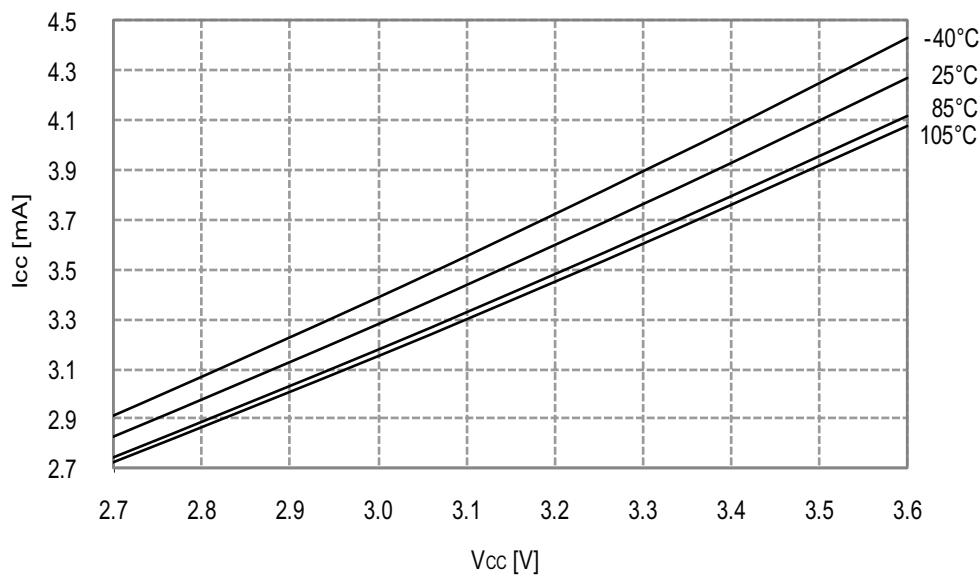
**Figure 33-62. 32MHz Internal Oscillator CALA Calibration Step Size**  
 **$T = -40^{\circ}\text{C}$ ,  $V_{CC} = 3.0\text{V}$**



**Figure 33-84. Idle Mode Supply Current vs. V<sub>CC</sub>**  
 $f_{SYS} = 32\text{MHz}$  internal oscillator prescaled to 8MHz

