

Welcome to **E-XFL.COM**

Understanding <u>Embedded - FPGAs (Field Programmable Gate Array)</u>

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details	
Product Status	Active
Number of LABs/CLBs	3118
Number of Logic Elements/Cells	49888
Total RAM Bits	2562048
Number of I/O	310
Number of Gates	-
Voltage - Supply	1.16V ~ 1.24V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/ep4cgx50df27c8

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



Cyclone IV E industrial devices I7 are offered with extended operating temperature range.

Absolute Maximum Ratings

Absolute maximum ratings define the maximum operating conditions for Cyclone IV devices. The values are based on experiments conducted with the device and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied at these conditions. Table 1–1 lists the absolute maximum ratings for Cyclone IV devices.



Conditions beyond those listed in Table 1–1 cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time have adverse effects on the device.

Table 1–1. Absolute Maximum Ratings for Cyclone IV Devices (1)

Symbol	Parameter	Min	Max	Unit
V _{CCINT}	Core voltage, PCI Express® (PCIe®) hard IP block, and transceiver physical coding sublayer (PCS) power supply	-0.5	1.8	V
V _{CCA}	Phase-locked loop (PLL) analog power supply	-0.5	3.75	V
V _{CCD_PLL}	PLL digital power supply	-0.5	1.8	V
V _{CCIO}	I/O banks power supply	-0.5	3.75	V
V _{CC_CLKIN}	Differential clock input pins power supply	-0.5	4.5	V
V _{CCH_GXB}	Transceiver output buffer power supply	-0.5	3.75	V
V _{CCA_GXB}	Transceiver physical medium attachment (PMA) and auxiliary power supply	-0.5	3.75	V
V _{CCL_GXB}	Transceiver PMA and auxiliary power supply	-0.5	1.8	V
VI	DC input voltage	-0.5	4.2	V
I _{OUT}	DC output current, per pin	-25	40	mA
T _{STG}	Storage temperature	-65	150	°C
T _J	Operating junction temperature	-40	125	°C

Note to Table 1-1:

Maximum Allowed Overshoot or Undershoot Voltage

During transitions, input signals may overshoot to the voltage shown in Table 1–2 and undershoot to -2.0 V for a magnitude of currents less than 100 mA and for periods shorter than 20 ns. Table 1-2 lists the maximum allowed input overshoot voltage and the duration of the overshoot voltage as a percentage over the lifetime of the device. The maximum allowed overshoot duration is specified as a percentage of high-time over the lifetime of the device.

⁽¹⁾ Supply voltage specifications apply to voltage readings taken at the device pins with respect to ground, not at the power supply.



A DC signal is equivalent to 100% duty cycle. For example, a signal that overshoots to 4.3 V can only be at 4.3 V for 65% over the lifetime of the device; for a device lifetime of 10 years, this amounts to 65/10ths of a year.

Table 1–2. Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame for Cyclone IV Devices

Symbol	Parameter	Condition (V)	Overshoot Duration as % of High Time	Unit
		V _I = 4.20	100	%
		V _I = 4.25	98	%
		V _I = 4.30	65	%
		V _I = 4.35	43	%
V _i	AC Input Voltage	V _I = 4.40	29	%
	l	V _I = 4.45	20	%
		V _I = 4.50	13	%
		V _I = 4.55	9	%
		V _I = 4.60	6	%

Figure 1–1 shows the methodology to determine the overshoot duration. The overshoot voltage is shown in red and is present on the input pin of the Cyclone IV device at over 4.3 V but below 4.4 V. From Table 1–2, for an overshoot of 4.3 V, the percentage of high time for the overshoot can be as high as 65% over a 10-year period. Percentage of high time is calculated as ([delta T]/T) \times 100. This 10-year period assumes that the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

Figure 1-1. Cyclone IV Devices Overshoot Duration

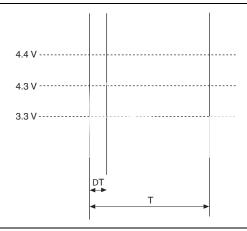


Table 1–7. Bus Hold Parameter for Cyclone IV Devices (Part 2 of 2) (1)

Parameter	Condition		V _{CCIO} (V)											
		1.2		1	.5	1.8		2.5		3.0		3.3		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
Bus hold trip point	_	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2	0.8	2	V

Note to Table 1-7:

(1) Bus hold trip points are based on the calculated input voltages from the JEDEC standard.

OCT Specifications

Table 1–8 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

Table 1-8. Series OCT Without Calibration Specifications for Cyclone IV Devices

		Resistance	Tolerance	
Description	V _{CCIO} (V)	Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	Unit
	3.0	±30	±40	%
0 · 00 T ···	2.5	±30	±40	%
Series OCT without calibration	1.8	±40	±50	%
- Cambration	1.5	±50	±50	%
	1.2	±50	±50	%

OCT calibration is automatically performed at device power-up for OCT-enabled I/Os.

Table 1–9 lists the OCT calibration accuracy at device power-up.

Table 1–9. Series OCT with Calibration at Device Power-Up Specifications for Cyclone IV Devices

		Calibration	n Accuracy	
Description	V _{CCIO} (V)	Commercial Maximum	Industrial, Extended industrial, and Automotive Maximum	Unit
	3.0	±10	±10	%
Series OCT with	2.5	±10	±10	%
calibration at device	1.8	±10	±10	%
power-up	1.5	±10	±10	%
	1.2	±10	±10	%

Operating Conditions

Example 1–1 shows how to calculate the change of 50- Ω I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V.

Example 1-1. Impedance Change

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because ΔR_V is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because ΔR_T is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{final} = 50 \times 1.114 = 55.71 \Omega$$

Pin Capacitance

Table 1–11 lists the pin capacitance for Cyclone IV devices.

