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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|-----------------------------------------------------------------------------------------------------------------------------------|
| Product Status | Active |
| Number of LABs/CLBs | 1840 |
| Number of Logic Elements/Cells | 29440 |
| Total RAM Bits | 1105920 |
| Number of I/O | 290 |
| Number of Gates | - |
| Voltage - Supply | 1.16V ~ 1.24V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 484-BGA |
| Supplier Device Package | 484-FBGA (23x23) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/ep4cgx30cf23i7 |

Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices ⁽¹⁾, ⁽²⁾ (Part 1 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------------|----------------------------------------------------|----------------------------------------------|------------|-----|------------|------|
| $V_{CCINT}^{(3)}$ | Supply voltage for internal logic, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply voltage for internal logic, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| $V_{CCIO}^{(3), (4)}$ | Supply voltage for output buffers, 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Supply voltage for output buffers, 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | Supply voltage for output buffers, 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Supply voltage for output buffers, 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Supply voltage for output buffers, 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Supply voltage for output buffers, 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| $V_{CCA}^{(3)}$ | Supply (analog) voltage for PLL regulator | — | 2.375 | 2.5 | 2.625 | V |
| $V_{CCD_PLL}^{(3)}$ | Supply (digital) voltage for PLL, 1.2-V operation | — | 1.15 | 1.2 | 1.25 | V |
| | Supply (digital) voltage for PLL, 1.0-V operation | — | 0.97 | 1.0 | 1.03 | V |
| V_I | Input voltage | — | –0.5 | — | 3.6 | V |
| V_O | Output voltage | — | 0 | — | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | — | 85 | °C |
| | | For industrial use | –40 | — | 100 | °C |
| | | For extended temperature | –40 | — | 125 | °C |
| | | For automotive use | –40 | — | 125 | °C |
| t_{RAMP} | Power supply ramp time | Standard power-on reset (POR) ⁽⁵⁾ | 50 μ s | — | 50 ms | — |
| | | Fast POR ⁽⁶⁾ | 50 μ s | — | 3 ms | — |

Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices ^{(1), (2)} (Part 2 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-------------|------------------------------------------------------------|------------|-----|-----|-----|------|
| I_{Diode} | Magnitude of DC current across PCI-clamp diode when enable | — | — | — | 10 | mA |

Notes to Table 1–3:

- (1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades.
- (2) V_{CCIO} for all I/O banks must be powered up during device operation. All V_{CCA} pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (3) V_{CC} must rise monotonically.
- (4) V_{CCIO} powers all input buffers.
- (5) The POR time for Standard POR ranges between 50 and 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) The POR time for Fast POR ranges between 3 and 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.

Table 1–4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 1 of 2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|------------------------------------------|--------------------------------------------------------------------|------------|-------|-----|-------|------|
| V_{CCINT} ⁽³⁾ | Core voltage, PCIe hard IP block, and transceiver PCS power supply | — | 1.16 | 1.2 | 1.24 | V |
| V_{CCA} ^{(1), (3)} | PLL analog power supply | — | 2.375 | 2.5 | 2.625 | V |
| V_{CCD_PLL} ⁽²⁾ | PLL digital power supply | — | 1.16 | 1.2 | 1.24 | V |
| V_{CCIO} ^{(3), (4)} | I/O banks power supply for 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | I/O banks power supply for 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | I/O banks power supply for 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | I/O banks power supply for 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | I/O banks power supply for 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | I/O banks power supply for 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| V_{CC_CLKIN} ^{(3), (5), (6)} | Differential clock input pins power supply for 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Differential clock input pins power supply for 3.0-V operation | — | 2.85 | 3 | 3.15 | V |
| | Differential clock input pins power supply for 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Differential clock input pins power supply for 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Differential clock input pins power supply for 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Differential clock input pins power supply for 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| V_{CCH_GXB} | Transceiver output buffer power supply | — | 2.375 | 2.5 | 2.625 | V |

Table 1–7. Bus Hold Parameter for Cyclone IV Devices (Part 2 of 2) ⁽¹⁾

| Parameter | Condition | V _{CCIO} (V) | | | | | | | | | | | | Unit |
|---------------------|-----------|-----------------------|-----|-------|-------|------|------|-----|-----|-----|-----|-----|-----|------|
| | | 1.2 | | 1.5 | | 1.8 | | 2.5 | | 3.0 | | 3.3 | | |
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| Bus hold trip point | — | 0.3 | 0.9 | 0.375 | 1.125 | 0.68 | 1.07 | 0.7 | 1.7 | 0.8 | 2 | 0.8 | 2 | V |

Note to Table 1–7:

(1) Bus hold trip points are based on the calculated input voltages from the JEDEC standard.

OCT Specifications

Table 1–8 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

Table 1–8. Series OCT Without Calibration Specifications for Cyclone IV Devices

| Description | V_{CCIO} (V) | Resistance Tolerance | | Unit |
|--------------------------------|----------------|----------------------|---------------------------------------------------------|------|
| | | Commercial Maximum | Industrial, Extended industrial, and Automotive Maximum | |
| Series OCT without calibration | 3.0 | ±30 | ±40 | % |
| | 2.5 | ±30 | ±40 | % |
| | 1.8 | ±40 | ±50 | % |
| | 1.5 | ±50 | ±50 | % |
| | 1.2 | ±50 | ±50 | % |

OCT calibration is automatically performed at device power-up for OCT-enabled I/Os.

Table 1–9 lists the OCT calibration accuracy at device power-up.

Table 1–9. Series OCT with Calibration at Device Power-Up Specifications for Cyclone IV Devices

| Description | V_{CCIO} (V) | Calibration Accuracy | | Unit |
|------------------------------------------------|----------------|----------------------|---------------------------------------------------------|------|
| | | Commercial Maximum | Industrial, Extended industrial, and Automotive Maximum | |
| Series OCT with calibration at device power-up | 3.0 | ±10 | ±10 | % |
| | 2.5 | ±10 | ±10 | % |
| | 1.8 | ±10 | ±10 | % |
| | 1.5 | ±10 | ±10 | % |
| | 1.2 | ±10 | ±10 | % |

Schmitt Trigger Input

Cyclone IV devices support Schmitt trigger input on the TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with slow edge rate. Table 1–14 lists the hysteresis specifications across the supported V_{CCIO} range for Schmitt trigger inputs in Cyclone IV devices.

