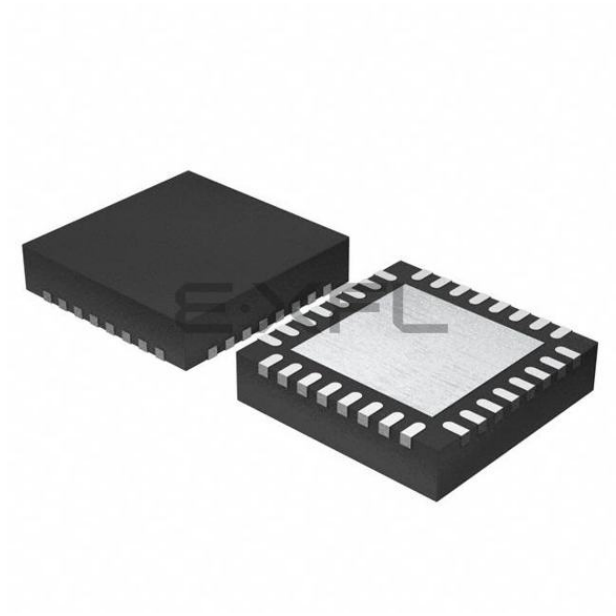

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Embedded - Microcontrollers - Application Specific: Tailored Solutions for Precision and Performance

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What Are Embedded - Microcontrollers - Application Specific?

Application-specific microcontrollers are engineered to

Details	
Product Status	Active
Applications	USB Microcontroller
Core Processor	M8C
Program Memory Type	FLASH (8kB)
Controller Series	CY7C643xx
RAM Size	1K x 8
Interface	I²C, SPI, USB
Number of I/O	25
Voltage - Supply	3V ~ 5.5V
Operating Temperature	0°C ~ 70°C
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy7c64343-32lqxct

SPI configuration register (SPI_CFG) sets master/slave functionality, clock speed, and interrupt select. SPI control register (SPI_CR) provides four control bits and four status bits for device interfacing and synchronization.

The SPIM hardware has no support for driving the Slave Select (SS_) signal. The behavior and use of this signal is dependent on the application and enCoRe V device and, if required, must be implemented in firmware.

There is an additional data input in the SPIS, Slave Select (SS_), which is an active low signal. SS_ must be asserted to enable the SPIS to receive and transmit. SS_ has two high level functions:

- To allow for the selection of a given slave in a multi-slave environment.
- To provide additional clocking for TX data queuing in SPI modes 0 and 1.

I²C Slave

The I²C slave enhanced communications block is a serial-to-parallel processor, designed to interface the enCoRe V device to a two-wire I²C serial communications bus. To eliminate the need for excessive CPU intervention and overhead, the block provides I²C-specific support for status detection and generation of framing bits. By default, the I²C slave enhanced module is firmware compatible with the previous generation of I²C slave functionality. However, this module provides new features that are configurable to implement significant flexibility for both internal and external interfacing. The basic I²C features include:

- Slave, transmitter, and receiver operation.
- Byte processing for low CPU overhead.
- Interrupt or polling CPU interface.
- Support for clock rates of up to 400 kHz.
- 7- or 10-bit addressing (through firmware support).
- SMBus operation (through firmware support).

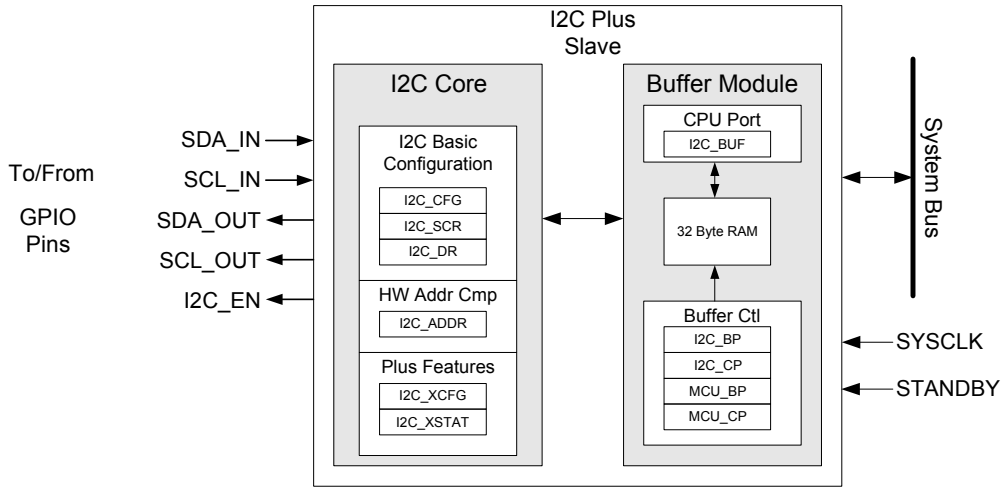
Enhanced features of the I²C Slave Enhanced Module include:

- Support for 7-bit hardware address compare.
- Flexible data buffering schemes.
- A “no bus stalling” operating mode.
- A low power bus monitoring mode.

The I²C block controls the data (SDA) and the clock (SCL) to the external I²C interface through direct connections to two dedicated GPIO pins. When I²C is enabled, these GPIO pins are not available for general purpose use. The enCoRe V CPU firmware interacts with the block through I/O register reads and writes, and firmware synchronization is implemented through polling and/or interrupts.

In the default operating mode, which is firmware compatible with previous versions of I²C slave modules, the I²C bus is stalled upon every received address or byte, and the CPU is required to read the data or supply data as required before the I²C bus continues. However, this I²C Slave Enhanced module provides new data buffering capability as an enhanced feature. In the EZI²C buffering mode, the I²C slave interface appears as a 32-byte RAM buffer to the external I²C master. Using a simple predefined protocol, the master controls the read and write pointers into the RAM. When this method is enabled, the slave never stalls the bus. In this protocol, the data available in the RAM (this is managed by the CPU) is valid.

Figure 5. I²C Block Diagram



Additional System Resources

System resources, some of which have been previously listed, provide additional capability useful to complete systems. Additional resources include low voltage detection and power on reset. The following statements describe the merits of each system resource.

- Low voltage detection (LVD) interrupts can signal the application of falling voltage levels, while the advanced POR (power on reset) circuit eliminates the need for a system supervisor.
- The 5 V maximum input, 1.8, 2.5, or 3 V selectable output, LDO regulator provides regulation for I/Os. A register controlled bypass mode enables the user to disable the LDO.
- Standard Cypress PSoC IDE tools are available for debugging the enCoRe V family of parts.

Getting Started

The quickest path to understanding the enCoRe V silicon is by reading this data sheet and using the PSoC Designer Integrated Development Environment (IDE). This datasheet is an overview of the PSoC integrated circuit and presents specific pin, register, and electrical specifications. For in-depth information, along with detailed programming information, see the *enCoRe™ V CY7C643xx, enCoRe™ V LV CY7C604xx Technical Reference Manual (TRM)* for this PSoC device.

For up-to-date ordering, packaging, and electrical specification information, see the latest PSoC device data sheets on the web at http://www.cypress.com.

