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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I <sup>2</sup> C, IrDA, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	50
Program Memory Size	384KB (384K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/atxmega384d3-anr">https://www.e-xfl.com/product-detail/microchip-technology/atxmega384d3-anr</a>

**Table 32-92. Current Consumption for Modules and Peripherals**

Symbol	Parameter	Condition <sup>(1)</sup>	Min.	Typ.	Max.	Units	
I <sub>CC</sub>	ULP oscillator			0.9		μA	
	32.768kHz int. oscillator			25			
	2MHz int. oscillator			78			
		DFLL enabled with 32.768kHz int. osc. as reference		110			
	32MHz int. oscillator			250			
		DFLL enabled with 32.768kHz int. osc. as reference		440			
	PLL	20× multiplication factor, 32MHz int. osc. DIV4 as reference		310			
	Watchdog timer			1.0			
	BOD	Continuous mode			132		
		Sampled mode, includes ULP oscillator			1.4		
	Internal 1.0V reference			185			
Temperature sensor			182				
ADC	16ksps V <sub>REF</sub> = Ext. ref.			1.12		mA	
		CURRLIMIT = LOW		1.01			
		CURRLIMIT = MEDIUM		0.9			
		CURRLIMIT = HIGH		0.8			
	75ksps V <sub>REF</sub> = Ext. ref.	CURRLIMIT = LOW		1.7			
	300ksps, V <sub>REF</sub> = Ext. ref.		3.1				
USART	Rx and Tx enabled, 9600 BAUD			9.5		μA	
	Flash memory and EEPROM programming			10		mA	

Note: 1. All parameters measured as the difference in current consumption between module enabled and disabled. All data at V<sub>CC</sub> = 3.0V, Clk<sub>SYS</sub> = 1MHz external clock without prescaling, T = 25°C unless other conditions are given.

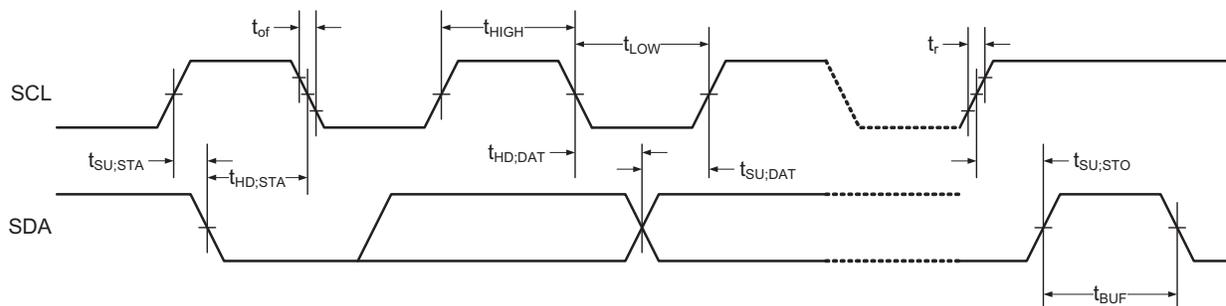
**Table 32-115. SPI Timing Characteristics and Requirements**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$t_{SCK}$	SCK period	Master		(See Table 20-3 in XMEGA D manual)		ns
$t_{SCKW}$	SCK high/low width	Master		$0.5 * SCK$		
$t_{SCKR}$	SCK rise time	Master		2.7		
$t_{SCKF}$	SCK fall time	Master		2.7		
$t_{MIS}$	MISO setup to SCK	Master		10		
$t_{MIH}$	MISO hold after SCK	Master		10		
$t_{MOS}$	MOSI setup SCK	Master		$0.5 * SCK$		
$t_{MOH}$	MOSI hold after SCK	Master		1		
$t_{SSCK}$	Slave SCK Period	Slave	$4 * t_{Clk_{PER}}$			
$t_{SSCKW}$	SCK high/low width	Slave	$2 * t_{Clk_{PER}}$			
$t_{SSCKR}$	SCK rise time	Slave			1600	
$t_{SSCKF}$	SCK fall time	Slave			1600	
$t_{SIS}$	MOSI setup to SCK	Slave	3			
$t_{SIH}$	MOSI hold after SCK	Slave	$t_{Clk_{PER}}$			
$t_{SSS}$	$\overline{SS}$ setup to SCK	Slave	21			
$t_{SSH}$	$\overline{SS}$ hold after SCK	Slave	20			
$t_{SOS}$	MISO setup SCK	Slave		8		
$t_{SOH}$	MISO hold after SCK	Slave		13		
$t_{SOSS}$	MISO setup after $\overline{SS}$ low	Slave		11		
$t_{SOSSH}$	MISO hold after $\overline{SS}$ high	Slave		8		

**32.4.15 Two-wire Interface Characteristics**

Table 32-116 on page 138 describes the requirements for devices connected to the Two-Wire Interface Bus. The Atmel AVR XMEGA Two-Wire Interface meets or exceeds these requirements under the noted conditions. Timing symbols refer to Figure 32-28.

**Figure 32-28. Two-wire Interface Bus Timing**



### 32.5.3 Current Consumption

Table 32-120. Current Consumption for Active Mode and Sleep Modes

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units		
I <sub>CC</sub>	Active power consumption <sup>(1)</sup>	32kHz, Ext. Clk	V <sub>CC</sub> = 1.8V	60		μA		
			V <sub>CC</sub> = 3.0V	140				
		1MHz, Ext. Clk	V <sub>CC</sub> = 1.8V	245				
			V <sub>CC</sub> = 3.0V	550				
		2MHz, Ext. Clk	V <sub>CC</sub> = 1.8V	440	700			
			V <sub>CC</sub> = 3.0V	0.9	1.5		mA	
	32MHz, Ext. Clk		9.0	15				
	Idle power consumption <sup>(2)</sup>	32kHz, Ext. Clk	V <sub>CC</sub> = 1.8V		3.0		μA	
			V <sub>CC</sub> = 3.0V		3.5			
		1MHz, Ext. Clk	V <sub>CC</sub> = 1.8V		55			
			V <sub>CC</sub> = 3.0V		110			
		2MHz, Ext. Clk	V <sub>CC</sub> = 1.8V		105	350		
			V <sub>CC</sub> = 3.0V		215	650		mA
	32MHz, Ext. Clk			3.4	8.0			
	Power-down power consumption		T = 25°C	V <sub>CC</sub> = 3.0V		0.1	1.0	
			T = 85°C			3.5	6.0	
			T = 105°C			10	15	
			WDT and sampled BOD enabled, T = 25°C		V <sub>CC</sub> = 3.0V		1.5	2.0
			WDT and sampled BOD enabled, T = 85°C				5.8	10
			WDT and sampled BOD enabled, T = 105°C				12	20
	Power-save power consumption <sup>(3)</sup>	RTC from ULP clock, WDT and sampled BOD enabled, T = 25°C	V <sub>CC</sub> = 1.8V		1.3		μA	
			V <sub>CC</sub> = 3.0V		1.4			
		RTC from 1.024kHz low power 32.768kHz TOSC, T = 25°C	V <sub>CC</sub> = 1.8V		0.7	2.0		
			V <sub>CC</sub> = 3.0V		0.8	2.0		
		RTC from low power 32.768kHz TOSC, T = 25°C	V <sub>CC</sub> = 1.8V		0.9	3.0		
			V <sub>CC</sub> = 3.0V		1.1	3.0		
	Reset power consumption	Current through $\overline{\text{RESET}}$ pin subtracted	V <sub>CC</sub> = 3.0V		170			

- Notes:
1. All power reduction registers set including FPRM and EPRM.
  2. All power reduction registers set without FPRM and EPRM.
  3. Maximum limits are based on characterization, and not tested in production.