Table 1–14. Hysteresis Specifications for Schmitt Trigger Input in Cyclone IV Devices

| Symbol | Parameter | Conditions (V) | Minimum | Unit |
|---------------|--------------------------------------|------------------|---------|------|
| $V_{SCHMITT}$ | Hysteresis for Schmitt trigger input | $V_{CCIO} = 3.3$ | 200 | mV |
| | | $V_{CCIO} = 2.5$ | 200 | mV |
| | | $V_{CCIO} = 1.8$ | 140 | mV |
| | | $V_{CCIO} = 1.5$ | 110 | mV |

I/O Standard Specifications

The following tables list input voltage sensitivities (V_{IH} and V_{IL}), output voltage (V_{OH} and V_{OL}), and current drive characteristics (I_{OH} and I_{OL}), for various I/O standards supported by Cyclone IV devices. Table 1–15 through Table 1–20 provide the I/O standard specifications for Cyclone IV devices.

Table 1–15. Single-Ended I/O Standard Specifications for Cyclone IV Devices ^{(1), (2)}

| I/O Standard | V_{CCIO} (V) | | | V_{IL} (V) | | V_{IH} (V) | | V_{OL} (V) | V_{OH} (V) | I_{OL} (mA) (4) | I_{OH} (mA) (4) |
|-----------------------------|----------------|-----|-------|--------------|------------------------|------------------------|------------------|------------------------|------------------------|----------------------|----------------------|
| | Min | Typ | Max | Min | Max | Min | Max | Max | Min | | |
| 3.3-V LVTTTL ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.45 | 2.4 | 4 | –4 |
| 3.3-V LVCMOS ⁽³⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.2 | $V_{CCIO} - 0.2$ | 2 | –2 |
| 3.0-V LVTTTL ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.45 | 2.4 | 4 | –4 |
| 3.0-V LVCMOS ⁽³⁾ | 2.85 | 3.0 | 3.15 | –0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.2 | $V_{CCIO} - 0.2$ | 0.1 | –0.1 |
| 2.5 V ⁽³⁾ | 2.375 | 2.5 | 2.625 | –0.3 | 0.7 | 1.7 | $V_{CCIO} + 0.3$ | 0.4 | 2.0 | 1 | –1 |
| 1.8 V | 1.71 | 1.8 | 1.89 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | 2.25 | 0.45 | $V_{CCIO} - 0.45$ | 2 | –2 |
| 1.5 V | 1.425 | 1.5 | 1.575 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 1.2 V | 1.14 | 1.2 | 1.26 | –0.3 | $0.35 \times V_{CCIO}$ | $0.65 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 \times V_{CCIO}$ | $0.75 \times V_{CCIO}$ | 2 | –2 |
| 3.0-V PCI | 2.85 | 3.0 | 3.15 | — | $0.3 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |
| 3.0-V PCI-X | 2.85 | 3.0 | 3.15 | — | $0.35 \times V_{CCIO}$ | $0.5 \times V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 \times V_{CCIO}$ | $0.9 \times V_{CCIO}$ | 1.5 | –0.5 |

Notes to Table 1–15:

- (1) For voltage-referenced receiver input waveform and explanation of terms used in Table 1–15, refer to “Glossary” on page 1–37.
- (2) AC load $CL = 10$ pF
- (3) For more information about interfacing Cyclone IV devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O standards, refer to *AN 447: Interfacing Cyclone III and Cyclone IV Devices with 3.3/3.0/2.5-V LVTTTL/LVCMOS I/O Systems*.
- (4) To meet the I_{OL} and I_{OH} specifications, you must set the current strength settings accordingly. For example, to meet the **3.3-V LVTTTL** specification (4 mA), set the current strength settings to 4 mA or higher. Setting at lower current strength may not meet the I_{OL} and I_{OH} specifications in the handbook.

Table 1–20. Differential I/O Standard Specifications for Cyclone IV Devices ⁽¹⁾ (Part 2 of 2)

| I/O Standard | V _{CCIO} (V) | | | V _{ID} (mV) | | V _{ICM} (V) ⁽²⁾ | | | V _{OD} (mV) ⁽³⁾ | | | V _{OS} (V) ⁽³⁾ | | |
|---------------------------------------------|-----------------------|-----|-------|----------------------|-----|-------------------------------------|-------------------------------------------------------|------|-------------------------------------|-----|-----|------------------------------------|------|-------|
| | Min | Typ | Max | Min | Max | Min | Condition | Max | Min | Typ | Max | Min | Typ | Max |
| LVDS (Column I/Os) | 2.375 | 2.5 | 2.625 | 100 | — | 0.05 | $D_{MAX} \leq 500 \text{ Mbps}$ | 1.80 | 247 | — | 600 | 1.125 | 1.25 | 1.375 |
| | | | | | | 0.55 | $500 \text{ Mbps} \leq D_{MAX} \leq 700 \text{ Mbps}$ | 1.80 | | | | | | |
| | | | | | | 1.05 | $D_{MAX} > 700 \text{ Mbps}$ | 1.55 | | | | | | |
| BLVDS (Row I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| BLVDS (Column I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| mini-LVDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| mini-LVDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| RSDS [®] (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| RSDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| PPDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |
| PPDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |

Notes to Table 1–20:

- (1) For an explanation of terms used in Table 1–20, refer to “Glossary” on page 1–37.
- (2) V_{IN} range: $0 \text{ V} \leq V_{IN} \leq 1.85 \text{ V}$.
- (3) R_L range: $90 \leq R_L \leq 110 \Omega$.
- (4) There are no fixed V_{IN}, V_{OD}, and V_{OS} specifications for BLVDS. They depend on the system topology.
- (5) The Mini-LVDS, RSDS, and PPDS standards are only supported at the output pins.
- (6) The LVPECL I/O standard is only supported on dedicated clock input pins. This I/O standard is not supported for output pins.

