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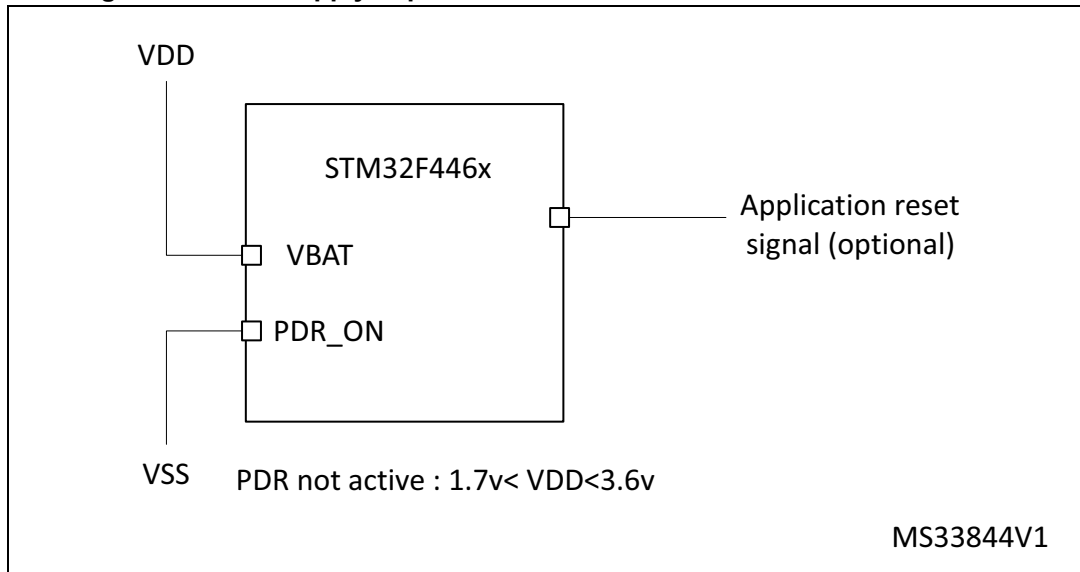
"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	180MHz
Connectivity	CANbus, EBI/EMI, I ² C, IrDA, LINbus, SAI, SD, SPDIF-Rx, SPI, UART/USART, USB, USB OTG
Peripherals	Brown-out Detect/Reset, DMA, I ² S, LVD, POR, PWM, WDT
Number of I/O	63
Program Memory Size	256KB (256K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	128K x 8
Voltage - Supply (Vcc/Vdd)	1.7V ~ 3.6V
Data Converters	A/D 14x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	81-UFBGA, WLCSP
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/stm32f446mcy6tr

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Figure 6. Power supply supervisor interconnection with internal reset OFF

The V_{DD} specified threshold, below which the device must be maintained under reset, is 1.7 V.

A comprehensive set of power-saving mode allows to design low-power applications.

When the internal reset is OFF, the following integrated features are no more supported:

- The integrated power-on reset (POR) / power-down reset (PDR) circuitry is disabled
- The brownout reset (BOR) circuitry must be disabled
- The embedded programmable voltage detector (PVD) is disabled
- V_{BAT} functionality is no more available and V_{BAT} pin should be connected to V_{DD} .

All packages, except for the LQFP100/LQFP64, allow to disable the internal reset through the PDR_ON signal.

3.17 Voltage regulator

The regulator has four operating modes:

- Regulator ON
 - Main regulator mode (MR)
 - Low power regulator (LPR)
 - Power-down
- Regulator OFF

3.17.1 Regulator ON

On packages embedding the BYPASS_REG pin, the regulator is enabled by holding BYPASS_REG low. On all other packages, the regulator is always enabled.

Table 10. STM32F446xx pin and ball descriptions (continued)

Pin Number					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64	LQFP100	WLCSP 81	UFBGA144	LQFP144						
6	13	F9	E1	24	PH1-OSC_OUT(PH1)	I/O	FT	-	EVENTOUT	OSC_OUT
7	14	D8	F1	25	NRST	I/O	RS T	-	-	-
8	15	G9	H1	26	PC0	I/O	FT	-	SAI1_MCLK_B, OTG_HS_ULPI_STP, FMC_SDNWE, EVENTOUT	ADC123_IN10
9	16	-	H2	27	PC1	I/O	FT	-	SPI3_MOSI/I2S3_SD, SAI1_SD_A, SPI2_MOSI/I2S2_SD, EVENTOUT	ADC123_IN11
10	17	E8	H3	28	PC2	I/O	FT	-	SPI2_MISO, OTG_HS_ULPI_DIR, FMC_SDNE0, EVENTOUT	ADC123_IN12
11	18	F8	H4	29	PC3	I/O	FT	-	SPI2_MOSI/I2S2_SD, OTG_HS_ULPI_NXT, FMC_SDCKE0, EVENTOUT	ADC123_IN13
-	19	H9	-	30	VDD	S	-	-	-	-
-	-	G8	-	-	VSS	S	-	-	-	-
12	20	F7	J1	31	VSSA	S	-	-	-	-
-	-	-	K1	-	VREF-	S	-	-	-	-
-	21	-	L1	32	VREF+	S	-	-	-	-
13	22	H8	M1	33	VDDA	S	-	-	-	-
14	23	J9	J2	34	PA0-WKUP(PA0)	I/O	FT	-	TIM2_CH1/TIM2_ETR, TIM5_CH1, TIM8_ETR, USART2_CTS, UART4_TX, EVENTOUT	ADC123_IN0, WKUP0/TAMP_2
15	24	G7	K2	35	PA1	I/O	FT	-	TIM2_CH2, TIM5_CH2, USART2_RTS, UART4_RX, QUADSPI_BK1_IO3, SAI2_MCLK_B, EVENTOUT	ADC123_IN1
16	25	E7	L2	36	PA2	I/O	FT	-	TIM2_CH3, TIM5_CH3, TIM9_CH1, USART2_TX, SAI2_SCK_B, EVENTOUT	ADC123_IN2

Table 10. STM32F446xx pin and ball descriptions (continued)