**Table 32-145. Two-wire Interface Characteristics**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
V <sub>IH</sub>	Input high voltage		0.7V <sub>CC</sub>		V <sub>CC</sub> + 0.5	V
V <sub>IL</sub>	Input low voltage		-0.5		0.3V <sub>CC</sub>	
V <sub>hys</sub>	Hysteresis of Schmitt trigger inputs		0.05V <sub>CC</sub> <sup>(1)</sup>			
V <sub>OL</sub>	Output low voltage	3mA, sink current	0		0.4	ns
t <sub>r</sub>	Rise time for both SDA and SCL		20 + 0.1C <sub>b</sub> <sup>(1)(2)</sup>		300	
t <sub>of</sub>	Output fall time from V <sub>IHmin</sub> to V <sub>ILmax</sub>	10pF < C <sub>b</sub> < 400pF <sup>(2)</sup>	20 + 0.1C <sub>b</sub> <sup>(1)(2)</sup>		250	
t <sub>SP</sub>	Spikes suppressed by input filter		0		50	
I <sub>I</sub>	Input current for each I/O pin	0.1V <sub>CC</sub> < V <sub>I</sub> < 0.9V <sub>CC</sub>	-10		10	μA
C <sub>I</sub>	Capacitance for each I/O pin				10	pF
f <sub>SCL</sub>	SCL clock frequency	f <sub>PER</sub> <sup>(3)</sup> > max(10f <sub>SCL</sub> , 250kHz)	0		400	kHz
R <sub>P</sub>	Value of pull-up resistor	f <sub>SCL</sub> ≤ 100kHz	$\frac{V_{CC} - 0.4V}{3mA}$		$\frac{100ns}{C_b}$	Ω
		f <sub>SCL</sub> > 100kHz			$\frac{300ns}{C_b}$	
t <sub>HD;STA</sub>	Hold time (repeated) START condition	f <sub>SCL</sub> ≤ 100kHz	4.0			μs
		f <sub>SCL</sub> > 100kHz	0.6			
t <sub>LOW</sub>	Low period of SCL clock	f <sub>SCL</sub> ≤ 100kHz	4.7			
		f <sub>SCL</sub> > 100kHz	1.3			
t <sub>HIGH</sub>	High period of SCL clock	f <sub>SCL</sub> ≤ 100kHz	4.0			
		f <sub>SCL</sub> > 100kHz	0.6			
t <sub>SU;STA</sub>	Set-up time for a repeated START condition	f <sub>SCL</sub> ≤ 100kHz	4.7			
		f <sub>SCL</sub> > 100kHz	0.6			
t <sub>HD;DAT</sub>	Data hold time	f <sub>SCL</sub> ≤ 100kHz	0		3.45	μs
		f <sub>SCL</sub> > 100kHz	0		0.9	
t <sub>SU;DAT</sub>	Data setup time	f <sub>SCL</sub> ≤ 100kHz	250			
		f <sub>SCL</sub> > 100kHz	100			
t <sub>SU;STO</sub>	Setup time for STOP condition	f <sub>SCL</sub> ≤ 100kHz	4.0			
		f <sub>SCL</sub> > 100kHz	0.6			
t <sub>BUF</sub>	Bus free time between a STOP and START condition	f <sub>SCL</sub> ≤ 100kHz	4.7			
		f <sub>SCL</sub> > 100kHz	1.3			

- Notes:
1. Required only for f<sub>SCL</sub> > 100kHz.
  2. C<sub>b</sub> = Capacitance of one bus line in pF.
  3. f<sub>PER</sub> = Peripheral clock frequency.69

**Table 32-173. SPI Timing Characteristics and Requirements**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$t_{SCK}$	SCK period	Master		(See Table 20-3 in XMEGA D manual)		ns
$t_{SCKW}$	SCK high/low width	Master		$0.5 * SCK$		
$t_{SCKR}$	SCK rise time	Master		2.7		
$t_{SCKF}$	SCK fall time	Master		2.7		
$t_{MIS}$	MISO setup to SCK	Master		10		
$t_{MIH}$	MISO hold after SCK	Master		10		
$t_{MOS}$	MOSI setup SCK	Master		$0.5 * SCK$		
$t_{MOH}$	MOSI hold after SCK	Master		1		
$t_{SSCK}$	Slave SCK Period	Slave	$4 * t_{Clk_{PER}}$			
$t_{SSCKW}$	SCK high/low width	Slave	$2 * t_{Clk_{PER}}$			
$t_{SSCKR}$	SCK rise time	Slave			1600	
$t_{SSCKF}$	SCK fall time	Slave			1600	
$t_{SIS}$	MOSI setup to SCK	Slave	3			
$t_{SIH}$	MOSI hold after SCK	Slave	$t_{Clk_{PER}}$			
$t_{SSS}$	$\overline{SS}$ setup to SCK	Slave	21			
$t_{SSH}$	$\overline{SS}$ hold after SCK	Slave	20			
$t_{SOS}$	MISO setup SCK	Slave		8		
$t_{SOH}$	MISO hold after SCK	Slave		13		
$t_{SOSS}$	MISO setup after $\overline{SS}$ low	Slave		11		
$t_{SOSSH}$	MISO hold after $\overline{SS}$ high	Slave		8		

**32.6.15 Two-wire Interface Characteristics**

Table 32-174 on page 176 describes the requirements for devices connected to the Two-Wire Interface Bus. The Atmel AVR XMEGA Two-Wire Interface meets or exceeds these requirements under the noted conditions. Timing symbols refer to Figure 32-42.

**Figure 32-42. Two-wire Interface Bus Timing**

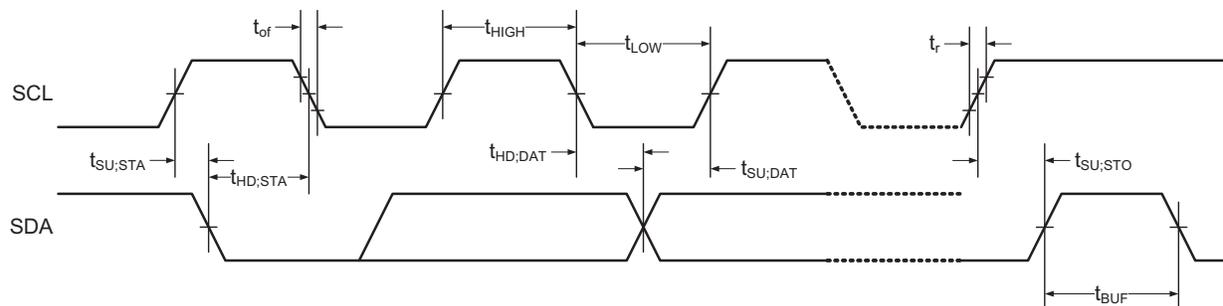
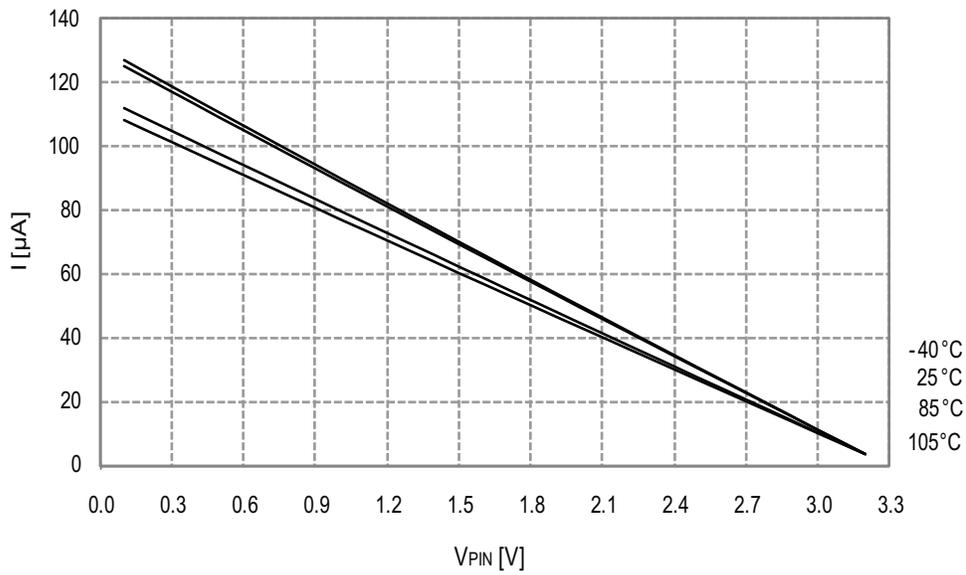