Table 1-21. Transceiver Specification for Cyclone IV GX Devices (Part 3 of 4)

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|----------------------------------------------------------------|-----------------------------------------------------|-----------|-----|-------|--------|-----|-------|-----|-----|-------|--------------------------------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| Signal detect/loss threshold | PIPE mode | 65 | — | 175 | 65 | — | 175 | 65 | — | 175 | mV |
| t_{LTR} ⁽¹⁰⁾ | — | — | — | 75 | — | — | 75 | — | — | 75 | μs |
| $t_{LTR-LTD_Manual}$ ⁽¹¹⁾ | — | 15 | — | — | 15 | — | — | 15 | — | — | μs |
| t_{LTD} ⁽¹²⁾ | — | 0 | 100 | 4000 | 0 | 100 | 4000 | 0 | 100 | 4000 | ns |
| t_{LTD_Manual} ⁽¹³⁾ | — | — | — | 4000 | — | — | 4000 | — | — | 4000 | ns |
| t_{LTD_Auto} ⁽¹⁴⁾ | — | — | — | 4000 | — | — | 4000 | — | — | 4000 | ns |
| Receiver buffer and CDR offset cancellation time (per channel) | — | — | — | 17000 | — | — | 17000 | — | — | 17000 | recon fig_c lk cycles |
| Programmable DC gain | DC Gain Setting = 0 | — | 0 | — | — | 0 | — | — | 0 | — | dB |
| | DC Gain Setting = 1 | — | 3 | — | — | 3 | — | — | 3 | — | dB |
| | DC Gain Setting = 2 | — | 6 | — | — | 6 | — | — | 6 | — | dB |
| Transmitter | | | | | | | | | | | |
| Supported I/O Standards | 1.5 V PCML | | | | | | | | | | |
| Data rate (F324 and smaller package) | — | 600 | — | 2500 | 600 | — | 2500 | 600 | — | 2500 | Mbps |
| Data rate (F484 and larger package) | — | 600 | — | 3125 | 600 | — | 3125 | 600 | — | 2500 | Mbps |
| V_{OCM} | 0.65 V setting | — | 650 | — | — | 650 | — | — | 650 | — | mV |
| Differential on-chip termination resistors | 100-Ω setting | — | 100 | — | — | 100 | — | — | 100 | — | Ω |
| | 150-Ω setting | — | 150 | — | — | 150 | — | — | 150 | — | Ω |
| Differential and common mode return loss | PIPE, CPRI LV, Serial Rapid I/O SR, SDI, XAUI, SATA | Compliant | | | | | | | | | — |
| Rise time | — | 50 | — | 200 | 50 | — | 200 | 50 | — | 200 | ps |
| Fall time | — | 50 | — | 200 | 50 | — | 200 | 50 | — | 200 | ps |
| Intra-differential pair skew | — | — | — | 15 | — | — | 15 | — | — | 15 | ps |
| Intra-transceiver block skew | — | — | — | 120 | — | — | 120 | — | — | 120 | ps |

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 4 of 4)

| Symbol/ Description | Conditions | C6 | | | C7, I7 | | | C8 | | | Unit |
|--------------------------------------------------|------------|------------------------------------|-----|--------|--------|-----|--------|-----|-----|--------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| PLD-Transceiver Interface | | | | | | | | | | | |
| Interface speed (F324 and smaller package) | — | 25 | — | 125 | 25 | — | 125 | 25 | — | 125 | MHz |
| Interface speed (F484 and larger package) | — | 25 | — | 156.25 | 25 | — | 156.25 | 25 | — | 156.25 | MHz |
| Digital reset pulse width | — | Minimum is 2 parallel clock cycles | | | | | | | | | |

Notes to Table 1–21:

- (1) This specification is valid for transmitter output jitter specification with a maximum total jitter value of 112 ps, typically for 3.125 Gbps SRIO and XAUI protocols.
- (2) The minimum `reconfig_clk` frequency is 2.5 MHz if the transceiver channel is configured in **Transmitter Only** mode. The minimum `reconfig_clk` frequency is 37.5 MHz if the transceiver channel is configured in **Receiver Only** or **Receiver and Transmitter** mode.
- (3) The device cannot tolerate prolonged operation at this absolute maximum.
- (4) The rate matcher supports only up to ± 300 parts per million (ppm).
- (5) Supported for the F169 and F324 device packages only.
- (6) Supported for the F484, F672, and F896 device packages only. Pending device characterization.
- (7) To support CDR ppm tolerance greater than ± 300 ppm, implement ppm detector in user logic and configure CDR to Manual Lock Mode.
- (8) Asynchronous spread-spectrum clocking is not supported.
- (9) For the EP4CGX30 (F484 package only), EP4CGX50, and EP4CGX75 devices, the CDR ppl tolerance is ± 200 ppm.
- (10) Time taken until `p11_locked` goes high after `p11_powerdown` deasserts.
- (11) Time that the CDR must be kept in lock-to-reference mode after `rx_analogreset` deasserts and before `rx_locktodata` is asserted in manual mode.
- (12) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode (Figure 1–2), or after `rx_freqlocked` signal goes high in automatic mode (Figure 1–3).
- (13) Time taken to recover valid data after the `rx_locktodata` signal is asserted in manual mode.
- (14) Time taken to recover valid data after the `rx_freqlocked` signal goes high in automatic mode.
- (15) To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.

Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 2 of 2)

| Device | Performance | | | | | | | | Unit |
|-----------|-------------|-------|-----|--------------------|--------------------|-------|--------------------|----|------|
| | C6 | C7 | C8 | C8L ⁽¹⁾ | C9L ⁽¹⁾ | I7 | I8L ⁽¹⁾ | A7 | |
| EP4CE55 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE75 | 500 | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CE115 | — | 437.5 | 402 | 362 | 265 | 437.5 | 362 | — | MHz |
| EP4CGX15 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX22 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX30 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX50 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX75 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX110 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |
| EP4CGX150 | 500 | 437.5 | 402 | — | — | 437.5 | — | — | MHz |

Note to Table 1–24:

(1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades.

PLL Specifications

Table 1–25 lists the PLL specifications for Cyclone IV devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (–40°C to 100°C), the extended industrial junction temperature range (–40°C to 125°C), and the automotive junction temperature range (–40°C to 125°C). For more information about the PLL block, refer to “Glossary” on page 1–37.

