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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M3
Core Size	32-Bit Single-Core
Speed	36MHz
Connectivity	I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	DMA, PDR, POR, PVD, PWM, Temp Sensor, WDT
Number of I/O	51
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	2V ~ 3.6V
Data Converters	A/D 16x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-LQFP
Supplier Device Package	64-LQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f101r6t6atr

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2.1 Device overview

[Figure 1](#) shows the general block diagram of the device family.

Table 2. Low-density STM32F101xx device features and peripheral counts

Peripheral		STM32F101Tx		STM32F101Cx		STM32F101Rx	
Flash - Kbytes		16	32	16	32	16	32
SRAM - Kbytes		4	6	4	6	4	6
Timers	General-purpose	2	2	2	2	2	2
Communication	SPI	1	1	1	1	1	1
	I ² C	1	1	1	1	1	1
	USART	2	2	2	2	2	2
12-bit synchronized ADC number of channels		1 10 channels		1 10 channels		1 16 channels	
GPIOs		26		37		51	
CPU frequency		36 MHz					
Operating voltage		2.0 to 3.6 V					
Operating temperatures		Ambient temperature: –40 to +85 °C (see Table 8) Junction temperature: –40 to +105 °C (see Table 8)					
Packages		VFQFPN36		LQFP48		LQFP64	

2.2 Full compatibility throughout the family

The STM32F101xx is a complete family whose members are fully pin-to-pin, software and feature compatible. In the reference manual, the STM32F101x4 and STM32F101x6 are referred to as low-density devices, the STM32F101x8 and STM32F101xB are referred to as medium-density devices, and the STM32F101xC, STM32F101xD and STM32F101xE are referred to as high-density devices.

Low- and high-density devices are an extension of the STM32F101x8/B devices, they are specified in the STM32F101x4/6 and STM32F101xC/D/E datasheets, respectively. Low-density devices feature lower Flash memory and RAM capacities and a timer less. High-density devices have higher Flash memory and RAM capacities, and additional peripherals like FSMC and DAC, while remaining fully compatible with the other members of the STM32F101xx family.

The STM32F101x4, STM32F101x6, STM32F101xC, STM32F101xD and STM32F101xE are a drop-in replacement for the STM32F101x8/B medium-density devices, allowing the user to try different memory densities and providing a greater degree of freedom during the development cycle.

Moreover, the STM32F101xx performance line family is fully compatible with all existing STM32F101xx access line and STM32F102xx USB access line devices.

Table 3. STM32F101xx family

Pinout	Memory size						
	Low-density devices		Medium-density devices		High-density devices		
	16 KB Flash	32 KB Flash ⁽¹⁾	64 KB Flash	128 KB Flash	256 KB Flash	384 KB Flash	512 KB Flash
	4 KB RAM	6 KB RAM	10 KB RAM	16 KB RAM	32 KB RAM	48 KB RAM	48 KB RAM
144	-	-	-	-	5 × USARTs 4 × 16-bit timers, 2 × basic timers 3 × SPIs, 2 × I ² Cs, 1 × ADC, 2 × DACs, FSMC (100 and 144 pins)		
100	-	-	3 × USARTs 3 × 16-bit timers 2 × SPIs, 2 × I2Cs, 1 × ADC				
64	2 × USARTs 2 × 16-bit timers 1 × SPI, 1 × I ² C						
48							
36							
					-	-	-
					-	-	-

1. For orderable part numbers that do not show the A internal code after the temperature range code (6), the reference datasheet for electrical characteristics is that of the STM32F101x8/B medium-density devices.

2.3.6 External interrupt/event controller (EXTI)

The external interrupt/event controller consists of 19 edge detector lines used to generate interrupt/event requests. Each line can be independently configured to select the trigger event (rising edge, falling edge, both) and can be masked independently. A pending register maintains the status of the interrupt requests. The EXTI can detect an external line with a pulse width shorter than the Internal APB2 clock period. Up to 80 GPIOs can be connected to the 16 external interrupt lines.

2.3.7 Clocks and startup

System clock selection is performed on startup, however the internal RC 8 MHz oscillator is selected as default CPU clock on reset. An external 4-16 MHz clock can be selected, in which case it is monitored for failure. If failure is detected, the system automatically switches back to the internal RC oscillator. A software interrupt is generated if enabled. Similarly, full interrupt management of the PLL clock entry is available when necessary (for example on failure of an indirectly used external crystal, resonator or oscillator).

Several prescalers allow the configuration of the AHB frequency, the high-speed APB (APB2) and the low-speed APB (APB1) domains. The maximum frequency of the AHB and the APB domains is 36 MHz. See [Figure 2](#) for details on the clock tree.

2.3.8 Boot modes

At startup, boot pins are used to select one of three boot options:

- Boot from User Flash
- Boot from System Memory
- Boot from embedded SRAM

The boot loader is located in System Memory. It is used to reprogram the Flash memory by using USART1. For further details please refer to AN2606.

