



Welcome to [E-XFL.COM](#)

[Embedded - Microcontrollers - Application Specific](#): Tailored Solutions for Precision and Performance

[Embedded - Microcontrollers - Application Specific](#) represents a category of microcontrollers designed with unique features and capabilities tailored to specific application needs. Unlike general-purpose microcontrollers, application-specific microcontrollers are optimized for particular tasks, offering enhanced performance, efficiency, and functionality to meet the demands of specialized applications.

What Are [Embedded - Microcontrollers - Application Specific](#)?

Application specific microcontrollers are engineered to

Details

Product Status	Active
Applications	USB Microcontroller
Core Processor	M8C
Program Memory Type	FLASH (32kB)
Controller Series	CY7C643xx
RAM Size	2K x 8
Interface	I ² C, SPI, USB
Number of I/O	36
Voltage - Supply	3V ~ 5.5V
Operating Temperature	0°C ~ 70°C
Mounting Type	Surface Mount
Package / Case	48-VFQFN Exposed Pad
Supplier Device Package	48-QFN (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy7c64356-48ltxc

Contents

Functional Overview	3	Register Conventions	13
The enCoRe V Core	3	Register Mapping Tables	13
Full-Speed USB	3	Electrical Specifications	16
10-bit ADC	4	Absolute Maximum Ratings	17
SPI	4	Operating Temperature	17
I2C Slave	5	DC Electrical Characteristics	18
Additional System Resources	6	AC Electrical Characteristics	22
Getting Started	6	Package Diagram	29
Application Notes	6	Packaging Dimensions	29
Development Kits	6	Package Handling	31
Training	6	Thermal Impedances	31
CYPros Consultants	6	Capacitance on Crystal Pins	31
Solutions Library	6	Solder Reflow Peak Temperature	31
Technical Support	6	Ordering Information	32
Development Tools	7	Ordering Code Definitions	33
PSoC Designer Software Subsystems	7	Acronyms	34
Designing with PSoC Designer	8	Document Conventions	34
Select User Modules	8	Units of Measure	34
Configure User Modules	8	Numeric Naming	34
Organize and Connect	8	Errata	35
Generate, Verify, and Debug	8	CY7C643xx Errata Summary	35
Pin Information	9	Document History Page	37
16-pin part pinout	9	Sales, Solutions, and Legal Information	41
Pin Definitions	9	Worldwide Sales and Design Support	41
32-pin part pinout	10	Products	41
Pin Definitions	10	PSoC® Solutions	41
48-pin Part Pinout	11	Cypress Developer Community	41
Pin Definitions	11	Technical Support	41
Register Reference	13		

Functional Overview

The enCoRe V family of devices are designed to replace multiple traditional full-speed USB microcontroller system components with one, low cost single-chip programmable component. Communication peripherals (I²C/SPI), a fast CPU, Flash program memory, SRAM data memory, and configurable I/O are included in a range of convenient pinouts.

The architecture for this device family, as illustrated in the [enCoRe V Block Diagram on page 1](#), consists of two main areas: the CPU core and the system resources. Depending on the enCoRe V package, up to 36 GPIO are also included.

This product is an enhanced version of Cypress's successful full speed-USB peripheral controllers. Enhancements include faster CPU at lower voltage operation, lower current consumption, twice the RAM and Flash, hot-swappable I/Os, I²C hardware address recognition, new very low current sleep mode, and new package options.

The enCoRe V Core

The enCoRe V Core is a powerful engine that supports a rich instruction set. It encompasses SRAM for data storage, an interrupt controller, sleep and watchdog timers, and IMO and ILO. The CPU core, called the M8C, is a powerful processor with speeds up to 24 MHz. The M8C is a four-MIPS, 8-bit Harvard architecture microprocessor.

During USB operation, the CPU speed can be set to any setting. Be aware that USB throughput decreases with a decrease in CPU speed. For maximum throughput, the CPU clock should be made equal to the system clock. The system clock must be 24 MHz for USB operation.

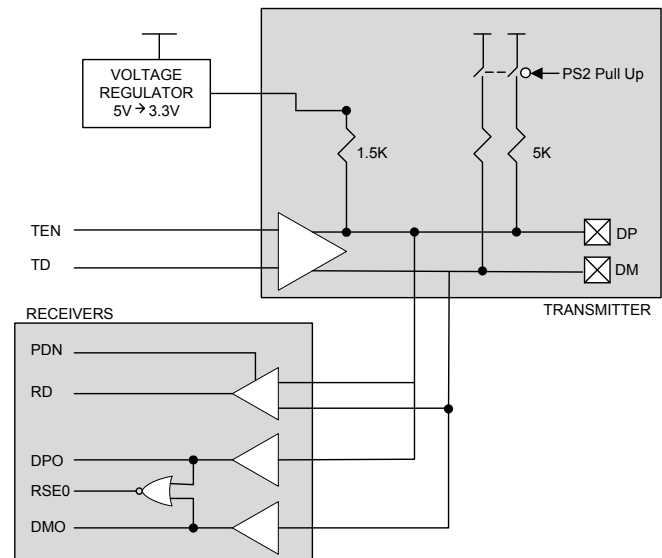
System resources provide additional capability, such as a configurable I²C slave and SPI master-slave communication interface and various system resets supported by the M8C.

Full-Speed USB

The enCoRe V USB system resource adheres to the USB 2.0 Specification for full speed devices operating at 12 Mb/second with one upstream port and one USB address. enCoRe V USB consists of these components:

- Serial interface engine (SIE) block.
- PSoC memory arbiter (PMA) block.
- 512 bytes of dedicated SRAM.
- A full-speed USB Transceiver with internal regulator and two dedicated USB pins.

Figure 1. USB Transceiver Regulator



At the enCoRe V system level, the full-speed USB system resource interfaces to the rest of the enCoRe V by way of the M8C's register access instructions and to the outside world by way of the two USB pins. The SIE supports nine endpoints including a bidirectional control endpoint (endpoint 0) and eight unidirectional data endpoints (endpoints 1 to 8). The unidirectional data endpoints are individually configurable as either IN or OUT.

Low value series resistors R_{EXT} (22 Ω) must be added externally to the D+ and D- lines to meet the driving impedance requirement for full-speed USB.

The USB Serial Interface Engine (SIE) allows the enCoRe V device to communicate with the USB host at full speed data rates (12 Mb/s). The SIE simplifies the interface to USB traffic by automatically handling the following USB processing tasks without firmware intervention:

- Translates the encoded received data and formats the data to be transmitted on the bus.
- Generates and checks cyclical redundancy checks (CRCs). Incoming packets failing checksum verification are ignored.
- Checks addresses. Ignores all transactions not addressed to the device.
- Sends appropriate ACK/NAK/Stall handshakes.
- Identifies token type (SETUP, IN, OUT) and sets the appropriate token bit once a valid token is received.
- Identifies Start-of-Frame (SOF) and saves the frame count.
- Sends data to or retrieves data from the USB SRAM, by way of the PSoC Memory Arbiter (PMA).