Application Notes

Application notes are an excellent introduction to the wide variety of possible PSoC designs and are available at http://www.cypress.com.

Development Kits

PSoC development kits are available online from Cypress at http://www.cypress.com and through a growing number of regional and global distributors, including Arrow, Avnet, Digi-Key, Farnell, Future Electronics, and Newark.

Training

Free PSoC technical training (on demand, webinars, and workshops) is available online at http://www.cypress.com. The training covers a wide variety of topics and skill levels to assist you in your designs.

CYPros Consultants

Certified PSoC Consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC Consultant, go to http://www.cypress.com and look for CYPros Consultants.

Solutions Library

Visit our growing library of solution-focused designs at http://www.cypress.com. Here you can find various application designs that include firmware and hardware design files that enable you to complete your designs quickly.

Technical Support

For assistance with technical issues, search KnowledgeBase articles and forums at http://www.cypress.com. If you cannot find an answer to your question, call technical support at 1-800-541-4736.

Development Tools

PSoC Designer™ is the revolutionary Integrated Design Environment (IDE) that you can use to customize PSoC to meet your specific application requirements. PSoC Designer software accelerates system design and time to market. Develop your applications using a library of precharacterized analog and digital peripherals (called user modules) in a drag-and-drop design environment. Then, customize your design by leveraging the dynamically generated application programming interface (API) libraries of code. Finally, debug and test your designs with the integrated debug environment, including in-circuit emulation and standard software debug features. PSoC Designer includes:

- Application editor graphical user interface (GUI) for device and user module configuration and dynamic reconfiguration
- Extensive user module catalog
- Integrated source-code editor (C and assembly)
- Free C compiler with no size restrictions or time limits
- Built-in debugger
- In-circuit emulation
- Built-in support for communication interfaces:
  - Hardware and software I^2C slaves and masters
  - Full-speed USB 2.0
  - Up to four full-duplex universal asynchronous receiver/transmitters (UARTs), SPI master and slave, and wireless

PSoC Designer supports the entire library of PSoC 1 devices and runs on Windows XP, Windows Vista, and Windows 7.

PSoC Designer Software Subsystems

Design Entry

In the chip-level view, choose a base device to work with. Then select different onboard analog and digital components that use the PSoC blocks, which are called user modules. Examples of user modules are analog-to-digital converters (ADCs), digital-to-analog converters (DACs), amplifiers, and filters. Configure the user modules for your chosen application and connect them to each other and to the proper pins. Then generate your project. This prepopulates your project with APIs and libraries that you can use to program your application.

The tool also supports easy development of multiple configurations and dynamic reconfiguration. Dynamic reconfiguration makes it possible to change configurations at run time. In essence, this allows you to use more than 100 percent of PSoC's resources for a given application.

Code Generation Tools

The code generation tools work seamlessly within the PSoC Designer interface and have been tested with a full range of debugging tools. You can develop your design in C, assembly, or a combination of the two.

Assemblers. The assemblers allow you to merge assembly code seamlessly with C code. Link libraries automatically use absolute addressing or are compiled in relative mode, and linked with other software modules to get absolute addressing.

C Language Compilers. C language compilers are available that support the PSoC family of devices. The products allow you to create complete C programs for the PSoC family devices. The optimizing C compilers provide all of the features of C, tailored to the PSoC architecture. They come complete with embedded libraries providing port and bus operations, standard keypad and display support, and extended math functionality.

Debugger

PSoC Designer has a debug environment that provides hardware in-circuit emulation, allowing you to test the program in a physical system while providing an internal view of the PSoC device. Debugger commands allow you to read and program and read and write data memory, and read and write I/O registers. You can read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows you to create a trace buffer of registers and memory locations of interest.

Online Help System

The online help system displays online, context-sensitive help. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an Online Support Forum to aid the designer.

In-Circuit Emulator

A low-cost, high-functionality In-Circuit Emulator (ICE) is available for development support. This hardware can program single devices.

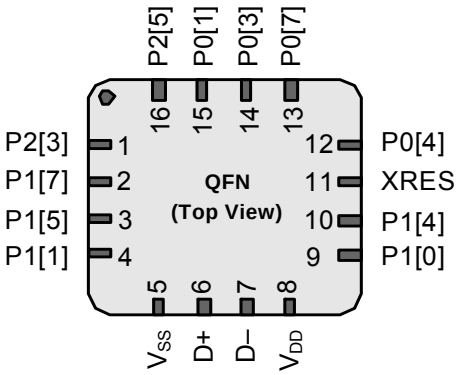
The emulator consists of a base unit that connects to the PC using a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full-speed (24-MHz) operation.

Pin Information

The enCoRe V USB device is available in a variety of packages which are listed and illustrated in the subsequent tables.

16-pin part pinout

Figure 6. CY7C64315/CY7C64316 16-pin enCoRe V USB Device



Pin Definitions

16-pin part pinout (QFN)

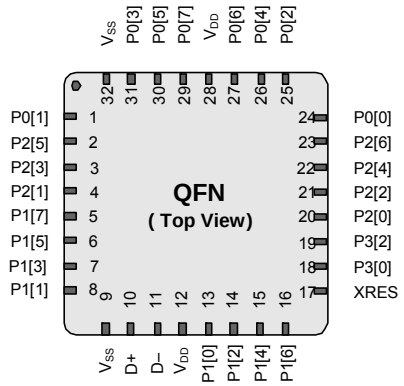
Pin No.	Type	Name	Description
1	I/O	P2[3]	Digital I/O, crystal input (Xin)
2	I/OHR	P1[7]	Digital I/O, SPI SS, I^2C SCL
3	I/OHR	P1[5]	Digital I/O, SPI MISO, I^2C SDA
4	I/OHR	P1[1][1, 2]	Digital I/O, ISSP CLK, I^2C SCL, SPI MOSI
5	Power	V_{SS}	Ground connection
6	USB line	D+	USB PHY
7	USB line	D–	USB PHY
8	Power	V_{DD}	Supply
9	I/OHR	P1[0][1, 2]	Digital I/O, ISSP DATA, I^2C SDA, SPI CLK
10	I/OHR	P1[4]	Digital I/O, optional external clock input (EXTCLK)
11	Input	XRES	Active high external reset with internal pull-down
12	I/OH	P0[4]	Digital I/O
13	I/OH	P0[7]	Digital I/O
14	I/OH	P0[3]	Digital I/O
15	I/OH	P0[1]	Digital I/O
16	I/O	P2[5]	Digital I/O, crystal output (Xout)

LEGEND I = Input, O = Output, OH = 5 mA High Output Drive, R = Regulated Output

Notes
1. During power up or reset event, device P1[0] and P1[1] may disturb the I^2C bus. Use alternate pins if issues are encountered.
2. These are the in-system serial programming (ISSP) pins that are not High Z at power on reset (POR).