2.3.9 Power supply schemes

- $V_{DD} = 2.0$ to 3.6 V: External power supply for I/Os and the internal regulator. Provided externally through V_{DD} pins.
- V_{SSA} , $V_{DDA} = 2.0$ to 3.6 V: External analog power supplies for ADC, Reset blocks, RCs and PLL (minimum voltage to be applied to V_{DDA} is 2.4 V when the ADC is used). V_{DDA} and V_{SSA} must be connected to V_{DD} and V_{SS} , respectively.
- $V_{BAT} = 1.8$ to 3.6 V: Power supply for RTC, external clock 32 kHz oscillator and backup registers (through power switch) when V_{DD} is not present.

For more details on how to connect power pins, refer to [Figure 10: Power supply scheme](#).

2.3.10 Power supply supervisor

The device has an integrated power on reset (POR)/power down reset (PDR) circuitry. It is always active, and ensures proper operation starting from/down to 2 V. The device remains in reset mode when V_{DD} is below a specified threshold, $V_{POR/PDR}$, without the need for an external reset circuit.

The device features an embedded programmable voltage detector (PVD) that monitors the V_{DD}/V_{DDA} power supply and compares it to the V_{PVD} threshold. An interrupt can be generated when V_{DD}/V_{DDA} drops below the V_{PVD} threshold and/or when V_{DD}/V_{DDA} is

Table 4. Low-density STM32F101xx pin definitions (continued)

Pins			Pin name	Type ⁽¹⁾	I / O level ⁽²⁾	Main function ⁽³⁾ (after reset)	Alternate functions ⁽³⁾⁽⁴⁾	
LQFP48	LQFP64	VFQFPN36					Default	Remap
37	49	28	PA14	I/O	FT	JTCK/SWCLK	-	PA14
38	50	29	PA15	I/O	FT	JTDI	-	TIM2_CH1_ETR/ PA15 / SPI_NSS
-	51	-	PC10	I/O	FT	PC10	-	-
-	52	-	PC11	I/O	FT	PC11	-	-
-	53	-	PC12	I/O	FT	PC12	-	-
5	5	2	PD0	I/O	FT	OSC_IN ⁽⁸⁾	-	-
6	6	3	PD1	I/O	FT	OSC_OUT ⁽⁸⁾	-	-
-	54	-	PD2	I/O	FT	PD2	TIM3_ETR	-
39	55	30	PB3	I/O	FT	JTDO	-	TIM2_CH2 / PB3 TRACESWO SPI_SCK
40	56	31	PB4	I/O	FT	NJTRST	-	TIM3_CH1 / PB4 SPI_MISO
41	57	32	PB5	I/O	-	PB5	I2C_SMBA	TIM3_CH2 / SPI_MOSI
42	58	33	PB6	I/O	FT	PB6	I2C_SCL ⁽⁷⁾	USART1_TX
43	59	34	PB7	I/O	FT	PB7	I2C_SDA ⁽⁷⁾	USART1_RX
44	60	35	BOOT0	I	-	BOOT0	-	-
45	61	-	PB8	I/O	FT	PB8	-	I2C_SCL
46	62	-	PB9	I/O	FT	PB9	-	I2C_SDA
47	63	36	V _{SS_3}	S	-	V _{SS_3}	-	-
48	64	1	V _{DD_3}	S	-	V _{DD_3}	-	-

1. I = input, O = output, S = supply.

2. FT= 5 V tolerant.

3. Function availability depends on the chosen device. For devices having reduced peripheral counts, it is always the lower number of peripherals that is included. For example, if a device has only one SPI, two USARTs and two timers, they will be called SPI, USART1 & USART2 and TIM2 & TIM 3, respectively. Refer to [Table 2 on page 11](#).