Table 1–11. Pin Capacitance for Cyclone IV Devices (1)

Symbol	Parameter	Typical – Quad Flat Pack (QFP)	Typical – Quad Flat No Leads (QFN)	Typical – Ball-Grid Array (BGA)	Unit
C _{IOTB}	Input capacitance on top and bottom I/O pins	7	7	6	pF
C _{IOLR}	Input capacitance on right I/O pins	7	7	5	pF
C _{LVDSLR}	Input capacitance on right I/O pins with dedicated LVDS output	8	8	7	pF
C _{VREFLR} (2)	Input capacitance on right dual-purpose $\ensuremath{\mathtt{VREF}}$ pin when used as V_{REF} or user I/O pin	21	21	21	pF
C _{VREFTB} (2)	Input capacitance on top and bottom dual-purpose ${\tt VREF}$ pin when used as $V_{{\tt REF}}$ or user I/O pin	23 (3)	23	23	pF
C _{CLKTB}	Input capacitance on top and bottom dedicated clock input pins	7	7	6	pF
C _{CLKLR}	Input capacitance on right dedicated clock input pins	6	6	5	pF

Notes to Table 1-11:

- (1) The pin capacitance applies to FBGA, UBGA, and MBGA packages.
- (2) When you use the VREF pin as a regular input or output, you can expect a reduced performance of toggle rate and t_{CO} because of higher pin capacitance.
- (3) C_{VREFTB} for the EP4CE22 device is 30 pF.

Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 1-12 lists the weak pull-up and pull-down resistor values for Cyclone IV devices.

Table 1–12. Internal Weak Pull-Up and Weak Pull-Down Resistor Values for Cyclone IV Devices (1)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
		$V_{CCIO} = 3.3 \text{ V} \pm 5\%$ (2), (3)	7	25	41	kΩ
	Value of the I/O pin pull-up resistor	$V_{CCIO} = 3.0 \text{ V} \pm 5\%$ (2), (3)	7	28	47	kΩ
D	before and during configuration, as	$V_{CCIO} = 2.5 \text{ V} \pm 5\%$ (2), (3)	8	35	61	kΩ
R_ _{PU}	well as user mode if you enable the	$V_{CCIO} = 1.8 \text{ V} \pm 5\%$ (2), (3)	10	57	108	kΩ
	programmable pull-up resistor option	$V_{CCIO} = 1.5 \text{ V} \pm 5\%$ (2), (3)	13	82	163	kΩ
		$V_{CCIO} = 1.2 \text{ V} \pm 5\%$ (2), (3)	19	143	351	kΩ
		$V_{CCIO} = 3.3 \text{ V} \pm 5\%$ (4)	6	19	30	kΩ
	Value of the 1/O air well decreased as	$V_{CCIO} = 3.0 \text{ V} \pm 5\%$ (4)	6	22	36	kΩ
R_PD	Value of the I/O pin pull-down resistor before and during configuration	$V_{CCIO} = 2.5 \text{ V} \pm 5\%$ (4)	6	25	43	kΩ
	bololo and during bollingulation	$V_{CCIO} = 1.8 \text{ V} \pm 5\%$ (4)	7	35	71	kΩ
		$V_{CCIO} = 1.5 \text{ V} \pm 5\%$ (4)	8	50	112	kΩ

Notes to Table 1-12:

- (1) All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- (2) Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO}.
- (3) $R_{PU} = (V_{CC10} V_1)/I_{R_PU}$ Minimum condition: $-40^{\circ}C$; $V_{CC10} = V_{CC} + 5\%$, $V_1 = V_{CC} + 5\% 50$ mV; Typical condition: $25^{\circ}C$; $V_{CC10} = V_{CC}$, $V_1 = 0$ V; $V_2 = 0$ V; $V_3 = 0$ V; $V_4 = 0$ V and $V_5 = 0$ V and $V_6 = 0$ V and $V_7 = 0$ V and $V_8 = 0$ V and $V_$

Maximum condition: 100°C ; $V_{\text{CCIO}} = V_{\text{CC}} - 5\%$, $V_{\text{I}} = 0$ V; in which V_{I} refers to the input voltage at the I/O pin.

(4) $R_{PD} = V_I/I_{RPD}$

Minimum condition: -40°C; $V_{CCIO} = V_{CC} + 5\%$, $V_I = 50$ mV;

Typical condition: 25°C; $V_{CCIO} = V_{CC}$, $V_1 = V_{CC} - 5\%$; Maximum condition: 100°C; $V_{CCIO} = V_{CC} - 5\%$, $V_1 = V_{CC} - 5\%$; in which V_1 refers to the input voltage at the I/O pin.

Hot-Socketing

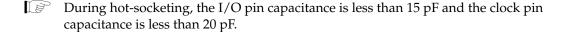
Table 1–13 lists the hot-socketing specifications for Cyclone IV devices.

Table 1–13. Hot-Socketing Specifications for Cyclone IV Devices

Symbol	Parameter	Maximum
I _{IOPIN(DC)}	DC current per I/O pin	300 μΑ
I _{IOPIN(AC)}	AC current per I/O pin	8 mA (1)
I _{XCVRTX(DC)}	DC current per transceiver TX pin	100 mA
I _{XCVRRX(DC)}	DC current per transceiver RX pin	50 mA

Note to Table 1-13:

(1) The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, $|IIOPIN| = C \frac{dv}{dt}$, in which C is the I/O pin capacitance and dv/dt is the slew rate.



Schmitt Trigger Input

Cyclone IV devices support Schmitt trigger input on the TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with slow edge rate. Table 1–14 lists the hysteresis specifications across the supported $V_{\rm CCIO}$ range for Schmitt trigger inputs in Cyclone IV devices.

Table 1–14. Hysteresis Specifications for Schmitt Trigger Input in Cyclone IV Devices

Symbol	Parameter	Conditions (V)	Minimum	Unit	
V _{SCHМІТТ}		$V_{CCIO} = 3.3$	200	mV	
	Hysteresis for Schmitt trigger	Hysteresis for Schmitt trigger	V _{CCIO} = 2.5	200	mV
	input	V _{CCIO} = 1.8	140	mV	
		V _{CCIO} = 1.5	110	mV	

I/O Standard Specifications

The following tables list input voltage sensitivities (V_{IH} and V_{IL}), output voltage (V_{OH} and V_{OL}), and current drive characteristics (I_{OH} and I_{OL}), for various I/O standards supported by Cyclone IV devices. Table 1–15 through Table 1–20 provide the I/O standard specifications for Cyclone IV devices.

