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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	16
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 5.25V
Data Converters	A/D 2x14b; D/A 1x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	20-SSOP (0.209", 5.30mm Width)
Supplier Device Package	20-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c22213-24pvit

processor. The CPU utilizes an interrupt controller with 10 vectors, to simplify programming of real time embedded events. Program execution is timed and protected using the included Sleep and Watch Dog Timers (WDT).

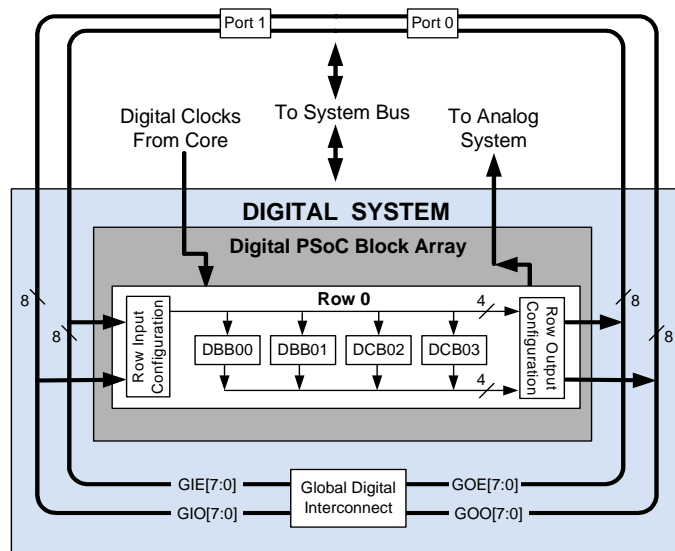
Memory encompasses 2 KB of Flash for program storage, 256 bytes of SRAM for data storage, and up to 2 KB of EEPROM emulated using the Flash. Program Flash utilizes four protection levels on blocks of 64 bytes, allowing customized software IP protection.

The PSoC device incorporates flexible internal clock generators, including a 24 MHz IMO (internal main oscillator) accurate to 2.5% over temperature and voltage. The 24 MHz IMO can also be doubled to 48 MHz for use by the digital system. A low power 32 kHz ILO (internal low speed oscillator) is provided for the Sleep timer and WDT. If crystal accuracy is desired, the ECO (32.768 kHz external crystal oscillator) is available for use as a Real Time Clock (RTC) and can optionally generate a crystal-accurate 24 MHz system clock using a PLL. The clocks, together with programmable clock dividers (as a System Resource), provide the flexibility to integrate almost any timing requirement into the PSoC device.

PSoC GPIOs provide connection to the CPU, digital and analog resources of the device. Each pin's drive mode may be selected from eight options, allowing great flexibility in external interfacing. Every pin also has the capability to generate a system interrupt on high level, low level, and change from last read.

The Digital System

The Digital System is composed of 4 digital PSoC blocks. Each block is an 8-bit resource that can be used alone or combined with other blocks to form 8, 16, 24, and 32-bit peripherals, which are called user module references.



Digital System Block Diagram

Digital peripheral configurations include those listed below.

- PWMs (8 to 32 bit)
- PWMs with Dead band (8 to 32 bit)
- Counters (8 to 32 bit)
- Timers (8 to 32 bit)
- UART 8-bit with selectable parity (up to 1)
- SPI master and slave (up to 1)
- I2C slave and master (1 available as a System Resource)
- Cyclical Redundancy Checker/Generator (8 to 32 bit)
- IrDA (up to 1)
- Pseudo Random Sequence Generators (8 to 32 bit)

The digital blocks can be connected to any GPIO through a series of global buses that can route any signal to any pin. The buses also allow for signal multiplexing and for performing logic operations. This configurability frees your designs from the constraints of a fixed peripheral controller.

Digital blocks are provided in rows of four, where the number of blocks varies by PSoC device family. This allows you the optimum choice of system resources for your application. Family resources are shown in the table titled “PSoC Device Characteristics” on page 3.

The Analog System

The Analog System is composed of 3 configurable blocks, each comprised of an opamp circuit allowing the creation of complex analog signal flows. Analog peripherals are very flexible and can be customized to support specific application requirements. Some of the more common PSoC analog functions (most available as user modules) are listed below.

- Analog-to-digital converters (one with 6- to 14-bit resolution, selectable as Incremental, Delta Sigma, and SAR)
- Filters (two pole band-pass, low-pass, and notch)
- Amplifiers (one with selectable gain to 48x)
- Comparators (one with 16 selectable thresholds)
- DACs (one with 6- to 9-bit resolution)
- Multiplying DACs (one with 6- to 9-bit resolution)
- High current output drivers (one with 30 mA drive as a Core Resource)
- 1.3V reference (as a System Resource)
- Many other topologies possible

Getting Started

The quickest path to understanding the PSoC silicon is by reading this data sheet and using the PSoC Designer Integrated Development Environment (IDE). This data sheet is an overview of the PSoC integrated circuit and presents specific pin, register, and electrical specifications. For in-depth information, along with detailed programming information, reference the *PSoC™ Mixed Signal Array Technical Reference Manual*.

For up-to-date Ordering, Packaging, and Electrical Specification information, reference the latest PSoC device data sheets on the web at <http://www.cypress.com/psoc>.

Development Kits

Development Kits are available from the following distributors: Digi-Key, Avnet, Arrow, and Future. The Cypress Online Store at <http://www.onfulfillment.com/cypressstore/> contains development kits, C compilers, and all accessories for PSoC development. Click on *PSoC (Programmable System-on-Chip)* to view a current list of available items.

Tele-Training

Free PSoC "Tele-training" is available for beginners and taught by a live marketing or application engineer over the phone. Five training classes are available to accelerate the learning curve including introduction, designing, debugging, advanced design, advanced analog, as well as application-specific classes covering topics like PSoC and the LIN bus. For days and times of the tele-training, see <http://www.cypress.com/support/training.cfm>.

Consultants

Certified PSoC Consultants offer everything from technical assistance to completed PSoC designs. To contact or become a PSoC Consultant, go to the following Cypress support web site: <http://www.cypress.com/support/cypros.cfm>.

Technical Support

PSoC application engineers take pride in fast and accurate response. They can be reached with a 4-hour guaranteed response at <http://www.cypress.com/support/login.cfm>.

Application Notes

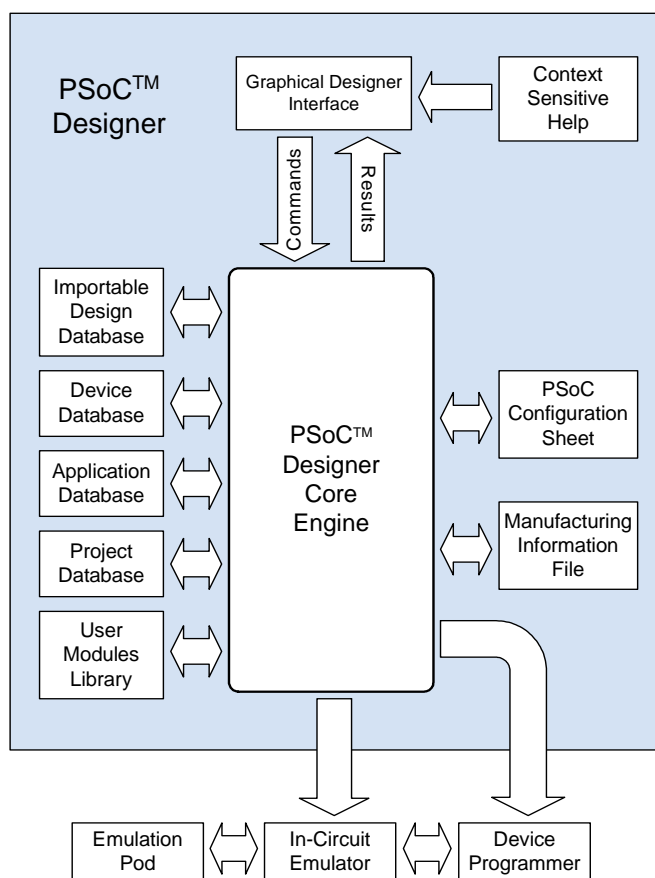
A long list of application notes will assist you in every aspect of your design effort. To locate the PSoC application notes, go to <http://www.cypress.com/design/results.cfm>.