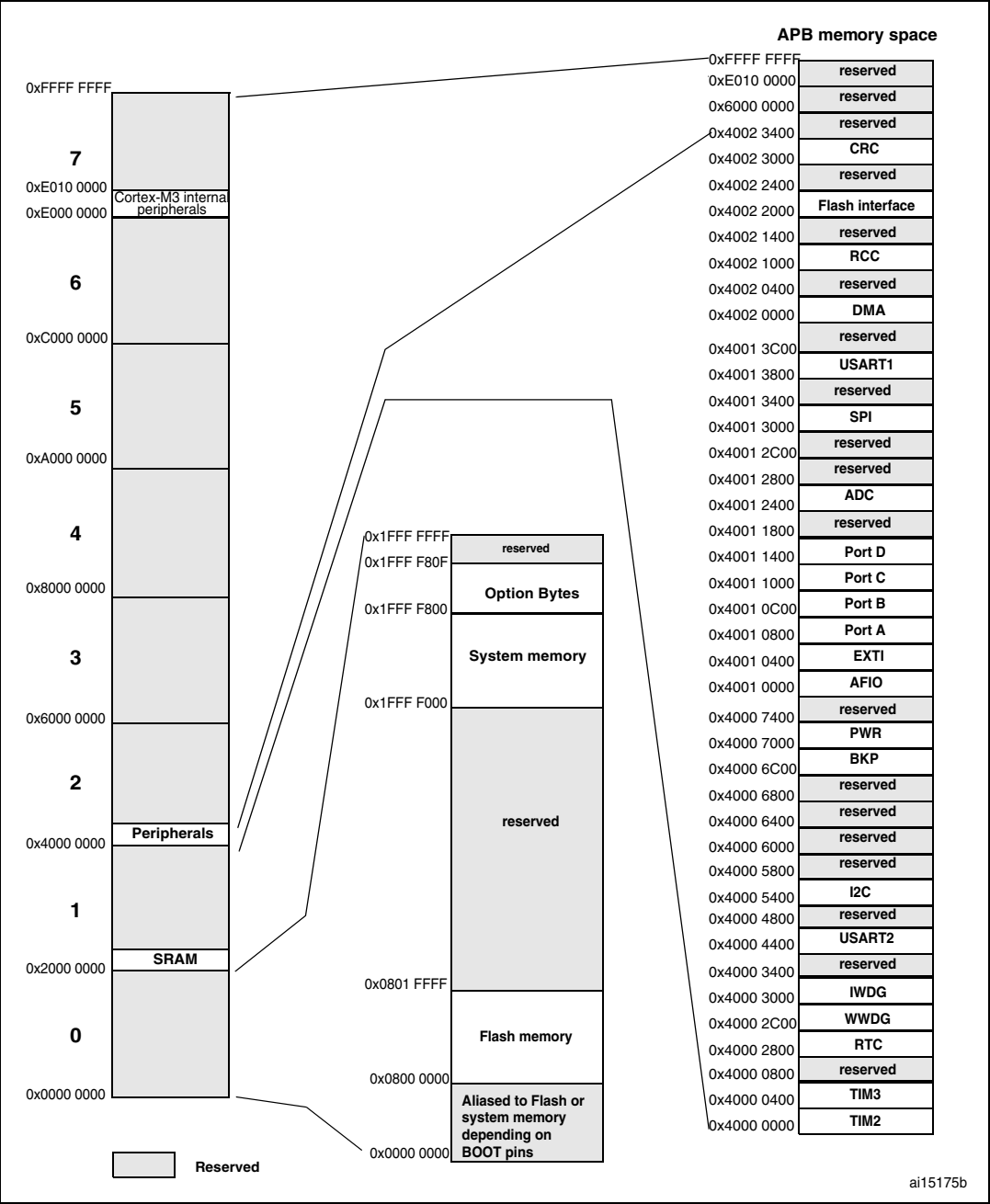
4. If several peripherals share the same I/O pin, to avoid conflict between these alternate functions only one peripheral should be enabled at a time through the peripheral clock enable bit (in the corresponding RCC peripheral clock enable register).

5. PC13, PC14 and PC15 are supplied through the power switch. Since the switch only sinks a limited amount of current (3 mA), the use of GPIOs PC13 to PC15 in output mode is limited: the speed should not exceed 2 MHz with a maximum load of 30 pF and these IOs must not be used as a current source (e.g. to drive an LED).

4 Memory mapping

The memory map is shown in [Figure 7](#).

Figure 7. Memory map



5 Electrical characteristics

5.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to V_{SS} .

5.1.1 Minimum and maximum values

Unless otherwise specified the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at $T_A = 25\text{ }^{\circ}\text{C}$ and $T_A = T_{A\text{max}}$ (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation ($\text{mean} \pm 3\sigma$).

5.1.2 Typical values

Unless otherwise specified, typical data are based on $T_A = 25\text{ }^{\circ}\text{C}$, $V_{DD} = 3.3\text{ V}$ (for the $2\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ voltage range). They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range, where 95% of the devices have an error less than or equal to the value indicated ($\text{mean} \pm 2\sigma$).

5.1.3 Typical curves

Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

5.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in [Figure 8](#).

5.1.5 Pin input voltage

The input voltage measurement on a pin of the device is described in [Figure 9](#).

Table 10. Embedded reset and power control block characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{PVD}	Programmable voltage detector level selection	PLS[2:0]=000 (rising edge)	2.1	2.18	2.26	V
		PLS[2:0]=000 (falling edge)	2	2.08	2.16	
		PLS[2:0]=001 (rising edge)	2.19	2.28	2.37	
		PLS[2:0]=001 (falling edge)	2.09	2.18	2.27	
		PLS[2:0]=010 (rising edge)	2.28	2.38	2.48	
		PLS[2:0]=010 (falling edge)	2.18	2.28	2.38	
		PLS[2:0]=011 (rising edge)	2.38	2.48	2.58	
		PLS[2:0]=011 (falling edge)	2.28	2.38	2.48	
		PLS[2:0]=100 (rising edge)	2.47	2.58	2.69	
		PLS[2:0]=100 (falling edge)	2.37	2.48	2.59	
		PLS[2:0]=101 (rising edge)	2.57	2.68	2.79	
		PLS[2:0]=101 (falling edge)	2.47	2.58	2.69	
		PLS[2:0]=110 (rising edge)	2.66	2.78	2.9	
		PLS[2:0]=110 (falling edge)	2.56	2.68	2.8	
		PLS[2:0]=111 (rising edge)	2.76	2.88	3	
		PLS[2:0]=111 (falling edge)	2.66	2.78	2.9	
$V_{PVDhyst}^{(2)}$	PVD hysteresis	-	-	100	-	mV
$V_{POR/PDR}$	Power on/power down reset threshold	Falling edge	1.8 ⁽¹⁾	1.88	1.96	V
		Rising edge	1.84	1.92	2.0	
$V_{PDRhyst}^{(2)}$	PDR hysteresis	-	-	40	-	mV
$t_{RSTTEMPO}^{(2)}$	Reset temporization	-	1.5	2.5	4.5	ms

