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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)


Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	3118
Number of Logic Elements/Cells	49888
Total RAM Bits	2562048
Number of I/O	310
Number of Gates	-
Voltage - Supply	1.16V ~ 1.24V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/ep4cgx50df27c6n">https://www.e-xfl.com/product-detail/intel/ep4cgx50df27c6n</a>

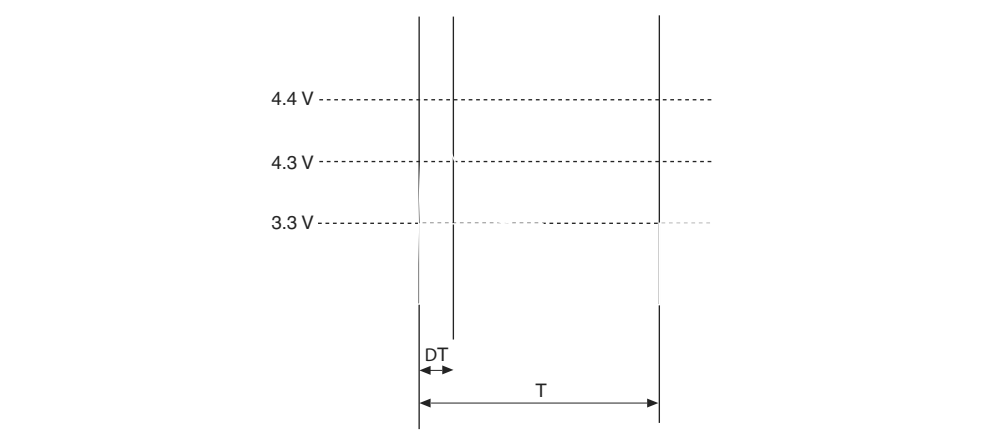
 A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

**Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices**

Symbol	Parameter	Condition (V)	Overshoot Duration as % of High Time	Unit
$V_i$	AC Input Voltage	$V_i = 4.20$	100	%
		$V_i = 4.25$	98	%
		$V_i = 4.30$	65	%
		$V_i = 4.35$	43	%
		$V_i = 4.40$	29	%
		$V_i = 4.45$	20	%
		$V_i = 4.50$	13	%
		$V_i = 4.55$	9	%
		$V_i = 4.60$	6	%

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as  $([\Delta T]/T) \times 100$ . This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

**Figure 1–1. Cyclone IV Devices Overshoot Duration**



## Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone IV devices. Table 1–3 and Table 1–4 list the steady-state voltage and current values expected from Cyclone IV E and Cyclone IV GX devices. All supplies must be strictly monotonic without plateaus.

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1)</sup>, <sup>(2)</sup> (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}^{(3)}$	Supply voltage for internal logic, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply voltage for internal logic, 1.0-V operation	—	0.97	1.0	1.03	V
$V_{CCIO}^{(3), (4)}$	Supply voltage for output buffers, 3.3-V operation	—	3.135	3.3	3.465	V
	Supply voltage for output buffers, 3.0-V operation	—	2.85	3	3.15	V
	Supply voltage for output buffers, 2.5-V operation	—	2.375	2.5	2.625	V
	Supply voltage for output buffers, 1.8-V operation	—	1.71	1.8	1.89	V
	Supply voltage for output buffers, 1.5-V operation	—	1.425	1.5	1.575	V
	Supply voltage for output buffers, 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCA}^{(3)}$	Supply (analog) voltage for PLL regulator	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}^{(3)}$	Supply (digital) voltage for PLL, 1.2-V operation	—	1.15	1.2	1.25	V
	Supply (digital) voltage for PLL, 1.0-V operation	—	0.97	1.0	1.03	V
$V_I$	Input voltage	—	–0.5	—	3.6	V
$V_O$	Output voltage	—	0	—	$V_{CCIO}$	V
$T_J$	Operating junction temperature	For commercial use	0	—	85	°C
		For industrial use	–40	—	100	°C
		For extended temperature	–40	—	125	°C
		For automotive use	–40	—	125	°C
$t_{RAMP}$	Power supply ramp time	Standard power-on reset (POR) <sup>(5)</sup>	50 $\mu$ s	—	50 ms	—
		Fast POR <sup>(6)</sup>	50 $\mu$ s	—	3 ms	—

**Table 1–3. Recommended Operating Conditions for Cyclone IV E Devices <sup>(1), (2)</sup> (Part 2 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{Diode}$	Magnitude of DC current across PCI-clamp diode when enable	—	—	—	10	mA

**Notes to Table 1–3:**

- (1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades.
- (2)  $V_{CCIO}$  for all I/O banks must be powered up during device operation. All  $V_{CCA}$  pins must be powered to 2.5 V (even when PLLs are not used) and must be powered up and powered down at the same time.
- (3)  $V_{CC}$  must rise monotonically.
- (4)  $V_{CCIO}$  powers all input buffers.
- (5) The POR time for Standard POR ranges between 50 and 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) The POR time for Fast POR ranges between 3 and 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.

**Table 1–4. Recommended Operating Conditions for Cyclone IV GX Devices (Part 1 of 2)**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CCINT}$ <sup>(3)</sup>	Core voltage, PCIe hard IP block, and transceiver PCS power supply	—	1.16	1.2	1.24	V
$V_{CCA}$ <sup>(1), (3)</sup>	PLL analog power supply	—	2.375	2.5	2.625	V
$V_{CCD\_PLL}$ <sup>(2)</sup>	PLL digital power supply	—	1.16	1.2	1.24	V
$V_{CCIO}$ <sup>(3), (4)</sup>	I/O banks power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	I/O banks power supply for 3.0-V operation	—	2.85	3	3.15	V
	I/O banks power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	I/O banks power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	I/O banks power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	I/O banks power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CC\_CLKIN}$ <sup>(3), (5), (6)</sup>	Differential clock input pins power supply for 3.3-V operation	—	3.135	3.3	3.465	V
	Differential clock input pins power supply for 3.0-V operation	—	2.85	3	3.15	V
	Differential clock input pins power supply for 2.5-V operation	—	2.375	2.5	2.625	V
	Differential clock input pins power supply for 1.8-V operation	—	1.71	1.8	1.89	V
	Differential clock input pins power supply for 1.5-V operation	—	1.425	1.5	1.575	V
	Differential clock input pins power supply for 1.2-V operation	—	1.14	1.2	1.26	V
$V_{CCH\_GXB}$	Transceiver output buffer power supply	—	2.375	2.5	2.625	V

## DC Characteristics

This section lists the I/O leakage current, pin capacitance, on-chip termination (OCT) tolerance, and bus hold specifications for Cyclone IV devices.