Table 1–25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 1 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|-------------------------------------------------------|-------------------------------------------------------------|-----|-----|-------|------|
| $f_{IN}^{(3)}$ | Input clock frequency (–6, –7, –8 speed grades) | 5 | — | 472.5 | MHz |
| | Input clock frequency (–8L speed grade) | 5 | — | 362 | MHz |
| | Input clock frequency (–9L speed grade) | 5 | — | 265 | MHz |
| f_{INPFD} | PFD input frequency | 5 | — | 325 | MHz |
| $f_{VCO}^{(4)}$ | PLL internal VCO operating range | 600 | — | 1300 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | — | 60 | % |
| $t_{INJITTER_CCJ}^{(5)}$ | Input clock cycle-to-cycle jitter $F_{REF} \geq 100$ MHz | — | — | 0.15 | UI |
| | $F_{REF} < 100$ MHz | — | — | ±750 | ps |
| f_{OUT_EXT} (external clock output) ⁽³⁾ | PLL output frequency | — | — | 472.5 | MHz |
| f_{OUT} (to global clock) | PLL output frequency (–6 speed grade) | — | — | 472.5 | MHz |
| | PLL output frequency (–7 speed grade) | — | — | 450 | MHz |
| | PLL output frequency (–8 speed grade) | — | — | 402.5 | MHz |
| | PLL output frequency (–8L speed grade) | — | — | 362 | MHz |
| | PLL output frequency (–9L speed grade) | — | — | 265 | MHz |
| $t_{OUTDUTY}$ | Duty cycle for external clock output (when set to 50%) | 45 | 50 | 55 | % |
| t_{LOCK} | Time required to lock from end of device configuration | — | — | 1 | ms |

Table 1–25. PLL Specifications for Cyclone IV Devices ^{(1), (2)} (Part 2 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------|-----|--------------------|----------|----------------|
| t_{DLOCK} | Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or \overline{areset} is deasserted) | — | — | 1 | ms |
| $t_{OUTJITTER_PERIOD_DEDCLK}^{(6)}$ | Dedicated clock output period jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_CCJ_DEDCLK}^{(6)}$ | Dedicated clock output cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_PERIOD_IO}^{(6)}$ | Regular I/O period jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| $t_{OUTJITTER_CCJ_IO}^{(6)}$ | Regular I/O cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | — | — | ± 50 | ps |
| t_{ARESET} | Minimum pulse width on \overline{areset} signal. | 10 | — | — | ns |
| $t_{CONFIGPLL}$ | Time required to reconfigure scan chains for PLLs | — | 3.5 ⁽⁷⁾ | — | SCANCLK cycles |
| $f_{SCANCLK}$ | scanclk frequency | — | — | 100 | MHz |
| $t_{CASC_OUTJITTER_PERIOD_DEDCLK}^{(8), (9)}$ | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} \geq 100$ MHz) | — | — | 425 | ps |
| | Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} < 100$ MHz) | — | — | 42.5 | mUI |

Notes to Table 1–25:

- (1) This table is applicable for general purpose PLLs and multipurpose PLLs.
- (2) You must connect V_{CCD_PLL} to V_{CCINT} through the decoupling capacitor and ferrite bead.
- (3) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (4) The V_{CO} frequency reported by the Quartus II software in the PLL Summary section of the compilation report takes into consideration the V_{CO} post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the f_{VCO} specification.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source that is less than 200 ps.
- (6) Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL when an input jitter of 30 ps is applied.
- (7) With 100-MHz scanclk frequency.
- (8) The cascaded PLLs specification is applicable only with the following conditions:
 - Upstream PLL— $0.59 \text{ MHz} \leq \text{Upstream PLL bandwidth} < 1 \text{ MHz}$
 - Downstream PLL—Downstream PLL bandwidth $> 2 \text{ MHz}$
- (9) PLL cascading is not supported for transceiver applications.

Embedded Multiplier Specifications

Table 1–26 lists the embedded multiplier specifications for Cyclone IV devices.

Table 1–26. Embedded Multiplier Specifications for Cyclone IV Devices

| Mode | Resources Used | Performance | | | | | Unit |
|------------------------|-----------------------|-------------|------------|-----|----------|-----|------|
| | Number of Multipliers | C6 | C7, I7, A7 | C8 | C8L, I8L | C9L | |
| 9 × 9-bit multiplier | 1 | 340 | 300 | 260 | 240 | 175 | MHz |
| 18 × 18-bit multiplier | 1 | 287 | 250 | 200 | 185 | 135 | MHz |

Memory Block Specifications

Table 1–27 lists the M9K memory block specifications for Cyclone IV devices.

Table 1–27. Memory Block Performance Specifications for Cyclone IV Devices

| Memory | Mode | Resources Used | | Performance | | | | | Unit |
|-----------|------------------------------------|----------------|------------|-------------|------------|-----|----------|-----|------|
| | | LEs | M9K Memory | C6 | C7, I7, A7 | C8 | C8L, I8L | C9L | |
| M9K Block | FIFO 256 × 36 | 47 | 1 | 315 | 274 | 238 | 200 | 157 | MHz |
| | Single-port 256 × 36 | 0 | 1 | 315 | 274 | 238 | 200 | 157 | MHz |
| | Simple dual-port 256 × 36 CLK | 0 | 1 | 315 | 274 | 238 | 200 | 157 | MHz |
| | True dual port 512 × 18 single CLK | 0 | 1 | 315 | 274 | 238 | 200 | 157 | MHz |

Configuration and JTAG Specifications

Table 1–28 lists the configuration mode specifications for Cyclone IV devices.