Development Tools

The Cypress MicroSystems PSoC Designer is a Microsoft® Windows-based, integrated development environment for the Programmable System-on-Chip (PSoC) devices. The PSoC Designer IDE and application runs on Windows 98, Windows NT 4.0, Windows 2000, Windows Millennium (Me), or Windows XP. (Reference the PSoC Designer Functional Flow diagram below.)

PSoC Designer helps the customer to select an operating configuration for the PSoC, write application code that uses the PSoC, and debug the application. This system provides design database management by project, an integrated debugger with In-Circuit Emulator, in-system programming support, and the CYASM macro assembler for the CPUs.

PSoC Designer also supports a high-level C language compiler developed specifically for the devices in the family.



PSoC Designer Subsystems

User Modules and the PSoC Development Process

The development process for the PSoC device differs from that of a traditional fixed function microprocessor. The configurable analog and digital hardware blocks give the PSoC architecture a unique flexibility that pays dividends in managing specification change during development and by lowering inventory costs. These configurable resources, called PSoC Blocks, have the ability to implement a wide variety of user-selectable functions. Each block has several registers that determine its function and connectivity to other blocks, multiplexers, buses, and to the IO pins. Iterative development cycles permit you to adapt the hardware as well as the software. This substantially lowers the risk of having to select a different part to meet the final design requirements.

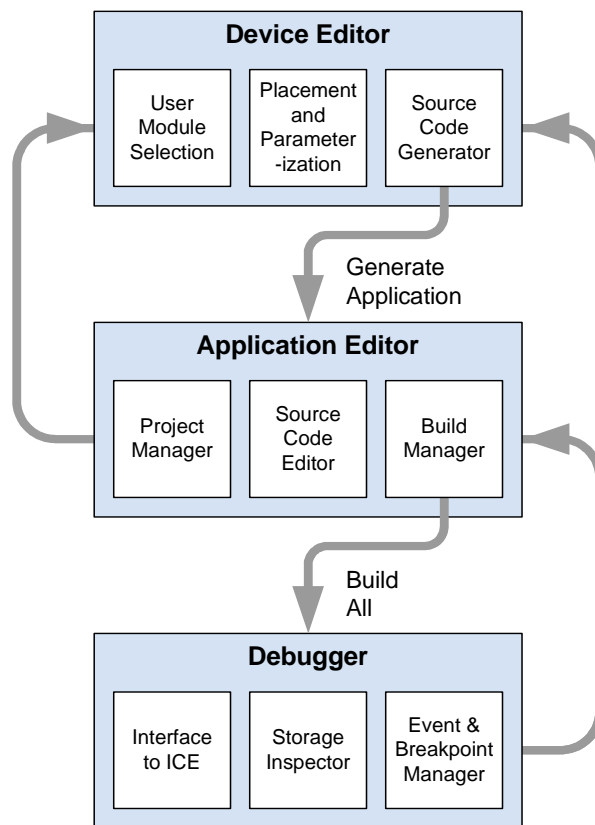
To speed the development process, the PSoC Designer Integrated Development Environment (IDE) provides a library of pre-built, pre-tested hardware peripheral functions, called “User Modules.” User modules make selecting and implementing peripheral devices simple, and come in analog, digital, and mixed signal varieties. The standard User Module library contains over 50 common peripherals such as ADCs, DACs Timers, Counters, UARTs, and other not-so common peripherals such as DTMF Generators and Bi-Quad analog filter sections.

Each user module establishes the basic register settings that implement the selected function. It also provides parameters that allow you to tailor its precise configuration to your particular application. For example, a Pulse Width Modulator User Module configures one or more digital PSoC blocks, one for each 8 bits of resolution. The user module parameters permit you to establish the pulse width and duty cycle. User modules also provide tested software to cut your development time. The user module application programming interface (API) provides high-level functions to control and respond to hardware events at run-time. The API also provides optional interrupt service routines that you can adapt as needed.

The API functions are documented in user module data sheets that are viewed directly in the PSoC Designer IDE. These data sheets explain the internal operation of the user module and provide performance specifications. Each data sheet describes the use of each user module parameter and documents the setting of each register controlled by the user module.

The development process starts when you open a new project and bring up the Device Editor, a pictorial environment (GUI) for configuring the hardware. You pick the user modules you need for your project and map them onto the PSoC blocks with point-and-click simplicity. Next, you build signal chains by interconnecting user modules to each other and the IO pins. At this stage, you also configure the clock source connections and enter parameter values directly or by selecting values from drop-down menus. When you are ready to test the hardware configuration or move on to developing code for the project, you perform the “Generate Application” step. This causes PSoC Designer to generate source code that automatically configures

the device to your specification and provides the high-level user module API functions.



User Modules and Development Process Flow Chart

The next step is to write your main program, and any sub-routines using PSoC Designer's Application Editor subsystem. The Application Editor includes a Project Manager that allows you to open the project source code files (including all generated code files) from a hierarchal view. The source code editor provides syntax coloring and advanced edit features for both C and assembly language. File search capabilities include simple string searches and recursive “grep-style” patterns. A single mouse click invokes the Build Manager. It employs a professional-strength “makefile” system to automatically analyze all file dependencies and run the compiler and assembler as necessary. Project-level options control optimization strategies used by the compiler and linker. Syntax errors are displayed in a console window. Double clicking the error message takes you directly to the offending line of source code. When all is correct, the linker builds a ROM file image suitable for programming.

The last step in the development process takes place inside the PSoC Designer's Debugger subsystem. The Debugger downloads the ROM image to the In-Circuit Emulator (ICE) where it runs at full speed. Debugger capabilities rival those of systems costing many times more. In addition to traditional single-step, run-to-breakpoint and watch-variable features, the Debugger provides a large trace buffer and allows you define complex breakpoint events that include monitoring address and data bus values, memory locations and external signals.

Document Conventions

Acronyms Used

The following table lists the acronyms that are used in this document.

Acronym	Description
AC	alternating current
ADC	analog-to-digital converter
API	application programming interface
CPU	central processing unit
CT	continuous time
DAC	digital-to-analog converter
DC	direct current
EEPROM	electrically erasable programmable read-only memory
FSR	full scale range
GPIO	general purpose IO
IO	input/output
IPOR	imprecise power on reset
LSb	least-significant bit
LVD	low voltage detect
MSb	most-significant bit
PC	program counter
POR	power on reset
PPOR	precision power on reset
PSoC™	Programmable System-on-Chip
PWM	pulse width modulator
RAM	random access memory
ROM	read only memory
SC	switched capacitor
SMP	switch mode pump

Units of Measure

A units of measure table is located in the Electrical Specifications section. [Table 3-1 on page 13](#) lists all the abbreviations used to measure the PSoC devices.

Numeric Naming

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase 'h' (for example, '14h' or '3Ah'). Hexadecimal numbers may also be represented by a '0x' prefix, the C coding convention. Binary numbers have an appended lowercase 'b' (e.g., '01010100b' or '01000011b'). Numbers not indicated by an 'h' or 'b' are decimal.

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For an in depth discussion and more information on your PSoC device, obtain the *PSoC Mixed Signal Array Technical Reference Manual*. This document encompasses and is organized into the following chapters and sections.

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1. Pin Information



This chapter describes, lists, and illustrates the CY8C22x13 PSoC device pins and pinout configurations.

1.1 Pinouts

The CY8C22x13 PSoC device is available in a variety of packages which are listed and illustrated in the following tables. Every port pin (labeled with a "P") is capable of Digital IO. However, Vss, Vdd, SMP, and XRES are not capable of Digital IO.