32-pin part pinout

Figure 7. CY7C64343/CY7C64345/CY7C64346 32-pin enCoRe V USB Device



Pin Definitions

32-pin part pinout (QFN)

Pin No.	Type	Name	Description
1	I/OH	P0[1]	Digital I/O
2	I/O	P2[5]	Digital I/O, crystal output (Xout)
3	I/O	P2[3]	Digital I/O, crystal Input (Xin)
4	I/O	P2[1]	Digital I/O
5	I/OHR	P1[7]	Digital I/O, I^2C SCL, SPI SS
6	I/OHR	P1[5]	Digital I/O, I^2C SDA, SPI MISO
7	I/OHR	P1[3]	Digital I/O, SPI CLK
8	I/OHR	P1[1][3, 4]	Digital I/O, ISSP CLK, I^2C SCL, SPI MOSI
9	Power	V_{SS}	Ground
10	I/O	D+	USB PHY
11	I/O	D–	USB PHY
12	Power	V_{DD}	Supply voltage
13	I/OHR	P1[0][3, 4]	Digital I/O, ISSP DATA, I^2C SDA, SPI CLK
14	I/OHR	P1[2]	Digital I/O
15	I/OHR	P1[4]	Digital I/O, optional external clock input (EXTCLK)
16	I/OHR	P1[6]	Digital I/O
17	Reset	XRES	Active high external reset with internal pull down
18	I/O	P3[0]	Digital I/O
19	I/O	P3[2]	Digital I/O
20	I/O	P2[0]	Digital I/O
21	I/O	P2[2]	Digital I/O
22	I/O	P2[4]	Digital I/O
23	I/O	P2[6]	Digital I/O
24	I/OH	P0[0]	Digital I/O
25	I/OH	P0[2]	Digital I/O
26	I/OH	P0[4]	Digital I/O
27	I/OH	P0[6]	Digital I/O
28	Power	V_{DD}	Supply voltage
29	I/OH	P0[7]	Digital I/O
30	I/OH	P0[5]	Digital I/O
31	I/OH	P0[3]	Digital I/O
32	Power	V_{SS}	Ground
CP	Power	V_{SS}	Ensure the center pad is connected to ground

LEGEND I = Input, O = Output, OH = 5 mA High Output Drive, R = Regulated Output

Notes
3. During power up or reset event, device P1[0] and P1[1] may disturb the I^2C bus. Use alternate pins if issues are encountered.
4. These are the in-system serial programming (ISSP) pins that are not High Z at power on reset (POR).

Table 3. Register Map Bank 1 Table: Configuration Space

Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access
PRT0DM0	00	RW	PMA4_RA	40	RW		80			C0	
PRT0DM1	01	RW	PMA5_RA	41	RW		81			C1	
	02		PMA6_RA	42	RW		82			C2	
	03		PMA7_RA	43	RW		83			C3	
PRT1DM0	04	RW	PMA8_WA	44	RW		84			C4	
PRT1DM1	05	RW	PMA9_WA	45	RW		85			C5	
	06		PMA10_WA	46	RW		86			C6	
	07		PMA11_WA	47	RW		87			C7	
PRT2DM0	08	RW	PMA12_WA	48	RW		88			C8	
PRT2DM1	09	RW	PMA13_WA	49	RW		89			C9	
	0A		PMA14_WA	4A	RW		8A			CA	
	0B		PMA15_WA	4B	RW		8B			CB	
PRT3DM0	0C	RW	PMA8_RA	4C	RW		8C			CC	
PRT3DM1	0D	RW	PMA9_RA	4D	RW		8D			CD	
	0E		PMA10_RA	4E	RW		8E			CE	
	0F		PMA11_RA	4F	RW		8F			CF	
PRT4DM0	10	RW	PMA12_RA	50	RW		90			D0	
PRT4DM1	11	RW	PMA13_RA	51	RW		91			D1	
	12		PMA14_RA	52	RW		92		ECO_ENBUS	D2	RW
	13		PMA15_RA	53	RW		93		ECO_TRIM	D3	RW
	14		EP1_CR0	54	#		94			D4	
	15		EP2_CR0	55	#		95			D5	
	16		EP3_CR0	56	#		96			D6	
	17		EP4_CR0	57	#		97			D7	
	18		EP5_CR0	58	#		98		MUX_CR0	D8	RW
	19		EP6_CRO	59	#		99		MUX_CR1	D9	RW
	1A		EP7_CR0	5A	#		9A		MUX_CR2	DA	RW
	1B		EP8_CR0	5B	#		9B		MUX_CR3	DB	RW
	1C			5C			9C		IO_CFG1	DC	RW
	1D			5D			9D		OUT_P1	DD	RW
	1E			5E			9E		IO_CFG2	DE	RW
	1F			5F			9F		MUX_CR4	DF	RW
	20			60			A0		OSC_CR0	E0	RW
	21			61			A1		ECO_CFG	E1	#
	22			62			A2		OSC_CR2	E2	RW
	23			63			A3		VLT_CR	E3	RW
	24			64			A4		VLT_CMP	E4	R
	25			65			A5			E5	
	26			66			A6			E6	
	27			67			A7			E7	
	28			68			A8		IMO_TR	E8	W
SPI_CFG	29	RW		69			A9		ILO_TR	E9	W
	2A			6A			AA			EA	
	2B			6B			AB		SLP_CFG	EB	RW
	2C		TMP_DR0	6C	RW		AC		SLP_CFG2	EC	RW
	2D		TMP_DR1	6D	RW		AD		SLP_CFG3	ED	RW
	2E		TMP_DR2	6E	RW		AE			EE	
	2F		TMP_DR3	6F	RW		AF			EF	
USB_CR1	30	#		70			B0			F0	
	31			71			B1			F1	
	32			72			B2			F2	
	33			73			B3			F3	
PMA0_WA	34	RW		74			B4			F4	
PMA1_WA	35	RW		75			B5			F5	
PMA2_WA	36	RW		76			B6			F6	
PMA3_WA	37	RW		77			B7		CPU_F	F7	RL
PMA4_WA	38	RW		78			B8			F8	
PMA5_WA	39	RW		79			B9			F9	
PMA6_WA	3A	RW		7A			BA		IMO_TR1	FA	RW
PMA7_WA	3B	RW		7B			BB			FB	
PMA0_RA	3C	RW		7C			BC			FC	
PMA1_RA	3D	RW		7D		USB_MISC_CR	BD	RW		FD	
PMA2_RA	3E	RW		7E			BE			FE	
PMA3_RA	3F	RW		7F			BF			FF	

Gray fields are reserved; do not access these fields. # Access is bit specific.

