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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	8051
Core Size	8-Bit
Speed	25MHz
Connectivity	SMBus (2-Wire/I²C), SPI, UART/USART
Peripherals	Cap Sense, POR, PWM, Temp Sensor, WDT
Number of I/O	39
Program Memory Size	16KB (16K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/c8051f706-gqr

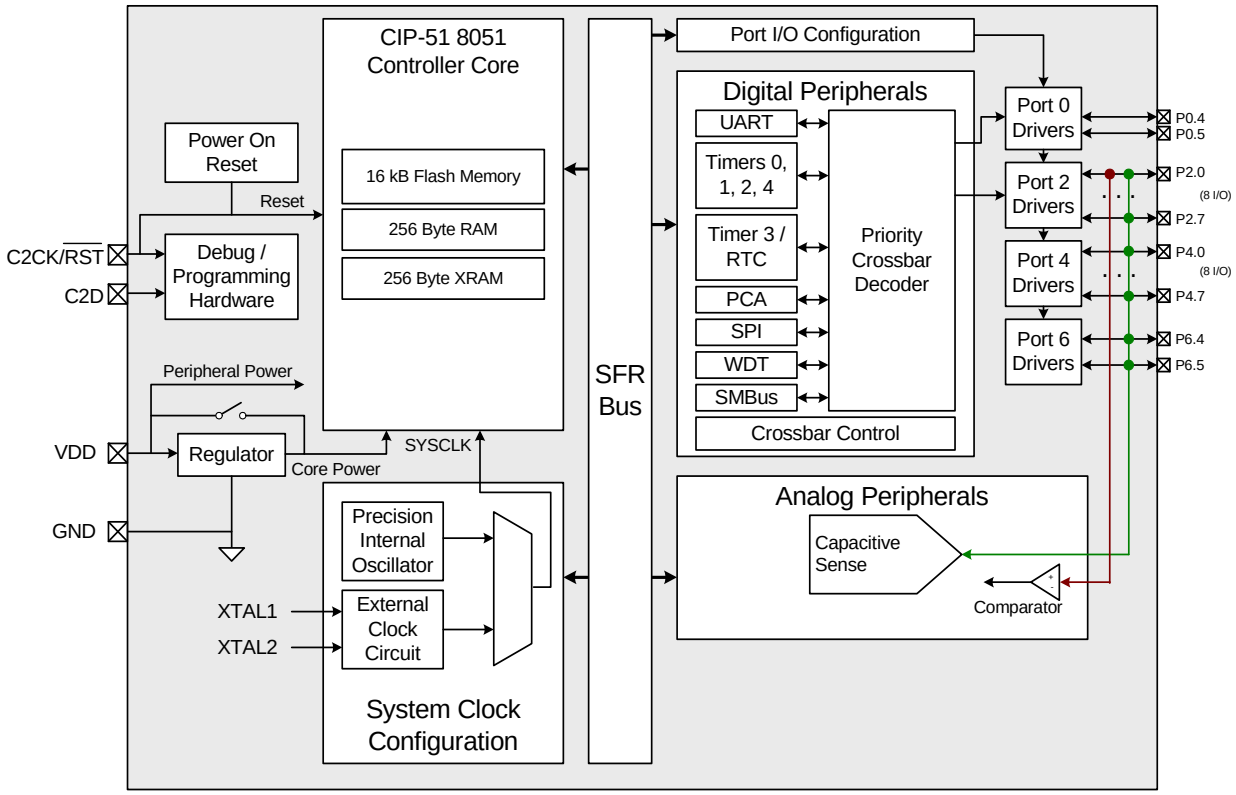

Figure 1.8. C8051F717 Block Diagram

4. TQFP-64 Package Specifications

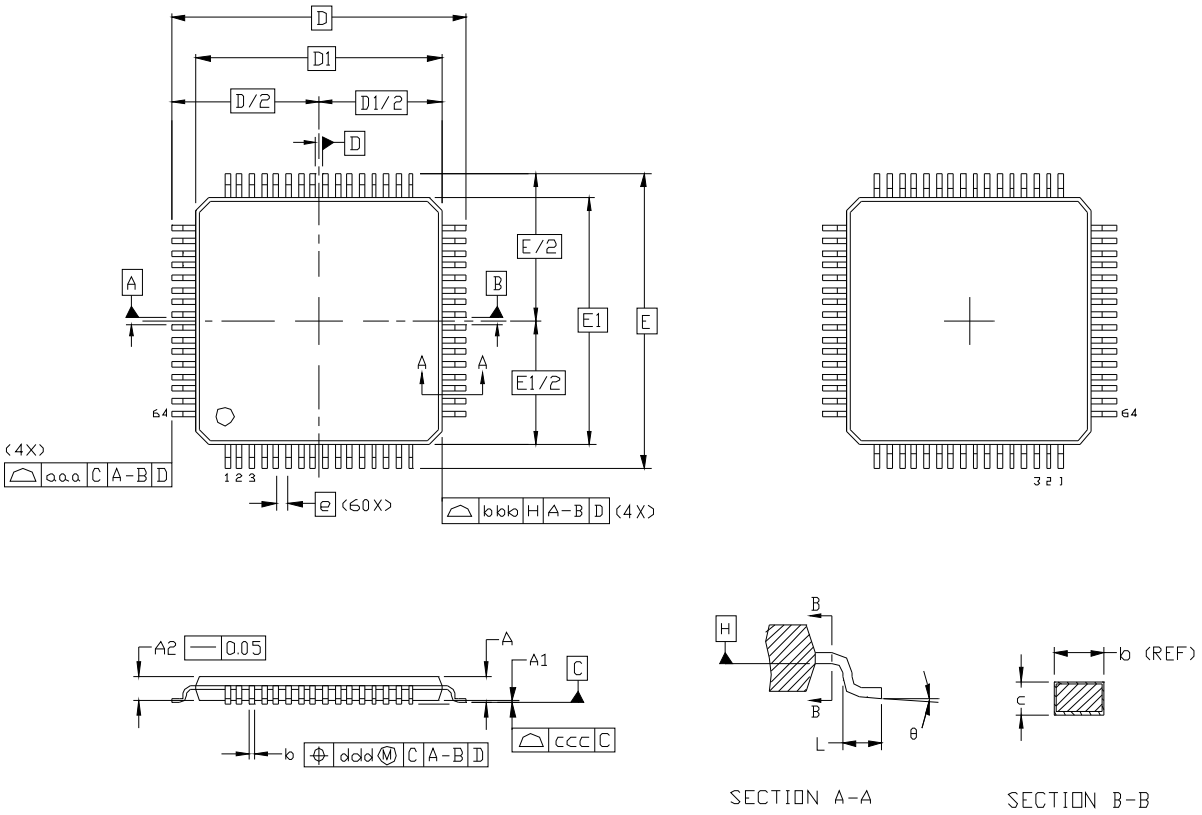

Figure 4.1. TQFP-64 Package Drawing

Table 4.1. TQFP-64 Package Dimensions

Dimension	Min	Nom	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.17	0.22	0.27
c	0.09	—	0.20
D	12.00 BSC.		
D1	10.00 BSC.		
e	0.50 BSC.		

Dimension	Min	Nom	Max
E	12.00 BSC.		
E1	10.00 BSC.		
L	0.45	0.60	0.75
aaa	—	—	0.20
bbb	—	—	0.20
ccc	—	—	0.08
ddd	—	—	0.08
Θ	0°	3.5°	7°