Figure 33-21. I/O Pin Pull-up Resistor Current vs. Input Voltage

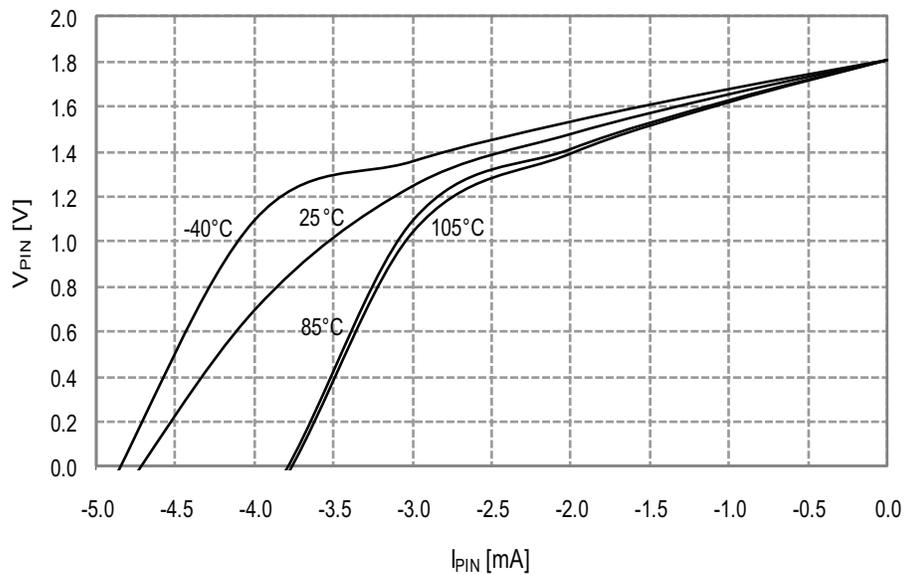
$V_{CC} = 3.3V$



### 33.1.2.2 Output Voltage vs. Sink/Source Current

Figure 33-22. I/O Pin Output Voltage vs. Source Current

$V_{CC} = 1.8V$



### 33.1.6 BOD Characteristics

Figure 33-47. BOD Thresholds vs. Temperature

*BOD level = 1.6V*

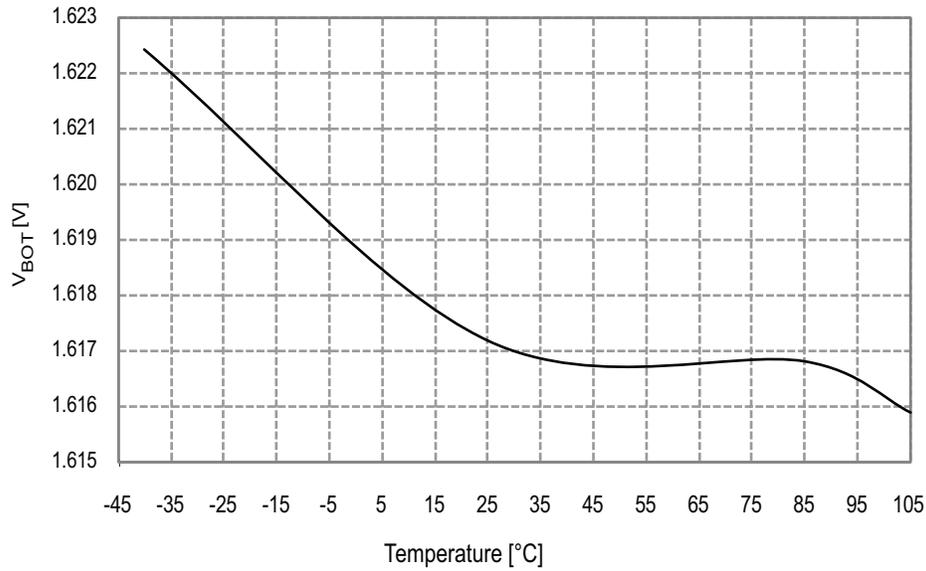
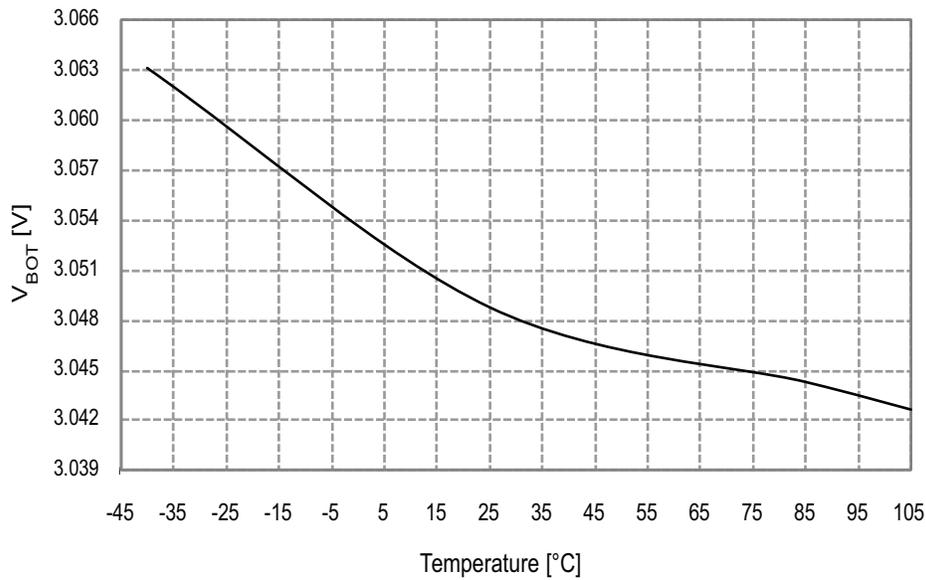


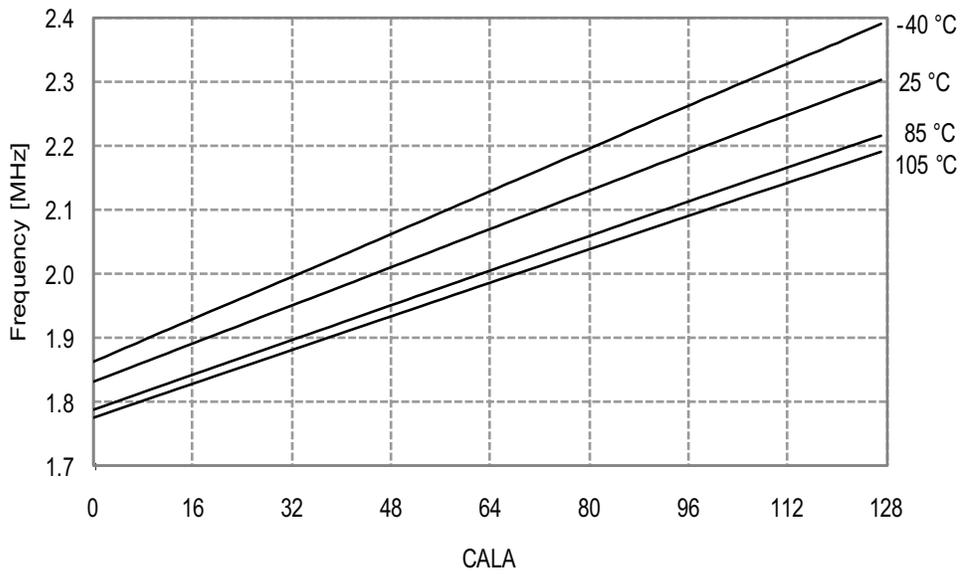
Figure 33-48. BOD Thresholds vs. Temperature

