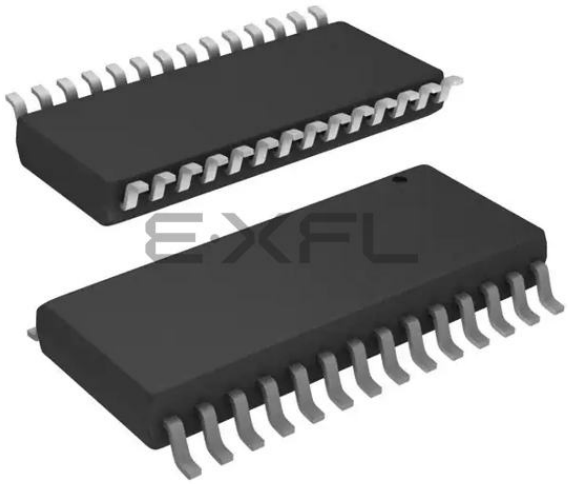

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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	25
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 24x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf18854-e-so

TABLE 1-2: PIC16F18854 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
RB7/ANB7/DAC1OUT2/T6IN(1)/ CLCIN3(1)/IOCB7/ICSPDAT	RB7	TTL/ST	CMOS/OD	General purpose I/O.
	ANB7	AN	—	ADC Channel B7 input.
	DAC1OUT2	—	AN	Digital-to-Analog Converter output.
	T6IN(1)	TTL/ST	—	Timer6 external digital clock input.
	CLCIN3(1)	TTL/ST	—	Configurable Logic Cell source input.
	IOCB7	TTL/ST	—	Interrupt-on-change input.
	ICSPDAT	ST	CMOS	In-Circuit Serial Programming™ and debugging data input/output.
RC0/ANC0/T1CKI(1)/T3CKI(1)/T3G(1)/ SMTWIN1(1)/IOCC0/SOSCO	RC0	TTL/ST	CMOS/OD	General purpose I/O.
	ANC0	AN	—	ADC Channel C0 input.
	T1CKI(1)	TTL/ST	—	Timer1 external digital clock input.
	T3CKI(1)	TTL/ST	—	Timer3 external digital clock input.
	T3G(1)	TTL/ST	—	Timer3 gate input.
	SMTWIN1(1)	TTL/ST	—	Signal Measurement Timer1 (SMT1) input.
	IOCC0	TTL/ST	—	Interrupt-on-change input.
	SOSCO	—	AN	32.768 kHz secondary oscillator crystal driver output.
RC1/ANC1/SMTSIG1(1)/CCP2(1)/ IOCC1/SOSCI	RC1	TTL/ST	CMOS/OD	General purpose I/O.
	ANC1	AN	—	ADC Channel C1 input.
	SMTSIG1(1)	TTL/ST	—	Signal Measurement Timer1 (SMT1) signal input.
	CCP2(1)	TTL/ST	CMOS/OD	Capture/compare/PWM2 (default input location for capture function).
	IOCC1	TTL/ST	—	Interrupt-on-change input.
	SOSCI	AN	—	32.768 kHz secondary oscillator crystal driver input.
RC2/ANC2/T5CKI(1)/CCP1(1)/IOCC2	RC2	TTL/ST	CMOS/OD	General purpose I/O.
	ANC2	AN	—	ADC Channel C2 input.
	T5CKI(1)	TTL/ST	—	Timer5 external digital clock input.
	CCP1(1)	TTL/ST	CMOS/OD	Capture/compare/PWM1 (default input location for capture function).
	IOCC2	TTL/ST	—	Interrupt-on-change input.
RC3/ANC3/SCL1(3,4)/SCK1(1)/T2IN(1)/ IOCC3	RC3	TTL/ST	CMOS/OD	General purpose I/O.
	ANC3	AN	—	ADC Channel C3 input.
	SCL1(3,4)	I^2C/ SMBus	OD	MSSP1 I^2C clock input/output.
	SCK1(1)	TTL/ST	CMOS/OD	MSSP1 SPI clock input/output (default input location, SCK1 is a PPS remappable input and output).
	T2IN(1)	TTL/ST	—	Timer2 external input.
	IOCC3	TTL/ST	—	Interrupt-on-change input.

Legend: AN = Analog input or output; CMOS = CMOS compatible input or output; OD = Open-Drain
TTL = TTL compatible input; ST = Schmitt Trigger input with CMOS levels; I^2C = Schmitt Trigger input with I^2C
HV = High Voltage; XTAL = Crystal levels

Note 1: This is a PPS remappable input signal. The input function may be moved from the default location shown to one of several other PORTx pins. Refer to Table 13-1 for details on which PORT pins may be used for this signal.

2: All output signals shown in this row are PPS remappable. These signals may be mapped to output onto one of several PORTx pin options as described in Table 13-3.

3: This is a bidirectional signal. For normal module operation, the firmware should map this signal to the same pin in both the PPS input and PPS output registers.

4: These pins are configured for I^2C logic levels. The SCLx/SDAx signals may be assigned to any of the RB1/RB2/RC3/RC4 pins. PPS assignments to the other pins (e.g., RA5) will operate, but input logic levels will be standard TTL/ST, as selected by the INLVL register, instead of the I^2C specific or SMBus input buffer thresholds.

5.2.3 BOR CONTROLLED BY SOFTWARE

When the BOREN bits of Configuration Words are programmed to '01', the BOR is controlled by the SBOREN bit of the BORCON register. The device start-up is not delayed by the BOR ready condition or the VDD level.

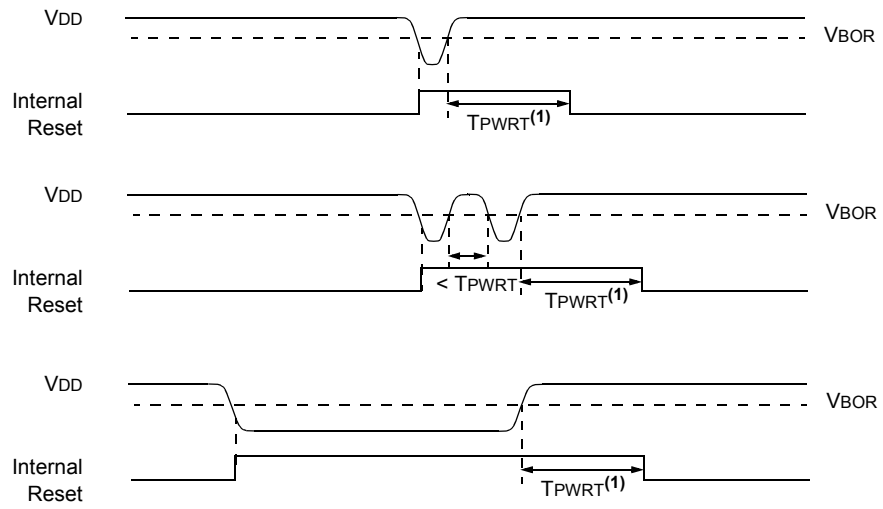
BOR protection begins as soon as the BOR circuit is ready. The status of the BOR circuit is reflected in the BORRDY bit of the BORCON register.

