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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)


Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	1840
Number of Logic Elements/Cells	29440
Total RAM Bits	1105920
Number of I/O	150
Number of Gates	-
Voltage - Supply	1.16V ~ 1.24V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	324-LBGA
Supplier Device Package	324-FBGA (19x19)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep4cgx30cf19c7">https://www.e-xfl.com/product-detail/intel/ep4cgx30cf19c7</a>

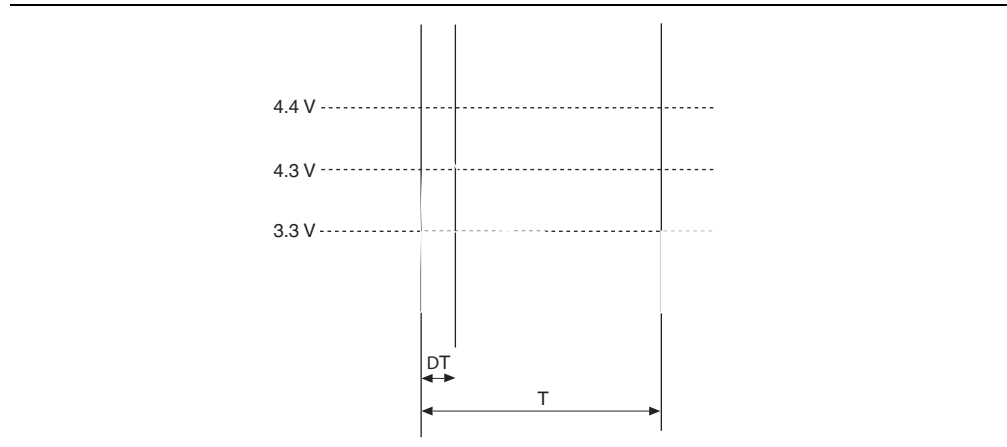
 A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

**Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices**

Symbol	Parameter	Condition (V)	Overshoot Duration as % of High Time	Unit
$V_i$	AC Input Voltage	$V_i = 4.20$	100	%
		$V_i = 4.25$	98	%
		$V_i = 4.30$	65	%
		$V_i = 4.35$	43	%
		$V_i = 4.40$	29	%
		$V_i = 4.45$	20	%
		$V_i = 4.50$	13	%
		$V_i = 4.55$	9	%
		$V_i = 4.60$	6	%

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as  $([\Delta T]/T) \times 100$ . This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

**Figure 1–1. Cyclone IV Devices Overshoot Duration**



## Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1)</sup>, <sup>(2)</sup> (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}^{(3)}$	Supply voltage for internal logic, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply voltage for internal logic, 1.0-V operation	—	0.97	1.0	1.03	V
$V_{CCIO}^{(3), (4)}$	Supply voltage for output buffers, 3.3-V operation	—	3.135	3.3	3.465	V
	Supply voltage for output buffers, 3.0-V operation	—	2.85	3	3.15	V
	Supply voltage for output buffers, 2.5-V operation	—	2.375	2.5	2.625	V
	Supply voltage for output buffers, 1.8-V operation	—	1.71	1.8	1.89	V
	Supply voltage for output buffers, 1.5-V operation	—	1.425	1.5	1.575	V
	Supply voltage for output buffers, 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCA}^{(3)}$	Supply (analog) voltage for PLL regulator	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}^{(3)}$	Supply (digital) voltage for PLL, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply (digital) voltage for PLL, 1.0-V operation	—	0.97	1.0	1.03	V
$V_I$	Input voltage	—	–0.5	—	3.6	V
$V_O$	Output voltage	—	0	—	$V_{CCIO}$	V
$T_J$	Operating junction temperature	For commercial use	0	—	85	°C
		For industrial use	–40	—	100	°C
		For extended temperature	–40	—	125	°C
		For automotive use	–40	—	125	°C
$t_{RAMP}$	Power supply ramp time	Standard power-on reset (POR) <sup>(5)</sup>	50 $\mu$ s	—	50 ms	—
		Fast POR <sup>(6)</sup>	50 $\mu$ s	—	3 ms	—

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1), (2)</sup> (Part 2 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{Diode}$	Magnitude of DC current across PCI-clamp diode when enable	—	—	—	10	mA

**Notes to Table 1–3:**

- (1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades.
- (2)  $V_{CCIO}$  for all I/O banks must be powered up during device operation. All  $V_{CCA}$  pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (3)  $V_{CC}$  must rise monotonically.
- (4)  $V_{CCIO}$  powers all input buffers.
- (5) The POR time for Standard POR ranges between 50 and 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) The POR time for Fast POR ranges between 3 and 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.

**Table 1–4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}$ <sup>(3)</sup>	Core voltage, PCIe hard IP block, and transceiver PCS power supply	—	1.16	1.2	1.24	V
$V_{CCA}$ <sup>(1), (3)</sup>	PLL analog power supply	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}$ <sup>(2)</sup>	PLL digital power supply	—	1.16	1.2	1.24	V
$V_{CCIO}$ <sup>(3), (4)</sup>	I/O banks power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	I/O banks power supply for 3.0-V operation	—	2.85	3	3.15	V
	I/O banks power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	I/O banks power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	I/O banks power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	I/O banks power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CC\_CLKIN}$ <sup>(3), (5), (6)</sup>	Differential clock input pins power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	Differential clock input pins power supply for 3.0-V operation	—	2.85	3	3.15	V
	Differential clock input pins power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	Differential clock input pins power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	Differential clock input pins power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	Differential clock input pins power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCH\_GXB}$	Transceiver output buffer power supply	—	2.375	2.5	2.625	V