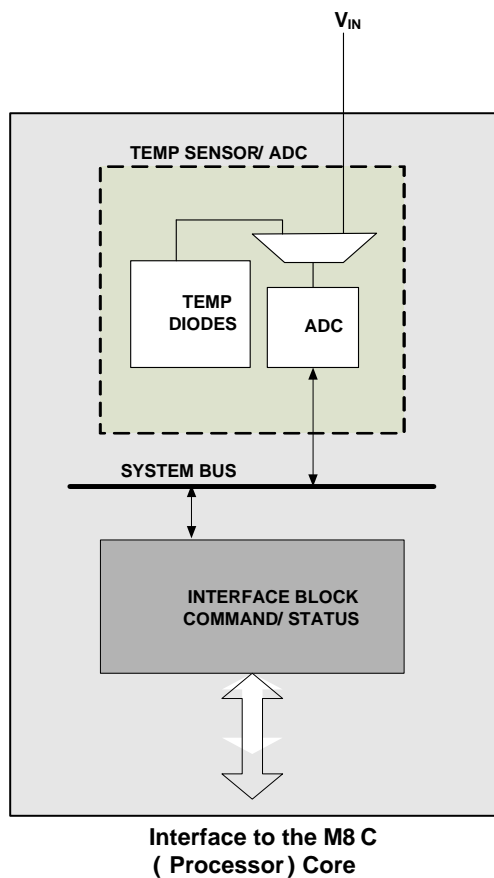
Firmware is required to handle various parts of the USB interface. The SIE issues interrupts after key USB events to direct firmware to appropriate tasks:

- Fill and empty the USB data buffers in USB SRAM.
- Enable PMA channels appropriately.
- Coordinate enumeration by decoding USB device requests.
- Suspend and resume coordination.
- Verify and select data toggle values.

10-bit ADC

The ADC on enCoRe V device is an independent block with a state machine interface to control accesses to the block. The ADC is housed together with the temperature sensor core and can be connected to this or the Analog mux bus. As a default operation, the ADC is connected to the temperature sensor diodes to give digital values of the temperature.

Figure 2. ADC System Performance Block Diagram



The ADC User Module contains an integrator block and one comparator with positive and negative input set by the MUXes. The input to the integrator stage comes from the analog global

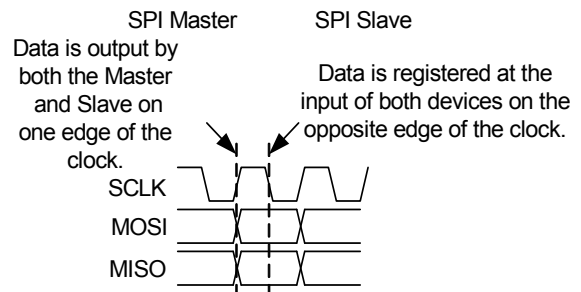
input mux or the temperature sensor with an input voltage range of 0 V to V_{REFADC} .

In the ADC only configuration (the ADC MUX selects the Analog mux bus, not the default temperature sensor connection), an external voltage can be connected to the input of the modulator for voltage conversion. The ADC is run for a number of cycles set by the timer, depending upon the desired resolution of the ADC. A counter counts the number of trips by the comparator, which is proportional to the input voltage. The Temp Sensor block clock speed is 36 MHz and is divided down to 1 to 12 MHz for ADC operation.

SPI

The serial peripheral interconnect (SPI) 3-wire protocol uses both edges of the clock to enable synchronous communication without the need for stringent setup and hold requirements.

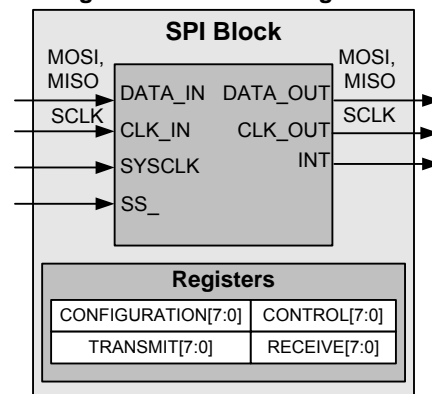
Figure 3. Basic SPI Configuration



A device can be a master or slave. A master outputs clock and data to the slave device and inputs slave data. A slave device inputs clock and data from the master device and outputs data for input to the master. Together, the master and slave are essentially a circular Shift register, where the master generates the clocking and initiates data transfers.

A basic data transfer occurs when the master sends eight bits of data, along with eight clocks. In any transfer, both master and slave transmit and receive simultaneously. If the master only sends data, the received data from the slave is ignored. If the master wishes to receive data from the slave, the master must send dummy bytes to generate the clocking for the slave to send data back.

Figure 4. SPI Block Diagram



Additional System Resources

System resources, some of which have been previously listed, provide additional capability useful to complete systems. Additional resources include low voltage detection and power on reset. The following statements describe the merits of each system resource.

- Low voltage detection (LVD) interrupts can signal the application of falling voltage levels, while the advanced POR (power on reset) circuit eliminates the need for a system supervisor.
- The 5 V maximum input, 1.8, 2.5, or 3 V selectable output, LDO regulator provides regulation for I/Os. A register controlled bypass mode enables the user to disable the LDO.
- Standard Cypress PSoC IDE tools are available for debugging the enCoRe V family of parts.

Getting Started

The quickest path to understanding the enCoRe V silicon is by reading this data sheet and using the PSoC Designer Integrated Development Environment (IDE). This datasheet is an overview of the PSoC integrated circuit and presents specific pin, register, and electrical specifications. For in-depth information, along with detailed programming information, see the *enCoRe™ V CY7C643xx, enCoRe™ V LV CY7C604xx Technical Reference Manual (TRM)* for this PSoC device.

For up-to-date ordering, packaging, and electrical specification information, see the latest PSoC device data sheets on the web at <http://www.cypress.com>.

Application Notes

Application notes are an excellent introduction to the wide variety of possible PSoC designs and are available at <http://www.cypress.com>.

Development Kits

PSoC development kits are available online from Cypress at <http://www.cypress.com> and through a growing number of regional and global distributors, including Arrow, Avnet, Digi-Key, Farnell, Future Electronics, and Newark.

Training

Free PSoC technical training (on demand, webinars, and workshops) is available online at <http://www.cypress.com>. The training covers a wide variety of topics and skill levels to assist you in your designs.

CYPros Consultants

Certified PSoC Consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC Consultant, go to <http://www.cypress.com> and look for CYPros Consultants.

Solutions Library

Visit our growing library of solution-focused designs at <http://www.cypress.com>. Here you can find various application designs that include firmware and hardware design files that enable you to complete your designs quickly.

