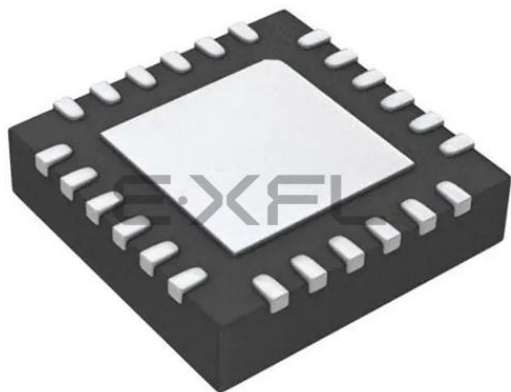




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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	8051
Core Size	8-Bit
Speed	50MHz
Connectivity	SMBus (2-Wire/I ² C), LINbus, SPI, UART/USART
Peripherals	POR, PWM, Temp Sensor, WDT
Number of I/O	18
Program Memory Size	32KB (32K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	2.25K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.25V
Data Converters	A/D 18x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	24-WFQFN Exposed Pad
Supplier Device Package	24-QFN (4x4)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/c8051f552-im

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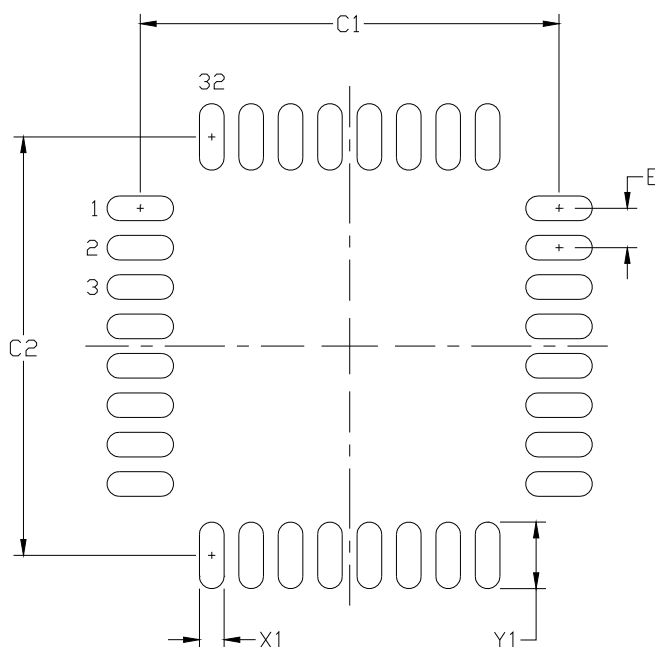


Figure 4.4. QFP-32 Landing Diagram

Table 4.4. QFP-32 Landing Diagram Dimensions

Dimension	Min	Max	Dimension	Min	Max
C1	8.40	8.50	X1	0.40	0.50
C2	8.40	8.50	Y1	1.25	1.35
E	0.80 BSC				

Notes:

General

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This Land Pattern Design is based on the IPC-7351 guidelines.

Solder Mask Design

3. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 μ m minimum, all the way around the pad.

Stencil Design

4. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
5. The stencil thickness should be 0.125 mm (5 mils).
6. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pads.