1. The product behavior is guaranteed by design down to the minimum $V_{POR/PDR}$ value.

2. Guaranteed by design, not tested in production.

Figure 16. Typical current consumption in Stop mode with regulator in Low-power mode versus temperature at $V_{DD} = 3.3\text{ V}$ and 3.6 V

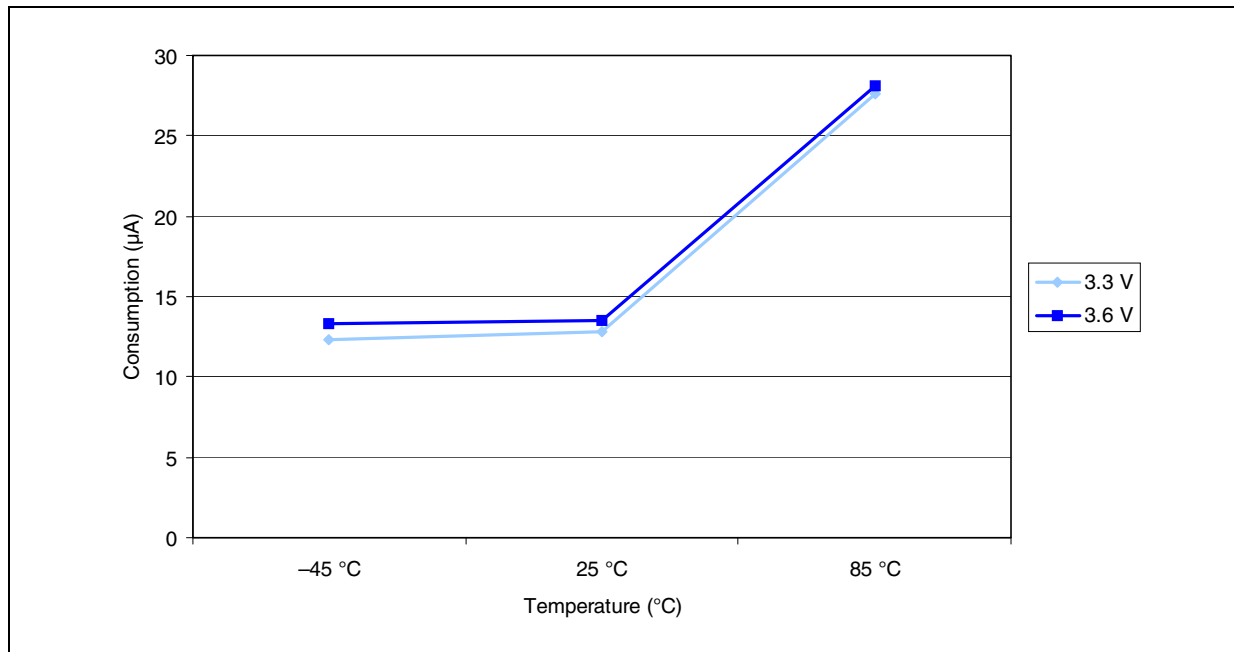
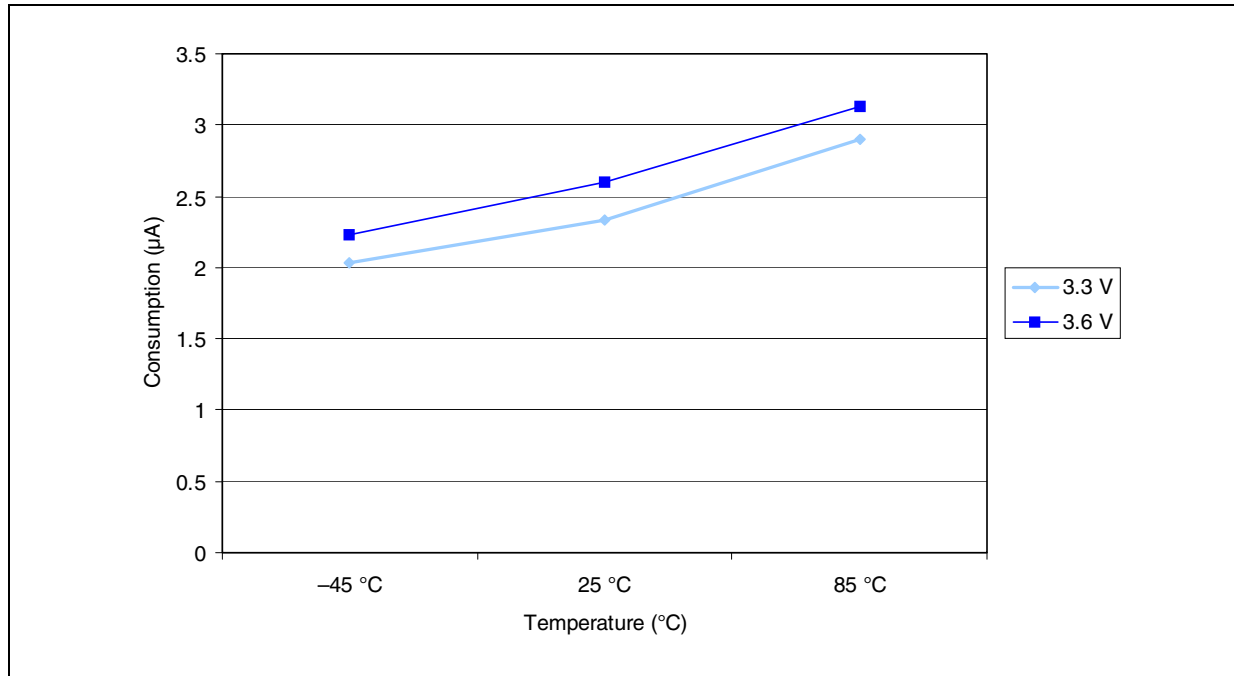