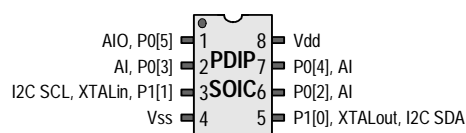
1.1.1 8-Pin Part Pinout

Table 1-1. 8-Pin Part Pinout (PDIP, SOIC)

Pin No.	Type		Pin Name	Description
	Digital	Analog		
1	IO	IO	P0[5]	Analog column mux input and column output.
2	IO	I	P0[3]	Analog column mux input.
3	IO		P1[1]	Crystal Input (XTALin), I2C Serial Clock (SCL)
4	Power		Vss	Ground connection.
5	IO		P1[0]	Crystal Output (XTALout), I2C Serial Data (SDA)
6	IO	I	P0[2]	Analog column mux input.
7	IO	I	P0[4]	Analog column mux input.
8	Power		Vdd	Supply voltage.

LEGEND: A = Analog, I = Input, and O = Output.

CY8C22113 8-Pin PSoC Device



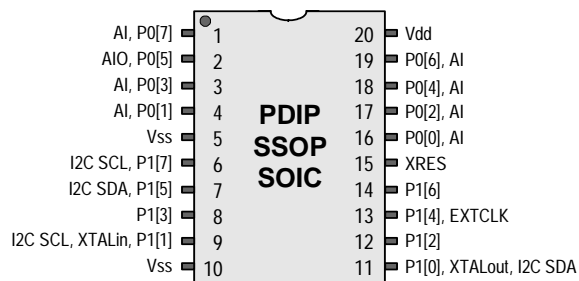
1.1.2 20-Pin Part Pinout

Table 1-2. 20-Pin Part Pinout (PDIP, SSOP, SOIC)

Pin No.	Type		Pin Name	Description
	Digital	Analog		
1	IO	I	P0[7]	Analog column mux input.
2	IO	IO	P0[5]	Analog column mux input and column output.
3	IO	I	P0[3]	Analog column mux input.
4	IO	I	P0[1]	Analog column mux input.
5	Power		Vss	Ground connection.
6	IO		P1[7]	I2C Serial Clock (SCL)
7	IO		P1[5]	I2C Serial Data (SDA)
8	IO		P1[3]	
9	IO		P1[1]	Crystal Input (XTALin), I2C Serial Clock (SCL)
10	Power		Vss	Ground connection.
11	IO		P1[0]	Crystal Output (XTALout), I2C Serial Data (SDA)
12	IO		P1[2]	
13	IO		P1[4]	Optional External Clock Input (EXTCLK)
14	IO		P1[6]	
15	Input		XRES	Active high external reset with internal pull down.
16	IO	I	P0[0]	Analog column mux input.
17	IO	I	P0[2]	Analog column mux input.
18	IO	I	P0[4]	Analog column mux input.
19	IO	I	P0[6]	Analog column mux input.
20	Power		Vdd	Supply voltage.

LEGEND: A = Analog, I = Input, and O = Output.

CY8C22213 20-Pin PSoC Device



1.1.3 32-Pin Part Pinout

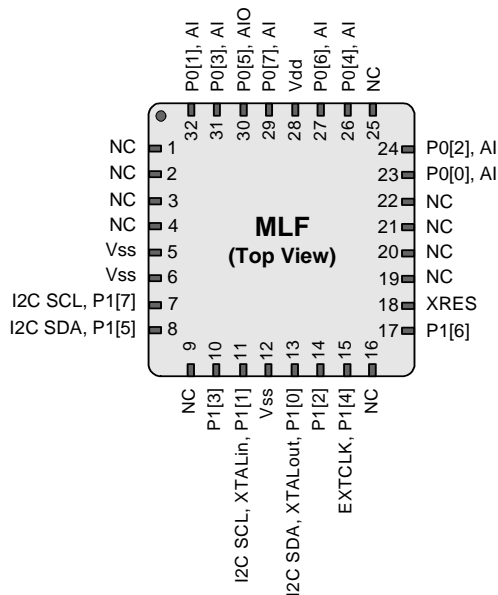
Table 1-3. 32-Pin Part Pinout (MLF*)

Pin No.	Type		Pin Name	Description
	Digital	Analog		
1			NC	No connection. Do not use.
2			NC	No connection. Do not use.
3			NC	No connection. Do not use.
4			NC	No connection. Do not use.
5	Power		Vss	Ground connection.
6	Power		Vss	Ground connection.
7	IO		P1[7]	I2C Serial Clock (SCL)
8	IO		P1[5]	I2C Serial Data (SDA)
9			NC	No connection. Do not use.
10	IO		P1[3]	
11	IO		P1[1]	Crystal Input (XTALin), I2C Serial Clock (SCL)
12	Power		Vss	Ground connection.
13	IO		P1[0]	Crystal Output (XTALout), I2C Serial Data (SDA)
14	IO		P1[2]	
15	IO		P1[4]	Optional External Clock Input (EXTCLK)
16			NC	No connection. Do not use.
17	IO		P1[6]	
18	Input		XRES	Active high external reset with internal pull down.
19			NC	No connection. Do not use.
20			NC	No connection. Do not use.
21			NC	No connection. Do not use.
22			NC	No connection. Do not use.
23	IO	I	P0[0]	Analog column mux input.
24	IO	I	P0[2]	Analog column mux input.
25			NC	No connection. Do not use.
26	IO	I	P0[4]	Analog column mux input.
27	IO	I	P0[6]	Analog column mux input.
28	Power		Vdd	Supply voltage.
29	IO	I	P0[7]	Analog column mux input.
30	IO	IO	P0[5]	Analog column mux input and column output.
31	IO	I	P0[3]	Analog column mux input.
32	IO	I	P0[1]	Analog column mux input.

LEGEND: A = Analog, I = Input, and O = Output.

* The MLF package has a center pad that must be connected to the same ground as the Vss pin.

CY8C22213 PSoC Device



Register Map Bank 1 Table: Configuration Space

Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access	Name	Addr (1,Hex)	Access
PRT0DM0	00	RW		40			80			C0	
PRT0DM1	01	RW		41			81			C1	
PRT0IC0	02	RW		42			82			C2	
PRT0IC1	03	RW		43			83			C3	
PRT1DM0	04	RW		44		ASD11CR0	84	RW		C4	
PRT1DM1	05	RW		45		ASD11CR1	85	RW		C5	
PRT1IC0	06	RW		46		ASD11CR2	86	RW		C6	
PRT1IC1	07	RW		47		ASD11CR3	87	RW		C7	
	08			48			88			C8	
	09			49			89			C9	
	0A			4A			8A			CA	
	0B			4B			8B			CB	
	0C			4C			8C			CC	
	0D			4D			8D			CD	
	0E			4E			8E			CE	
	0F			4F			8F			CF	
	10			50			90		GDI_O_IN	D0	RW
	11			51			91		GDI_E_IN	D1	RW
	12			52			92		GDI_O_OU	D2	RW
	13			53			93		GDI_E_OU	D3	RW
	14			54		ASC21CR0	94	RW		D4	
	15			55		ASC21CR1	95	RW		D5	
	16			56		ASC21CR2	96	RW		D6	
	17			57		ASC21CR3	97	RW		D7	
	18			58			98			D8	
	19			59			99			D9	
	1A			5A			9A			DA	
	1B			5B			9B			DB	
	1C			5C			9C			DC	
	1D			5D			9D		OSC_GO_EN	DD	RW
	1E			5E			9E		OSC_CR4	DE	RW
	1F			5F			9F		OSC_CR3	DF	RW
DBB00FN	20	RW	CLK_CR0	60	RW		A0		OSC_CR0	E0	RW
DBB00IN	21	RW	CLK_CR1	61	RW		A1		OSC_CR1	E1	RW
DBB00OU	22	RW	ABF_CR0	62	RW		A2		OSC_CR2	E2	RW
	23			63			A3		VLT_CR	E3	RW
DBB01FN	24	RW		64			A4		VLT_CMP	E4	R
DBB01IN	25	RW		65			A5			E5	
DBB01OU	26	RW	AMD_CR1	66	RW		A6			E6	
	27		ALT_CR0	67	RW		A7			E7	
DCB02FN	28	RW		68			A8		IMO_TR	E8	W
DCB02IN	29	RW		69			A9		ILO_TR	E9	W
DCB02OU	2A	RW		6A			AA		BDG_TR	EA	RW
	2B			6B			AB		ECO_TR	EB	W
DCB03FN	2C	RW		6C			AC			EC	
DCB03IN	2D	RW		6D			AD			ED	
DCB03OU	2E	RW		6E			AE			EE	
	2F			6F			AF			EF	
	30			70		RDI0RI	B0	RW		F0	
	31			71		RDI0SYN	B1	RW		F1	
	32			72		RDI0IS	B2	RW		F2	
	33			73		RDI0LT0	B3	RW		F3	
	34		ACB01CR3	74	RW	RDI0LT1	B4	RW		F4	
	35		ACB01CR0	75	RW	RDI0RO0	B5	RW		F5	
	36		ACB01CR1	76	RW	RDI0RO1	B6	RW		F6	
	37		ACB01CR2	77	RW		B7		CPU_F	F7	RL
	38			78			B8			F8	
	39			79			B9			F9	
	3A			7A			BA			FA	
	3B			7B			BB			FB	
	3C			7C			BC			FC	
	3D			7D			BD			FD	
	3E			7E			BE		CPU_SCR1	FE	#
	3F			7F			BF		CPU_SCR0	FF	#