Card Assembly

7. A No-Clean, Type-3 solder paste is recommended.
8. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

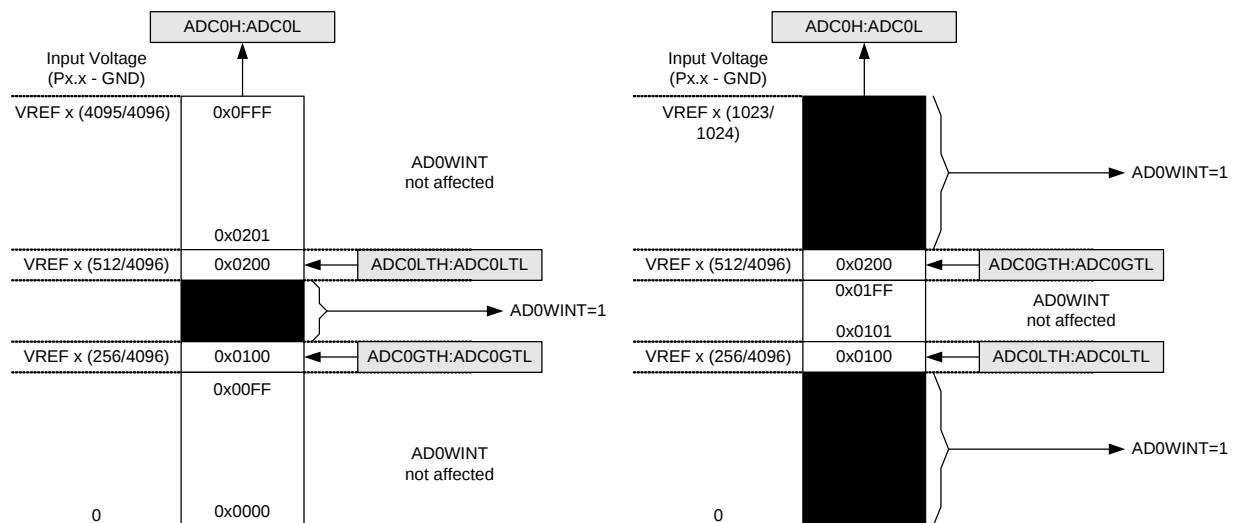


Figure 6.6. ADC Window Compare Example: Right-Justified Data

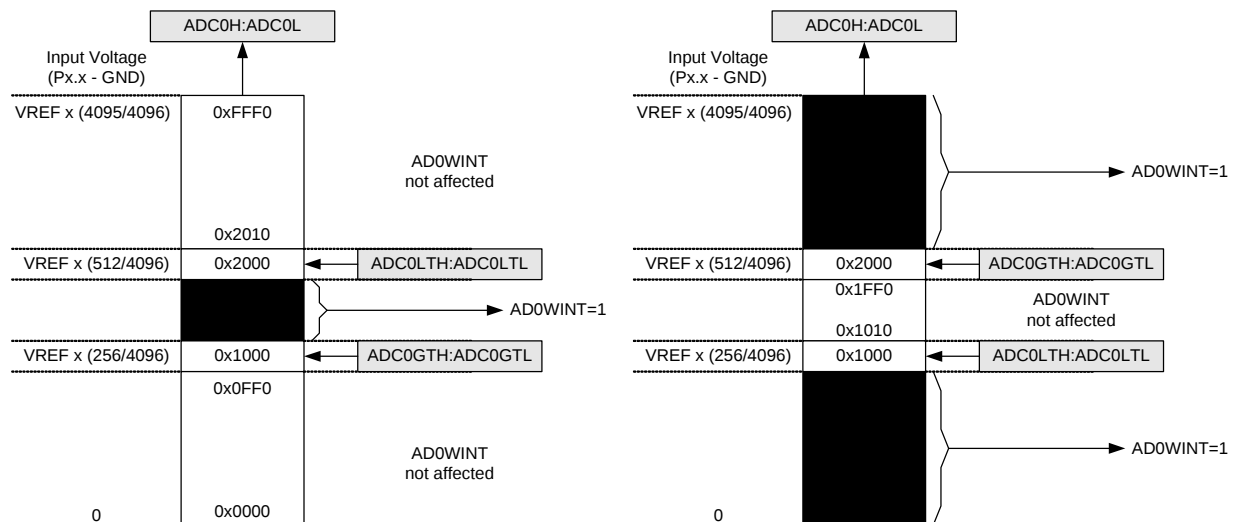


Figure 6.7. ADC Window Compare Example: Left-Justified Data

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SFR Definition 10.1. DPL: Data Pointer Low Byte

Bit	7	6	5	4	3	2	1	0
Name	DPL[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x82; SFR Page = All Pages

Bit	Name	Function
7:0	DPL[7:0]	Data Pointer Low. The DPL register is the low byte of the 16-bit DPTR. DPTR is used to access indirectly addressed Flash memory or XRAM.

SFR Definition 10.2. DPH: Data Pointer High Byte

Bit	7	6	5	4	3	2	1	0
Name	DPH[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x83; SFR Page = All Pages

Bit	Name	Function
7:0	DPH[7:0]	Data Pointer High. The DPH register is the high byte of the 16-bit DPTR. DPTR is used to access indirectly addressed Flash memory or XRAM.

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While CIP-51 executes in-line code (writing values to SPI0DAT in this example), the CAN0 Interrupt occurs. The CIP-51 vectors to the CAN0 ISR and pushes the current SFR Page value (SFR Page 0x00) into SFRNEXT in the SFR Page Stack. The SFR page needed to access CAN's SFRs is then automatically placed in the SFRPAGE register (SFR Page 0x0C). SFRPAGE is considered the “top” of the SFR Page Stack. Software can now access the CAN0 SFRs. Software may switch to any SFR Page by writing a new value to the SFRPAGE register at any time during the CAN0 ISR to access SFRs that are not on SFR Page 0x0C. See Figure 12.3.