BOR protection is unchanged by Sleep.

5.2.4 BOR IS ALWAYS OFF

When the BOREN bits of the Configuration Words are programmed to '00', the BOR is off at all times. The device start-up is not delayed by the BOR ready condition or the VDD level.

FIGURE 5-2: BROWN-OUT SITUATIONS



Note 1: TPWRT delay only if $\overline{\text{PWRTE}}$ bit is programmed to '0'.

6.0 OSCILLATOR MODULE (WITH FAIL-SAFE CLOCK MONITOR)

6.1 Overview

The oscillator module has a wide variety of clock sources and selection features that allow it to be used in a wide range of applications while maximizing performance and minimizing power consumption. Figure 6-1 illustrates a block diagram of the oscillator module.

Clock sources can be supplied from external oscillators, quartz-crystal resonators and ceramic resonators. In addition, the system clock source can be supplied from one of two internal oscillators and PLL circuits, with a choice of speeds selectable via software. Additional clock features include:

- Selectable system clock source between external or internal sources via software.
- Fail-Safe Clock Monitor (FSCM) designed to detect a failure of the external clock source (LP, XT, HS, ECH, ECM, ECL) and switch automatically to the internal oscillator.
- Oscillator Start-up Timer (OST) ensures stability of crystal oscillator sources.

The RSTOSC bits of Configuration Word 1 determine the type of oscillator that will be used when the device reset, including when it is first powered up.

The internal clock modes, LFINTOSC, HFINTOSC (set at 1 MHz), or HFINTOSC (set at 32 MHz) can be set through the RSTOSC bits.

If an external clock source is selected, the FEXTOSC bits of Configuration Word 1 must be used in conjunction with the RSTOSC bits to select the external clock mode.

The external oscillator module can be configured in one of the following clock modes, by setting the FEXTOSC<2:0> bits of Configuration Word 1:

1. ECL – External Clock Low-Power mode (below 500 kHz)
2. ECM – External Clock Medium Power mode (500 kHz to 8 MHz)
3. ECH – External Clock High-Power mode (above 8 MHz)
4. LP – 32 kHz Low-Power Crystal mode.
5. XT – Medium Gain Crystal or Ceramic Resonator Oscillator mode (between 100 kHz and 4 MHz)
6. HS – High Gain Crystal or Ceramic Resonator mode (above 4 MHz)

The ECH, ECM, and ECL clock modes rely on an external logic level signal as the device clock source. The LP, XT, and HS clock modes require an external crystal or resonator to be connected to the device. Each mode is optimized for a different frequency range. The INTOSC internal oscillator block produces low and high-frequency clock sources, designated LFINTOSC and HFINTOSC. (see Internal Oscillator Block, Figure 6-1). A wide selection of device clock frequencies may be derived from these clock sources.

REGISTER 6-4: OSCSTAT: OSCILLATOR STATUS REGISTER 1

R-q/q	R-0/q	R-0/q	R-0/q	R-q/q	R-q/q	U-0	R-q/q
EXTOR	HFOR	MFOR	LFOR	SOR	ADOR	—	PLLR
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **EXTOR:** EXTOSC (external) Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used.

bit 6 **HFOR:** HFINTOSC Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used.

bit 5 **MFOR:** MFINTOSC Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used

bit 4 **LFOR:** LFINTOSC Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used.

bit 3 **SOR:** Secondary (Timer1) Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used.

bit 2 **ADOR:** CRC Oscillator Ready bit
1 = The oscillator is ready to be used
0 = The oscillator is not enabled, or is not yet ready to be used

bit 1 **Unimplemented:** Read as '0'

bit 0 **PLLR:** PLL is Ready bit
1 = The PLL is ready to be used
0 = The PLL is not enabled, the required input source is not ready, or the PLL is not locked.

REGISTER 7-2: PIE0: PERIPHERAL INTERRUPT ENABLE REGISTER 0

U-0	U-0	R/W-0/0	R/W-0/0	U-0	U-0	U-0	R/W-0/0
—	—	TMR0IE	IOCIE	—	—	—	INTE
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS = Hardware set

bit 7-6 **Unimplemented**: Read as '0'

bit 5 **TMR0IE:** TMR0 Overflow Interrupt Enable bit
- 1 = Enables the TMR0 interrupt
- 0 = Disables the TMR0 interrupt

bit 4 **IOCIE:** Interrupt-on-Change Interrupt Enable bit
- 1 = Enables the IOC change interrupt
- 0 = Disables the IOC change interrupt

bit 3-1 **Unimplemented**: Read as '0'

bit 0 **INTE:** INT External Interrupt Flag bit(1)
- 1 = Enables the INT external interrupt
- 0 = Disables the INT external interrupt

Note 1: The External Interrupt GPIO pin is selected by INTPPS (Register 13-1).

Note: Bit PEIE of the INTCON register must be set to enable any peripheral interrupt controlled by PIE1-PIE8. Interrupt sources controlled by the PIE0 register do not require PEIE to be set in order to allow interrupt vectoring (when GIE is set).

REGISTER 7-14: PIR3: PERIPHERAL INTERRUPT REQUEST REGISTER 3

U-0	U-0	R-0	R-0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
—	—	RCIF	TXIF	BCL2IF	SSP2IF	BCL1IF	SSP1IF
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HS = Hardware clearable

bit 7-6 **Unimplemented:** Read as '0'

bit 5 **RCIF:** EUSART Receive Interrupt Flag (read-only) bit (1)
- 1 = The EUSART receive buffer is not empty (contains at least one byte)
- 0 = The EUSART receive buffer is empty

bit 4 **TXIF:** EUSART Transmit Interrupt Flag (read-only) bit(2)
- 1 = The EUSART transmit buffer contains at least one unoccupied space
- 0 = The EUSART transmit buffer is currently full. The application firmware should not write to TXREG again, until more room becomes available in the transmit buffer.

bit 3 **BCL2IF:** MSSP2 Bus Collision Interrupt Flag bit
- 1 = A bus collision was detected (must be cleared in software)
- 0 = No bus collision was detected

bit 2 **SSP2IF:** Synchronous Serial Port (MSSP2) Interrupt Flag bit
- 1 = The Transmission/Reception/Bus Condition is complete (must be cleared in software)
- 0 = Waiting for the Transmission/Reception/Bus Condition in progress

bit 1 **BCL1IF:** MSSP1 Bus Collision Interrupt Flag bit
- 1 = A bus collision was detected (must be cleared in software)
- 0 = No bus collision was detected

bit 0 **SSP1IF:** Synchronous Serial Port (MSSP1) Interrupt Flag bit
- 1 = The Transmission/Reception/Bus Condition is complete (must be cleared in software)
- 0 = Waiting for the Transmission/Reception/Bus Condition in progress

Note 1: The RCIF flag is a read-only bit. To clear the RCIF flag, the firmware must read from RCREG enough times to remove all bytes from the receive buffer.

