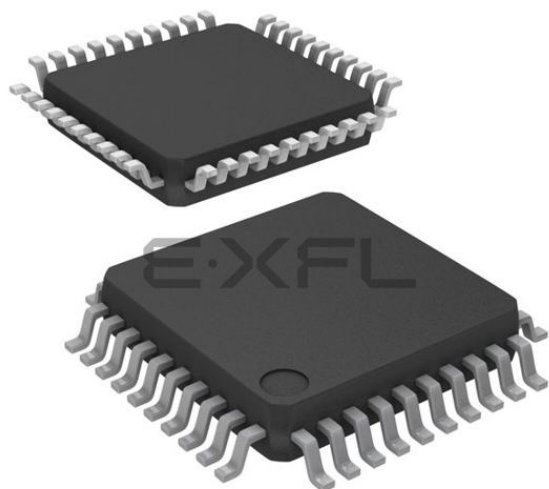




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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Not For New Designs
Core Processor	R8C
Core Size	16-Bit
Speed	20MHz
Connectivity	SIO, UART/USART
Peripherals	LED, POR, Voltage Detect, WDT
Number of I/O	22
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f21114fp-u0

1. Overview

This MCU is built using the high-performance silicon gate CMOS process using a R8C/Tiny Series CPU core and is packaged in a 32-pin plastic molded LQFP. This MCU operates using sophisticated instructions featuring a high level of instruction efficiency. With 1M bytes of address space, it is capable of executing instructions at high speed.

1.1 Applications

Electric household appliance, office equipment, housing equipment (sensor, security), general industrial equipment, audio, etc.

1.3 Block Diagram

Figure 1.1 shows this MCU block diagram.

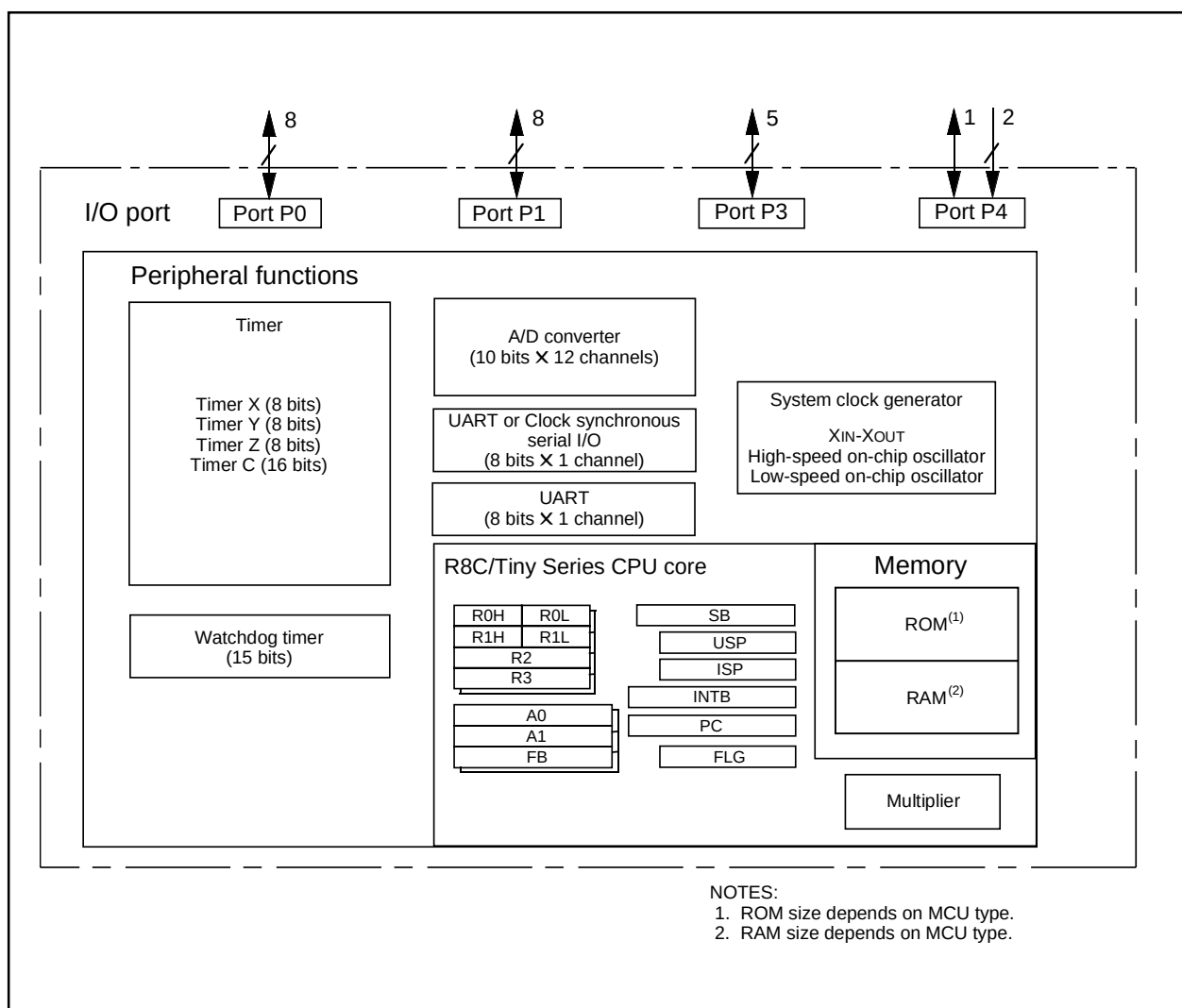


Figure 1.1 Block Diagram

1.4 Product Information

Table 1.2 lists the product information.

Table 1.2 Product Information

As of January 2006

Type No.	ROM capacity	RAM capacity	Package type	Remarks
R5F21112FP	8K bytes	512 bytes	PLQP0032GB-A	Flash memory version
R5F21113FP	12K bytes	768 bytes	PLQP0032GB-A	
R5F21114FP	16K bytes	1K bytes	PLQP0032GB-A	
R5F21112DFP	8K bytes	512 bytes	PLQP0032GB-A	D version
R5F21113DFP	12K bytes	768 bytes	PLQP0032GB-A	
R5F21114DFP	16K bytes	1K bytes	PLQP0032GB-A	

