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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	e200z0h
Core Size	32-Bit Single-Core
Speed	64MHz
Connectivity	CANbus, I ² C, LINbus, SCI, SPI
Peripherals	DMA, POR, PWM, WDT
Number of I/O	123
Program Memory Size	512KB (512K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	32K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.5V
Data Converters	A/D 36x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	144-LQFP
Supplier Device Package	144-LQFP (20x20)
Purchase URL	https://www.e-xfl.com/product-detail/stmicroelectronics/spc560b50l5c6e0y

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2 Block diagram

Figure 1 shows a top-level block diagram of the SPC560B40x/50x and SPC560C40x/50x device series.

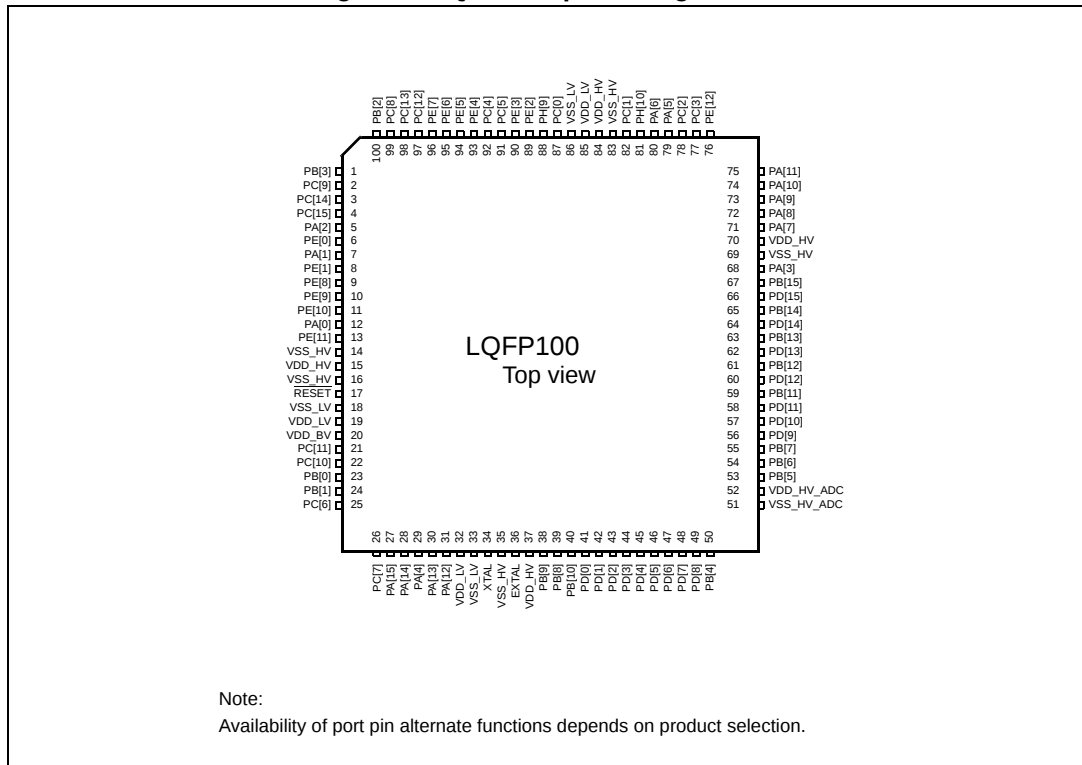


Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ⁽¹⁾	Function	Peripheral	I/O direction ⁽²⁾	Pad type	RESET configuration	Pin number			
								LQFP64	LQFP100	LQFP144	LBGA208 ⁽³⁾
PB[11] (8)	PCR[27]	AF0 AF1 AF2 AF3 —	GPIO[27] E0UC[3] — CS0_0 ANS[3]	SIUL eMIOS_0 — DSPI_0 ADC	I/O I/O — I/O I	J	Tristate	38	59	81	N13
PB[12]	PCR[28]	AF0 AF1 AF2 AF3 —	GPIO[28] E0UC[4] — CS1_0 ANX[0]	SIUL eMIOS_0 — DSPI_0 ADC	I/O I/O — O I	J	Tristate	39	61	83	M16
PB[13]	PCR[29]	AF0 AF1 AF2 AF3 —	GPIO[29] E0UC[5] — CS2_0 ANX[1]	SIUL eMIOS_0 — DSPI_0 ADC	I/O I/O — O I	J	Tristate	40	63	85	M13
PB[14]	PCR[30]	AF0 AF1 AF2 AF3 —	GPIO[30] E0UC[6] — CS3_0 ANX[2]	SIUL eMIOS_0 — DSPI_0 ADC	I/O I/O — O I	J	Tristate	41	65	87	L16
PB[15]	PCR[31]	AF0 AF1 AF2 AF3 —	GPIO[31] E0UC[7] — CS4_0 ANX[3]	SIUL eMIOS_0 — DSPI_0 ADC	I/O I/O — O I	J	Tristate	42	67	89	L13
PC[0] ⁽⁹⁾	PCR[32]	AF0 AF1 AF2 AF3	GPIO[32] — TDI —	SIUL — JTAGC —	I/O — I —	M	Input, weak pull-up	59	87	126	A8
PC[1] ⁽⁹⁾	PCR[33]	AF0 AF1 AF2 AF3	GPIO[33] — TDO ⁽¹⁰⁾ —	SIUL — JTAGC —	I/O — O —	M	Tristate	54	82	121	C9

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ⁽¹⁾	Function	Peripheral	I/O direction ⁽²⁾	Pad type	RESET configuration	Pin number			
								LQFP64	LQFP100	LQFP144	LBGA208 ⁽³⁾
PD[6]	PCR[54]	AF0 AF1 AF2 AF3 —	GPIO[54] — — — GPI[10]	SIUL — — — ADC	I — — — I	I	Tristate	—	47	69	T14
PD[7]	PCR[55]	AF0 AF1 AF2 AF3 —	GPIO[55] — — — GPI[11]	SIUL — — — ADC	I — — — I	I	Tristate	—	48	70	R14
PD[8]	PCR[56]	AF0 AF1 AF2 AF3 —	GPIO[56] — — — GPI[12]	SIUL — — — ADC	I — — — I	I	Tristate	—	49	71	T15
PD[9]	PCR[57]	AF0 AF1 AF2 AF3 —	GPIO[57] — — — GPI[13]	SIUL — — — ADC	I — — — I	I	Tristate	—	56	78	N15
PD[10]	PCR[58]	AF0 AF1 AF2 AF3 —	GPIO[58] — — — GPI[14]	SIUL — — — ADC	I — — — I	I	Tristate	—	57	79	N14
PD[11]	PCR[59]	AF0 AF1 AF2 AF3 —	GPIO[59] — — — GPI[15]	SIUL — — — ADC	I — — — I	I	Tristate	—	58	80	N16
PD[12] ⁽⁸⁾	PCR[60]	AF0 AF1 AF2 AF3 —	GPIO[60] CS5_0 E0UC[24] — ANS[4]	SIUL DSPI_0 eMIOS_0 — ADC	I/O O I/O — I	J	Tristate	—	60	82	M15