*BOD level = 3.0V*



**Figure 33-59. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value**

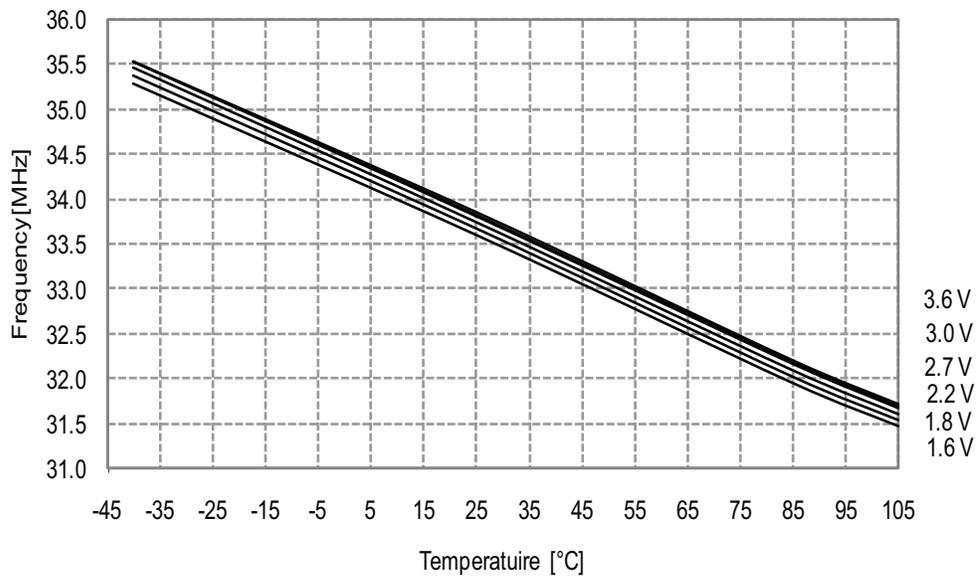
$V_{CC} = 3V$



#### 33.1.8.4 32MHz Internal Oscillator

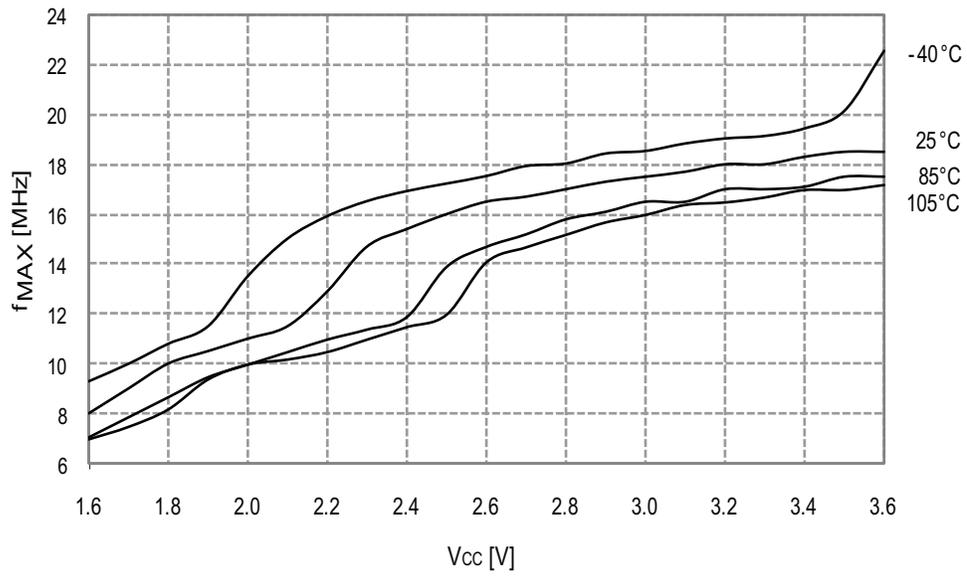
**Figure 33-60. 32MHz Internal Oscillator Frequency vs. Temperature**

