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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of **Embedded - Microprocessors**

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details

Obsolete
PowerPC e300
1 Core, 32-Bit
400MHz
-
DDR, DDR2
No
-
10/100/1000Mbps (3)
-
USB 2.0 + PHY (2)
1.8V, 2.5V, 3.3V
0°C ~ 105°C (TA)
-
620-BBGA Exposed Pad
620-HBGA (29x29)
https://www.e-xfl.com/product-detail/nxp-semiconductors/mpc8343vragd

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



	Parameter	Symbol	Max Value	Unit	Notes
Input voltage	DDR DRAM signals	MV _{IN}	–0.3 to (GV _{DD} + 0.3)	V	2, 5
	DDR DRAM reference	MV_{REF}	–0.3 to (GV _{DD} + 0.3)	V	2, 5
	Three-speed Ethernet signals	LV _{IN}	–0.3 to (LV _{DD} + 0.3)	V	4, 5
	Local bus, DUART, CLKIN, system control and power management, I ² C, and JTAG signals	OV _{IN}	-0.3 to (OV _{DD} + 0.3)	V	3, 5
	PCI	OV _{IN}	–0.3 to (OV _{DD} + 0.3)	V	6
Storage temperature range		T _{STG}	–55 to 150	°C	—

Table 1. Absolute Maximum Ratings¹ (continued)

Notes:

- ¹ Functional and tested operating conditions are given in Table 2. Absolute maximum ratings are stress ratings only, and functional operation at the maximums is not guaranteed. Stresses beyond those listed may affect device reliability or cause permanent damage to the device.
- ² Caution: MV_{IN} must not exceed GV_{DD} by more than 0.3 V. This limit can be exceeded for a maximum of 20 ms during power-on reset and power-down sequences.
- ³ **Caution:** OV_{IN} must not exceed OV_{DD} by more than 0.3 V. This limit can be exceeded for a maximum of 20 ms during power-on reset and power-down sequences.
- ⁴ **Caution:** LV_{IN} must not exceed LV_{DD} by more than 0.3 V. This limit can be exceeded for a maximum of 20 ms during power-on reset and power-down sequences.
- ⁵ (M,L,O)V_{IN} and MV_{REF} may overshoot/undershoot to a voltage and for a maximum duration as shown in Figure 2.
- 6 OVIN on the PCI interface can overshoot/undershoot according to the PCI Electrical Specification for 3.3-V operation, as shown in Figure 3.

2.1.2 Power Supply Voltage Specification

Table 2 provides the recommended operating conditions for the MPC8343EA. Note that the values in Table 2 are the recommended and tested operating conditions. Proper device operation outside these conditions is not guaranteed.

Parameter	Symbol	Recommended Value	Unit	Notes
Core supply voltage	V _{DD}	1.2 V ± 60 mV	V	1
PLL supply voltage	AV _{DD}	1.2 V ± 60 mV	V	1
DDR and DDR2 DRAM I/O voltage	GV _{DD}	2.5 V ± 125 mV 1.8 V ± 90 mV	V	—
Three-speed Ethernet I/O supply voltage	LV _{DD1}	3.3 V ± 330 mV 2.5 V ± 125 mV	V	—
Three-speed Ethernet I/O supply voltage	LV _{DD2}	3.3 V ± 330 mV 2.5 V ± 125 mV	V	—

 Table 2. Recommended Operating Conditions

Parameter	Symbol	Recommended Value	Unit	Notes
PCI, local bus, DUART, system control and power management, I ² C, and JTAG I/O voltage	OV _{DD}	3.3 V ± 330 mV	V	—

Table 2. Recommended Operating Conditions (continued)

Note:

¹ GV_{DD}, LV_{DD}, OV_{DD}, AV_{DD}, and V_{DD} must track each other and must vary in the same direction—either in the positive or negative direction.

Figure 2 shows the undershoot and overshoot voltages at the interfaces of the MPC8343EA.



Figure 2. Overshoot/Undershoot Voltage for $GV_{DD}/OV_{DD}/LV_{DD}$



Figure 3 shows the undershoot and overshoot voltage of the PCI interface of the MPC8343EA for the 3.3-V signals, respectively.



Figure 3. Maximum AC Waveforms on PCI Interface for 3.3-V Signaling

2.1.3 Output Driver Characteristics

Table 3 provides information on the characteristics of the output driver strengths. The values are preliminary estimates.

Driver Type	Output Impedance (Ω)	Supply Voltage
Local bus interface utilities signals	40	OV _{DD} = 3.3 V
PCI signals (not including PCI output clocks)	25	
PCI output clocks (including PCI_SYNC_OUT)	40	
DDR signal	18	GV _{DD} = 2.5 V
DDR2 signal	18 36 (half-strength mode)	GV _{DD} = 1.8 V
TSEC/10/100 signals	40	LV _{DD} = 2.5/3.3 V
DUART, system control, I ² C, JTAG, USB	40	OV _{DD} = 3.3 V
GPIO signals	40	OV _{DD} = 3.3 V, LV _{DD} = 2.5/3.3 V

Table 3. Output Drive Capability

2.2 **Power Sequencing**

This section details the power sequencing considerations for the MPC8343EA.