Table 6. Functional port pin descriptions (continued)

Port pin	PCR	Alternate function ⁽¹⁾	Function	Peripheral	I/O direction ⁽²⁾	Pad type	RESET configuration	Pin number			
								LQFP64	LQFP100	LQFP144	LBGA208 ⁽³⁾
PG[7]	PCR[103]	AF0 AF1 AF2 AF3	GPIO[103] E1UC[16] — —	SIUL eMIOS_1 — —	I/O I/O — —	M	Tristate	—	—	29	M1
PG[8]	PCR[104]	AF0 AF1 AF2 AF3 —	GPIO[104] E1UC[17] — CS0_2 EIRQ[15]	SIUL eMIOS_1 — DSPI_2 SIUL	I/O I/O — I/O I	S	Tristate	—	—	26	L2
PG[9]	PCR[105]	AF0 AF1 AF2 AF3	GPIO[105] E1UC[18] — SCK_2	SIUL eMIOS_1 — DSPI_2	I/O I/O — I/O	S	Tristate	—	—	25	L1
PG[10]	PCR[106]	AF0 AF1 AF2 AF3	GPIO[106] E0UC[24] — —	SIUL eMIOS_0 — —	I/O I/O — —	S	Tristate	—	—	114	D13
PG[11]	PCR[107]	AF0 AF1 AF2 AF3	GPIO[107] E0UC[25] — —	SIUL eMIOS_0 — —	I/O I/O — —	M	Tristate	—	—	115	B12
PG[12]	PCR[108]	AF0 AF1 AF2 AF3	GPIO[108] E0UC[26] — —	SIUL eMIOS_0 — —	I/O I/O — —	M	Tristate	—	—	92	K14
PG[13]	PCR[109]	AF0 AF1 AF2 AF3	GPIO[109] E0UC[27] — —	SIUL eMIOS_0 — —	I/O I/O — —	M	Tristate	—	—	91	K16
PG[14]	PCR[110]	AF0 AF1 AF2 AF3	GPIO[110] E1UC[0] — —	SIUL eMIOS_1 — —	I/O I/O — —	S	Tristate	—	—	110	B14

Table 24. I/O weight⁽¹⁾ (continued)

Supply segment			Pad	LQFP144/LQFP100				LQFP64 ⁽²⁾			
				Weight 5 V		Weight 3.3 V		Weight 5 V		Weight 3.3 V	
LQFP 144	LQFP 100	LQFP 64		SRC ⁽³⁾ = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1	SRC = 0	SRC = 1
2	2	2	PB[13]	10%	—	12%	—	18%	—	21%	—
		—	PD[14]	10%	—	12%	—	—	—	—	—
		2	PB[14]	10%	—	12%	—	18%	—	21%	—
		—	PD[15]	10%	—	11%	—	—	—	—	—
		2	PB[15]	9%	—	11%	—	18%	—	21%	—
			PA[3]	9%	—	11%	—	18%	—	21%	—
	—	—	PG[13]	9%	13%	10%	11%	—	—	—	—
	—	—	PG[12]	9%	12%	10%	11%	—	—	—	—
	—	—	PH[0]	5%	8%	6%	7%	—	—	—	—
	—	—	PH[1]	5%	7%	6%	6%	—	—	—	—
	—	—	PH[2]	5%	6%	5%	6%	—	—	—	—
	—	—	PH[3]	4%	6%	5%	5%	—	—	—	—
	—	—	PG[1]	4%	—	4%	—	—	—	—	—
	—	—	PG[0]	3%	4%	4%	4%	—	—	—	—
3	—	—	PF[15]	3%	—	4%	—	—	—	—	—
	—	—	PF[14]	4%	5%	5%	5%	—	—	—	—
	—	—	PE[13]	4%	—	5%	—	—	—	—	—
	3	2	PA[7]	5%	—	6%	—	16%	—	19%	—
			PA[8]	5%	—	6%	—	16%	—	19%	—
			PA[9]	5%	—	6%	—	15%	—	18%	—
			PA[10]	6%	—	7%	—	15%	—	18%	—
			PA[11]	6%	—	8%	—	14%	—	17%	—
		—	PE[12]	7%	—	8%	—	—	—	—	—
	—	—	PG[14]	7%	—	8%	—	—	—	—	—
	—	—	PG[15]	7%	10%	8%	9%	—	—	—	—
	—	—	PE[14]	7%	—	8%	—	—	—	—	—
	—	—	PE[15]	7%	9%	8%	8%	—	—	—	—
	—	—	PG[10]	6%	—	8%	—	—	—	—	—
	—	—	PG[11]	6%	9%	7%	8%	—	—	—	—
	3	2	PC[3]	6%	—	7%	—	7%	—	9%	—
			PC[2]	6%	8%	7%	7%	6%	9%	8%	8%

Table 25. Reset electrical characteristics (continued)

Symbol	C	Parameter	Conditions ⁽¹⁾	Value			Unit
				Min	Typ	Max	
V _{HYS}	CC	C	Input hysteresis CMOS (Schmitt Trigger)	—	0.1V _{DD}	—	V
V _{OL}	CC	P	Push Pull, I _{OL} = 2mA, V _{DD} = 5.0 V ± 10%, PAD3V5V = 0 (recommended)	—	—	0.1V _{DD}	V
		C	Output low level, Push Pull, I _{OL} = 1mA, V _{DD} = 5.0 V ± 10%, PAD3V5V = 1 ⁽²⁾	—	—	0.1V _{DD}	
		C	Output low level, Push Pull, I _{OL} = 1mA, V _{DD} = 3.3 V ± 10%, PAD3V5V = 1 (recommended)	—	—	0.5	
t _{tr}	CC	D	Output transition time output pin ⁽³⁾ , C _L = 25pF, V _{DD} = 5.0 V ± 10%, PAD3V5V = 0	—	—	10	ns
			C _L = 50pF, V _{DD} = 5.0 V ± 10%, PAD3V5V = 0	—	—	20	
			C _L = 100pF, V _{DD} = 5.0 V ± 10%, PAD3V5V = 0	—	—	40	
			C _L = 25pF, V _{DD} = 3.3 V ± 10%, PAD3V5V = 1	—	—	12	
			C _L = 50pF, V _{DD} = 3.3 V ± 10%, PAD3V5V = 1	—	—	25	
			C _L = 100pF, V _{DD} = 3.3 V ± 10%, PAD3V5V = 1	—	—	40	
W _{FRST}	SR	P	RESET input filtered pulse	—	—	40	ns
W _{NFRST}	SR	P	RESET input not filtered pulse	—	1000	—	ns
I _{WPUL}	CC	P	Weak pull-up current absolute value	V _{DD} = 3.3 V ± 10%, PAD3V5V = 1	10	—	μA
		D		V _{DD} = 5.0 V ± 10%, PAD3V5V = 0	10	—	
		P		V _{DD} = 5.0 V ± 10%, PAD3V5V = 1 ⁽²⁾	10	—	

1. V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = -40 to 125 °C, unless otherwise specified

2. This transient configuration does not occurs when device is used in the V_{DD} = 3.3 V ± 10% range.

3. C_L includes device and package capacitance (C_{PKG} < 5 pF).

$$ESR_{STDBY}(MAX) = |\Delta V_{DD}(STDBY)| / (I_{DD_BV} - 200 \text{ mA}) = (30 \text{ mV}) / (100 \text{ mA}) = 0.3 \Omega$$

$$C_{STDBY}(MIN) = (I_{DD_BV} - 200 \text{ mA}) / dV_{DD}(STDBY) / dt = (300 \text{ mA} - 200 \text{ mA}) / (15 \text{ mV}/\mu\text{s}) = 6.7 \mu\text{F}$$

In case optimization is required, $C_{STDBY}(MIN)$ and $ESR_{STDBY}(MAX)$ should be calculated based on the regulator characteristics as well as the board V_{DD} plane characteristics.

