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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|---|
| Product Status | Active |
| Number of LABs/CLBs | 9360 |
| Number of Logic Elements/Cells | 149760 |
| Total RAM Bits | 6635520 |
| Number of I/O | 270 |
| Number of Gates | - |
| Voltage - Supply | 1.16V ~ 1.24V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 484-BGA |
| Supplier Device Package | 484-FBGA (23x23) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/ep4cgx150cf23i7 |


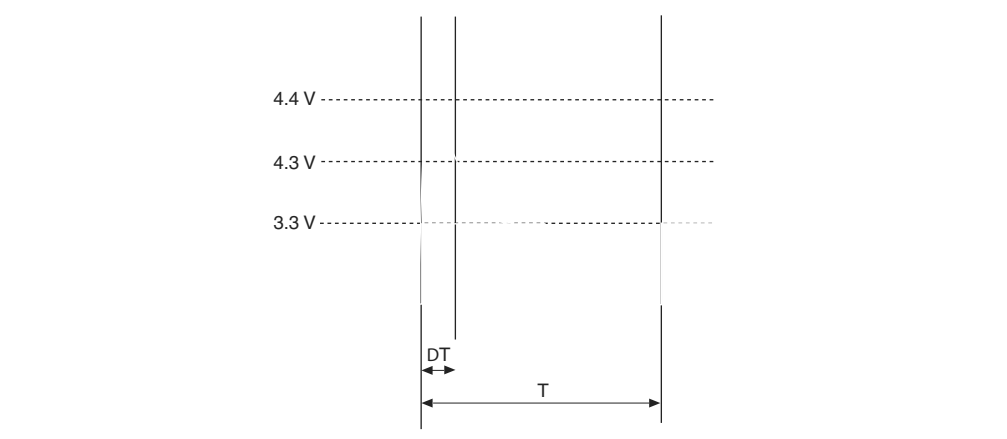
 A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices

| Symbol | Parameter | Condition (V) | Overshoot Duration as % of High Time | Unit |
|--------|------------------|---------------|--------------------------------------|------|
| V_i | AC Input Voltage | $V_i = 4.20$ | 100 | % |
| | | $V_i = 4.25$ | 98 | % |
| | | $V_i = 4.30$ | 65 | % |
| | | $V_i = 4.35$ | 43 | % |
| | | $V_i = 4.40$ | 29 | % |
| | | $V_i = 4.45$ | 20 | % |
| | | $V_i = 4.50$ | 13 | % |
| | | $V_i = 4.55$ | 9 | % |
| | | $V_i = 4.60$ | 6 | % |

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as $([\Delta T]/T) \times 100$. This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

Figure 1–1. Cyclone IV Devices Overshoot Duration



Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices ⁽¹⁾, ⁽²⁾ (Part 1 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|--|--|------------|-----|------------|------|
| $V_{CCINT}^{(3)}$ | Supply voltage for internal logic, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply voltage for internal logic, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| $V_{CCIO}^{(3), (4)}$ | Supply voltage for output buffers, 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Supply voltage for output buffers, 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | Supply voltage for output buffers, 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Supply voltage for output buffers, 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Supply voltage for output buffers, 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Supply voltage for output buffers, 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| $V_{CCA}^{(3)}$ | Supply (analog) voltage for PLL regulator | — | 2.375 | 2.5 | 2.625 | V |
| $V_{CCD_PLL}^{(3)}$ | Supply (digital) voltage for PLL, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply (digital) voltage for PLL, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| V_I | Input voltage | — | –0.5 | — | 3.6 | V |
| V_O | Output voltage | — | 0 | — | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | — | 85 | °C |
| | | For industrial use | –40 | — | 100 | °C |
| | | For extended temperature | –40 | — | 125 | °C |
| | | For automotive use | –40 | — | 125 | °C |
| t_{RAMP} | Power supply ramp time | Standard power-on reset (POR) ⁽⁵⁾ | 50 μ s | — | 50 ms | — |
| | | Fast POR ⁽⁶⁾ | 50 μ s | — | 3 ms | — |

Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices ^{(1), (2)} (Part 2 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------|--|------------|-----|-----|-----|------|
| I_{Diode} | Magnitude of DC current across PCI-clamp diode when enable | — | — | — | 10 | mA |

Notes to Table 1–3:

- (1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades.
- (2) V_{CCIO} for all I/O banks must be powered up during device operation. All V_{CCA} pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (3) V_{CC} must rise monotonically.
- (4) V_{CCIO} powers all input buffers.
- (5) The POR time for Standard POR ranges between 50 and 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) The POR time for Fast POR ranges between 3 and 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.

Table 1–4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 1 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|--|--|------------|-------|-----|-------|------|
| V_{CCINT} ⁽³⁾ | Core voltage, PCIe hard IP block, and transceiver PCS power supply | — | 1.16 | 1.2 | 1.24 | V |
| V_{CCA} ^{(1), (3)} | PLL analog power supply | — | 2.375 | 2.5 | 2.625 | V |
| V_{CCD_PLL} ⁽²⁾ | PLL digital power supply | — | 1.16 | 1.2 | 1.24 | V |
| V_{CCIO} ^{(3), (4)} | I/O banks power supply for 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | I/O banks power supply for 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | I/O banks power supply for 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | I/O banks power supply for 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | I/O banks power supply for 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | I/O banks power supply for 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| V_{CC_CLKIN} ^{(3), (5), (6)} | Differential clock input pins power supply for 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Differential clock input pins power supply for 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | Differential clock input pins power supply for 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Differential clock input pins power supply for 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Differential clock input pins power supply for 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Differential clock input pins power supply for 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| V_{CCH_GXB} | Transceiver output buffer power supply | — | 2.375 | 2.5 | 2.625 | V |

Table 1–7. Bus Hold Parameter for Cyclone IV Devices (Part 2 of 2) ⁽¹⁾

| Parameter | Condition | V _{CCIO} (V) | | | | | | | | | | | | Unit |
|---------------------|-----------|-----------------------|-----|-------|-------|------|------|-----|-----|-----|-----|-----|-----|------|
| | | 1.2 | | 1.5 | | 1.8 | | 2.5 | | 3.0 | | 3.3 | | |
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| Bus hold trip point | — | 0.3 | 0.9 | 0.375 | 1.125 | 0.68 | 1.07 | 0.7 | 1.7 | 0.8 | 2 | 0.8 | 2 | V |

Note to Table 1–7:

(1) Bus hold trip points are based on the calculated input voltages from the JEDEC standard.