2: The TXIF flag is a read-only bit, indicating if there is room in the transmit buffer. To clear the TXIF flag, the firmware must write enough data to TXREG to completely fill all available bytes in the buffer. The TXIF flag does not indicate transmit completion (use TRMT for this purpose instead).

Note: Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE, of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt.

REGISTER 11-11: SCANCON0: SCANNER ACCESS CONTROL REGISTER 0

R/W-0/0	R/W/HC-0/0	R-0	R-0	R/W-0/0	U-0	R/W-0/0	R/W-0/0
EN(1)	SCANGO(2, 3)	BUSY(4)	INVALID	INTM	—	MODE<1:0>(5)	
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	HC = Bit is cleared by hardware

bit 7 **EN:** Scanner Enable bit(1)
- 1 = Scanner is enabled
- 0 = Scanner is disabled, internal states are reset

bit 6 **SCANGO:** Scanner GO bit(2, 3)
- 1 = When the CRC sends a ready signal, NVM will be accessed according to MDx and data passed to the client peripheral.
- 0 = Scanner operations will not occur

bit 5 **BUSY:** Scanner Busy Indicator bit(4)
- 1 = Scanner cycle is in process
- 0 = Scanner cycle is complete (or never started)

bit 4 **INVALID:** Scanner Abort signal bit
- 1 = SCANLADRL/H has incremented or contains an invalid address(6)
- 0 = SCANLADRL/H points to a valid address

bit 3 **INTM:** NVM Scanner Interrupt Management Mode Select bit

If MODE = 10:

This bit is ignored

If MODE = 01 (CPU is stalled until all data is transferred):
- 1 = SCANGO is overridden (to zero) during interrupt operation; scanner resumes after returning from interrupt
- 0 = SCANGO is not affected by interrupts, the interrupt response will be affected

If MODE = 00 or 11:
- 1 = SCANGO is overridden (to zero) during interrupt operation; scan operations resume after returning from interrupt
- 0 = Interrupts do not prevent NVM access

bit 2 **Unimplemented:** Read as '0'

bit 1-0 **MODE<1:0>:** Memory Access Mode bits(5)
- 11 = Triggered mode
- 10 = Peek mode
- 01 = Burst mode
- 00 = Concurrent mode

Note 1: Setting EN = 0 (SCANCON0 register) does not affect any other register content.

2: This bit is cleared when LADR > HADR (and a data cycle is not occurring).

3: If INTM = 1, this bit is overridden (to zero, but not cleared) during an interrupt response.

4: BUSY = 1 when the NVM is being accessed, or when the CRC sends a ready signal.

5: See Table 11-1 for more detailed information.

6: An invalid address happens when the entire range of the PFM is scanned and completed, i.e., device memory is 0x4000 and SCANHADR = 0x3FFF, after the last scan SCANLADR increments to 0x4000, the address is invalid.

14.0 PERIPHERAL MODULE DISABLE

The PIC16F18855/75 provides the ability to disable selected modules, placing them into the lowest possible Power mode.

For legacy reasons, all modules are ON by default following any Reset.

14.1 Disabling a Module

Disabling a module has the following effects:

- All clock and control inputs to the module are suspended; there are no logic transitions, and the module will not function.
- The module is held in Reset.
- Any SFRs become “unimplemented”
  - Writing is disabled
  - Reading returns 00h
- Module outputs are disabled; I/O goes to the next module according to pin priority

14.2 Enabling a module

When the register bit is cleared, the module is re-enabled and will be in its Reset state; SFR data will reflect the POR Reset values.

Depending on the module, it may take up to one full instruction cycle for the module to become active. There should be no interaction with the module (e.g., writing to registers) for at least one instruction after it has been re-enabled.

14.3 Disabling a Module

When a module is disabled, any and all associated input selection registers (ISMs) are also disabled.

14.4 System Clock Disable

Setting SYSCMD (PMD0, Register 14-1) disables the system clock (FOSC) distribution network to the peripherals. Not all peripherals make use of SYSCLK, so not all peripherals are affected. Refer to the specific peripheral description to see if it will be affected by this bit.

20.0 COMPLEMENTARY WAVEFORM GENERATOR (CWG) MODULE

The Complementary Waveform Generator (CWG) produces half-bridge, full-bridge, and steering of PWM waveforms. It is backwards compatible with previous ECCP functions.

The CWG has the following features:

- Six operating modes:
  - Synchronous Steering mode
  - Asynchronous Steering mode
  - Full-Bridge mode, Forward
  - Full-Bridge mode, Reverse
  - Half-Bridge mode
  - Push-Pull mode
- Output polarity control
- Output steering
  - Synchronized to rising event
  - Immediate effect
- Independent 6-bit rising and falling event dead-band timers
  - Clocked dead band
  - Independent rising and falling dead-band enables
- Auto-shutdown control with:
  - Selectable shutdown sources
  - Auto-restart enable
  - Auto-shutdown pin override control

The CWG modules available are shown in Table 20-1.

TABLE 20-1: AVAILABLE CWG MODULES

Device	CWG1	CWG2	CWG2
PIC16(L)F18854	●	●	●

20.1 Fundamental Operation

The CWG module can operate in six different modes, as specified by MODE of the CWGxCON0 register:

- Half-Bridge mode (Figure 20-9)
- Push-Pull mode (Figure 20-2)
  - Full-Bridge mode, Forward (Figure 20-3)
  - Full-Bridge mode, Reverse (Figure 20-3)
- Steering mode (Figure 20-10)
- Synchronous Steering mode (Figure 20-11)

It may be necessary to guard against the possibility of circuit faults or a feedback event arriving too late or not at all. In this case, the active drive must be terminated before the Fault condition causes damage. Thus, all output modes support auto-shutdown, which is covered in **20.10 “Auto-Shutdown”**.

