



Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	LINbus, SCI
Peripherals	LVD, POR, PWM
Number of I/O	24
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	28-DIP (0.600", 15.24mm)
Supplier Device Package	28-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08se4vrl

Table of Contents

1	MCU Block Diagram	3	3.8	Internal Clock Source (ICS) Characteristics	20
2	Pin Assignments	4	3.9	ADC Characteristics	22
3	Electrical Characteristics	6	3.10	AC Characteristics	25
3.1	Parameter Classification	6	3.10.1	Control Timing	25
3.2	Absolute Maximum Ratings	6	3.10.2	TPM/MTIM Module Timing	26
3.3	Thermal Characteristics	7	3.11	Flash Specifications	27
3.4	ESD Protection and Latch-Up Immunity	8	4	Ordering Information	27
3.5	DC Characteristics	9	4.1	Package Information	28
3.6	Supply Current Characteristics	15	4.2	Mechanical Drawings	28
3.7	External Oscillator (XOSC) Characteristics	19			

Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to: freescale.com

The following revision history table summarizes changes contained in this document.

Revision	Date	Description of Changes
1	10/8/2008	Initial public released.
2	1/16/2009	In Table 8 , added the Max. of S2I _{DD} and S3I _{DD} in 0–105 °C; changed the Max. of S2I _{DD} and S3I _{DD} in 0–85 °C; changed the typical of S2I _{DD} and S3I _{DD} ; changed the S23I _{DDRTI} to P.
3	4/7/2009	Added I _{OZTOT} in the Table 7 . Changed V _{DDAD} to V _{DDA} , V _{SSAD} to V _{SSA} . Updated Table 9 , Table 10 , Table 11 , and Table 12 . Updated Figure 13 and Figure 14 .
4	4/10/2015	Updated Table 9 .

Related Documentation

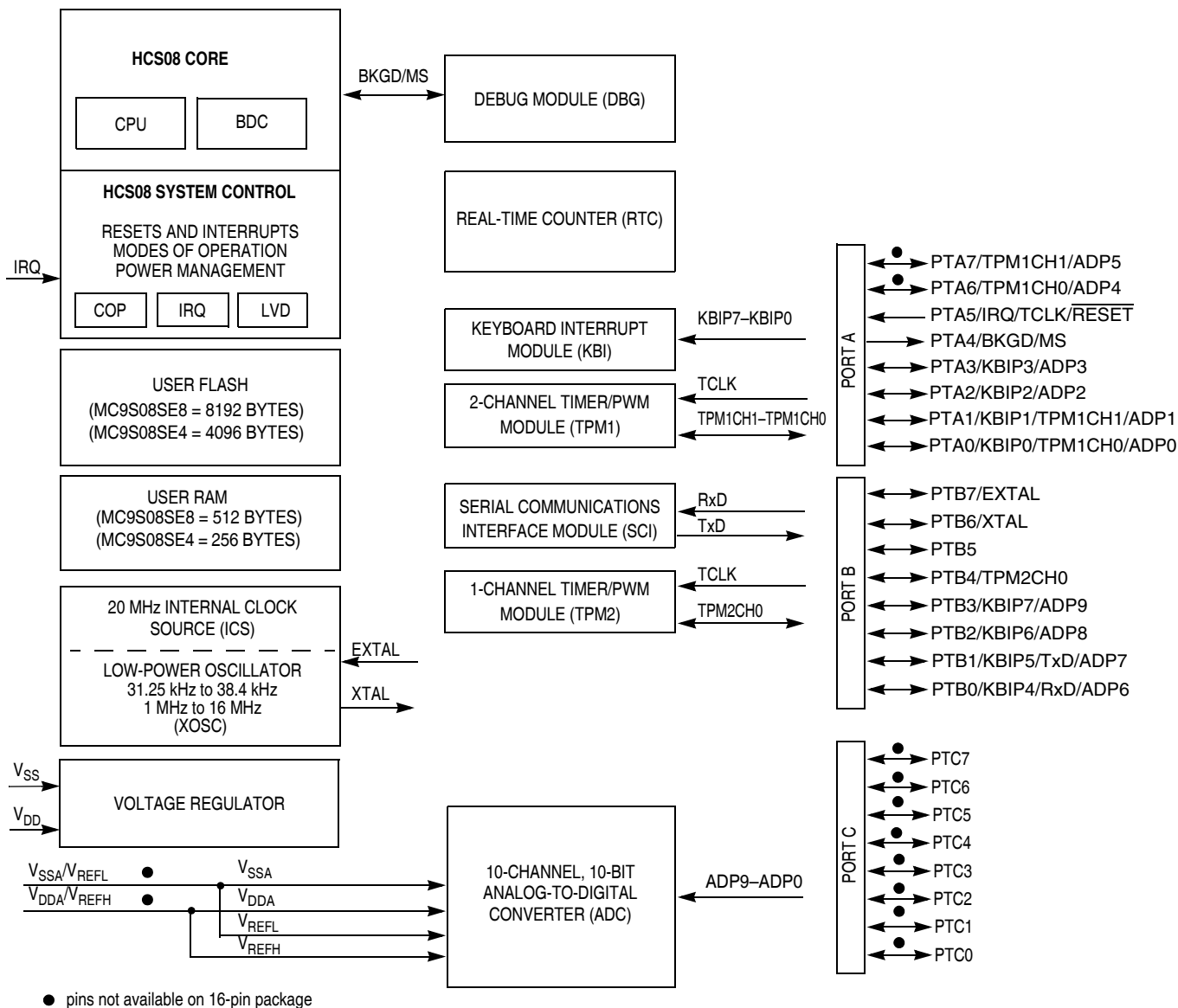
Find the most current versions of all documents at: <http://www.freescale.com>

Reference Manual (MC9S08SE8RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

1 MCU Block Diagram

The block diagram, [Figure 1](#), shows the structure of the MC9S08SE8 series MCUs.



Notes:

When PTA4 is configured as BKGD, pin is bi-directional.

For the 16-pin package: V_{SSA}/V_{REFL} and V_{DDA}/V_{REFH} are double bonded to V_{SS} and V_{DD} respectively.

Figure 1. MC9S08SE8 Series Block Diagram

2 Pin Assignments

This chapter shows the pin assignments in the packages available for the MC9S08SE8 series.