2.2.1 Power-Up Sequencing

MPC8343EAdoes not require the core supply voltage (V_{DD} and AV_{DD}) and I/O supply voltages (GV_{DD} , LV_{DD} , and OV_{DD}) to be applied in any particular order. During the power ramp up, before the power



Power Characteristics

supplies are stable and if the I/O voltages are supplied before the core voltage, there may be a period of time that all input and output pins will actively be driven and cause contention and excessive current from 3A to 5A. In order to avoid actively driving the I/O pins and to eliminate excessive current draw, apply the core voltage (V_{DD}) before the I/O voltage (GV_{DD} , LV_{DD} , and OV_{DD}) and assert PORESET before the power supplies fully ramp up. In the case where the core voltage is applied first, the core voltage supply must rise to 90% of its nominal value before the I/O supplies reach 0.7 V, see Figure 4.



Figure 4. Power Sequencing Example

I/O voltage supplies (GV_{DD} , LV_{DD} , and OV_{DD}) do not have any ordering requirements with respect to one another.

3 Power Characteristics

The estimated typical power dissipation for the MPC8343EA device is shown in Table 4.

	Core Frequency (MHz)	CSB Frequency (MHz)	Typical at T _J = 65	Typical ^{2,3}	Maximum ⁴	Unit
PBGA	266	266	1.3	1.6	1.8	W
		133	1.1	1.4	1.6	W
	400	266	1.5	1.9	2.1	W
		133	1.4	1.7	1.9	W
	400	200	1.5	1.8	2.0	W
		100	1.3	1.7	1.9	W

 Table 4. MPC8343EA Power Dissipation¹

¹ The values do not include I/O supply power (OV_{DD}, LV_{DD}, GV_{DD}) or AV_{DD}. For I/O power values, see Table 5.

² Typical power is based on a voltage of V_{DD} = 1.2 V, a junction temperature of T_J = 105°C, and a Dhrystone benchmark application.

³ Thermal solutions may need to design to a value higher than typical power based on the end application, T_A target, and I/O power.

⁴ Maximum power is based on a voltage of V_{DD} = 1.2 V, worst case process, a junction temperature of T_J = 105°C, and an artificial smoke test.



DDR and DDR2 SDRAM

Table 13 provides the DDR2 capacitance when $GV_{DD}(typ) = 1.8$ V.

Table 13. DDR2 SDRAM Capacitance for GV_{DD}(typ) = 1.8 V

Parameter/Condition	Symbol	Min	Мах	Unit	Notes
Input/output capacitance: DQ, DQS, DQS	C _{IO}	6	8	pF	1
Delta input/output capacitance: DQ, DQS, DQS	C _{DIO}	—	0.5	pF	1

Note:

1. This parameter is sampled. $GV_{DD} = 1.8 \text{ V} \pm 0.090 \text{ V}$, f = 1 MHz, $T_A = 25^{\circ}C$, $V_{OUT} = GV_{DD}/2$, V_{OUT} (peak-to-peak) = 0.2 V.

Table 14 provides the recommended operating conditions for the DDR SDRAM component(s) when $GV_{DD}(typ) = 2.5 \text{ V}.$

Table 14. DDR SDRAM DC Electrical Characteristics for GV_{DD}(typ) = 2.5 V

Parameter/Condition	Symbol	Min	Мах	Unit	Notes
I/O supply voltage	GV _{DD}	2.375	2.625	V	1
I/O reference voltage	MV _{REF}	$0.49 imes GV_{DD}$	$0.51 imes GV_{DD}$	V	2
I/O termination voltage	V _{TT}	MV _{REF} – 0.04	MV _{REF} + 0.04	V	3
Input high voltage	V _{IH}	MV _{REF} + 0.18	GV _{DD} + 0.3	V	_
Input low voltage	V _{IL}	-0.3	MV _{REF} – 0.18	V	_
Output leakage current	I _{OZ}	-9.9	-9.9	μA	4
Output high current (V _{OUT} = 1.95 V)	I _{ОН}	-15.2	—	mA	_
Output low current (V _{OUT} = 0.35 V)	I _{OL}	15.2	—	mA	_

Notes:

1. GV_{DD} is expected to be within 50 mV of the DRAM GV_{DD} at all times.

2. MV_{REF} is expected to be equal to 0.5 × GV_{DD} , and to track GV_{DD} DC variations as measured at the receiver. Peak-to-peak noise on MV_{REF} may not exceed ±2% of the DC value.