### Supply Current

The device supply current requirement is the minimum current drawn from the power supply pins that can be used as a reference for power size planning. Use the Excel-based early power estimator (EPE) to get the supply current estimates for your design because these currents vary greatly with the resources used. Table 1-6 lists the I/O pin leakage current for Cyclone IV devices.

**Table 1-6. I/O Pin Leakage Current for Cyclone IV Devices <sup>(1), (2)</sup>**

Symbol	Parameter	Conditions	Device	Min	Typ	Max	Unit
$I_I$	Input pin leakage current	$V_I = 0\text{ V to }V_{CCIOMAX}$	—	-10	—	10	$\mu\text{A}$
$I_{OZ}$	Tristated I/O pin leakage current	$V_O = 0\text{ V to }V_{CCIOMAX}$	—	-10	—	10	$\mu\text{A}$

**Notes to Table 1-6:**

- (1) This value is specified for normal device operation. The value varies during device power-up. This applies for all  $V_{CCIO}$  settings (3.3, 3.0, 2.5, 1.8, 1.5, and 1.2 V).
- (2) The 10  $\mu\text{A}$  I/O leakage current limit is applicable when the internal clamping diode is off. A higher current can be observed when the diode is on.

### Bus Hold

The bus hold retains the last valid logic state after the source driving it either enters the high impedance state or is removed. Each I/O pin has an option to enable bus hold in user mode. Bus hold is always disabled in configuration mode.

Table 1-7 lists bus hold specifications for Cyclone IV devices.

**Table 1-7. Bus Hold Parameter for Cyclone IV Devices (Part 1 of 2) <sup>(1)</sup>**

Parameter	Condition	V <sub>CCIO</sub> (V)												Unit
		1.2		1.5		1.8		2.5		3.0		3.3		
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus hold low, sustaining current	V <sub>IN</sub> > V <sub>IL</sub> (maximum)	8	—	12	—	30	—	50	—	70	—	70	—	μA
Bus hold high, sustaining current	V <sub>IN</sub> < V <sub>IL</sub> (minimum)	−8	—	−12	—	−30	—	−50	—	−70	—	−70	—	μA
Bus hold low, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	—	125	—	175	—	200	—	300	—	500	—	500	μA
Bus hold high, overdrive current	0 V < V <sub>IN</sub> < V <sub>CCIO</sub>	—	−125	—	−175	—	−200	—	−300	—	−500	—	−500	μA

The OCT resistance may vary with the variation of temperature and voltage after calibration at device power-up. Use Table 1-10 and Equation 1-1 to determine the final OCT resistance considering the variations after calibration at device power-up. Table 1-10 lists the change percentage of the OCT resistance with voltage and temperature.

**Table 1-10. OCT Variation After Calibration at Device Power-Up for Cyclone IV Devices**

Nominal Voltage	dR/dT (%/°C)	dR/dV (%/mV)
3.0	0.262	-0.026
2.5	0.234	-0.039
1.8	0.219	-0.086
1.5	0.199	-0.136
1.2	0.161	-0.288

**Equation 1-1. Final OCT Resistance (1), (2), (3), (4), (5), (6)**

$$\Delta R_V = (V_2 - V_1) \times 1000 \times dR/dV \text{ — (7)}$$

$$\Delta R_T = (T_2 - T_1) \times dR/dT \text{ — (8)}$$

$$\text{For } \Delta R_x < 0; MF_x = 1 / (|\Delta R_x|/100 + 1) \text{ — (9)}$$

$$\text{For } \Delta R_x > 0; MF_x = \Delta R_x/100 + 1 \text{ — (10)}$$

$$MF = MF_V \times MF_T \text{ — (11)}$$

$$R_{\text{final}} = R_{\text{initial}} \times MF \text{ — (12)}$$

**Notes to Equation 1-1:**

- (1)  $T_2$  is the final temperature.
- (2)  $T_1$  is the initial temperature.
- (3) MF is multiplication factor.
- (4)  $R_{\text{final}}$  is final resistance.
- (5)  $R_{\text{initial}}$  is initial resistance.
- (6) Subscript  $x$  refers to both  $V$  and  $T$ .
- (7)  $\Delta R_V$  is a variation of resistance with voltage.
- (8)  $\Delta R_T$  is a variation of resistance with temperature.
- (9)  $dR/dT$  is the change percentage of resistance with temperature after calibration at device power-up.
- (10)  $dR/dV$  is the change percentage of resistance with voltage after calibration at device power-up.
- (11)  $V_2$  is final voltage.
- (12)  $V_1$  is the initial voltage.

Example 1–1 shows how to calculate the change of 50-Ω I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V.

#### Example 1–1. Impedance Change

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because  $\Delta R_V$  is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because  $\Delta R_T$  is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{\text{final}} = 50 \times 1.114 = 55.71 \, \Omega$$

## Pin Capacitance

Table 1–11 lists the pin capacitance for Cyclone IV devices.

**Table 1–11. Pin Capacitance for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Parameter	Typical – Quad Flat Pack (QFP)	Typical – Quad Flat No Leads (QFN)	Typical – Ball-Grid Array (BGA)	Unit
C <sub>IOTB</sub>	Input capacitance on top and bottom I/O pins	7	7	6	pF
C <sub>IOLR</sub>	Input capacitance on right I/O pins	7	7	5	pF
C <sub>LVDSLR</sub>	Input capacitance on right I/O pins with dedicated LVDS output	8	8	7	pF
C <sub>VREFLR</sub> (2)	Input capacitance on right dual-purpose V <sub>REF</sub> pin when used as V <sub>REF</sub> or user I/O pin	21	21	21	pF
C <sub>VREFTB</sub> (2)	Input capacitance on top and bottom dual-purpose V <sub>REF</sub> pin when used as V <sub>REF</sub> or user I/O pin	23 (3)	23	23	pF
C <sub>CLKTB</sub>	Input capacitance on top and bottom dedicated clock input pins	7	7	6	pF
C <sub>CLKLR</sub>	Input capacitance on right dedicated clock input pins	6	6	5	pF

#### Notes to Table 1–11:

- (1) The pin capacitance applies to FBGA, UBGA, and MBGA packages.
- (2) When you use the V<sub>REF</sub> pin as a regular input or output, you can expect a reduced performance of toggle rate and t<sub>CO</sub> because of higher pin capacitance.
- (3) C<sub>VREFTB</sub> for the EP4CE22 device is 30 pF.