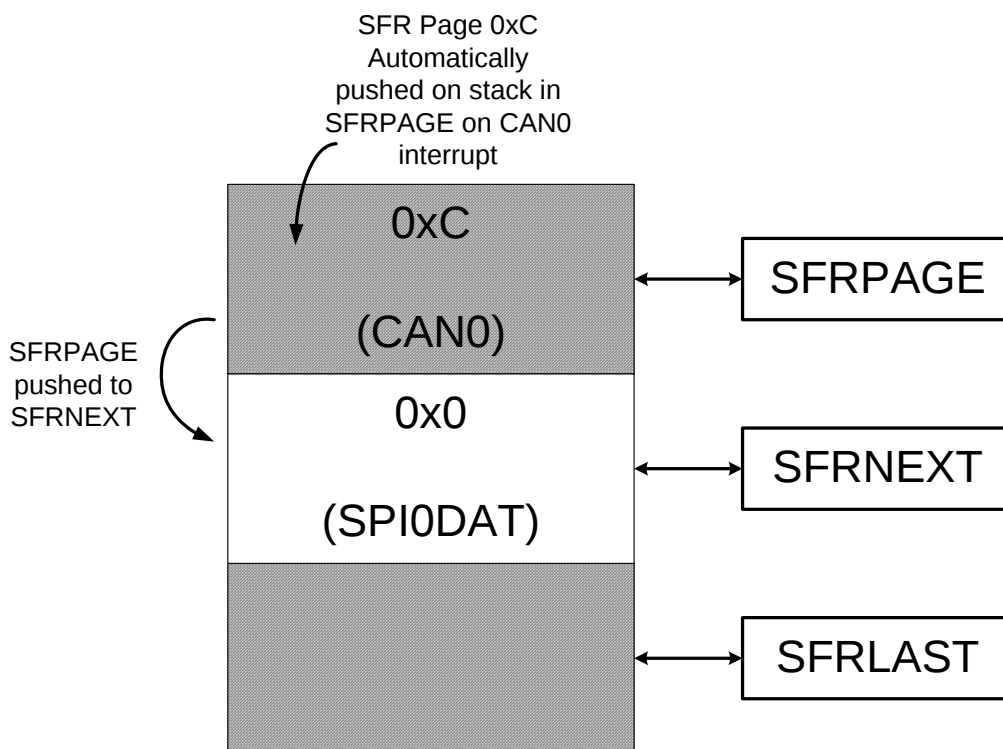


Figure 12.3. SFR Page Stack After CAN0 Interrupt Occurs

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On exit from the PCA interrupt service routine, the CIP-51 will return to the CAN0 ISR. On execution of the RETI instruction, SFR Page 0x00 used to access the PCA registers will be automatically popped off of the SFR Page Stack, and the contents of the SFRNEXT register will be moved to the SFRPAGE register. Software in the CAN0 ISR can continue to access SFRs as it did prior to the PCA interrupt. Likewise, the contents of SFRLAST are moved to the SFRNEXT register. Recall this was the SFR Page value 0x00 being used to access SPI0DAT before the CAN0 interrupt occurred. See Figure 12.5.