Table 1–15. Single-Ended I/O Standard Specifications for Cyclone IV Devices (1), (2)

I/O Ctondovd	V _{CCIO} (V)			V	V _{IL} (V)		/ _{IH} (V)	V _{OL} (V)	V _{OH} (V)	I _{OL}	I _{OH}
I/O Standard	Min	Тур	Max	Min	Max	Min	Max	Max	Min	(mA) <i>(4)</i>	(mA) (4)
3.3-V LVTTL (3)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.45	2.4	4	-4
3.3-V LVCMOS (3)	3.135	3.3	3.465	_	0.8	1.7	3.6	0.2	V _{CCIO} - 0.2	2	-2
3.0-V LVTTL (3)	2.85	3.0	3.15	-0.3	0.8	1.7	V _{CCIO} + 0.3	0.45	2.4	4	-4
3.0-V LVCMOS (3)	2.85	3.0	3.15	-0.3	0.8	1.7	V _{CCIO} + 0.3	0.2	V _{CCIO} - 0.2	0.1	-0.1
2.5 V ⁽³⁾	2.375	2.5	2.625	-0.3	0.7	1.7	V _{CCIO} + 0.3	0.4	2.0	1	-1
1.8 V	1.71	1.8	1.89	-0.3	0.35 x V _{CCIO}	0.65 x V _{CCIO}	2.25	0.45	V _{CCIO} – 0.45	2	-2
1.5 V	1.425	1.5	1.575	-0.3	0.35 x V _{CCIO}	0.65 x V _{CCIO}	V _{CCIO} + 0.3	0.25 x V _{CCIO}	0.75 x V _{CCIO}	2	-2
1.2 V	1.14	1.2	1.26	-0.3	0.35 x V _{CCIO}	0.65 x V _{CCIO}	V _{CCIO} + 0.3	0.25 x V _{CCIO}	0.75 x V _{CCIO}	2	-2
3.0-V PCI	2.85	3.0	3.15	_	0.3 x V _{CCIO}	0.5 x V _{CCIO}	V _{CCIO} + 0.3	0.1 x V _{CCIO}	0.9 x V _{CCIO}	1.5	-0.5
3.0-V PCI-X	2.85	3.0	3.15	_	0.35 x V _{CCIO}	0.5 x V _{CCIO}	V _{CCIO} + 0.3	0.1 x V _{CCIO}	0.9 x V _{CCIO}	1.5	-0.5

Notes to Table 1-15:

- (1) For voltage-referenced receiver input waveform and explanation of terms used in Table 1-15, refer to "Glossary" on page 1-37.
- (2) AC load CL = 10 pF
- (3) For more information about interfacing Cyclone IV devices with 3.3/3.0/2.5-V LVTTL/LVCMOS I/O standards, refer to AN 447: Interfacing Cyclone III and Cyclone IV Devices with 3.3/3.0/2.5-V LVTTL/LVCMOS I/O Systems.
- (4) To meet the loL and loH specifications, you must set the current strength settings accordingly. For example, to meet the 3.3-V LVTTL specification (4 mA), set the current strength settings to 4 mA or higher. Setting at lower current strength may not meet the loL and loH specifications in the handbook.

For more information about receiver input and transmitter output waveforms, and for other differential I/O standards, refer to the I/O Features in Cyclone IV Devices chapter.

Table 1–18. Differential SSTL I/O Standard Specifications for Cyclone IV Devices (1)

V _{CCIO} (V)		V _{Swing}	_{J(DC)} (V)	V _{x(} ,	V _{X(AC)} (V)			ng(AC) /)	V _{OX(AC)} (V)				
	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Max	Min	Тур	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.36	V _{CCIO}	V _{CCIO} /2 - 0.2	_	V _{CCIO} /2 + 0.2	0.7	V _{CCI}	V _{CCIO} /2 - 0.125	_	V _{CCIO} /2 + 0.125
SSTL-18 Class I, II	1.7	1.8	1.90	0.25	V _{CCIO}	V _{CCIO} /2 - 0.175	_	V _{CCIO} /2 + 0.175	0.5	V _{CCI}	V _{CCIO} /2 - 0.125	_	V _{CCIO} /2 + 0.125

Note to Table 1-18:

Table 1–19. Differential HSTL I/O Standard Specifications for Cyclone IV Devices (1)

	V	_{CCIO} (V)	V _{DIF(DC)} (V)		V _x		V _{CM(DC)} (V)				_{F(AC)} (V)	
I/O Standard	Min	Тур	Max	Min	Max	Min	Тур	Max	Min	Тур	Max	Mi n	Max
HSTL-18 Class I, II	1.71	1.8	1.89	0.2	_	0.85		0.95	0.85	_	0.95	0.4	_
HSTL-15 Class I, II	1.425	1.5	1.575	0.2	_	0.71		0.79	0.71	_	0.79	0.4	_
HSTL-12 Class I, II	1.14	1.2	1.26	0.16	V _{CCIO}	0.48 x V _{CCIO}		0.52 x V _{CCIO}	0.48 x V _{CCIO}		0.52 x V _{CCIO}	0.3	0.48 x V _{CCIO}

Note to Table 1-19:

Table 1–20. Differential I/O Standard Specifications for Cyclone IV Devices (1) (Part 1 of 2)