Pin Number					Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64	LQFP100	WLCSP 81	UFBGA144	LQFP144						
34	52	H2	M12	74	PB13	I/O	FT	-	TIM1_CH1N, SPI2_SCK/I2S2_CK, USART3_CTS, CAN2_TX, OTG_HS_ULPI_D6, EVENTOUT	OTG_HS_VBUS
35	53	J1	L11	75	PB14 ⁽¹⁾	I/O	FT	-	TIM1_CH2N, TIM8_CH2N, SPI2_MISO, USART3_RTS, TIM12_CH1, OTG_HS_DM, EVENTOUT	-
36	54	G3	L12	76	PB15 ⁽¹⁾	I/O	FT	-	RTC_REFIN, TIM1_CH3N, TIM8_CH3N, SPI2_MOSI/I2S2_SD, TIM12_CH2, OTG_HS_DP, EVENTOUT	-
-	55	-	L9	77	PD8	I/O	FT	-	USART3_TX, SPDIFRX_IN1, FMC_D13, EVENTOUT	-
-	56	-	K9	78	PD9	I/O	FT	-	USART3_RX, FMC_D14, EVENTOUT	-
-	57	-	J9	79	PD10	I/O	FT	-	USART3_CK, FMC_D15, EVENTOUT	-
-	58	H1	H9	80	PD11	I/O	FT	-	FMPI2C1_SMBA, USART3_CTS, QUADSPI_BK1_IO0, SAI2_SD_A, FMC_A16, EVENTOUT	-
-	59	G2	L10	81	PD12	I/O	FTf	-	TIM4_CH1, FMPI2C1_SCL, USART3_RTS, QUADSPI_BK1_IO1, SAI2_FS_A, FMC_A17, EVENTOUT	-
-	60	G1	K10	82	PD13	I/O	FTf	-	TIM4_CH2, FMPI2C1_SDA, QUADSPI_BK1_IO3, SAI2_SCK_A, FMC_A18, EVENTOUT	-
-	-	-	G8	83	VSS	S	-	-	-	-
-	-	-	F8	84	VDD	S	-	-	-	-

Table 11. Alternate function (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7	AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		SYS	TIM1/2	TIM3/4/5	TIM8/9/ 10/11/ CEC	I2C1/2/3 /4/CEC	SPI1/2/3/ 4	SPI2/3/4/ SAI1	SPI2/3/ USART1/ 2/3/UART 5/SPDIFR X	SAI/ USART6/ UART4/5/ SPDIFRX	CAN1/2 TIM12/13/ 14/ QUADSPI	SAI2/ QUADSPI/ OTG2_HS/ OTG1_FS	OTG1_FS	FMC/ SDIO/ OTG2_FS	DCMI	-	SYS
Port E	PE0	-	-	TIM4_ETR	-	-	-	-	-	-	-	SAI2_ MCLK_A	-	FMC_ NBL0	DCMI_D2	-	EVENT OUT
	PE1	-	-	-	-	-	-	-	-	-	-	-	-	FMC_ NBL1	DCMI_D3	-	EVENT OUT
	PE2	TRACE CLK	-	-	-	-	SPI4_SCK	SAI1_ MCLK_A	-	-	QUADSPI_ BK1_IO2	-	-	FMC_A23	-	-	EVENT OUT
	PE3	TRACE D0	-	-	-	-	-	SAI1_ SD_B	-	-	-	-	-	FMC_A19	-	-	EVENT OUT
	PE4	TRACE D1	-	-	-	-	SPI4_NSS	SAI1_ FS_A	-	-	-	-	-	FMC_A20	DCMI_D4	-	EVENT OUT
	PE5	TRACE D2	-	-	TIM9_CH1	-	SPI4_MISO	SAI1_ SCK_A	-	-	-	-	-	FMC_A21	DCMI_D6	-	EVENT OUT
	PE6	TRACE D3	-	-	TIM9_CH2	-	SPI4_MOSI	SAI1_ SD_A	-	-	-	-	-	FMC_A22	DCMI_D7	-	EVENT OUT
	PE7	-	TIM1_ETR	-	-	-	-	-	-	UART5_RX	-	QUADSPI_ BK2_IO0	-	FMC_D4	-	-	EVENT OUT
	PE8	-	TIM1_CH1N	-	-	-	-	-	-	UART5_TX	-	QUADSPI_ BK2_IO1	-	FMC_D5	-	-	EVENT OUT
	PE9	-	TIM1_CH1	-	-	-	-	-	-	-	-	QUADSPI_ BK2_IO2	-	FMC_D6	-	-	EVENT OUT
	PE10	-	TIM1_CH2N	-	-	-	-	-	-	-	-	QUADSPI_ BK2_IO3	-	FMC_D7	-	-	EVENT OUT
	PE11	-	TIM1_CH2	-	-	-	SPI4_NSS	-	-	-	-	SAI2_ SD_B	-	FMC_D8	-	-	EVENT OUT
	PE12	-	TIM1_CH3N	-	-	-	SPI4_SCK	-	-	-	-	SAI2_ SCK_B	-	FMC_D9	-	-	EVENT OUT
	PE13	-	TIM1_CH3	-	-	-	SPI4_MISO	-	-	-	-	SAI2_ FS_B	-	FMC_D10	-	-	EVENT OUT
	PE14	-	TIM1_CH4	-	-	-	SPI4_MOSI	-	-	-	-	SAI2_ MCLK_B	-	FMC_D11	-	-	EVENT OUT
	PE15	-	TIM1_BKIN	-	-	-	-	-	-	-	-	-	-	FMC_D12	-	-	EVENT OUT

Table 25. Typical and maximum current consumption in Run mode, code with data processing running from Flash memory (ART accelerator disabled)

Symbol	Parameter	Conditions	f _{HCLK} (MHz)	Typ	Max ⁽¹⁾			Unit
					TA=25 °C	TA=85 °C	TA=105 °C	
I _{DD}	Supply current in RUN mode	External clock, PLL ON, all peripherals enabled ⁽²⁾⁽³⁾	180	81	89.0	110.0	120.0	mA
			168 ⁽⁴⁾	74	80.2	105.7	112.0	
			150	69	74.9	99.5	105.6	
			144 ⁽⁴⁾	63	69.3	92.4	98.1	
			120	51	56.3	76.1	81.1	
			90	40	45.32	63.19	67.63	
			60	28	33.1	48.7	52.6	
			30	16	20.8	34.0	37.4	
			25	13	18.4	31.2	34.5	
		External clock, PLL ON, all Peripherals disabled ⁽²⁾⁽³⁾	16	8	13.8	25.0	28.2	
			8	5	10.8	21.1	24.2	
			4	3.0	9.1	19.0	22.0	
			2	2.1	8.1	17.9	20.9	
			180	41	47.0	69.0	79.0	
			168	38	43.2	61.9	67.1	
			150	37	41.8	60.3	65.4	
			144 ⁽⁴⁾	34	39.3	56.9	61.6	
			120	29	34.3	50.2	54.4	
		HSI, PLL OFF, all peripherals disabled ⁽³⁾	90	24	28.8	43.6	47.5	
			60	17	22.0	35.6	39.2	
			30	10	14.8	27.0	30.1	
			25	8	13.51	25.36	28.47	
		HSI, PLL OFF, all Peripherals disabled ⁽³⁾	16	5	11.1	21.8	24.9	
			8	3	9.5	19.4	22.5	
			4	2.3	8.35	18.12	21.17	
			2	1.8	7.78	17.42	20.51	