Table 1. Pin Availability by Package Pin-Count

Pin Number (Package)		<-- Lowest Priority --> Highest			
28 (SOIC/PDIP)	16 (TSSOP)	Port Pin	Alt 1	Alt 2	Alt 3
1	—	PTC5			
2	—	PTC4			
3	1	PTA5	IRQ	TCLK	RESET
4	2	PTA4		BKGD	MS
5	3				V _{DD}
6	—			V _{DDA}	V _{REFH}
7	—			V _{SSA}	V _{REFL}
8	4				V _{SS}
9	5	PTB7	EXTAL		
10	6	PTB6	XTAL		
11	7	PTB5			
12	8	PTB4		TPM2CH0	
13	—	PTC3			
14	—	PTC2			
15	—	PTC1			
16	—	PTC0			
17	9	PTB3	KBIP7		ADP9
18	10	PTB2	KBIP6		ADP8
19	11	PTB1	KBIP5	TxD	ADP7
20	12	PTB0	KBIP4	RxD	ADP6
21	—	PTA7		TPM1CH1 ¹	ADP5
22	—	PTA6		TPM1CH0 ¹	ADP4
23	13	PTA3	KBIP3		ADP3
24	14	PTA2	KBIP2		ADP2
25	15	PTA1	KBIP1	TPM1CH1 ¹	ADP1
26	16	PTA0	KBIP0	TPM1CH0 ¹	ADP0
27	—	PTC7			
28	—	PTC6			

¹ TPM1 pins can be remapped to PTA7, PTA6 and PTA1,PTA0

Electrical Characteristics

The average chip-junction temperature (T_J) in $^{\circ}\text{C}$ can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA}) \quad \text{Eqn. 1}$$

Where:

T_A = Ambient temperature, $^{\circ}\text{C}$

θ_{JA} = Package thermal resistance, junction-to-ambient, $^{\circ}\text{C}/\text{W}$

$P_D = P_{\text{int}} + P_{\text{I/O}}$

$P_{\text{int}} = I_{\text{DD}} \times V_{\text{DD}}$, Watts — chip internal power

$P_{\text{I/O}}$ = Power dissipation on input and output pins — user-determined

For most applications, $P_{\text{I/O}} \ll P_{\text{int}}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{\text{I/O}}$ is neglected) is:

$$P_D = K \div (T_J + 273^{\circ}\text{C}) \quad \text{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273^{\circ}\text{C}) + \theta_{JA} \times (P_D)^2 \quad \text{Eqn. 3}$$

Where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring P_D (at equilibrium) for a known T_A . Using this value of K , the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A .

3.4 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

During the device qualification ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Table 5. ESD and Latch-up Test Conditions

Model	Description	Symbol	Value	Unit
Human body	Series resistance	R1	1500	Ω
	Storage capacitance	C	100	pF
	Number of pulses per pin	—	3	—
Machine	Series resistance	R1	0	Ω
	Storage capacitance	C	200	pF
	Number of pulses per pin	—	3	—

Table 7. DC Characteristics (continued)

Num	C	Parameter	Symbol	Min	Typical ¹	Max	Unit
5	P	Output low current — Max total I_{OL} for all ports 5 V 3 V	I_{OLT}	— —	— —	100 60	mA
6	P	Input high voltage; all digital inputs	V_{IH}	$0.65 \times V_{DD}$	—	—	V
7	P	Input low voltage; all digital inputs	V_{IL}	—	—	$0.35 \times V_{DD}$	
8	P	Input hysteresis; all digital inputs	V_{hys}	$0.06 \times V_{DD}$	—	—	mV
9	C	Input leakage current; input only pins ²	$ I_{in} $	—	0.1	1	μA
10	P	High impedance (off-state) leakage current ²	$ I_{OZ} $	—	0.1	1	μA
11	C	Total leakage combined for all inputs and Hi-Z pins — All input only and I/O^2	$ I_{OZTOT} $	—	—	2	μA
12	P	Internal pullup resistors ³	R_{PU}	20	45	65	k Ω
13	P	Internal pulldown resistors ⁴	R_{PD}	20	45	65	k Ω
14	D	DC injection current ^{5, 6, 7} $V_{IN} < V_{SS}$, $V_{IN} > V_{DD}$ Single pin limit Total MCU limit, includes sum of all stressed pins	I_{IC}	–0.2 –5	— —	0.2 5	mA
15	C	Input capacitance; all non-supply pins	C_{In}	—	—	8	pF
16	C	RAM retention voltage	V_{RAM}	0.6	1.0	—	V
17	P	POR re-arm voltage ⁸	V_{POR}	0.9	1.4	2.0	V
18	D	POR re-arm time	t_{POR}	10	—	—	μs
19	P	Low-voltage detection threshold — high range V_{DD} falling V_{DD} rising	V_{LVD1}	3.9 4.0	4.0 4.1	4.1 4.2	V
20	P	Low-voltage detection threshold — low range V_{DD} falling V_{DD} rising	V_{LVD0}	2.48 2.54	2.56 2.62	2.64 2.70	V
21	C	Low-voltage warning threshold — high range 1 V_{DD} falling V_{DD} rising	V_{LVW3}	4.5 4.6	4.6 4.7	4.7 4.8	V
22	P	Low-voltage warning threshold — high range 0 V_{DD} falling V_{DD} rising	V_{LVW2}	4.2 4.3	4.3 4.4	4.4 4.5	V
23	P	Low-voltage warning threshold low range 1 V_{DD} falling V_{DD} rising	V_{LVW1}	2.84 2.90	2.92 2.98	3.00 3.06	V
24	C	Low-voltage warning threshold — low range 0 V_{DD} falling V_{DD} rising	V_{LVW0}	2.66 2.72	2.74 2.80	2.82 2.88	V

Table 7. DC Characteristics (continued)

Num	C	Parameter	Symbol	Min	Typical ¹	Max	Unit
25	T	Low-voltage inhibit reset/recover hysteresis 5 V 3 V	V_{hys}	— —	100 60	— —	mV
26	P	Bandgap voltage reference ⁹	V_{BG}	1.18	1.20	1.21	V

¹ Typical values are measured at 25 °C. Characterized, not tested.

² Measured with $V_{In} = V_{DD}$ or V_{SS} .

³ Measured with $V_{In} = V_{SS}$.

⁴ Measured with $V_{In} = V_{DD}$.

⁵ All functional non-supply pins are internally clamped to V_{SS} and V_{DD} .

⁶ Input must be current-limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.

⁷ Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD} , the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

⁸ Maximum is highest voltage that POR is guaranteed.

⁹ Factory trimmed at $V_{DD} = 5.0$ V, Temp = 25 °C.