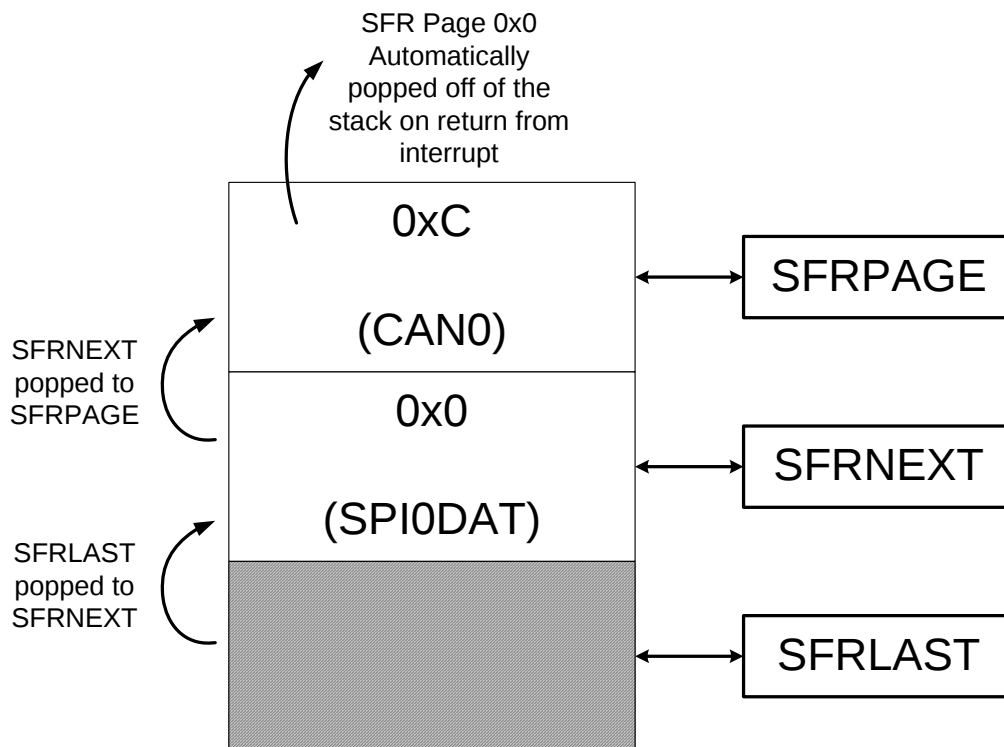


Figure 12.5. SFR Page Stack Upon Return From PCA Interrupt

On the execution of the RETI instruction in the CAN0 ISR, the value in SFRPAGE register is overwritten with the contents of SFRNEXT. The CIP-51 may now access the SPI0DAT register as it did prior to the interrupts occurring. See Figure 12.6.

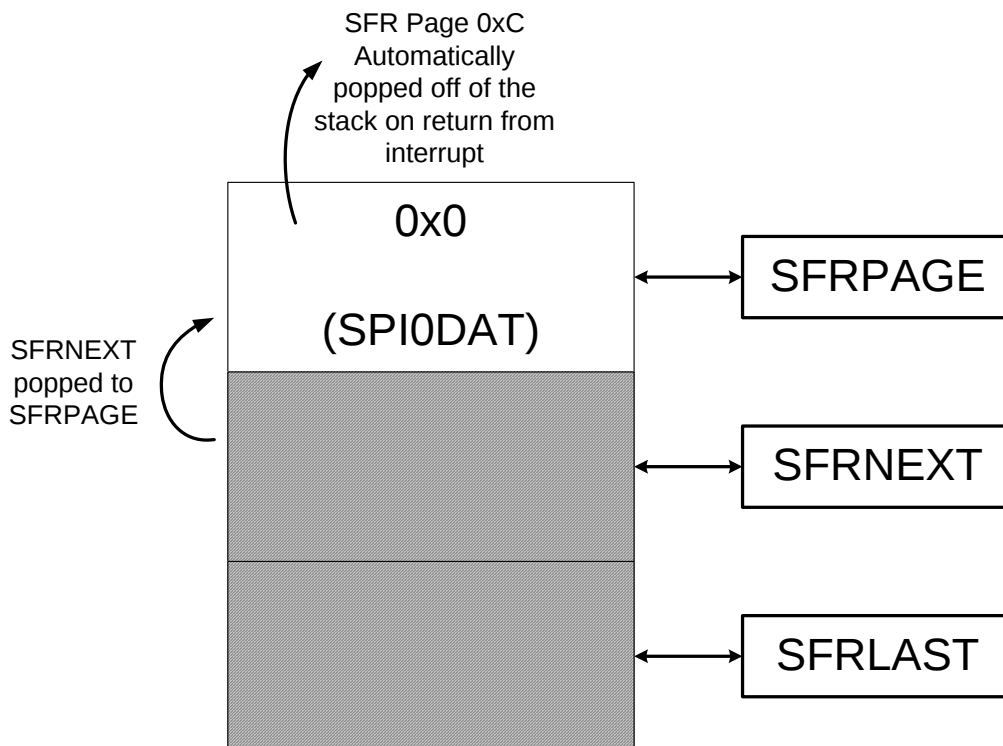


Figure 12.6. SFR Page Stack Upon Return From CAN0 Interrupt

In the example above, all three bytes in the SFR Page Stack are accessible via the SFRPAGE, SFRNEXT, and SFRLAST special function registers. If the stack is altered while servicing an interrupt, it is possible to return to a different SFR Page upon interrupt exit than selected prior to the interrupt call. Direct access to the SFR Page stack can be useful to enable real-time operating systems to control and manage context switching between multiple tasks.

Push operations on the SFR Page Stack only occur on interrupt service, and pop operations only occur on interrupt exit (execution on the RETI instruction). The automatic switching of the SFRPAGE and operation of the SFR Page Stack as described above can be disabled in software by clearing the SFR Automatic Page Enable Bit (SFRPGEN) in the SFR Page Control Register (SFR0CN). See SFR Definition 12.1.