Figure 17. Typical current consumption in Standby mode versus temperature at $V_{DD} = 3.3\text{ V}$ and 3.6 V



time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 22. LSE oscillator characteristics ($f_{LSE} = 32.768 \text{ kHz}$)^{(1) (2)}

Symbol	Parameter	Conditions	-	Min	Typ	Max	Unit
R_F	Feedback resistor	-	-	-	5	-	MΩ
C	Recommended load capacitance versus equivalent serial resistance of the crystal (R_S)	$R_S = 30 \text{ K}\Omega$	-	-	-	15	pF
I_2	LSE driving current	$V_{DD} = 3.3 \text{ V}$ $V_{IN} = V_{SS}$	-	-	-	1.4	μA
g_m	Oscillator transconductance	-	-	5	-	-	μA/V
$t_{SU(LSE)}^{(3)}$	Startup time	V_{DD} is stabilized	$T_A = 50 \text{ }^\circ\text{C}$	-	1.5	-	s
			$T_A = 25 \text{ }^\circ\text{C}$	-	2.5	-	
			$T_A = 10 \text{ }^\circ\text{C}$	-	4	-	
			$T_A = 0 \text{ }^\circ\text{C}$	-	6	-	
			$T_A = -10 \text{ }^\circ\text{C}$	-	10	-	
			$T_A = -20 \text{ }^\circ\text{C}$	-	17	-	
			$T_A = -30 \text{ }^\circ\text{C}$	-	32	-	
			$T_A = -40 \text{ }^\circ\text{C}$	-	60	-	

1. Based on characterization, not tested in production.
2. Refer to the note and caution paragraphs below the table, and to the application note AN2867 "Oscillator design guide for ST microcontrollers".
3. $t_{SU(LSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal and it can vary significantly with the crystal manufacturer

Note: For CL1 and CL2 it is recommended to use high-quality ceramic capacitors in the 5 pF to 15 pF range selected to match the requirements of the crystal or resonator. CL1 and CL2, are usually the same size. The crystal manufacturer typically specifies a load capacitance which is the series combination of CL1 and CL2.
Load capacitance CL has the following formula: $CL = CL1 \times CL2 / (CL1 + CL2) + C_{stray}$ where C_{stray} is the pin capacitance and board or trace PCB-related capacitance. Typically, it is between 2 pF and 7 pF.

Caution: To avoid exceeding the maximum value of CL1 and CL2 (15 pF) it is strongly recommended to use a resonator with a load capacitance $CL \leq 7 \text{ pF}$. Never use a resonator with a load capacitance of 12.5 pF.
Example: if resonator with a load capacitance of $CL = 6 \text{ pF}$, and $C_{stray} = 2 \text{ pF}$ is chosen, then $CL1 = CL2 = 8 \text{ pF}$.

Table 26. PLL characteristics (continued)

Symbol	Parameter	Value			Unit
		Min ⁽¹⁾	Typ	Max ⁽¹⁾	
t _{LOCK}	PLL lock time	-	-	200	μs
Jitter	Cycle-to-cycle jitter	-	-	300	ps

1. Based on device characterization, not tested in production.
2. Take care of using the appropriate multiplier factors so as to have PLL input clock values compatible with the range defined by f_{PLL_OUT}.

5.3.9 Memory characteristics

Flash memory

The characteristics are given at T_A = -40 to 85 °C unless otherwise specified.