Technical Support

For assistance with technical issues, search KnowledgeBase articles and forums at <http://www.cypress.com>. If you cannot find an answer to your question, call technical support at 1-800-541-4736.

Development Tools

PSoC Designer™ is the revolutionary Integrated Design Environment (IDE) that you can use to customize PSoC to meet your specific application requirements. PSoC Designer software accelerates system design and time to market. Develop your applications using a library of precharacterized analog and digital peripherals (called user modules) in a drag-and-drop design environment. Then, customize your design by leveraging the dynamically generated application programming interface (API) libraries of code. Finally, debug and test your designs with the integrated debug environment, including in-circuit emulation and standard software debug features. PSoC Designer includes:

- Application editor graphical user interface (GUI) for device and user module configuration and dynamic reconfiguration
- Extensive user module catalog
- Integrated source-code editor (C and assembly)
- Free C compiler with no size restrictions or time limits
- Built-in debugger
- In-circuit emulation
- Built-in support for communication interfaces:
 - Hardware and software I²C slaves and masters
 - Full-speed USB 2.0
 - Up to four full-duplex universal asynchronous receiver/transmitters (UARTs), SPI master and slave, and wireless

PSoC Designer supports the entire library of PSoC 1 devices and runs on Windows XP, Windows Vista, and Windows 7.

PSoC Designer Software Subsystems

Design Entry

In the chip-level view, choose a base device to work with. Then select different onboard analog and digital components that use the PSoC blocks, which are called user modules. Examples of user modules are analog-to-digital converters (ADCs), digital-to-analog converters (DACs), amplifiers, and filters. Configure the user modules for your chosen application and connect them to each other and to the proper pins. Then generate your project. This prepopulates your project with APIs and libraries that you can use to program your application.

The tool also supports easy development of multiple configurations and dynamic reconfiguration. Dynamic reconfiguration makes it possible to change configurations at run time. In essence, this allows you to use more than 100 percent of PSoC's resources for a given application.

Code Generation Tools

The code generation tools work seamlessly within the PSoC Designer interface and have been tested with a full range of debugging tools. You can develop your design in C, assembly, or a combination of the two.

Assemblers. The assemblers allow you to merge assembly code seamlessly with C code. Link libraries automatically use absolute addressing or are compiled in relative mode, and linked with other software modules to get absolute addressing.

C Language Compilers. C language compilers are available that support the PSoC family of devices. The products allow you to create complete C programs for the PSoC family devices. The optimizing C compilers provide all of the features of C, tailored to the PSoC architecture. They come complete with embedded libraries providing port and bus operations, standard keypad and display support, and extended math functionality.

Debugger

PSoC Designer has a debug environment that provides hardware in-circuit emulation, allowing you to test the program in a physical system while providing an internal view of the PSoC device. Debugger commands allow you to read and program and read and write data memory, and read and write I/O registers. You can read and write CPU registers, set and clear breakpoints, and provide program run, halt, and step control. The debugger also allows you to create a trace buffer of registers and memory locations of interest.

Online Help System

The online help system displays online, context-sensitive help. Designed for procedural and quick reference, each functional subsystem has its own context-sensitive help. This system also provides tutorials and links to FAQs and an Online Support Forum to aid the designer.

In-Circuit Emulator

A low-cost, high-functionality In-Circuit Emulator (ICE) is available for development support. This hardware can program single devices.

The emulator consists of a base unit that connects to the PC using a USB port. The base unit is universal and operates with all PSoC devices. Emulation pods for each device family are available separately. The emulation pod takes the place of the PSoC device in the target board and performs full-speed (24-MHz) operation.

Designing with PSoC Designer

The development process for the PSoC device differs from that of a traditional fixed-function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and lowering inventory costs. These configurable resources, called PSoC blocks, have the ability to implement a wide variety of user-selectable functions. The PSoC development process is:

1. Select [user modules](#).
2. Configure user modules.
3. Organize and connect.
4. Generate, verify, and debug.

Select User Modules

PSoC Designer provides a library of prebuilt, pretested hardware peripheral components called user modules. User modules make selecting and implementing peripheral devices, both analog and digital, simple.

Configure User Modules

Each user module that you select establishes the basic register settings that implement the selected function. They also provide parameters and properties that allow you to tailor their precise configuration to your particular application. For example, a Pulse width modulator (PWM) user module configures one or more digital PSoC blocks, one for each eight bits of resolution. Using these parameters, you can establish the pulse width and duty cycle. Configure the parameters and properties to correspond to your chosen application. Enter values directly or by selecting values from drop-down menus. All of the user modules are documented in datasheets that may be viewed directly in PSoC Designer or on the Cypress website. These [user module](#)

[data sheets](#) explain the internal operation of the user module and provide performance specifications. Each datasheet describes the use of each user module parameter, and other information that you may need to successfully implement your design.

Organize and Connect

Build signal chains at the chip level by interconnecting user modules to each other and the I/O pins. Perform the selection, configuration, and routing so that you have complete control over all on-chip resources.

Generate, Verify, and Debug

When you are ready to test the hardware configuration or move on to developing code for the project, perform the “Generate Configuration Files” step. This causes PSoC Designer to generate source code that automatically configures the device to your specification and provides the software for the system. The generated code provides APIs with high-level functions to control and respond to hardware events at run time, and interrupt service routines that you can adapt as needed.

A complete code development environment allows you to develop and customize your applications in C, assembly language, or both.

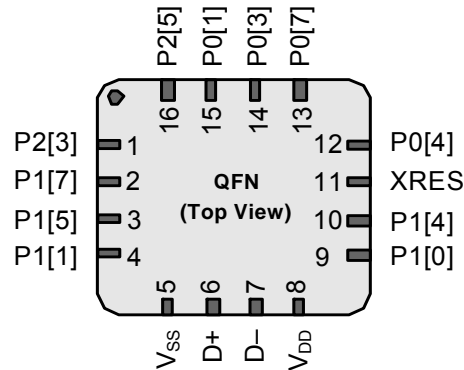
The last step in the development process takes place inside PSoC Designer's Debugger (accessed by clicking the Connect icon). PSoC Designer downloads the HEX image to the ICE where it runs at full speed. PSoC Designer debugging capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint, and watch-variable features, the debug interface provides a large trace buffer. It allows you to define complex breakpoint events that include monitoring address and data bus values, memory locations, and external signals.

Pin Information

The enCoRe V USB device is available in a variety of packages which are listed and illustrated in the subsequent tables.

