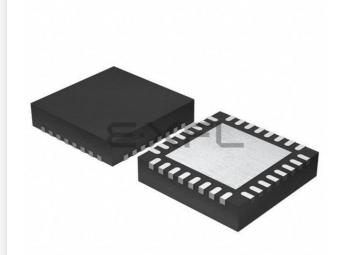
## Cypress Semiconductor Corp - <u>CY7C64346-32LQXC Datasheet</u>



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Details	
Product Status	Obsolete
Applications	-
Core Processor	-
Program Memory Type	-
Controller Series	-
RAM Size	-
Interface	USB
Number of I/O	-
Voltage - Supply	3V ~ 5.5V
Operating Temperature	0°C ~ 70°C
Mounting Type	Surface Mount
Package / Case	32-UFQFN Exposed Pad
Supplier Device Package	32-QFN (5x5)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy7c64346-32lqxc

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SPI configuration register (SPI\_CFG) sets master/slave functionality, clock speed, and interrupt select. SPI control register (SPI\_CR) provides four control bits and four status bits for device interfacing and synchronization.

The SPIM hardware has no support for driving the Slave Select (SS\_) signal. The behavior and use of this signal is dependent on the application and enCoRe V device and, if required, must be implemented in firmware.

There is an additional data input in the SPIS, Slave Select (SS\_), which is an active low signal. SS\_ must be asserted to enable the SPIS to receive and transmit. SS\_ has two high level functions:

- To allow for the selection of a given slave in a multi-slave environment.
- To provide additional clocking for TX data queuing in SPI modes 0 and 1.

#### I<sup>2</sup>C Slave

The  $I^2C$  slave enhanced communications block is a serial-to-parallel processor, designed to interface the enCoRe V device to a two-wire  $I^2C$  serial communications bus. To eliminate the need for excessive CPU intervention and overhead, the block provides  $I^2C$ -specific support for status detection and generation of framing bits. By default, the  $I^2C$  slave enhanced module is firmware compatible with the previous generation of  $I^2C$  slave functionality. However, this module provides new features that are configurable to implement significant flexibility for both internal and external interfacing. The basic  $I^2C$  features include:

- Slave, transmitter, and receiver operation.
- Byte processing for low CPU overhead.

- Interrupt or polling CPU interface.
- Support for clock rates of up to 400 kHz.
- 7- or 10-bit addressing (through firmware support).
- SMBus operation (through firmware support).

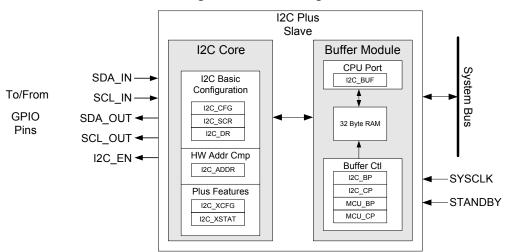
Enhanced features of the I<sup>2</sup>C Slave Enhanced Module include:

- Support for 7-bit hardware address compare.
- Flexible data buffering schemes.
- A "no bus stalling" operating mode.
- A low power bus monitoring mode.

The  $I^2C$  block controls the data (SDA) and the clock (SCL) to the external  $I^2C$  interface through direct connections to two dedicated GPIO pins. When  $I^2C$  is enabled, these GPIO pins are not available for general purpose use. The enCoRe V CPU firmware interacts with the block through I/O register reads and writes, and firmware synchronization is implemented through polling and/or interrupts.

In the default operating mode, which is firmware compatible with previous versions of  $\rm I^2C$  slave modules, the  $\rm I^2C$  bus is stalled upon every received address or byte, and the CPU is required to read the data or supply data as required before the  $\rm I^2C$  bus continues. However, this  $\rm I^2C$  Slave Enhanced module provides new data buffering capability as an enhanced feature. In the EZI^2C buffering mode, the  $\rm I^2C$  slave interface appears as a 32-byte RAM buffer to the external  $\rm I^2C$  master. Using a simple predefined protocol, the master controls the read and write pointers into the RAM. When this method is enabled, the slave never stalls the bus. In this protocol, the data available in the RAM (this is managed by the CPU) is valid.

Figure 5. I<sup>2</sup>C Block Diagram





### Designing with PSoC Designer

The development process for the PSoC device differs from that of a traditional fixed-function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and lowering inventory costs. These configurable resources, called PSoC blocks, have the ability to implement a wide variety of user-selectable functions. The PSoC development process is:

- 1. Select user modules.
- 2. Configure user modules.
- 3. Organize and connect.
- 4. Generate, verify, and debug.

#### Select User Modules

PSoC Designer provides a library of prebuilt, pretested hardware peripheral components called user modules. User modules make selecting and implementing peripheral devices, both analog and digital, simple.

#### **Configure User Modules**

Each user module that you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. For example, a Pulse width modulator (PWM) user module configures one or more digital PSoC blocks, one for each eight bits of resolution. Using these parameters, you can establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All of the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These user module

data sheets explain the internal operation of the user module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information that you may need to successfully implement your design.

#### **Organize and Connect**

Build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. Perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

#### Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, perform the "Generate Configuration Files" step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides APIs with high-level functions to control and respond to hardware events at run time, and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in C, assembly language, or both.

The last step in the development process takes place inside PSoC Designer's Debugger (accessed by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint, and watch-variable features, the debug interface provides a large trace buffer. It allows you to define complex breakpoint events that include monitoring address and data bus values, memory locations, and external signals.