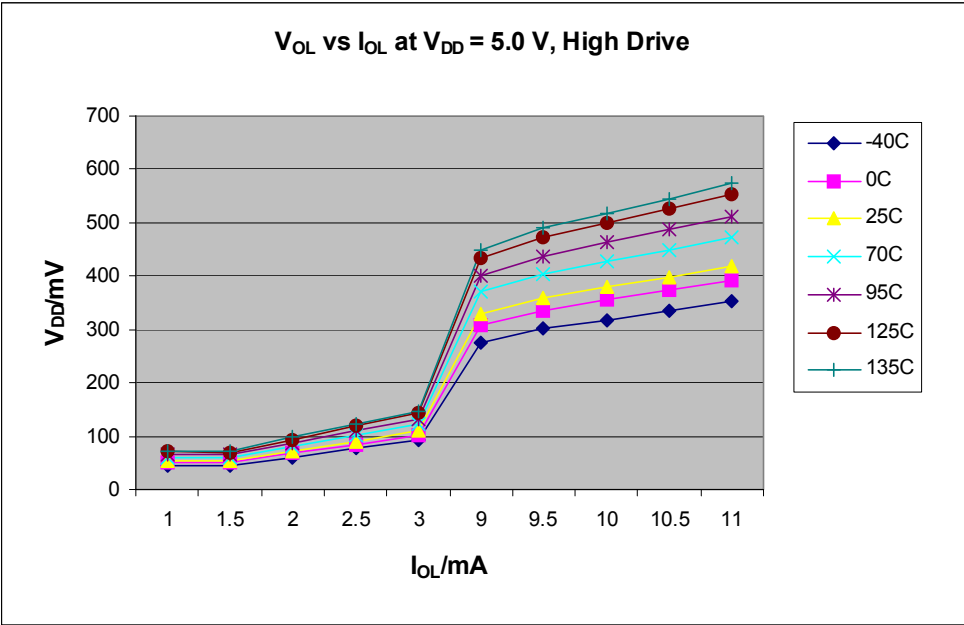


Figure 4. Typical V_{OL} vs. I_{OL} for High Drive Enabled Pad (V_{DD} = 5 V)

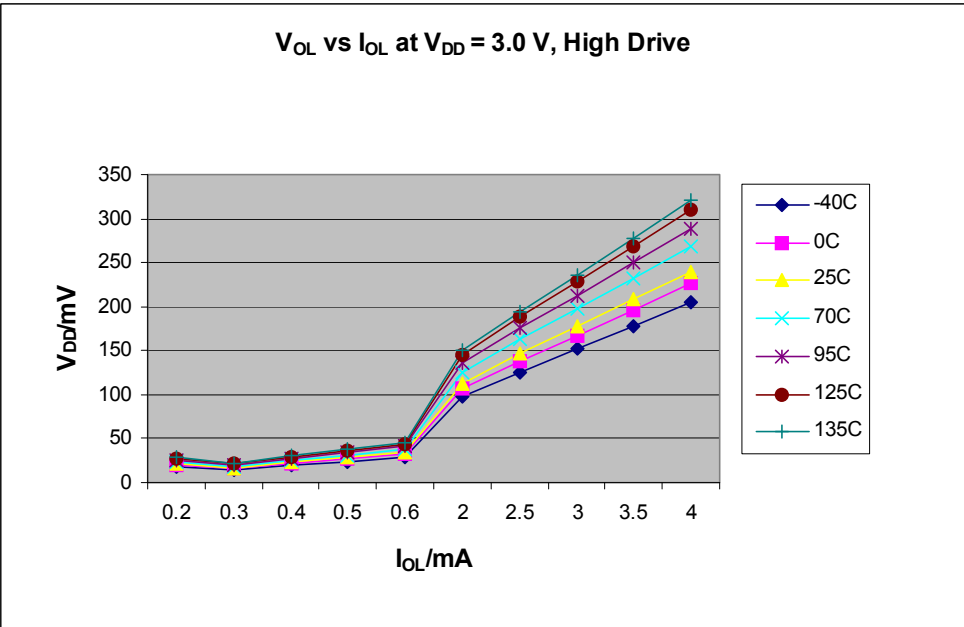


Figure 5. Typical V_{OL} vs. I_{OL} for High Drive Enabled Pad (V_{DD} = 3 V)

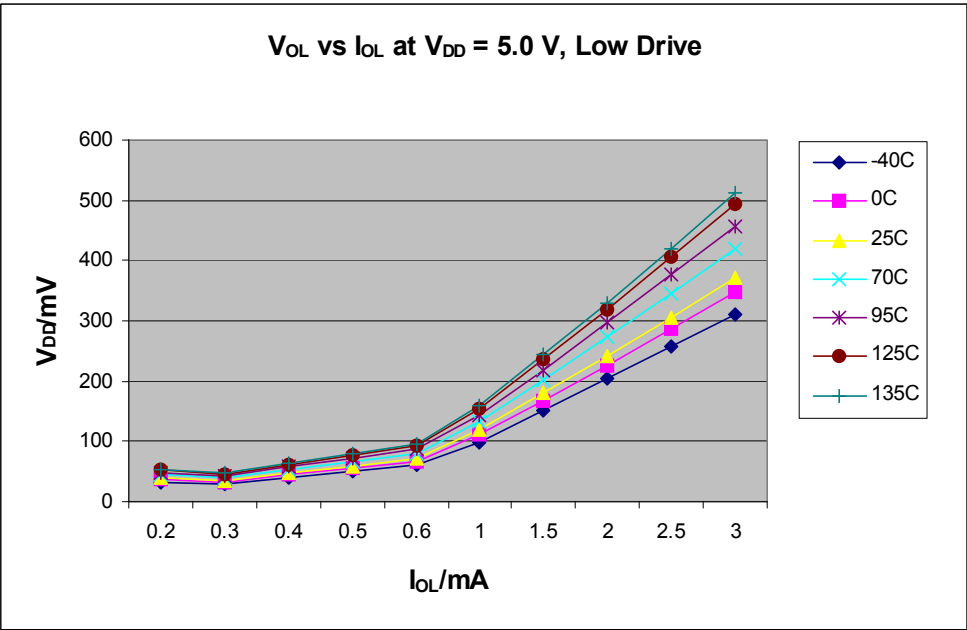


Figure 6. Typical V_{OL} vs. I_{OL} for Low Drive Enabled Pad ($V_{DD} = 5$ V)

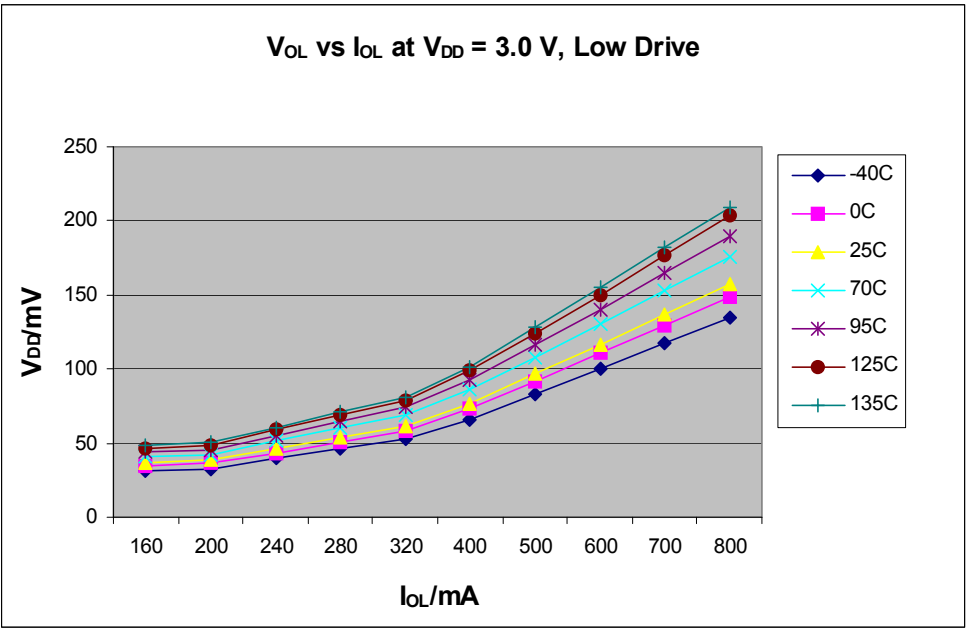


Figure 7. Typical V_{OL} vs. I_{OL} for Low Drive Enabled Pad ($V_{DD} = 3$ V)