I/O Standard		V _{CCIO} (V)		V _{ID}	(mV)		V _{ICM} (V) ⁽²⁾		Vo	_D (mV)	(3)	V _{0S} (V) ⁽³⁾			
i/O Stanuaru	Min	Тур	Max	Min	Max	Min	Condition	Max	Min	Тур	Max	Min	Тур	Max	
L) (DEOL						0.05	$D_{MAX} \leq 500 \; Mbps$	1.80							
LVPECL (Row I/Os)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{l} 500 \; \text{Mbps} \leq D_{\text{MAX}} \\ \leq 700 \; \text{Mbps} \end{array}$	1.80			_	_	_	_	
						1.05	D _{MAX} > 700 Mbps	1.55							
IV/DEOL						0.05	$D_{MAX} \leq 500 \text{ Mbps}$	1.80							
LVPECL (Column I/Os) (6)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{l} 500 \; \text{Mbps} \leq D_{\text{MAX}} \\ \leq 700 \; \text{Mbps} \end{array}$	1.80	_	_	_	_	_	_	
1,00)						1.05	D _{MAX} > 700 Mbps	1.55							
						0.05	$D_{MAX} \leq 500 \; Mbps$	1.80							
LVDS (Row I/Os)	2.375	2.5	2.625	100	_	0.55	$\begin{array}{l} 500 \; \text{Mbps} \leq D_{\text{MAX}} \\ \leq \; 700 \; \text{Mbps} \end{array}$	1.80	247	_	600	1.125	1.25	1.375	
						1.05	D _{MAX} > 700 Mbps	1.55							

⁽¹⁾ Differential SSTL requires a V_{REF} input.

⁽¹⁾ Differential HSTL requires a V_{REF} input.

Power Consumption

Use the following methods to estimate power for a design:

- the Excel-based EPE
- the Quartus® II PowerPlay power analyzer feature

The interactive Excel-based EPE is used prior to designing the device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, combined with detailed circuit models, can yield very accurate power estimates.

For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

Switching Characteristics

This section provides performance characteristics of Cyclone IV core and periphery blocks for commercial grade devices.

These characteristics can be designated as Preliminary or Final.

- Preliminary characteristics are created using simulation results, process data, and other known parameters. The upper-right hand corner of these tables show the designation as "Preliminary".
- Final numbers are based on actual silicon characterization and testing. The numbers reflect the actual performance of the device under worst-case silicon process, voltage, and junction temperature conditions. There are no designations on finalized tables.

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 2 of 4)

Symbol/	Oanditions		C6			C7, I7			C8		11!4
Description	Conditions	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
Receiver			•				•			<u> </u>	
Supported I/O Standards	1.4 V PCML, 1.5 V PCML, 2.5 V PCML, LVPECL, LVDS										
Data rate (F324 and smaller package) (15)	_	600	_	2500	600	_	2500	600	_	2500	Mbps
Data rate (F484 and larger package) (15)	_	600	_	3125	600	_	3125	600	_	2500	Mbps
Absolute V _{MAX} for a receiver pin (3)	_	_	_	1.6	_	_	1.6	_	_	1.6	V
Operational V _{MAX} for a receiver pin	_	_	_	1.5	_	_	1.5	_	_	1.5	V
Absolute V _{MIN} for a receiver pin	_	-0.4	_	_	-0.4	_	_	-0.4	_	_	V
Peak-to-peak differential input voltage V _{ID} (diff p-p)	V _{ICM} = 0.82 V setting, Data Rate = 600 Mbps to 3.125 Gbps	0.1	_	2.7	0.1	_	2.7	0.1	_	2.7	V
V _{ICM}	V _{ICM} = 0.82 V setting	_	820 ± 10%	_	_	820 ± 10%	_	_	820 ± 10%	_	mV
Differential on-chip	100–Ω setting	_	100	_	_	100	_	_	100	_	Ω
termination resistors	150– Ω setting	_	150	_	_	150	_	_	150	_	Ω
Differential and common mode return loss	PIPE, Serial Rapid I/O SR, SATA, CPRI LV, SDI, XAUI					Compliant	i				_
Programmable ppm detector ⁽⁴⁾	_				± 62.5	, 100, 125 250, 300	5, 200,				ppm
Clock data recovery (CDR) ppm tolerance (without spread-spectrum clocking enabled)	_		_	±300 (5), ±350 (6), (7)		_	±300 (5), ±350 (6), (7)	_	_	±300 (5), ±350 (6), (7)	ppm
CDR ppm tolerance (with synchronous spread-spectrum clocking enabled) (8)	_	_	_	350 to -5350 (7), (9)	_	_	350 to -5350 (7), (9)	_	_	350 to -5350 (7), (9)	ppm
Run length	_		80	_	_	80	_		80		UI
	No Equalization	_	_	1.5	_	_	1.5	_	_	1.5	dB
Programmable	Medium Low	_	_	4.5	_	_	4.5		_	4.5	dB
equalization	Medium High	_	_	5.5	_	_	5.5		_	5.5	dB
	High	_	_	7	_	_	7	_		7	dB

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 3 of 4)

Symbol/	0 1111		C6			C7, I7			C8		
Description	Conditions	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
Signal detect/loss threshold	PIPE mode	65	_	175	65	_	175	65	_	175	mV
t _{LTR} (10)	_	_	_	75	_	_	75	_	_	75	μs
t _{LTR-LTD_Manual} (11)	_	15	_	_	15	_	_	15	_	_	μs
t _{LTD} (12)	_	0	100	4000	0	100	4000	0	100	4000	ns
t _{LTD_Manual} (13)	_		_	4000	_		4000	_		4000	ns
t _{LTD_Auto} (14)	_		_	4000	_		4000	_		4000	ns
Receiver buffer and CDR offset cancellation time (per channel)	_		_	17000	_	_	17000			17000	recon fig_c lk cycles
	DC Gain Setting = 0	_	0	_	_	0	_	_	0	_	dB
Programmable DC gain	DC Gain Setting = 1	_	3	_	_	3	_	_	3	_	dB
	DC Gain Setting = 2	_	6	_	_	6	_	_	6	_	dB
Transmitter											
Supported I/O Standards	1.5 V PCML										
Data rate (F324 and smaller package)	_	600	_	2500	600	_	2500	600	_	2500	Mbps
Data rate (F484 and larger package)	_	600	_	3125	600	_	3125	600	_	2500	Mbps
V _{OCM}	0.65 V setting	_	650	_	_	650	_	_	650	_	mV
Differential on-chip	100–Ω setting	_	100	_	_	100	_	_	100	_	Ω
termination resistors	150– Ω setting	_	150	_	_	150	_	_	150	_	Ω
Differential and common mode return loss	PIPE, CPRI LV, Serial Rapid I/O SR, SDI, XAUI, SATA					Complian	į		150		_
Rise time	_	50	_	200	50	_	200	50	_	200	ps
Fall time	_	50	_	200	50	_	200	50	_	200	ps
Intra-differential pair skew	_	_	_	15	_	_	15	_	_	15	ps
Intra-transceiver block skew	_	_	_	120	_	_	120	_	_	120	ps

