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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	48MHz
Connectivity	I <sup>2</sup> C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	24
Program Memory Size	16KB (8K x 16)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 19x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18lf24k22-e-ss

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

# 2.11.3 CLOCK SWITCH TIMING

When switching between one oscillator and another, the new oscillator may not be operating which saves power (see Figure 2-9). If this is the case, there is a delay after the SCS<1:0> bits of the OSCCON register are modified before the frequency change takes place. The OSTS and IOFS bits of the OSCCON register will reflect the current active status of the external and HFINTOSC oscillators. The timing of a frequency selection is as follows:

- 1. SCS<1:0> bits of the OSCCON register are modified.
- 2. The old clock continues to operate until the new clock is ready.
- 3. Clock switch circuitry waits for two consecutive rising edges of the old clock after the new clock ready signal goes true.
- 4. The system clock is held low starting at the next falling edge of the old clock.
- 5. Clock switch circuitry waits for an additional two rising edges of the new clock.
- 6. On the next falling edge of the new clock the low hold on the system clock is released and new clock is switched in as the system clock.
- 7. Clock switch is complete.

See Figure 2-1 for more details.

If the HFINTOSC is the source of both the old and new frequency, there is no start-up delay before the new frequency is active. This is because the old and new frequencies are derived from the HFINTOSC via the postscaler and multiplexer.

Start-up delay specifications are located in **Section 27.0 "Electrical Specifications**", under AC Specifications (Oscillator Module).

# 2.12 Two-Speed Clock Start-up Mode

Two-Speed Start-up mode provides additional power savings by minimizing the latency between external oscillator start-up and code execution. In applications that make heavy use of the Sleep mode, Two-Speed Start-up will remove the external oscillator start-up time from the time spent awake and can reduce the overall power consumption of the device.

This mode allows the application to wake-up from Sleep, perform a few instructions using the HFINTOSC as the clock source and go back to Sleep without waiting for the primary oscillator to become stable.

Note: Executing a SLEEP instruction will abort the oscillator start-up time and will cause the OSTS bit of the OSCCON register to remain clear.

When the oscillator module is configured for LP, XT or HS modes, the Oscillator Start-up Timer (OST) is enabled (see **Section 2.5.1 "Oscillator Start-up Timer (OST)**"). The OST will suspend program execution until 1024 oscillations are counted. Two-Speed Start-up mode minimizes the delay in code execution by operating from the internal oscillator as the OST is counting. When the OST count reaches 1024 and the OSTS bit of the OSCCON register is set, program execution switches to the external oscillator.

#### 2.12.1 TWO-SPEED START-UP MODE CONFIGURATION

Two-Speed Start-up mode is enabled when all of the following settings are configured as noted:

- Two-Speed Start-up mode is enabled when the IESO of the CONFIG1H Configuration register is set.
- SCS<1:0> (of the OSCCON register) = 00.
- FOSC<2:0> bits of the CONFIG1H Configuration register are configured for LP, XT or HS mode.

Two-Speed Start-up mode becomes active after:

- Power-on Reset (POR) and, if enabled, after Power-up Timer (PWRT) has expired, or
- · Wake-up from Sleep.

# 4.5 Brown-out Reset (BOR)

PIC18(L)F2X/4XK22 devices implement a BOR circuit that provides the user with a number of configuration and power-saving options. The BOR is controlled by the BORV<1:0> and BOREN<1:0> bits of the CONFIG2L Configuration register. There are a total of four BOR configurations which are summarized in Table 4-1.

The BOR threshold is set by the BORV<1:0> bits. If BOR is enabled (any values of BOREN<1:0>, except '00'), any drop of VDD below VBOR for greater than TBOR will reset the device. A Reset may or may not occur if VDD falls below VBOR for less than TBOR. The chip will remain in Brown-out Reset until VDD rises above VBOR.

If the Power-up Timer is enabled, it will be invoked after VDD rises above VBOR; it then will keep the chip in Reset for an additional time delay, TPWRT. If VDD drops below VBOR while the Power-up Timer is running, the chip will go back into a Brown-out Reset and the Power-up Timer will be initialized. Once VDD rises above VBOR, the Power-up Timer will execute the additional time delay.