Blank fields are Reserved and should not be accessed. # Access is bit specific.

3.1 Absolute Maximum Ratings

Table 3-2. Absolute Maximum Ratings

Symbol	Description	Min	Typ	Max	Units	Notes
T_{STG}	Storage Temperature	-55	–	+100	°C	Higher storage temperatures will reduce data retention time.
T_A	Ambient Temperature with Power Applied	-40	–	+85	°C	
Vdd	Supply Voltage on Vdd Relative to Vss	-0.5	–	+6.0	V	
V_{IO}	DC Input Voltage	Vss - 0.5	–	Vdd + 0.5	V	
–	DC Voltage Applied to Tri-state	Vss - 0.5	–	Vdd + 0.5	V	
I_{MIO}	Maximum Current into any Port Pin	-25	–	+50	mA	
I_{MAIO}	Maximum Current into any Port Pin Configured as Analog Driver	-50	–	+50	mA	
–	Static Discharge Voltage	2000	–	–	V	
–	Latch-up Current	–	–	200	mA	

3.2 Operating Temperature

Table 3-3. Operating Temperature

Symbol	Description	Min	Typ	Max	Units	Notes
T_A	Ambient Temperature	-40	–	+85	°C	
T_J	Junction Temperature	-40	–	+100	°C	The temperature rise from ambient to junction is package specific. See “Thermal Impedances” on page 34 . The user must limit the power consumption to comply with this requirement.

3.3.3 DC Operational Amplifier Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

The Operational Amplifier is a component of both the Analog Continuous Time PSoC blocks and the Analog Switched Cap PSoC blocks. The guaranteed specifications are measured in the Analog Continuous Time PSoC block. Typical parameters apply to 5V at 25°C and are for design guidance only.

Table 3-6. 5V DC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{OSOA}	Input Offset Voltage (absolute value) Low Power	–	1.6	10	mV	
	Input Offset Voltage (absolute value) Mid Power	–	1.3	8	mV	
	Input Offset Voltage (absolute value) High Power	–	1.2	7.5	mV	
TCV_{OSOA}	Average Input Offset Voltage Drift	–	7.0	35.0	$\mu\text{V}/^{\circ}\text{C}$	
I_{EBOA}	Input Leakage Current (Port 0 Analog Pins)	–	20	–	pA	Gross tested to 1 μA .
C_{INOA}	Input Capacitance (Port 0 Analog Pins)	–	4.5	9.5	pF	Package and pin dependent. Temp = 25°C .
V_{CMOA}	Common Mode Voltage Range	0.0	–	V_{DD}	V	The common-mode input voltage range is measured through an analog output buffer. The specification includes the limitations imposed by the characteristics of the analog output buffer.
	Common Mode Voltage Range (high power or high opamp bias)	0.5	–	$V_{\text{DD}} - 0.5$	V	
G_{OLOA}	Open Loop Gain	–	–	–	dB	Specification is applicable at high power. For all other bias modes (except high power, high opamp bias), minimum is 60 dB.
	Power = Low	60	–	–	–	
	Power = Medium	60	–	–	–	
V_{OHIGHOA}	High Output Voltage Swing (worst case internal load)	–	–	–	–	
	Power = Low	$V_{\text{DD}} - 0.2$	–	–	V	
	Power = Medium	$V_{\text{DD}} - 0.2$	–	–	V	
V_{OLOWA}	Low Output Voltage Swing (worst case internal load)	–	–	–	–	
	Power = Low	–	–	0.2	V	
	Power = Medium	–	–	0.2	V	
I_{SOA}	Power = High	–	–	0.5	V	
	Supply Current (including associated AGND buffer)	–	–	–	–	
	Power = Low	–	150	200	μA	
	Power = Low, Opamp Bias = High	–	300	400	μA	
	Power = Medium	–	600	800	μA	
	Power = Medium, Opamp Bias = High	–	1200	1600	μA	
PSRR_{OA}	Power = High	–	2400	3200	μA	
	Power = High, Opamp Bias = High	–	4600	6400	μA	
PSRR_{OA}	Supply Voltage Rejection Ratio	60	–	–	dB	

3.3.7 DC POR and LVD Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Note The bits PORLEV and VM in the table below refer to bits in the VLT_CR register. See the *PSoC Mixed Signal Array Technical Reference Manual* for more information on the VLT_CR register.

Table 3-13. DC POR and LVD Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
V_{PPOR0R}	Vdd Value for PPOR Trip (positive ramp) PORLEV[1:0] = 00b		2.908		V	
V_{PPOR1R}	PORLEV[1:0] = 01b	—	4.394	—	V	
V_{PPOR2R}	PORLEV[1:0] = 10b		4.548		V	
V_{PPOR0}	Vdd Value for PPOR Trip (negative ramp) PORLEV[1:0] = 00b		2.816		V	
V_{PPOR1}	PORLEV[1:0] = 01b	—	4.394	—	V	
V_{PPOR2}	PORLEV[1:0] = 10b		4.548		V	
V_{PH0}	PPOR Hysteresis PORLEV[1:0] = 00b	—	92	—	mV	
V_{PH1}	PORLEV[1:0] = 01b	—	0	—	mV	
V_{PH2}	PORLEV[1:0] = 10b	—	0	—	mV	
V_{LVD0}	Vdd Value for LVD Trip VM[2:0] = 000b	2.863	2.921	2.979 ^a	V	
V_{LVD1}	VM[2:0] = 001b	2.963	3.023	3.083	V	
V_{LVD2}	VM[2:0] = 010b	3.070	3.133	3.196	V	
V_{LVD3}	VM[2:0] = 011b	3.920	4.00	4.080	V	
V_{LVD4}	VM[2:0] = 100b	4.393	4.483	4.573	V	
V_{LVD5}	VM[2:0] = 101b	4.550	4.643	4.736 ^b	V	
V_{LVD6}	VM[2:0] = 110b	4.632	4.727	4.822	V	
V_{LVD7}	VM[2:0] = 111b	4.718	4.814	4.910	V	

a. Always greater than 50 mV above PPOR (PORLEV = 00) for falling supply.

b. Always greater than 50 mV above PPOR (PORLEV = 10) for falling supply.

