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Understanding Embedded - FPGAs (Field Programmable Gate Array)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|---|
| Product Status | Active |
| Number of LABs/CLBs | 6839 |
| Number of Logic Elements/Cells | 109424 |
| Total RAM Bits | 5621760 |
| Number of I/O | 475 |
| Number of Gates | - |
| Voltage - Supply | 1.16V ~ 1.24V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 896-BGA |
| Supplier Device Package | 896-FBGA (31x31) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/ep4cgx110df31i7 |



Cyclone IV E industrial devices I7 are offered with extended operating temperature range.

Absolute Maximum Ratings

Absolute maximum ratings define the maximum operating conditions for Cyclone IV devices. The values are based on experiments conducted with the device and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied at these conditions. Table 1–1 lists the absolute maximum ratings for Cyclone IV devices.



Conditions beyond those listed in Table 1–1 cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time have adverse effects on the device.

Table 1–1. Absolute Maximum Ratings for Cyclone IV Devices ⁽¹⁾

| Symbol | Parameter | Min | Max | Unit |
|-----------------|---|------|------|------|
| V_{CCINT} | Core voltage, PCI Express® (PCIe®) hard IP block, and transceiver physical coding sublayer (PCS) power supply | –0.5 | 1.8 | V |
| V_{CCA} | Phase-locked loop (PLL) analog power supply | –0.5 | 3.75 | V |
| V_{CCD_PLL} | PLL digital power supply | –0.5 | 1.8 | V |
| V_{CCIO} | I/O banks power supply | –0.5 | 3.75 | V |
| V_{CC_CLKIN} | Differential clock input pins power supply | –0.5 | 4.5 | V |
| V_{CCH_GXB} | Transceiver output buffer power supply | –0.5 | 3.75 | V |
| V_{CCA_GXB} | Transceiver physical medium attachment (PMA) and auxiliary power supply | –0.5 | 3.75 | V |
| V_{CCL_GXB} | Transceiver PMA and auxiliary power supply | –0.5 | 1.8 | V |
| V_I | DC input voltage | –0.5 | 4.2 | V |
| I_{OUT} | DC output current, per pin | –25 | 40 | mA |
| T_{STG} | Storage temperature | –65 | 150 | °C |
| T_J | Operating junction temperature | –40 | 125 | °C |

Note to Table 1–1:

(1) Supply voltage specifications apply to voltage readings taken at the device pins with respect to ground, not at the power supply.

Maximum Allowed Overshoot or Undershoot Voltage

During transitions, input signals may overshoot to the voltage shown in Table 1–2 and undershoot to –2.0 V for a magnitude of currents less than 100 mA and for periods shorter than 20 ns. Table 1–2 lists the maximum allowed input overshoot voltage and the duration of the overshoot voltage as a percentage over the lifetime of the device. The maximum allowed overshoot duration is specified as a percentage of high-time over the lifetime of the device.


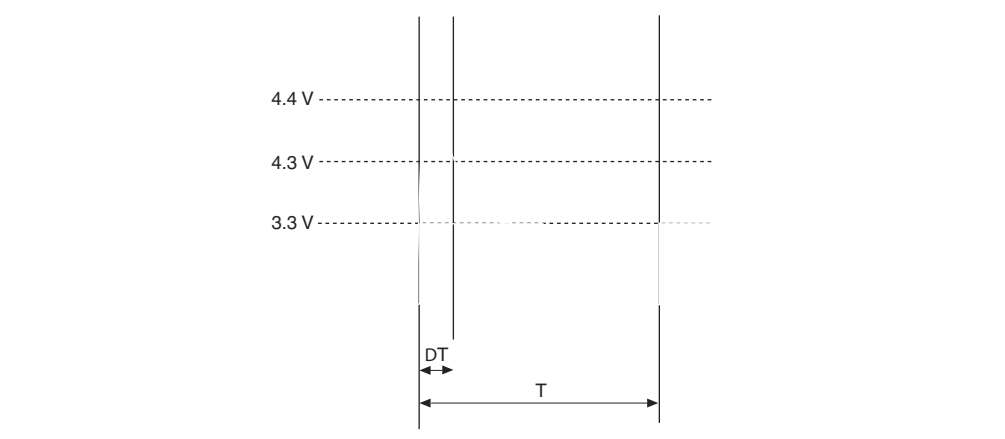
 A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices

| Symbol | Parameter | Condition (V) | Overshoot Duration as % of High Time | Unit |
|--------|------------------|---------------|--------------------------------------|------|
| V_i | AC Input Voltage | $V_i = 4.20$ | 100 | % |
| | | $V_i = 4.25$ | 98 | % |
| | | $V_i = 4.30$ | 65 | % |
| | | $V_i = 4.35$ | 43 | % |
| | | $V_i = 4.40$ | 29 | % |
| | | $V_i = 4.45$ | 20 | % |
| | | $V_i = 4.50$ | 13 | % |
| | | $V_i = 4.55$ | 9 | % |
| | | $V_i = 4.60$ | 6 | % |

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as $([\Delta T]/T) \times 100$. This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

Figure 1–1. Cyclone IV Devices Overshoot Duration



Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices ⁽¹⁾, ⁽²⁾ (Part 1 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|--|--|------------|-----|------------|------|
| $V_{CCINT}^{(3)}$ | Supply voltage for internal logic, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply voltage for internal logic, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| $V_{CCIO}^{(3), (4)}$ | Supply voltage for output buffers, 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Supply voltage for output buffers, 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | Supply voltage for output buffers, 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Supply voltage for output buffers, 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Supply voltage for output buffers, 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Supply voltage for output buffers, 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| $V_{CCA}^{(3)}$ | Supply (analog) voltage for PLL regulator | — | 2.375 | 2.5 | 2.625 | V |
| $V_{CCD_PLL}^{(3)}$ | Supply (digital) voltage for PLL, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply (digital) voltage for PLL, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| V_I | Input voltage | — | –0.5 | — | 3.6 | V |
| V_O | Output voltage | — | 0 | — | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | — | 85 | °C |
| | | For industrial use | –40 | — | 100 | °C |
| | | For extended temperature | –40 | — | 125 | °C |
| | | For automotive use | –40 | — | 125 | °C |
| t_{RAMP} | Power supply ramp time | Standard power-on reset (POR) ⁽⁵⁾ | 50 μ s | — | 50 ms | — |
| | | Fast POR ⁽⁶⁾ | 50 μ s | — | 3 ms | — |