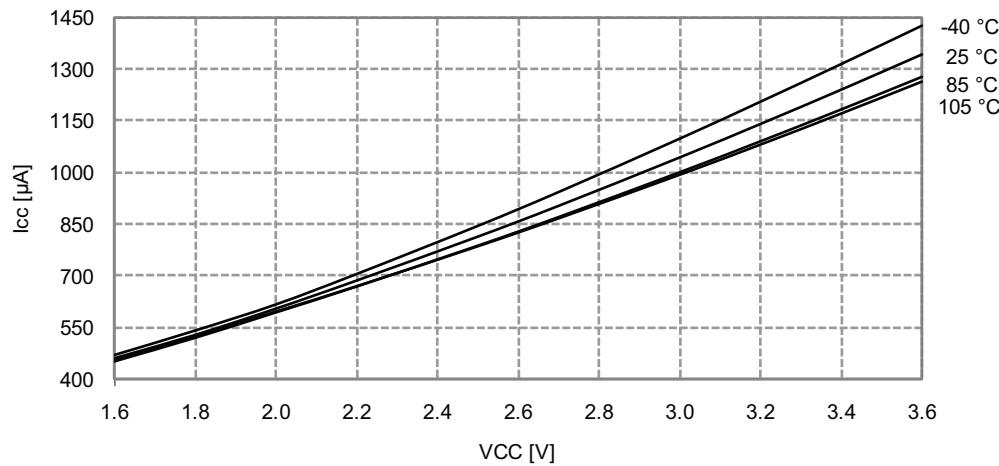


**Figure 33-85. Idle Mode Current vs. V<sub>CC</sub>**  
 $f_{SYS} = 32\text{MHz}$  internal oscillator



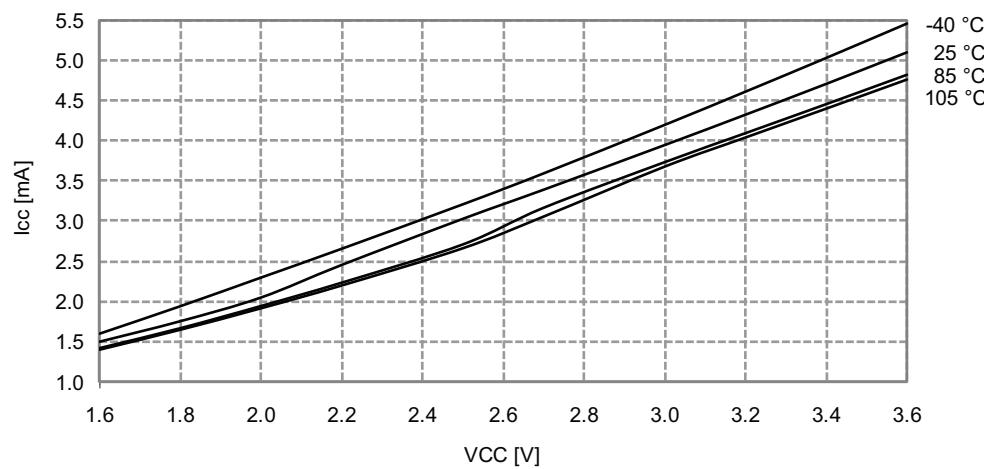
**Figure 33-287.Active Mode Supply Current vs. V<sub>CC</sub>**

*f<sub>SYS</sub> = 2MHz internal oscillator*



**Figure 33-288.Active Mode Supply Current vs. V<sub>CC</sub>**

*f<sub>SYS</sub> = 32MHz internal oscillator prescaled to 8MHz*



### 33.5.2.2 Output Voltage vs. Sink/Source Current

Figure 33-303.I/O Pin Output Voltage vs. Source Current

$V_{CC} = 1.8V$

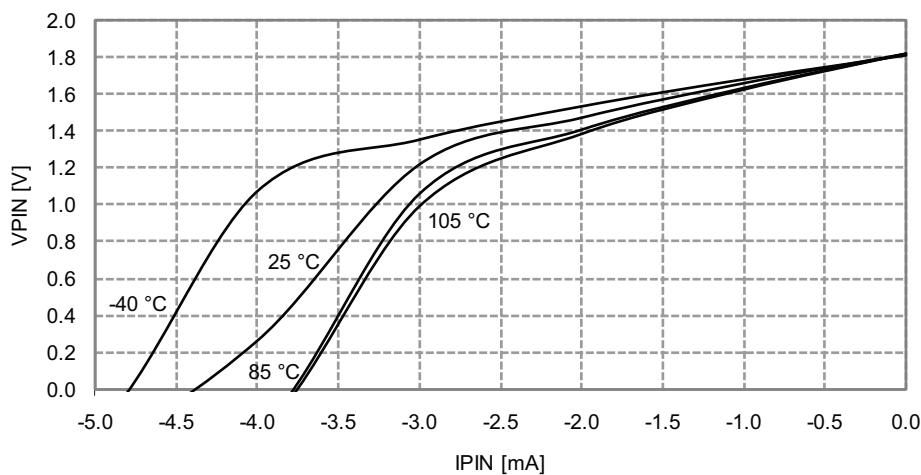
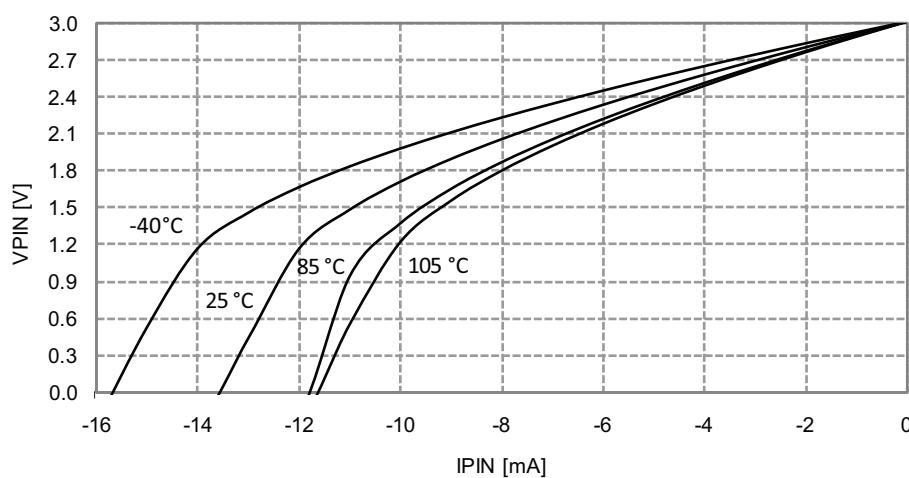