Table 8. Supply Current Characteristics

Num	C	Parameter	Symbol	V _{DD} (V)	Typical ¹	Max	Unit	Temp (°C)
1	C	Run supply current ² measured at (CPU clock = 4 MHz, f _{BUS} = 2 MHz)	R _I DD	5	2.4	2.72	mA	-40 to 125
				3	2.18	2.26		
2	P	Run supply current ² measured at (CPU clock = 20 MHz, f _{BUS} = 10 MHz)	R _I DD	5	6.35	7.29	mA	-40 to 125
				3	5.79	6.42		
3	P	Wait supply current ² measured at f _{BUS} = 2 MHz	W _I DD	5	1.4	1.56	mA	-40 to 125
				3	1.36	1.53		
4	P	Stop2 mode supply current	S2I _{DD}	5	1.4	19 28 45.8	μA	-40 to 85 -40 to 105 -40 to 125
				3	1.3	15 22 37.2	μA	-40 to 85 -40 to 105 -40 to 125
5	P	Stop3 mode supply current	S3I _{DD}	5	1.61	23 43 76.1	μA	-40 to 85 -40 to 105 -40 to 125
				3	1.44	19 38 66.4	μA	-40 to 85 -40 to 105 -40 to 125
6	P	RTC adder to stop2 or stop3 ³	S23I _{DDRTI}	5	300	500 500	nA	-40 to 85 -40 to 125
				3	300	500 500	nA	-40 to 85 -40 to 125
7	C	LVD adder to stop3 (LVDE = LVDSE = 1)	S3I _{DDLVD}	5	122	180	μA	-40 to 125
				3	110	160	μA	-40 to 125
8	C	Adder to stop3 for oscillator enabled ⁴ (OSCSTEN = 1)	S3I _{DDOSC}	5,3	5	8	μA	-40 to 125

¹ Typical values are based on characterization data at 25 °C unless otherwise stated. See [Figure 12](#) through [Figure 13](#) for typical curves across voltage/temperature.

² All modules except ADC active, ICS configured for FBE, and does not include any dc loads on port pins.

³ Most customers are expected to find that auto-wakeup from stop2 or stop3 can be used instead of the higher current wait mode. Wait mode typical is 220 μA at 5 V with f_{BUS} = 1 MHz.

⁴ Values given under the following conditions: low range operation (RANGE = 0) with a 32.768 kHz crystal and low power mode (HGO = 0).