Table 1–21. Transceiver Specification for Cyclone IV GX Devices (Part 4 of 4)

Symbol/	Conditions		C6			C7, I7				Unit	
Description	Collultions	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	UIIIL
PLD-Transceiver Inte	rface										
Interface speed (F324 and smaller package)	_	25	_	125	25	_	125	25	_	125	MHz
Interface speed (F484 and larger package)	_	25	_	156.25	25	_	156.25	25	_	156.25	MHz
Digital reset pulse width	_				Minimum is 2 parallel clock cycles						

Notes to Table 1-21:

- (1) This specification is valid for transmitter output jitter specification with a maximum total jitter value of 112 ps, typically for 3.125 Gbps SRIO and XAUI protocols.
- (2) The minimum reconfig_clk frequency is 2.5 MHz if the transceiver channel is configured in **Transmitter Only** mode. The minimum reconfig_clk frequency is 37.5 MHz if the transceiver channel is configured in **Receiver Only** or **Receiver and Transmitter** mode.
- (3) The device cannot tolerate prolonged operation at this absolute maximum.
- (4) The rate matcher supports only up to ±300 parts per million (ppm).
- (5) Supported for the F169 and F324 device packages only.
- (6) Supported for the F484, F672, and F896 device packages only. Pending device characterization.
- (7) To support CDR ppm tolerance greater than ±300 ppm, implement ppm detector in user logic and configure CDR to Manual Lock Mode.
- (8) Asynchronous spread-spectrum clocking is not supported.
- (9) For the EP4CGX30 (F484 package only), EP4CGX50, and EP4CGX75 devices, the CDR ppl tolerance is ±200 ppm.
- (10) Time taken until pll locked goes high after pll powerdown deasserts.
- (11) Time that the CDR must be kept in lock-to-reference mode after rx analogreset deasserts and before rx locktodata is asserted in manual mode.
- (12) Time taken to recover valid data after the rx_locktodata signal is asserted in manual mode (Figure 1–2), or after rx_freqlocked signal goes high in automatic mode (Figure 1–3).
- (13) Time taken to recover valid data after the $rx_locktodata$ signal is asserted in manual mode.
- (14) Time taken to recover valid data after the $rx_freqlocked$ signal goes high in automatic mode.
- (15) To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.

Table 1–25. PLL Specifications for Cyclone IV Devices (1), (2) (Part 2 of 2)

Symbol	Parameter	Min	Тур	Max	Unit
t _{DLOCK}	Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or areset is deasserted)	_	_	1	ms
toutjitter_period_dedclk (6)	Dedicated clock output period jitter $F_{OUT} \ge 100 \text{ MHz}$	_	_	300	ps
	F _{OUT} < 100 MHz	_	_	30	mUI
toutjitter_ccj_dedclk (6)	Dedicated clock output cycle-to-cycle jitter $F_{OUT} \ge 100 \text{ MHz}$	_	_	300	ps
	F _{OUT} < 100 MHz	_	_	30	mUI
toutjitter_period_io (6)	Regular I/O period jitter $F_{OUT} \ge 100 \text{ MHz}$	_	_	650	ps
	F _{OUT} < 100 MHz	_	_	75	mUI
toutjitter_ccj_io <i>(6)</i>	Regular I/O cycle-to-cycle jitter F _{OUT} ≥ 100 MHz	_	_	650	ps
	F _{OUT} < 100 MHz	_	_	75	mUI
t _{PLL_PSERR}	Accuracy of PLL phase shift	_	_	±50	ps
t _{ARESET}	Minimum pulse width on areset signal.	10	_	_	ns
t _{CONFIGPLL}	Time required to reconfigure scan chains for PLLs	_	3.5 (7)		SCANCLK cycles
f _{SCANCLK}	scanclk frequency	_	_	100	MHz
t _{CASC_OUTJITTER_PERIOD_DEDCLK}	Period jitter for dedicated clock output in cascaded PLLs ($F_{OUT} \ge 100 \text{ MHz}$)	_	_	425	ps
(8), (9)	Period jitter for dedicated clock output in cascaded PLLs (F _{OUT} < 100 MHz)	_	_	42.5	mUI

Notes to Table 1-25:

- (1) This table is applicable for general purpose PLLs and multipurpose PLLs.
- (2) You must connect $V_{CCD\ PLL}$ to V_{CCINT} through the decoupling capacitor and ferrite bead.
- (3) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (4) The V_{CO} frequency reported by the Quartus II software in the PLL Summary section of the compilation report takes into consideration the V_{CO} post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the f_{VCO} specification.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source that is less than 200 ps.
- (6) Peak-to-peak jitter with a probability level of 10⁻¹² (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL when an input jitter of 30 ps is applied.
- (7) With 100-MHz scanclk frequency.
- $\begin{tabular}{ll} (8) & The cascaded PLLs specification is applicable only with the following conditions: \end{tabular}$
 - Upstream PLL—0.59 MHz \leq Upstream PLL bandwidth < 1 MHz
 - Downstream PLL—Downstream PLL bandwidth > 2 MHz
- (9) PLL cascading is not supported for transceiver applications.

Embedded Multiplier Specifications

Table 1–26 lists the embedded multiplier specifications for Cyclone IV devices.

Table 1–26. Embedded Multiplier Specifications for Cyclone IV Devices

Mode	Resources Used		Performance								
	Number of Multipliers	C6	C7, I7, A7	C8	C8L, I8L	C9L	Unit				
9 × 9-bit multiplier	1	340	300	260	240	175	MHz				
18 × 18-bit multiplier	1	287	250	200	185	135	MHz				

Memory Block Specifications

Table 1–27 lists the M9K memory block specifications for Cyclone IV devices.

