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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)


Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	4713
Number of Logic Elements/Cells	75408
Total RAM Bits	2810880
Number of I/O	426
Number of Gates	-
Voltage - Supply	1.15V ~ 1.25V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	780-BGA
Supplier Device Package	780-FBGA (29x29)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep4ce75f29c6n">https://www.e-xfl.com/product-detail/intel/ep4ce75f29c6n</a>

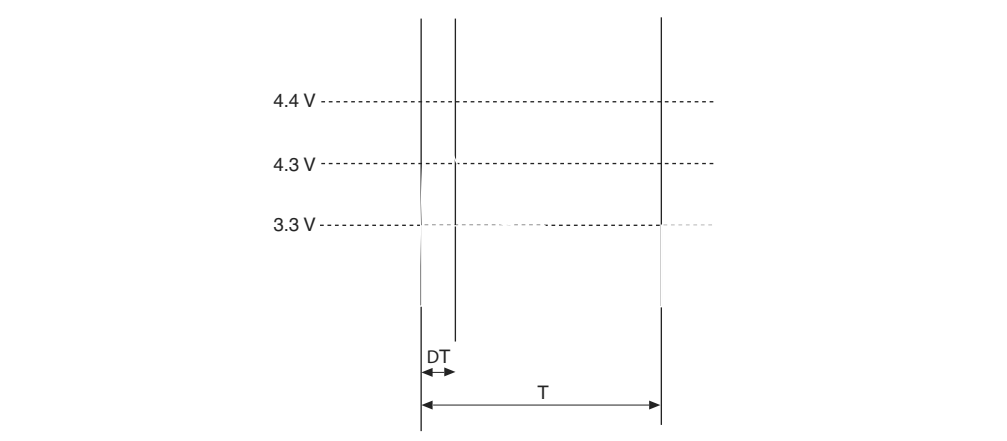
 A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

**Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices**

Symbol	Parameter	Condition (V)	Overshoot Duration as % of High Time	Unit
$V_i$	AC Input Voltage	$V_i = 4.20$	100	%
		$V_i = 4.25$	98	%
		$V_i = 4.30$	65	%
		$V_i = 4.35$	43	%
		$V_i = 4.40$	29	%
		$V_i = 4.45$	20	%
		$V_i = 4.50$	13	%
		$V_i = 4.55$	9	%
		$V_i = 4.60$	6	%

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as  $([\Delta T]/T) \times 100$ . This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

**Figure 1–1. Cyclone IV Devices Overshoot Duration**



## Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1)</sup>, <sup>(2)</sup> (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}^{(3)}$	Supply voltage for internal logic, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply voltage for internal logic, 1.0-V operation	—	0.97	1.0	1.03	V
$V_{CCIO}^{(3), (4)}$	Supply voltage for output buffers, 3.3-V operation	—	3.135	3.3	3.465	V
	Supply voltage for output buffers, 3.0-V operation	—	2.85	3	3.15	V
	Supply voltage for output buffers, 2.5-V operation	—	2.375	2.5	2.625	V
	Supply voltage for output buffers, 1.8-V operation	—	1.71	1.8	1.89	V
	Supply voltage for output buffers, 1.5-V operation	—	1.425	1.5	1.575	V
	Supply voltage for output buffers, 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCA}^{(3)}$	Supply (analog) voltage for PLL regulator	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}^{(3)}$	Supply (digital) voltage for PLL, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply (digital) voltage for PLL, 1.0-V operation	—	0.97	1.0	1.03	V
$V_I$	Input voltage	—	–0.5	—	3.6	V
$V_O$	Output voltage	—	0	—	$V_{CCIO}$	V
$T_J$	Operating junction temperature	For commercial use	0	—	85	°C
		For industrial use	–40	—	100	°C
		For extended temperature	–40	—	125	°C
		For automotive use	–40	—	125	°C
$t_{RAMP}$	Power supply ramp time	Standard power-on reset (POR) <sup>(5)</sup>	50 $\mu$ s	—	50 ms	—
		Fast POR <sup>(6)</sup>	50 $\mu$ s	—	3 ms	—

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1), (2)</sup> (Part 2 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{Diode}$	Magnitude of DC current across PCI-clamp diode when enable	—	—	—	10	mA

**Notes to Table 1–3:**

- (1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades.
- (2)  $V_{CCIO}$  for all I/O banks must be powered up during device operation. All  $V_{CCA}$  pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (3)  $V_{CC}$  must rise monotonically.
- (4)  $V_{CCIO}$  powers all input buffers.
- (5) The POR time for Standard POR ranges between 50 and 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) The POR time for Fast POR ranges between 3 and 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.

**Table 1–4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}$ <sup>(3)</sup>	Core voltage, PCIe hard IP block, and transceiver PCS power supply	—	1.16	1.2	1.24	V
$V_{CCA}$ <sup>(1), (3)</sup>	PLL analog power supply	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}$ <sup>(2)</sup>	PLL digital power supply	—	1.16	1.2	1.24	V
$V_{CCIO}$ <sup>(3), (4)</sup>	I/O banks power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	I/O banks power supply for 3.0-V operation	—	2.85	3	3.15	V
	I/O banks power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	I/O banks power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	I/O banks power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	I/O banks power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CC\_CLKIN}$ <sup>(3), (5), (6)</sup>	Differential clock input pins power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	Differential clock input pins power supply for 3.0-V operation	—	2.85	3	3.15	V
	Differential clock input pins power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	Differential clock input pins power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	Differential clock input pins power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	Differential clock input pins power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCH\_GXB}$	Transceiver output buffer power supply	—	2.375	2.5	2.625	V

**Table 1–7. Bus Hold Parameter for Cyclone IV Devices (Part 2 of 2) <sup>(1)</sup>**

Parameter	Condition	V <sub>CCIO</sub> (V)												Unit
		1.2		1.5		1.8		2.5		3.0		3.3		
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus hold trip point	—	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2	0.8	2	V

**Note to Table 1–7:**

(1) Bus hold trip points are based on the calculated input voltages from the JEDEC standard.