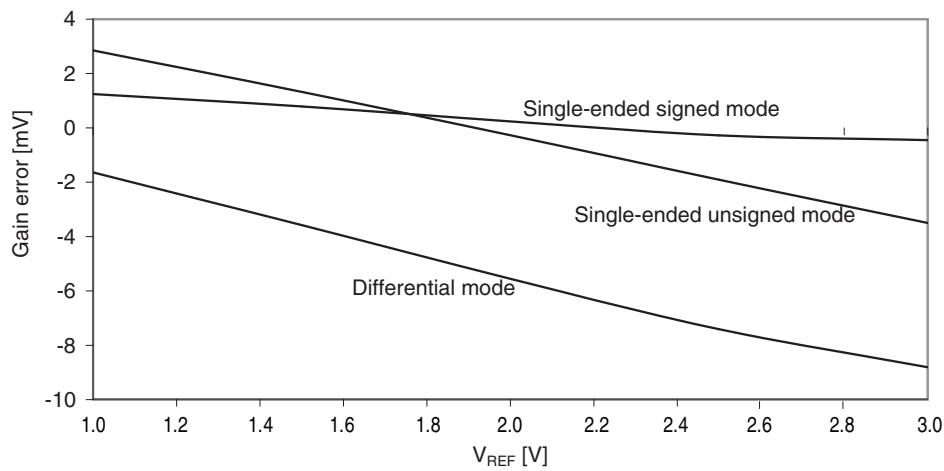
Figure 33-304.I/O Pin Output Voltage vs. Source Current

$V_{CC} = 3.0V$



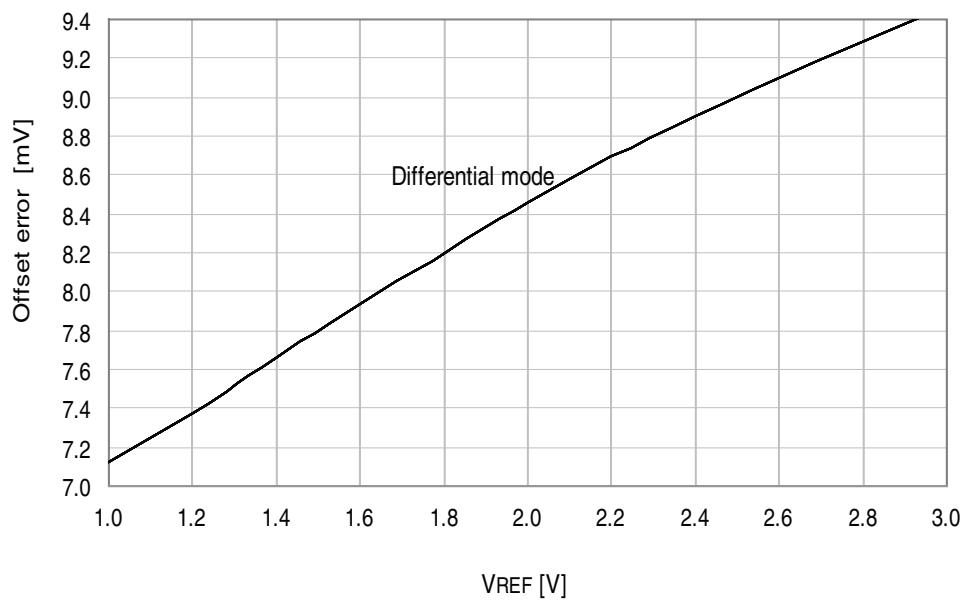
**Figure 33-319. Gain Error vs.  $V_{CC}$**

$T = 25^\circ\text{C}$ ,  $V_{REF} = \text{external } 1.0\text{V}$ , ADC sample rate = 300ksps



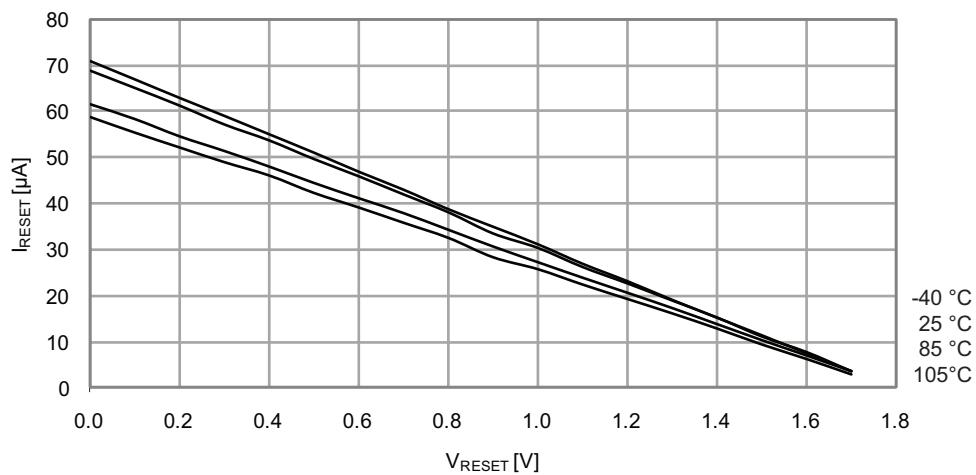
**Figure 33-320. Offset Error vs.  $V_{REF}$**