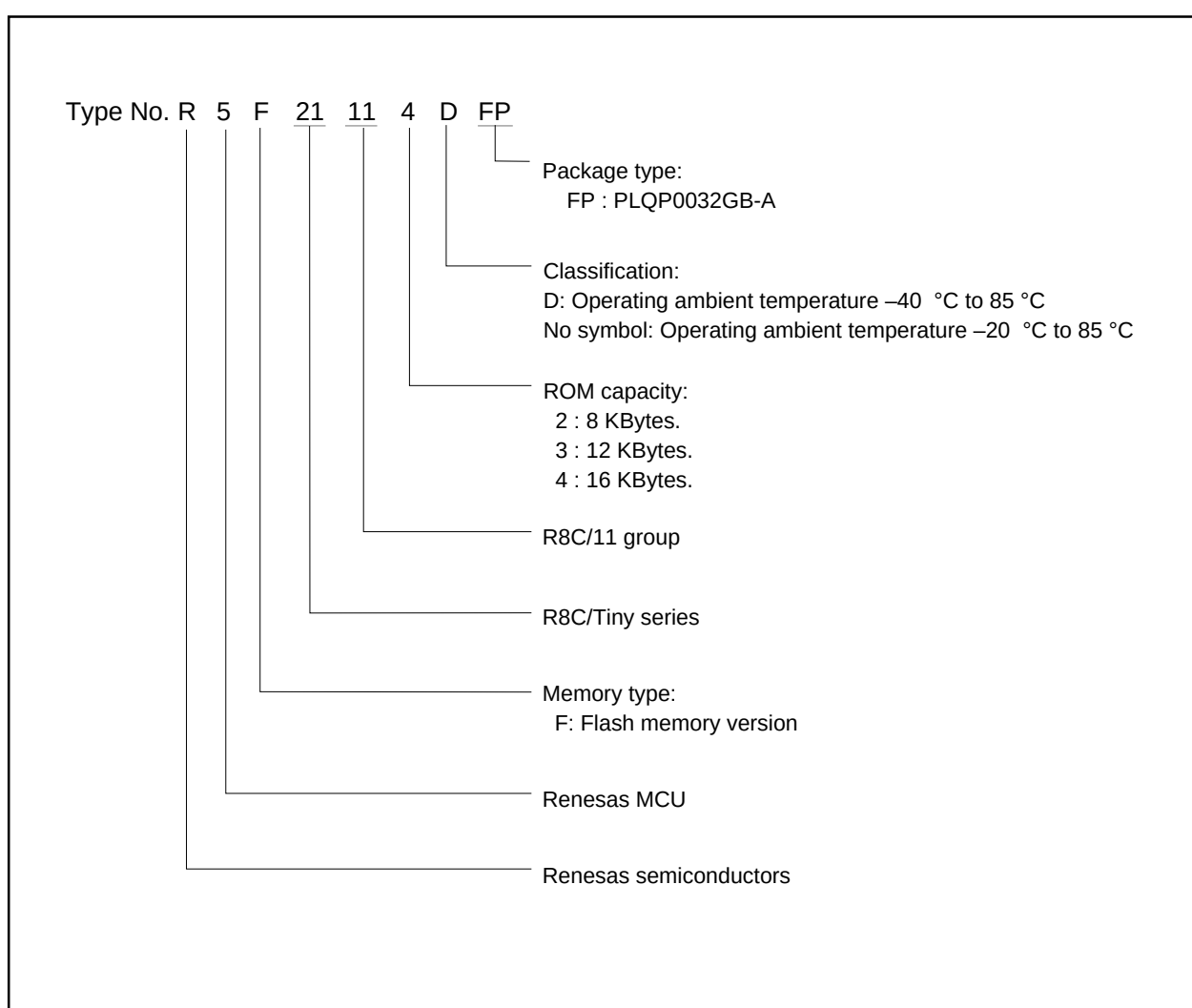


Figure 1.2 Type No., Memory Size, and Package

2. Central Processing Unit (CPU)

Figure 2.1 shows the CPU registers. The CPU has 13 registers. Of these, R0, R1, R2, R3, A0, A1 and FB comprise a register bank. Two sets of register banks are provided.

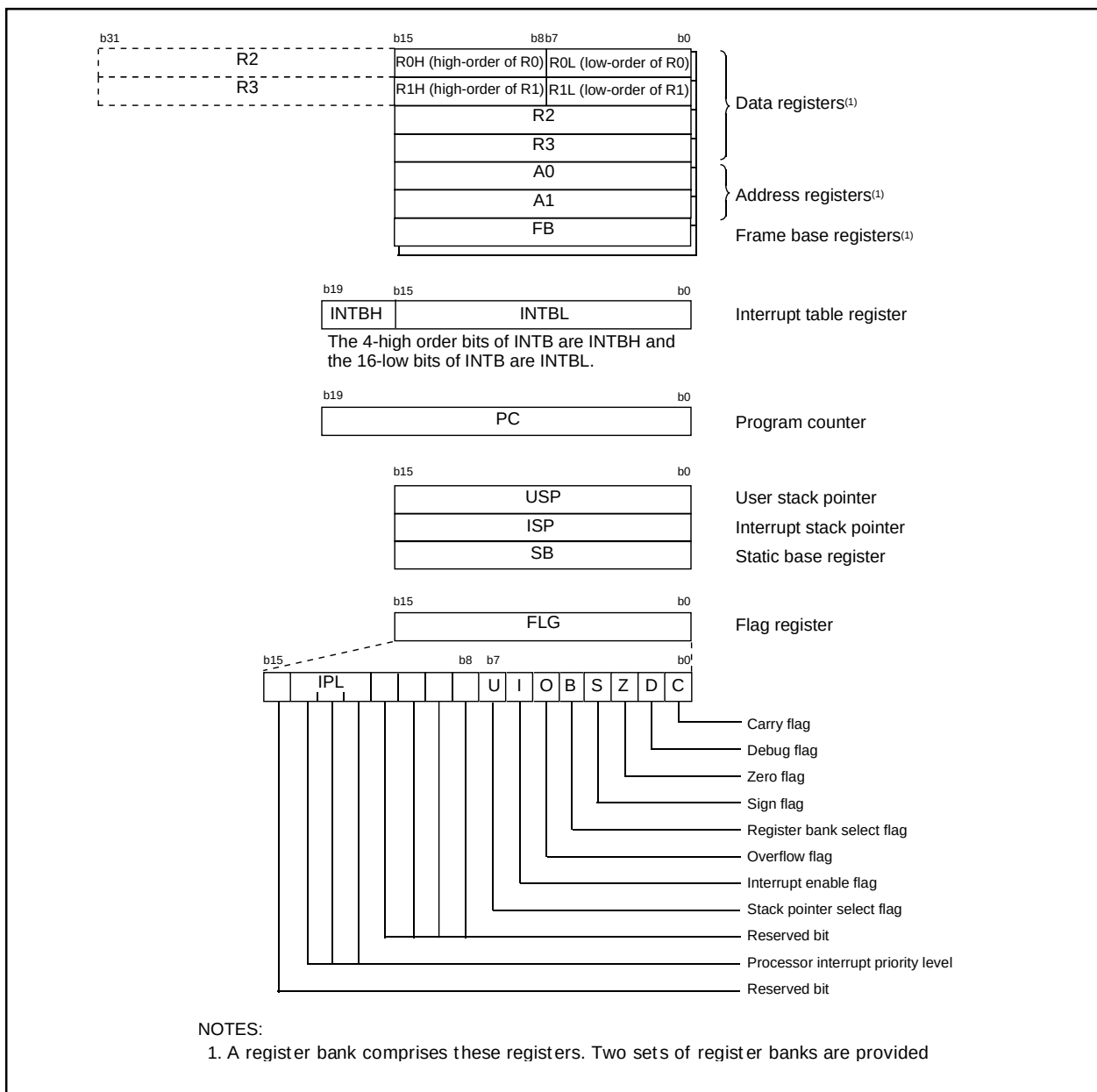


Figure 2.1 CPU Register

2.1 Data Registers (R0, R1, R2 and R3)

R0 is a 16-bit register for transfer, arithmetic and logic operations. The same applies to R1 to R3. The R0 can be split into high-order bit (R0H) and low-order bit (R0L) to be used separately as 8-bit data registers. The same applies to R1H and R1L as R0H and R0L. R2 can be combined with R0 to be used as a 32-bit data register (R2R0). The same applies to R3R1 as R2R0.

2.2 Address Registers (A0 and A1)

A0 is a 16-bit register for address register indirect addressing and address register relative addressing. They also are used for transfer, arithmetic and logic operations. The same applies to A1 as A0. A0 can be combined with A1 to be used as a 32-bit address register (A1A0).

2.3 Frame Base Register (FB)

FB is a 16-bit register for FB relative addressing.

2.4 Interrupt Table Register (INTB)

INTB is a 20-bit register indicates the start address of an interrupt vector table.

2.5 Program Counter (PC)

PC, 20 bits wide, indicates the address of an instruction to be executed.

