



Welcome to [E-XFL.COM](https://www.e-xfl.com)

### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	22
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 12x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-VFQFN Exposed Pad
Supplier Device Package	24-QFN (4x4)
Purchase URL	<a href="https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=s9keazn8acfk">https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=s9keazn8acfk</a>

# Table of Contents

1 Ordering parts.....	3	4.2.2 FTM module timing.....	15
1.1 Determining valid orderable parts.....	3	4.3 Thermal specifications.....	16
2 Part identification.....	3	4.3.1 Thermal characteristics.....	16
2.1 Description.....	3	5 Peripheral operating requirements and behaviors.....	17
2.2 Format.....	3	5.1 Core modules.....	17
2.3 Fields.....	3	5.1.1 SWD electricals .....	18
2.4 Example.....	4	5.2 External oscillator (OSC) and ICS characteristics.....	19
3 Ratings.....	4	5.3 NVM specifications.....	21
3.1 Thermal handling ratings.....	4	5.4 Analog.....	22
3.2 Moisture handling ratings.....	4	5.4.1 ADC characteristics.....	22
3.3 ESD handling ratings.....	5	5.4.2 Analog comparator (ACMP) electricals.....	24
3.4 Voltage and current operating ratings.....	5	5.5 Communication interfaces.....	25
4 General.....	6	5.5.1 SPI switching specifications.....	25
4.1 Nonswitching electrical specifications.....	6	6 Dimensions.....	28
4.1.1 DC characteristics.....	6	6.1 Obtaining package dimensions.....	28
4.1.2 Supply current characteristics.....	12	7 Pinout.....	28
4.1.3 EMC performance.....	14	7.1 Signal multiplexing and pin assignments.....	28
4.2 Switching specifications.....	14	8 Revision History.....	29
4.2.1 Control timing.....	14		

Field	Description	Values
FFF	Program flash memory size	<ul style="list-style-type: none"> <li>8 = 8 KB</li> </ul>
M	Maskset revision	<ul style="list-style-type: none"> <li>A = 1<sup>st</sup> Fab version</li> <li>B = Revision after 1<sup>st</sup> version</li> </ul>
T	Temperature range (°C)	<ul style="list-style-type: none"> <li>C = -40 to 85</li> <li>V = -40 to 105</li> <li>M = -40 to 125</li> </ul>
PP	Package identifier	<ul style="list-style-type: none"> <li>TG = 16 TSSOP (4.5 mm x 5 mm)</li> <li>FK = 24 QFN (4 mm x 4 mm)</li> </ul>
N	Packaging type	<ul style="list-style-type: none"> <li>R = Tape and reel</li> <li>(Blank) = Trays</li> </ul>

## 2.4 Example

This is an example part number:

S9KEAZN8AMFK

## 3 Ratings

### 3.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T <sub>STG</sub>	Storage temperature	-55	150	°C	1
T <sub>SDR</sub>	Solder temperature, lead-free	—	260	°C	2

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 3.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

### 3.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
$V_{HBM}$	Electrostatic discharge voltage, human body model	−6000	+6000	V	1
$V_{CDM}$	Electrostatic discharge voltage, charged-device model	−500	+500	V	2
$I_{LAT}$	Latch-up current at ambient temperature of °C	−90	+95	mA	3

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.
3. Determined according to JEDEC Standard JESD78D, *IC Latch-up Test*. The test produced the following results:
  - Test was performed at 125 °C case temperature (Class II).
  - I/O pins pass +95/-90 mA I-test with  $I_{DD}$  current limit at 200 mA ( $V_{DD}$  collapsed during positive injection).
  - I/O pins pass +30/-90 mA I-test with  $I_{DD}$  current limit at 1000 mA for  $V_{DD}$ .
  - Supply groups pass 1.5  $V_{CCmax}$ .
  - RESET\_B pin was only tested with negative I-test due to product conditioning requirement.

### 3.4 Voltage and current operating ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in the following table may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this document.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pullup resistor associated with the pin is enabled.

**Table 1. Voltage and current operating ratings**

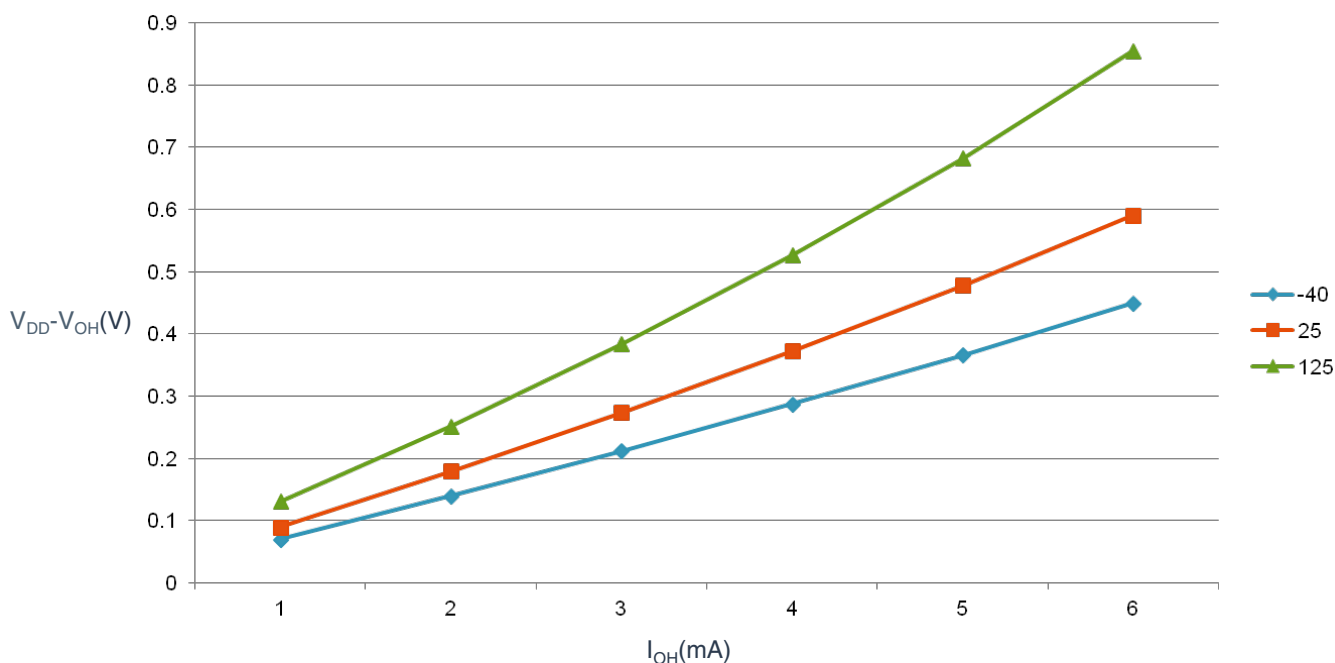
Symbol	Description	Min.	Max.	Unit
$V_{DD}$	Digital supply voltage	−0.3	6.0	V
$I_{DD}$	Maximum current into $V_{DD}$	—	120	mA
$V_{IN}$	Input voltage except true open drain pins	−0.3	$V_{DD} + 0.3$ <sup>1</sup>	V
	Input voltage of true open drain pins	−0.3	6	V
$I_D$	Instantaneous maximum current single pin limit (applies to all port pins)	−25	25	mA
$V_{DDA}$	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V

1. Maximum rating of  $V_{DD}$  also applies to  $V_{IN}$ .

**Table 3. LVD and POR specification (continued)**

Symbol	Description		Min	Typ	Max	Unit
$V_{LVDL}$	Falling low-voltage detect threshold—low range ( $LVDV = 0$ )		2.56	2.61	2.66	V
$V_{LVW1L}$	Falling low-voltage warning threshold—low range	Level 1 falling ( $LVWV = 00$ )	2.62	2.7	2.78	V
$V_{LVW2L}$		Level 2 falling ( $LVWV = 01$ )	2.72	2.8	2.88	V
$V_{LVW3L}$		Level 3 falling ( $LVWV = 10$ )	2.82	2.9	2.98	V
$V_{LVW4L}$		Level 4 falling ( $LVWV = 11$ )	2.92	3.0	3.08	V
$V_{HYSDL}$	Low range low-voltage detect hysteresis		—	40	—	mV
$V_{HYSWL}$	Low range low-voltage warning hysteresis		—	80	—	mV
$V_{BG}$	Buffered bandgap output <sup>3</sup>		1.14	1.16	1.18	V