$T = 25^\circ\text{C}$ ,  $V_{CC} = 3.6\text{V}$ , ADC sample rate = 300ksps



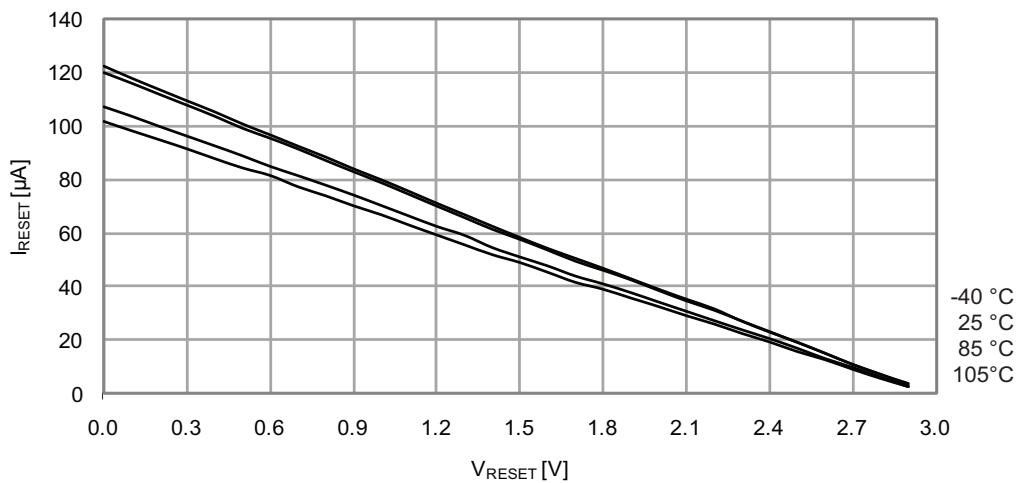
**Figure 33-331. Reset Pin Pull-up Resistor Current vs. Reset Pin Voltage**