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SFR Definition 12.3. SFRNEXT: SFR Next

Bit	7	6	5	4	3	2	1	0
Name	SFRNEXT[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x85; SFR Page = All Pages

Bit	Name	Function
7:0	SFRNEXT[7:0]	SFR Page Bits. This is the value that will go to the SFR Page register upon a return from interrupt. Write: Sets the SFR Page contained in the second byte of the SFR Stack. This will cause the SFRPAGE SFR to have this SFR page value upon a return from interrupt. Read: Returns the value of the SFR page contained in the second byte of the SFR stack. SFR page context is retained upon interrupts/return from interrupts in a 3 byte SFR Page Stack: SFRPAGE is the first entry, SFRNEXT is the second, and SFRLAST is the third entry. The SFR stack bytes may be used alter the context in the SFR Page Stack, and will not cause the stack to “push” or “pop”. Only interrupts and return from interrupts cause pushes and pops of the SFR Page Stack.

The level of Flash security depends on the Flash access method. The three Flash access methods that can be restricted are reads, writes, and erases from the C2 debug interface, user firmware executing on unlocked pages, and user firmware executing on locked pages. Table 14.1 summarizes the Flash security features of the C8051F55x/56x/57x devices.

Table 14.1. Flash Security Summary

Action	C2 Debug Interface	User Firmware executing from:	
		an unlocked page	a locked page
Read, Write or Erase unlocked pages (except page with Lock Byte)	Permitted	Permitted	Permitted
Read, Write or Erase locked pages (except page with Lock Byte)	Not Permitted	Flash Error Reset	Permitted
Read or Write page containing Lock Byte (if no pages are locked)	Permitted	Permitted	Permitted
Read or Write page containing Lock Byte (if any page is locked)	Not Permitted	Flash Error Reset	Permitted
Read contents of Lock Byte (if no pages are locked)	Permitted	Permitted	Permitted
Read contents of Lock Byte (if any page is locked)	Not Permitted	Flash Error Reset	Permitted
Erase page containing Lock Byte (if no pages are locked)	Permitted	Flash Error Reset	Flash Error Reset
Erase page containing Lock Byte—Unlock all pages (if any page is locked)	C2 Device Erase Only	Flash Error Reset	Flash Error Reset
Lock additional pages (change '1's to '0's in the Lock Byte)	Not Permitted	Flash Error Reset	Flash Error Reset
Unlock individual pages (change '0's to '1's in the Lock Byte)	Not Permitted	Flash Error Reset	Flash Error Reset
Read, Write or Erase Reserved Area	Not Permitted	Flash Error Reset	Flash Error Reset
C2 Device Erase—Erases all Flash pages including the page containing the Lock Byte. Flash Error Reset—Not permitted; Causes Flash Error Device Reset (FERROR bit in RSTSRC is '1' after reset). - All prohibited operations that are performed via the C2 interface are ignored (do not cause device reset). - Locking any Flash page also locks the page containing the Lock Byte. - Once written to, the Lock Byte cannot be modified except by performing a C2 Device Erase. - If user code writes to the Lock Byte, the Lock does not take effect until the next device reset.			

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SFR Definition 18.5. CLKMUL: Clock Multiplier

Bit	7	6	5	4	3	2	1	0
Name	MULEN	MULINIT	MULRDY	MULDIV[2:0]			MULSEL[1:0]	
Type	R/W	R/W	R	R/W			R/W	
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x97; SFR Page = 0x0F