2.6 User Stack Pointer (USP) and Interrupt Stack Pointer (ISP)

The stack pointer (SP), USP and ISP, are 16 bits wide each.

The U flag of FLG is used to switch between USP and ISP.

2.7 Static Base Register (SB)

SB is a 16-bit register for SB relative addressing.

2.8 Flag Register (FLG)

FLG is a 11-bit register indicating the CPU state.

2.8.1 Carry Flag (C)

The C flag retains a carry, borrow, or shift-out bit that has occurred in the arithmetic logic unit.

2.8.2 Debug Flag (D)

The D flag is for debug only. Set to "0".

2.8.3 Zero Flag (Z)

The Z flag is set to "1" when an arithmetic operation resulted in 0; otherwise, "0".

2.8.4 Sign Flag (S)

The S flag is set to "1" when an arithmetic operation resulted in a negative value; otherwise, "0".

2.8.5 Register Bank Select Flag (B)

The register bank 0 is selected when the B flag is "0". The register bank 1 is selected when this flag is set to "1".

2.8.6 Overflow Flag (O)

The O flag is set to "1" when the operation resulted in an overflow; otherwise, "0".

2.8.7 Interrupt Enable Flag (I)

The I flag enables a maskable interrupt.

An interrupt is disabled when the I flag is set to "0", and are enabled when the I flag is set to "1". The I flag is set to "0" when an interrupt request is acknowledged.

2.8.8 Stack Pointer Select Flag (U)

ISP is selected when the U flag is set to "0", USP is selected when the U flag is set to "1".

The U flag is set to "0" when a hardware interrupt request is acknowledged or the INT instruction of software interrupt numbers 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL, 3 bits wide, assigns processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has greater priority than IPL, the interrupt is enabled.

2.8.10 Reserved Bit

When write to this bit, set to "0". When read, its content is indeterminate.

3. Memory

Figure 3.1 is a memory map of this MCU. This MCU provides 1-Mbyte address space from addresses 00000₁₆ to FFFFF₁₆.

The internal ROM is allocated lower addresses beginning with address 0C000₁₆. For example, a 16-Kbyte internal ROM is allocated addresses from 0C000₁₆ to 0FFFF₁₆.

The fixed interrupt vector table is allocated addresses 0FFDC₁₆ to 0FFFF₁₆. They store the starting address of each interrupt routine.

The internal RAM is allocated higher addresses beginning with address 00400₁₆. For example, a 1-Kbyte internal RAM is allocated addresses 00400₁₆ to 007FF₁₆. The internal RAM is used not only for storing data, but for calling subroutines and stacks when interrupt request is acknowledged.

Special function registers (SFR) are allocated addresses 00000₁₆ to 002FF₁₆. The peripheral function control registers are located there. All addresses, which have nothing allocated within the SFR, are reserved area and cannot be accessed by users.

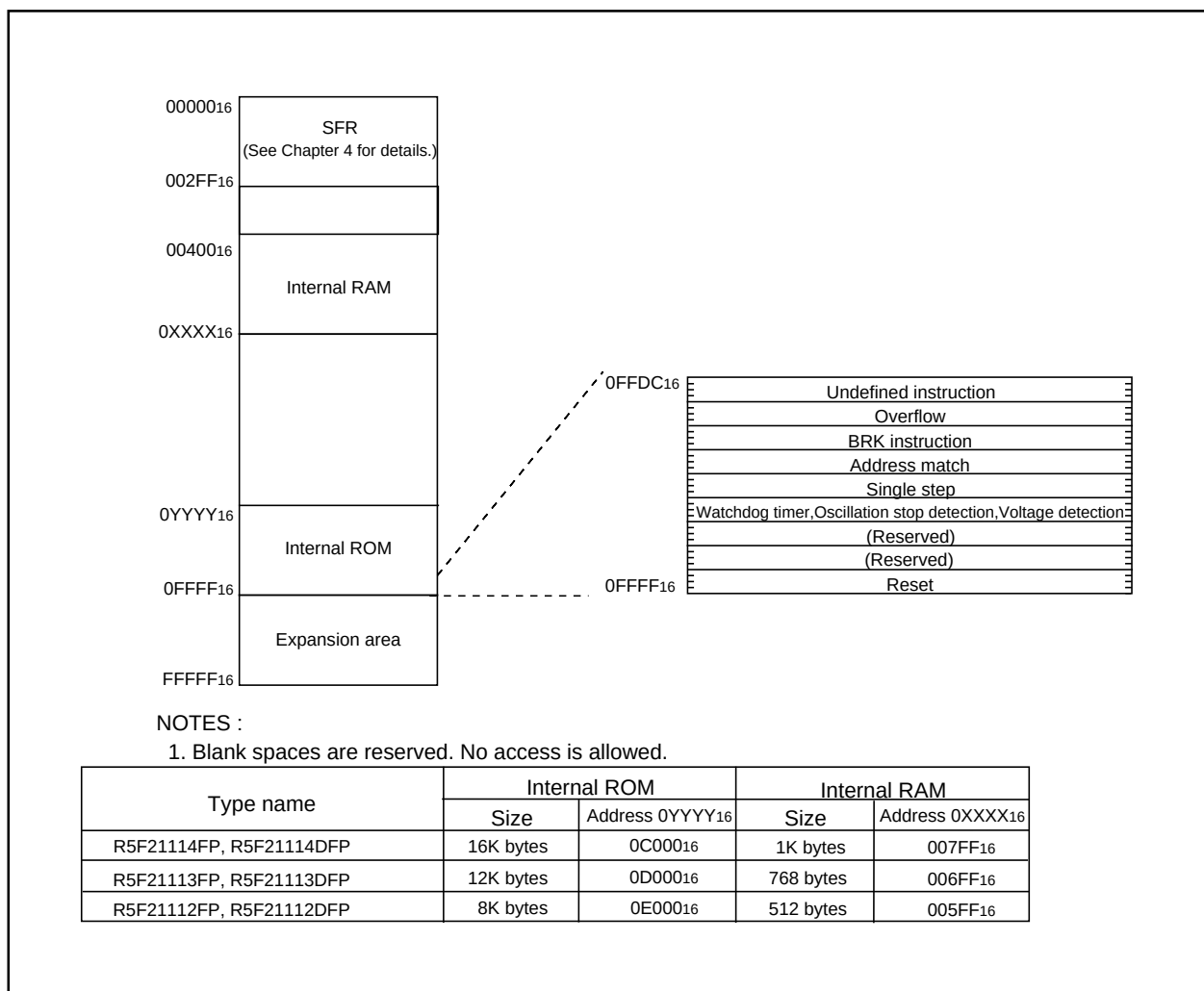


Figure 3.1 Memory Map

Table 4.4 SFR Information(4)(1)