**Table 1-16. Single-Ended SSTL and HSTL I/O Reference Voltage Specifications for Cyclone IV Devices <sup>(1)</sup>**

I/O Standard	V <sub>CCIO</sub> (V)			V <sub>REF</sub> (V)			V <sub>TT</sub> (V) <sup>(2)</sup>		
	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max
SSTL-2 Class I, II	2.375	2.5	2.625	1.19	1.25	1.31	V <sub>REF</sub> - 0.04	V <sub>REF</sub>	V <sub>REF</sub> + 0.04
SSTL-18 Class I, II	1.7	1.8	1.9	0.833	0.9	0.969	V <sub>REF</sub> - 0.04	V <sub>REF</sub>	V <sub>REF</sub> + 0.04
HSTL-18 Class I, II	1.71	1.8	1.89	0.85	0.9	0.95	0.85	0.9	0.95
HSTL-15 Class I, II	1.425	1.5	1.575	0.71	0.75	0.79	0.71	0.75	0.79
HSTL-12 Class I, II	1.14	1.2	1.26	0.48 × V <sub>CCIO</sub> <sup>(3)</sup>	0.5 × V <sub>CCIO</sub> <sup>(3)</sup>	0.52 × V <sub>CCIO</sub> <sup>(3)</sup>	—	0.5 × V <sub>CCIO</sub>	—
				0.47 × V <sub>CCIO</sub> <sup>(4)</sup>	0.5 × V <sub>CCIO</sub> <sup>(4)</sup>	0.53 × V <sub>CCIO</sub> <sup>(4)</sup>			

**Notes to Table 1-16:**

- (1) For an explanation of terms used in Table 1-16, refer to “Glossary” on page 1-37.
- (2) V<sub>TT</sub> of the transmitting device must track V<sub>REF</sub> of the receiving device.
- (3) Value shown refers to DC input reference voltage, V<sub>REF(DC)</sub>.
- (4) Value shown refers to AC input reference voltage, V<sub>REF(AC)</sub>.

**Table 1-17. Single-Ended SSTL and HSTL I/O Standards Signal Specifications for Cyclone IV Devices**

I/O Standard	V <sub>IL(DC)</sub> (V)		V <sub>IH(DC)</sub> (V)		V <sub>IL(AC)</sub> (V)		V <sub>IH(AC)</sub> (V)		V <sub>OL</sub> (V)	V <sub>OH</sub> (V)	I <sub>OL</sub> (mA)	I <sub>OH</sub> (mA)
	Min	Max	Min	Max	Min	Max	Min	Max	Max	Min		
SSTL-2 Class I	—	V <sub>REF</sub> - 0.18	V <sub>REF</sub> + 0.18	—	—	V <sub>REF</sub> - 0.35	V <sub>REF</sub> + 0.35	—	V <sub>TT</sub> - 0.57	V <sub>TT</sub> + 0.57	8.1	-8.1
SSTL-2 Class II	—	V <sub>REF</sub> - 0.18	V <sub>REF</sub> + 0.18	—	—	V <sub>REF</sub> - 0.35	V <sub>REF</sub> + 0.35	—	V <sub>TT</sub> - 0.76	V <sub>TT</sub> + 0.76	16.4	-16.4
SSTL-18 Class I	—	V <sub>REF</sub> - 0.125	V <sub>REF</sub> + 0.125	—	—	V <sub>REF</sub> - 0.25	V <sub>REF</sub> + 0.25	—	V <sub>TT</sub> - 0.475	V <sub>TT</sub> + 0.475	6.7	-6.7
SSTL-18 Class II	—	V <sub>REF</sub> - 0.125	V <sub>REF</sub> + 0.125	—	—	V <sub>REF</sub> - 0.25	V <sub>REF</sub> + 0.25	—	0.28	V <sub>CCIO</sub> - 0.28	13.4	-13.4
HSTL-18 Class I	—	V <sub>REF</sub> - 0.1	V <sub>REF</sub> + 0.1	—	—	V <sub>REF</sub> - 0.2	V <sub>REF</sub> + 0.2	—	0.4	V <sub>CCIO</sub> - 0.4	8	-8
HSTL-18 Class II	—	V <sub>REF</sub> - 0.1	V <sub>REF</sub> + 0.1	—	—	V <sub>REF</sub> - 0.2	V <sub>REF</sub> + 0.2	—	0.4	V <sub>CCIO</sub> - 0.4	16	-16
HSTL-15 Class I	—	V <sub>REF</sub> - 0.1	V <sub>REF</sub> + 0.1	—	—	V <sub>REF</sub> - 0.2	V <sub>REF</sub> + 0.2	—	0.4	V <sub>CCIO</sub> - 0.4	8	-8
HSTL-15 Class II	—	V <sub>REF</sub> - 0.1	V <sub>REF</sub> + 0.1	—	—	V <sub>REF</sub> - 0.2	V <sub>REF</sub> + 0.2	—	0.4	V <sub>CCIO</sub> - 0.4	16	-16
HSTL-12 Class I	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>CCIO</sub> + 0.15	-0.24	V <sub>REF</sub> - 0.15	V <sub>REF</sub> + 0.15	V <sub>CCIO</sub> + 0.24	0.25 × V <sub>CCIO</sub>	0.75 × V <sub>CCIO</sub>	8	-8
HSTL-12 Class II	-0.15	V <sub>REF</sub> - 0.08	V <sub>REF</sub> + 0.08	V <sub>CCIO</sub> + 0.15	-0.24	V <sub>REF</sub> - 0.15	V <sub>REF</sub> + 0.15	V <sub>CCIO</sub> + 0.24	0.25 × V <sub>CCIO</sub>	0.75 × V <sub>CCIO</sub>	14	-14



## Power Consumption

Use the following methods to estimate power for a design:

- the Excel-based EPE
- the Quartus® II PowerPlay power analyzer feature

The interactive Excel-based EPE is used prior to designing the device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, combined with detailed circuit models, can yield very accurate power estimates.



For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

## Switching Characteristics

This section provides performance characteristics of Cyclone IV core and periphery blocks for commercial grade devices.

These characteristics can be designated as Preliminary or Final.

- Preliminary characteristics are created using simulation results, process data, and other known parameters. The upper-right hand corner of these tables show the designation as “Preliminary”.
- Final numbers are based on actual silicon characterization and testing. The numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions. There are no designations on finalized tables.


Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 2 of 4)

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Receiver											
Supported I/O Standards	1.4 V PCML, 1.5 V PCML, 2.5 V PCML, LVPECL, LVDS										
Data rate (F324 and smaller package) <sup>(15)</sup>	—	600	—	2500	600	—	2500	600	—	2500	Mbps
Data rate (F484 and larger package) <sup>(15)</sup>	—	600	—	3125	600	—	3125	600	—	2500	Mbps
Absolute V <sub>MAX</sub> for a receiver pin <sup>(3)</sup>	—	—	—	1.6	—	—	1.6	—	—	1.6	V
Operational V <sub>MAX</sub> for a receiver pin	—	—	—	1.5	—	—	1.5	—	—	1.5	V
Absolute V <sub>MIN</sub> for a receiver pin	—	–0.4	—	—	–0.4	—	—	–0.4	—	—	V
Peak-to-peak differential input voltage V <sub>ID</sub> (diff p-p)	V <sub>ICM</sub> = 0.82 V setting, Data Rate = 600 Mbps to 3.125 Gbps	0.1	—	2.7	0.1	—	2.7	0.1	—	2.7	V
V <sub>ICM</sub>	V <sub>ICM</sub> = 0.82 V setting	—	820 ± 10%	—	—	820 ± 10%	—	—	820 ± 10%	—	mV
Differential on-chip termination resistors	100–Ω setting	—	100	—	—	100	—	—	100	—	Ω
	150–Ω setting	—	150	—	—	150	—	—	150	—	Ω
Differential and common mode return loss	PIPE, Serial Rapid I/O SR, SATA, CPRI LV, SDI, XAUI	Compliant									—
Programmable ppm detector <sup>(4)</sup>	—	± 62.5, 100, 125, 200, 250, 300									ppm
Clock data recovery (CDR) ppm tolerance (without spread-spectrum clocking enabled)	—	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	—	—	±300 <sup>(5)</sup> , ±350 <sup>(6), (7)</sup>	ppm
CDR ppm tolerance (with synchronous spread-spectrum clocking enabled) <sup>(8)</sup>	—	—	—	350 to –5350 <sup>(7), (9)</sup>	—	—	350 to –5350 <sup>(7), (9)</sup>	—	—	350 to –5350 <sup>(7), (9)</sup>	ppm
Run length	—	—	80	—	—	80	—	—	80	—	UI
Programmable equalization	No Equalization	—	—	1.5	—	—	1.5	—	—	1.5	dB
	Medium Low	—	—	4.5	—	—	4.5	—	—	4.5	dB
	Medium High	—	—	5.5	—	—	5.5	—	—	5.5	dB
	High	—	—	7	—	—	7	—	—	7	dB

**Table 1-21. Transceiver Specification for Cyclone IV GX Devices (Part 3 of 4)**

Symbol/ Description	Conditions	C6			C7, I7			C8			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
Signal detect/loss threshold	PIPE mode	65	—	175	65	—	175	65	—	175	mV
$t_{LTR}$ <sup>(10)</sup>	—	—	—	75	—	—	75	—	—	75	μs
$t_{LTR-LTD\_Manual}$ <sup>(11)</sup>	—	15	—	—	15	—	—	15	—	—	μs
$t_{LTD}$ <sup>(12)</sup>	—	0	100	4000	0	100	4000	0	100	4000	ns
$t_{LTD\_Manual}$ <sup>(13)</sup>	—	—	—	4000	—	—	4000	—	—	4000	ns
$t_{LTD\_Auto}$ <sup>(14)</sup>	—	—	—	4000	—	—	4000	—	—	4000	ns
Receiver buffer and CDR offset cancellation time (per channel)	—	—	—	17000	—	—	17000	—	—	17000	recon fig_c lk cycles
Programmable DC gain	DC Gain Setting = 0	—	0	—	—	0	—	—	0	—	dB
	DC Gain Setting = 1	—	3	—	—	3	—	—	3	—	dB
	DC Gain Setting = 2	—	6	—	—	6	—	—	6	—	dB
<b>Transmitter</b>											
Supported I/O Standards	1.5 V PCML										
Data rate (F324 and smaller package)	—	600	—	2500	600	—	2500	600	—	2500	Mbps
Data rate (F484 and larger package)	—	600	—	3125	600	—	3125	600	—	2500	Mbps
$V_{OCM}$	0.65 V setting	—	650	—	—	650	—	—	650	—	mV
Differential on-chip termination resistors	100-Ω setting	—	100	—	—	100	—	—	100	—	Ω
	150-Ω setting	—	150	—	—	150	—	—	150	—	Ω
Differential and common mode return loss	PIPE, CPRI LV, Serial Rapid I/O SR, SDI, XAUI, SATA	Compliant									—
Rise time	—	50	—	200	50	—	200	50	—	200	ps
Fall time	—	50	—	200	50	—	200	50	—	200	ps
Intra-differential pair skew	—	—	—	15	—	—	15	—	—	15	ps
Intra-transceiver block skew	—	—	—	120	—	—	120	—	—	120	ps

Figure 1-2 shows the lock time parameters in manual mode.

 LTD = lock-to-data. LTR = lock-to-reference.