Bit	Name	Function															
7	MULEN	Clock Multiplier Enable. 0: Clock Multiplier disabled. 1: Clock Multiplier enabled.															
6	MULINIT	Clock Multiplier Initialize. This bit is 0 when the Clock Multiplier is enabled. Once enabled, writing a 1 to this bit will initialize the Clock Multiplier. The MULRDY bit reads 1 when the Clock Multiplier is stabilized.															
5	MULRDY	Clock Multiplier Ready. 0: Clock Multiplier is not ready. 1: Clock Multiplier is ready (PLL is locked).															
4:2	MULDIV[2:0]	Clock Multiplier Output Scaling Factor. 000: Clock Multiplier Output scaled by a factor of 1. 001: Clock Multiplier Output scaled by a factor of 1. 010: Clock Multiplier Output scaled by a factor of 1. 011: Clock Multiplier Output scaled by a factor of 2/3*. 100: Clock Multiplier Output scaled by a factor of 2/4 (1/2). 101: Clock Multiplier Output scaled by a factor of 2/5*. 110: Clock Multiplier Output scaled by a factor of 2/6 (1/3). 111: Clock Multiplier Output scaled by a factor of 2/7*. *Note: The Clock Multiplier output duty cycle is not 50% for these settings.															
1:0	MULSEL[1:0]	Clock Multiplier Input Select. These bits select the clock supplied to the Clock Multiplier <table> <tr> <th>MULSEL[1:0]</th><th>Selected Input Clock</th><th>Clock Multiplier Output for MULDIV[2:0] = 000b</th></tr> <tr> <td>00</td><td>Internal Oscillator</td><td>Internal Oscillator x 2</td></tr> <tr> <td>01</td><td>External Oscillator</td><td>External Oscillator x 2</td></tr> <tr> <td>10</td><td>Internal Oscillator</td><td>Internal Oscillator x 4</td></tr> <tr> <td>11</td><td>External Oscillator</td><td>External Oscillator x 4</td></tr> </table>	MULSEL[1:0]	Selected Input Clock	Clock Multiplier Output for MULDIV[2:0] = 000b	00	Internal Oscillator	Internal Oscillator x 2	01	External Oscillator	External Oscillator x 2	10	Internal Oscillator	Internal Oscillator x 4	11	External Oscillator	External Oscillator x 4
MULSEL[1:0]	Selected Input Clock	Clock Multiplier Output for MULDIV[2:0] = 000b															
00	Internal Oscillator	Internal Oscillator x 2															
01	External Oscillator	External Oscillator x 2															
10	Internal Oscillator	Internal Oscillator x 4															
11	External Oscillator	External Oscillator x 4															

Notes: The maximum system clock is 50 MHz, and so the Clock Multiplier output should be scaled accordingly.
If Internal Oscillator x 2 or External Oscillator x 2 is selected using the MULSEL bits, MULDIV[2:0] is ignored.

SFR Definition 19.2. XBR1: Port I/O Crossbar Register 1

Bit	7	6	5	4	3	2	1	0
Name	T1E	T0E	ECIE	PCA0ME[2:0]			SYSCKE	Reserved
Type	R/W	R/W	R/W	R/W	R/W	R	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Address = 0xE2; SFR Page = 0x0F

Bit	Name	Function
7	T1E	T1 Enable. 0: T1 unavailable at Port pin. 1: T1 routed to Port pin.
6	T0E	T0 Enable. 0: T0 unavailable at Port pin. 1: T0 routed to Port pin.
5	ECIE	PCA0 External Counter Input Enable. 0: ECI unavailable at Port pin. 1: ECI routed to Port pin.
4:2	PCA0ME[2:0]	PCA Module I/O Enable Bits. 000: All PCA I/O unavailable at Port pins. 001: CEX0 routed to Port pin. 010: CEX0, CEX1 routed to Port pins. 011: CEX0, CEX1, CEX2 routed to Port pins. 100: CEX0, CEX1, CEX2, CEX3 routed to Port pins. 101: CEX0, CEX1, CEX2, CEX3, CEX4 routed to Port pins. 110: CEX0, CEX1, CEX2, CEX3, CEX4, CEX5 routed to Port pins. 111: RESERVED
1	SYSCKE	/SYSCLK Output Enable. 0: /SYSCLK unavailable at Port pin. 1: /SYSCLK output routed to Port pin.
0	Reserved	Always Write to 0.

LIN Register Definition 20.4. LIN0DTn: LIN0 Data Byte n

Bit	7	6	5	4	3	2	1	0
Name	DATAn[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

Indirect Address: LIN0DT1 = 0x00, LIN0DT2 = 0x01, LIN0DT3 = 0x02, LIN0DT4 = 0x03, LIN0DT5 = 0x04, LIN0DT6 = 0x05, LIN0DT7 = 0x06, LIN0DT8 = 0x07

Bit	Name	Function
7:0	DATAn[7:0]	LIN Data Byte n. Serial Data Byte that is received or transmitted across the LIN interface.

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22.4.2. SMB0CN Control Register

SMB0CN is used to control the interface and to provide status information (see SFR Definition 22.2). The higher four bits of SMB0CN (MASTER, TXMODE, STA, and STO) form a status vector that can be used to jump to service routines. MASTER indicates whether a device is the master or slave during the current transfer. TXMODE indicates whether the device is transmitting or receiving data for the current byte.

STA and STO indicate that a START and/or STOP has been detected or generated since the last SMBus interrupt. STA and STO are also used to generate START and STOP conditions when operating as a master. Writing a 1 to STA will cause the SMBus interface to enter Master Mode and generate a START when the bus becomes free (STA is not cleared by hardware after the START is generated). Writing a 1 to STO while in Master Mode will cause the interface to generate a STOP and end the current transfer after the next ACK cycle. If STO and STA are both set (while in Master Mode), a STOP followed by a START will be generated.