Address	Register	Symbol	After reset
00C0 ₁₆	AD register	AD	XX16
00C1 ₁₆			XX16
00C2 ₁₆			
00C3 ₁₆			
00C4 ₁₆			
00C5 ₁₆			
00C6 ₁₆			
00C7 ₁₆			
00C8 ₁₆			
00C9 ₁₆			
00CA ₁₆			
00CB ₁₆			
00CC ₁₆			
00CD ₁₆			
00CE ₁₆			
00CF ₁₆			
00D0 ₁₆			
00D1 ₁₆			
00D2 ₁₆			
00D3 ₁₆			
00D4 ₁₆	AD control register 2	ADCON2	0016
00D5 ₁₆			
00D6 ₁₆	AD control register 0	ADCON0	00000XX2
00D7 ₁₆	AD control register 1	ADCON1	0016
00D8 ₁₆			
00D9 ₁₆			
00DA ₁₆			
00DB ₁₆			
00DC ₁₆			
00DD ₁₆			
00DE ₁₆			
00DF ₁₆			
00E0 ₁₆	Port P0 register	P0	XX16
00E1 ₁₆	Port P1 register	P1	XX16
00E2 ₁₆	Port P0 direction register	PD0	0016
00E3 ₁₆	Port P1 direction register	PD1	0016
00E4 ₁₆			
00E5 ₁₆	Port P3 register	P3	XX16
00E6 ₁₆			
00E7 ₁₆	Port P3 direction register	PD3	0016
00E8 ₁₆	Port P4 register	P4	XX16
00E9 ₁₆			
00EA ₁₆	Port P4 direction register	PD4	0016
00EB ₁₆			
00EC ₁₆			
00ED ₁₆			
00EE ₁₆			
00EF ₁₆			
00F0 ₁₆			
00F1 ₁₆			
00F2 ₁₆			
00F3 ₁₆			
00F4 ₁₆			
00F5 ₁₆			
00F6 ₁₆			
00F7 ₁₆			
00F8 ₁₆			
00F9 ₁₆			
03FA ₁₆			
00FB ₁₆			
00FC ₁₆	Pull-up control register 0	PUR0	00XX00002
00FD ₁₆	Pull-up control register 1	PUR1	XXXXXX0X2
00FE ₁₆	Port P1 drive capacity control register	DRR	0016
00FF ₁₆	Timer C output control register	TCOUT	0016
⋮			
01B3 ₁₆	Flash memory control register 4	FMR4	010000002
01B4 ₁₆			
01B5 ₁₆	Flash memory control register 1	FMR1	0100XX0X2
01B6 ₁₆			
01B7 ₁₆	Flash memory control register 0	FMR0	000000012

X : Undefined

NOTES:

1. Blank columns, 0100₁₆ to 01B2₁₆ and 01B8₁₆ to 02FF₁₆ are all reserved. No access is allowed.

5. Electrical Characteristics

Table 5.1 Absolute Maximum Ratings

Symbol	Parameter	Condition	Rated value	Unit
V _{CC}	Supply voltage	V _{CC} =AV _{CC}	-0.3 to 6.5	V
AV _{CC}	Analog supply voltage	V _{CC} =AV _{CC}	-0.3 to 6.5	V
V _I	Input voltage		-0.3 to V _{CC} +0.3	V
V _O	Output voltage		-0.3 to V _{CC} +0.3	V
P _d	Power dissipation	T _{opr} =25 °C	300	mW
T _{opr}	Operating ambient temperature		-20 to 85 / -40 to 85 (D version)	°C
T _{stg}	Storage temperature		-65 to 150	°C

Table 5.2 Recommended Operating Conditions

Symbol	Parameter	Conditions	Standard			Unit
			Min.	Typ.	Max.	
V _{CC}	Supply voltage		2.7	—	5.5	V
AV _{CC}	Analog supply voltage		—	V _{CC} (3)	—	V
V _{SS}	Supply voltage		—	0	—	V
AV _{SS}	Analog supply voltage		—	0	—	V
V _{IH}	"H" input voltage		0.8V _{CC}	—	V _{CC}	V
V _{IL}	"L" input voltage		0	—	0.2V _{CC}	V
I _{OH} (sum)	"H" peak all output currents	Sum of all pins' I _{OH} (peak)	—	—	-60.0	mA
I _{OH} (peak)	"H" peak output current		—	—	-10.0	mA
I _{OH} (avg)	"H" average output current		—	—	-5.0	mA
I _{OL} (sum)	"L" peak all output currents	Sum of all pins' I _{OL} (peak)	—	—	60	mA
I _{OL} (peak)	"L" peak output current	Except P10 to P17	—	—	10	mA
		P10 to P17				
		Drive capacity HIGH	—	—	30	mA
I _{OL} (avg)	"L" average output current	Except P10 to P17	—	—	5	mA
		P10 to P17				
		Drive capacity HIGH	—	—	15	mA
		Drive capacity LOW	—	—	5	mA
f (XIN)	Main clock input oscillation frequency	3.0V ≤ V _{CC} ≤ 5.5V	0	—	20	MHz
		2.7V ≤ V _{CC} < 3.0V	0	—	10	MHz

NOTES:

1. V_{CC} = AV_{CC} = 2.7 to 5.5V at T_{opr} = -20 to 85 °C / -40 to 85 °C, unless otherwise specified.
2. The typical values when average output current is 100ms.
3. Hold V_{CC}=AV_{CC}.

Table 5.3 A/D Conversion Characteristics

Symbol	Parameter		Measuring condition	Standard			Unit
				Min.	Typ.	Max.	
—	Resolution		$V_{ref} = V_{CC}$	—	—	10	Bit
—	Absolute accuracy	10 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 5.0 \text{ V}$	—	—	± 3	LSB
		8 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 5.0 \text{ V}$	—	—	± 2	LSB
		10 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 3.3 \text{ V}^{(3)}$	—	—	± 5	LSB
		8 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 3.3 \text{ V}^{(3)}$	—	—	± 2	LSB
R_{LADDER}	Ladder resistance		$V_{REF} = V_{CC}$	10	—	40	$k\Omega$
t_{CONV}	Conversion time	10 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 5.0 \text{ V}$	3.3	—	—	μs
		8 bit mode	$\phi AD = 10 \text{ MHz}$, $V_{ref} = V_{CC} = 5.0 \text{ V}$	2.8	—	—	μs
V_{REF}	Reference voltage			—	$V_{CC}^{(4)}$	—	V
V_{IA}	Analog input voltage			0	—	V_{ref}	V
—	A/D operating clock frequency ⁽²⁾	Without sample & hold		0.25	—	10	MHz
		With sample & hold		1.0	—	10	MHz

NOTES:

1. $V_{CC} = AV_{CC} = 2.7$ to 5.5 V at $T_{opr} = -20$ to $85 \text{ }^\circ\text{C}$ / -40 to $85 \text{ }^\circ\text{C}$, unless otherwise specified.
2. If f_{AD} exceeds 10 MHz more, divide the f_{AD} and hold A/D operating clock frequency (ϕAD) 10 MHz or below.
3. If the AV_{CC} is less than 4.2V, divide the f_{AD} and hold A/D operating clock frequency (ϕAD) $f_{AD}/2$ or below.
4. Hold $V_{CC} = V_{ref}$.

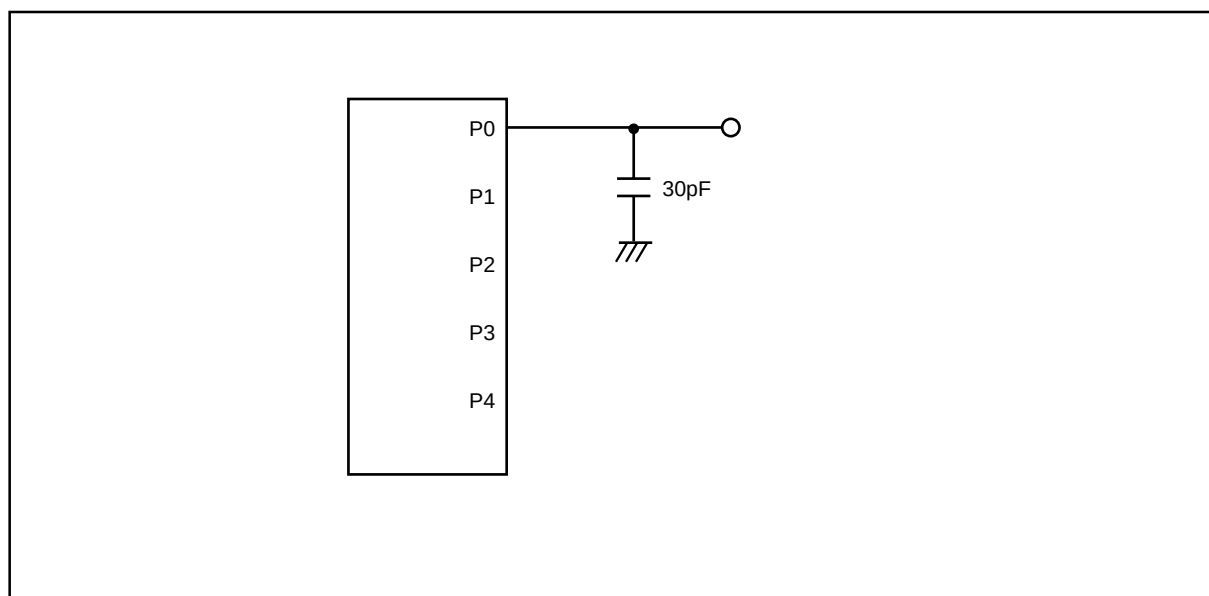
**Figure 5.1 Port P0 to P4 measurement circuit**