*DFLL disabled*



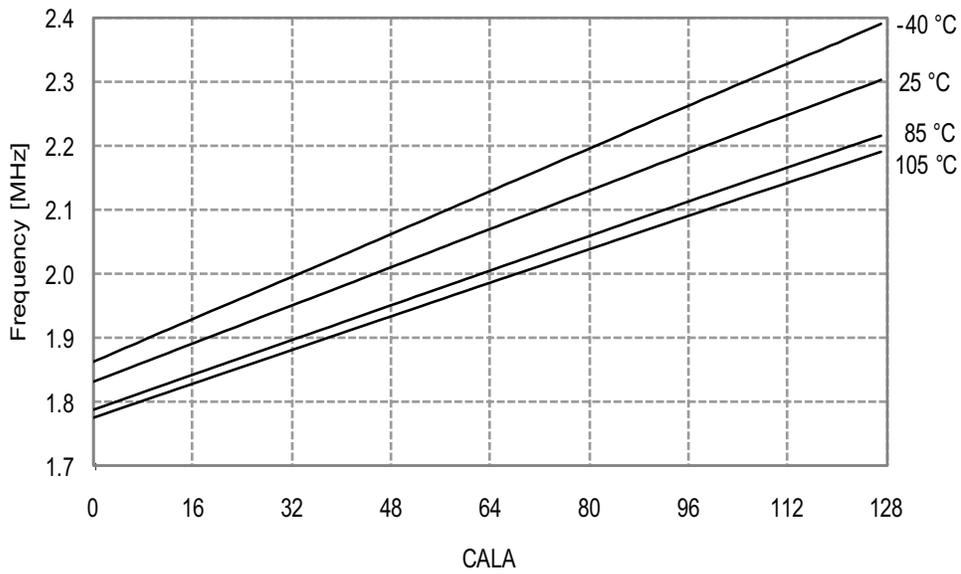
### 33.1.10 PDI Characteristics

Figure 33-71. Maximum PDI Frequency vs.  $V_{CC}$



**Figure 33-130. 2MHz Internal Oscillator Frequency vs. CALA Calibration Value**

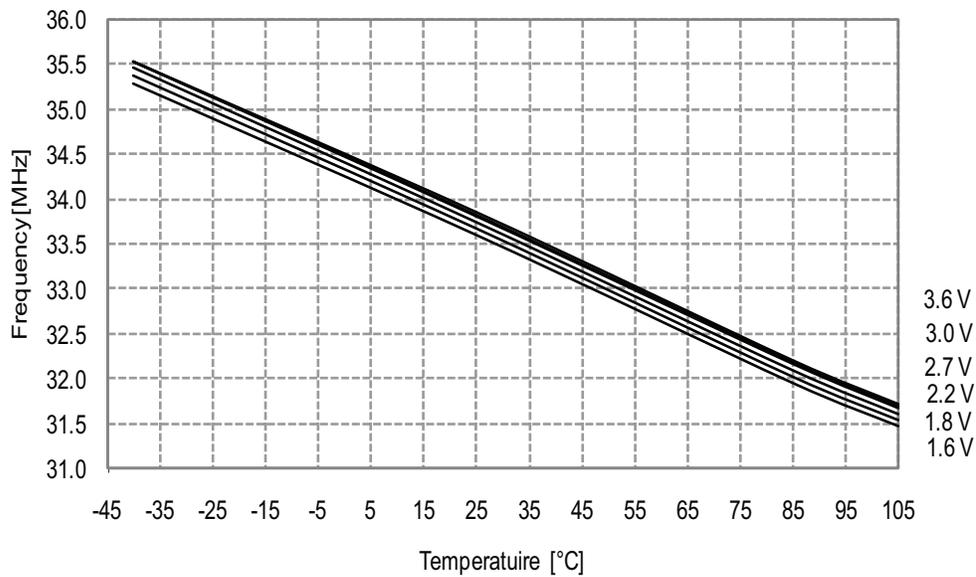
$V_{CC} = 3V$



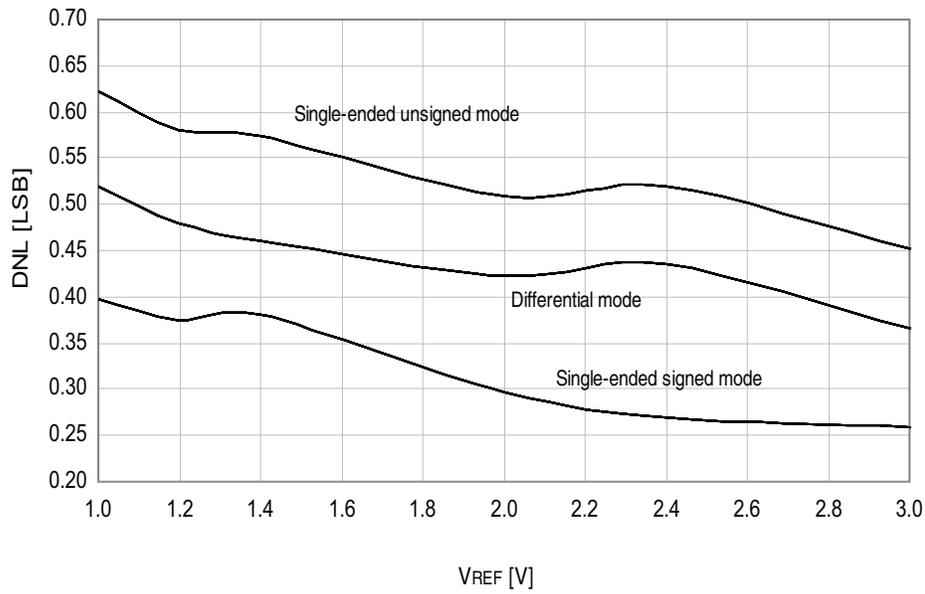
#### 33.2.8.4 32MHz Internal Oscillator

**Figure 33-131. 32MHz Internal Oscillator Frequency vs. Temperature**

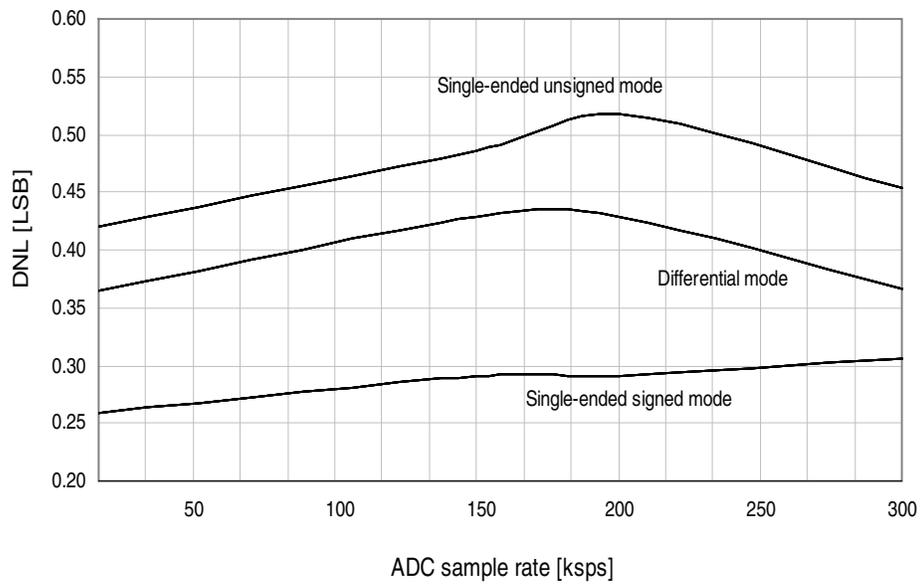
*DFLL disabled*



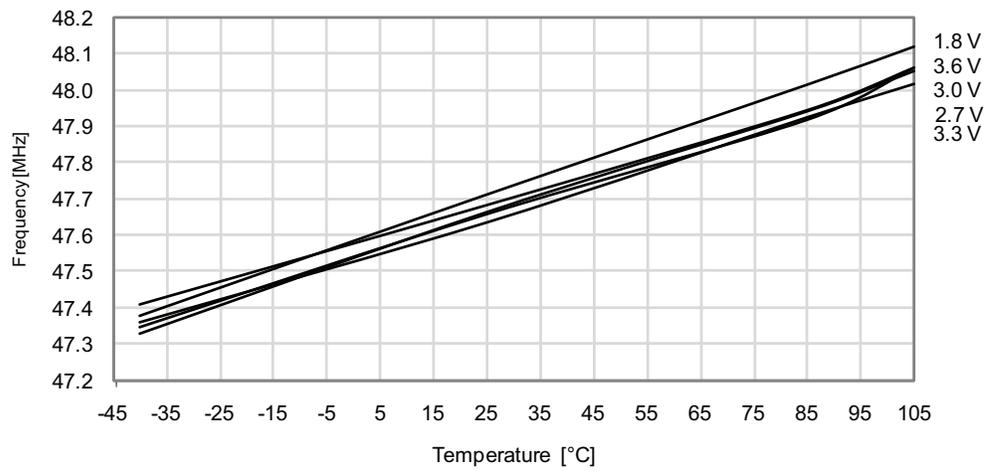
**Figure 33-175. DNL Error vs. External  $V_{REF}$**   
 $T = 25^{\circ}\text{C}$ ,  $V_{CC} = 3.6\text{V}$ , external reference



**Figure 33-176. DNL Error vs. Sample Rate**  
 $T = 25^{\circ}\text{C}$ ,  $V_{CC} = 3.6\text{V}$ ,  $V_{REF} = 3.0\text{V}$  external

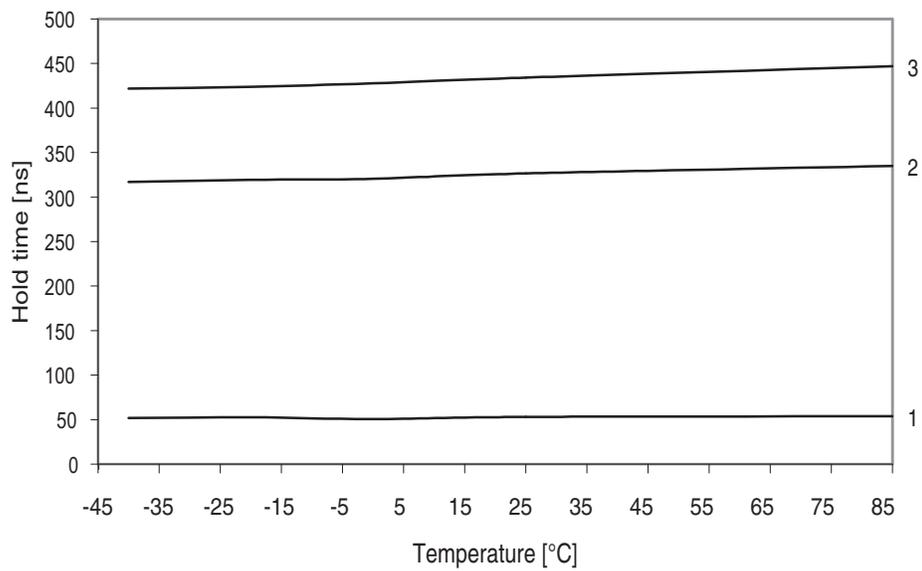


**Figure 33-209. 48MHz Internal Oscillator Frequency vs. Temperature**  
*DPLL enabled, from the 32.768kHz internal oscillator*