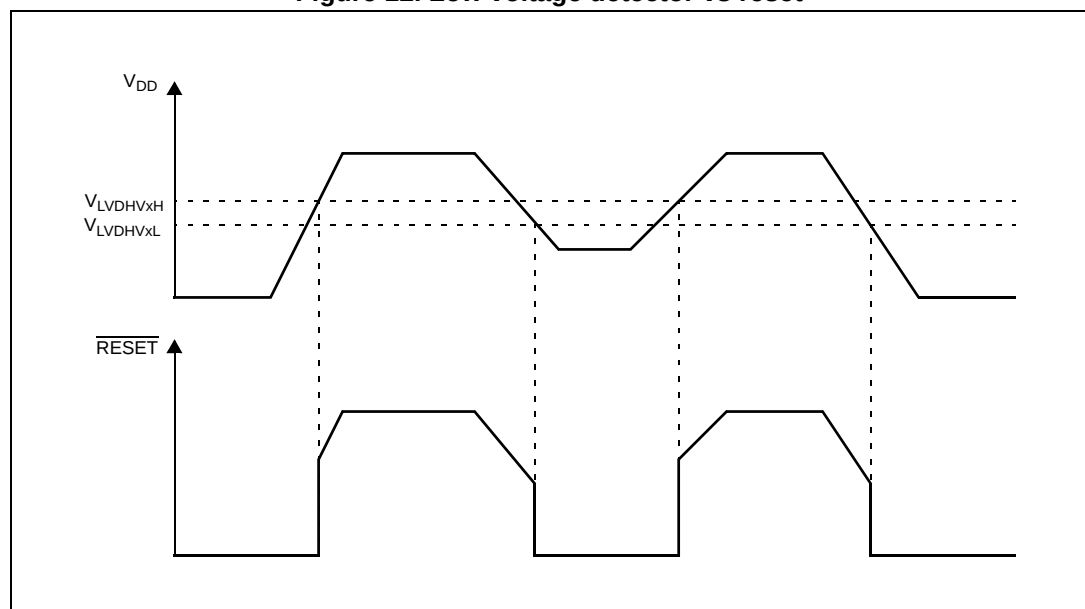
3.17.2 Low voltage detector electrical characteristics

The device implements a Power-on Reset (POR) module to ensure correct power-up initialization, as well as four low voltage detectors (LVDs) to monitor the V_{DD} and the V_{DD_LV} voltage while device is supplied:

- POR monitors V_{DD} during the power-up phase to ensure device is maintained in a safe reset state (refer to RGM Destructive Event Status (RGM_DES) Register flag F_POR in device reference manual)
- LVDHV3 monitors V_{DD} to ensure device reset below minimum functional supply (refer to RGM Destructive Event Status (RGM_DES) Register flag F_LVD27 in device reference manual)
- LVDHV5 monitors V_{DD} when application uses device in the $5.0 \text{ V} \pm 10\%$ range (refer to RGM Functional Event Status (RGM_FES) Register flag F_LVD45 in device reference manual)
- LVDLVCOR monitors power domain No. 1 (refer to RGM Destructive Event Status (RGM_DES) Register flag F_LVD12_PD1 in device reference manual)
- LVDLVBKP monitors power domain No. 0 (refer to RGM Destructive Event Status (RGM_DES) Register flag F_LVD12_PD0 in device reference manual)

Note: When enabled, power domain No. 2 is monitored through LVDLVBKP.

Figure 12. Low voltage detector vs reset



Note: [Figure 12: Low voltage detector vs reset](#) does not apply to LVDHV5 low voltage detector because LVDHV5 is automatically disabled during reset and it must be enabled by software again. Once the device is forced to reset by LVDHV5, the LVDHV5 is disabled and reset is

Table 31. Flash read access timing

Symbol	C	Parameter	Conditions ⁽¹⁾	Max	Unit
f_{READ}	CC	Maximum frequency for Flash reading	2 wait states	64	MHz
			1 wait state	40	
			0 wait states	20	

1. $V_{\text{DD}} = 3.3 \text{ V} \pm 10\% / 5.0 \text{ V} \pm 10\%$, $T_{\text{A}} = -40$ to 125 °C, unless otherwise specified

3.19.2 Flash power supply DC characteristics

Table 32 shows the power supply DC characteristics on external supply.

Table 32. Flash memory power supply DC electrical characteristics

Symbol	C	Parameter	Conditions ⁽¹⁾	Value			Unit
				Min	Typ	Max	
$I_{\text{FREAD}}^{(2)}$	CC	Sum of the current consumption on VDD_HV and VDD_BV on read access	Code flash memory module read $f_{\text{CPU}} = 64 \text{ MHz}^{(3)}$	—	15	33	mA
			Data flash memory module read $f_{\text{CPU}} = 64 \text{ MHz}^{(3)}$	—	15	33	
$I_{\text{FMOD}}^{(2)}$	CC	Sum of the current consumption on VDD_HV and VDD_BV on matrix modification (program/erase)	Program/Erase ongoing while reading code flash memory registers $f_{\text{CPU}} = 64 \text{ MHz}^{(3)}$	—	15	33	mA
			Program/Erase ongoing while reading data flash memory registers $f_{\text{CPU}} = 64 \text{ MHz}^{(3)}$	—	15	33	
I_{FLPW}	CC	Sum of the current consumption on VDD_HV and VDD_BV	During code flash memory low-power mode	—	—	900	μA
			During data flash memory low-power mode	—	—	900	
I_{FPWD}	CC	Sum of the current consumption on VDD_HV and VDD_BV	During code flash memory power-down mode	—	—	150	μA
			During data flash memory power-down mode	—	—	150	

1. $V_{\text{DD}} = 3.3 \text{ V} \pm 10\% / 5.0 \text{ V} \pm 10\%$, $T_{\text{A}} = -40$ to 125 °C, unless otherwise specified