Table 5.4 Flash Memory Version Electrical Characteristics

Symbol	Parameter	Measuring condition	Standard			Unit
			Min.	Typ.	Max.	
—	Program/erase endurance		100	—	—	times
—	Byte program time		—	50	400	μs
—	Block erase time		—	0.4	9	s
td(SR-ES)	Time delay from suspend request until erase suspend		—	—	8	ms
—	Erase Suspend Request Interval		10	—	—	ms
—	Program, Erase voltage		2.7	—	5.5	V
—	Read voltage		2.7	—	5.5	V
—	Program, Erase temperature		0	—	60	°C
—	Data hold time ⁽²⁾	Ambient temperature=55 °C	20	—	—	year

NOTES:

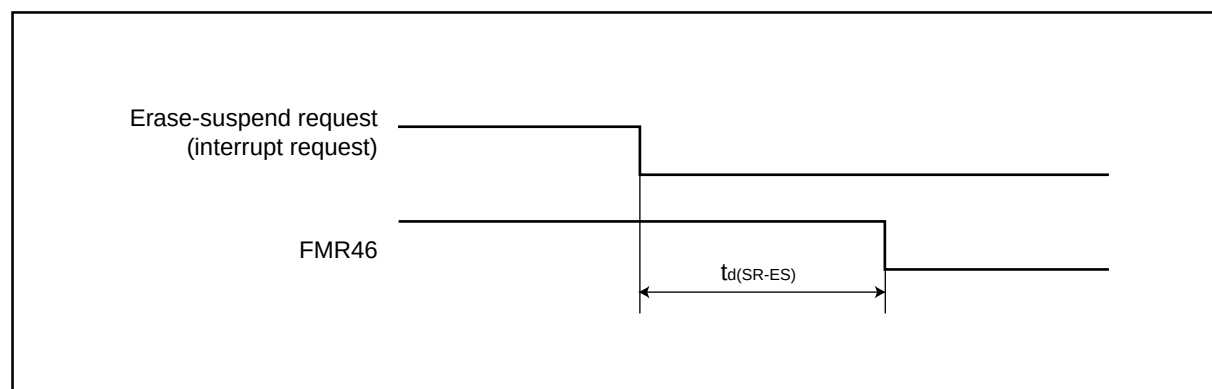
1. Referenced to V_{CC1}=AV_{CC}=2.7 to 5.5V at Topr = 0 to 60 °C unless otherwise specified.
2. The data hold time includes time that the power supply is off or the clock is not supplied.

Table 5.5 Voltage Detection Circuit Electrical Characteristics

Symbol	Parameter	Measuring condition	Standard			Unit
			Min.	Typ.	Max.	
Vdet	Voltage detection level		3.3	3.8	4.3	V
—	Voltage detection interrupt request generating time ⁽²⁾		—	40	—	μs
—	Voltage detection circuit self consumption current	VC27=1, VCC=5.0V	—	600	—	nA
td(E-A)	Waiting time till voltage detection circuit operation starts ⁽³⁾		—	—	20	μs
Vccmin	Minimum value of microcomputer operation voltage		2.7	—	—	V

NOTES:

1. The measuring condition is V_{CC}=AV_{CC}=2.7V to 5.5V and Topr= -40°C to 85 °C.
2. This shows the time until the voltage detection interrupt request is generated since the voltage passes Vdet.
3. This shows the required time until the voltage detection circuit operates when setting to "1" again after setting the VC27 bit in the VCR2 register to "0".

**Figure 5.2 Time delay from Suspend Request until Erase Suspend**

Timing requirements (Unless otherwise noted: $V_{CC} = 5V$, $V_{SS} = 0V$ at $T_{opr} = 25\text{ }^{\circ}C$) [$V_{CC}=5V$]**Table 5.12 XIN input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(XIN)$	XIN input cycle time	50	—	ns
$t_{WH}(XIN)$	XIN input HIGH pulse width	25	—	ns
$t_{WL}(XIN)$	XIN input LOW pulse width	25	—	ns

Table 5.13 CNTR0 input, CNTR1 input, $\overline{INT2}$ input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(CNTR0)$	CNTR0 input cycle time	100	—	ns
$t_{WH}(CNTR0)$	CNTR0 input HIGH pulse width	40	—	ns
$t_{WL}(CNTR0)$	CNTR0 input LOW pulse width	40	—	ns

Table 5.14 TCIN input, $\overline{INT3}$ input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(TCIN)$	TCIN input cycle time	400 ⁽¹⁾	—	ns
$t_{WH}(TCIN)$	TCIN input HIGH pulse width	200 ⁽²⁾	—	ns
$t_{WL}(TCIN)$	TCIN input LOW pulse width	200 ⁽²⁾	—	ns

NOTES:

1. When using the Timer C input capture mode, adjust the cycle time above (1/ Timer C count source frequency x 3).
2. When using the Timer C input capture mode, adjust the pulse width above (1/ Timer C count source frequency x 1.5).

Table 5.15 Serial Interface

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(CLKi)$	CLKi input cycle time	200	—	ns
$t_W(CLKH)$	CLKi input HIGH pulse width	100	—	ns
$t_W(CLKL)$	CLKi input LOW pulse width	100	—	ns
$t_d(C-Q)$	TxDi output delay time	—	80	ns
$t_h(C-Q)$	TxDi hold time	0	—	ns
$t_{su}(D-C)$	RxDi input setup time	35	—	ns
$t_h(C-D)$	RxDi input hold time	90	—	ns

Table 5.16 External interrupt $\overline{INT0}$ input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_W(\overline{INT0})$	$\overline{INT0}$ input HIGH pulse width	250 ⁽¹⁾	—	ns
$t_W(\overline{INT0})$	$\overline{INT0}$ input LOW pulse width	250 ⁽²⁾	—	ns

NOTES:

1. When selecting the digital filter by the $\overline{INT0}$ input filter select bit, use the $\overline{INT0}$ input HIGH pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.
2. When selecting the digital filter by the $\overline{INT0}$ input filter select bit, use the $\overline{INT0}$ input LOW pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.