**Figure 1-2. Lock Time Parameters for Manual Mode**

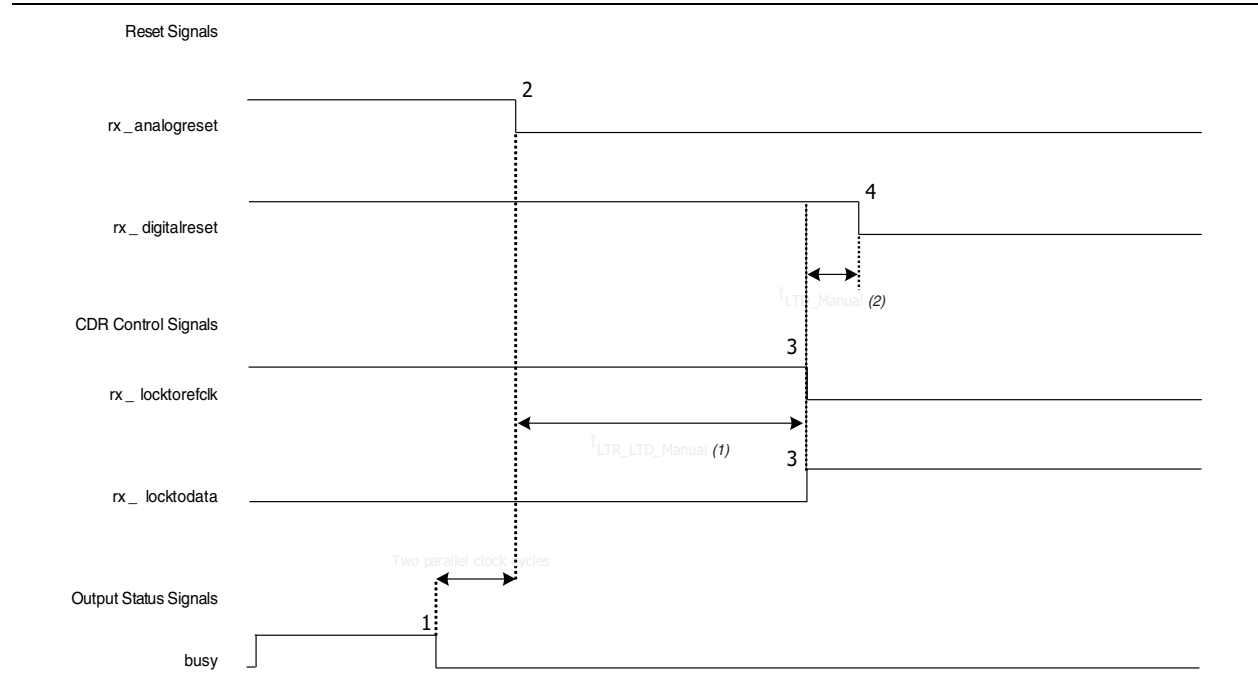


Figure 1-3 shows the lock time parameters in automatic mode.

**Figure 1-3. Lock Time Parameters for Automatic Mode**

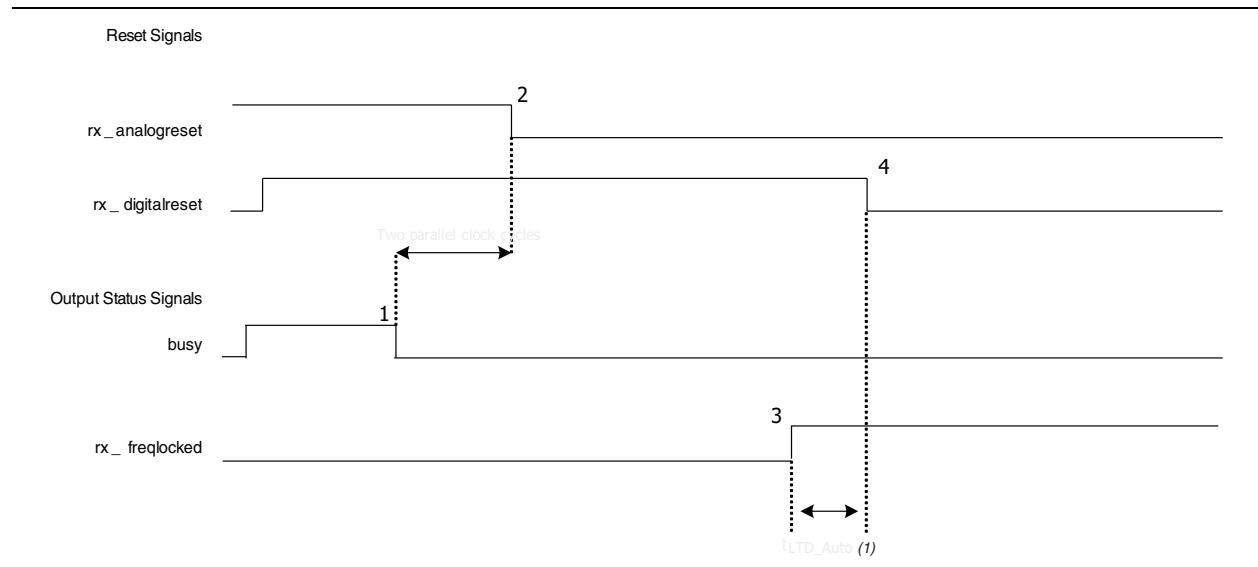


Figure 1-4 shows the differential receiver input waveform.

**Figure 1-4. Receiver Input Waveform**

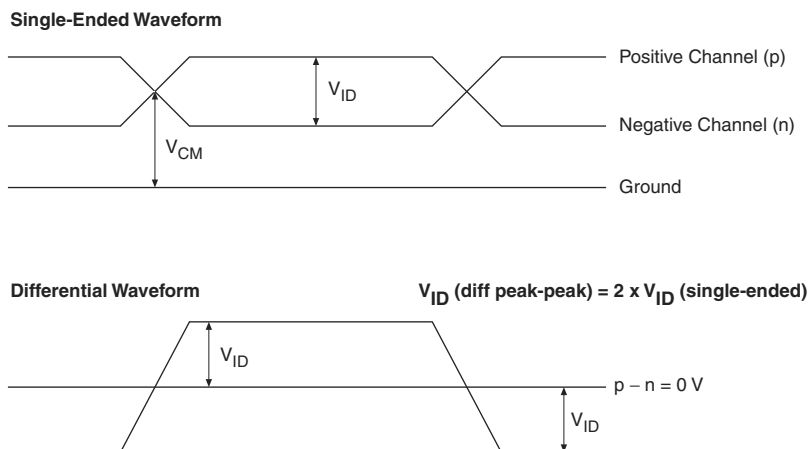


Figure 1-5 shows the transmitter output waveform.

**Figure 1-5. Transmitter Output Waveform**

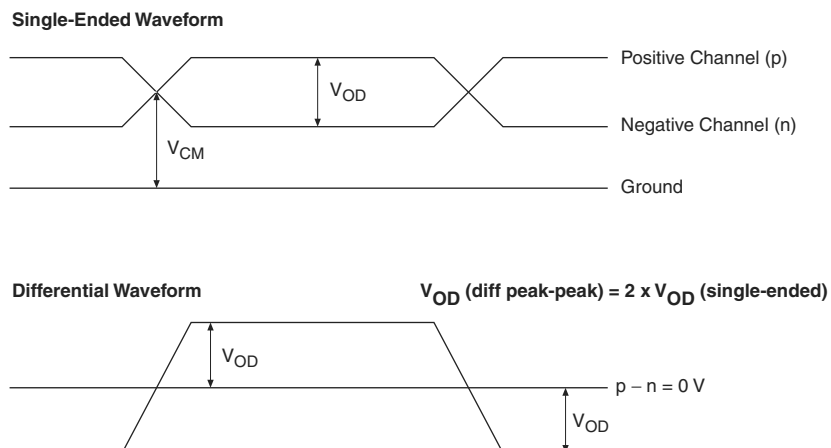


Table 1-22 lists the typical  $V_{OD}$  for Tx term that equals 100  $\Omega$ .