1. Guaranteed based on test during characterization unless otherwise specified.
2. When analog peripheral blocks such as ADCs, DACs, HSE, LSE, HSI, or LSI are ON, an additional power consumption should be considered.
3. When the ADC is ON (ADON bit set in the ADC_CR2 register), add an additional power consumption of 1.6 mA per ADC for the analog part.
4. Overdrive OFF

Table 26. Typical and maximum current consumption in Sleep mode⁽¹⁾

Symbol	Parameter	Conditions		fHCLK (MHz)	Typ	Max			Unit
						T _A = 25 °C	T _A = 25 °C	T _A = 25 °C	
IDD	Supply current in Sleep mode	all peripherals enabled	External clock, PLL ON, Flash on	180	51.2	59.00	77.25	102.00	mA
				168 ⁽²⁾	46.8	53.94	66.48	79.40	
				150	42.2	49.26	60.84	73.41	
				144 ⁽²⁾	38.6	45.37	55.47	66.96	
				120	29.3	35.70	42.49	51.46	
				90	22.8	29.17	34.78	43.12	
				60	16.3	22.41	27.12	34.83	
				30	10.1	16.03	19.72	26.86	
				25	9.0	14.92	18.41	25.38	
			HSI, PLL off, Flash on	16	6.5	13.10	15.1	22.3	
				8	5.2	12.31	13.5	20.4	
				4	4.5	11.63	12.5	19.3	
				2	4.1	11.23	12.0	18.8	

Table 37. High-speed external user clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSE_ext}	External user clock source frequency ⁽¹⁾	-	1	-	50	MHz
V_{HSEH}	OSC_IN input pin high level voltage		$0.7V_{DD}$	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	
$t_{w(HSE)}$ $t_{f(HSE)}$	OSC_IN high or low time ⁽¹⁾		5	-	-	ns
$t_{r(HSE)}$ $t_{f(HSE)}$	OSC_IN rise or fall time ⁽¹⁾		-	-	10	
$C_{in(HSE)}$	OSC_IN input capacitance ⁽¹⁾	-	-	5	-	pF
$DuCy_{(HSE)}$	Duty cycle	-	45	-	55	%
I_L	OSC_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_{DD}$	-	-	± 1	μA

1. Guaranteed by design.

Low-speed external user clock generated from an external source

In bypass mode the LSE oscillator is switched off and the input pin is a standard I/O. The external clock signal has to respect the [Table 56: I/O static characteristics](#). However, the recommended clock input waveform is shown in [Figure 24](#).

The characteristics given in [Table 38](#) result from tests performed using an low-speed external clock source, and under ambient temperature and supply voltage conditions summarized in [Table 16](#).

Table 38. Low-speed external user clock characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{LSE_ext}	User External clock source frequency ⁽¹⁾	-	-	32.768	1000	kHz
V_{LSEH}	OSC32_IN input pin high level voltage		$0.7V_{DD}$	-	V_{DD}	V
V_{LSEL}	OSC32_IN input pin low level voltage		V_{SS}	-	$0.3V_{DD}$	
$t_{w(LSE)}$ $t_{f(LSE)}$	OSC32_IN high or low time ⁽¹⁾		450	-	-	ns
$t_{r(LSE)}$ $t_{f(LSE)}$	OSC32_IN rise or fall time ⁽¹⁾		-	-	200	
$C_{in(LSE)}$	OSC32_IN input capacitance ⁽¹⁾	-	-	5	-	pF
$DuCy_{(LSE)}$	Duty cycle	-	30	-	70	%
I_L	OSC32_IN Input leakage current	$V_{SS} \leq V_{IN} \leq V_{DD}$	-	-	± 1	μA

1. Guaranteed by design.

Figure 29 and Figure 30 show the main PLL output clock waveforms in center spread and down spread modes, where:

- F0 is f_{PLL_OUT} nominal.
- T_{mode} is the modulation period.
- md is the modulation depth.

Figure 29. PLL output clock waveforms in center spread mode

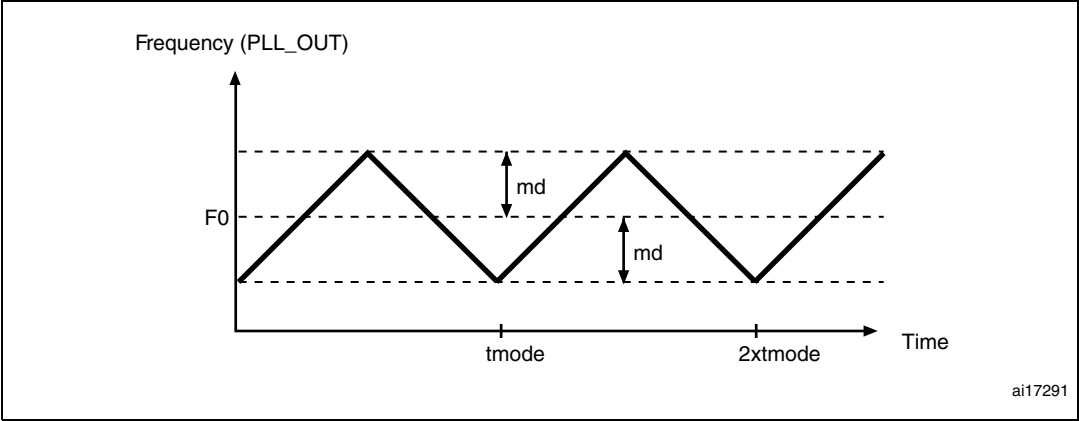
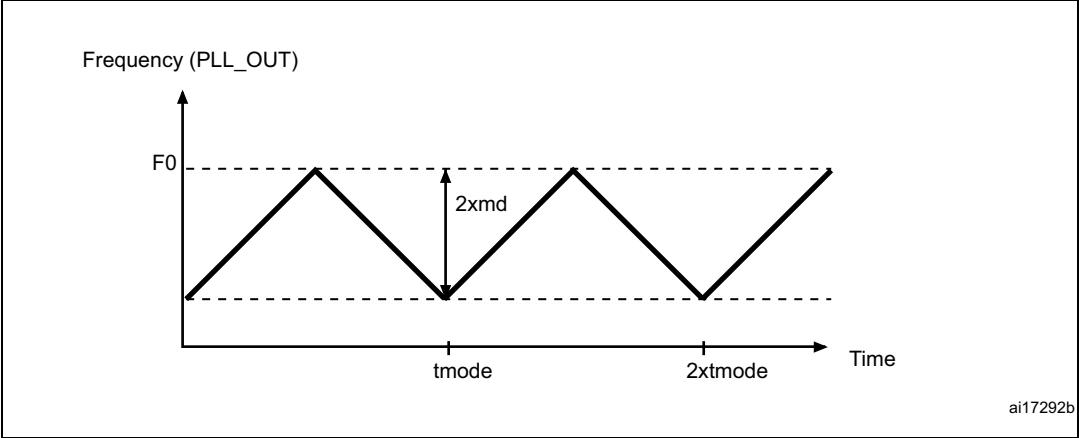