BOR and the Power-on Timer (PWRT) are independently configured. Enabling BOR Reset does not automatically enable the PWRT.

The BOR circuit has an output that feeds into the POR circuit and rearms the POR within the operating range of the BOR. This early rearming of the POR ensures that the device will remain in Reset in the event that VDD falls below the operating range of the BOR circuitry.

#### 4.5.1 DETECTING BOR

When BOR is enabled, the  $\overline{\text{BOR}}$  bit always resets to '0' on any BOR or POR event. This makes it difficult to determine if a BOR event has occurred just by reading the state of  $\overline{\text{BOR}}$  alone. A more reliable method is to simultaneously check the state of both POR and  $\overline{\text{BOR}}$ . This assumes that the POR and  $\overline{\text{BOR}}$  bits are reset to '1' by software immediately after any POR event. If  $\overline{\text{BOR}}$  is '0' while  $\overline{\text{POR}}$  is '1', it can be reliably assumed that a BOR event has occurred.

### 4.5.2 SOFTWARE ENABLED BOR

When BOREN<1:0> = 01, the BOR can be enabled or disabled by the user in software. This is done with the SBOREN control bit of the RCON register. Setting SBOREN enables the BOR to function as previously described. Clearing SBOREN disables the BOR entirely. The SBOREN bit operates only in this mode; otherwise it is read as '0'.

Placing the BOR under software control gives the user the additional flexibility of tailoring the application to the environment without having to reprogram the device to change BOR configuration. It also allows the user to tailor device power consumption in software by eliminating the incremental current that the BOR consumes. While the BOR current is typically very small, it may have some impact in low-power applications.

Note:	Even	when	BOR	is	under	software				
	control, the BOR Reset voltage level is still									
	set by the BORV<1:0> Configuration bits.									
	lt canr	not be c	hangeo	d by	softwar	e.				

#### 4.5.3 DISABLING BOR IN SLEEP MODE

When BOREN<1:0> = 10, the BOR remains under hardware control and operates as previously described. Whenever the device enters Sleep mode, however, the BOR is automatically disabled. When the device returns to any other operating mode, BOR is automatically re-enabled.

This mode allows for applications to recover from brown-out situations, while actively executing code, when the device requires BOR protection the most. At the same time, it saves additional power in Sleep mode by eliminating the small incremental BOR current.

### 4.5.4 MINIMUM BOR ENABLE TIME

Enabling the BOR also enables the Fixed Voltage Reference (FVR) when no other peripheral requiring the FVR is active. The BOR becomes active only after the FVR stabilizes. Therefore, to ensure BOR protection, the FVR settling time must be considered when enabling the BOR in software or when the BOR is automatically enabled after waking from Sleep. If the BOR is disabled, in software or by reentering Sleep before the FVR stabilizes, the BOR circuit will not sense a BOR condition. The FVRST bit of the VREFCON0 register can be used to determine FVR stability.



Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
ANSELA	—	—	ANSA5	—	ANSA3	ANSA2	ANSA1	ANSA0	149
CM1CON0	C10N	C10UT	C10E	C1POL	C1SP	C1R	C1CH	l<1:0>	308
CM2CON0	C2ON	C2OUT	C2OE	C2POL	C2SP	C2R	C2CH	l<1:0>	308
LATA	LATA7	LATA6	LATA5	LATA4	LATA3	LATA2	LATA1	LATA0	152
VREFCON1	DACEN	DACLPS	DACOE	—	DACPSS<1:0> — DACNSS				335
VREFCON2	—	—				DACR<4:0>			336
HLVDCON	VDIRMAG	BGVST	IRVST	HLVDEN		HLVDL	<3:0>		337
PORTA	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	148
SLRCON	—	—	_	SLRE	SLRD	SLRC	SLRB	SLRA	153
SRCON0	SRLEN	S	RCLK<2:0	>	SRQEN	SRNQEN	SRPS	SRPR	329
SSP1CON1	WCOL	SSPOV	SSPEN	CKP		SSPM	<3:0>		253
TOCON	TMR0ON	T08BIT	TOCS	T0SE	PSA	Т	0PS<2:0>		154
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	151