**Table 1-22. Typical  $V_{OD}$  Setting, Tx Term = 100  $\Omega$**

Symbol	$V_{OD}$ Setting (mV)					
	1	2	3	4 (1)	5	6
$V_{OD}$ differential peak to peak typical (mV)	400	600	800	900	1000	1200

**Note to Table 1-22:**

(1) This setting is required for compliance with the PCIe protocol.

**Table 1–24. Clock Tree Performance for Cyclone IV Devices (Part 2 of 2)**

Device	Performance								Unit
	C6	C7	C8	C8L <sup>(1)</sup>	C9L <sup>(1)</sup>	I7	I8L <sup>(1)</sup>	A7	
EP4CE55	500	437.5	402	362	265	437.5	362	—	MHz
EP4CE75	500	437.5	402	362	265	437.5	362	—	MHz
EP4CE115	—	437.5	402	362	265	437.5	362	—	MHz
EP4CGX15	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX22	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX30	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX50	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX75	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX110	500	437.5	402	—	—	437.5	—	—	MHz
EP4CGX150	500	437.5	402	—	—	437.5	—	—	MHz

**Note to Table 1–24:**


(1) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades.


## PLL Specifications

Table 1–25 lists the PLL specifications for Cyclone IV devices when operating in the commercial junction temperature range (0°C to 85°C), the industrial junction temperature range (–40°C to 100°C), the extended industrial junction temperature range (–40°C to 125°C), and the automotive junction temperature range (–40°C to 125°C). For more information about the PLL block, refer to “Glossary” on page 1–37.

**Table 1–25. PLL Specifications for Cyclone IV Devices <sup>(1), (2)</sup> (Part 1 of 2)**

Symbol	Parameter	Min	Typ	Max	Unit
$f_{IN}$ <sup>(3)</sup>	Input clock frequency (–6, –7, –8 speed grades)	5	—	472.5	MHz
	Input clock frequency (–8L speed grade)	5	—	362	MHz
	Input clock frequency (–9L speed grade)	5	—	265	MHz
$f_{INPFD}$	PFD input frequency	5	—	325	MHz
$f_{VCO}$ <sup>(4)</sup>	PLL internal VCO operating range	600	—	1300	MHz
$f_{INDUTY}$	Input clock duty cycle	40	—	60	%
$t_{INJITTER\_CCJ}$ <sup>(5)</sup>	Input clock cycle-to-cycle jitter $F_{REF} \geq 100$ MHz	—	—	0.15	UI
	$F_{REF} < 100$ MHz	—	—	±750	ps
$f_{OUT\_EXT}$ (external clock output) <sup>(3)</sup>	PLL output frequency	—	—	472.5	MHz
$f_{OUT}$ (to global clock)	PLL output frequency (–6 speed grade)	—	—	472.5	MHz
	PLL output frequency (–7 speed grade)	—	—	450	MHz
	PLL output frequency (–8 speed grade)	—	—	402.5	MHz
	PLL output frequency (–8L speed grade)	—	—	362	MHz
	PLL output frequency (–9L speed grade)	—	—	265	MHz
$t_{OUTDUTY}$	Duty cycle for external clock output (when set to 50%)	45	50	55	%
$t_{LOCK}$	Time required to lock from end of device configuration	—	—	1	ms

 For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interfaces Handbook*.

 Actual achievable frequency depends on design- and system-specific factors. Perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

## High-Speed I/O Specifications

Table 1–31 through Table 1–36 list the high-speed I/O timing for Cyclone IV devices. For definitions of high-speed timing specifications, refer to “Glossary” on page 1–37.

**Table 1–31. RSDS Transmitter Timing Specifications for Cyclone IV Devices <sup>(1)</sup>, <sup>(2)</sup>, <sup>(4)</sup> (Part 1 of 2)**

Symbol	Modes	C6			C7, I7			C8, A7			C8L, I8L			C9L			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$f_{\text{HSCLK}}$ (input clock frequency)	×10	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×8	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×7	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×4	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×2	5	—	180	5	—	155.5	5	—	155.5	5	—	155.5	5	—	132.5	MHz
	×1	5	—	360	5	—	311	5	—	311	5	—	311	5	—	265	MHz
Device operation in Mbps	×10	100	—	360	100	—	311	100	—	311	100	—	311	100	—	265	Mbps
	×8	80	—	360	80	—	311	80	—	311	80	—	311	80	—	265	Mbps
	×7	70	—	360	70	—	311	70	—	311	70	—	311	70	—	265	Mbps
	×4	40	—	360	40	—	311	40	—	311	40	—	311	40	—	265	Mbps
	×2	20	—	360	20	—	311	20	—	311	20	—	311	20	—	265	Mbps
	×1	10	—	360	10	—	311	10	—	311	10	—	311	10	—	265	Mbps
$t_{\text{DUTY}}$	—	45	—	55	45	—	55	45	—	55	45	—	55	45	—	55	%
Transmitter channel-to-channel skew (TCCS)	—	—	—	200	—	—	200	—	—	200	—	—	200	—	—	200	ps
Output jitter (peak to peak)	—	—	—	500	—	—	500	—	—	550	—	—	600	—	—	700	ps
$t_{\text{RISE}}$	20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$	—	500	—	—	500	—	—	500	—	—	500	—	—	500	—	ps
$t_{\text{FALL}}$	20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$	—	500	—	—	500	—	—	500	—	—	500	—	—	500	—	ps

For more information about the supported maximum clock rate, device and pin planning, IP implementation, and device termination, refer to *Section III: System Performance Specifications* of the *External Memory Interface Handbook*.

Table 1–37 lists the memory output clock jitter specifications for Cyclone IV devices.

**Table 1–37. Memory Output Clock Jitter Specifications for Cyclone IV Devices <sup>(1), (2)</sup>**

Parameter	Symbol	Min	Max	Unit
Clock period jitter	$t_{JIT(per)}$	–125	125	ps
Cycle-to-cycle period jitter	$t_{JIT(cc)}$	–200	200	ps
Duty cycle jitter	$t_{JIT(duty)}$	–150	150	ps

**Notes to Table 1–37:**

- (1) Memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
- (2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock (GCLK) network.