3. V_{TT} is not applied directly to the device. It is the supply to which far end signal termination is made and is expected to be equal to MV_{REF}. This rail should track variations in the DC level of MV_{REF}.

4. Output leakage is measured with all outputs disabled, 0 V \leq V_{OUT} \leq GV_{DD}.

Table 15 provides the DDR capacitance when $GV_{DD}(typ) = 2.5$ V.

Table 15. DDR SDRAM Capacitance for GV_{DD}(typ) = 2.5 V

Parameter/Condition	Symbol	Min	Мах	Unit	Notes
Input/output capacitance: DQ, DQS	C _{IO}	6	8	pF	1
Delta input/output capacitance: DQ, DQS	C _{DIO}	—	0.5	pF	1

Note:

1. This parameter is sampled. $GV_{DD} = 2.5 V \pm 0.125 V$, f = 1 MHz, T_A = 25°C, V_{OUT} = $GV_{DD}/2$, V_{OUT} (peak-to-peak) = 0.2 V.

NP

DDR and DDR2 SDRAM

Table 20. DDR and DDR2 SDRAM Output AC Timing Specifications (continued)

At recommended operating conditions with GV_{DD} of (1.8 or 2.5 V) \pm 5%.

Parameter	Symbol ¹	Min	Мах	Unit	Notes
MDQS epilogue end	t _{DDKHME}	-0.6	0.6	ns	6

Notes:

- The symbols for timing specifications follow the pattern of t<sub>(first two letters of functional block)(signal)(state)(reference)(state) for inputs and t_{(first two letters of functional block)(reference)(state)(signal)(state)} for outputs. Output hold time can be read as DDR timing (DD) from the rising or falling edge of the reference clock (KH or KL) until the output goes invalid (AX or DX). For example, t_{DDKHAS} symbolizes DDR timing (DD) for the time t_{MCK} memory clock reference (K) goes from the high (H) state until outputs (A) are set up (S) or output valid time. Also, t_{DDKLDX} symbolizes DDR timing (DD) for the time t_{MCK} memory clock reference (K) goes low (L) until data outputs (D) are invalid (X) or data output hold time.
 </sub>
- 2. All MCK/ \overline{MCK} referenced measurements are made from the crossing of the two signals ±0.1 V.
- 3. ADDR/CMD includes all DDR SDRAM output signals except MCK/MCK, MCS, and MDQ/MECC/MDM/MDQS. For the ADDR/CMD setup and hold specifications, it is assumed that the clock control register is set to adjust the memory clocks by 1/2 applied cycle.
- 4. t_{DDKHMH} follows the symbol conventions described in note 1. For example, t_{DDKHMH} describes the DDR timing (DD) from the rising edge of the MCK(n) clock (KH) until the MDQS signal is valid (MH). t_{DDKHMH} can be modified through control of the DQSS override bits in the TIMING_CFG_2 register and is typically set to the same delay as the clock adjust in the CLK_CNTL register. The timing parameters listed in the table assume that these two parameters are set to the same adjustment value. See the MPC8349EA PowerQUICC II Pro Integrated Host Processor Family Reference Manual for the timing modifications enabled by use of these bits.
- 5. Determined by maximum possible skew between a data strobe (MDQS) and any corresponding bit of data (MDQ), ECC (MECC), or data mask (MDM). The data strobe should be centered inside the data eye at the pins of the microprocessor.
- 6. All outputs are referenced to the rising edge of MCK(n) at the pins of the microprocessor. Note that t_{DDKHMP} follows the symbol conventions described in note 1.

Figure 6 shows the DDR SDRAM output timing for the MCK to MDQS skew measurement (t_{DDKHMH}).



Figure 6. Timing Diagram for t_{DDKHMH}



Ethernet: Three-Speed Ethernet, MII Management

8.2.2 RGMII and RTBI AC Timing Specifications

Table 27 presents the RGMII and RTBI AC timing specifications.

Table 27. RGMII and RTBI AC Timing Specifications

At recommended operating conditions with LV_{DD} of 2.5 V \pm 5%.

Parameter/Condition	Symbol ¹	Min	Тур	Max	Unit
Data to clock output skew (at transmitter)	t _{SKRGT}	-0.5	—	0.5	ns
Data to clock input skew (at receiver) ²	t _{SKRGT}	1.0	—	2.8	ns
Clock cycle duration ³	t _{RGT}	7.2	8.0	8.8	ns
Duty cycle for 1000Base-T ^{4, 5}	t _{RGTH} /t _{RGT}	45	50	55	%
Duty cycle for 10BASE-T and 100BASE-TX ^{3, 5}	t _{RGTH} /t _{RGT}	40	50	60	%
Rise time (20%–80%)	t _{RGTR}	—	—	0.75	ns
Fall time (80%–20%)	t _{RGTF}	—	—	0.75	ns

Notes:

1. In general, the clock reference symbol for this section is based on the symbols RGT to represent RGMII and RTBI timing. For example, the subscript of t_{RGT} represents the TBI (T) receive (RX) clock. Also, the notation for rise (R) and fall (F) times follows the clock symbol. For symbols representing skews, the subscript is SK followed by the clock being skewed (RGT).