### 33.3.9 Two-Wire Interface Characteristics

**Figure 33-210. SDA Hold Time vs. Temperature**



### 33.4.2.2 Output Voltage vs. Sink/Source Current

Figure 33-233.I/O Pin Output Voltage vs. Source Current

$V_{CC} = 1.8V$

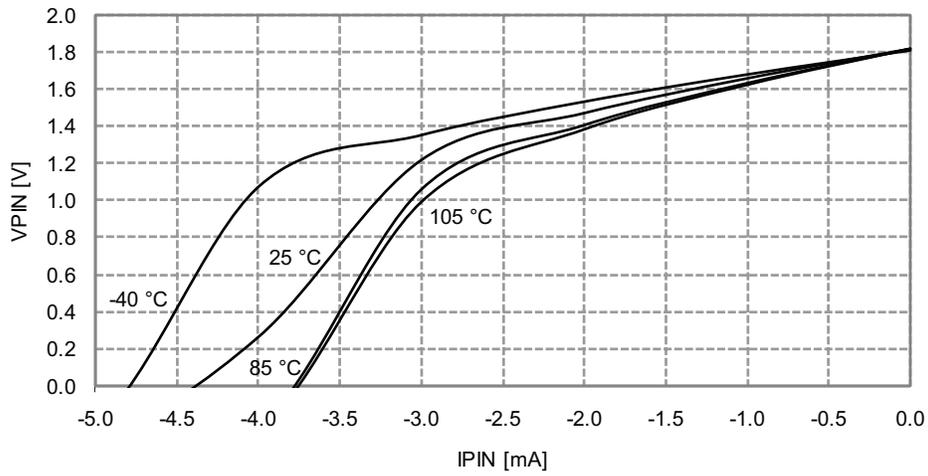


Figure 33-234.I/O Pin Output Voltage vs. Source Current

$V_{CC} = 3.0V$

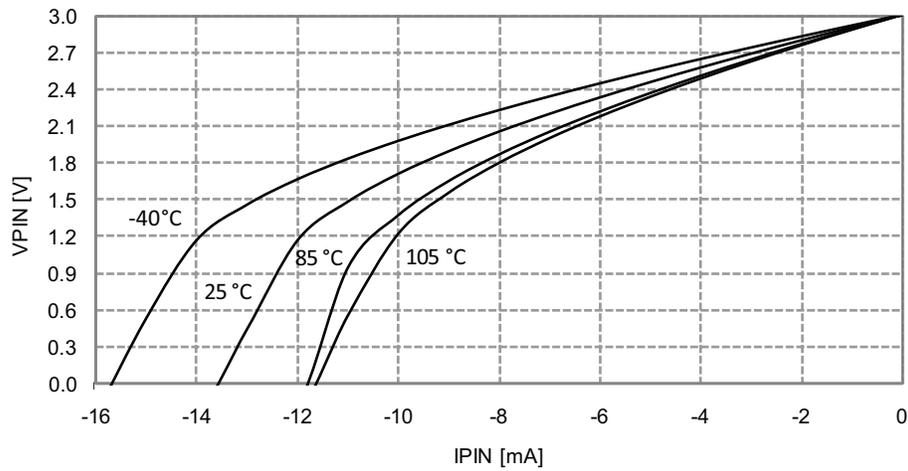


Figure 33-235. I/O Pin Output Voltage vs. Source Current

$V_{CC} = 3.3V$

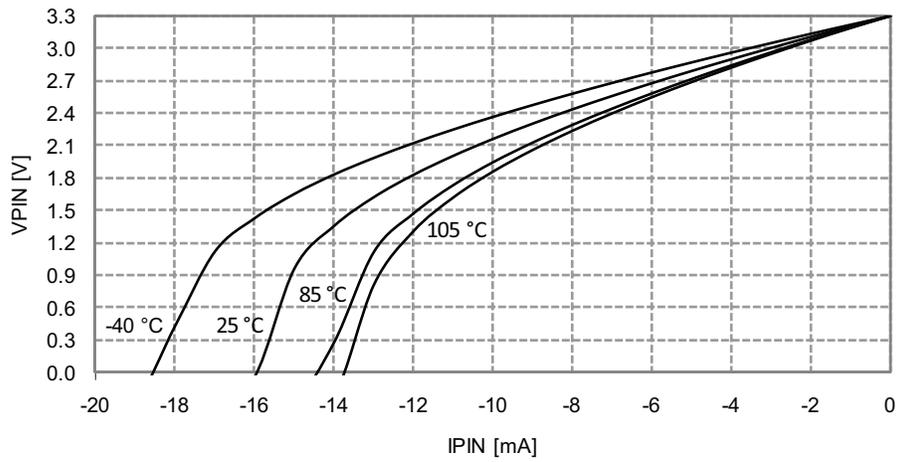
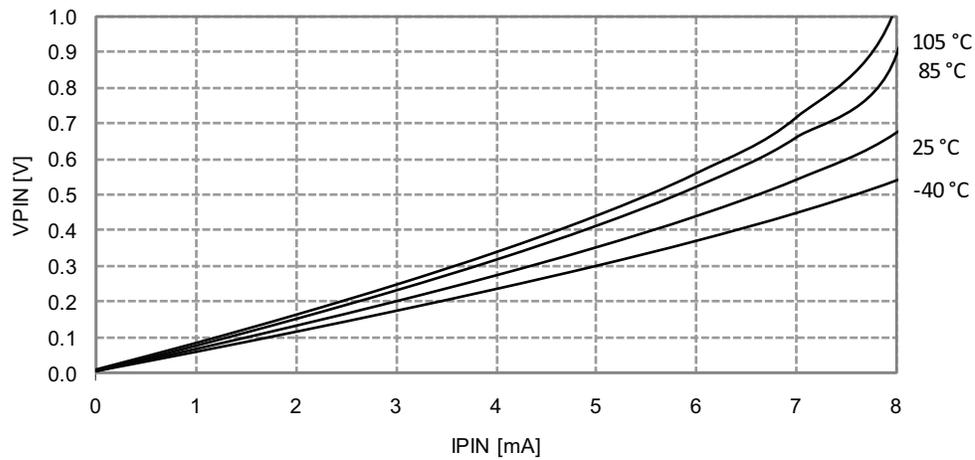


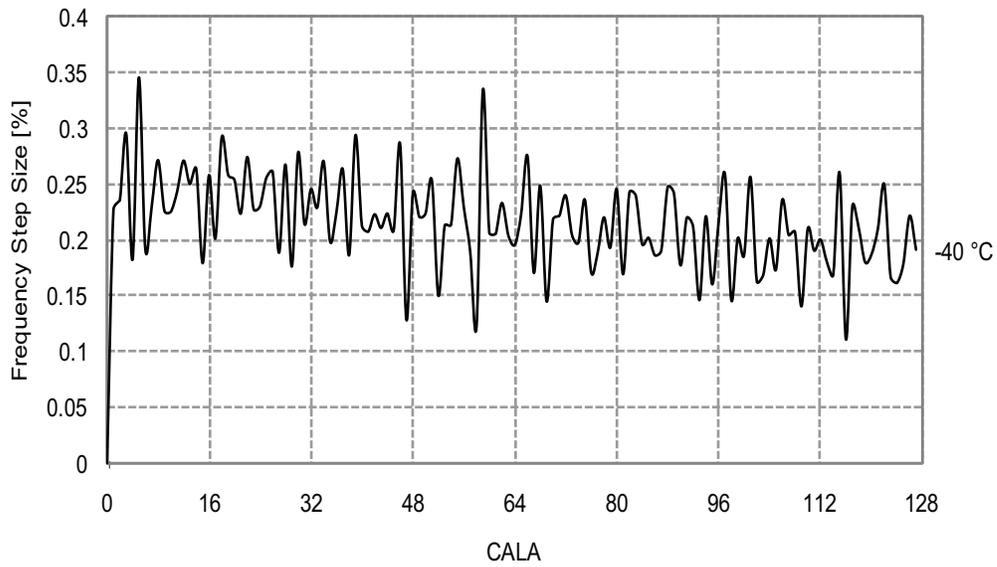
Figure 33-236. I/O Pin Output Voltage vs. Sink Current

$V_{CC} = 1.8V$



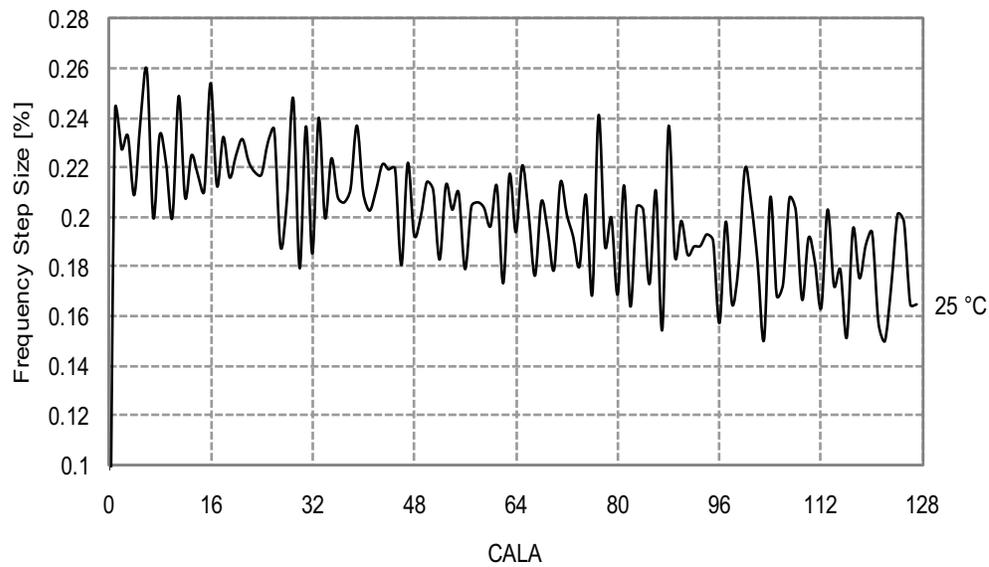
**Figure 33-273. 32MHz Internal Oscillator CALA Calibration Step Size**