$V_{CC} = 1.8V$

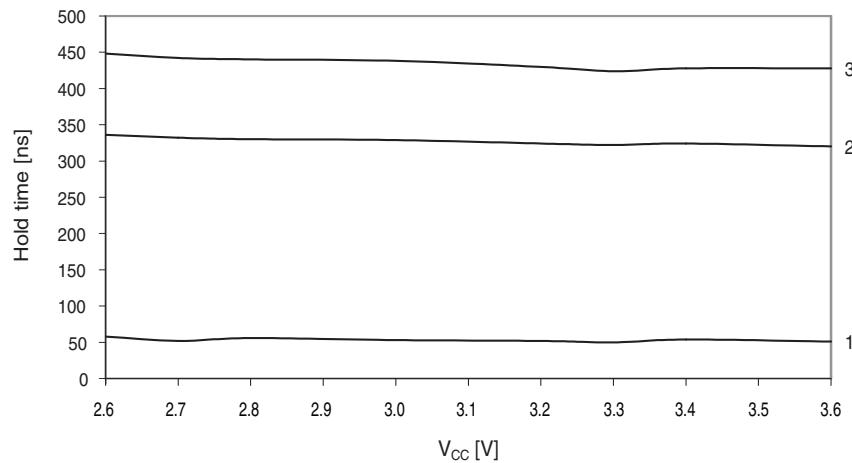


**Figure 33-332. Reset Pin Pull-up Resistor Current vs. Reset Pin Voltage**

$V_{CC} = 3.0V$

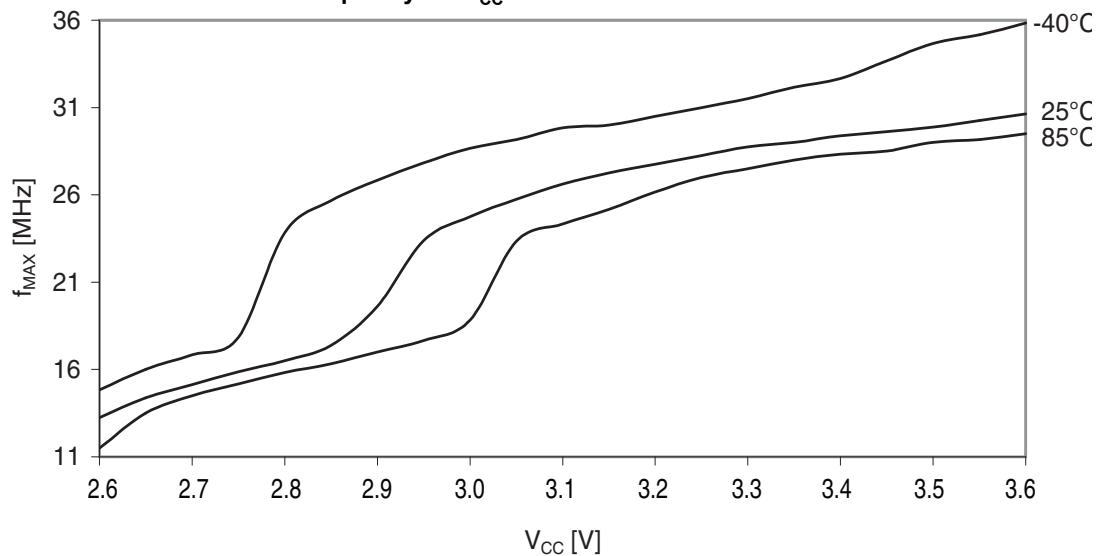


**Figure 33-351. SDA Hold Time vs. Supply Voltage**

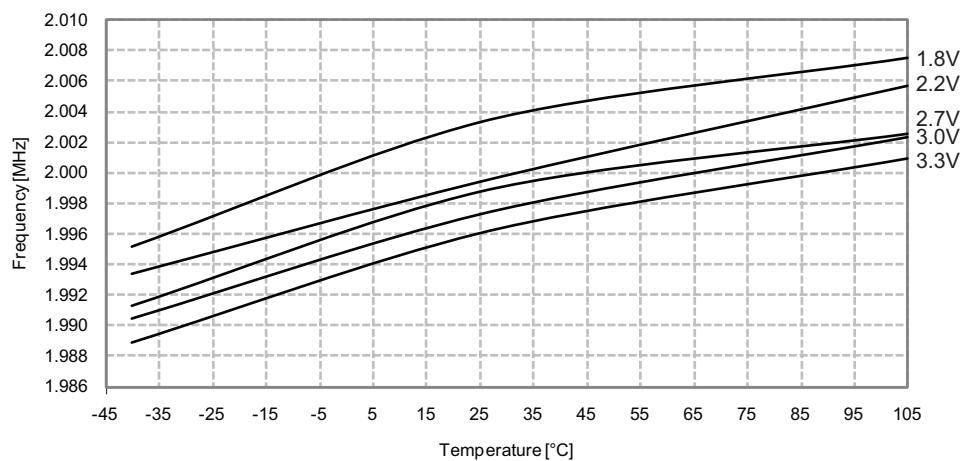


### 33.5.10 PDI Characteristics

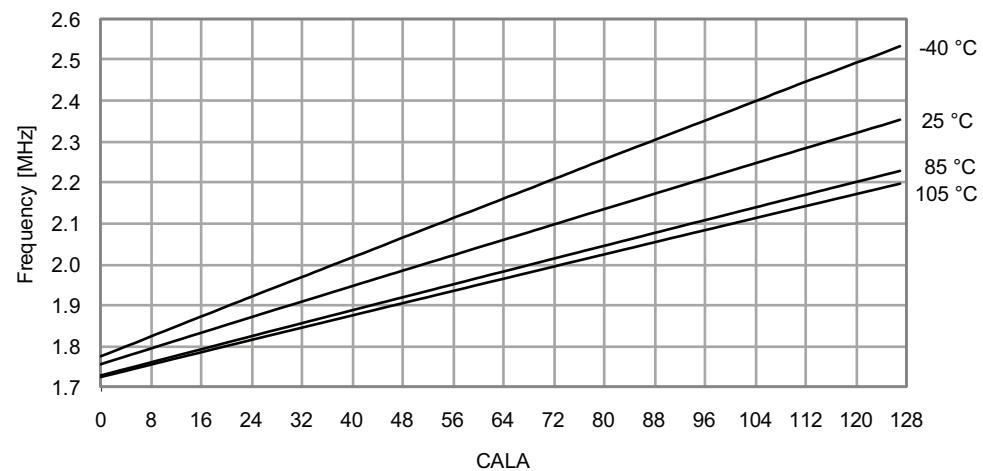
**Figure 33-352. Maximum PDI Frequency vs.  $V_{CC}$**