20.1.1 HALF-BRIDGE MODE

In Half-Bridge mode, two output signals are generated as true and inverted versions of the input as illustrated in Figure 20-9. A non-overlap (dead-band) time is inserted between the two outputs to prevent shoot through current in various power supply applications. Dead-band control is described in **Section 20.5 “Dead-Band Control”**.

The unused outputs CWGxC and CWGxD drive similar signals, with polarity independently controlled by the POLC and POLD bits of the CWGxCON1 register, respectively.

REGISTER 20-8: CWGxCLK: CWGx CLOCK SELECTION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0/0
—	—	—	—	—	—	—	CS
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	q = Value depends on condition

bit 7-1 **Unimplemented:** Read as ‘0’

bit 0 **CS:** CWGx Clock Selection bit
1 = HFINTOSC 16 MHz is selected
0 = FOSC is selected

REGISTER 20-9: CWGxISM: CWGx INPUT SELECTION REGISTER

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	IS<3:0>			
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	q = Value depends on condition

bit 7-4 **Unimplemented:** Read as ‘0’

bit 3-0 **IS<3:0>:** CWGx Input Selection bits
1111 = Reserved. No channel connected.
•
•
•
1011 = Reserved. No channel connected.
1010 = PWM4_out
1001 = PWM3_out
1000 = Reserved. No channel connected.
0111 = Reserved. No channel connected.
0110 = LC2_out
0101 = LC1_out
0100 = CCP4_out
0011 = CCP3_out
0010 = CCP2_out
0001 = CCP1_out
0000 = CWGx1CLK

22.1 CLCx Setup

Programming the CLCx module is performed by configuring the four stages in the logic signal flow. The four stages are:

- Data selection
- Data gating
- Logic function selection
- Output polarity

Each stage is setup at run time by writing to the corresponding CLCx Special Function Registers. This has the added advantage of permitting logic reconfiguration on-the-fly during program execution.

22.1.1 DATA SELECTION

There are 32 signals available as inputs to the configurable logic. Four 32-input multiplexers are used to select the inputs to pass on to the next stage.

Data selection is through four multiplexers as indicated on the left side of Figure 22-2. Data inputs in the figure are identified by a generic numbered input name.

Table 22-2 correlates the generic input name to the actual signal for each CLC module. The column labeled 'LCxDyS<4:0> Value' indicates the MUX selection code for the selected data input. LCxDyS is an abbreviation for the MUX select input codes: LCxD1S<4:0> through LCxD4S<4:0>.

Data inputs are selected with CLCxSEL0 through CLCxSEL3 registers (Register 22-3 through Register 22-6).

Note: Data selections are undefined at power-up.

TABLE 22-2: CLCx DATA INPUT SELECTION

LCxDyS<4:0> Value	CLCx Input Source
110000 to 111111 [48+]	Reserved
101111 [47]	CWG3B output
101110 [46]	CWG3A output
101101 [45]	CWG2B output
101100 [44]	CWG2A output
101011 [43]	CWG1B output
101010 [42]	CWG1A output
101001 [41]	MSSP2 SCK output
101000 [40]	MSSP2 SDO output
100111 [39]	MSSP1 SCK output
100110 [38]	MSSP1 SDO output
100101 [37]	EUSART (TX/CK) output
100100 [36]	EUSART (DT) output
100011 [35]	CLC4 output
100010 [34]	CLC3 output
100001 [33]	CLC2 output
100000 [32]	CLC1 output
011111 [31]	DSM output
011110 [30]	IOCIF
011101 [29]	ZCD output
011100 [28]	Comparator 2 output
011011 [27]	Comparator 1 output
011010 [26]	NCO1 output
011001 [25]	PWM7 output
011000 [24]	PWM6 output
010111 [23]	CCP5 output
010110 [22]	CCP4 output
010101 [21]	CCP3 output
010100 [20]	CCP2 output
010011 [19]	CCP1 output
010010 [18]	SMT2 output
010001 [17]	SMT1 output
010000 [16]	TMR6 to PR6 match
001111 [15]	TMR5 overflow
001110 [14]	TMR4 to PR4 match
001101 [13]	TMR3 overflow
001100 [12]	TMR2 to PR2 match
001011 [11]	TMR1 overflow
001010 [10]	TMR0 overflow
001001 [9]	CLKR output
001000 [8]	FRC
000111 [7]	SOSC
000110 [6]	LFINTOSC
000101 [5]	HFINTOSC
000100 [4]	FOSC
000011 [3]	CLCIN3PPS
000010 [2]	CLCIN2PPS
000001 [1]	CLCIN1PPS
000000 [0]	CLCIN0PPS

25.6 Register Definitions: DAC Control

REGISTER 25-1: DAC1CON0: VOLTAGE REFERENCE CONTROL REGISTER 0

R/W-0/0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0
DAC1EN	—	DAC1OE1	DAC1OE2	DAC1PSS<1:0>		—	DAC1NSS
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7 **DAC1EN:** DAC1 Enable bit
1 = DAC is enabled
0 = DAC is disabled

bit 6 **Unimplemented:** Read as '0'

bit 5 **DAC1OE1:** DAC1 Voltage Output 1 Enable bit
1 = DAC voltage level is also an output on the DAC1OUT1 pin
0 = DAC voltage level is disconnected from the DAC1OUT1 pin

bit 4 **DAC1OE2:** DAC1 Voltage Output 1 Enable bit
1 = DAC voltage level is also an output on the DAC1OUT2 pin
0 = DAC voltage level is disconnected from the DAC1OUT2 pin

bit 3-2 **DAC1PSS<1:0>:** DAC1 Positive Source Select bits
11 = Reserved, do not use
10 = FVR output
01 = V_{REF}+ pin
00 = V_{DD}

bit 1 **Unimplemented:** Read as '0'

bit 0 **DAC1NSS:** DAC1 Negative Source Select bits
1 = V_{REF}- pin
0 = V_{SS}

REGISTER 25-2: DAC1CON1: VOLTAGE REFERENCE CONTROL REGISTER 1

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	DAC1R<4:0>				
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **DAC1R<4:0>:** DAC1 Voltage Output Select bits
$V_{OUT} = (V_{SRC}+ - V_{SRC}-)*(DAC1R<4:0>/32) + V_{SRC}$