**Table 1-4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 2 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCA\_GXB}$	Transceiver PMA and auxiliary power supply	—	2.375	2.5	2.625	V
$V_{CCL\_GXB}$	Transceiver PMA and auxiliary power supply	—	1.16	1.2	1.24	V
$V_I$	DC input voltage	—	-0.5	—	3.6	V
$V_O$	DC output voltage	—	0	—	$V_{CCIO}$	V
$T_J$	Operating junction temperature	For commercial use	0	—	85	°C
		For industrial use	-40	—	100	°C
$t_{RAMP}$	Power supply ramp time	Standard power-on reset (POR) <sup>(7)</sup>	50 $\mu$ s	—	50 ms	—
		Fast POR <sup>(8)</sup>	50 $\mu$ s	—	3 ms	—
$I_{Diode}$	Magnitude of DC current across PCI-clamp diode when enabled	—	—	—	10	mA

**Notes to Table 1-4:**

- (1) All  $V_{CCA}$  pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (2) You must connect  $V_{CCD\_PLL}$  to  $V_{CCINT}$  through a decoupling capacitor and ferrite bead.
- (3) Power supplies must rise monotonically.
- (4)  $V_{CCIO}$  for all I/O banks must be powered up during device operation. Configurations pins are powered up by  $V_{CCIO}$  of I/O Banks 3, 8, and 9 where I/O Banks 3 and 9 only support  $V_{CCIO}$  of 1.5, 1.8, 2.5, 3.0, and 3.3 V. For fast passive parallel (FPP) configuration mode, the  $V_{CCIO}$  level of I/O Bank 8 must be powered up to 1.5, 1.8, 2.5, 3.0, and 3.3 V.
- (5) You must set  $V_{CC\_CLKIN}$  to 2.5 V if you use  $CLKIN$  as a high-speed serial interface (HSSI)  $refclk$  or as a  $DIFFCLK$  input.
- (6) The  $CLKIN$  pins in I/O Banks 3B and 8B can support single-ended I/O standard when the pins are used to clock left PLLs in non-transceiver applications.
- (7) The POR time for Standard POR ranges between 50 and 200 ms.  $V_{CCINT}$ ,  $V_{CCA}$ , and  $V_{CCIO}$  of I/O Banks 3, 8, and 9 must reach the recommended operating range within 50 ms.
- (8) The POR time for Fast POR ranges between 3 and 9 ms.  $V_{CCINT}$ ,  $V_{CCA}$ , and  $V_{CCIO}$  of I/O Banks 3, 8, and 9 must reach the recommended operating range within 3 ms.

## ESD Performance

This section lists the electrostatic discharge (ESD) voltages using the human body model (HBM) and charged device model (CDM) for Cyclone IV devices general purpose I/Os (GPIOs) and high-speed serial interface (HSSI) I/Os. Table 1-5 lists the ESD for Cyclone IV devices GPIOs and HSSI I/Os.

**Table 1-5. ESD for Cyclone IV Devices GPIOs and HSSI I/Os**

Symbol	Parameter	Passing Voltage	Unit
$V_{ESDHBM}$	ESD voltage using the HBM (GPIOs) <sup>(1)</sup>	$\pm 2000$	V
	ESD using the HBM (HSSI I/Os) <sup>(2)</sup>	$\pm 1000$	V
$V_{ESDCDM}$	ESD using the CDM (GPIOs)	$\pm 500$	V
	ESD using the CDM (HSSI I/Os) <sup>(2)</sup>	$\pm 250$	V

**Notes to Table 1-5:**

- (1) The passing voltage for EP4CGX15 and EP4CGX30 row I/Os is  $\pm 1000$ V.
- (2) This value is applicable only to Cyclone IV GX devices.

**Table 1–7. Bus Hold Parameter for Cyclone IV Devices (Part 2 of 2) <sup>(1)</sup>**

Parameter	Condition	V <sub>CCIO</sub> (V)												Unit
		1.2		1.5		1.8		2.5		3.0		3.3		
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus hold trip point	—	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2	0.8	2	V

**Note to Table 1–7:**

(1) Bus hold trip points are based on the calculated input voltages from the JEDEC standard.

## OCT Specifications

Table 1–8 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

**Table 1–8. Series OCT Without Calibration Specifications for Cyclone IV Devices**

Description	$V_{CCIO}$ (V)	Resistance Tolerance		Unit
		Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	
Series OCT without calibration	3.0	±30	±40	%
	2.5	±30	±40	%
	1.8	±40	±50	%
	1.5	±50	±50	%
	1.2	±50	±50	%

OCT calibration is automatically performed at device power-up for OCT-enabled I/Os.

Table 1–9 lists the OCT calibration accuracy at device power-up.

**Table 1–9. Series OCT with Calibration at Device Power-Up Specifications for Cyclone IV Devices**

Description	$V_{CCIO}$ (V)	Calibration Accuracy		Unit
		Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	
Series OCT with calibration at device power-up	3.0	±10	±10	%
	2.5	±10	±10	%
	1.8	±10	±10	%
	1.5	±10	±10	%
	1.2	±10	±10	%

## Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1-12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