Table 2. Register Map Bank 0 Table: User Space

	egister Ma										
Name	Addr (0, Hex)		Name	Addr (0, Hex)	Access	Name	Addr (0, Hex)	Access	Name	Addr (0, Hex)	Access
PRT0DR	00	RW	EP1_CNT0	40	#		80			C0	
PRT0IE	01	RW	EP1_CNT1	41	RW		81			C1	
	02		EP2 CNT0	42	#		82			C2	
	03		EP2 CNT1	43	RW		83			C3	
PRT1DR	04	RW	EP3_CNT0	44	#		84			C4	
PRT1IE	05	RW	EP3 CNT1	45	RW		85			C5	
FRITIL	06	IXVV	EP4 CNT0	46	#		86			C6	
	07		EP4_CNT1	47	RW		87			C7	
PRT2DR	08	RW	EP5_CNT0	48	#		88		I2C_XCFG	C8	RW
PRT2IE	09	RW	EP5_CNT1	49	RW		89		I2C_XSTAT	C9	R
	0A		EP6_CNT0	4A	#		8A		I2C_ADDR	CA	RW
	0B		EP6 CNT1	4B	RW		8B		I2C BP	CB	R
PRT3DR	0C	RW	EP7 CNT0	4C	#		8C		I2C CP	CC	R
PRT3IE	0D	RW	EP7_CNT1	4D	RW		8D		CPU BP	CD	RW
	0E		EP8 CNT0	4E	#		8E		CPU CP	CE	R
	0F		EP8_CNT1	4F	RW		8F		I2C BUF	CF	RW
DDT4DD		D)A/	EFO_CIVIT		KVV						
PRT4DR	10	RW		50			90		CUR_PP	D0	RW
PRT4IE	11	RW		51			91		STK_PP	D1	RW
	12			52			92			D2	
	13			53			93		IDX_PP	D3	RW
	14			54			94		MVR_PP	D4	RW
	15			55			95		MVW PP	D5	RW
	16			56			96		I2C CFG	D6	RW
	17			57			97		I2C_CFG	D7	#
			PMA0 DR		RW				I2C_SCR	D8	RW
	18			58			98		IZC_DR		RVV
	19		PMA1_DR	59	RW		99			D9	
	1A		PMA2_DR	5A	RW		9A		INT_CLR0	DA	RW
	1B		PMA3_DR	5B	RW		9B		INT_CLR1	DB	RW
	1C		PMA4_DR	5C	RW		9C		INT_CLR2	DC	RW
	1D		PMA5_DR	5D	RW		9D			DD	
	1E		PMA6 DR	5E	RW		9E		INT MSK2	DE	RW
	1F		PMA7_DR	5F	RW		9F		INT MSK1	DF	RW
	20		T WO W_DIX	60	1377		A0		INT MSK0	E0	RW
	21			61						E1	RW
							A1		INT_SW_EN		
	22			62			A2		INT_VC	E2	RC
	23			63			A3		RES_WDT	E3	W
	24		PMA8_DR	64	RW		A4			E4	
	25		PMA9_DR	65	RW		A5			E5	
	26		PMA10_DR	66	RW		A6			E6	
	27		PMA11 DR	67	RW		A7			E7	
	28		PMA12 DR	68	RW		A8			E8	
SPI TXR	29	W	PMA13 DR	69	RW		A9			E9	
SPI RXR	29 2A	R	PMA14_DR	6A	RW		AA			EA	
			PMA14_DR PMA15 DR								
SPI_CR	2B	#		6B	RW		AB			EB	
	2C		TMP_DR0	6C	RW		AC			EC	
	2D		TMP_DR1	6D	RW		AD			ED	
	2E		TMP_DR2	6E	RW		AE			EE	
	2F		TMP_DR3	6F	RW		AF			EF	
	30			70		PT0_CFG	В0	RW		F0	
USB SOF0	31	R		71		PT0 DATA1	B1	RW		F1	
USB SOF1	32	R		72		PT0 DATA0	B2	RW		F2	
USB_GOT I	33	RW		73		PT1 CFG	B3	RW		F3	
_											
USBIO_CR0	34	#		74		PT1_DATA1	B4	RW		F4	
USBIO_CR1	35	#		75		PT1_DATA0	B5	RW		F5	
EP0_CR	36	#		76		PT2_CFG	B6	RW		F6	
EP0_CNT0	37	#		77		PT2_DATA1	B7	RW	CPU_F	F7	RL
EP0_DR0	38	RW		78		PT2_DATA0	B8	RW		F8	
EP0_DR1	39	RW		79			B9			F9	
EP0 DR2	3A	RW		7A			BA			FA	
EP0 DR3	3B	RW		7B			BB			FB	
EP0_DR3	3C	RW		7C			BC			FC	
EP0_DR5	3D	RW		7D			BD		OBIL COT	FD	
EP0_DR6	3E	RW		7E			BE		CPU_SCR1	FE	#
EP0_DR7	3F	RW		7F			BF		CPU_SCR0	FF	#
Cray fields ar			d C. L.L.	# Accord is hit							

Gray fields are reserved; do not access these fields. # Access is bit specific.



# **Electrical Specifications**

This section presents the DC and AC electrical specifications of the enCoRe V USB devices. For the most up-to-date electrical specifications, verify that you have the most recent data sheet available by visiting the company web site at http://www.cypress.com

Figure 9. Voltage versus CPU Frequency

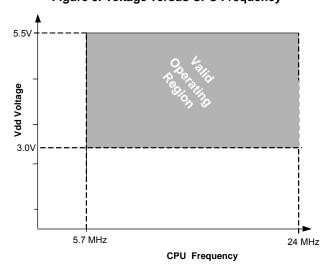
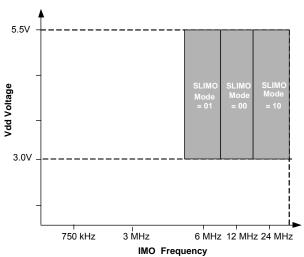