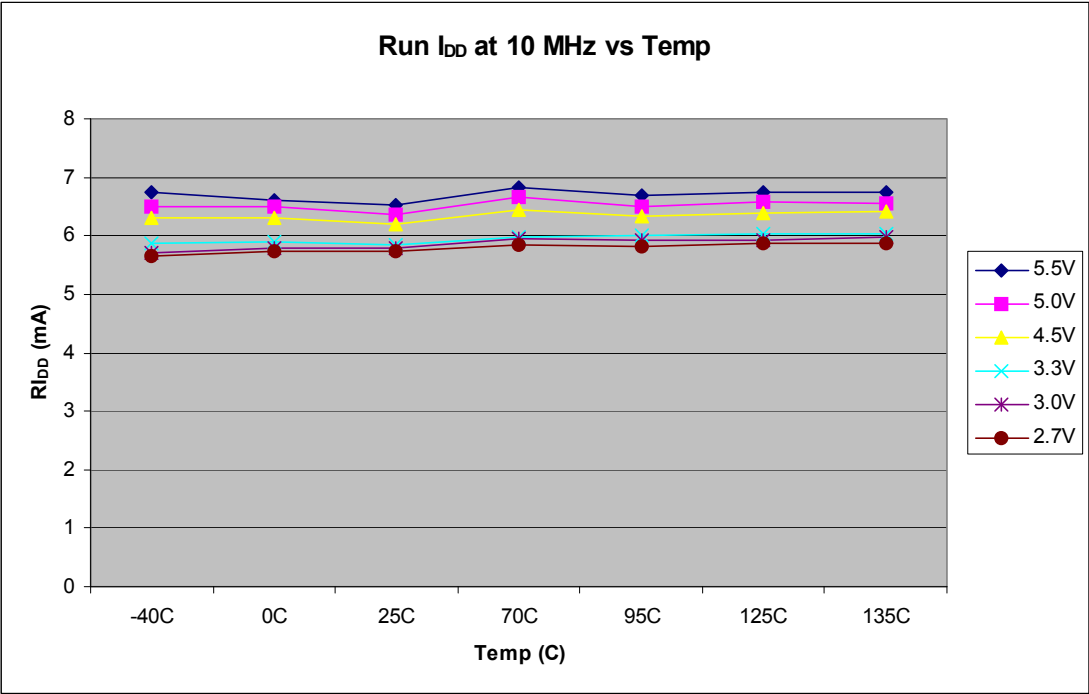


Figure 12. Typical Run I_{DD} Curves

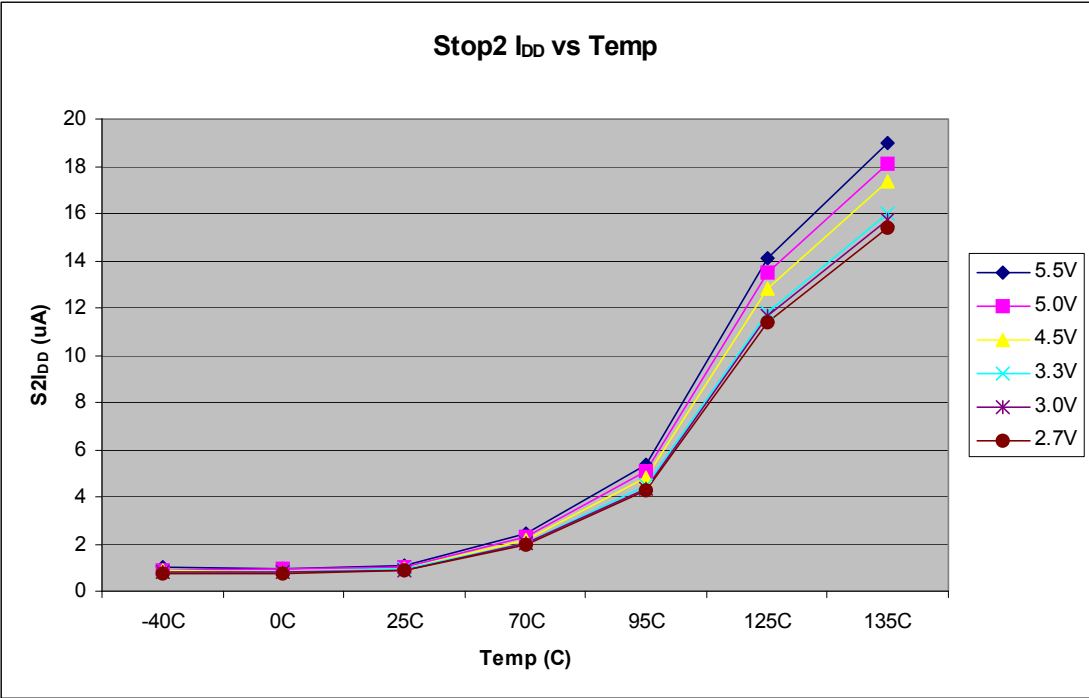


Figure 13. Typical Stop2 I_{DD} Curves

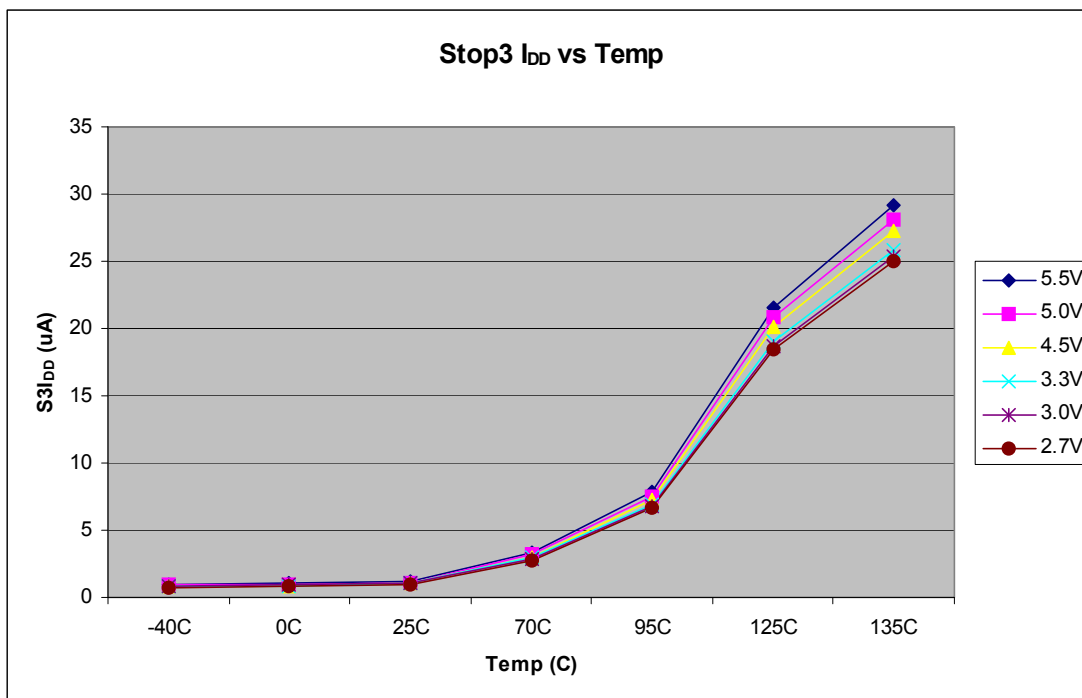


Figure 14. Typical Stop3 I_{DD} Curves

3.7 External Oscillator (XOSC) Characteristics

Table 9. Oscillator electrical specifications (Temperature Range = –40 to 125°C Ambient)

Num	C	Characteristic	Symbol	Min.	Typical ¹	Max.	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1)					
		Low range (RANGE = 0)	f _{lo}	32	—	38.4	kHz
		High range (RANGE = 1), high gain (HGO = 1) ²	f _{hi-hgo}	1	—	16	MHz
		High range (RANGE = 1), low power (HGO = 0) ²	f _{hi-lp}	1	—	8	MHz
2	—	Load capacitors	C ₁ , C ₂	See crystal or resonator manufacturer's recommendation			
3	—	Feedback resistor	R _F				
		Low range (32 kHz to 100 kHz)		—	10	—	MΩ
		High range (1 MHz to 16 MHz)		—	1	—	
4	—	Series resistor	R _S				
		Low range, low gain (RANGE = 0, HGO = 0)		—	0	—	kΩ
		Low range, high gain (RANGE = 0, HGO = 1)		—	100	—	
		High range, low gain (RANGE = 1, HGO = 0)		—	0	—	
		High range, high gain (RANGE = 1, HGO = 1)					
		≥ 8 MHz		—	0	0	
		4 MHz		—	0	10	
		1 MHz		—	0	20	

Table 9. Oscillator electrical specifications (Temperature Range = –40 to 125°C Ambient)

Num	C	Characteristic	Symbol	Min.	Typical ¹	Max.	Unit
5	T	Crystal start-up time ³					
		Low range, low gain (RANGE = 0, HGO = 0)	$t_{CSTL-LP}$	—	200	—	ms
		Low range, high gain (RANGE = 0, HGO = 1)	$t_{CSTH-HGO}$	—	400	—	
		High range, low gain (RANGE = 1, HGO = 0) ⁴	$t_{CSTH-LP}$	—	5	—	
		High range, high gain (RANGE = 1, HGO = 1) ⁴	$t_{CSTH-HGO}$	—	15	—	
6	T	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1)					
		FEE or FBE mode ²	f_{extal}	0.03125	—	20	MHz
		FBELP mode		0	—	20	MHz

- ¹ Typical column was characterized at 5.0 V, 25 °C or is recommended value.
- ² The input clock source must be divided using RDIV to within the range of 31.25 kHz to 39.0625 kHz.
- ³ This parameter is characterized and not tested on each device. Proper PC board layout procedures must be followed to achieve specifications. This data will vary based upon the crystal manufacturer and board design. The crystal should be characterized by the crystal manufacturer.
- ⁴ 4 MHz crystal.