16-pin part pinout

Figure 6. CY7C64315/CY7C64316 16-pin enCoRe V USB Device



Pin Definitions

16-pin part pinout (QFN)

Pin No.	Type	Name	Description
1	I/O	P2[3]	Digital I/O, crystal input (Xin)
2	I/OHR	P1[7]	Digital I/O, SPI SS, I ² C SCL
3	I/OHR	P1[5]	Digital I/O, SPI MISO, I ² C SDA
4	I/OHR	P1[1] ^[1, 2]	Digital I/O, ISSP CLK, I ² C SCL, SPI MOSI
5	Power	V _{SS}	Ground connection
6	USB line	D+	USB PHY
7	USB line	D-	USB PHY
8	Power	V _{DD}	Supply
9	I/OHR	P1[0] ^[1, 2]	Digital I/O, ISSP DATA, I ² C SDA, SPI CLK
10	I/OHR	P1[4]	Digital I/O, optional external clock input (EXTCLK)
11	Input	XRES	Active high external reset with internal pull-down
12	I/OH	P0[4]	Digital I/O
13	I/OH	P0[7]	Digital I/O
14	I/OH	P0[3]	Digital I/O
15	I/OH	P0[1]	Digital I/O
16	I/O	P2[5]	Digital I/O, crystal output (Xout)

LEGEND I = Input, O = Output, OH = 5 mA High Output Drive, R = Regulated Output

Notes

- During power up or reset event, device P1[0] and P1[1] may disturb the I²C bus. Use alternate pins if issues are encountered.
- These are the in-system serial programming (ISSP) pins that are not High Z at power on reset (POR).

Register Reference

The section discusses the registers of the enCoRe V device. It lists all the registers in mapping tables, in address order.

Register Conventions

The register conventions specific to this section are listed in the following table.

Table 1. Register Conventions

Convention	Description
R	Read register or bits
W	Write register or bits
L	Logical register or bits
C	Clearable register or bits
#	Access is bit specific

Register Mapping Tables

The enCoRe V device has a total register address space of 512 bytes. The register space is also referred to as I/O space and is broken into two parts: Bank 0 (user space) and Bank 1 (configuration space). The XIO bit in the Flag register (CPU_F) determines which bank the user is currently in. When the XIO bit is set, the user is said to be in the “extended” address space or the “configuration” registers.

Table 3. Register Map Bank 1 Table: Configuration Space

Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access	Name	Addr (1, Hex)	Access
PRT0DM0	00	RW	PMA4_RA	40	RW		80			C0	
PRT0DM1	01	RW	PMA5_RA	41	RW		81			C1	
	02		PMA6_RA	42	RW		82			C2	
	03		PMA7_RA	43	RW		83			C3	
PRT1DM0	04	RW	PMA8_WA	44	RW		84			C4	
PRT1DM1	05	RW	PMA9_WA	45	RW		85			C5	
	06		PMA10_WA	46	RW		86			C6	
	07		PMA11_WA	47	RW		87			C7	
PRT2DM0	08	RW	PMA12_WA	48	RW		88			C8	
PRT2DM1	09	RW	PMA13_WA	49	RW		89			C9	
	0A		PMA14_WA	4A	RW		8A			CA	
	0B		PMA15_WA	4B	RW		8B			CB	
PRT3DM0	0C	RW	PMA8_RA	4C	RW		8C			CC	
PRT3DM1	0D	RW	PMA9_RA	4D	RW		8D			CD	
	0E		PMA10_RA	4E	RW		8E			CE	
	0F		PMA11_RA	4F	RW		8F			CF	
PRT4DM0	10	RW	PMA12_RA	50	RW		90			D0	
PRT4DM1	11	RW	PMA13_RA	51	RW		91			D1	
	12		PMA14_RA	52	RW		92		ECO_ENBUS	D2	RW
	13		PMA15_RA	53	RW		93		ECO_TRIM	D3	RW
	14		EP1_CR0	54	#		94			D4	
	15		EP2_CR0	55	#		95			D5	
	16		EP3_CR0	56	#		96			D6	
	17		EP4_CR0	57	#		97			D7	
	18		EP5_CR0	58	#		98		MUX_CR0	D8	RW
	19		EP6_CRO	59	#		99		MUX_CR1	D9	RW
	1A		EP7_CR0	5A	#		9A		MUX_CR2	DA	RW
	1B		EP8_CR0	5B	#		9B		MUX_CR3	DB	RW
	1C			5C			9C		IO_CFG1	DC	RW
	1D			5D			9D		OUT_P1	DD	RW
	1E			5E			9E		IO_CFG2	DE	RW
	1F			5F			9F		MUX_CR4	DF	RW
	20			60			A0		OSC_CR0	E0	RW
	21			61			A1		ECO_CFG	E1	#
	22			62			A2		OSC_CR2	E2	RW
	23			63			A3		VLT_CR	E3	RW
	24			64			A4		VLT_CMP	E4	R
	25			65			A5			E5	
	26			66			A6			E6	
	27			67			A7			E7	
	28			68			A8		IMO_TR	E8	W
SPI_CFG	29	RW		69			A9		ILO_TR	E9	W
	2A			6A			AA			EA	
	2B			6B			AB		SLP_CFG	EB	RW
	2C		TMP_DR0	6C	RW		AC		SLP_CFG2	EC	RW
	2D		TMP_DR1	6D	RW		AD		SLP_CFG3	ED	RW
	2E		TMP_DR2	6E	RW		AE			EE	
	2F		TMP_DR3	6F	RW		AF			EF	
USB_CR1	30	#		70			B0			F0	
	31			71			B1			F1	
	32			72			B2			F2	
	33			73			B3			F3	
PMA0_WA	34	RW		74			B4			F4	
PMA1_WA	35	RW		75			B5			F5	
PMA2_WA	36	RW		76			B6			F6	
PMA3_WA	37	RW		77			B7		CPU_F	F7	RL
PMA4_WA	38	RW		78			B8			F8	
PMA5_WA	39	RW		79			B9			F9	
PMA6_WA	3A	RW		7A			BA		IMO_TR1	FA	RW
PMA7_WA	3B	RW		7B			BB			FB	
PMA0_RA	3C	RW		7C			BC			FC	
PMA1_RA	3D	RW		7D		USB_MISC_CR	BD	RW		FD	
PMA2_RA	3E	RW		7E			BE			FE	
PMA3_RA	3F	RW		7F			BF			FF	

Gray fields are reserved; do not access these fields. # Access is bit specific.