Figure 10. IMO Frequency Trim Options





#### **DC Electrical Characteristics**

DC Chip Level Specifications

Table 6 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

#### Table 6. DC Chip Level Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
$V_{DD}$	Operating voltage [7, 9]	No USB activity.	3.0	_	5.5	V
I <sub>DD24,3</sub>	Supply current, CPU = 24 MHz	Conditions are $V_{DD}$ = 3.0 V, $T_A$ = 25 °C, CPU = 24 MHz, No USB/I <sup>2</sup> C/SPI.	-	2.9	4.0	mA
I <sub>DD12,3</sub>	Supply current, CPU = 12 MHz	Conditions are $V_{DD}$ = 3.0 V, $T_A$ = 25 °C, CPU = 12 MHz, No USB/I <sup>2</sup> C/SPI.	-	1.7	2.6	mA
I <sub>DD6,3</sub>	Supply current, CPU = 6 MHz	Conditions are $V_{DD}$ = 3.0 V, $T_A$ = 25 °C, CPU = 6 MHz, No USB/I $^2$ C/SPI.	-	1.2	1.8	mA
I <sub>SB1,3</sub>	Standby current with POR, LVD, and sleep timer	$V_{DD}$ = 3.0 V, $T_{A}$ = 25 °C, I/O regulator turned off.	_	1.1	1.5	μА
I <sub>SB0,3</sub>	Deep sleep current	$V_{DD}$ = 3.0 V, $T_{A}$ = 25 °C, I/O regulator turned off.	_	0.1	-	μА
$V_{DDUSB}$	Operating voltage	USB activity, USB regulator enabled	4.35	-	5.25	V
I <sub>DD24,5</sub>	Supply current, CPU = 24 MHz	Conditions are $V_{DD}$ = 5.0 V, $T_A$ = 25 °C, CPU = 24 MHz, IMO = 24 MHz USB Active, No I <sup>2</sup> C/SPI.	-	7.1	_	mA
I <sub>DD12,5</sub>	Supply current, CPU = 12 MHz	Conditions are $V_{DD}$ = 5.0 V, $T_A$ = 25 °C, CPU = 12 MHz, IMO = 24 MHz USB Active, No I <sup>2</sup> C/SPI.	-	6.2	_	mA
I <sub>DD6,5</sub>	Supply current, CPU = 6 MHz	Conditions are $V_{DD}$ = 5.0 V, $T_A$ = 25 °C, CPU = 6 MHz, IMO = 24 MHz USB Active, No I <sup>2</sup> C/SPI	-	5.8	_	mA
I <sub>SB1,5</sub>	Standby current with POR, LVD, and sleep timer	$V_{\rm DD}$ = 5.0 V, $T_{\rm A}$ = 25 °C, I/O regulator turned off.	_	1.1	_	μΑ
I <sub>SB0,5</sub>	Deep sleep current	$V_{DD}$ = 5.0 V, $T_{A}$ = 25 °C, I/O regulator turned off.		0.1	-	μА
$V_{DDUSB}$	Operating voltage	USB activity, USB regulator bypassed	3.15	3.3	3.60	V

#### Notes

Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 85 °C degrade reliability.

<sup>11.</sup> The temperature rise from ambient to junction is package specific. See Package Handling on page 31. The user must limit the power consumption to comply with this requirement.



Table 7. DC Characteristics – USB Interface

Symbol	Description	Conditions	Min	Тур	Max	Units
Rusbi	USB D+ pull-up resistance	With idle bus	0.900	_	1.575	kΩ
Rusba	USB D+ pull-up resistance	While receiving traffic	1.425	_	3.090	kΩ
Vohusb	Static output high		2.8	_	3.6	V
Volusb	Static output low		_	_	0.3	V
Vdi	Differential input sensitivity		0.2	_	_	V
Vcm	Differential input common mode range		8.0	_	2.5	V
Vse	Single-ended receiver threshold		8.0	_	2.0	V
Cin	Transceiver capacitance			_	50	pF
lio	High Z state data Line Leakage	On D+ or D– line	-10	_	+10	μΑ
Rps2	PS/2 Pull Up Resistance		3	5	7	kΩ
Rext	External USB Series Resistor	In series with each USB pin	21.78	22.0	22.22	Ω

#### ADC Electrical Specifications

**Table 8. ADC User Module Electrical Specifications** 

Symbol	Description	Conditions	Min	Тур	Max	Units
Input	•		•		•	
V <sub>IN</sub>	Input voltage range		0	_	VREFADC	V
C <sub>IIN</sub>	Input capacitance		_	_	5	pF
R <sub>IN</sub>	Input resistance	Equivalent switched cap input resistance for 8-, 9-, or 10-bit resolution	1/(500fF* Data Clock)	1/(400fF* Data Clock)	1/(300fF* Data Clock)	Ω
Reference	·			•		
V <sub>REFADC</sub>	ADC reference voltage		1.14	_	1.26	V
Conversion Rate			1			
F <sub>CLK</sub>	Data clock	Source is chip's internal main oscillator. See AC Chip-Level Specifications for accuracy	2.25	_	6	MHz
S8	8-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2^Resolution/Data Clock)	_	23.4375	_	ksps
S10	10-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2^Resolution/Data Clock)	_	5.859	_	ksps
DC Accuracy			1	l	•	
RES	Resolution	Can be set to 8-, 9-, or 10-bit	8	_	10	bits
DNL	Differential nonlinearity		-1	_	+2	LSB
INL	Integral nonlinearity		-2	_	+2	LSB
E <sub>Offset</sub>	Offset error	8-bit resolution	0	3.2	19.2	LSB
		10-bit resolution	0	12.8	76.8	LSB
E <sub>gain</sub>	Gain error	For any resolution	-5	_	+5	%FSR
Power	•	•	•	•	•	
I <sub>ADC</sub>	Operating current		_	2.1	2.6	mA
PSRR	Power supply rejection ratio	PSRR (V <sub>DD</sub> > 3.0 V)	_	24	-	dB
		PSRR (V <sub>DD</sub> < 3.0 V)	_	30	-	dB

Document Number: 001-12394 Rev. \*T



#### DC General Purpose I/O Specifications

Table 9 lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 3.0 V to 5.5 V and package specific temperature range. Typical parameters apply to 5 V and 3.3 V at  $25 \,^{\circ}\text{C}$ . These are for design guidance only.