**Figure 33-409. 2MHz Internal Oscillator Frequency vs. Temperature**  
*DFLL enabled, from the 32.768kHz internal oscillator*



**Figure 33-410. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value**  
 $V_{CC} = 3V$



### 33.6.8.5 32MHz Internal Oscillator Calibrated to 48MHz

Figure 33-415. 48MHz Internal Oscillator Frequency vs. Temperature  
*DFLL disabled*

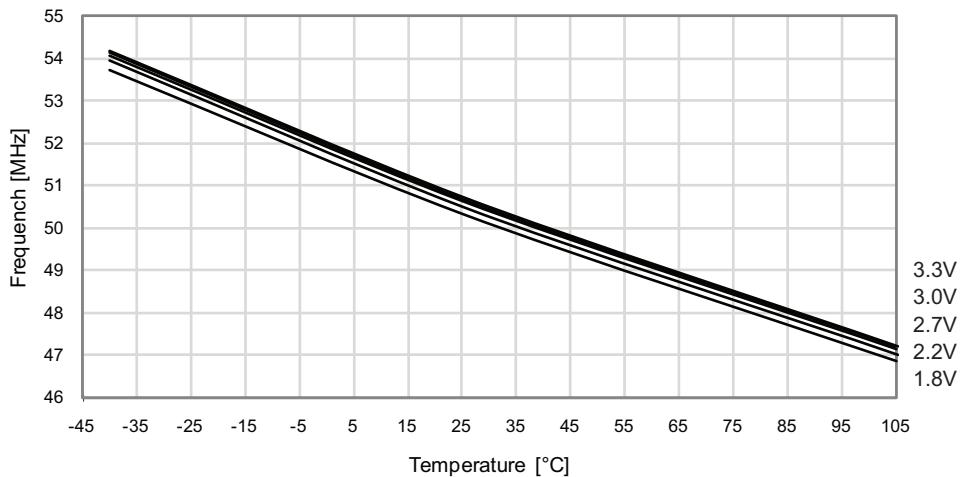
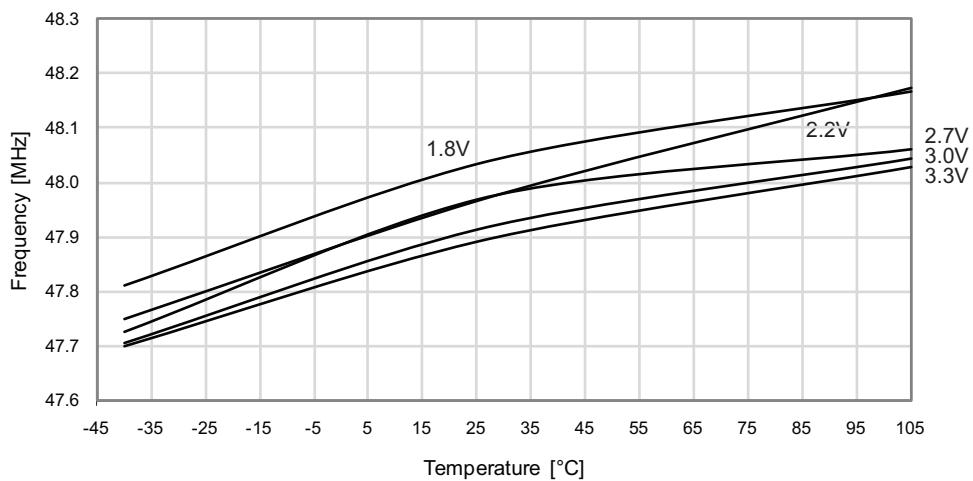


Figure 33-416. 48MHz Internal Oscillator Frequency vs. Temperature  
*DFLL enabled, from the 32.768kHz internal oscillator*



### **Problem fix/workaround**

The TxD pin direction can be set to input using the Port DIR register. Be advised that setting the Port DIR register to input will be immediate. Ongoing transmissions will be truncated.

#### **34.3.10 Rev. A**

Not sampled.

—	1×	gain:	2.4	V
—	2×	gain:	1.2	V
—	4×	gain:	0.6	V
—	8×	gain:	300	mV
—	16×	gain:	150	mV
—	32×	gain:	75	mV
—	64×	gain:	38	mV

#### **Problem fix/workaround**

Keep the amplified voltage output from the ADC gain stage below 2.4V in order to get a correct result, or keep ADC voltage reference below 2.4V.