2. This implies that PC board design requires clocks to be routed so that an additional trace delay of greater than 1.5 ns is added to the associated clock signal.

3. For 10 and 100 Mbps, t_{RGT} scales to 400 ns \pm 40 ns and 40 ns \pm 4 ns, respectively.

4. Duty cycle may be stretched/shrunk during speed changes or while transitioning to a received packet clock domains as long as the minimum duty cycle is not violated and stretching occurs for no more than three t_{RGT} of the lowest speed transitioned.

5. Duty cycle reference is $LV_{DD}/2$.







Figure 22. Local Bus Signals, GPCM/UPM Signals for LCCR[CLKDIV] = 4 (DLL Enabled)

11 JTAG

This section describes the DC and AC electrical specifications for the IEEE Std. 1149.1 (JTAG) interface of the MPC8343EA.

11.1 JTAG DC Electrical Characteristics

Table 36 provides the DC electrical characteristics for the IEEE Std. 1149.1 (JTAG) interface of the MPC8343EA.

Parameter	Symbol	Condition	Min	Мах	Unit
Input high voltage	V _{IH}	—	OV _{DD} - 0.3	OV _{DD} + 0.3	V
Input low voltage	V _{IL}	—	-0.3	0.8	V
Input current	I _{IN}	—	—	±5	μA
Output high voltage	V _{OH}	I _{OH} = -8.0 mA	2.4	—	V



Figure 26 provides the boundary-scan timing diagram.



Figure 26. Boundary-Scan Timing Diagram





Figure 27. Test Access Port Timing Diagram



12 I²C

This section describes the DC and AC electrical characteristics for the I²C interface of the MPC8343EA.

12.1 I²C DC Electrical Characteristics

Table 38 provides the DC electrical characteristics for the I²C interface of the MPC8343EA.

Table 38. I²C DC Electrical Characteristics

At recommended operating conditions with OV_{DD} of 3.3 V \pm 10%.

Parameter	Symbol	Min	Max	Unit	Notes
Input high voltage level	V _{IH}	$0.7 \times OV_{DD}$	OV _{DD} + 0.3	V	_
Input low voltage level	V _{IL}	-0.3	$0.3\times \text{OV}_{\text{DD}}$	V	_
Low level output voltage	V _{OL}	0	$0.2\times \text{OV}_{\text{DD}}$	V	1
Output fall time from $V_{IH}(\text{min})$ to $V_{IL}(\text{max})$ with a bus capacitance from 10 to 400 pF	t _{I2KLKV}	$20 + 0.1 \times C_B$	250	ns	2
Pulse width of spikes which must be suppressed by the input filter	t _{i2KHKL}	0	50	ns	3
Input current each I/O pin (input voltage is between $0.1 \times OV_{DD}$ and $0.9 \times OV_{DD}$ (max)	I	-10	10	μA	4
Capacitance for each I/O pin	Cl	—	10	pF	_

Notes:

1. Output voltage (open drain or open collector) condition = 3 mA sink current.

2. C_B = capacitance of one bus line in pF.

3. Refer to the MPC8349EA Integrated Host Processor Family Reference Manual, for information on the digital filter used.

4. I/O pins obstruct the SDA and SCL lines if $\ensuremath{\mathsf{OV}_{\mathsf{DD}}}$ is switched off.

12.2 I²C AC Electrical Specifications

Table 39 provides the AC timing parameters for the I²C interface of the MPC8343EA. Note that all values refer to $V_{IH}(min)$ and $V_{IL}(max)$ levels (see Table 38).

Table 39. I²C AC Electrical Specifications

Parameter	Symbol ¹	Min	Мах	Unit
SCL clock frequency	f _{I2C}	0	400	kHz
Low period of the SCL clock	t _{I2CL}	1.3	_	μS
High period of the SCL clock	t _{I2CH}	0.6	_	μS
Setup time for a repeated START condition	t _{I2SVKH}	0.6	_	μS
Hold time (repeated) START condition (after this period, the first clock pulse is generated)	t _{I2SXKL}	0.6	_	μs
Data setup time	t _{I2DVKH}	100	_	ns
Data hold time:CBUS compatible masters I ² C bus devices	t _{i2DXKL}	$\overline{0^2}$	 0.9 ³	μS



13 PCI

This section describes the DC and AC electrical specifications for the PCI bus of the MPC8343EA.

13.1 PCI DC Electrical Characteristics

Table 40 provides the DC electrical characteristics for the PCI interface of the MPC8343EA.

