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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

Details

Product Status	Active
Number of LABs/CLBs	-
Number of Logic Elements/Cells	192000
Total RAM Bits	13619200
Number of I/O	284
Number of Gates	-
Voltage - Supply	0.97V ~ 1.08V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	484-BFBGA
Supplier Device Package	484-FPBGA (19x19)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/mpf200ts-1fcvg484i

7.9.4	Design Dependence of T PUFT and T WRFT	67
7.9.5	Cold Reset to Fabric and I/Os (Low Speed) Functional	67
7.9.6	Warm Reset to Fabric and I/Os (Low Speed) Functional	67
7.9.7	Miscellaneous Initialization Parameters	67
7.9.8	I/O Calibration	68
7.10	Dedicated Pins	69
7.10.1	JTAG Switching Characteristics	69
7.10.2	SPI Switching Characteristics	69
7.10.3	SmartDebug Probe Switching Characteristics	70
7.10.4	DEVRST_N Switching Characteristics	70
7.10.5	FF_EXIT Switching Characteristics	70
7.11	User Crypto	71
7.11.1	TeraFire 5200B Switching Characteristics	71
7.11.2	TeraFire 5200B Throughput Characteristics	71

1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 1.3

Revision 1.3 was published in June 2018. The following is a summary of changes.

- The System Services section was updated. For more information, see [System Services \(see page 59\)](#).
- The Non-Volatile Characteristics section was updated. For more information, see [Non-Volatile Characteristics \(see page 51\)](#).
- The Fabric Macros section was updated. For more information, see [Fabric Macros \(see page 60\)](#).
- The Transceiver Switching Characteristics section was updated. For more information, see [Transceiver Switching Characteristics \(see page 42\)](#).

1.2 Revision 1.2

Revision 1.2 was published in June 2018. The following is a summary of changes.

- The datasheet has moved to preliminary status. Every table has been updated.

1.3 Revision 1.1

Revision 1.1 was published in August 2017. The following is a summary of changes.

- LVDS specifications changed to 1.25G. For more information, see [HSIO Maximum Input Buffer Speed](#) and [HSIO Maximum Output Buffer Speed](#).
- LVDS18, LVDS25/LVDS33, and LVDS25 specifications changed to 800 Mbps. For more information, see [I/O Standards Specifications](#).
- A note was added indicating a zeroization cycle counts as a programming cycle. For more information, see [Non-Volatile Characteristics](#).
- A note was added defining power down conditions for programming recovery conditions. For more information, see [Power-Supply Ramp Times](#).

1.4 Revision 1.0

Revision 1.0 was the first publication of this document.

2 Overview

This datasheet describes PolarFire® FPGA device characteristics with industrial temperature range (-40°C to 100°C T_J) and extended commercial temperature range (0°C to 100°C T_J). The devices are provided with a standard speed grade (STD) and a -1 speed grade with higher performance. The FPGA core supply V_{DD} can operate at 1.0 V for lower-power or 1.05 V for higher performance. Similarly, the transceiver core supply V_{DDA} can also operate at 1.0 V or 1.05 V. Users select the core operating voltage while creating the Libero project.

6 DC Characteristics

This section lists the DC characteristics of the PolarFire FPGA device.

6.1 Absolute Maximum Rating

The following table lists the absolute maximum ratings for PolarFire devices.

Table 3 • Absolute Maximum Rating

Parameter	Symbol	Min	Max	Unit
FPGA core power supply	V _{DD}	-0.5	1.13	V
Transceiver Tx and Rx lanes supply	V _{DDA}	-0.5	1.13	V
Programming and HSIO receiver supply	V _{DD18}	-0.5	2.0	V
FPGA core and FPGA PLL high-voltage supply	V _{DD25}	-0.5	2.7	V
Transceiver PLL high-voltage supply	V _{DDA25}	-0.5	2.7	V
Transceiver reference clock supply	V _{DD_XCVR_CLK}	-0.5	3.6	V
Global V _{REF} for transceiver reference clocks	XCVR _{VREF}	-0.5	3.6	V
HSIO DC I/O supply ²	V _{DDIX}	-0.5	2.0	V
GPIO DC I/O supply ²	V _{DDIX}	-0.5	3.6	V
Dedicated I/O DC supply for JTAG and SPI	V _{DDI3}	-0.5	3.6	V
GPIO auxiliary power supply for I/O bank x ²	V _{DDAUXx}	-0.5	3.6	V
Maximum DC input voltage on GPIO	V _{IN}	-0.5	3.8	V
Maximum DC input voltage on HSIO	V _{IN}	-0.5	2.2	V
Transceiver Receiver absolute input voltage	Transceiver V _{IN}	-0.5	1.26	V
Transceiver Reference clock absolute input voltage	Transceiver REFCLK V _{IN}	-0.5	3.6	V
Storage temperature (ambient) ¹	T _{STG}	-65	150	°C
Junction temperature ¹	T _J	-55	135	°C
Maximum soldering temperature RoHS	T _{SOLROHS}		260	°C
Maximum soldering temperature leaded	T _{SOLPB}		220	°C

1. See [FPGA Programming Cycles vs Retention Characteristics](#) for retention time vs. temperature. The total time used in calculating the device retention includes storage time and the device stored temperature.
2. The power supplies for a given I/O bank x are shown as V_{DDIX} and V_{DDAUXx}.

6.2 Recommended Operating Conditions

The following table lists the recommended operating conditions.