OCT Specifications

Table 1–8 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

Table 1–8. Series OCT Without Calibration Specifications for Cyclone IV Devices

| Description | V_{CCIO} (V) | Resistance Tolerance | | Unit |
|--------------------------------|----------------|----------------------|---|------|
| | | Commercial Maximum | Industrial, Extended industrial, and Automotive Maximum | |
| Series OCT without calibration | 3.0 | ±30 | ±40 | % |
| | 2.5 | ±30 | ±40 | % |
| | 1.8 | ±40 | ±50 | % |
| | 1.5 | ±50 | ±50 | % |
| | 1.2 | ±50 | ±50 | % |

OCT calibration is automatically performed at device power-up for OCT-enabled I/Os.

Table 1–9 lists the OCT calibration accuracy at device power-up.

Table 1–9. Series OCT with Calibration at Device Power-Up Specifications for Cyclone IV Devices

| Description | V_{CCIO} (V) | Calibration Accuracy | | Unit |
|--|----------------|----------------------|---|------|
| | | Commercial Maximum | Industrial, Extended industrial, and Automotive Maximum | |
| Series OCT with calibration at device power-up | 3.0 | ±10 | ±10 | % |
| | 2.5 | ±10 | ±10 | % |
| | 1.8 | ±10 | ±10 | % |
| | 1.5 | ±10 | ±10 | % |
| | 1.2 | ±10 | ±10 | % |

Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1-12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

Table 1-12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices ⁽¹⁾

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------|--|--|-----|-----|-----|------|
| R _{PU} | Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you enable the programmable pull-up resistor option | V _{CCIO} = 3.3 V ± 5% ^{(2), (3)} | 7 | 25 | 41 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ^{(2), (3)} | 7 | 28 | 47 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ^{(2), (3)} | 8 | 35 | 61 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ^{(2), (3)} | 10 | 57 | 108 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ^{(2), (3)} | 13 | 82 | 163 | kΩ |
| | | V _{CCIO} = 1.2 V ± 5% ^{(2), (3)} | 19 | 143 | 351 | kΩ |
| R _{PD} | Value of the I/O pin pull-down resistor before and during configuration | V _{CCIO} = 3.3 V ± 5% ⁽⁴⁾ | 6 | 19 | 30 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ⁽⁴⁾ | 6 | 22 | 36 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ⁽⁴⁾ | 6 | 25 | 43 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ⁽⁴⁾ | 7 | 35 | 71 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ⁽⁴⁾ | 8 | 50 | 112 | kΩ |

Notes to Table 1-12:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO}.
- (3) $R_{PU} = (V_{CCIO} - V_I) / I_{R_{PU}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = V_{CC} + 5% - 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = 0 V;
Maximum condition: 100°C; V_{CCIO} = V_{CC} - 5%, V_I = 0 V; in which V_I refers to the input voltage at the I/O pin.
- (4) $R_{PD} = V_I / I_{R_{PD}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = V_{CC} - 5%;
Maximum condition: 100°C; V_{CCIO} = V_{CC} - 5%, V_I = V_{CC} - 5%; in which V_I refers to the input voltage at the I/O pin.

Hot-Socketing

Table 1-13 lists the hot-socketing specifications for Cyclone IV devices.

Table 1-13. Hot-Socketing Specifications for Cyclone IV Devices

| Symbol | Parameter | Maximum |
|-------------------------|-----------------------------------|---------------------|
| I _{IOPIN(DC)} | DC current per I/O pin | 300 μA |
| I _{IOPIN(AC)} | AC current per I/O pin | 8 mA ⁽¹⁾ |
| I _{XCVRTX(DC)} | DC current per transceiver TX pin | 100 mA |
| I _{XCVRRX(DC)} | DC current per transceiver RX pin | 50 mA |

Note to Table 1-13:

- (1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |I_{IOPIN}| = C dv/dt, in which C is the I/O pin capacitance and dv/dt is the slew rate.



During hot-socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF.

Schmitt Trigger Input

Cyclone IV devices support Schmitt trigger input on the TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with slow edge rate. Table 1–14 lists the hysteresis specifications across the supported V_{CCIO} range for Schmitt trigger inputs in Cyclone IV devices.

Table 1–14. Hysteresis Specifications for Schmitt Trigger Input in Cyclone IV Devices

| Symbol | Parameter | Conditions (V) | Minimum | Unit |
|---------------|--------------------------------------|------------------|---------|------|
| $V_{SCHMITT}$ | Hysteresis for Schmitt trigger input | $V_{CCIO} = 3.3$ | 200 | mV |
| | | $V_{CCIO} = 2.5$ | 200 | mV |
| | | $V_{CCIO} = 1.8$ | 140 | mV |
| | | $V_{CCIO} = 1.5$ | 110 | mV |

I/O Standard Specifications

The following tables list input voltage sensitivities (V_{IH} and V_{IL}), output voltage (V_{OH} and V_{OL}), and current drive characteristics (I_{OH} and I_{OL}), for various I/O standards supported by Cyclone IV devices. Table 1–15 through Table 1–20 provide the I/O standard specifications for Cyclone IV devices.

Table 1–15. Single-Ended I/O Standard Specifications for Cyclone IV Devices ^{(1), (2)}

| I/O Standard | V_{CCIO} (V) | | | V_{IL} (V) | | V_{IH} (V) | | V_{OL} (V) | V_{OH} (V) | I_{OL} (mA) (4) | I_{OH} (mA) (4) |
|-----------------------------|----------------|-----|-------|--------------|------------------------|------------------------|------------------|------------------------|------------------------|----------------------|----------------------|
| | Min | Typ | Max | Min | Max | Min | Max | Max | Min | | |
| 3.3-V LVTTTL ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.45 | 2.4 | 4 | –4 |
| 3.3-V LVCMOS ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.2 | $V_{CCIO} - 0.2$ | 2 | –2 |
| 3.0-V LVTTTL ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.45 | 2.4 | 4 | –4 |
| 3.0-V LVCMOS ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.2 | $V_{CCIO} - 0.2$ | 0.1 | –0.1 |
| 2.5 V ⁽³⁾ | 2.375 | 2.5 | 2.625 | –0.3 | 0.7 | 1.7 | $V_{CCIO} + 0.3$ | 0.4 | 2.0 | 1 | –1 |
| 1.8 V | 1.71 | 1.8 | 1.89 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | 2.25 | 0.45 | $V_{CCIO} - 0.45$ | 2 | –2 |
| 1.5 V | 1.425 | 1.5 | 1.575 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 1.2 V | 1.14 | 1.2 | 1.26 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 3.0-V PCI | 2.85 | 3.0 | 3.15 | — | $0.3 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |
| 3.0-V PCI-X | 2.85 | 3.0 | 3.15 | — | $0.35 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |

Notes to Table 1–15:

- (1) For voltage-referenced receiver input waveform and explanation of terms used in Table 1–15, refer to “Glossary” on page 1–37.
- (2) AC load $CL = 10$ pF
- (3) For more information about interfacing Cyclone IV devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O standards, refer to *AN 447: Interfacing Cyclone III and Cyclone IV Devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O Systems*.
- (4) To meet the I_{OL} and I_{OH} specifications, you must set the current strength settings accordingly. For example, to meet the **3.3-V LVTTTL** specification (4 mA), set the current strength settings to 4 mA or higher. Setting at lower current strength may not meet the I_{OL} and I_{OH} specifications in the handbook.

Table 1-16. Single-Ended SSTL and HSTL I/O Reference Voltage Specifications for Cyclone IV Devices ⁽¹⁾

| I/O Standard | V _{CCIO} (V) | | | V _{REF} (V) | | | V _{TT} (V) ⁽²⁾ | | |
|---------------------|-----------------------|-----|-------|---|--|---|------------------------------------|-------------------------|-------------------------|
| | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |
| SSTL-2 Class I, II | 2.375 | 2.5 | 2.625 | 1.19 | 1.25 | 1.31 | V _{REF} - 0.04 | V _{REF} | V _{REF} + 0.04 |
| SSTL-18 Class I, II | 1.7 | 1.8 | 1.9 | 0.833 | 0.9 | 0.969 | V _{REF} - 0.04 | V _{REF} | V _{REF} + 0.04 |
| HSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.85 | 0.9 | 0.95 | 0.85 | 0.9 | 0.95 |
| HSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.71 | 0.75 | 0.79 | 0.71 | 0.75 | 0.79 |
| HSTL-12 Class I, II | 1.14 | 1.2 | 1.26 | 0.48 x V _{CCIO} ⁽³⁾ | 0.5 x V _{CCIO} ⁽³⁾ | 0.52 x V _{CCIO} ⁽³⁾ | — | 0.5 x V _{CCIO} | — |
| | | | | 0.47 x V _{CCIO} ⁽⁴⁾ | 0.5 x V _{CCIO} ⁽⁴⁾ | 0.53 x V _{CCIO} ⁽⁴⁾ | | | |

Notes to Table 1-16:

- (1) For an explanation of terms used in Table 1-16, refer to “Glossary” on page 1-37.
- (2) V_{TT} of the transmitting device must track V_{REF} of the receiving device.
- (3) Value shown refers to DC input reference voltage, V_{REF(DC)}.
- (4) Value shown refers to AC input reference voltage, V_{REF(AC)}.

Table 1-17. Single-Ended SSTL and HSTL I/O Standards Signal Specifications for Cyclone IV Devices

| I/O Standard | V _{IL(DC)} (V) | | V _{IH(DC)} (V) | | V _{IL(AC)} (V) | | V _{IH(AC)} (V) | | V _{OL} (V) | V _{OH} (V) | I _{OL} (mA) | I _{OH} (mA) |
|------------------|-------------------------|--------------------------|--------------------------|--------------------------|-------------------------|-------------------------|-------------------------|--------------------------|--------------------------|--------------------------|----------------------|----------------------|
| | Min | Max | Min | Max | Min | Max | Min | Max | Max | Min | | |
| SSTL-2 Class I | — | V _{REF} - 0.18 | V _{REF} + 0.18 | — | — | V _{REF} - 0.35 | V _{REF} + 0.35 | — | V _{TT} - 0.57 | V _{TT} + 0.57 | 8.1 | -8.1 |
| SSTL-2 Class II | — | V _{REF} - 0.18 | V _{REF} + 0.18 | — | — | V _{REF} - 0.35 | V _{REF} + 0.35 | — | V _{TT} - 0.76 | V _{TT} + 0.76 | 16.4 | -16.4 |
| SSTL-18 Class I | — | V _{REF} - 0.125 | V _{REF} + 0.125 | — | — | V _{REF} - 0.25 | V _{REF} + 0.25 | — | V _{TT} - 0.475 | V _{TT} + 0.475 | 6.7 | -6.7 |
| SSTL-18 Class II | — | V _{REF} - 0.125 | V _{REF} + 0.125 | — | — | V _{REF} - 0.25 | V _{REF} + 0.25 | — | 0.28 | V _{CCIO} - 0.28 | 13.4 | -13.4 |
| HSTL-18 Class I | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 8 | -8 |
| HSTL-18 Class II | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 16 | -16 |
| HSTL-15 Class I | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 8 | -8 |
| HSTL-15 Class II | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 16 | -16 |
| HSTL-12 Class I | -0.15 | V _{REF} - 0.08 | V _{REF} + 0.08 | V _{CCIO} + 0.15 | -0.24 | V _{REF} - 0.15 | V _{REF} + 0.15 | V _{CCIO} + 0.24 | 0.25 x V _{CCIO} | 0.75 x V _{CCIO} | 8 | -8 |
| HSTL-12 Class II | -0.15 | V _{REF} - 0.08 | V _{REF} + 0.08 | V _{CCIO} + 0.15 | -0.24 | V _{REF} - 0.15 | V _{REF} + 0.15 | V _{CCIO} + 0.24 | 0.25 x V _{CCIO} | 0.75 x V _{CCIO} | 14 | -14 |

For more information about receiver input and transmitter output waveforms, and for other differential I/O standards, refer to the *I/O Features in Cyclone IV Devices* chapter.

Table 1–18. Differential SSTL I/O Standard Specifications for Cyclone IV Devices ⁽¹⁾

| I/O Standard | V_{CCIO} (V) | | | $V_{Swing(DC)}$ (V) | | $V_{X(AC)}$ (V) | | | $V_{Swing(AC)}$ (V) | | $V_{OX(AC)}$ (V) | | |
|------------------------|----------------|-----|-------|---------------------|------------|----------------------|-----|----------------------|---------------------|------------|----------------------|-----|----------------------|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Max | Min | Typ | Max |
| SSTL-2 Class I, II | 2.375 | 2.5 | 2.625 | 0.36 | V_{CCIO} | $V_{CCIO}/2 - 0.2$ | — | $V_{CCIO}/2 + 0.2$ | 0.7 | V_{CCIO} | $V_{CCIO}/2 - 0.125$ | — | $V_{CCIO}/2 + 0.125$ |
| SSTL-18 Class I, II | 1.7 | 1.8 | 1.90 | 0.25 | V_{CCIO} | $V_{CCIO}/2 - 0.175$ | — | $V_{CCIO}/2 + 0.175$ | 0.5 | V_{CCIO} | $V_{CCIO}/2 - 0.125$ | — | $V_{CCIO}/2 + 0.125$ |

Note to Table 1–18:(1) Differential SSTL requires a V_{REF} input.**Table 1–19. Differential HSTL I/O Standard Specifications for Cyclone IV Devices ⁽¹⁾**

| I/O Standard | V_{CCIO} (V) | | | $V_{DIF(DC)}$ (V) | | $V_{X(AC)}$ (V) | | | $V_{CM(DC)}$ (V) | | | $V_{DIF(AC)}$ (V) | |
|------------------------|----------------|-----|-------|-------------------|------------|------------------------|-----|------------------------|------------------------|-----|------------------------|-------------------|------------------------|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Typ | Max | Min | Max |
| HSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.2 | — | 0.85 | — | 0.95 | 0.85 | — | 0.95 | 0.4 | — |
| HSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.2 | — | 0.71 | — | 0.79 | 0.71 | — | 0.79 | 0.4 | — |
| HSTL-12 Class I, II | 1.14 | 1.2 | 1.26 | 0.16 | V_{CCIO} | $0.48 \times V_{CCIO}$ | — | $0.52 \times V_{CCIO}$ | $0.48 \times V_{CCIO}$ | — | $0.52 \times V_{CCIO}$ | 0.3 | $0.48 \times V_{CCIO}$ |

Note to Table 1–19:(1) Differential HSTL requires a V_{REF} input.**Table 1–20. Differential I/O Standard Specifications for Cyclone IV Devices ⁽¹⁾ (Part 1 of 2)**

| I/O Standard | V_{CCIO} (V) | | | V_{ID} (mV) | | V_{ICM} (V) ⁽²⁾ | | | V_{OD} (mV) ⁽³⁾ | | | V_{OS} (V) ⁽³⁾ | | |
|--|----------------|-----|-------|---------------|-----|------------------------------|---|------|------------------------------|-----|-----|-----------------------------|------|-------|
| | Min | Typ | Max | Min | Max | Min | Condition | Max | Min | Typ | Max | Min | Typ | Max |
| LVPECL (Row I/Os) ⁽⁶⁾ | 2.375 | 2.5 | 2.625 | 100 | — | 0.05 | $D_{MAX} \leq 500$ Mbps | 1.80 | — | — | — | — | — | — |
| | | | | | | 0.55 | $500 \text{ Mbps} \leq D_{MAX} \leq 700$ Mbps | 1.80 | | | | | | |
| | | | | | | 1.05 | $D_{MAX} > 700$ Mbps | 1.55 | | | | | | |
| LVPECL (Column I/Os) ⁽⁶⁾ | 2.375 | 2.5 | 2.625 | 100 | — | 0.05 | $D_{MAX} \leq 500$ Mbps | 1.80 | — | — | — | — | — | — |
| | | | | | | 0.55 | $500 \text{ Mbps} \leq D_{MAX} \leq 700$ Mbps | 1.80 | | | | | | |
| | | | | | | 1.05 | $D_{MAX} > 700$ Mbps | 1.55 | | | | | | |
| LVDS (Row I/Os) | 2.375 | 2.5 | 2.625 | 100 | — | 0.05 | $D_{MAX} \leq 500$ Mbps | 1.80 | 247 | — | 600 | 1.125 | 1.25 | 1.375 |
| | | | | | | 0.55 | $500 \text{ Mbps} \leq D_{MAX} \leq 700$ Mbps | 1.80 | | | | | | |
| | | | | | | 1.05 | $D_{MAX} > 700$ Mbps | 1.55 | | | | | | |

Transceiver Performance Specifications

Table 1-21 lists the Cyclone IV GX transceiver specifications.

Table 1-21. Transceiver Specification for Cyclone IV GX Devices (Part 1 of 4)

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|--|---|-------------------------|------------|--------|-------------------------|------------|--------|-------------------------|------------|--------|--------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| Reference Clock | | | | | | | | | | | |
| Supported I/O Standards | 1.2 V PCML, 1.5 V PCML, 3.3 V PCML, Differential LVPECL, LVDS, HCSL | | | | | | | | | | |
| Input frequency from REFCLK input pins | — | 50 | — | 156.25 | 50 | — | 156.25 | 50 | — | 156.25 | MHz |
| Spread-spectrum modulating clock frequency | Physical interface for PCI Express (PIPE) mode | 30 | — | 33 | 30 | — | 33 | 30 | — | 33 | kHz |
| Spread-spectrum downspread | PIPE mode | — | 0 to –0.5% | — | — | 0 to –0.5% | — | — | 0 to –0.5% | — | — |
| Peak-to-peak differential input voltage | — | 0.1 | — | 1.6 | 0.1 | — | 1.6 | 0.1 | — | 1.6 | V |
| V _{ICM} (AC coupled) | — | 1100 ± 5% | | | 1100 ± 5% | | | 1100 ± 5% | | | mV |
| V _{ICM} (DC coupled) | HCSL I/O standard for PCIe reference clock | 250 | — | 550 | 250 | — | 550 | 250 | — | 550 | mV |
| Transmitter REFCLK Phase Noise ⁽¹⁾ | Frequency offset = 1 MHz – 8 MHz | — | — | –123 | — | — | –123 | — | — | –123 | dBc/Hz |
| Transmitter REFCLK Total Jitter ⁽¹⁾ | | — | — | 42.3 | — | — | 42.3 | — | — | 42.3 | ps |
| R _{ref} | — | — | 2000 ± 1% | — | — | 2000 ± 1% | — | — | 2000 ± 1% | — | Ω |
| Transceiver Clock | | | | | | | | | | | |
| cal_blk_clk clock frequency | — | 10 | — | 125 | 10 | — | 125 | 10 | — | 125 | MHz |
| fixedclk clock frequency | PCIe Receiver Detect | — | 125 | — | — | 125 | — | — | 125 | — | MHz |
| reconfig_clk clock frequency | Dynamic reconfiguration clock frequency | 2.5/37.5 ⁽²⁾ | — | 50 | 2.5/37.5 ⁽²⁾ | — | 50 | 2.5/37.5 ⁽²⁾ | — | 50 | MHz |
| Delta time between reconfig_clk | — | — | — | 2 | — | — | 2 | — | — | 2 | ms |
| Transceiver block minimum power-down pulse width | — | — | 1 | — | — | 1 | — | — | 1 | — | μs |

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 4 of 4)

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|--|------------|------------------------------------|-----|--------|--------|-----|--------|-----|-----|--------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| PLD-Transceiver Interface | | | | | | | | | | | |
| Interface speed (F324 and smaller package) | — | 25 | — | 125 | 25 | — | 125 | 25 | — | 125 | MHz |
| Interface speed (F484 and larger package) | — | 25 | — | 156.25 | 25 | — | 156.25 | 25 | — | 156.25 | MHz |
| Digital reset pulse width | — | Minimum is 2 parallel clock cycles | | | | | | | | | |

Notes to Table 1–21:

- (1) This specification is valid for transmitter output jitter specification with a maximum total jitter value of 112 ps, typically for 3.125 Gbps SRIO and XAUI protocols.
- (2) The minimum `reconfig_clk` frequency is 2.5 MHz if the transceiver channel is configured in **Transmitter Only** mode. The minimum `reconfig_clk` frequency is 37.5 MHz if the transceiver channel is configured in **Receiver Only** or **Receiver and Transmitter** mode.
- (3) The device cannot tolerate prolonged operation at this absolute maximum.
- (4) The rate matcher supports only up to ± 300 parts per million (ppm).
- (5) Supported for the F169 and F324 device packages only.
- (6) Supported for the F484, F672, and F896 device packages only. Pending device characterization.
- (7) To support CDR ppm tolerance greater than ± 300 ppm, implement ppm detector in user logic and configure CDR to Manual Lock Mode.
- (8) Asynchronous spread-spectrum clocking is not supported.
- (9) For the EP4CGX30 (F484 package only), EP4CGX50, and EP4CGX75 devices, the CDR ppl tolerance is ± 200 ppm.
- (10) Time taken until `p11_locked` goes high after `p11_powerdown` deasserts.
- (11) Time that the CDR must be kept in lock-to-reference mode after `rx_analogreset` deasserts and before `rx_locktodata` is asserted in manual mode.
- (12) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode (Figure 1–2), or after `rx_freqlocked` signal goes high in automatic mode (Figure 1–3).
- (13) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode.
- (14) Time taken to recover valid data after the `rx_freqlocked` signal goes high in automatic mode.
- (15) To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.

Figure 1-2 shows the lock time parameters in manual mode.


 LTD = lock-to-data. LTR = lock-to-reference.

Figure 1-2. Lock Time Parameters for Manual Mode

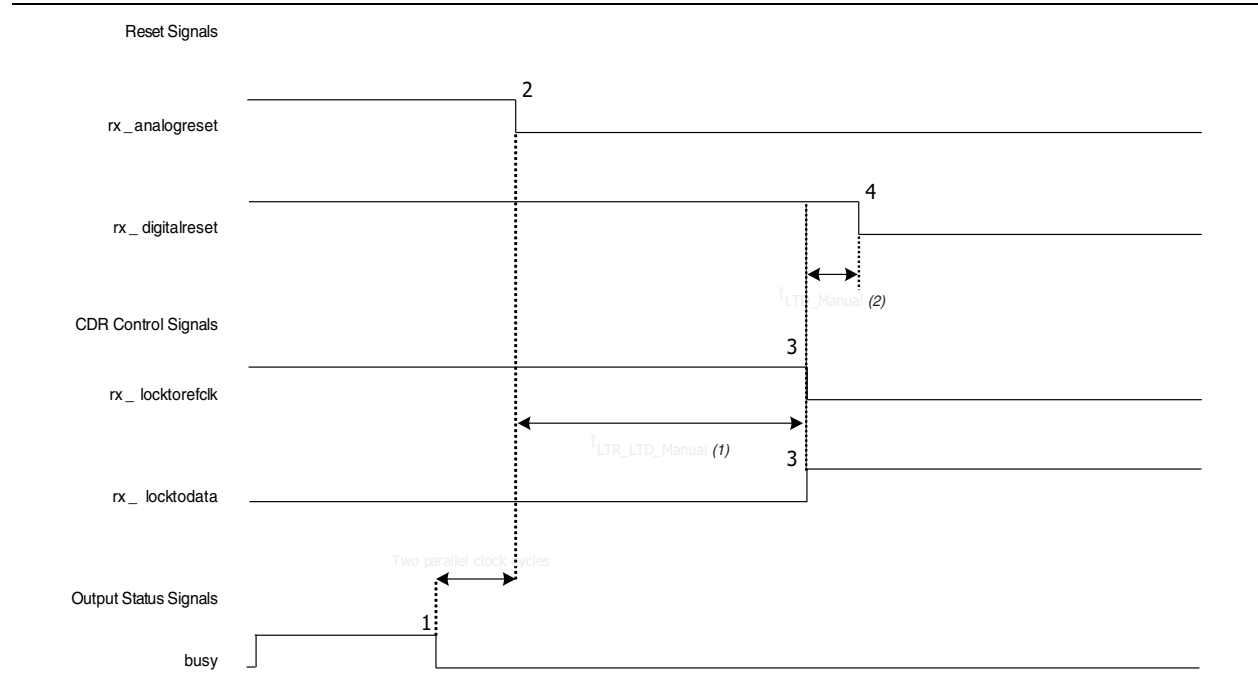


Figure 1-3 shows the lock time parameters in automatic mode.

Figure 1-3. Lock Time Parameters for Automatic Mode

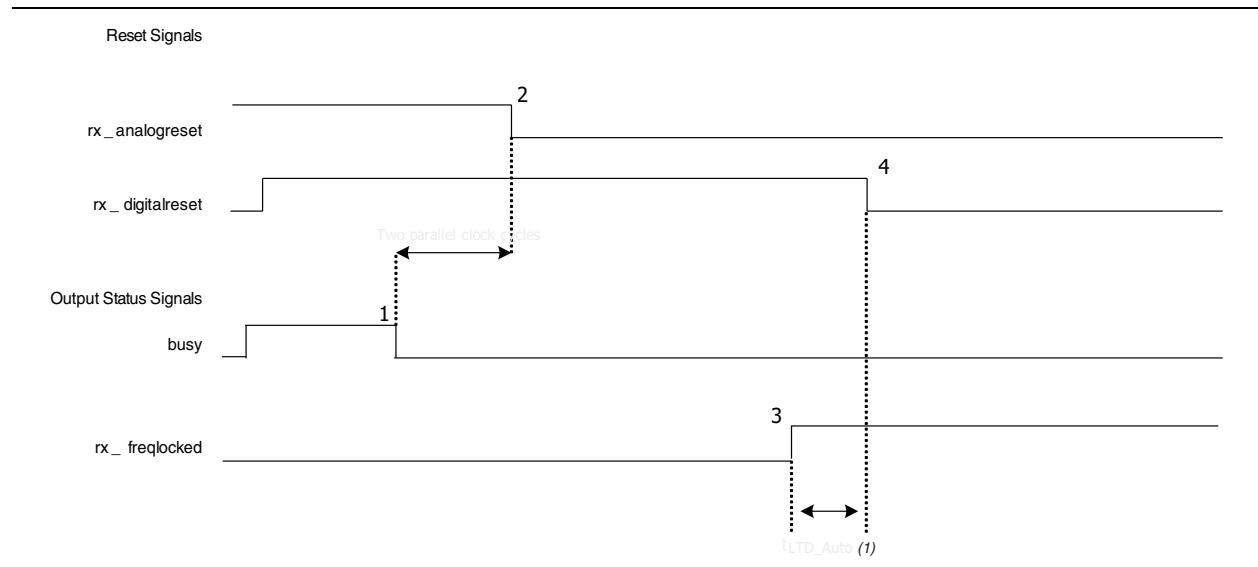


Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 2 of 2)

| Device | Performance | | | | | | | | Unit |
|-----------|-------------|-------|-----|--------------------|--------------------|-------|--------------------|----|------|
| | C6 | C7 | C8 | C8L ⁽¹⁾ | C9L ⁽¹⁾ | I7 | I8L ⁽¹⁾ | A7 | |
| EP4CE55 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE75 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE115 | — | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CGX15 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX22 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX30 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX50 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX75 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX110 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX150 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |

Note to Table 1–24:

(1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades.

PLL Specifications

Table 1–25 lists the PLL specifications for Cyclone IV devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (–40°C to 100°C), the extended industrial junction temperature range (–40°C to 125°C), and the automotive junction temperature range (–40°C to 125°C). For more information about the PLL block, refer to “Glossary” on page 1–37.

Table 1–25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 1 of 2)


| Symbol | Parameter | Min | Typ | Max | Unit |
|---|---|-----|-----|-------|------|
| f_{IN} ⁽³⁾ | Input clock frequency (–6, –7, –8 speed grades) | 5 | — | 472.5 | MHz |
| | Input clock frequency (–8L speed grade) | 5 | — | 362 | MHz |
| | Input clock frequency (–9L speed grade) | 5 | — | 265 | MHz |
| f_{INPFD} | PFD input frequency | 5 | — | 325 | MHz |
| f_{VCO} ⁽⁴⁾ | PLL internal VCO operating range | 600 | — | 1300 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | — | 60 | % |
| $t_{INJITTER_CCJ}$ ⁽⁵⁾ | Input clock cycle-to-cycle jitter $F_{REF} \geq 100$ MHz | — | — | 0.15 | UI |
| | $F_{REF} < 100$ MHz | — | — | ±750 | ps |
| f_{OUT_EXT} (external clock output) ⁽³⁾ | PLL output frequency | — | — | 472.5 | MHz |
| f_{OUT} (to global clock) | PLL output frequency (–6 speed grade) | — | — | 472.5 | MHz |
| | PLL output frequency (–7 speed grade) | — | — | 450 | MHz |
| | PLL output frequency (–8 speed grade) | — | — | 402.5 | MHz |
| | PLL output frequency (–8L speed grade) | — | — | 362 | MHz |
| | PLL output frequency (–9L speed grade) | — | — | 265 | MHz |
| $t_{OUTDUTY}$ | Duty cycle for external clock output (when set to 50%) | 45 | 50 | 55 | % |
| t_{LOCK} | Time required to lock from end of device configuration | — | — | 1 | ms |


Table 1–25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 2 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|--|---|-----|--------------------|----------|----------------|
| t_{DLOCK} | Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or \overline{areset} is deasserted) | — | — | 1 | ms |
| $t_{OUTJITTER_PERIOD_DEDCLK}^{(6)}$ | Dedicated clock output period jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_CCJ_DEDCLK}^{(6)}$ | Dedicated clock output cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_PERIOD_IO}^{(6)}$ | Regular I/O period jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| $t_{OUTJITTER_CCJ_IO}^{(6)}$ | Regular I/O cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | — | — | ± 50 | ps |
| t_{ARESET} | Minimum pulse width on \overline{areset} signal. | 10 | — | — | ns |
| $t_{CONFIGPLL}$ | Time required to reconfigure scan chains for PLLs | — | 3.5 ⁽⁷⁾ | — | SCANCLK cycles |
| $f_{SCANCLK}$ | $scanclk$ frequency | — | — | 100 | MHz |
| $t_{CASC_OUTJITTER_PERIOD_DEDCLK}^{(8), (9)}$ | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} \geq 100$ MHz) | — | — | 425 | ps |
| | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} < 100$ MHz) | — | — | 42.5 | mUI |

Notes to Table 1–25:

- (1) This table is applicable for general purpose PLLs and multipurpose PLLs.
- (2) You must connect V_{CCD_PLL} to V_{CCINT} through the decoupling capacitor and ferrite bead.
- (3) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (4) The V_{CO} frequency reported by the Quartus II software in the PLL Summary section of the compilation report takes into consideration the V_{CO} post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the f_{VCO} specification.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source that is less than 200 ps.
- (6) Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL when an input jitter of 30 ps is applied.
- (7) With 100-MHz $scanclk$ frequency.
- (8) The cascaded PLLs specification is applicable only with the following conditions:
 - Upstream PLL— $0.59 \text{ MHz} \leq \text{Upstream PLL bandwidth} < 1 \text{ MHz}$
 - Downstream PLL—Downstream PLL bandwidth $> 2 \text{ MHz}$
- (9) PLL cascading is not supported for transceiver applications.

 For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interfaces Handbook*.

 Actual achievable frequency depends on design- and system-specific factors. Perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

High-Speed I/O Specifications

Table 1–31 through Table 1–36 list the high-speed I/O timing for Cyclone IV devices. For definitions of high-speed timing specifications, refer to “Glossary” on page 1–37.

Table 1–31. RSDS Transmitter Timing Specifications for Cyclone IV Devices ⁽¹⁾, ⁽²⁾, ⁽⁴⁾ (Part 1 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|---|---|-----|-----|-----|--------|-----|-------|--------|-----|-------|----------|-----|-------|-----|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f_{HSCLK} (input clock frequency) | ×10 | 5 | — | 180 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×8 | 5 | — | 180 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×7 | 5 | — | 180 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×4 | 5 | — | 180 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×2 | 5 | — | 180 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×1 | 5 | — | 360 | 5 | — | 311 | 5 | — | 311 | 5 | — | 311 | 5 | — | 265 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 360 | 100 | — | 311 | 100 | — | 311 | 100 | — | 311 | 100 | — | 265 | Mbps |
| | ×8 | 80 | — | 360 | 80 | — | 311 | 80 | — | 311 | 80 | — | 311 | 80 | — | 265 | Mbps |
| | ×7 | 70 | — | 360 | 70 | — | 311 | 70 | — | 311 | 70 | — | 311 | 70 | — | 265 | Mbps |
| | ×4 | 40 | — | 360 | 40 | — | 311 | 40 | — | 311 | 40 | — | 311 | 40 | — | 265 | Mbps |
| | ×2 | 20 | — | 360 | 20 | — | 311 | 20 | — | 311 | 20 | — | 311 | 20 | — | 265 | Mbps |
| | ×1 | 10 | — | 360 | 10 | — | 311 | 10 | — | 311 | 10 | — | 311 | 10 | — | 265 | Mbps |
| t_{DUTY} | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| Transmitter channel-to-channel skew (TCCS) | — | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 500 | — | — | 550 | — | — | 600 | — | — | 700 | ps |
| t_{RISE} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t_{FALL} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |

Table 1-31. RSDS Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (2), (4)} (Part 2 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|----------------------------------|-------|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| t_{LOCK} ⁽³⁾ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1-31:

- (1) Applicable for true RSDS and emulated RSDS_E_3R transmitter.
- (2) Cyclone IV E devices—true RSDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Emulated RSDS transmitter is supported at the output pin of all I/O Banks.
Cyclone IV GX devices—true RSDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated RSDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (3) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (4) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1-32. Emulated RSDS_E_1R Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (3)} (Part 1 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|---|---|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f_{HCLK} (input clock frequency) | ×10 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×8 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×7 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×4 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×2 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 85 | 5 | — | 72.5 | MHz |
| | ×1 | 5 | — | 170 | 5 | — | 170 | 5 | — | 170 | 5 | — | 170 | 5 | — | 145 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 170 | 100 | — | 170 | 100 | — | 170 | 100 | — | 170 | 100 | — | 145 | Mbps |
| | ×8 | 80 | — | 170 | 80 | — | 170 | 80 | — | 170 | 80 | — | 170 | 80 | — | 145 | Mbps |
| | ×7 | 70 | — | 170 | 70 | — | 170 | 70 | — | 170 | 70 | — | 170 | 70 | — | 145 | Mbps |
| | ×4 | 40 | — | 170 | 40 | — | 170 | 40 | — | 170 | 40 | — | 170 | 40 | — | 145 | Mbps |
| | ×2 | 20 | — | 170 | 20 | — | 170 | 20 | — | 170 | 20 | — | 170 | 20 | — | 145 | Mbps |
| | ×1 | 10 | — | 170 | 10 | — | 170 | 10 | — | 170 | 10 | — | 170 | 10 | — | 145 | Mbps |
| t_{DUTY} | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 500 | — | — | 550 | — | — | 600 | — | — | 700 | ps |
| t_{RISE} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t_{FALL} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |

Table 1–35. Emulated LVDS Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (3)} (Part 2 of 2)

| Symbol | Modes | C6 | | C7, I7 | | C8, A7 | | C8L, I8L | | C9L | | Unit |
|----------------------------------|-------|-----|-----|--------|-----|--------|-----|----------|-----|-----|-----|------|
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{DUTY} | — | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | % |
| TCCS | — | — | 200 | — | 200 | — | 200 | — | 200 | — | 200 | ps |
| Output jitter (peak to peak) | — | — | 500 | — | 500 | — | 550 | — | 600 | — | 700 | ps |
| t _{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | — | 1 | — | 1 | — | 1 | ms |

Notes to Table 1–35:

- (1) Cyclone IV E—emulated LVDS transmitter is supported at the output pin of all I/O Banks.
Cyclone IV GX—emulated LVDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–36. LVDS Receiver Timing Specifications for Cyclone IV Devices ^{(1), (3)}

| Symbol | Modes | C6 | | C7, I7 | | C8, A7 | | C8L, I8L | | C9L | | Unit |
|---|-------|-----|-------|--------|-------|--------|-------|----------|-----|-----|-----|------|
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| f _{HCLK} (input clock frequency) | ×10 | 10 | 437.5 | 10 | 370 | 10 | 320 | 10 | 320 | 10 | 250 | MHz |
| | ×8 | 10 | 437.5 | 10 | 370 | 10 | 320 | 10 | 320 | 10 | 250 | MHz |
| | ×7 | 10 | 437.5 | 10 | 370 | 10 | 320 | 10 | 320 | 10 | 250 | MHz |
| | ×4 | 10 | 437.5 | 10 | 370 | 10 | 320 | 10 | 320 | 10 | 250 | MHz |
| | ×2 | 10 | 437.5 | 10 | 370 | 10 | 320 | 10 | 320 | 10 | 250 | MHz |
| | ×1 | 10 | 437.5 | 10 | 402.5 | 10 | 402.5 | 10 | 362 | 10 | 265 | MHz |
| HSIODR | ×10 | 100 | 875 | 100 | 740 | 100 | 640 | 100 | 640 | 100 | 500 | Mbps |
| | ×8 | 80 | 875 | 80 | 740 | 80 | 640 | 80 | 640 | 80 | 500 | Mbps |
| | ×7 | 70 | 875 | 70 | 740 | 70 | 640 | 70 | 640 | 70 | 500 | Mbps |
| | ×4 | 40 | 875 | 40 | 740 | 40 | 640 | 40 | 640 | 40 | 500 | Mbps |
| | ×2 | 20 | 875 | 20 | 740 | 20 | 640 | 20 | 640 | 20 | 500 | Mbps |
| | ×1 | 10 | 437.5 | 10 | 402.5 | 10 | 402.5 | 10 | 362 | 10 | 265 | Mbps |
| SW | — | — | 400 | — | 400 | — | 400 | — | 550 | — | 640 | ps |
| Input jitter tolerance | — | — | 500 | — | 500 | — | 550 | — | 600 | — | 700 | ps |
| t _{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | — | 1 | — | 1 | — | 1 | ms |

Notes to Table 1–36:

- (1) Cyclone IV E—LVDS receiver is supported at all I/O Banks.
Cyclone IV GX—LVDS receiver is supported at I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

External Memory Interface Specifications

The external memory interfaces for Cyclone IV devices are auto-calibrating and easy to implement.

IOE Programmable Delay

Table 1–40 and Table 1–41 list the IOE programmable delay for Cyclone IV E 1.0 V core voltage devices.

Table 1–40. IOE Programmable Delay on Column Pins for Cyclone IV E 1.0 V Core Voltage Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Setting | Min Offset | Max Offset | | | | | Unit |
|---|-----------------------------|-------------------|------------|-------------|-------|-------------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | |
| | | | | C8L | I8L | C8L | C9L | I8L | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 2.054 | 1.924 | 3.387 | 4.017 | 3.411 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 2.010 | 1.875 | 3.341 | 4.252 | 3.367 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.641 | 0.631 | 1.111 | 1.377 | 1.124 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.971 | 0.931 | 1.684 | 2.298 | 1.684 | ns |

Notes to Table 1–40:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–41. IOE Programmable Delay on Row Pins for Cyclone IV E 1.0 V Core Voltage Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Setting | Min Offset | Max Offset | | | | | Unit |
|---|-----------------------------|-------------------|------------|-------------|-------|-------------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | |
| | | | | C8L | I8L | C8L | C9L | I8L | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 2.057 | 1.921 | 3.389 | 4.146 | 3.412 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 2.059 | 1.919 | 3.420 | 4.374 | 3.441 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.670 | 0.623 | 1.160 | 1.420 | 1.168 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.960 | 0.919 | 1.656 | 2.258 | 1.656 | ns |

Notes to Table 1–41:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

I/O Timing

Use the following methods to determine I/O timing:

- the Excel-based I/O Timing
- the Quartus II timing analyzer

The Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II timing analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.



The Excel-based I/O Timing spreadsheet is downloadable from Cyclone IV Devices Literature website.

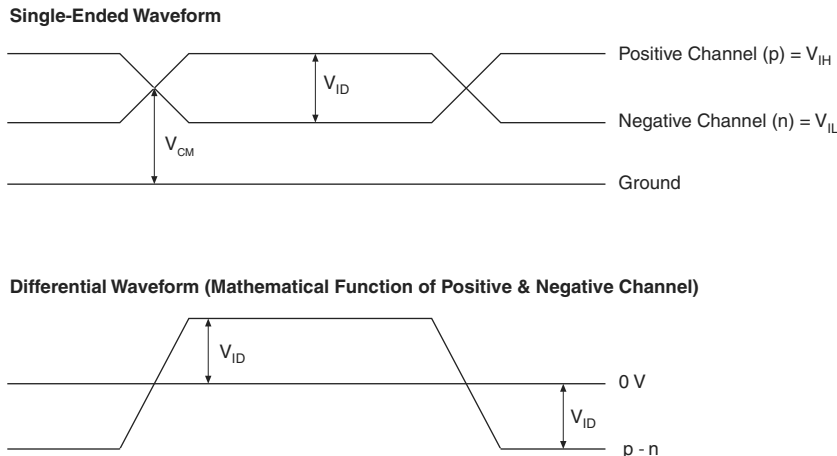
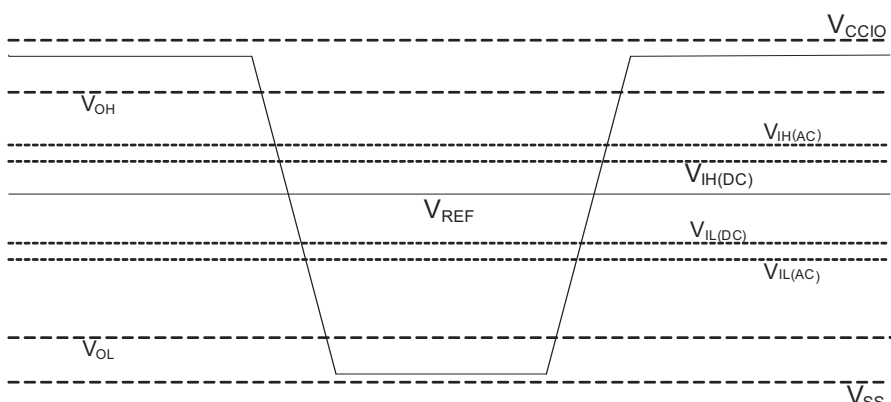
Glossary

Table 1–46 lists the glossary for this chapter.

Table 1–46. Glossary (Part 1 of 5)

| Letter | Term | Definitions |
|--------|--|---|
| A | — | — |
| B | — | — |
| C | — | — |
| D | — | — |
| E | — | — |
| F | f_{HSCLK} | High-speed I/O block: High-speed receiver/transmitter input and output clock frequency. |
| G | GCLK | Input pin directly to Global Clock network. |
| | GCLK PLL | Input pin to Global Clock network through the PLL. |
| H | HSIODR | High-speed I/O block: Maximum/minimum LVDS data transfer rate ($\text{HSIODR} = 1/\text{TUI}$). |
| I | Input Waveforms for the SSTL Differential I/O Standard | |

Table 1-46. Glossary (Part 3 of 5)

| Letter | Term | Definitions |
|--------|--|---|
| R | R_L | Receiver differential input discrete resistor (external to Cyclone IV devices). |
| | Receiver Input Waveform | <p>Receiver input waveform for LVDS and LVPECL differential standards:</p>  |
| | Receiver input skew margin (RSKM) | High-speed I/O block: The total margin left after accounting for the sampling window and TCCS. $RSKM = (TUI - SW - TCCS) / 2$. |
| S | Single-ended voltage-referenced I/O Standard |  <p>The JEDEC standard for SSTI and HSTL I/O standards defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform <i>ringing</i>.</p> |
| | SW (Sampling Window) | High-speed I/O block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window. |