### **6. ADC Event on compare match non-functional**

ADC signalling event will be given at every conversion complete even if Interrupt mode (INTMODE) is set to BELOW or ABOVE.

#### **Problem fix/workaround**

Enable and use interrupt on compare match when using the compare function.

### **7. ADC propagation delay is not correct when 8x – 64x gain is used**

The propagation delay will increase by only one ADC clock cycle for all gain settings.

#### **Problem fix/workaround**

None.

### **8. Bandgap measurement with the ADC is non-functional when V<sub>CC</sub> is below 2.7V**

The ADC can not be used to do bandgap measurements when V<sub>CC</sub> is below 2.7V.

#### **Problem fix/workaround**

None.

### **9. Accuracy lost on first three samples after switching input to ADC gain stage**

Due to memory effect in the ADC gain stage, the first three samples after changing input channel must be disregarded to achieve 12-bit accuracy.

#### **Problem fix/workaround**

Run three ADC conversions and discard these results after changing input channels to ADC gain stage.

### **10. Configuration of PGM and CWCM not as described in XMEGA D Manual**

Enabling Common Waveform Channel Mode will enable Pattern generation mode (PGM), but not Common Waveform Channel Mode.

Enabling Pattern Generation Mode (PGM) and not Common Waveform Channel Mode (CWCM) will enable both Pattern Generation Mode and Common Waveform Channel Mode.

## **16. NMI Flag for Crystal Oscillator Failure automatically cleared**

NMI flag for Crystal Oscillator Failure (XOSCFDIF) will be automatically cleared when executing the NMI interrupt handler.

### **Problem fix/workaround**

This device revision has only one NMI interrupt source, so checking the interrupt source in software is not required.

## **17. RTC Counter value not correctly read after sleep**

If the RTC is set to wake up the device on RTC Overflow and bit 0 of RTC CNT is identical to bit 0 of RTC PER as the device is entering sleep, the value in the RTC count register can not be read correctly within the first prescaled RTC clock cycle after wake-up. The value read will be the same as the value in the register when entering sleep.

The same applies if RTC Compare Match is used as wake-up source.

### **Problem fix/workaround**

Wait at least one prescaled RTC clock cycle before reading the RTC CNT value.

## **18. Pending asynchronous RTC-interrupts will not wake up device**

Asynchronous Interrupts from the Real-Time-Counter that is pending when the sleep instruction is executed, will be ignored until the device is woken from another source or the source triggers again.

### **Problem fix/workaround**

None.

## **19. TWI Transmit collision flag not cleared on repeated start**

The TWI transmit collision flag should be automatically cleared on start and repeated start, but is only cleared on start.

### **Problem fix/workaround**

Clear the flag in software after address interrupt.

## **20. Clearing TWI Stop Interrupt Flag may lock the bus**

If software clears the STOP Interrupt Flag (APIF) on the same Peripheral Clock cycle as the hardware sets this flag due to a new address received, CLKHOLD is not cleared and the SCL line is not released. This will lock the bus.

### **Problem fix/workaround**

Check if the bus state is IDLE. If this is the case, it is safe to clear APIF. If the bus state is not IDLE, wait for the SCL pin to be low before clearing APIF.

#### **Code:**

```
/* Only clear the interrupt flag if within a "safe zone". */
while ( /* Bus not IDLE: */
       ( (COMMS_TWI.MASTER.STATUS & TWI_MASTER_BUSSTATE_gm) != TWI_MASTER_BUSSTATE_IDLE_gc) &&
       /* SCL not held by slave: */
       ! (COMMS_TWI.SLAVE.STATUS & TWI_SLAVE_CLKHOLD_bm)
     )
{
  /* Ensure that the SCL line is low */
```

- PORT remap functions with alternate pin locations for Timer/Counter output compare channels, USART0 and SPI, and the PORT REMAP register
- PORT RTC clock output option and the RTCOUT bit in the PORT CLKEVOUT register
- PORT remap functions with alternate pin locations for the clock and event output, and the CLKEVPIN bit in the PORT CLKEVOUT register
- TOSC alternate pin locations, and TOSCSEL bit in FUSEBYTE2
- Real Time Counter clock source options of external clock from TOSC1, and 32.768kHz from TOSC, and 32.768kHz from the 32.768kHz internal oscillator, and these configuration options in the RTCSRC bits in the Clock RTCTRL register
- PLL divide by two option, and the PLLDIV bit in the Clock PLLCTRL register
- PLL lock detection failure function and the PLLDIF and PLLFDEN bits in the Clock XOSCFAIL register
- The high drive option for external crystal and the XOSCPWR bit on the Oscillator XOSCCTRL register
- The option to enable sequential startup of the analog modules and the ANAINIT register in MCU Control memory

#### **Problem fix/workaround**

None.