Table 4 • Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit
FPGA core supply at 1.0 V mode ¹	V _{DD}	0.97	1.00	1.03	V
FPGA core supply at 1.05 V mode ¹	V _{DD}	1.02	1.05	1.08	V
Transceiver TX and RX lanes supply at 1.0 V mode (when all lane rates are 10.3125 Gbps or less) ¹	V _{DDA}	0.97	1.00	1.03	V

Parameter	Symbol	Min	Typ	Max	Unit
Transceiver TX and RX lanes supply at 1.05 V mode (when any lane rate is greater than 10.3125 Gbps) ¹	V _{DDA}	1.02	1.05	1.08	V
Programming and HSIO receiver supply	V _{DD18}	1.71	1.80	1.89	V
FPGA core and FPGA PLL high-voltage supply	V _{DD25}	2.425	2.50	2.575	V
Transceiver PLL high-voltage supply	V _{DDA25}	2.425	2.50	2.575	V
Transceiver reference clock supply –3.3 V nominal	V _{DD_XCVR_CLK}	3.135	3.3	3.465	V
Transceiver reference clock supply –2.5 V nominal	V _{DD_XCVR_CLK}	2.375	2.5	2.625	V
Global V _{REF} for transceiver reference clocks ³	XCVR _{VREF}	Ground		V _{DD_XCVR_CLK}	V
HSIO DC I/O supply. Allowed nominal options: 1.2 V, 1.35 V, 1.5 V, and 1.8 V ⁴	V _{DDI_x}	1.14	Various	1.89	V
GPIO DC I/O supply. Allowed nominal options: 1.2 V, 1.5 V, 1.8 V, 2.5 V, and 3.3 V ^{2,4}	V _{DDI_x}	1.14	Various	3.465	V
Dedicated I/O DC supply for JTAG and SPI (GPIO Bank 3). Allowed nominal options: 1.8 V, 2.5 V, and 3.3 V	V _{DDI₃}	1.71	Various	3.465	V
GPIO auxiliary supply for I/O bank x with V _{DDI_x} = 3.3 V nominal ^{2,4}	V _{DDAU_x}	3.135	3.3	3.465	V
GPIO auxiliary supply for I/O bank x with V _{DDI_x} = 2.5 V nominal or lower ^{2,4}	V _{DDAU_x}	2.375	2.5	2.625	V
Extended commercial temperature range	T _J	0		100	°C
Industrial temperature range	T _J	-40		100	°C
Extended commercial programming temperature range	T _{PRG}	0		100	°C
Industrial programming temperature range	T _{PRG}	-40		100	°C

1. V_{DD} and V_{DDA} can independently operate at 1.0 V or 1.05 V nominal. These supplies are not dynamically adjustable.
2. For GPIO buffers where I/O bank is designated as bank number, if V_{DDI_x} is 2.5 V nominal or 3.3 V nominal, V_{DDAU_x} must be connected to the V_{DDI_x} supply for that bank. If V_{DDI_x} for a given GPIO bank is <2.5 V nominal, V_{DDAU_x} per I/O bank must be powered at 2.5 V nominal.
3. XCVR_{VREF} globally sets the reference voltage of the transceiver's single-ended reference clock input buffers. It is typically near V_{DD_XCVR_CLK}/2 V but is allowed in the specified range.
4. The power supplies for a given I/O bank x are shown as V_{DDI_x} and V_{DDAU_x}.

6.2.1 DC Characteristics over Recommended Operating Conditions

The following table lists the DC characteristics over recommended operating conditions.

Table 5 • DC Characteristics over Recommended Operating Conditions

Parameter	Symbol	Min	Max	Unit	Condition
Input pin capacitance ¹	C _{IN} (dedicated GPIO)	5.6		pf	
	C _{IN} (GPIO)	5.6		pf	
	C _{IN} (HSIO)	2.8		pf	
Input or output leakage current per pin	I _L (GPIO)	10		µA	I/O disabled, high – Z
	I _L (HSIO)	10		µA	I/O disabled, high – Z
Input rise time (10%–90% of V _{DDI_x}) ^{2, 3, 4}	T _{RISE}	0.66	2.64	ns	V _{DDI_x} = 3.3 V
Input rise time (10%–90% of V _{DDI_x}) ^{2, 3, 4}		0.50	2.00	ns	V _{DDI_x} = 2.5 V
Input rise time (10%–90% of V _{DDI_x}) ^{2, 3, 4}		0.36	1.44	ns	V _{DDI_x} = 1.8 V
Input rise time (10%–90% of V _{DDI_x}) ^{2, 3, 4}		0.30	1.20	ns	V _{DDI_x} = 1.5 V
Input rise time (10%–90% of V _{DDI_x}) ^{2, 3, 4}		0.24	0.96	ns	V _{DDI_x} = 1.2 V
Input fall time (90%–10% of V _{DDI_x}) ^{2, 3, 4}	T _{FALL}	0.66	2.64	ns	V _{DDI_x} = 3.3 V
Input fall time (90%–10% of V _{DDI_x}) ^{2, 3, 4}		0.50	2.00	ns	V _{DDI_x} = 2.5 V
Input fall time (90%–10% of V _{DDI_x}) ^{2, 3, 4}		0.36	1.44	ns	V _{DDI_x} = 1.8 V
Input fall time (90%–10% of V _{DDI_x}) ^{2, 3, 4}		0.30	1.20	ns	V _{DDI_x} = 1.5 V
Input fall time (90%–10% of V _{DDI_x}) ^{2, 3, 4}		0.24	0.96	ns	V _{DDI_x} = 1.2 V
Pad pull-up when V _{IN} = 0 ⁵	I _{PU}	137	220	µA	V _{DDI_x} = 3.3 V
Pad pull-up when V _{IN} = 0 ⁵		102	166	µA	V _{DDI_x} = 2.5 V
Pad pull-up when V _{IN} = 0		68	115	µA	V _{DDI_x} = 1.8 V
Pad pull-up when V _{IN} = 0		51	88	µA	V _{DDI_x} = 1.5 V
Pad pull-up when V _{IN} = 0 ⁶		29	73	µA	V _{DDI_x} = 1.35 V
Pad pull-up when V _{IN} = 0		16	46	µA	V _{DDI_x} = 1.2 V
Pad pull-down when V _{IN} = 3.3 V ⁵	I _{PD}	65	187	µA	V _{DDI_x} = 3.3 V
Pad pull-down when V _{IN} = 2.5 V ⁵		63	160	µA	V _{DDI_x} = 2.5 V
Pad pull-down when V _{IN} = 1.8 V		60	117	µA	V _{DDI_x} = 1.8 V
Pad pull-down when V _{IN} = 1.5 V		57	95	µA	V _{DDI_x} = 1.5 V
Pad pull-down when V _{IN} = 1.35 V		52	86	µA	V _{DDI_x} = 1.35 V
Pad pull-down when V _{IN} = 1.2 V		47	79	µA	V _{DDI_x} = 1.2 V