*T = -40°C, V<sub>CC</sub> = 3.0V*



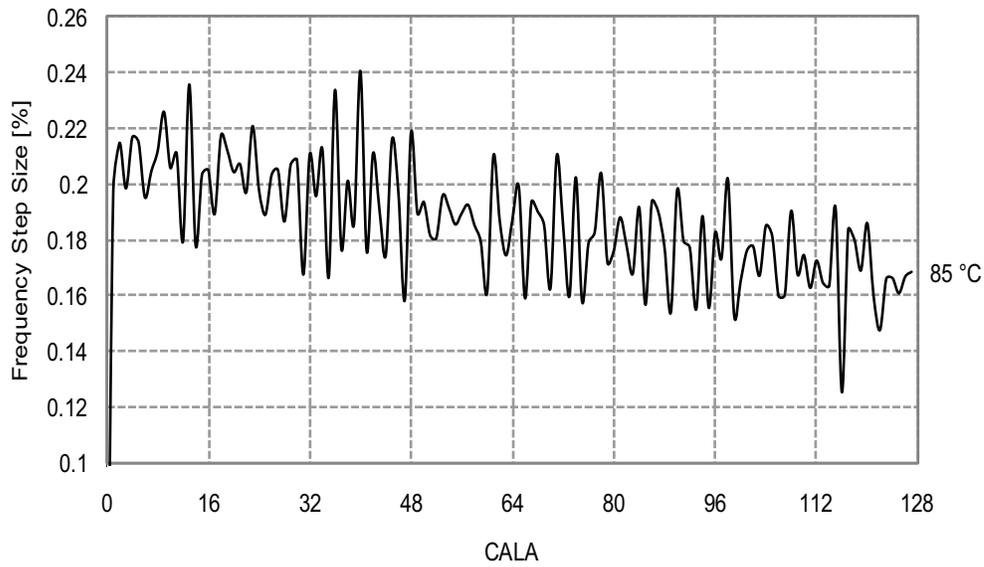
**Figure 33-274. 32MHz Internal Oscillator CALA Calibration Step Size**

*T = 25°C, V<sub>CC</sub> = 3.0V*



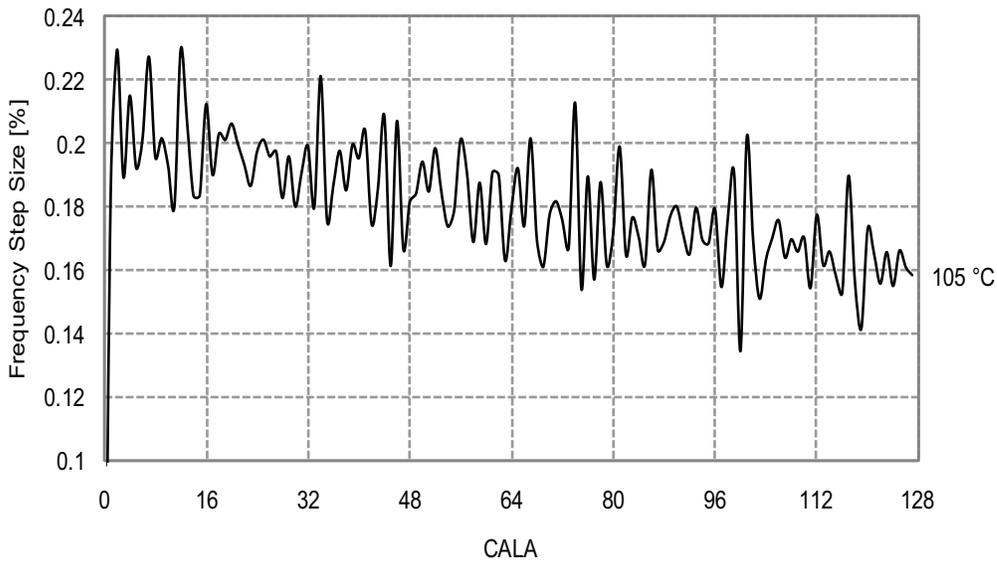
**Figure 33-345. 32MHz Internal Oscillator CALA Calibration Step Size**

$T = 85^{\circ}\text{C}$ ,  $V_{CC} = 3.0\text{V}$

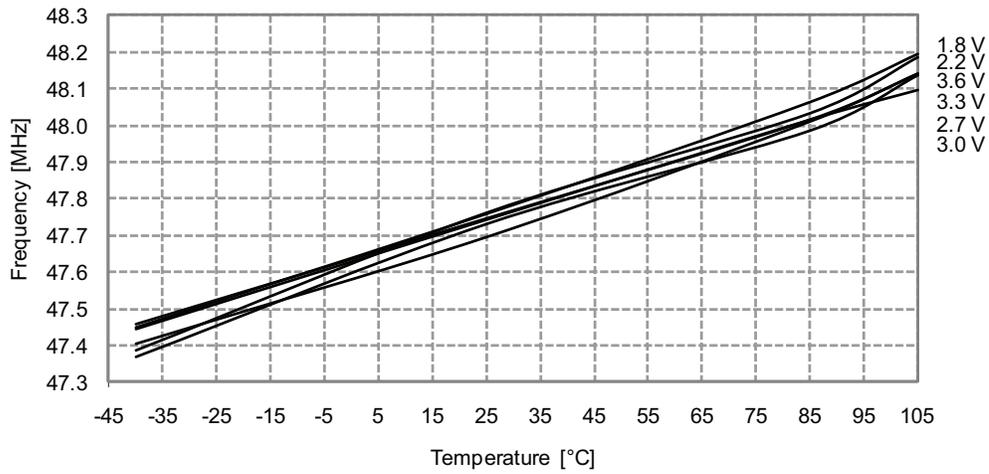


**Figure 33-346. 32MHz Internal Oscillator CALA Calibration Step Size**

$T = 105^{\circ}\text{C}$ ,  $V_{CC} = 3.0\text{V}$

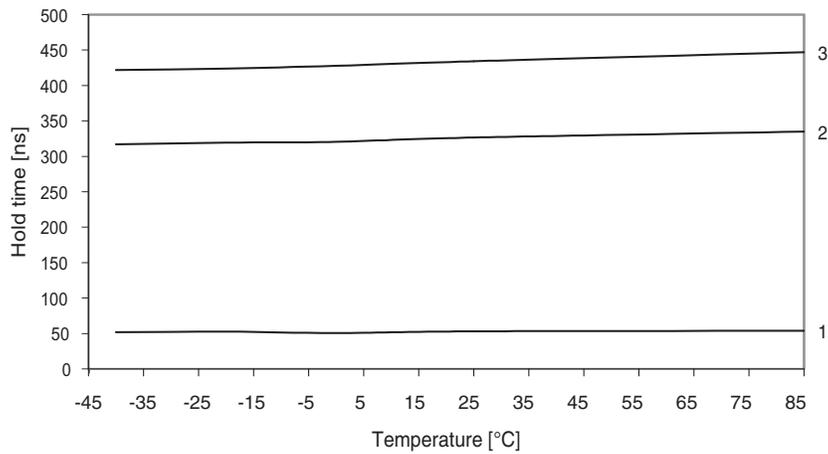


**Figure 33-349. 48MHz Internal Oscillator Frequency vs. Temperature**  
*DPLL enabled, from the 32.768kHz internal oscillator*