1. Maximum is highest voltage that POR is guaranteed.
2. Rising thresholds are falling threshold + hysteresis.
3. voltage Factory trimmed at  $V_{DD} = 5.0$  V, Temp = 125 °C


**Figure 1. Typical  $V_{DD} - V_{OH}$  Vs.  $I_{OH}$  (standard drive strength) ( $V_{DD} = 5$  V)**

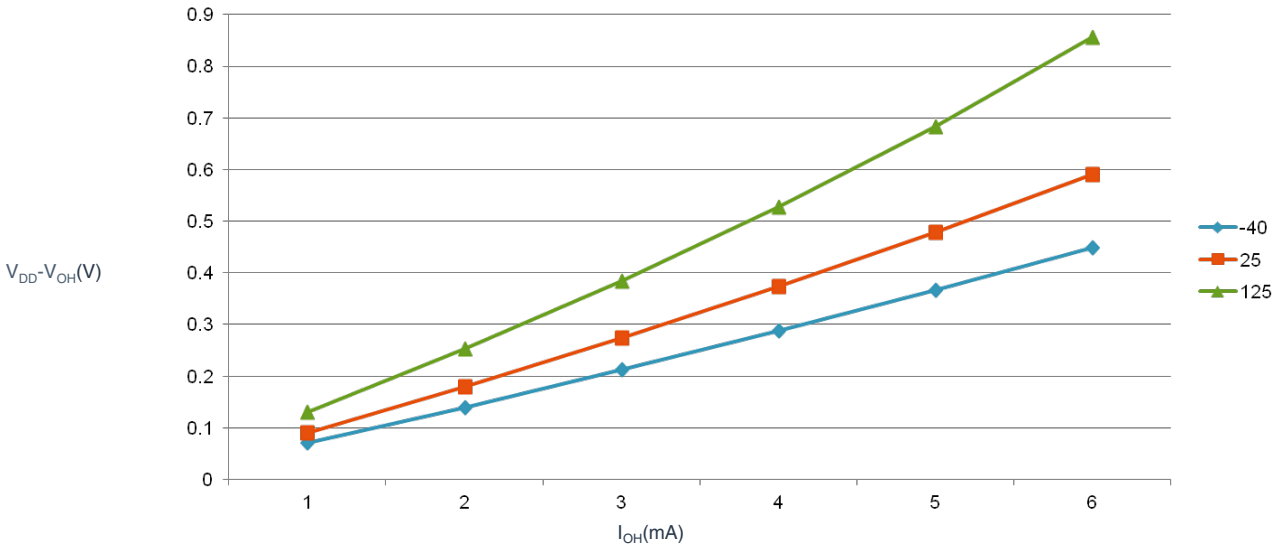


Figure 2. Typical  $V_{DD}-V_{OH}$  Vs.  $I_{OH}$  (standard drive strength) ( $V_{DD} = 3\text{ V}$ )

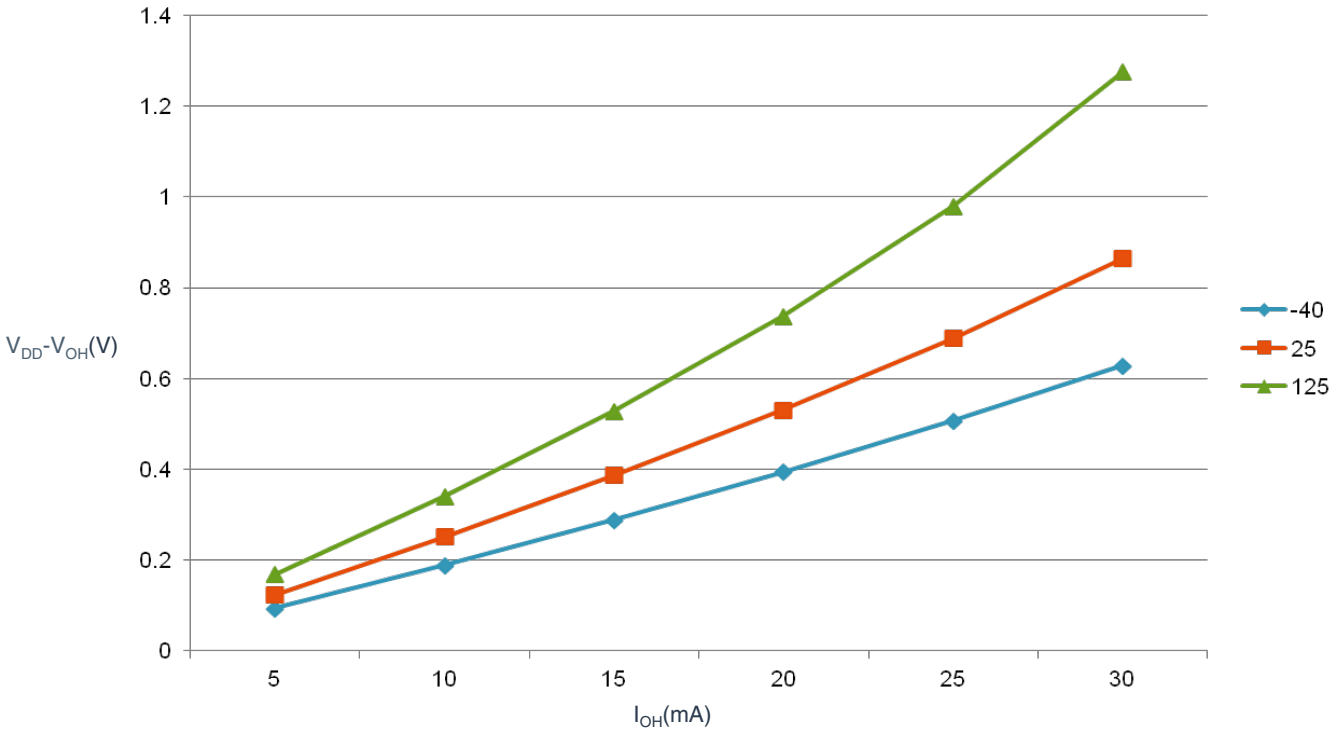


Figure 3. Typical  $V_{DD}-V_{OH}$  Vs.  $I_{OH}$  (high drive strength) ( $V_{DD} = 5\text{ V}$ )