DC Electrical Characteristics

DC Chip Level Specifications

Table 6 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 6. DC Chip Level Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
V_{DD}	Operating voltage [7, 9]	No USB activity.	3.0	–	5.5	V
$I_{DD24,3}$	Supply current, CPU = 24 MHz	Conditions are V_{DD} = 3.0 V, T_A = 25 °C, CPU = 24 MHz, No USB/I^2C/SPI.	–	2.9	4.0	mA
$I_{DD12,3}$	Supply current, CPU = 12 MHz	Conditions are V_{DD} = 3.0 V, T_A = 25 °C, CPU = 12 MHz, No USB/I^2C/SPI.	–	1.7	2.6	mA
$I_{DD6,3}$	Supply current, CPU = 6 MHz	Conditions are V_{DD} = 3.0 V, T_A = 25 °C, CPU = 6 MHz, No USB/I^2C/SPI.	–	1.2	1.8	mA
$I_{SB1,3}$	Standby current with POR, LVD, and sleep timer	V_{DD} = 3.0 V, T_A = 25 °C, I/O regulator turned off.	–	1.1	1.5	µA
$I_{SB0,3}$	Deep sleep current	V_{DD} = 3.0 V, T_A = 25 °C, I/O regulator turned off.	–	0.1	–	µA
V_{DDUSB}	Operating voltage	USB activity, USB regulator enabled	4.35	–	5.25	V
$I_{DD24,5}$	Supply current, CPU = 24 MHz	Conditions are V_{DD} = 5.0 V, T_A = 25 °C, CPU = 24 MHz, IMO = 24 MHz USB Active, No I^2C/SPI.	–	7.1	–	mA
$I_{DD12,5}$	Supply current, CPU = 12 MHz	Conditions are V_{DD} = 5.0 V, T_A = 25 °C, CPU = 12 MHz, IMO = 24 MHz USB Active, No I^2C/SPI.	–	6.2	–	mA
$I_{DD6,5}$	Supply current, CPU = 6 MHz	Conditions are V_{DD} = 5.0 V, T_A = 25 °C, CPU = 6 MHz, IMO = 24 MHz USB Active, No I^2C/SPI	–	5.8	–	mA
$I_{SB1,5}$	Standby current with POR, LVD, and sleep timer	V_{DD} = 5.0 V, T_A = 25 °C, I/O regulator turned off.	–	1.1	–	µA
$I_{SB0,5}$	Deep sleep current	V_{DD} = 5.0 V, T_A = 25 °C, I/O regulator turned off.	–	0.1	–	µA
V_{DDUSB}	Operating voltage	USB activity, USB regulator bypassed	3.15	3.3	3.60	V

Notes
10. Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 85 °C degrade reliability.
11. The temperature rise from ambient to junction is package specific. See Package Handling on page 31. The user must limit the power consumption to comply with this requirement.

Table 7. DC Characteristics – USB Interface

Symbol	Description	Conditions	Min	Typ	Max	Units
Rusbi	USB D+ pull-up resistance	With idle bus	0.900	–	1.575	kΩ
Rusba	USB D+ pull-up resistance	While receiving traffic	1.425	–	3.090	kΩ
Vohusb	Static output high		2.8	–	3.6	V
Volusb	Static output low		–	–	0.3	V
Vdi	Differential input sensitivity		0.2	–	–	V
Vcm	Differential input common mode range		0.8	–	2.5	V
Vse	Single-ended receiver threshold		0.8	–	2.0	V
Cin	Transceiver capacitance			–	50	pF
Iio	High Z state data Line Leakage	On D+ or D– line	–10	–	+10	µA
Rps2	PS/2 Pull Up Resistance		3	5	7	kΩ
Rext	External USB Series Resistor	In series with each USB pin	21.78	22.0	22.22	Ω

ADC Electrical Specifications

Table 8. ADC User Module Electrical Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
Input						
V_{IN}	Input voltage range		0	–	VREFADC	V
C_{IIN}	Input capacitance		–	–	5	pF
R_{IN}	Input resistance	Equivalent switched cap input resistance for 8-, 9-, or 10-bit resolution	1/(500fF* Data Clock)	1/(400fF* Data Clock)	1/(300fF* Data Clock)	Ω
Reference						
V_{REFADC}	ADC reference voltage		1.14	–	1.26	V
Conversion Rate						
F_{CLK}	Data clock	Source is chip's internal main oscillator. See AC Chip-Level Specifications for accuracy	2.25	–	6	MHz
S8	8-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2^Resolution/Data Clock)	–	23.4375	–	ksps
S10	10-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2^Resolution/Data Clock)	–	5.859	–	ksps
DC Accuracy						
RES	Resolution	Can be set to 8-, 9-, or 10-bit	8	–	10	bits
DNL	Differential nonlinearity		–1	–	+2	LSB
INL	Integral nonlinearity		–2	–	+2	LSB
E_{Offset}	Offset error	8-bit resolution	0	3.2	19.2	LSB
		10-bit resolution	0	12.8	76.8	LSB
E_{gain}	Gain error	For any resolution	–5	–	+5	%FSR
Power						
I_{ADC}	Operating current		–	2.1	2.6	mA
PSRR	Power supply rejection ratio	PSRR (V_{DD} > 3.0 V)	–	24	–	dB
		PSRR (V_{DD} < 3.0 V)	–	30	–	dB

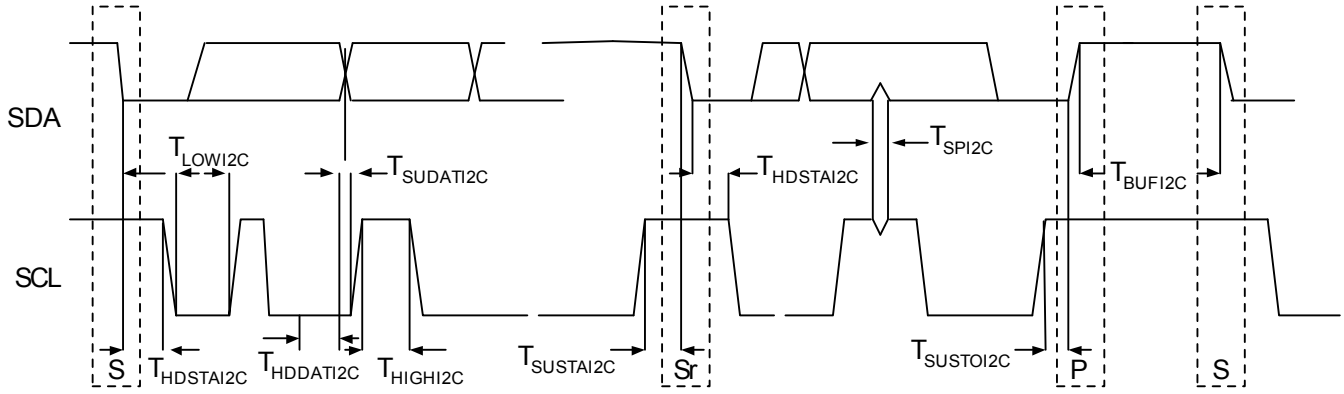
AC I²C Specifications

Table 18 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 18. AC Characteristics of the I²C SDA and SCL Pins

Symbol	Description	Standard Mode		Fast Mode		Units
		Min	Max	Min	Max	
F_{SCLI2C}	SCL clock frequency	0	100	0	400	kHz
$T_{HDSTAI2C}$	Hold time (repeated) START condition. After this period, the first clock pulse is generated	4.0	–	0.6	–	µs
T_{LOWI2C}	LOW period of the SCL clock	4.7	–	1.3	–	µs
$T_{HIGHI2C}$	HIGH period of the SCL clock	4.0	–	0.6	–	µs
$T_{SUSTAI2C}$	Setup time for a repeated START condition	4.7	–	0.6	–	µs
$T_{HDDATI2C}$	Data hold time	0	–	0	–	µs
$T_{SUDATI2C}$	Data setup time	250	–	100[20]	–	ns
$T_{SUSTOI2C}$	Setup time for STOP condition	4.0	–	0.6	–	µs
T_{BUFI2C}	Bus free time between a STOP and START condition	4.7	–	1.3	–	µs
T_{SPI2C}	Pulse width of spikes are suppressed by the input filter	–	–	0	50	ns

Figure 13. Definition of Timing for Fast/Standard Mode on the I²C Bus



Note

20. A Fast mode I²C bus device can be used in a standard mode I²C bus system, but the requirement $t_{SUDAT} \geq 250$ ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line $t_{rmax} + t_{SUDAT} = 1000 + 250 = 1250$ ns (according to the standard mode I²C bus specification) before the SCL line is released.