Table 1-27. Memory Block Performance Specifications for Cyclone IV Devices

		Resou	rces Used						
Memory	Mode	LEs	M9K Memory	C6	C7, I7, A7	C8	C8L, I8L	C9L	Unit
	FIFO 256 × 36	47	1	315	274	238	200	157	MHz
M9K Block	Single-port 256 × 36	0	1	315	274	238	200	157	MHz
INISK DIOCK	Simple dual-port 256 × 36 CLK	0	1	315	274	238	200	157	MHz
	True dual port 512 × 18 single CLK	0	1	315	274	238	200	157	MHz

Configuration and JTAG Specifications

Table 1–28 lists the configuration mode specifications for Cyclone IV devices.

Table 1–28. Passive Configuration Mode Specifications for Cyclone IV Devices (1)

Programming Mode	V _{CCINT} Voltage Level (V)	DCLK f _{max}	Unit
Passive Serial (PS)	1.0 <i>(3)</i>	66	MHz
rassive serial (FS)	1.2	133	MHz
Fast Passive Parallel (FPP) (2)	1.0 ⁽³⁾	66	MHz
Tast rassive ratallel (FFF) 1-7	1.2 (4)	100	MHz

Notes to Table 1-28:

- (1) For more information about PS and FPP configuration timing parameters, refer to the *Configuration and Remote System Upgrades in Cyclone IV Devices* chapter.
- (2) FPP configuration mode supports all Cyclone IV E devices (except for E144 package devices) and EP4CGX50, EP4CGX75, EP4CGX110, and EP4CGX150 only.
- (3) $V_{CCINT} = 1.0 \text{ V}$ is only supported for Cyclone IV E 1.0 V core voltage devices.
- (4) Cyclone IV E devices support 1.2 V V_{CCINT}. Cyclone IV E 1.2 V core voltage devices support 133 MHz DCLK f_{MAX} for EP4CE6, EP4CE10, EP4CE15, EP4CE22, EP4CE30, and EP4CE40 only.

Table 1–29 lists the active configuration mode specifications for Cyclone IV devices.

Table 1–29. Active Configuration Mode Specifications for Cyclone IV Devices

Programming Mode	DCLK Range	Typical DCLK	Unit
Active Parallel (AP) (1)	20 to 40	33	MHz
Active Serial (AS)	20 to 40	33	MHz

Note to Table 1-29:

(1) AP configuration mode is only supported for Cyclone IV E devices.

Table 1–30 lists the JTAG timing parameters and values for Cyclone IV devices.

Table 1–30. JTAG Timing Parameters for Cyclone IV Devices (1)

Symbol	Parameter	Min	Max	Unit
t _{JCP}	TCK clock period	40	_	ns
t _{JCH}	TCK clock high time	19	_	ns
t _{JCL}	TCK clock low time	19	_	ns
t _{JPSU_TDI}	JTAG port setup time for TDI	1	_	ns
t _{JPSU_TMS}	JTAG port setup time for TMS	3	_	ns
t_{JPH}	JTAG port hold time	10	_	ns
t _{JPCO}	JTAG port clock to output (2), (3)	_	15	ns
t _{JPZX}	JTAG port high impedance to valid output (2), (3)	_	15	ns
t _{JPXZ}	JTAG port valid output to high impedance (2), (3)	_	15	ns
t _{JSSU}	Capture register setup time	5	_	ns
t _{JSH}	Capture register hold time	10	_	ns
t _{JSCO}	Update register clock to output	_	25	ns
t _{JSZX}	Update register high impedance to valid output	_	25	ns
t _{JSXZ}	Update register valid output to high impedance		25	ns

Notes to Table 1-30:

- (1) For more information about JTAG waveforms, refer to "JTAG Waveform" in "Glossary" on page 1-37.
- (2) The specification is shown for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 16 ns.
- (3) For EP4CGX22, EP4CGX30 (F324 and smaller package), EP4CGX110, and EP4CGX150 devices, the output time specification for 3.3-, 3.0-, and 2.5-V LVTTL/LVCMOS operation of JTAG pins is 16 ns. For 1.8-V LVTTL/LVCMOS and 1.5-V LVCMOS, the output time specification is 18 ns.

Periphery Performance

This section describes periphery performance, including high-speed I/O and external memory interface.

I/O performance supports several system interfaces, such as the high-speed I/O interface, external memory interface, and the PCI/PCI-X bus interface. I/Os using the SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speeds. I/Os using general-purpose I/O standards such as 3.3-, 3.0-, 2.5-, 1.8-, or 1.5-LVTTL/LVCMOS are capable of a typical 200 MHz interfacing frequency with a 10 pF load.

Table 1–32. Emulated RSDS_E_1R Transmitter Timing Specifications for Cyclone IV Devices (1), (3) (Part 2 of 2)

Symbol	Modes	C6			C7, I7			C8, A7			C8L, I8L			C9L			Unit	
		Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit	
t_{LOO}	CK <i>(2)</i>	_		_	1	_	_	1	_	_	1	_	_	1	_	_	1	ms

Notes to Table 1-32:

- (1) Emulated RSDS_E_1R transmitter is supported at the output pin of all I/O Banks of Cyclone IV E devices and I/O Banks 3, 4, 5, 6, 7, 8, and 9 of Cyclone IV GX devices.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–33. Mini-LVDS Transmitter Timing Specifications for Cyclone IV Devices (1), (2), (4)