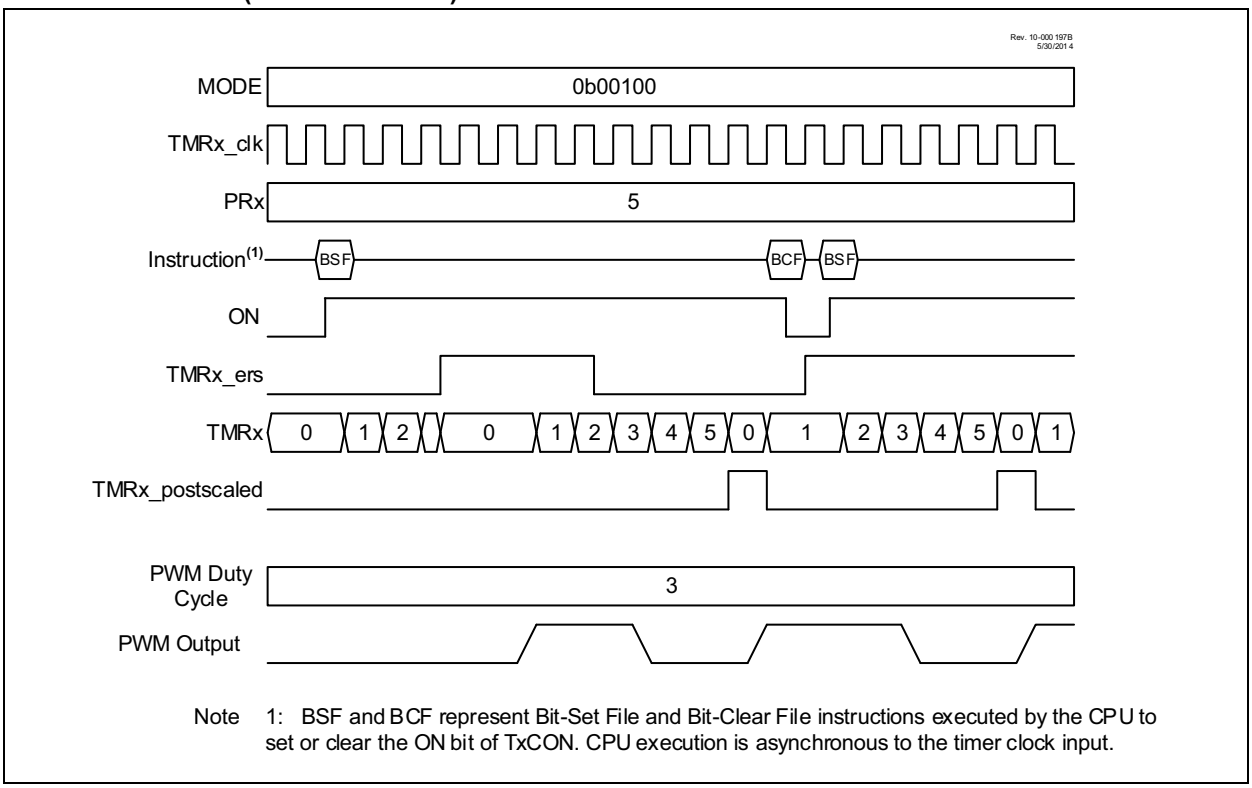
29.5.3 EDGE-TRIGGERED HARDWARE LIMIT MODE

In Hardware Limit mode the timer can be reset by the TMRx_ers external signal before the timer reaches the period count. Three types of Resets are possible:

- Reset on rising or falling edge (MODE<4:0>= 00011)
- Reset on rising edge (MODE<4:0> = 00100)
- Reset on falling edge (MODE<4:0> = 00101)

When the timer is used in conjunction with the CCP in PWM mode then an early Reset shortens the period and restarts the PWM pulse after a two clock delay. Refer to Figure 29-6.

FIGURE 29-6: EDGE-TRIGGERED HARDWARE LIMIT MODE TIMING DIAGRAM (MODE = 00100)



Note 1: BSF and BCF represent Bit-Set File and Bit-Clear File instructions executed by the CPU to set or clear the ON bit of TxCON. CPU execution is asynchronous to the timer clock input.

TABLE 29-3: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER2

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CCP1CON	EN	—	OUT	FMT	MODE<3:0>				418
CCP2CON	EN	—	OUT	FMT	MODE<3:0>				418
CCPTMRS0	C4TSEL<1:0>		C3TSEL<1:0>		C2TSEL<1:0>		C1TSEL<1:0>		421
CCPTMRS1	—	—	P7TSEL<1:0>		P6TSEL<1:0>		C5TSEL<1:0>		421
INTCON	GIE	PEIE	—	—	—	—	—	INTEDG	114
PIE1	OSFIE	CSWIE	—	—	—	—	ADTIE	ADIE	116
PIR1	OSFIF	CSWIF	—	—	—	—	ADTIF	ADIF	125
PR2	Timer2 Module Period Register								389*
TMR2	Holding Register for the 8-bit TMR2 Register								389*
T2CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T2CLKCON	—	—	—	—	CS<3:0>				406
T2RST	—	—	—	RSEL<4:0>					409
T2HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408
PR4	Timer4 Module Period Register								389*
TMR4	Holding Register for the 8-bit TMR4 Register								389*
T4CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T4CLKCON	—	—	—	—	—	CS<3:0>			406
T4RST	—	—	—	RSEL<4:0>					409
T4HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408
PR6	Timer6 Module Period Register								389*
TMR6	Holding Register for the 8-bit TMR6 Register								389*
T6CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T6CLKCON	—	—	—	—	—	CS<2:0>			406
T6RST	—	—	—	RSEL<4:0>					409
T6HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408

Legend: — = unimplemented location, read as '0'. Shaded cells are not used for Timer2 module.

* Page provides register information.