Table 1-4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 2 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|----------------|---|--|------------|-----|------------|------|
| V_{CCA_GXB} | Transceiver PMA and auxiliary power supply | — | 2.375 | 2.5 | 2.625 | V |
| V_{CCL_GXB} | Transceiver PMA and auxiliary power supply | — | 1.16 | 1.2 | 1.24 | V |
| V_I | DC input voltage | — | -0.5 | — | 3.6 | V |
| V_O | DC output voltage | — | 0 | — | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | — | 85 | °C |
| | | For industrial use | -40 | — | 100 | °C |
| t_{RAMP} | Power supply ramp time | Standard power-on reset (POR) ⁽⁷⁾ | 50 μ s | — | 50 ms | — |
| | | Fast POR ⁽⁸⁾ | 50 μ s | — | 3 ms | — |
| I_{Diode} | Magnitude of DC current across PCI-clamp diode when enabled | — | — | — | 10 | mA |

Notes to Table 1-4:

- (1) All V_{CCA} pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (2) You must connect V_{CCD_PLL} to V_{CCINT} through a decoupling capacitor and ferrite bead.
- (3) Power supplies must rise monotonically.
- (4) V_{CCIO} for all I/O banks must be powered up during device operation. Configurations pins are powered up by V_{CCIO} of I/O Banks 3, 8, and 9 where I/O Banks 3 and 9 only support V_{CCIO} of 1.5, 1.8, 2.5, 3.0, and 3.3 V. For fast passive parallel (FPP) configuration mode, the V_{CCIO} level of I/O Bank 8 must be powered up to 1.5, 1.8, 2.5, 3.0, and 3.3 V.
- (5) You must set V_{CC_CLKIN} to 2.5 V if you use $CLKIN$ as a high-speed serial interface (HSSI) $refclk$ or as a $DIFFCLK$ input.
- (6) The $CLKIN$ pins in I/O Banks 3B and 8B can support single-ended I/O standard when the pins are used to clock left PLLs in non-transceiver applications.
- (7) The POR time for Standard POR ranges between 50 and 200 ms. V_{CCINT} , V_{CCA} , and V_{CCIO} of I/O Banks 3, 8, and 9 must reach the recommended operating range within 50 ms.
- (8) The POR time for Fast POR ranges between 3 and 9 ms. V_{CCINT} , V_{CCA} , and V_{CCIO} of I/O Banks 3, 8, and 9 must reach the recommended operating range within 3 ms.

ESD Performance

This section lists the electrostatic discharge (ESD) voltages using the human body model (HBM) and charged device model (CDM) for Cyclone IV devices general purpose I/Os (GPIOs) and high-speed serial interface (HSSI) I/Os. Table 1-5 lists the ESD for Cyclone IV devices GPIOs and HSSI I/Os.

Table 1-5. ESD for Cyclone IV Devices GPIOs and HSSI I/Os

| Symbol | Parameter | Passing Voltage | Unit |
|--------------|--|-----------------|------|
| V_{ESDHBM} | ESD voltage using the HBM (GPIOs) ⁽¹⁾ | ± 2000 | V |
| | ESD using the HBM (HSSI I/Os) ⁽²⁾ | ± 1000 | V |
| V_{ESDCDM} | ESD using the CDM (GPIOs) | ± 500 | V |
| | ESD using the CDM (HSSI I/Os) ⁽²⁾ | ± 250 | V |

Notes to Table 1-5:

- (1) The passing voltage for EP4CGX15 and EP4CGX30 row I/Os is ± 1000 V.
- (2) This value is applicable only to Cyclone IV GX devices.

Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1-12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

Table 1-12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices ⁽¹⁾

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------|--|--|-----|-----|-----|------|
| R _{PU} | Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you enable the programmable pull-up resistor option | V _{CCIO} = 3.3 V ± 5% ^{(2), (3)} | 7 | 25 | 41 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ^{(2), (3)} | 7 | 28 | 47 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ^{(2), (3)} | 8 | 35 | 61 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ^{(2), (3)} | 10 | 57 | 108 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ^{(2), (3)} | 13 | 82 | 163 | kΩ |
| | | V _{CCIO} = 1.2 V ± 5% ^{(2), (3)} | 19 | 143 | 351 | kΩ |
| R _{PD} | Value of the I/O pin pull-down resistor before and during configuration | V _{CCIO} = 3.3 V ± 5% ⁽⁴⁾ | 6 | 19 | 30 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ⁽⁴⁾ | 6 | 22 | 36 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ⁽⁴⁾ | 6 | 25 | 43 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ⁽⁴⁾ | 7 | 35 | 71 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ⁽⁴⁾ | 8 | 50 | 112 | kΩ |

Notes to Table 1-12:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO}.
- (3) $R_{PU} = (V_{CCIO} - V_I) / I_{R_{PU}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = V_{CC} + 5% - 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = 0 V;
Maximum condition: 100°C; V_{CCIO} = V_{CC} - 5%, V_I = 0 V; in which V_I refers to the input voltage at the I/O pin.
- (4) $R_{PD} = V_I / I_{R_{PD}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = V_{CC} - 5%;
Maximum condition: 100°C; V_{CCIO} = V_{CC} - 5%, V_I = V_{CC} - 5%; in which V_I refers to the input voltage at the I/O pin.

Hot-Socketing

Table 1-13 lists the hot-socketing specifications for Cyclone IV devices.

Table 1-13. Hot-Socketing Specifications for Cyclone IV Devices

| Symbol | Parameter | Maximum |
|-------------------------|-----------------------------------|---------------------|
| I _{IOPIN(DC)} | DC current per I/O pin | 300 μA |
| I _{IOPIN(AC)} | AC current per I/O pin | 8 mA ⁽¹⁾ |
| I _{XCVRTX(DC)} | DC current per transceiver TX pin | 100 mA |
| I _{XCVRRX(DC)} | DC current per transceiver RX pin | 50 mA |

Note to Table 1-13:

- (1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |I_{IOPIN}| = C dv/dt, in which C is the I/O pin capacitance and dv/dt is the slew rate.



During hot-socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF.

Schmitt Trigger Input

Cyclone IV devices support Schmitt trigger input on the TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with slow edge rate. Table 1–14 lists the hysteresis specifications across the supported V_{CCIO} range for Schmitt trigger inputs in Cyclone IV devices.

Table 1–14. Hysteresis Specifications for Schmitt Trigger Input in Cyclone IV Devices

| Symbol | Parameter | Conditions (V) | Minimum | Unit |
|---------------|--------------------------------------|------------------|---------|------|
| $V_{SCHMITT}$ | Hysteresis for Schmitt trigger input | $V_{CCIO} = 3.3$ | 200 | mV |
| | | $V_{CCIO} = 2.5$ | 200 | mV |
| | | $V_{CCIO} = 1.8$ | 140 | mV |
| | | $V_{CCIO} = 1.5$ | 110 | mV |

I/O Standard Specifications

The following tables list input voltage sensitivities (V_{IH} and V_{IL}), output voltage (V_{OH} and V_{OL}), and current drive characteristics (I_{OH} and I_{OL}), for various I/O standards supported by Cyclone IV devices. Table 1–15 through Table 1–20 provide the I/O standard specifications for Cyclone IV devices.

Table 1–15. Single-Ended I/O Standard Specifications for Cyclone IV Devices ^{(1), (2)}

| I/O Standard | V_{CCIO} (V) | | | V_{IL} (V) | | V_{IH} (V) | | V_{OL} (V) | V_{OH} (V) | I_{OL} (mA) (4) | I_{OH} (mA) (4) |
|-----------------------------|----------------|-----|-------|--------------|------------------------|------------------------|------------------|------------------------|------------------------|----------------------|----------------------|
| | Min | Typ | Max | Min | Max | Min | Max | Max | Min | | |
| 3.3-V LVTTTL ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.45 | 2.4 | 4 | –4 |
| 3.3-V LVCMOS ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.2 | $V_{CCIO} - 0.2$ | 2 | –2 |
| 3.0-V LVTTTL ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.45 | 2.4 | 4 | –4 |
| 3.0-V LVCMOS ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.2 | $V_{CCIO} - 0.2$ | 0.1 | –0.1 |
| 2.5 V ⁽³⁾ | 2.375 | 2.5 | 2.625 | –0.3 | 0.7 | 1.7 | $V_{CCIO} + 0.3$ | 0.4 | 2.0 | 1 | –1 |
| 1.8 V | 1.71 | 1.8 | 1.89 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | 2.25 | 0.45 | $V_{CCIO} - 0.45$ | 2 | –2 |
| 1.5 V | 1.425 | 1.5 | 1.575 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 1.2 V | 1.14 | 1.2 | 1.26 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 3.0-V PCI | 2.85 | 3.0 | 3.15 | — | $0.3 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |
| 3.0-V PCI-X | 2.85 | 3.0 | 3.15 | — | $0.35 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |

Notes to Table 1–15:

- (1) For voltage-referenced receiver input waveform and explanation of terms used in Table 1–15, refer to “Glossary” on page 1–37.
- (2) AC load $CL = 10$ pF
- (3) For more information about interfacing Cyclone IV devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O standards, refer to *AN 447: Interfacing Cyclone III and Cyclone IV Devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O Systems*.
- (4) To meet the I_{OL} and I_{OH} specifications, you must set the current strength settings accordingly. For example, to meet the **3.3-V LVTTTL** specification (4 mA), set the current strength settings to 4 mA or higher. Setting at lower current strength may not meet the I_{OL} and I_{OH} specifications in the handbook.

Table 1–20. Differential I/O Standard Specifications for Cyclone IV Devices ⁽¹⁾ (Part 2 of 2)

| I/O Standard | V _{CCIO} (V) | | | V _{ID} (mV) | | V _{ICM} (V) ⁽²⁾ | | | V _{OD} (mV) ⁽³⁾ | | | V _{OS} (V) ⁽³⁾ | | |
|---|-----------------------|-----|-------|----------------------|-----|-------------------------------------|---|------|-------------------------------------|-----|-----|------------------------------------|------|-------|
| | Min | Typ | Max | Min | Max | Min | Condition | Max | Min | Typ | Max | Min | Typ | Max |
| LVDS (Column I/Os) | 2.375 | 2.5 | 2.625 | 100 | — | 0.05 | $D_{MAX} \leq 500 \text{ Mbps}$ | 1.80 | 247 | — | 600 | 1.125 | 1.25 | 1.375 |
| | | | | | | 0.55 | $500 \text{ Mbps} \leq D_{MAX} \leq 700 \text{ Mbps}$ | 1.80 | | | | | | |
| | | | | | | 1.05 | $D_{MAX} > 700 \text{ Mbps}$ | 1.55 | | | | | | |
| BLVDS (Row I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| BLVDS (Column I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| mini-LVDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| mini-LVDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| RSDS [®] (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| RSDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| PPDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |
| PPDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |

Notes to Table 1–20:

- (1) For an explanation of terms used in Table 1–20, refer to “Glossary” on page 1–37.
- (2) V_{IN} range: $0 \text{ V} \leq V_{IN} \leq 1.85 \text{ V}$.
- (3) R_L range: $90 \leq R_L \leq 110 \Omega$.
- (4) There are no fixed V_{IN}, V_{OD}, and V_{OS} specifications for BLVDS. They depend on the system topology.
- (5) The Mini-LVDS, RSDS, and PPDS standards are only supported at the output pins.
- (6) The LVPECL I/O standard is only supported on dedicated clock input pins. This I/O standard is not supported for output pins.

Power Consumption

Use the following methods to estimate power for a design:

- the Excel-based EPE
- the Quartus® II PowerPlay power analyzer feature

The interactive Excel-based EPE is used prior to designing the device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, combined with detailed circuit models, can yield very accurate power estimates.



For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

Switching Characteristics

This section provides performance characteristics of Cyclone IV core and periphery blocks for commercial grade devices.

These characteristics can be designated as Preliminary or Final.

- Preliminary characteristics are created using simulation results, process data, and other known parameters. The upper-right hand corner of these tables show the designation as “Preliminary”.
- Final numbers are based on actual silicon characterization and testing. The numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions. There are no designations on finalized tables.

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 4 of 4)

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|--|------------|------------------------------------|-----|--------|--------|-----|--------|-----|-----|--------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| PLD-Transceiver Interface | | | | | | | | | | | |
| Interface speed (F324 and smaller package) | — | 25 | — | 125 | 25 | — | 125 | 25 | — | 125 | MHz |
| Interface speed (F484 and larger package) | — | 25 | — | 156.25 | 25 | — | 156.25 | 25 | — | 156.25 | MHz |
| Digital reset pulse width | — | Minimum is 2 parallel clock cycles | | | | | | | | | |

Notes to Table 1–21:

- (1) This specification is valid for transmitter output jitter specification with a maximum total jitter value of 112 ps, typically for 3.125 Gbps SRIO and XAUI protocols.
- (2) The minimum `reconfig_clk` frequency is 2.5 MHz if the transceiver channel is configured in **Transmitter Only** mode. The minimum `reconfig_clk` frequency is 37.5 MHz if the transceiver channel is configured in **Receiver Only** or **Receiver and Transmitter** mode.
- (3) The device cannot tolerate prolonged operation at this absolute maximum.
- (4) The rate matcher supports only up to ± 300 parts per million (ppm).
- (5) Supported for the F169 and F324 device packages only.
- (6) Supported for the F484, F672, and F896 device packages only. Pending device characterization.
- (7) To support CDR ppm tolerance greater than ± 300 ppm, implement ppm detector in user logic and configure CDR to Manual Lock Mode.
- (8) Asynchronous spread-spectrum clocking is not supported.
- (9) For the EP4CGX30 (F484 package only), EP4CGX50, and EP4CGX75 devices, the CDR ppl tolerance is ± 200 ppm.
- (10) Time taken until `p11_locked` goes high after `p11_powerdown` deasserts.
- (11) Time that the CDR must be kept in lock-to-reference mode after `rx_analogreset` deasserts and before `rx_locktodata` is asserted in manual mode.
- (12) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode (Figure 1–2), or after `rx_freqlocked` signal goes high in automatic mode (Figure 1–3).
- (13) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode.
- (14) Time taken to recover valid data after the `rx_freqlocked` signal goes high in automatic mode.
- (15) To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.

Figure 1-4 shows the differential receiver input waveform.

Figure 1-4. Receiver Input Waveform

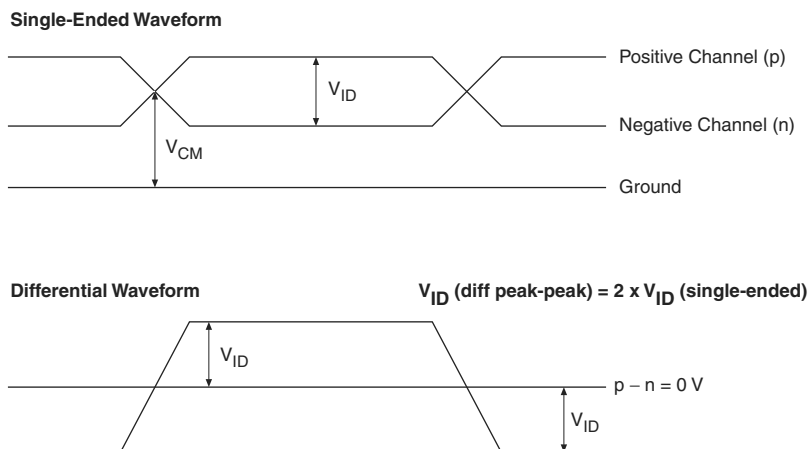


Figure 1-5 shows the transmitter output waveform.

Figure 1-5. Transmitter Output Waveform

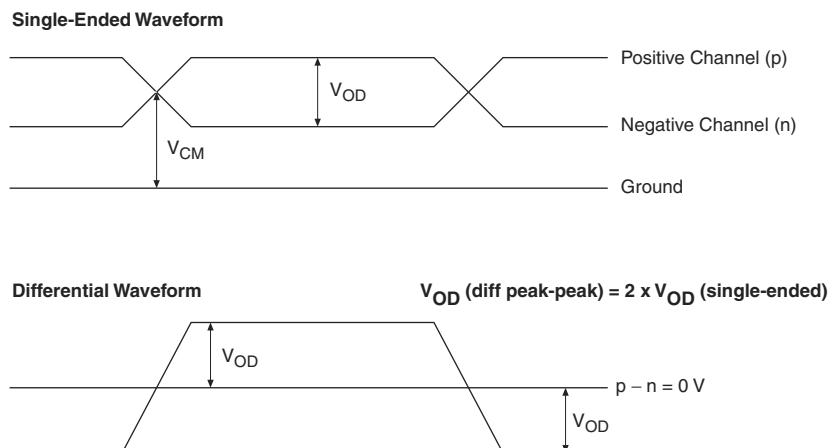


Table 1-22 lists the typical V_{OD} for Tx term that equals 100 Ω .

Table 1-22. Typical V_{OD} Setting, Tx Term = 100 Ω

| Symbol | V_{OD} Setting (mV) | | | | | |
|---|-----------------------|-----|-----|-------|------|------|
| | 1 | 2 | 3 | 4 (1) | 5 | 6 |
| V_{OD} differential peak to peak typical (mV) | 400 | 600 | 800 | 900 | 1000 | 1200 |

Note to Table 1-22:

(1) This setting is required for compliance with the PCIe protocol.

Table 1–23 lists the Cyclone IV GX transceiver block AC specifications.

Table 1–23. Transceiver Block AC Specification for Cyclone IV GX Devices ^{(1), (2)}

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|---|--------------------|--------|-----|-------|--------|-----|-------|--------|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| PCIe Transmit Jitter Generation ⁽³⁾ | | | | | | | | | | | |
| Total jitter at 2.5 Gbps (Gen1) | Compliance pattern | — | — | 0.25 | — | — | 0.25 | — | — | 0.25 | UI |
| PCIe Receiver Jitter Tolerance ⁽³⁾ | | | | | | | | | | | |
| Total jitter at 2.5 Gbps (Gen1) | Compliance pattern | > 0.6 | | | > 0.6 | | | > 0.6 | | | UI |
| GIGE Transmit Jitter Generation ⁽⁴⁾ | | | | | | | | | | | |
| Deterministic jitter (peak-to-peak) | Pattern = CRPAT | — | — | 0.14 | — | — | 0.14 | — | — | 0.14 | UI |
| Total jitter (peak-to-peak) | Pattern = CRPAT | — | — | 0.279 | — | — | 0.279 | — | — | 0.279 | UI |
| GIGE Receiver Jitter Tolerance ⁽⁴⁾ | | | | | | | | | | | |
| Deterministic jitter tolerance (peak-to-peak) | Pattern = CJPAT | > 0.4 | | | > 0.4 | | | > 0.4 | | | UI |
| Combined deterministic and random jitter tolerance (peak-to-peak) | Pattern = CJPAT | > 0.66 | | | > 0.66 | | | > 0.66 | | | UI |

Notes to Table 1–23:

- (1) Dedicated `refclk` pins were used to drive the input reference clocks.
- (2) The jitter numbers specified are valid for the stated conditions only.
- (3) The jitter numbers for PIPE are compliant to the PCIe Base Specification 2.0.
- (4) The jitter numbers for GIGE are compliant to the IEEE802.3-2002 Specification.

Core Performance Specifications

The following sections describe the clock tree specifications, PLLs, embedded multiplier, memory block, and configuration specifications for Cyclone IV Devices.

Clock Tree Specifications

Table 1–24 lists the clock tree specifications for Cyclone IV devices.

Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 1 of 2)

| Device | Performance | | | | | | | | Unit |
|---------|-------------|-------|-----|--------------------|--------------------|-------|--------------------|-----|------|
| | C6 | C7 | C8 | C8L ⁽¹⁾ | C9L ⁽¹⁾ | I7 | I8L ⁽¹⁾ | A7 | |
| EP4CE6 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |
| EP4CE10 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |
| EP4CE15 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |
| EP4CE22 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |
| EP4CE30 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |
| EP4CE40 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | 402 | MHz |

Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 2 of 2)

| Device | Performance | | | | | | | | Unit |
|-----------|-------------|-------|-----|--------------------|--------------------|-------|--------------------|----|------|
| | C6 | C7 | C8 | C8L ⁽¹⁾ | C9L ⁽¹⁾ | I7 | I8L ⁽¹⁾ | A7 | |
| EP4CE55 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE75 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE115 | — | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CGX15 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX22 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX30 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX50 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX75 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX110 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX150 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |

Note to Table 1–24:

(1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades.

PLL Specifications

Table 1–25 lists the PLL specifications for Cyclone IV devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (–40°C to 100°C), the extended industrial junction temperature range (–40°C to 125°C), and the automotive junction temperature range (–40°C to 125°C). For more information about the PLL block, refer to “Glossary” on page 1–37.

Table 1–25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 1 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|-----|-----|-------|------|
| f_{IN} ⁽³⁾ | Input clock frequency (–6, –7, –8 speed grades) | 5 | — | 472.5 | MHz |
| | Input clock frequency (–8L speed grade) | 5 | — | 362 | MHz |
| | Input clock frequency (–9L speed grade) | 5 | — | 265 | MHz |
| f_{INPFD} | PFD input frequency | 5 | — | 325 | MHz |
| f_{VCO} ⁽⁴⁾ | PLL internal VCO operating range | 600 | — | 1300 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | — | 60 | % |
| $t_{INJITTER_CCJ}$ ⁽⁵⁾ | Input clock cycle-to-cycle jitter $F_{REF} \geq 100$ MHz | — | — | 0.15 | UI |
| | $F_{REF} < 100$ MHz | — | — | ±750 | ps |
| f_{OUT_EXT} (external clock output) ⁽³⁾ | PLL output frequency | — | — | 472.5 | MHz |
| f_{OUT} (to global clock) | PLL output frequency (–6 speed grade) | — | — | 472.5 | MHz |
| | PLL output frequency (–7 speed grade) | — | — | 450 | MHz |
| | PLL output frequency (–8 speed grade) | — | — | 402.5 | MHz |
| | PLL output frequency (–8L speed grade) | — | — | 362 | MHz |
| | PLL output frequency (–9L speed grade) | — | — | 265 | MHz |
| $t_{OUTDUTY}$ | Duty cycle for external clock output (when set to 50%) | 45 | 50 | 55 | % |
| t_{LOCK} | Time required to lock from end of device configuration | — | — | 1 | ms |

Table 1-25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 2 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|--|---|-----|--------------------|----------|----------------|
| t_{DLOCK} | Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or \overline{areset} is deasserted) | — | — | 1 | ms |
| $t_{OUTJITTER_PERIOD_DEDCLK}^{(6)}$ | Dedicated clock output period jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_CCJ_DEDCLK}^{(6)}$ | Dedicated clock output cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_PERIOD_IO}^{(6)}$ | Regular I/O period jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| $t_{OUTJITTER_CCJ_IO}^{(6)}$ | Regular I/O cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | — | — | ± 50 | ps |
| t_{ARESET} | Minimum pulse width on \overline{areset} signal. | 10 | — | — | ns |
| $t_{CONFIGPLL}$ | Time required to reconfigure scan chains for PLLs | — | 3.5 ⁽⁷⁾ | — | SCANCLK cycles |
| $f_{SCANCLK}$ | scanclk frequency | — | — | 100 | MHz |
| $t_{CASC_OUTJITTER_PERIOD_DEDCLK}^{(8), (9)}$ | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} \geq 100$ MHz) | — | — | 425 | ps |
| | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} < 100$ MHz) | — | — | 42.5 | mUI |

Notes to Table 1-25:

- (1) This table is applicable for general purpose PLLs and multipurpose PLLs.
- (2) You must connect V_{CCD_PLL} to V_{CCINT} through the decoupling capacitor and ferrite bead.
- (3) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (4) The V_{CO} frequency reported by the Quartus II software in the PLL Summary section of the compilation report takes into consideration the V_{CO} post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the f_{VCO} specification.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source that is less than 200 ps.
- (6) Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL when an input jitter of 30 ps is applied.
- (7) With 100-MHz scanclk frequency.
- (8) The cascaded PLLs specification is applicable only with the following conditions:
 - Upstream PLL— $0.59 \text{ MHz} \leq \text{Upstream PLL bandwidth} < 1 \text{ MHz}$
 - Downstream PLL—Downstream PLL bandwidth $> 2 \text{ MHz}$
- (9) PLL cascading is not supported for transceiver applications.

Table 1–29 lists the active configuration mode specifications for Cyclone IV devices.

Table 1–29. Active Configuration Mode Specifications for Cyclone IV Devices

| Programming Mode | DCLK Range | Typical DCLK | Unit |
|-------------------------------------|------------|--------------|------|
| Active Parallel (AP) ⁽¹⁾ | 20 to 40 | 33 | MHz |
| Active Serial (AS) | 20 to 40 | 33 | MHz |

Note to Table 1–29:

(1) AP configuration mode is only supported for Cyclone IV E devices.

Table 1–30 lists the JTAG timing parameters and values for Cyclone IV devices.

Table 1–30. JTAG Timing Parameters for Cyclone IV Devices ⁽¹⁾

| Symbol | Parameter | Min | Max | Unit |
|-----------------------|--|-----|-----|------|
| t _{JCP} | TCK clock period | 40 | — | ns |
| t _{JCH} | TCK clock high time | 19 | — | ns |
| t _{JCL} | TCK clock low time | 19 | — | ns |
| t _{JPSU_TDI} | JTAG port setup time for TDI | 1 | — | ns |
| t _{JPSU_TMS} | JTAG port setup time for TMS | 3 | — | ns |
| t _{JPH} | JTAG port hold time | 10 | — | ns |
| t _{JPCO} | JTAG port clock to output ^{(2), (3)} | — | 15 | ns |
| t _{JPZX} | JTAG port high impedance to valid output ^{(2), (3)} | — | 15 | ns |
| t _{JPXZ} | JTAG port valid output to high impedance ^{(2), (3)} | — | 15 | ns |
| t _{JSSU} | Capture register setup time | 5 | — | ns |
| t _{JSH} | Capture register hold time | 10 | — | ns |
| t _{JSCO} | Update register clock to output | — | 25 | ns |
| t _{JSZX} | Update register high impedance to valid output | — | 25 | ns |
| t _{JSXZ} | Update register valid output to high impedance | — | 25 | ns |

Notes to Table 1–30:

(1) For more information about JTAG waveforms, refer to “JTAG Waveform” in “Glossary” on page 1–37.

(2) The specification is shown for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 16 ns.

(3) For EP4CGX22, EP4CGX30 (F324 and smaller package), EP4CGX110, and EP4CGX150 devices, the output time specification for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins is 16 ns. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 18 ns.

Periphery Performance

This section describes periphery performance, including high-speed I/O and external memory interface.

I/O performance supports several system interfaces, such as the high-speed I/O interface, external memory interface, and the PCI/PCI-X bus interface. I/Os using the SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speeds. I/Os using general-purpose I/O standards such as 3.3-, 3.0-, 2.5-, 1.8-, or 1.5-V LVTTL/LVCMOS are capable of a typical 200 MHz interfacing frequency with a 10 pF load.

Table 1-31. RSDS Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (2), (4)} (Part 2 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|----------------------------------|-------|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| t _{LOCK} ⁽³⁾ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1-31:

- (1) Applicable for true RSDS and emulated RSDS_E_3R transmitter.
- (2) Cyclone IV E devices—true RSDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Emulated RSDS transmitter is supported at the output pin of all I/O Banks.
Cyclone IV GX devices—true RSDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated RSDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (3) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (4) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1-32. Emulated RSDS_E_1R Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (3)} (Part 1 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|---|---------------------------------------|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f _{HCLK} (input clock frequency) | ×10 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×8 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×7 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×4 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×2 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×1 | 5 | — | 170 | 5 | — | 170 | 5 | — | 170 | 5 | — | 170 | 5 | — | 145 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 170 | 100 | — | 170 | 100 | — | 170 | 100 | — | 170 | 100 | — | 145 | Mbps |
| | ×8 | 80 | — | 170 | 80 | — | 170 | 80 | — | 170 | 80 | — | 170 | 80 | — | 145 | Mbps |
| | ×7 | 70 | — | 170 | 70 | — | 170 | 70 | — | 170 | 70 | — | 170 | 70 | — | 145 | Mbps |
| | ×4 | 40 | — | 170 | 40 | — | 170 | 40 | — | 170 | 40 | — | 170 | 40 | — | 145 | Mbps |
| | ×2 | 20 | — | 170 | 20 | — | 170 | 20 | — | 170 | 20 | — | 170 | 20 | — | 145 | Mbps |
| | ×1 | 10 | — | 170 | 10 | — | 170 | 10 | — | 170 | 10 | — | 170 | 10 | — | 145 | Mbps |
| t _{DUTY} | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 500 | — | — | 550 | — | — | 600 | — | — | 700 | ps |
| t _{RISE} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t _{FALL} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |

Table 1–32. Emulated RSDS_E_1R Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (3)} (Part 2 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|------------------|-------|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| $t_{LOCK}^{(2)}$ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1–32:

- (1) Emulated RSDS_E_1R transmitter is supported at the output pin of all I/O Banks of Cyclone IV E devices and I/O Banks 3, 4, 5, 6, 7, 8, and 9 of Cyclone IV GX devices.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–33. Mini-LVDS Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (2), (4)}

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|-------------------------------------|--------------------------------|-----|-----|-----|--------|-----|-------|--------|-----|-------|----------|-----|-------|-----|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f_{HSCLK} (input clock frequency) | ×10 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×8 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×7 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×4 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×2 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×1 | 5 | — | 400 | 5 | — | 311 | 5 | — | 311 | 5 | — | 311 | 5 | — | 265 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 400 | 100 | — | 311 | 100 | — | 311 | 100 | — | 311 | 100 | — | 265 | Mbps |
| | ×8 | 80 | — | 400 | 80 | — | 311 | 80 | — | 311 | 80 | — | 311 | 80 | — | 265 | Mbps |
| | ×7 | 70 | — | 400 | 70 | — | 311 | 70 | — | 311 | 70 | — | 311 | 70 | — | 265 | Mbps |
| | ×4 | 40 | — | 400 | 40 | — | 311 | 40 | — | 311 | 40 | — | 311 | 40 | — | 265 | Mbps |
| | ×2 | 20 | — | 400 | 20 | — | 311 | 20 | — | 311 | 20 | — | 311 | 20 | — | 265 | Mbps |
| | ×1 | 10 | — | 400 | 10 | — | 311 | 10 | — | 311 | 10 | — | 311 | 10 | — | 265 | Mbps |
| t_{DUTY} | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 500 | — | — | 550 | — | — | 600 | — | — | 700 | ps |
| t_{RISE} | 20 – 80%, $C_{LOAD} = 5$ pF | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t_{FALL} | 20 – 80%, $C_{LOAD} = 5$ pF | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| $t_{LOCK}^{(3)}$ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1–33:

- (1) Applicable for true and emulated mini-LVDS transmitter.
- (2) Cyclone IV E—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Emulated mini-LVDS transmitter is supported at the output pin of all I/O banks.
Cyclone IV GX—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated mini-LVDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (3) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (4) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–44 and Table 1–45 list the IOE programmable delay for Cyclone IV GX devices.

Table 1–44. IOE Programmable Delay on Column Pins for Cyclone IV GX Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Settings | Min Offset | Max Offset | | | | | | Unit |
|---|-----------------------------|--------------------|------------|-------------|-------|-------------|-------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | | |
| | | | | C6 | I7 | C6 | C7 | C8 | I7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.313 | 1.209 | 2.184 | 2.336 | 2.451 | 2.387 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.312 | 1.208 | 2.200 | 2.399 | 2.554 | 2.446 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.438 | 0.404 | 0.751 | 0.825 | 0.886 | 0.839 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.713 | 0.682 | 1.228 | 1.41 | 1.566 | 1.424 | ns |

Notes to Table 1–44:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–45. IOE Programmable Delay on Row Pins for Cyclone IV GX Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Settings | Min Offset | Max Offset | | | | | | Unit |
|---|-----------------------------|--------------------|------------|-------------|-------|-------------|-------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | | |
| | | | | C6 | I7 | C6 | C7 | C8 | I7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.314 | 1.210 | 2.209 | 2.398 | 2.526 | 2.443 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.313 | 1.208 | 2.205 | 2.406 | 2.563 | 2.450 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.461 | 0.421 | 0.789 | 0.869 | 0.933 | 0.884 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.712 | 0.682 | 1.225 | 1.407 | 1.562 | 1.421 | ns |

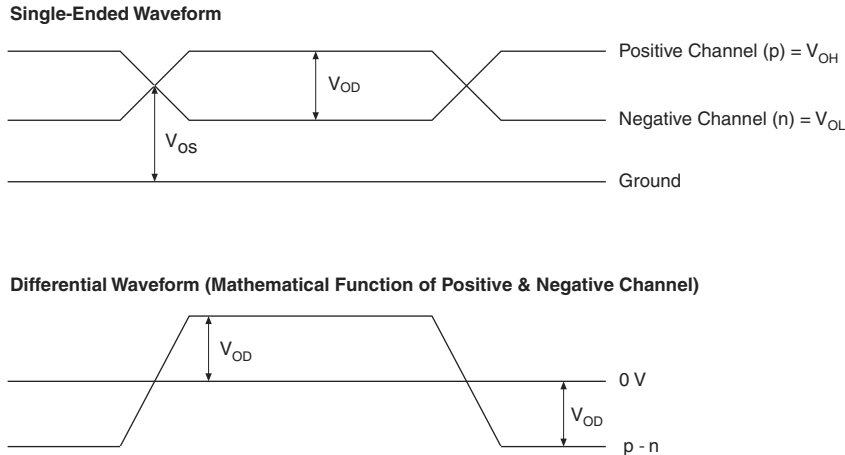
Notes to Table 1–45:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software

Table 1-46. Glossary (Part 2 of 5)

| Letter | Term | Definitions |
|----------|---------------|--|
| J | JTAG Waveform | <p>The diagram illustrates the JTAG waveform with the following timing parameters:</p> <ul style="list-style-type: none"> t_{JCP}: Time from TCK rising edge to TDI setup. t_{JCH}: Time from TCK rising edge to TDI hold. t_{JCL}: Time from TCK falling edge to TDI setup. t_{JCH}: Time from TCK falling edge to TDI hold. t_{JPSU_TDI}: Setup time for TDI before TCK rising edge. t_{JPSU_TMS}: Setup time for TMS before TCK rising edge. t_{JPH}: Hold time for TMS after TCK rising edge. t_{JPZX}: Time from TCK rising edge to TDO setup. t_{JPCO}: Time from TCK rising edge to TDO output. t_{JPXZ}: Time from TCK rising edge to TDO hold. t_{JSSU}: Setup time for Signal to be Captured before TCK rising edge. t_{JSH}: Hold time for Signal to be Captured after TCK rising edge. t_{JSZX}: Time from TCK rising edge to Signal to be Driven setup. t_{JSCO}: Time from TCK rising edge to Signal to be Driven output. t_{JSXZ}: Time from TCK rising edge to Signal to be Driven hold. |
| K | — | — |
| L | — | — |
| M | — | — |
| N | — | — |
| O | — | — |
| P | PLL Block | <p>The following highlights the PLL specification parameters:</p> <p>The diagram shows the internal structure of the PLL block. It includes a Switchover block, a Core Clock input, a CLK input, a divider N, a PFD (Phase-Frequency Divider), a CP (Charge Pump), a LF (Loop Filter), a VCO (Voltage-Controlled Oscillator), a phase tap, a divider M, and a counters block (C0..C4). The output is f_{OUT}, which can be connected to CLKOUT Pins or GCLK. The external output frequency is f_{OUT_EXT}.</p> <p>Key</p> <ul style="list-style-type: none"> Reconfigurable in User Mode |
| Q | — | — |

Table 1-46. Glossary (Part 4 of 5)

| Letter | Term | Definitions |
|--------|--------------------------------|---|
| T | t_C | High-speed receiver and transmitter input and output clock period. |
| | Channel-to-channel-skew (TCCS) | High-speed I/O block: The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement. |
| | t_{cin} | Delay from the clock pad to the I/O input register. |
| | t_{CO} | Delay from the clock pad to the I/O output. |
| | t_{cout} | Delay from the clock pad to the I/O output register. |
| | t_{DUTY} | High-speed I/O block: Duty cycle on high-speed transmitter output clock. |
| | t_{FALL} | Signal high-to-low transition time (80–20%). |
| | t_H | Input register hold time. |
| | Timing Unit Interval (TUI) | High-speed I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(\text{Receiver Input Clock Frequency Multiplication Factor}) = t_C/w$). |
| | $t_{INJITTER}$ | Period jitter on the PLL clock input. |
| | $t_{OUTJITTER_DEDCLK}$ | Period jitter on the dedicated clock output driven by a PLL. |
| | $t_{OUTJITTER_IO}$ | Period jitter on the general purpose I/O driven by a PLL. |
| | t_{pllcin} | Delay from the PLL inclk pad to the I/O input register. |
| | $t_{pllcout}$ | Delay from the PLL inclk pad to the I/O output register. |
| | Transmitter Output Waveform | <p>Transmitter output waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards:</p>  |
| | t_{RISE} | Signal low-to-high transition time (20–80%). |
| | t_{SU} | Input register setup time. |
| U | — | — |

Document Revision History

Table 1–47 lists the revision history for this chapter.

Table 1–47. Document Revision History

| Date | Version | Changes |
|---------------|---------|--|
| March 2016 | 2.0 | Updated note (5) in Table 1–21 to remove support for the N148 package. |
| October 2014 | 1.9 | Updated maximum value for V_{CCD_PLL} in Table 1–1. Removed extended temperature note in Table 1–3. |
| December 2013 | 1.8 | Updated Table 1–21 by adding Note (15). |
| May 2013 | 1.7 | Updated Table 1–15 by adding Note (4). |
| October 2012 | 1.6 | <ul style="list-style-type: none"> ■ Updated the maximum value for V_I, V_{CCD_PLL}, V_{CCIO}, V_{CC_CLKIN}, V_{CCH_GXB}, and V_{CCA_GXB} in Table 1–1. ■ Updated Table 1–11 and Table 1–22. ■ Updated Table 1–21 to include peak-to-peak differential input voltage for the Cyclone IV GX transceiver input reference clock. ■ Updated Table 1–29 to include the typical $DCLK$ value. ■ Updated the minimum f_{HCLK} value in Table 1–31, Table 1–32, Table 1–33, Table 1–34, and Table 1–35. |
| November 2011 | 1.5 | <ul style="list-style-type: none"> ■ Updated “Maximum Allowed Overshoot or Undershoot Voltage”, “Operating Conditions”, and “PLL Specifications” sections. ■ Updated Table 1–2, Table 1–3, Table 1–4, Table 1–5, Table 1–8, Table 1–9, Table 1–15, Table 1–18, Table 1–19, and Table 1–21. ■ Updated Figure 1–1. |
| December 2010 | 1.4 | <ul style="list-style-type: none"> ■ Updated for the Quartus II software version 10.1 release. ■ Updated Table 1–21 and Table 1–25. ■ Minor text edits. |
| July 2010 | 1.3 | <p>Updated for the Quartus II software version 10.0 release:</p> <ul style="list-style-type: none"> ■ Updated Table 1–3, Table 1–4, Table 1–21, Table 1–25, Table 1–28, Table 1–30, Table 1–40, Table 1–41, Table 1–42, Table 1–43, Table 1–44, and Table 1–45. ■ Updated Figure 1–2 and Figure 1–3. ■ Removed SW Requirement and TCCS for Cyclone IV Devices tables. ■ Minor text edits. |
| March 2010 | 1.2 | <p>Updated to include automotive devices:</p> <ul style="list-style-type: none"> ■ Updated the “Operating Conditions” and “PLL Specifications” sections. ■ Updated Table 1–1, Table 1–8, Table 1–9, Table 1–21, Table 1–26, Table 1–27, Table 1–31, Table 1–32, Table 1–33, Table 1–34, Table 1–35, Table 1–36, Table 1–37, Table 1–38, Table 1–40, Table 1–42, and Table 1–43. ■ Added Table 1–5 to include ESD for Cyclone IV devices GPIOs and HSSI I/Os. ■ Added Table 1–44 and Table 1–45 to include IOE programmable delay for Cyclone IV E 1.2 V core voltage devices. ■ Minor text edits. |