0			C6			C7, I	7		C8, A	7		C8L, I	8L		C9L		
Symbol	Modes	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Unit
	×10	5	_	200	5	_	155.5	5	_	155.5	5	_	155.5	5	_	132.5	MHz
	×8	5	_	200	5	_	155.5	5	_	155.5	5	_	155.5	5	_	132.5	MHz
f _{HSCLK} (input clock	×7	5		200	5	_	155.5	5	_	155.5	5		155.5	5	_	132.5	MHz
frequency)	×4	5		200	5		155.5	5		155.5	5		155.5	5		132.5	MHz
1 37	×2	5		200	5	_	155.5	5	_	155.5	5		155.5	5	_	132.5	MHz
	×1	5		400	5		311	5		311	5		311	5		265	MHz
	×10	100		400	100	_	311	100		311	100		311	100	_	265	Mbps
	×8	80		400	80		311	80		311	80		311	80		265	Mbps
Device operation in	×7	70	_	400	70	_	311	70	_	311	70	_	311	70	_	265	Mbps
Mbps	×4	40		400	40	_	311	40	_	311	40		311	40	_	265	Mbps
•	×2	20		400	20	_	311	20	_	311	20		311	20		265	Mbps
	×1	10	_	400	10	_	311	10	_	311	10	_	311	10	_	265	Mbps
t _{DUTY}	_	45		55	45	_	55	45	_	55	45		55	45	_	55	%
TCCS	_	_	_	200	_	_	200	_	_	200	_	_	200	_	_	200	ps
Output jitter (peak to peak)	_	_	_	500	_	_	500	_	_	550	_	_	600	_	_	700	ps
t _{RISE}	20 – 80%, C _{LOAD} = 5 pF	_	500	_	_	500	_	_	500	_	_	500	_	_	500	_	ps
t _{FALL}	20 – 80%, C _{LOAD} = 5 pF	_	500	_	_	500	_	_	500	_	_	500	_	_	500	_	ps
t _{LOCK} (3)	_	_	_	1	_	_	1	_	_	1	_	_	1	_	_	1	ms

Notes to Table 1-33:

- (1) Applicable for true and emulated mini-LVDS transmitter.
- (2) Cyclone IV E—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Emulated mini-LVDS transmitter is supported at the output pin of all I/O banks.

 Cyclone IV GX—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated mini-LVDS transmitter is supported at the
 - Cyclone IV GX—true mini-LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6. Emulated mini-LVDS transmitter is supported at the output pin of I/O Banks 3, 4, 5, 6, 7, 8, and 9.
- (3) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (4) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–34. True LVDS Transmitter Timing Specifications for Cyclone IV Devices (1), (3	ue LVDS Transmitter Timing Specifications	for Cyclone IV Devices (1), (3)
--	---	---------------------------------

Cumbal	Madaa	C	6	C7	, I7	C8,	, A7	C8L	, I8L	C	9L	llmit
Symbol	Modes	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Unit
	×10	5	420	5	370	5	320	5	320	5	250	MHz
	×8	5	420	5	370	5	320	5	320	5	250	MHz
f _{HSCLK} (input	×7	5	420	5	370	5	320	5	320	5	250	MHz
clock frequency)	×4	5	420	5	370	5	320	5	320	5	250	MHz
, ,,,	×2	5	420	5	370	5	320	5	320	5	250	MHz
	×1	5	420	5	402.5	5	402.5	5	362	5	265	MHz
	×10	100	840	100	740	100	640	100	640	100	500	Mbps
	×8	80	840	80	740	80	640	80	640	80	500	Mbps
HSIODR	×7	70	840	70	740	70	640	70	640	70	500	Mbps
nolubh	×4	40	840	40	740	40	640	40	640	40	500	Mbps
	×2	20	840	20	740	20	640	20	640	20	500	Mbps
	×1	10	420	10	402.5	10	402.5	10	362	10	265	Mbps
t _{DUTY}	_	45	55	45	55	45	55	45	55	45	55	%
TCCS	_	_	200	_	200	_	200	_	200	_	200	ps
Output jitter (peak to peak)	_	_	500	_	500	_	550	_	600	_	700	ps
t _{LOCK} (2)	_	_	1	_	1	_	1	_	1	_	1	ms

Notes to Table 1-34:

- (1) Cyclone IV E—true LVDS transmitter is only supported at the output pin of Row I/O Banks 1, 2, 5, and 6. Cyclone IV GX—true LVDS transmitter is only supported at the output pin of Row I/O Banks 5 and 6.
- (2) t_{LOCK} is the time required for the PLL to lock from the end-of-device configuration.
- (3) Cyclone IV E 1.0 V core voltage devices only support C8L, C9L, and I8L speed grades. Cyclone IV E 1.2 V core voltage devices only support C6, C7, C8, I7, and A7 speed grades. Cyclone IV GX devices only support C6, C7, C8, and I7 speed grades.

Table 1–35. Emulated LVDS Transmitter Timing Specifications for Cyclone IV Devices (1), (3) (Part 1 of 2)

Combal	Madaa	C	6	C7,	, I7	C8,	A7	C8L,	, I8L	C	9L	IIi4
Symbol	Modes	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Unit
	×10	5	320	5	320	5	275	5	275	5	250	MHz
	×8	5	320	5	320	5	275	5	275	5	250	MHz
f _{HSCLK} (input clock	×7	5	320	5	320	5	275	5	275	5	250	MHz
frequency)	×4	5	320	5	320	5	275	5	275	5	250	MHz
, ,,	×2	5	320	5	320	5	275	5	275	5	250	MHz
	×1	5	402.5	5	402.5	5	402.5	5	362	5	265	MHz
	×10	100	640	100	640	100	550	100	550	100	500	Mbps
	×8	80	640	80	640	80	550	80	550	80	500	Mbps
HSIODR	×7	70	640	70	640	70	550	70	550	70	500	Mbps
חשטוטוו	×4	40	640	40	640	40	550	40	550	40	500	Mbps
	×2	20	640	20	640	20	550	20	550	20	500	Mbps
	×1	10	402.5	10	402.5	10	402.5	10	362	10	265	Mbps

Table 1–42 and Table 1–43 list the IOE programmable delay for Cyclone IV E 1.2 V core voltage devices.

Table 1-42. IOE Programmable Delay on Column Pins for Cyclone IV E 1.2 V Core Voltage Devices (1), (2)

		Number		Max Offset								
Parameter	Paths Affected	of	Min Offset	Fa	ast Corn	er		Unit				
		Setting		C6	17	A7	C6	C 7	C8	17	A7	
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.314	1.211	1.211	2.177	2.340	2.433	2.388	2.508	ns
Input delay from pin to input register	Pad to I/O input register	8	0	1.307	1.203	1.203	2.19	2.387	2.540	2.430	2.545	ns
Delay from output register to output pin	I/O output register to pad	2	0	0.437	0.402	0.402	0.747	0.820	0.880	0.834	0.873	ns
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.693	0.665	0.665	1.200	1.379	1.532	1.393	1.441	ns

Notes to Table 1-42:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting **0** as available in the Quartus II software.