3.3.8 DC Programming Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-14. DC Programming Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
I_{DDP}	Supply Current During Programming or Verify	–	5	25	mA	
V_{ILP}	Input Low Voltage During Programming or Verify	–	–	0.8	V	
V_{IHP}	Input High Voltage During Programming or Verify	2.2	–	–	V	
I_{ILP}	Input Current when Applying V_{ilp} to P1[0] or P1[1] During Programming or Verify	–	–	0.2	mA	Driving internal pull-down resistor.
I_{IHP}	Input Current when Applying V_{ihp} to P1[0] or P1[1] During Programming or Verify	–	–	1.5	mA	Driving internal pull-down resistor.
V_{OLV}	Output Low Voltage During Programming or Verify	–	–	$V_{SS} + 0.75$	V	
V_{OHV}	Output High Voltage During Programming or Verify	$V_{DD} - 1.0$	–	V_{DD}	V	
Flash _{ENPB}	Flash Endurance (per block)	50,000	–	–	–	Erase/write cycles per block.
Flash _{ENT}	Flash Endurance (total) ^a	1,800,000	–	–	–	Erase/write cycles.
Flash _{DR}	Flash Data Retention	10	–	–	Years	

- a. A maximum of 36 x 50,000 block endurance cycles is allowed. This may be balanced between operations on 36x1 blocks of 50,000 maximum cycles each, 36x2 blocks of 25,000 maximum cycles each, or 36x4 blocks of 12,500 maximum cycles each (and so forth to limit the total number of cycles to 36x50,000 and that no single block ever sees more than 50,000 cycles).

For the full industrial range, the user must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing. Refer to the Flash APIs Application Note AN2015 at <http://www.cypress.com> under Application Notes for more information.

3.4 AC Electrical Characteristics

3.4.1 AC Chip-Level Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-15. AC Chip-Level Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F _{IMO}	Internal Main Oscillator Frequency	23.4	24	24.6 ^a	MHz	Trimmed. Utilizing factory trim values.
F _{CPU1}	CPU Frequency (5V Nominal)	0.93	24	24.6 ^{a,b}	MHz	
F _{CPU2}	CPU Frequency (3.3V Nominal)	0.93	12	12.3 ^{b,c}	MHz	
F _{48M}	Digital PSoC Block Frequency	0	48	49.2 ^{a,b,d}	MHz	Refer to the AC Digital Block Specifications below.
F _{24M}	Digital PSoC Block Frequency	0	24	24.6 ^{b,e,d}	MHz	
F _{32K1}	Internal Low Speed Oscillator Frequency	15	32	64	kHz	
F _{32K2}	External Crystal Oscillator	—	32.768	—	kHz	Accuracy is capacitor and crystal dependent. 50% duty cycle.
F _{PLL}	PLL Frequency	—	23.986	—	MHz	Is a multiple (x732) of crystal frequency.
Jitter24M2	24 MHz Period Jitter (PLL)	—	—	600	ps	
T _{PLLSLEW}	PLL Lock Time	0.5	—	10	ms	
T _{PLLSLEWS-LOW}	PLL Lock Time for Low Gain Setting	0.5	—	50	ms	
T _{OS}	External Crystal Oscillator Startup to 1%	—	1700	2620	ms	
T _{OSACC}	External Crystal Oscillator Startup to 100 ppm	—	2800	3800 ^f	ms	
Jitter32k	32 kHz Period Jitter	—	100	—	ns	
T _{XRST}	External Reset Pulse Width	10	—	—	μs	
DC24M	24 MHz Duty Cycle	40	50	60	%	
Step24M	24 MHz Trim Step Size	—	50	—	kHz	
F _{out48M}	48 MHz Output Frequency	46.8	48.0	49.2 ^{a,c}	MHz	Trimmed. Utilizing factory trim values.
Jitter24M1	24 MHz Period Jitter (IMO)	—	600	—	ps	
F _{MAX}	Maximum frequency of signal on row input or row output.	—	—	12.3	MHz	
T _{RAMP}	Supply Ramp Time	0	—	—	μs	

a. $4.75\text{V} < V_{DD} < 5.25\text{V}$.

b. Accuracy derived from Internal Main Oscillator with appropriate trim for Vdd range.

c. $3.0\text{V} < V_{DD} < 3.6\text{V}$. See Application Note AN2012 "Adjusting PSoC Microcontroller Trims for Dual Voltage-Range Operation" for information on trimming for operation at 3.3V.

d. See the individual user module data sheets for information on maximum frequencies for user modules.

e. $3.0\text{V} < 5.25\text{V}$.

f. The crystal oscillator frequency is within 100 ppm of its final value by the end of the T_{OSACC} period. Correct operation assumes a properly loaded 1 uW maximum drive level 32.768 kHz crystal. $3.0\text{V} \leq V_{DD} \leq 5.5\text{V}$, $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$.

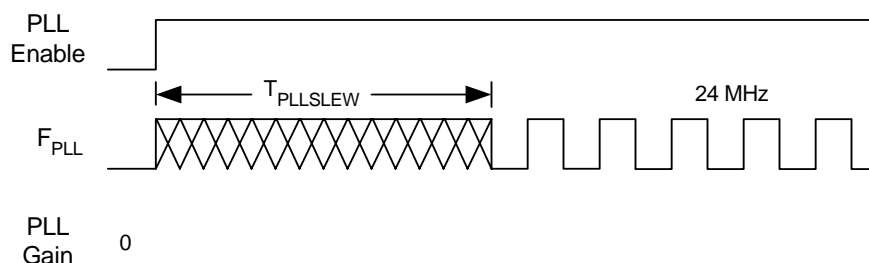


Figure 3-2. PLL Lock Timing Diagram

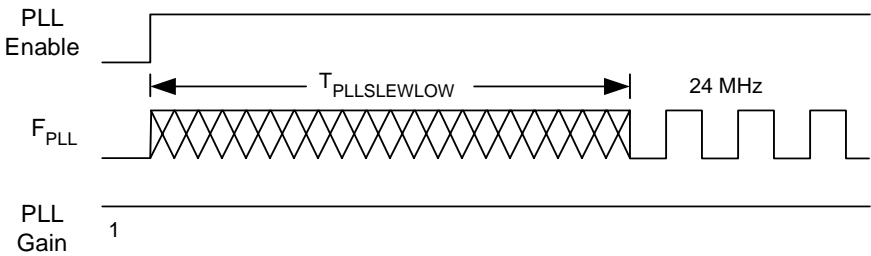


Figure 3-3. PLL Lock for Low Gain Setting Timing Diagram

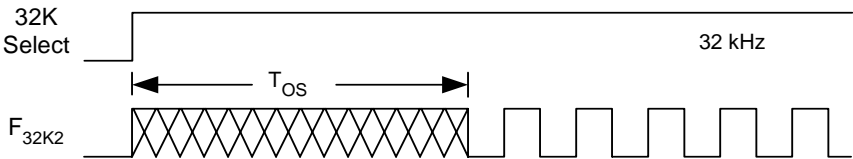


Figure 3-4. External Crystal Oscillator Startup Timing Diagram



Figure 3-5. 24 MHz Period Jitter (IMO) Timing Diagram



Figure 3-6. 32 kHz Period Jitter (ECO) Timing Diagram

3.4.3 AC Operational Amplifier Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Note Settling times, slew rates, and gain bandwidth are based on the Analog Continuous Time PSoC block.