FIGURE 31-7: SPI DAISY-CHAIN CONNECTION

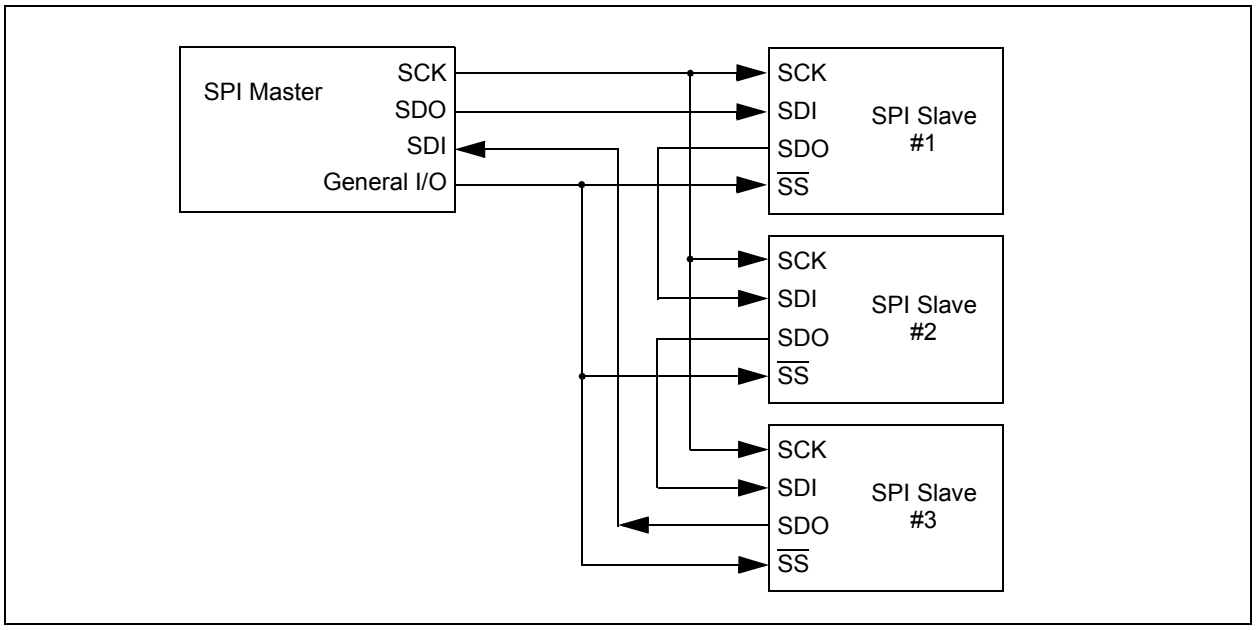


FIGURE 31-8: SLAVE SELECT SYNCHRONOUS WAVEFORM

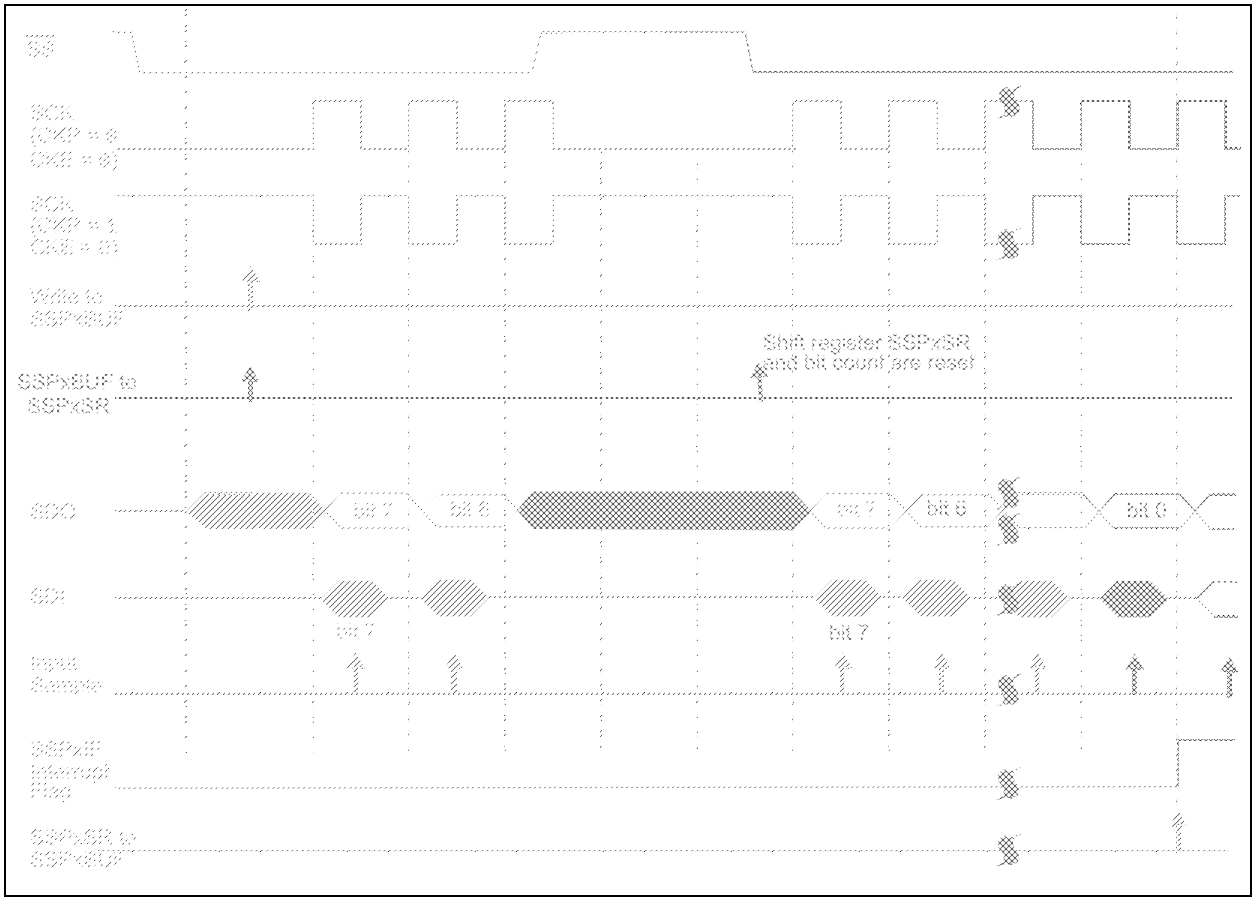


FIGURE 31-9: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 0)