Table 27. Flash memory characteristics

Symbol	Parameter	Conditions	Min ⁽¹⁾	Typ	Max ⁽¹⁾	Unit
t _{prog}	16-bit programming time	T _A = -40 to +85 °C	40	52.5	70	μs
t _{ERASE}	Page (1 KB) erase time	T _A = -40 to +85 °C	20	-	40	ms
t _{ME}	Mass erase time	T _A = -40 to +85 °C	20	-	40	ms
I _{DD}	Supply current	Read mode f _{HCLK} = 36 MHz with 1 wait state, V _{DD} = 3.3 V	-	-	20	mA
		Write / Erase modes f _{HCLK} = 36 MHz, V _{DD} = 3.3 V	-	-	5	mA
		Power-down mode / Halt, V _{DD} = 3.0 to 3.6 V	-	-	50	μA
V _{prog}	Programming voltage	-	2	-	3.6	V

1. Guaranteed by design, not tested in production.

5.3.10 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

Functional EMS (Electromagnetic susceptibility)

While a simple application is executed on the device (toggling 2 LEDs through I/O ports), the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs:

- **Electrostatic discharge (ESD)** (positive and negative) is applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- **FTB:** A Burst of Fast Transient voltage (positive and negative) is applied to V_{DD} and V_{SS} through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

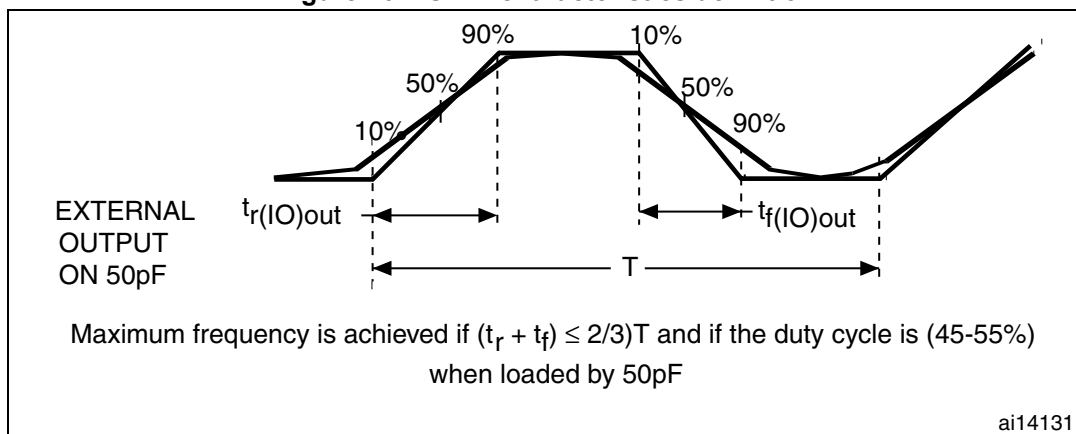
The failure is indicated by an out of range parameter: ADC error above a certain limit (>5 LSB TUE), out of spec current injection on adjacent pins or other functional failure (for example reset, oscillator frequency deviation).

The test results are given in [Table 32](#)

Table 32. I/O current injection susceptibility

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
I _{INJ}	Injected current on OSC_IN32, OSC_OUT32, PA4, PA5, PC13	-0	+0	mA
	Injected current on all FT pins	-5	+0	
	Injected current on any other pin	-5	+5	

Figure 26. I/O AC characteristics definition



5.3.14 NRST pin characteristics

The NRST pin input driver uses CMOS technology. It is connected to a permanent pull-up resistor, R_{PU} (see [Table 33](#)).

Unless otherwise specified, the parameters given in [Table 36](#) are derived from tests performed under the ambient temperature and V_{DD} supply voltage conditions summarized in [Table 8](#).

Table 36. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}^{(1)}$	NRST Input low level voltage	-	-0.5	-	0.8	V
$V_{IH(NRST)}^{(1)}$	NRST Input high level voltage	-	2	-	$V_{DD}+0.5$	
$V_{hys(NRST)}$	NRST Schmitt trigger voltage hysteresis	-	-	200	-	mV
R_{PU}	Weak pull-up equivalent resistor ⁽²⁾	$V_{IN} = V_{SS}$	30	40	50	k Ω
$V_{F(NRST)}^{(1)}$	NRST Input filtered pulse	-	-	-	100	ns
$V_{NF(NRST)}^{(1)}$	NRST Input not filtered pulse	-	300	-	-	ns

1. Guaranteed by design, not tested in production.

2. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance must be minimum (~10% order).

5.3.15 TIM timer characteristics

The parameters given in [Table 37](#) are guaranteed by design.

Refer to [Section 5.3.12: I/O current injection characteristics](#) for details on the input/output alternate function characteristics (output compare, input capture, external clock, PWM output).