Parameter	Symbol	Test Condition	Min	Мах	Unit
High-level input voltage	V _{IH}	$V_{OUT} \ge V_{OH}$ (min) or	2	OV _{DD} + 0.3	V
Low-level input voltage	V _{IL}	$V_{OUT} \le V_{OL}$ (max)	-0.3	0.8	V
Input current	I _{IN}	$V_{IN}^{1} = 0 V \text{ or } V_{IN} = OV_{DD}$	_	±5	μA
High-level output voltage	V _{OH}	OV _{DD} = min, I _{OH} = −100 μA	OV _{DD} – 0.2	_	V
Low-level output voltage	V _{OL}	OV _{DD} = min, I _{OL} = 100 μA	_	0.2	V

Table 40. PCI DC Electrical Characteristics

Note:

1. The symbol V_{IN} , in this case, represents the OV_{IN} symbol referenced in Table 1.

13.2 PCI AC Electrical Specifications

This section describes the general AC timing parameters of the PCI bus of the MPC8343EA. Note that the PCI_CLK or PCI_SYNC_IN signal is used as the PCI input clock depending on whether the device is configured as a host or agent device. Table 41 provides the PCI AC timing specifications at 66 MHz.

Parameter	Symbol ²	Min	Мах	Unit	Notes
Clock to output valid	^t PCKHOV	—	6.0	ns	3
Output hold from clock	t _{PCKHOX}	1	—	ns	3
Clock to output high impedance	t _{PCKHOZ}	—	14	ns	3, 4
Input setup to clock	t _{PCIVKH}	3.0	—	ns	3, 5



Figure 34 and Figure 35 represent the AC timings from Table 50. Note that although the specifications generally reference the rising edge of the clock, these AC timing diagrams also apply when the falling edge is the active edge.

Figure 34 shows the SPI timings in slave mode (external clock).



Note: The clock edge is selectable on SPI.

Figure 34. SPI AC Timing in Slave Mode (External Clock) Diagram

Figure 35 shows the SPI timings in master mode (internal clock).



Note: The clock edge is selectable on SPI.

Figure 35. SPI AC Timing in Master Mode (Internal Clock) Diagram

18 Package and Pin Listings

This section details package parameters, pin assignments, and dimensions. The MPC8343EA is available in a plastic ball grid array (PBGA). See Section 18.1, "Package Parameters for the MPC8343EA PBGA," and Section 18.2, "Mechanical Dimensions for the MPC8343EA PBGA."

18.1 Package Parameters for the MPC8343EA PBGA

The package parameters are as provided in the following list. The package type is $29 \text{ mm} \times 29 \text{ mm}$, 620 plastic ball grid array (PBGA).

Package outline	29 mm × 29 mm
Interconnects	620
Pitch	1.00 mm
Module height (maximum)	2.46 mm



18.3 Pinout Listings

Table 51 provides the pin-out listing for the MPC8343EA, 620-PBGA package.

Table 51. MPC8343EA (PBGA) Pinout Listing

Signal	Package Pin Number	Pin Type	Power Supply	Notes			
PCI							
PCI1_INTA/IRQ_OUT	D20	0	OV _{DD}	2			
PCI1_RESET_OUT	B21	0	OV _{DD}	—			
PCI1_AD[31:0]	E19, D17, A16, A18, B17, B16, D16, B18, E17, E16, A15, C16, D15, D14, C14, A12, D12, B11, C11, E12, A10, C10, A9, E11, E10, B9, B8, D9, A8, C9, D8, C8	I/O	OV _{DD}	—			
PCI1_C/BE[3:0]	A17, A14, A11, B10	I/O	OV _{DD}	—			
PCI1_PAR	D13	I/O	OV _{DD}	—			
PCI1_FRAME	B14	I/O	OV _{DD}	5			
PCI1_TRDY	A13	I/O	OV _{DD}	5			
PCI1_IRDY	E13	I/O	OV _{DD}	5			
PCI1_STOP	C13	I/O	OV _{DD}	5			
PCI1_DEVSEL	B13	I/O	OV _{DD}	5			
PCI1_IDSEL	C17	I	OV _{DD}	—			
PCI1_SERR	C12	I/O	OV _{DD}	5			
PCI1_PERR	B12	I/O	OV _{DD}	5			
PCI1_REQ[0]	A21	I/O	OV _{DD}	—			
PCI1_REQ[1]/CPCI1_HS_ES	C19	I	OV _{DD}	—			
PCI1_REQ[2:4]	C18, A19, E20	I	OV _{DD}	—			
PCI1_GNT0	B20	I/O	OV _{DD}	—			
PCI1_GNT1/CPCI1_HS_LED	C20	0	OV _{DD}	—			
PCI1_GNT2/CPCI1_HS_ENUM	B19	0	OV _{DD}	—			
PCI1_GNT[3:4]	A20, E18	0	OV _{DD}	—			
M66EN	L26	I	OV _{DD}	—			
	DDR SDRAM Memory Interface						
MDQ[0:31]	AC25, AD27, AD25, AH27, AE28, AD26, AD24, AF27, AF25, AF28, AH24, AG26, AE25, AG25, AH26, AH25, AG22, AH22, AE21, AD19, AE22, AF23, AE19, AG20, AG19, AD17, AE16, AF16, AF18, AG18, AH17, AH16	I/O	GV _{DD}	_			