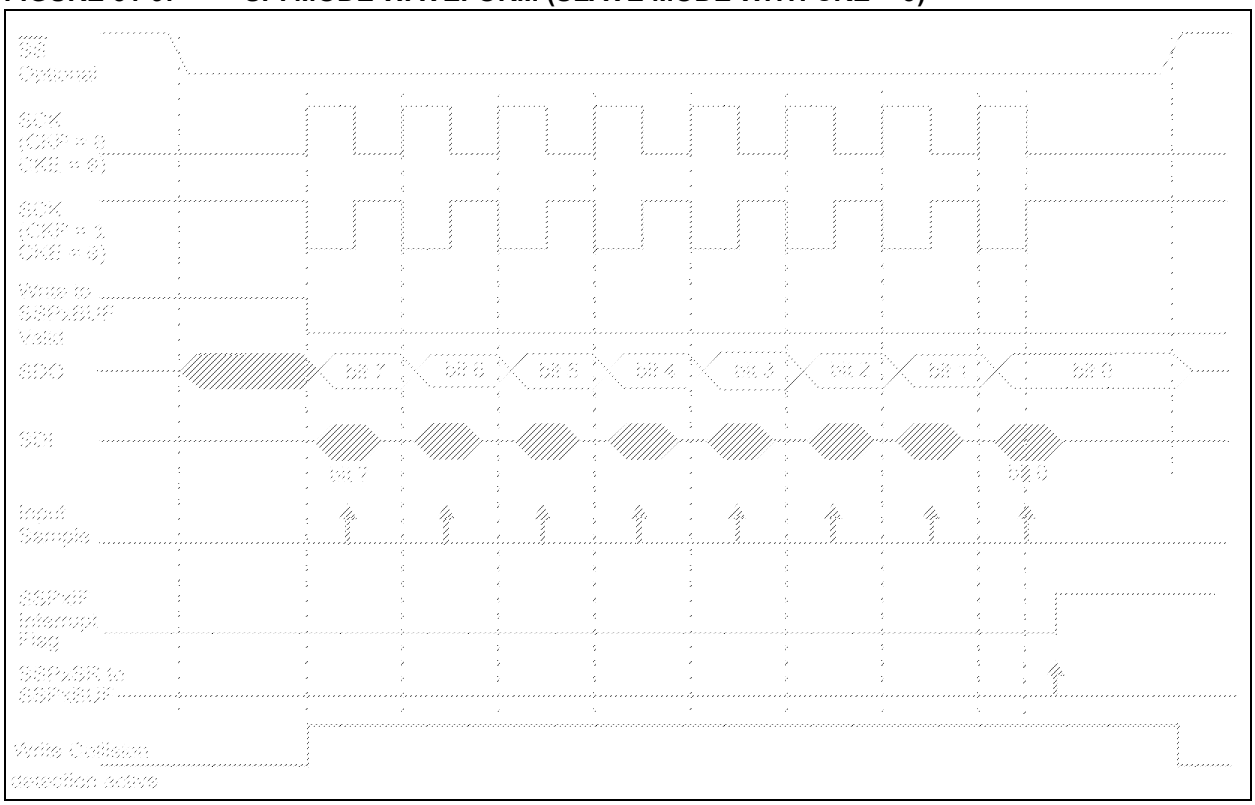
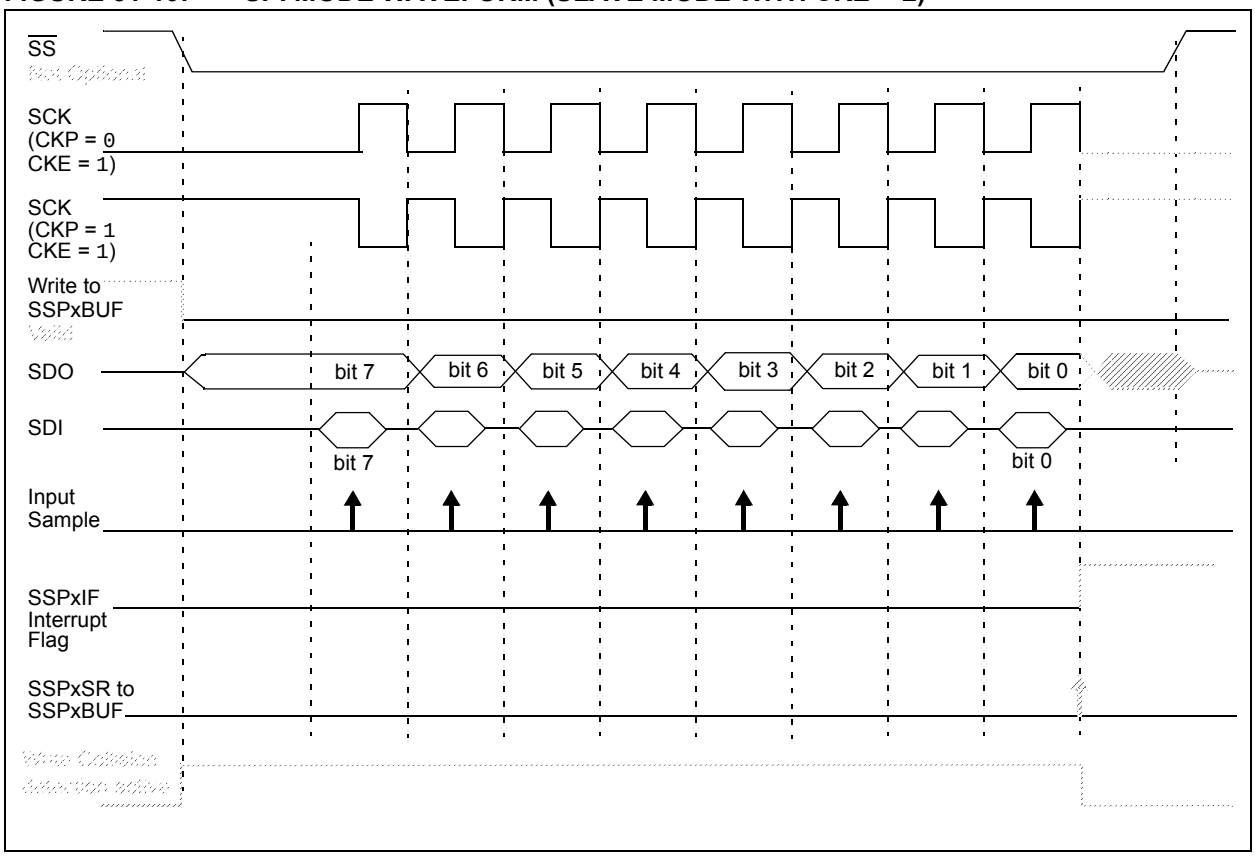


FIGURE 31-10: SPI MODE WAVEFORM (SLAVE MODE WITH CKE = 1)



32.6.9 COUNTER MODE

This mode increments the timer on each pulse of the SMTx_signal input. This mode is asynchronous to the SMT clock and uses the SMTx_signal as a time source. The SMTxCPW register will be updated with the current SMTxTMR value on the rising edge of the SMTxWIN input. See Figure 32-18.

SWAPF **Swap Nibbles in f**

Syntax:	[*label*] SWAPF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(f<3:0>) → (destination<7:4>), (f<7:4>) → (destination<3:0>)
Status Affected:	None
Description:	The upper and lower nibbles of register 'f' are exchanged. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is placed in register 'f'.

