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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I²C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	25
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 24x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf18854t-i-ss

Digital Peripherals (Cont.)

- Cyclical Redundancy Check (CRC/SCAN):
  - 16-bit CRC
  - Scans memory for NVM integrity
- Communication:
  - EUSART, RS-232, RS-485, LIN compatible
  - Two SPI
  - Two I^2C, SMBus, PMBus™ compatible
- Up to 25 I/O Pins:
  - Individually programmable pull-ups
  - Slew rate control
  - Interrupt-on-change with edge-select
  - Input level selection control (ST or TTL)
  - Digital open-drain enable
  - Current mode enable
- Peripheral Pin Select (PPS):
  - Enables pin mapping of digital I/O
- Data Signal Modulator (DSM)
  - Modulates a carrier signal with digital data to create custom carrier synchronized output waveforms

Analog Peripherals

- Analog-to-Digital Converter with Computation (ADC^2):
  - 10-bit with up to 24 external channels
  - Automated post-processing
  - Automates math functions on input signals: averaging, filter calculations, oversampling and threshold comparison
  - Operates in Sleep
- Two Comparators (COMP):
  - Fixed Voltage Reference at (non) inverting input(s)
  - Comparator outputs externally accessible
- 5-Bit Digital-to-Analog Converter (DAC):
  - 5-bit resolution, rail-to-rail
  - Positive Reference Selection
  - Unbuffered I/O pin output
  - Internal connections to ADCs and comparators
- Voltage Reference:
  - Fixed Voltage Reference with 1.024V, 2.048V and 4.096V output levels

Flexible Oscillator Structure

- High-Precision Internal Oscillator:
  - Software selectable frequency range up to 32 MHz, ±1% typical
- x2/x4 PLL with Internal and External Sources
- Low-Power Internal 32 kHz Oscillator (LFINTOSC)
- External 32 kHz Crystal Oscillator (SOSC)
- External Oscillator Block with:
  - Three crystal/resonator modes up to 20 MHz
  - Three external clock modes up to 20 MHz
- Fail-Safe Clock Monitor:
  - Allows for safe shutdown if peripheral clock stops
- Oscillator Start-up Timer (OST)
  - Ensures stability of crystal oscillator resources

3.2.1.1 STATUS Register

The STATUS register, shown in Register 3-1, contains:

- the arithmetic status of the ALU
- the Reset status

The STATUS register can be the destination for any instruction, like any other register. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to the device logic. Furthermore, the $\overline{TO}$ and $\overline{PD}$ bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS` will clear the upper three bits and set the Z bit. This leaves the STATUS register as '`000u u1uu`' (where u = unchanged).

It is recommended, therefore, that only `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions are used to alter the STATUS register, because these instructions do not affect any Status bits. For other instructions not affecting any Status bits (refer to **Section 3.0 "Memory Organization"**).

Note 1: The C and DC bits operate as $\overline{Borrow}$ and $\overline{Digit\ Borrow}$ out bits, respectively, in subtraction.

REGISTER 3-1: STATUS: STATUS REGISTER

U-0	U-0	U-0	R-1/q	R-1/q	R/W-0/u	R/W-0/u	R/W-0/u
—	—	—	$\overline{TO}$	$\overline{PD}$	Z	DC(1)	C(1)
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7-5 **Unimplemented:** Read as '0'

bit 4 **$\overline{TO}$:** Time-Out bit
- 1 = After power-up, `CLRWDT` instruction or `SLEEP` instruction
- 0 = A WDT time-out occurred

bit 3 **$\overline{PD}$:** Power-Down bit
- 1 = After power-up or by the `CLRWDT` instruction
- 0 = By execution of the `SLEEP` instruction

bit 2 **Z:** Zero bit
- 1 = The result of an arithmetic or logic operation is zero
- 0 = The result of an arithmetic or logic operation is not zero

bit 1 **DC:** Digit Carry/$\overline{Digit\ Borrow}$ bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)(1)
- 1 = A carry-out from the 4th low-order bit of the result occurred
- 0 = No carry-out from the 4th low-order bit of the result

bit 0 **C:** Carry/$\overline{Borrow}$ bit(1) (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions)(1)
- 1 = A carry-out from the Most Significant bit of the result occurred
- 0 = No carry-out from the Most Significant bit of the result occurred

Note 1: For $\overline{Borrow}$, the polarity is reversed. A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high-order or low-order bit of the source register.

TABLE 3-11: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-31 (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 1											
CPU CORE REGISTERS; see Table 3-2 for specifics											
08Ch	ADRESL	ADRESL<7:0>								0000 0000	0000 0000
08Dh	ADRESH	ADRESH<7:0>								0000 0000	0000 0000
08Eh	ADPREVL	ADPREVL<7:0>								0000 0000	0000 0000
08Fh	ADPREVH	ADPREVH<7:0>								0000 0000	0000 0000
090h	ADACCL	ADACCL<7:0>								xxxx xxxx	uuuu uuuu
091h	ADACCH	ADACCH<7:0>								xxxx xxxx	uuuu uuuu
092h	—	Unimplemented								—	—
093h	ADCON0	ADON	ADCONT	—	ADCS	—	ADFRM0	—	ADGO	00-0 -0-0	00-0 -0-0
094h	ADCON1	ADPPOL	ADIPEN	ADGPOL	—	—	—	—	ADDSEN	000- ---0	000- ---0
095h	ADCON2	ADPSIS	ADCRS<2:0>			ADACLR	ADMD<2:0>			0000 0000	0000 0000
096h	ADCON3	—	ADCALC<2:0>			ADSOI	ADTMD<2:0>			-000 0000	-000 0000
097h	ADSTAT	ADAOV	ADUTHR	ADLTHR	ADMATH	—	ADSTAT<2:0>			0000 -000	0000 -000
098h	ADCLK	—	—	ADCCS<5:0>						--00 0000	--00 0000
099h	ADACT	—	—	—	ADACT<4:0>					---0 0000	---0 0000
09Ah	ADREF	—	—	—	ADNREF	—	—	ADPREF<1:0>		---0 --00	---0 --00
09Bh	ADCAP	—	—	—	ADCAP<4:0>					---0 0000	---0 0000
09Ch	ADPRE	ADPRE<7:0>								0000 0000	0000 0000
09Dh	ADACQ	ADACQ<7:0>								0000 0000	0000 0000
09Eh	ADPCH	—	—	ADPCH<5:0>						--00 0000	--00 0000
09Fh	—	Unimplemented								—	—

Legend: x = unknown, u = unchanged, q =depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Register present on PIC16F18854 devices only.