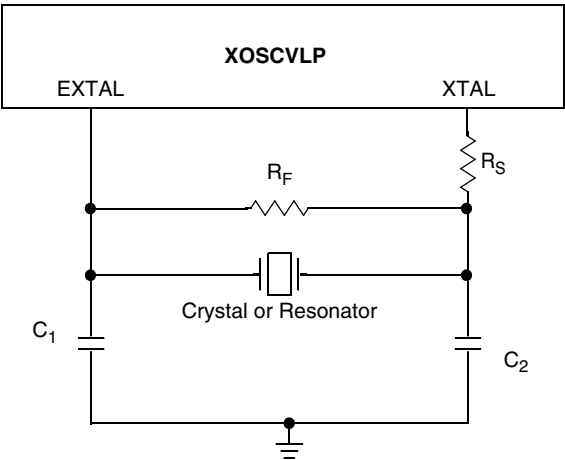


Figure 15. Typical Crystal or Resonator Circuit: High Range and Low Range/High Gain

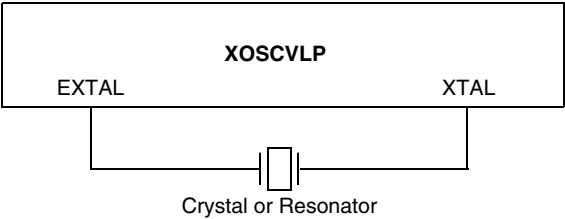


Figure 16. Typical Crystal or Resonator Circuit: Low Range/Low Power

Electrical Characteristics

¹ Typical values assume $V_{DDA} = 5.0\text{ V}$, $\text{Temp} = 25\text{ }^{\circ}\text{C}$, $f_{ADCK} = 1.0\text{ MHz}$ unless otherwise stated. Typical values are for reference only and are not tested in production.

² DC potential difference.

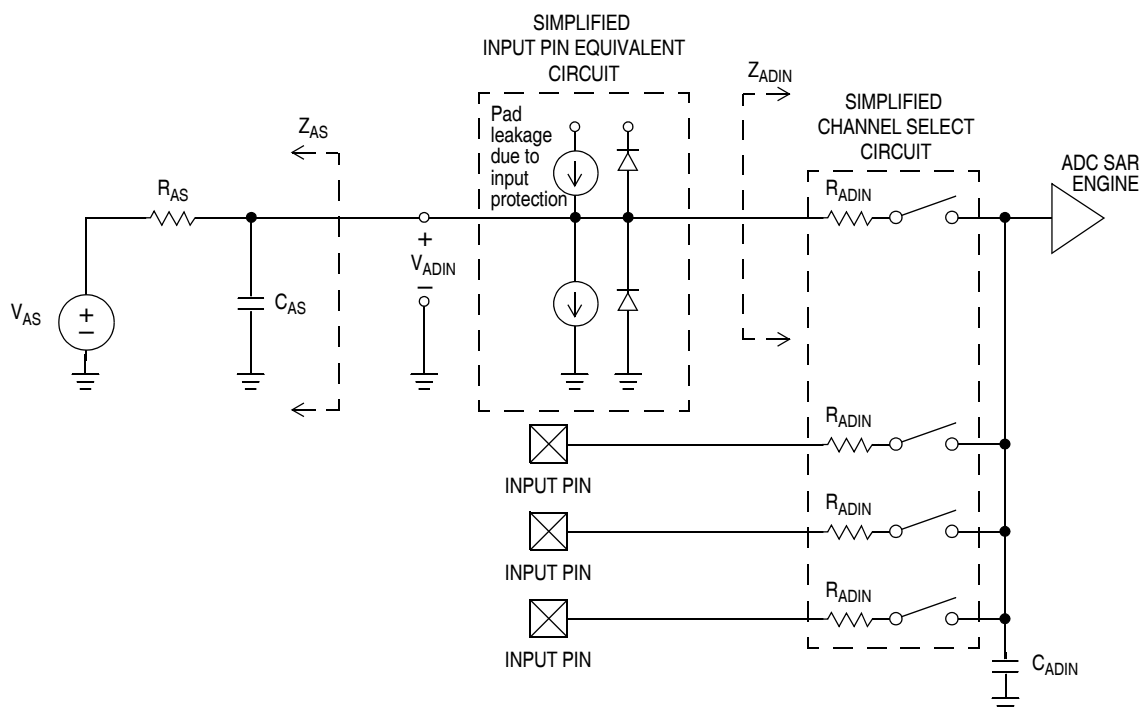


Figure 18. ADC Input Impedance Equivalency Diagram

Table 12. 10-Bit ADC Characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$)

Characteristic	Conditions	C	Symb	Min	Typ ¹	Max	Unit	Comment
Supply Current ADLPC = 1 ADLSMP = 1 ADCO = 1		T	I_{DDA}	—	133	—	μA	
Supply Current ADLPC = 1 ADLSMP = 0 ADCO = 1		T	I_{DDA}	—	218	—	μA	
Supply Current ADLPC = 0 ADLSMP = 1 ADCO = 1		T	I_{DDA}	—	327	—	μA	
Supply Current ADLPC = 0 ADLSMP = 0 ADCO = 1		D	I_{DDA}	—	0.582	1	mA	
Supply Current	Stop, Reset, Module Off	D	I_{DDA}	—	0.011	1	μA	

Table 12. 10-Bit ADC Characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

Characteristic	Conditions	C	Symb	Min	Typ ¹	Max	Unit	Comment
ADC Asynchronous Clock Source	High Speed (ADLPC = 0)	D	f _{ADACK}	2	3.3	5	MHz	t _{ADACK} = 1/f _{ADACK}
	Low Power (ADLPC = 1)			1.25	2	3.3		
Conversion Time (Including sample time)	Short Sample (ADLSMP = 0)	D	t _{ADC}	—	20	—	ADCK cycles	See SE8 reference manual for conversion time variances
	Long Sample (ADLSMP = 1)			—	40	—		
Sample Time	Short Sample (ADLSMP = 0)	D	t _{ADS}	—	3.5	—	ADCK cycles	
	Long Sample (ADLSMP = 1)			—	23.5	—		
Temp Sensor Slope	–40°C– 25°C	D	m	—	3.266	—	mV/°C	
	25°C– 125°C			—	3.638	—		
Temp Sensor Voltage	25°C	D	V _{TEMP25}	—	1.396	—	mV	
Characteristics for 28-pin packages only								
Total Unadjusted Error	10-bit mode	P	E _{TUE}	—	±1	±2.5	LSB ³	Includes quantization
	8-bit mode	P		—	±0.5	±1.0		
Differential Non-Linearity	10-bit mode ²	P	DNL	—	±0.5	±1.0	LSB ³	
	8-bit mode ³	P		—	±0.3	±0.5		
Integral Non-Linearity	10-bit mode	T	INL	—	±0.5	±1.0	LSB ³	
	8-bit mode	T		—	±0.3	±0.5		
Zero-Scale Error	10-bit mode	P	E _{ZS}	—	±0.5	±1.5	LSB ³	V _{ADIN} = V _{SSA}
	8-bit mode	P		—	±0.5	±0.5		
Full-Scale Error	10-bit mode	T	E _{FS}	—	±0.5	±1	LSB ³	V _{ADIN} = V _{DDA}
	8-bit mode	T		—	±0.5	±0.5		
Quantization Error	10-bit mode	D	E _Q	—	—	±0.5	LSB ³	
	8-bit mode			—	—	±0.5		
Input Leakage Error	10-bit mode	D	E _{IL}	—	±0.2	±2.5	LSB ³	Pad leakage ^{4*} R _{AS}
	8-bit mode			—	±0.1	±1		
Characteristics for 16-pin package only								
Total Unadjusted Error	10-bit mode	P	E _{TUE}	—	±1.5	±3.5	LSB ³	Includes quantization
	8-bit mode	P		—	±0.7	±1.5		