Signal	Package Pin Number	Pin Type	Power Supply	Notes
LBCTL	H5	0	OV _{DD}	_
LALE	E3	0	OV _{DD}	
LGPL0/LSDA10/cfg_reset_source0	F4	I/O	OV _{DD}	
LGPL1/LSDWE/cfg_reset_source1	D2	I/O	OV _{DD}	
LGPL2/LSDRAS/LOE	C1	0	OV _{DD}	_
LGPL3/LSDCAS/cfg_reset_source2	C2	I/O	OV _{DD}	_
LGPL4/LGTA/LUPWAIT/LPBSE	С3	I/O	OV _{DD}	12
LGPL5/cfg_clkin_div	B3	I/O	OV _{DD}	_
LCKE	E4	0	OV _{DD}	_
LCLK[0:2]	D4, A3, C4	0	OV _{DD}	_
LSYNC_OUT	U3	0	OV _{DD}	_
LSYNC_IN	Y2	I	OV_{DD}	
	General Purpose I/O Timers			
GPIO1[0]/DMA_DREQ0/GTM1_TIN1/ GTM2_TIN2	D27	I/O	OV _{DD}	
GPIO1[1]/DMA_DACK0/GTM1_TGATE1/ GTM2_TGATE2	E26	I/O	OV _{DD}	—
GPIO1[2]/DMA_DDONE0/ GTM1_TOUT1	D28	I/O	OV _{DD}	—
GPIO1[3]/DMA_DREQ1/GTM1_TIN2/ GTM2_TIN1	G25	I/O	OV _{DD}	_
GPIO1[4]/DMA_DACK1/ GTM1_TGATE2/GTM2_TGATE1	J24	I/O	OV _{DD}	_
GPIO1[5]/DMA_DDONE1/ GTM1_TOUT2/GTM2_TOUT1	F26	I/O	OV _{DD}	_
GPIO1[6]/DMA_DREQ2/GTM1_TIN3/ GTM2_TIN4	E27	I/O	OV _{DD}	—
GPIO1[7]/DMA_DACK2/GTM1_TGATE3/ GTM2_TGATE4	E28	I/O	OV _{DD}	_
GPIO1[8]/DMA_DDONE2/ GTM1_TOUT3	H25	I/O	OV _{DD}	_
GPIO1[9]/DMA_DREQ3/GTM1_TIN4/ GTM2_TIN3	F27	I/O	OV _{DD}	—
GPIO1[10]/DMA_DACK3/ GTM1_TGATE4/GTM2_TGATE3	K24	I/O	OV _{DD}	—
GPIO1[11]/DMA_DDONE3/ GTM1_TOUT4/GTM2_TOUT3	G26	I/O	OV _{DD}	_



Table 51 MPC83/3EA			na (contin	(hau
TADIE 31. INF CO343EA	(FDGA)) Fillout Listii	ig (contin	ueu)

Signal	Package Pin Number	Pin Type	Power Supply	Notes
	SPI		-	•
SPIMOSI/LCS[6]	D7	I/O	OV _{DD}	—
SPIMISO/LCS[7]	C7	I/O	OV _{DD}	—
SPICLK	B7	I/O	OV _{DD}	—
SPISEL	A7	I	OV _{DD}	—
	Clocks			
PCI_CLK_OUT[0:2]	Y1, W3, W2	0	OV _{DD}	—
PCI_CLK_OUT[3]/LCS[6]	W1	0	OV _{DD}	—
PCI_CLK_OUT[4]/LCS[7]	V3	0	OV _{DD}	—
PCI_SYNC_IN/PCI_CLOCK	U4	I	OV _{DD}	—
PCI_SYNC_OUT	U5	0	OV _{DD}	3
RTC/PIT_CLOCK	E9	I	OV _{DD}	—
CLKIN	W5	I	OV _{DD}	—
	JTAG			
тск	H27	I	OV _{DD}	—
TDI	H28	I	OV _{DD}	4
TDO	M24	0	OV _{DD}	3
TMS	J27	I	OV _{DD}	4
TRST	K26	I	OV _{DD}	4
	Test			
TEST	F28	I	OV _{DD}	6
TEST_SEL	Т3	I	OV _{DD}	7
	РМС			
QUIESCE	K27	0	OV _{DD}	—
	System Control			
PORESET	K28	I	OV _{DD}	—
HRESET	M25	I/O	OV _{DD}	1
SRESET	L27	I/O	OV _{DD}	2
	Thermal Management	_		
THERM0	B15	I	_	8