Absolute Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

Table 4. Absolute Maximum Ratings

Symbol	Description	Conditions	Min	Typ	Max	Units
T _{STG}	Storage temperature ^[10]	Higher storage temperatures reduces data retention time. Recommended Storage Temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 85°C degrades reliability.	–55	+25	+125	°C
V _{DD}	Supply voltage relative to V _{SS}		–0.5	–	+6.0	V
V _{IO}	DC input voltage		V _{SS} – 0.5	–	V _{DD} + 0.5	V
V _{IOZ}	DC voltage applied to tristate		V _{SS} – 0.5	–	V _{DD} + 0.5	V
I _{MIO}	Maximum current into any port pin		–25	–	+50	mA
ESD	Electrostatic discharge voltage	Human body model ESD	2000	–	–	V
LU ^[8]	Latch up current	In accordance with JESD78 standard	–	–	200	mA

Operating Temperature

Table 5. Operating Temperature

Symbol	Description	Conditions	Min	Typ	Max	Units
T _{AI}	Ambient industrial temperature		–40	–	+85	°C
T _{AC}	Ambient commercial temperature		0	–	+70	°C
T _{Jl}	Operational industrial die temperature ^[11]	The temperature rise from ambient to junction is package specific. Refer the table Thermal Impedances per Package on page 31 . The user must limit the power consumption to comply with this requirement.	–40	–	+100	°C
T _{Jc}	Operational commercial die temperature	The temperature rise from ambient to junction is package specific. Refer the table Thermal Impedances per Package on page 31 . The user must limit the power consumption to comply with this requirement.	0	–	+85	°C

Notes

- When V_{DD} remains in the range from 1.71 V to 1.9 V for more than 50 μsec, the slew rate when moving from the 1.71 V to 1.9 V range to greater than 2 V must be slower than 1 V/500 μsec to avoid triggering POR. The only other restriction on slew rates for any other voltage range or transition is the SRPOWER_UP parameter.
 - Errata:** For Port 1 pins P1[1], P1[4], and P1[5] 300 Ohm external resistor is needed to meet this spec. Refer to [“Errata”](#) on page 35 for more details.
 - If powering down in standby sleep mode, to properly detect and recover from a V_{DD} brown out condition any of the following actions must be taken:
 - Bring the device out of sleep before powering down.
 - Assure that V_{DD} falls below 100 mV before powering back up.
 - Set the No Buzz bit in the OSC_CR0 register to keep the voltage monitoring circuit powered during sleep.
 - Increase the buzz rate to assure that the falling edge of V_{DD} is captured. The rate is configured through the PSSDC bits in the SLP_CFG register.
- For the referenced registers, refer to the enCoRe V Technical Reference Manual. In deep sleep mode, additional low power voltage monitoring circuitry allows V_{DD} brown out conditions to be detected for edge rates slower than 1 V/ms.

DC Electrical Characteristics

DC Chip Level Specifications

Table 6 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 6. DC Chip Level Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
V_{DD}	Operating voltage ^[7, 9]	No USB activity.	3.0	–	5.5	V
$I_{DD24,3}$	Supply current, CPU = 24 MHz	Conditions are $V_{DD} = 3.0$ V, $T_A = 25$ °C, CPU = 24 MHz, No USB/I ² C/SPI.	–	2.9	4.0	mA
$I_{DD12,3}$	Supply current, CPU = 12 MHz	Conditions are $V_{DD} = 3.0$ V, $T_A = 25$ °C, CPU = 12 MHz, No USB/I ² C/SPI.	–	1.7	2.6	mA
$I_{DD6,3}$	Supply current, CPU = 6 MHz	Conditions are $V_{DD} = 3.0$ V, $T_A = 25$ °C, CPU = 6 MHz, No USB/I ² C/SPI.	–	1.2	1.8	mA
$I_{SB1,3}$	Standby current with POR, LVD, and sleep timer	$V_{DD} = 3.0$ V, $T_A = 25$ °C, I/O regulator turned off.	–	1.1	1.5	μA
$I_{SB0,3}$	Deep sleep current	$V_{DD} = 3.0$ V, $T_A = 25$ °C, I/O regulator turned off.	–	0.1	–	μA
V_{DDUSB}	Operating voltage	USB activity, USB regulator enabled	4.35	–	5.25	V
$I_{DD24,5}$	Supply current, CPU = 24 MHz	Conditions are $V_{DD} = 5.0$ V, $T_A = 25$ °C, CPU = 24 MHz, $I_{MO} = 24$ MHz, USB Active, No I ² C/SPI.	–	7.1	–	mA
$I_{DD12,5}$	Supply current, CPU = 12 MHz	Conditions are $V_{DD} = 5.0$ V, $T_A = 25$ °C, CPU = 12 MHz, $I_{MO} = 24$ MHz, USB Active, No I ² C/SPI.	–	6.2	–	mA
$I_{DD6,5}$	Supply current, CPU = 6 MHz	Conditions are $V_{DD} = 5.0$ V, $T_A = 25$ °C, CPU = 6 MHz, $I_{MO} = 24$ MHz, USB Active, No I ² C/SPI.	–	5.8	–	mA
$I_{SB1,5}$	Standby current with POR, LVD, and sleep timer	$V_{DD} = 5.0$ V, $T_A = 25$ °C, I/O regulator turned off.	–	1.1	–	μA
$I_{SB0,5}$	Deep sleep current	$V_{DD} = 5.0$ V, $T_A = 25$ °C, I/O regulator turned off.	–	0.1	–	μA
V_{DDUSB}	Operating voltage	USB activity, USB regulator bypassed	3.15	3.3	3.60	V

Notes

10. Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 85 °C degrade reliability.
11. The temperature rise from ambient to junction is package specific. See [Package Handling on page 31](#). The user must limit the power consumption to comply with this requirement.

Table 7. DC Characteristics – USB Interface

Symbol	Description	Conditions	Min	Typ	Max	Units
Rusbi	USB D+ pull-up resistance	With idle bus	0.900	–	1.575	k Ω
Rusba	USB D+ pull-up resistance	While receiving traffic	1.425	–	3.090	k Ω
Vohusb	Static output high		2.8	–	3.6	V
Volusb	Static output low		–	–	0.3	V
Vdi	Differential input sensitivity		0.2	–	–	V
Vcm	Differential input common mode range		0.8	–	2.5	V
Vse	Single-ended receiver threshold		0.8	–	2.0	V
Cin	Transceiver capacitance			–	50	pF
Iio	High Z state data Line Leakage	On D+ or D– line	–10	–	+10	μ A
Rps2	PS/2 Pull Up Resistance		3	5	7	k Ω
Rext	External USB Series Resistor	In series with each USB pin	21.78	22.0	22.22	Ω

ADC Electrical Specifications

Table 8. ADC User Module Electrical Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
Input						
V _{IN}	Input voltage range		0	–	VREFADC	V
C _{IIN}	Input capacitance		–	–	5	pF
R _{IN}	Input resistance	Equivalent switched cap input resistance for 8-, 9-, or 10-bit resolution	1/(500fF* Data Clock)	1/(400fF* Data Clock)	1/(300fF* Data Clock)	Ω
Reference						
V _{REFADC}	ADC reference voltage		1.14	–	1.26	V
Conversion Rate						
F _{CLK}	Data clock	Source is chip's internal main oscillator. See AC Chip-Level Specifications for accuracy	2.25	–	6	MHz
S8	8-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2 [^] Resolution/Data Clock)	–	23.4375	–	ksps
S10	10-bit sample rate	Data Clock set to 6 MHz. Sample Rate = 0.001/ (2 [^] Resolution/Data Clock)	–	5.859	–	ksps
DC Accuracy						
RES	Resolution	Can be set to 8-, 9-, or 10-bit	8	–	10	bits
DNL	Differential nonlinearity		–1	–	+2	LSB
INL	Integral nonlinearity		–2	–	+2	LSB
E _{Offset}	Offset error	8-bit resolution	0	3.2	19.2	LSB
		10-bit resolution	0	12.8	76.8	LSB
E _{gain}	Gain error	For any resolution	–5	–	+5	%FSR
Power						
I _{ADC}	Operating current		–	2.1	2.6	mA
PSRR	Power supply rejection ratio	PSRR (V _{DD} > 3.0 V)	–	24	–	dB
		PSRR (V _{DD} < 3.0 V)	–	30	–	dB

AC Programming Specifications

Table 17 lists guaranteed maximum and minimum specifications for the entire voltage and temperature ranges.