Table 9. 3.0 V and 5.5 V DC GPIO Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
R <sub>PU</sub>	Pull-up resistor		4	5.6	8	kΩ
V <sub>OH1</sub>	High output voltage Port 2 or 3 pins	I <sub>OH</sub> ≤ 10 μA, maximum of 10 mA source current in all I/Os.	V <sub>DD</sub> – 0.2	_	_	V
V <sub>OH2</sub>	High output voltage Port 2 or 3 Pins	I <sub>OH</sub> = 1 mA, maximum of 20 mA source current in all I/Os.	V <sub>DD</sub> – 0.9	_	_	V
V <sub>OH3</sub>	High output voltage Port 0 or 1 pins with LDO regulator disabled	$I_{OH}$ < 10 $\mu$ A, maximum of 10 mA source current in all I/Os.	V <sub>DD</sub> – 0.2	-	_	V
V <sub>OH4</sub>	High output voltage Port 0 or 1 pins with LDO regulator disabled	I <sub>OH</sub> = 5 mA, maximum of 20 mA source current in all I/Os.	V <sub>DD</sub> – 0.9	-	_	V
V <sub>OH5</sub>	High output voltage Port 1 pins with LDO regulator enabled for 3 V Out	$I_{OH}$ < 10 $\mu$ A, $V_{DD}$ > 3.1 V, maximum of 4 I/Os all sourcing 5 mA	2.85	3.00	3.3	V
V <sub>OH6</sub>	High output voltage Port 1 pins with LDO regulator enabled for 3 V out	I <sub>OH</sub> = 5 mA, V <sub>DD</sub> > 3.1 V, maximum of 20 mA source current in all I/Os	2.20	ı	ı	V
V <sub>OH7</sub>	High output voltage Port 1 pins with LDO enabled for 2.5 V out	$I_{OH}$ < 10 $\mu$ A, $V_{DD}$ > 3.0 V, maximum of 20 mA source current in all I/Os	2.35	2.50	2.75	V
V <sub>OH8</sub>	High output voltage Port 1 pins with LDO enabled for 2.5 V out	I <sub>OH</sub> = 2 mA, V <sub>DD</sub> > 3.0 V, maximum of 20 mA source current in all I/Os	1.90	ı	_	V
V <sub>OH9</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	$I_{OH}$ < 10 $\mu$ A, $V_{DD}$ > 3.0 V, maximum of 20 mA source current in all I/Os	1.60	1.80	2.1	V
V <sub>OH10</sub>	High output voltage Port 1 pins with LDO enabled for 1.8 V out	I <sub>OH</sub> = 1 mA, V <sub>DD</sub> > 3.0 V, maximum of 20 mA source current in all I/Os	1.20	_	-	V
V <sub>OL</sub>	Low output voltage	I <sub>OL</sub> = 25 mA, V <sub>DD</sub> > 3.3 V, maximum of 60 mA sink current on even port pins (for example, P0[2] and P1[4]) and 60 mA sink current on odd port pins (for example, P0[3] and P1[5]).	-	ı	0.75	V
V <sub>IL</sub>	Input low voltage		_	_	8.0	V
V <sub>IH</sub>	Input high voltage		2.0	_	-	V
$V_{H}$	Input hysteresis voltage		_	80	_	mV
I <sub>IL</sub>	Input leakage (absolute value)		_	0.001	1	μΑ
C <sub>PIN</sub>	Pin capacitance	Package and pin dependent. Temp = 25 °C.	0.5	1.7	5	pF



#### **AC Electrical Characteristics**

AC Chip Level Specifications

The following tables list guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 12. AC Chip Level Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
F <sub>CPU</sub>	Processing frequency <sup>[16]</sup>		5.7	-	25.2	MHz
F <sub>32K1</sub>	Internal low-speed oscillator (ILO) frequency	Trimmed <sup>[17]</sup>	19	32	50	kHz
F <sub>32K_U</sub>	ILO untrimmed frequency)		13	32	82	kHz
F <sub>32K2</sub>	ILO frequency	Untrimmed	13	32	82	kHz
F <sub>IMO24</sub>	Internal main oscillator (IMO) stability for 24 MHz ± 5% <sup>(12)</sup>		22.8	24	25.2	MHz
F <sub>IMO12</sub>	IMO stability for 12 MHz <sup>[17]</sup>		11.4	12	12.6	MHz
F <sub>IMO6</sub>	IMO stability for 6 MHz <sup>[17]</sup>		5.7	6.0	6.3	MHz
DC <sub>IMO</sub>	Duty cycle of IMO		40	50	60	%
DC <sub>ILO</sub>	ILO duty cycle		40	50	60	%
SR <sub>POWER_UP</sub>	Power supply slew rate		-	-	250	V/ms
T <sub>XRST</sub>	External reset pulse width at power-up	After supply voltage is valid	1	_	-	ms
T <sub>XRST2</sub>	External reset pulse width after power-up <sup>[18]</sup>	Applies after part has booted	10	_	_	μ\$