Signal	Package Pin Number	Pin Type	Power Supply	Notes		
OV _{DD}	B27, D3, D11, D19, E15, E23, F5, F8, F11, F14, F17, F20, G24, H23, H24, J6, J14, J17, J18, K4, L9, L20, L23, L25, M6, M9, M20, P5, P20, P23, R6, R9, R24, U23, V4, V6	PCI, 10/100 Ethernet, and other standard (3.3 V)	OV _{DD}	_		
MVREF1	AF19	I	DDR reference voltage	_		
MVREF2	AE10	I	DDR reference voltage	_		
No Connection						
NC	A22, A23, A24, B22, B23, B24, C21, C22, C23, C24, D21, D22, D23, D24, E21, M27, M28, N26, N27, N28, P25, P26, P27, R28, T24, T25, T26, T27, T28, U27, U28, Y3, Y4, Y5, AA1, AA2, AA3, AA4, AB1, AB2, AB3, AB4, AC1, AC2, AC3, AC4, AD1, AD2, AD3, AD5, AD7, AD11, AD12, AE4, AE6, AE8, AE9, AE23, AF1, AF5, AF6, AF8, AF24, AG1, AG3, AG4, AG7, AG8, AG9, AG10, AH2, AH3, AH5, AH8, AH9, V5, V2, V1	_	_	_		

Table 51. MPC8343EA (PBGA) Pinout Listing (continued)

Notes:

1. This pin is an open-drain signal. A weak pull-up resistor (1 kΩ) should be placed on this pin to OV_{DD}.

2. This pin is an open-drain signal. A weak pull-up resistor (2-10 kΩ) should be placed on this pin to OV_{DD}.

3. During reset, this output is actively driven rather than three-stated.

4. These JTAG pins have weak internal pull-up P-FETs that are always enabled.

5. This pin should have a weak pull-up if the chip is in PCI host mode. Follow the PCI specifications.

6. This pin must be always be tied to GND.

7. This pin must always be pulled up to OV_{DD}.

8. Thermal sensitive resistor.

9. It is recommended that MDIC0 be tied to GND using an 18.2 Ω resistor and MDIC1 be tied to DDR power using an 18.2 Ω resistor.

10.TSEC1_TXD[3] is required an external pull-up resistor. For proper functionality of the device, this pin must be pulled up or actively driven high during a hard reset. No external pull-down resistors are allowed to be attached to this net.

11. A weak pull-up resistor (2–10 k Ω) should be placed on this pin to LV_{DD1}.

12. For systems that boot from local bus (GPCM)-controlled NOR flash, a pull up on LGPL4 is required.



Clocking

Table 53 provides the operating frequencies for the MPC8343EA PBGA under recommended operating conditions.

Parameter ¹	266 MHz	333 MHz	400 MHz	Unit
e300 core frequency (<i>core_clk</i>)	200–266	200–333	200–400	MHz
Coherent system bus frequency (<i>csb_clk</i>)	100–266			MHz
DDR1 memory bus frequency (MCK) ² 100–133			MHz	
DDR2 memory bus frequency (MCK) ³	100–133		MHz	
Local bus frequency (LCLK <i>n</i>) ⁴	16.67–133			MHz
PCI input frequency (CLKIN or PCI_CLK)	25–66			MHz
Security core maximum internal operating frequency	133			MHz
USB_DR, USB_MPH maximum internal operating frequency	133			MHz

Table 53. Operating Frequencies for PBGA

¹ The CLKIN frequency, RCWL[SPMF], and RCWL[COREPLL] settings must be chosen so that the resulting *csb_clk*, MCLK, LCLK[0:2], and *core_clk* frequencies do not exceed their respective maximum or minimum operating frequencies. The value of SCCR[ENCCM], SCCR[USBDRCM], and SCCR[USBMPHCM] must be programmed so that the maximum internal operating frequency of the Security core and USB modules does not exceed the respective values listed in this table.

² The DDR data rate is 2× the DDR memory bus frequency.

³ The DDR data rate is 2× the DDR memory bus frequency.

⁴ The local bus frequency is ½, ¼, or 1/8 of the *lbiu_clk* frequency (depending on LCCR[CLKDIV]) which is in turn 1× or 2× the *csb_clk* frequency (depending on RCWL[LBIUCM]).

19.1 System PLL Configuration

The system PLL is controlled by the RCWL[SPMF] parameter. Table 54 shows the multiplication factor encodings for the system PLL.