2. This value is only relative to the actual duration of the read cycle

3. $f_{\text{CPU}} 64 \text{ MHz}$ can be achieved only at up to 105 °C

3.19.3 Start-up/Switch-off timings

Table 33. Start-up time/Switch-off time

Symbol	C		Parameter	Conditions ⁽¹⁾	Value			Unit
					Min	Typ	Max	
T _{FLARSTEXIT}	CC	T	Delay for Flash module to exit reset mode	Code Flash	—	—	125	μs
		T		Data Flash	—	—	125	
T _{FLALPEXIT}	CC	T	Delay for Flash module to exit low-power mode	Code Flash	—	—	0.5	
		T		Data Flash	—	—	0.5	
T _{FLAPDEXIT}	CC	T	Delay for Flash module to exit power-down mode	Code Flash	—	—	30	
		T		Data Flash	—	—	30	
T _{FLALPENTRY}	CC	T	Delay for Flash module to enter low-power mode	Code Flash	—	—	0.5	
		T		Data Flash	—	—	0.5	
T _{FLAPDENTRY}	CC	T	Delay for Flash module to enter power-down mode	Code Flash	—	—	1.5	
		T		Data Flash	—	—	1.5	

1. V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = -40 to 125 °C, unless otherwise specified

3.20 Electromagnetic compatibility (EMC) characteristics

Susceptibility tests are performed on a sample basis during product characterization.

3.20.1 Designing hardened software to avoid noise problems

EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. It should be noted that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user apply EMC software optimization and prequalification tests in relation with the EMC level requested for his application.

- Software recommendations: The software flowchart must include the management of runaway conditions such as:
 - Corrupted program counter
 - Unexpected reset
 - Critical data corruption (control registers...)
- Prequalification trials: Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the reset pin or the oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device. When unexpected behavior is detected, the software can be hardened to prevent unrecoverable errors occurring (see application note *Software Techniques For Improving Microcontroller EMC Performance* (AN1015)).

Table 38. Fast external crystal oscillator (4 to 16 MHz) electrical characteristics (continued)

Symbol		C	Parameter	Conditions ⁽¹⁾	Value			Unit
					Min	Typ	Max	
V _{IH}	SR	P	Input high level CMOS (Schmitt Trigger)	Oscillator bypass mode	0.65V _{DD}	—	V _{DD} +0.4	V
V _{IL}	SR	P	Input low level CMOS (Schmitt Trigger)	Oscillator bypass mode	−0.4	—	0.35V _{DD}	V

1. V_{DD} = 3.3 V ± 10% / 5.0 V ± 10%, T_A = −40 to 125 °C, unless otherwise specified
2. Stated values take into account only analog module consumption but not the digital contributor (clock tree and enabled peripherals)

3.22 Slow external crystal oscillator (32 kHz) electrical characteristics

The device provides a low power oscillator/resonator driver.

Figure 15. Crystal oscillator and resonator connection scheme

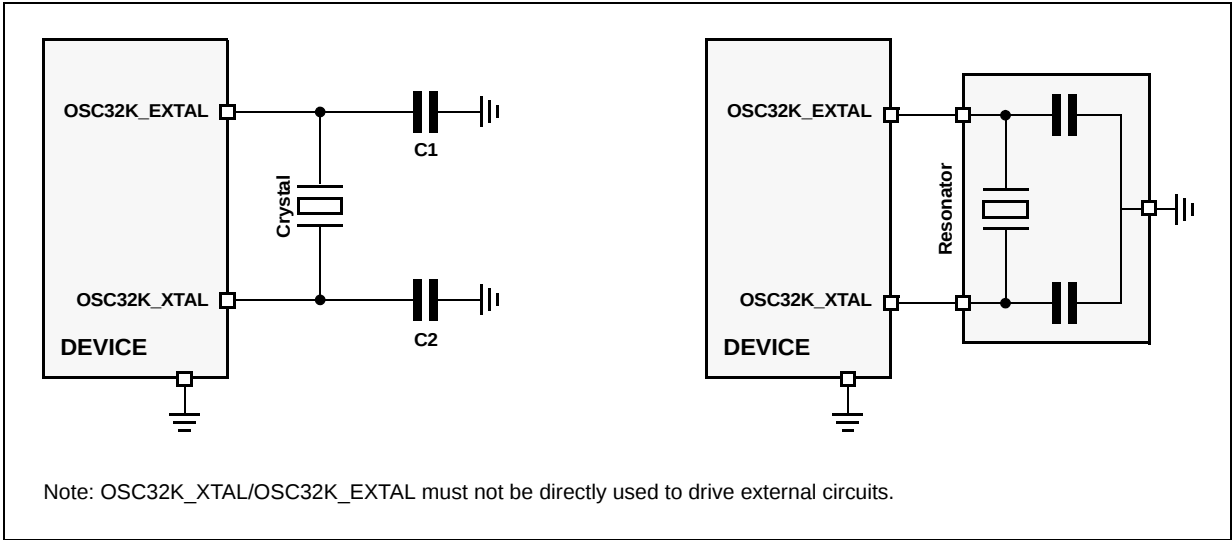


Figure 19. Input equivalent circuit (precise channels)