Table 13. AC Characteristics – USB Data Timings

Symbol	Description	Conditions	Min	Тур	Max	Units
Tdrate	Full speed data rate	Average bit rate	11.97	12	12.03	MHz
Tdjr1	Receiver data jitter tolerance	To next transition	-18.5	_	18.5	ns
Tdjr2	Receiver data jitter tolerance	To pair transition	-9	_	9	ns
Tudj1	Driver differential jitter	To next transition	-3.5	_	3.5	ns
Tudj2	Driver differential jitter	To pair transition	-4.0	_	4.0	ns
Tfdeop	Source jitter for differential transition	To SE0 transition	-2	_	5	ns
Tfeopt	Source SE0 interval of EOP		160	_	175	ns
Tfeopr	Receiver SE0 interval of EOP		82	_	_	ns
Tfst	Width of SE0 interval during differential transition		-	_	14	ns

Table 14. AC Characteristics - USB Driver

Symbol	Description	Conditions	Min	Тур	Max	Units
Tr	Transition rise time	50 pF	4	_	20	ns
Tf	Transition fall time	50 pF	4	_	20	ns
TR <sup>[19]</sup>	Rise/fall time matching		90.00	_	111.1	%
Vcrs	Output signal crossover voltage		1.3	_	2.0	V

 <sup>16.</sup> V<sub>DD</sub> = 3.0 V and T<sub>J</sub> = 85 °C, CPU speed.
 17. Trimmed for 3.3 V operation using factory trim values.
 18. The minimum required XRES pulse length is longer when programming the device (see Table 17 on page 24).
 19. Errata: Rising to falling rate matching of the USB D+ and D- lines has a corner case issue when operating voltage is below 3.3 V. Refer to "Errata" on page 35 for more details.



#### AC General Purpose I/O Specifications

Table 15 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 15. AC GPIO Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
F <sub>GPIO</sub>	GPIO operating frequency	Normal strong mode, Ports 0, 1	_	-	12	MHz
TRise23	Rise time, strong mode Ports 2, 3	V <sub>DD</sub> = 3.0 to 3.6 V, 10% - 90%	15	_	80	ns
TRise01	Rise time, strong mode Ports 0, 1	V <sub>DD</sub> = 3.0 to 3.6 V, 10% - 90%	10	_	50	ns
TFall	Fall time, strong mode All Ports	V <sub>DD</sub> = 3.0 to 3.6 V, 10% - 90%	10	_	50	ns

TFall

Figure 11. GPIO Timing Diagram

### AC External Clock Specifications

Table 16 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

TRise23 TRise01

90%

GPIO Pin Output Voltage

Table 16. AC External Clock Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
F <sub>OSCEXT</sub>	Frequency		0.750	-	25.2	MHz
_	High period		20.6	-	5300	ns
_	Low period		20.6	-	_	ns
_	Power-up IMO to switch		150	_	_	μS

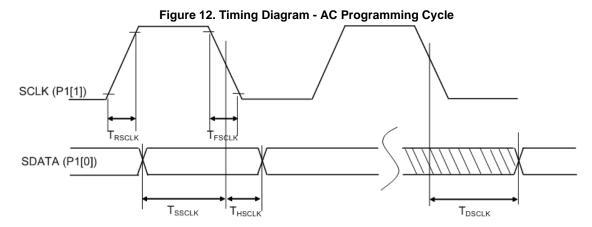


#### AC Programming Specifications

Table 17 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

**Table 17. AC Programming Specifications** 

Symbol	Description	Conditions	Min	Тур	Max	Units
T <sub>RSCLK</sub>	Rise time of SCLK		1	_	20	ns
T <sub>FSCLK</sub>	Fall time of SCLK		1	_	20	ns
T <sub>SSCLK</sub>	Data setup time to falling edge of SCLK		40	_	-	ns
T <sub>HSCLK</sub>	Data hold time from falling edge of SCLK		40	_	-	ns
F <sub>SCLK</sub>	Frequency of SCLK		0	_	8	MHz
T <sub>ERASEB</sub>	Flash erase time (Block)		-	_	18	ms
T <sub>WRITE</sub>	Flash block write time		-	_	25	ms
T <sub>DSCLK1</sub>	Data out delay from falling edge of SCLK,	V <sub>DD</sub> > 3.6 V	-	_	60	ns
T <sub>DSCLK2</sub>	Data out delay from falling edge of SCLK	3.0 V < V <sub>DD</sub> < 3.6 V	-	_	85	ns
T <sub>XRST3</sub>	External reset pulse width after power-up	Required to enter programming mode when coming out of sleep	263	_	_	μS





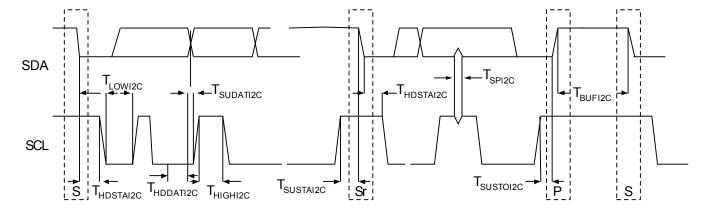
#### AC I<sup>2</sup>C Specifications

Table 18 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 18. AC Characteristics of the I<sup>2</sup>C SDA and SCL Pins