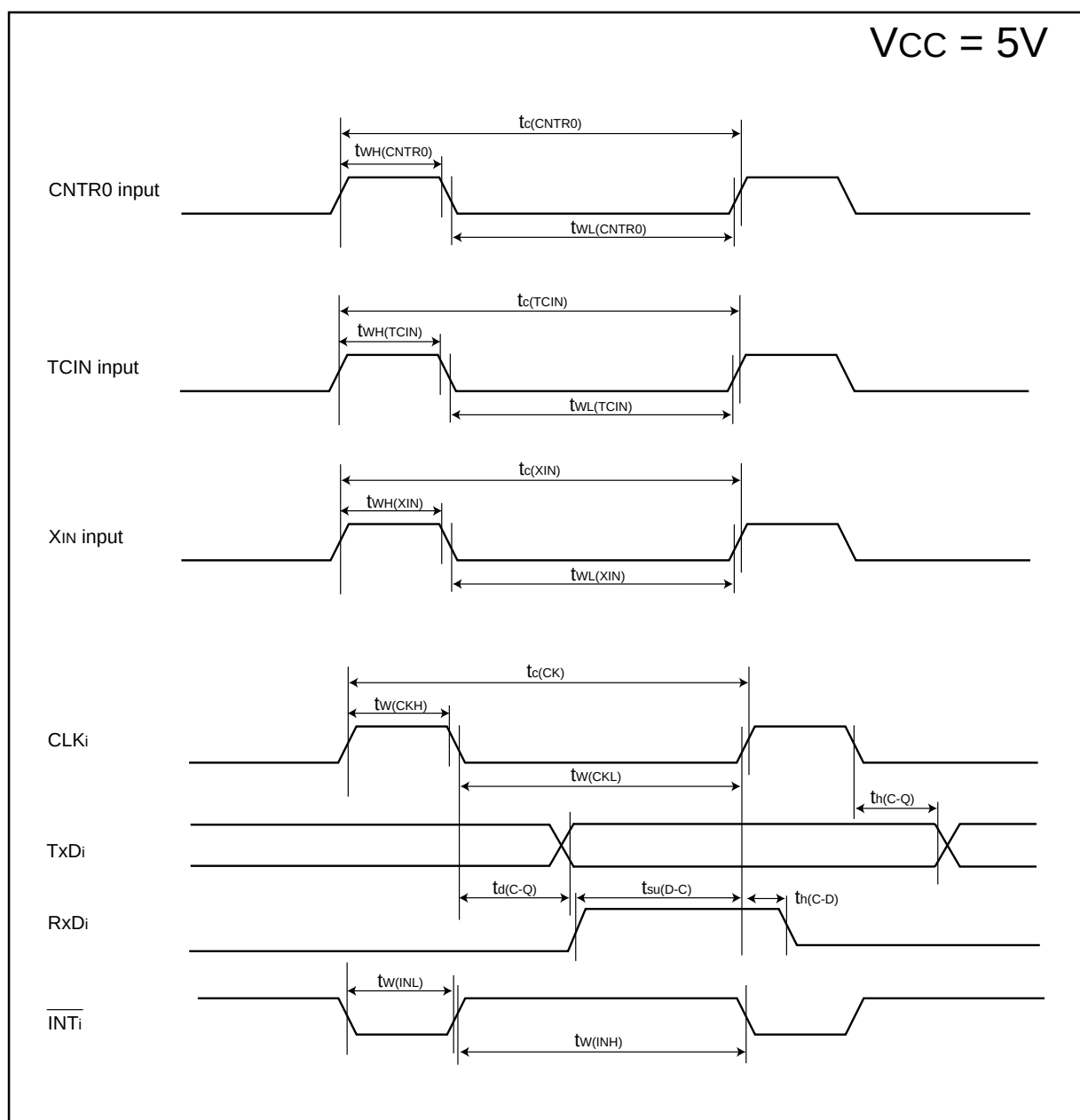
Figure 5.4 V_{CC}=5V timing diagram

Table 5.17 Electrical Characteristics (3) [Vcc=3V]

Symbol	Parameter		Measuring condition		Standard			Unit
					Min.	Typ.	Max.	
VOH	"H" output voltage	Except XOUT	IOH=-1mA		Vcc-0.5	—	Vcc	V
		XOUT	Drive capacity HIGH	IOH=-0.1 mA	Vcc-0.5	—	Vcc	V
			Drive capacity LOW	IOH=-50 μA	Vcc-0.5	—	Vcc	V
VOL	"L" output voltage	Except P10 to P17, XOUT	IOl= 1 mA		—	—	0.5	V
		P10 to P17	Drive capacity HIGH	IOl= 2 mA	—	—	0.5	V
			Drive capacity LOW	IOl= 1 mA	—	—	0.5	V
		XOUT	Drive capacity HIGH	IOl= 0.1 mA	—	—	0.5	V
			Drive capacity LOW	IOl=50 μA	—	—	0.5	V
VT+-VT-	Hysteresis	INT0, INT1, INT2, INT3, K10, K11, K12, K13, CNTR0, CNTR1, TCIN, RxD0, RxD1, P45			0.2	—	0.8	V
		RESET			0.2	—	1.8	V
IIH	"H" input current		VI=3V		—	—	4.0	μA
IIL	"L" input current		VI=0V		—	—	-4.0	μA
RPULLUP	Pull-up resistance		VI=0V		66	160	500	kΩ
RFXIN	Feedback resistance	XIN			—	3.0	—	MΩ
fRING-S	Low-speed on-chip oscillator frequency				40	125	250	kHz
V _{RAM}	RAM retention voltage		At stop mode		2.0	—	—	V

NOTES:

1. Referenced to Vcc = AVcc = 2.7 to 3.3V at Topr = -20 to 85 °C / -40 to 85 °C, f(XIN)=10MHz unless otherwise specified.

Table 5.18 Electrical Characteristics (4) [Vcc=3V]

Symbol	Parameter	Measuring condition	Standard			Unit
			Min.	Typ.	Max.	
I _{cc}	Power supply current (V _{cc} =2.7 to 3.3V) In single-chip mode, the output pins are open and other pins are V _{ss}	High-speed mode X _{IN} =20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division	—	8	13	mA
		X _{IN} =16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division	—	7	12	mA
		X _{IN} =10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz No division	—	5	—	mA
		Medium-speed mode X _{IN} =20 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	—	3	—	mA
		X _{IN} =16 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	—	2.5	—	mA
		X _{IN} =10 MHz (square wave) High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	—	1.6	—	mA
		High-speed on-chip oscillator mode Main clock off High-speed on-chip oscillator on=8 MHz Low-speed on-chip oscillator on=125 kHz No division	—	3.5	7.5	mA
		Main clock off High-speed on-chip oscillator on=8 MHz Low-speed on-chip oscillator on=125 kHz Division by 8	—	1.5	—	mA
		Low-speed on-chip oscillator mode Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz Division by 8	—	420	800	μA
		Wait mode Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz When a WAIT instruction is executed ⁽¹⁾ Peripheral clock operation VC27="0"	—	37	74	μA
		Wait mode Main clock off High-speed on-chip oscillator off Low-speed on-chip oscillator on=125 kHz When a WAIT instruction is executed ⁽¹⁾ Peripheral clock off VC27="0"	—	35	70	μA
		Stop mode Main clock off, T _{opr} = 25 °C High-speed on-chip oscillator off Low-speed on-chip oscillator off CM10="1" Peripheral clock off VC27="0"	—	0.7	3.0	μA

NOTES:

1. Timer Y is operated with timer mode.
2. Referenced to V_{cc} = AV_{cc} = 2.7 to 3.3V at T_{opr} = -20 to 85 °C / -40 to 85 °C, f(X_{IN})=10MHz unless otherwise specified.