Table 1–28. Passive Configuration Mode Specifications for Cyclone IV Devices ⁽¹⁾

| Programming Mode | V _{CCINT} Voltage Level (V) | DCLK f _{MAX} | Unit |
|--------------------------------------------|--------------------------------------|-----------------------|------|
| Passive Serial (PS) | 1.0 ⁽³⁾ | 66 | MHz |
| | 1.2 | 133 | MHz |
| Fast Passive Parallel (FPP) ⁽²⁾ | 1.0 ⁽³⁾ | 66 | MHz |
| | 1.2 ⁽⁴⁾ | 100 | MHz |

Notes to Table 1–28:

- (1) For more information about PS and FPP configuration timing parameters, refer to the *Configuration and Remote System Upgrades in Cyclone IV Devices* chapter.
- (2) FPP configuration mode supports all Cyclone IV E devices (except for E144 package devices) and EP4CGX50, EP4CGX75, EP4CGX110, and EP4CGX150 only.
- (3) V_{CCINT} = 1.0 V is only supported for Cyclone IV E 1.0 V core voltage devices.
- (4) Cyclone IV E devices support 1.2 V V_{CCINT}. Cyclone IV E 1.2 V core voltage devices support 133 MHz DCLK f_{MAX} for EP4CE6, EP4CE10, EP4CE15, EP4CE22, EP4CE30, and EP4CE40 only.

Table 1–32. Emulated RSDS_E_1R Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (3)} (Part 2 of 2)

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|----------------------------------|-------|-----|-----|-----|--------|-----|-----|--------|-----|-----|----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| t_{LOCK} ⁽²⁾ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1–32:

- (1) Emulated RSDS_E_1R transmitter is supported at the output pin of all I/O Banks of Cyclone IV E devices and I/O Banks 3, 4, 5, 6, 7, 8, and 9 of Cyclone IV GX devices.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–33. Mini-LVDS Transmitter Timing Specifications for Cyclone IV Devices ^{(1), (2), (4)}

| Symbol | Modes | C6 | | | C7, I7 | | | C8, A7 | | | C8L, I8L | | | C9L | | | Unit |
|--------------------------------------------|-----------------------------------------------|-----|-----|-----|--------|-----|-------|--------|-----|-------|----------|-----|-------|-----|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| f_{HSCLK} (input clock frequency) | ×10 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×8 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×7 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×4 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×2 | 5 | — | 200 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 155.5 | 5 | — | 132.5 | MHz |
| | ×1 | 5 | — | 400 | 5 | — | 311 | 5 | — | 311 | 5 | — | 311 | 5 | — | 265 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 400 | 100 | — | 311 | 100 | — | 311 | 100 | — | 311 | 100 | — | 265 | Mbps |
| | ×8 | 80 | — | 400 | 80 | — | 311 | 80 | — | 311 | 80 | — | 311 | 80 | — | 265 | Mbps |
| | ×7 | 70 | — | 400 | 70 | — | 311 | 70 | — | 311 | 70 | — | 311 | 70 | — | 265 | Mbps |
| | ×4 | 40 | — | 400 | 40 | — | 311 | 40 | — | 311 | 40 | — | 311 | 40 | — | 265 | Mbps |
| | ×2 | 20 | — | 400 | 20 | — | 311 | 20 | — | 311 | 20 | — | 311 | 20 | — | 265 | Mbps |
| | ×1 | 10 | — | 400 | 10 | — | 311 | 10 | — | 311 | 10 | — | 311 | 10 | — | 265 | Mbps |
| t_{DUTY} | — | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 500 | — | — | 550 | — | — | 600 | — | — | 700 | ps |
| t_{RISE} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t_{FALL} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | — | 500 | — | ps |
| t_{LOCK} ⁽³⁾ | — | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | — | — | 1 | ms |

Notes to Table 1–33:

- (1) Applicable for true and emulated mini-LVDS transmitter.
- (2) Cyclone IV E—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Emulated mini-LVDS transmitter is supported at the output pin of all I/O banks.
Cyclone IV GX—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated mini-LVDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (3) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (4) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1-34. True LVDS Transmitter Timing Specifications for Cyclone IV Devices ⁽¹⁾, ⁽³⁾

| Symbol | Modes | C6 | | C7, I7 | | C8, A7 | | C8L, I8L | | C9L | | Unit |
|-------------------------------------------|-------|-----|-----|--------|-------|--------|-------|----------|-----|-----|-----|------|
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| f _{HCLK} (input clock frequency) | ×10 | 5 | 420 | 5 | 370 | 5 | 320 | 5 | 320 | 5 | 250 | MHz |
| | ×8 | 5 | 420 | 5 | 370 | 5 | 320 | 5 | 320 | 5 | 250 | MHz |
| | ×7 | 5 | 420 | 5 | 370 | 5 | 320 | 5 | 320 | 5 | 250 | MHz |
| | ×4 | 5 | 420 | 5 | 370 | 5 | 320 | 5 | 320 | 5 | 250 | MHz |
| | ×2 | 5 | 420 | 5 | 370 | 5 | 320 | 5 | 320 | 5 | 250 | MHz |
| | ×1 | 5 | 420 | 5 | 402.5 | 5 | 402.5 | 5 | 362 | 5 | 265 | MHz |
| HSIODR | ×10 | 100 | 840 | 100 | 740 | 100 | 640 | 100 | 640 | 100 | 500 | Mbps |
| | ×8 | 80 | 840 | 80 | 740 | 80 | 640 | 80 | 640 | 80 | 500 | Mbps |
| | ×7 | 70 | 840 | 70 | 740 | 70 | 640 | 70 | 640 | 70 | 500 | Mbps |
| | ×4 | 40 | 840 | 40 | 740 | 40 | 640 | 40 | 640 | 40 | 500 | Mbps |
| | ×2 | 20 | 840 | 20 | 740 | 20 | 640 | 20 | 640 | 20 | 500 | Mbps |
| | ×1 | 10 | 420 | 10 | 402.5 | 10 | 402.5 | 10 | 362 | 10 | 265 | Mbps |
| t _{DUTY} | — | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | % |
| TCCS | — | — | 200 | — | 200 | — | 200 | — | 200 | — | 200 | ps |
| Output jitter (peak to peak) | — | — | 500 | — | 500 | — | 550 | — | 600 | — | 700 | ps |
| t _{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | — | 1 | — | 1 | — | 1 | ms |

Notes to Table 1-34:

- (1) Cyclone IV E—true LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6.
Cyclone IV GX—true LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1-35. Emulated LVDS Transmitter Timing Specifications for Cyclone IV Devices ⁽¹⁾, ⁽³⁾ (Part 1 of 2)

| Symbol | Modes | C6 | | C7, I7 | | C8, A7 | | C8L, I8L | | C9L | | Unit |
|-------------------------------------------|-------|-----|-------|--------|-------|--------|-------|----------|-----|-----|-----|------|
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| f _{HCLK} (input clock frequency) | ×10 | 5 | 320 | 5 | 320 | 5 | 275 | 5 | 275 | 5 | 250 | MHz |
| | ×8 | 5 | 320 | 5 | 320 | 5 | 275 | 5 | 275 | 5 | 250 | MHz |
| | ×7 | 5 | 320 | 5 | 320 | 5 | 275 | 5 | 275 | 5 | 250 | MHz |
| | ×4 | 5 | 320 | 5 | 320 | 5 | 275 | 5 | 275 | 5 | 250 | MHz |
| | ×2 | 5 | 320 | 5 | 320 | 5 | 275 | 5 | 275 | 5 | 250 | MHz |
| | ×1 | 5 | 402.5 | 5 | 402.5 | 5 | 402.5 | 5 | 362 | 5 | 265 | MHz |
| HSIODR | ×10 | 100 | 640 | 100 | 640 | 100 | 550 | 100 | 550 | 100 | 500 | Mbps |
| | ×8 | 80 | 640 | 80 | 640 | 80 | 550 | 80 | 550 | 80 | 500 | Mbps |
| | ×7 | 70 | 640 | 70 | 640 | 70 | 550 | 70 | 550 | 70 | 500 | Mbps |
| | ×4 | 40 | 640 | 40 | 640 | 40 | 550 | 40 | 550 | 40 | 500 | Mbps |
| | ×2 | 20 | 640 | 20 | 640 | 20 | 550 | 20 | 550 | 20 | 500 | Mbps |
| | ×1 | 10 | 402.5 | 10 | 402.5 | 10 | 402.5 | 10 | 362 | 10 | 265 | Mbps |

For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interface Handbook*.

Table 1–37 lists the memory output clock jitter specifications for Cyclone IV devices.

Table 1–37. Memory Output Clock Jitter Specifications for Cyclone IV Devices ^{(1), (2)}

| Parameter | Symbol | Min | Max | Unit |
|------------------------------|-----------------|------|-----|------|
| Clock period jitter | $t_{JIT(per)}$ | –125 | 125 | ps |
| Cycle-to-cycle period jitter | $t_{JIT(cc)}$ | –200 | 200 | ps |
| Duty cycle jitter | $t_{JIT(duty)}$ | –150 | 150 | ps |

Notes to Table 1–37:

- (1) Memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock (GCLK) network.

Duty Cycle Distortion Specifications

Table 1–38 lists the worst case duty cycle distortion for Cyclone IV devices.

Table 1–38. Duty Cycle Distortion on Cyclone IV Devices I/O Pins ^{(1), (2), (3)}

| Symbol | C6 | | C7, I7 | | C8, I8L, A7 | | C9L | | Unit |
|-------------------|-----|-----|--------|-----|-------------|-----|-----|-----|------|
| | Min | Max | Min | Max | Min | Max | Min | Max | |
| Output Duty Cycle | 45 | 55 | 45 | 55 | 45 | 55 | 45 | 55 | % |

Notes to Table 1–38:

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and IOE driving the dedicated and general purpose I/O pins.
- (2) Cyclone IV devices meet the specified duty cycle distortion at the maximum output toggle rate for each combination of I/O standard and current strength.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

OCT Calibration Timing Specification

Table 1–39 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone IV devices.

Table 1–39. Timing Specification for Series OCT with Calibration at Device Power-Up for Cyclone IV Devices ⁽¹⁾

| Symbol | Description | Maximum | Units |
|--------------|------------------------------------------------------------|---------|---------|
| t_{OCTCAL} | Duration of series OCT with calibration at device power-up | 20 | μ s |

Note to Table 1–39:

- (1) OCT calibration takes place after device configuration and before entering user mode.

Table 1–42 and Table 1–43 list the IOE programmable delay for Cyclone IV E 1.2 V core voltage devices.

Table 1–42. IOE Programmable Delay on Column Pins for Cyclone IV E 1.2 V Core Voltage Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Setting | Min Offset | Max Offset | | | | | | | | Unit |
|-----------------------------------------------------------------|-----------------------------|-------------------|------------|-------------|-------|-------|-------------|-------|-------|-------|-------|------|
| | | | | Fast Corner | | | Slow Corner | | | | | |
| | | | | C6 | I7 | A7 | C6 | C7 | C8 | I7 | A7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.314 | 1.211 | 1.211 | 2.177 | 2.340 | 2.433 | 2.388 | 2.508 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.307 | 1.203 | 1.203 | 2.19 | 2.387 | 2.540 | 2.430 | 2.545 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.437 | 0.402 | 0.402 | 0.747 | 0.820 | 0.880 | 0.834 | 0.873 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.693 | 0.665 | 0.665 | 1.200 | 1.379 | 1.532 | 1.393 | 1.441 | ns |

Notes to Table 1–42:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–43. IOE Programmable Delay on Row Pins for Cyclone IV E 1.2 V Core Voltage Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Setting | Min Offset | Max Offset | | | | | | | | Unit |
|-----------------------------------------------------------------|-----------------------------|-------------------|------------|-------------|-------|-------|-------------|-------|-------|-------|-------|------|
| | | | | Fast Corner | | | Slow Corner | | | | | |
| | | | | C6 | I7 | A7 | C6 | C7 | C8 | I7 | A7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.314 | 1.209 | 1.209 | 2.201 | 2.386 | 2.510 | 2.429 | 2.548 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.312 | 1.207 | 1.207 | 2.202 | 2.402 | 2.558 | 2.447 | 2.557 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.458 | 0.419 | 0.419 | 0.783 | 0.861 | 0.924 | 0.875 | 0.915 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.686 | 0.657 | 0.657 | 1.185 | 1.360 | 1.506 | 1.376 | 1.422 | ns |

Notes to Table 1–43:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–44 and Table 1–45 list the IOE programmable delay for Cyclone IV GX devices.