Cumbal	Decembries	Standar	d Mode	Fast	Mode	Units
Symbol	Description	Min	Max	Min	Max	Units
F <sub>SCLI2C</sub>	SCL clock frequency	0	100	0	400	kHz
T <sub>HDSTAI2C</sub>	Hold time (repeated) START condition. After this period, the first clock pulse is generated	4.0	_	0.6	_	μS
T <sub>LOWI2C</sub>	LOW period of the SCL clock	4.7	-	1.3	_	μS
T <sub>HIGHI2C</sub>	HIGH period of the SCL clock	4.0	-	0.6	_	μS
T <sub>SUSTAI2C</sub>	Setup time for a repeated START condition		-	0.6	_	μS
T <sub>HDDATI2C</sub>	Data hold time	0	-	0	_	μS
T <sub>SUDATI2C</sub>	Data setup time	250	-	100 <sup>[20]</sup>	_	ns
T <sub>SUSTOI2C</sub>	Setup time for STOP condition		-	0.6	_	μS
T <sub>BUFI2C</sub>	Bus free time between a STOP and START condition	4.7	_	1.3	_	μS
T <sub>SPI2C</sub>	Pulse width of spikes are suppressed by the input filter	_	_	0	50	ns

Figure 13. Definition of Timing for Fast/Standard Mode on the I<sup>2</sup>C Bus



#### Note

<sup>20.</sup> A Fast mode I²C bus device can be used in a standard mode I²C bus system, but the requirement t<sub>SUDAT</sub> ≥ 250 ns must then be met. This is automatically the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line t<sub>rmax</sub> + t<sub>SUDAT</sub> = 1000 + 250 = 1250 ns (according to the standard mode I²C bus specification) before the SCL line is released.



Table 19. SPI Master AC Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
F <sub>SCLK</sub>	SCLK clock frequency		_	_	6	MHz
DC	SCLK duty cycle		_	50	_	%
T <sub>SETUP</sub>	MISO to SCLK setup time		60	_	_	ns
T <sub>HOLD</sub>	SCLK to MISO hold time		40	_	-	ns
T <sub>OUT_VAL</sub>	SCLK to MOSI valid time		_	_	40	ns
T <sub>OUT_H</sub>	SCLK to MOSI hold time		40	-	1	ns

Figure 14. SPI Master Mode 0 and 2

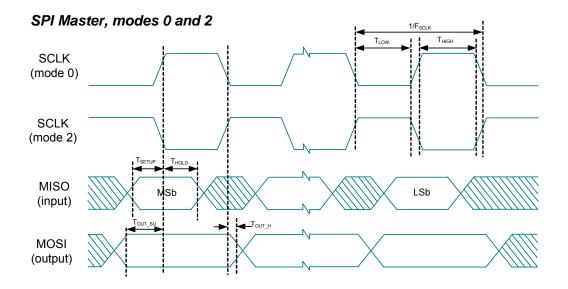


Figure 15. SPI Master Mode 1 and 3

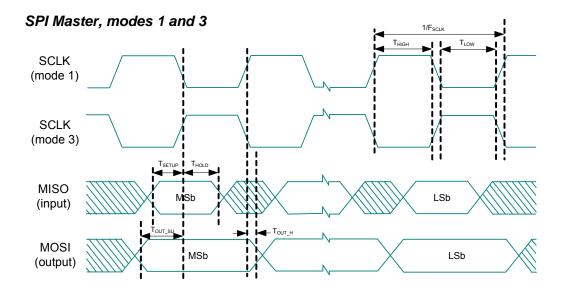




Table 20. SPI Slave AC Specifications

Symbol	Description	Conditions	Min	Тур	Max	Units
F <sub>SCLK</sub>	SCLK clock frequency		0.0469	_	12	MHz
T <sub>LOW</sub>	SCLK low time		41.67	_	_	ns
T <sub>HIGH</sub>	SCLK high time		41.67	_	_	ns
T <sub>SETUP</sub>	MOSI to SCLK setup time		30	_	_	ns
T <sub>HOLD</sub>	SCLK to MOSI hold time		50	_	_	ns
T <sub>SS_MISO</sub>	SS low to MISO valid		_	_	153	ns
T <sub>SCLK_MISO</sub>	SCLK to MISO valid		_	_	125	ns
T <sub>SS_HIGH</sub>	SS high time		50	_	_	ns
T <sub>SS_CLK</sub>	Time from SS low to first SCLK		2/F <sub>SCLK</sub>	_	_	ns
T <sub>CLK_SS</sub>	Time from last SCLK to SS high		2/F <sub>SCLK</sub>	_	_	ns

Figure 16. SPI Slave Mode 0 and 2

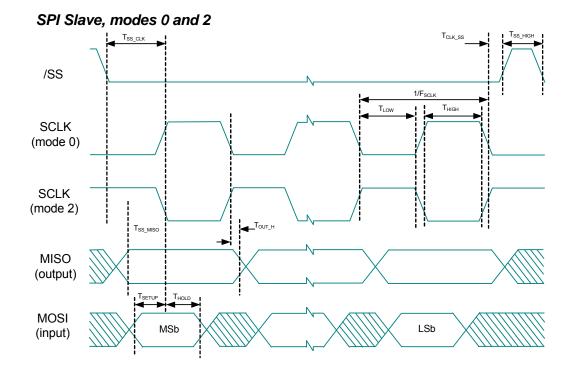
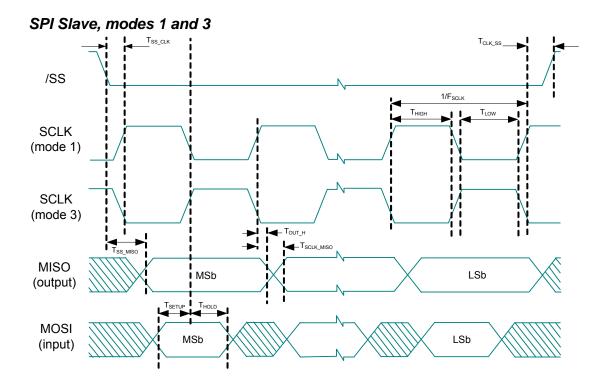




Figure 17. SPI Slave Mode 1 and 3





#### **Package Handling**

Some IC packages require baking before they are soldered onto a PCB to remove moisture that may have been absorbed after leaving the factory. A label on the package has details about the actual bake temperature and the minimum bake time to remove this moisture. The maximum bake time is the aggregate time that the parts exposed to the bake temperature. Exceeding this exposure may degrade device reliability.