1. Represents the die input capacitance at the pad not the package.
2. Voltage ramp must be monotonic.
3. Numbers based on rail-to-rail input signal swing and minimum 1 V/ns and maximum 4 V/ns. These are to be used for input delay measurement consistency.
4. I/O signal standards with smaller than rail-to-rail input swings can use a nominal value of 200 ps 20%–80% of swing and maximum value of 500 ps 20%–80% of swing.
5. GPIO only.

6.2.2 Maximum Allowed Overshoot and Undershoot

During transitions, input signals may overshoot and undershoot the voltage shown in the following table. Input currents must be limited to less than 100 mA per latch-up specifications.

Table 8 • Maximum Overshoot During Transitions for GPIO

AC (V_{IN}) Overshoot Duration as % at $T_J = 100^\circ C$	Condition (V)
100	3.8
100	3.85
100	3.9
100	3.95
70	4
50	4.05
33	4.1
22	4.15
14	4.2
9.8	4.25
6.5	4.3
4.4	4.35
3	4.4
2	4.45
1.4	4.5
0.9	4.55
0.6	4.6

Note: Overshoot level is for V_{DDI} at 3.3 V.

The following table shows the maximum AC input voltage (V_{IN}) undershoot duration for GPIO.

Table 9 • Maximum Undershoot During Transitions for GPIO

AC (V_{IN}) Undershoot Duration as % at $T_J = 100^\circ C$	Condition (V)
100	-0.5
100	-0.55
100	-0.6
100	-0.65
100	-0.7
100	-0.75
100	-0.8
100	-0.85
100	-0.9
100	-0.95
100	-1
100	-1.05
100	-1.1
100	-1.15
100	-1.2
69	-1.25
45	-1.3

6.2.2.1 Power-Supply Ramp Times

The following table shows the allowable power-up ramp times. Times shown correspond to the ramp of the supply from 0 V to the minimum recommended voltage as specified in the section [Recommended Operating Conditions \(see page 6\)](#). All supplies must rise and fall monotonically.

Table 10 • Power-Supply Ramp Times

Parameter	Symbol	Min	Max	Unit
FPGA core supply	V _{DD}	0.2	50	ms
Transceiver core supply	V _{DDA}	0.2	50	ms
Must connect to 1.8 V supply	V _{DD18}	0.2	50	ms
Must connect to 2.5 V supply	V _{DD25}	0.2	50	ms
Must connect to 2.5 V supply	V _{DDA25}	0.2	50	ms
HSIO bank I/O power supplies	V _{DD[0,1,6,7]}	0.2	50	ms
GPIO bank I/O power supplies	V _{DD[2,4,5]}	0.2	50	ms
Bank 3 dedicated I/O buffers (GPIO)	V _{DDI3}	0.2	50	ms
GPIO bank auxiliary power supplies	V _{DDAUX[2,4,5]}	0.2	50	ms
Transceiver reference clock supply	V _{DD_XCVR_CLK}	0.2	50	ms
Global V _{REF} for transceiver reference clocks	XCVRV _{REF}	0.2	50	ms

Note: For proper operation of programming recovery mode, if a VDD supply brownout occurs during programming, a minimum supply ramp down time for only the VDD supply is recommended to be 10 ms or longer by using a programmable regulator or on-board capacitors.

6.2.2.2 Hot Socketing

The following table lists the hot-socketing DC characteristics over recommended operating conditions.

Table 11 • Hot Socketing DC Characteristics over Recommended Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Current per transceiver Rx input pin (P or N single-ended) ^{1,2}	XCVRRX_HS			±4	mA	V _{DDA} = 0 V
Current per transceiver Tx output pin (P or N single-ended) ³	XCVRTX_HS			±10	mA	V _{DDA} = 0 V
Current per transceiver reference clock input pin (P or N single-ended) ⁴	XCVRREF_HS			±1	mA	V _{DD_XCVR_CLK} = 0 V
Current per GPIO pin (P or N single-ended) ⁵	I _{GPIO_HS}			±1	mA	V _{DDIx} = 0 V
Current per HSIO pin (P or N single-ended)						Hot socketing is not supported in HSIO.

1. Assumes that the device is powered-down, all supplies are grounded, AC-coupled interface, and input pin pairs are driven by a CML driver at the maximum amplitude (1 V pk-pk) that is toggling at any rate with PRBS7 data.
2. Each P and N transceiver input has less than the specified maximum input current.
3. Each P and N transceiver output is connected to a 40 Ω resistor (50 Ω CML termination – 20% tolerance) to the maximum allowed output voltage (V_{DDAmax} + 0.3 V = 1.4 V) through an AC-coupling capacitor with all PolarFire device supplies grounded. This shows the current for a worst-case DC coupled interface. As an AC-coupled interface, the output signal will settle at ground and no hot socket current will be seen.
4. V_{DD_XCVR_CLK} is powered down and the device is driven to $-0.3 \text{ V} < V_{IN} < V_{DD_XCVR_CLK}$.
5. V_{DDIx} is powered down and the device is driven to $-0.3 \text{ V} < V_{IN} < \text{GPIO } V_{DDImax}$.