Table 1–44. IOE Programmable Delay on Column Pins for Cyclone IV GX Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Settings | Min Offset | Max Offset | | | | | | Unit |
|-----------------------------------------------------------------|-----------------------------|--------------------|------------|-------------|-------|-------------|-------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | | |
| | | | | C6 | I7 | C6 | C7 | C8 | I7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.313 | 1.209 | 2.184 | 2.336 | 2.451 | 2.387 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.312 | 1.208 | 2.200 | 2.399 | 2.554 | 2.446 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.438 | 0.404 | 0.751 | 0.825 | 0.886 | 0.839 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.713 | 0.682 | 1.228 | 1.41 | 1.566 | 1.424 | ns |

Notes to Table 1–44:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–45. IOE Programmable Delay on Row Pins for Cyclone IV GX Devices ^{(1), (2)}

| Parameter | Paths Affected | Number of Settings | Min Offset | Max Offset | | | | | | Unit |
|-----------------------------------------------------------------|-----------------------------|--------------------|------------|-------------|-------|-------------|-------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | | |
| | | | | C6 | I7 | C6 | C7 | C8 | I7 | |
| Input delay from pin to internal cells | Pad to I/O dataout to core | 7 | 0 | 1.314 | 1.210 | 2.209 | 2.398 | 2.526 | 2.443 | ns |
| Input delay from pin to input register | Pad to I/O input register | 8 | 0 | 1.313 | 1.208 | 2.205 | 2.406 | 2.563 | 2.450 | ns |
| Delay from output register to output pin | I/O output register to pad | 2 | 0 | 0.461 | 0.421 | 0.789 | 0.869 | 0.933 | 0.884 | ns |
| Input delay from dual-purpose clock pin to fan-out destinations | Pad to global clock network | 12 | 0 | 0.712 | 0.682 | 1.225 | 1.407 | 1.562 | 1.421 | ns |

Notes to Table 1–45:

- (1) The incremental values for the settings are generally linear. For exact values of each setting, use the latest version of Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software

I/O Timing

Use the following methods to determine I/O timing:

- the Excel-based I/O Timing
- the Quartus II timing analyzer

The Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II timing analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.



The Excel-based I/O Timing spreadsheet is downloadable from Cyclone IV Devices Literature website.

Glossary

Table 1–46 lists the glossary for this chapter.

Table 1–46. Glossary (Part 1 of 5)

| Letter | Term | Definitions |
|--------|--------------------------------------------------------|---------------------------------------------------------------------------------------------------|
| A | — | — |
| B | — | — |
| C | — | — |
| D | — | — |
| E | — | — |
| F | f_{HSCLK} | High-speed I/O block: High-speed receiver/transmitter input and output clock frequency. |
| G | GCLK | Input pin directly to Global Clock network. |
| | GCLK PLL | Input pin to Global Clock network through the PLL. |
| H | HSIODR | High-speed I/O block: Maximum/minimum LVDS data transfer rate ($\text{HSIODR} = 1/\text{TUI}$). |
| I | Input Waveforms for the SSTL Differential I/O Standard | |

Table 1-46. Glossary (Part 3 of 5)

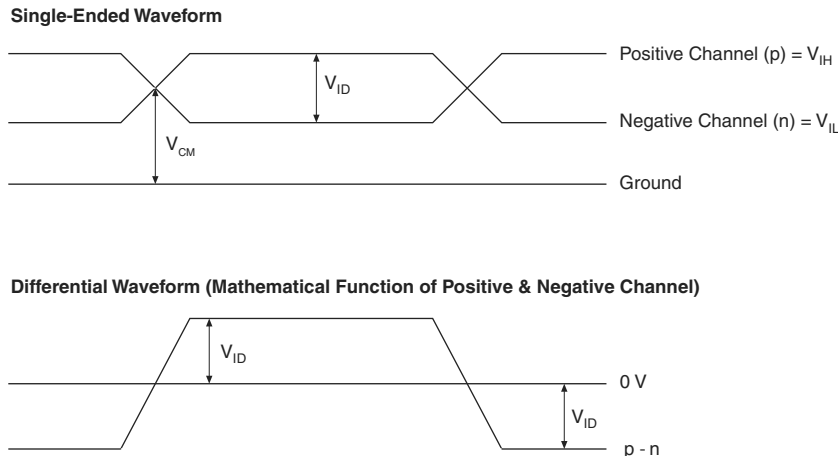
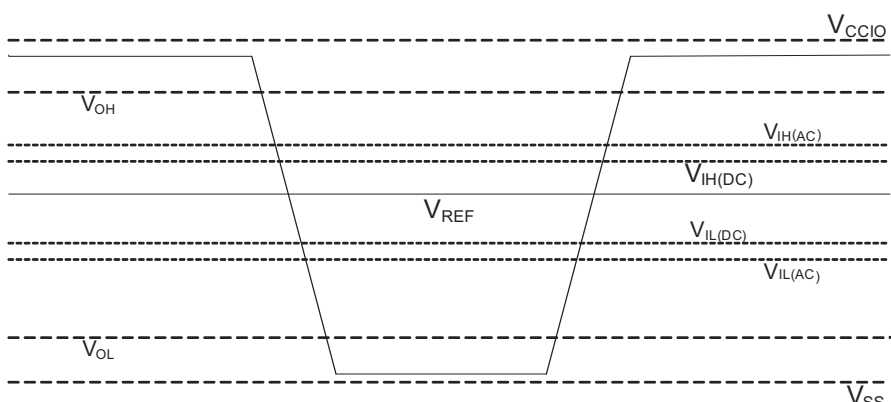
| Letter | Term | Definitions |
|--------|----------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| R | R_L | Receiver differential input discrete resistor (external to Cyclone IV devices). |
| | Receiver Input Waveform | <p>Receiver input waveform for LVDS and LVPECL differential standards:</p>  |
| | Receiver input skew margin (RSKM) | High-speed I/O block: The total margin left after accounting for the sampling window and TCCS. $RSKM = (TUI - SW - TCCS) / 2$. |
| S | Single-ended voltage-referenced I/O Standard |  <p>The JEDEC standard for SSTI and HSTL I/O standards defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform <i>ringing</i>.</p> |
| | SW (Sampling Window) | High-speed I/O block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window. |