Table 3-17. 5V AC Operational Amplifier Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{ROA}	Rising Settling Time from 80% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)					Specification maximums for low power and high opamp bias, medium power, and medium power and high opamp bias levels are between low and high power levels.
	Power = Low	—	—	3.9	μs	
	Power = Low, Opamp Bias = High	—	—		μs	
	Power = Medium	—	—		μs	
	Power = Medium, Opamp Bias = High	—	—	0.72	μs	
	Power = High	—	—		μs	
	Power = High, Opamp Bias = High	—	—	0.62	μs	
T_{SOA}	Falling Settling Time from 20% of ΔV to 0.1% of ΔV (10 pF load, Unity Gain)					Specification maximums for low power and high opamp bias, medium power, and medium power and high opamp bias levels are between low and high power levels.
	Power = Low	—	—	5.9	μs	
	Power = Low, Opamp Bias = High	—	—		μs	
	Power = Medium	—	—		μs	
	Power = Medium, Opamp Bias = High	—	—	0.92	μs	
	Power = High	—	—		μs	
	Power = High, Opamp Bias = High	—	—	0.72	μs	
SR_{ROA}	Rising Slew Rate (20% to 80%)(10 pF load, Unity Gain)					Specification minimums for low power and high opamp bias, medium power, and medium power and high opamp bias levels are between low and high power levels.
	Power = Low	0.15	—		V/ μs	
	Power = Low, Opamp Bias = High		—		V/ μs	
	Power = Medium		—		V/ μs	
	Power = Medium, Opamp Bias = High	1.7	—		V/ μs	
	Power = High		—		V/ μs	
	Power = High, Opamp Bias = High	6.5	—		V/ μs	
SR_{FOA}	Falling Slew Rate (20% to 80%)(10 pF load, Unity Gain)					Specification minimums for low power and high opamp bias, medium power, and medium power and high opamp bias levels are between low and high power levels.
	Power = Low	0.01	—		V/ μs	
	Power = Low, Opamp Bias = High		—		V/ μs	
	Power = Medium		—		V/ μs	
	Power = Medium, Opamp Bias = High	0.5	—		V/ μs	
	Power = High		—		V/ μs	
	Power = High, Opamp Bias = High	4.0	—		V/ μs	
BW_{OA}	Gain Bandwidth Product					Specification minimums for low power and high opamp bias, medium power, and medium power and high opamp bias levels are between low and high power levels.
	Power = Low	0.75	—		MHz	
	Power = Low, Opamp Bias = High		—		MHz	
	Power = Medium		—		MHz	
	Power = Medium, Opamp Bias = High	3.1	—		MHz	
	Power = High		—		MHz	
	Power = High, Opamp Bias = High	5.4	—		MHz	
E_{NOA}	Noise at 1 kHz (Power = Medium, Opamp Bias = High)	—	200	—	nV/rt-Hz	

3.4.5 AC Analog Output Buffer Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-20. 5V AC Analog Output Buffer Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{ROB}	Rising Settling Time to 0.1%, 1V Step, 100pF Load					
	Power = Low	–	–	2.5	μs	
	Power = High	–	–	2.5	μs	
T_{SOB}	Falling Settling Time to 0.1%, 1V Step, 100pF Load					
	Power = Low	–	–	2.2	μs	
	Power = High	–	–	2.2	μs	
SR_{ROB}	Rising Slew Rate (20% to 80%), 1V Step, 100pF Load					
	Power = Low	0.65	–	–	V/ μs	
	Power = High	0.65	–	–	V/ μs	
SR_{FOB}	Falling Slew Rate (80% to 20%), 1V Step, 100pF Load					
	Power = Low	0.65	–	–	V/ μs	
	Power = High	0.65	–	–	V/ μs	
BW_{OB}	Small Signal Bandwidth, 20mV_{pp} , 3dB BW, 100pF Load					
	Power = Low	0.8	–	–	MHz	
	Power = High	0.8	–	–	MHz	
BW_{OB}	Large Signal Bandwidth, 1V_{pp} , 3dB BW, 100pF Load					
	Power = Low	300	–	–	kHz	
	Power = High	300	–	–	kHz	

Table 3-21. 3.3V AC Analog Output Buffer Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T_{ROB}	Rising Settling Time to 0.1%, 1V Step, 100pF Load					
	Power = Low	–	–	3.8	μs	
	Power = High	–	–	3.8	μs	
T_{SOB}	Falling Settling Time to 0.1%, 1V Step, 100pF Load					
	Power = Low	–	–	2.6	μs	
	Power = High	–	–	2.6	μs	
SR_{ROB}	Rising Slew Rate (20% to 80%), 1V Step, 100pF Load					
	Power = Low	0.5	–	–	V/ μs	
	Power = High	0.5	–	–	V/ μs	
SR_{FOB}	Falling Slew Rate (80% to 20%), 1V Step, 100pF Load					
	Power = Low	0.5	–	–	V/ μs	
	Power = High	0.5	–	–	V/ μs	
BW_{OB}	Small Signal Bandwidth, 20mV_{pp} , 3dB BW, 100pF Load					
	Power = Low	0.7	–	–	MHz	
	Power = High	0.7	–	–	MHz	
BW_{OB}	Large Signal Bandwidth, 1V_{pp} , 3dB BW, 100pF Load					
	Power = Low	200	–	–	kHz	
	Power = High	200	–	–	kHz	

3.4.6 AC External Clock Specifications

The following tables list guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-22. 5V AC External Clock Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F _{OSCEXT}	Frequency	0	–	24.24	MHz	
–	High Period	20.6	–	–	ns	
–	Low Period	20.6	–	–	ns	
–	Power Up IMO to Switch	150	–	–	μs	

Table 3-23. 3.3V AC External Clock Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
F _{OSCEXT}	Frequency with CPU Clock divide by 1 ^a	0	–	12.12	MHz	
F _{OSCEXT}	Frequency with CPU Clock divide by 2 or greater ^b	0	–	24.24	MHz	
–	High Period with CPU Clock divide by 1	41.7	–	–	ns	
–	Low Period with CPU Clock divide by 1	41.7	–	–	ns	
–	Power Up IMO to Switch	150	–	–	μs	

a. Maximum CPU frequency is 12 MHz at 3.3V. With the CPU clock divider set to 1, the external clock must adhere to the maximum frequency and duty cycle requirements.

b. If the frequency of the external clock is greater than 12 MHz, the CPU clock divider must be set to 2 or greater. In this case, the CPU clock divider will ensure that the fifty per cent duty cycle requirement is met.

3.4.7 AC Programming Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-24. AC Programming Specifications

Symbol	Description	Min	Typ	Max	Units	Notes
T _{RSCLK}	Rise Time of SCLK	1	–	20	ns	
T _{FSCLK}	Fall Time of SCLK	1	–	20	ns	
T _{SSCLK}	Data Set up Time to Falling Edge of SCLK	40	–	–	ns	
T _{HSCLK}	Data Hold Time from Falling Edge of SCLK	40	–	–	ns	
F _{SCLK}	Frequency of SCLK	0	–	8	MHz	
T _{ERASEB}	Flash Erase Time (Block)	–	15	–	ms	
T _{WRITE}	Flash Block Write Time	–	30	–	ms	
T _{DSCLK}	Data Out Delay from Falling Edge of SCLK	–	–	45	ns	

3.4.8 AC I²C Specifications

The following table lists guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75V to 5.25V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, or 3.0V to 3.6V and $-40^{\circ}\text{C} \leq T_A \leq 85^{\circ}\text{C}$, respectively. Typical parameters apply to 5V and 3.3V at 25°C and are for design guidance only or unless otherwise specified.

Table 3-25. AC Characteristics of the I²C SDA and SCL Pins

Symbol	Description	Standard Mode		Fast Mode		Units	Notes
		Min	Max	Min	Max		
$F_{\text{SCL}2\text{C}}$	SCL Clock Frequency	0	100	0	400	kHz	
$T_{\text{HDSTA}2\text{C}}$	Hold Time (repeated) START Condition. After this period, the first clock pulse is generated.	4.0	—	0.6	—	μs	
$T_{\text{LOW}2\text{C}}$	LOW Period of the SCL Clock	4.7	—	1.3	—	μs	
$T_{\text{HIGH}2\text{C}}$	HIGH Period of the SCL Clock	4.0	—	0.6	—	μs	
$T_{\text{SUSTA}2\text{C}}$	Set-up Time for a Repeated START Condition	4.7	—	0.6	—	μs	
$T_{\text{HDDAT}2\text{C}}$	Data Hold Time	0	—	0	—	μs	
$T_{\text{SUDAT}2\text{C}}$	Data Set-up Time	250	—	100 ^a	—	ns	
$T_{\text{SUSTOI}2\text{C}}$	Set-up Time for STOP Condition	4.0	—	0.6	—	μs	
$T_{\text{BUF}2\text{C}}$	Bus Free Time Between a STOP and START Condition	4.7	—	1.3	—	μs	
$T_{\text{SPI}2\text{C}}$	Pulse Width of spikes are suppressed by the input filter.	—	—	0	50	ns	

- a. A Fast-Mode I²C-bus device can be used in a Standard-Mode I²C-bus system, but the requirement $t_{\text{SU, DAT}} \geq 250$ ns must then be met. This will automatically be the case if the device does not stretch the LOW period of the SCL signal. If such device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line $t_{\text{rmax}} + t_{\text{SU, DAT}} = 1000 + 250 = 1250$ ns (according to the Standard-Mode I²C-bus specification) before the SCL line is released.