Table 13 • DC Output Levels

I/O Standard	V _{DDI} Min (V)	V _{DDI} Typ (V)	V _{DDI} Max (V)	V _{OL} Min (V)	V _{OL} Max (V)	V _{OH} Min (V)	V _{OH} Max (V)	I _{OL^{2,6}} mA	I _{OH^{2,6}} mA
PCI ¹	3.15	3.3	3.45		0.1 x V _{DDI}	0.9 x V _{DDI}		1.5	0.5
LVTTL	3.15	3.3	3.45		0.4	2.4			
LVCMOS33	3.15	3.3	3.45		0.4	V _{DDI} — 0.4			
LVCMOS25	2.375	2.5	2.625		0.4	V _{DDI} — 0.4			
LVCMOS18	1.71	1.8	1.89		0.45	V _{DDI} — 0.45			
LVCMOS15	1.425	1.5	1.575		0.25 x V _{DDI}	0.75 x V _{DDI}			
LVCMOS12	1.14	1.2	1.26		0.25 x V _{DDI}	0.75 x V _{DDI}			
SSTL25I ³	2.375	2.5	2.625		V _{TT} — 0.608	V _{TT} + 0.608	8.1	8.1	
SSTL25II ³	2.375	2.5	2.625		V _{TT} — 0.810	V _{TT} + 0.810	16.2	16.2	
SSTL18I ³	1.71	1.8	1.89		V _{TT} — 0.603	V _{TT} + 0.603	6.7	6.7	
SSTL18II ³	1.71	1.8	1.89		V _{TT} — 0.603	V _{TT} + 0.603	13.4	13.4	
SSTL15I ⁴	1.425	1.5	1.575		0.2 x V _{DDI}	0.8 x V _{DDI}	V _{OL} /40 (V _{DDI} – V _{OH}) /40		
SSTL15II ⁴	1.425	1.5	1.575		0.2 x V _{DDI}	0.8 x V _{DDI}	V _{OL} /34 (V _{DDI} – V _{OH}) /34		
SSTL135I ⁴	1.283	1.35	1.418		0.2 x V _{DDI}	0.8 x V _{DDI}	V _{OL} /40 (V _{DDI} – V _{OH}) /40		
SSTL135II ⁴	1.283	1.35	1.418		0.2 x V _{DDI}	0.8 x V _{DDI}	V _{OL} /34 (V _{DDI} – V _{OH}) /34		
HSTL15I	1.425	1.5	1.575		0.4	V _{DDI} — 0.4	8	8	
HSTL15II	1.425	1.5	1.575		0.4	V _{DDI} — 0.4	16	16	

Standard	Description	R _{REF} (Ω)	C _{REF} (pF)	V _{MEAS} (V)	V _{REF} (V)
SSTL18I	SSTL 1.8 V Class I	50	0	V _{REF}	0.9
SSTL18II	SSTL 1.8 V Class II	50	0	V _{REF}	0.9
SSTL15I	SSTL 1.5 V Class I	50	0	V _{REF}	0.75
SSTL15II	SSTL 1.5 V Class II	50	0	V _{REF}	0.75
SSTL135I	SSTL 1.35 V Class I	50	0	V _{REF}	0.675
SSTL135II	SSTL 1.35 V Class II	50	0	V _{REF}	0.675
HSTL15I	High-speed transceiver logic (HSTL) 1.5 V Class I	50	0	V _{REF}	0.75
HSTL15II	HSTL 1.5 V Class II	50	0	V _{REF}	0.75
HSTL135I	HSTL 1.35 V Class I	50	0	V _{REF}	0.675
HSTL135II	HSTL 1.35 V Class II	50	0	V _{REF}	0.675
HSTL12	HSTL 1.2 V	50	0	V _{REF}	0.6
HSUL18I	High-speed unterminated logic 1.8 V Class I	50	0	V _{REF}	0.9
HSUL18II	HSUL 1.8 V Class II	50	0	V _{REF}	0.9
HSUL12	HSUL 1.2 V	50	0	V _{REF}	0.6
POD12I	Pseudo open drain (POD) logic 1.2 V Class I	50	0	V _{REF}	0.84
POD12II	POD 1.2 V Class II	50	0	V _{REF}	0.84
LVDS33	LVDS 3.3 V	100	0	0 ¹	0
LVDS25	LVDS 2.5 V	100	0	0 ¹	0
LVDS18	LVDS 1.8 V	100	0	0 ¹	0
RSDS33	Reduced swing differential signaling 3.3 V	100	0	0 ¹	0
RSDS25	RSDS 2.5 V	100	0	0 ¹	0
RSDS18	RSDS 1.8 V	100	0	0 ¹	0
MINILVDS33	Mini-LVDS 3.3 V	100	0	0 ¹	0
MINILVDS25	Mini-LVDS 2.5 V	100	0	0 ¹	0
SUBLVDS33	Sub-LVDS 3.3 V	100	0	0 ¹	0
SUBLVDS25	Sub-LVDS 2.5 V	100	0	0 ¹	0
PPDS33	Point-to-point differential signaling 3.3 V	100	0	0 ¹	0
PPDS25	PPDS 2.5 V	100	0	0 ¹	0
BUSLVDSE25	Bus LVDS	100	0	0 ¹	0
MLVDSE25	Multipoint LVDS 2.5 V	100	0	0 ¹	0
LVPECLE33	Low-voltage positive emitter-coupled logic	100	0	0 ¹	0
MIPIE25	Mobile industry processor interface 2.5 V	100	0	0 ¹	0

1. The value given is the differential output voltage.

Standard	STD	-1	Unit
LVCMOS18 (12 mA)	500	500	Mbps
LVCMOS15 (10 mA)	500	500	Mbps
LVCMOS12 (8 mA)	300	300	Mbps
MIPI25/MIPI33	800	800	Mbps

1. All SSTLD/HSTLD/HSULD/LVSTLD/POD type receivers use the LVDS differential receiver.
2. Performance is achieved with $V_{ID} \geq 200$ mV.