Table 21. Package Handling

Parameter	Description Minimum Typical		Maximum	Unit	
TBAKETEMP	Bake temperature	-	125	See package label	°C
TBAKETIME	Bake time	See package label	_	72	hours

#### **Thermal Impedances**

#### Table 22. Thermal Impedances per Package

Package	Typical θ <sub>JA</sub> <sup>[21]</sup>
16-pin QFN	32.69 °C / W
32-pin QFN <sup>[22]</sup>	19.51 °C / W
48-pin QFN <sup>[22]</sup>	17.68 °C / W

#### **Capacitance on Crystal Pins**

#### Table 23. Typical Package Capacitance on Crystal Pins

Package	Package Capacitance
32-pin QFN	3.2 pF
48-pin QFN	3.3 pF

#### **Solder Reflow Peak Temperature**

Following is the minimum solder reflow peak temperature to achieve good solderability.

#### Table 24. Solder Reflow Peak Temperature

Package	Minimum Peak Temperature [23]	Maximum Peak Temperature
16-pin QFN	240 °C	260 °C
32-pin QFN	240 °C	260 °C
48-pin QFN	240 °C	260 °C

21. T<sub>J</sub> = T<sub>A</sub> + Power x θ<sub>JA</sub>.
22. To achieve the thermal impedance specified for the package, solder the center thermal pad to the PCB ground plane.

23. Higher temperatures may be required based on the solder melting point. Typical temperatures for solder are 220 ± 5 °C with Sn-Pb or 245 ± 5 °C with Sn-Ag-Cu paste. Refer to the solder manufacturer specifications.



# **Ordering Information**

Table 25. Ordering Code - Commercial Parts

Ordering Code	Package Information	Flash (KB)	SRAM (KB)	No. of GPIOs	Target Applications
CY7C64315-16LKXC	16-pin QFN (3 × 3 mm)	16	1	11	Mid-tier Full-Speed USB dongle, Remote Control Host Module, Various
CY7C64315-16LKXCT	16-pin QFN (Tape and Reel), (3 × 3 mm)	16	1	11	Mid-tier Full-Speed USB dongle, Remote Control Host Module, Various
CY7C64316-16LKXC	16-pin QFN (3 × 3 mm)	32	2	11	Feature-rich Full-Speed USB dongle, Remote Control Host Module, Various
CY7C64316-16LKXCT	16-pin QFN (Tape and Reel), (3 × 3 mm)	32	2	11	Feature-rich Full-Speed USB dongle, Remote Control Host Module, Various
CY7C64343-32LQXC	32-pin QFN (5 × 5 mm)	8	1	25	Full-Speed USB mouse, Various
CY7C64343-32LQXCT	32-pin QFN (Tape and Reel), (5 × 5 mm)	8	1	25	Full-Speed USB mouse, Various
CY7C64345-32LQXC	32-pin QFN (5 × 5 mm)	16	1	25	Full-Speed USB mouse, Various
CY7C64345-32LQXCT	32-pin QFN (Tape and Reel), (5 × 5 mm)	16	1	25	Full-Speed USB mouse, Various
CY7C64346-32LQXCT	32-pin QFN (Tape and Reel), (5 × 5 mm)	32	1	25	Full-Speed USB keyboard, Various
CY7C64355-48LTXC	48-pin QFN (7 × 7 mm)	16	1	36	Full-Speed USB keyboard, Various
CY7C64355-48LTXCT	48-pin QFN (Tape and Reel), (7 × 7 mm)	16	1	36	Full-Speed USB keyboard, Various
CY7C64356-48LTXC	48-pin QFN (7 × 7 mm)	32	2	36	Feature-rich Full-Speed USB keyboard, Various
CY7C64356-48LTXCT	48-pin QFN (Tape and Reel), (7 × 7 mm)	32	2	36	Feature-rich Full-Speed USB keyboard, Various

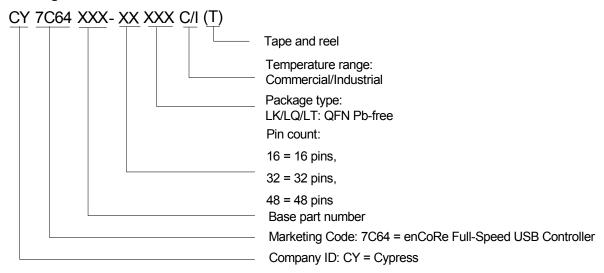
Table 26. Ordering Code - Industrial Parts

Ordering Code	Package Information	Flash (KB)	SRAM (KB)	No. of GPIOs	Target Applications
CY7C64315-16LKXI	16-pin QFN, Industrial (3 × 3 mm)	16	1	11	Mid-tier Full-Speed USB dongle, Remote Control Host Module, Various
CY7C64315-16LKXIT	16-pin QFN, Industrial (Tape and Reel), (3 × 3 mm)	16	1	11	Mid-tier Full-Speed USB dongle, Remote Control Host Module, Various

Document Number: 001-12394 Rev. \*T



#### **Ordering Code Definitions**





#### **Errata**

This section describes the errata for the enCoRe V – CY7C643xx. Details include errata trigger conditions, scope of impact, available workaround, and silicon revision applicability.

Contact your local Cypress Sales Representative if you have questions.

#### CY7C643xx Errata Summary

The following Errata item applies to the CY7C643xx data sheets.