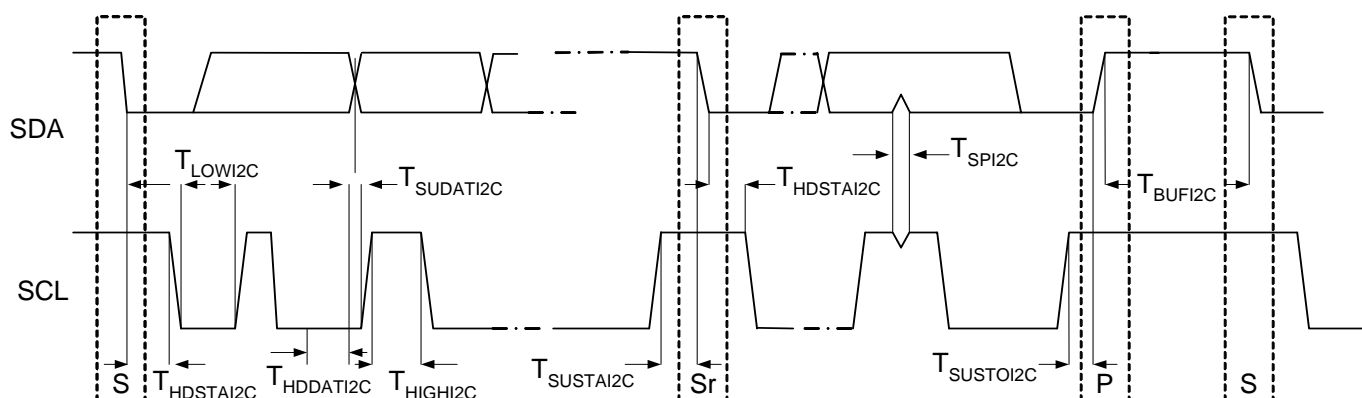


Figure 3-8. Definition for Timing for Fast/Standard Mode on the I²C Bus

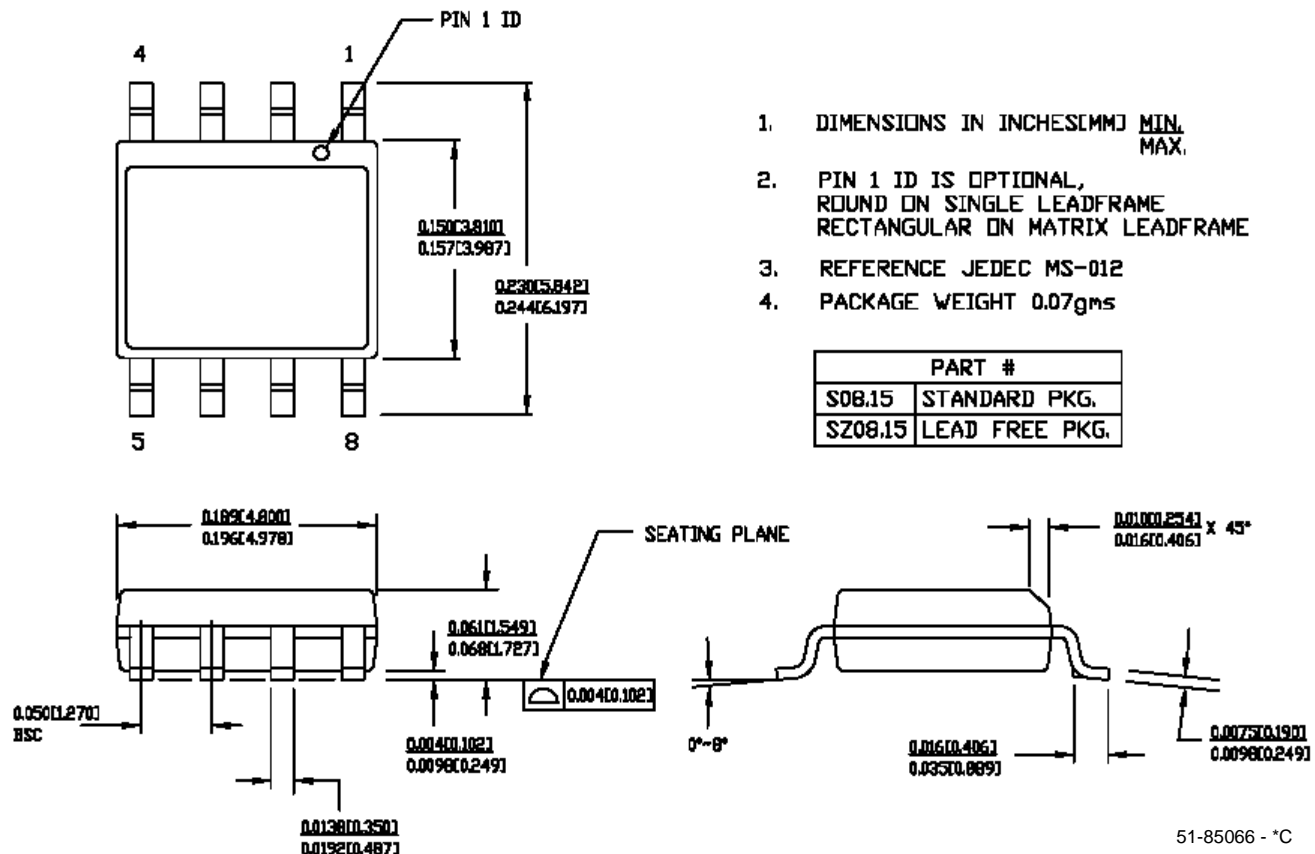


Figure 4-2. 8-Lead (150-Mil) SOIC

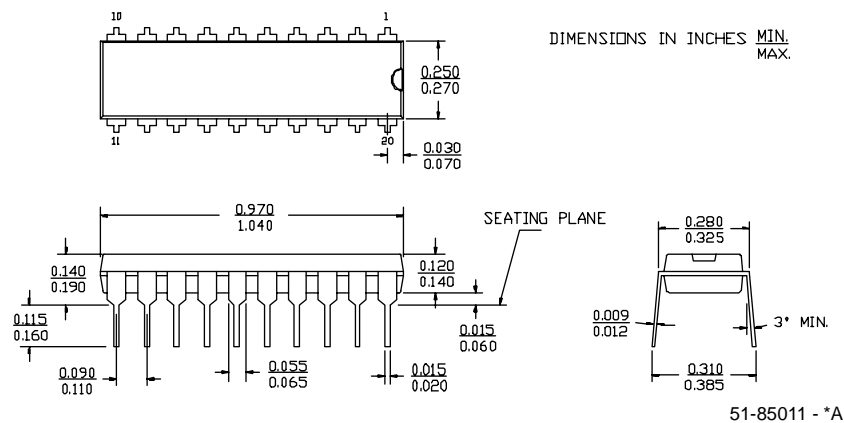


Figure 4-3. 20-Lead (300-Mil) Molded DIP

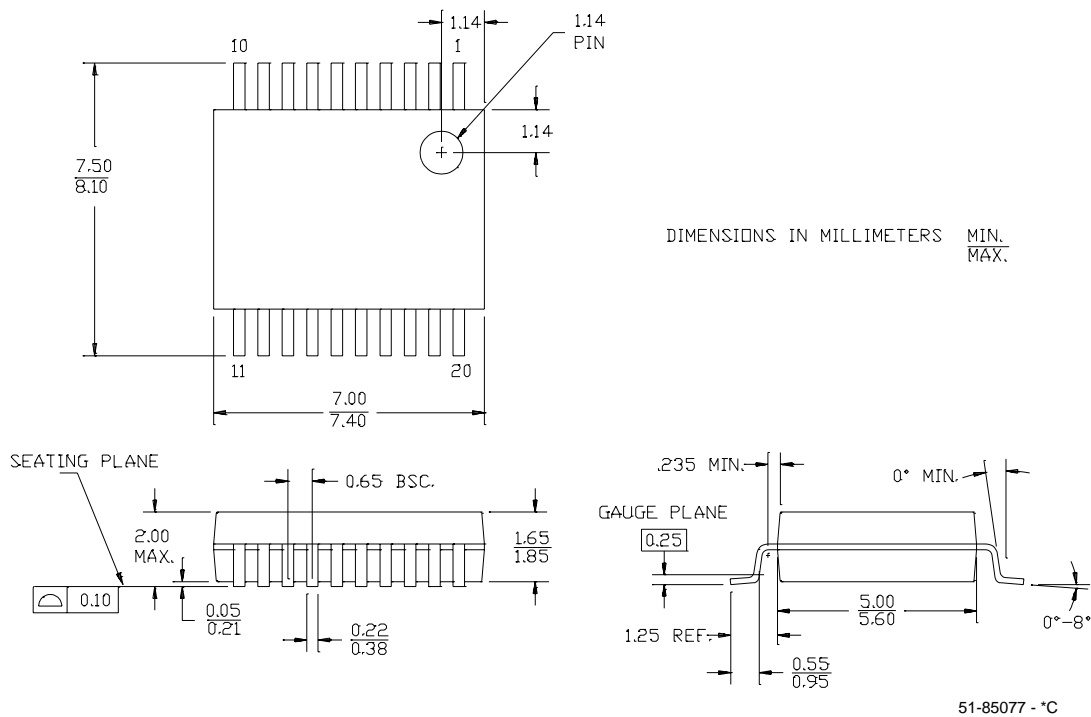


Figure 4-4. 20-Lead (210-Mil) SSOP

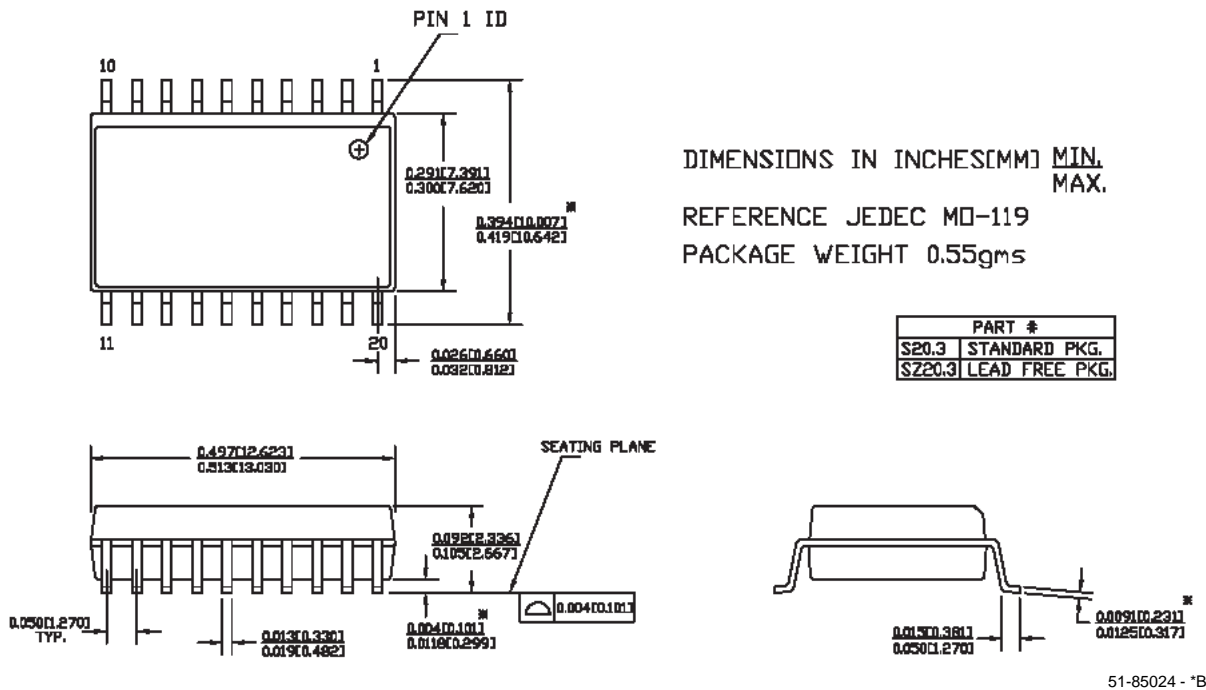


Figure 4-5. 20-Lead (300-Mil) Molded SOIC

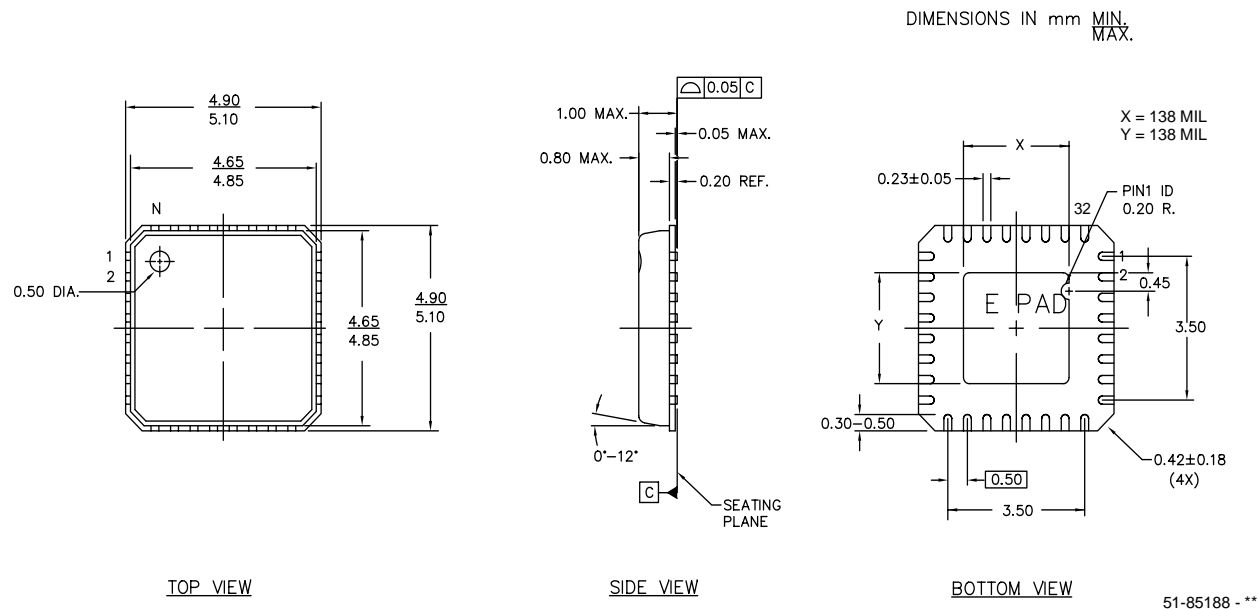


Figure 4-6. 32-Lead (5x5 mm) MLF

4.2 Thermal Impedances

Table 4-1. Thermal Impedances per Package

Package	Typical θ_{JA} *
8 PDIP	123 °C/W
8 SOIC	185 °C/W
20 PDIP	109 °C/W
20 SSOP	117 °C/W
20 SOIC	81 °C/W
32 MLF	22 °C/W

* $T_J = T_A + \text{POWER} \times \theta_{JA}$

4.3 Capacitance on Crystal Pins

Table 4-2: Typical Package Capacitance on Crystal Pins

Package	Package Capacitance
8 PDIP	2.8 pF
8 SOIC	2.0 pF
20 PDIP	3.0 pF
20 SSOP	2.6 pF
20 SOIC	2.5 pF
32 MLF	2.0 pF