2: Unimplemented, read as '1'.

TABLE 3-11: SPECIAL FUNCTION REGISTER SUMMARY BANKS 0-31 (CONTINUED)

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on: POR, BOR	Value on all other Resets
Bank 7											
CPU CORE REGISTERS; see Table 3-2 for specifics											
38Ch	PWM6DCL	DC<1:0>		—	—	—	—	—	—	xx-- ----	uu-- ----
38Dh	PWM6DCH	DC<9:2>								xxxx xxxx	uuuu uuuu
38Eh	PWM6CON	EN	—	OUT	POL	—	—	—	—	0-00 ----	0-00 ----
38Fh	—	Unimplemented								—	—
390h	PWM7DCL	DC<1:0>		—	—	—	—	—	—	xx-- ----	uu-- ----
391h	PWM7DCH	DC<9:2>								xxxx xxxx	uuuu uuuu
392h	PWM7CON	EN	—	OUT	POL	—	—	—	—	0-00 ----	0-00 ----
393h	—	Unimplemented								—	—
394h	—	Unimplemented								—	—
395h	—	Unimplemented								—	—
396h	—	Unimplemented								—	—
397h	—	Unimplemented								—	—
398h	—	Unimplemented								—	—
399h	—	Unimplemented								—	—
39Ah	—	Unimplemented								—	—
39Bh	—	Unimplemented								—	—
39Ch	—	Unimplemented								—	—
39Dh	—	Unimplemented								—	—
39Eh	—	Unimplemented								—	—
39Fh	—	Unimplemented								—	—

Legend: x = unknown, u = unchanged, q =depends on condition, - = unimplemented, read as '0', r = reserved. Shaded locations unimplemented, read as '0'.

Note 1: Register present on PIC16F18854 devices only.

2: Unimplemented, read as '1'.

REGISTER 4-3: CONFIG3: CONFIGURATION WORD 3: WINDOWED WATCHDOG

R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1
WDTCCS<2:0>			WDTCWS<2:0>		
bit 13					bit 8

U-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1	R/P-1
	WDTE<1:0>		WDTCPS<4:0>				
bit 7							bit 0

Legend:			
R = Readable bit	P = Programmable bit	x = Bit is unknown	U = Unimplemented bit, read as ‘1’
‘0’ = Bit is cleared	‘1’ = Bit is set	W = Writable bit	n = Value when blank or after Bulk Erase

bit 13-11 **WDTCCS<2:0>**: WDT Input Clock Selector bits
- 111 = Software Control
- 110 = Reserved
- .
- .
- .
- 010 = Reserved
- 001 = WDT reference clock is the 31.25 kHz HFINTOSC (MFINTOSC) output
- 000 = WDT reference clock is the 31.0 kHz LFINTOSC (default value)

bit 10-8 **WDTCWS<2:0>**: WDT Window Select bits

WDTCWS	WDTWS at POR			Software control of WDTWS?	Keyed access required?
	Value	Window delay Percent of time	Window opening Percent of time		
111	111	n/a	100	Yes	No
110	111	n/a	100	No	Yes
101	101	25	75		
100	100	37.5	62.5		
011	011	50	50		
010	010	62.5	37.5		
001	001	75	25		
000	000	87.5	12.5		

bit 7 **Unimplemented**: Read as ‘1’

bit 6-5 **WDTE<1:0>**: WDT Operating mode:
- 11 = WDT enabled regardless of Sleep; SWDTEN is ignored
- 10 = WDT enabled while Sleep = 0, suspended when Sleep = 1; SWDTEN ignored
- 01 = WDT enabled/disabled by SWDTEN bit in WDTCON0
- 00 = WDT disabled, SWDTEN is ignored

5.0 RESETS

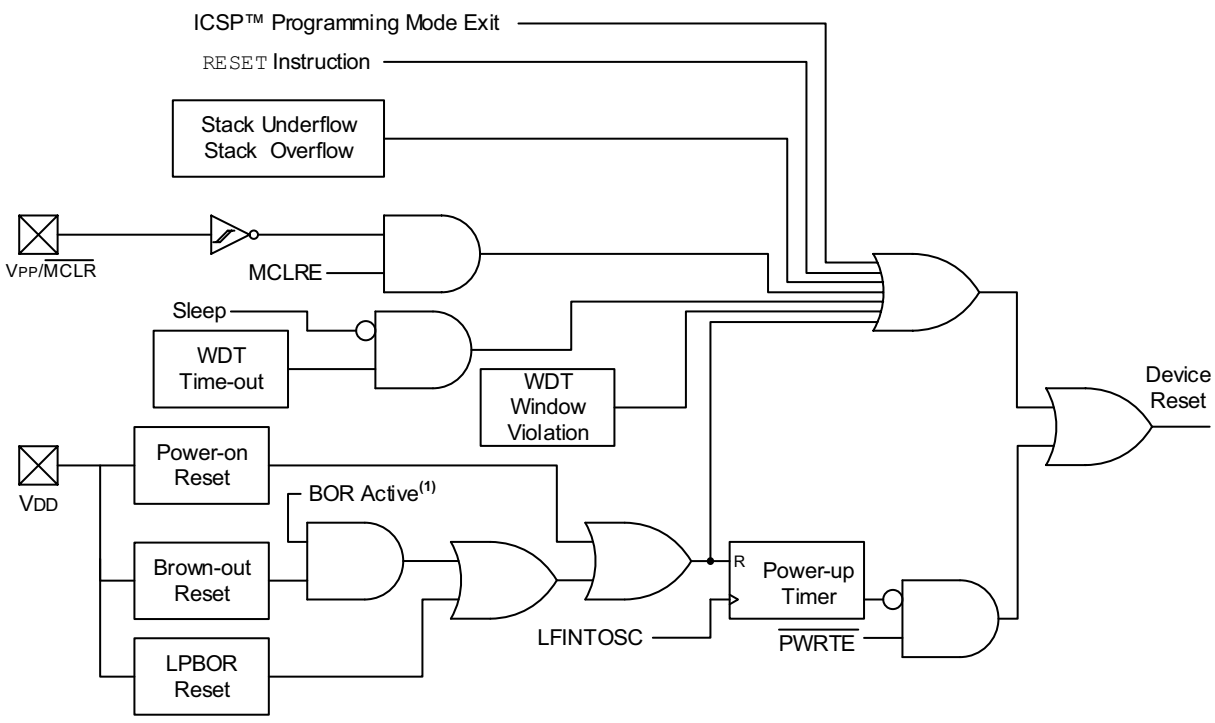
There are multiple ways to reset this device:

- Power-On Reset (POR)
- Brown-Out Reset (BOR)
- $\overline{\text{MCLR}}$ Reset
- WDT Reset
- RESET instruction
- Stack Overflow
- Stack Underflow
- Programming mode exit

To allow VDD to stabilize, an optional Power-up timer can be enabled to extend the Reset time after a BOR or POR event.

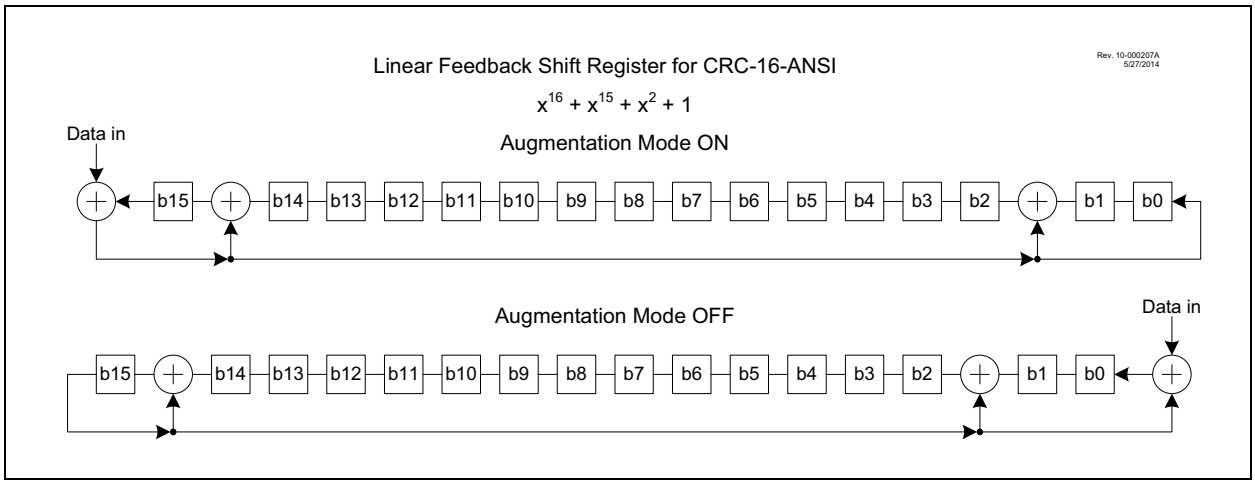
A simplified block diagram of the On-Chip Reset Circuit is shown in Figure 5-1.

FIGURE 5-1: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT



Note 1: See Table 5-1 for BOR active conditions.

FIGURE 11-1: CRC LFSR EXAMPLE



11.4 CRC Data Sources

Data can be input to the CRC module in two ways:

- User data using the CRCDAT registers
- Flash using the Program Memory Scanner

To set the number of bits of data, up to 16 bits, the DLEN bits of CRCCON1 must be set accordingly. Only data bits in CRCDATA registers up to DLEN will be used, other data bits in CRCDATA registers will be ignored.

Data is moved into the CRCSHIFT as an intermediate to calculate the check value located in the CRCACC registers.

The SHIFTM bit is used to determine the bit order of the data being shifted into the accumulator. If SHIFTM is not set, the data will be shifted in MSb first. The value of DLEN will determine the MSb. If SHIFTM bit is set, the data will be shifted into the accumulator in reversed order, LSb first.

The CRC module can be seeded with an initial value by setting the CRCACC<15:0> registers to the appropriate value before beginning the CRC.

11.4.1 CRC FROM USER DATA

To use the CRC module on data input from the user, the user must write the data to the CRCDAT registers. The data from the CRCDAT registers will be latched into the shift registers on any write to the CRCDATL register.

11.4.2 CRC FROM FLASH

To use the CRC module on data located in Flash memory, the user can initialize the Program Memory Scanner as defined in **Section 11.8, Program Memory Scan Configuration**.

11.5 CRC Check Value

The CRC check value will be located in the CRCACC registers after the CRC calculation has finished. The check value will depend on two mode settings of the CRCCON: ACCM and SHIFTM.

If the ACCM bit is set, the CRC module will augment the data with a number of zeros equal to the length of the polynomial to find the final check value. If the ACCM bit is not set, the CRC will stop at the end of the data. A number of zeros equal to the length of the polynomial can then be entered to find the same check value as augmented mode, alternatively the expected check value can be entered at this point to make the final result equal to 0.

A final XOR value may be needed with the check value to find the desired CRC result

11.6 CRC Interrupt

The CRC will generate an interrupt when the BUSY bit transitions from '1' to '0'. The CRCIF interrupt flag bit of the PIR6 register is set every time the BUSY bit transitions, regardless of whether or not the CRC interrupt is enabled. The CRCIF bit can only be cleared in software. The CRC interrupt enable is the CRCIE bit of the PIE6 register.

19.1.1 PWM CLOCK SELECTION

The PIC16(L)F18855/75 allows each individual CCP and PWM module to select the timer source that controls the module. Each module has an independent selection.

As there are up to three 8-bit timers with auto-reload (Timer2/4/6), PWM mode on the CCP and PWM modules can use any of these timers.

The CCPTMRS0 and CCPTMRS1 register are used to select which timer is used.

19.1.2 USING THE TMR2/4/6 WITH THE PWM MODULE

This device has a newer version of the TMR2 module that has many new modes, which allow for greater customization and control of the PWM signals than on older parts. Refer to Section 29.5, Operation Examples for examples of PWM signal generation using the different modes of Timer2. PWM operation requires that the timer used as the PWM time base has the FOSC/4 clock source selected.

19.1.3 PWM PERIOD

Referring to Figure 19-1, the PWM output has a period and a pulse width. The frequency of the PWM is the inverse of the period (1/period).

The PWM period is specified by writing to the PR2 register. The PWM period can be calculated using the following formula:

EQUATION 19-1: PWM PERIOD

$$PWM\ Period = [(PR2) + 1] \cdot 4 \cdot TOSC \cdot (TMR2\ Prescale\ Value)$$

Note 1: TOSC = 1/FOSC

When TMR2 is equal to PR2, the following three events occur on the next increment cycle:

- TMR2 is cleared
- The PWMx pin is set (Exception: If the PWM duty cycle = 0%, the pin will not be set.)
- The PWM pulse width is latched from PWMxDC.

Note:	If the pulse width value is greater than the period the assigned PWM pin(s) will remain unchanged.

19.1.4 PWM DUTY CYCLE

The PWM duty cycle is specified by writing a 10-bit value to the PWMxDC register. The PWMxDCH contains the eight MSbs and the PWMxDCL<7:6> bits contain the two LSbs.

The PWMDC register is double-buffered and can be updated at any time. This double buffering is essential for glitch-free PWM operation. New values take effect when TMR2 = PR2. Note that PWMDC is left-justified.

The 8-bit timer TMR2 register is concatenated with either the 2-bit internal system clock (FOSC), or two bits of the prescaler, to create the 10-bit time base. The system clock is used if the Timer2 prescaler is set to 1:1.

Equation 19-2 is used to calculate the PWM pulse width.

Equation 19-3 is used to calculate the PWM duty cycle ratio.

EQUATION 19-2: PULSE WIDTH

$$Pulse\ Width = (PWMxDC) \cdot TOSC \cdot (TMR2\ Prescale\ Value)$$

EQUATION 19-3: DUTY CYCLE RATIO

$$Duty\ Cycle\ Ratio = \frac{(PWMxDC)}{4(PR2+1)}$$

19.1.5 PWM RESOLUTION

The resolution determines the number of available duty cycles for a given period. For example, a 10-bit resolution will result in 1024 discrete duty cycles, whereas an 8-bit resolution will result in 256 discrete duty cycles.

The maximum PWM resolution is ten bits when PR2 is 255. The resolution is a function of the PR2 register value as shown by Equation 19-4.

EQUATION 19-4: PWM RESOLUTION

$$Resolution = \frac{\log[4(PR2+1)]}{\log(2)}\ bits$$

Note:	If the pulse width value is greater than the period the assigned PWM pin(s) will remain unchanged.

19.1.6 OPERATION IN SLEEP MODE

In Sleep mode, the TMR2 register will not increment and the state of the module will not change. If the PWMx pin is driving a value, it will continue to drive that value. When the device wakes up, TMR2 will continue from its previous state.

19.1.7 CHANGES IN SYSTEM CLOCK FREQUENCY

The PWM frequency is derived from the system clock frequency. Any changes in the system clock frequency will result in changes to the PWM frequency. See **Section 6.0 "Oscillator Module (with Fail-Safe Clock Monitor)"** for additional details.

19.1.8 EFFECTS OF RESET

Any Reset will force all ports to Input mode and the PWMx registers to their Reset states.

TABLE 19-1: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (FOSC = 20 MHz)

PWM Frequency	1.22 kHz	4.88 kHz	19.53 kHz	78.12 kHz	156.3 kHz	208.3 kHz
Timer Prescale	16	4	1	1	1	1
PR2 Value	0xFF	0xFF	0xFF	0x3F	0x1F	0x17
Maximum Resolution (bits)	10	10	10	8	7	6.6

TABLE 19-2: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (FOSC = 8 MHz)

PWM Frequency	1.22 kHz	4.90 kHz	19.61 kHz	76.92 kHz	153.85 kHz	200.0 kHz
Timer Prescale	16	4	1	1	1	1
PR2 Value	0xFF	0xFF	0xFF	0x3F	0x1F	0x17
Maximum Resolution (bits)	10	10	10	8	7	6.6

19.1.9 SETUP FOR PWM OPERATION

The following steps should be taken when configuring the module for using the PWMx outputs:

1. Disable the PWMx pin output driver(s) by setting the associated TRIS bit(s).
2. Configure the PWM output polarity by configuring the PWMxPOL bit of the PWMxCON register.
3. Load the PR2 register with the PWM period value, as determined by Equation 19-1.
4. Load the PWMxDCH register and bits <7:6> of the PWMxDCL register with the PWM duty cycle value, as determined by Equation 19-2.
5. Configure and start Timer2:
   - Clear the TMR2IF interrupt flag bit of the PIR1 register.
   - Select the Timer2 prescale value by configuring the T2CKPS<1:0> bits of the T2CON register.
   - Enable Timer2 by setting the TMR2ON bit of the T2CON register.
6. Wait until the TMR2IF is set.
7. When the TMR2IF flag bit is set:
   - Clear the associated TRIS bit(s) to enable the output driver.
   - Route the signal to the desired pin by configuring the RxyPPS register.
   - Enable the PWMx module by setting the PWMxEN bit of the PWMxCON register.

In order to send a complete duty cycle and period on the first PWM output, the above steps must be followed in the order given. If it is not critical to start with a complete PWM signal, then the PWM module can be enabled during Step 2 by setting the PWMxEN bit of the PWMxCON register.

23.5.1 DIGITAL FILTER/AVERAGE

The digital filter/average module consists of an accumulator with data feedback options, and control logic to determine when threshold tests need to be applied. The accumulator is a 16-bit wide signed register (15 bits + 1 sign bit), which can be accessed through the ADACCH:ADACCL register pair.

Upon each trigger event (the ADGO bit set or external event trigger), the ADC conversion result is added to the accumulator. If the value exceeds '111111111111111', then the overflow bit ADAOV in the ADSTAT register is set.

The number of samples to be accumulated is determined by the ADRPT (A/D Repeat Setting) register. Each time a sample is added to the accumulator, the ADCNT register is incremented. In Average and Burst Average modes the ADCNT and ADACC registers are cleared automatically when a trigger causes the ADCNT value to exceed the ADRPT value to '1' and replace the ADACC contents with the conversion result.

The ADAOV (accumulator overflow) bit in the ADSTAT register, ADACC, and ADCNT registers will be cleared any time the ADACLR bit in the ADCON2 register is set.

Note:	When ADC is operating from FRC, 5 FRC clock cycles are required to execute the ADACC clearing operation.

The ADCRS <2:0> bits in the ADCON2 register control the data shift on the accumulator result, which effectively divides the value in the accumulator (ADACCH:ADACCL) register pair. For the Accumulate mode of the digital filter, the shift provides a simple scaling operation. For the Average/Burst Average mode, the shift bits are used to determine number of samples for averaging. For the Lowpass Filter mode, the shift is an integral part of the filter, and determines the cut-off frequency of the filter. Table 23-4 shows the -3 dB cut-off frequency in ωT (radians) and the highest signal attenuation obtained by this filter at nyquist frequency (ωT = π).

TABLE 23-4: LOWPASS FILTER -3 dB CUT-OFF FREQUENCY

ADCRS	ωT (radians) @ -3 dB Frequency	dB @ $F_{nyquist}$=1/(2T)
1	0.72	-9.5
2	0.284	-16.9
3	0.134	-23.5
4	0.065	-29.8
5	0.032	-36.0

23.5.2 BASIC MODE

Basic mode (ADMD= '000') disables all additional computation features. In this mode, no accumulation occurs and no threshold error comparison is performed. Double sampling, continuous mode, and all CVD features are still available, but no features involving the digital filter/average features are used.

23.5.3 ACCUMULATE MODE:

In Accumulate mode (ADMD = '001'), the ADC conversion result is right shifted by the value of the ADCRS bits in the ADCON2 register and added to the ADACC registers. The Formatting mode does not affect the right-justification of the ADACC value. Upon each sample, ADCNT is incremented, indicating the number of samples accumulated. After each sample and accumulation, the ADACC value has a threshold comparison performed on it (see **Section 23.5.7 "Threshold Comparison"**) and the ADTIF interrupt may trigger.

23.5.4 AVERAGE MODE

In Average Mode (ADMD = '010'), the ADACC registers accumulate with each ADC sample, much as in Accumulate mode, and the ADCNT register increments with each sample. However, in Average mode, the threshold comparison is performed upon ADCNT being greater than or equal to a user-defined ADRPT value. The ADCRS bits still right-shift the final result, but in this mode when ADCRS= log(ADRPT)/log(2) then the final accumulated value will be divided by number of samples, allowing for a threshold comparison operation on the average of all gathered samples.

REGISTER 24-3: NCO1ACCL: NCO1 ACCUMULATOR REGISTER – LOW BYTE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
NCO1ACC<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7-0 **NCO1ACC<7:0>:** NCO1 Accumulator, Low Byte

REGISTER 24-4: NCO1ACCH: NCO1 ACCUMULATOR REGISTER – HIGH BYTE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
NCO1ACC<15:8>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7-0 **NOC1ACC<15:8>:** NCO1 Accumulator, High Byte

REGISTER 24-5: NCO1ACCU: NCO1 ACCUMULATOR REGISTER – UPPER BYTE(1)

U-0	U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
—	—	—	—	NCO1ACC<19:16>			
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as ‘0’
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
‘1’ = Bit is set	‘0’ = Bit is cleared	

bit 7-4 **Unimplemented:** Read as ‘0’

bit 3-0 **NCO1ACC<19:16>:** NCO1 Accumulator, Upper Byte

Note 1: The accumulator spans registers NCO1ACCU:NCO1ACCH: NCO1ACCL. The 24 bits are reserved but not all are used.This register updates in real-time, asynchronously to the CPU; there is no provision to guarantee atomic access to this 24-bit space using an 8-bit bus. Writing to this register while the module is operating will produce undefined results.

TABLE 29-3: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER2

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CCP1CON	EN	—	OUT	FMT	MODE<3:0>				418
CCP2CON	EN	—	OUT	FMT	MODE<3:0>				418
CCPTMRS0	C4TSEL<1:0>		C3TSEL<1:0>		C2TSEL<1:0>		C1TSEL<1:0>		421
CCPTMRS1	—	—	P7TSEL<1:0>		P6TSEL<1:0>		C5TSEL<1:0>		421
INTCON	GIE	PEIE	—	—	—	—	—	INTEDG	114
PIE1	OSFIE	CSWIE	—	—	—	—	ADTIE	ADIE	116
PIR1	OSFIF	CSWIF	—	—	—	—	ADTIF	ADIF	125
PR2	Timer2 Module Period Register								389*
TMR2	Holding Register for the 8-bit TMR2 Register								389*
T2CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T2CLKCON	—	—	—	—	CS<3:0>				406
T2RST	—	—	—	RSEL<4:0>					409
T2HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408
PR4	Timer4 Module Period Register								389*
TMR4	Holding Register for the 8-bit TMR4 Register								389*
T4CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T4CLKCON	—	—	—	—	—	CS<3:0>			406
T4RST	—	—	—	RSEL<4:0>					409
T4HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408
PR6	Timer6 Module Period Register								389*
TMR6	Holding Register for the 8-bit TMR6 Register								389*
T6CON	ON	CKPS<2:0>			OUTPS<3:0>				407
T6CLKCON	—	—	—	—	—	CS<2:0>			406
T6RST	—	—	—	RSEL<4:0>					409
T6HLT	PSYNC	CKPOL	CKSYNC	—	MODE<3:0>				408

Legend: — = unimplemented location, read as '0'. Shaded cells are not used for Timer2 module.

* Page provides register information.

31.2.6 SPI OPERATION IN SLEEP MODE

In SPI Master mode, module clocks may be operating at a different speed than when in Full-Power mode; in the case of the Sleep mode, all clocks are halted.

Special care must be taken by the user when the MSSP clock is much faster than the system clock.

In Slave mode, when MSSP interrupts are enabled, after the master completes sending data, an MSSP interrupt will wake the controller from Sleep.

If an exit from Sleep mode is not desired, MSSP interrupts should be disabled.

In SPI Master mode, when the Sleep mode is selected, all module clocks are halted and the transmission/reception will remain in that state until the device wakes. After the device returns to Run mode, the module will resume transmitting and receiving data.

In SPI Slave mode, the SPI Transmit/Receive Shift register operates asynchronously to the device. This allows the device to be placed in Sleep mode and data to be shifted into the SPI Transmit/Receive Shift register. When all eight bits have been received, the MSSP interrupt flag bit will be set and if enabled, will wake the device.

31.3 I²C MODE OVERVIEW

The Inter-Integrated Circuit (I^2C) bus is a multi-master serial data communication bus. Devices communicate in a master/slave environment where the master devices initiate the communication. A slave device is controlled through addressing.

The I^2C bus specifies two signal connections:

- Serial Clock (SCL)
- Serial Data (SDA)

Figure 31-11 shows the block diagram of the MSSP module when operating in I^2C mode.

Both the SCL and SDA connections are bidirectional open-drain lines, each requiring pull-up resistors for the supply voltage. Pulling the line to ground is considered a logical zero and letting the line float is considered a logical one.

Figure 31-11 shows a typical connection between two processors configured as master and slave devices.

The I^2C bus can operate with one or more master devices and one or more slave devices.

There are four potential modes of operation for a given device:

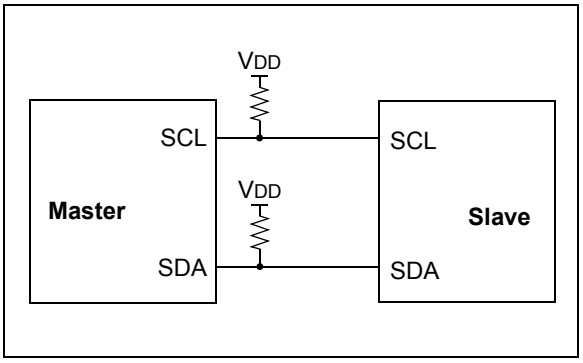
- Master Transmit mode
  (master is transmitting data to a slave)
- Master Receive mode
  (master is receiving data from a slave)
- Slave Transmit mode
  (slave is transmitting data to a master)
- Slave Receive mode
  (slave is receiving data from the master)

To begin communication, a master device starts out in Master Transmit mode. The master device sends out a Start bit followed by the address byte of the slave it intends to communicate with. This is followed by a single Read/Write bit, which determines whether the master intends to transmit to or receive data from the slave device.

If the requested slave exists on the bus, it will respond with an Acknowledge bit, otherwise known as an $\overline{ACK}$. The master then continues in either Transmit mode or Receive mode and the slave continues in the complement, either in Receive mode or Transmit mode, respectively.

A Start bit is indicated by a high-to-low transition of the SDA line while the SCL line is held high. Address and data bytes are sent out, Most Significant bit (MSb) first. The Read/Write bit is sent out as a logical one when the master intends to read data from the slave, and is sent out as a logical zero when it intends to write data to the slave.

FIGURE 31-11: I²C MASTER/ SLAVE CONNECTION



The Acknowledge bit ($\overline{ACK}$) is an active-low signal, which holds the SDA line low to indicate to the transmitter that the slave device has received the transmitted data and is ready to receive more.

The transition of a data bit is always performed while the SCL line is held low. Transitions that occur while the SCL line is held high are used to indicate Start and Stop bits.

FIGURE 31-14: I²C SLAVE, 7-BIT ADDRESS, RECEPTION (SEN = 0, AHEN = 0, DHEN = 0)

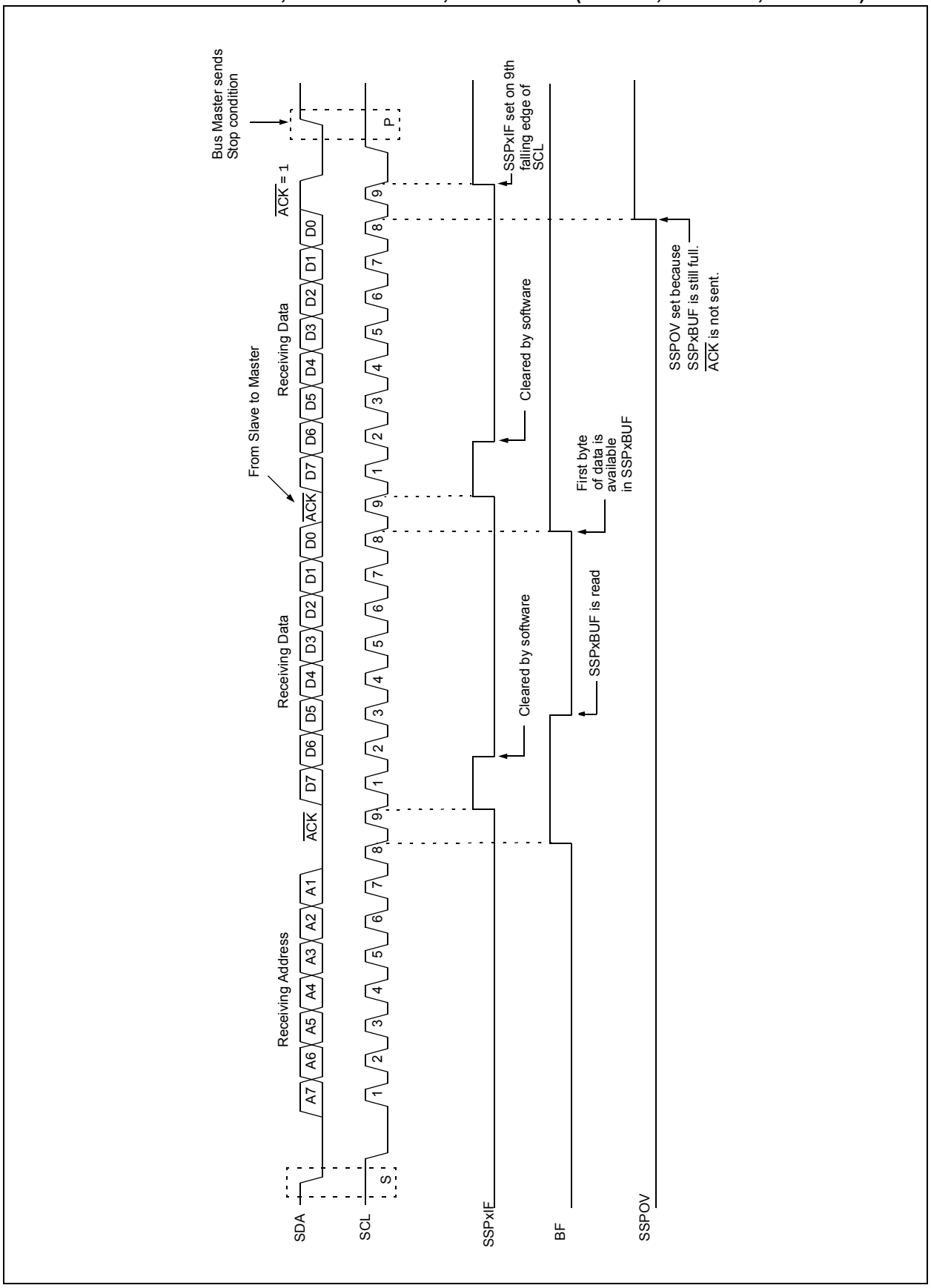
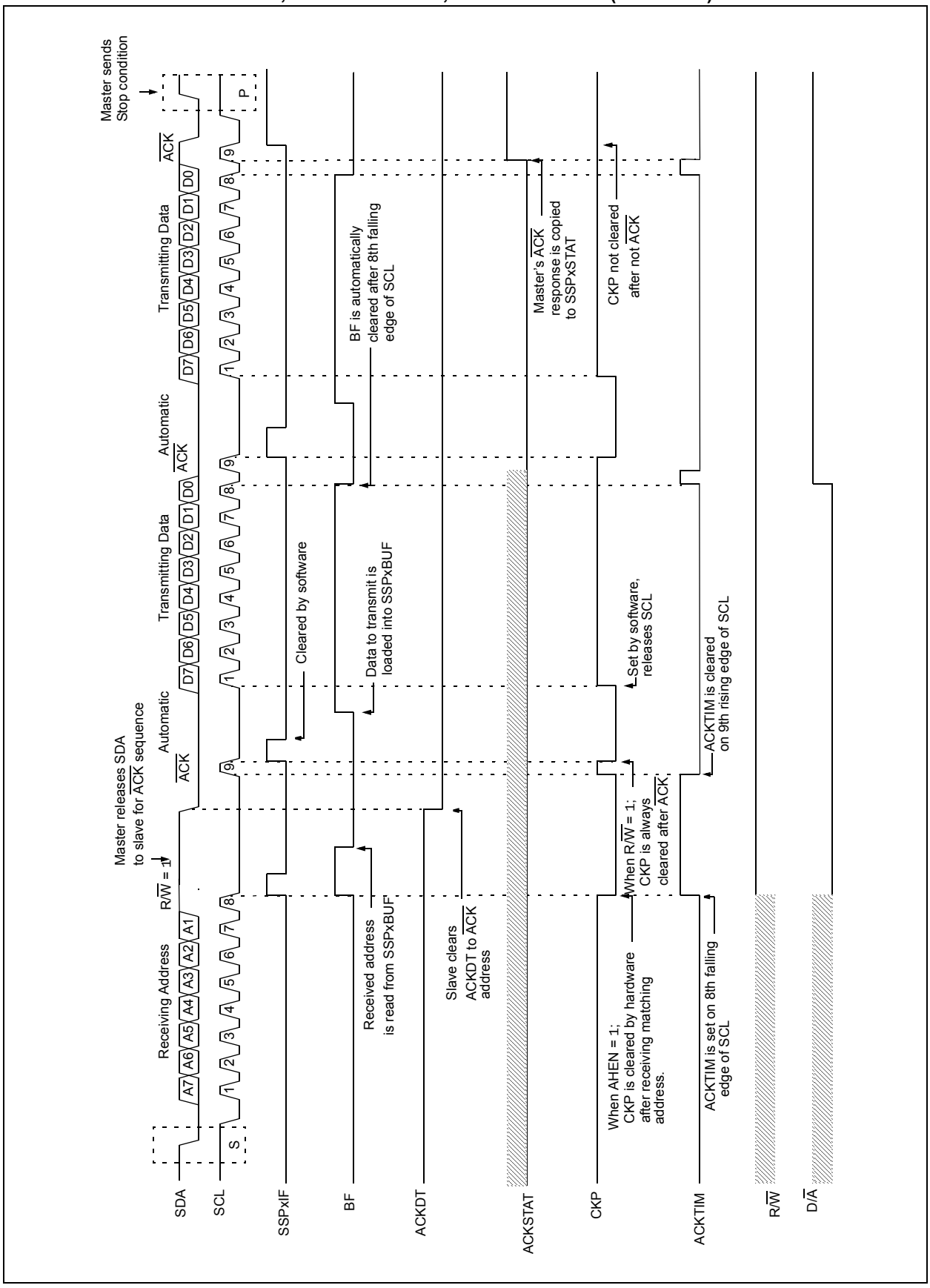


FIGURE 31-19: I²C SLAVE, 7-BIT ADDRESS, TRANSMISSION (AHEN = 1)



REGISTER 31-5: SSPxMSK: SSPx MASK REGISTER

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
SSPxMSK<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-1 **SSPxMSK<7:1>:** Mask bits
1 = The received address bit n is compared to SSPxADD<n> to detect I^2C address match
0 = The received address bit n is not used to detect I^2C address match

bit 0 **SSPxMSK<0>:** Mask bit for I^2C Slave mode, 10-bit Address
I^2C Slave mode, 10-bit address (SSPM<3:0> = 0111 or 1111):
1 = The received address bit 0 is compared to SSPxADD<0> to detect I^2C address match
0 = The received address bit 0 is not used to detect I^2C address match
I^2C Slave mode, 7-bit address:
MSK0 bit is ignored.

REGISTER 31-6: SSPxADD: MSSPx ADDRESS AND BAUD RATE REGISTER (I^2C MODE)

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
SSPxADD<7:0>							
bit 7							bit 0

Legend:		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

Master mode:

bit 7-0 **SSPxADD<7:0>:** Baud Rate Clock Divider bits
SCL pin clock period = ((ADD<7:0> + 1) *4)/FOSC

10-Bit Slave mode – Most Significant Address Byte:

bit 7-3 **Not used:** Unused for Most Significant Address Byte. Bit state of this register is a "don't care". Bit pattern sent by master is fixed by I^2C specification and must be equal to '11110'. However, those bits are compared by hardware and are not affected by the value in this register.

bit 2-1 **SSPxADD<2:1>:** Two Most Significant bits of 10-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a "don't care".

10-Bit Slave mode – Least Significant Address Byte:

bit 7-0 **SSPxADD<7:0>:** Eight Least Significant bits of 10-bit address

7-Bit Slave mode:

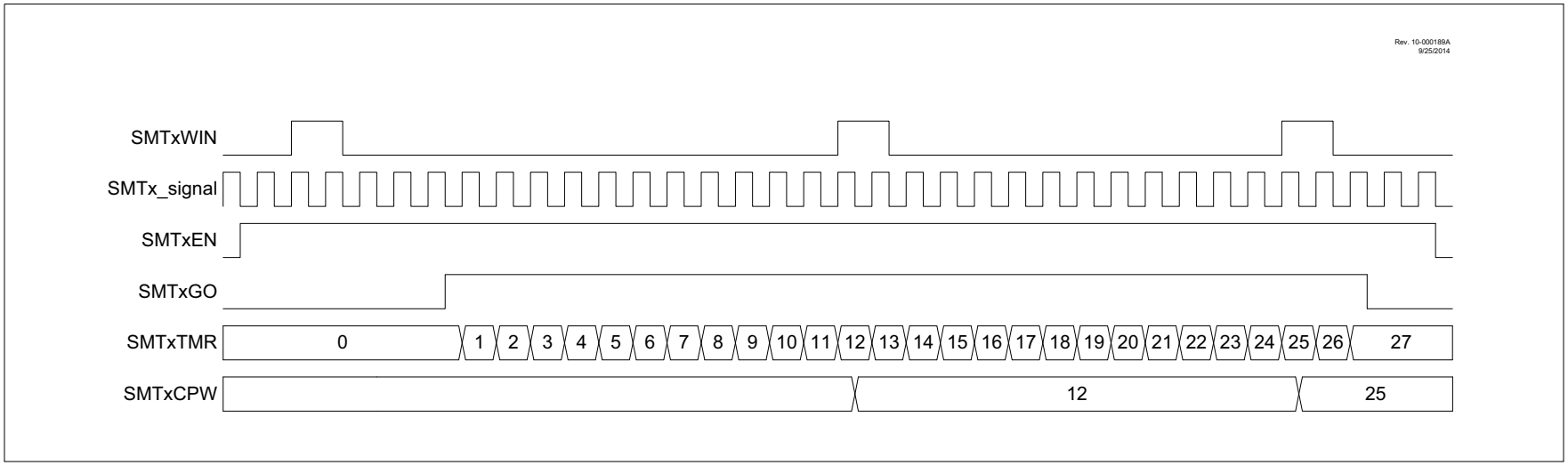
bit 7-1 **SSPxADD<7:1>:** 7-bit address

bit 0 **Not used:** Unused in this mode. Bit state is a "don't care".