TABLE 10-2: REGISTERS ASSOCIATED WITH PORTA

**Legend:** — = unimplemented locations, read as '0'. Shaded bits are not used for PORTA.

#### TABLE 10-3: CONFIGURATION REGISTERS ASSOCIATED WITH PORTA

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CONFIG1H	IESO	FCMEN	PRICLKEN	PLLCFG	FOSC<3:0>				345

**Legend:** — = unimplemented locations, read as '0'. Shaded bits are not used for PORTA.

R/W-1	R/W-1	R/W-1	R/W-1	U-0	U-0	U-0	U-0
IOCB7	IOCB6	IOCB5	IOCB4	—	—	_	—
bit 7	-						bit 0

#### REGISTER 10-13: IOCB: INTERRUPT-ON-CHANGE PORTB CONTROL REGISTER

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-4 **IOCB<7:4>:** Interrupt-on-Change PORTB control bits

1 = Interrupt-on-change enabled<sup>(1)</sup>

0 = Interrupt-on-change disabled

**Note 1:** Interrupt-on-change requires that the RBIE bit (INTCON<3>) is set.

# REGISTER 10-14: SLRCON: SLEW RATE CONTROL REGISTER

U-0	U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	—	SLRE <sup>(1)</sup>	SLRD <sup>(1)</sup>	SLRC	SLRB	SLRA
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-5	Unimplemented: Read as '0'	
bit 4	SLRE: PORTE Slew Rate Control bit <sup>(1)</sup>	
	<ul> <li>1 = All outputs on PORTE slew at a limited rate</li> <li>0 = All outputs on PORTE slew at the standard rate</li> </ul>	
bit 3	SLRD: PORTD Slew Rate Control bit <sup>(1)</sup>	
	<ul> <li>1 = All outputs on PORTD slew at a limited rate</li> <li>0 = All outputs on PORTD slew at the standard rate</li> </ul>	
bit 2	SLRC: PORTC Slew Rate Control bit	
	<ul> <li>1 = All outputs on PORTC slew at a limited rate</li> <li>0 = All outputs on PORTC slew at the standard rate</li> </ul>	
bit 1	SLRB: PORTB Slew Rate Control bit	
	<ul> <li>1 = All outputs on PORTB slew at a limited rate</li> <li>0 = All outputs on PORTB slew at the standard rate</li> </ul>	
bit 0	SLRA: PORTA Slew Rate Control bit	
	<ul> <li>1 = All outputs on PORTA slew at a limited rate<sup>(2)</sup></li> <li>0 = All outputs on PORTA slew at the standard rate</li> </ul>	
Note 1	These hits are sucilable on DIC19/L\E4VK22 devices	

**Note 1:** These bits are available on PIC18(L)F4XK22 devices.

2: The slew rate of RA6 defaults to standard rate when the pin is used as CLKOUT.