7.1.4 Output Buffer Speed

Table 26 • HSIO Maximum Output Buffer Speed

Standard	STD	-1	Unit
SSTL18I	800	1066	Mbps
SSTL18II	800	1066	Mbps
SSTL18I (differential)	800	1066	Mbps
SSTL18II (differential)	800	1066	Mbps
SSTL15I	1066	1333	Mbps
SSTL15II	1066	1333	Mbps
SSTL15I (differential)	1066	1333	Mbps
SSTL15II (differential)	1066	1333	Mbps
SSTL135I	1066	1333	Mbps
SSTL135II	1066	1333	Mbps
SSTL135I (differential)	1066	1333	Mbps
SSTL135II (differential)	1066	1333	Mbps
HSTL15I	900	1100	Mbps
HSTL15II	900	1100	Mbps
HSTL15I (differential)	900	1100	Mbps
HSTL15II (differential)	900	1100	Mbps
HSTL135I	1066	1066	Mbps
HSTL135II	1066	1066	Mbps
HSTL135I (differential)	1066	1066	Mbps
HSTL135II (differential)	1066	1066	Mbps
HSUL18I	400	400	Mbps
HSUL18II	400	400	Mbps
HSUL18II (differential)	400	400	Mbps
HSUL12	1066	1333	Mbps
HSUL12I (differential)	1066	1333	Mbps
HSTL12	1066	1266	Mbps
HSTL12I (differential)	1066	1266	Mbps
POD12I	1333	1600	Mbps
POD12II	1333	1600	Mbps
LVCMOS18 (12 mA)	500	500	Mbps
LVCMOS15 (10 mA)	500	500	Mbps

Parameter	Interface Name	Topology	STD Min	STD Typ	STD Max	-1 Min	-1 Typ	-1 Max	Unit	Clock-to- Data Condition
F_{MAX} 8:1	RX_DDRX_BL_C	Rx DDR digital mode							MHz	From a HS_IO_CLK clock source, centered

Table 32 • I/O Digital Transmit Single-Data Rate Switching Characteristics

Parameter	Interface Name	Topology	STD Min	STD Typ	STD Max	-1 Min	-1 Typ	-1 Max	Unit	Forwarded Clock-to-Data Skew
Output F_{MAX}	TX_SDR_G_A	Tx SDR							MHz	From a global clock source, aligned ¹
	TX_SDR_G_C	Tx SDR							MHz	From a global clock source, centered ¹

1. A centered clock-to-data interface can be created with a negedge launch of the data.

Table 33 • I/O Digital Transmit Double-Data Rate Switching Characteristics

Parameter	Interface Name	Topology	STD Min	STD Typ	STD Max	-1 Min	-1 Typ	-1 Max	Unit	Forwarded Clock-to- Data Skew
Output F_{MAX}	TX_DDR_G_A	Tx DDR			335			335	MHz	From a global clock source, aligned
	TX_DDR_G_C	Tx DDR			335			335	MHz	From a global clock source, centered
	TX_DDR_L_A	Tx DDR			250			250	MHz	From a lane clock source, aligned
	TX_DDR_L_C	Tx DDR			250			250	MHz	From a lane clock source, centered
Output F_{MAX} 2:1	TX_DDRX_B_A	Tx DDR digital mode							MHz	From a HS_IO_CLK clock source, aligned
Output F_{MAX} 4:1	TX_DDRX_B_A	Tx DDR digital mode							MHz	From a HS_IO_CLK clock source, aligned
Output F_{MAX} 8:1	TX_DDRX_B_A	Tx DDR digital mode							MHz	From a HS_IO_CLK clock source, aligned

Parameter	Symbol	Min	Typ	Max	Unit
Maximum input period clock jitter (reference and feedback clocks) ²	F_{MAXINJ}		120	1000	ps
PLL VCO frequency	F_{VCO}	800		5000	MHz
Loop bandwidth (Int) ³	F_{BW}	$F_{PHDET}/55$	$F_{PHDET}/44$	$F_{PHDET}/30$	MHz
Loop bandwidth (FRAC) ³	F_{BW}	$F_{PHDET}/91$	$F_{PHDET}/77$	$F_{PHDET}/56$	MHz
Static phase offset of the PLL outputs ⁴	T_{SPO}			Max (± 60 ps, ± 0.5 degrees)	ps
		$T_{OUTJITTER}$			ps
PLL output duty cycle precision	$T_{OUTDUTY}$	48		54	%
PLL lock time ⁵	T_{LOCK}			Max (6.0 μ s, 625 PFD cycles)	μ s
PLL unlock time ⁶	T_{UNLOCK}	2		8	PFD cycles
PLL output frequency	F_{OUT}	0.050		1250	MHz
Minimum reset pulse width	T_{MRPW}				μ s
Maximum delay in the feedback path ⁷	F_{MAXDFB}			1.5	PFD cycles
Spread spectrum modulation spread ⁸	Mod_Spread	0.1		3.1	%
Spread spectrum modulation frequency ⁹	Mod_Freq	$F_{PHDETF}/(128 \times 63)$	32	$F_{PHDETF}/(128)$	KHz

1. Minimum time for high or low pulse width.
2. Maximum jitter the PLL can tolerate without losing lock.
3. Default bandwidth setting of BW_PROP_CTRL = "01" for Integer and Fraction modes leads to the typical estimated bandwidth. This bandwidth can be lowered by setting BW_PROP_CTRL = "00" and can be increased if BW_PROP_CTRL = "10" and will be at the highest value if BW_PROP_CTRL = "11".
4. Maximum (± 3 -Sigma) phase error between any two outputs with nominally aligned phases.
5. Input clock cycle is REFDIV/ F_{REF} . For example, $F_{REF} = 25$ MHz, REFDIV = 1, lock time = 10.0 (assumes LOCKCOUNTSEL setting = 4'd8 (256 cycles)).
6. Unlock occurs if two cycle slip within LOCKCOUNT/4 PFD cycles.
7. Maximum propagation delay of external feedback path in deskew mode.
8. Programmable capability for depth of down spread or center spread modulation.
9. Programmable modulation rate based on the modulation divider setting (1 to 63).