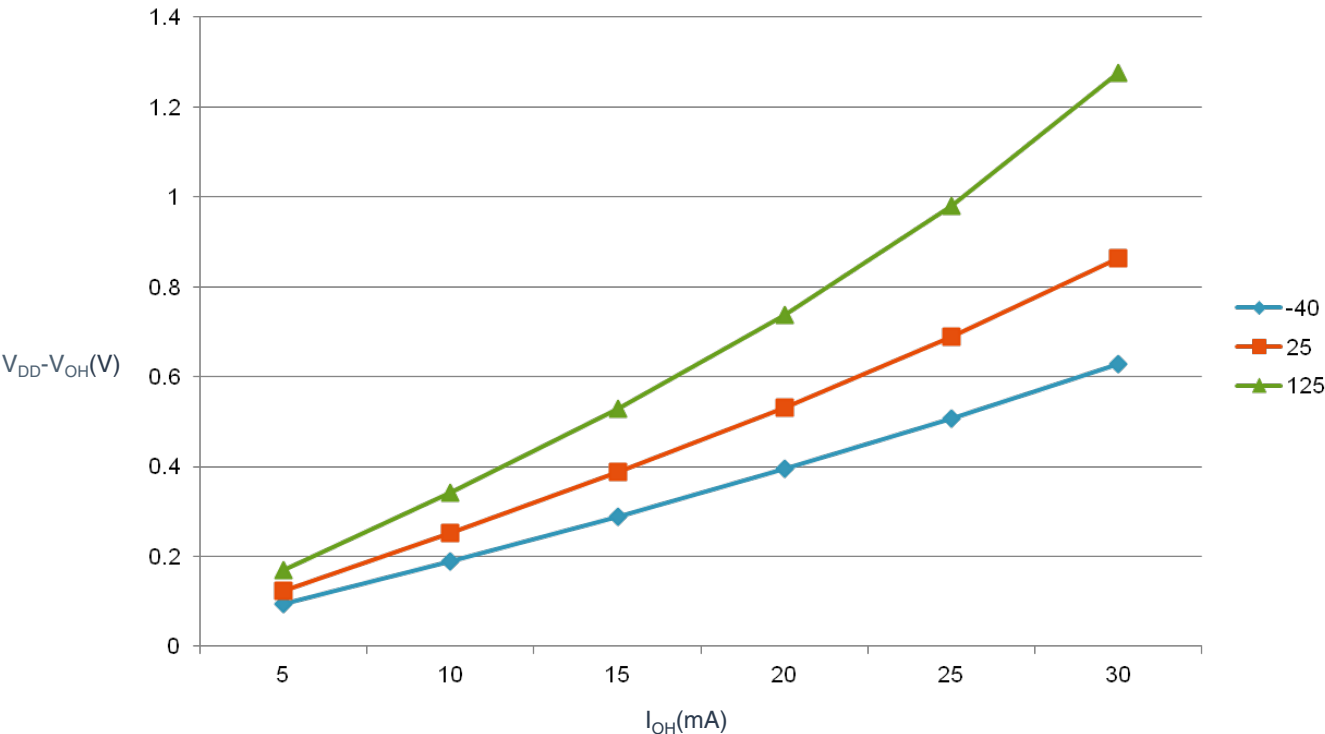


Figure 4. Typical  $V_{DD}-V_{OH}$  Vs.  $I_{OH}$  (high drive strength) ( $V_{DD} = 3$  V)

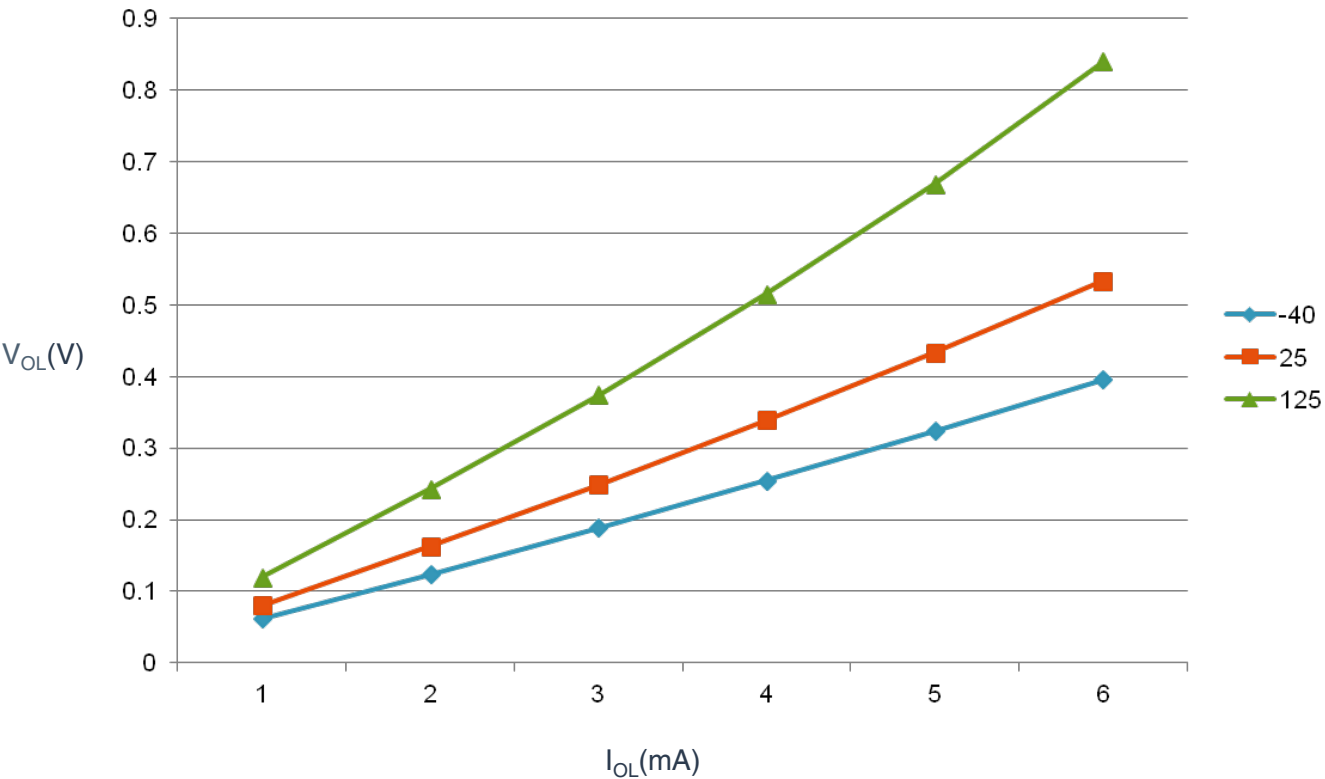


Figure 5. Typical  $V_{OL}$  Vs.  $I_{OL}$  (standard drive strength) ( $V_{DD} = 5$  V)

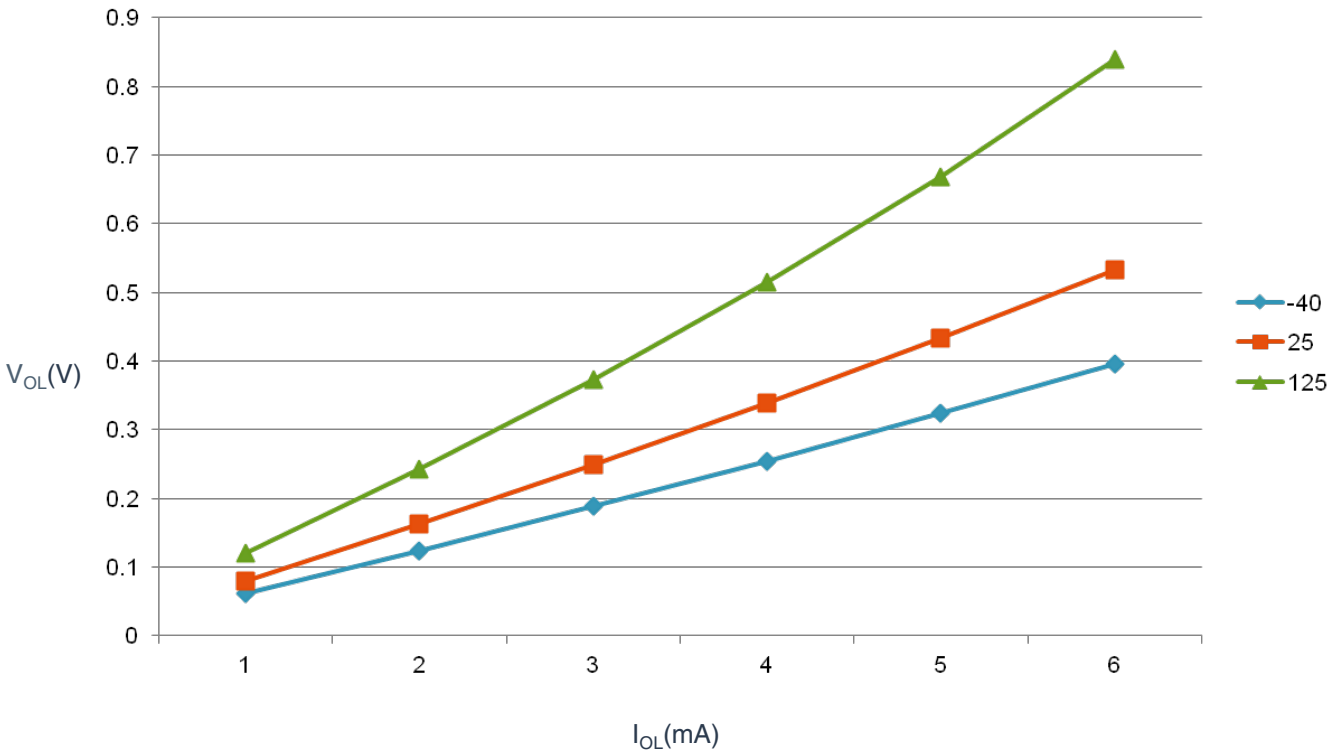


Figure 6. Typical  $V_{OL}$  Vs.  $I_{OL}$  (standard drive strength) ( $V_{DD} = 3$  V)

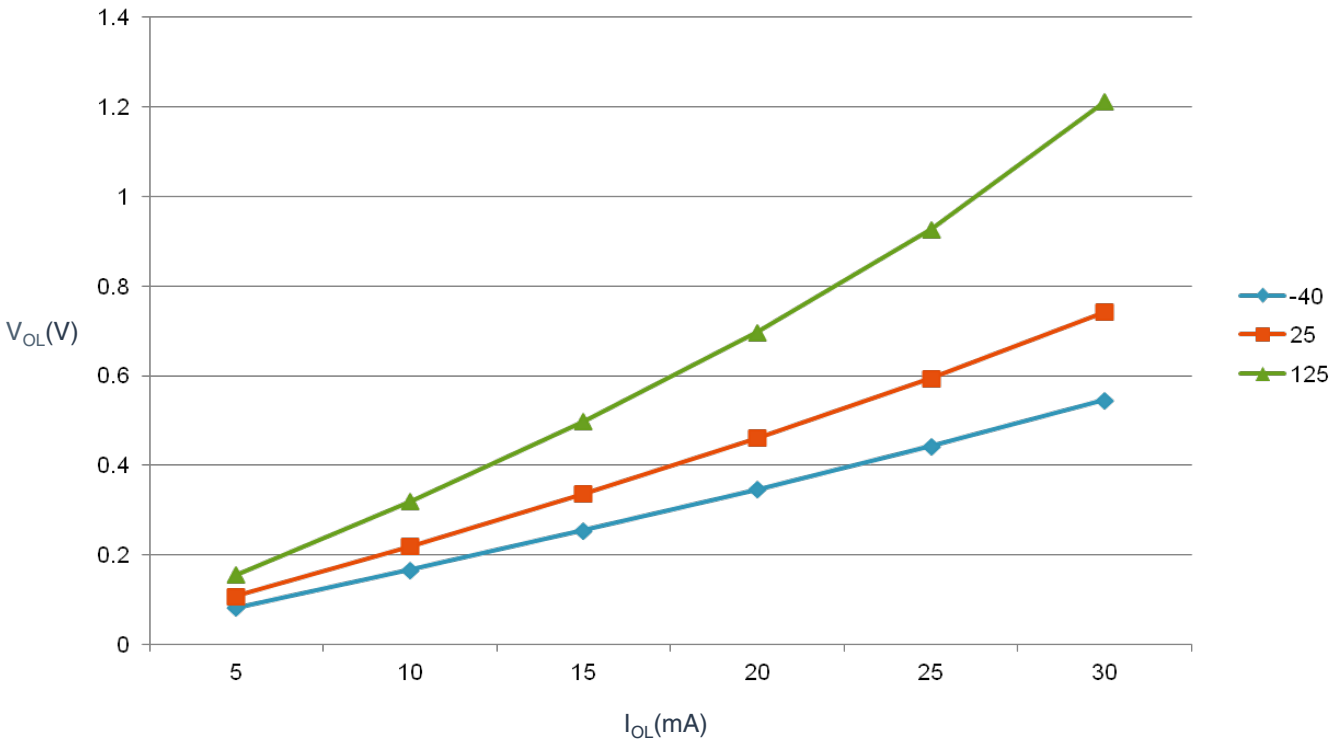


Figure 7. Typical  $V_{OL}$  Vs.  $I_{OL}$  (high drive strength) ( $V_{DD} = 5$  V)



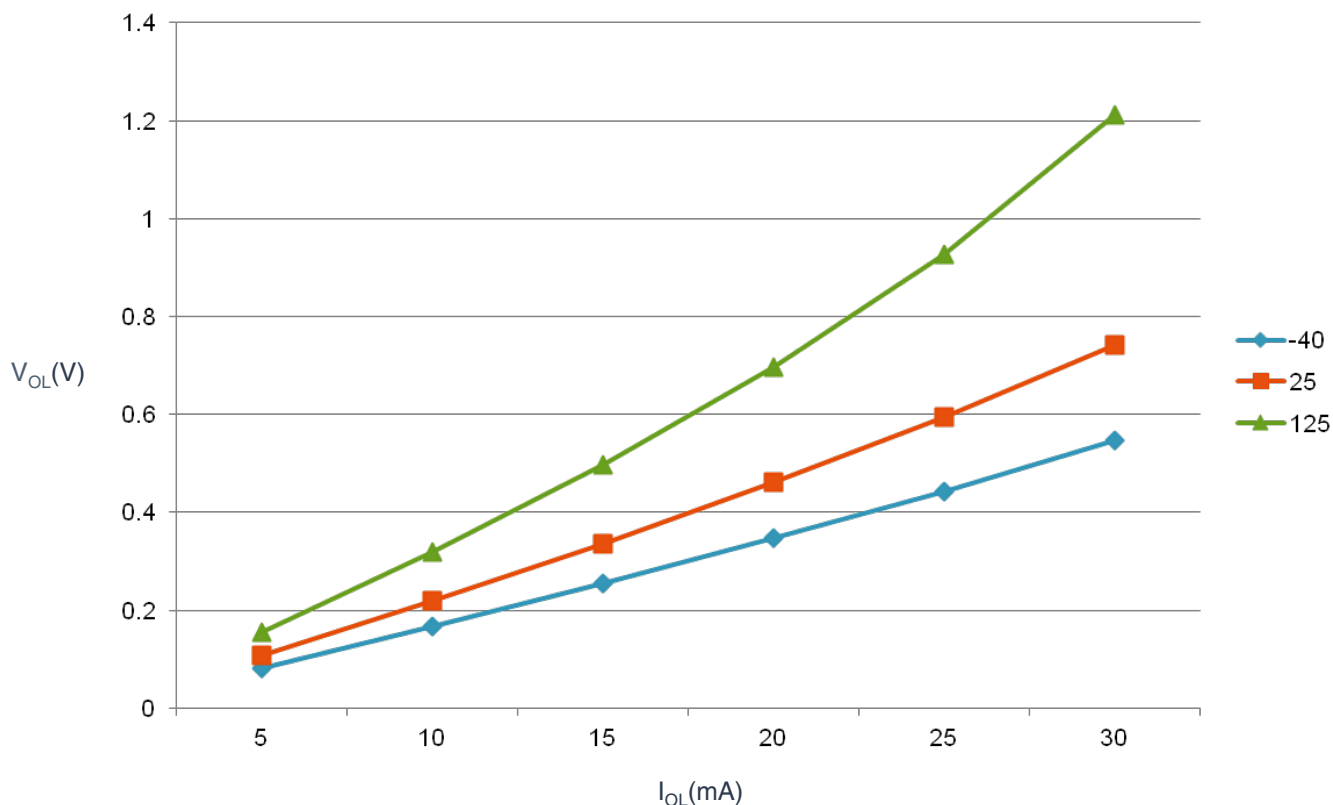


Figure 8. Typical  $V_{OL}$  Vs.  $I_{OL}$  (high drive strength) ( $V_{DD} = 3\text{ V}$ )

#### 4.1.2 Supply current characteristics

This section includes information about power supply current in various operating modes.

Table 4. Supply current characteristics

Parameter	Symbol	Core/Bus Freq	$V_{DD}$ (V)	Typical <sup>1</sup>	Max <sup>2</sup>	Unit	Temp
Run supply current FEI mode, all modules clocks enabled; run from flash	$RI_{DD}$	48/24 MHz	5	10.1	—	mA	-40 to 125 °C
		24/24 MHz		7.1	—		
		12/12 MHz		4.4	—		
		1/1 MHz		2.1	—		
		48/24 MHz	3	9.9	—		
		24/24 MHz		6.9	—		
		12/12 MHz		4.2	—		
		1/1 MHz		1.9	—		
Run supply current FEI mode, all modules clocks disabled and gated; run from flash	$RI_{DD}$	48/24 MHz	5	7.4	—	mA	-40 to 125 °C
		24/24 MHz		5.2	—		
		12/12 MHz		3.5	—		
		1/1 MHz		2	—		

Table continues on the next page...

**Table 4. Supply current characteristics (continued)**

Parameter	Symbol	Core/Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max <sup>2</sup>	Unit	Temp
		48/24 MHz	3	7.2	—		
		24/24 MHz		5	—		
		12/12 MHz		3.3	—		
		1/1 MHz		1.8	—		
Run supply current FBE mode, all modules clocks enabled; run from RAM	R <sub>IDD</sub>	48/24 MHz	5	13.2	—	mA	-40 to 125 °C
		24/24 MHz		9.1	10.8		
		12/12 MHz		5.1	—		
		1/1 MHz		1.8	—		
		48/24 MHz	3	13	—		
		24/24 MHz		9	10.7		
		12/12 MHz		5	—		
		1/1 MHz		1.7	—		
Run supply current FBE mode, all modules clocks disabled and gated; run from RAM	R <sub>IDD</sub>	48/24 MHz	5	10.6	—	mA	-40 to 125 °C
		24/24 MHz		7.6	9.2		
		12/12 MHz		4.3	—		
		1/1 MHz		1.7	—		
		48/24 MHz	3	10.5	—		
		24/24 MHz		7.5	9.1		
		12/12 MHz		4.2	—		
		1/1 MHz		1.6	—		
Wait mode current FEI mode, all modules clocks enabled	W <sub>IDD</sub>	48/24 MHz	5	7.2	—	mA	-40 to 125 °C
		24/24 MHz		6.3	7.4		
		12/12 MHz		3.6	—		
		1/1 MHz		1.9	—		
		48/24 MHz	3	7.1	—		
		24/24 MHz		6.2	7.3		
		12/12 MHz		3.5	—		
		1/1 MHz		1.8	—		
Stop mode supply current no clocks active (except 1 kHz LPO clock) <sup>3, 4</sup>	S <sub>IDD</sub>	—	5	2	110	μA	-40 to 125 °C
		—	3	1.9	105		-40 to 125 °C
ADC adder to Stop ADLPC = 1 ADLSMP = 1 ADCO = 1 MODE = 10B ADICLK = 11B	—	—	5	86	—	μA	-40 to 125 °C
			3	82	—		
LVD adder to Stop <sup>5</sup>	—	—	5	130	—	μA	-40 to 125 °C
			3	125	—		

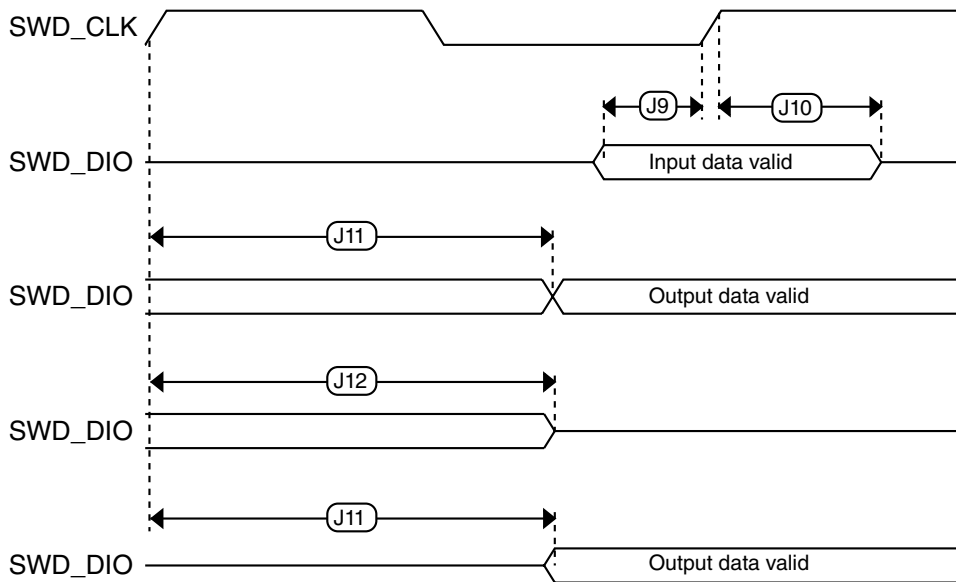


Figure 14. Serial wire data timing

## 5.2 External oscillator (OSC) and ICS characteristics

Table 9. OSC and ICS specifications (temperature range = -40 to 125 °C ambient)

Num	Characteristic		Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	Crystal or resonator frequency	Low range (RANGE = 0)	$f_{lo}$	31.25	32.768	39.0625	kHz
		High range (RANGE = 1)	$f_{hi}$	4	—	24	MHz
2	Load capacitors		C1, C2	See Note <sup>2</sup>			
3	Feedback resistor	Low Frequency, Low-Power Mode <sup>3</sup>	$R_F$	—	—	—	MΩ
		Low Frequency, High-Gain Mode		—	10	—	MΩ
		High Frequency, Low-Power Mode		—	1	—	MΩ
		High Frequency, High-Gain Mode		—	1	—	MΩ
4	Series resistor - Low Frequency	Low-Power Mode <sup>3</sup>	$R_S$	—	0	—	kΩ
		High-Gain Mode		—	200	—	kΩ
5	Series resistor - High Frequency	Low-Power Mode <sup>3</sup>	$R_S$	—	0	—	kΩ
	Series resistor - High Frequency, High-Gain Mode	4 MHz		—	0	—	kΩ
		8 MHz		—	0	—	kΩ

Table continues on the next page...

**Table 9. OSC and ICS specifications (temperature range = -40 to 125 °C ambient) (continued)**

Num	Characteristic		Symbol	Min	Typical <sup>1</sup>	Max	Unit
		16 MHz		—	0	—	kΩ
6	Crystal start-up time low range = 32.768 kHz crystal; High range = 20 MHz crystal <sup>4,5</sup>	Low range, low power	$t_{\text{CSTL}}$	—	1000	—	ms
		Low range, high gain		—	800	—	ms
		High range, low power	$t_{\text{CSTH}}$	—	3	—	ms
		High range, high gain		—	1.5	—	ms
7	Internal reference start-up time		$t_{\text{IRST}}$	—	20	50	μs
8	Internal reference clock (IRC) frequency trim range		$f_{\text{int\_t}}$	31.25	—	39.0625	kHz
9	Internal reference clock frequency, factory trimmed	$T = 125\text{ °C}, V_{\text{DD}} = 5\text{ V}$	$f_{\text{int\_ft}}$	—	37.5	—	kHz
10	DCO output frequency range	FLL reference = $f_{\text{int\_t}}$ , $f_{\text{lo}}$ , or $f_{\text{hi}}/\text{RDIV}$	$f_{\text{dco}}$	40	—	50	MHz
11	Factory trimmed internal oscillator accuracy	$T = 125\text{ °C}, V_{\text{DD}} = 5\text{ V}$	$\Delta f_{\text{int\_ft}}$	-0.8	—	0.8	%
12	Deviation of IRC over temperature when trimmed at $T = 25\text{ °C}, V_{\text{DD}} = 5\text{ V}$	Over temperature range from -40 °C to 125°C	$\Delta f_{\text{int\_t}}$	-1	—	0.8	%
13	Frequency accuracy of DCO output using factory trim value	Over temperature range from -40 °C to 125°C	$\Delta f_{\text{dco\_ft}}$	-2.3	—	0.8	%
14	FLL acquisition time <sup>4,6</sup>		$t_{\text{Acquire}}$	—	—	2	ms
15	Long term jitter of DCO output clock (averaged over 2 ms interval) <sup>7</sup>		$C_{\text{Jitter}}$	—	0.02	0.2	% $f_{\text{dco}}$

1. Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.
2. See crystal or resonator manufacturer's recommendation.
3. Load capacitors ( $C_1, C_2$ ), feedback resistor ( $R_F$ ) and series resistor ( $R_S$ ) are incorporated internally when RANGE = HGO = 0.
4. This parameter is characterized and not tested on each device.
5. Proper PC board layout procedures must be followed to achieve specifications.
6. This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
7. Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum  $f_{\text{Bus}}$ . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via  $V_{\text{DD}}$  and  $V_{\text{SS}}$  and variation in crystal oscillator frequency increase the  $C_{\text{Jitter}}$  percentage for a given interval.

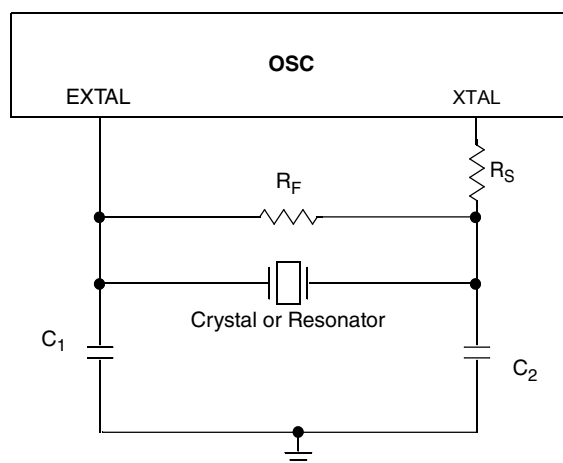


Figure 15. Typical crystal or resonator circuit

## 5.3 NVM specifications

This section provides details about program/erase times and program/erase endurance for the flash memories.

Table 10. Flash characteristics

Characteristic	Symbol	Min <sup>1</sup>	Typical <sup>2</sup>	Max <sup>3</sup>	Unit <sup>4</sup>
Supply voltage for program/erase –40 °C to 125 °C	$V_{\text{prog/erase}}$	2.7	—	5.5	V
Supply voltage for read operation	$V_{\text{Read}}$	2.7	—	5.5	V
NVM Bus frequency	$f_{\text{NVMBUS}}$	1	—	24	MHz
NVM Operating frequency	$f_{\text{NVMOP}}$	0.8	1	1.05	MHz
Erase Verify All Blocks	$t_{\text{VFYALL}}$	—	—	2605	$t_{\text{cyc}}$
Erase Verify Flash Block	$t_{\text{RD1BLK}}$	—	—	2579	$t_{\text{cyc}}$
Erase Verify Flash Section	$t_{\text{RD1SEC}}$	—	—	485	$t_{\text{cyc}}$
Read Once	$t_{\text{RDONCE}}$	—	—	464	$t_{\text{cyc}}$
Program Flash (2 word)	$t_{\text{PGM2}}$	0.12	0.13	0.31	ms
Program Flash (4 word)	$t_{\text{PGM4}}$	0.21	0.21	0.49	ms
Program Once	$t_{\text{PGMONCE}}$	0.20	0.21	0.21	ms
Erase All Blocks	$t_{\text{ERSALL}}$	95.42	100.18	100.30	ms
Erase Flash Block	$t_{\text{ERSBLK}}$	95.42	100.18	100.30	ms
Erase Flash Sector	$t_{\text{ERSPG}}$	19.10	20.05	20.09	ms
Unsecure Flash	$t_{\text{UNSECU}}$	95.42	100.19	100.31	ms
Verify Backdoor Access Key	$t_{\text{VFYKEY}}$	—	—	482	$t_{\text{cyc}}$
Set User Margin Level	$t_{\text{MLOADU}}$	—	—	415	$t_{\text{cyc}}$
FLASH Program/erase endurance $T_L$ to $T_H$ = –40 °C to 125 °C	$\eta_{\text{FLPE}}$	10 k	100 k	—	Cycles

Table continues on the next page...

**Table 10. Flash characteristics (continued)**

Characteristic	Symbol	Min <sup>1</sup>	Typical <sup>2</sup>	Max <sup>3</sup>	Unit <sup>4</sup>
Data retention at an average junction temperature of $T_{Javg} = 85^{\circ}C$ after up to 10,000 program/erase cycles	$t_{D\_ret}$	15	100	—	years

1. Minimum times are based on maximum  $f_{NVMOP}$  and maximum  $f_{NVMBUS}$
2. Typical times are based on typical  $f_{NVMOP}$  and maximum  $f_{NVMBUS}$
3. Maximum times are based on typical  $f_{NVMOP}$  and typical  $f_{NVMBUS}$  plus aging
4.  $t_{cyc} = 1 / f_{NVMBUS}$

Program and erase operations do not require any special power sources other than the normal  $V_{DD}$  supply. For more detailed information about program/erase operations, see the Flash Memory Module section in the reference manual.

## 5.4 Analog

### 5.4.1 ADC characteristics

**Table 11. 5 V 12-bit ADC operating conditions**

Characteristic	Conditions	Symbol	Min	Typ <sup>1</sup>	Max	Unit	Comment
Supply voltage	Absolute	$V_{DDA}$	2.7	—	5.5	V	—
	Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ )	$\Delta V_{DDA}$	-100	0	+100	mV	—
Input voltage		$V_{ADIN}$	$V_{REFL}$	—	$V_{REFH}$	V	—
Input capacitance		$C_{ADIN}$	—	4.5	5.5	pF	—
Input resistance		$R_{ADIN}$	—	3	5	k $\Omega$	—
Analog source resistance	12-bit mode	$R_{AS}$	—	—	2	k $\Omega$	External to MCU
	• $f_{ADCK} > 4$ MHz		—	—	5		
	• $f_{ADCK} < 4$ MHz		—	—	5		
	10-bit mode		—	—	5		
	• $f_{ADCK} > 4$ MHz		—	—	10		
	• $f_{ADCK} < 4$ MHz		—	—	10		
	8-bit mode		—	—	10		
	(all valid $f_{ADCK}$ )						
ADC conversion clock frequency	High speed (ADLPC=0)	$f_{ADCK}$	0.4	—	8.0	MHz	—
	Low power (ADLPC=1)		0.4	—	4.0		

1. Typical values assume  $V_{DDA} = 5.0$  V, Temp =  $25^{\circ}C$ ,  $f_{ADCK} = 1.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

**Table 12. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Characteristic	Conditions	Symbol	Min	Typ <sup>1</sup>	Max	Unit
	Low power (ADLPC = 1)		1.25	2	3.3	
Conversion time (including sample time)	Short sample (ADLSMP = 0)	$t_{ADC}$	—	20	—	ADCK cycles
	Long sample (ADLSMP = 1)		—	40	—	
Sample time	Short sample (ADLSMP = 0)	$t_{ADS}$	—	3.5	—	ADCK cycles
	Long sample (ADLSMP = 1)		—	23.5	—	
Total unadjusted Error <sup>2</sup>	12-bit mode	$E_{TUE}$	—	±3.0	—	LSB <sup>3</sup>
	10-bit mode		—	±1.0	±6.0	
	8-bit mode		—	±0.8	—	
Differential Non- Linearity	12-bit mode	DNL	—	±1.2	—	LSB <sup>3</sup>
	10-bit mode <sup>4</sup>		—	±0.3	±4.0	
	8-bit mode <sup>4</sup>		—	±0.15	—	
Integral Non-Linearity	12-bit mode	INL	—	±1.2	—	LSB <sup>3</sup>
	10-bit mode		—	±0.3	±5.0	
	8-bit mode		—	±0.15	—	
Zero-scale error <sup>5</sup>	12-bit mode	$E_{ZS}$	—	±1.2	—	LSB <sup>3</sup>
	10-bit mode		—	±0.15	±6.0	
	8-bit mode		—	±0.3	—	
Full-scale error <sup>6</sup>	12-bit mode	$E_{FS}$	—	±1.8	—	LSB <sup>3</sup>
	10-bit mode		—	±0.7	±1.0	
	8-bit mode		—	±0.5	—	
Quantization error	≤12 bit modes	$E_Q$	—	—	±0.5	LSB <sup>3</sup>
Input leakage error <sup>7</sup>	all modes	$E_{IL}$	$I_{IN} \times R_{AS}$			mV
Temp sensor slope	-40 °C–25 °C	m	—	3.266	—	mV/°C
	25 °C–125 °C		—	3.638	—	
Temp sensor voltage	25 °C	$V_{TEMP25}$	—	1.396	—	V

1. Typical values assume  $V_{DDA} = 5.0$  V, Temp = 25 °C,  $f_{ADCK}=2.5$  MHz under FBE mode and alternate clock source (ALTCLK) is selected as ADC clock.
2. Includes quantization
3.  $1 \text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
4. Monotonicity and no-missing-codes guaranteed in 10-bit and 8-bit modes
5.  $V_{ADIN} = V_{SSA}$
6.  $V_{ADIN} = V_{DDA}$
7.  $I_{IN}$  = leakage current (refer to DC characteristics)

## 5.4.2 Analog comparator (ACMP) electricals

**Table 13. Comparator electrical specifications**

Characteristic	Symbol	Min	Typical	Max	Unit
Supply voltage	$V_{DDA}$	2.7	—	5.5	V
Supply current (Operation mode)	$I_{DDA}$	—	10	20	$\mu$ A
Analog input voltage	$V_{AIN}$	$V_{SS} - 0.3$	—	$V_{DDA}$	V
Analog input offset voltage	$V_{AIO}$	—	—	40	mV
Analog comparator hysteresis (HYST=0)	$V_H$	—	15	20	mV
Analog comparator hysteresis (HYST=1)	$V_H$	—	20	30	mV
Supply current (Off mode)	$I_{DDA\text{OFF}}$	—	60	—	nA
Propagation Delay	$t_D$	—	0.4	1	$\mu$ s

## 5.5 Communication interfaces

### 5.5.1 SPI switching specifications

The serial peripheral interface (SPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic SPI timing modes. See the SPI chapter of the chip's reference manual for information about the modified transfer formats used for communicating with slower peripheral devices. All timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$ , unless noted, and 25 pF load on all SPI pins. All timing assumes slew rate control is disabled and high-drive strength is enabled for SPI output pins.

**Table 14. SPI master mode timing**

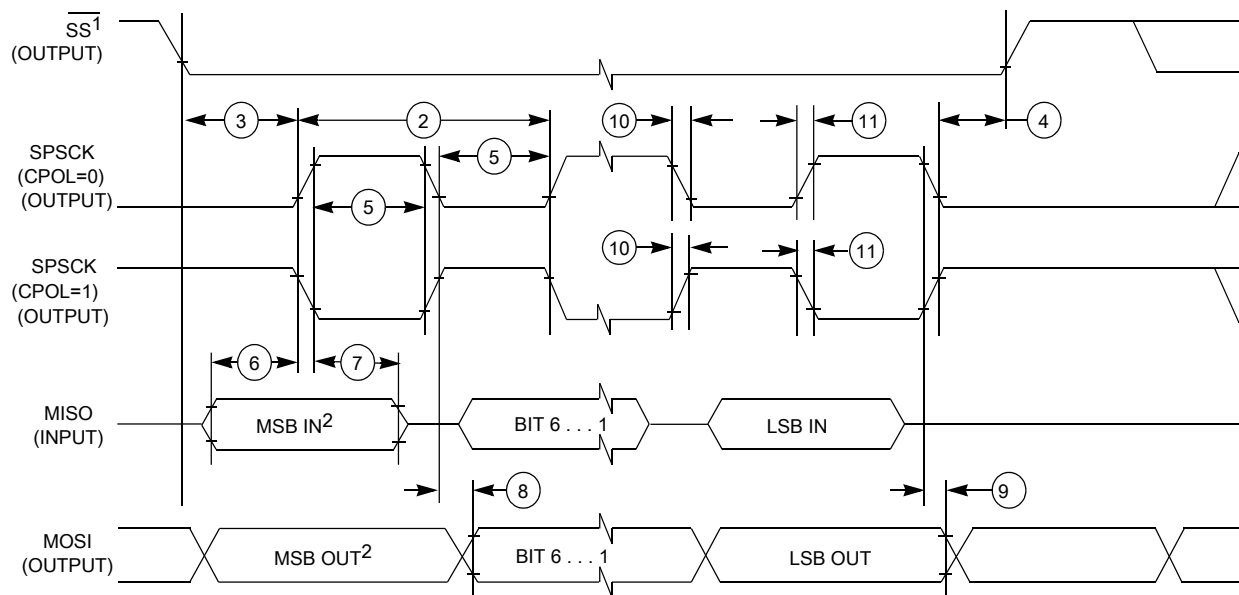
Nu m.	Symbol	Description	Min.	Max.	Unit	Comment
1	$f_{op}$	Frequency of operation	$f_{Bus}/2048$	$f_{Bus}/2$	Hz	$f_{Bus}$ is the bus clock
2	$t_{SPSCK}$	SPSCK period	$2 \times t_{Bus}$	$2048 \times t_{Bus}$	ns	$t_{Bus} = 1/f_{Bus}$
3	$t_{Lead}$	Enable lead time	1/2	—	$t_{SPSCK}$	—
4	$t_{Lag}$	Enable lag time	1/2	—	$t_{SPSCK}$	—
5	$t_{WSPSCK}$	Clock (SPSCK) high or low time	$t_{Bus} - 30$	$1024 \times t_{Bus}$	ns	—
6	$t_{SU}$	Data setup time (inputs)	8	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	8	—	ns	—
8	$t_v$	Data valid (after SPSCK edge)	—	25	ns	—
9	$t_{HO}$	Data hold time (outputs)	20	—	ns	—

Table continues on the next page...



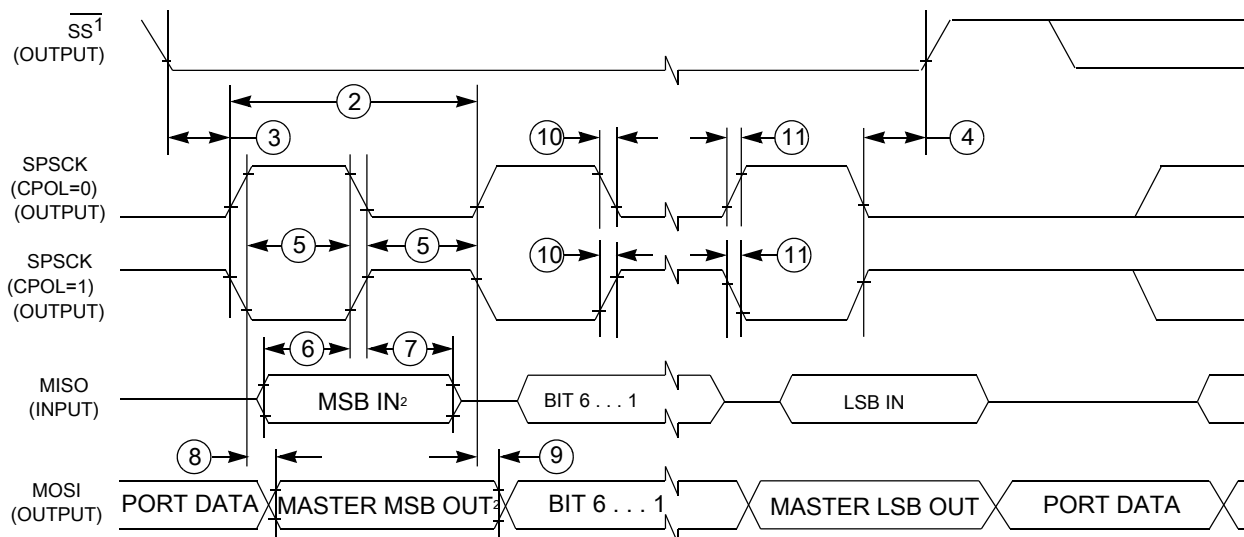
**Table 14. SPI master mode timing (continued)**

Nu m.	Symbol	Description	Min.	Max.	Unit	Comment
10	$t_{RI}$	Rise time input	—	$t_{Bus} - 25$	ns	—
	$t_{FI}$	Fall time input				
11	$t_{RO}$	Rise time output	—	25	ns	—
	$t_{FO}$	Fall time output				



1. If configured as an output.
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

**Figure 17. SPI master mode timing (CPHA=0)**

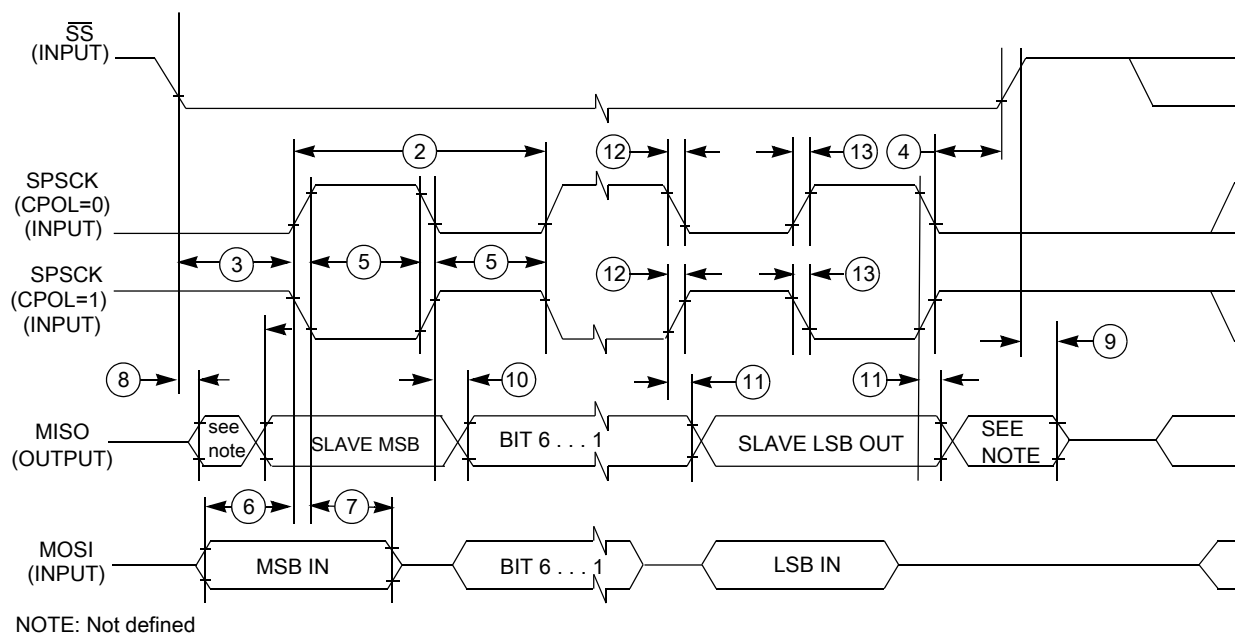


1. If configured as output
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

**Figure 18. SPI master mode timing (CPHA=1)**

**Table 15. SPI slave mode timing**

Nu m.	Symbol	Description	Min.	Max.	Unit	Comment
1	$f_{op}$	Frequency of operation	0	$f_{Bus}/4$	Hz	$f_{Bus}$ is the bus clock as defined in <a href="#">Control timing</a> .
2	$t_{SPSCK}$	SPSCK period	$4 \times t_{Bus}$	—	ns	$t_{Bus} = 1/f_{Bus}$
3	$t_{Lead}$	Enable lead time	1	—	$t_{Bus}$	—
4	$t_{Lag}$	Enable lag time	1	—	$t_{Bus}$	—
5	$t_{WSPSCK}$	Clock (SPSCK) high or low time	$t_{Bus} - 30$	—	ns	—
6	$t_{SU}$	Data setup time (inputs)	15	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	25	—	ns	—
8	$t_a$	Slave access time	—	$t_{Bus}$	ns	Time to data active from high-impedance state
9	$t_{dis}$	Slave MISO disable time	—	$t_{Bus}$	ns	Hold time to high-impedance state
10	$t_v$	Data valid (after SPSCK edge)	—	25	ns	—
11	$t_{HO}$	Data hold time (outputs)	0	—	ns	—
12	$t_{RI}$	Rise time input	—	$t_{Bus} - 25$	ns	—
	$t_{FI}$	Fall time input	—	$t_{Bus} - 25$	ns	—
13	$t_{RO}$	Rise time output	—	25	ns	—
	$t_{FO}$	Fall time output	—	25	ns	—


**Figure 19. SPI slave mode timing (CPHA = 0)**

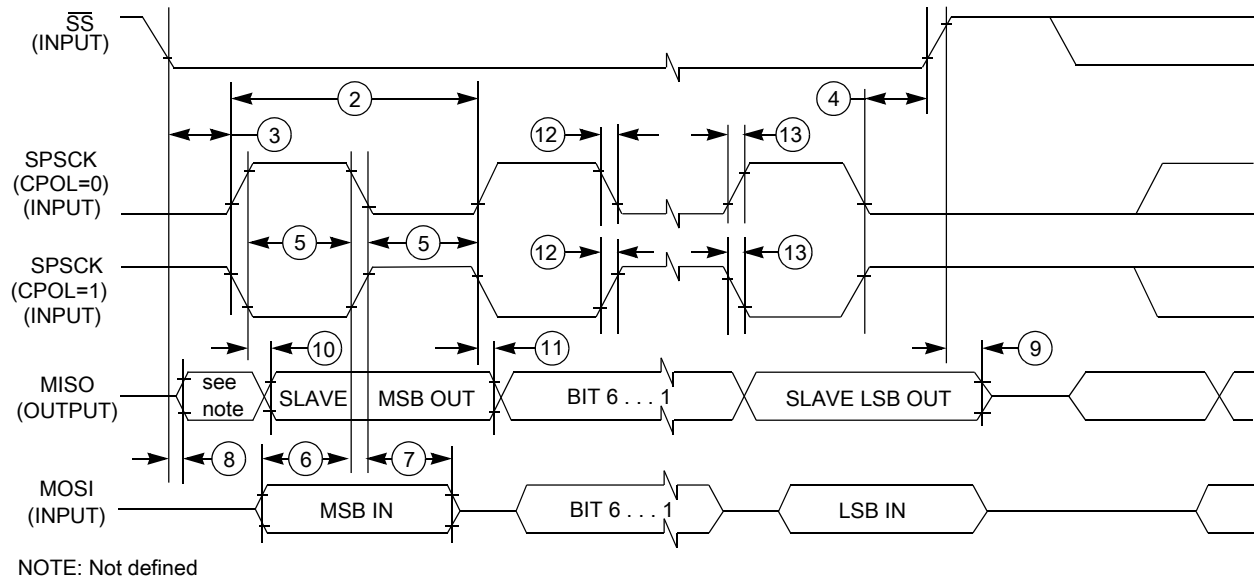


Figure 20. SPI slave mode timing (CPHA=1)

## 6 Dimensions

### 6.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to [freescale.com](http://freescale.com) and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
16-pin TSSOP	98ASH70247A
24-pin QFN	98ASA00474D

## 7 Pinout

### 7.1 Signal multiplexing and pin assignments

For the pin muxing details see section Signal Multiplexing and Signal Descriptions of KEA8 Reference Manual.

# 8 Revision History

The following table provides a revision history for this document.

**Table 16. Revision History**

Rev. No.	Date	Substantial Changes
Rev. 1	11 March 2014	Initial Release
Rev. 2	18 June 2014	<ul style="list-style-type: none"> <li>Parameter Classification section is removed.</li> <li>Classification column is removed from all the tables in the document.</li> <li>New section added - <a href="#">Supply current characteristics</a>.</li> </ul>
Rev. 3	18 July 2014	<ul style="list-style-type: none"> <li><a href="#">ESD handling ratings</a> section is updated.</li> <li>Figures in <a href="#">DC characteristics</a> section are updated.</li> <li>Specs updated in following tables: <ul style="list-style-type: none"> <li><a href="#">Table 9</a>.</li> <li><a href="#">Table 12</a>.</li> </ul> </li> </ul>
Rev. 4	03 Sept 2014	<ul style="list-style-type: none"> <li>Data Sheet type changed to "Technical Data".</li> </ul>

**How to Reach Us:****Home Page:**[freescale.com](http://freescale.com)**Web Support:**[freescale.com/support](http://freescale.com/support)

Information in this document is provided solely to enable system and software implementers to use Freescale products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits based on the information in this document. Freescale reserves the right to make changes without further notice to any products herein.

Freescale makes no warranty, representation, or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in Freescale data sheets and/or specifications can and do vary in different applications, and actual performance may vary over time. All operating parameters, including "typicals," must be validated for each customer application by customer's technical experts. Freescale does not convey any license under its patent rights nor the rights of others. Freescale sells products pursuant to standard terms and conditions of sale, which can be found at the following address: [freescale.com/SalesTermsandConditions](http://freescale.com/SalesTermsandConditions).

Freescale, the Freescale logo, and Kinetis are trademarks of Freescale Semiconductor, Inc., Reg. U.S. Pat. & Tm. Off. All other product or service names are the property of their respective owners. ARM and Cortex-M0+ are the registered trademarks of ARM Limited.

©2014 Freescale Semiconductor, Inc.