# PIC18(L)F2X/4XK22

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
PIE2	OSCFIE	C1IE	C2IE	EEIE	BCL1IE	HLVDIE	TMR3IE	CCP2IE	118
PIE4	—	—	—	—	—	CCP5IE	CCP4IE	CCP3IE	120
PIR1	—	ADIF	RC1IF	TX1IF	SSP1IF	CCP1IF	TMR2IF	TMR1IF	112
PIR2	OSCFIF	C1IF	C2IF	EEIF	BCL1IF	HLVDIF	TMR3IF	CCP2IF	113
PIR4	—	—	—	—	—	CCP5IF	CCP4IF	CCP3IF	115
PMD0	UART2MD	UART1MD	TMR6MD	TMR5MD	TMR4MD	TMR3MD	TMR2MD	TMR1MD	52
PMD1	MSSP2MD	MSSP1MD	—	CCP5MD	CCP4MD	CCP3MD	CCP2MD	CCP1MD	53
T1CON	TMR1C	S<1:0>	T1CKP	S<1:0>	T1SOSCEN	T1SYNC	T1RD16	TMR10N	166
T1GCON	TMR1GE	T1GPOL	T1GTM	T1GSPM	T1GGO/DONE	T1GVAL	T1GSS<1:0>		167
T3CON	TMR3C	S<1:0>	T3CKP	S<1:0>	T3SOSCEN	T3SYNC	T3RD16 TMR3ON		166
T3GCON	TMR3GE	T3GPOL	T3GTM	T3GSPM	T3GGO/DONE	T3GVAL	T3GSS	5<1:0>	167
T5CON	TMR5C	S<1:0>	T5CKP	S<1:0>	T5SOSCEN	T5SYNC	T5RD16	TMR5ON	166
T5GCON	TMR5GE	T5GPOL	T5GTM	T5GSPM	T5GGO/DONE	T5GVAL	T5GSS	5<1:0>	167
TMR1H		Holding	Register for th	e Most Signifi	icant Byte of the 1	6-bit TMR1 Re	egister		—
TMR1L			Least Sign	ificant Byte of	the 16-bit TMR1	Register			_
TMR3H		Holding	Register for th	e Most Signifi	icant Byte of the 1	6-bit TMR3 Re	egister		_
TMR3L			Least Sign	ificant Byte of	the 16-bit TMR3	Register			_
TMR5H		Holding	Register for th	e Most Signifi	icant Byte of the 1	6-bit TMR5 Re	egister		_
TMR5L			Least Sign	ificant Byte of	f the 16-bit TMR5	Register			—
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	151
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	151
TRISC	TRISC7	TRISC6	TRISC5	TRISC4	TRISC3	TRISC2	TRISC1	TRISC0	151
TRISD <sup>(1)</sup>	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	151
TRISE	WPUE3	—	—	—	—	TRISE2(1)	TRISE1 <sup>(1)</sup>	TRISE0 <sup>(1)</sup>	151

### TABLE 14-3: REGISTERS ASSOCIATED WITH CAPTURE (CONTINUED)

Legend: — = Unimplemented location, read as '0'. Shaded bits are not used by Capture mode.

**Note 1:** These registers/bits are available on PIC18(L)F4XK22 devices.

### TABLE 14-4: CONFIGURATION REGISTERS ASSOCIATED WITH CAPTURE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
CONFIG3H	MCLRE	_	P2BMX	T3CMX	HFOFST	ССР3МХ	PBADEN	CCP2MX	348

Legend: — = Unimplemented location, read as '0'. Shaded bits are not used by Capture mode.

28-Lead Ultra Thin Plastic Quad Flat, No Lead Package (MV) - 4x4 mm Body [UQFN] With 0.40 mm Contact Length





	MILLIMETERS				
Dimension	MIN	NOM	MAX		
Contact Pitch	Е	0.40 BSC			
Optional Center Pad Width	W2			2.35	
Optional Center Pad Length	T2			2.35	
Contact Pad Spacing	C1		4.00		
Contact Pad Spacing	C2		4.00		
Contact Pad Width (X28)	X1			0.20	
Contact Pad Length (X28)	Y1			0.80	
Distance Between Pads	G	0.20			

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2152A

# 44-Lead Plastic Quad Flat, No Lead Package (ML) - 8x8 mm Body [QFN or VQFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	44		
Pitch	е	0.65 BSC		
Overall Height	Α	0.80	0.90	1.00
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	A3	0.20 REF		
Overall Width	E	8.00 BSC		
Exposed Pad Width	E2	6.25	6.45	6.60
Overall Length	D	8.00 BSC		
Exposed Pad Length	D2	6.25	6.45	6.60
Terminal Width	b	0.20	0.30	0.35
Terminal Length	L	0.30	0.40	0.50
Terminal-to-Exposed-Pad	K	0.20	-	-

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated
- 3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-103D Sheet 2 of 2

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