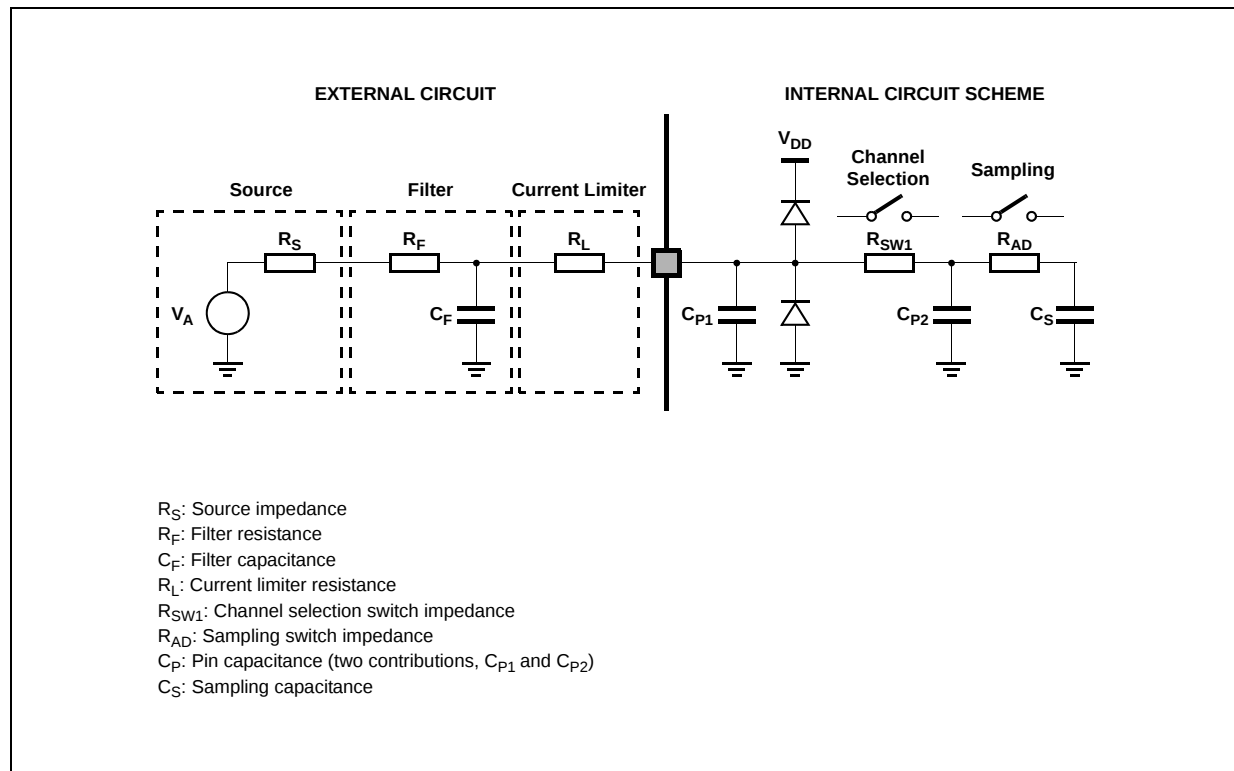
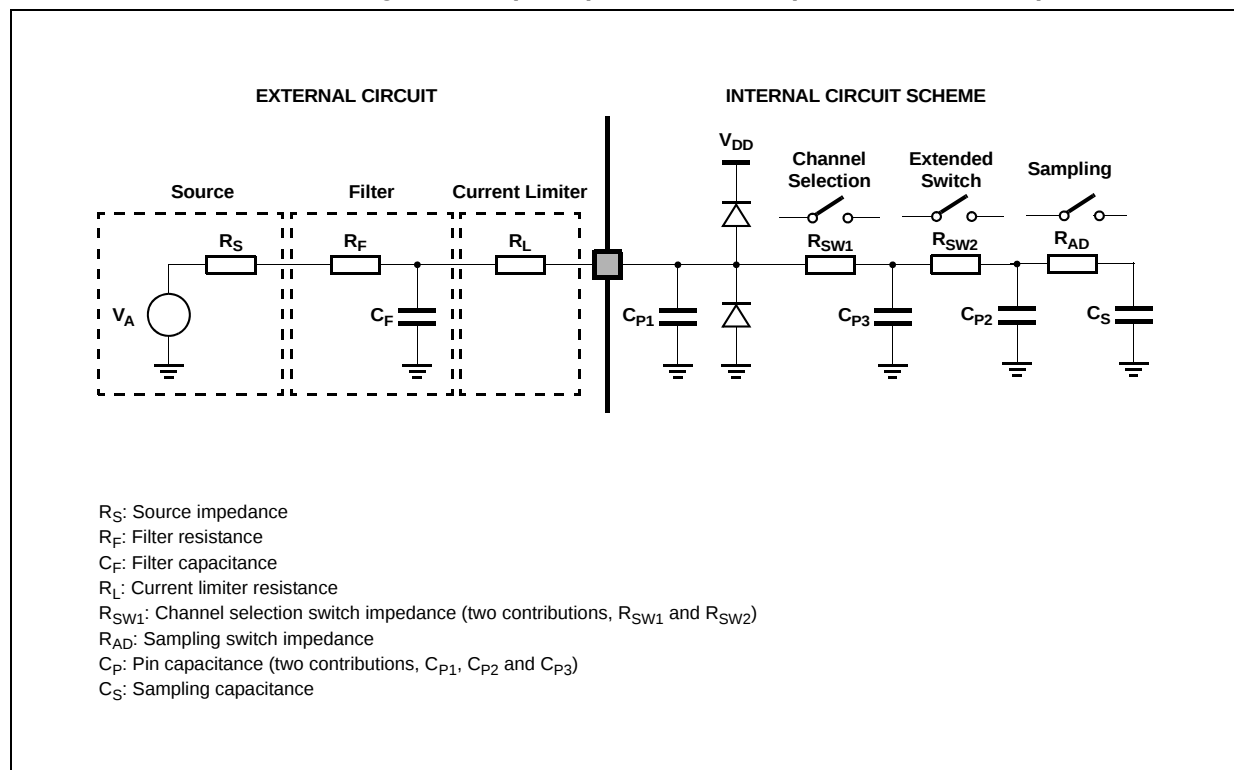


Figure 20. Input equivalent circuit (extended channels)



Equation 7

$$V_{A1} \cdot (C_S + C_{P1} + C_{P2}) = V_A \cdot (C_{P1} + C_{P2})$$

2. A second charge transfer involves also C_F (that is typically bigger than the on-chip capacitance) through the resistance R_L : again considering the worst case in which C_{P2} and C_S were in parallel to C_{P1} (since the time constant in reality would be faster), the time constant is:

Equation 8

$$\tau_2 < R_L \cdot (C_S + C_{P1} + C_{P2})$$

In this case, the time constant depends on the external circuit: in particular imposing that the transient is completed well before the end of sampling time t_s , a constraints on R_L sizing is obtained:

Equation 9

$$8.5 \cdot \tau_2 = 8.5 \cdot R_L \cdot (C_S + C_{P1} + C_{P2}) < t_s$$

Of course, R_L shall be sized also according to the current limitation constraints, in combination with R_S (source impedance) and R_F (filter resistance). Being C_F definitively bigger than C_{P1} , C_{P2} and C_S , then the final voltage V_{A2} (at the end of the charge transfer transient) will be much higher than V_{A1} . [Equation 10](#) must be respected (charge balance assuming now C_S already charged at V_{A1}):

Equation 10

$$V_{A2} \cdot (C_S + C_{P1} + C_{P2} + C_F) = V_A \cdot C_F + V_{A1} \cdot (C_{P1} + C_{P2} + C_S)$$

The two transients above are not influenced by the voltage source that, due to the presence of the $R_F C_F$ filter, is not able to provide the extra charge to compensate the voltage drop on C_S with respect to the ideal source V_A ; the time constant $R_F C_F$ of the filter is very high with respect to the sampling time (t_s). The filter is typically designed to act as anti-aliasing.

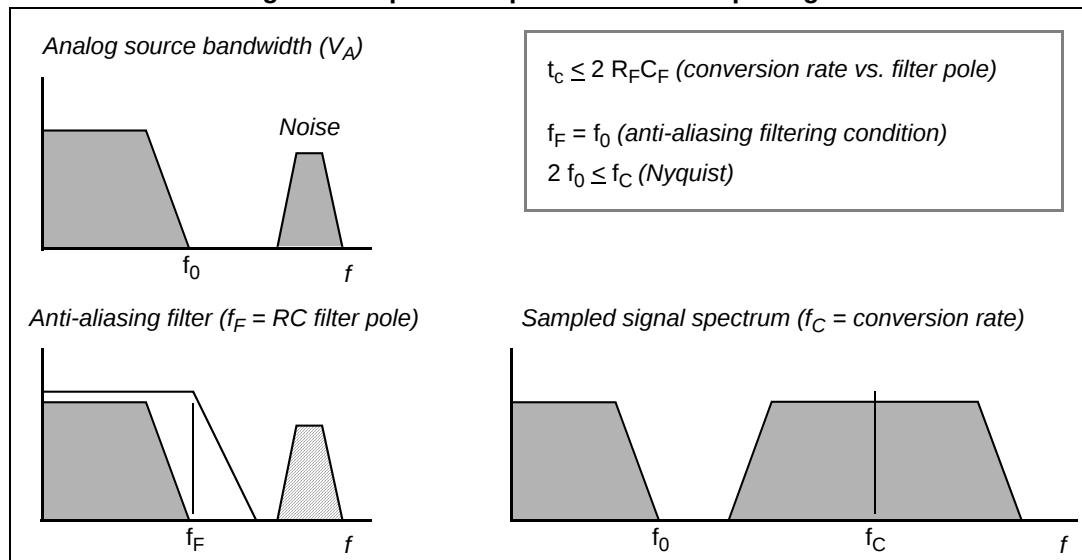
Figure 22. Spectral representation of input signal