## OCT Specifications

Table 1–8 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

**Table 1–8. Series OCT Without Calibration Specifications for Cyclone IV Devices**

Description	$V_{CCIO}$ (V)	Resistance Tolerance		Unit
		Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	
Series OCT without calibration	3.0	±30	±40	%
	2.5	±30	±40	%
	1.8	±40	±50	%
	1.5	±50	±50	%
	1.2	±50	±50	%

OCT calibration is automatically performed at device power-up for OCT-enabled I/Os.

Table 1–9 lists the OCT calibration accuracy at device power-up.

**Table 1–9. Series OCT with Calibration at Device Power-Up Specifications for Cyclone IV Devices**

Description	$V_{CCIO}$ (V)	Calibration Accuracy		Unit
		Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	
Series OCT with calibration at device power-up	3.0	±10	±10	%
	2.5	±10	±10	%
	1.8	±10	±10	%
	1.5	±10	±10	%
	1.2	±10	±10	%

Example 1–1 shows how to calculate the change of 50-Ω I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V.

#### Example 1–1. Impedance Change

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because  $\Delta R_V$  is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because  $\Delta R_T$  is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{\text{final}} = 50 \times 1.114 = 55.71 \, \Omega$$

## Pin Capacitance

Table 1–11 lists the pin capacitance for Cyclone IV devices.

**Table 1–11. Pin Capacitance for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Typical – Quad Flat Pack (QFP)	Typical – Quad Flat No Leads (QFN)	Typical – Ball-Grid Array (BGA)	Unit
C <sub>IOTB</sub>	Input capacitance on top and bottom I/O pins	7	7	6	pF
C <sub>IOLR</sub>	Input capacitance on right I/O pins	7	7	5	pF
C <sub>LVDSLR</sub>	Input capacitance on right I/O pins with dedicated LVDS output	8	8	7	pF
C <sub>VREFLR</sub> (2)	Input capacitance on right dual-purpose V <sub>REF</sub> pin when used as V <sub>REF</sub> or user I/O pin	21	21	21	pF
C <sub>VREFTB</sub> (2)	Input capacitance on top and bottom dual-purpose V <sub>REF</sub> pin when used as V <sub>REF</sub> or user I/O pin	23 (3)	23	23	pF
C <sub>CLKTB</sub>	Input capacitance on top and bottom dedicated clock input pins	7	7	6	pF
C <sub>CLKLR</sub>	Input capacitance on right dedicated clock input pins	6	6	5	pF

#### Notes to Table 1–11:

- (1) The pin capacitance applies to FBGA, UBGA, and MBGA packages.
- (2) When you use the V<sub>REF</sub> pin as a regular input or output, you can expect a reduced performance of toggle rate and t<sub>CO</sub> because of higher pin capacitance.
- (3) C<sub>VREFTB</sub> for the EP4CE22 device is 30 pF.

## Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1-12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

**Table 1-12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
R <sub>PU</sub>	Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you enable the programmable pull-up resistor option	V <sub>CCIO</sub> = 3.3 V ± 5% <sup>(2), (3)</sup>	7	25	41	kΩ
		V <sub>CCIO</sub> = 3.0 V ± 5% <sup>(2), (3)</sup>	7	28	47	kΩ
		V <sub>CCIO</sub> = 2.5 V ± 5% <sup>(2), (3)</sup>	8	35	61	kΩ
		V <sub>CCIO</sub> = 1.8 V ± 5% <sup>(2), (3)</sup>	10	57	108	kΩ
		V <sub>CCIO</sub> = 1.5 V ± 5% <sup>(2), (3)</sup>	13	82	163	kΩ
		V <sub>CCIO</sub> = 1.2 V ± 5% <sup>(2), (3)</sup>	19	143	351	kΩ
R <sub>PD</sub>	Value of the I/O pin pull-down resistor before and during configuration	V <sub>CCIO</sub> = 3.3 V ± 5% <sup>(4)</sup>	6	19	30	kΩ
		V <sub>CCIO</sub> = 3.0 V ± 5% <sup>(4)</sup>	6	22	36	kΩ
		V <sub>CCIO</sub> = 2.5 V ± 5% <sup>(4)</sup>	6	25	43	kΩ
		V <sub>CCIO</sub> = 1.8 V ± 5% <sup>(4)</sup>	7	35	71	kΩ
		V <sub>CCIO</sub> = 1.5 V ± 5% <sup>(4)</sup>	8	50	112	kΩ

### Notes to Table 1-12:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V<sub>CCIO</sub>.
- (3)  $R_{PU} = (V_{CCIO} - V_I) / I_{R_{PU}}$   
Minimum condition: -40°C; V<sub>CCIO</sub> = V<sub>CC</sub> + 5%, V<sub>I</sub> = V<sub>CC</sub> + 5% - 50 mV;  
Typical condition: 25°C; V<sub>CCIO</sub> = V<sub>CC</sub>, V<sub>I</sub> = 0 V;  
Maximum condition: 100°C; V<sub>CCIO</sub> = V<sub>CC</sub> - 5%, V<sub>I</sub> = 0 V; in which V<sub>I</sub> refers to the input voltage at the I/O pin.
- (4)  $R_{PD} = V_I / I_{R_{PD}}$   
Minimum condition: -40°C; V<sub>CCIO</sub> = V<sub>CC</sub> + 5%, V<sub>I</sub> = 50 mV;  
Typical condition: 25°C; V<sub>CCIO</sub> = V<sub>CC</sub>, V<sub>I</sub> = V<sub>CC</sub> - 5%;  
Maximum condition: 100°C; V<sub>CCIO</sub> = V<sub>CC</sub> - 5%, V<sub>I</sub> = V<sub>CC</sub> - 5%; in which V<sub>I</sub> refers to the input voltage at the I/O pin.

## Hot-Socketing

Table 1-13 lists the hot-socketing specifications for Cyclone IV devices.

**Table 1-13. Hot-Socketing Specifications for Cyclone IV Devices**

Symbol	Parameter	Maximum
I <sub>IOPIN(DC)</sub>	DC current per I/O pin	300 μA
I <sub>IOPIN(AC)</sub>	AC current per I/O pin	8 mA <sup>(1)</sup>
I <sub>XCVRTX(DC)</sub>	DC current per transceiver TX pin	100 mA
I <sub>XCVRRX(DC)</sub>	DC current per transceiver RX pin	50 mA

### Note to Table 1-13:

- (1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |I<sub>IOPIN</sub>| = C dv/dt, in which C is the I/O pin capacitance and dv/dt is the slew rate.



During hot-socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF.

## Power Consumption

Use the following methods to estimate power for a design:

- the Excel-based EPE
- the Quartus® II PowerPlay power analyzer feature

The interactive Excel-based EPE is used prior to designing the device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, combined with detailed circuit models, can yield very accurate power estimates.



For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

## Switching Characteristics

This section provides performance characteristics of Cyclone IV core and periphery blocks for commercial grade devices.

These characteristics can be designated as Preliminary or Final.

- Preliminary characteristics are created using simulation results, process data, and other known parameters. The upper-right hand corner of these tables show the designation as “Preliminary”.
- Final numbers are based on actual silicon characterization and testing. The numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions. There are no designations on finalized tables.




## Transceiver Performance Specifications

Table 1-21 lists the Cyclone IV GX transceiver specifications.

**Table 1-21. Transceiver Specification for Cyclone IV GX Devices (Part 1 of 4)**

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Reference Clock											
Supported I/O Standards	1.2 V PCML, 1.5 V PCML, 3.3 V PCML, Differential LVPECL, LVDS, HCSL										
Input frequency from REFCLK input pins	—	50	—	156.25	50	—	156.25	50	—	156.25	MHz
Spread-spectrum modulating clock frequency	Physical interface for PCI Express (PIPE) mode	30	—	33	30	—	33	30	—	33	kHz
Spread-spectrum downspread	PIPE mode	—	0 to –0.5%	—	—	0 to –0.5%	—	—	0 to –0.5%	—	—
Peak-to-peak differential input voltage	—	0.1	—	1.6	0.1	—	1.6	0.1	—	1.6	V
V <sub>ICM</sub> (AC coupled)	—	1100 ± 5%			1100 ± 5%			1100 ± 5%			mV
V <sub>ICM</sub> (DC coupled)	HCSL I/O standard for PCIe reference clock	250	—	550	250	—	550	250	—	550	mV
Transmitter REFCLK Phase Noise <sup>(1)</sup>	Frequency offset = 1 MHz – 8 MHz	—	—	–123	—	—	–123	—	—	–123	dBc/Hz
Transmitter REFCLK Total Jitter <sup>(1)</sup>		—	—	42.3	—	—	42.3	—	—	42.3	ps
R <sub>ref</sub>	—	—	2000 ± 1%	—	—	2000 ± 1%	—	—	2000 ± 1%	—	Ω
Transceiver Clock											
cal_blk_clk clock frequency	—	10	—	125	10	—	125	10	—	125	MHz
fixedclk clock frequency	PCIe Receiver Detect	—	125	—	—	125	—	—	125	—	MHz
reconfig_clk clock frequency	Dynamic reconfiguration clock frequency	2.5/37.5 <sup>(2)</sup>	—	50	2.5/37.5 <sup>(2)</sup>	—	50	2.5/37.5 <sup>(2)</sup>	—	50	MHz
Delta time between reconfig_clk	—	—	—	2	—	—	2	—	—	2	ms
Transceiver block minimum power-down pulse width	—	—	1	—	—	1	—	—	1	—	μs

Figure 1-2 shows the lock time parameters in manual mode.

 LTD = lock-to-data. LTR = lock-to-reference.

**Figure 1-2. Lock Time Parameters for Manual Mode**

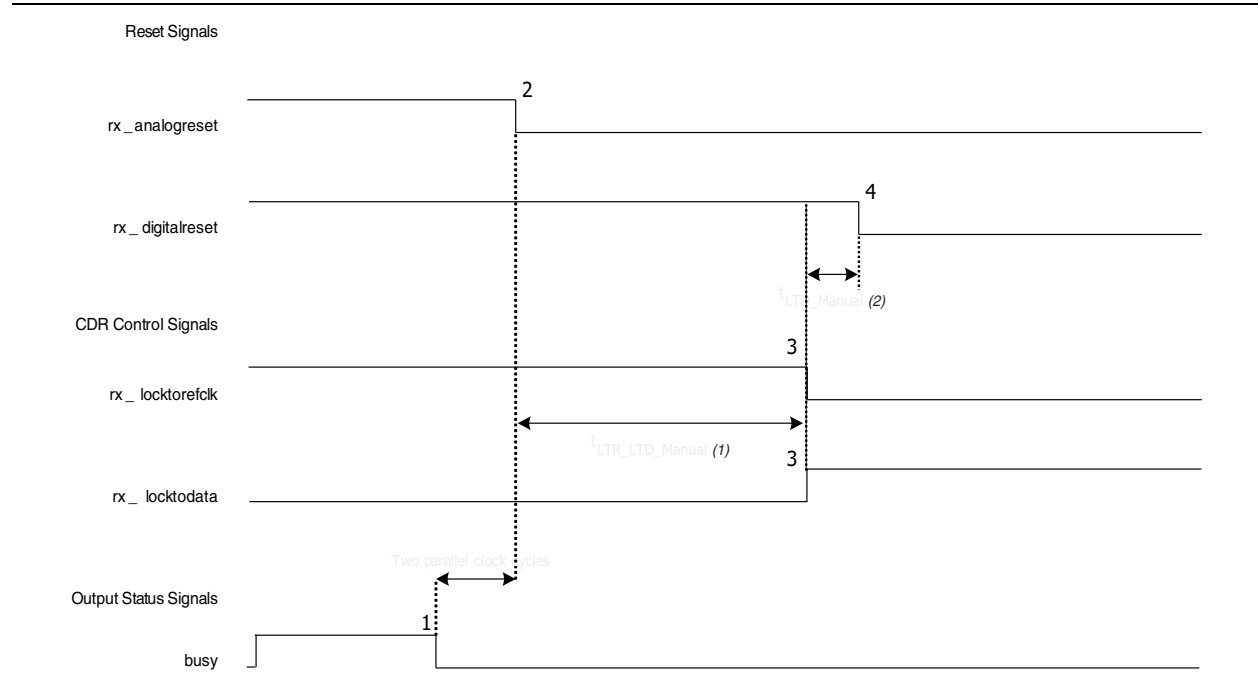


Figure 1-3 shows the lock time parameters in automatic mode.

**Figure 1-3. Lock Time Parameters for Automatic Mode**

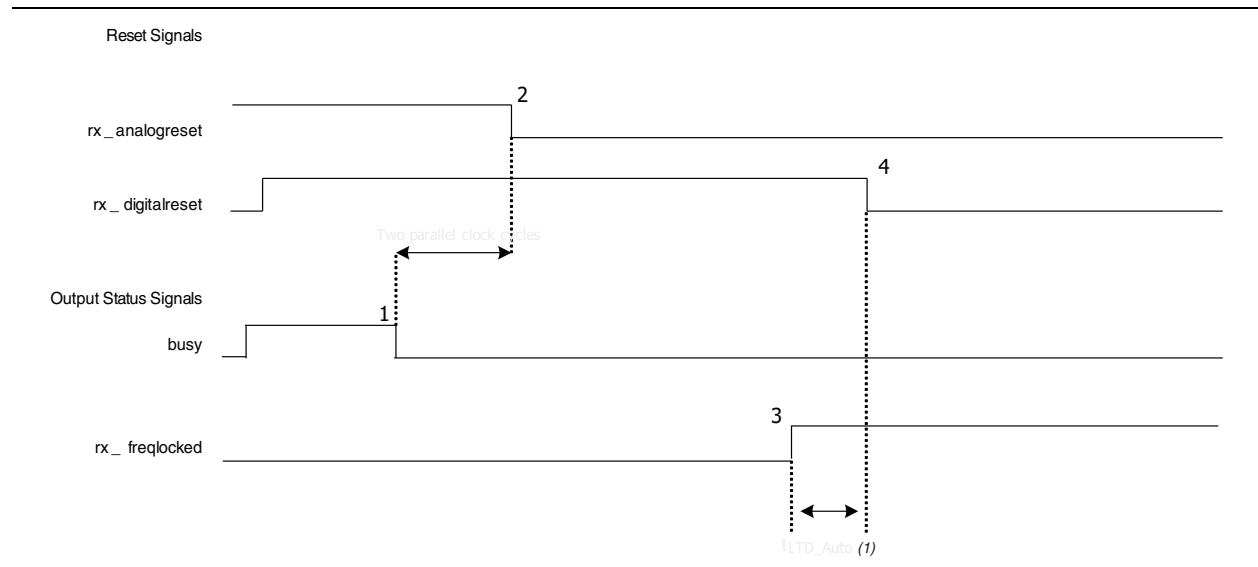


Table 1–23 lists the Cyclone IV GX transceiver block AC specifications.

**Table 1–23. Transceiver Block AC Specification for Cyclone IV GX Devices <sup>(1), (2)</sup>**

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
PCIe Transmit Jitter Generation <sup>(3)</sup>											
Total jitter at 2.5 Gbps (Gen1)	Compliance pattern	—	—	0.25	—	—	0.25	—	—	0.25	UI
PCIe Receiver Jitter Tolerance <sup>(3)</sup>											
Total jitter at 2.5 Gbps (Gen1)	Compliance pattern	> 0.6			> 0.6			> 0.6			UI
GIGE Transmit Jitter Generation <sup>(4)</sup>											
Deterministic jitter (peak-to-peak)	Pattern = CRPAT	—	—	0.14	—	—	0.14	—	—	0.14	UI
Total jitter (peak-to-peak)	Pattern = CRPAT	—	—	0.279	—	—	0.279	—	—	0.279	UI
GIGE Receiver Jitter Tolerance <sup>(4)</sup>											
Deterministic jitter tolerance (peak-to-peak)	Pattern = CJPAT	> 0.4			> 0.4			> 0.4			UI
Combined deterministic and random jitter tolerance (peak-to-peak)	Pattern = CJPAT	> 0.66			> 0.66			> 0.66			UI

**Notes to Table 1–23:**

- (1) Dedicated `refclk` pins were used to drive the input reference clocks.
- (2) The jitter numbers specified are valid for the stated conditions only.
- (3) The jitter numbers for PIPE are compliant to the PCIe Base Specification 2.0.
- (4) The jitter numbers for GIGE are compliant to the IEEE802.3-2002 Specification.

## Core Performance Specifications

The following sections describe the clock tree specifications, PLLs, embedded multiplier, memory block, and configuration specifications for Cyclone IV Devices.

### Clock Tree Specifications

Table 1–24 lists the clock tree specifications for Cyclone IV devices.

**Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 1 of 2)**

Device	Performance								Unit
	C6	C7	C8	C8L <sup>(1)</sup>	C9L <sup>(1)</sup>	I7	I8L <sup>(1)</sup>	A7	
EP4CE6	500	437.5	402	362	265	437.5	362	402	MHz
EP4CE10	500	437.5	402	362	265	437.5	362	402	MHz
EP4CE15	500	437.5	402	362	265	437.5	362	402	MHz
EP4CE22	500	437.5	402	362	265	437.5	362	402	MHz
EP4CE30	500	437.5	402	362	265	437.5	362	402	MHz
EP4CE40	500	437.5	402	362	265	437.5	362	402	MHz

## Embedded Multiplier Specifications

Table 1–26 lists the embedded multiplier specifications for Cyclone IV devices.

**Table 1–26. Embedded Multiplier Specifications for Cyclone IV Devices**

Mode	Resources Used	Performance					Unit
	Number of Multipliers	C6	C7, I7, A7	C8	C8L, I8L	C9L	
9 × 9-bit multiplier	1	340	300	260	240	175	MHz
18 × 18-bit multiplier	1	287	250	200	185	135	MHz

## Memory Block Specifications

Table 1–27 lists the M9K memory block specifications for Cyclone IV devices.

**Table 1–27. Memory Block Performance Specifications for Cyclone IV Devices**

Memory	Mode	Resources Used		Performance					Unit
		LEs	M9K Memory	C6	C7, I7, A7	C8	C8L, I8L	C9L	
M9K Block	FIFO 256 × 36	47	1	315	274	238	200	157	MHz
	Single-port 256 × 36	0	1	315	274	238	200	157	MHz
	Simple dual-port 256 × 36 CLK	0	1	315	274	238	200	157	MHz
	True dual port 512 × 18 single CLK	0	1	315	274	238	200	157	MHz

## Configuration and JTAG Specifications

Table 1–28 lists the configuration mode specifications for Cyclone IV devices.

**Table 1–28. Passive Configuration Mode Specifications for Cyclone IV Devices <sup>(1)</sup>**

Programming Mode	V <sub>CCINT</sub> Voltage Level (V)	DCLK f <sub>MAX</sub>	Unit
Passive Serial (PS)	1.0 <sup>(3)</sup>	66	MHz
	1.2	133	MHz
Fast Passive Parallel (FPP) <sup>(2)</sup>	1.0 <sup>(3)</sup>	66	MHz
	1.2 <sup>(4)</sup>	100	MHz

**Notes to Table 1–28:**

- (1) For more information about PS and FPP configuration timing parameters, refer to the *Configuration and Remote System Upgrades in Cyclone IV Devices* chapter.
- (2) FPP configuration mode supports all Cyclone IV E devices (except for E144 package devices) and EP4CGX50, EP4CGX75, EP4CGX110, and EP4CGX150 only.
- (3) V<sub>CCINT</sub> = 1.0 V is only supported for Cyclone IV E 1.0 V core voltage devices.
- (4) Cyclone IV E devices support 1.2 V V<sub>CCINT</sub>. Cyclone IV E 1.2 V core voltage devices support 133 MHz DCLK f<sub>MAX</sub> for EP4CE6, EP4CE10, EP4CE15, EP4CE22, EP4CE30, and EP4CE40 only.

Table 1–29 lists the active configuration mode specifications for Cyclone IV devices.

**Table 1–29. Active Configuration Mode Specifications for Cyclone IV Devices**

Programming Mode	DCLK Range	Typical DCLK	Unit
Active Parallel (AP) <sup>(1)</sup>	20 to 40	33	MHz
Active Serial (AS)	20 to 40	33	MHz

**Note to Table 1–29:**

(1) AP configuration mode is only supported for Cyclone IV E devices.

Table 1–30 lists the JTAG timing parameters and values for Cyclone IV devices.

**Table 1–30. JTAG Timing Parameters for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Min	Max	Unit
t <sub>JCP</sub>	TCK clock period	40	—	ns
t <sub>JCH</sub>	TCK clock high time	19	—	ns
t <sub>JCL</sub>	TCK clock low time	19	—	ns
t <sub>JPSU_TDI</sub>	JTAG port setup time for TDI	1	—	ns
t <sub>JPSU_TMS</sub>	JTAG port setup time for TMS	3	—	ns
t <sub>JPH</sub>	JTAG port hold time	10	—	ns
t <sub>JPCO</sub>	JTAG port clock to output <sup>(2), (3)</sup>	—	15	ns
t <sub>JPZX</sub>	JTAG port high impedance to valid output <sup>(2), (3)</sup>	—	15	ns
t <sub>JPXZ</sub>	JTAG port valid output to high impedance <sup>(2), (3)</sup>	—	15	ns
t <sub>JSSU</sub>	Capture register setup time	5	—	ns
t <sub>JSH</sub>	Capture register hold time	10	—	ns
t <sub>JSCO</sub>	Update register clock to output	—	25	ns
t <sub>JSZX</sub>	Update register high impedance to valid output	—	25	ns
t <sub>JSXZ</sub>	Update register valid output to high impedance	—	25	ns

**Notes to Table 1–30:**

(1) For more information about JTAG waveforms, refer to “JTAG Waveform” in “Glossary” on page 1–37.

(2) The specification is shown for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 16 ns.

(3) For EP4CGX22, EP4CGX30 (F324 and smaller package), EP4CGX110, and EP4CGX150 devices, the output time specification for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins is 16 ns. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 18 ns.

## Periphery Performance

This section describes periphery performance, including high-speed I/O and external memory interface.

I/O performance supports several system interfaces, such as the high-speed I/O interface, external memory interface, and the PCI/PCI-X bus interface. I/Os using the SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speeds. I/Os using general-purpose I/O standards such as 3.3-, 3.0-, 2.5-, 1.8-, or 1.5-V LVTTL/LVCMOS are capable of a typical 200 MHz interfacing frequency with a 10 pF load.

**Table 1-34. True LVDS Transmitter Timing Specifications for Cyclone IV Devices <sup>(1)</sup>, <sup>(3)</sup>**

Symbol	Modes	C6		C7, I7		C8, A7		C8L, I8L		C9L		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
f <sub>HCLK</sub> (input clock frequency)	×10	5	420	5	370	5	320	5	320	5	250	MHz
	×8	5	420	5	370	5	320	5	320	5	250	MHz
	×7	5	420	5	370	5	320	5	320	5	250	MHz
	×4	5	420	5	370	5	320	5	320	5	250	MHz
	×2	5	420	5	370	5	320	5	320	5	250	MHz
	×1	5	420	5	402.5	5	402.5	5	362	5	265	MHz
HSIODR	×10	100	840	100	740	100	640	100	640	100	500	Mbps
	×8	80	840	80	740	80	640	80	640	80	500	Mbps
	×7	70	840	70	740	70	640	70	640	70	500	Mbps
	×4	40	840	40	740	40	640	40	640	40	500	Mbps
	×2	20	840	20	740	20	640	20	640	20	500	Mbps
	×1	10	420	10	402.5	10	402.5	10	362	10	265	Mbps
t <sub>DUTY</sub>	—	45	55	45	55	45	55	45	55	45	55	%
TCCS	—	—	200	—	200	—	200	—	200	—	200	ps
Output jitter (peak to peak)	—	—	500	—	500	—	550	—	600	—	700	ps
t <sub>LOCK</sub> <sup>(2)</sup>	—	—	1	—	1	—	1	—	1	—	1	ms

**Notes to Table 1-34:**

- (1) Cyclone IV E—true LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Cyclone IV GX—true LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6.
- (2) t<sub>LOCK</sub> is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

**Table 1-35. Emulated LVDS Transmitter Timing Specifications for Cyclone IV Devices <sup>(1)</sup>, <sup>(3)</sup> (Part 1 of 2)**

Symbol	Modes	C6		C7, I7		C8, A7		C8L, I8L		C9L		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
f <sub>HCLK</sub> (input clock frequency)	×10	5	320	5	320	5	275	5	275	5	250	MHz
	×8	5	320	5	320	5	275	5	275	5	250	MHz
	×7	5	320	5	320	5	275	5	275	5	250	MHz
	×4	5	320	5	320	5	275	5	275	5	250	MHz
	×2	5	320	5	320	5	275	5	275	5	250	MHz
	×1	5	402.5	5	402.5	5	402.5	5	362	5	265	MHz
HSIODR	×10	100	640	100	640	100	550	100	550	100	500	Mbps
	×8	80	640	80	640	80	550	80	550	80	500	Mbps
	×7	70	640	70	640	70	550	70	550	70	500	Mbps
	×4	40	640	40	640	40	550	40	550	40	500	Mbps
	×2	20	640	20	640	20	550	20	550	20	500	Mbps
	×1	10	402.5	10	402.5	10	402.5	10	362	10	265	Mbps

For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interface Handbook*.

Table 1–37 lists the memory output clock jitter specifications for Cyclone IV devices.

**Table 1–37. Memory Output Clock Jitter Specifications for Cyclone IV Devices <sup>(1), (2)</sup>**

Parameter	Symbol	Min	Max	Unit
Clock period jitter	$t_{JIT(per)}$	–125	125	ps
Cycle-to-cycle period jitter	$t_{JIT(cc)}$	–200	200	ps
Duty cycle jitter	$t_{JIT(duty)}$	–150	150	ps

**Notes to Table 1–37:**

- (1) Memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock (GCLK) network.

## Duty Cycle Distortion Specifications

Table 1–38 lists the worst case duty cycle distortion for Cyclone IV devices.

**Table 1–38. Duty Cycle Distortion on Cyclone IV Devices I/O Pins <sup>(1), (2), (3)</sup>**

Symbol	C6		C7, I7		C8, I8L, A7		C9L		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	45	55	%

**Notes to Table 1–38:**

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and IOE driving the dedicated and general purpose I/O pins.
- (2) Cyclone IV devices meet the specified duty cycle distortion at the maximum output toggle rate for each combination of I/O standard and current strength.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

## OCT Calibration Timing Specification

Table 1–39 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone IV devices.

**Table 1–39. Timing Specification for Series OCT with Calibration at Device Power-Up for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Description	Maximum	Units
$t_{OCTCAL}$	Duration of series OCT with calibration at device power-up	20	$\mu$ s

**Note to Table 1–39:**

- (1) OCT calibration takes place after device configuration and before entering user mode.

## IOE Programmable Delay

Table 1–40 and Table 1–41 list the IOE programmable delay for Cyclone IV E 1.0 V core voltage devices.

**Table 1–40. IOE Programmable Delay on Column Pins for Cyclone IV E 1.0 V Core Voltage Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Setting	Min Offset	Max Offset					Unit
				Fast Corner		Slow Corner			
				C8L	I8L	C8L	C9L	I8L	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	2.054	1.924	3.387	4.017	3.411	ns
Input delay from pin to input register	Pad to I/O input register	8	0	2.010	1.875	3.341	4.252	3.367	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.641	0.631	1.111	1.377	1.124	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.971	0.931	1.684	2.298	1.684	ns

**Notes to Table 1–40:**

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

**Table 1–41. IOE Programmable Delay on Row Pins for Cyclone IV E 1.0 V Core Voltage Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Setting	Min Offset	Max Offset					Unit
				Fast Corner		Slow Corner			
				C8L	I8L	C8L	C9L	I8L	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	2.057	1.921	3.389	4.146	3.412	ns
Input delay from pin to input register	Pad to I/O input register	8	0	2.059	1.919	3.420	4.374	3.441	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.670	0.623	1.160	1.420	1.168	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.960	0.919	1.656	2.258	1.656	ns

**Notes to Table 1–41:**

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.



Table 1–44 and Table 1–45 list the IOE programmable delay for Cyclone IV GX devices.

**Table 1–44. IOE Programmable Delay on Column Pins for Cyclone IV GX Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Settings	Min Offset	Max Offset						Unit
				Fast Corner		Slow Corner				
				C6	I7	C6	C7	C8	I7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.313	1.209	2.184	2.336	2.451	2.387	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.312	1.208	2.200	2.399	2.554	2.446	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.438	0.404	0.751	0.825	0.886	0.839	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.713	0.682	1.228	1.41	1.566	1.424	ns

**Notes to Table 1–44:**

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

**Table 1–45. IOE Programmable Delay on Row Pins for Cyclone IV GX Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Settings	Min Offset	Max Offset						Unit
				Fast Corner		Slow Corner				
				C6	I7	C6	C7	C8	I7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.314	1.210	2.209	2.398	2.526	2.443	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.313	1.208	2.205	2.406	2.563	2.450	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.461	0.421	0.789	0.869	0.933	0.884	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.712	0.682	1.225	1.407	1.562	1.421	ns

**Notes to Table 1–45:**

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software

Table 1-46. Glossary (Part 2 of 5)

Letter	Term	Definitions
<b>J</b>	JTAG Waveform	<p>The diagram illustrates the JTAG waveform with the following timing parameters:</p> <ul style="list-style-type: none"> <li><math>t_{JCP}</math>: Time from TCK rising edge to TDI setup.</li> <li><math>t_{JCH}</math>: Time from TCK rising edge to TDI hold.</li> <li><math>t_{JCL}</math>: Time from TCK falling edge to TDI setup.</li> <li><math>t_{JCH}</math>: Time from TCK falling edge to TDI hold.</li> <li><math>t_{JPSU\_TDI}</math>: Setup time for TDI before TCK rising edge.</li> <li><math>t_{JPSU\_TMS}</math>: Setup time for TMS before TCK rising edge.</li> <li><math>t_{JPH}</math>: Hold time for TMS after TCK rising edge.</li> <li><math>t_{JPZX}</math>: Time from TCK rising edge to TDO setup.</li> <li><math>t_{JPCO}</math>: Time from TCK rising edge to TDO output.</li> <li><math>t_{JPXZ}</math>: Time from TCK rising edge to TDO hold.</li> <li><math>t_{JSSU}</math>: Setup time for Signal to be Captured before TCK rising edge.</li> <li><math>t_{JSH}</math>: Hold time for Signal to be Captured after TCK rising edge.</li> <li><math>t_{JSZX}</math>: Time from TCK rising edge to Signal to be Driven setup.</li> <li><math>t_{JSCO}</math>: Time from TCK rising edge to Signal to be Driven output.</li> <li><math>t_{JSXZ}</math>: Time from TCK rising edge to Signal to be Driven hold.</li> </ul>
<b>K</b>	—	—
<b>L</b>	—	—
<b>M</b>	—	—
<b>N</b>	—	—
<b>O</b>	—	—
<b>P</b>	PLL Block	<p>The following highlights the PLL specification parameters:</p> <p>The diagram shows the internal structure of the PLL block. It includes a Core Clock input, a Switchover block, a Divider (N), a Phase-Locked Loop (PLL) block containing a Phase Frequency Divider (PFD), Charge Pump (CP), Loop Filter (LF), and Voltage-Controlled Oscillator (VCO). The output of the VCO is <math>f_{VCO}</math>, which is divided by a Counter (C0..C4) to produce <math>f_{OUT\_EXT}</math> and <math>f_{OUT}</math>. A Phase tap is also shown. A Key indicates that the PLL block is Reconfigurable in User Mode.</p>
<b>Q</b>	—	—

Table 1-46. Glossary (Part 4 of 5)

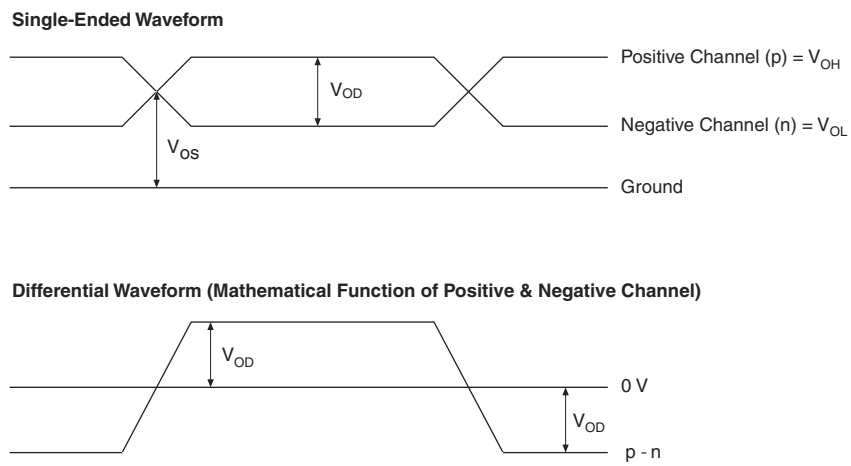
Letter	Term	Definitions
T	$t_C$	High-speed receiver and transmitter input and output clock period.
	Channel-to-channel-skew (TCCS)	High-speed I/O block: The timing difference between the fastest and slowest output edges, including $t_{CO}$ variation and clock skew. The clock is included in the TCCS measurement.
	$t_{cin}$	Delay from the clock pad to the I/O input register.
	$t_{CO}$	Delay from the clock pad to the I/O output.
	$t_{cout}$	Delay from the clock pad to the I/O output register.
	$t_{DUTY}$	High-speed I/O block: Duty cycle on high-speed transmitter output clock.
	$t_{FALL}$	Signal high-to-low transition time (80–20%).
	$t_H$	Input register hold time.
	Timing Unit Interval (TUI)	High-speed I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(\text{Receiver Input Clock Frequency Multiplication Factor}) = t_C/w$ ).
	$t_{INJITTER}$	Period jitter on the PLL clock input.
	$t_{OUTJITTER\_DEDCLK}$	Period jitter on the dedicated clock output driven by a PLL.
	$t_{OUTJITTER\_IO}$	Period jitter on the general purpose I/O driven by a PLL.
	$t_{pllcin}$	Delay from the PLL inclk pad to the I/O input register.
	$t_{pllcout}$	Delay from the PLL inclk pad to the I/O output register.
	Transmitter Output Waveform	<p>Transmitter output waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards:</p> 
	$t_{RISE}$	Signal low-to-high transition time (20–80%).
	$t_{SU}$	Input register setup time.
U	—	—

Table 1-46. Glossary (Part 5 of 5)

Letter	Term	Definitions
<b>V</b>	$V_{CM(DC)}$	DC common mode input voltage.
	$V_{DIF(AC)}$	AC differential input voltage: The minimum AC input differential voltage required for switching.
	$V_{DIF(DC)}$	DC differential input voltage: The minimum DC input differential voltage required for switching.
	$V_{ICM}$	Input common mode voltage: The common mode of the differential signal at the receiver.
	$V_{ID}$	Input differential voltage swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
	$V_{IH}$	Voltage input high: The minimum positive voltage applied to the input that is accepted by the device as a logic high.
	$V_{IH(AC)}$	High-level AC input voltage.
	$V_{IH(DC)}$	High-level DC input voltage.
	$V_{IL}$	Voltage input low: The maximum positive voltage applied to the input that is accepted by the device as a logic low.
	$V_{IL(AC)}$	Low-level AC input voltage.
	$V_{IL(DC)}$	Low-level DC input voltage.
	$V_{IN}$	DC input voltage.
	$V_{OCM}$	Output common mode voltage: The common mode of the differential signal at the transmitter.
	$V_{OD}$	Output differential voltage swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the transmitter. $V_{OD} = V_{OH} - V_{OL}$ .
	$V_{OH}$	Voltage output high: The maximum positive voltage from an output that the device considers is accepted as the minimum positive high level.
	$V_{OL}$	Voltage output low: The maximum positive voltage from an output that the device considers is accepted as the maximum positive low level.
	$V_{OS}$	Output offset voltage: $V_{OS} = (V_{OH} + V_{OL}) / 2$ .
	$V_{OX(AC)}$	AC differential output cross point voltage: the voltage at which the differential output signals must cross.
	$V_{REF}$	Reference voltage for the SSTL and HSTL I/O standards.
	$V_{REF(AC)}$	AC input reference voltage for the SSTL and HSTL I/O standards. $V_{REF(AC)} = V_{REF(DC)} + \text{noise}$ . The peak-to-peak AC noise on $V_{REF}$ must not exceed 2% of $V_{REF(DC)}$ .
	$V_{REF(DC)}$	DC input reference voltage for the SSTL and HSTL I/O standards.
	$V_{SWING(AC)}$	AC differential input voltage: AC input differential voltage required for switching. For the SSTL differential I/O standard, refer to Input Waveforms.
	$V_{SWING(DC)}$	DC differential input voltage: DC input differential voltage required for switching. For the SSTL differential I/O standard, refer to Input Waveforms.
	$V_{TT}$	Termination voltage for the SSTL and HSTL I/O standards.
	$V_X(AC)$	AC differential input cross point voltage: The voltage at which the differential input signals must cross.
<b>W</b>	—	—
<b>X</b>	—	—
<b>Y</b>	—	—
<b>Z</b>	—	—

**Table 1–47. Document Revision History**

Date	Version	Changes
February 2010	1.1	<ul style="list-style-type: none"><li>■ Updated Table 1–3 through Table 1–44 to include information for Cyclone IV E devices and Cyclone IV GX devices for Quartus II software version 9.1 SP1 release.</li><li>■ Minor text edits.</li></ul>
November 2009	1.0	Initial release.