1. Latch up susceptibility when maximum I/O sink current exceeded

#### **■PROBLEM DEFINITION**

P1[3], P1[6], and P1[7] pins are susceptible to latch up when the I/O sink current exceeds 25 mA per pin on these pins.

#### **■PARAMETERS AFFECTED**

LU – Latch up current. Per JESD78A, the maximum allowable latch up current per pin is 100 mA. Cypress internal specification is 200 mA latch up current limit.

#### **■TRIGGER CONDITIONS**

Latch up occurs when both the following conditions are met:

- A.The offending I/O is externally connected to a voltage higher than the I/O high state, causing a current to flow into the pin that exceeds 25 mA.
- B.A Port1 I/O (P1[1], P1[4], and P1[5] respectively) adjacent to the offending I/O is connected to a voltage lower than the I/O low state. This causes a signal that drops below Vss (signal undershoot) and a current greater than 200 mA to flow out of the pin.

#### **■SCOPE OF IMPACT**

The trigger conditions outlined in this item exceed the maximum ratings specified in the CY7C643xx data sheets.

#### **■WORKAROUND**

Add a series resistor > 300  $\Omega$  to P1[3], P1[6], and P1[7] pins to restrict current to within latch up limits.

#### **■FIX STATUS**

This issue will be corrected in the next new silicon revision.

# 2. Does not meet USB 2.0 specification for D+ and D- rise/fall matching when supply voltage is under 3.3 V ■PROBLEM DEFINITION

Rising to falling rate matching of the USB D+ and D- lines has a corner case at lower supply voltages, such as those under 3.3 V.

#### **■PARAMETERS AFFECTED**

Rising to falling rate matching of the USB data lines.

#### **■TRIGGER CONDITION(S)**

Operating the VCC supply voltage at the low end of the chip's specification (under 3.3 V) may cause a mismatch in the rising to falling rate.

#### **■SCOPE OF IMPACT**

This condition does not affect USB communications but could cause corner case issues with USB lines' rise/fall matching specification. Signal integrity tests were run using the Cypress development kit and excellent eye was observed with supply voltage of 3.15 V.



# **Document History Page** (continued)

	t Title: CY7C t Number: 00		C6434x/CY7C6	435x, enCoRe™ V Full Speed USB Controller
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change
*F	2583853	TYJ/ PYRS/ HMT	10/10/08	Converted from Preliminary to Final Added operating voltage ranges with USB ADC resolution changed from 10-bit to 8-bit Rephrased battery monitoring clause in page 1 to include "with external components" Included ADC specifications table Included Voh7, Voh8, Voh9, Voh10 specs Flash data retention – condition added to Note [11] Input leakage spec changed to 25 nA max Under AC Char, Frequency accuracy of ILO corrected GPIO rise time for ports 0,1 and ports 2,3 made common AC Programming specifications updated Included AC Programming cycle timing diagram AC SPI specification updated Spec change for 32-QFN package Input Leakage Current maximum value changed to 1 µA Updated V <sub>OHV</sub> parameter in Table 13 Updated thermal impedances for the packages Update Development Tools, add Designing with PSoC Designer. Edit, fix link and table format. Update TMs.
*G	2653717	DVJA / PYRS	02/04/09	Updated Features, Functional Overview, Development Tools, and Designing with PSoC Designer sections with edits.  Removed 'GUI - graphical user interface' from Document Conventions acronym table.  Removed 'O - Only a read/write register or bits' in Table 4  Edited Table 8: removed 10-bit resolution information and corrected units column.  Added package handling section  Added 8K part 'CY7C64343-32LQXC' to Ordering Information.
*Н	2714694	DVJA / AESA	06/04/2009	Updated Block Diagram. Added Full Speed USB, 10-bit ADC, SPI, and I2C Slave sections. ADC Resolution changed from 8-bit to 10-bit Updated Table 9 DC Chip Level Specs Updated Table10 DC Char - USB Interface Updated Table 12 DC POR and LDV Specs Changed operating temperature from Commercial to Industrial Changed Temperature Range to Industrial: –40 to 85°C Figure 9: Changed minimum CPU Frequency from 750 kHz to 5.7 MHz Table 14: Removed "Maximum" from the F <sub>CPU</sub> description Ordering Information: Replaced 'C' with 'I' in all part numbers to denote Industrial Temp Range
*	2764460	DVJA / AESA	09/16/2009	Changed Table 12: ADC Specs Added F <sub>32K2</sub> (Untrimmed) spec to Table 16: AC Chip level Specs Changed T <sub>RAMP</sub> spec to SR <sub>POWER UP</sub> in Table 16: AC Chip Level Specs Added Table 27: Typical Package Capacitance on Crystal Pins
*J	2811903	DVJA	11/20/2009	Added USB-IF TID number in Features on page 1. Added Note 5 on page 1. Changed $V_{\rm IHP}$ in Table 12 on page 22.



# **Document History Page** (continued)

	t Title: CY7C t Number: 00		C6434x/CY7C6	435x, enCoRe™ V Full Speed USB Controller
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change
*S	4578605	GINS	12/11/2014	Updated Pin Information: Updated 32-pin part pinout: Updated Figure 7 (No change in figure, included CY7C64346 in figure caption) Updated Package Diagrams: spec 001-09116 – Changed revision from *I to *J.  Updated Ordering Information: Updated Table 25: Updated part numbers.
*T	5548557	ANKC	12/12/2016	Updated Cypress Logo, Sales Page and Disclaimer.  Updated Figure 20 (spec 001-13191 *G to *H) in Package Diagrams.  Removed the following obsolete part numbers (Table 26) in Ordering Information: CY7C64343-32LQXI, CY7C64343-32LQXIT, CY7C64345-32LQXI, CY7C64356-48LTXI, CY7C64356-48LTXIT.