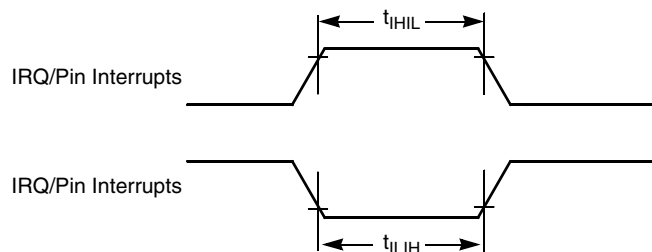


Figure 20. IRQ/Pin Interrupt Timing

3.10.2 TPM/MTIM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 14. TPM Input Timing

Num	C	Rating	Symbol	Min	Max	Unit
1	D	External clock frequency	f_{TPMext}	DC	$f_{Bus}/4$	MHz
2	D	External clock period	t_{TPMext}	4	—	t_{cyc}
3	D	External clock high time	t_{clkh}	1.5	—	t_{cyc}
4	D	External clock low time	t_{clkl}	1.5	—	t_{cyc}
5	D	Input capture pulse width	t_{ICPW}	1.5	—	t_{cyc}

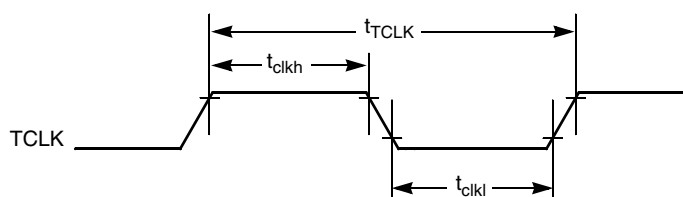


Figure 21. Timer External Clock

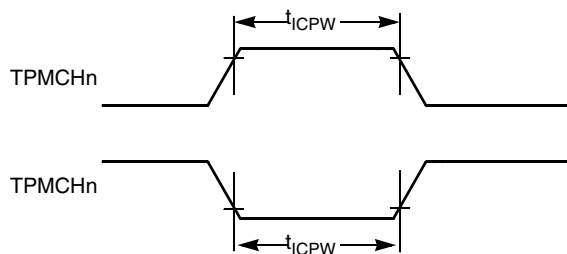
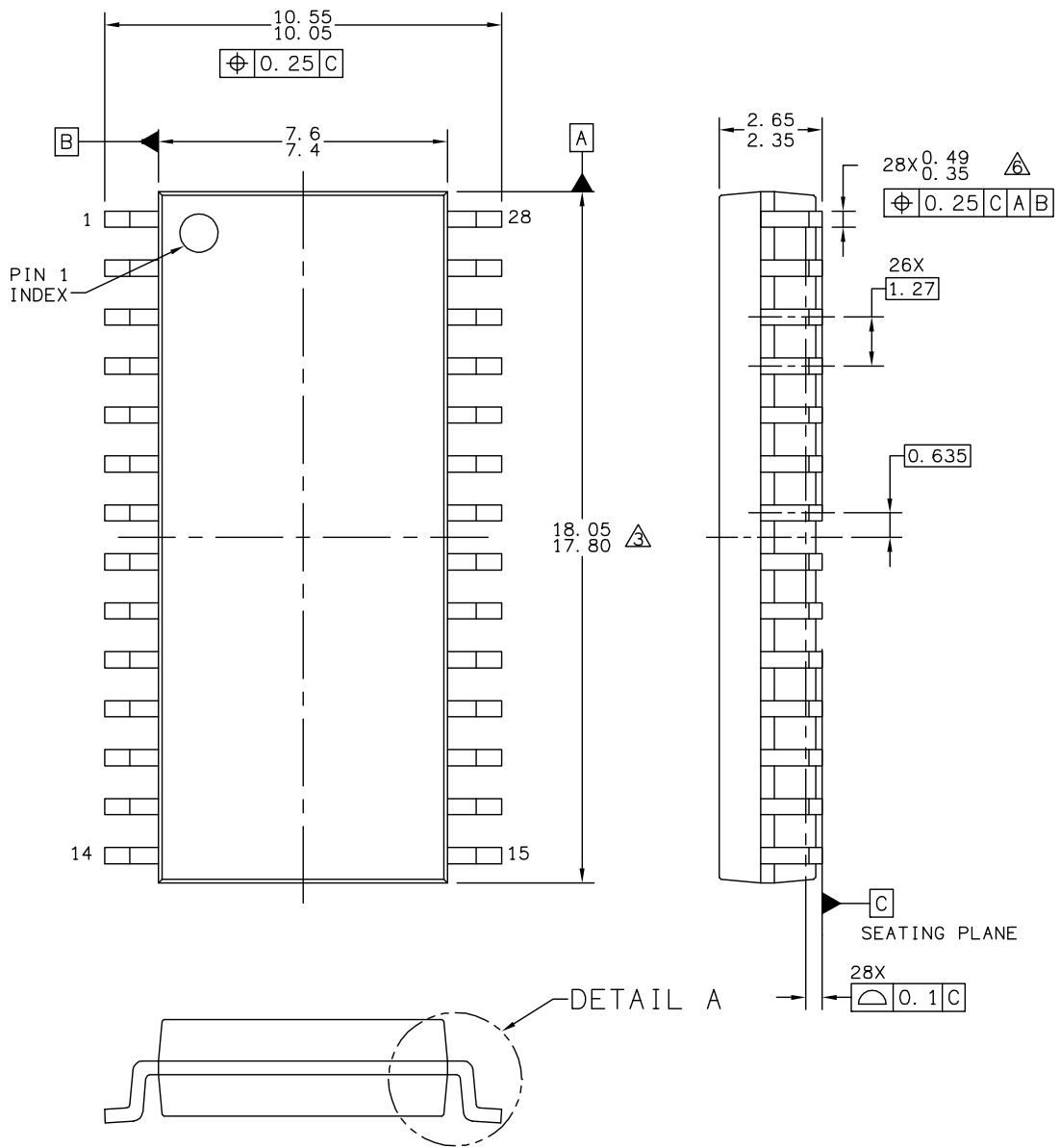