Table 45. ADC conversion characteristics (continued)

Symbol		C	Parameter	Conditions ⁽¹⁾		Value			Unit
						Min	Typ	Max	
I _{INJ}	S R	—	Input current Injection	Current injection on one ADC input, different from the converted one	V _{DD} = 3.3 V ± 10%	−5	—	5	mA
					V _{DD} = 5.0 V ± 10%	−5	—	5	
INL	C C	T	Absolute value for integral non-linearity	No overload		—	0.5	1.5	LSB
DNL	C C	T	Absolute differential non-linearity	No overload		—	0.5	1.0	LSB
E _O	C C	T	Absolute offset error	—		—	0.5	—	LSB
E _G	C C	T	Absolute gain error	—		—	0.6	—	LSB
TUE _p	C C	P	Total unadjusted error ⁽⁷⁾ for precise channels, input only pins	Without current injection	−2	0.6	2	LSB	
		With current injection		−3		3			
TUE _x	C C	T	Total unadjusted error ⁽⁷⁾ for extended channel	Without current injection	−3	1	3	LSB	
		With current injection		−4		4			

- $V_{DD} = 3.3\text{ V} \pm 10\% / 5.0\text{ V} \pm 10\%$, $T_A = -40$ to $125\text{ }^{\circ}\text{C}$, unless otherwise specified.
- Analog and digital V_{SS} **must** be common (to be tied together externally).
- V_{AINx} may exceed V_{SS_ADC} and V_{DD_ADC} limits, remaining on absolute maximum ratings, but the results of the conversion will be clamped respectively to 0x000 or 0x3FF.
- Duty cycle is ensured by using system clock without prescaling. When $ADCLKSEL = 0$, the duty cycle is ensured by internal divider by 2.
- During the sampling time the input capacitance C_S can be charged/discharged by the external source. The internal resistance of the analog source must allow the capacitance to reach its final voltage level within t_S . After the end of the sampling time t_S , changes of the analog input voltage have no effect on the conversion result. Values for the sample clock t_S depend on programming.
- This parameter does not include the sampling time t_S , but only the time for determining the digital result and the time to load the result's register with the conversion result.
- Total Unadjusted Error: The maximum error that occurs without adjusting Offset and Gain errors. This error is a combination of Offset, Gain and Integral Linearity errors.

3.27 On-chip peripherals

3.27.1 Current consumption

Figure 28. DSPI modified transfer format timing – master, CPHA = 1

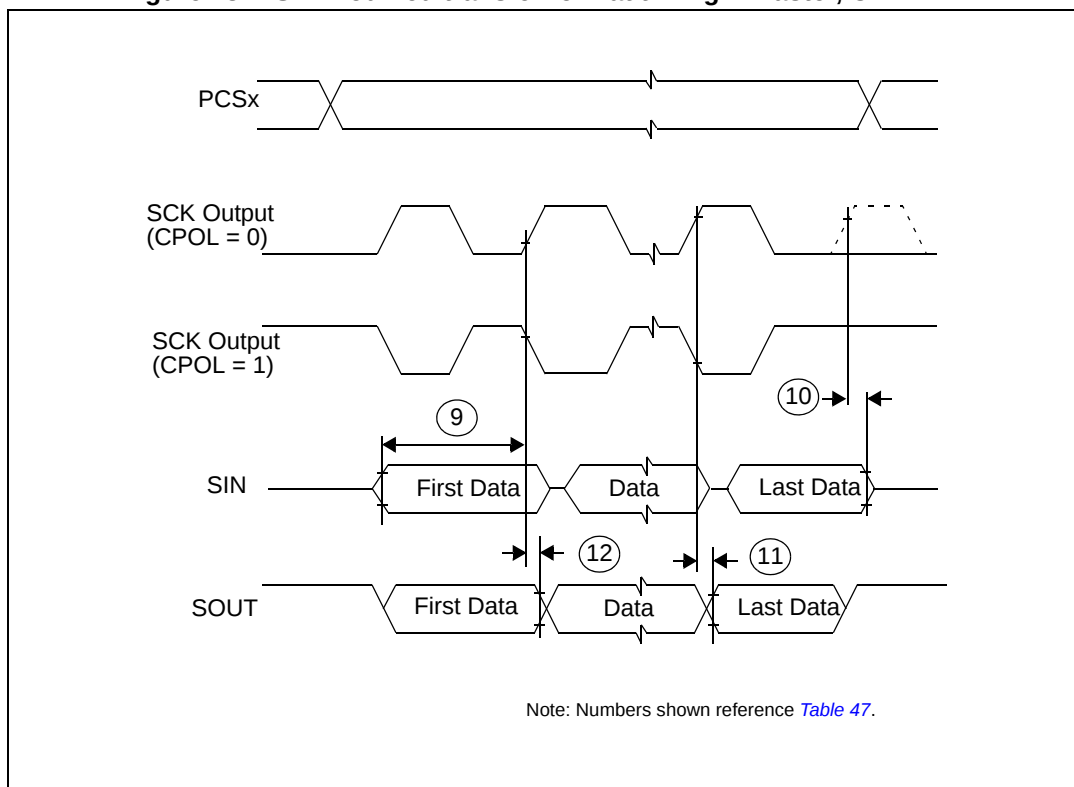
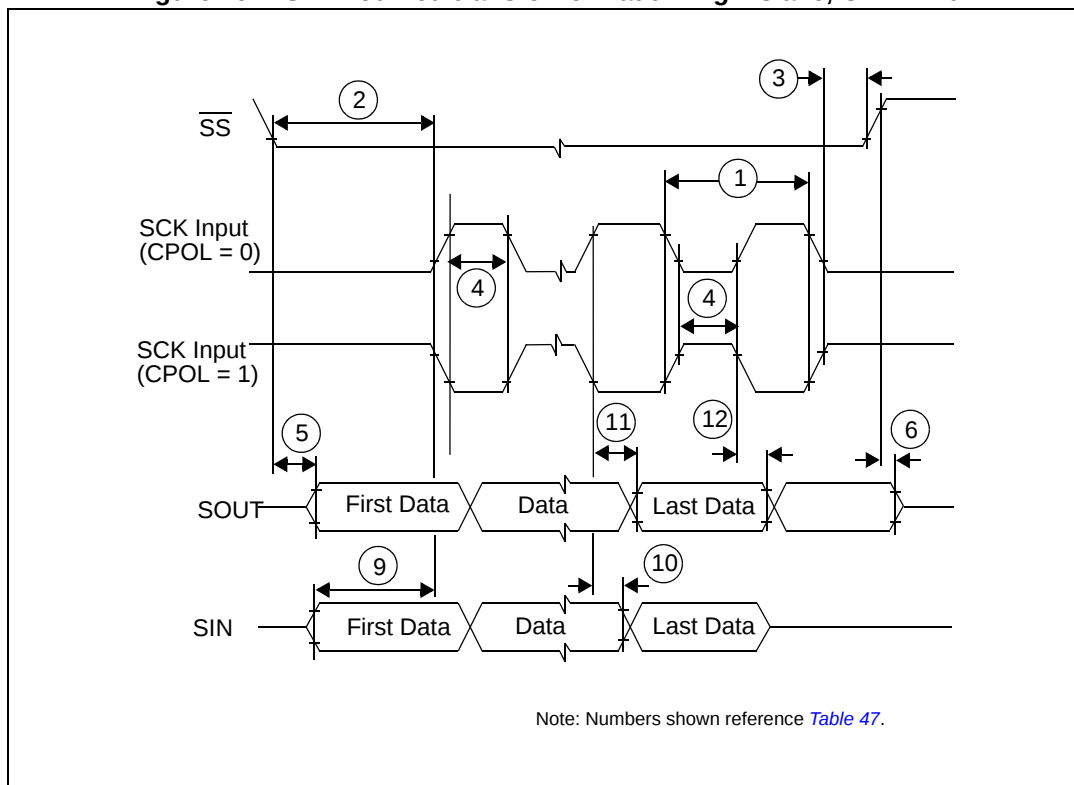