**Table 1-12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
R <sub>PU</sub>	Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you enable the programmable pull-up resistor option	V <sub>CCIO</sub> = 3.3 V ± 5% <sup>(2), (3)</sup>	7	25	41	kΩ
		V <sub>CCIO</sub> = 3.0 V ± 5% <sup>(2), (3)</sup>	7	28	47	kΩ
		V <sub>CCIO</sub> = 2.5 V ± 5% <sup>(2), (3)</sup>	8	35	61	kΩ
		V <sub>CCIO</sub> = 1.8 V ± 5% <sup>(2), (3)</sup>	10	57	108	kΩ
		V <sub>CCIO</sub> = 1.5 V ± 5% <sup>(2), (3)</sup>	13	82	163	kΩ
		V <sub>CCIO</sub> = 1.2 V ± 5% <sup>(2), (3)</sup>	19	143	351	kΩ
R <sub>PD</sub>	Value of the I/O pin pull-down resistor before and during configuration	V <sub>CCIO</sub> = 3.3 V ± 5% <sup>(4)</sup>	6	19	30	kΩ
		V <sub>CCIO</sub> = 3.0 V ± 5% <sup>(4)</sup>	6	22	36	kΩ
		V <sub>CCIO</sub> = 2.5 V ± 5% <sup>(4)</sup>	6	25	43	kΩ
		V <sub>CCIO</sub> = 1.8 V ± 5% <sup>(4)</sup>	7	35	71	kΩ
		V <sub>CCIO</sub> = 1.5 V ± 5% <sup>(4)</sup>	8	50	112	kΩ

### Notes to Table 1-12:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V<sub>CCIO</sub>.
- (3)  $R_{PU} = (V_{CCIO} - V_I) / I_{R_{PU}}$   
Minimum condition: -40°C; V<sub>CCIO</sub> = V<sub>CC</sub> + 5%, V<sub>I</sub> = V<sub>CC</sub> + 5% - 50 mV;  
Typical condition: 25°C; V<sub>CCIO</sub> = V<sub>CC</sub>, V<sub>I</sub> = 0 V;  
Maximum condition: 100°C; V<sub>CCIO</sub> = V<sub>CC</sub> - 5%, V<sub>I</sub> = 0 V; in which V<sub>I</sub> refers to the input voltage at the I/O pin.
- (4)  $R_{PD} = V_I / I_{R_{PD}}$   
Minimum condition: -40°C; V<sub>CCIO</sub> = V<sub>CC</sub> + 5%, V<sub>I</sub> = 50 mV;  
Typical condition: 25°C; V<sub>CCIO</sub> = V<sub>CC</sub>, V<sub>I</sub> = V<sub>CC</sub> - 5%;  
Maximum condition: 100°C; V<sub>CCIO</sub> = V<sub>CC</sub> - 5%, V<sub>I</sub> = V<sub>CC</sub> - 5%; in which V<sub>I</sub> refers to the input voltage at the I/O pin.

## Hot-Socketing

Table 1-13 lists the hot-socketing specifications for Cyclone IV devices.

**Table 1-13. Hot-Socketing Specifications for Cyclone IV Devices**

Symbol	Parameter	Maximum
I <sub>IOPIN(DC)</sub>	DC current per I/O pin	300 μA
I <sub>IOPIN(AC)</sub>	AC current per I/O pin	8 mA <sup>(1)</sup>
I <sub>XCVRTX(DC)</sub>	DC current per transceiver TX pin	100 mA
I <sub>XCVRRX(DC)</sub>	DC current per transceiver RX pin	50 mA

### Note to Table 1-13:

- (1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |I<sub>IOPIN</sub>| = C dv/dt, in which C is the I/O pin capacitance and dv/dt is the slew rate.



During hot-socketing, the I/O pin capacitance is less than 15 pF and the clock pin capacitance is less than 20 pF.

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 2 of 4)

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Receiver											
Supported I/O Standards	1.4 V PCML, 1.5 V PCML, 2.5 V PCML, LVPECL, LVDS										
Data rate (F324 and smaller package) <sup>(15)</sup>	—	600	—	2500	600	—	2500	600	—	2500	Mbps
Data rate (F484 and larger package) <sup>(15)</sup>	—	600	—	3125	600	—	3125	600	—	2500	Mbps
Absolute V <sub>MAX</sub> for a receiver pin <sup>(3)</sup>	—	—	—	1.6	—	—	1.6	—	—	1.6	V
Operational V <sub>MAX</sub> for a receiver pin	—	—	—	1.5	—	—	1.5	—	—	1.5	V
Absolute V <sub>MIN</sub> for a receiver pin	—	–0.4	—	—	–0.4	—	—	–0.4	—	—	V
Peak-to-peak differential input voltage V <sub>ID</sub> (diff p-p)	V <sub>ICM</sub> = 0.82 V setting, Data Rate = 600 Mbps to 3.125 Gbps	0.1	—	2.7	0.1	—	2.7	0.1	—	2.7	V
V <sub>ICM</sub>	V <sub>ICM</sub> = 0.82 V setting	—	820 ± 10%	—	—	820 ± 10%	—	—	820 ± 10%	—	mV
Differential on-chip termination resistors	100–Ω setting	—	100	—	—	100	—	—	100	—	Ω
	150–Ω setting	—	150	—	—	150	—	—	150	—	Ω
Differential and common mode return loss	PIPE, Serial Rapid I/O SR, SATA, CPRI LV, SDI, XAUI	Compliant									—
Programmable ppm detector <sup>(4)</sup>	—	± 62.5, 100, 125, 200, 250, 300									ppm
Clock data recovery (CDR) ppm tolerance (without spread-spectrum clocking enabled)	—	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	ppm
CDR ppm tolerance (with synchronous spread-spectrum clocking enabled) <sup>(8)</sup>	—	—	—	350 to –5350 <sup>(7), (9)</sup>	—	—	350 to –5350 <sup>(7), (9)</sup>	—	—	350 to –5350 <sup>(7), (9)</sup>	ppm
Run length	—	—	80	—	—	80	—	—	80	—	UI
Programmable equalization	No Equalization	—	—	1.5	—	—	1.5	—	—	1.5	dB
	Medium Low	—	—	4.5	—	—	4.5	—	—	4.5	dB
	Medium High	—	—	5.5	—	—	5.5	—	—	5.5	dB
	High	—	—	7	—	—	7	—	—	7	dB



**Table 1-21. Transceiver Specification for Cyclone IV GX Devices (Part 3 of 4)**

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Signal detect/loss threshold	PIPE mode	65	—	175	65	—	175	65	—	175	mV
$t_{LTR}$ <sup>(10)</sup>	—	—	—	75	—	—	75	—	—	75	μs
$t_{LTR-LTD\_Manual}$ <sup>(11)</sup>	—	15	—	—	15	—	—	15	—	—	μs
$t_{LTD}$ <sup>(12)</sup>	—	0	100	4000	0	100	4000	0	100	4000	ns
$t_{LTD\_Manual}$ <sup>(13)</sup>	—	—	—	4000	—	—	4000	—	—	4000	ns
$t_{LTD\_Auto}$ <sup>(14)</sup>	—	—	—	4000	—	—	4000	—	—	4000	ns
Receiver buffer and CDR offset cancellation time (per channel)	—	—	—	17000	—	—	17000	—	—	17000	recon fig_c lk cycles
Programmable DC gain	DC Gain Setting = 0	—	0	—	—	0	—	—	0	—	dB
	DC Gain Setting = 1	—	3	—	—	3	—	—	3	—	dB
	DC Gain Setting = 2	—	6	—	—	6	—	—	6	—	dB
<b>Transmitter</b>											
Supported I/O Standards	1.5 V PCML										
Data rate (F324 and smaller package)	—	600	—	2500	600	—	2500	600	—	2500	Mbps
Data rate (F484 and larger package)	—	600	—	3125	600	—	3125	600	—	2500	Mbps
$V_{OCM}$	0.65 V setting	—	650	—	—	650	—	—	650	—	mV
Differential on-chip termination resistors	100-Ω setting	—	100	—	—	100	—	—	100	—	Ω
	150-Ω setting	—	150	—	—	150	—	—	150	—	Ω
Differential and common mode return loss	PIPE, CPRI LV, Serial Rapid I/O SR, SDI, XAUI, SATA	Compliant									—
Rise time	—	50	—	200	50	—	200	50	—	200	ps
Fall time	—	50	—	200	50	—	200	50	—	200	ps
Intra-differential pair skew	—	—	—	15	—	—	15	—	—	15	ps
Intra-transceiver block skew	—	—	—	120	—	—	120	—	—	120	ps

**Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 2 of 2)**

Device	Performance								Unit
	C6	C7	C8	C8L <sup>(1)</sup>	C9L <sup>(1)</sup>	I7	I8L <sup>(1)</sup>	A7	
EP4CE55	500	437.5	402	362	265	437.5	362	—	MHz
EP4CE75	500	437.5	402	362	265	437.5	362	—	MHz
EP4CE115	—	437.5	402	362	265	437.5	362	—	MHz
EP4CGX15	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX22	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX30	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX50	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX75	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX110	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX150	500	437.5	402	—	—	437.5	—	—	MHz

**Note to Table 1–24:**

(1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades.

## PLL Specifications

Table 1–25 lists the PLL specifications for Cyclone IV devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (–40°C to 100°C), the extended industrial junction temperature range (–40°C to 125°C), and the automotive junction temperature range (–40°C to 125°C). For more information about the PLL block, refer to “Glossary” on page 1–37.

**Table 1–25. PLL Specifications for Cyclone IV Devices <sup>(1), (2)</sup> (Part 1 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{IN}$ <sup>(3)</sup>	Input clock frequency (–6, –7, –8 speed grades)	5	—	472.5	MHz
	Input clock frequency (–8L speed grade)	5	—	362	MHz
	Input clock frequency (–9L speed grade)	5	—	265	MHz
$f_{INPFD}$	PFD input frequency	5	—	325	MHz
$f_{VCO}$ <sup>(4)</sup>	PLL internal VCO operating range	600	—	1300	MHz
$f_{INDUTY}$	Input clock duty cycle	40	—	60	%
$t_{INJITTER\_CCJ}$ <sup>(5)</sup>	Input clock cycle-to-cycle jitter $F_{REF} \geq 100$ MHz	—	—	0.15	UI
	$F_{REF} < 100$ MHz	—	—	±750	ps
$f_{OUT\_EXT}$ (external clock output) <sup>(3)</sup>	PLL output frequency	—	—	472.5	MHz
$f_{OUT}$ (to global clock)	PLL output frequency (–6 speed grade)	—	—	472.5	MHz
	PLL output frequency (–7 speed grade)	—	—	450	MHz
	PLL output frequency (–8 speed grade)	—	—	402.5	MHz
	PLL output frequency (–8L speed grade)	—	—	362	MHz
	PLL output frequency (–9L speed grade)	—	—	265	MHz
$t_{OUTDUTY}$	Duty cycle for external clock output (when set to 50%)	45	50	55	%
$t_{LOCK}$	Time required to lock from end of device configuration	—	—	1	ms

**Table 1–25. PLL Specifications for Cyclone IV Devices <sup>(1), (2)</sup> (Part 2 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$t_{DLOCK}$	Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or $\overline{areset}$ is deasserted)	—	—	1	ms
$t_{OUTJITTER\_PERIOD\_DEDCLK}$ <sup>(6)</sup>	Dedicated clock output period jitter $F_{OUT} \geq 100$ MHz	—	—	300	ps
	$F_{OUT} < 100$ MHz	—	—	30	mUI
$t_{OUTJITTER\_CCJ\_DEDCLK}$ <sup>(6)</sup>	Dedicated clock output cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz	—	—	300	ps
	$F_{OUT} < 100$ MHz	—	—	30	mUI
$t_{OUTJITTER\_PERIOD\_IO}$ <sup>(6)</sup>	Regular I/O period jitter $F_{OUT} \geq 100$ MHz	—	—	650	ps
	$F_{OUT} < 100$ MHz	—	—	75	mUI
$t_{OUTJITTER\_CCJ\_IO}$ <sup>(6)</sup>	Regular I/O cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz	—	—	650	ps
	$F_{OUT} < 100$ MHz	—	—	75	mUI
$t_{PLL\_PSERR}$	Accuracy of PLL phase shift	—	—	$\pm 50$	ps
$t_{ARESET}$	Minimum pulse width on $\overline{areset}$ signal.	10	—	—	ns
$t_{CONFIGPLL}$	Time required to reconfigure scan chains for PLLs	—	3.5 <sup>(7)</sup>	—	SCANCLK cycles
$f_{SCANCLK}$	scanclk frequency	—	—	100	MHz
$t_{CASC\_OUTJITTER\_PERIOD\_DEDCLK}$ <sup>(8), (9)</sup>	Period jitter for dedicated clock output in cascaded PLLs ( $F_{OUT} \geq 100$ MHz)	—	—	425	ps
	Period jitter for dedicated clock output in cascaded PLLs ( $F_{OUT} < 100$ MHz)	—	—	42.5	mUI

**Notes to Table 1–25:**

- (1) This table is applicable for general purpose PLLs and multipurpose PLLs.
- (2) You must connect  $V_{CCD\_PLL}$  to  $V_{CCINT}$  through the decoupling capacitor and ferrite bead.
- (3) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (4) The  $V_{CO}$  frequency reported by the Quartus II software in the PLL Summary section of the compilation report takes into consideration the  $V_{CO}$  post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the  $f_{VCO}$  specification.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source that is less than 200 ps.
- (6) Peak-to-peak jitter with a probability level of  $10^{-12}$  (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL when an input jitter of 30 ps is applied.
- (7) With 100-MHz scanclk frequency.
- (8) The cascaded PLLs specification is applicable only with the following conditions:
  - Upstream PLL— $0.59 \text{ MHz} \leq \text{Upstream PLL bandwidth} < 1 \text{ MHz}$
  - Downstream PLL—Downstream PLL bandwidth  $> 2 \text{ MHz}$
- (9) PLL cascading is not supported for transceiver applications.

## Embedded Multiplier Specifications

Table 1–26 lists the embedded multiplier specifications for Cyclone IV devices.

**Table 1–26. Embedded Multiplier Specifications for Cyclone IV Devices**

Mode	Resources Used	Performance					Unit
	Number of Multipliers	C6	C7, I7, A7	C8	C8L, I8L	C9L	
9 × 9-bit multiplier	1	340	300	260	240	175	MHz
18 × 18-bit multiplier	1	287	250	200	185	135	MHz

## Memory Block Specifications

Table 1–27 lists the M9K memory block specifications for Cyclone IV devices.

**Table 1–27. Memory Block Performance Specifications for Cyclone IV Devices**

Memory	Mode	Resources Used		Performance					Unit
		LEs	M9K Memory	C6	C7, I7, A7	C8	C8L, I8L	C9L	
M9K Block	FIFO 256 × 36	47	1	315	274	238	200	157	MHz
	Single-port 256 × 36	0	1	315	274	238	200	157	MHz
	Simple dual-port 256 × 36 CLK	0	1	315	274	238	200	157	MHz
	True dual port 512 × 18 single CLK	0	1	315	274	238	200	157	MHz

## Configuration and JTAG Specifications

Table 1–28 lists the configuration mode specifications for Cyclone IV devices.

**Table 1–28. Passive Configuration Mode Specifications for Cyclone IV Devices <sup>(1)</sup>**

Programming Mode	V <sub>CCINT</sub> Voltage Level (V)	DCLK f <sub>MAX</sub>	Unit
Passive Serial (PS)	1.0 <sup>(3)</sup>	66	MHz
	1.2	133	MHz
Fast Passive Parallel (FPP) <sup>(2)</sup>	1.0 <sup>(3)</sup>	66	MHz
	1.2 <sup>(4)</sup>	100	MHz

**Notes to Table 1–28:**

- (1) For more information about PS and FPP configuration timing parameters, refer to the *Configuration and Remote System Upgrades in Cyclone IV Devices* chapter.
- (2) FPP configuration mode supports all Cyclone IV E devices (except for E144 package devices) and EP4CGX50, EP4CGX75, EP4CGX110, and EP4CGX150 only.
- (3) V<sub>CCINT</sub> = 1.0 V is only supported for Cyclone IV E 1.0 V core voltage devices.
- (4) Cyclone IV E devices support 1.2 V V<sub>CCINT</sub>. Cyclone IV E 1.2 V core voltage devices support 133 MHz DCLK f<sub>MAX</sub> for EP4CE6, EP4CE10, EP4CE15, EP4CE22, EP4CE30, and EP4CE40 only.

Table 1–29 lists the active configuration mode specifications for Cyclone IV devices.

**Table 1–29. Active Configuration Mode Specifications for Cyclone IV Devices**

Programming Mode	DCLK Range	Typical DCLK	Unit
Active Parallel (AP) <sup>(1)</sup>	20 to 40	33	MHz
Active Serial (AS)	20 to 40	33	MHz

**Note to Table 1–29:**

(1) AP configuration mode is only supported for Cyclone IV E devices.

Table 1–30 lists the JTAG timing parameters and values for Cyclone IV devices.

**Table 1–30. JTAG Timing Parameters for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Min	Max	Unit
t <sub>JCP</sub>	TCK clock period	40	—	ns
t <sub>JCH</sub>	TCK clock high time	19	—	ns
t <sub>JCL</sub>	TCK clock low time	19	—	ns
t <sub>JPSU_TDI</sub>	JTAG port setup time for TDI	1	—	ns
t <sub>JPSU_TMS</sub>	JTAG port setup time for TMS	3	—	ns
t <sub>JPH</sub>	JTAG port hold time	10	—	ns
t <sub>JPCO</sub>	JTAG port clock to output <sup>(2), (3)</sup>	—	15	ns
t <sub>JPZX</sub>	JTAG port high impedance to valid output <sup>(2), (3)</sup>	—	15	ns
t <sub>JPXZ</sub>	JTAG port valid output to high impedance <sup>(2), (3)</sup>	—	15	ns
t <sub>JSSU</sub>	Capture register setup time	5	—	ns
t <sub>JSH</sub>	Capture register hold time	10	—	ns
t <sub>JSCO</sub>	Update register clock to output	—	25	ns
t <sub>JSZX</sub>	Update register high impedance to valid output	—	25	ns
t <sub>JSXZ</sub>	Update register valid output to high impedance	—	25	ns

**Notes to Table 1–30:**

(1) For more information about JTAG waveforms, refer to “JTAG Waveform” in “Glossary” on page 1–37.


(2) The specification is shown for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 16 ns.


(3) For EP4CGX22, EP4CGX30 (F324 and smaller package), EP4CGX110, and EP4CGX150 devices, the output time specification for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins is 16 ns. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 18 ns.

## Periphery Performance

This section describes periphery performance, including high-speed I/O and external memory interface.

I/O performance supports several system interfaces, such as the high-speed I/O interface, external memory interface, and the PCI/PCI-X bus interface. I/Os using the SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speeds. I/Os using general-purpose I/O standards such as 3.3-, 3.0-, 2.5-, 1.8-, or 1.5-V LVTTL/LVCMOS are capable of a typical 200 MHz interfacing frequency with a 10 pF load.

 For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interfaces Handbook*.

 Actual achievable frequency depends on design- and system-specific factors. Perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

## High-Speed I/O Specifications

Table 1–31 through Table 1–36 list the high-speed I/O timing for Cyclone IV devices. For definitions of high-speed timing specifications, refer to “Glossary” on page 1–37.

**Table 1–31. RSDS Transmitter Timing Specifications for Cyclone IV Devices <sup>(1)</sup>, <sup>(2)</sup>, <sup>(4)</sup> (Part 1 of 2)**

Symbol	Modes	C6			C7, I7			C8, A7			C8L, I8L			C9L			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$f_{\text{HSCLK}}$ (input clock frequency)	×10	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×8	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×7	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×4	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×2	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×1	5	—	360	5	—	311	5	—	311	5	—	311	5	—	265	MHz
Device operation in Mbps	×10	100	—	360	100	—	311	100	—	311	100	—	311	100	—	265	Mbps
	×8	80	—	360	80	—	311	80	—	311	80	—	311	80	—	265	Mbps
	×7	70	—	360	70	—	311	70	—	311	70	—	311	70	—	265	Mbps
	×4	40	—	360	40	—	311	40	—	311	40	—	311	40	—	265	Mbps
	×2	20	—	360	20	—	311	20	—	311	20	—	311	20	—	265	Mbps
	×1	10	—	360	10	—	311	10	—	311	10	—	311	10	—	265	Mbps
$t_{\text{DUTY}}$	—	45	—	55	45	—	55	45	—	55	45	—	55	45	—	55	%
Transmitter channel-to-channel skew (TCCS)	—	—	—	200	—	—	200	—	—	200	—	—	200	—	—	200	ps
Output jitter (peak to peak)	—	—	—	500	—	—	500	—	—	550	—	—	600	—	—	700	ps
$t_{\text{RISE}}$	20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$	—	500	—	—	500	—	—	500	—	—	500	—	—	500	—	ps
$t_{\text{FALL}}$	20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$	—	500	—	—	500	—	—	500	—	—	500	—	—	500	—	ps

For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interface Handbook*.

Table 1–37 lists the memory output clock jitter specifications for Cyclone IV devices.

**Table 1–37. Memory Output Clock Jitter Specifications for Cyclone IV Devices <sup>(1), (2)</sup>**

Parameter	Symbol	Min	Max	Unit
Clock period jitter	$t_{JIT(per)}$	–125	125	ps
Cycle-to-cycle period jitter	$t_{JIT(cc)}$	–200	200	ps
Duty cycle jitter	$t_{JIT(duty)}$	–150	150	ps

**Notes to Table 1–37:**

- (1) Memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock (GCLK) network.

## Duty Cycle Distortion Specifications

Table 1–38 lists the worst case duty cycle distortion for Cyclone IV devices.

**Table 1–38. Duty Cycle Distortion on Cyclone IV Devices I/O Pins <sup>(1), (2), (3)</sup>**

Symbol	C6		C7, I7		C8, I8L, A7		C9L		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	45	55	%

**Notes to Table 1–38:**

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and IOE driving the dedicated and general purpose I/O pins.
- (2) Cyclone IV devices meet the specified duty cycle distortion at the maximum output toggle rate for each combination of I/O standard and current strength.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

## OCT Calibration Timing Specification

Table 1–39 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone IV devices.

**Table 1–39. Timing Specification for Series OCT with Calibration at Device Power-Up for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Description	Maximum	Units
$t_{OCTCAL}$	Duration of series OCT with calibration at device power-up	20	$\mu$ s

**Note to Table 1–39:**

- (1) OCT calibration takes place after device configuration and before entering user mode.

Table 1–44 and Table 1–45 list the IOE programmable delay for Cyclone IV GX devices.

**Table 1–44. IOE Programmable Delay on Column Pins for Cyclone IV GX Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Settings	Min Offset	Max Offset						Unit
				Fast Corner		Slow Corner				
				C6	I7	C6	C7	C8	I7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.313	1.209	2.184	2.336	2.451	2.387	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.312	1.208	2.200	2.399	2.554	2.446	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.438	0.404	0.751	0.825	0.886	0.839	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.713	0.682	1.228	1.41	1.566	1.424	ns

**Notes to Table 1–44:**

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

**Table 1–45. IOE Programmable Delay on Row Pins for Cyclone IV GX Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Settings	Min Offset	Max Offset						Unit
				Fast Corner		Slow Corner				
				C6	I7	C6	C7	C8	I7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.314	1.210	2.209	2.398	2.526	2.443	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.313	1.208	2.205	2.406	2.563	2.450	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.461	0.421	0.789	0.869	0.933	0.884	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.712	0.682	1.225	1.407	1.562	1.421	ns

**Notes to Table 1–45:**

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software



## I/O Timing

Use the following methods to determine I/O timing:

- the Excel-based I/O Timing
- the Quartus II timing analyzer

The Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II timing analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.



The Excel-based I/O Timing spreadsheet is downloadable from Cyclone IV Devices Literature website.

## Glossary

Table 1–46 lists the glossary for this chapter.

**Table 1–46. Glossary (Part 1 of 5)**

Letter	Term	Definitions
A	—	—
B	—	—
C	—	—
D	—	—
E	—	—
F	$f_{\text{HSCLK}}$	High-speed I/O block: High-speed receiver/transmitter input and output clock frequency.
G	GCLK	Input pin directly to Global Clock network.
	GCLK PLL	Input pin to Global Clock network through the PLL.
H	HSIODR	High-speed I/O block: Maximum/minimum LVDS data transfer rate ( $\text{HSIODR} = 1/\text{TUI}$ ).
I	Input Waveforms for the SSTL Differential I/O Standard	<p>The diagram shows a differential signal waveform. The signal transitions between <math>V_{\text{IH}}</math> and <math>V_{\text{IL}}</math> levels, with a swing of <math>V_{\text{SWING}}</math>. The reference voltage <math>V_{\text{REF}}</math> is also indicated.</p>

Table 1-46. Glossary (Part 2 of 5)

Letter	Term	Definitions
<b>J</b>	JTAG Waveform	<p>The diagram illustrates the JTAG waveform with the following timing parameters:</p> <ul style="list-style-type: none"> <li><math>t_{JCP}</math>: Time from TCK rising edge to TDI setup.</li> <li><math>t_{JCH}</math>: Time from TCK falling edge to TDI hold.</li> <li><math>t_{JCL}</math>: Time from TCK falling edge to TDI setup.</li> <li><math>t_{JPSU\_TDI}</math>: Setup time for TDI before TCK rising edge.</li> <li><math>t_{JPSU\_TMS}</math>: Setup time for TMS before TCK rising edge.</li> <li><math>t_{JPH}</math>: Hold time for TMS after TCK rising edge.</li> <li><math>t_{JPZX}</math>: Time from TCK rising edge to TDO setup.</li> <li><math>t_{JPCO}</math>: Time from TCK falling edge to TDO setup.</li> <li><math>t_{JPXZ}</math>: Time from TCK falling edge to TDO hold.</li> <li><math>t_{JSSU}</math>: Setup time for Signal to be Captured before TCK rising edge.</li> <li><math>t_{JSH}</math>: Hold time for Signal to be Captured after TCK rising edge.</li> <li><math>t_{JSZX}</math>: Time from TCK rising edge to Signal to be Driven setup.</li> <li><math>t_{JSCO}</math>: Time from TCK falling edge to Signal to be Driven setup.</li> <li><math>t_{JSXZ}</math>: Time from TCK falling edge to Signal to be Driven hold.</li> </ul>
<b>K</b>	—	—
<b>L</b>	—	—
<b>M</b>	—	—
<b>N</b>	—	—
<b>O</b>	—	—
<b>P</b>	PLL Block	<p>The following highlights the PLL specification parameters:</p> <p>The diagram shows the PLL block architecture with the following components and signals:</p> <ul style="list-style-type: none"> <li><b>Inputs:</b> CLK, Core Clock.</li> <li><b>Internal Blocks:</b> Switchover, PFD (Phase-Frequency Divider), CP (Charge Pump), LF (Loop Filter), VCO (Voltage-Controlled Oscillator), Counters C0..C4, Phase tap, M (Modulator).</li> <li><b>Signals:</b> <math>f_{IN}</math>, <math>f_{INPFD}</math>, <math>f_{VCO}</math>, <math>f_{OUT\_EXT}</math>, <math>f_{OUT}</math>, GCLK.</li> </ul> <p><b>Key:</b></p> <ul style="list-style-type: none"> <li>Reconfigurable in User Mode</li> </ul>
<b>Q</b>	—	—

Table 1-46. Glossary (Part 3 of 5)

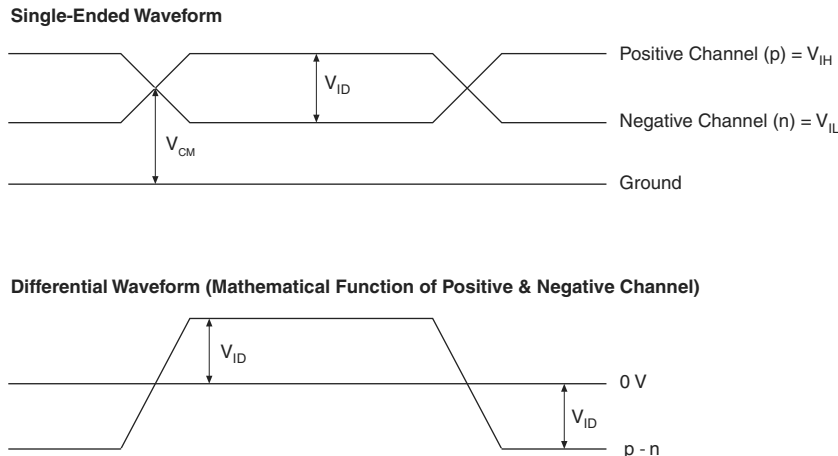
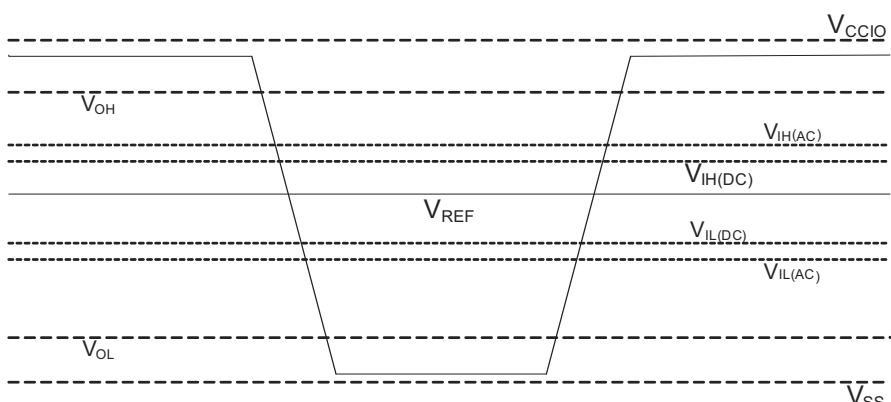
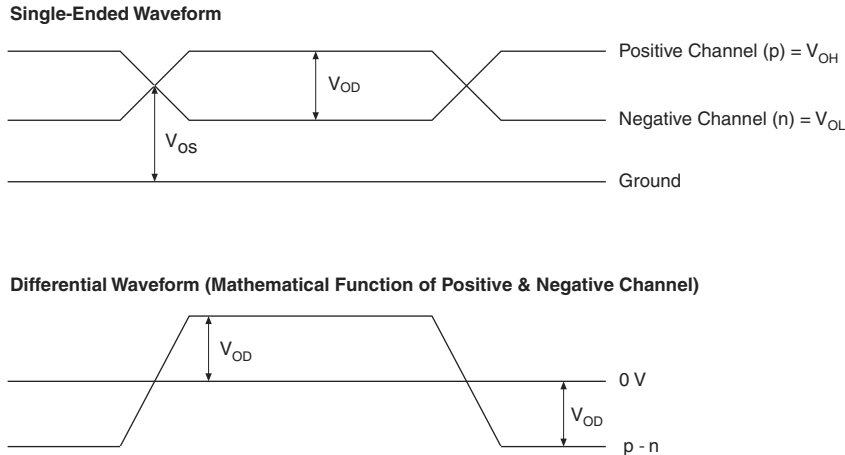
Letter	Term	Definitions
R	$R_L$	Receiver differential input discrete resistor (external to Cyclone IV devices).
	Receiver Input Waveform	<p>Receiver input waveform for LVDS and LVPECL differential standards:</p>  <p>Single-Ended Waveform</p> <p>Differential Waveform (Mathematical Function of Positive &amp; Negative Channel)</p>
	Receiver input skew margin (RSKM)	High-speed I/O block: The total margin left after accounting for the sampling window and TCCS. $RSKM = (TUI - SW - TCCS) / 2$ .
S	Single-ended voltage-referenced I/O Standard	 <p>The JEDEC standard for SSTI and HSTL I/O standards defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform <i>ringing</i>.</p>
	SW (Sampling Window)	High-speed I/O block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window.

Table 1-46. Glossary (Part 4 of 5)

Letter	Term	Definitions
T	$t_C$	High-speed receiver and transmitter input and output clock period.
	Channel-to-channel-skew (TCCS)	High-speed I/O block: The timing difference between the fastest and slowest output edges, including $t_{CO}$ variation and clock skew. The clock is included in the TCCS measurement.
	$t_{cin}$	Delay from the clock pad to the I/O input register.
	$t_{CO}$	Delay from the clock pad to the I/O output.
	$t_{cout}$	Delay from the clock pad to the I/O output register.
	$t_{DUTY}$	High-speed I/O block: Duty cycle on high-speed transmitter output clock.
	$t_{FALL}$	Signal high-to-low transition time (80–20%).
	$t_H$	Input register hold time.
	Timing Unit Interval (TUI)	High-speed I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(\text{Receiver Input Clock Frequency Multiplication Factor}) = t_C/w$ ).
	$t_{INJITTER}$	Period jitter on the PLL clock input.
	$t_{OUTJITTER\_DEDCLK}$	Period jitter on the dedicated clock output driven by a PLL.
	$t_{OUTJITTER\_IO}$	Period jitter on the general purpose I/O driven by a PLL.
	$t_{pllcin}$	Delay from the PLL inclk pad to the I/O input register.
	$t_{pllcout}$	Delay from the PLL inclk pad to the I/O output register.
	Transmitter Output Waveform	<p>Transmitter output waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards:</p> 
	$t_{RISE}$	Signal low-to-high transition time (20–80%).
	$t_{SU}$	Input register setup time.
U	—	—

**Table 1–47. Document Revision History**

Date	Version	Changes
February 2010	1.1	<ul style="list-style-type: none"><li>■ Updated Table 1–3 through Table 1–44 to include information for Cyclone IV E devices and Cyclone IV GX devices for Quartus II software version 9.1 SP1 release.</li><li>■ Minor text edits.</li></ul>
November 2009	1.0	Initial release.