#### **25. Sampled BOD in Active mode will cause noise when bandgap is used as reference**

Using the BOD in sampled mode when the device is running in Active or Idle mode will add noise on the bandgap reference for ADC, DAC and Analog Comparator.

#### **Problem fix/workaround**

If the bandgap is used as reference for either the ADC, DAC and Analog Comparator, the BOD must not be set in sampled mode.

#### **26. Temperature sensor not calibrated**

Temperature sensor factory calibration not implemented.

#### **Problem fix/workaround**

None.

#### **27. Disabling of USART transmitter does not automatically set the TxD pin direction to input**

If the USART transmitter is idle with no frames to transmit, setting TXEN to zero will not automatically set the TxD pin direction to input.

#### **Problem fix/workaround**

The TxD pin direction can be set to input using the Port DIR register. Be advised that setting the Port DIR register to input will be immediate. Ongoing transmissions will be truncated.

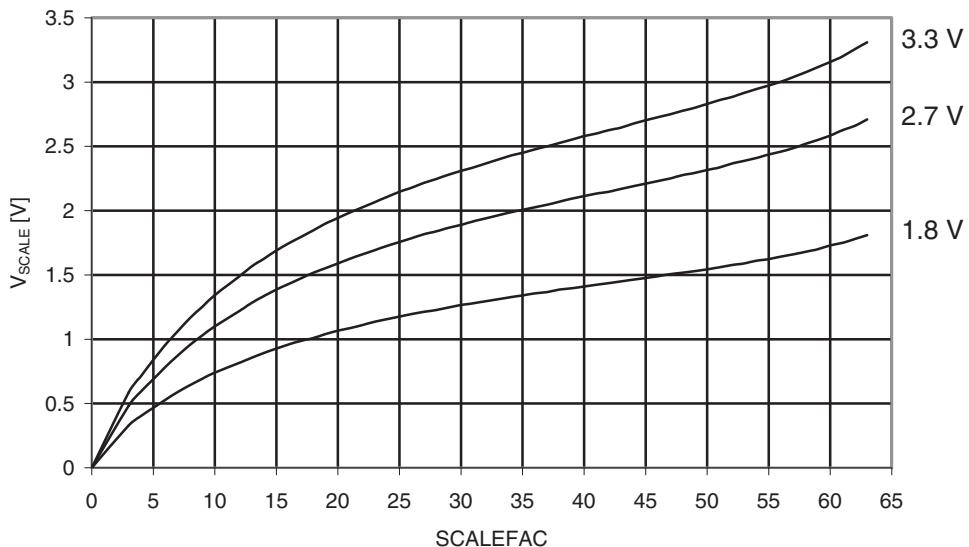
#### **34.5.6 Rev. D**

Not sampled.

#### **34.5.7 Rev. C**

Not sampled.

**Figure 34-8. Analog Comparator Voltage Scaler vs. Scalefac**  
 $T = 25^\circ\text{C}$



#### Problem fix/workaround

Use external voltage input for the analog comparator if accurate voltage levels are needed.

### 3. ADC gain stage cannot be used for single conversion

The ADC gain stage will not output correct result for single conversion that is triggered and started from software or event system.

#### Problem fix/workaround

When the gain stage is used, the ADC must be set in free running mode for correct results.

### 4. ADC has increased INL error for some operating conditions

Some ADC configurations or operating condition will result in increased INL error.

In signed mode INL is increased to:

6LSB for sample rates above 130ksps, and up to 8LSB for 200ksps sample rate.

6LSB for reference voltage below 1.1V when  $V_{CC}$  is above 3.0V.

20LSB for ambient temperature below  $0^\circ\text{C}$  and reference voltage below 1.3V.

In unsigned mode, the INL error cannot be guaranteed, and this mode should not be used.

#### Problem fix/workaround

None, avoid using the ADC in the above configurations in order to prevent increased INL error. Use the ADC in signed mode also for single ended measurements.

### 5. ADC gain stage output range is limited to 2.4V

The amplified output of the ADC gain stage will never go above 2.4V, hence the differential input will only give correct output when below 2.4V/gain. For the available gain settings, this gives a differential input range of: