

Welcome to [E-XFL.COM](#)

Understanding [Embedded - Microprocessors](#)

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of [Embedded - Microprocessors](#)

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Product Status	Obsolete
Core Processor	Z80
Number of Cores/Bus Width	1 Core, 8-Bit
Speed	8MHz
Co-Processors/DSP	-
RAM Controllers	-
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	-
SATA	-
USB	-
Voltage - I/O	5.0V
Operating Temperature	-40°C ~ 100°C (TA)
Security Features	-
Package / Case	44-LQFP
Supplier Device Package	44-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z84c0008fec00tr

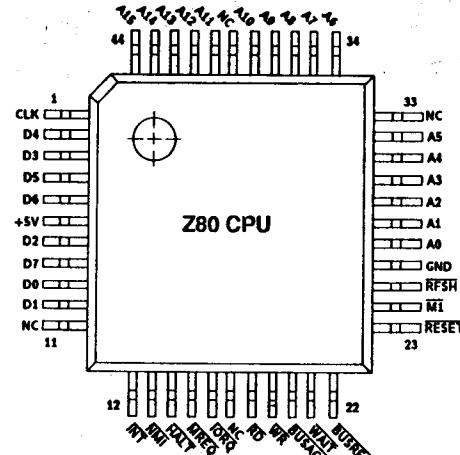


Figure 2a. 44-Pin LQFP, Pin Assignments
(Only available for 84C00)

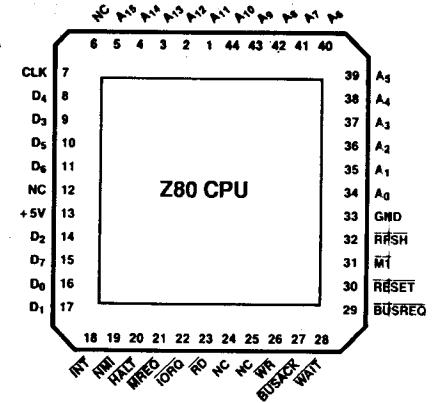


Figure 2b. 44-Pin Chip Carrier Pin
Assignments

GENERAL DESCRIPTION

The CPUs are fourth-generation enhanced microprocessors with exceptional computational power. They offer higher system throughput and more efficient memory utilization than comparable second- and third-generation microprocessors. The internal registers contain 208 bits of read/write memory that are accessible to the programmer. These registers include two sets of six general-purpose registers which may be used individually as either 8-bit registers or as 16-bit register pairs. In addition, there are two sets of accumulator and flag registers. A group of "Exchange" instructions makes either set of main or alternate registers accessible to the programmer. The alternate set allows operation in foreground-background mode or it may be reserved for very fast interrupt response.

The CPU also contains a Stack Pointer, Program Counter, two index registers, a Refresh register (counter), and an Interrupt register. The CPU is easy to incorporate into a system since it requires only a single +5V power source. All output signals are fully decoded and timed to control standard memory or peripheral circuits; the CPU is supported by an extensive family of peripheral controllers. The internal block diagram (Figure 3) shows the primary functions of the processors. Subsequent text provides more detail on the I/O controller family, registers, instruction set, interrupts and daisy chaining, and CPU timing.

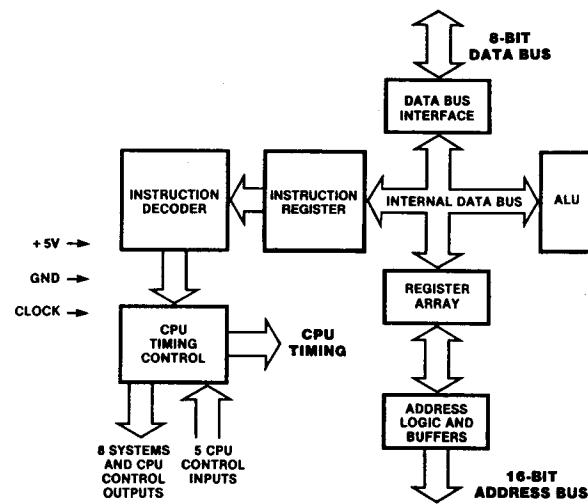


Figure 3. Z80C CPU Block Diagram

Table 1. Z80C CPU Registers

Register	Size (Bits)	Remarks
A, A'	8	Stores an operand or the results of an operation.
F, F'	8	See Instruction Set.
B, B'	8	Can be used separately or as a 16-bit register with C.
C, C'	8	Can be used separately or as a 16-bit register with C.
D, D'	8	Can be used separately or as a 16-bit register with E.
E, E'	8	Can be used separately or as a 16-bit register with E.
H, H'	8	Can be used separately or as a 16-bit register with L.
L, L'	8	Can be used separately or as a 16-bit register with L.
		Note: The (B,C), (D,E), and (H,L) sets are combined as follows: B — High byte C — Low byte D — High byte E — Low byte H — High byte L — Low byte
I	8	Stores upper eight bits of memory address for vectored interrupt processing.
R	8	Provides user-transparent dynamic memory refresh. Automatically incremented and placed on the address bus during each instruction fetch cycle.
IX	16	Used for indexed addressing.
IY	16	Used for indexed addressing
SP	16	Holds address of the top of the stack. See Push or Pop in instruction set.
PC	16	Holds address of next instruction.
IFF ₁ -IFF ₂	Flip-Flops	Set or reset to indicate interrupt status (see Figure 4).
IMFa-IMFb	Flip-Flops	Reflect Interrupt mode (see Figure 4).

failure has been detected. After recognition of the NMI signal (providing BUSREQ is not active), the CPU jumps to restart location 0066H. Normally, software starting at this address contains the interrupt service routine.

Maskable Interrupt (INT). Regardless of the interrupt mode set by the user, the CPU response to a maskable interrupt input follows a common timing cycle. After the interrupt has been detected by the CPU (provided that interrupts are enabled and BUSREQ is not active) a special interrupt processing cycle begins. This is a special fetch (M1) cycle in which IORQ becomes active rather than MREQ, as in a normal M1 cycle. In addition, this special M1 cycle is automatically extended by two WAIT states, to allow for the time required to acknowledge the interrupt request.

Mode 0 Interrupt Operation. This mode is similar to the 8080 microprocessor interrupt service procedures. The interrupting device places an instruction on the data bus. This is normally a Restart instruction, which will initiate a call

to the selected one of eight restart locations in page zero of memory. Unlike the 8080, the Z80 CPU responds to the Call instruction with only one interrupt acknowledge cycle followed by two memory read cycles.

Mode 1 Interrupt Operation. Mode 1 operation is very similar to that for the NMI. The principal difference is that the Mode 1 interrupt has only one restart location, 0038H.

Mode 2 Interrupt Operation. This interrupt mode has been designed to most effectively utilize the capabilities of the Z80 microprocessor and its associated peripheral family. The interrupting peripheral device selects the starting address of the interrupt service routine. It does this by placing an 8-bit vector on the data bus during the interrupt acknowledge cycle. The CPU forms a pointer using this byte as the lower 8 bits and the contents of the I register as the upper 8 bits. This points to an entry in a table of addresses for interrupt service routines. The CPU then jumps to the routine at that

address. This flexibility in selecting the interrupt service routine address allows the peripheral device to use several different types of service routines. These routines may be located at any available location in memory. Since the interrupting device supplies the low-order byte of the 2-byte vector, bit 0 (A_0) must be a zero.

Interrupt Enable/Disable Operation. Two flip-flops, IFF_1 and IFF_2 , referred to in the register description, are used to signal the CPU interrupt status. Operation of the two flip-flops is described in Table 2. For more details, refer to the *Z80 CPU Technical Manual* (03-0029-01) and *Z80 Assembly Language Programming Manual* (03-0002-01).

Table 2. State of Flip-Flops

Action	IFF_1	IFF_2	Comments
CPU Reset	0	0	Maskable interrupt \overline{INT} disabled
DI instruction execution	0	0	Maskable interrupt \overline{INT} disabled
EI instruction execution	1	1	Maskable interrupt \overline{INT} enabled
LD A,I instruction execution	•	•	$IFF_2 \rightarrow$ Parity flag
LD A,R instruction execution	•	•	$IFF_2 \rightarrow$ Parity flag
Accept NMI	0	•	Maskable interrupt \overline{INT} disabled
RETN instruction execution	IFF_2	•	$IFF_2 \rightarrow IFF_1$ at completion of an NMI service routine.

INSTRUCTION SET

The microprocessor has one of the most powerful and versatile instruction sets available in any 8-bit microprocessor. It includes such unique operations as a block move for fast, efficient data transfers within memory, or between memory and I/O. It also allows operations on any bit in any location in memory.

The following is a summary of the instruction set which shows the assembly language mnemonic, the operation, the flag status, and gives comments on each instruction. For an explanation of flag notations and symbols for mnemonic tables, see the Symbolic Notations section which follows these tables. The *Z80 CPU Technical Manual* (03-0029-01), the *Programmer's Reference Guide* (03-0012-03), and *Assembly Language Programming Manual* (03-0002-01) contain significantly more details for programming use.

The instructions are divided into the following categories:

- 8-bit loads
- 16-bit loads
- Exchanges, block transfers, and searches
- 8-bit arithmetic and logic operations
- General-purpose arithmetic and CPU control
- 16-bit arithmetic operations
- Rotates and shifts

- Bit set, reset, and test operations
- Jumps
- Calls, returns, and restarts
- Input and output operations

A variety of addressing modes are implemented to permit efficient and fast data transfer between various registers, memory locations, and input/output devices. These addressing modes include:

- Immediate
- Immediate extended
- Modified page zero
- Relative
- Extended
- Indexed
- Register
- Register indirect
- Implied
- Bit

8-BIT LOAD GROUP

Mnemonic	Symbolic Operation	Flags						Opcode			No. of Bytes	No. of M Cycles	No. of T States	Comments		
		S	Z	H	P/V	N	C	76	543	210						
LD r, r'	r ← r'	•	•	X	•	X	•	•	•	01	r	r'	1	1	4	r, r' Reg.
LD r, n	r ← n	•	•	X	•	X	•	•	•	00	r	110	2	2	7	000 B
										← n →					001 C	
LD r, (HL)	r ← (HL)	•	•	X	•	X	•	•	•	01	r	110	1	2	7	010 D
LD r, (IX+d)	r ← (IX+d)	•	•	X	•	X	•	•	•	11	011	101 DD	3	5	19	011 E
										01	r	110			100 H	
										← d →					101 L	
LD r, (IY+d)	r ← (IY+d)	•	•	X	•	X	•	•	•	11	111	101 FD	3	5	19	111 A
										01	r	110			← d →	
LD (HL), r	(HL) ← r	•	•	X	•	X	•	•	•	01	110	r	1	2	7	
LD (IX+d), r	(IX+d) ← r	•	•	X	•	X	•	•	•	11	011	101 DD	3	5	19	
										01	110	r			← d →	
LD (IY+d), r	(IY+d) ← r	•	•	X	•	X	•	•	•	11	111	101 FD	3	5	19	
										01	110	r			← d →	
LD (HL), n	(HL) ← n	•	•	X	•	X	•	•	•	00	110	110 36	2	3	10	
										← n →						
LD (IX+d), n	(IX+d) ← n	•	•	X	•	X	•	•	•	11	011	101 DD	4	5	19	
										00	110	110 36			← d →	
										← n →						

16-BIT LOAD GROUP (Continued)

Mnemonic	Symbolic Operation	S	Z	H	P/V	N	C	76	Opcode 543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments
LD IX, (nn)	$IX_H \leftarrow (nn+1)$ $IX_L \leftarrow (nn)$	•	•	X	•	X	•	•	11	011	101	DD	4	6	20
									00	101	010	2A		↔ n ↔	
														↔ n ↔	
LD IY, (nn)	$IY_H \leftarrow (nn+1)$ $IY_L \leftarrow (nn)$	•	•	X	•	X	•	•	11	111	101	FD	4	6	20
									00	101	010	2A		↔ n ↔	
														↔ n ↔	
LD (nn), HL	$(nn+1) \leftarrow H$ $(nn) \leftarrow L$	•	•	X	•	X	•	•	00	100	010	22	3	5	16
														↔ n ↔	
														↔ n ↔	
LD (nn), dd	$(nn+1) \leftarrow dd_H$ $(nn) \leftarrow dd_L$	•	•	X	•	X	•	•	11	101	101	ED	4	6	20
									01	dd0	011			↔ n ↔	
														↔ n ↔	
LD (nn), IX	$(nn+1) \leftarrow IX_H$ $(nn) \leftarrow IX_L$	•	•	X	•	X	•	•	11	011	101	DD	4	6	20
									00	100	010	22		↔ n ↔	
														↔ n ↔	
LD (nn), IY	$(nn+1) \leftarrow IY_H$ $(nn) \leftarrow IY_L$	•	•	X	•	X	•	•	11	111	101	FD	4	6	20
									00	100	010	22		↔ n ↔	
														↔ n ↔	
LD SP, HL	$SP \leftarrow HL$	•	•	X	•	X	•	•	11	111	001	F9	1	1	6
LD SP, IX	$SP \leftarrow IX$	•	•	X	•	X	•	•	11	011	101	DD	2	2	10
									11	111	001	F9			
LD SP, IY	$SP \leftarrow IY$	•	•	X	•	X	•	•	11	111	101	FD	2	2	10
									11	111	001	F9			
PUSH qq	$(SP-2) \leftarrow qq_L$ $(SP-1) \leftarrow qq_H$ $SP \rightarrow SP - 2$	•	•	X	•	X	•	•	11	qq0	101		1	3	11
														qq 00 BC	
														01 DE	
														10 HL	
PUSH IX	$(SP-2) \leftarrow IX_L$ $(SP-1) \leftarrow IX_H$ $SP \rightarrow SP - 2$	•	•	X	•	X	•	•	11	011	101	DD	2	4	15
									11	100	101	E5			11 AF
PUSH IY	$(SP-2) \leftarrow IY_L$ $(SP-1) \leftarrow IY_H$ $SP \rightarrow SP - 2$	•	•	X	•	X	•	•	11	111	101	FD	2	4	15
									11	100	101	E5			
POP qq	$qq_H \leftarrow (SP+1)$ $qq_L \leftarrow (SP)$ $SP \rightarrow SP + 2$	•	•	X	•	X	•	•	11	qq0	001		1	3	10
POP IX	$IX_H \leftarrow (SP+1)$ $IX_L \leftarrow (SP)$ $SP \rightarrow SP + 2$	•	•	X	•	X	•	•	11	011	101	DD	2	4	14
									11	100	001	E1			
POP IY	$IY_H \leftarrow (SP+1)$ $IY_L \leftarrow (SP)$ $SP \rightarrow SP + 2$	•	•	X	•	X	•	•	11	111	101	FD	2	4	14
									11	100	001	E1			

NOTE: (PAIR)_H, (PAIR)_L refer to high order and low order eight bits of the register pair respectively, e.g., BC_L = C, AF_H = A.

EXCHANGE, BLOCK TRANSFER, BLOCK SEARCH GROUPS (Continued)

Mnemonic	Symbolic Operation	S	Z	H	P/V	N	C	76	Opcode 543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments	
CPIR	A - (HL)	†	†	X	†	X	†	1	•	11	101 101	ED	2	5	21	If BC ≠ 0 and A ≠ (HL)
	HL ← HL + 1							10	110 001	B1		2	4	16	If BC = 0 or A = (HL)	
	BC ← BC - 1								10	101 001	A9					
	Repeat until															
	A = (HL) or															
	BC = 0															
CPD	A - (HL)	†	†	X	†	X	†	1	•	11	101 101	ED	2	4	16	
	HL ← HL - 1							10	101 001	A9						
	BC ← BC - 1															
CPDR	A - (HL)	†	†	X	†	X	†	1	•	11	101 101	ED	2	5	21	If BC ≠ 0 and A ≠ (HL)
	HL ← HL - 1							10	111 001	B9		2	4	16	If BC = 0 or A = (HL)	
	BC ← BC - 1															
	Repeat until															
	A = (HL) or															
	BC = 0															

NOTE: ① P/V flag is 0 if the result of BC - 1 = 0, otherwise P/V = 1.

② P/V flag is 0 only at completion of instruction.

③ Z flag is 1 if A = (HL), otherwise Z = 0.

8-BIT ARITHMETIC AND LOGICAL GROUP

Mnemonic	Symbolic Operation	S	Z	H	P/V	N	C	76	Opcode 543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments	
ADD A, r	A ← A+r	†	†	X	†	X	V	0	†	10	000	r	1	1	4	r Reg.
ADD A, n	A ← A+n	†	†	X	†	X	V	0	†	11	000	110 ↔ n ↔	2	2	7	000 B 001 C 010 D
ADD A, (HL)	A ← A+(HL)	†	†	X	†	X	V	0	†	10	000	110	1	2	7	011 E
ADD A, (IX+d)	A ← A+(IX+d)	†	†	X	†	X	V	0	†	11	011	101 DD 10 000 110 ↔ d ↔	3	5	19	100 H 101 L 111 A
ADD A, (IY+d)	A ← A+(IY+d)	†	†	X	†	X	V	0	†	11	111	101 FD 10 000 110 ↔ d ↔	3	5	19	
ADC A, s	A ← A+s+CY	†	†	X	†	X	V	0	†		001				s is any of r, n, (HL), (IX+d), (IY+d) as shown for ADD instruction. The indicated bits replace the 000 in the ADD set above.	
SUB s	A ← A-s	†	†	X	†	X	V	1	†		010					
SBC A, s	A ← A-s-CY	†	†	X	†	X	V	1	†		011					
AND s	A ← A>s	†	†	X	1	X	P	0	0		100					
OR s	A ← A>s	†	†	X	0	X	P	0	0		110					
XOR s	A ← A&s	†	†	X	0	X	P	0	0		101					
CP s	A-s	†	†	X	†	X	V	1	†		111					

16-BIT ARITHMETIC GROUP

Mnemonic	Symbolic Operation	S	Z	H	P/V	N	C	76	543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments	
ADD HL, ss	HL ← HL + ss	•	•	X	X	X	•	0	†	00	ss1	001	1	3	11	ss Reg. 00 BC 01 DE 10 HL 11 SP
ADC HL, ss	HL ← HL + ss + CY	†	†	X	X	X	V	0	†	11	101	101	ED	2	4	15
								01	ss1	010					11 SP	
SBC HL, ss	HL ← HL - ss - CY	†	†	X	X	X	V	1	†	11	101	101	ED	2	4	15
								01	ss0	010						
ADD IX, pp	IX ← IX + pp	•	•	X	X	X	•	0	†	11	011	101	DD	2	4	15
								01	pp1	001					pp Reg. 00 BC 01 DE 10 IX 11 SP	
ADD IY, rr	IY ← IY + rr	•	•	X	X	X	•	0	†	11	111	101	FD	2	4	15
								00	rr1	001					rr Reg. 00 BC	
INC ss	ss ← ss + 1	•	•	X	•	X	•	•	•	00	ss0	011		1	1	6
INC IX	IX ← IX + 1	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	10
								00	100	011	23				11 SP	
INC IY	IY ← IY + 1	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	10
								00	100	011	23					
DEC ss	ss ← ss - 1	•	•	X	•	X	•	•	•	00	ss1	011		1	1	6
DEC IX	IX ← IX - 1	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	10
								00	101	011	2B					
DEC IY	IY ← IY - 1	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	10
								00	101	011	2B					

ROTATE AND SHIFT GROUP

Mnemonic	Symbolic Operation	S	Z	H	P/V	N	C	76	543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments		
RLCA		•	•	X	0	X	•	0	†	00	000	111	07	1	1	4	Rotate left circular accumulator.
RLA		•	•	X	0	X	•	0	†	00	010	111	17	1	1	4	Rotate left accumulator.
RRCA		•	•	X	0	X	•	0	†	00	001	111	0F	1	1	4	Rotate right circular accumulator.
RRA		•	•	X	0	X	•	0	†	00	011	111	1F	1	1	4	Rotate right accumulator.

JUMP GROUP

Mnemonic	Symbolic Operation	S	Z	H	Flags	P/V	N	C	76	543	210	Opcode Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments	
JP nn	PC ← nn	•	•	X	•	X	•	•	•	11	000	011	C3	3	3	10	cc Condition 000 NZ (non-zero) 001 Z (zero)
JP cc, nn	If condition cc is true PC←nn, otherwise continue	•	•	X	•	X	•	•	•	11	cc	010		3	3	10	010 NC (non-carry) 011 C (carry) 100 PO (parity odd) 101 PE (parity even) 110 P (sign positive) 111 M (sign negative)
JR e	PC ← PC+e	•	•	X	•	X	•	•	•	00	011	000	18	2	3	12	If condition not met.
JRC, e	If C=0, continue If C=1, PC ← PC+e	•	•	X	•	X	•	•	•	00	111	000	38	2	3	12	If condition is met.
JR NC, e	IFC=1, continue IFC=0, PC ← PC+e	•	•	X	•	X	•	•	•	00	110	000	30	2	2	7	If condition not met.
JP Z, e	If Z=0 continue If Z=1, PC ← PC+e	•	•	X	•	X	•	•	•	00	101	000	28	2	2	7	If condition not met. If condition is met.
JRNZ, e	If Z=1, continue If Z=0, PC ← PC+e	•	•	X	•	X	•	•	•	00	100	000	20	2	2	7	If condition not met. If condition is met.
JP (HL)	PC ← HL	•	•	X	•	X	•	•	•	11	101	001	E9	1	1	4	
JP (IX)	PC ← IX	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	8	
JP (IY)	PC ← IY	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	8	
DJNZ, e	B ← B-1 If B=0, continue If B≠0, PC ← PC+e	•	•	X	•	X	•	•	•	00	010	000	10	2	2	8	If B=0 If B≠0.

NOTES: e represents the extension in the relative addressing mode.

e is a signal two's complement number in the range < -126, 129 >.

e-2 in the opcode provides an effective address of pc+e as PC is incremented by 2 prior to the addition of e.

INPUT AND OUTPUT GROUP

	Symbolic Mnemonic Operation	S	Z	H	Flags P/V/N C	Opcode 76	543	210	Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments
IN A, (n)	A ← (n)	•	•	X	• X • • •	11	011	01	DB	2	3	11	n to A ₀ ~ A ₇ Acc. to A ₈ ~ A ₁₅
IN r, (C)	r ← (C) if r = 110 only the flags will be affected	‡	‡	X	‡ X P 0 •	11	101	101	ED	2	3	12	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅
①						01	r	000					
INI	(HL) ← (C) B ← B - 1 HL ← HL + 1	X	‡	X X X X 1 X	11	101	101	ED	2	4	16	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
②						10	100	010	A2				
INIR	(HL) ← (C) B ← B - 1 HL ← HL + 1 Repeat until B = 0	X	1	X X X X 1 X	11	101	101	ED	2	5	21	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
						10	110	010	B2				(If B ≠ 0)
										2	4	16	(If B = 0)
IND	(HL) ← (C) B ← B - 1 HL ← HL - 1	X	‡	X X X X 1 X	11	101	101	ED	2	4	16	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
①						10	101	010	AA				
INDR	(HL) ← (C) B ← B - 1 HL ← HL - 1 Repeat until B = 0	X	1	X X X X 1 X	11	101	101	ED	2	5	21	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
						10	111	010	BA				(If B ≠ 0)
										2	4	16	(If B = 0)
OUT (n), A (n) ← A	• • X • X • • •	11	010	011	D3	2	3	11	n to A ₀ ~ A ₇ Acc. to A ₈ ~ A ₁₅				
						→ n →							
OUT (C), r (C) ← r	• • X • X • • •	11	101	101	ED	2	3	12	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅				
①						01	r	001					
OUTI	(C) ← (HL) B ← B - 1 HL ← HL + 1	X	‡	X X X X 1 X	11	101	101	ED	2	4	16	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
②						10	100	011	A3				
OTIR	(C) ← (HL) B ← B - 1 HL ← HL + 1 Repeat until B = 0	X	1	X X X X 1 X	11	101	101	ED	2	5	21	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
						10	110	011	B3				(If B ≠ 0)
										2	4	16	(If B = 0)
OUTD	(C) ← (HL) B ← B - 1 HL ← HL - 1	X	‡	X X X X 1 X	11	101	101	ED	2	4	16	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
①						10	101	011	AB				
OTDR	(C) ← (HL) B ← B - 1 HL ← HL - 1 Repeat until B = 0	X	1	X X X X 1 X	11	101	101	ED	2	5	21	C to A ₀ ~ A ₇ B to A ₈ ~ A ₁₅	
						10	111	011					(If B ≠ 0)
										2	4	16	(If B = 0)

NOTES: ① If the result of B - 1 is zero, the Z flag is set; otherwise it is reset.

② Z flag is set upon instruction completion only.

Input or Output Cycles. Figure 7 shows the timing for an I/O read or I/O write operation. During I/O operations, the CPU automatically inserts a single Wait state (T_{WA}). This

extra Wait state allows sufficient time for an I/O port to decode the address from the port address lines.

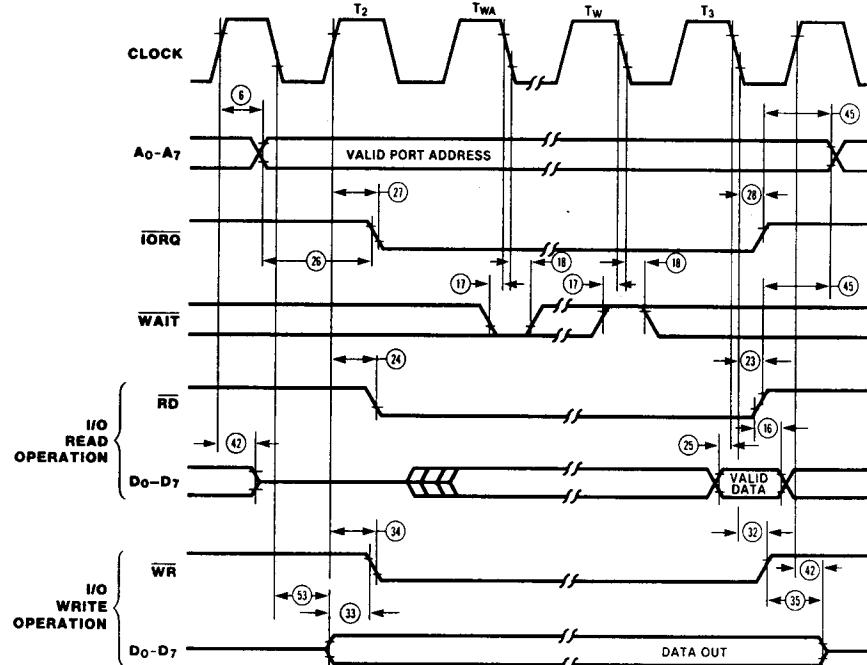
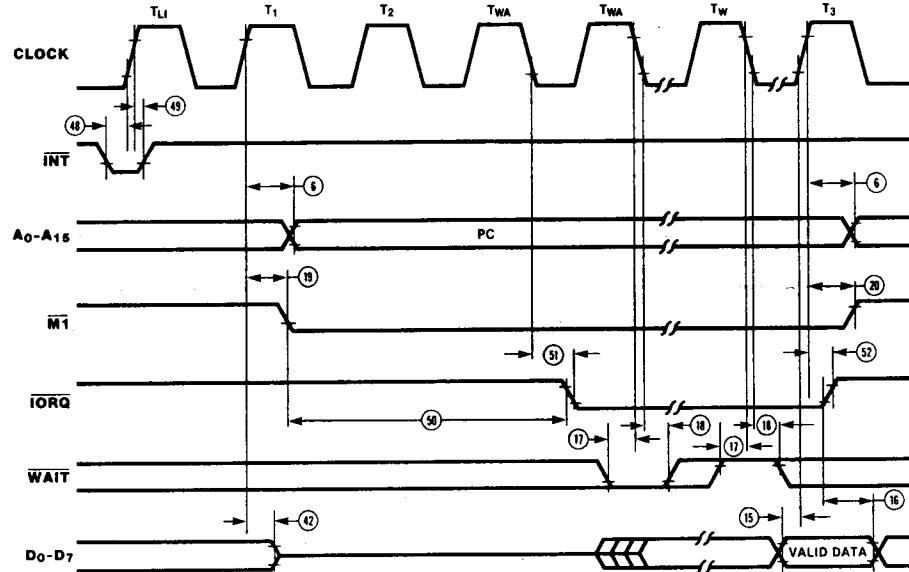


Figure 7. Input or Output Cycles

Interrupt Request/Acknowledge Cycle. The CPU samples the interrupt signal with the rising edge of the last clock cycle at the end of any instruction (Figure 8). When an interrupt is accepted, a special M1 cycle is generated.

During this $\overline{M1}$ cycle, \overline{IORQ} becomes active (instead of \overline{MREQ}) to indicate that the interrupting device can place an 8-bit vector on the data bus. The CPU automatically adds two Wait states to this cycle.



Power-Down mode of operation (Only applies to CMOS Z80 CPU).

CMOS Z80 CPU supports Power-Down mode of operation.

This mode is also referred to as the "standby mode", and supply current for the CPU goes down as low as 10 μ A (Where specified as I_{CC2}).

Power-Down Acknowledge Cycle. When the clock input to the CPU is stopped at either a High or Low level, the CPU stops its operation and maintains all registers and control signals. However, I_{CC2} (standby supply current) is guaranteed only when the system clock is stopped at a Low

level during T_4 of the machine cycle following the execution of the HALT instruction. The timing diagram for the power-down function, when implemented with the HALT instruction, is shown in Figure 13.

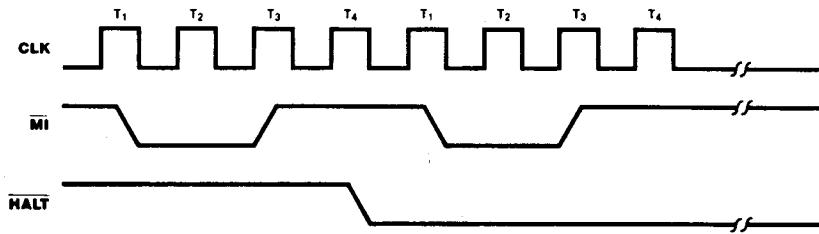


Figure 13. Power-Down Acknowledge

Power-Down Release Cycle. The system clock must be supplied to the CPU to release the power-down state. When the system clock is supplied to the CLK input, the CPU restarts operations from the point at which the power-down state was implemented. The timing diagrams for the release from power-down mode are shown in Figure 14.

NOTES:

- 1) When the external oscillator has been stopped to enter the power-down state, some warm-up time may be required to obtain a stable clock for the release.
- 2) When the HALT instruction is executed to enter the power-down state, the CPU will also enter the Halt state. An interrupt signal (either NMI or INT) or a RESET signal must be applied to the CPU after the system clock is supplied in order to release the power-down state.

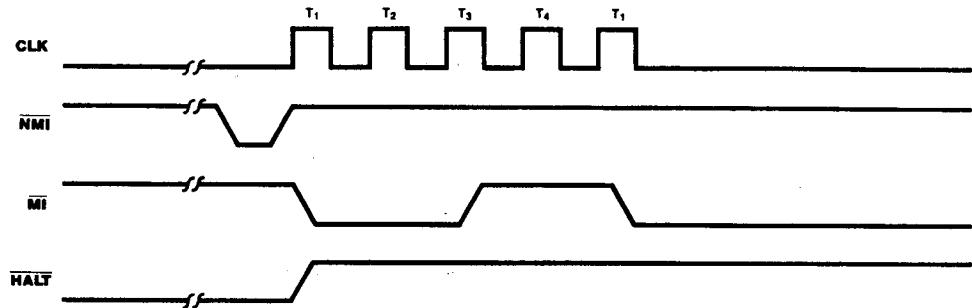


Figure 14a.

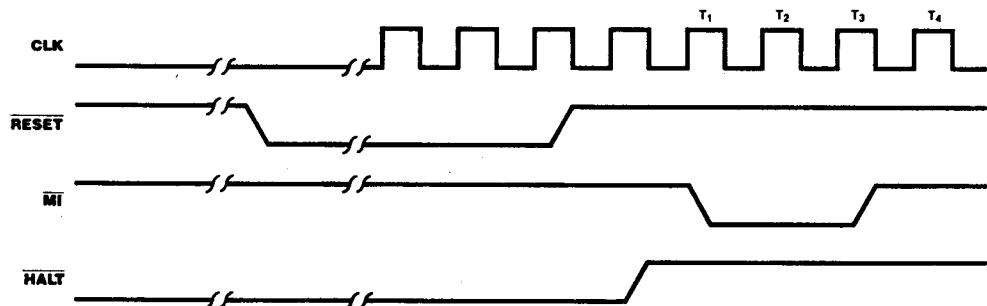


Figure 14b.

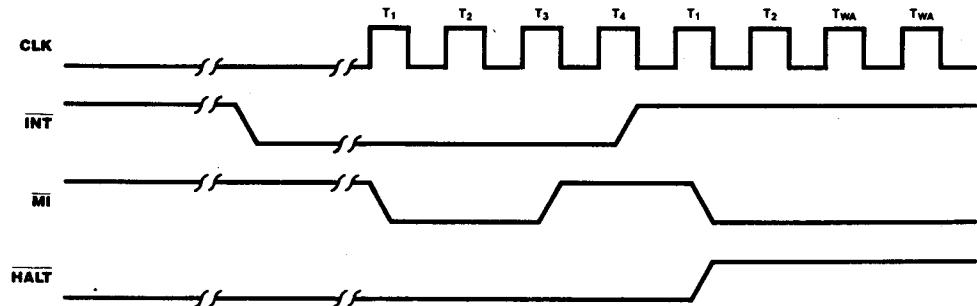


Figure 14c.

Figure 13. Power-Down Release

DC CHARACTERISTICS (Z84C00/CMOS Z80 CPU)

Symbol	Parameter	Min	Max	Unit	Condition
V_{ILC}	Clock Input Low Voltage	-0.3	0.45	V	
V_{IHC}	Clock Input High Voltage	$V_{CC} - .6$	$V_{CC} + .3$	V	
V_{IL}	Input Low Voltage	-0.3	0.8	V	
V_{IH}	Input High Voltage	2.2	V_{CC}	V	
V_{OL}	Output Low Voltage		0.4	V	$I_{OL} = 2.0 \text{ mA}$
V_{OH_1}	Output High Voltage	2.4		V	$I_{OH} = -1.6 \text{ mA}$
V_{OH_2}	Output High Voltage	$V_{CC} - 0.8$		V	$I_{OH} = -250 \mu\text{A}$
I_{CC_1}	Power Supply Current 4 MHz	20		mA	$V_{CC} = 5\text{V}$
	6 MHz	30		mA	$V_{IH} = V_{CC} - 0.2\text{V}$
	8 MHz	40		mA	$V_{IL} = 0.2\text{V}$
	10 MHz	50		mA	
	20 MHz	100		mA	$V_{CC} = 5\text{V}$
I_{CC_2}	Standby Supply Current	10		μA	$V_{CC} = 5\text{V}$
					$CLK = (0)$
					$V_{IH} = V_{CC} - 0.2\text{V}$
					$V_{IL} = 0.2\text{V}$
I_{LI}	Input Leakage Current	-10	10	μA	$V_{IN} = 0.4 \text{ to } V_{CC}$
I_{LO}	3-State Output Leakage Current in Float	-10	10^2	μA	$V_{OUT} = 0.4 \text{ to } V_{CC}$

1. Measurements made with outputs floating.

2. $A_{15}\text{-}A_0$, $D_7\text{-}D_0$, \overline{MREQ} , \overline{IORQ} , \overline{RD} , and \overline{WR} .

3. I_{CC_2} standby supply current is guaranteed only when the supplied clock is stopped at a low level during T_4 of the machine cycle immediately following the execution of a HALT instruction.

CAPACITANCE

Symbol	Parameter	Min	Max	Unit
C_{CLOCK}	Clock Capacitance		10	pf
C_{IN}	Input Capacitance		5	pf
C_{OUT}	Output Capacitance		15	pf

$T_A = 25^\circ\text{C}$, $f = 1 \text{ MHz}$.

Unmeasured pins returned to ground.

AC CHARACTERISTICS[†] (Z84C00/CMOS Z80 CPU)

$V_{cc} = 5.0V \pm 10\%$, unless otherwise specified

No	Symbol	Parameter	Z84C0004		Z84C0006		Z84C0008		Z84C0010		Z84C0020[1]		Unit	Note	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max			
1	T _{cC}	Clock Cycle time	250*	DC	162*	DC	125*	DC	100*	DC	50*	DC	nS		
2	T _{wCh}	Clock Pulse width (high)	110	DC	65	DC	55	DC	40	DC	20	DC	nS		
3	T _{wCl}	Clock Pulse width (low)	110	DC	65	DC	55	DC	40	DC	20	DC	nS		
4	T _{fC}	Clock Fall time	30		20		10		10		10		nS		
5	T _{rC}	Clock Rise time	30		20		10		10		10		nS		
6	T _{dCr(A)}	Address valid from Clock Rise	110		90		80		65		57		nS	[2]	
7	T _{dA(MREQf)}	Address valid to /MREQ Fall	65*		35*		20*		5*		-15*		nS		
8	T _{dCf(MREQf)}	Clock Fall to /MREQ Fall delay	85		70		60		55		40		nS		
9	T _{dCr(MREQr)}	Clock Rise to /MREQ Rise delay	85		70		60		55		40		nS		
10	T _{wMREQh}	/MREQ pulse width (High)	110*		65*		45**		30*		10*		nS	[3]	
11	T _{wMREQl}	/MREQ pulse width (low)	220*		132*		100*		75*		25*		nS	[3]	
12	T _{dCf(MERQr)}	Clock Fall to /MREQ Rise delay	85		70		60		55		40		nS		
13	T _{dCf(RDf)}	Clock Fall to /RD Fall delay	95		80		70		65		40		nS		
14	T _{dCr(RDr)}	Clock Rise to /RD Rise delay	85		70		60		55		40		nS		
15	T _{sD(Cr)}	Data setup time to Clock Rise	35		30		30		25		12		nS		
16	T _{hD(RDr)}	Data hold time after /RD Rise	0		0		0		0		0		nS		
17	T _{sWAIT(Cf)}	/WAIT setup time to Clock Fall	70		60		50		20		7.5		nS		
18	T _{hWAIT(Cf)}	/WAIT hold time after Clock Fall	10		10		10		10		10		nS		
19	T _{dCr(M1f)}	Clock Rise to /M1 Fall delay	100		80		70		65		45		nS		
20	T _{dCr(M1r)}	Clock Rise to /M1 Rise delay	100		80		70		65		45		nS		
21	T _{dCr(RFSHf)}	Clock Rise to /RFSH Fall delay	130		110		95		80		60		nS		
22	T _{dCr(RFSHr)}	Clock Rise to /RFSH Rise delay	120		100		85		80		60		nS		
23	T _{dCf(RDf)}	Clock Fall to /RD Rise delay	85		70		60		55		40		nS		
24	T _{dCr(RDf)}	Clock Rise to /RD Fall delay	85		70		60		55		40		nS		
25	T _{sD(Cf)}	Data setup to Clock Fall during M2, M3, M4 or M5 cycles	50		40		30		25		12		nS		
26	T _{dA(IORQf)}	Address stable prior to /IORQ Fall	180*		107*		75*		50*		0*		nS		
27	T _{dCr(IORQf)}	Clock Rise to /IORQ Fall delay	75		65		55		50		40		nS		
28	T _{dCf(IORQr)}	Clock Fall to /IORQ Rise delay	85		70		60		55		40		nS		
29	T _{dD(WRf)Mw}	Data stable prior to /WR Fall	80*		22*		5*		40*		-10*		nS		
30	T _{dCf(WRf)}	Clock Fall to /WR Fall delay	80		70		60		55		40		nS		
31	T _{wWR}	/WR pulse width	220*		132*		100*		75*		25*		nS		
32	T _{dCf(WRr)}	Clock Fall to /WR Rise delay	80		70		60		55		40		nS		
33	T _{dD(WRf)IO}	Data stable prior to /WR Fall	-10*		-55*		-55*		-10*		-30*		nS		
34	T _{dCr(WRf)}	Clock Rise to /WR Fall delay	65		60		60		50		40		nS		
35	T _{dWRr(D)}	Data stable from /WR Rise	60*		30*		15*		10*		0*		nS		
36	T _{dCf(HALT)}	Clock Fall to /HALT 'L' or 'H'		300		260		225		90		70		nS	
37	T _{wNMI}	/NMI pulse width	80		60		60		60		60		nS		
38	T _{sBUSREQ(Cr)}	/BUSREQ setup time to Clock Rise	50		50		40		30		15		nS		

*For clock periods other than the minimums shown, calculate parameters using the table on the following page.
Calculated values above assumed TrC = TIC = 20 ns.

†Units in nanoseconds (ns).

†† For loading ≥ 50 pF. Decrease width by 10 ns for each additional 50 pF.

** 4 MHz CMOS Z80 is obsolete and replaced by 6 MHz

AC CHARACTERISTICS[†] (Z84C00/CMOS Z80 CPU; Continued)

$V_{cc} = 5.0V \pm 10\%$, unless otherwise specified

No	Symbol	Parameter	Z84C0004 ^{**}					Z84C0006		Z84C0008		Z84C0010		Z84C0020[1]		Unit	Note
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
39	ThBUSREQ (Cr)	/BUSREQ hold time after Clock Rise	10	10	10	10	10	10	10	10	10	10	10	10	10	nS	
40	TdCr (BUSACKf)	Clock Rise to /BASACK Fall delay			100	90	80		75		40					nS	
41	TdCr (BUSACKr)	Clock Fall to /BASACK Rise delay	100	90	80		75		40							nS	
42	TdCr(Dz)	Clock Rise to Data float delay	90	80	70		65		40							nS	
43	TdCr(CTz)	Clock Rise to Control Outputs Float Delay (/MREQ, /IORQ, /RD and /WR)		80	70	60		65		40						nS	
44	TdCr(Az)	Clock Rise to Address float delay	90	80	70		75		40							nS	
45	TdCTR(A)	Address Hold time from /MREQ, /IORQ, /RD or /WR	80*		35*	20*	20*		0*							nS	
46	TsRESET(Cr)	/RESET to Clock Rise setup time	60		60	45	40		15							nS	
47	ThRESET(Cr)	/RESET to Clock Rise Hold time	10		10		10		10							nS	
48	TsINTf(Cr)	/INT Fall to Clock Rise Setup Time	80		70	55	50		15							nS	
49	ThINTr(Cr)	/INT Rise to Clock Rise Hold Time	10		10		10		10							nS	
50	TdM1f (IORQf)	/M1 Fall to /IORQ Fall delay	565*		359*	270*	220*		100*							nS	
51	TdCr(IORQf)	/Clock Fall to /IORQ Fall delay	85		70	60	55		45							nS	
52	TdCr(IORQr)	Clock Rise to /IORQ Rise delay	85		70	60	55		45							nS	
53	TdCr(D)	Clock Fall to Data Valid delay	150		130	115	110		75							nS	

Notes:

- For Clock periods other than the minimum shown, calculate parameters using the following table.
Calculated values above assumed TrC = TIC = maximum.

^{**} 4 MHz CMOS Z80 is obsoleted and replaced by 6 MHz

[1] Z84C0020 parameters are guaranteed with 50pF load Capacitance.

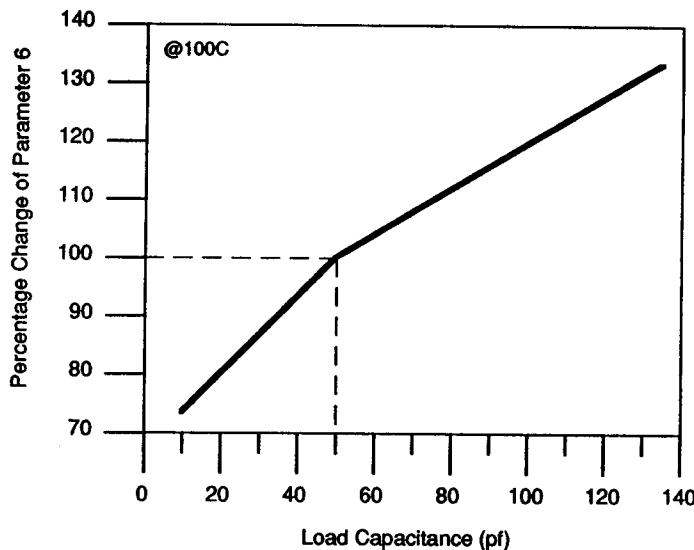
[2] If Capacitive Load is other than 50pF, please use Figure 1. to calculate the value.

[3] Increasing delay by 10nS for each 50pF increase in loading, 200pF max for data lines, and 100pF for control lines.

FOOTNOTES TO AC CHARACTERISTICS

No	Symbol	Parameter	Z84C0004 ^{**}	Z84C0006	Z84C0008	Z84C0010	Z84C0020
1	TcC	$TwCh + TwCl + TrC + TfC$					
7	TdA(MREQf)	$TwCh + TIC$	-65	-50	-45	-45	-45
10	TwMREQh	$TwCh + TIC$	-20	-20	-20	-20	-20
11	TwMREQl	TcC	-30	-30	-25	-25	-25
26	TdA(IORQf)	TcC	-70	-55	-50	-50	-50
29	TdD(WRf)	TcC	-170	-140	-120	-60	-60
31	TwWR	TcC	-30	-30	-25	-25	-25
33	TdD(WRf)	$TwCl + TrC$	-140	-140	-120	-60	-60
35	TdWRr(D)	$TwCl + TrC$	-70	-55	-50	-40	-25
45	TdCTR(A)	$TwCl + TrC$	-50	-50	-45	-30	-30
50	TdM1f(IORQf)	$2TcC + TwCh + TIC$	-65	-50	-45	-30	-30

AC Test Conditions: $V_{IH} = 2.0V$ $V_{OH} = 1.5V$ $V_{IL} = 0.8V$ $V_{OL} = 1.5V$ $V_{IHC} = V_{CC} - 0.6V$ FLOAT = $\pm 0.5V$ $V_{ILC} = 0.45V$



**Figure 1. Address Delay Characteristics
(Parameter 6)**

DC CHARACTERISTICS (Z8400/NMOS Z80 CPU)

All parameters are tested unless otherwise noted.

Symbol	Parameter	Min	Max	Unit	Test Condition
V_{ILC}	Clock Input Low Voltage	-0.3	0.45	V	
V_{IHC}	Clock Input High Voltage	$V_{CC} - .6$	$V_{CC} + .3$	V	
V_{IL}	Input Low Voltage	-0.3	0.8	V	
V_{IH}	Input High Voltage	2.0 ¹	V_{CC}	V	
V_{OL}	Output Low Voltage		0.4	V	$I_{OL} = 2.0 \text{ mA}$
V_{OH}	Output High Voltage		2.4 ¹	V	$I_{OH} = -250 \mu\text{A}$
I_{CC}	Power Supply Current		200	mA	Note 3
I_{LI}	Input Leakage Current		10	μA	$V_{IN} = 0 \text{ to } V_{CC}$
I_{LO}	3-State Output Leakage Current in Float	-10	10^2	μA	$V_{OUT} = 0.4 \text{ to } V_{CC}$

1. For military grade parts, refer to the Z80 Military Electrical Specification.

2. A₁₅-A₀, D₇-D₀, MREQ, IORQ, RD, and WR.

3. Measurements made with outputs floating.

CAPACITANCE

Guaranteed by design and characterization.

Symbol	Parameter	Min	Max	Unit
C_{CLOCK}	Clock Capacitance		35	pf
C_{IN}	Input Capacitance		5	pf
C_{OUT}	Output Capacitance		15	pf

NOTES:

$T_A = 25^\circ\text{C}$, $f = 1 \text{ MHz}$.

Unmeasured pins returned to ground.

AC CHARACTERISTICS[†] (Z8400/NMOS Z80 CPU)

Number	Symbol	Parameter	Z0840004		Z0840006		Z0840008	
			Min	Max	Min	Max	Min	Max
1	T _{cC}	Clock Cycle Time	250*		162*		125*	
2	T _{wCh}	Clock Pulse Width (High)	110	2000	65	2000	55	2000
3	T _{wCl}	Clock Pulse Width (Low)	110	2000	65	2000	55	2000
4	T _{fC}	Clock Fall Time		30		20		10
5	T _{rC}	Clock Rise Time		30		20		10
6	T _{dCr(A)}	Clock \uparrow to Address Valid Delay		110		90		80
7	T _{dA(MREQf)}	Address Valid to $\overline{MREQ} \downarrow$ Delay	65*		35*		20*	
8	T _{dCr(MREQf)}	Clock \uparrow to $\overline{MREQ} \downarrow$ Delay		85		70		60
9	T _{dCr(MREQr)}	Clock \uparrow to $\overline{MREQ} \uparrow$ Delay		85		70		60
10	T _{wMREQh}	\overline{MREQ} Pulse Width (High)	110*††		65*††		45*††	
11	T _{wMREQl}	\overline{MREQ} Pulse Width (Low)	220*††		135*††		100*††	
12	T _{dCr(MREQr)}	Clock \downarrow to $\overline{MREQ} \uparrow$ Delay		85		70		60
13	T _{dCr(RDf)}	Clock \downarrow to $\overline{RD} \downarrow$ Delay		95		80		70
14	T _{dCr(RDr)}	Clock \uparrow to $\overline{RD} \uparrow$ Delay		85		70		60
15	T _{sD(Cr)}	Data Setup Time to Clock \uparrow	35		30		30	
16	T _{hD(RDr)}	Data Hold Time to $\overline{RD} \uparrow$		0		0		0
17	T _{sWAIT(Cf)}	\overline{WAIT} Setup Time to Clock \downarrow	70		60		50	
18	T _{hWAIT(Cf)}	\overline{WAIT} Hold Time after Clock \downarrow		0		0		0
19	T _{dCr(M1f)}	Clock \uparrow to $\overline{M1} \downarrow$ Delay	100		80		70	
20	T _{dCr(M1r)}	Clock \uparrow to $\overline{M1} \uparrow$ Delay	100		80		70	
21	T _{dCr(RFSHf)}	Clock \uparrow to $\overline{RFSH} \downarrow$ Delay	130		110		95	
22	T _{dCr(RFSHr)}	Clock \uparrow to $\overline{RFSH} \uparrow$ Delay	120		100		85	
23	T _{dCr(RDr)}	Clock \downarrow to $\overline{RD} \uparrow$ Delay	85		70		60	
24	T _{dCr(RDf)}	Clock \uparrow to $\overline{RD} \downarrow$ Delay	85		70		60	
25	T _{sD(Cf)}	Data Setup to Clock \downarrow during M ₂ , M ₃ , M ₄ , or M ₅ Cycles	50		40		30	
26	T _{dA(IORQf)}	Address Stable prior to $\overline{IORQ} \downarrow$	180*		110*		75*	
27	T _{dCr(IORQf)}	Clock \uparrow to $\overline{IORQ} \downarrow$ Delay		75		65		55
28	T _{dCr(IORQr)}	Clock \downarrow to $\overline{IORQ} \uparrow$ Delay		85		70		60
29	T _{dD(WRf)}	Data Stable prior to $\overline{WR} \downarrow$	80*		25*		5*	
30	T _{dCr(WRf)}	Clock \downarrow to $\overline{WR} \downarrow$ Delay	80		70		60	
31	T _{wWR}	\overline{WR} Pulse Width	220*		135*		100*	
32	T _{dCr(WRr)}	Clock \downarrow to $\overline{WR} \uparrow$ Delay		80		70		60
33	T _{dD(WRf)}	Data Stable prior to $\overline{WR} \downarrow$	-10*		-55*		55*	
34	T _{dCr(WRf)}	Clock \uparrow to $\overline{WR} \downarrow$ Delay		65		60		55
35	T _{dWRr(D)}	Data Stable from $\overline{WR} \uparrow$	60*		30*		15*	
36	T _{dCr(HALT)}	Clock \downarrow to $\overline{HALT} \uparrow$ or \downarrow		300		260		225
37	T _{wNMI}	NMI Pulse Width	80		70		60*	
38	T _{sBUSREQ(Cr)}	BUSREQ Setup Time to Clock \uparrow	50		50		40	

*For clock periods other than the minimums shown, calculate parameters using the table on the following page. Calculated values above assumed TrC = TIC = 20 ns.

†Units in nanoseconds (ns).

†† For loading $\geq 50 \text{ pF}$, Decrease width by 10 ns for each additional 50 pF.

AC CHARACTERISTICS[†] (Z8400/NMOS Z80 CPU; Continued)

Number	Symbol	Parameter	Z0840004		Z0840006		Z0840008	
			Min	Max	Min	Max	Min	Max
39	ThBUSREQ(Cr)	BUSREQ Hold Time after Clock \uparrow	0	0	0	0	0	0
40	TdCr(BUSACKf)	Clock \uparrow to BUSACK \downarrow Delay		100	90	80	80	
41	TdCf(BUSACKr)	Clock \downarrow to BUSACK \uparrow Delay		100	90	80	80	
42	TdCr(Dz)	Clock \uparrow to Data Float Delay		90	80	70	70	
43	TdCr(CTz)	Clock \uparrow to Control Outputs Float Delay (MREQ, IORQ, RD, and WR)		80	70	60	60	
44	TdCr(Az)	Clock \uparrow to Address Float Delay		90	80	70	70	
45	TdCtr(A)	MREQ \uparrow , IORQ \uparrow , RD \uparrow , and WR \uparrow to Address Hold Time	80*	35*		20*		
46	TsRESET(Cr)	RESET to Clock \uparrow Setup Time	60	60	45			
47	ThRESET(Cr)	RESET to Clock \uparrow Hold Time		0	0	0	0	
48	TsINTf(Cr)	INT to Clock \uparrow Setup Time	80	70	55			
49	ThINTf(Cr)	INT to Clock \uparrow Hold Time		0	0	0	0	
50	TdM1f(IORQf)	M1 \downarrow to IORQ \downarrow Delay	565*	365*	270*			
51	TdCf(IORQf)	Clock \downarrow to IORQ \downarrow Delay		85	70	60	60	
52	TdCf(IORQr)	Clock \uparrow IORQ \uparrow Delay		85	70	60	60	
53	TdCf(D)	Clock \downarrow to Data Valid Delay		150	130	115	115	

*For clock periods other than the minimums shown, calculate parameters using the following table. Calculated values above assumed TrC = TIC = 20 ns.

†Units in nanoseconds (ns).

FOOTNOTES TO AC CHARACTERISTICS

Number	Symbol	General Parameter	Z0840004	Z0840006	Z0840008
1	TcC	TwCh + TwCl + TrC + TIC			
7	TdA(MREQf)	TwCh + TfC	-65	-50	-45
10	TwMREQh	TwCh + TfC	-20	-20	-20
11	TwMREQl	TcC	-30	-30	-25
26	TdA(IORQf)	TcC	-70	-55	-50
29	TdD(WRf)	TcC	-170	-140	-120
31	TwWR	TcC	-30	-30	-25
33	TdD(WRf)	TwCl + TrC	-140	-140	-120
35	TdWRr(D)	TwCl + TrC	-70	-55	-50
45	TdCtr(A)	TwCl + TrC	-50	-50	-45
50	TdM1f(IORQf)	2TcC + TwCh + TfC	-65	-50	-45

AC Test Conditions:

$V_{IH} = 2.0\text{ V}$ $V_{OH} = 1.5\text{ V}$
 $V_{IL} = 0.8\text{ V}$ $V_{OL} = 1.5\text{ V}$
 $V_{IHC} = V_{CC} - 0.6\text{ V}$ FLOAT = $\pm 0.5\text{ V}$
 $V_{ILC} = 0.45\text{ V}$

Customer Support

For answers to technical questions about the product, documentation, or any other issues with Zilog's offerings, please visit Zilog's Knowledge Base at <http://www.zilog.com/kb>.

For any comments, detail technical questions, or reporting problems, please visit Zilog's Technical Support at <http://support.zilog.com>.