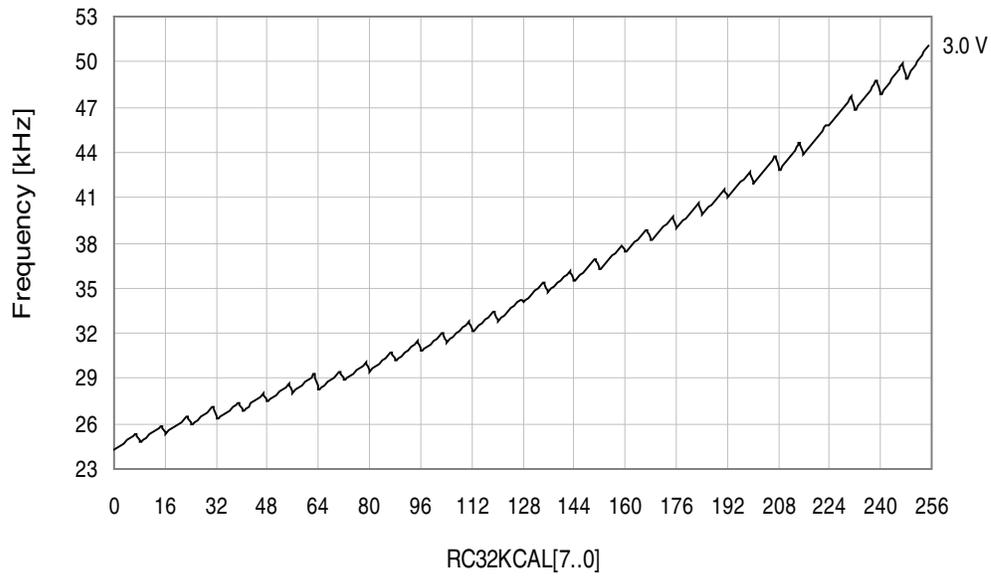
### 33.5.9 Two-Wire Interface Characteristics

**Figure 33-350. SDA Hold Time vs. Temperature**



**Figure 33-407. 32.768kHz Internal Oscillator Frequency vs. Calibration Value**

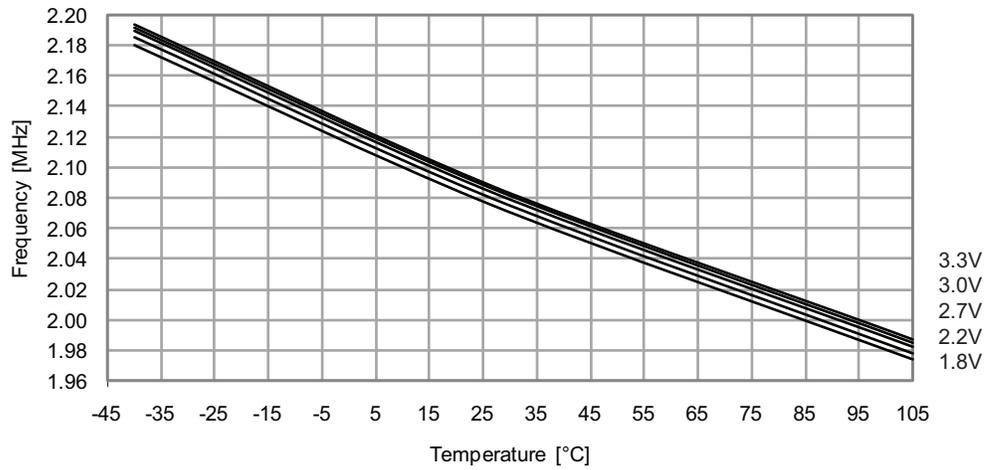
$V_{CC} = 3.0V, T = 25^{\circ}C$



### 33.6.8.3 2MHz Internal Oscillator

**Figure 33-408. 2MHz Internal Oscillator Frequency vs. Temperature**

*DFLL disabled*



## Problem fix/workaround

Table 34-7. Configure PWM and CWCM According to this Table:

PGM	CWCM	Description
0	0	PGM and CWCM disabled
0	1	PGM enabled
1	0	PGM and CWCM enabled
1	1	PGM enabled

### 11. PWM is not restarted properly after a fault in cycle-by-cycle mode

When the AWeX fault restore mode is set to cycle-by-cycle, the waveform output will not return to normal operation at first update after fault condition is no longer present.

#### Problem fix/workaround

Do a write to any AWeX I/O register to re-enable the output.

### 12. BOD will be enabled after any reset

If any reset source goes active, the BOD will be enabled and keep the device in reset if the  $V_{CC}$  voltage is below the programmed BOD level. During Power-On Reset, reset will not be released until  $V_{CC}$  is above the programmed BOD level even if the BOD is disabled.

#### Problem fix/workaround

Do not set the BOD level higher than  $V_{CC}$  even if the BOD is not used.

### 13. EEPROM page buffer always written when NVM DATA0 is written

If the EEPROM is memory mapped, writing to NVM DATA0 will corrupt data in the EEPROM page buffer.

#### Problem fix/workaround

Before writing to NVM DATA0, for example when doing software CRC or flash page buffer write, check if EEPROM page buffer active loading flag (EELoad) is set. Do not write NVM DATA0 when EELoad is set.

### 14. Pending full asynchronous pin change interrupts will not wake the device

Any full asynchronous pin-change Interrupt from pin 2, on any port, that is pending when the sleep instruction is executed, will be ignored until the device is woken from another source or the source triggers again. This applies when entering all sleep modes where the System Clock is stopped.

#### Problem fix/workaround

None.

### 15. Pin configuration does not affect Analog Comparator output

The Output/Pull and inverted pin configuration does not affect the Analog Comparator output.

#### Problem fix/workaround

None for Output/Pull configuration.

For inverted I/O, configure the Analog Comparator to give an inverted result (that is, connect positive input to the negative AC input and vice versa), or use an external inverter to change polarity of Analog Comparator output.

```

        if ( !(COMMS_PORT.IN & PIN1_bm) )
            if ( !(COMMS_PORT.IN & PIN1_bm) )
                break;
    }
    /* Check for an pending address match interrupt */
    if ( !(COMMS_TWI.SLAVE.STATUS & TWI_SLAVE_CLKHOLD_bm) )
    {
        /* Safely clear interrupt flag */
        COMMS_TWI.SLAVE.STATUS |= (uint8_t)TWI_SLAVE_APIF_bm;
    }

```

## 21. TWI START condition at bus timeout will cause transaction to be dropped

If Bus Timeout is enabled and a timeout occurs on the same Peripheral Clock cycle as a START is detected, the transaction will be dropped.

### Problem fix/workaround

None.

## 22. TWI Data Interrupt Flag erroneously read as set

When issuing the TWI slave response command CMD=0b11, it takes one Peripheral Clock cycle to clear the data interrupt flag (DIF). A read of DIF directly after issuing the command will show the DIF still set.

### Problem fix/workaround

Add one NOP instruction before checking DIF.

## 23. WDR instruction inside closed window will not issue reset

When a WDR instruction is execute within one ULP clock cycle after updating the window control register, the counter can be cleared without giving a system reset.

### Problem fix/workaround

Wait at least one ULP clock cycle before executing a WDR instruction.

## 24. Non available functions and options

The below function and options are not available. Writing to any registers or fuse to try and enable or configure these functions or options will have no effect, and will be as writing to a reserved address location.

- TWIE, the TWI module on PORTE
- TWI SDAHOLD option in the TWI CTRL register is one bit
- CRC generator module
- ADC 1/2× gain option, and this configuration option in the GAIN bits in the ADC Channel CTRL register
- ADC VCC/2 reference option and this configuration option in the REFSEL bits on the ADC REFCTRL register
- ADC option to use internal Gnd as negative input in differential measurements and this configuration option in the MUXNEG bits in the ADC Channel MUXCTRL register
- ADC channel scan and the ADC SCAN register
- ADC current limitation option, and the CURRLIMIT bits in the ADC CTRLB register
- ADC impedance mode selection for the gain stage, and the IMPMODE bit in the ADC CTRLB register
- Timer/Counter 2 and the SPLITMODE configuration option in the BYTEM bits in the Timer/Counter 0 CTRL register
- Analog Comparator (AC) current output option, and the AC CURRCTRL and CURRCALIB registers