TRIS **Load TRIS Register with W**

Syntax:	[*label*] TRIS f
Operands:	$5 \le f \le 7$
Operation:	(W) → TRIS register 'f'
Status Affected:	None
Description:	Move data from W register to TRIS register. When 'f' = 5, TRISA is loaded. When 'f' = 6, TRISB is loaded. When 'f' = 7, TRISC is loaded.

XORLW **Exclusive OR literal with W**

Syntax:	[*label*] XORLW k
Operands:	$0 \le k \le 255$
Operation:	(W) .XOR. k → (W)
Status Affected:	Z
Description:	The contents of the W register are XOR'ed with the 8-bit literal 'k'. The result is placed in the W register.

XORWF **Exclusive OR W with f**

Syntax:	[*label*] XORWF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(W) .XOR. (f) → (destination)
Status Affected:	Z
Description:	Exclusive OR the contents of the W register with register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

TABLE 37-2: SUPPLY CURRENT (I_{DD})(1,2,4)

PIC16LF18854			Standard Operating Conditions (unless otherwise stated)					
PIC16F18854								
Param. No.	Symbol	Device Characteristics	Min.	Typ.†	Max.	Units	Conditions	
							V_{DD}	Note
D100	$I_{DD_{XT4}}$	XT = 4 MHz	—	360	600	µA	3.0V	
D100	$I_{DD_{XT4}}$	XT = 4 MHz	—	380	700	µA	3.0V	
D101	$I_{DD_{HFO16}}$	HFINTOSC = 16 MHz	—	1.4	2.0	mA	3.0V	
D101	$I_{DD_{HFO16}}$	HFINTOSC = 16 MHz	—	1.5	2.1	mA	3.0V	
D102	$I_{DD_{HFOPLL}}$	HFINTOSC = 32 MHz	—	2.6	3.6	mA	3.0V	
D102	$I_{DD_{HFOPLL}}$	HFINTOSC = 32 MHz	—	2.7	3.7	mA	3.0V	
D103	$I_{DD_{HSPLL32}}$	HS+PLL = 32 MHz	—	2.6	3.6	mA	3.0V	
D103	$I_{DD_{HSPLL32}}$	HS+PLL = 32 MHz	—	2.7	3.7	mA	3.0V	
D104	$I_{DD_{IDLE}}$	IDLE mode, HFINTOSC = 16 MHz	—	1.05	—	mA	3.0V	
D104	$I_{DD_{IDLE}}$	IDLE mode, HFINTOSC = 16 MHz	—	1.15	—	mA	3.0V	
D105	$I_{DD_{DOZE}}$(3)	DOZE mode, HFINTOSC = 16 MHz, Doze Ratio = 16	—	1.1	—	mA	3.0V	
D105	$I_{DD_{DOZE}}$(3)	DOZE mode, HFINTOSC = 16 MHz, Doze Ratio = 16	—	1.2	—	mA	3.0V	

† Data in "Typ." column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

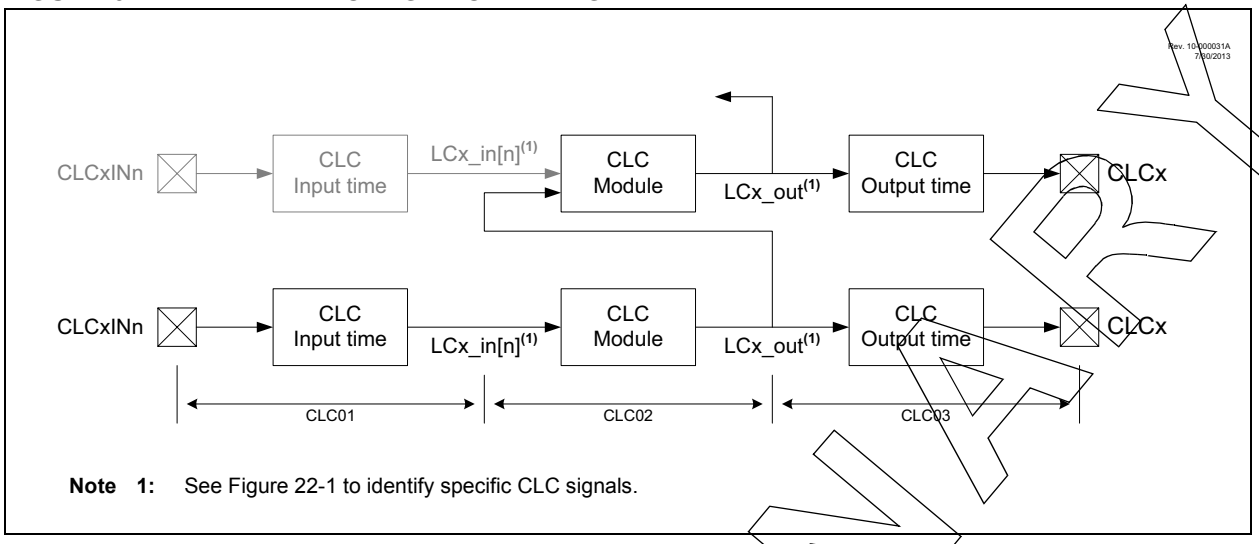
Note 1: The test conditions for all I_{DD} measurements in active operation mode are: OSC1 = external square wave, from rail-to-rail; all I/O pins are outputs driven low; MCLR = V_{DD}; WDT disabled.

2: The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption.

3: $I_{DD_{DOZE}} = [I_{DD_{IDLE}}*(N-1)/N] + I_{DD_{HFO}}16/N$ where N = DOZE Ratio (Register 8-2).

4: PMD bits are all in the default state, no modules are disabled.

FIGURE 37-14: CLC PROPAGATION TIMING



Note 1: See Figure 22-1 to identify specific CLC signals.

TABLE 37-20: CONFIGURABLE LOGIC CELL (CLC) CHARACTERISTICS

Standard Operating Conditions (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +125°C							
Param. No.	**Sym.**	**Characteristic**	**Min.**	**Typ†**	**Max.**	**Units**	**Conditions**
CLC01*	TCLCIN	CLC input time	—	7	OS17	ns	**(Note 1)**
CLC02*	TCLC	CLC module input to output progagation time	— —	24 12	— —	ns ns	VDD = 1.8V VDD > 3.6V
CLC03*	TCLCOUT	CLC output time Rise Time	—	OS18	—	—	**(Note 1)**
		Fall Time	—	OS19	—	—	**(Note 1)**
CLC04*	FCLCMAX	CLC maximum switching frequency	—	32	FOSC	MHz	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: See Table 37-10 for OS17, OS18 and OS19 rise and fall times.