Table 19. SPI Master AC Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
F_{SCLK}	SCLK clock frequency		–	–	6	MHz
DC	SCLK duty cycle		–	50	–	%
T_{SETUP}	MISO to SCLK setup time		60	–	–	ns
T_{HOLD}	SCLK to MISO hold time		40	–	–	ns
T_{OUT_VAL}	SCLK to MOSI valid time		–	–	40	ns
T_{OUT_H}	SCLK to MOSI hold time		40	–	–	ns

Figure 14. SPI Master Mode 0 and 2

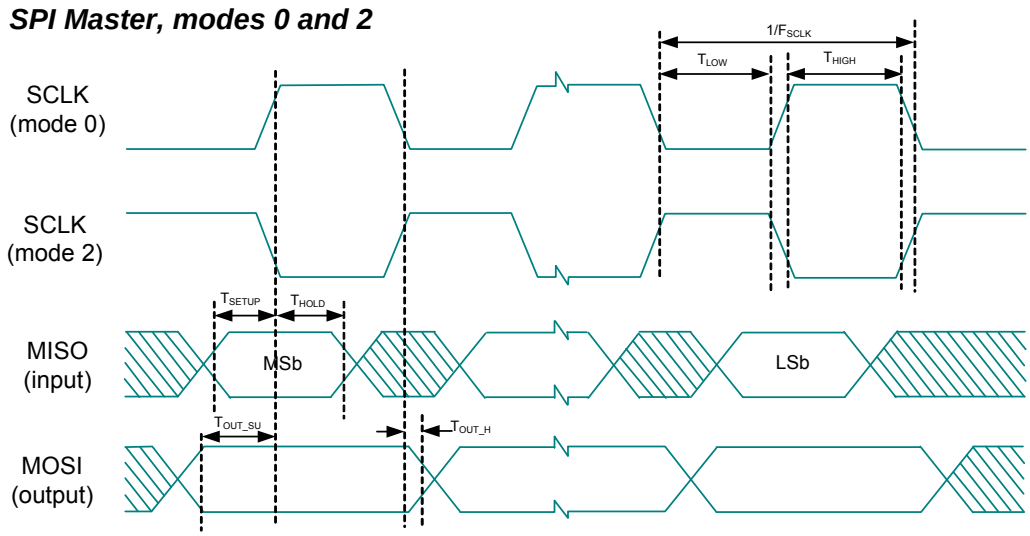


Figure 15. SPI Master Mode 1 and 3

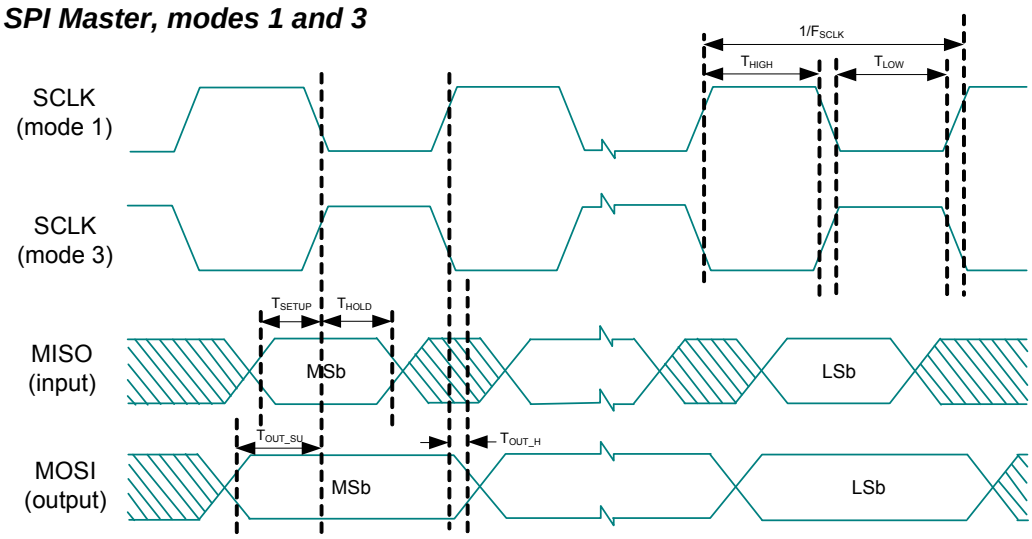


Table 20. SPI Slave AC Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
F_{SCLK}	SCLK clock frequency		0.0469	–	12	MHz
T_{LOW}	SCLK low time		41.67	–	–	ns
T_{HIGH}	SCLK high time		41.67	–	–	ns
T_{SETUP}	MOSI to SCLK setup time		30	–	–	ns
T_{HOLD}	SCLK to MOSI hold time		50	–	–	ns
T_{SS_MISO}	SS low to MISO valid		–	–	153	ns
T_{SCLK_MISO}	SCLK to MISO valid		–	–	125	ns
T_{SS_HIGH}	SS high time		50	–	–	ns
T_{SS_CLK}	Time from SS low to first SCLK		$2/F_{SCLK}$	–	–	ns
T_{CLK_SS}	Time from last SCLK to SS high		$2/F_{SCLK}$	–	–	ns