## Duty Cycle Distortion Specifications

Table 1–38 lists the worst case duty cycle distortion for Cyclone IV devices.

**Table 1–38. Duty Cycle Distortion on Cyclone IV Devices I/O Pins <sup>(1), (2), (3)</sup>**

Symbol	C6		C7, I7		C8, I8L, A7		C9L		Unit
	Min	Max	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	45	55	%

**Notes to Table 1–38:**

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and IOE driving the dedicated and general purpose I/O pins.
- (2) Cyclone IV devices meet the specified duty cycle distortion at the maximum output toggle rate for each combination of I/O standard and current strength.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

## OCT Calibration Timing Specification

Table 1–39 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone IV devices.

**Table 1–39. Timing Specification for Series OCT with Calibration at Device Power-Up for Cyclone IV Devices <sup>(1)</sup>**

Symbol	Description	Maximum	Units
$t_{OCTCAL}$	Duration of series OCT with calibration at device power-up	20	$\mu$ s

**Note to Table 1–39:**

- (1) OCT calibration takes place after device configuration and before entering user mode.



## IOE Programmable Delay

Table 1–40 and Table 1–41 list the IOE programmable delay for Cyclone IV E 1.0 V core voltage devices.

**Table 1–40. IOE Programmable Delay on Column Pins for Cyclone IV E 1.0 V Core Voltage Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Setting	Min Offset	Max Offset					Unit
				Fast Corner		Slow Corner			
				C8L	I8L	C8L	C9L	I8L	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	2.054	1.924	3.387	4.017	3.411	ns
Input delay from pin to input register	Pad to I/O input register	8	0	2.010	1.875	3.341	4.252	3.367	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.641	0.631	1.111	1.377	1.124	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.971	0.931	1.684	2.298	1.684	ns

**Notes to Table 1–40:**

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

**Table 1–41. IOE Programmable Delay on Row Pins for Cyclone IV E 1.0 V Core Voltage Devices <sup>(1), (2)</sup>**

Parameter	Paths Affected	Number of Setting	Min Offset	Max Offset					Unit
				Fast Corner		Slow Corner			
				C8L	I8L	C8L	C9L	I8L	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	2.057	1.921	3.389	4.146	3.412	ns
Input delay from pin to input register	Pad to I/O input register	8	0	2.059	1.919	3.420	4.374	3.441	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.670	0.623	1.160	1.420	1.168	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.960	0.919	1.656	2.258	1.656	ns

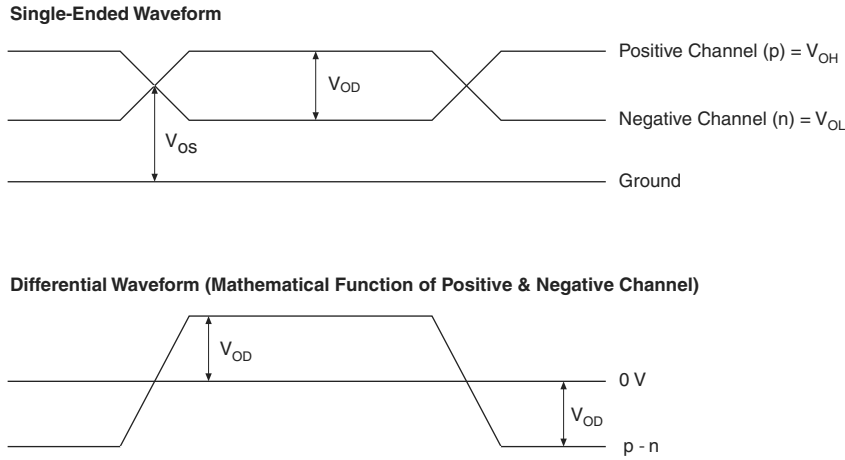
**Notes to Table 1–41:**

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1-46. Glossary (Part 2 of 5)

Letter	Term	Definitions
<b>J</b>	JTAG Waveform	<p>The diagram illustrates the JTAG waveform with the following timing parameters:</p> <ul style="list-style-type: none"> <li><math>t_{JCP}</math>: Time from TCK rising edge to TDI setup.</li> <li><math>t_{JCH}</math>: Time from TCK rising edge to TDI hold.</li> <li><math>t_{JCL}</math>: Time from TCK falling edge to TDI setup.</li> <li><math>t_{JCH}</math>: Time from TCK falling edge to TDI hold.</li> <li><math>t_{JPSU\_TDI}</math>: Setup time for TDI before TCK rising edge.</li> <li><math>t_{JPSU\_TMS}</math>: Setup time for TMS before TCK rising edge.</li> <li><math>t_{JPH}</math>: Hold time for TMS after TCK rising edge.</li> <li><math>t_{JPZX}</math>: Time from TCK rising edge to TDO setup.</li> <li><math>t_{JPCO}</math>: Time from TCK rising edge to TDO output.</li> <li><math>t_{JPXZ}</math>: Time from TCK rising edge to TDO hold.</li> <li><math>t_{JSSU}</math>: Setup time for Signal to be Captured before TCK rising edge.</li> <li><math>t_{JSH}</math>: Hold time for Signal to be Captured after TCK rising edge.</li> <li><math>t_{JSZX}</math>: Time from TCK rising edge to Signal to be Driven setup.</li> <li><math>t_{JSCO}</math>: Time from TCK rising edge to Signal to be Driven output.</li> <li><math>t_{JSXZ}</math>: Time from TCK rising edge to Signal to be Driven hold.</li> </ul>
<b>K</b>	—	—
<b>L</b>	—	—
<b>M</b>	—	—
<b>N</b>	—	—
<b>O</b>	—	—
<b>P</b>	PLL Block	<p>The following highlights the PLL specification parameters:</p> <p>The diagram shows the internal structure of the PLL block, including the following components and signal flow:</p> <ul style="list-style-type: none"> <li><b>Inputs:</b> CLK (Core Clock) and Core Clock.</li> <li><b>Switchover:</b> A block that selects between the CLK and Core Clock inputs.</li> <li><b>Frequency Divider (N):</b> Receives the selected clock signal and outputs <math>f_{IN}</math>.</li> <li><b>Phase-Frequency Detector (PFD):</b> Receives <math>f_{IN}</math> and outputs <math>f_{INPFD}</math>.</li> <li><b>Charge Pump (CP):</b> Receives <math>f_{INPFD}</math> and outputs to the Loop Filter (LF).</li> <li><b>Loop Filter (LF):</b> Receives the output from the CP and outputs to the Voltage-Controlled Oscillator (VCO).</li> <li><b>Voltage-Controlled Oscillator (VCO):</b> Receives the output from the LF and outputs <math>f_{VCO}</math>.</li> <li><b>Phase tap:</b> Receives <math>f_{VCO}</math> and outputs to the M (Modulator) block.</li> <li><b>Modulator (M):</b> Receives the output from the Phase tap and outputs to the Counters (C0..C4).</li> <li><b>Counters (C0..C4):</b> Receives the output from the M block and outputs <math>f_{OUT}</math>.</li> <li><b>Outputs:</b> CLKOUT Pins (outputting <math>f_{OUT\_EXT}</math>) and GCLK (outputting <math>f_{OUT}</math>).</li> </ul> <p><b>Key:</b></p> <ul style="list-style-type: none"> <li>Reconfigurable in User Mode</li> </ul>
<b>Q</b>	—	—