Figure 30. PLL output clock waveforms in down spread mode



6.3.13 Memory characteristics

Flash memory

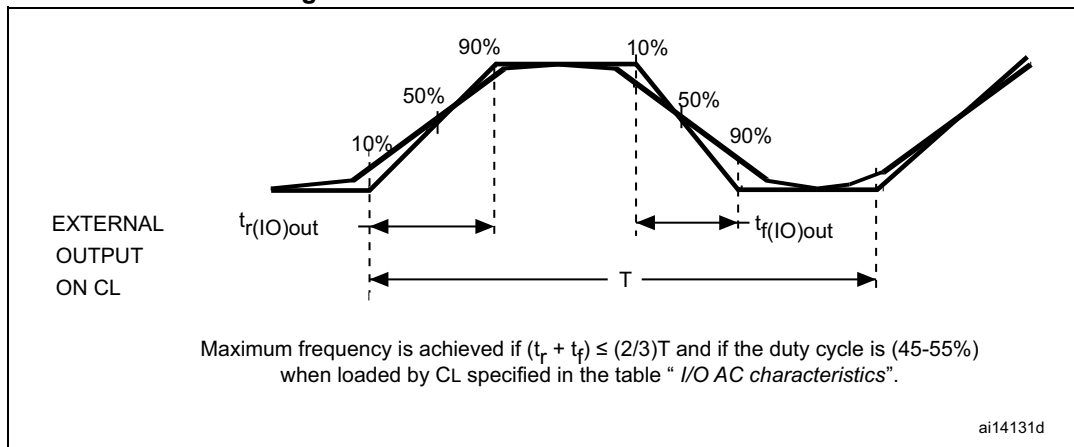
The characteristics are given at $T_A = -40$ to $105\text{ }^{\circ}\text{C}$ unless otherwise specified.
The devices are shipped to customers with the Flash memory erased.

Table 47. Flash memory characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{DD}	Supply current	Write / Erase 8-bit mode, $V_{DD} = 1.7\text{ V}$	-	5	-	mA
		Write / Erase 16-bit mode, $V_{DD} = 2.1\text{ V}$	-	8	-	
		Write / Erase 32-bit mode, $V_{DD} = 3.3\text{ V}$	-	12	-	

1. Guaranteed by design.
2. The I/O speed is configured using the OSPEEDRy[1:0] bits. Refer to the STM32F4xx reference manual for a description of the GPIOx_SPEEDR GPIO port output speed register.
3. The maximum frequency is defined in [Figure 32](#).
4. For maximum frequencies above 50 MHz and $V_{DD} > 2.4$ V, the compensation cell should be used.

Figure 32. I/O AC characteristics definition



6.3.18 NRST pin characteristics

The NRST pin input driver uses CMOS technology. It is connected to a permanent pull-up resistor, R_{PU} (see [Table 56: I/O static characteristics](#)).

Unless otherwise specified, the parameters given in [Table 59](#) are derived from tests performed under the ambient temperature and V_{DD} supply voltage conditions summarized in [Table 16](#).

Table 59. NRST pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
R_{PU}	Weak pull-up equivalent resistor ⁽¹⁾	$V_{IN} = V_{SS}$	30	40	50	k Ω
$V_{F(NRST)}^{(2)}$	NRST Input filtered pulse	-	-	-	100	ns
$V_{NF(NRST)}^{(2)}$	NRST Input not filtered pulse	$V_{DD} > 2.7$ V	300	-	-	ns
T_{NRST_OUT}	Generated reset pulse duration	Internal Reset source	20	-	-	μ s

1. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance must be minimum (~10% order).
2. Guaranteed by design.

SPI interface characteristics

Unless otherwise specified, the parameters given in [Table 63](#) for SPI are derived from tests performed under the ambient temperature, fPCLKx frequency and VDD supply voltage conditions summarized in [Table 16](#), with the following configuration:

- Output speed is set to OSPEEDRy[1:0] = 10
- Capacitive load C=30pF
- Measurement points are done at CMOS levels: 0.5VDD

Refer to [Section 6.3.17: I/O port characteristics](#) for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO for SPI).

Table 63. SPI dynamic characteristics⁽¹⁾

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{SCK} 1/ $t_{c(SCK)}$	SPI clock frequency	Master full duplex/receiver mode, 2.7 V ≤ V _{DD} ≤ 3.6 V SPI1/4	-	-	45	MHz
		Master transmitter 1.71V < V _{DD} < 3.6V SPI1/4			45	
		Master 1.71V < V _{DD} < 3.6V SPI1/2/3/4			22.5	
		Slave transmitter/ full duplex mode SPI1/4 2.7V < V _{DD} < 3.6V			45	
		Slave receiver mode SPI1/4 1.71V < V _{DD} < 3.6V			45	
		Slave mode SPI1/2/3/4 1.71V < V _{DD} < 3.6V			22.5 ⁽²⁾	
Duty(SCK)	Duty cycle of SPI clock frequency	Slave mode	30	50	70	%

6.3.21 12-bit ADC characteristics

Unless otherwise specified, the parameters given in [Table 74](#) are derived from tests performed under the ambient temperature, f_{PCLK2} frequency and V_{DDA} supply voltage conditions summarized in [Table 16](#).