Figure 16. SPI Slave Mode 0 and 2

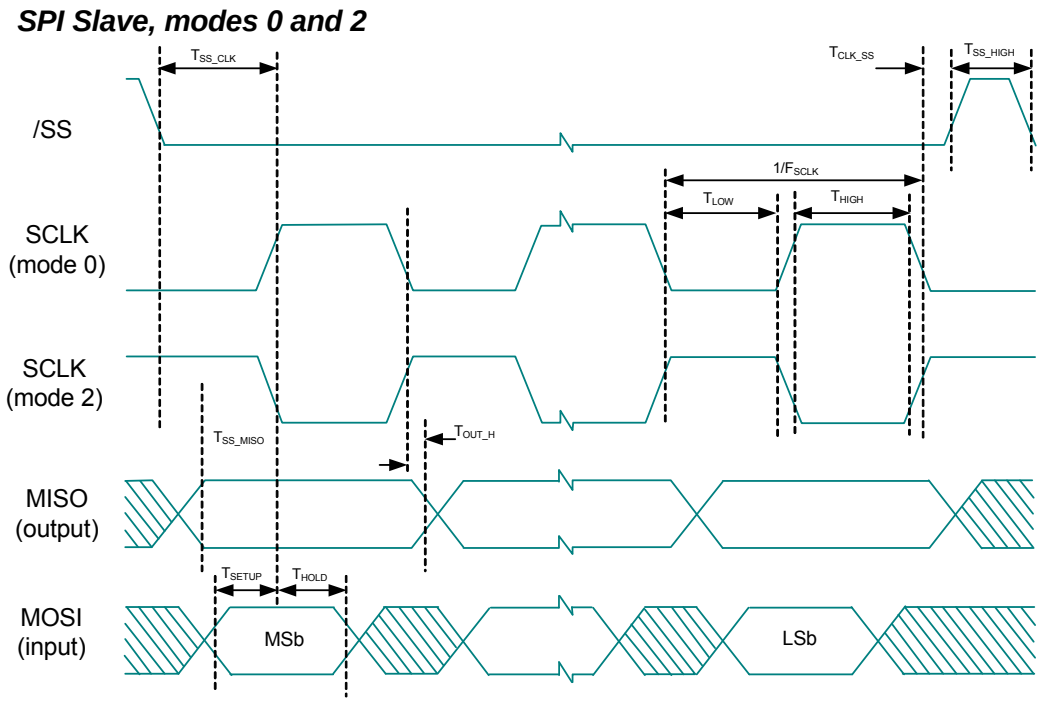
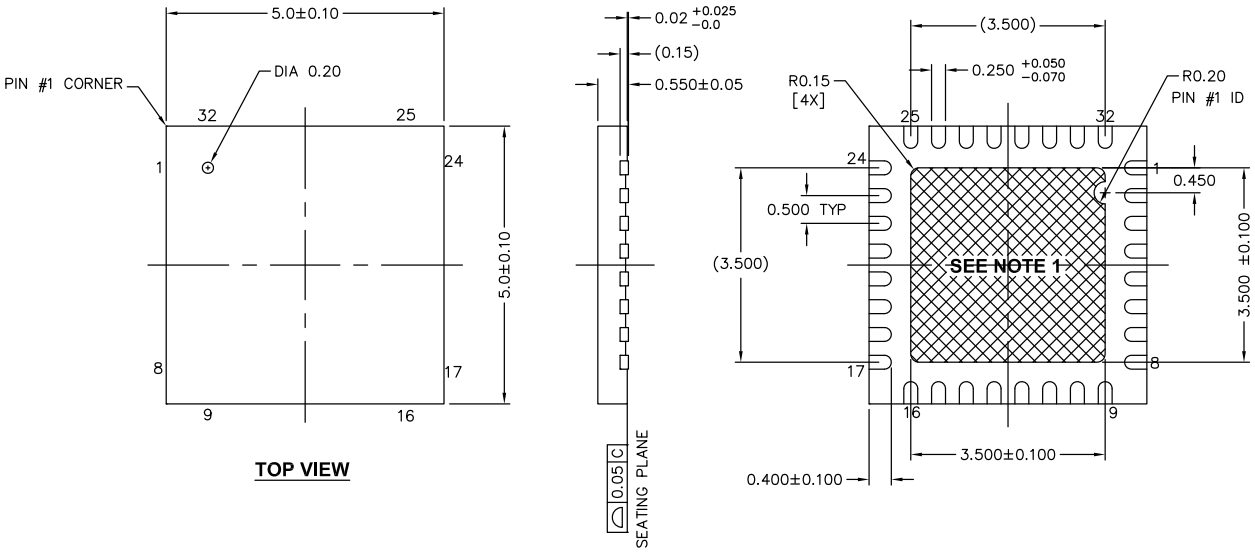


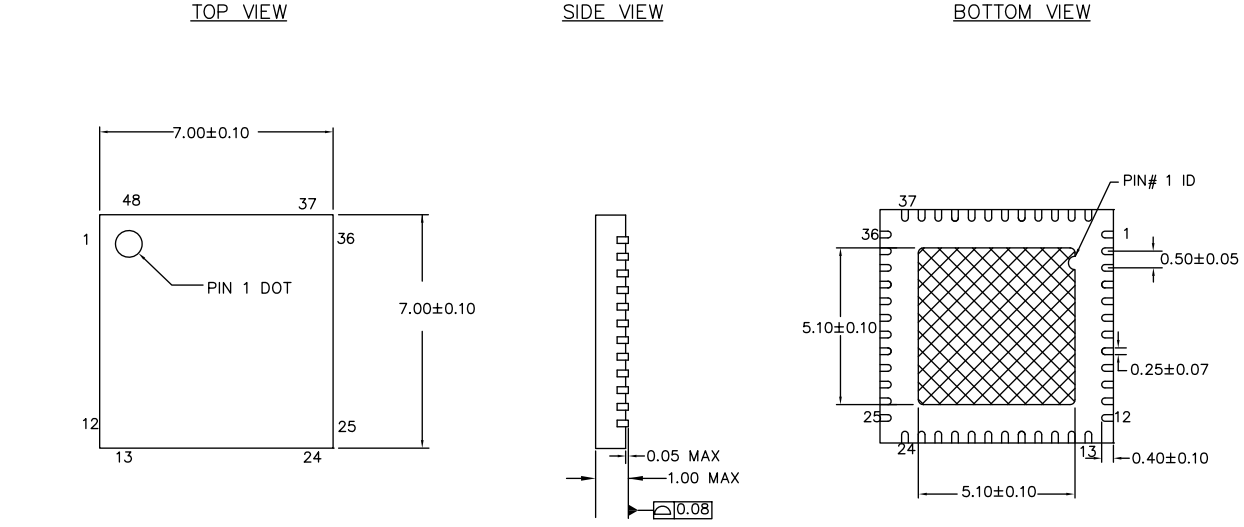
Figure 19. 32-pin QFN (5 × 5 × 0.55 mm) LQ32 3.5 × 3.5 E-Pad (Sawn) Package Outline, 001-42168



NOTES:
1. HATCH AREA IS SOLDERABLE EXPOSED PAD
2. BASED ON REF JEDEC # MO−248
3. PACKAGE WEIGHT: 0.0388g
4. DIMENSIONS ARE IN MILLIMETERS

001-42168 *E

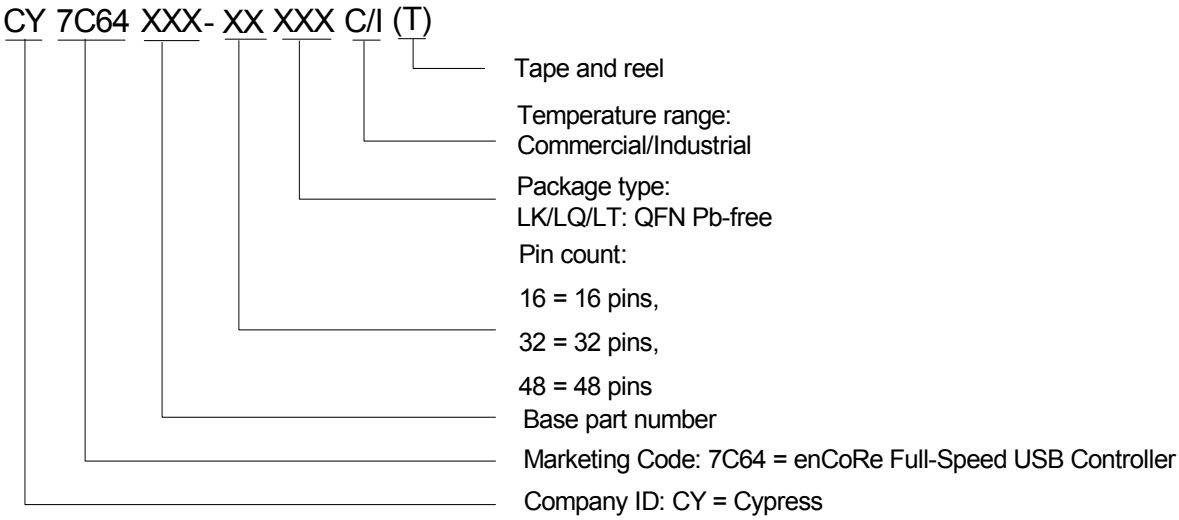
Figure 20. 48-pin QFN (7 × 7 × 1.00 mm) LT48A 5.1 × 5.1 E-Pad (Sawn) Package Outline, 001-13191