Notes:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This package outline conforms to JEDEC MS-026, variant ACD.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

5. TQFP-48 Package Specifications

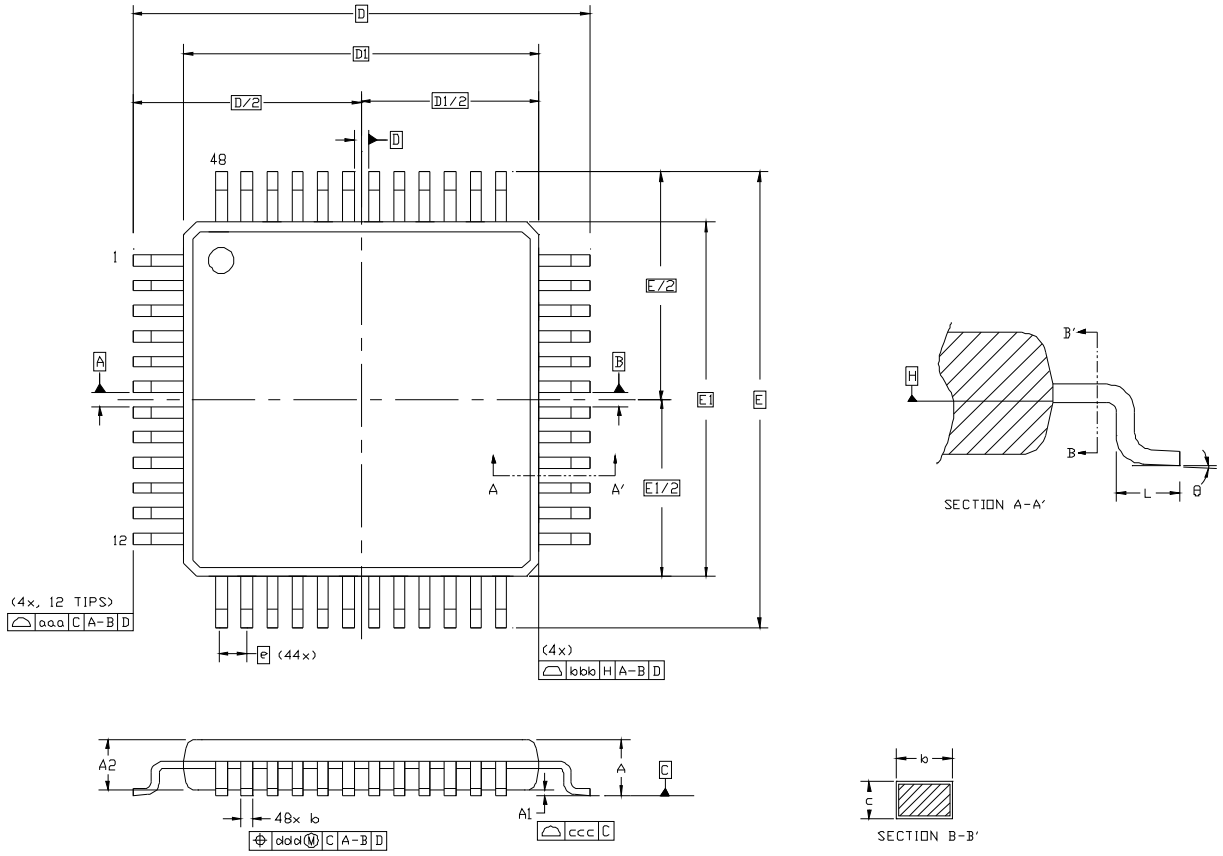

Figure 5.1. TQFP-48 Package Drawing

Table 5.1. TQFP-48 Package Dimensions

Dimension	Min	Nom	Max
A	—	—	1.20
A1	0.05	—	0.15
A2	0.95	1.00	1.05
b	0.17	0.22	0.27
c	0.09	—	0.20
D	9.00 BSC.		
D1	7.00 BSC.		
e	0.50 BSC.		

Dimension	Min	Nom	Max
E	9.00 BSC.		
E1	7.00 BSC.		
L	0.45	0.60	0.75
aaa	0.20		
bbb	0.20		
ccc	0.08		
ddd	0.08		
Θ	0°	3.5°	7°

Notes:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. This drawing conforms to JEDEC outline MS-026, variation ABC.
4. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

The Comparator response time may be configured in software via the CPT0MD register (see SFR Definition 14.2). Selecting a longer response time reduces the Comparator supply current.

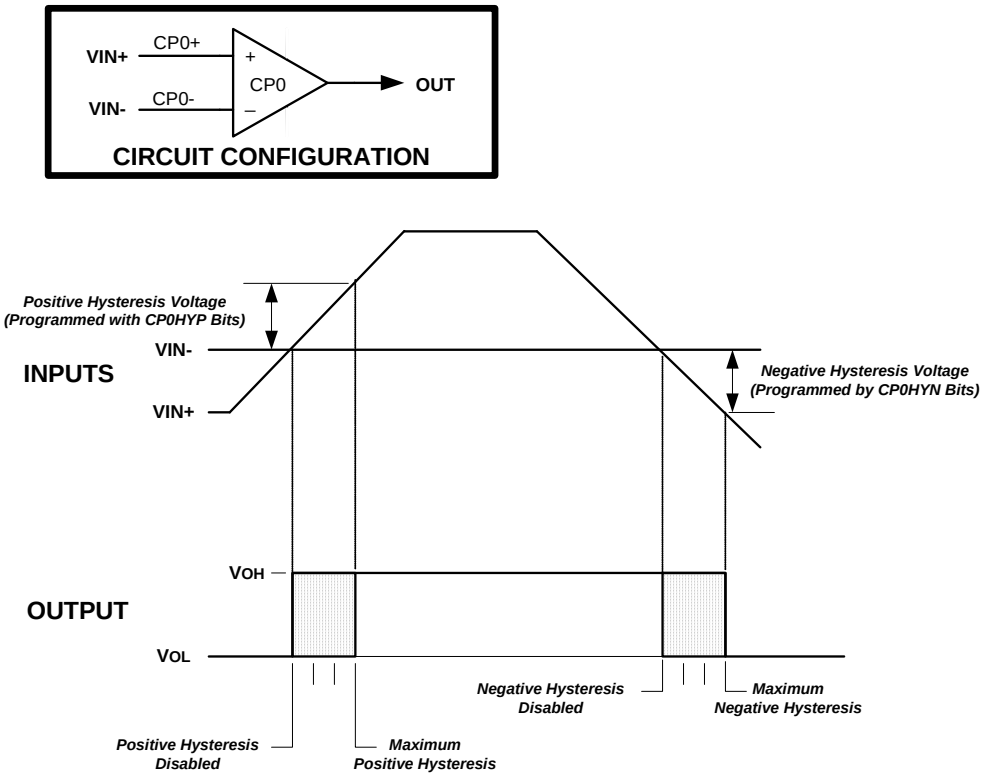

Figure 14.2. Comparator Hysteresis Plot

The Comparator hysteresis is software-programmable via its Comparator Control register CPT0CN. The user can program both the amount of hysteresis voltage (referred to the input voltage) and the positive and negative-going symmetry of this hysteresis around the threshold voltage.

The Comparator hysteresis is programmed using Bits3–0 in the Comparator Control Register CPT0CN (shown in SFR Definition 14.1). The amount of negative hysteresis voltage is determined by the settings of the CP0HYN bits. As shown in Figure 14.2, settings of 20, 10 or 5 mV of negative hysteresis can be programmed, or negative hysteresis can be disabled. In a similar way, the amount of positive hysteresis is determined by the setting the CP0HYP bits.

Comparator interrupts can be generated on both rising-edge and falling-edge output transitions. (For Interrupt enable and priority control, see Section “21.1. MCU Interrupt Sources and Vectors” on page 138). The CP0FIF flag is set to logic 1 upon a Comparator falling-edge occurrence, and the CP0RIF flag is set to logic 1 upon the Comparator rising-edge occurrence. Once set, these bits remain set until cleared by software. The Comparator rising-edge interrupt mask is enabled by setting CP0RIE to a logic 1. The Comparator0 falling-edge interrupt mask is enabled by setting CP0FIE to a logic 1.

The output state of the Comparator can be obtained at any time by reading the CP0OUT bit. The Comparator is enabled by setting the CP0EN bit to logic 1, and is disabled by clearing this bit to logic 0.

Note that false rising edges and falling edges can be detected when the comparator is first powered on or if changes are made to the hysteresis or response time control bits. Therefore, it is recommended that the rising-edge and falling-edge flags be explicitly cleared to logic 0 a short time after the comparator is enabled or its mode bits have been changed.

SFR Definition 14.3. CPT0MX: Comparator0 MUX Selection

Bit	7	6	5	4	3	2	1	0
Name		CMX0N[2:0]				CMX0P[2:0]		
Type	R	R/W			R	R/W		
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x9F; SFR Page = 0

Bit	Name	Function				
7	Unused	Read = 0b; Write = don't care.				
6:4	CMX0N[2:0]	**Comparator0 Negative Input MUX Selection.**				
			64-Pin Devices	**48-Pin Devices**	**32-Pin Devices**	**24-Pin Devices**
		000	P1.1	P1.1	—	—
		001	P1.3	P1.3	—	—
		010	P1.5	—	—	—
		011	P1.7	—	P2.0 (see note)	P2.0 (see note)
		100-111	No input selected.	No input selected.	No input selected.	No input selected.
3	Unused	Read = 0b; Write = don't care.				
2:0	CMX0P[2:0]	**Comparator0 Positive Input MUX Selection.**				
			64-Pin Devices	**48-Pin Devices**	**32-Pin Devices**	**24-Pin Devices**
		000	P1.0	P1.0	—	—
		001	P1.2	P1.2	—	—
		010	P1.4	—	—	—
		011	P1.6	—	(P1.6—see note)	(P1.6—see note)
		100-111	No input selected.	No input selected.	No input selected.	No input selected.

Note: On 32 and 24-pin devices, P2.0 can be used as the negative comparator input, for detecting low-level signals near the GND or VDD supply rails. The P1.6 setting for the positive input should be used in conjunction with the selection of P2.0 as the negative input. P1.6 should be configured for push-pull mode and driven to the desired supply rail. Although P1.6 is not connected to a device pin in these packages, it is still a valid signal internally.

SFR Definition 15.11. CS0MD2: Capacitive Sense Mode 2

Bit	7	6	5	4	3	2	1	0
Name	CS0CR[1:0]		CS0DT[2:0]			CS0IA[2:0]		
Type	R/W		R/W			R/W		
Reset	0	1	0	0	0	0	0	0

SFR Address = 0xBE; SFR Page = F

Bit	Name	Description
7:6	CS0CR[1:0]	**CS0 Conversion Rate.** These bits control the conversion rate of the CS0 module. See the electrical specifications table for specific timing. 00: Conversions last 12 internal CS0 clocks and are 12 bits in length. 01: Conversions last 13 internal CS0 clocks and are 13 bits in length. 10: Conversions last 14 internal CS0 clocks and are 14 bits in length. 11: Conversions last 16 internal CS0 clocks.and are 16 bits in length.
5:3	CS0DT[2:0]	**CS0 Discharge Time.** These bits adjust the primary CS0 reset time. For most touch-sensitive switches, the default (fastest) value is sufficient, and these bits should not be modified. 000: Discharge time is 0.75 µs (recommended for most switches) 001: Discharge time is 1.0 µs 010: Discharge time is 1.2 µs 011: Discharge time is 1.5 µs 100: Discharge time is 2 µs 101: Discharge time is 3 µs 110: Discharge time is 6 µs 111: Discharge time is 12 µs
2:0	CS0IA[2:0]	**CS0 Output Current Adjustment.** These bits allow the user to adjust the output current used to charge up the capacitive sensor element. For most touch-sensitive switches, the default (highest) current is sufficient, and these bits should not be modified. 000: Full Current (recommended for most switches) 001: 1/8 Current 010: 1/4 Current 011: 3/8 Current 100: 1/2 Current 101: 5/8 Current 110: 3/4 Current 111: 7/8 Current

Table 20.2. Special Function Registers (Continued)

SFRs are listed in alphabetical order. All undefined SFR locations are reserved

Register	Address	Page	Description	Page
PCA0CPM0	0xDA	F	PCA Module 0 Mode Register	298
PCA0CPM1	0xDB	F	PCA Module 1 Mode Register	298
PCA0CPM2	0xDC	F	PCA Module 2 Mode Register	298
PCA0H	0xFA	0	PCA Counter High	299
PCA0L	0xF9	0	PCA Counter Low	299
PCA0MD	0xED	F	PCA Mode	296
PCA0PWM	0xA1	F	PCA PWM Configuration	297
PCON	0x87	All Pages	Power Control	162
PSCTL	0x8F	All Pages	Program Store R/W Control	153
PSW	0xD0	All Pages	Program Status Word	107
REF0CN	0xD2	F	Voltage Reference Control	71
REG0CN	0xB9	F	Voltage Regulator Control	73
REVID	0xAD	F	Revision ID	129
RSTSRC	0xEF	All Pages	Reset Source Configuration/Status	168
SBUF0	0x99	All Pages	UART0 Data Buffer	260
SCON0	0x98	All Pages	UART0 Control	259
SFRPAGE	0xA7	All Pages	SFR Page	132
SMB0ADM	0xBB	F	SMBus Slave Address mask	230
SMB0ADR	0xBA	F	SMBus Slave Address	229
SMB0CF	0xC1	0	SMBus Configuration	225
SMB0CN	0xC0	All Pages	SMBus Control	227
SMB0DAT	0xC2	0	SMBus Data	231
SP	0x81	All Pages	Stack Pointer	105
SPI0CFG	0xA1	0	SPI0 Configuration	248
SPI0CKR	0xA2	F	SPI0 Clock Rate Control	250
SPI0CN	0xF8	All Pages	SPI0 Control	249
SPI0DAT	0xA3	0	SPI0 Data	250
TCON	0x88	All Pages	Timer/Counter Control	268
TH0	0x8C	All Pages	Timer/Counter 0 High	271
TH1	0x8D	All Pages	Timer/Counter 1 High	271
TL0	0x8A	All Pages	Timer/Counter 0 Low	270
TL1	0x8B	All Pages	Timer/Counter 1 Low	270
TMOD	0x89	All Pages	Timer/Counter Mode	269
TMR2CN	0xC8	All Pages	Timer/Counter 2 Control	275
TMR2H	0xCD	0	Timer/Counter 2 High	277
TMR2L	0xCC	0	Timer/Counter 2 Low	277
TMR2RLH	0xCB	0	Timer/Counter 2 Reload High	276
TMR2RLL	0xCA	0	Timer/Counter 2 Reload Low	276

SFR Definition 21.3. EIE1: Extended Interrupt Enable 1

Bit	7	6	5	4	3	2	1	0
Name	ET3	Reserved	ECP0	EPCA0	EADC0	EWADC0	EMAT	ESMB0
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xE6; SFR Page = All Pages

Bit	Name	Function
7	ET3	**Enable Timer 3 Interrupt.** This bit sets the masking of the Timer 3 interrupt. 0: Disable Timer 3 interrupt. 1: Enable interrupt requests generated by the TF3L or TF3H flags.
6	Reserved	Must write 0.
5	ECP0	**Enable Comparator0 (CP0) Interrupt.** This bit sets the masking of the CP0 rising edge or falling edge interrupt. 0: Disable CP0 interrupts. 1: Enable interrupt requests generated by the CP0RIF and CP0FIF flags.
4	EPCA0	**Enable Programmable Counter Array (PCA0) Interrupt.** This bit sets the masking of the PCA0 interrupts. 0: Disable all PCA0 interrupts. 1: Enable interrupt requests generated by PCA0.
3	EADC0	**Enable ADC0 Conversion Complete Interrupt.** This bit sets the masking of the ADC0 Conversion Complete interrupt. 0: Disable ADC0 Conversion Complete interrupt. 1: Enable interrupt requests generated by the AD0INT flag.
2	EWADC0	**Enable Window Comparison ADC0 interrupt.** This bit sets the masking of ADC0 Window Comparison interrupt. 0: Disable ADC0 Window Comparison interrupt. 1: Enable interrupt requests generated by ADC0 Window Compare flag (AD0WINT).
1	EMAT	**Enable Port Match Interrupts.** This bit sets the masking of the Port Match event interrupt. 0: Disable all Port Match interrupts. 1: Enable interrupt requests generated by a Port Match.
0	ESMB0	**Enable SMBus (SMB0) Interrupt.** This bit sets the masking of the SMB0 interrupt. 0: Disable all SMB0 interrupts. 1: Enable interrupt requests generated by SMB0.

SFR Definition 22.1. PSCTL: Program Store R/W Control

Bit	7	6	5	4	3	2	1	0
Name							PSEE	PSWE
Type	R	R	R	R	R	R	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address =0x8F; SFR Page = All Pages

Bit	Name	Function
7:2	Unused	Read = 000000b, Write = don't care.
1	PSEE	**Program Store Erase Enable.** Setting this bit (in combination with PSWE) allows an entire page of Flash program memory to be erased. If this bit is logic 1 and Flash writes are enabled (PSWE is logic 1), a write to Flash memory using the MOVX instruction will erase the entire page that contains the location addressed by the MOVX instruction. The value of the data byte written does not matter. 0: Flash program memory erasure disabled. 1: Flash program memory erasure enabled.
0	PSWE	**Program Store Write Enable.** Setting this bit allows writing a byte of data to the Flash program memory using the MOVX write instruction. The Flash location should be erased before writing data. 0: Writes to Flash program memory disabled. 1: Writes to Flash program memory enabled; the MOVX write instruction targets Flash memory.

SFR Definition 22.2. FLKEY: Flash Lock and Key

Bit	7	6	5	4	3	2	1	0
Name	FLKEY[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xB7; SFR Page = All Pages

Bit	Name	Function
7:0	FLKEY[7:0]	**Flash Lock and Key Register.** Write: This register provides a lock and key function for Flash erasures and writes. Flash writes and erases are enabled by writing 0xA5 followed by 0xF1 to the FLKEY register. Flash writes and erases are automatically disabled after the next write or erase is complete. If any writes to FLKEY are performed incorrectly, or if a Flash write or erase operation is attempted while these operations are disabled, the Flash will be permanently locked from writes or erasures until the next device reset. If an application never writes to Flash, it can intentionally lock the Flash by writing a non-0xA5 value to FLKEY from software. Read: When read, bits 1–0 indicate the current Flash lock state. 00: Flash is write/erase locked. 01: The first key code has been written (0xA5). 10: Flash is unlocked (writes/erases allowed). 11: Flash writes/erases disabled until the next reset.

26. Watchdog Timer

The MCU includes a programmable Watchdog Timer (WDT) running off the system clock. A WDT overflow will force the MCU into the reset state. To prevent the reset, the WDT must be restarted by application software before overflow. If the system experiences a software or hardware malfunction preventing the software from restarting the WDT, the WDT will overflow and cause a reset.

Following a reset the WDT is automatically enabled and running with the default maximum time interval. If desired the WDT can be disabled by system software or locked on to prevent accidental disabling. Once locked, the WDT cannot be disabled until the next system reset. The state of the /RST pin is unaffected by this reset.

The WDT consists of a 21-bit timer running from the programmed system clock. The timer measures the period between specific writes to its control register. If this period exceeds the programmed limit, a WDT reset is generated. The WDT can be enabled and disabled as needed in software, or can be permanently enabled if desired. Watchdog features are controlled via the Watchdog Timer Control Register (WDTCN) shown in SFR Definition 26.1.

26.1. Enable/Reset WDT

The watchdog timer is both enabled and reset by writing 0xA5 to the WDTCN register. The user's application software should include periodic writes of 0xA5 to WDTCN as needed to prevent a watchdog timer overflow. The WDT is enabled and reset as a result of any system reset.

26.2. Disable WDT

Writing 0xDE followed by 0xAD to the WDTCN register disables the WDT. The following code segment illustrates disabling the WDT:

```
CLR EA           ; disable all interrupts
MOV WDTCN,#0DEh  ; disable software watchdog timer
MOV WDTCN,#0ADh
SETB EA          ; re-enable interrupts
```

The writes of 0xDE and 0xAD must occur within 4 clock cycles of each other, or the disable operation is ignored. Interrupts should be disabled during this procedure to avoid delay between the two writes.

26.3. Disable WDT Lockout

Writing 0xFF to WDTCN locks out the disable feature. Once locked out, the disable operation is ignored until the next system reset. Writing 0xFF does not enable or reset the watchdog timer. Applications always intending to use the watchdog should write 0xFF to WDTCN in the initialization code.

26.4. Setting WDT Interval

WDTCN.[2:0] control the watchdog timeout interval. The interval is given by the following equation:

4^(3+WDTCN[2-0]) x Tsysclk ;where T_{sysclk} is the system clock period.

For a 3 MHz system clock, this provides an interval range of 0.021 to 349.5 ms. WDTCN.7 must be logic 0 when setting this interval. Reading WDTCN returns the programmed interval. WDTCN.[2:0] reads 111b after a system reset.

SFR Definition 27.1. CLKSEL: Clock Select

Bit	7	6	5	4	3	2	1	0
Name	CLKRDY	CLKDIV[2:0]			Reserved	CLKSEL[2:0]		
Type	R	R/W	R/W	R/W	R	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xBD; SFR Page= F

Bit	Name	Function
7	CLKRDY	**System Clock Divider Clock Ready Flag.** 0: The selected clock divide setting has not been applied to the system clock. 1: The selected clock divide setting has been applied to the system clock.
6:4	CLKDIV	**System Clock Divider Bits.** Selects the clock division to be applied to the selected source (internal or external). 000: Selected clock is divided by 1. 001: Selected clock is divided by 2. 010: Selected clock is divided by 4. 011: Selected clock is divided by 8. 100: Selected clock is divided by 16. 101: Selected clock is divided by 32. 110: Selected clock is divided by 64. 111: Selected clock is divided by 128.
3	Reserved	Read = 0b. Must write 0b.
2:0	CLKSEL[2:0]	**System Clock Select.** Selects the oscillator to be used as the undivided system clock source. 000: Internal Oscillator 001: External Oscillator All other values reserved.

SFR Definition 28.2. XBR1: Port I/O Crossbar Register 1

Bit	7	6	5	4	3	2	1	0
Name	WEAKPUD	XBARE	T1E	T0E	ECIE		PCA0ME[1:0]	
Type	R/W	R/W	R/W	R/W	R/W	R	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xE2; SFR Page = F

Bit	Name	Function
7	WEAKPUD	**Port I/O Weak Pullup Disable.** 0: Weak Pullups enabled (except for Ports whose I/O are configured for analog mode). 1: Weak Pullups disabled.
6	XBARE	**Crossbar Enable.** 0: Crossbar disabled. 1: Crossbar enabled.
5	T1E	**T1 Enable.** 0: T1 unavailable at Port pin. 1: T1 routed to Port pin.
4	T0E	**T0 Enable.** 0: T0 unavailable at Port pin. 1: T0 routed to Port pin.
3	ECIE	**PCA0 External Counter Input Enable.** 0: ECI unavailable at Port pin. 1: ECI routed to Port pin.
2	Unused	Read = 0b; Write = Don't Care.
1:0	PCA0ME[1:0]	**PCA Module I/O Enable Bits.** 00: All PCA I/O unavailable at Port pins. 01: CEX0 routed to Port pin. 10: CEX0, CEX1 routed to Port pins. 11: CEX0, CEX1, CEX2 routed to Port pins.

30.1. Supporting Documents

It is assumed the reader is familiar with or has access to the following supporting documents:

1. The I2C-Bus and How to Use It (including specifications), Philips Semiconductor.
2. The I2C-Bus Specification—Version 2.0, Philips Semiconductor.
3. System Management Bus Specification—Version 1.1, SBS Implementers Forum.

30.2. SMBus Configuration

Figure 30.2 shows a typical SMBus configuration. The SMBus specification allows any recessive voltage between 3.0 V and 5.0 V; different devices on the bus may operate at different voltage levels. The bi-directional SCL (serial clock) and SDA (serial data) lines must be connected to a positive power supply voltage through a pullup resistor or similar circuit. Every device connected to the bus must have an open-drain or open-collector output for both the SCL and SDA lines, so that both are pulled high (recessive state) when the bus is free. The maximum number of devices on the bus is limited only by the requirement that the rise and fall times on the bus not exceed 300 ns and 1000 ns, respectively.

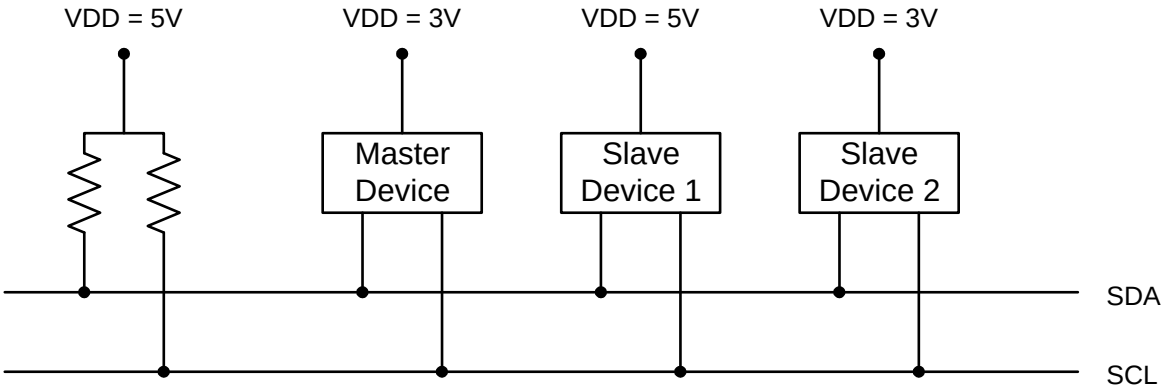

Figure 30.2. Typical SMBus Configuration

30.3. SMBus Operation

Two types of data transfers are possible: data transfers from a master transmitter to an addressed slave receiver (WRITE), and data transfers from an addressed slave transmitter to a master receiver (READ). The master device initiates both types of data transfers and provides the serial clock pulses on SCL. The SMBus interface may operate as a master or a slave, and multiple master devices on the same bus are supported. If two or more masters attempt to initiate a data transfer simultaneously, an arbitration scheme is employed with a single master always winning the arbitration. It is not necessary to specify one device as the Master in a system; any device who transmits a START and a slave address becomes the master for the duration of that transfer.

A typical SMBus transaction consists of a START condition followed by an address byte (Bits7–1: 7-bit slave address; Bit0: R/W direction bit), one or more bytes of data, and a STOP condition. Bytes that are received (by a master or slave) are acknowledged (ACK) with a low SDA during a high SCL (see Figure 30.3). If the receiving device does not ACK, the transmitting device will read a NACK (not acknowledge), which is a high SDA during a high SCL.

The direction bit (R/W) occupies the least-significant bit position of the address byte. The direction bit is set to logic 1 to indicate a "READ" operation and cleared to logic 0 to indicate a "WRITE" operation.

case, either a 1 or a 0 value are acceptable on the incoming slave address. Additionally, if the GC bit in register SMB0ADR is set to 1, hardware will recognize the General Call Address (0x00). Table 30.4 shows some example parameter settings and the slave addresses that will be recognized by hardware under those conditions.

Table 30.4. Hardware Address Recognition Examples (EHACK = 1)

Hardware Slave Address SLV[6:0]	Slave Address Mask SLVM[6:0]	GC bit	Slave Addresses Recognized by Hardware
0x34	0x7F	0	0x34
0x34	0x7F	1	0x34, 0x00 (General Call)
0x34	0x7E	0	0x34, 0x35
0x34	0x7E	1	0x34, 0x35, 0x00 (General Call)
0x70	0x73	0	0x70, 0x74, 0x78, 0x7C

SFR Definition 30.3. SMB0ADR: SMBus Slave Address

Bit	7	6	5	4	3	2	1	0
Name	SLV[6:0]							GC
Type	R/W							R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xBA; SFR Page = F

Bit	Name	Function
7:1	SLV[6:0]	**SMBus Hardware Slave Address.** Defines the SMBus Slave Address(es) for automatic hardware acknowledgement. Only address bits which have a 1 in the corresponding bit position in SLVM[6:0] are checked against the incoming address. This allows multiple addresses to be recognized.
0	GC	**General Call Address Enable.** When hardware address recognition is enabled (EHACK = 1), this bit will determine whether the General Call Address (0x00) is also recognized by hardware. 0: General Call Address is ignored. 1: General Call Address is recognized.

30.5.2. Read Sequence (Master)

During a read sequence, an SMBus master reads data from a slave device. The master in this transfer will be a transmitter during the address byte, and a receiver during all data bytes. The SMBus interface generates the START condition and transmits the first byte containing the address of the target slave and the data direction bit. In this case the data direction bit (R/W) will be logic 1 (READ). Serial data is then received from the slave on SDA while the SMBus outputs the serial clock. The slave transmits one or more bytes of serial data.

If hardware ACK generation is disabled, the ACKRQ is set to 1 and an interrupt is generated after each received byte. Software must write the ACK bit at that time to ACK or NACK the received byte.

With hardware ACK generation enabled, the SMBus hardware will automatically generate the ACK/NACK, and then post the interrupt. **It is important to note that the appropriate ACK or NACK value should be set up by the software prior to receiving the byte when hardware ACK generation is enabled.**

Writing a 1 to the ACK bit generates an ACK; writing a 0 generates a NACK. Software should write a 0 to the ACK bit for the last data transfer, to transmit a NACK. The interface exits Master Receiver Mode after the STO bit is set and a STOP is generated. The interface will switch to Master Transmitter Mode if SMB0DAT is written while an active Master Receiver. Figure 30.6 shows a typical master read sequence. Two received data bytes are shown, though any number of bytes may be received. Notice that the ‘data byte transferred’ interrupts occur at different places in the sequence, depending on whether hardware ACK generation is enabled. The interrupt occurs **before** the ACK with hardware ACK generation disabled, and **after** the ACK when hardware ACK generation is enabled.

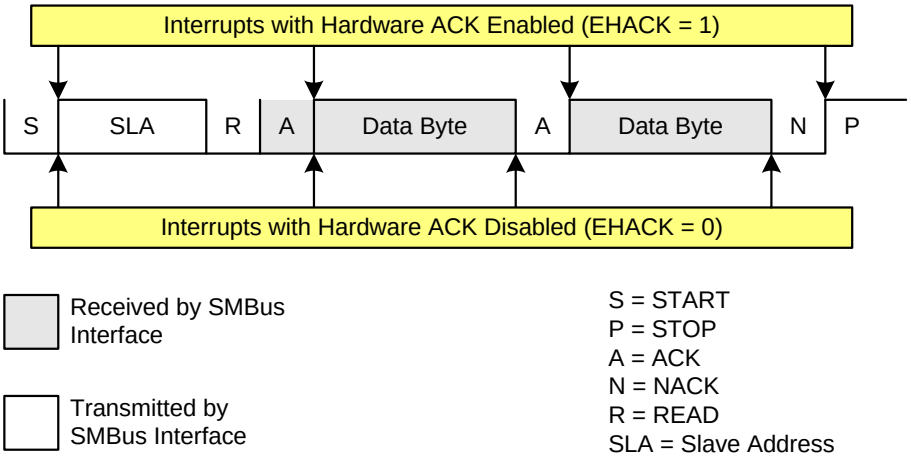

Figure 30.6. Typical Master Read Sequence

32.1. Enhanced Baud Rate Generation

The UART0 baud rate is generated by Timer 1 in 8-bit auto-reload mode. The TX clock is generated by TL1; the RX clock is generated by a copy of TL1 (shown as RX Timer in Figure 32.2), which is not user-accessible. Both TX and RX Timer overflows are divided by two to generate the TX and RX baud rates. The RX Timer runs when Timer 1 is enabled, and uses the same reload value (TH1). However, an RX Timer reload is forced when a START condition is detected on the RX pin. This allows a receive to begin any time a START is detected, independent of the TX Timer state.

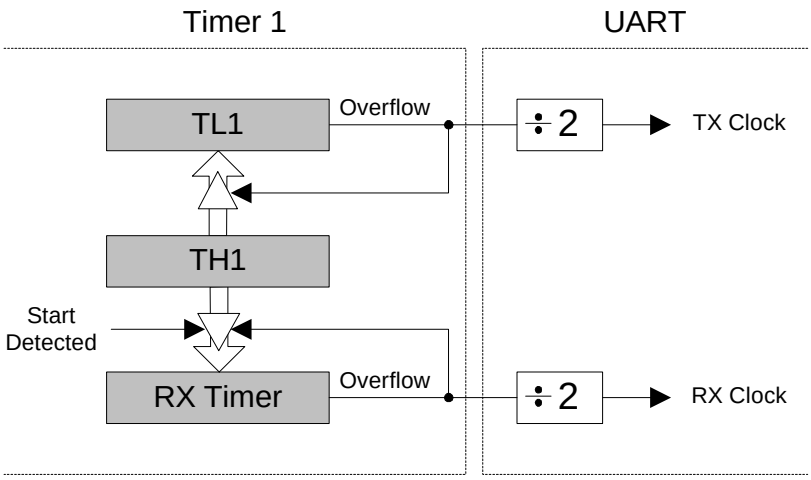

Figure 32.2. UART0 Baud Rate Logic

Timer 1 should be configured for Mode 2, 8-bit auto-reload (see Section “33.1.3. Mode 2: 8-bit Counter/Timer with Auto-Reload” on page 265). The Timer 1 reload value should be set so that overflows will occur at two times the desired UART baud rate frequency. Timer 1 may be clocked by one of six sources: SYSCLK, SYSCLK/4, SYSCLK/12, SYSCLK/48, the external oscillator clock/8, or an external input T1. For any given Timer 1 clock source, the UART0 baud rate is determined by Equation 32.1-A and Equation 32.1-B.

A) $$\text{UartBaudRate} = \frac{1}{2} \times \text{T1\_Overflow\_Rate}$$

B) $$\text{T1\_Overflow\_Rate} = \frac{\text{T1}_{\text{CLK}}}{256 - \text{TH1}}$$

Equation 32.1. UART0 Baud Rate

Where $T1_{CLK}$ is the frequency of the clock supplied to Timer 1, and *T1H* is the high byte of Timer 1 (reload value). Timer 1 clock frequency is selected as described in Section “33. Timers” on page 262. A quick reference for typical baud rates and system clock frequencies is given in Table 32.1 through Table 32.2. The internal oscillator may still generate the system clock when the external oscillator is driving Timer 1.

Table 34.2. PCA0CPM and PCA0PWM Bit Settings for PCA Modules

Operational Mode	PCA0CPMn								PCA0PWM				
Bit Number	7	6	5	4	3	2	1	0	7	6	5	4:2	1:0
Capture triggered by positive edge on CEXn	X	X	1	0	0	0	0	A	0	X	B	XXX	XX
Capture triggered by negative edge on CEXn	X	X	0	1	0	0	0	A	0	X	B	XXX	XX
Capture triggered by any transition on CEXn	X	X	1	1	0	0	0	A	0	X	B	XXX	XX
Software Timer	X	C	0	0	1	0	0	A	0	X	B	XXX	XX
High Speed Output	X	C	0	0	1	1	0	A	0	X	B	XXX	XX
Frequency Output	X	C	0	0	0	1	1	A	0	X	B	XXX	XX
8-Bit Pulse Width Modulator (Note 7)	0	C	0	0	E	0	1	A	0	X	B	XXX	00
9-Bit Pulse Width Modulator (Note 7)	0	C	0	0	E	0	1	A	D	X	B	XXX	01
10-Bit Pulse Width Modulator (Note 7)	0	C	0	0	E	0	1	A	D	X	B	XXX	10
11-Bit Pulse Width Modulator (Note 7)	0	C	0	0	E	0	1	A	D	X	B	XXX	11
16-Bit Pulse Width Modulator	1	C	0	0	E	0	1	A	0	X	B	XXX	XX

Notes:

1. X = Don't Care (no functional difference for individual module if 1 or 0).
2. A = Enable interrupts for this module (PCA interrupt triggered on CCFn set to 1).
3. B = Enable 8th, 9th, 10th or 11th bit overflow interrupt (Depends on setting of CLSEL[1:0]).
4. C = When set to 0, the digital comparator is off. For high speed and frequency output modes, the associated pin will not toggle. In any of the PWM modes, this generates a 0% duty cycle (output = 0).
5. D = Selects whether the Capture/Compare register (0) or the Auto-Reload register (1) for the associated channel is accessed via addresses PCA0CPHn and PCA0CPLn.
6. E = When set, a match event will cause the CCFn flag for the associated channel to be set.
7. All modules set to 8, 9, 10 or 11-bit PWM mode use the same cycle length setting.

35.2. C2CK Pin Sharing

The C2CK pin is shared with the $\overline{\text{RST}}$ signal on this device family. If the $\overline{\text{RST}}$ pin is used by other parts of the system, debugging and programming the device can still be accomplished without disrupting the rest of the system. If this is desired, it is normally necessary to add a resistor to isolate the system's reset line from the C2CK signal. This external resistors would not be necessary for production boards, where debugging capabilities are not needed. A typical isolation configuration is shown in Figure 35.1.

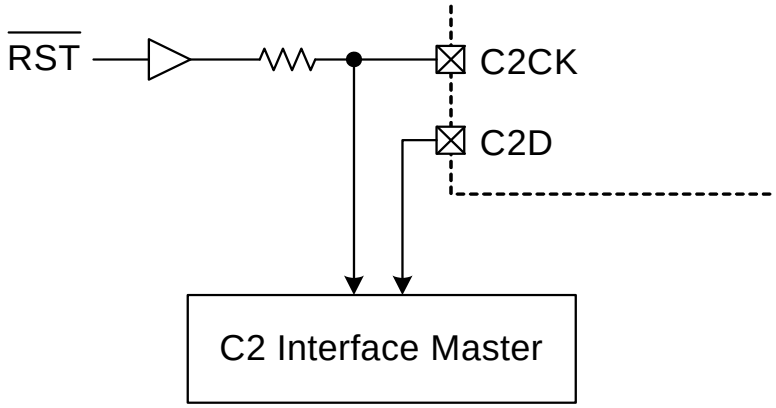

Figure 35.1. Typical C2CK Pin Sharing

The configuration in Figure 35.1 assumes the $\overline{\text{RST}}$ pin on the target device is used as an input only. Additional resistors may be necessary depending on the specific application.