Note: In order to meet all data sheet specifications, the PLL must be programmed such that the PLL Loop Bandwidth < $(0.0017 * VCO Frequency) - 0.4863$ MHz. The Libero PLL configuration tool will enforce this rule when creating PLL configurations.

7.2.3 DLL

The following table provides information about DLL.

Table 38 • DLL Electrical Characteristics

Parameter ¹	Symbol	Min	Typ	Max	Unit
Input reference clock frequency	F_{INF}	133		800	MHz
Input feedback clock frequency	F_{INFDBF}	133		800	MHz
Primary output clock frequency	F_{OUTPF}	133		800	MHz

7.3 Fabric Specifications

The following section describes specifications for the fabric.

7.3.1 Math Blocks

The following tables describe math block performance.

Table 41 • Math Block Performance Extended Commercial Range (0 °C to 100 °C)

Parameter	Symbol	Modes	V _{DD} = 1.0 V – STD	V _{DD} = 1.0 V – 1	V _{DD} = 1.05 V – STD	V _{DD} = 1.05 V – 1	Unit
Maximum operating frequency	F _{MAX}	18 × 18 multiplication	370	470	440	500	MHz
		18 × 18 multiplication summed with 48-bit input	370	470	440	500	MHz
		18 × 19 multiplier pre-adder ROM mode	365	465	435	500	MHz
		Two 9 × 9 multiplication	370	470	440	500	MHz
		9 × 9 dot product (DOTP)	370	470	440	500	MHz
		Complex 18 × 19 multiplication	360	455	430	500	MHz

Table 42 • Math Block Performance Industrial Range (-40 °C to 100 °C)

Parameter	Symbol	Modes	V _{DD} = 1.0 V – STD	V _{DD} = 1.0 V – 1	V _{DD} = 1.05 V – STD	V _{DD} = 1.05 V – 1	Unit
Maximum operating frequency	F _{MAX}	18 × 18 multiplication	365	465	435	500	MHz
		18 × 18 multiplication summed with 48-bit input	365	465	435	500	MHz
		18 × 19 multiplier pre-adder ROM mode	355	460	430	500	MHz
		Two 9 × 9 multiplication	365	465	435	500	MHz
		9 × 9 DOTP	365	465	435	500	MHz
		Complex 18 × 19 multiplication	350	450	425	500	MHz

5. Improved jitter characteristics for a specific industry standard are possible in many cases due to improved reference clock or higher V_{CO} rate used.
6. Tx jitter is specified with all transmitters on the device enabled, a 10–12-bit error rate (BER) and Tx data pattern of PRBS7.
7. From the PMA mode, the TX_ELEC_IDLE port to the XVCN TXP/N pins.
FTxRefClk = 75 MHz with typical settings.
For data rates greater than 10.3125 Gbps, VDDA must be set to 1.05 V mode. See supply tolerance in the section [Recommended Operating Conditions \(see page 6\)](#). (see page 6)

7.4.6 Receiver Performance

The following table describes performance of the receiver.

Table 53 • PolarFire Transceiver Receiver Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Condition
Input voltage range	V _{IN}	0		V _{DDA} + 0.3	V	
Differential peak-to-peak amplitude	V _{IDPP}	140		1250	mV	
Differential termination	V _{ITERM}	85			Ω	
	V _{ITERM}	100			Ω	
	V _{ITERM}	150			Ω	
Common mode voltage	V _{ICMDC} ¹	0.7 × V _{DDA}		0.9 × V _{DDA}	V	DC coupled
Exit electrical idle detection time	T _{EIDET}	50	100		ns	
Run length of consecutive identical digits (CID)	C _{ID}		200		UI	
CDR PPM tolerance ²	C _{DRPPM}		1.15		% UI	
CDR lock-to-data time	T _{LTD}				CDR _{REFCLK}	
					UI	
CDR lock-to-ref time	T _{LTF}				CDR _{REFCLK}	
					UI	
Loss-of-signal detect (Peak Detect Range setting = high) ⁹	V _{DETLHIGH}				mV	Setting = 1
	V _{DETLHIGH}				mV	Setting = 2
	V _{DETLHIGH}				mV	Setting = 3
	V _{DETLHIGH}				mV	Setting = 4
	V _{DETLHIGH}				mV	Setting = 5
	V _{DETLHIGH}				mV	Setting = 6
	V _{DETLHIGH}				mV	Setting = 7
Loss-of-signal detect (Peak Detect Range setting = low) ⁹	V _{DETLOW}	65	175		mV	Setting = PCIe ^{3,7}
	V _{DETLOW}	95	190		mV	Setting = SATA ^{4,8}
	V _{DETLOW}	75	170		mV	Setting = 1
	V _{DETLOW}	95	185		mV	Setting = 2
	V _{DETLOW}	100	190		mV	Setting = 3
	V _{DETLOW}	140	210		mV	Setting = 4
	V _{DETLOW}	155	240		mV	Setting = 5
	V _{DETLOW}	165	245		mV	Setting = 6
	V _{DETLOW}	170	250		mV	Setting = 7
Sinusoidal jitter tolerance	T _{SJTOL}				UI	>8.5 Gbps – 12.7 Gbps ^{5,10}