NOTES:
1. HATCH AREA IS SOLDERABLE EXPOSED METAL.
2. REFERENCE JEDEC#: MO−220
3. PACKAGE WEIGHT: 13 ± 1 mg
4. ALL DIMENSIONS ARE IN MILLIMETERS

001-13191 *H

Ordering Code Definitions



Acronyms

Acronym	Description
API	Application Programming Interface
CPU	Central Processing Unit
GPIO	General Purpose I/O
ICE	In-Circuit Emulator
ILO	Internal Low speed Oscillator
IMO	Internal Main Oscillator
I/O	Input/Output
LSb	Least Significant Bit
LVD	Low Voltage Detect
MSb	Most Significant Bit
POR	Power On Reset
PPOR	Precision Power On Reset
PSoC	Programmable System-on-Chip
SLIMO	Slow IMO
SRAM	Static Random Access Memory

Document Conventions

Units of Measure

Symbol	Unit of Measure
°C	degree Celsius
dB	decibel
fF	femtofarad
Hz	hertz
KB	1024 bytes
Kbit	1024 bits
kHz	kilohertz
kΩ	kilohm
MHz	megahertz
MΩ	megaohm
µA	microampere
µF	microfarad
µH	microhenry
µs	microsecond
µV	microvolt
µVrms	microvolts root-mean-square
µW	microwatt
mA	milliampere
ms	milli-second
mV	millivolt
nA	nanoampere
ns	nanosecond
nV	nanovolt
W	ohm
pA	picoampere
pF	picofarad
pp	peak-to-peak
ppm	parts per million
ps	picosecond
sps	samples per second
σ	sigma: one standard deviation
V	volt

Numeric Naming

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase ‘h’ (for example, ‘14h’ or ‘3Ah’). Hexadecimal numbers may also be represented by a ‘0x’ prefix, the C coding convention. Binary numbers have an appended lowercase ‘b’ (for example, ‘01010100b’ or ‘01000011b’). Numbers not indicated by an ‘h’, ‘b’, or ‘0x’ are decimal.

Errata

This section describes the errata for the enCoRe V – CY7C643xx. Details include errata trigger conditions, scope of impact, available workaround, and silicon revision applicability.

Contact your local Cypress Sales Representative if you have questions.

CY7C643xx Errata Summary

The following Errata item applies to the **CY7C643xx** data sheets.

1. Latch up susceptibility when maximum I/O sink current exceeded

■PROBLEM DEFINITION

P1[3], P1[6], and P1[7] pins are susceptible to latch up when the I/O sink current exceeds 25 mA per pin on these pins.

■PARAMETERS AFFECTED

LU – Latch up current. Per JESD78A, the maximum allowable latch up current per pin is 100 mA. Cypress internal specification is 200 mA latch up current limit.

■TRIGGER CONDITIONS

Latch up occurs when both the following conditions are met:

A. The offending I/O is externally connected to a voltage higher than the I/O high state, causing a current to flow into the pin that exceeds 25 mA.

B. A Port1 I/O (P1[1], P1[4], and P1[5] respectively) adjacent to the offending I/O is connected to a voltage lower than the I/O low state. This causes a signal that drops below Vss (signal undershoot) and a current greater than 200 mA to flow out of the pin.

■SCOPE OF IMPACT

The trigger conditions outlined in this item exceed the maximum ratings specified in the CY7C643xx data sheets.

■WORKAROUND

Add a series resistor > 300 Ω to P1[3], P1[6], and P1[7] pins to restrict current to within latch up limits.

■FIX STATUS

This issue will be corrected in the next new silicon revision.

2. Does not meet USB 2.0 specification for D+ and D- rise/fall matching when supply voltage is under 3.3 V

■PROBLEM DEFINITION

Rising to falling rate matching of the USB D+ and D- lines has a corner case at lower supply voltages, such as those under 3.3 V.

■PARAMETERS AFFECTED

Rising to falling rate matching of the USB data lines.

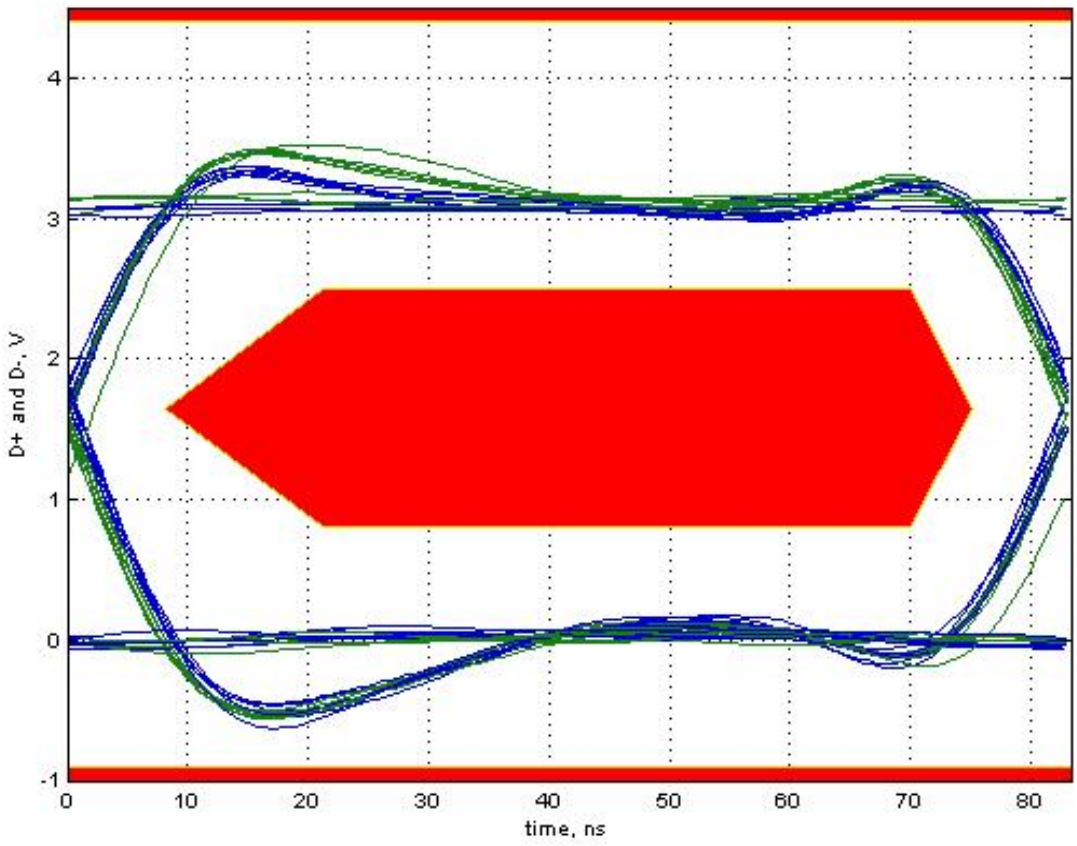
■TRIGGER CONDITION(S)

Operating the VCC supply voltage at the low end of the chip's specification (under 3.3 V) may cause a mismatch in the rising to falling rate.