Table 17. AC Programming Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
T_{RSCLK}	Rise time of SCLK		1	–	20	ns
T_{FSCLK}	Fall time of SCLK		1	–	20	ns
T_{SSCLK}	Data setup time to falling edge of SCLK		40	–	–	ns
T_{HSCLK}	Data hold time from falling edge of SCLK		40	–	–	ns
F_{SCLK}	Frequency of SCLK		0	–	8	MHz
T_{ERASEB}	Flash erase time (Block)		–	–	18	ms
T_{WRITE}	Flash block write time		–	–	25	ms
T_{DSCLK1}	Data out delay from falling edge of SCLK,	$V_{DD} > 3.6 \text{ V}$	–	–	60	ns
T_{DSCLK2}	Data out delay from falling edge of SCLK	$3.0 \text{ V} < V_{DD} < 3.6 \text{ V}$	–	–	85	ns
T_{XRST3}	External reset pulse width after power-up	Required to enter programming mode when coming out of sleep	263	–	–	μs

Figure 12. Timing Diagram - AC Programming Cycle

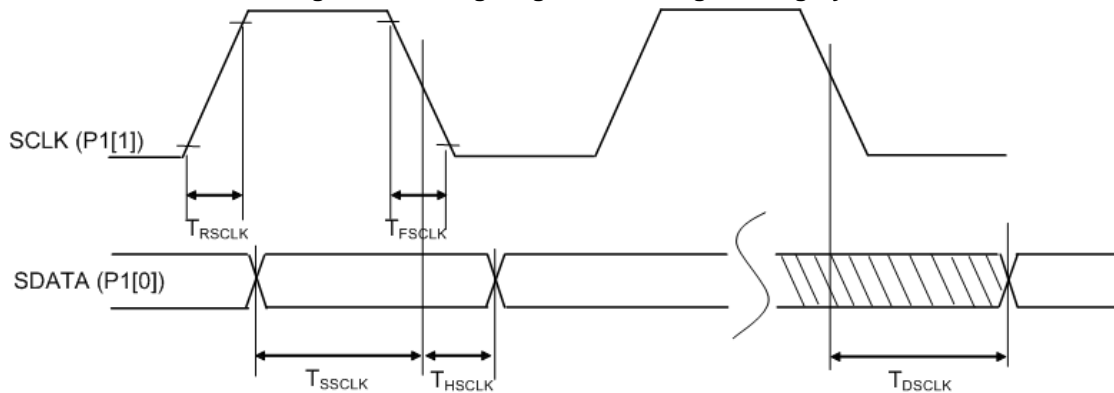


Table 20. SPI Slave AC Specifications

Symbol	Description	Conditions	Min	Typ	Max	Units
F_{SCLK}	SCLK clock frequency		0.0469	–	12	MHz
T_{LOW}	SCLK low time		41.67	–	–	ns
T_{HIGH}	SCLK high time		41.67	–	–	ns
T_{SETUP}	MOSI to SCLK setup time		30	–	–	ns
T_{HOLD}	SCLK to MOSI hold time		50	–	–	ns
T_{SS_MISO}	SS low to MISO valid		–	–	153	ns
T_{SCLK_MISO}	SCLK to MISO valid		–	–	125	ns
T_{SS_HIGH}	SS high time		50	–	–	ns
T_{SS_CLK}	Time from SS low to first SCLK		$2/F_{SCLK}$	–	–	ns
T_{CLK_SS}	Time from last SCLK to SS high		$2/F_{SCLK}$	–	–	ns