Timing requirements (Unless otherwise noted: $V_{CC} = 3V$, $V_{SS} = 0V$ at $T_{opr} = 25\text{ }^{\circ}C$) [$V_{CC}=3V$]**Table 5.19 X_{IN} input**

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(X_{IN})$	X_{IN} input cycle time	100	—	ns
$t_{WH}(X_{IN})$	X_{IN} input HIGH pulse width	40	—	ns
$t_{WL}(X_{IN})$	X_{IN} input LOW pulse width	40	—	ns

Table 5.20 CNTR0 input, CNTR1 input, $\overline{INT2}$ input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(CNTR0)$	CNTR0 input cycle time	300	—	ns
$t_{WH}(CNTR0)$	CNTR0 input HIGH pulse width	120	—	ns
$t_{WL}(CNTR0)$	CNTR0 input LOW pulse width	120	—	ns

Table 5.21 TCIN input, $\overline{INT3}$ input

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(TCIN)$	TCIN input cycle time	1200 ⁽¹⁾	—	ns
$t_{WH}(TCIN)$	TCIN input HIGH pulse width	600 ⁽²⁾	—	ns
$t_{WL}(TCIN)$	TCIN input LOW pulse width	600 ⁽²⁾	—	ns

NOTES:

1. When using the Timer C input capture mode, adjust the cycle time above (1/ Timer C count source frequency x 3).
2. When using the Timer C input capture mode, adjust the pulse width above (1/ Timer C count source frequency x 1.5).

Table 5.22 Serial Interface

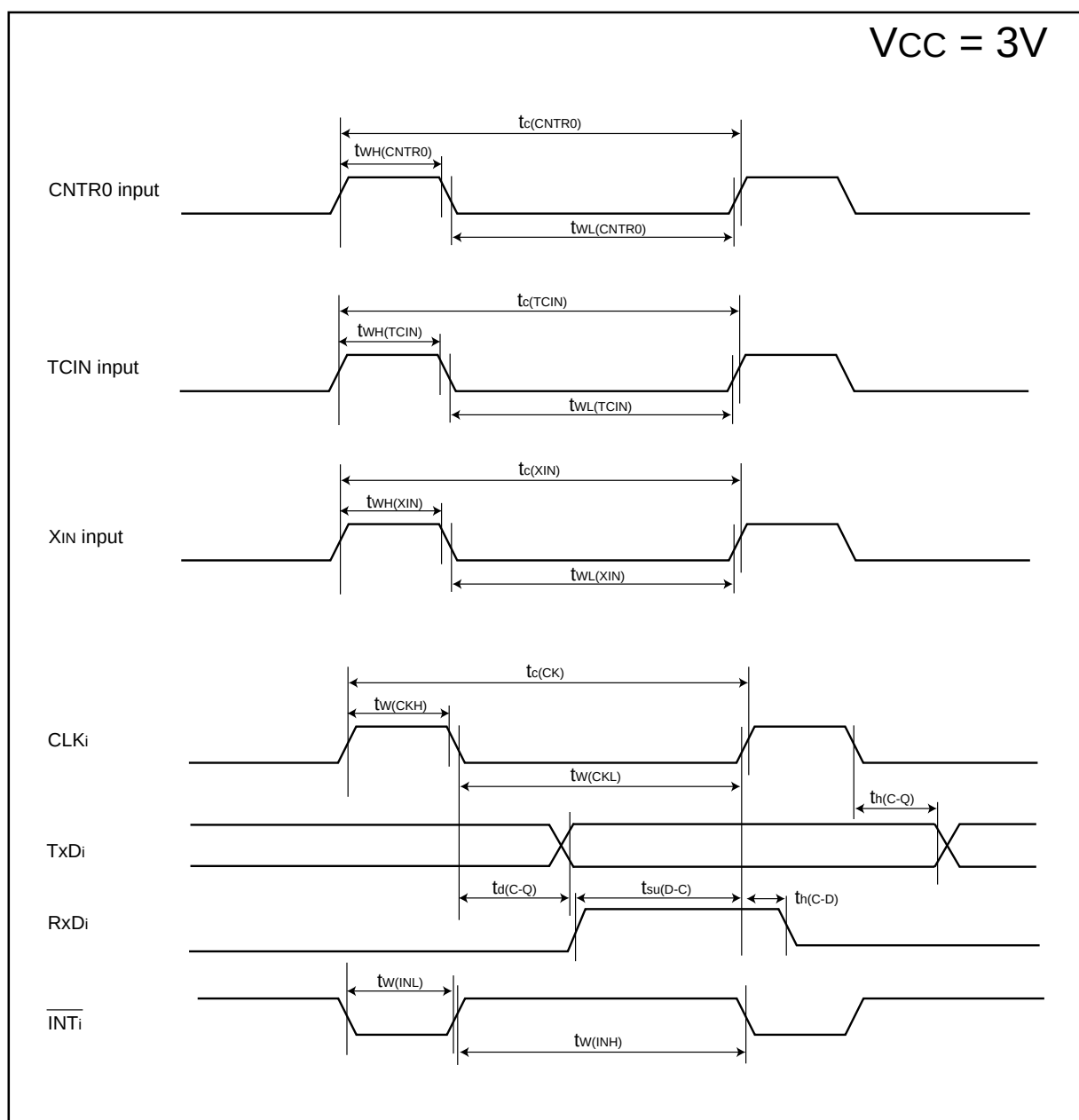
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_C(CK)$	CLKi input cycle time	300	—	ns
$t_W(CKH)$	CLKi input HIGH pulse width	150	—	ns
$t_W(CKL)$	CLKi input LOW pulse width	150	—	ns
$t_d(C-Q)$	TxDi output delay time	—	160	ns
$t_h(C-Q)$	TxDi hold time	0	—	ns
$t_{su}(D-C)$	RxDi input setup time	55	—	ns
$t_h(C-D)$	RxDi input hold time	90	—	ns

Table 5.23 External interrupt $\overline{INT0}$ input

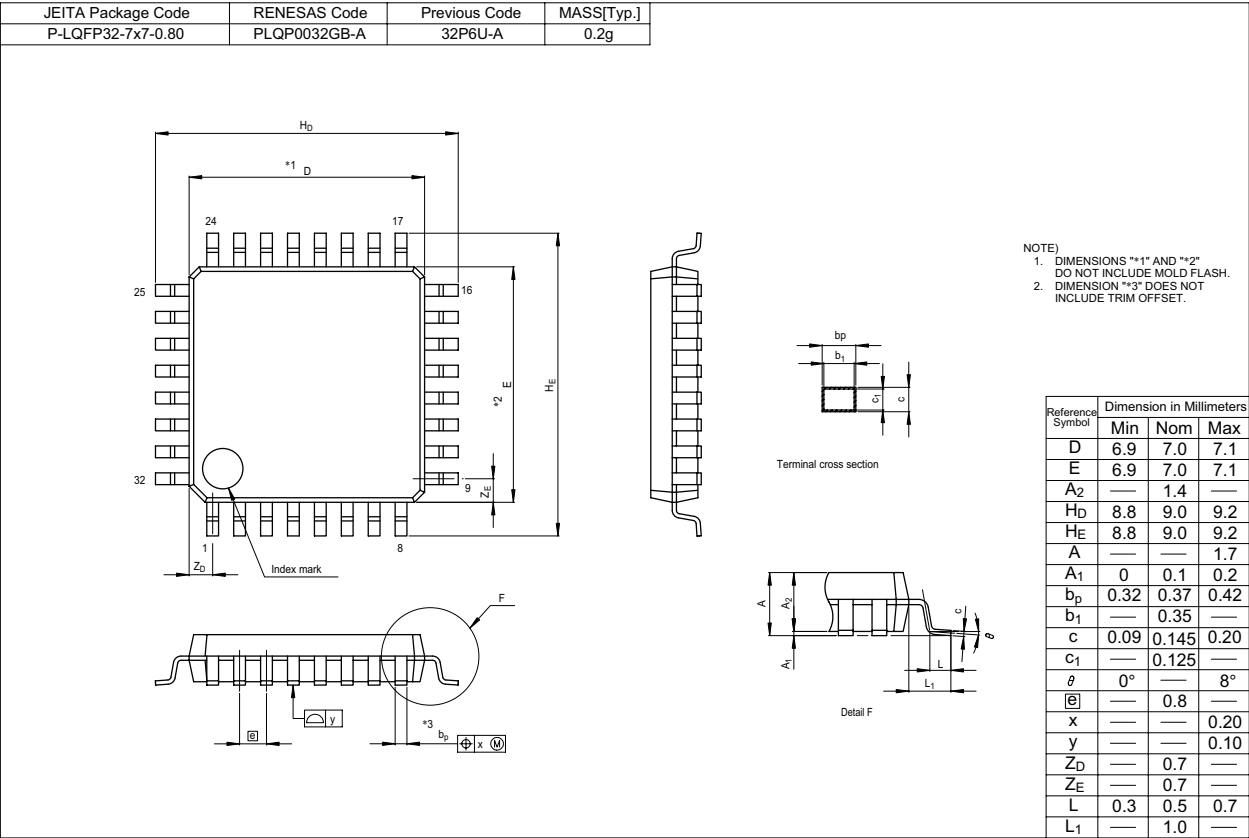
Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_W(INH)$	$\overline{INT0}$ input HIGH pulse width	380 ⁽¹⁾	—	ns
$t_W(INL)$	$\overline{INT0}$ input LOW pulse width	380 ⁽²⁾	—	ns