Table 1-46. Glossary (Part 4 of 5)

Letter	Term	Definitions
T	$t_C$	High-speed receiver and transmitter input and output clock period.
	Channel-to-channel-skew (TCCS)	High-speed I/O block: The timing difference between the fastest and slowest output edges, including $t_{CO}$ variation and clock skew. The clock is included in the TCCS measurement.
	$t_{cin}$	Delay from the clock pad to the I/O input register.
	$t_{CO}$	Delay from the clock pad to the I/O output.
	$t_{cout}$	Delay from the clock pad to the I/O output register.
	$t_{DUTY}$	High-speed I/O block: Duty cycle on high-speed transmitter output clock.
	$t_{FALL}$	Signal high-to-low transition time (80–20%).
	$t_H$	Input register hold time.
	Timing Unit Interval (TUI)	High-speed I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(\text{Receiver Input Clock Frequency Multiplication Factor}) = t_C/w$ ).
	$t_{INJITTER}$	Period jitter on the PLL clock input.
	$t_{OUTJITTER\_DEDCLK}$	Period jitter on the dedicated clock output driven by a PLL.
	$t_{OUTJITTER\_IO}$	Period jitter on the general purpose I/O driven by a PLL.
	$t_{pllcin}$	Delay from the PLL inclk pad to the I/O input register.
	$t_{pllcout}$	Delay from the PLL inclk pad to the I/O output register.
	Transmitter Output Waveform	<p>Transmitter output waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards:</p> 
	$t_{RISE}$	Signal low-to-high transition time (20–80%).
	$t_{SU}$	Input register setup time.
U	—	—

## Document Revision History

Table 1-47 lists the revision history for this chapter.

**Table 1-47. Document Revision History**

Date	Version	Changes
March 2016	2.0	Updated note (5) in Table 1-21 to remove support for the N148 package.
October 2014	1.9	Updated maximum value for $V_{CCD\_PLL}$ in Table 1-1. Removed extended temperature note in Table 1-3.
December 2013	1.8	Updated Table 1-21 by adding Note (15).
May 2013	1.7	Updated Table 1-15 by adding Note (4).
October 2012	1.6	<ul style="list-style-type: none"> <li>■ Updated the maximum value for <math>V_I</math>, <math>V_{CCD\_PLL}</math>, <math>V_{CCIO}</math>, <math>V_{CC\_CLKIN}</math>, <math>V_{CCH\_GXB}</math>, and <math>V_{CCA\_GXB}</math> in Table 1-1.</li> <li>■ Updated Table 1-11 and Table 1-22.</li> <li>■ Updated Table 1-21 to include peak-to-peak differential input voltage for the Cyclone IV GX transceiver input reference clock.</li> <li>■ Updated Table 1-29 to include the typical <math>DCLK</math> value.</li> <li>■ Updated the minimum <math>f_{HCLK}</math> value in Table 1-31, Table 1-32, Table 1-33, Table 1-34, and Table 1-35.</li> </ul>
November 2011	1.5	<ul style="list-style-type: none"> <li>■ Updated “Maximum Allowed Overshoot or Undershoot Voltage”, “Operating Conditions”, and “PLL Specifications” sections.</li> <li>■ Updated Table 1-2, Table 1-3, Table 1-4, Table 1-5, Table 1-8, Table 1-9, Table 1-15, Table 1-18, Table 1-19, and Table 1-21.</li> <li>■ Updated Figure 1-1.</li> </ul>
December 2010	1.4	<ul style="list-style-type: none"> <li>■ Updated for the Quartus II software version 10.1 release.</li> <li>■ Updated Table 1-21 and Table 1-25.</li> <li>■ Minor text edits.</li> </ul>
July 2010	1.3	<p>Updated for the Quartus II software version 10.0 release:</p> <ul style="list-style-type: none"> <li>■ Updated Table 1-3, Table 1-4, Table 1-21, Table 1-25, Table 1-28, Table 1-30, Table 1-40, Table 1-41, Table 1-42, Table 1-43, Table 1-44, and Table 1-45.</li> <li>■ Updated Figure 1-2 and Figure 1-3.</li> <li>■ Removed SW Requirement and TCCS for Cyclone IV Devices tables.</li> <li>■ Minor text edits.</li> </ul>
March 2010	1.2	<p>Updated to include automotive devices:</p> <ul style="list-style-type: none"> <li>■ Updated the “Operating Conditions” and “PLL Specifications” sections.</li> <li>■ Updated Table 1-1, Table 1-8, Table 1-9, Table 1-21, Table 1-26, Table 1-27, Table 1-31, Table 1-32, Table 1-33, Table 1-34, Table 1-35, Table 1-36, Table 1-37, Table 1-38, Table 1-40, Table 1-42, and Table 1-43.</li> <li>■ Added Table 1-5 to include ESD for Cyclone IV devices GPIOs and HSSI I/Os.</li> <li>■ Added Table 1-44 and Table 1-45 to include IOE programmable delay for Cyclone IV E 1.2 V core voltage devices.</li> <li>■ Minor text edits.</li> </ul>

**Table 1–47. Document Revision History**

Date	Version	Changes
February 2010	1.1	<ul style="list-style-type: none"><li>■ Updated Table 1–3 through Table 1–44 to include information for Cyclone IV E devices and Cyclone IV GX devices for Quartus II software version 9.1 SP1 release.</li><li>■ Minor text edits.</li></ul>
November 2009	1.0	Initial release.