RCWL[SPMF]	System PLL Multiplication Factor	
0000	× 16	
0001	Reserved	
0010	× 2	
0011	× 3	
0100	× 4	
0101	× 5	
0110	× 6	
0111	× 7	
1000	× 8	
1001	× 9	
1010	× 10	

Table 54. System PLL Multiplication Factors

NP

Thermal

The junction-to-ambient thermal resistance is an industry-standard value that provides a quick and easy estimation of thermal performance. Generally, the value obtained on a single-layer board is appropriate for a tightly packed printed-circuit board. The value obtained on the board with the internal planes is usually appropriate if the board has low power dissipation and the components are well separated. Test cases have demonstrated that errors of a factor of two (in the quantity $T_J - T_A$) are possible.

20.2.2 Estimation of Junction Temperature with Junction-to-Board Thermal Resistance

The thermal performance of a device cannot be adequately predicted from the junction-to-ambient thermal resistance. The thermal performance of any component is strongly dependent on the power dissipation of surrounding components. In addition, the ambient temperature varies widely within the application. For many natural convection and especially closed box applications, the board temperature at the perimeter (edge) of the package is approximately the same as the local air temperature near the device. Specifying the local ambient conditions explicitly as the board temperature provides a more precise description of the local ambient conditions that determine the temperature of the device.

At a known board temperature, the junction temperature is estimated using the following equation:

$$T_J = T_A + (R_{\theta JA} \times P_D)$$

where:

 T_I = junction temperature (°C)

 T_A = ambient temperature for the package (°C)

 $R_{\theta IA}$ = junction-to-ambient thermal resistance (°C/W)

 P_D = power dissipation in the package (W)

When the heat loss from the package case to the air can be ignored, acceptable predictions of junction temperature can be made. The application board should be similar to the thermal test condition: the component is soldered to a board with internal planes.

20.2.3 Experimental Determination of Junction Temperature

To determine the junction temperature of the device in the application after prototypes are available, use the thermal characterization parameter (Ψ_{JT}) to determine the junction temperature and a measure of the temperature at the top center of the package case using the following equation:

$$T_J = T_T + (\Psi_{JT} \times P_D)$$

where:

 T_I = junction temperature (°C)

 T_T = thermocouple temperature on top of package (°C)

 Ψ_{JT} = junction-to-ambient thermal resistance (°C/W)

 P_D = power dissipation in the package (W)

The thermal characterization parameter is measured per the JESD51-2 specification using a 40 gauge type T thermocouple epoxied to the top center of the package case. The thermocouple should be positioned so



System Design Information

21.3 Decoupling Recommendations

Due to large address and data buses and high operating frequencies, the MPC8343EA can generate transient power surges and high frequency noise in its power supply, especially while driving large capacitive loads. This noise must be prevented from reaching other components in the MPC8343EA system, and the device itself requires a clean, tightly regulated source of power. Therefore, the system designer should place at least one decoupling capacitor at each V_{DD} , OV_{DD} , GV_{DD} , and LV_{DD} pin of the device. These capacitors should receive their power from separate V_{DD} , OV_{DD} , GV_{DD} , LV_{DD} , and GND power planes in the PCB, with short traces to minimize inductance. Capacitors can be placed directly under the device using a standard escape pattern. Others can surround the part.

These capacitors should have a value of 0.01 or 0.1 μ F. Only ceramic SMT (surface mount technology) capacitors should be used to minimize lead inductance, preferably 0402 or 0603 sizes.

In addition, distribute several bulk storage capacitors around the PCB, feeding the V_{DD} , OV_{DD} , GV_{DD} , and LV_{DD} planes, to enable quick recharging of the smaller chip capacitors. These bulk capacitors should have a low ESR (equivalent series resistance) rating to ensure the quick response time. They should also be connected to the power and ground planes through two vias to minimize inductance. Suggested bulk capacitors are 100–330 μ F (AVX TPS tantalum or Sanyo OSCON).

21.4 Connection Recommendations

To ensure reliable operation, connect unused inputs to an appropriate signal level. Unused active low inputs should be tied to OV_{DD} , GV_{DD} , or LV_{DD} as required. Unused active high inputs should be connected to GND. All NC (no-connect) signals must remain unconnected.

Power and ground connections must be made to all external V_{DD} , GV_{DD} , LV_{DD} , OV_{DD} , and GND pins of the MPC8343EA.

21.5 Output Buffer DC Impedance

The MPC8343EA drivers are characterized over process, voltage, and temperature. For all buses, the driver is a push-pull single-ended driver type (open drain for I^2C).

To measure Z_0 for the single-ended drivers, an external resistor is connected from the chip pad to OV_{DD} or GND. Then the value of each resistor is varied until the pad voltage is $OV_{DD}/2$ (see Figure 39). The output impedance is the average of two components, the resistances of the pull-up and pull-down devices. When data is held high, SW1 is closed (SW2 is open) and R_P is trimmed until the voltage at the pad equals

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