Table 74. ADC characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Power supply	$V_{DDA} - V_{REF+} < 1.2\text{ V}$	1.7 ⁽¹⁾	-	3.6	V
V_{REF+}	Positive reference voltage		1.7 ⁽¹⁾	-	V_{DDA}	
V_{REF-}	Negative reference voltage	-	-	0	-	
f_{ADC}	ADC clock frequency	$V_{DDA} = 1.7^{(1)} \text{ to } 2.4\text{ V}$	0.6	15	18	MHz
		$V_{DDA} = 2.4 \text{ to } 3.6\text{ V}$	0.6	30	36	MHz
$f_{TRIG}^{(2)}$	External trigger frequency	$f_{ADC} = 30\text{ MHz}$, 12-bit resolution	-	-	1764	kHz
		-	-	-	17	$1/f_{ADC}$
V_{AIN}	Conversion voltage range ⁽³⁾	-	0 (V_{SSA} or V_{REF-} tied to ground)		V_{REF+}	V
$R_{AIN}^{(2)}$	External input impedance	See Equation 1 for details	-	-	50	$\kappa\Omega$
$R_{ADC}^{(2)(4)}$	Sampling switch resistance	-	-	-	6	$\kappa\Omega$
$C_{ADC}^{(2)}$	Internal sample and hold capacitor	-	-	4	7	pF
$t_{lat}^{(2)}$	Injection trigger conversion latency	$f_{ADC} = 30\text{ MHz}$	-	-	0.100	μs
		-	-	-	3 ⁽⁵⁾	$1/f_{ADC}$
$t_{latr}^{(2)}$	Regular trigger conversion latency	$f_{ADC} = 30\text{ MHz}$	-	-	0.067	μs
		-	-	-	2 ⁽⁵⁾	$1/f_{ADC}$
$t_S^{(2)}$	Sampling time	$f_{ADC} = 30\text{ MHz}$	0.100	-	16	μs
		-	3	-	480	$1/f_{ADC}$
$t_{STAB}^{(2)}$	Power-up time	-	-	2	3	μs
$t_{CONV}^{(2)}$	Total conversion time (including sampling time)	$f_{ADC} = 30\text{ MHz}$ 12-bit resolution	0.50	-	16.40	μs
		$f_{ADC} = 30\text{ MHz}$ 10-bit resolution	0.43	-	16.34	μs
		$f_{ADC} = 30\text{ MHz}$ 8-bit resolution	0.37	-	16.27	μs
		$f_{ADC} = 30\text{ MHz}$ 6-bit resolution	0.30	-	16.20	μs
		9 to 492 (t_S for sampling +n-bit resolution for successive approximation)				$1/f_{ADC}$

6.3.23 V_{BAT} monitoring characteristics

Table 82. V_{BAT} monitoring characteristics

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor bridge for V_{BAT}	-	50	-	K Ω
Q	Ratio on V_{BAT} measurement	-	4	-	-
$Er^{(1)}$	Error on Q	- 1	-	+ 1	%
$T_{S_vbat}^{(2)(2)}$	ADC sampling time when reading the V_{BAT} 1 mV accuracy	5	-	-	μs

1. Guaranteed by design.
2. Shortest sampling time can be determined in the application by multiple iterations.

6.3.24 Reference voltage

The parameters given in [Table 83](#) are derived from tests performed under ambient temperature and V_{DD} supply voltage conditions summarized in [Table 16](#).

Table 83. internal reference voltage

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{REFINT}	Internal reference voltage	$-40\text{ }^{\circ}\text{C} < T_A < +105\text{ }^{\circ}\text{C}$	1.18	1.21	1.24	V
$T_{S_vrefint}^{(1)}$	ADC sampling time when reading the internal reference voltage	-	10	-	-	μs
$V_{RERINT_s}^{(2)}$	Internal reference voltage spread over the temperature range	$V_{DD} = 3V \pm 10mV$	-	3	5	mV
$T_{Coeff}^{(2)}$	Temperature coefficient	-	-	30	50	ppm/ $^{\circ}\text{C}$
$t_{START}^{(2)}$	Startup time	-	-	6	10	μs

1. Shortest sampling time can be determined in the application by multiple iterations.
2. Guaranteed by design.

Table 84. Internal reference voltage calibration values

Symbol	Parameter	Memory address
V_{REFIN_CAL}	Raw data acquired at temperature of $30\text{ }^{\circ}\text{C}$ $V_{DDA} = 3.3\text{ V}$	0x1FFF 7A2A - 0x1FFF 7A2B

6.3.25 DAC electrical characteristics

Table 85. DAC characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	Comments
V_{DDA}	Analog supply voltage	-	1.7 ⁽¹⁾	-	3.6	V	-
V_{REF+}	Reference supply voltage	-	1.7 ⁽¹⁾	-	3.6	V	$V_{REF+} \leq V_{DDA}$

6.3.26 FMC characteristics

Unless otherwise specified, the parameters given in [Table 86](#) to [Table 93](#) for the FMC interface are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage conditions summarized in [Table 15](#), with the following configuration:

- Output speed is set to $OSPEEDRy[1:0] = 10$
- Capacitance load $C = 30$ pF
- Measurement points are done at CMOS levels: $0.5V_{DD}$

Refer to [Section 6.3.17: I/O port characteristics](#) for more details on the input/output characteristics.

Asynchronous waveforms and timings

[Figure 50](#) through [Figure 53](#) represent asynchronous waveforms and [Table 86](#) through [Table 93](#) provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- AddressSetupTime = 0x1
- AddressHoldTime = 0x1
- DataSetupTime = 0x1 (except for asynchronous NWAIT mode , DataSetupTime = 0x5)
- BusTurnAroundDuration = 0x0

In all timing tables, the T_{HCLK} is the HCLK clock period.