Table 37. TIMx⁽¹⁾ characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{res(TIM)}$	Timer resolution time	-	1	-	$t_{TIMxCLK}$
		$f_{TIMxCLK} = 36\text{ MHz}$	27.8	-	ns
f_{EXT}	Timer external clock frequency on CH1 to CH4	-	0	$f_{TIMxCLK}/2$	MHz
		$f_{TIMxCLK} = 36\text{ MHz}$	0	18	MHz
Res_{TIM}	Timer resolution	-	-	16	bit
$t_{COUNTER}$	16-bit counter clock period when internal clock is selected	-	1	65536	$t_{TIMxCLK}$
		$f_{TIMxCLK} = 36\text{ MHz}$	0.0278	1820	μs
t_{MAX_COUNT}	Maximum possible count	-	-	65536×65536	$t_{TIMxCLK}$
		$f_{TIMxCLK} = 36\text{ MHz}$	-	119.2	s

1. TIMx is used as a general term to refer to the TIM2, TIM3 and TIM4 timers.

5.3.16 Communications interfaces

I²C interface characteristics

The STM32F101xx Low-density access line I²C interface meets the requirements of the standard I²C communication protocol with the following restrictions: the I/O pins SDA and SCL are mapped to are not “true” open-drain. When configured as open-drain, the PMOS connected between the I/O pin and V_{DD} is disabled, but is still present.

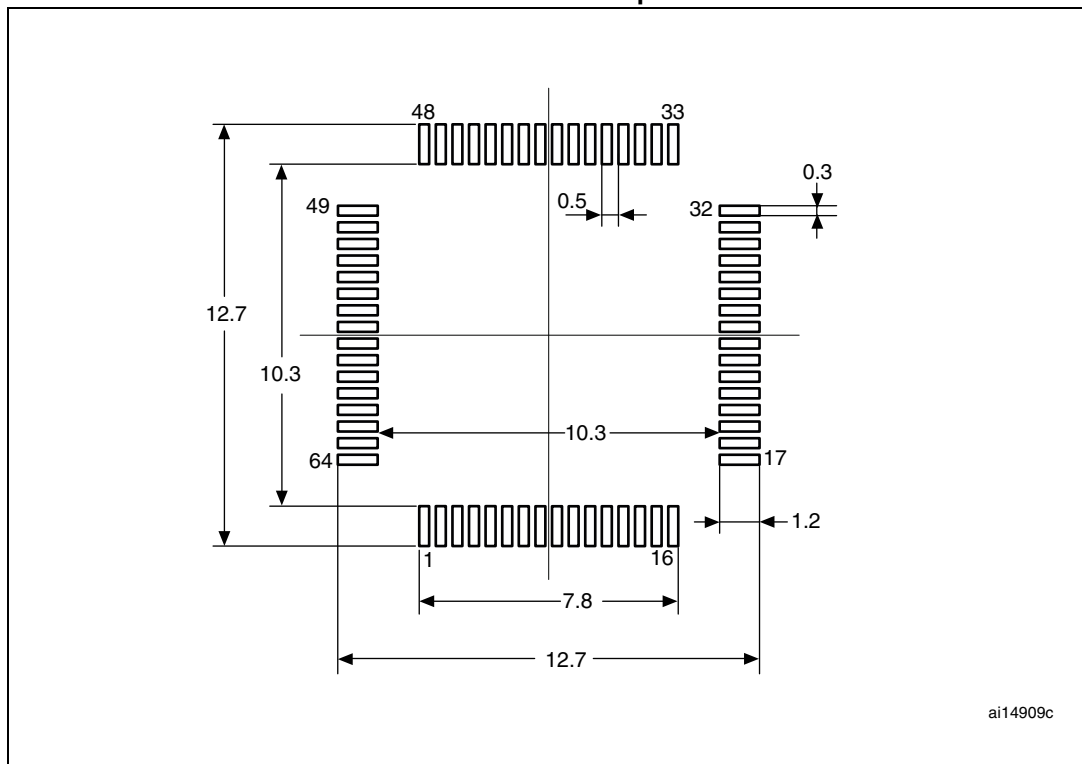
The I²C characteristics are described in [Table 38](#). Refer also to [Section 5.3.12: I/O current injection characteristics](#) for more details on the input/output alternate function characteristics (SDA and SCL).

Table 47. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package mechanical data (continued)

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
E3	-	7.500	-	-	0.2953	-
e	-	0.500	-	-	0.0197	-
K	0°	3.5°	7°	0°	3.5°	7°
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