As a receiver, writing the ACK bit defines the outgoing ACK value; as a transmitter, reading the ACK bit indicates the value received during the last ACK cycle. ACKRQ is set each time a byte is received, indicating that an outgoing ACK value is needed. When ACKRQ is set, software should write the desired outgoing value to the ACK bit before clearing SI. A NACK will be generated if software does not write the ACK bit before clearing SI. SDA will reflect the defined ACK value immediately following a write to the ACK bit; however SCL will remain low until SI is cleared. If a received slave address is not acknowledged, further slave events will be ignored until the next START is detected.

The ARBLOST bit indicates that the interface has lost an arbitration. This may occur anytime the interface is transmitting (master or slave). A lost arbitration while operating as a slave indicates a bus error condition. ARBLOST is cleared by hardware each time SI is cleared.

The SI bit (SMBus Interrupt Flag) is set at the beginning and end of each transfer, after each byte frame, or when an arbitration is lost; see Table 22.3 for more details.

Important Note About the SI Bit: The SMBus interface is stalled while SI is set; thus SCL is held low, and the bus is stalled until software clears SI.

25. Timers

Each MCU includes four counter/timers: two are 16-bit counter/timers compatible with those found in the standard 8051, and two are 16-bit auto-reload timer for use with the ADC, SMBus, or for general purpose use. These timers can be used to measure time intervals, count external events and generate periodic interrupt requests. Timer 0 and Timer 1 are nearly identical and have four primary modes of operation. Timer 2 and Timer 3 offer 16-bit and split 8-bit timer functionality with auto-reload.

Timer 0 and Timer 1 Modes	Timer 2 Modes	Timer 3 Modes
13-bit counter/timer	16-bit timer with auto-reload	16-bit timer with auto-reload
16-bit counter/timer		
8-bit counter/timer with auto-reload	Two 8-bit timers with auto-reload	Two 8-bit timers with auto-reload
Two 8-bit counter/timers (Timer 0 only)		

Timers 0 and 1 may be clocked by one of five sources, determined by the Timer Mode Select bits (T1M–T0M) and the Clock Scale bits (SCA1–SCA0). The Clock Scale bits define a pre-scaled clock from which Timer 0 and/or Timer 1 may be clocked (See SFR Definition 25.1 for pre-scaled clock selection). Timer 0/1 may then be configured to use this pre-scaled clock signal or the system clock.

Timer 2 and Timer 3 may be clocked by the system clock, the system clock divided by 12, or the external oscillator clock source divided by 8.

Timer 0 and Timer 1 may also be operated as counters. When functioning as a counter, a counter/timer register is incremented on each high-to-low transition at the selected input pin (T0 or T1). Events with a frequency of up to one-fourth the system clock frequency can be counted. The input signal need not be periodic, but it should be held at a given level for at least two full system clock cycles to ensure the level is properly sampled.