Figure 55. Synchronous multiplexed PSRAM write timings

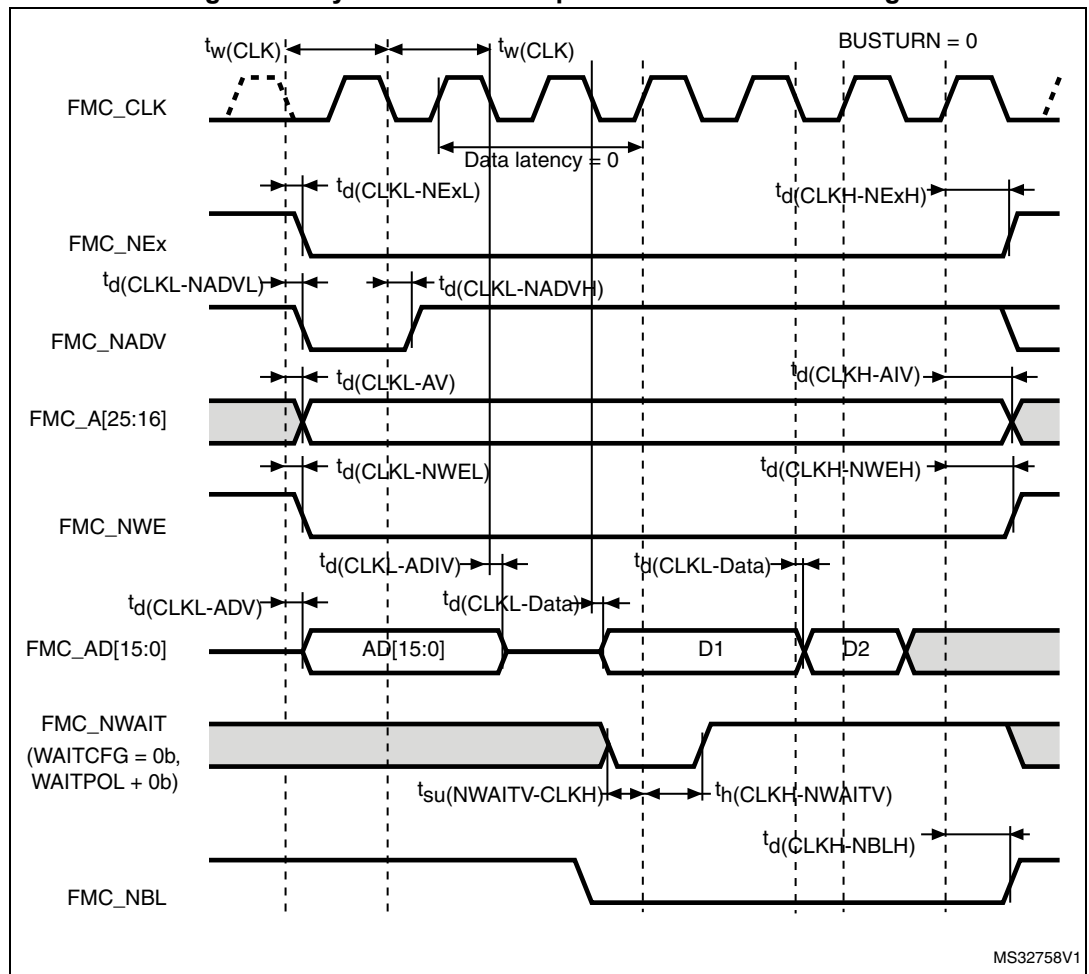
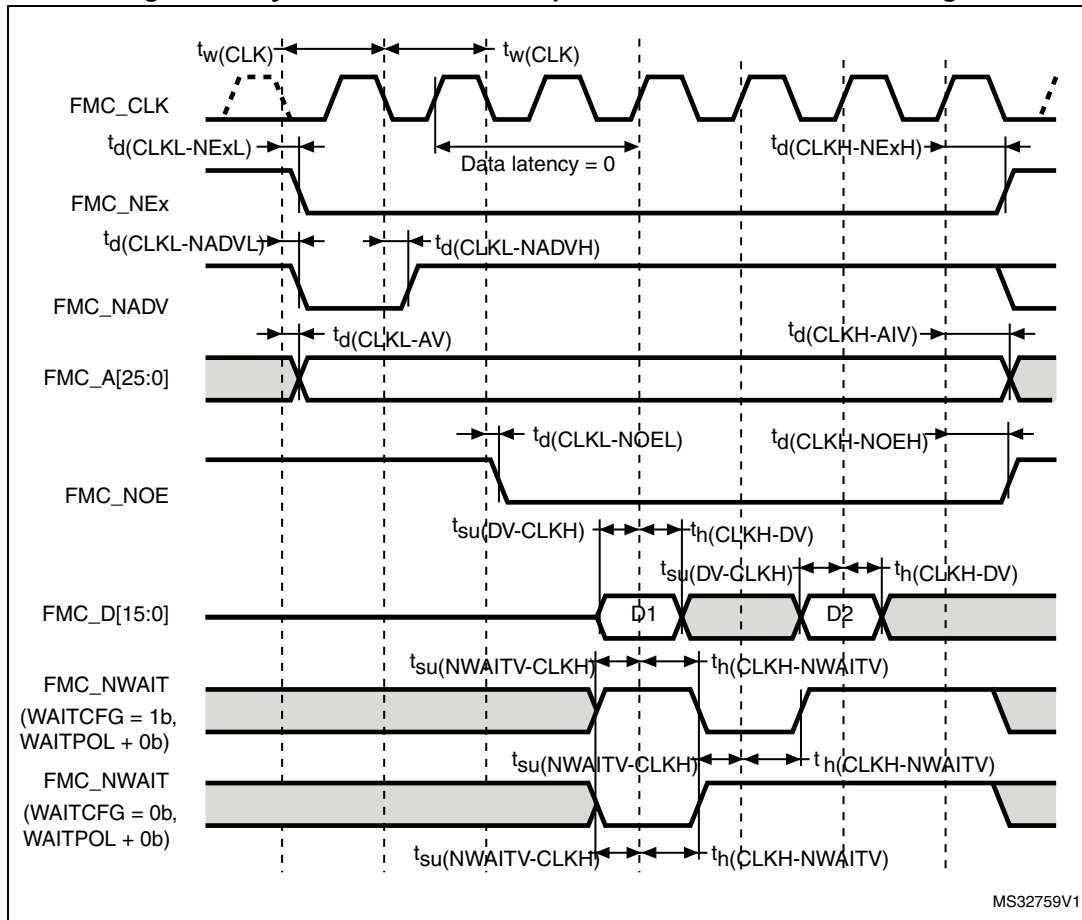