Figure 16. SPI Slave Mode 0 and 2

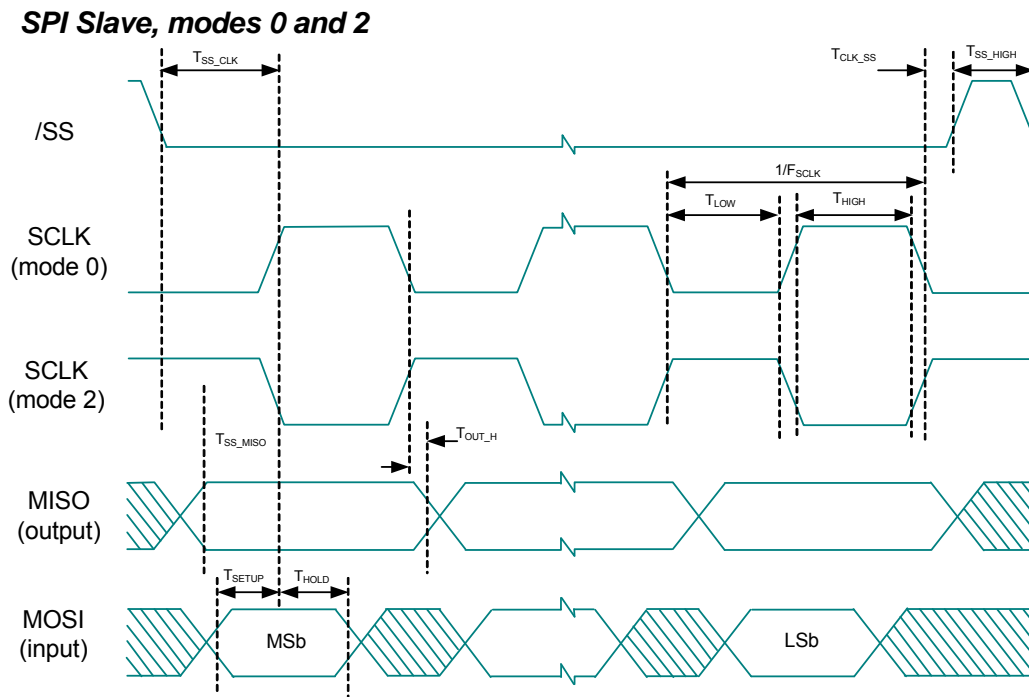


Figure 17. SPI Slave Mode 1 and 3

SPI Slave, modes 1 and 3

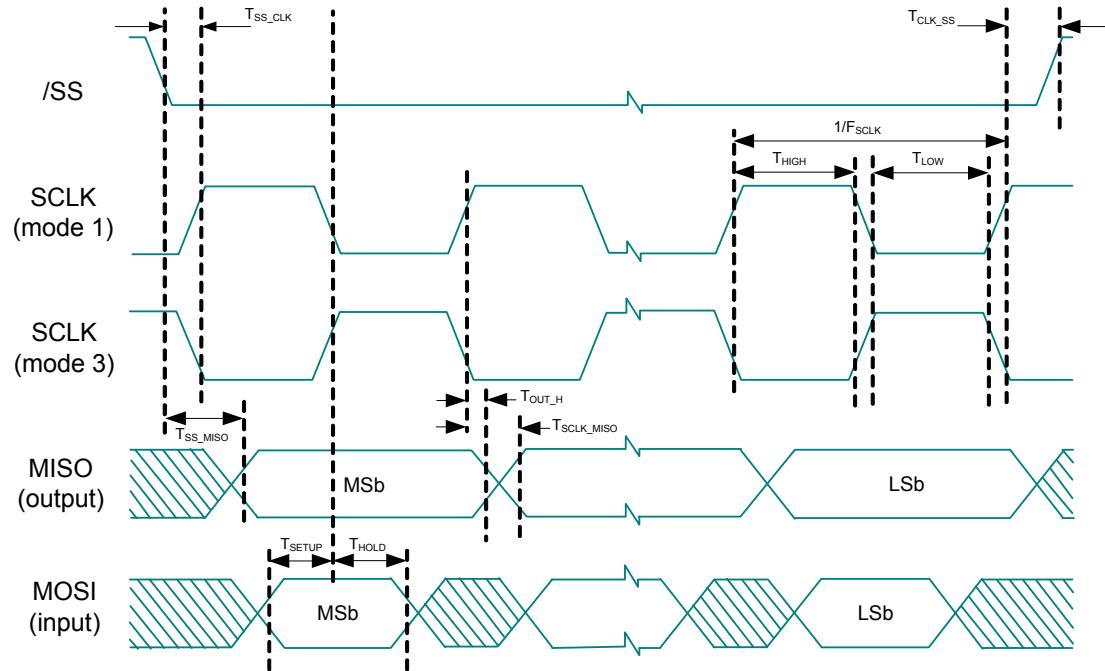
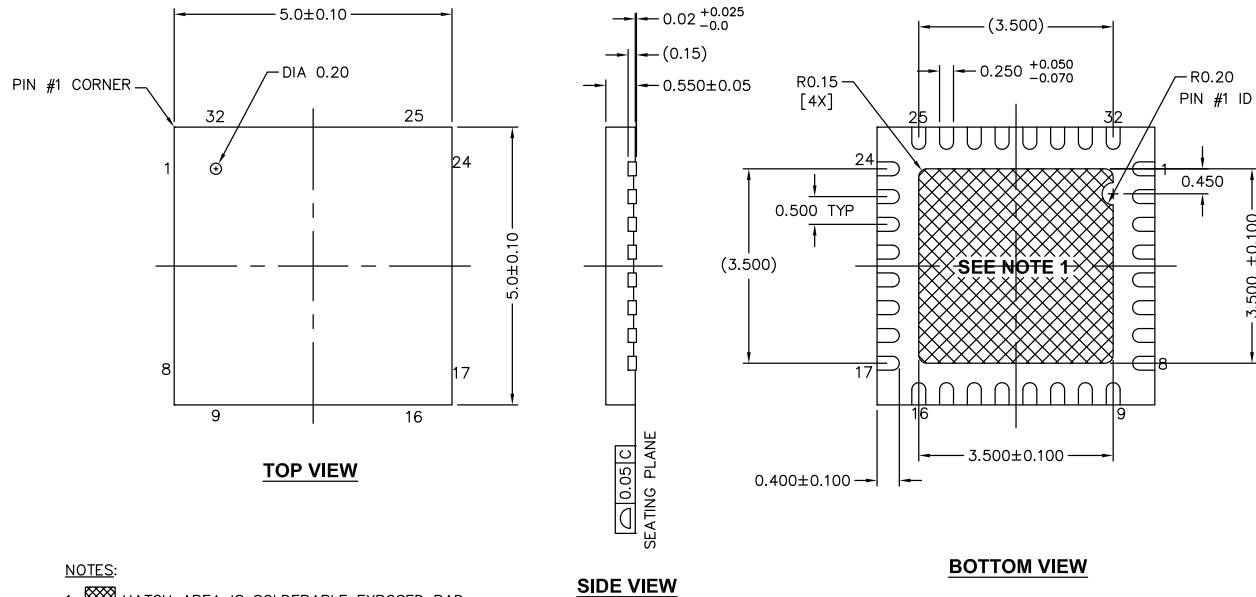
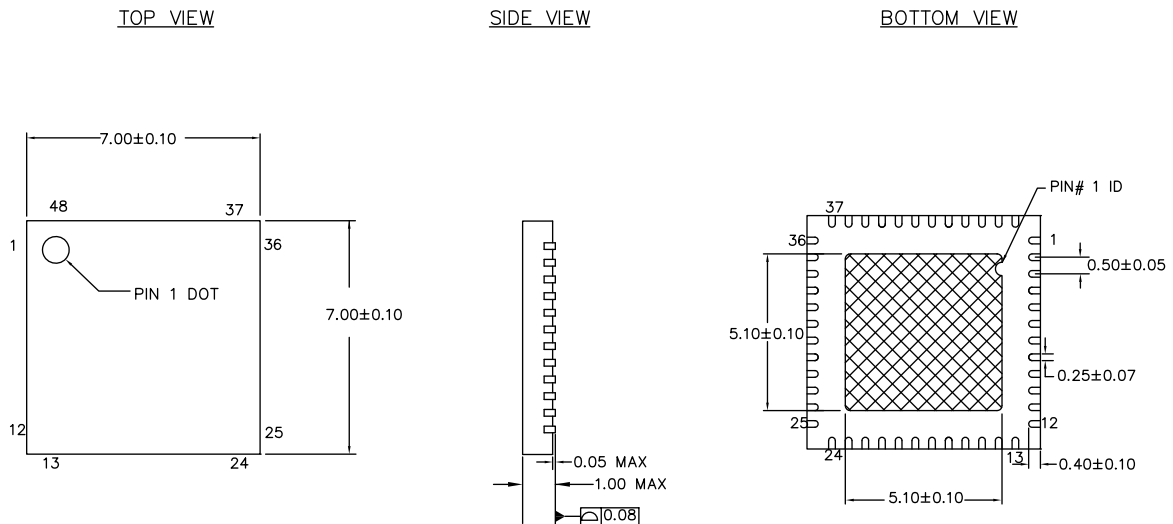


Figure 19. 32-pin QFN (5 × 5 × 0.55 mm) LQ32 3.5 × 3.5 E-Pad (Sawn) Package Outline, 001-42168



001-42168 *E

Figure 20. 48-pin QFN (7 × 7 × 1.00 mm) LT48A 5.1 × 5.1 E-Pad (Sawn) Package Outline, 001-13191



001-13191 *H

Errata

This section describes the errata for the enCoRe V – CY7C643xx. Details include errata trigger conditions, scope of impact, available workaround, and silicon revision applicability.