Parameter	Symbol	Min	Typ	Max	Unit	Condition
		0.41			UI	>3.2–8.5 Gbps ⁵
		0.41			UI	>1.6 to 3.2 Gbps ⁵
		0.41			UI	>0.8 to 1.6 Gbps ⁵
		0.41			UI	250 to 800 Mpbs ⁵
Total jitter tolerance with stressed eye	T _{JTOLSE}	0.65			UI	3.125 Gbps ⁵
		0.65			UI	6.25 Gbps ⁶
		0.7			UI	10.3125 Gbps ⁶
					UI	12.7 Gbps ^{6, 10}
Sinusoidal jitter tolerance with stressed eye	T _{SJOLSE}	0.1			UI	3.125 Gbps ⁵
		0.05			UI	6.25 Gbps ⁶
		0.05			UI	10.3125 Gbps ⁶
					UI	12.7 Gbps ^{6, 10}
CTLE DC gain (all stages, max settings)				10	dB	
CTLE AC gain (all stages, max settings)				16	dB	
DFE AC gain (per 5 stages, max settings)				7.5	dB	

1. Valid at 3.2 Gbps and below.
2. Data vs. Rx reference clock frequency.
3. Achieves compliance with PCIe electrical idle detection.
4. Achieves compliance with SATA OOB specification.
5. Rx jitter values based on bit error ratio (BER) of 10–12, AC coupled input with 400 mV V_{ID}, all stages of Rx CTLE enabled, DFE disabled, 80 MHz sinusoidal jitter injected to Rx data.
6. Rx jitter values based on bit error ratio (BER) of 10–12, AC coupled input with 400 mV V_{ID}, all stages of Rx CTLE enabled, DFE enabled, 80 MHz sinusoidal jitter injected to Rx data.
7. For PCIe: Low Threshold Setting = 1, High Threshold Setting = 2.
8. For SATA: Low Threshold Setting = 2, High Threshold Setting = 3.
9. Loss of signal detection is valid for input signals that transition at a density ≥ 1 Gbps for PRBS7 data or 6 Gbps for PRBS31 data.
10. For data rates greater than 10.3125 Gbps, VDDA must be set to 1.05 V mode. See supply tolerance in the section [Recommended Operating Conditions \(see page 6\)](#).

7.5 Transceiver Protocol Characteristics

The following section describes transceiver protocol characteristics.

7.5.1 PCI Express

The following tables describe the PCI express.

Table 54 • PCI Express Gen1

Parameter	Data Rate	Min	Max	Unit
Total transmit jitter	2.5 Gbps	0.25		UI
Receiver jitter tolerance	2.5 Gbps	0.4		UI

Note: With add-in card, as specified in PCI Express CEM Rev 2.0.

7.6.3 FPGA Bitstream Sizes

The following table describes FPGA bitstream sizes.

Table 72 • Initialization Client Sizes

Device	Plaintext	Ciphertext
MPF100T, TL, TS, TLS		
MPF200T, TL, TS, TLS	2916 KB	3006 KB
MPF300T, TL, TS, TLS	4265 KB	4403 KB
MPF500T, TL, TS, TLS		

Note: Worst case initializing all fabric LSRAM, USRAM, and UPROM.

Table 73 • Bitstream Sizes

File	Devices	FPGA	Security	SNVM (all pages)	FPGA+ SNVM	FPGA+ Sec	SNVM+ Sec	FPGA+ SNVM+ Sec
SPI	MPF100T, TL, TS, TLS							
DAT	MPF100T, TL, TS, TLS							
SPI	MPF200T, TL, TS, TLS	5.9 MB	3.4 KB	59.7 KB	5.9 MB	5.9 MB	62.2 KB	6.0 MB
DAT	MPF200T, TL, TS, TLS	5.9 MB	7.3 KB	61.2 KB	6.0 MB	5.9 MB	66.3 KB	6.0 MB
SPI	MPF300T, TL, TS, TLS	9.3 MB	3.5 KB	59.7 KB	9.6 MB	9.5 MB	62.2 KB	9.6 MB
DAT	MPF300T, TL, TS, TLS	9.3 MB	7.6 KB	61.2 KB	9.6 MB	9.5 MB	66.3 KB	9.6 MB
SPI	MPF500T, TL, TS, TLS							
DAT	MPF500T, TL, TS, TLS							

7.6.4 Digest Cycles

Digests verify the integrity of the programmed non-volatile data. Digests are a cryptographic hash of various data areas. Any digest that reports back an error raises the digest tamper flag.

Table 74 • Maximum Number of Digest Cycles

Retention Since Programmed (N = Number Digests During that Time) ¹										
Digest T_J	Storage and Operating T_J	N ≤ 300	N = 500	N = 1000	N = 1500	N = 2000	N = 4000	N = 6000	Unit	Retention
-40 to 100	-40 to 100	20 × LF	17 × LF	12 × LF	10 × LF	8 × LF	4 × LF	2 × LF	°C	Years
-40 to 100	0 to 100	20 × LF	17 × LF	12 × LF	10 × LF	8 × LF	4 × LF	2 × LF	°C	Years
-40 to 85	-40 to 85	20 × LF	20 × LF	20 × LF	20 × LF	16 × LF	8 × LF	4 × LF	°C	Years
-40 to 55	-40 to 55	20 × LF	20 × LF	20 × LF	20 × LF	20 × LF	20 × LF	20 × LF	°C	Years

1. LF = Lifetime factor as defined by the number of programming cycles the device has seen under the conditions listed in the following table.

Parameter	Type	Max	Unit	Conditions
Time to destroy data in non-volatile memory (non-recoverable) ^{1,4}		ms		One iteration of scrubbing
Time to scrub the fabric data ¹		s		Full scrubbing
Time to scrub the pNVM data (like new) ^{1,2}		s		Full scrubbing
Time to scrub the pNVM data (recoverable) ^{1,3}		s		Full scrubbing
Time to scrub the fabric data pNVM data (non-recoverable) ¹		s		Full scrubbing
Time to verify ⁵		s		

1. Total completion time after entering zeroization.
2. Like new mode—zeroizes user design security setting and sNVM content.
3. Recoverable mode—zeroizes user design security setting, sNVM and factory keys.
4. Non-recoverable mode—zeroizes user design security setting, sNVM and factory keys, and factory data required for programming.
5. Time to verify after scrubbing completes.