NOTES:

1. When selecting the digital filter by the $\overline{INT0}$ input filter select bit, use the $\overline{INT0}$ input HIGH pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.
2. When selecting the digital filter by the $\overline{INT0}$ input filter select bit, use the $\overline{INT0}$ input LOW pulse width to the greater value, either (1/ digital filter clock frequency x 3) or the minimum value of standard.

Figure 5.5 $V_{CC}=3V$ timing diagram

Package Dimensions



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Rev.	Date	Description	
		Page	Summary
1.00	Jun. 19, 2003		First edition issued
1.10	Sep. 08, 2003	2 5 6 10 12 14	Table 1.1: Shortest instruction execution time and $f(X_{IN})$ changed Figure 1.3: Pin name changed from TXOUT to $\overline{CNTR0}$ Table 1.3: Pin name changed from TXOUT to $\overline{CNTR0}$ The value of HR1 register after reset changed The value of TC register after reset changed Chapter "5. Electrical Characteristics" added
1.20	Oct. 31, 2003	2 6 11 14 15 17 19 20 21 22 23 24 25	Table 1.1: Power consumption values added Table 1.3: Resistor value for CNVss and MODE deleted Register name of address 0050 ₁₆ modified from CMP2IC to CMP1IC, register name of address 005C ₁₆ modified from CMP1IC to CMP0IC Table 5.2: Note 3 and Note 4 deleted tsamp in Table 5.3 deleted Figure 5.1 added Table 5.10: Vcc changed from "4.2 to 5.5V" to "3.3V to 5.5V", low-power on-chip oscillator changed from "on 100kHz" to "125kHz", $X_{IN}=5\text{MHz}$ deleted and $X_{IN}=10\text{MHz}$ added in high-speed mode and medium-speed mode, VC27="0" added in stop mode measuring condition, data added and modified Table 11 to Table 15 added Figure 5.2 added Table 5.16: Note 1, $f(\text{BCLK})=5\text{ MHz}$ changed to 10 MHz Table 5.17: low-power ring oscillator changed from "on 100kHz" to "125kHz", $X_{IN}=5\text{MHz}$ deleted and $X_{IN}=10\text{MHz}$ added in high-speed mode and medium-speed mode, VC27="0" added in stop mode measuring condition, data added and modified Table 5.18 to Table 5.22 added Figure 5.3 added
1.30	Dec 05, 2003	4 15	Table 1.2 : ** deleted Table 5.4 revised
1.40	Sep 30, 2004	all pages 2 5 6 9 10-13 12 14 15 16 17 18	Words standardized (on-chip oscillator, serial interface, A/D) Table 1.1 revised Figure 1.3, NOTES 3 added Table 1.3 revised Figure 3.1, NOTES added One body sentence in chapter 4 added ; Title of Table 4.1 to 4.4 added Table 4.3 revised ; Table 4.4 revised Table 5.2 revised Table 5.3 revised Table 5.4 revised ; Table 16.5 revised Table 5.6, 5.7 adn 5.8 revised ; Figure 5.3 revised Table 5.9 revised ; Table 5.10 revised

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Rev.	Date	Description	
		Page	Summary
1.40	Sep 30, 2004	20	Table 5.12 revised ; Table 5.16 revised
		22	Table 16.17 revised
		24	Table 16.19 revised
1.50	Apr.27.2005	4	Table 1.2, Figure 1.2 package name revised
		5	Figure 1.3 package name revised
		10	Table 4.1 revised
		12	Table 4.3 revised
		15	Table 5.3 partly revised
		16	Table 5.4 partly added
		17	Table 5.6, Table 5.7 revised
		18	Table 5.9, Table 10 partly revised
		22	Table 5.17 partly revised
		26	Package Dimensions revised
1.60	Jan.27.2006	2	Table 1.1 Performance outline revised
		3	Figure 1.1 Block diagram partly revised
		4	1.4 Product Information, title of Table 1.2 "Product List" → "Product Informaton" revised
			Figure 1.2 Type No., Memory Size, and Package partly revised
		6	Table 1.3 Pin description revised
		7-8	2 Central Processing Unit (CPU) revised
			Figure 2.1 CPU register revised
		10	Table 4.1 SFR Information(1) NOTES:1 revised
		11	Table 4.2 SFR Information(2) NOTES:1 revised
		12	Table 4.3 SFR Information(3); 0081 ₁₆ : "Prescaler Y" → "Prescaler Y Register"
			0082 ₁₆ : "Timer Y Secondary" → "Timer Y Secondary Register"
			0083 ₁₆ : "Timer Y Primary" → "Timer Y Primary Register"
			0085 ₁₆ : "Prescaler Z" → "Prescaler Z Register"
			0086 ₁₆ : "Timer Z Secondary" → "Timer Z Secondary Register"
			0087 ₁₆ : "Timer Z Primary" → "Timer Z Primary Register"
			008C ₁₆ : "Prescaler X" → "Prescaler X Register" revised
			NOTES:1, 2 revised
		13	Table 4.4 SFR Information(4) NOTES:1 revised
		14	Table 5.2 Recommended Operating Conditions; NOTES: 1, 2, 3 revised
		15	Table 5.3 A/D Conversion Characteristics; "A/D operation clock frequency" → "A/D operating clock frequency" revised
			NOTES: 1, 2, 3, 4 revised
		16	Table 5.4 Flash Memory (Program ROM) Electrical Characteristics; "Topr" → "Ambient temperature" revised
			Measuring condition of byte program time and block erase time deleted
		17	Table 5.6 Reset Circuit Electrical Characteristics (When Using Hardware Reset 2) NOTES: 3 revised
		18	Table 5.8 High-speed On-Chip Oscillator Circuit Electrical Characteristics; "High-speed on-chip oscillator temperature dependence" → "High-speed on-chip oscillator frequency temperature dependence" revised
			Table 5.10 Electrical Characteristics (1) [V _{CC} =5V]; "P1 ₀ to P1 ₇ Except Xout" → "Except P1 ₀ to P1 ₇ , Xout" revised

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