Contact your local Cypress Sales Representative if you have questions.

CY7C643xx Errata Summary

The following Errata item applies to the **CY7C643xx** data sheets.

1. Latch up susceptibility when maximum I/O sink current exceeded

■PROBLEM DEFINITION

P1[3], P1[6], and P1[7] pins are susceptible to latch up when the I/O sink current exceeds 25 mA per pin on these pins.

■PARAMETERS AFFECTED

LU – Latch up current. Per JESD78A, the maximum allowable latch up current per pin is 100 mA. Cypress internal specification is 200 mA latch up current limit.

■TRIGGER CONDITIONS

Latch up occurs when both the following conditions are met:

A. The offending I/O is externally connected to a voltage higher than the I/O high state, causing a current to flow into the pin that exceeds 25 mA.

B. A Port1 I/O (P1[1], P1[4], and P1[5] respectively) adjacent to the offending I/O is connected to a voltage lower than the I/O low state. This causes a signal that drops below V_{ss} (signal undershoot) and a current greater than 200 mA to flow out of the pin.

■SCOPE OF IMPACT

The trigger conditions outlined in this item exceed the maximum ratings specified in the CY7C643xx data sheets.

■WORKAROUND

Add a series resistor > 300 Ω to P1[3], P1[6], and P1[7] pins to restrict current to within latch up limits.

■FIX STATUS

This issue will be corrected in the next new silicon revision.

2. Does not meet USB 2.0 specification for D+ and D- rise/fall matching when supply voltage is under 3.3 V

■PROBLEM DEFINITION

Rising to falling rate matching of the USB D+ and D- lines has a corner case at lower supply voltages, such as those under 3.3 V.

■PARAMETERS AFFECTED

Rising to falling rate matching of the USB data lines.

■TRIGGER CONDITION(S)

Operating the VCC supply voltage at the low end of the chip's specification (under 3.3 V) may cause a mismatch in the rising to falling rate.

■SCOPE OF IMPACT

This condition does not affect USB communications but could cause corner case issues with USB lines' rise/fall matching specification. Signal integrity tests were run using the Cypress development kit and excellent eye was observed with supply voltage of 3.15 V.

Document History Page

Document Title: CY7C6431x/CY7C6434x/CY7C6435x, enCoRe™ V Full Speed USB Controller Document Number: 001-12394				
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change
**	626256	TYJ	See ECN	New data sheet.
*A	735718	TYJ / ARI	See ECN	Filled in TBDs, added new block diagram, and corrected some values. Part numbers updated as per new specifications.
*B	1120404	ARI	See ECN	Corrected the block diagram and Figure 3, which is the 16-pin enCoRe V device. Corrected the description to pin 29 on Table 2, the Typ/Max values for I _{SB0} on the DC chip-level specifications, the current value for the latch-up current in the Electrical Characteristics section, and corrected the 16 QFN package information in the Thermal Impedance table. Corrected some of the bulleted items on the first page. Added DC Characteristics—USB Interface table. Added AC Characteristics—USB Data Timings table. Added AC Characteristics—USB Driver table. Corrected Flash Write Endurance minimum value in the DC Programming Specifications table. Corrected the Flash Erase Time max value and the Flash Block Write Time max value in the AC Programming Specifications table. Implemented new latest template. Include parameters: V _{crs} , R _{pu} (USB, active), R _{pu} (USB suspend), T _{fdeop} , T _{fopr2} , T _{fopr} , T _{fst} . Added register map tables. Corrected a value in the DC Chip-Level Specifications table.
*C	1241024	TYJ / ARI	See ECN	Corrected I _{dd} values in Table 6 - DC Chip-Level Specifications.
*D	1639963	AESA	See ECN	Post to www.cypress.com
*E	2138889	TYJ / PYRS	See ECN	Updated Ordering Code table: - Ordering code changed for 32-QFN package: From -32LKXC to -32LTXC - Added a new package type – “LTXC” for 48-QFN - Included Tape and Reel ordering code for 32-QFN and 48-QFN packages Changed active current values at 24, 12 and 6MHz in table “DC Chip-Level Specifications” - IDD24: 2.15 to 3.1mA - IDD12: 1.45 to 2.0mA - IDD6: 1.1 to 1.5mA Added information on using P1[0] and P1[1] as the I2C interface during POR or reset events

Document History Page *(continued)*

Document Title: CY7C6431x/CY7C6434x/CY7C6435x, enCoRe™ V Full Speed USB Controller Document Number: 001-12394				
Rev.	ECN No.	Orig. of Change	Submission Date	Description of Change
*S	4578605	GINS	12/11/2014	Updated Pin Information : Updated 32-pin part pinout : Updated Figure 7 (No change in figure, included CY7C64346 in figure caption). Updated Package Diagrams : spec 001-09116 – Changed revision from *I to *J. Updated Ordering Information : Updated Table 25 : Updated part numbers.
*T	5548557	ANKC	12/12/2016	Updated Cypress Logo, Sales Page and Disclaimer. Updated Figure 20 (spec 001-13191 *G to *H) in Package Diagrams . Removed the following obsolete part numbers (Table 26) in Ordering Information : CY7C64343-32LQXI, CY7C64343-32LQXIT, CY7C64345-32LQXI, CY7C64345-32LQXIT, CY7C64356-48LTXI, CY7C64356-48LTXIT.

Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](#).

Products

ARM® Cortex® Microcontrollers	cypress.com/arm
Automotive	cypress.com/automotive
Clocks & Buffers	cypress.com/clocks
Interface	cypress.com/interface
Internet of Things	cypress.com/iot
Memory	cypress.com/memory
Microcontrollers	cypress.com/mcu
PSoC	cypress.com/psoc
Power Management ICs	cypress.com/pmic
Touch Sensing	cypress.com/touch
USB Controllers	cypress.com/usb
Wireless Connectivity	cypress.com/wireless

PSoC® Solutions

[PSoC 1](#) | [PSoC 3](#) | [PSoC 4](#) | [PSoC 5LP](#)

Cypress Developer Community

[Forums](#) | [WICED IOT Forums](#) | [Projects](#) | [Video](#) | [Blogs](#) | [Training](#) | [Components](#)

Technical Support

cypress.com/support

© Cypress Semiconductor Corporation, 2006-2016. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.