7.6.7 Verify Time

The following tables describe verify time.

Table 81 • Standalone Fabric Verify Times

Parameter	Devices	Max	Unit
Standalone verification over JTAG	MPF100T, TL, TS, TLS		s
	MPF200T, TL, TS, TLS	53 ¹	s
	MPF300T, TL, TS, TLS	90 ¹	s
	MPF500T, TL, TS, TLS		s
Standalone verification over SPI	MPF100T, TL, TS, TLS		s
	MPF200T, TL, TS, TLS	37 ²	s
	MPF300T, TL, TS, TLS	55 ²	s
	MPF500T, TL, TS, TLS		s

1. Programmer: FlashPro5, TCK 10 MHz; PC configuration: Intel i7 at 3.6 GHz, 32 GB RAM, Windows 10.
2. SmartFusion2 with MSS running at 100 MHz, MSS_SPI_0 port running at 6.67 MHz. DirectC version 4.1.

Notes:

- Standalone verify is limited to 2,000 total device hours over the industrial –40 °C to 100 °C temperature.
- Use the digest system service, for verify device time more than 2,000 hours.
- Standalone verify checks the programming margin on both the P and N gates of the push-pull cell.
- Digest checks only the P side of the push-pull gate. However, the push-pull gates work in tandem. Digest check is recommended if users believe they will exceed the 2,000-hour verify time specification.

Table 82 • Verify Time by Programming Hardware

Devices	IAP	FlashPro4	FlashPro5	BP	Silicon Sculptor	Units
MPF100T, TL, TS, TLS						
MPF200T, TL, TS, TLS	9	67	53			s
MPF300T, TL, TS, TLS	14	95	90			s

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Authenticated text read		113.25	114.02	118.5	μs	
Authenticated and decrypted text read		159.59	160.53	166.5	μs	

Notes:

- Page size= 252 bytes (non-authenticated), 236 bytes (authenticated).
- Only page reads and writes allowed.
- T_{PUF_OVHD} is an additional time that occurs on the first R/W, after cold or warm boot, to sNVM using authenticated or encrypted text.

7.6.10 Secure NVM Programming Cycles

The following table describes secure NVM programming cycles.

Table 86 • sNVM Programming Cycles vs. Retention Characteristics

Programming Temperature	Programming Cycles per Page, Max	Programming Cycles per Block, Max	Retention Years
-40 °C to 100 °C	10,000	100,000	20
-40 °C to 85 °C	10,000	100,000	20
-40 °C to 55 °C	10,000	100,000	20

Note: Page size = 128 bytes. Block size = 56 KBytes.

7.7 System Services

This section describes system switching and throughput characteristics.

7.7.1 System Services Throughput Characteristics

The following table describes system services throughput characteristics.

Table 87 • System Services Throughput Characteristics

Parameter	Symbol	Service ID	Typ	Max	Unit	Conditions
Serial number	T_{Serial}	00H	65	67	μs	
User code	T_{User}	01H	0.8	1.05	μs	
Design information	T_{Design}	02H	2.4	2.7	μs	
Device certificate	T_{Cert}	03H	255	271	ms	
Read digests	T_{digest_read}	04H	201	215	μs	
Query security locks	T_{sec_Query}	05H	15	17	μs	
Read debug information	T_{Rd_debug}	06H	34	38	μs	
Reserved		07H–0FH				
Secure NVM write plain text	$T_{SNVM_Wr_Plain}$	10H				Note 1
Secure NVM write authenticated plain text	$T_{SNVM_Wr_Auth}$	11H				Note 1
Secure NVM write authenticated cipher text	$T_{SNVM_Wr_Cipher}$	12H				Note 1
Reserved		13H–17H				

Parameter	Symbol	Service ID	Typ	Max	Unit	Conditions
Secure NVM read	T _{SNVM_Rd}	18H				Note 1
Digital signature service raw	T _{SIG_RAW}	19H	174	187	ms	
Digital signature service DER	T _{SIG_DER}	1AH	174	187	ms	
Reserved		1BH–1FH				
PUF emulation	T _{Challenge}	20H	1.8	2.0	ms	
Nonce service	T _{Nonce}	21H	1.2	1.4	ms	
Bitstream authentication	T _{BIT_AUTH}	22H				Note 4
IAP Image authentication	T _{IAP_AUTH}	23H				Note 4
Reserved		26H–3FH				
In application programming by index	T _{IAP_Prg_Index}	42H				Note 2
In application programming by SPI address	T _{IAP_Prg_Addr}	43H				Note 2
In application verify by index	T _{IAP_Ver_Index}	44H				Note 5
In application verify by SPI address	T _{IAP_Ver_Addr}	45H				Note 5
Auto update	T _{AutoUpdate}	46H				Note 2
Digest check	T _{Digest_chk}	47H				Note 3

1. See [sNVM Read/Write Characteristics \(see page 58\)](#).
2. See [SPI Master Programming Time \(see page 52\)](#).
3. See [Digest Times \(see page 54\)](#).
4. See [Authentication Services Time \(see page 58\)](#).
5. See [Verify Services Time \(see page 58\)](#).
6. Throughputs described are measured from SS_REQ assertion to BUSY de-assertion.

7.8

Fabric Macros

This section describes switching characteristics of UJTAG, UJTAG_SEC, USPI, system controller, and temper detectors and dynamic reconfiguration details.

7.8.1

UJTAG Switching Characteristics

The following section describes characteristics of UJTAG switching.

Table 88 • UJTAG Performance Characteristics

Parameter	Symbol	Min	Typ	Max	Unit	Condition
TCK frequency	F _{TCK}			25	MHz	