Figure 56. Synchronous non-multiplexed NOR/PSRAM read timings

Table 96. Synchronous non-multiplexed NOR/PSRAM read timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$t_w(\text{CLK})$	FMC_CLK period	$2T_{\text{HCLK}}$	-	ns
$t_{\text{d}}(\text{CLKL-NExL})$	FMC_CLK low to FMC_NEx low ($x=0..2$)	-	2.5	
$t_{\text{d}}(\text{CLKH-NExH})$	FMC_CLK high to FMC_NEx high ($x=0..2$)	$T_{\text{HCLK}} - 0.5$	-	
$t_{\text{d}}(\text{CLKL-NADV})$	FMC_CLK low to FMC_NADV low	-	0	
$t_{\text{d}}(\text{CLKL-NADVH})$	FMC_CLK low to FMC_NADV high	0	-	
$t_{\text{d}}(\text{CLKL-AV})$	FMC_CLK low to FMC_Ax valid ($x=16..25$)	-	2.5	
$t_{\text{d}}(\text{CLKH-AIV})$	FMC_CLK high to FMC_Ax invalid ($x=16..25$)	T_{HCLK}	-	
$t_{\text{d}}(\text{CLKL-NOEL})$	FMC_CLK low to FMC_NOE low	-	2	
$t_{\text{d}}(\text{CLKH-NOEH})$	FMC_CLK high to FMC_NOE high	$T_{\text{HCLK}} - 0.5$	-	
$t_{\text{su}}(\text{DV-CLKH})$	FMC_D[15:0] valid data before FMC_CLK high	1	-	
$t_{\text{h}}(\text{CLKH-DV})$	FMC_D[15:0] valid data after FMC_CLK high	3.5	-	
$t_{\text{su}}(\text{NWAITV-CLKH})$	FMC_NWAIT valid before FMC_CLK high	1	-	
$t_{\text{h}}(\text{CLKH-NWAITV})$	FMC_NWAIT valid after FMC_CLK high	3.5	-	

Table 103. LPDDR SDRAM write timings⁽¹⁾⁽²⁾

Symbol	Parameter	Min	Max	Unit
$F_{(SDCLK)}$	Frequency of operation	-	84	MHz
$t_{w(SDCLK)}$	FMC_SDCLK period	$2T_{HCLK} - 0.5$	$2T_{HCLK} + 0.5$	ns
$t_{d(SDCLKL_Data)}$	Data output valid time	-	5	
$t_{h(SDCLKL_Data)}$	Data output hold time	0.5	-	
$t_{d(SDCLK_Add)}$	Address valid time	-	3	
$t_{d(SDCLKL_SDNWE)}$	SDNWE valid time	-	3	
$t_{h(SDCLKL_SDNWE)}$	SDNWE hold time	0	-	
$t_{d(SDCLKL_SDNE)}$	Chip select valid time	-	2.5	
$t_{h(SDCLKL_SDNE)}$	Chip select hold time	0	-	
$t_{d(SDCLKL_SDNRAS)}$	SDNRAS valid time	-	2	
$t_{h(SDCLKL_SDNRAS)}$	SDNRAS hold time	0	-	
$t_{d(SDCLKL_SDNCAS)}$	SDNCAS valid time	-	2	
$t_{d(SDCLKL_SDNCAS)}$	SDNCAS hold time	0	-	

1. CL = 10 pF.

2. Guaranteed based on test during characterization.

6.3.27 Camera interface (DCMI) timing specifications

Unless otherwise specified, the parameters given in [Table 104](#) for DCMI are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage summarized in [Table 16](#), with the following configuration:

- DCMI_PIXCLK polarity: falling
- DCMI_VSYNC and DCMI_HSYNC polarity: high
- Data formats: 14 bits

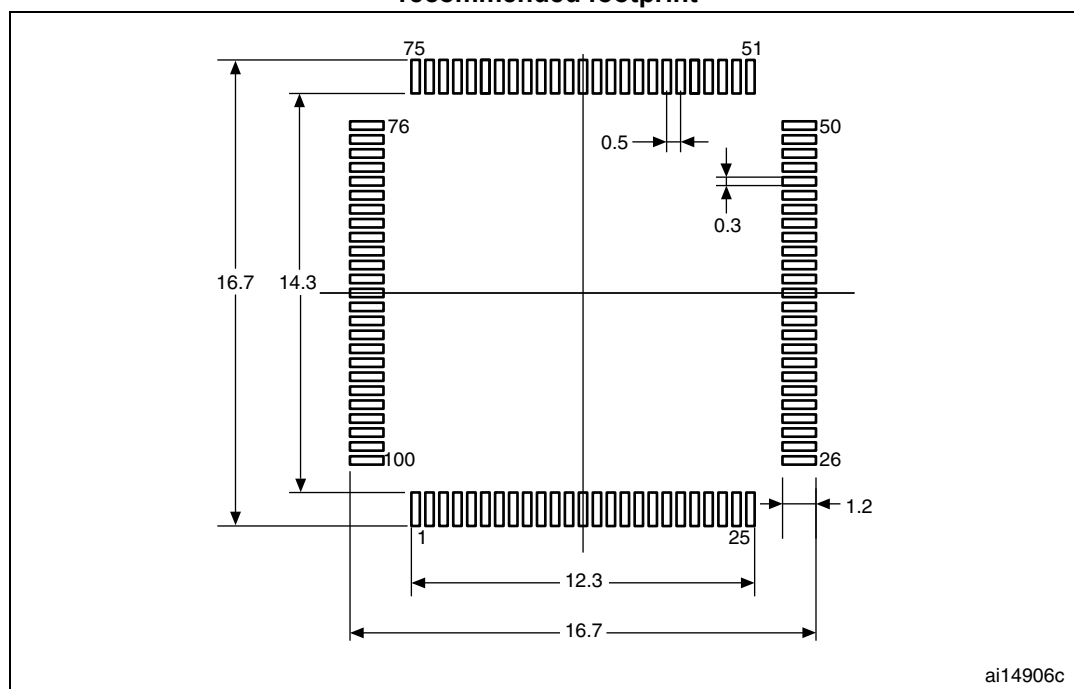
Table 104. DCMI characteristics

Symbol	Parameter	Min	Max	Unit
-	Frequency ratio DCMI_PIXCLK/ f_{HCLK}	-	0.4	-
DCMI_PIXCLK	Pixel clock input	-	54	MHz
D_{Pixel}	Pixel clock input duty cycle	30	70	%
$t_{su(DATA)}$	Data input setup time	1	-	ns
$t_{h(DATA)}$	Data input hold time	3.5	-	
$t_{su(HSYNC)}$ $t_{su(VSYNC)}$	DCMI_HSYNC/DCMI_VSYNC input setup time	2	-	
$t_{h(HSYNC)}$ $t_{h(VSYNC)}$	DCMI_HSYNC/DCMI_VSYNC input hold time	0	-	