Table 1–43. IOE Programmable Delay on Row Pins for Cyclone IV E 1.2 V Core Voltage Devices (1), (2)

		Number		Max Offset									
Parameter	Paths Affected	of	Min Offset	Fact Lorner				Slow Corner					
		Setting		C6	17	A7	C6	C 7	C8	17	A7		
Input delay from pin to internal cells	Pad to I/O dataout to core	7	0	1.314	1.209	1.209	2.201	2.386	2.510	2.429	2.548	ns	
Input delay from pin to input register	Pad to I/O input register	8	0	1.312	1.207	1.207	2.202	2.402	2.558	2.447	2.557	ns	
Delay from output register to output pin	I/O output register to pad	2	0	0.458	0.419	0.419	0.783	0.861	0.924	0.875	0.915	ns	
Input delay from dual-purpose clock pin to fan-out destinations	Pad to global clock network	12	0	0.686	0.657	0.657	1.185	1.360	1.506	1.376	1.422	ns	

Notes to Table 1-43:

- (1) The incremental values for the settings are generally linear. For the exact values for each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers are in reference to setting 0 as available in the Quartus II software.

Table 1-46. Glossary (Part 4 of 5)

ter	Term	Definitions									
	t _C	High-speed receiver and transmitter input and output clock period.									
	Channel-to- channel-skew (TCCS)	High-speed I/O block: The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement.									
	t _{cin}	Delay from the clock pad to the I/O input register.									
	t _{co}	Delay from the clock pad to the I/O output.									
	t _{cout}	Delay from the clock pad to the I/O output register.									
	t _{DUTY}	High-speed I/O block: Duty cycle on high-speed transmitter output clock.									
	t _{FALL}	Signal high-to-low transition time (80–20%).									
	t _H	Input register hold time.									
	Timing Unit Interval (TUI)	High-speed I/O block: The timing budget allowed for skew, propagation delays, and data sampling window. (TUI = $1/(Receiver\ Input\ Clock\ Frequency\ Multiplication\ Factor) = t_C/w)$.									
	t _{INJITTER}	Period jitter on the PLL clock input.									
	t _{OUTJITTER_DEDCLK}	Period jitter on the dedicated clock output driven by a PLL.									
	t _{OUTJITTER_IO}	Period jitter on the general purpose I/O driven by a PLL.									
	t _{pllcin}	Delay from the PLL inclk pad to the I/O input register.									
-	t _{pllcout}	Delay from the PLL inclk pad to the I/O output register.									
	Transmitter Output Waveform	Transmitter output waveforms for the LVDS, mini-LVDS, PPDS and RSDS Differential I/O Standards: Single-Ended Waveform Positive Channel (p) = V _{OH} Negative Channel (n) = V _{OL} Ground Differential Waveform (Mathematical Function of Positive & Negative Channel) V _{OD} 0 V p - n									
	t _{RISE}	Signal low-to-high transition time (20–80%).									
	t _{SU}	Input register setup time.									
J	_	_									

Document Revision History

Table 1–47 lists the revision history for this chapter.

Table 1–47. Document Revision History

Date	Version	Changes							
March 2016	2.0	Updated note (5) in Table 1–21 to remove support for the N148 package.							
October 2014	1.0	Updated maximum value for V _{CCD_PLL} in Table 1–1.							
October 2014	1.9	Removed extended temperature note in Table 1–3.							
December 2013	1.8	Updated Table 1–21 by adding Note (15).							
May 2013	1.7	Updated Table 1–15 by adding Note (4).							
		■ Updated the maximum value for V _I , V _{CCD_PLL} , V _{CCIO} , V _{CC_CLKIN} , V _{CCH_GXB} , and V _{CCA_GXB} Table 1–1.							
		■ Updated Table 1–11 and Table 1–22.							
October 2012	1.6	 Updated Table 1–21 to include peak-to-peak differential input voltage for the Cyclone IV GX transceiver input reference clock. 							
		■ Updated Table 1–29 to include the typical DCLK value.							
		■ Updated the minimum f _{HSCLK} value in Table 1–31, Table 1–32, Table 1–33, Table 1–34, and Table 1–35.							
		 Updated "Maximum Allowed Overshoot or Undershoot Voltage", "Operating Conditions", and "PLL Specifications" sections. 							
November 2011	1.5	■ Updated Table 1–2, Table 1–3, Table 1–4, Table 1–5, Table 1–8, Table 1–9, Table 1–15, Table 1–18, Table 1–19, and Table 1–21.							
		■ Updated Figure 1–1.							
		■ Updated for the Quartus II software version 10.1 release.							
December 2010	1.4	■ Updated Table 1–21 and Table 1–25.							
		■ Minor text edits.							
		Updated for the Quartus II software version 10.0 release:							
		■ Updated Table 1–3, Table 1–4, Table 1–21, Table 1–25, Table 1–28, Table 1–30, Table 1–40, Table 1–41, Table 1–42, Table 1–43, Table 1–44, and Table 1–45.							
July 2010	1.3	■ Updated Figure 1–2 and Figure 1–3.							
		 Removed SW Requirement and TCCS for Cyclone IV Devices tables. 							
		■ Minor text edits.							
		Updated to include automotive devices:							
		Updated the "Operating Conditions" and "PLL Specifications" sections.							
March 2010	1.2	■ Updated Table 1–1, Table 1–8, Table 1–9, Table 1–21, Table 1–26, Table 1–27, Table 1–31, Table 1–32, Table 1–33, Table 1–35, Table 1–36, Table 1–37, Table 1–38, Table 1–40, Table 1–42, and Table 1–43.							
		■ Added Table 1–5 to include ESD for Cyclone IV devices GPIOs and HSSI I/Os.							
		 Added Table 1–44 and Table 1–45 to include IOE programmable delay for Cyclone IV E 1.2 V core voltage devices. 							
		Minor text edits.							