Figure 29. DSPI modified transfer format timing – slave, CPHA = 0

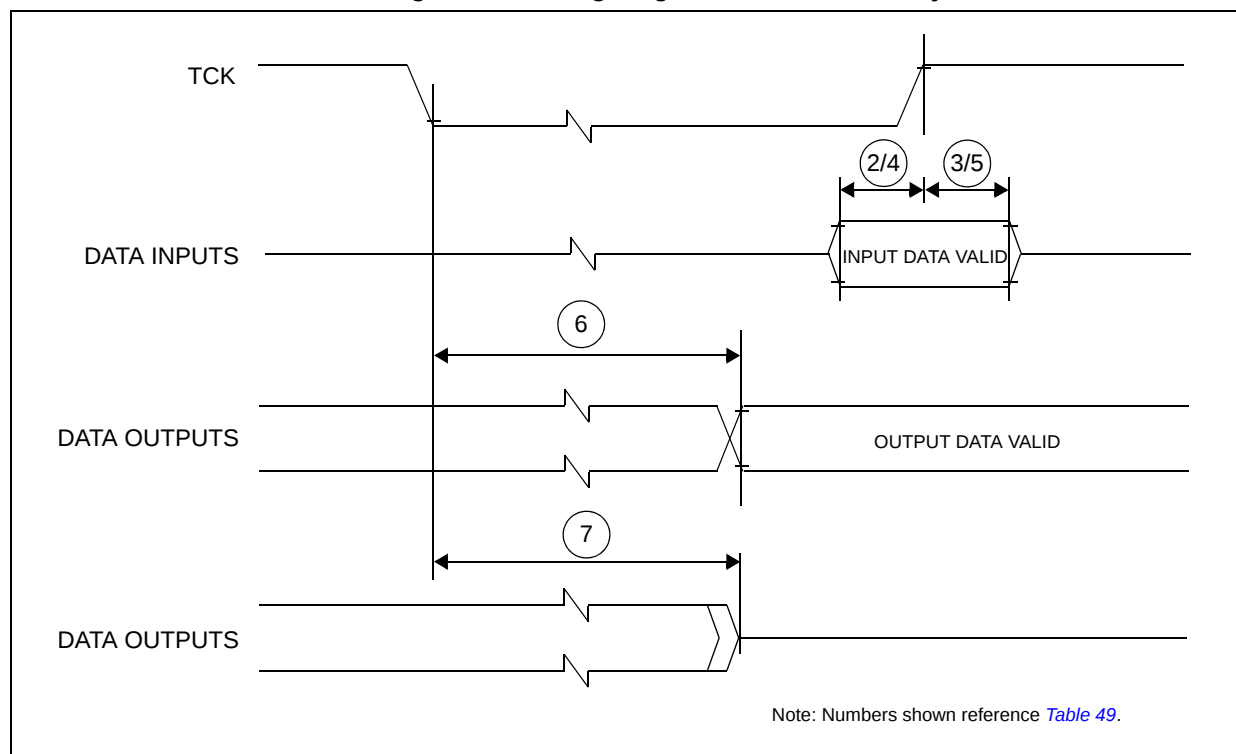


3.27.4 JTAG characteristics

Table 49. JTAG characteristics

No.	Symbol	C	D	Parameter	Value			Unit
					Min	Typ	Max	
1	t_{JCYC}	CC	D	TCK cycle time	64	—	—	ns
2	t_{TDIS}	CC	D	TDI setup time	15	—	—	ns
3	t_{TDIH}	CC	D	TDI hold time	5	—	—	ns
4	t_{TMSS}	CC	D	TMS setup time	15	—	—	ns
5	t_{TMSh}	CC	D	TMS hold time	5	—	—	ns
6	t_{TDOV}	CC	D	TCK low to TDO valid	—	—	33	ns
7	t_{TDOI}	CC	D	TCK low to TDO invalid	6	—	—	ns

Figure 33. Timing diagram – JTAG boundary scan



4 Package characteristics

4.1 ECOPACK®

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK® is an ST trademark.