32.6.5 WINDOWED MEASURE MODE

This mode measures the window duration of the SMTWINx input of the SMT. It begins incrementing the timer on a rising edge of the SMTWINx input and updates the SMTxCPR register with the value of the timer and resets the timer on a second rising edge. See Figure 32-10 and Figure 32-11.

FIGURE 32-18: COUNTER MODE TIMING DIAGRAM



33.1.2.3 Receive Interrupts

The RCIF interrupt flag bit of the PIR3 register is set whenever the EUSART receiver is enabled and there is an unread character in the receive FIFO. The RCIF interrupt flag bit is read-only, it cannot be set or cleared by software.

RCIF interrupts are enabled by setting all of the following bits:

- RCIE, Interrupt Enable bit of the PIE3 register
- PEIE, Peripheral Interrupt Enable bit of the INTCON register
- GIE, Global Interrupt Enable bit of the INTCON register

The RCIF interrupt flag bit will be set when there is an unread character in the FIFO, regardless of the state of interrupt enable bits.

33.1.2.4 Receive Framing Error

Each character in the receive FIFO buffer has a corresponding framing error Status bit. A framing error indicates that a Stop bit was not seen at the expected time. The framing error status is accessed via the FERR bit of the RC1STA register. The FERR bit represents the status of the top unread character in the receive FIFO. Therefore, the FERR bit must be read before reading the RCREG.

The FERR bit is read-only and only applies to the top unread character in the receive FIFO. A framing error (FERR = 1) does not preclude reception of additional characters. It is not necessary to clear the FERR bit. Reading the next character from the FIFO buffer will advance the FIFO to the next character and the next corresponding framing error.

The FERR bit can be forced clear by clearing the SPEN bit of the RC1STA register which resets the EUSART. Clearing the CREN bit of the RC1STA register does not affect the FERR bit. A framing error by itself does not generate an interrupt.

Note:	If all receive characters in the receive FIFO have framing errors, repeated reads of the RCREG will not clear the FERR bit.

33.1.2.5 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before the FIFO is accessed. When this happens the OERR bit of the RC1STA register is set. The characters already in the FIFO buffer can be read but no additional characters will be received until the error is cleared. The error must be cleared by either clearing the CREN bit of the RC1STA register or by resetting the EUSART by clearing the SPEN bit of the RC1STA register.

33.1.2.6 Receiving 9-Bit Characters

The EUSART supports 9-bit character reception. When the RX9 bit of the RC1STA register is set the EUSART will shift nine bits into the RSR for each character received. The RX9D bit of the RC1STA register is the ninth and Most Significant data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the eight Least Significant bits from the RCREG.

33.1.2.7 Address Detection

A special Address Detection mode is available for use when multiple receivers share the same transmission line, such as in RS-485 systems. Address detection is enabled by setting the ADDEN bit of the RC1STA register.

Address detection requires 9-bit character reception. When address detection is enabled, only characters with the ninth data bit set will be transferred to the receive FIFO buffer, thereby setting the RCIF interrupt bit. All other characters will be ignored.

Upon receiving an address character, user software determines if the address matches its own. Upon address match, user software must disable address detection by clearing the ADDEN bit before the next Stop bit occurs. When user software detects the end of the message, determined by the message protocol used, software places the receiver back into the Address Detection mode by setting the ADDEN bit.

TABLE 36-3: PIC16(L)F18855/75 INSTRUCTION SET (CONTINUED)

Mnemonic, Operands		Description	Cycles	14-Bit Opcode MSb	LSb	Status Affected	Notes
CONTROL OPERATIONS							
BRA	k	Relative Branch	2	11 001k kkkk kkkk			
BRW	–	Relative Branch with W	2	00 0000 0000 1011			
CALL	k	Call Subroutine	2	10 0kkk kkkk kkkk			
CALLW	–	Call Subroutine with W	2	00 0000 0000 1010			
GOTO	k	Go to address	2	10 1kkk kkkk kkkk			
RETFIE	k	Return from interrupt	2	00 0000 0000 1001			
RETLW	k	Return with literal in W	2	11 0100 kkkk kkkk			
RETURN	–	Return from Subroutine	2	00 0000 0000 1000			
INHERENT OPERATIONS							
CLRWDT	–	Clear Watchdog Timer	1	00 0000 0110 0100		$\overline{TO}$, $\overline{PD}$	
NOP	–	No Operation	1	00 0000 0000 0000			
OPTION	–	Load OPTION_REG register with W	1	00 0000 0110 0010			
RESET	–	Software device Reset	1	00 0000 0000 0001			
SLEEP	–	Go into Standby or IDLE mode	1	00 0000 0110 0011		$\overline{TO}$, $\overline{PD}$	
TRIS	f	Load TRIS register with W	1	00 0000 0110 0fff			
C-COMPILER OPTIMIZED							
ADDFSR	n, k	Add Literal k to FSRn	1	11 0001 0nkk kkkk			
MOVIW	n mm	Move Indirect FSRn to W with pre/post inc/dec modifier, mm	1	00 0000 0001 0nmm		Z	**2, 3**
	k[n]	Move INDFn to W, Indexed Indirect.	1	11 1111 0nkk kkkk		Z	**2**
MOVWI	n mm	Move W to Indirect FSRn with pre/post inc/dec modifier, mm	1	00 0000 0001 1nmm			**2, 3**
	k[n]	Move W to INDFn, Indexed Indirect.	1	11 1111 1nkk kkkk			**2**

Note 1: If the Program Counter (PC) is modified, or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP.

2: If this instruction addresses an INDF register and the MSb of the corresponding FSR is set, this instruction will require one additional instruction cycle.

3: See Table in the MOVIW and MOVWI instruction descriptions.