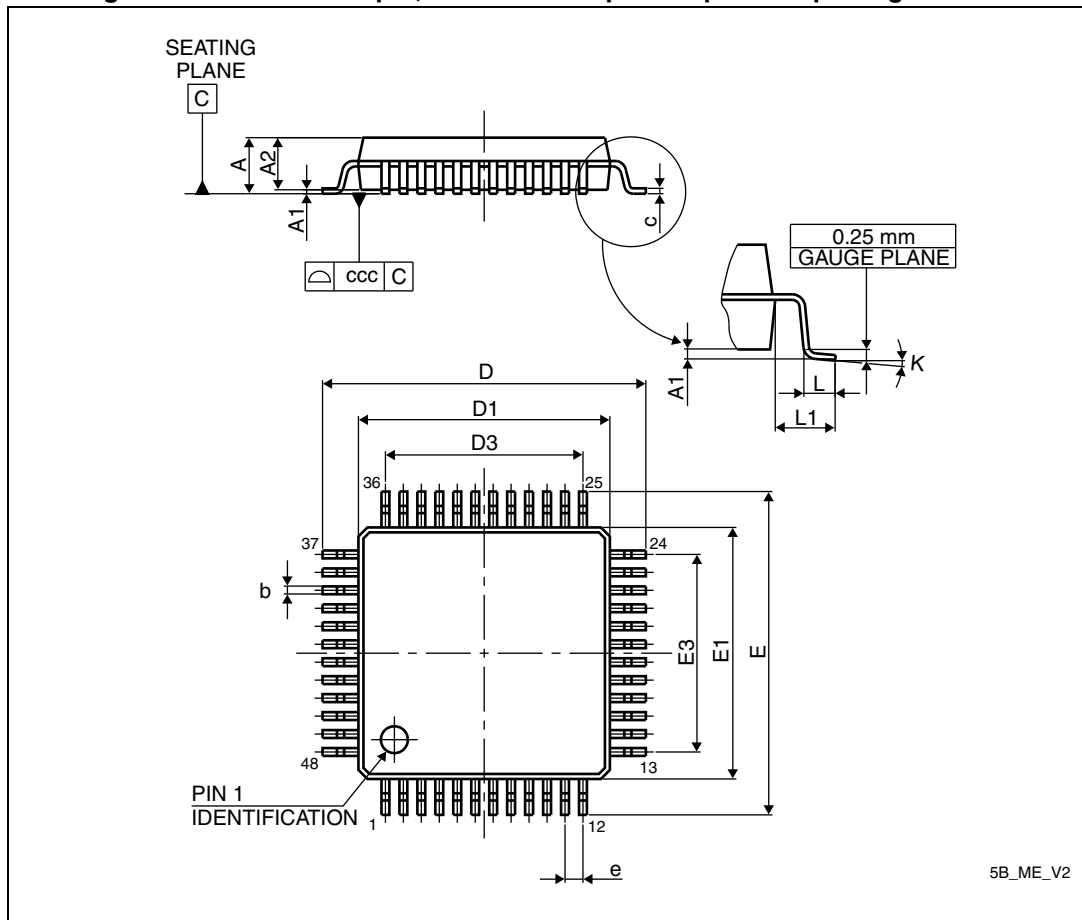
Figure 39. LQFP64 - 64-pin, 10 x 10 mm low-profile quad flat package recommended footprint



1. Dimensions are expressed in millimeters.

6.4 LQFP48 package information

Figure 41. LQFP48 - 48-pin, 7 x 7 mm low-profile quad flat package outline



1. Drawing is not to scale.

Table 51. Document revision history (continued)

Date	Revision	Changes
19-Apr-2011	5	<p>Updated footnotes below Table 5: Voltage characteristics on page 30 and Table 6: Current characteristics on page 31</p> <p>Updated $t_{w\ min}$ in Table 19: High-speed external user clock characteristics on page 43</p> <p>Updated startup time in Table 22: LSE oscillator characteristics (fLSE = 32.768 kHz) on page 46</p> <p>Added Section 5.3.12: I/O current injection characteristics</p> <p>Updated Section 5.3.13: I/O port characteristics</p>
25-Sep-2015	6	<p>Updated:</p> <ul style="list-style-type: none"> – All GPIOs are high current...’ in Section 2.3.22: GPIOs (general-purpose inputs/outputs) – first sentence in Output driving current – Table 2: Low-density STM32F101xx device features and peripheral counts, Table 4: Low-density STM32F101xx pin definitions, – Table 6: Current characteristics – Table 8: General operating conditions – Table 18: Peripheral current consumption – notes in Table 38: I2C characteristics – note 2. in Table 44: ADC accuracy – title of Table 39: SCL frequency (fPCLK1= MHz, VDD_I2C = 3.3 V) – reference for ‘V_{ESD(CDM)}’ in Table 30: ESD absolute maximum ratings – Table 50: Ordering information scheme, – Table 49: Package thermal characteristics, – Figure 28: I2C bus AC waveforms and measurement circuit(1) <p>Added</p> <ul style="list-style-type: none"> – note 5. in Table 23: HSI oscillator characteristics – Figure 37: VFQFPN36 marking example (package top view) – Figure 40: LQFP64 marking example (package top view) – Figure 43: LQFP48 marking example (package top view) <p>Corrected</p> <ul style="list-style-type: none"> – Corrected ‘tf(IO)out’ in Figure 26: I/O AC characteristics definition – Sigma letter in Section 5.1.1: Minimum and maximum values <p>Removed</p> <ul style="list-style-type: none"> – UFD FPN48 package – First sentence in Section 5.3.16: Communications interfaces

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