4.2 Package mechanical data

4.2.1 LQFP64

Figure 34. LQFP64 package mechanical drawing

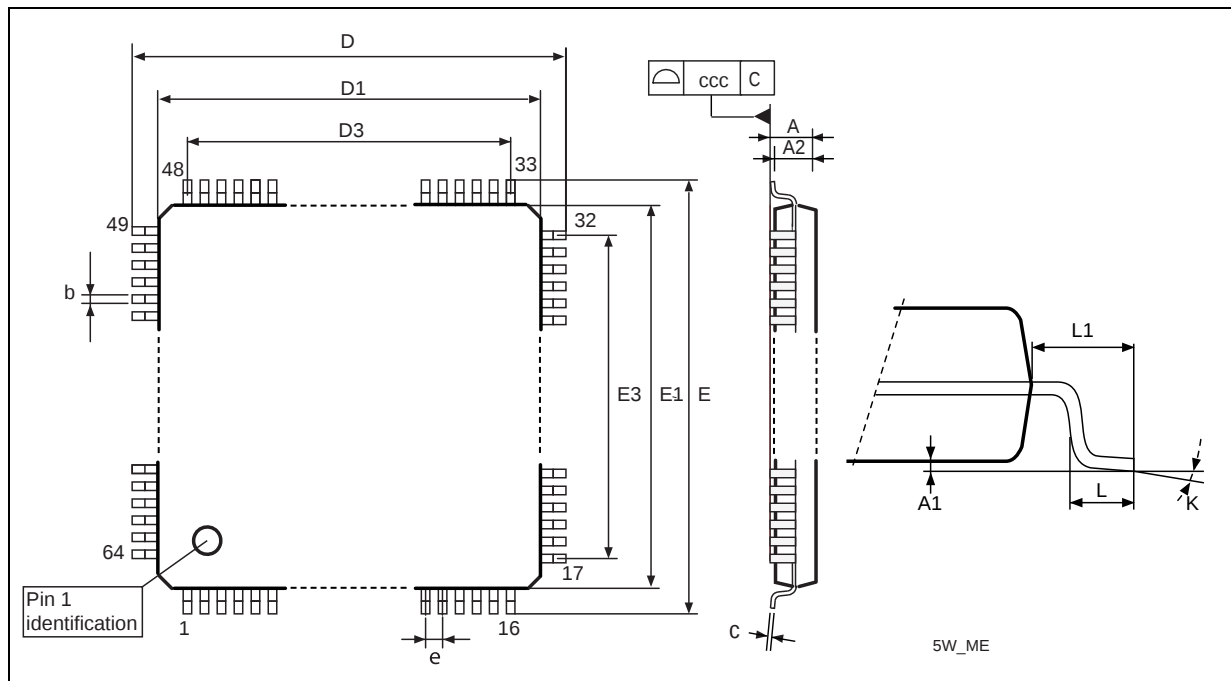
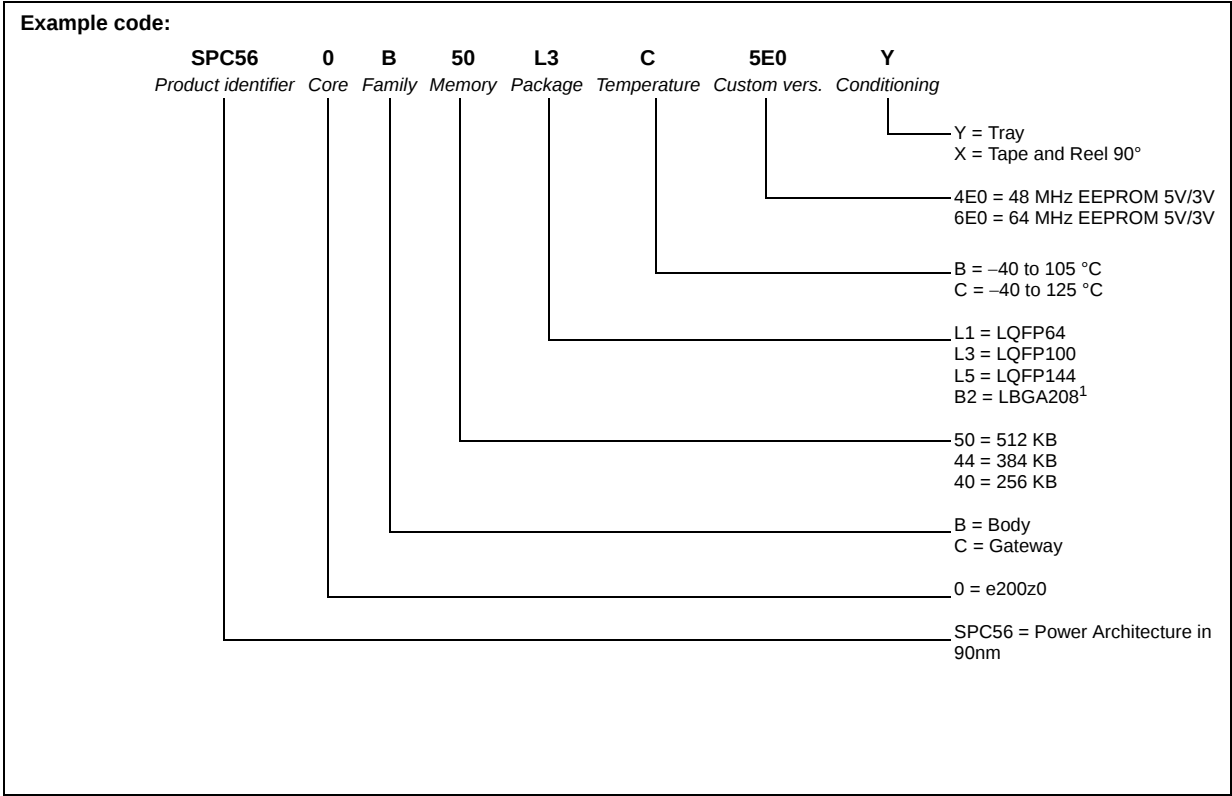


Table 50. LQFP64 mechanical data

Symbol	mm			inches ⁽¹⁾		
	Min	Typ	Max	Min	Typ	Max
A	—	—	1.6	—	—	0.063
A1	0.05	—	0.15	0.002	—	0.0059
A2	1.35	1.4	1.45	0.0531	0.0551	0.0571
b	0.17	0.22	0.27	0.0067	0.0087	0.0106
c	0.09	—	0.2	0.0035	—	0.0079
D	11.8	12	12.2	0.4646	0.4724	0.4803

5 Ordering information

Figure 38. Commercial product code structure



1. LBGA208 available only as development package for Nexus2+

Table 55. Document revision history (continued)

Date	Revision	Changes
06-Aug-2009	4	Updated "LBGA208 configuration" figure "Absolute maximum ratings" table: – V_{DD_ADC}, V_{IN}: changed min value for "relative to V_{DD}" condition – I_{CORELV}: added new row "Recommended operating conditions (5.0 V)" table: – T_A C-Grade Part, T_J C-Grade Part, T_A V-Grade Part, T_J V-Grade Part, T_A M-Grade Part, T_J M-Grade Part: added new rows – Changed capacitance value in footnote "Output pin transition times" table: – MEDIUM configuration: added condition for $PAD3V5V = 0$ Updated "Voltage regulator capacitance connection" "Voltage regulator electrical characteristics" table: – C_{DEC1}: changed min value – I_{MREG}: changed max value – I_{DD_BV}: added max value footnote "Low voltage monitor electrical characteristics" table: – $V_{LVDHV3H}$, $V_{LVDHV5H}$: changed max value – $V_{LVDHV3L}$, $V_{LVDHV5L}$: added max value Updated "Low voltage power domain electrical characteristics" table "Flash module life" table: – Retention: deleted min value footnote for "Blocks with 100000 P/E cycles" "Fast external crystal oscillator (4 to 16 MHz) electrical characteristics" table: – I_{FXOSC}: added typ value "Slow external crystal oscillator (32 kHz) electrical characteristics" table: – V_{SXOSC}: changed typ value – $T_{SXOSCSU}$: added max value footnote "FMPLL electrical characteristics" table – Δt_{LTJIT}: added max value Updated "LQFP100 package mechanical drawing"