Table 1-46. Glossary (Part 5 of 5)

| Letter | Term | Definitions |
|----------|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| V | $V_{CM(DC)}$ | DC common mode input voltage. |
| | $V_{DIF(AC)}$ | AC differential input voltage: The minimum AC input differential voltage required for switching. |
| | $V_{DIF(DC)}$ | DC differential input voltage: The minimum DC input differential voltage required for switching. |
| | V_{ICM} | Input common mode voltage: The common mode of the differential signal at the receiver. |
| | V_{ID} | Input differential voltage swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver. |
| | V_{IH} | Voltage input high: The minimum positive voltage applied to the input that is accepted by the device as a logic high. |
| | $V_{IH(AC)}$ | High-level AC input voltage. |
| | $V_{IH(DC)}$ | High-level DC input voltage. |
| | V_{IL} | Voltage input low: The maximum positive voltage applied to the input that is accepted by the device as a logic low. |
| | $V_{IL(AC)}$ | Low-level AC input voltage. |
| | $V_{IL(DC)}$ | Low-level DC input voltage. |
| | V_{IN} | DC input voltage. |
| | V_{OCM} | Output common mode voltage: The common mode of the differential signal at the transmitter. |
| | V_{OD} | Output differential voltage swing: The difference in voltage between the positive and complementary conductors of a differential transmission at the transmitter. $V_{OD} = V_{OH} - V_{OL}$. |
| | V_{OH} | Voltage output high: The maximum positive voltage from an output that the device considers is accepted as the minimum positive high level. |
| | V_{OL} | Voltage output low: The maximum positive voltage from an output that the device considers is accepted as the maximum positive low level. |
| | V_{OS} | Output offset voltage: $V_{OS} = (V_{OH} + V_{OL}) / 2$. |
| | $V_{OX(AC)}$ | AC differential output cross point voltage: the voltage at which the differential output signals must cross. |
| | V_{REF} | Reference voltage for the SSTL and HSTL I/O standards. |
| | $V_{REF(AC)}$ | AC input reference voltage for the SSTL and HSTL I/O standards. $V_{REF(AC)} = V_{REF(DC)} + \text{noise}$. The peak-to-peak AC noise on V_{REF} must not exceed 2% of $V_{REF(DC)}$. |
| | $V_{REF(DC)}$ | DC input reference voltage for the SSTL and HSTL I/O standards. |
| | $V_{SWING(AC)}$ | AC differential input voltage: AC input differential voltage required for switching. For the SSTL differential I/O standard, refer to Input Waveforms. |
| | $V_{SWING(DC)}$ | DC differential input voltage: DC input differential voltage required for switching. For the SSTL differential I/O standard, refer to Input Waveforms. |
| | V_{TT} | Termination voltage for the SSTL and HSTL I/O standards. |
| | $V_X(AC)$ | AC differential input cross point voltage: The voltage at which the differential input signals must cross. |
| W | — | — |
| X | — | — |
| Y | — | — |
| Z | — | — |

Document Revision History

Table 1–47 lists the revision history for this chapter.

Table 1–47. Document Revision History

| Date | Version | Changes |
|---------------|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| March 2016 | 2.0 | Updated note (5) in Table 1–21 to remove support for the N148 package. |
| October 2014 | 1.9 | Updated maximum value for V_{CCD_PLL} in Table 1–1. Removed extended temperature note in Table 1–3. |
| December 2013 | 1.8 | Updated Table 1–21 by adding Note (15). |
| May 2013 | 1.7 | Updated Table 1–15 by adding Note (4). |
| October 2012 | 1.6 | <ul style="list-style-type: none"> ■ Updated the maximum value for V_I, V_{CCD_PLL}, V_{CCIO}, V_{CC_CLKIN}, V_{CCH_GXB}, and V_{CCA_GXB} in Table 1–1. ■ Updated Table 1–11 and Table 1–22. ■ Updated Table 1–21 to include peak-to-peak differential input voltage for the Cyclone IV GX transceiver input reference clock. ■ Updated Table 1–29 to include the typical $DCLK$ value. ■ Updated the minimum f_{HCLK} value in Table 1–31, Table 1–32, Table 1–33, Table 1–34, and Table 1–35. |
| November 2011 | 1.5 | <ul style="list-style-type: none"> ■ Updated “Maximum Allowed Overshoot or Undershoot Voltage”, “Operating Conditions”, and “PLL Specifications” sections. ■ Updated Table 1–2, Table 1–3, Table 1–4, Table 1–5, Table 1–8, Table 1–9, Table 1–15, Table 1–18, Table 1–19, and Table 1–21. ■ Updated Figure 1–1. |
| December 2010 | 1.4 | <ul style="list-style-type: none"> ■ Updated for the Quartus II software version 10.1 release. ■ Updated Table 1–21 and Table 1–25. ■ Minor text edits. |
| July 2010 | 1.3 | <p>Updated for the Quartus II software version 10.0 release:</p> <ul style="list-style-type: none"> ■ Updated Table 1–3, Table 1–4, Table 1–21, Table 1–25, Table 1–28, Table 1–30, Table 1–40, Table 1–41, Table 1–42, Table 1–43, Table 1–44, and Table 1–45. ■ Updated Figure 1–2 and Figure 1–3. ■ Removed SW Requirement and TCCS for Cyclone IV Devices tables. ■ Minor text edits. |
| March 2010 | 1.2 | <p>Updated to include automotive devices:</p> <ul style="list-style-type: none"> ■ Updated the “Operating Conditions” and “PLL Specifications” sections. ■ Updated Table 1–1, Table 1–8, Table 1–9, Table 1–21, Table 1–26, Table 1–27, Table 1–31, Table 1–32, Table 1–33, Table 1–34, Table 1–35, Table 1–36, Table 1–37, Table 1–38, Table 1–40, Table 1–42, and Table 1–43. ■ Added Table 1–5 to include ESD for Cyclone IV devices GPIOs and HSSI I/Os. ■ Added Table 1–44 and Table 1–45 to include IOE programmable delay for Cyclone IV E 1.2 V core voltage devices. ■ Minor text edits. |