Figure 22. Timer Input Capture Pulse

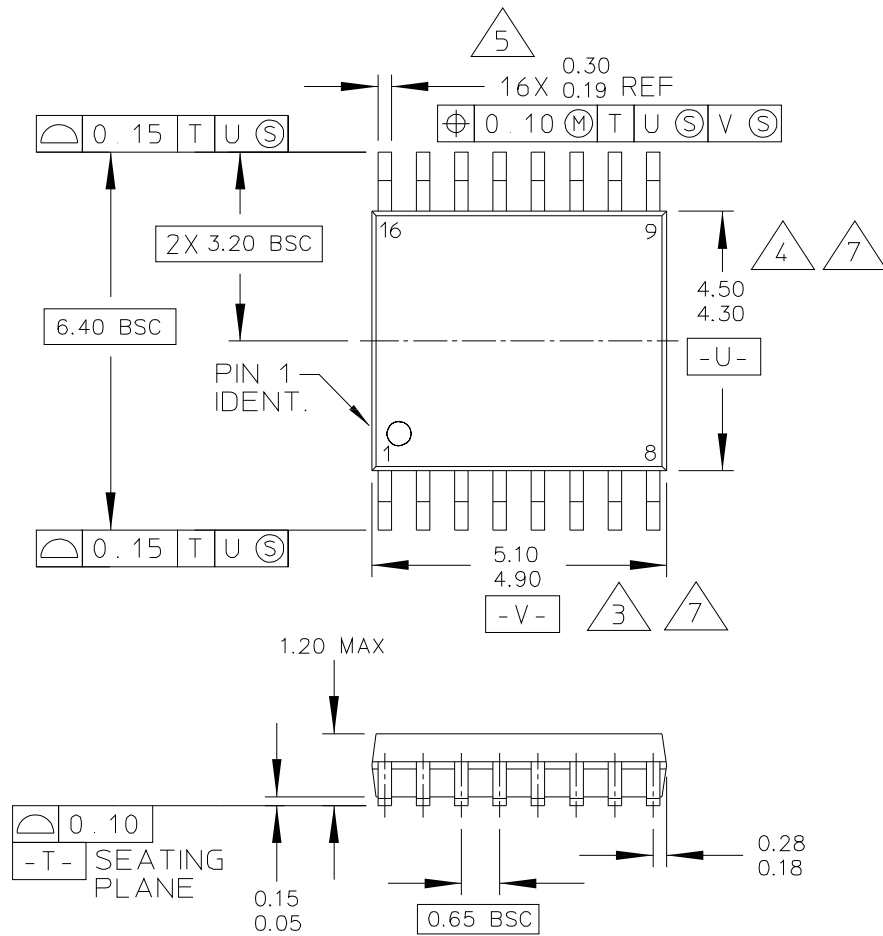


© FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED.	MECHANICAL OUTLINE		PRINT VERSION NOT TO SCALE	
	TITLE: SOIC, WIDE BODY, 28 LEAD CASEOUTLINE		DOCUMENT NO: 98ASB42345B	REV: G
			CASE NUMBER: 751F-05	10 MAR 2005
			STANDARD: MS-013AE	

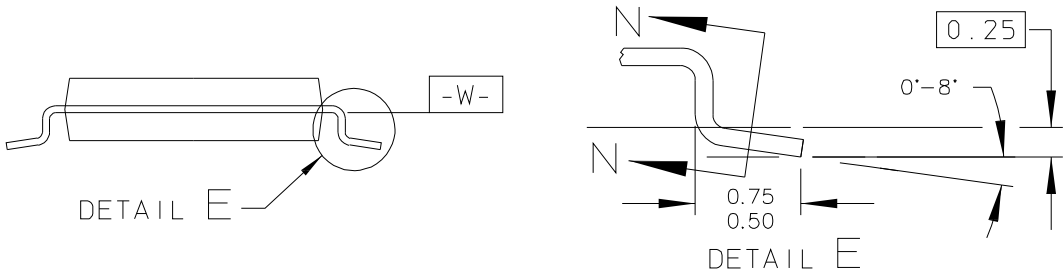
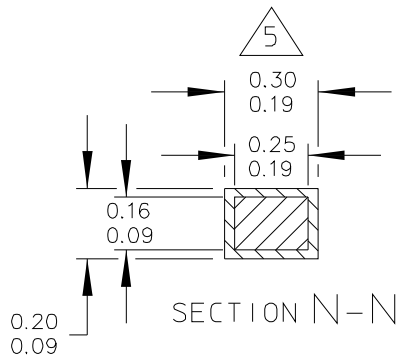
NOTES:

1. POSITIONAL TOLERANCE OF LEADS, SHALL BE WITHIN 0.25 MM (0.010) AT MAXIMUM MATERIAL CONDITION, IN RELATION TO SEATING PLANE AND EACH OTHER.
2. DIMENSION TO CENTER OF LEADS WHEN FORMED PARALLEL.
3. DIMENSION DOES NOT INCLUDE MOLD FLASH.
4. 710-01 OBSOLETE, NEW STD 710-02.
5. CONTROLLING DIMENSION: INCH

INCH			MILLIMETER		DIM	INCH		MILLIMETER	
DIM	MIN	MAX	MIN	MAX		MIN	MAX	MIN	MAX
A	1.435	1.465	36.45	37.21					
B	0.540	0.560	13.72	14.22					
C	0.155	0.200	3.94	5.08					
D	0.014	0.022	0.36	0.56					
F	0.040	0.060	1.02	1.52					
G	0.100 BSC		2.54 BSC						
H	0.065	0.085	1.65	2.16					
J	0.008	0.015	0.20	0.38					
K	0.115	0.135	2.92	3.43					
L	0.600 BSC		15.24 BSC						
M	0°	15°	0°	15°					
N	0.020	0.040	0.51	1.02					
© FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED.				MECHANICAL OUTLINE			PRINT VERSION NOT TO SCALE		
TITLE: 28 LD PDIP					DOCUMENT NO: 98ASB42390B			REV: D	
					CASE NUMBER: 710-02			24 MAY 2005	
					STANDARD: NON-JEDEC				



© FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED.		MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE
TITLE: 16 LD TSSOP, PITCH 0.65MM		DOCUMENT NO: 98ASH70247A	REV: B
		CASE NUMBER: 948F-01	19 MAY 2005
		STANDARD: JEDEC	



© FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED.		MECHANICAL OUTLINE		PRINT VERSION NOT TO SCALE	
TITLE: 16 LD TSSOP, PITCH 0.65MM		DOCUMENT NO: 98ASH70247A		REV: B	
		CASE NUMBER: 948F-01		19 MAY 2005	
		STANDARD: JEDEC			

Ordering Information

NOTES:

1. CONTROLLING DIMENSION: MILLIMETER
2. DIMENSIONS AND TOLERANCES PER ANSI Y14.5M-1982.
3. DIMENSION DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH OR GATE BURRS SHALL NOT EXCEED 0.15 PER SIDE.
4. DIMENSION DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.25 PER SIDE.
5. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 TOTAL IN EXCESS OF THE DIMENSION AT MAXIMUM MATERIAL CONDITION.
6. TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.
7. DIMENSIONS ARE TO BE DETERMINED AT DATUM PLANE -W-.

© FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED.		MECHANICAL OUTLINE	PRINT VERSION NOT TO SCALE
TITLE: 16 LD TSSOP, PITCH 0.65MM	DOCUMENT NO: 98ASH70247A		REV: B
	CASE NUMBER: 948F-01		19 MAY 2005
	STANDARD: JEDEC		