■SCOPE OF IMPACT

This condition does not affect USB communications but could cause corner case issues with USB lines' rise/fall matching specification. Signal integrity tests were run using the Cypress development kit and excellent eye was observed with supply voltage of 3.15 V.

Figure 21. Eye Diagram



■WORKAROUND

Avoid the trigger condition by using lower tolerance voltage regulators.

■FIX STATUS

This issue will not be corrected in the next new silicon revision.

Document History Page

Document Title: CY7C6431x/CY7C6434x/CY7C6435x, enCoRe™ V Full Speed USB Controller Document Number: 001-12394				
Rev.	**ECN No.**	**Orig. of Change**	**Submission Date**	**Description of Change**
**	626256	TYJ	See ECN	New data sheet.
*A	735718	TYJ / ARI	See ECN	Filled in TBDs, added new block diagram, and corrected some values. Part numbers updated as per new specifications.
*B	1120404	ARI	See ECN	Corrected the block diagram and Figure 3, which is the 16-pin enCoRe V device. Corrected the description to pin 29 on Table 2, the Typ/Max values for I_{SB0} on the DC chip-level specifications, the current value for the latch-up current in the Electrical Characteristics section, and corrected the 16 QFN package information in the Thermal Impedance table. Corrected some of the bulleted items on the first page. Added DC Characteristics–USB Interface table. Added AC Characteristics–USB Data Timings table. Added AC Characteristics–USB Driver table. Corrected Flash Write Endurance minimum value in the DC Programming Specifications table. Corrected the Flash Erase Time max value and the Flash Block Write Time max value in the AC Programming Specifications table. Implemented new latest template. Include parameters: Vcrs, Rpu (USB, active), Rpu (USB suspend), Tfdeop, Tfeopr2, Tfeopt, Tfst. Added register map tables. Corrected a value in the DC Chip-Level Specifications table.
*C	1241024	TYJ / ARI	See ECN	Corrected Idd values in Table 6 - DC Chip-Level Specifications.
*D	1639963	AESA	See ECN	Post to www.cypress.com
*E	2138889	TYJ / PYRS	See ECN	Updated Ordering Code table: - Ordering code changed for 32-QFN package: From -32LKXC to -32LTXC - Added a new package type – “LTXC” for 48-QFN - Included Tape and Reel ordering code for 32-QFN and 48-QFN packages Changed active current values at 24, 12 and 6MHz in table “DC Chip-Level Specifications” - IDD24: 2.15 to 3.1mA - IDD12: 1.45 to 2.0mA - IDD6: 1.1 to 1.5mA Added information on using P1[0] and P1[1] as the I2C interface during POR or reset events

Document History Page *(continued)*

Document Title: CY7C6431x/CY7C6434x/CY7C6435x, enCoRe™ V Full Speed USB Controller Document Number: 001-12394				
Rev.	**ECN No.**	**Orig. of Change**	**Submission Date**	**Description of Change**
*K	2874274	KKU / PYRS	02/05/10	On page 4, changed the input voltage range from '0 V to 1.3 V' to '0 V to V_{REFADC}'. Added note for Operating Voltage in Table 6. Updated Register Map. Added SPI slave and master mode diagrams; in Table 19, changed T_{OUT_HIGH} parameter to T_{OUT_H} and modified description; in Table 20, updated T_{SS_CLK} and T_{CLK_SS} min values to $2/F_{SCLK}$ and changed description of T_{SS_MISO}. Added Vdd_{USB} parameter in Table 6. Updated package diagrams.
*L	3028310	XUT	09/13/2010	Removed HPOR bit reference from DC POR and LVD Specifications Updated Development Tools and Designing with PSoC Designer. Added Ordering Code Definitions Moved Acronyms and Document Conventions to end of document.
*M	3048308	NXZ	10/06/2010	Updated Features section as furnished in the CDT 74890 Updated datasheet as per new template All footnotes updated sequentially
*N	3557631	CSAI	03/21/2012	Updated Getting Started. Updated Package Diagrams. Updated in new template.
*O	3912957	NXZ	03/06/2013	Updated Functional Overview (Updated The enCoRe V Core (Updated contents in the section), updated Full-Speed USB (Updated contents in the section)). Updated Register Mapping Tables (Updated Table 3 (Replaced "EC0_ENBUS" with "ECO_ENBUS" and replaced "EC0_TRIM" with "ECO_TRIM")). Updated Package Diagrams: spec 001-09116 – Changed revision from *F to *H. spec 001-42168 – Changed revision from *D to *E. spec 001-13191 – Changed revision from *F to *G.
*P	3979449	ANKC	04/23/2013	Added Errata.
*Q	4074443	ANKC	07/23/2013	Added Errata footnotes (Note 8, 19). Updated Electrical Specifications: Updated Absolute Maximum Ratings: Added Note 8 and referred the same note in LU parameter. Updated AC Electrical Characteristics Updated AC Chip Level Specifications: Added Note 19 and referred the same note in TR parameter in Table 14. Updated to new template.
*R	4197134	ANKC	11/20/2013	Updated Package Diagrams: spec 001-09116 – Changed revision from *H to *I. Completing Sunset Review.

Document History Page *(continued)*

Document Title: CY7C6431x/CY7C6434x/CY7C6435x, enCoRe™ V Full Speed USB Controller Document Number: 001-12394				
Rev.	**ECN No.**	**Orig. of Change**	**Submission Date**	**Description of Change**
*S	4578605	GINS	12/11/2014	Updated Pin Information: Updated 32-pin part pinout: Updated Figure 7 (No change in figure, included CY7C64346 in figure caption). Updated Package Diagrams: spec 001-09116 – Changed revision from *I to *J. Updated Ordering Information: Updated Table 25: Updated part numbers.
*T	5548557	ANKC	12/12/2016	Updated Cypress Logo, Sales Page and Disclaimer. Updated Figure 20 (spec 001-13191 *G to *H) in Package Diagrams. Removed the following obsolete part numbers (Table 26) in Ordering Information: CY7C64343-32LQXI, CY7C64343-32LQXIT, CY7C64345-32LQXI, CY7C64345-32LQXIT, CY7C64356-48LTXI, CY7C64356-48LTXIT.

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