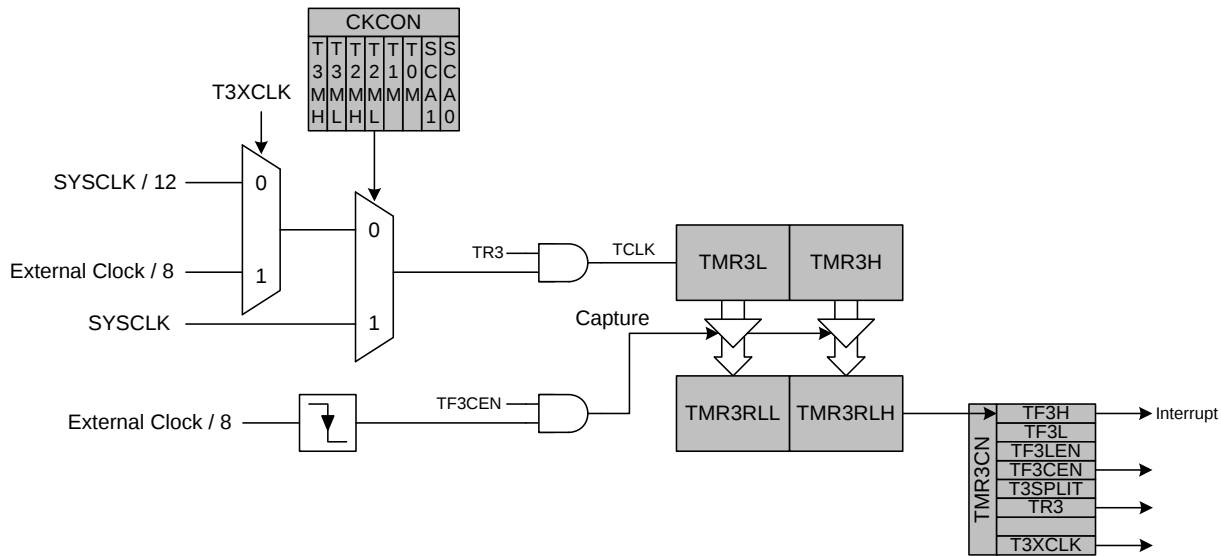


Figure 25.9. Timer 3 External Oscillator Capture Mode Block Diagram

SFR Definition 25.14. TMR3RLL: Timer 3 Reload Register Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3RLL[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x92; SFR Page = 0x00

Bit	Name	Function
7:0	TMR3RLL[7:0]	Timer 3 Reload Register Low Byte. TMR3RLL holds the low byte of the reload value for Timer 3.

SFR Definition 25.15. TMR3RLH: Timer 3 Reload Register High Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3RLH[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x93; SFR Page = 0x00

Bit	Name	Function
7:0	TMR3RLH[7:0]	Timer 3 Reload Register High Byte. TMR3RLH holds the high byte of the reload value for Timer 3.

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SFR Definition 25.16. TMR3L: Timer 3 Low Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3L[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x94; SFR Page = 0x00

Bit	Name	Function
7:0	TMR3L[7:0]	Timer 3 Low Byte. In 16-bit mode, the TMR3L register contains the low byte of the 16-bit Timer 3. In 8-bit mode, TMR3L contains the 8-bit low byte timer value.

SFR Definition 25.17. TMR3H Timer 3 High Byte

Bit	7	6	5	4	3	2	1	0
Name	TMR3H[7:0]							
Type	R/W							
Reset	0	0	0	0	0	0	0	0

SFR Address = 0x95; SFR Page = 0x00

Bit	Name	Function
7:0	TMR3H[7:0]	Timer 3 High Byte. In 16-bit mode, the TMR3H register contains the high byte of the 16-bit Timer 3. In 8-bit mode, TMR3H contains the 8-bit high byte timer value.

SFR Definition 26.4. PCA0CPMn: PCA Capture/Compare Mode

Bit	7	6	5	4	3	2	1	0
Name	PWM16n	ECOMn	CAPPn	CAPNn	MATn	TOGn	PWMn	ECCFn
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

SFR Addresses: PCA0CPM0 = 0xDA, PCA0CPM1 = 0xDB, PCA0CPM2 = 0xDC; PCA0CPM3 = 0xDD, PCA0CPM4 = 0xDE, PCA0CPM5 = 0xDF, SFR Page (all registers) = 0x00

Bit	Name	Function
7	PWM16n	16-bit Pulse Width Modulation Enable. This bit enables 16-bit mode when Pulse Width Modulation mode is enabled. 0: 8 to 11-bit PWM selected. 1: 16-bit PWM selected.
6	ECOMn	Comparator Function Enable. This bit enables the comparator function for PCA module n when set to 1.
5	CAPPn	Capture Positive Function Enable. This bit enables the positive edge capture for PCA module n when set to 1.
4	CAPNn	Capture Negative Function Enable. This bit enables the negative edge capture for PCA module n when set to 1.
3	MATn	Match Function Enable. This bit enables the match function for PCA module n when set to 1. When enabled, matches of the PCA counter with a module's capture/compare register cause the CCFn bit in PCA0MD register to be set to logic 1.
2	TOGn	Toggle Function Enable. This bit enables the toggle function for PCA module n when set to 1. When enabled, matches of the PCA counter with a module's capture/compare register cause the logic level on the CEXn pin to toggle. If the PWMn bit is also set to logic 1, the module operates in Frequency Output Mode.
1	PWMn	Pulse Width Modulation Mode Enable. This bit enables the PWM function for PCA module n when set to 1. When enabled, a pulse width modulated signal is output on the CEXn pin. 8 to 11-bit PWM is used if PWM16n is cleared; 16-bit mode is used if PWM16n is set to logic 1. If the TOGn bit is also set, the module operates in Frequency Output Mode.
0	ECCFn	Capture/Compare Flag Interrupt Enable. This bit sets the masking of the Capture/Compare Flag (CCFn) interrupt. 0: Disable CCFn interrupts. 1: Enable a Capture/Compare Flag interrupt request when CCFn is set.
Note: When the WDTE bit is set to 1, the PCA0CPM5 register cannot be modified, and module 5 acts as the watchdog timer. To change the contents of the PCA0CPM5 register or the function of module 5, the Watchdog Timer must be disabled.		