Symbol	millimeters			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
E1	13.800	14.000	14.200	0.5433	0.5512	0.5591
E3	-	12.000	-	-	0.4724	-
e	-	0.500	-	-	0.0197	-
L	0.450	0.600	0.750	0.0177	0.0236	0.0295
L1	-	1.000	-	-	0.0394	-
k	0°	3.5°	7°	0°	3.5°	7°
ccc	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 71. LQFP100 - 100-pin, 14 x 14 mm low-profile quad flat recommended footprint



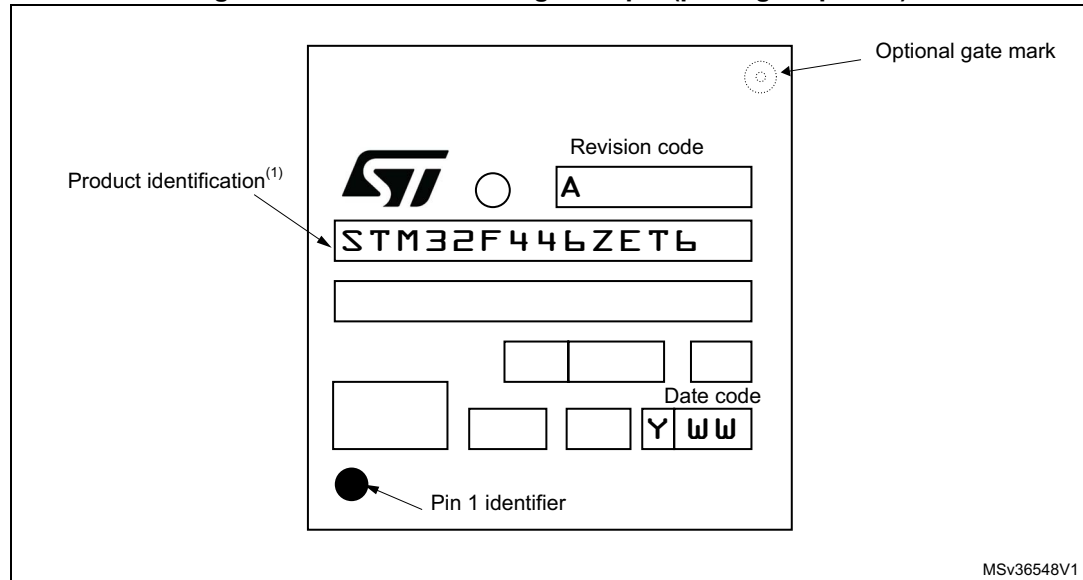
1. Dimensions are expressed in millimeters.

Device marking for LQFP144 package

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

Other optional marking or inset/upset marks, which identify the parts throughout supply chain operations, are not indicated below.

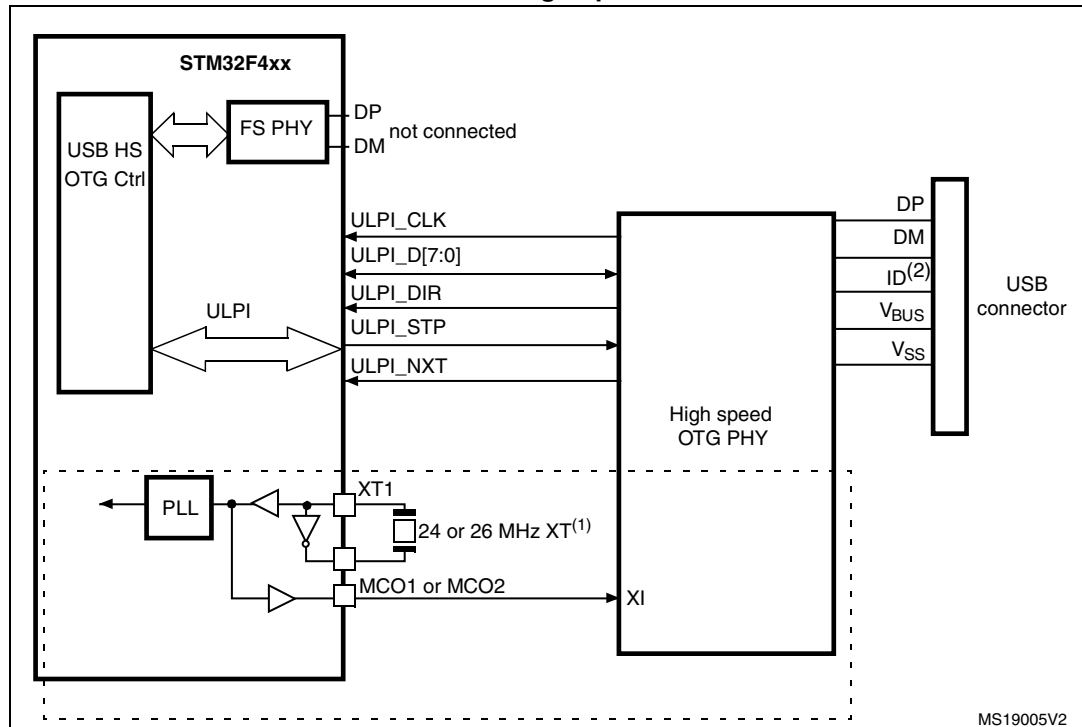
Figure 75. LQFP144 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

A.2 USB OTG high speed (HS) interface solutions

Figure 88. USB controller configured as peripheral, host, or dual-mode and used in high speed mode



1. It is possible to use MCO1 or MCO2 to save a crystal. It is however not mandatory to clock the STM32F446xx with a 24 or 26 MHz crystal when using USB HS. The above figure only shows an example of a possible connection.
2. The ID pin is required in dual role only.